# HIGHER ORDER GRASSMANN BUNDLES $\dagger$ 

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## INTRODUCTION

The aim of this paper is to discuss higher-order Grassmann bundles as a setting for (nonlinear) partial differential equations (including systems of such equations). The kinds of equations we have in mind are those whose solutions are submanifolds of a given manifold $M$, e.g. the equation for a $p$-dimensional minimal surface in a $d$-dimensional Riemannian manifold. From a geometric point of view a system of $k$ th order partial differential equations assigns at each point $m$ of $M$ some collection of $k$ th order contact spaces there, a $k$ th order contact space at $m$ being a linear subspace of the $k$ th order tangent vectors at $m$; a solution is then a submanifold $N$ of $M$ such that the $k$ th order tangent space to $N$ at each $n \in N$ is one of the given contact spaces at $n$. For example, in the minimal surface equation (usually called a system of equations) one is given at each $m \in M$ ( $M$ being assumed Riemannian) a family of second-order tangent spaces at each point of $M$, namely all those whose first-order part is $p$-dimensional and such that the trace of the second fundamental form of the second order space, relative to any first-order tangent vector which is perpendicular to this $p$-dimensional space, vanishes. (One can define a second fundamental form for a second-order tangent space at a point-a whole submanifold is unnecessary.)

We attempt to formulate systems of partial differential equations of this kind geometrically because they arise geometrically; a co-ordinate expression for such equations seems to be an extra complication, depending on an arbitrary choice of a co-ordinate system.

Now we indicate how the usual expression for a partial differential equation (or system-but hereafter we shall use the term 'partial differential equation' to include what are usually called 'systems') can be transcribed into geometrical language. First consider a single first order equation for a single unknown function, which is usually written as

$$
f\left(x_{1}, \ldots, x_{p}, u, \ldots, \frac{\partial u}{\partial x_{i}}, \ldots\right)=0
$$

$u$ being the 'unknown' function and $x_{1}, \ldots, x_{p}$ the 'independent variables'. Consider the graph of $u$; at a point $\left(x_{1}, \ldots, x_{p}, u\right)-(x, u)$ of that graph the $\frac{\partial u}{\partial x_{i}}$ are the slopes of the tangent plane to the graph at $(x, u)$, and characterize that $p$-plane. So $f$ may be considered
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as a function on $p$-planes at points in $R^{p+1}$. Then a solution of this equation is a function $u$ such that $f$ vanishes at every $p$-plane tangent to the graph of $u$. We may generalize this situation, replacing $R^{p+1}$ by a manifold $M$, and taking $f$ to be a function on $G_{p}(M)$, where $G_{p}(M)$ is the Grassmann bundle over $M$ whose elements are all the ( $m, P$ ) such that $m \in M$ and $P$ is a $p$-dimensional subspace of the tangent space at $m$. Then a 'solution' will be any $p$-dimensional submanifold $N$ of $M$ such that at each point $n$ of $N, f$ vanishes on the tangent plane to $N$. So a solution is now a submanifold rather than a function; the possibility above of representing the submanifold as the graph of a function $u$ was related to a particular co-ordinate system for $R^{p+1}$ so we are willing to drop that feature.

Now suppose we have a single first order equation for a family of 'unknown' functions, written classically as

$$
f\left(x_{1}, \ldots, x_{p}, u_{1}, \ldots, u_{q}, \ldots, \frac{\partial u_{r}}{\partial x_{i}}, \ldots\right)=0
$$

Letting $u=\left(u_{1}, \ldots, u_{q}\right)$ the graph of $u$ is a submanifold of $R^{p+q}$ and $f$ can be considered as a function on $p$-planes at points of $R^{p+q}$; a solution is a $u$ such that $f$ vanishes on the $p$-planes tangent to the graph of $u$. Similarly, if we have a collection $f_{1}, \ldots, f_{s}$ of such $f$ 's; a solution is still a $u=\left(u_{1}, \ldots, u_{q}\right)$ whose graph lies in $R^{p+q}$, but such that all the $f_{k}$ vanish on the graph of $u$. So to generalize this as above we replace $R^{p+q}$ by a manifold $M$ of dimension $d=p+q$, replace the $f_{k}$ 's by functions on $G_{p}(M)$, and define a solution to be a $p$-dimensional submanifold $N$ of $M$ such that at each point of $N$ all the $f_{k}$ vanish on the tangent plane to $N$. The only difference from the preceeding case is that now $d-p=q$ instead of $d-p=1$. So in our general formulation we define the 'number of unknown functions' to be $d-p$.

Now we note that the only feature of $f$, or of the $f_{k}$, which was used above was the set of its zeros, or the set of common zeros in the case of more than one $f$. So letting $E$ be this set of zeros, a solution is a submanifold $N$ of $M$ whose tangent space at each point is in $E$. For this reason we shall define a 'system of first-order partial differential equations', depending on a given manifold $M$ and integer $p$, to be a subset $E$ of $G_{p}(M)$. If $N$ is any $p$-dimensional submanifold of $M$ it has a natural lift ${ }^{[1]} N$ which is a submanifold of $G_{p}(M)$, i.e. ${ }^{[1]} N$ consists of all $(n, P) \in G_{p}(M)$ such that $n \in N$ and $P$ is the tangent space to $N$ at $n$. Then $N$ is defined to be a solution of $E$ if and only if ${ }^{[1]} N \subseteq E$.

We have been discussing first-order systems. Now we turn to higher-order systems. The concepts here can be formulated as above, but using higher-order tangent vectors, higher-order spaces (i.e. spaces of these higher-order tangent vectors) and Grassmann bundles of these higher-order spaces. But at this point there arises something which is the main concern of this paper, namely, the relation between these higher-order Grassmann bundles and the iterated first-order bundles. By the iterated first-order bundles we mean $G_{p}\left(G_{p}(M)\right)$, etc. This relation seems important to us for the following reasons: (1) Through it we can express in general the fact that every system of partial differential equations is equivalent to a first-order system, (2) In removing the co-ordinate systems from the notion of a partial differential equation one loses the fact that each higher order derivative is an iterate of lower order derivatives. This loss is restored, however, by a theorem which we
call the Kuranishi factoring theorem, which says that every higher-order contact space is uniquely expressible as a 'product' of first-order integrable contact spaces; however the factors are first-order tangent spaces to successive first-order Grassmann bundles. Thus this theorem seems to us to restore the gradation of derivatives and to provide an important structural element to the higher-order Grassmann bundles.

This paper begins with a discussion of integrability conditions and leads up to the Kuranishi factoring theorem (Theorem 4.1). This theorem occurs in Kuranishi [3] in a purely co-ordinate form and is also intertwined with prolongations of differential systems. Our contribution is to give the theorem a geometric setting. It ends with a discussion of characteristics of (non-linear) partial differential equations.

We are greatly indebted to both James Simons and I. M. Singer, first for many discussions of matters considered here, but more importantly, for the very concepts on which this paper is based. The notion of an integrable element of an iterated Grassmann bundle was pointed out to us by Simons; he not only pointed out that there was an important notion here but he also explained to us that such elements were characterized by the vanishing of certain differential forms. Our characterization of these forms as 'lift-forms' and differentials of lift forms is our way of describing these forms. But the notion of these lift forms we owe to I. M. Singer, who pointed out to us that these were the essential feature of certain matters in [3]. We also owe to I. M. Singer the procedure for passing from an $f$ defined on $M$ to the related $e_{\alpha} f$ on $S_{p}^{z}(M)$, used in section 1 . We are also indebted to $\mathrm{H} . \mathrm{Wu}$ for reading and criticizing this paper.

## NOTATION

We use $u_{1}, \ldots, u_{n}$ for the usual co-ordinate functions on $R^{n}$. Usually the integers $i, j$ will satisfy $1 \leq i, j \leq p$, though sometimes they will be allowed to be 0 ; the integers $r, s$ will usually satisfy $p+1 \leq r, s \leq d$, and $a, b$ will be integers satisfying $1 \leq a, b \leq d$.

## §1. ITERATED STIEFEL BUNDLES AND THEIR INTEGRABLE POINTS

Let $p$ be any integer with $1 \leq p \leq d$ and we now define the Stiefel bundle $S_{p}(M)$ over $M$. The elements of $S_{p}(M)$ shall be, by definition, all the ( $m, e_{1}, \ldots, e_{p}$ ) where $m$ is any point of $M$ and $e_{1}, \ldots, e_{p}$ is any ordered set of $p$ linearly independent elements from $M_{m}$. We define the projection map $\pi: S_{p}(M) \rightarrow M$, by $\pi\left(m, e_{1}, \ldots, e_{p}\right)=m$. Co-ordinate systems of $S_{p}(M)$ are defined as follows. For any co-ordinate system $\left\{x_{a}\right\}$ of $M$ with domain $Q$ we define a co-ordinate system for $S_{p}(M)$, with domain $\pi^{-1}(Q)$, consisting of the functions $x_{a}^{0}$ and $x_{a}^{i}$ defined (for $1 \leq a \leq d, 1 \leq i \leq p$ ) by

$$
\begin{aligned}
& x_{a}^{0}=x_{a} \circ \pi \\
& x_{a}^{i}\left(m, e_{1}, \ldots, e_{p}\right)=d x_{a}\left(e_{i}\right)=e_{i} x_{a} .
\end{aligned}
$$

Thus $S_{p}(M)$ has dimension $d+p d$.
Now we define, for any non-negative integer $z$, the $z$ th iterated Stiefel bundle $S_{p}^{z}(M)$ by $S_{p}^{z}(M)=S_{p}\left(S_{p}^{z-1}(M)\right.$, making the convention that $S_{p}^{0}(M)=M, S_{p}^{1}(M)=S_{p}(M)$.

Iterating the procedure used above to define a co-ordinate system for $S_{p}(M)$ from a given co-ordinate system for $M$ we obtain, starting with a co-ordinate system $\left\{x_{a}\right\}$ of $M$, a coordinate system of $S_{p}^{z}(M)$, consisting of functions $x_{a}^{\alpha}$, where $1 \leq a \leq d$ and $\alpha$ runs through all $\alpha=\left(\alpha_{1}, \ldots, \alpha_{z}\right)$ such that the $\alpha_{w}$ are integers with $0 \leq \alpha_{w} \leq p$. That is, if such a coordinate system $\left\{x_{a}^{\alpha}\right\}$ has been defined for $S_{p}^{z-1}(M)$ ( $\alpha^{\prime}$ running through the ( $\alpha_{1}, \ldots, \alpha_{z-1}$ )) we then obtain the co-ordinate system $\left\{x_{a}^{\alpha}\right\}$ of $S_{p}^{z}(M)$ by

$$
\begin{aligned}
& x_{a}^{\left(\alpha^{\prime}, 0\right)}=x_{a}^{\alpha^{\prime}} \circ \pi \\
& x_{a}^{\left(\alpha^{\prime}, i\right)}\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)=c_{i}^{z} x_{a}^{\alpha^{\prime}} .
\end{aligned}
$$

Note that among these are functions $x_{a}^{(0, \ldots, 0)}$ which we shall usually denote by $x_{a}^{0}$, this last superscript 0 denoting the zero element of $R^{z}$; for induction purposes we shall sometimes write $x_{a}^{0}$ also for $x_{a}$, considering this zero superscript as the zero element of $R^{0}$. The context will always show where the 0 really lies.

If $\phi$ is any non-singular map of an open $Q$ in $R^{p}$ into $M$ then $\phi$ has a natural lift, which we denote by $\phi^{1}$, mapping $Q$ into $S_{p}(M) . \phi^{1}$ is defined by

$$
\phi^{1}(q)=\left(\phi(q), \phi_{*} \frac{\partial}{\partial u_{1}}(q), \ldots, \phi_{*} \frac{\partial}{\partial u_{p}}(q)\right) .
$$

Iterating this procedure we define the $z$ th lift $\phi^{z}$, a map of $Q$ into $S_{p}^{z}(M)$ by

$$
\phi^{z}(q)=\left(\phi^{z-1}(q), \phi_{*}^{z-1} \frac{\partial}{\partial u_{1}}(q), \ldots, \phi_{*}^{z-1} \frac{\partial}{\partial u_{p}}(q)\right)
$$

and we clearly have

$$
\pi \circ \phi^{z}=\phi^{z-1} \quad \pi=\pi\left[S_{p}^{z}(M) \rightarrow S_{p}^{z-1}(M)\right]
$$

If $(m, e)$ is any point of $S_{p}(M)$ it is trivial that there exists such a $\phi$ with $\phi^{1}(q)=(m, e)$. However, the corresponding property for $S_{p}^{z}(M)$ is false if $z>1$.

Definition. A point $(m, e) \in S_{p}^{z}(M)$ is integrable if and only if there is a non-singular map of an open $Q$ in $R^{p}$ into $M$ and a point $q \in Q$ such that $\phi^{z}(q)=(m, e)$.

The purpose of this section is to prove Theorem (1.1) below, which characterizes integrable points intrinsically, i.e. without referring to a $\phi$ as above. At this point we note that if ( $m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}$ ) is an integrable point of $S_{p}^{z}(M)$ then

$$
\begin{equation*}
\left.\pi_{*} e_{i}^{z}=e_{i}^{z-1} \quad(1 \leq i \leq p) \pi=\pi\left[S_{p}^{z-1}(M) \rightarrow S_{p}^{z-2}(M)\right]\right) \tag{1.1}
\end{equation*}
$$

This is proved inductively from

$$
\pi_{*} e_{i}^{z}=\pi_{*} \circ \phi_{*}^{z-1}\left(\frac{\partial}{\partial u_{i}}(q)\right)=\phi_{*}^{z-2}\left(\frac{\partial}{\partial u_{i}}(q)\right)=e_{i}^{z-1} .
$$

Notation. We shall write $\alpha=\left(\alpha_{1}, \ldots, \alpha_{z}\right)$ and $\beta=\left(\beta_{1}, \ldots, \beta_{z}\right)$ where the $\alpha_{w}$ and $\beta_{w}$ are integers with $0 \leq \alpha_{w}, \beta_{w} \leq p$; this meaning for the letters $\alpha$ and $\beta$ will be fixed throughout this paper. We say $\beta$ is a permutation of $\alpha$ if and only if there is a permutation $\pi$ of $\{1, \ldots, z\}$ such that $\beta_{w}=\alpha_{\pi w}$ for all $w$, and in this case we write $\beta=\pi \alpha$. We define $|\alpha|$ to be the number of $w$ for which $\alpha_{w} \neq 0$ and $\alpha!=n_{1}!\ldots n_{p}!$ where $n_{i}$ is the number of $w$ for which $\alpha_{w}=i$. We shall also use this notation $|\mu|$ and $\mu$ ! below where $\mu=\left(\mu_{1}, \ldots, \mu_{z}\right)$ with $0 \leq \mu_{w} \leq d$, replacing $p$ by $d$ in the above definitions.

We now point out that each ( $m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}$ ) in $S_{p}^{z}(M)$ gives rise to a family $\left\{e_{\alpha}\right\}$ of tangent vectors of order $\leq z$ at $m$. To define the $e_{\alpha}$ we must define $e_{\alpha} f$ for $f$ in $C^{\infty}$ at $m$. We first note that each such $f$ gives rise to $p+1$ functions, $f^{0}, f^{1}, \ldots, f^{p}$ of $S_{p}(M)$ defined (on $\pi^{-1}(Q)$ where $Q$ is the domain of $f$ ) by

$$
\begin{aligned}
f^{0}\left(m, e_{1}, \ldots, e_{p}\right) & =f(m) \\
f^{i}\left(m, e_{1}, \ldots, e_{p}\right) & =e_{i} f \quad(1 \leq i \leq p)
\end{aligned}
$$

It will be convenient also to write $e_{0} f=f(m)$, so the preceding becomes

$$
f^{j}\left(m, e_{1}, \ldots, e_{p}\right)=e_{j} f \quad(0 \leq j \leq p)
$$

Now we iterate this procedure to define, for any such $f$, functions $f^{\alpha}$ of $S_{p}^{z}(M)$, i.e.

$$
f^{z}=f^{\left(\alpha_{1}, \ldots, \alpha_{z}\right)}=\left(\ldots\left(f^{\alpha 1}\right)^{\alpha 2} \ldots\right)^{\alpha z}
$$

and in particular, we have

$$
e_{\alpha} f=e_{a_{z}}^{z} f^{\left(\alpha_{1}, \ldots, \alpha_{z}-1\right)}=f^{\alpha}\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right) .
$$

If $\left\{x_{a}\right\}$ is a co-ordinate system of $M$ then this definition of $x_{a}^{\alpha}$ coincides with that used above in defining a co-ordinate system of $S_{p}^{z}(M)$.

It is easily verified that $e_{\alpha}$ is a tangent vector of order $|\alpha|$ at $m$. As such we have the usual representation

$$
\begin{equation*}
e_{\alpha}=\sum\left(e_{\alpha} x_{\mu} / \mu!\right) \frac{\partial}{\partial x_{\mu}} \tag{1.2}
\end{equation*}
$$

where $\mu$ ranges through all $\mu=\left(\mu_{1}, \ldots, \mu_{z}\right)$ such that $0 \leq \mu_{w} \leq d$, and we use the following conventions,

$$
\frac{\partial}{\partial x_{\mu}}=\frac{\partial}{\partial x_{\mu_{1}}} \ldots \frac{\partial}{\partial x_{\mu_{z}}}, \frac{\partial f}{\partial x_{0}}=f .
$$

If $(m, e) \in S_{p}^{z}(M)$ we let $H(m, e)=\left(m,\left\{e_{\alpha}\right\}\right)$ where $\left\{e_{\alpha}\right\}$ is the family of tangent vectors (of various orders) at $m$ obtained, as above, from ( $m, e$ ), thus defining a map $H$ from $S_{p}^{z}(M)$ into certain families of tangent vectors. $H$ is $1: 1$ because if $H(m, e)=H\left(m, e^{*}\right)$ then $e_{\alpha}=e_{\alpha}^{*}$, hence, for any co-ordinate system $\left\{x_{a}\right\}$ at $m, e_{\alpha} x_{a}=e_{\alpha}^{*} x_{a}$, i.e. $x_{a}^{\alpha}(m, e)=x_{a}^{\alpha}\left(m, e^{*}\right)$ for all $a, \alpha$. Since the $x_{a}^{\alpha}$ are a co-ordinate system this shows $(m, e)=\left(m, e^{*}\right)$.

Now we show that (1.1) is equivalent to

$$
e_{i}^{z} e_{0}^{z-1} e_{\alpha^{\prime \prime}}=e_{0}^{z} e_{i}^{z-1} e_{\alpha^{\prime \prime}} \quad(0 \leq i \leq p)
$$

Proof. Let $\alpha=\left(i, 0, \alpha^{\prime \prime}\right), \alpha^{*}=\left(0, i, \alpha^{\prime \prime}\right)$. If (1.1) holds then

$$
\begin{aligned}
e_{i}^{z} e_{0}^{z-1} e_{\alpha^{\prime \prime}} f & =e_{i}^{z} e_{0}^{z-1} f^{\alpha^{\prime \prime}}=e_{i}^{z}\left(f^{\alpha^{\prime \prime}} \circ \pi\right)=e_{i}^{z-1} f^{\alpha^{\prime \prime}} \\
& =f^{\left(\alpha^{\prime \prime}, i\right)}=e_{0} f^{\left(\alpha^{\prime \prime}, i\right)}=e_{0}^{z} e_{i}^{z-1} e_{\alpha^{\prime \prime}} f
\end{aligned}
$$

On the other hand, if ( $1.1^{\prime}$ ) holds then the two ends of this string of equalities are equal, hence the middle equality must hold, since the others are true by definition. And the middle equality is (1.1).

By virtue of (1.1') the condition (1.3) below includes (1.1). We shall prove in the following theorem that (1.3) characterizes integrable points.

Lemma (1.1). If $\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)$ is an integrable point of $S_{p}^{z}(M)$ then

$$
\begin{equation*}
e_{\alpha}=e_{\beta} \quad \text { if } \beta \text { is a permutation of } \alpha . \tag{1.3}
\end{equation*}
$$

In fact, if $\phi$ is a non-singular map of an open $Q$ in $R^{p}$ into $M$ with $\phi^{z}(q)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots\right.$, $e_{1}^{z}, \ldots, e_{p}^{z}$ ) then

$$
\begin{equation*}
\phi_{*} \frac{\partial}{\partial u_{\alpha}}(q)=e_{\alpha} . \tag{1.3'}
\end{equation*}
$$

Proof. It is sufficient to prove (1.3'), i.e. that

$$
e_{\alpha} f=\frac{\partial(f \circ \phi)}{\partial u_{\alpha}}(q)
$$

for $f$ in $C^{\infty}$ at $m=\phi(q)$. For this it is sufficient to prove

$$
f^{\alpha} \circ \phi^{z}=\frac{\partial(f \circ \phi)}{\partial u_{z}}
$$

If $\alpha=\left(\alpha_{1}, \ldots, \alpha_{z}\right)$ we let $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right)$. Then (1.3") follows by induction on $z$ from

$$
\begin{aligned}
f^{\alpha} \circ \phi^{z} & =\phi_{*}^{z-1}\left(\frac{\partial}{\partial u_{\alpha_{z}}}\right) f^{\alpha^{\prime}}=\frac{\partial}{\partial u_{\alpha_{z}}}\left(f^{\left.\alpha^{\prime} \circ \phi^{z-1}\right)}\right. \\
& =\frac{\partial}{\partial u_{\alpha_{z}}}\left(\frac{\partial(f \circ \phi)}{\partial u_{\alpha^{\prime}}}\right)=\frac{\partial}{\partial u_{z}}(f \circ \phi) .
\end{aligned}
$$

We remark that (1.3') shows, on the $z$ th order tangent spaces at points of $R^{p}$, and for $\phi$ as above, that

$$
\begin{equation*}
\left(H \circ \phi^{z}\right)(q)=\left(m,\left\{\phi_{*} \frac{\partial}{\partial u_{\alpha}}(q)\right\}\right) . \tag{1.4}
\end{equation*}
$$

We now state a generalized Leibnitz product rule for our derivatives $e_{\alpha}$ for which we need the following notation. Let $E$ be any subset of $\{1, \ldots, z\}$. We define the support of $\alpha$ by $\operatorname{supp} \alpha=\left[w \mid \alpha_{w} \neq 0\right]$ and $E \alpha=\alpha^{*}$ where $\alpha_{w}^{*}=\alpha_{w}$ if $w \in E, \alpha_{w}^{*}=0$ if $w \notin E$. Then the product rule, which is easily proved by induction, is: if $f_{1}, \ldots, f_{w}$ are functions in $C^{\infty}$ at $m$, then

$$
\begin{equation*}
\left(f_{1} \ldots f_{w}\right)^{\alpha}=\sum f_{1}^{E} 1^{\alpha} \ldots f_{w}^{E} w^{\alpha} \tag{1.5}
\end{equation*}
$$

where this sum is over all partitions of supp $\alpha$ into $w$ subsets, i.e. over all choices of ordered families of subsets $E_{1}, \ldots, E_{w}$ of supp $\alpha$ such that each $E_{v}$ is disjoint from $E_{u}$ if $u \neq v$ and $\bigcup_{v} E_{v}=\operatorname{supp} \alpha$; in this we include those partitions in which any number of the $E_{v}$ may be empty and we emphasize that for each $E_{1}, \ldots, E_{w}$ which occurs, each permutation of it will also occur. We note that in another notation (1.5) reads:

$$
e_{\alpha}\left(f_{1} \ldots . f_{w}\right)=\sum\left(\left(e_{E_{1} \alpha}\right)\left(f_{1}\right)\right) \ldots\left(\left(e_{E_{w}}\right)\left(f_{w}\right)\right)
$$

and we point out that by previous conventions, $e_{(0, \ldots, 0)} f=f(m)$, and $f^{(0, \ldots, 0)}=f$.
Theorem (1.1). The following conditions on a point $(m, e)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots\right.$, $e_{p}^{z}$ ) of $S_{p}^{z}(M)$ are equivalent:
(a) $(m, e)$ is integrable,
(b) $e_{\alpha}=e_{\beta}$ if $\beta$ is a permutation of $\alpha$,
(c) there exists a co-ordinate system $\left\{x_{a}\right\}$ of $M$ at $m$ such that all $x_{a}(m)=0$ and

$$
\begin{equation*}
e_{\chi}=\frac{\partial}{\partial x_{\alpha}}(m) \quad \text { for all } \alpha, \tag{1.6}
\end{equation*}
$$

(d) there exists a co-ordinate system $\left\{x_{a}\right\}$ of $M$ at $m$ such that $x_{a}^{\alpha}(m, e)=x_{a}^{\beta}(m, e)$ whenever $\beta$ is a permutation of $\alpha$,
(e) for all co-ordinate systems $\left\{x_{a}\right\}$ of $M$ at $m, x_{a}^{\alpha}(m, e)=x_{a}^{\beta}(m, e)$ whenever $\beta$ is a permutation of $\alpha$.

Proof. Lemma (1.1) says (a) implies (b). It is trivial that (c) implies (a) because, restricting the homeomorphism that defines the $x_{a}$ to its first $p$ co-ordinates gives a nonsingular $\phi$ as above for which

$$
\phi_{*} \frac{\hat{\partial}}{\partial u_{\alpha}}(q)=\frac{\partial}{\partial x_{\alpha}}(m)=e_{\alpha} .
$$

Using (1.4) and the fact that $H$ is $1: 1$ we see that $\phi^{z}(q)=(m, e)$, proving (a). Clearly (b) implies (e) since $x_{a}^{\alpha}(m, e)=e_{\alpha} x_{a}$, and (e) contains (d). Hence it will be sufficient to prove (d) implies (b) and (b) implies (c). Proof that (d) implies (b): From (d) we have $e_{\alpha} x_{a}=e_{\beta} x_{a}$ whenever $\beta$ is a permutation of $\alpha$. Let $x_{\mu}=x_{\mu_{1}} \ldots x_{\mu_{w}}$ with $1 \leq \mu_{v} \leq d$ and we shall show
(i) $e_{\beta} x_{\mu}=e_{\alpha} x_{\mu}$ if $\beta$ is a permutation of $\alpha$.

By (1.2) this will prove (b).
To prove (i) we first observe
(ii) $\pi(E \alpha)=\left(\pi^{-1} E\right)(\pi \alpha)$
for all $\alpha$ and all subsets $E$ of $\{1, \ldots, z\}, \pi$ being any permutation of $\{1, \ldots, z\}$. We also observe that when $E_{1}, \ldots, E_{w}$ run through all partitions of supp $\alpha$ then $\pi^{-1} E_{1}, \ldots, \pi^{-1} E_{w}$ run through all partitions of $\operatorname{supp} \beta$, if $\beta=\pi \alpha$. The following calculation, using (1.5), (ii) and (d), now proves (i):

$$
\begin{aligned}
e_{\beta} x_{\mu} & =\sum\left(e_{\left(\pi^{-1} E_{1}\right) \beta}\right) x_{\mu_{1}} \ldots\left(e_{\left(\pi^{-1} E_{w}\right) \beta}\right) x_{\mu_{w}} \\
& =\sum\left(e_{\left(\pi^{-1} E_{1}\right)(\pi \alpha)}\right) x_{\mu_{1}} \ldots\left(e_{\left(\pi^{-1} E_{w}\right)(\pi \alpha)}\right) x_{\mu_{w}} \\
& =\sum\left(e_{\pi\left(E_{1} \alpha\right)} x_{\mu_{1}}\right) \ldots\left(e_{\pi\left(E_{w} \alpha\right)} x_{\mu_{w}}\right) \\
& =\sum\left(e_{E_{1 \alpha}} x_{\mu}\right) \ldots\left(e_{E_{w \alpha}} x_{\mu_{w}}\right) \\
& =e_{\alpha} x_{\mu} .
\end{aligned}
$$

Proof that (b) implies (c): We induct on $z$. This is trivial for $z=1$ and we now show it for $z$ assuming it for $z-1 \leq 1$. Let ( $m, e$ ) be any point of $S_{p}^{z}(M)$. By the induction assumption there is a co-ordinate system $x_{a}^{*}$ at $m$ such that all $x_{a}^{*}(m)=0$ and
(i) $e_{\alpha^{\prime}}=\frac{\partial}{\partial x_{\alpha^{\prime}}^{*}}(m)$
for all $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right)$. For any numbers $c_{a}^{\mu}$ with $|\mu|=z$ we can define functions $x_{a}$ by
(ii) $x_{a}=x_{a}^{*}+\sum_{|\mu|=z} c_{a}^{\mu} x_{\mu}^{*}$
and these $x_{a}$ will form a co-ordinate system with all $x_{a}(m)=0$. We now determine the $c_{a}^{\mu}$ so these will satisfy (1.6). By (1.2) we see that (1.6) is equivalent to
(iii) $e_{\alpha} x_{\mu}= \begin{cases}\alpha! & \text { if } \alpha \text { is a permutation of } \mu \\ 0 & \text { if not }\end{cases}$
for all $\mu=\left(\mu_{1}, \ldots, \mu_{z}\right)$ such that $0 \leq \mu_{w} \leq d$ and all $\alpha$. We first determine the $c_{a}^{\mu}$ so that
(iv) $e_{\alpha} x_{a}=0 \quad$ if $|\alpha|=z, 1 \leq a \leq d$
and then show that (i) plus (ii) plus (iv) implies (iii).
Using (1.5) and that all $x_{a}^{*}(m)=0$ we have, if $|\mu|=|\alpha|=z$,

$$
e_{\alpha} x_{\mu}^{*}=\sum\left(e_{\alpha_{11}} x_{\mu_{1}}^{*}\right) \ldots\left(e_{\alpha_{\pi z}} x_{\mu_{z}}^{*}\right)
$$

which is clearly either $\alpha$ ! or 0 according as $\alpha$ is or is not a permutation of $\mu$. By (ii) then,

$$
e_{\alpha} x_{a}=e_{\alpha} x_{a}^{*}+c_{a}^{\alpha} \alpha!.
$$

Hence if we choose the $c_{a}^{\alpha}=-\left(e_{\alpha} x_{a}^{*}\right) / \alpha$ ! we shall have (iv), no matter how the remaining $c_{a}^{\mu}$ are chosen.

We now show that (i) plus (ii) plus (iv) implies (iii). If $\alpha_{z}=0$, thus $\alpha=\left(\alpha^{\prime}, 0\right)$ we have, by (i),

$$
\begin{aligned}
e_{\alpha} x_{\mu} & =e_{\alpha^{\prime}} x_{\mu}=e_{\alpha^{\prime}}\left(\prod_{w=1}^{z}\left(x_{\mu_{w}}^{*}+\sum_{v} c_{\mu_{w}}^{v} x_{v}^{*}\right)\right) \\
& =\frac{\partial}{\partial x_{\alpha^{\prime}}^{*}}\left(\prod_{w=1}^{z}\left(x_{\mu_{w}}^{*}+\sum_{v} c_{\mu_{w}}^{v} x_{v}^{*}\right)\right)=\frac{\partial}{\partial x_{\alpha^{\prime}}^{*}} x_{\mu}^{*}
\end{aligned}
$$

and this shows (iii) in case $\alpha_{z}=0$. If $|\alpha|<z$ then there is a permutation $\beta$ of $\alpha$ with $\beta_{z}=0$, and $e_{\alpha}=e_{\beta}$, hence (iii) also holds whenever $|\alpha|<z$. If $|\alpha|=z$ then, by (1.5),

$$
e_{\alpha} x_{\mu}=\sum\left(\left(e_{E_{1} \alpha}\right) x_{\mu_{1}}\right) \ldots\left(\left(e_{E_{z}}\right) x_{\mu_{z}}\right) .
$$

Any product here containing an $\left(e_{E_{w} \alpha}\right) x_{\mu_{w}}$ with $1<\left|E_{w} \alpha\right|<z$ will be 0 by the preceeding case and any containing such a term with $\left|E_{\alpha} w\right|=z$ will be 0 by (iv). Since $E_{1} \cup \ldots \cup E_{z}=$ $\{1, \ldots, z\}$ and $|\alpha|=z$, the only products here which do not contain an $\left(e_{E_{w z}}\right) x_{\mu_{w}}$ with $\left|E_{w} \alpha\right|>1$ are those in which all $\left|E_{w} \alpha\right|=1$. Hence

$$
e_{\alpha} x_{\mu}=\sum\left(e_{\alpha_{\alpha_{1}}} x_{\mu_{1}}\right) \ldots\left(e_{\alpha_{\pi z}} x_{\mu_{z}}\right)
$$

and this, by the result for the case $|\alpha|<z$, equals $\alpha$ ! or 0 according as $\mu$ is a permutation of $\alpha$ or not. This proves (iii) and hence the theorem.

The preceding theorem shows that the integrable points of $S_{p}^{z}(M)$ form a submanifold of dimension $d\left(p_{z}\right)$ where $p_{w}$ is the dimension of the linear space of polynomials in $p$ variables of degree $\leq w$. The integrable points form a submanifold because in any co-ordinate region with co-ordinates $\left\{x_{a}^{\alpha}\right\}$ as above, the integrable points are those for which $x_{a}^{\alpha}=x_{a}^{\beta}$ whenever $\beta$ is a permutation of $\alpha$; and the dimension is $d(p)_{z}$ because this is the number of equivalence classes of $\alpha$ 's if we make two equivalent if and only if they differ by a permutation.

Notation. We shall denote the submanifold of integrable points of $S_{p}^{z}(M)$ by $I S_{p}^{z}(M)$.
Now we give an alternative to (1.3) which is important because it enables us to reduce certain considerations to the case where $z=2$.

If $\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right) \in S_{p}^{z}(M)$ then $e_{j}^{w} e_{i}^{w-1}$ is defined from the above, for $0 \leq i, j \leq p$ and is a second order tangent vector to $S_{p}^{w-2}(M)$ at $\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}, \ldots\right.$, $e_{p}^{w-2}$ ). Our alternative to (1.3) is

$$
\left(1.3^{*}\right) \quad e_{j}^{w} e_{i}^{w-1}=e_{i}^{w} e_{j}^{w-1} \quad \text { for } \quad 0 \leq i, j \leq p, 2 \leq w \leq z .
$$

Lemma (1.2). If ( $m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}$ ) is any point of $S_{p}^{z}(M)$ then the conditions (1.3) and (1.3*) are equivalent.

Proof. If (1.3*) holds then for each $C^{\infty}$ function $h$ of $S_{p}^{w-2}(M)$ which is defined at ( $m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{w-2}, \ldots, e_{p}^{w-2}$ ) we have $e_{j}^{w} e_{i}^{w-2} h=e_{i}^{w} e_{j}^{w-1} h$. In particular, if $\left\{x_{a}\right\}$ is any co-ordinate system of $M$ such that the $x_{a}^{\alpha^{\prime \prime}}$, for $\alpha^{\prime \prime}=\left(\alpha_{1}, \ldots, \alpha_{w-2}\right)$, are defined there then $x_{a}^{\left(\alpha^{\prime \prime}, i, j\right)}=x_{a}^{\left(\alpha^{\prime \prime}, j, i\right)}$. Hence $x_{a}^{\alpha}=x_{a}^{\beta}$ if $\alpha=\left(\alpha^{\prime \prime}, i, j, 0, \ldots, 0\right)$ and $\beta=\left(\alpha^{\prime \prime}, j, i, 0, \ldots, 0\right)$. Repeated application of this shows $x_{a}^{\alpha}=x_{a}^{\beta}$ whenever $\beta$ is a permutation of $\alpha$, hence $e_{\alpha}=e_{\beta}$ by Theorem (1.1).

If (1.3) holds then we have $x_{a}^{x}=x_{a}^{\beta}$ for any $\alpha=\left(\alpha^{\prime \prime}, i, j, 0, \ldots, 0\right)$ and $\beta=$ $\left(\alpha^{\prime \prime}, j, i, 0, \ldots, 0\right)$, where $\alpha^{\prime \prime}=\left(\alpha_{1}, \ldots, \alpha_{w-2}\right)$. Hence for any such $\alpha^{\prime \prime}, e_{j}^{w} e_{i}^{w-1} x_{a}^{\alpha^{\prime \prime}}=e_{i}^{w} e_{j}^{w-1} x_{a}^{\alpha^{\prime \prime}}$. Then, by Theorem (1.1), $e_{j}^{w} e_{i}^{w-1}=e_{i}^{w} e_{j}^{w-1}$.

Lemma (1.3). If $\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right) \in S_{p}^{z}(M)$ and for each $w \leq z-2$ the point $\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{w+2}, \ldots, e_{p}^{w+2}\right)$ is integrable over $S_{p}^{w}(M)$ then $\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots\right.$, $c_{p}^{z}$ ) is integrable over $M$, i.e. lies in $I S_{p}^{z}(M)$.

Proof. Immediate from Theorem (1.1) and Lemma (1.2).

## §2. ITERATED GRASSMANN BUNDLES, THEIR INTEGRABLE POINTS, AND A REDUCTION THEOREM

We begin by defining the Grassmann bundle, $G_{p}(M)$. The elements of $G_{p}(M)$ are (by definition) all the ( $m, P$ ) where $m$ is any point of $M$ and $P$ any $p$-plane at $m$, i.e. $P$ is any $p$-dimensional subspace of $M_{m}(1 \leq p \leq d)$. Given a co-ordinate system $\left\{x_{a}\right\}$ of $M$ with domain $Q$ we now define a co-ordinate system of $G_{p}(M)$ consisting of some functions that we denote by $y_{1}^{0}, \ldots, y_{p}^{0}, \ldots, y_{a}^{j}, \ldots$ where $1 \leq a \leq d$ and $0 \leq j \leq p$. To define the domain of these functions we consider, for each $m \in Q$, the projection $\rho_{m}$ (depending on $\left\{x_{a}\right\}$ ) of $M_{m}-M_{m}$ defined by

$$
\rho_{m} \sum_{a=1}^{d} c_{a} \frac{\partial}{\partial x_{a}}(m)=\sum_{a=1}^{p} c_{a} \frac{\partial}{\partial x_{a}}(m)
$$

We define the subset $Q^{*}$ of $G_{p}(M)$ by $Q^{*}=\left[(m, P) \mid m \in Q\right.$ and $\rho_{m}$ is non-singular on $\left.P\right]$. We also denote by $\pi$ the projection of $G_{p}(M) \rightarrow M$, defined by: $\pi(m, P)=m$. We now define the functions $y_{i}^{0}$ and $y_{a}^{j}$ on $Q^{*}$ by

$$
\begin{aligned}
& y_{a}^{0}=x_{a} \circ \pi \\
& y_{r}^{i}(m, P)=d x_{r}\left(e_{i}\right)=e_{i} x_{r} \quad(1 \leq i \leq p, p+1 \leq r \leq d)
\end{aligned}
$$

where $e_{i}$ is the (unique) element of $P$ such that $\rho_{m} e_{i}=\frac{\partial}{\partial x_{i}}(m)$. By a previous convention we have also

$$
y_{r}^{0}(m, P)=e_{0} x_{r} \quad(p+1 \leq r \leq d)
$$

Note that for the above $e_{i}(1 \leq \mathrm{i} \leq p)$ we have

$$
e_{i}=\frac{\partial}{\partial x_{i}}(m)+\sum_{r} y_{r}^{i}(m, P) \frac{\partial}{\partial x_{r}}(m) .
$$

Clearly, $\operatorname{dim} G_{p}(M)=d+p(d-p)$ and $S_{p}(M)$ is a bundle over $G_{p}(M)$ whose fibre is the group of non-singular $p \times p$ matrices (with real entries), the projection map $\pi$ of this bundle being defined by $\pi\left(m, e_{1}, \ldots, e_{p}\right)=\left(m, s p\left\{e_{1}, \ldots, e_{p}\right\}\right)$, where $s p\left\{v_{1}, \ldots, v_{p}\right\}$ denotes the span of the vectors $v_{1}, \ldots, v_{p}$-a notation that will be used frequently below.

We now define the iterated Grassmann bundles, $G_{p}^{z}(M)$, for each integer $z \geq 0$. They are defined inductively, by $G_{p}^{z}(M)=G_{p}\left(G_{p}^{z-1}(M)\right)$, with the conventions that $G_{p}^{0}(M)=M$, $G_{p}^{1}(M)=G_{p}(M)$. Iterating the procedure used above for defining a co-ordinate system for $G_{p}(M)$ from a given co-ordinate system for $M$ we obtain, for each $z$, starting from a coordinate system $\left\{x_{a}\right\}$ of $M$, a co-ordinate system for $G_{p}^{z}(M)$ consisting of functions that we denote by $y_{i}^{(0, \ldots, 0)}$ and $y_{r}^{\alpha}$ where $1 \leq i \leq p, p+1 \leq r \leq d$, and $\alpha=\left(\alpha_{1}, \ldots, \alpha_{z}\right)$ as usual (i.e. the $\alpha_{w}$ integers with $0 \leq \alpha_{w} \leq p$ ). However, if $z>1$, not every point of $G_{p}^{z}(M)$ is contained in the domain of such a co-ordinate system so we call these special co-ordinate systems.

If $A$ is a non-singular map of a $p$-dimensional manifold $N$ into $M$ then it has a lift, that we denote by $A^{[1]}$, into $G_{p}(M)$, defined by $A^{[1]}(n)=\left(n, A_{*} N_{n}\right)$, and a $z$ th lift, $A^{[z]}$, defined inductively by $A^{[z]}=\left(A^{[z-1]}\right)^{[1]}$. Since we shall be concerned here with conditions for integrability at a single point we shall consider only non-singular maps of an open $Q$ in $R^{p}$ into $M$. It is trivial that if $(m, P) \in G_{p}(M)$ then there exists such an $A$ with $A^{[1]}(q)$, ( $m, P$ ) (for some $q \in Q$ ) but, as in the Stiefel case, the corresponding statement for $z \geq 2$ is false. We define an integrable point of $G_{p}^{z}(M)$ to be a point ( $\left.m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)$ for which there exists such an $A$ with $A^{[z]}(q)=\left(m, P_{1}, \ldots, P_{z}\right)$. We seek, as in the Stiefel case, an intrinsic characterization of an integrable point, and we find such a characterization in terms of the 'lift forms' discussed below. Before discussing these however we reduce the problem of higher order lifts to the problem of second order lifts by the reduction theorem given below. We now develop some lemmas necessary for the reduction theorem and for other considerations below.

As with $S_{p}^{z}(M)$, we write $y_{a}^{0}$ for $y_{a}^{(0, \ldots, 0)}$ and sometimes, for induction purposes, write $x_{a}=y_{a}^{0}$. Writing $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right)$ we have, with $\pi=\pi\left[G_{p}^{z}(M) \rightarrow G_{p}^{z-1}(M)\right]$,

$$
\begin{align*}
& y_{i}^{0}=y_{i}^{0^{\prime}} \circ \pi \quad\left(0 \in R^{z}, 0^{\prime} \in R^{z-1}\right) \\
& y_{r}^{\left(\alpha^{\prime}, 0\right)}=y_{r}^{\alpha^{\prime}} \circ \pi  \tag{2.1}\\
& \frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)+\sum_{r, z^{\prime}} y_{r}^{\left(\alpha^{\prime}, i\right)}\left(m, P_{1}, \ldots, P_{z}\right) \frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}\left(m, P_{1}, \ldots, P_{z-1}\right) \in P_{z}
\end{align*}
$$

where $1 \leq i \leq p, p+1 \leq r \leq d$, and $\left(m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)$, so $\pi\left(m, P_{1}, \ldots, P_{z}\right)=$ ( $m, P_{1}, \ldots, P_{z-1}$ ). Consequently we have, at points in the domain of $y_{i}^{0}, y_{r}^{\alpha}$,

$$
\begin{gather*}
\pi_{*} \frac{\partial}{\partial y_{i}^{0}}=\frac{\partial}{\partial y_{i}^{0^{\prime}}} \\
\pi_{*} \frac{\partial}{\partial y_{r}^{\left(\alpha^{\prime}, 0\right)}}=\frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}  \tag{2.2}\\
\pi_{*} \frac{\partial}{\partial y_{r}^{\left(\alpha^{\prime}, i\right)}}=0
\end{gather*}
$$

for $i$ and $r$ as above.
Hence if $\rho_{\left(m, P_{1}, \ldots, P_{w}\right)}$ denotes the projection on $G_{p}^{w}(M)_{\left(m, P_{1}, \ldots, P_{w}\right)}$ given by the co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\alpha^{\prime \prime}}\right\}$, onto the span of the $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{w}\right)$ then we have, on tangent spaces to $G_{p}^{w}(M)$ at points in the domain of this co-ordinate system,

$$
\begin{equation*}
\pi_{*} \circ \rho_{\left(m, P_{1}, \ldots, P_{w}\right)}=\rho_{\left(m, P_{1}, \ldots, P_{w-1}\right)} \circ \pi_{*} \tag{2.3}
\end{equation*}
$$

provided, of course, that $\rho_{\left(m, P_{1}, \ldots, P_{w-1}\right)}$ is defined from the co-ordinate system of $G_{p}^{w-1}(M)$ obtained from the same $\left\{x_{a}\right\}$.

The domains of the special co-ordinate systems do not cover $G_{p}^{z}(M)$ (if $z>1$ ) but they cover the only part of $G_{p}^{z}(M)$ that will interest us so we shall be able to make all our coordinate computations with such systems. We now characterize intrinsically that open subset of $G_{p}^{z}(M)$ that is covered by the domains of special co-ordinate systems and shall denote this open submanifold of $G_{p}^{z}(M)$ by $G_{p}^{z}(M)^{0}$. We shall now write $\pi_{z}^{G}$ for $\pi\left[G_{p}^{z}(M) \rightarrow\right.$ $\left.G_{p}^{z-1}(M)\right]$. We assign to each $\left(m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)$ a sequence $P_{1}^{0}, \ldots, P_{z}^{0}$ of subspaces of $M_{m}$, defined by

$$
P_{1}^{0}=P_{1}, \quad P_{w}^{0}=\pi_{1 *}^{G} \ldots \pi_{w-1 *}^{G} P_{w}
$$

Lemma (2.1). $G_{p}^{z}(M)^{0}$ consists of those $\left(m, P_{1}, \ldots, P_{z}\right)$ in $G_{p}^{z}(M)$ for which $\operatorname{dim} P_{1}^{0}=\ldots$ $=\operatorname{dim} P_{z}^{0}=p$. If $\left\{x_{a}\right\}$ is any co-ordinate system of $M$ at $m$ for which the associated $\rho_{m}$ is non-singular on each $P_{w}^{o}(1 \leq w \leq z)$ then $\left(m, P_{1}, \ldots, P_{z}\right)$ is in the domain of the special co-ordinate system $y_{i}^{0}, y_{r}^{\alpha}$ obtained from this $\left\{x_{a}\right\}$.

Proof. Suppose $\left(m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)$ is in the domain of the special co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ obtained from the co-ordinate system $\left\{x_{a}\right\}$ of $M$. Then $P_{w}$ is spanned by a set of vectors of the form: $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{w-1}\right)+t_{i}$, where each $t_{i}$ is a linear combination of the $\frac{\partial}{\partial y_{r}^{a^{\prime \prime}}}\left(m, P_{1}, \ldots, P_{w-1}\right)$ and $p+1 \leq r \leq d$. Hence, by (2.1), $\pi_{1 *}^{G} \ldots \pi_{w-1 *}^{G} P_{w}$ is spanned by the $\frac{\partial}{\partial x_{i}}(m)+t_{i}^{\prime}$ where $t_{i}^{\prime}$ is a linear combination of the $\frac{\partial}{\partial x_{r}}(m)$, showing that $\operatorname{dim} P_{w}^{0}=p$.

Now suppose that $\left(m, P_{1}, \ldots, P_{z}\right)$ is a point of $G_{p}^{z}(M)$ for which all the $P_{w}^{0}$ have dimension $p$. Choose a $p$-dimensional linear subspace $Q$ of $M_{m}$ and a linear complement $Q^{\prime}$ of $Q$ such that the projection of $M_{m}$ onto $Q$ given by this decomposition is non-singular on each $P_{w}^{0}$. We can choose a co-ordinate system $\left\{x_{a}\right\}$ at $m$ such that the $\frac{\partial}{\partial x_{1}}(m), \ldots, \frac{\partial}{\partial x_{p}}(m)$ span $Q$ and the $\frac{\partial}{\partial x_{r}}(m)$ span $Q^{\prime}$. We shall finish the proof of both statements of the lemma by
showing $\left(m, P_{1}, \ldots, P_{z}\right)$ is in the domain of the special co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ obtained from such an $\left\{x_{a}\right\}$, whether the $\left\{x_{a}\right\}$ are obtained after $Q$ as above, or whether $Q$ and $Q^{\prime}$ are defined from the $\left\{x_{a}\right\}$.

By the definition of $Q, P_{1}=P_{1}^{0}$ is in the domain of the co-ordinate system $\left\{y_{i}^{0}, y_{r}^{j}\right\}$ of $G_{p}(M)$. Now we show by induction on $w$ that ( $m, P_{1}, \ldots, P_{w}$ ) is in the domain of the co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\alpha^{\prime \prime}}\right\}$ of $G_{p}^{w}(M)$. Assuming this for $w-1$ we wish to prove $\rho_{\left(m, P_{1}, \ldots, P_{w-1)}\right.}$ is non-singular on $P_{w}$. By assumption $P_{w}^{0}=\pi_{1 *}^{G} \ldots \pi_{w-1 *}^{G} P_{w}$ has dimension $p$ and by the choice of $Q$ and the $x_{a}, \rho_{m}$ is non-singular on $F_{w}^{0}$, hence $\rho_{m} \circ \pi_{1 *}^{G} \ldots \pi_{w-1 *}^{G}$ is non-singular on $P_{w}$. Using (2.3) and iterating we have

$$
\rho_{m} \circ \pi_{1 *}^{G} \ldots \pi_{w-1 *}^{G}=\pi_{1 *} \ldots \pi_{w-1 *} \cap \rho_{\left(m, P_{1}, \ldots, P_{w-1}\right)}
$$

hence the right side must be non-singular on $P_{w}$, thus $\rho_{\left(m, P_{1}, \ldots, P_{w-1}\right)}$ is non-singular on $P_{w}$. This proves Lemma (2.1).

We now define a subset $S_{p}^{z}(M)^{0}$ of $S_{p}^{z}(M)$ analogous to $G_{p}^{z}(M)^{0}$ in $G_{p}^{z}(M)$. Let $\pi_{z}^{S}$ be the projection of $S_{p}^{z}(M)$ into $S_{p}^{z-1}(M): \pi_{z}^{S}\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{2}, \ldots, c_{p}^{z}\right)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}\right.$, $\left.\ldots, e_{1}^{z-1}, \ldots, e_{p}\right)$. We define, for each $(m, e)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{2}\right)$ a sequence $P_{1}^{0}, \ldots, P_{q}^{0}$ of subspaces of $M_{m}$ by

$$
\begin{aligned}
& P_{1}^{0}=\operatorname{sp}\left\{e_{1}^{1}, \ldots, e_{p}^{1}\right\} \\
& P_{w}^{0}=\operatorname{sp}\left\{\pi_{1 *}^{s} \ldots \pi_{w-1 *}^{s} e_{1}^{w}, \ldots, \pi_{1 *}^{s} \ldots \pi_{w-1 *}^{s} e_{p}^{w}\right\} .
\end{aligned}
$$

Then we define $S_{p}^{z}(M)^{0}=\left[(m, e) \in S_{p}^{z}(M) \mid\right.$ for the associated sequence of subspaces, $P_{1}^{0}, \ldots, P_{z}^{0}$, all have dimension $\left.p\right]$.
$S_{p}^{z}(M)^{0}$ is an open subset of $S_{p}^{z}(M)$ for the following reason. In $S_{p}^{z}(M)$ (unlike $G_{p}^{z}(M)$ ) every point is in the domain of a co-ordinate system obtained from a co-ordinate system $\left\{x_{a}\right\}$ of $M$. One verifies easily that in the domain of each such co-ordinate system of $S_{p}^{2}(M)$ the points of $S_{p}^{z}(M)^{0}$ are those for which each of the matrices $x_{a}^{i \delta_{w}}$ has rank $p$, i.e. for each $w(1 \leq w \leq z)$ we have such a $p \times a$ matrix $1 \leq i \leq p, 1 \leq a \leq d$; we are using the notation here: $\delta_{w}=(0, \ldots, 0,1,0, \ldots, 0)$, so $i \delta_{w}=(0, \ldots, i, \ldots, 0)$.

We now define the projection map $\pi_{z}: S_{p}^{z}(M)^{0} \rightarrow G_{p}^{z}(M)^{0}$, under which $S_{p}^{z}(M)^{0}$ will be a bundle over $G_{p}^{z}(M)^{0} . \pi_{z}$ is defined inductively by:

$$
\pi_{1}: S_{p}^{1}(M)^{0} \rightarrow G_{p}^{1}(M)^{0}: \pi_{1}\left(m, e_{1}, \ldots, e_{p}\right)=\left(m, s p\left\{e_{1}, \ldots, e_{p}\right\}\right)
$$

and if $\pi_{z-1}$ has been defined then $\pi_{z}$ is defined by

$$
\pi_{z}: S_{p}^{z}(M)^{0} \rightarrow G_{p}^{z}(M)^{0}: \pi_{z}\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)=\left(m, P_{1}, \ldots, P_{z}\right),
$$

where the $P_{i}^{w}$ are defined by

$$
\begin{aligned}
& \pi_{z-1}\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z-1}, \ldots, m e_{p}^{z-1}\right)=\left(m, P_{1}, \ldots, P_{z-1}\right) \\
& P_{z}=\operatorname{sp}\left\{\pi_{z-1 *} e_{1}^{z}, \ldots, \pi_{z-1 *} e_{p}^{z}\right\}
\end{aligned}
$$

or, more briefly,

$$
\pi_{z}(m, e)=\left(\pi_{z-1}\left(m, e^{\prime}\right), \operatorname{sp}\left\{\pi_{z-1 *} e_{1}^{z}, \ldots, \pi_{z-1 *} e_{p}^{z}\right\}\right)
$$

if $(m, e)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)$ and $\left(m, e^{\prime}\right)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z-1}, \ldots, e_{p}^{z-1}\right)$; we shall frequently use the notation ( $m, e$ ) and ( $m, e^{\prime}$ ) in this way below. For inductive
purposes we also define $\pi_{0}$ to be the identity map of $M$ onto $M$; then the definition of $\pi_{1}$ above is given, in the inductive process, from $\pi_{0}$. One verifies trivially that the sequence of subspaces $P_{1}^{0}, \ldots, P_{z}^{0}$ associated with ( $m, e$ ) is the same as that associated with $\pi_{z}(m, e)$ and this shows that $\pi_{z}$ maps $S_{\rho}^{z}(M)^{0}$ onto $G_{p}^{z}(M)^{0}$ (and not just into $G_{p}^{z}(M)$ ). The reason for introducing $S_{p}^{z}(M)^{0}$ and $G_{p}^{z}(M)^{0}$ is that $\pi_{z}$ does not exist from $S_{p}^{z}(M)$ to $G_{p}^{z}(M)$ since the spans used above are not $p$-dimensional for a general point of $S_{p}^{2}(M)$. One verifies easily that

$$
\begin{equation*}
\pi_{z-1} \circ \pi_{z}^{S}=\pi_{z}^{G} \circ \pi_{z} \tag{2.3}
\end{equation*}
$$

For the purpose of seeing how $S_{p}^{z}(M)^{0}$ 'lies over' $G_{p}^{z}(M)^{0}$ in terms of the special coordinate systems we are using, and thus for showing that $S_{p}^{z}(M)^{0}$ is a bundle over $G_{p}^{z}(M)^{0}$ we now determine the ranges of the co-ordinate systems $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ and $\left\{x_{a}^{\alpha}\right\}$ obtained from a given co-ordinate system $x_{a}$ of $M$. We shall now use the following notation. $\left\{x_{a}\right\},\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ and $\left\{x_{a}^{\alpha}\right\}$ shall be as just described. $Q, Q^{[z]}, Q^{z}$ shall be the domains of these co-ordinate systems, and $0,0^{[z]}, 0^{z}$ shall be the ranges of these co-ordinate systems, i.e. $0,0^{[z]}, 0^{z}$ are the images of $Q, Q^{[z]}, Q^{z}$ under the homeomorphisms onto Euclidean spaces which define the co-ordinate systems; we also write $Q=Q^{[0]}=Q^{0}$ and $0=0^{[0]}=0^{0}$.

Lemma (A). The range of $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ is $0 \times R^{p(d-p)} \times R^{(1+p) p(d-p)} \times \ldots \times R^{(1+p)^{z-1} p(d-p)}$. More precisely, for each choice of real numbers $\left\{b_{i}^{0}, b_{r}^{\alpha}\right\}$ such that $\left(b_{1}^{0}, \ldots, b_{d}^{0}\right) \in 0$ there is a unique $\left(m, P_{1}, \ldots, P_{z}\right) \in Q^{[z]}$ such that $y_{i}^{0}\left(m, P_{1}, \ldots, P_{z}\right)=b_{i}^{0}$ and $y_{r}^{\alpha}\left(m, P_{1}, \ldots, P_{z}\right)=b_{r}^{\alpha}$, for all $i, r, \alpha$.

Remark. The product $R^{p(d-p)} \times R^{(1+p) p(d-p)} \times \ldots \times R^{(1+p)^{z-1} p(d-p)}$ above is just the Euclidean space of dimension $(d-p)\left((1+p)^{2}-1\right)$ but it will be convenient below to consider it decomposed as above. We note that the dimension of $G_{p}^{z}(M)$ (and $\left.G_{p}^{z}(M)^{0}\right)$ is $(d-p)(p+1)^{z}+p$.

Proof. One observes for any manifold $N$ with co-ordinate system $v_{1}, \ldots, v_{e}$ that for any real numbers $b_{1}, \ldots, b_{e}, \ldots, b_{s}^{i}, \ldots(1 \leq i \leq p ; p+1 \leq s \leq e)$ such that ( $b_{1}, \ldots, b_{e}$ ) is in the range of $v_{1}, \ldots, v_{e}$, say $b_{c}=v_{c}(n)$ for all $c$, that there is a unique $p$-plane $P$ at $n$ with these co-ordinates, namely, the $P$ spanned by the

$$
\frac{\partial}{\partial v_{i}}(n)+\sum_{s=p+1}^{e} b_{s}^{i} \frac{\partial}{\partial v_{s}}(n)
$$

Iteration of this remark yields Lemma (A).
If $p$ and $q$ are integers with $p \leq q$ we shall write $R^{p \times q}$ for the open set in $R^{p q}$ consisting of all matrices ( $a_{u, i}$ ) of rank $p$, where $1 \leq i \leq p$ and $u$ ranges through some set with $q$ elements. In particular then, $R^{p \times p}$ is the full linear group.

Lemma (B). The range of $\left\{x_{a}^{\alpha}\right\}$ is $0 \times R^{p \times d} \times R^{p \times((p+1) d)} \times \ldots \times R^{p \times\left((p+1)^{z-1 d}\right)}$. More precisely, the following is true. Considering any set of real numbers $c_{a}^{\alpha}$ satisfying the following two conditions:

1. $\left(c_{1}^{0}, \ldots, c_{d}^{0}\right) \in 0$
2. For each integer $w$ the matrix $\left(c_{u i}\right)$ defined as follows has rank $p$. Let $1 \leq i \leq p$ and $u$ run through all pairs $(a, \alpha)$ such that $1 \leq a \leq d$ and $\alpha=\left(\alpha_{1}, \ldots, \alpha_{w}, 0, \ldots, 0\right)$ and let $c_{u i}=c_{a}^{(\alpha, i)}$.

Then there exists a unique $(m, e) \in S_{p}^{z}(M)$ with $x_{a}^{c}(m, e)=c_{a}^{\alpha}$ for all $a$ and $\alpha$, and the set of all such $\left\{c_{a}^{\alpha}\right\}$ is the range of $\left\{x_{a}^{\alpha}\right\}$.

Proof. This is proved by iterating the following fact. Consider any manifold $N$ with co-ordinate system $v_{1}, \ldots, v_{e}$. Consider any real numbers $c_{1}, \ldots, c_{e}, \ldots, c_{b}^{i}, \ldots(1 \leq i \leq p$, $1 \leq b \leq e)$. Suppose there is an $n \in N$ with $v_{b}(n)=c_{b}$ for all $b$ and that the matrix ( $c_{b}^{i}$ ) has rank $p$. Then there exist unique linearly independent $f_{1}, \ldots, f_{p}$ in $N_{n}$ for which $v_{b}^{i}\left(n, f_{1}, \ldots, f_{p}\right)=c_{b}^{i}$, namely,

$$
f_{i}=\sum_{b=1}^{e} c_{b}^{l} \frac{\partial}{\partial v_{b}}(n)
$$

Iteration of this shows that for any $c_{a}^{\alpha}$ as in the Lemma there is a unique ( $m, e$ ) $\in S_{p}^{z}(M)$ with all $x_{a}^{\alpha}(m, e)=c_{a}^{\alpha}$. Conversely, the $c_{b}, c_{b}^{i}$ satisfying the above clearly form the range of the co-ordinate system $v_{b}^{0}$, $v_{b}^{i}$ of $S_{p}(N)$ obtained from the given $v_{b}$ and iterating this fact gives the statement in the lemma about the range of the $x_{a}^{\alpha}$.

Remark. The dimension of $S_{p}^{z}(M)$ is $d(1+p)^{z}$.
It is clear that

$$
\pi_{z}^{-1}\left(Q^{[z]}\right) \subseteq Q^{z}
$$

and we wish to determine the range of the $x_{a}^{\alpha}$ when restricted to $\pi_{z}^{-1}\left(Q^{[2]}\right)$. For this and other reasons we wish to obtain formulas expressing the $y_{i}^{0} \circ \pi_{z}$ and $y_{r}^{\alpha} \circ \pi_{z}$ in terms of the $x_{a}^{\alpha}$, these formulas to hold on $\pi_{z}^{-1}\left(Q^{[z]}\right)$. From (2.3) we have

$$
\begin{equation*}
y_{r}^{\left(n^{\prime}, 0\right)} \circ \pi_{z}=\left(y_{r}^{\alpha^{\prime}} \circ \pi_{z-1}\right)^{0} \tag{2.4a}
\end{equation*}
$$

where $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right)$ and the zero superscript on the right denotes the lift of the function in the parenthesis from $S_{p}^{z-1}(M)^{0}$ to $S_{p}^{2}(M)^{0}$.

In the following we shall often give special consideration to the functions $x_{i}^{(0, \ldots, 0, j, 0, \ldots, 0)}$; letting $\delta_{w}=(0, \ldots, 0,1,0, \ldots, 0)$ (the 1 in the $w$ th spot) so $j \delta_{w}=(0, \ldots, j, \ldots, 0)$; then these functions are denoted by $x_{i}^{j \delta} w$, in our usual notation. We note that for each integer $w$ with $1 \leq w \leq z$ we have a $p \times p$ matrix $\left(x_{i}^{j \delta} w\right)$ when $0 \leq i, j \leq p$. Now we prove

$$
\begin{gather*}
\left(y_{r}^{\alpha^{\prime}} \circ \pi_{z-1}\right)^{j}=\sum_{i} x_{i}^{j \delta_{z}}\left(y_{r}^{\left(\alpha^{\prime}, i\right)} \circ \pi_{z}\right) \\
\left(y_{i}^{0} \circ \pi_{z-1}\right)^{j}=x_{i}^{j \delta_{z}} . \tag{2.4b}
\end{gather*}
$$

We are using here our previous notation $f^{j}$ for the functions of $S_{p}(N)$ induced from a function $f$ of $N$ and it is understood in this formula that the $y_{i}^{0}, y_{r}^{\alpha}$ of $G_{p}^{z}(M)$ and the $x_{a}^{\alpha}$ of $S_{p}^{z}(M)$ are the co-ordinate functions obtained from the same co-ordinate system $\left\{x_{a}\right\}$ of $M$. The range of the indices appearing in this formula is: $1 \leq i, j \leq p, p+1 \leq r \leq d, \alpha^{\prime}=$ $\left(\alpha_{1}, \ldots, \alpha_{z-1}\right), 0 \leq \alpha_{w} \leq p$.

Proof of $(2.4 b)$. Let $(m, e)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)$ and $\pi_{z}(m, e)=(m, P)=$ $\left(m, P_{1}, \ldots, P_{z}\right) \in Q^{[z]},\left(m, P^{\prime}\right)=\left(m, P_{1}, \ldots, P_{z-1}\right)$. Then, by definition of $\pi_{z}$ and the coordinates $y_{i}^{0}, y_{r}^{\alpha}$,

$$
\pi_{z-1 *} e_{j}^{z}=\sum_{i} a_{i j}\left[\frac{\partial}{\partial y_{i}^{0}}\left(m, P^{\prime}\right)+\sum_{\alpha^{\prime}, r} y_{r}^{\left(\alpha^{\prime}, i\right)}(m, P) \frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}\left(m, P^{\prime}\right)\right]
$$

where $\left(a_{i j}\right)$ is a non-singular $p \times p$ matrix. We determine the $a_{i j}$ by

$$
a_{i j}=\left(\pi_{z-1 *} e_{j}^{z}\right) y_{i}^{0}=e_{j}^{z}\left(y_{i}^{0} \circ \pi_{z-1}\right)=e_{j}^{z} x_{i}^{0}=x_{i}^{j \delta_{z}} .
$$

Then the preceeding formula becomes

$$
\pi_{z-1 *^{2}} e_{j}^{z}=\sum_{i} x_{i}^{j \delta_{z}}(m, e) \frac{\hat{\partial}}{\partial y_{i}^{0}}\left(m, P^{\prime}\right)+\sum_{i, \alpha^{\prime}, r} x_{i}^{j \delta_{z}}(m, e) y_{r}^{\left(\alpha^{\prime}, i\right)}(m, P) \frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}\left(m, P^{\prime}\right)
$$

Hence

$$
\begin{aligned}
& \left(\pi_{z-1 *} e_{j}^{z}\right) y_{r}^{z^{\prime}}=\sum_{i} x_{i}^{j \delta_{z}}(m, e) y_{r}^{\left(\alpha^{\prime}, i\right)}(m, P) \\
& \left(\pi_{z-1 *} e_{j}^{z}\right) y_{i}^{0}=x_{i}^{j \delta_{z}}(m, e)
\end{aligned}
$$

and these are just (2.4b) in a different notation.
We now determine the range of the co-ordinate system $\left\{x_{a}^{\alpha}\right\}$ when restricted to $\pi_{z}^{-1}\left(Q^{[z]}\right)$; we also find, for any fixed $(m, P)=\left(m, P_{1}, \ldots, P_{z}\right) \in Q^{[z]}$, the range of $\left\{x_{a}^{\alpha}\right\}$ when restricted to the 'fibre' $\pi_{z}^{-1}(m, P)$. These facts will be useful in several ways including: (1) obtaining the local product representation needed to show $S_{p}^{z}(M)^{0}$ is a bundle over $G_{p}^{z}(M)^{0}$, (2) determining the fibre of this bundle, (3) obtaining the previous two facts for the manifolds of integrable points of $S_{p}^{z}(M)$ and $G_{p}^{z}(M)$.

For the determination of these ranges it would be convenient to have explicit formulas for the $y_{i}^{0} \circ \pi_{z}$ and $y_{r}^{\alpha} \circ \pi_{z}$ in terms of the $x_{a}^{\alpha}$. We could obtain such formulas from (2.4) but the explicit formulas would be complicated; the information obtained about them in the next lemma will be sufficient for our purposes.

We now introduce certain functions $v_{i}^{\alpha}$ on $Q^{z}$, where $1 \leq i \leq p$. These $v_{i}^{\alpha}$ will depend only on the $x_{i}^{\alpha}$ (not on the $x_{r}^{\alpha}$ ). We define the $v_{i}^{\alpha}$ as follows:
(a) $v_{i}^{0}=x_{i}^{0}$;
(b) $\left(v_{i}^{j \delta_{w}}\right)=$ the inverse matrix of $\left(x_{i}^{j \delta_{w}}\right)$;
(c) for general $\alpha=\left(\alpha_{1}, \ldots, \alpha_{z}\right)$ let $\alpha_{w}$ be its first non-zero co-ordinate; each $x_{i}^{j \delta_{w}}$ is the lift of a function $x_{i j}$ of $S_{p}^{w}(M)$, hence each $v_{i}^{j \delta^{j}} w$ is the lift of a function $v_{i j}$ of $S_{p}^{w}(M)$; we define

$$
\left.v_{i}^{\alpha}(m, e)=e_{\alpha_{z}} \ldots e_{\alpha_{w+1}} v_{i \alpha_{w}}=\left(\ldots\left(v_{i \alpha_{w}}\right)^{\alpha} w+1\right) \ldots\right)^{\alpha} z(m, e)
$$

where, as usual, $(m, e)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)$.
Lemma (C). If $1 \leq u<w \leq z$ then

$$
\begin{equation*}
v_{m}^{j \delta_{u}+l \delta_{w}}=-\sum_{k, i}\left(v_{m}^{i \delta_{u}}\right) x_{i}^{k \delta_{u}+l \delta_{w}}\left(v_{k}^{j \delta_{u}}\right) \tag{2.5}
\end{equation*}
$$

where $1 \leq i, j, k, l, m \leq p$.
Proof. If $x_{i j}, v_{i j}$ are functions of $S_{p}^{u}(M)$ related to $x_{i}^{j \delta_{u}}, v_{i}^{j \delta_{k}}$ as in (c) above (but with $u$ in place of $w$ ) and if $x_{i j}^{\prime}, v_{i j}^{\prime}$ are the lifts of $x_{i j}, v_{i j}$ to $S_{p}^{w-1}(M)$ then, because $\sum_{k} x_{i k}^{\prime} v={ }_{k j}^{\prime} \delta_{i j}$,

$$
\sum_{k}\left(x_{i k}^{\prime}\right)^{l}\left(v_{k j}^{\prime}\right)^{0}+\sum_{k}\left(x_{i k}^{\prime}\right)^{0}\left(v_{k j}^{\prime}\right)^{l}=0
$$

hence, multiplying on the left by $\left(\dot{v}_{m i}\right)^{0}$ and summing on $i$,

$$
-\sum\left(v_{m i}^{\prime}\right)^{0}\left(x_{i k}^{\prime}\right)^{l}\left(v_{k j}^{\prime}\right)^{0}=\left(v_{m j}^{\prime}\right)^{l}
$$

This is (2.5) in a different notation, hence (2.5) is proved.

Lemma (D). For each $r, \alpha(p+1 \leq r \leq d)$ there exists a polynomial $Q_{r}^{\alpha}$ such that

$$
\begin{equation*}
y_{r}^{\alpha} \pi_{z}=Q_{r}^{\alpha}\left(v_{i}^{j \delta_{w}}, x_{k}^{\beta}, x_{r}^{\gamma}\right)+\sum_{\omega} v_{\omega_{1}}^{\alpha_{1} \delta_{1}} \ldots v_{\omega_{z}}^{\alpha_{z} \delta_{z}} x_{r}^{\omega} \tag{2.6}
\end{equation*}
$$

where the $w, i, j, k, \beta, \gamma, \omega$ occurring in $Q_{r}^{\alpha}$ satisfy:
(a) $1 \leq i, j, k \leq p ;$
(b) $w \in\left[t \mid \alpha_{t} \neq 0\right]$;
(c) $\beta_{t}=\gamma_{t}=\omega_{t}=0$ if $\alpha_{t}=0$;
(d) $0<|\beta| \leq|\alpha|$;
(e) $|\gamma|<|\alpha|$;
(f) $|\omega|=|\alpha|$;
(g) every term of $Q_{r}^{\alpha}$ contains an $x_{r}^{\gamma}$ as a factor.

The sum in $(2.6)$ is over all $\omega=\left(\omega_{1}, \ldots, \omega_{z}\right)$ satisfying $(c)$ and $(f)$. We use the convention here that $v_{0}^{0}=1$.

Proof. We induct on $z$. If $z=0$ we have $y_{r}^{0}=x_{r}^{0}=x_{r}$ so (2.6) holds with $Q_{r}^{0}=0$. Now suppose it holds for all $z^{\prime}<z$ and we prove it for $z$. Let $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right)$ so $\alpha=\left(\alpha^{\prime}, \alpha_{z}\right)$. If $\alpha_{z}=0$ then (2.6) follows from (2.4a) and the induction assumption. So now suppose $\alpha_{z} \neq 0$.

From (2.4b) we have, if we multiply by $v_{1}^{\alpha} z^{\delta} z$ and sum on 1 ,

$$
\begin{equation*}
y_{r}^{\alpha} \circ \pi_{z}=\sum_{l} v_{l}^{\alpha_{z} \delta_{z}}\left(y_{r}^{\alpha^{\prime}} \circ \pi_{z-1}\right)^{l} . \tag{2.7}
\end{equation*}
$$

If $|\alpha|=1$ then, since $\alpha_{z} \neq 0, \alpha^{\prime}=0$ and (2.7) gives

$$
y_{r}^{\alpha} \circ \pi_{z}=\sum_{l} v_{l}^{\alpha_{z} \delta_{z}} x_{r}^{l \delta} z
$$

proving (2.6) in this case, with $Q_{r}^{\alpha}=0$. Henceforth we suppose that $\left\{z^{\alpha} \mid \geq 2\right.$. Now using (2.7) and the induction assumption,

$$
\begin{aligned}
y_{r}^{\alpha} \circ \pi_{z} & =\sum_{l} v_{l}^{\alpha_{z} \delta_{z}} Q_{r}^{\alpha^{\prime}}\left(v_{i}^{j \delta_{w}}, x_{k}^{\beta^{\prime}}, x_{r}^{\gamma^{\prime}}\right)^{l} \\
& +\sum_{l} v_{l}^{\alpha_{z} \delta_{z}}\left(\sum_{\omega^{\prime}} v_{\omega^{\prime}}^{\alpha_{1} \delta_{1}} \ldots v_{\omega^{\prime} z-1}^{\alpha_{z}-1 \delta_{z}-1} x_{r}^{\omega^{\prime}}\right)^{l}
\end{aligned}
$$

where
( $\left.\mathrm{a}^{\prime}\right) \quad 1 \leq i, j, k, l \leq p ;$
(b') $w \in\left[t \mid \alpha_{t}^{\prime} \neq 0\right] ;$
(c') $\quad \beta_{t}^{\prime}=\gamma_{t}^{\prime}=\omega_{t}^{\prime}=0 \quad$ if $\quad \alpha_{t}^{\prime}=0$;
(d') $0<\left|\beta^{\prime}\right| \leq\left|\alpha^{\prime}\right|=|\alpha|-1$;
(e') $\quad\left|\gamma^{\prime}\right|<\left|\alpha^{\prime}\right|=|\alpha|-1$;
(f) $\quad\left|\omega^{\prime}\right|=\left|\alpha^{\prime}\right|=|\alpha|-1$,
( $g^{\prime}$ ) every term of $Q_{r}^{\alpha^{\prime}}$ contains an $x_{r}^{\gamma^{\prime}}$ as a factor.
Repeated use of the differentiation rule for products then gives
(i) $Q_{r}^{\alpha^{\prime}}\left(v_{i}^{j \delta_{w}}, x_{k}^{\beta^{\prime}}, x_{r}^{\gamma^{\prime}}\right)^{l}=\mathrm{a}$ polynomial in the $v_{i}^{j \delta_{w}}, v_{i}^{j \delta_{w}+i \delta_{z}}, x_{k}^{\beta^{\prime}}, x_{k}^{\beta^{\prime}+i \delta_{z}}, x_{r}^{\gamma^{\prime}}, x_{r}^{\gamma^{\prime}+l \delta_{z}}$
(ii) $\left(\sum_{\omega^{\prime}} v_{\omega_{1}}^{\alpha_{1} \delta_{1}} \ldots v_{\omega_{z-1}}^{\alpha_{z}-1} \delta_{z-1} x_{r}^{\omega^{\prime}}\right)^{l}=\sum_{\omega^{\prime}} v_{\omega_{1}}^{\alpha_{1} \delta_{1}} \ldots v_{\omega_{z}-1}^{\alpha_{z}-1} \delta_{z-1} x_{r}^{\omega^{\prime}+1 \delta_{z}}$ plus a polynomial in the $v_{\omega_{i}}^{\alpha_{i} \delta_{i}}, v_{\omega_{i}}^{\alpha_{i} \delta_{i}+\delta_{z}}, x_{r}^{\omega^{\prime}}$,
where the $i, j, k, l, w, \alpha^{\prime}, \beta^{\prime}, \gamma^{\prime}, \omega^{\prime}$, satisfy $\left(a^{\prime}\right)-\left(e^{\prime}\right)$.
Using $(2,5)$ we then see
(i') $Q_{r}^{\alpha^{\prime}}\left(v_{i}^{j \delta_{w}}, x_{k}^{\beta^{\prime}}, x_{r}^{\gamma^{\prime}}\right)=$ a polynomial in the $v_{i}^{j \delta_{w}}, x_{k}^{\beta^{\prime}}, x_{k}^{\beta^{\prime}+m \delta_{z}}, x_{r}^{\gamma^{\prime}}, x_{r}^{\gamma^{\prime}+1 \delta_{z}}$,
(ii') $\left(\sum_{\omega^{\prime}} v_{\omega_{1} \delta_{1}}^{\alpha_{1} \delta_{1}} \ldots v_{\omega_{z-1}}^{\alpha_{z}-1 \delta_{z-1}} x_{r}^{\omega^{\prime}}\right)^{l}=\sum_{\omega^{\prime}} v_{\omega^{\prime}}^{\alpha_{1}^{\alpha} \delta_{1}} \ldots v_{\omega_{z-1}^{\prime}}^{\alpha_{z}-1 \delta_{z-1}} x_{r}^{\omega^{\prime}+1 \delta_{z}}$ plus a polynomial in the $v_{\omega \omega^{\prime}+1}^{\alpha_{j} \delta_{i}}, x_{i}^{\alpha_{i} \delta_{i}+m \delta_{2}}, x_{r}^{\omega^{\prime}}$,
where the $i, j, k, l, w, \beta^{\prime}, \gamma^{\prime}, \omega^{\prime}$, satisfy $\left(\mathrm{a}^{\prime}\right)-\left(\mathrm{g}^{\prime}\right)$ and $1 \leq m \leq p$. Substituting these expressions in (2.7) we see that we obtain the desired form for $y_{r}^{\alpha} \circ \pi_{z}$ and that the indices satisfy (a)-(g).

The following lemma shows that $S_{p}^{z}(M)^{0}$ is locally the product of $G_{p}^{z}(M)^{0}$ by $\left(L_{p}\right)^{z} \times R^{q}$ where $L_{p}$ denotes the full linear group of $p \times p$ matrices, $\left(L_{p}\right)^{z}$ denotes the product of $L_{p}$ by itself $z$ times, and $q=p(p+1)^{z}-p-z p^{2}$. It follows, except for showing that such local product representations are properly related (a step we omit because it is not relevant to what we are doing, and is only tedious to carry out), that $S_{p}^{z}(M)^{0}$ is a fibre bundle over $G_{p}^{2}(M)^{0}$ with fibre $\left(L_{p}\right)^{z} \times R^{q}$ ( $q$ as above).

We let $0(z)$ be the open set in Euclidean space of dimension $p(p+1)^{z}-p$ defined in the following way. Consider all $i, \alpha$ with $\alpha \neq 0$ ( $i$ and $\alpha$ as usual). Define

$$
0(z)=\left[\left(c_{i}^{\alpha}\right) \mid \text { for each } w \text { in } 1 \leq w \leq z \text { the } p \times p \text { matrix }\left(c_{i}^{j \delta_{w}}\right) \text { is non-singular }\right] .
$$

Clearly $O(z)$ is diffeomorphic to $\left(L_{p}\right)^{2} \times R^{q}$ ( $q$ as above).
We also define $\pi_{z}^{\prime}: Q^{[z]} \times O(z) \rightarrow Q^{[z-1]} \times 0(z-1)$, by

$$
\pi_{z}^{\prime}\left(\left(c_{i}^{\alpha}\right),(m, P)\right)=\left(\left(c_{i}^{\alpha^{\prime}}\right),\left(m, P^{\prime}\right)\right)
$$

where $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right),(m, P)=\left(m, P_{1}, \ldots, P_{z}\right)$, and $\left(m, P^{\prime}\right)=\left(m, P_{1}, \ldots, P_{z-1}\right)$.
Lemma (2.2). For each $(m, P) \in Q^{[z]}$ and $\left(c_{i}^{\alpha}\right) \in 0(z)$ there exists a unique $(m, e) \in \pi_{z}^{-1}$ ( $Q^{[z]}$ ) such that
(a) $\pi_{z}(m, e)=(m, P) ;$
(b) $\quad x_{i}^{\alpha}(m, e)=c_{i}^{\alpha} \quad$ (for all $i, \alpha$ as above).

This defines a map $A(z)$ of $Q^{[z]} \times 0(z)$ into $\pi_{z}^{-1}\left(Q^{[z]}\right)$. This $A(z)$ is a diffeomorphism of $Q^{[z]} \times 0(z)$ onto $\pi_{z}^{-1}\left(Q^{[z]}\right)$. The set of such maps $A(z)$, as $z$ varies (but all depending on the same co-ordinate system $\left\{x_{a}\right\}$ ) is consistent in the sense that
(c) $A(z-1) \circ \pi_{z}^{\prime}=\pi_{z}^{S} \circ A(z) \quad$ on $Q^{[z]} \times 0(z)$.

Proof. We induct on $z$. For $z=0$ there is nothing to prove so we now assume the lemma for all $z^{\prime}<z$ and prove it for $z$. First we prove the existence of $A(z)$, i.e. given $(m, P) \in Q^{[z]}$ and $\left(c_{i}^{\alpha}\right) \in O(z)$, we prove the existence of an $(m, e) \in 0^{z}$ which satisfies (a) and (b). We obtain ( $m, e$ ) by determining its co-ordinates $x_{a}^{\alpha}(m, e$ ), then use Lemma (B) to ensure the existence of an ( $m, e$ ) with these co-ordinates.

So let $(m, P)=\left(m, P_{1}, \ldots, P_{z}\right) \in Q^{[z]},\left(c_{i}^{\alpha}\right) \in 0(z)$, and let $\left(m, P^{\prime}\right)=\left(m, P_{1}, \ldots, P_{z-1}\right)$
and $\left(c_{i}^{\alpha^{\prime}}\right)$ be the point of $0(z-1)$ whose co-ordinates are the numbers $\left(c_{i}^{\left(\alpha^{\prime}, 0\right)}\right)\left(\alpha^{\prime}=\left(\alpha_{1}, \ldots\right.\right.$, $\alpha_{z-1}$ ), i.e.

$$
\pi_{z}^{\prime}\left(\left(c_{i}^{\alpha}\right),(m, P)\right)=\left(\left(c_{i}^{\alpha^{\prime}}\right),\left(m, P^{\prime}\right)\right)
$$

Using the induction assumption we choose $\left(m, e^{\prime}\right) \varepsilon \pi_{z-1}^{-1}\left(Q^{[z-1]}\right)$ such that
(a') $\pi_{z-1}\left(m, e^{\prime}\right)=\left(m, P^{\prime}\right) ;$
( $\left.\mathrm{b}^{\prime}\right) \quad x_{i}^{\alpha^{\prime}}\left(m, e^{\prime}\right)=c_{i}^{\alpha^{\prime}}$.
We can now define certain of the co-ordinates of the desired ( $m, e$ ), denoting them by $b_{a}^{\alpha}$, by

$$
b_{i}^{\left(\alpha^{\prime}, 0\right)}=c_{i}^{\alpha^{\prime}}=x_{i}^{\alpha^{\prime}}\left(m, e^{\prime}\right)
$$

(i) $b_{r}^{\left(\alpha^{\prime}, 0\right)}=\alpha_{r}^{\alpha^{\prime}}\left(m, e^{\prime}\right)$

$$
b_{i}^{\alpha}=c_{i}^{\alpha} \quad \text { if } \alpha_{z} \neq 0
$$

It remains to determine those $b_{r}^{\alpha}$ with $p+1 \leq r \leq d$ and $\alpha_{z} \neq 0$. For this we shall use (2.6).
First we define numbers ( $\left.d_{i}^{j \delta_{w}}\right)$ by: $\left(d_{i}^{j \delta_{w}}\right)$ is, for each $w$, the inverse matrix of $\left(b_{i}^{j \delta_{w}}\right)$. Now we use (2.6) to define the $b_{r}^{\alpha}$ for which $\alpha_{z} \neq 0$ by induction on $|\alpha|$. We define $b_{r}^{\alpha}$ by

$$
y_{r}^{\alpha}(m, P)=Q_{r}^{\alpha}\left(d_{i}^{j \delta_{w}}, b_{k}^{\beta}, b_{r}^{\gamma}\right)+\sum_{\omega} d_{\omega_{1}}^{\alpha_{1} \delta_{1}} \ldots d_{\omega_{z}}^{\alpha_{z} \delta_{z}} b_{r}^{\sigma_{i}^{\omega}}
$$

i.e. having determined the $b_{r}^{\gamma}$ for all $|\gamma|<|\alpha|$, this formula determines $b_{r}^{\alpha}$, since the ( $d_{i}^{j \beta_{w}}$ ) are non-singular. Using Lemma (B) (and our assumption about the $c_{i}^{\alpha}$ ) it is clear that there exists a unique ( $m, e$ ) in $Q^{z}$ such that
(ii) $\quad x_{a}^{\alpha}(m, e)=b_{a}^{\alpha} \quad$ for all $a, \alpha$,

Now we show this ( $m, e$ ) satisfies (a) and (b). By (i) we know it satisfies (b). To show it satisfies (a) it is sufficient to prove both:
(iii) $\pi_{z}(m, e) \in Q^{[z]}$
(iv)

$$
\begin{aligned}
& y_{i}^{0}\left(\pi_{z}(m, e)\right)=y_{i}^{0}(m, P) \\
& y_{r}^{\alpha}\left(\pi_{z}(m, e)\right)=y_{r}^{\alpha}(m, P) .
\end{aligned}
$$

Using (2.4b) we see that

$$
\pi_{z-1 *} e_{j}^{z}=\sum c_{i}^{j \delta_{z}} \frac{\partial}{\partial y_{i}^{0}}\left(m, P^{\prime}\right)+t_{j}^{z}
$$

where $t_{j}^{z}$ is a linear combination of the $\frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}\left(m, P^{\prime}\right)$; since the $\left(c_{i}^{i \delta_{z}}\right)$ are assumed non-singular it follows that $\pi_{z}(m, e) \in Q^{[z]}$, proving (iii).

Proof of (d). We have the first statement in (iv) by

$$
y_{i}^{0}\left(\pi_{z}(m, e)\right)=y_{i}^{0}\left(\pi_{z-1}\left(m, e^{\prime}\right)\right)=y_{i}^{0}\left(m, P^{\prime}\right)=y_{i}^{0}(m, P) .
$$

We have the second statement in (iv) for those $\alpha$ of the form ( $\alpha^{\prime}, 0$ ) by

$$
\begin{aligned}
y_{r}^{\left(\alpha^{\prime}, 0\right)}\left(\pi_{z}(m, e)\right) & =y_{r}^{\alpha^{\prime}} \circ \pi_{z}^{G} \circ \pi_{z}(m, e) \\
& =y_{r}^{\alpha^{\prime}} \circ \pi_{z-1} \circ \pi_{z}^{S}(m, e) \\
& =y_{r}^{\alpha^{\prime}} \circ \pi_{z-1}\left(m, e^{\prime}\right) \\
& =y_{r}^{\alpha^{\prime}}\left(m, P^{\prime}\right) \\
& =y_{r}^{\left(\alpha^{\prime}, 0\right)}(m, P) .
\end{aligned}
$$

Finally, for the $\alpha=\left(\alpha^{\prime}, \alpha_{z}\right)$ with $\alpha_{z} \neq 0$ we have (iv) by the definition of the $b_{r}^{\alpha}$, i.e. inducting on $|\alpha|$ and using (2.6) and that definition, we prove (iv).

It is now trivial that $A(z)$ is a diffeomorphism of $Q^{[z]} \times 0(z)$ onto $\pi_{z}^{-1}\left(Q^{[z]}\right)$ and (c) is trivial; hence the lemma is proved.

Reduction Theorem. Let $\left(m, P_{1}, \ldots, P_{z}\right)$ be in $G_{p}^{z}(M)$. Then $\left(m, P_{1}, \ldots, P_{z}\right)$ is integrable if and only if, for each $w \leq z-2$, the point $\left(m, P_{1}, \ldots, P_{w+2}\right)$ is integrable over $G_{p}^{w}(M)$.

Proof. We first note that $\left(m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)^{0}$ by showing
(*) $\quad \pi_{1 *}^{G} \ldots \pi_{w-1 *}^{G} P_{w}=P_{1} \quad(1 \leq w \leq z)$.
This holds because integrability of $x\left(m, P_{1}, \ldots, P_{w}\right)$ over $G_{p}^{w-2}(M)$ clearly gives

$$
\pi_{w-1 *}^{G} P_{w}=P_{w-1}
$$

and iteration of this gives $\left({ }^{*}\right)$.
We now proceed by induction on $z$. For $z=2$ this theorem is immediate so we now assume $z>2$ and prove that if it is true for $z-1$ then it is true for $z$. Consider our given $(m, P)=\left(m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)^{0}$ as in the statement of the theorem. By the induction assumption there exists a non-singular map $A$ of an open $Q$ in $R^{p}$ into $M$ such that $A^{[z]}(q)=$ $(m, P)$. We then define $\left(m, e^{\prime}\right)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z-1}, \ldots, e_{p}^{z-1}\right)$ by $A^{z}(q)=\left(m, e^{\prime}\right)$. Because $\pi_{z-1} A^{z-1}=A^{[z-1]}$ it is clear that $\pi_{z-1}\left(m, e^{\prime}\right)=\left(m, P^{\prime}\right)$. Since $\left(m, e^{\prime}\right)$ is intcgrable, by the way it was defined, we have, for $w$ with $w+2 \leq z-1$, that ( $m, e_{1}, \ldots, e_{p}, \ldots, e_{1}^{w+2}$, $\ldots, e_{p}^{w+2}$ ) is integrable over $S_{p}^{w}(M)$.

We now proceed as follows. We shall define $e_{1}^{z}, \ldots, e_{p}^{z} \in S_{p}^{z-1}(M)_{\left(m, e^{\prime}\right)}$ such that
(a) $(m, e)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)$ is integrable over $S_{p}^{z-2}(M)$
hence, combined with the preceding, for each $w$ with $w+2 \leq z$, the point ( $m, e_{1}, \ldots$, $e_{p}, \ldots, e_{1}^{w+2}, \ldots, e_{p}^{w+2}$ ) is integrable over $S_{p}^{w}(M)$. By Lemma (1.3) this implies ( $m, e$ ) is integrable over $M$. Furthermore, the $e_{1}^{z}, \ldots, e_{p}^{z}$ will be so chosen that
(b) $\pi_{z}(m, e)=(m, P)$.

This plus integrability of ( $m, e$ ) will prove ( $m, P$ ) is integrable since if $A^{z}(q)=(m, e)$ then $A^{[z]}(q)=\pi_{z}(m, e)=(m, P)$. Hence it will be sufficient to obtain $e_{1}^{z}, \ldots, e_{p}^{z}$ so that (a) and (b) hold.

Now choose $B$, a non-singular map of an open $Q$ in $R^{p}$ into $G_{p}^{z-2}(M)$ such that

$$
\left(B^{[2]}(q)=(m, P)\right.
$$

We now wish to obtain a local cross-section $\chi_{z-2}$ of $S_{p}^{2-2}(M)^{0}$ such that both the following hold:
(i) $\chi_{z-2}\left(m, P_{1}, \ldots, P_{z-2}\right)=\left(m, e_{1}, \ldots, e_{p}, \ldots, e_{1}^{z-2}, \ldots, e_{p}^{z-2}\right)$
(ii) $\left(\chi_{z-2} \circ B\right)^{1}(q)=\left(m, e^{\prime}\right)$.

It is clear from Lemma (2.2) (iterating it) that we can achieve (i) so we suppose we have that and now show how to modify a $\chi_{z-2}$ satisfying (i) to obtain one satisfying both (i) and
(ii). Let $v_{1}, \ldots, v_{p}$ be the elements of $G_{p}^{z-2}(M)\left(m, P_{1}, \ldots, P_{z-2}\right)$ such that $B_{*}\left(\frac{\partial}{\partial u_{i}}(q)\right)=v_{i}$.

Since $S_{p}^{z-2}(M)^{0}$ is a bundle over $G_{p}^{z-2}(M)^{0}$ we can choose another cross-section $\chi_{z-2}$ satisfying (i) and
(iii) $\chi_{z-2 *} v_{i}=e_{i}^{z-1} \quad 1 \leq i \leq p$.

It is then clear that (ii) holds.
We now define $e_{1}^{z}, \ldots, e_{p}^{z}$ by

$$
e_{i}^{z}=\left(\chi_{z-2} \circ B\right)^{1} *\left(\frac{\partial}{\partial u_{i}}(q)\right)
$$

i.e., by

$$
\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right)=\left(\chi_{z-2} \circ B\right)^{2}(q)
$$

so it is clear that (a) holds. It remains to prove that (b) holds.
To prove (b) we note the general fact: if $\chi$ is any local cross-section of $S_{p}^{w}(M)^{0}$ over $G_{p}^{w}(M)^{0}$ and $B$ any non-singular map of an open $Q$ in $R^{p}$ into $G_{p}^{w}(M)^{0}$ then
(c) $B^{[1]}=\pi_{w+1} \circ\left(\chi_{w} \circ B\right)^{1}$.

This holds because if ( $m, e^{\prime \prime}$ ) $\in S_{p}^{w}(M)^{0}$ and $e_{i}^{w} \in S_{p}^{w}(M)_{\left(m, e^{\prime \prime}\right)}^{0}$
then

$$
\begin{aligned}
B_{*}\left(\frac{\partial}{\partial u_{i}}(q)\right) & =\left(\pi_{w} \circ \chi_{w} \circ B\right)_{*}\left(\frac{\partial}{\partial u_{i}}(q)\right) \\
& =\pi_{w}^{*}\left(\chi_{w} B\right)_{*}\left(\frac{\partial}{\partial u_{i}}(q)\right) .
\end{aligned}
$$

Since $B^{[1]}(q)=\left(q, s p\left\{\frac{\partial}{\partial u_{i}}(q)\right\}\right)$ and $\pi_{w+1}\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{w}, \ldots, e_{p}^{w}\right)=\left(\pi_{w}\left(m, e_{1}^{1}, \ldots\right.\right.$, $\left.e_{p}^{1}, \ldots, e_{1}^{w-1}, \ldots, e_{p}^{w-1}\right), s p\left\{\pi_{w *} e_{1}^{w}, \ldots, \pi_{w *} e_{p}^{w}\right\}$ ), this proves (c).

Applying (c) again to $\mathrm{B}^{[1]}$ gives

$$
\begin{aligned}
(m, P)=B^{[2]}(q) & =\pi_{z} \circ\left(\chi_{z-1} \circ B^{[1]}\right)^{1}(q) \\
& =\pi_{z} \circ\left(\chi_{z-1} \circ \pi_{z-1} \circ\left(\chi_{z-2} \circ B\right)^{1}\right)^{1}(q) \\
& =\pi_{z} \circ\left(\chi_{z-2} \circ B\right)^{2}(q) \\
& =\pi_{z}(m, e) .
\end{aligned}
$$

This proves (b) and hence the theorem.

## §3. INTEGRABILITY AND LIFT FORMS

The reduction theorem of the previous section reduces certain integrability considerations about points in $G_{p}^{z}(M)$ for general $z$ to the case, $z=2$. We now turn to the case, $z=2$, and find an intrinsic condition for a point of $G_{p}^{2}(M)$ to be intcgrable. Combined with the reduction theorem this will give us an intrinsic criterion for a point of $G_{p}^{z}(M)$ to be integrable. This will enable us to show that the integrable points of $G_{p}^{z}(M)$ are a submanifold of $G_{p}^{z}(M)$, and that $I S_{p}^{z}(M)$ is a bundle over that submanifold.

Our intrinsic condition for integrability will be in terms of what we call 'lift forms' so we begin by discussing these. We shall use the following terminology. By a 1 -form on $M$
we shall mean a function $\omega$ on the tangent vectors to $M$, linear on each tangent space, and defined on all tangent vectors at all points of $M$; so $\omega$ is really a function on the tangent bundle to $M$. And we use the corresponding terminology for higher degree forms. If $m \in M$ then a 1-form at $m$ will mean a linear function on $M_{m}$; a 1 -form of $M$ will mean a 1 -form on an open submanifold of $M$. And similarly for higher degree forms.

Definition. Let $(m, P) \in G_{p}(M)$. A lift form at $(m, P)$ is a 1-form $\omega$ at $(m, P)$ with the property: $\omega(t)=0$ for all $t \in G_{p}(M)_{(m, P)}$ such that $\pi_{*} t \in P$, where $\pi=\pi_{1}^{G}=\pi\left[G_{p}(M) \rightarrow M\right]$. $A$ lift form on $G_{p}(M)$ is a 1-form on $G_{p}(M)$ which is a lift at each point of $G_{p}(M)$.

We note that the set of 1-forms at $(m, P)$ which are lift forms at $(m, P)$ is the annihilator of the subspace $\pi_{1 *}^{G-1}(P)$ of $G_{p}(M)$ hence an element of $G_{p}(M)_{(m, P)}$ projects (under $\pi_{1 *}^{G}$ ) into $P$ if and only if it is annihilated by all lift forms at $(m, P)$. As a consequence we obtain

Lemma (3.1). Let $(m, P, Q) \in G_{p}^{2}(M)$ and $\pi=\pi_{1}^{G}$. Then $\pi_{*} Q=P$ if and only if $(m, P, Q)$ $\in G_{p}^{2}(M)^{0}$ and all lift forms at $(m, P)$ vanish on $Q$.

Proof. If $\pi_{*} Q=P$ then clearly $(m, P, Q) \in G_{p}(M)^{0}$, and all lift forms at $(m, P)$ vanish on $Q$, by the definition of a lift form. If all lift forms vanish on $Q$ then the above remark shows each element of $Q$ maps into $P$ and then, because $(m, P, Q) \in G_{p}^{2}(M)^{0}$ we have $\pi_{*} Q=P$.

We call the above forms 'lift forms' because of the following property: if $A^{\prime}$ is any map of an open $0 \subseteq R^{p}$ into $G_{p}(M)$ such that $\pi_{1}^{G} \circ A^{\prime}=A$ is non-singular, then
$A^{\prime}=A^{[1]}$ if and only if $\omega \circ A_{*}^{\prime}=0$ for all lift forms $\omega$.
Proof. First suppose $A^{\prime}=A^{[1]}$, hence $A^{\prime}(q)=\left(q, A_{*}\left(0_{q}\right)\right)$ for $q \in 0$. Let $\omega$ be any lift form and we wish to show that $\omega$ vanishes on $A_{*}^{\prime}(0)$. So let $t \in A_{*}^{\prime}\left(0_{q}\right)$, thus $t$ is a tangent vector at $\left(q, A_{*}\left(0_{q}\right)\right.$ ) (using $A^{\prime}=A^{[1]}$ ). Then $\pi_{1}^{G} \circ A^{\prime}=A$ implies $\pi_{1 *}^{G} A_{*}^{\prime}=A_{*}$, hence $\pi_{1 *}^{G} t \in A_{*}\left(0_{q}\right)$, so $\omega(t)=0$, by definition of a lift form. Now suppose that $\omega \circ A_{*}^{\prime}=0$ for all lift forms $\omega$. Then $A_{*}^{\prime}\left(0_{q}\right) \subseteq$ the annihilator of all lift forms, hence $A_{*}^{\prime}\left(0_{q}\right)=P^{\prime}$ is a $p$-dimensional subspace of the tangent space at $A^{\prime}(q)=(m, P)$ and projects to $P$ under $\pi_{1 *}^{G}$, i.e. $\pi_{1 *}^{G} A_{*}^{\prime}=A^{\prime}$, so $\left(\pi_{1}^{G} \circ A^{\prime}\right)_{*}=A^{\prime}$, i.e. $A^{[1]}=A^{\prime}$.

We shall denote the set of integrable points of $G_{p}^{z}(M)$ by $I G_{p}^{z}(M)$. One aim of this section is to prove

Theorem (3.1). A point $(m, P, Q) \in G_{p}^{2}(M)$ is integrable if and only if $(m, P, Q) \in G_{p}^{2}(M)^{0}$ and every $C^{\infty}$ lift form $\omega$ on $G_{p}(M)$ has the property that $\omega$ and d $\omega$ vanish on $Q$, i.e. that $\omega(t)=0$ and $d \omega(s, t)=0$ for all $s, t \in Q$.

We also wish to prove:
THEOREM (3.2). $I G_{p}^{2}(M)$ is a submanifold of $G_{p}^{2}(M)$ and $I S_{p}^{2}(M)$ is, in a natural way, a bundle over $I G_{p}^{2}(M)$.

The proofs will depend on co-ordinate expressions for the lift forms, co-ordinate conditions describing $I G_{p}^{2}(M)$, etc. so we begin by obtaining co-ordinate expressions for the lift forms. In the following $\left\{x_{a}\right\}$ will be a co-ordinate system of $M$ and $y_{i}^{0}, y_{r}^{j}$ the associated
co-ordinate system of $G_{p}(M)$, with $1 \leq i \leq p, 0 \leq j \leq p, p+1 \leq r \leq d$. Let ( $m, P$ ) be any point in the domain of these co-ordinates, $t$ any tangent vector to $G_{p}(M)$ at ( $m, P$ ), so

$$
t=\sum_{i} c_{i} \frac{\partial}{\partial y_{i}^{0}}(m, P)+\sum_{r} c_{r} \frac{\partial}{\partial y_{r}^{0}}(m, P)+\sum_{i, r} c_{i, r} \frac{\partial}{\partial y_{r}^{i}}(m, P) .
$$

Then $\pi_{1 *}^{G} t \in P$ if and only if $\pi_{1 *}^{G} t$ is a linear combination of the

$$
e_{i}=\frac{\partial}{\partial x_{i}}(m)+\sum_{r} y_{r}^{i}(m, P) \frac{\partial}{\partial x_{r}}(m)
$$

Since

$$
\pi_{1 *}^{G} \frac{\partial}{\partial y_{a}^{0}}(m, P)=\frac{\partial}{\partial x_{a}}(m)
$$

this shows that $\pi_{1}^{G} \in P$ if and only if

$$
\sum_{i=1}^{p} c_{i} y_{r}^{i}(m, P)=c_{r} \quad \text { for all } r
$$

We define $\omega_{r}$, a 1 -form of $M$, by

$$
\omega_{r}=\sum_{i=1}^{p} y_{r}^{i} d y_{i}^{0}-d y_{r}^{0}, \quad p+1 \leq r \leq d .
$$

Then

$$
\omega_{r}(t)=\sum_{i=1}^{p} y_{r}^{i}(m, P) c_{i}-c_{r}
$$

hence $\pi_{1 *}^{G} t \in P$ if and only if all $\omega_{r}(t)=0$. Hence on the domain of this co-ordinate system, $\omega$ is a lift form if and only if

$$
\omega=\sum_{r=p+1}^{d} f_{r} \omega_{r}=\sum_{r} f_{r}\left(\sum_{i} y_{r}^{i} d y_{i}^{0}-d y_{r}^{0}\right)
$$

for some functions $f_{r}$. This shows that $C^{\infty}$ lift forms exist and that if $\omega$ is a lift form at a point of $G_{p}(M)$ then it can be extended to a $C^{\infty}$ lift form on the whole of $G_{p}(M)$.

Lemma (3.2). Let $\left\{x_{a}\right\}$ be any co-ordinate system of $M$ and $\left\{y_{i}^{0}, y_{r}^{j, k}\right\}$ the associated co-ordinate system of $G_{p}^{2}(M)(1 \leq i \leq p, 0 \leq j, k \leq p, p+1 \leq r \leq d)$. For points ( $m, P, Q$ ) in the domain of this co-ordinate system each of the following conditions is equivalent:
(a) $y_{r}^{(0, j)}(m, P, Q)=y_{r}^{(j, 0)}(m, P, Q)$;
(b) $\pi_{1 *}^{G} Q=P$;
(c) all lift forms at ( $m, P$ ) vanish on $Q$.

Proof. The equivalence of (b) and (c) follows from Lemma (3.1) and the fact, from §2, that all points in the domain of a special co-ordinate system of $G_{p}^{2}(M)$ are in $G_{p}^{2}(M)^{0}$.

Now we prove the equivalence of (a) and (b). We shall use also the co-ordinate system $\left\{y_{i}^{0}, y_{r}^{j}\right\}$ of $G_{p}(M)$ obtained from $\left\{x_{a}\right\}$; and we shall use the projections $\rho_{m}, \rho_{(m, P)}$ defined in $\S 2$ from these co-ordinate systems. Throughout the calculations below we write $\pi$ for $\pi_{1}^{G}$.

From (2.2) and (2.3) we have
(i) $\left\{\begin{array}{l}\pi_{*} \frac{\partial}{\partial y_{a}^{0}}(m, P)=\frac{\partial}{\partial x_{a}}(m) \\ \pi_{*} \frac{\partial}{\partial y_{r}^{i}}(m, P)=0\end{array}\right.$
(ii) $\pi_{*} \circ \rho_{(m, P)}=\rho_{m} \circ \pi_{*}$.

We let $e_{i}$ be the element of $P$ that projects to $\frac{\partial}{\partial x_{i}}(m)$ under $\rho_{m}$ and $f_{i}$ be the element of $Q$ that projects to $\frac{\partial}{\partial y_{i}^{0}}(m, P)$ under $\rho_{(m, P)}$ so,
(iii) $e_{i}=\frac{\partial}{\partial x_{i}}(m)+\sum_{r} y_{r}^{i}(m, P) \frac{\partial}{\partial x_{r}}(m)$
(iv) $f_{i}=\frac{\partial}{\partial y_{i}^{0}}(m, P)+\sum_{r, i} y_{r}^{j, i}(m, P, Q) \frac{\partial}{\partial y_{r}^{j}}(m, P)$.

Now we"show
(v) $\pi_{*} Q=P$ if and only if $\pi_{*} f_{i}=e_{i}$ for all $i$.

Proof of $(v)$. If all $\pi_{*} f_{i}=e_{i}$ it is clear that $\pi_{*} Q=P$. Now suppose $\pi_{*} Q=P$. Then by (i), (iv) and (ii),

$$
\rho_{m}\left(\pi_{*} f_{i}\right)=\left(\pi_{*} \circ \rho_{(m, P)}\right) f_{i}=\pi_{*}\left(\frac{\partial}{\partial y_{i}^{0}}(m, P)\right)=\frac{\partial}{\partial x_{i}}(m)
$$

Since $\rho_{m}$ is non-singular on $P, f_{i} \in Q$, and $\pi_{*} Q=P$, this implies $\pi_{1 *}^{G} f_{i}=e_{i}$, proving (v).
Now we finish the proof that (a) is equivalent to (b). From (i) and (iv) we have

$$
\pi_{1 *}^{G} f_{i}=\frac{\partial}{\partial x_{i}}(m)=\sum_{r} y_{r}^{0, i}(m, P, Q) \frac{\partial}{\partial x_{r}}(m)
$$

Comparing with (iii) we see that $\pi_{1 *}^{G} f_{i}=e_{i}$ (for all $i$ ) if and only if $y_{r}^{0, i}(m, P, Q)=y_{r}^{i}(m, P)$ (for all $i, r)$ and since $y_{r}^{i}(m, P)=y_{r}^{i, 0}(m, P, Q)$ this shows that $y_{r}^{i, 0}(m, P, Q)=y_{r}^{0, i}(m, P, Q)$ (for all $i, r$ ) if and only if $\pi_{1 *}^{G} f_{i}=e_{i}$ (for all $i$ ). Using (v) this gives the equivalence of (a) and (b), and hence proves the lemma.

Lemma (3.3). Let $\left\{x_{a}\right\}$ be any co-ordinate system of $M$ and $\left\{y_{i}^{0}, y_{r}^{j, k}\right\}$ the associated co-ordinate system $G_{p}^{2}(M)$ the following conditions are equivalent:
(a) for all $C^{\infty}$ lift forms $\omega$ on $G_{p}(M)$, both $\omega$ and d $\omega$ vanish on $Q$, i.e. $\omega(s)=0$ and $d \omega(s, t)=0$ for all $s, t \in Q$;
(b) $y_{r}^{j, k}(m, P, Q)=y_{r}^{k, j}(m, P, Q)$ for all $j, k, r(0 \leq j, k \leq p, p+1 \leq r \leq d)$.

Proof. Because all $C^{\infty}$ lift forms on $G_{p}(M)$ are, locally, linear combinations with $C^{\infty}$ coefficients of the

$$
\omega_{r}=\sum_{i} y_{r}^{i} d y_{i}^{0}-d y_{r}^{0} \quad(p+1 \leq r \leq d)
$$

we see that (a) is equivalent to
(a') each $\omega_{r}$ and $d \omega_{r}$ vanishes on $Q$.
For $1 \leq j \leq p$ let $f_{j}$ be the element of $Q$ such that $\rho_{(m, P)} f_{j}=\frac{\partial}{\partial y_{j}^{0}}(m, P)$, so
(c) $d \omega_{r}=0$ on $Q$ if and only if $d \omega_{r}\left(f_{j}, f_{k}\right)=0$ for all $j, k, r$.

Clearly

$$
d \omega_{r}=\sum_{i=1}^{p} d y_{r}^{i} d y_{i}^{0}
$$

hence

$$
\begin{aligned}
d \omega_{r}\left(f_{j}, f_{k}\right) & =\sum_{i} d y_{r}^{i}\left(f_{j}\right) d y_{i}^{0}\left(f_{k}\right)-\sum_{i} d y_{r}^{i}\left(f_{k}\right) d y_{i}^{0}\left(f_{j}\right) \\
& =\sum_{i} y_{r}^{i, j}(m, P, Q) \delta_{i k}-\sum_{i} y_{r}^{i, k}(m, P, Q) \delta_{i j} \\
& =y_{r}^{k, j}(m, P, Q)-y_{r}^{j, k}(m, P, Q) .
\end{aligned}
$$

Combining Lemma (3.2) with ( $a^{\prime}$ ), (c) and this calculation we see that this lemma holds.
Theorem (3.1). If $(m, P, Q) \in G_{p}^{2}(M)$ then the following conditions are equivalent:
(1) $(m, P, Q)$ is integrable;
(2) $(m, P, Q) \in G_{p}^{2}(M)^{0}$ and for every $C^{\infty}$ lift form $\omega$ on $G_{p}(M)$, both $\omega$ and d $\omega$ vanish on $Q$;
(3) if $(m, P, Q) \in G_{p}^{2}(M)^{0}$ and $\left\{y_{i}^{0}, y_{r}^{j, k}\right\}$ is a special co-ordinate system at ( $m, P$, $Q)$ then $y_{r}^{j, k}(m, P, Q)=y_{r}^{k, j}(m, P, Q)$ for all $r, j, k(0 \leq j, k \leq p, p+1 \leq r \leq d)$.
(4) There exists an $(m, e) \in I S_{p}^{2}(M)$ such that $\pi_{2}(m, e)=(m, P, Q)$.

Proof. By Lemma (3.3), (2) and (3) are equivalent, so it will be sufficient to show that (e) implies (4), (4) implies (1) and (1) implies (2).

Proof that (3) implies (4): Applying (2.4), (2.5), (2.7) one has, in the notation of $\S 2$, if $1 \leq i, j \leq p$,

$$
\begin{align*}
& y_{r}^{i, 0} \circ \pi_{2}=\sum v_{l}^{i, 0} x_{r}^{l, 0} \\
& y_{r}^{0, i} \circ \pi_{2}=\sum v_{l}^{0, i} x_{r}^{0, l}  \tag{3.1}\\
& y_{r}^{i, j} \circ \pi_{2}=-\sum v_{l}^{0, j} v_{m}^{n, 0} x_{n}^{u, l} v_{u}^{i, 0} x_{r}^{m, 0}+\sum v_{l}^{0, j} v_{m}^{i, 0} x_{r}^{m, l}
\end{align*}
$$

(This is the explicity expression, for the case $z=2$, of (2.6)). The summation indices in the above are $l, m, n, u$ and satisfy $1 \leq l, m, n, u \leq p$. We know by Lemma (2.2) that for any choice of numbers $\left(c_{i}^{j k}\right)(1 \leq i \leq p, 0 \leq j, k \leq p)$ such that the $p \times p$ matrices $\left(c_{i}^{j, 0}\right)$ and $\left(c_{i}^{0, j}\right)$ are non-singular, there exists a unique $(m, e) \in S_{p}^{2}(M)$ such that $\pi_{2}(m, e)=(m, P, Q)$ and $x_{i}^{j, k}(m, e)=c_{i}^{j, k}$. We now consider any fixed set of such numbers $c_{i}^{j, k}$ with the additional property: $c_{i}^{j, k}=c_{i}^{k, j}$ (for all $i, j, k$ ). (For our purposes it would suffice to make a particular choice, e.g. $c_{i}^{j, 0}=c_{j}^{i, 0}=\delta_{i j}$ and all other $c_{i}^{j, k}=0$.) Using that $y_{r}^{j, k}(m, P, Q)=y_{r}^{k, j}(m, P, Q)$ and (3.1) it then follows easily that the ( $m, e$ ) obtained with this choice of the $c_{i}^{j, k}$ satisfies

$$
x_{a}^{j, k}(m, e)=x_{a}^{k, j}(m, e)
$$

for all $a, j, k$. Hence, by Theorem (1.1), $(m, e) \in I S_{p}^{2}(M)$, so (4) holds.
Proof that (4) implies (1). If $A$ is a map of an open $0 \subseteq R^{p} \rightarrow M$ which is non-singular and with $\left.A^{2}(q)=m, e\right)$ then, because $A^{[2]}=\pi_{2} \circ A^{2}$ we have $A^{[2]}(q)=(m, P, Q)$, proving (1).

Proof that (1) implies (2): Let $A$ be a non-singular map of 0 (open, in $R^{p}$ ) into $M$ with $A^{[2]}(q)=(m, P, Q)$. Let $\omega$ be any $C^{\infty}$ lift form on $G_{p}(M)$. Then, by Lemma (3.1), $\omega \circ A_{*}^{[1]}=0$ hence $d \omega \circ A_{*}^{[1]}=d\left(\omega \circ A_{*}^{[1]}\right)=0$. In particular, applied at $A^{[1]}(q)=(m, P)$, this says $\omega$ and $d \omega$ vanish on $Q$. Hence the theorem is proved.

Remark. It is clear from the proof that it is equivalent to state (3) for all co-ordinate systems or for a single one.

Lemma (3.4). $I G_{p}^{z}(M)$ is a submanifold of $G_{p}^{z}(M)^{0}$ of dimension $p+(d-p)\left(p_{z}\right)$. If $\left\{x_{a}\right\}$ is any co-ordinate system of $M$ and $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ the associated co-ordinate system of $G_{p}^{z}(M)$, with domain $Q^{[z]}$, then

$$
\begin{aligned}
& Q^{[z]} \cap I G_{p}^{z}(M)=\left[(m, P) \in Q^{[z]} \mid y_{r}^{\alpha}(m, P)=y_{r}^{\pi \alpha}(m, P)\right. \\
&\text { for all permutations } \pi \text { of }\{1, \ldots, z\}] .
\end{aligned}
$$

Proof. The first statement is immediate from the second. We prove the second by induction. For $z=0$ or 1 it is immediate; for $z=2$ it was proved in Theorem (3.1). We now assume it for $z-1 \geq 2$ and prove it for $z$. By the reduction theorem of $\S 2$ we know that $\left(m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)$ is integrable if and only if $\left(m, P_{1}, \ldots, P_{z-1}\right) \in I G_{p}^{z-1}(M)$ and ( $m, P_{1}, \ldots, P_{z}$ ) is integrable over $G_{p}^{z-2}(M)$. For points in $Q^{[z]}$ the first of these is characterized by $y_{r}^{\left(\alpha^{\prime}, 0\right)}=y_{r}^{\left(\pi^{\prime} \alpha^{\prime}, 0\right)}$ (using our induction assumption) for all $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right)$ and permutations $\pi^{\prime}$ of $\{1, \ldots, z-1\}$. And the second is characterized by $y_{r}^{\left(\alpha^{\prime \prime}, j, k\right)}=y_{r}^{\left(\alpha^{\prime \prime}, k, j\right)}$ for all $\alpha^{\prime \prime}=\left(\alpha_{1}, \ldots, \alpha_{z-2}\right)$ and all $j, k$. Together these give the desired condition for $z$, thus proving the lemma.

Definition. We define a l-form $\theta$ of $G_{p}^{z}(M)$ to be a lift form of $G_{p}^{z}(M)$ if and only if it can be expressed either as $\theta=\omega \circ\left(\pi_{z}^{G} \circ \ldots \circ \pi_{w+1}^{G}\right)_{*}$ where is a lift form of $G_{p}^{w}(M)$, considered as $G_{p}\left(G_{p}^{w-1}(M)\right)$, (for some w with $\left.1 \leq w \leq z-1\right)$, or as a lift form of $G_{p}^{2}(M)$ over $G_{p}^{z-1}(M)$.

Corollary. The point $\left(m, P_{1}, \ldots, P_{z}\right) \in G_{p}^{z}(M)$ is integrable if and only if $\theta$ and $d \theta$ vanish on $P_{z}$ for all lift forms $\theta$ of $G_{p}^{z-1}(M)$.

Proof. Immediate from Lemma (3.3) and (3.4).
For the proof of Lemma (2.2) we defined a certain open subset $0(z)$ of Euclidean space of dimension $p(p+1)^{z}-p$. We now consider the subset $0_{I}(z)$ of $0(z)$ consisting of all those $\left(c_{i}^{\alpha}\right) \in O(z)$ such that $c_{i}^{\alpha}=c_{i}^{\pi x}$ for all permutations $\pi$ of the integers 1 through $z$. So $0_{1}(z)$ is naturally diffeomorphic to the space $L p \times R^{t}$ where $L_{p}$ is, as above, the group of nonsingular $p \times p$ matrices, and $t=p\left(p_{z}-1\right)-p^{2}=p\left(p_{z}-p-1\right)$. The following lemma contains the essential part of the proof that $I S_{p}^{z}(M)$ is a bundle over $I G_{p}^{z}(M)$ with fibre $L_{p} \times R^{t}$. We omit, as before, the proof that the strip maps of the type given by the following are properly related (it is easy and not necessary for us). Again we assume a co-ordinate system $\left\{x_{a}\right\}$ given for $M$ and use, in the following lemma, its associated co-ordinate systems for $G_{p}^{z}(M)$ and $S_{p}^{z}(M)$, and with our usual notation for those. We let, as before, $Q^{[z]}$ and $Q^{z}$ be the domains of those co-ordinate systems.

Lemma (3.5). If $A(z)$ is the map of Lemma (2.2) then the restriction of $A(z)$ to $\left(Q^{[z]} \cap I G_{p}^{z}(M) \times O_{I}(z)\right)$ is a diffeomorphism of the space onto $\pi_{z}^{-1}\left(Q^{[z]}\right) \cap I S_{p}^{z}(M)$.

Proof. The proof consists in performing an induction, essentially the same as in the proof of Lemma (2.2), to show that $A(z)(m, e) \in I S_{p}^{z}(M)$ if and only if $\left(c_{i}^{z}\right) \in 0_{I}(z)$. We omit the details because of the close similarity with the previous proof.

From Lemma (3.4) we see how to obtain, for each co-ordinate system $\left\{x_{a}\right\}$ of $M$, a co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\lambda}\right\}$ of $I G_{p}^{z}(M)$, where the ranges of these indices are: $1 \leq i \leq p$, $p+1 \leq r \leq d, \lambda=\left(\lambda_{1}, \ldots, \lambda_{p}\right), 0 \leq \lambda_{i} \leq z, \sum \lambda_{i} \leq z$. We define $y_{r}^{\lambda}$ to be $y_{r}^{\alpha}$ where $\alpha$ is any superscript such that, for all $i$, the number of $\alpha_{w}$ which equal $i$ is $\lambda_{i}$. These co-ordinate systems will be used often.

## s4. HIGHER ORDER GRASSMANN BUNDLES AND THE KURANISHI DIFFEOMORPHISM THFOREM

We now wish to define the analogs of $S_{p}(M)$ and $G_{p}(M)$ for higher order contact and shall denote those for $z$ th order contact by ${ }^{2} S_{p}(M)$ and ${ }^{z} G_{p}(M)$. We shall then establish a natural diffeomorphism between ${ }^{z} G_{p}(M)$ and $I G_{p}^{z}(M)$; from our point of view this diffeomorphism carries the information that a higher order system of partial differential equations is equivalent to a system of first order partial differential equations. It also provides an essential structure on ${ }^{7} G_{p}(M)$.

We first discuss ${ }^{z} S_{p}(M)$. The elements of ${ }^{z} S_{p}(M)$ will be certain bases of the spaces of $z$ th order tangent vectors at the points of $M$ and we now explain just which bases. If $A$ is a non-singular map of the open $0 \subseteq R^{p}$ into $M$ with $A(q)=m$ then $A_{*}$ maps the bases $\frac{\partial}{\partial u_{\alpha}}(q)$ $(|\alpha| \leq z)$ of $z$ the space of $z$ th order tangent vectors to $R^{p}$ at $q$ onto a base of a $z$ th order tangent $p$-plane to $M$ at $m$ and ${ }^{2} S_{p}(M)$ is to consist of all such bases at all points of $M$. We would like to characterize such bases intrinsically, without reference to such an $A$. We shall do this in the following way, which does eliminate $A$ but depends upon $I S_{p}^{z}(M)$, which is also not intrinsic to ${ }^{2} S_{p}(M)$. In fact our definition of ${ }^{2} S_{p}(M)$ will make it only trivially different from $I S_{p}^{z}(M)$ and for this reason ${ }^{z} S_{p}(M)$ does not seem of great interest.

Each $(m, e)=\left(m, e_{1}^{1}, \ldots, e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right) \in S_{p}^{z}(M)$ gives, by $\S 1$, a family $\left\{e_{\alpha}\right\}$ of tangent vectors (of $z$ th order) to $M$ at $m$. This set will be linearly dependent and if $(m, e) \in$ $I S_{p}^{z}(M)$ then various members of this set will be equal. More precisely, if $(m, e) \in I S_{p}^{z}(M)$ then $e_{\alpha}$ will equal $e_{\beta}$ if and only if $\beta$ is a permutation of $\alpha$. For such families $\left\{e_{\alpha}\right\}$ we now make a change of notation to eliminate this redundancy, i.e. we shall change to a system of subscripts in which different subscripts will indicate different ( $z$ th order) tangent vectors. We shall always use the letter $\lambda$ to denote a $p$-tuple of integers $\left(\lambda_{1}, \ldots, \lambda_{p}\right)$ where each $\lambda_{i}$ satisfies $0 \leq \lambda_{i} \leq z$. Then to each $\alpha$ as above we assign $\lambda=\lambda(\alpha)$ where $\lambda_{i}=$ the number of $w$ for which $\alpha_{w}=i$. Clearly, if $(m, e) \in I S_{p}^{z}(M)$ then $e_{\alpha}=e_{\beta}$ if and only if $\lambda(\alpha)=\lambda(\beta)$ so we now associate to the sequence $\left\{e_{\alpha}\right\}$ the sequence $\left\{e_{\lambda}\right\}$ where the $e_{\lambda}$ are defined by $e_{\lambda}=e_{\alpha}$ if and only if $\lambda=\lambda(\alpha)$. Clearly $\left\{e_{\lambda}\right\}$ is a base of the $z$ th order tangent space to $M$ at $m$. We define ${ }^{2} S_{p}(M)$ to be the set of all bases of $z$ th order tangent spaces to $M$ at all points of $M$, i.e. ${ }^{2} S_{p}(M)$ is the set of all $\left(m,\left\{e_{\lambda}\right\}\right)$ where $\left\{e_{\lambda}\right\}$ is obtained from an $\left\{e_{\alpha}\right\}$ obtained from an $(m, e) \in I S_{z}^{p}(M)$ as above.

We now put the differentiable structure on ${ }^{2} S_{p}(M)$. Recall our map $H$ of $\S 1$, from $S_{p}^{z}(M)$ to families ( $m,\left\{e_{\alpha}\right\}$ ). Then we define a map $K$ of $I S_{p}^{z}(M)$ to ${ }^{z} S_{p}(M)$ by $K(m, e)=$ the ( $m,\left\{e_{\alpha}\right\}$ ) associated with $H(m, e)=\left(m,\left\{e_{\alpha}\right\}\right)$ by the preceding paragraph. Because $H$ is $1: 1$ it follows that $K$ is $1: 1$. We put on ${ }^{2} S_{p}(M)$ that differentiable structure carried over via $K$ from our differentiable structure on $I S_{z}^{p}(M)$. This completes our definition of ${ }^{z} S_{p}(M)$.

Now we discuss the higher order Grassmann bundles ${ }^{z} G_{p}(M)$. The elements of ${ }^{z} G_{p}(M)$ are to be of the form $\left(m,{ }^{z} P\right)$ where ${ }^{z} P$ is the 'right kind' of $z$ th order contact space at $m$. We could define the 'right kind' of a ${ }^{z} P$ to be one of the form $A_{*} V$, where $V$ is all tangent vectors of order $\leq z$ at a point of $R^{p}$, and $A$ is a non-singular map carrying that point to $m$; we could also define it to be the span of the $e_{\lambda}$ belonging to a point $\left(m,\left\{e_{\lambda}\right\}\right)$ of ${ }^{z} S_{p}(M)$. We prefer,
however, to define it through the local ring of $M$, because that is more intrinsic. Our definition will thus be in the spirit of the Chevalley definition of a tangent vector at $m$. Let $R_{m}$ be the local ring of the manifold $M$ at $m$ (i.e. the $C^{\infty}$ functions at $m$, or the ring of germs of $C^{\infty}$ functions at $m$, or an equivalent). We shall define the 'right kind' of ${ }^{2} P$ to be the space of linear functions on $R_{m}$ which annihilate the 'right kind' of ideal in $R_{m}$. We now motivate the definition of the 'right kind' of an ideal in $R_{m}$.

If $N$ is any $p$-dimensional submanifold through $m \in M$ it gives rise to a certain ideal $I_{N}$ in $R_{m}$, namely $I_{N}=$ all germs of $C^{\infty}$ functions on $M$ which vanish on $N$. We would like first an algebraic characterization of those ideals $I$ in $R_{m}$ which are of the form $I_{N}$ for some such $N$. One such characterization (though non-algebraic) is: there exists a set of generators $f_{p+1}, \ldots, f_{d}$ of $I_{N}$ whose differentials are linearly independent at $m$. This definition can be rendered more algebraic to the extent of being phrased purely in terms of the local ring $R_{m}$, in the following way.

One can first give the definition of a germ of a $C^{\infty}$ vector field and a $C^{\infty}$ differential form at $m$, in terms of $R_{m}$, i.e. defining $V_{m}=$ the algebra of derivations of $R_{m}$, and $D_{m}=$ the space of $R_{m}$ - linear maps of $\nabla_{m}$ into $R_{m}$. It is easily proved that $V_{m}$ is naturally isomorphic to the germs of $C^{\infty}$ vector fields at $m$ and $D_{m}$ to the germs of $\mathrm{C}^{\infty}$ differential 1-forms at $m$. If $f \in R_{m}$ we also define $d f \in D_{m}$ by $d f(X)=X f$ for all $X \in V_{m}$; thus $d f$ is an $R_{m}$ linear map of $V_{m}$ into $R_{m}$. Then the statement made above, that the differentials of $f_{p+1}, \ldots, f_{d}$ are linearly independent at $m$ translates to: for each choice of real numbers $c_{p+1}, \ldots, c_{d}$, not all zero, $d\left(\sum c_{r} f_{r}\right)$ does not map $V_{m}$ into $I_{m}$, where $I_{m}$ is the maximal ideal of $R_{m}$. This gives a rather weak characterization of those ideals $I$ in $R_{m}$ which are of the form $I_{N}$ for some $p$-dimensional submanifold $N$ through $m$, but we shall use it and shall call such ideals p-ideals.

Definition. A p-ideal in $R_{m}$ is an ideal I for which there exists a set of $d$-p generators $f_{p+1}, \ldots, f_{d}$ with the property that for each choice of real numbers $c_{p+1}, \ldots, c_{d}$, not all zero, $d\left(\sum c_{r} f_{r}\right)$ does not map $V_{m}$ into $I_{m}$.

It is trivial that every $p$-ideal is an $I_{N}$, where $N$ is a $p$-dimensional submanifold through. $m$. Now we note that the local ring of such an $N$ at $m$, which we shall denote by $R_{m}(N)$, can be constructed from $I_{N}$ without reference to $N$ itself, i.e. we have
(a) $\quad R_{m} / I_{N} \approx R_{m}(N)$.

We have this because the restriction homormorphism $J: R_{m} \rightarrow R_{m}(N)$, is onto and has kernel $I_{N}$. Also, under the isomorphism (a),
(b) $I_{m} / I_{N} \approx I_{m}(N)$
where $I_{m}(N)$ is the maximal ideal in $R_{m}(N)$. The space of $k$ th order differentials of $N$ at $m$ is, by definition, $I_{m}(N) / I_{m}(N)^{k+1}$. This is isomorphic to $I_{m} /\left(I_{m}^{k+1}+I_{N}\right)$ because we have the natural homomorphisms

$$
I_{m} \rightarrow I_{m}(N) \rightarrow\left(I_{m} / I_{N}\right) /\left(I_{m} / I_{N}\right)^{k+1} .
$$

The composite here is onto and its kernel is $I_{m}^{k+1}+I_{N}$, hence

$$
I_{m}(N) / I_{m}(N)^{k+1} \approx I_{m} /\left(I_{m}^{k+1}+I_{N}\right) .
$$

Thus the $z$ th order tangent space to $N$ at $m$ is isomorphic to the space of linear (over $R$ ) functions $l$ from $R_{m}$ to $R$ which have the properties: (1) $l(f)=0$ if $f$ is constant (i.e. $f$ is the germ of a function constant on a neighbourhood of $m$ ), (2) $l(f)=0$ if $f \in I_{m}^{k+1}+I_{N}$.

Definition. $A$ zth order $p$-ideal at $m$ is any ideal in $R_{m}$ of the form $I+I_{m}^{k+1}$ where $I$ is any p-ideal in $R_{m}$. A $z$ th order $p$-space at $m$ is any dual space of an $I_{m} /\left(I+I_{m}^{2+1}\right)$ where $I$ is any p-ideal in $R_{m}$. We shall sometimes denote the dual space of $I_{m} /\left(I+I_{m}^{z+1}\right)$ by $\left(I_{m} /\left(I+I_{m}^{z+1}\right)\right)^{*}$.

A linear function on $I_{m} \mid\left(I+I_{m}^{2+1}\right)$ can naturally be identified with a linear function on $I_{m}$ which vanishes on $I+I_{m}^{2+1}$. We can then extend this function uniquely to a linear function on $R_{m}$ which vanishes on $C$, where $C$ is the germs of functions constant on a neighbourhood of $m$. Thus a $z$ th order $p$-space at $m$ is essentially a subspace of the linear functions from $R_{m}$ to $R$ which is the annihilator of some $C+I+I_{m}^{z+1}$, where $I$ is any $p$-ideal at $m$. We shall usually write ${ }^{2} P$ or ${ }^{2} Q$ for a $z$ th order space. We note that such a ${ }^{2} P$ is a linear space over $R$ of dimension $(d-p)\left(p_{z}-1\right)$. We may have $I+I_{m}^{z+1}=J+I_{m}^{z+1}$ with $I$ and $J$ distinct $p$-ideals, however, in this case each $f \in I$ has the form $g+h$ where $g \in J$ and $h \in I_{m}^{2+1}$, so $I$ and $J$ have the same elements if we neglect higher orders than the $z$ th.

We define ${ }^{z} G_{p}(M)$ to be the set of all $\left(m,{ }^{z} P\right)$ where $m$ is any point of $M$ and ${ }^{2} P$ is any $z$ th order $p$-space at $m$. We have projection mappings ${ }^{z} \pi^{G}:{ }^{z} G_{p}(M) \rightarrow{ }^{z-1} G_{p}(M)$, defined by
${ }^{2} \pi^{G}\left(m,{ }^{z} P\right)=\left(m\right.$, span of all tangent vectors of order $\leq z-1$ at $m$ which lie in $\left.{ }^{2} P\right)$.
One must show for this that span of this set of tangent vectors is a $(z-1)$ st order $p$-space but this is easy because if ${ }^{z} P$ is the annihilator of $C+I+I_{m}^{z+1}$ then this set is the annihilator of $C+I+I_{m}^{z}$.

Let $\left\{z_{a}\right\}$ be any co-ordinate system of $M$ with domain $Q$ and we shall define a coordinate system for ${ }^{z} G_{p}(M)$ consisting of functions $\left\{w_{i}^{0}, w_{r}^{\lambda}\right\}$ with $i, r, \lambda$ satisfying $1 \leq i \leq p$, $p+1 \leq r \leq d, \lambda=\left(\lambda_{1}, \ldots, \lambda_{p}\right), 0 \leq \lambda_{i} \leq z$. We also define $|\lambda|=\left(\sum_{i} \lambda_{i}\right.$ and $\lambda!=\lambda_{1}!\ldots \lambda_{p}!$. Let $N$ be the submanifold of $M$ consisting of the slice, defined through this co-ordinate system by

$$
N=\left[m \in M \mid x_{p+1}(m)=\ldots=x_{d}(m)=0\right]
$$

and $\tau$ be the projection of $Q$ into $N$ defined by: if $m$ has co-ordinates $\left(c_{1}, \ldots, c_{d}\right)$ then $\tau(m)$ has co-ordinates $\left(c_{1}, \ldots, c_{p}, 0, \ldots, 0\right)$. Let ${ }^{2} Q$ be the set of all $z$ th order $p$-spaces ( $m,{ }^{z} P$ ) such that $m \in Q$ and ${ }^{2} P$ has the form

$$
{ }^{z} P=\left(I_{m} /\left(I_{m}^{Z+1}+I\right)\right)^{*}
$$

where $I$ is a $p$-ideal having a set of generators of the form

$$
f_{p+1}=x_{p+1}-g_{p+1} \circ \tau, \ldots, f_{d}=x_{d}-g_{d} \circ \tau
$$

where the $g_{p+1}, \ldots, g_{d}$ are $C^{\infty}$ functions on $N$. We then define the functions $w_{i}^{0}, w_{r}^{\lambda}|\lambda| \leq z$ by,

$$
\begin{aligned}
& w_{i}^{0}\left(m,{ }^{z} P\right)=x_{i}(m) \\
& w_{r}^{\lambda}\left(m,{ }^{z} P\right)=\frac{\partial g_{r}}{\partial x_{\lambda}}(m),|\lambda| \leq z
\end{aligned}
$$

Although neither $I$ nor the $g_{r}$ are uniquely determined by ${ }^{2} P$ (even when the $x_{a}$ are given) it is trivial that these derivatives of order $\leq z$ are independent of the possible choices of $I$ and
the $g_{r}$. Said in other words, if ${ }^{z} P=\left(I_{m} /\left(I+I_{m}^{z+1}\right)\right)^{*}$ and if $I=I_{N}$, then, for $\left(m,{ }^{z} P\right) \in{ }^{z} Q, N^{\prime}$ is locally the graph of certain functions $g_{r}$ on the slice $N$, and we define the co-ordinates of ${ }^{z} P$ to be the derivatives of these $g_{r}$ of order $\leq z$, in all co-ordinate directions of $N$. Clearly the dimension of ${ }^{z} G_{p}(M)$ is $p+(d-p)(p)_{z}$.

We have a natural projection map ${ }^{z} \pi:{ }^{z} S_{p}(M) \rightarrow{ }^{z} G_{p}(M)$, defined by

$$
{ }^{z} \pi\left(m,\left\{e_{\lambda}\right\}\right)=\left(m, s p\left\{e_{\lambda}\right\}\right) .
$$

It is clear that this span is a $z$ th order $p$-space for these $e_{\lambda}$ come from an integrable point $(m, e)$ in $S_{p}^{z}(M)$ and if $A$ is a non-singular map of $Q \subseteq R^{p}$ into $M$ with $A^{z}(q)=(m, e)$ then ${ }^{z} P=A_{*}$ (the space of tangent vectors of order $\leq z$ at $q$ ). It is also clear, in the same way, that ${ }^{z} \pi$ maps ${ }^{z} S_{p}(M)$ onto ${ }^{z} G_{p}(M)$.

Theorem (4.1). (Kinanishi factoring theorem). There exists a unique $1: 1$ map $L$ of $I G_{p}^{z}(M)$ onto ${ }^{z} G_{p}(M)$ such that

$$
L \circ \pi_{z}={ }^{z} \pi \circ K .
$$

This $L$ is a diffeomorphism and $L \circ \pi_{z}^{G}={ }^{7} \pi^{G} \circ L$ (the $L$ on the left side being that associated with $z-1$ ).

Proof. To prove the first statement we shall prove, if ( $m, e$ ) and ( $m, e^{*}$ ) are any points of $I S_{p}^{z}(M)$, that
(a) $\quad\left({ }^{2} \pi_{\circ} K\right)(m, e)=\left({ }^{2} \pi \circ K\right)\left(m, e^{*}\right)$ if and only if $\pi_{z}(m, e)-\pi_{z}\left(m, e^{*}\right)$.

This clearly gives the existence of $L$ and the fact that $L$ is $1: 1$. Because $\pi_{z}, K,{ }^{z} \pi$ are onto it is then trivial that $L$ is onto. Hence to prove the first statement of the theorem it is sufficient to prove (a).

For this we shall need the following fact: if $\left\{x_{a}\right\}$ is any co-ordinate system of $M$ and $\left\{x_{a}^{\alpha}\right\}$ and $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ the associated co-ordinate systems of $S_{p}^{z}(M)$ and $G_{p}^{z}(M)$ then, for all $\alpha$,

$$
\begin{equation*}
\frac{\partial}{\partial x_{i}^{0}}\left(y_{r}^{\alpha} \circ \pi_{z}\right)=0 \quad \text { if } \quad 1 \leq i \leq p, p+1 \leq r \leq d . \tag{i}
\end{equation*}
$$

We prove this by induction on $z$. For $z=0$ it is trivial. If true for $z-1$ then (2.6) shows it is true for $z$, hence (i) is proved.

Because $\left({ }^{2} \pi \circ K\right)(m, e)=\left(m,{ }^{2} P\right)$ where ${ }^{2} P$ is the span of the $e_{\alpha}$ obtained from ( $m, e$ ) we see that (a) is equivalent to
(a) $\operatorname{sp}\left\{e_{\alpha}\right\}=\operatorname{sp}\left\{e_{\alpha *}\right\}$ if and only if $\pi_{z}(m, e)=\pi_{z}\left(m, e^{*}\right)$.

We now choose, using Theorem (1.1), a co-ordinate system $x_{a}$ at $m$ such that
(ii)

$$
e_{\alpha}^{*}=\frac{\partial}{\partial x_{\alpha}}(m) \quad \text { for all } \alpha
$$

Because the sets $\operatorname{sp}\left\{e_{\alpha}\right\}$ and $\operatorname{sp}\left\{e_{\alpha *}\right\}$ have the same dimension we see that ( $\mathrm{a}^{\prime}$ ) is equivalent to
$\left(a^{\prime \prime}\right)$ each $e_{\alpha}$ is a linear combination of the $\frac{\partial}{\partial x_{\beta}}(m)$ if and only if $\pi_{z}(m, e)=\pi_{z}\left(m, e^{*}\right)$. Since every $e_{\alpha}$ is expressible as in (1.2) we see that ( $\mathrm{a}^{\prime \prime}$ ) is equivalent to
( $\left.\mathrm{a}^{\prime \prime \prime}\right) \quad e_{\alpha} x_{\beta}=0$ if one or more $\beta_{w}$ is greater than $p$ if and only if $\pi_{z}(m, e)=\pi\left(m, e^{*}\right)$.

Then, because the set $\left\{e_{\alpha}\right\}$ contains all the $e_{E \alpha}$, in the notation of $\S 1$, we have, still assuming that (ii) holds, ( $\mathrm{a}^{\prime \prime}$ ) is equivalent to
(aiv) $e_{\alpha} x_{r}=0$ for all $\alpha$ and $r(p+1 \leq r \leq d)$ if and only if $\pi_{z}(m, e)=\pi_{z}\left(m, e^{*}\right)$.
Proof of $\left(\mathrm{a}^{\mathrm{iv}}\right)$ : We induct on $z$. For $z=1\left(\mathrm{a}^{\mathrm{iv}}\right)$ is the statement: if $e_{1}, \ldots, e_{p}$ are linearly independent vectors in $M_{m}$ then $e_{i} x_{r}=0$ for all $r$ if and only if $\operatorname{sp}\left\{e_{i}\right\}=\operatorname{sp}\left\{\frac{\partial}{\partial x_{i}}(m)\right\}$. This is trivially true. So we now assume ( $\mathrm{a}^{\mathrm{iv}}$ ) for $z-1$ and prove it for $z$.

Clearly either of the conditions, $\pi_{z}(m, e)=\pi_{z}\left(m, e^{*}\right)$ or $\left({ }^{2} \pi_{\circ} K\right)(m, e)=\left({ }^{2} \pi \circ K\right)\left(m, e^{*}\right)$ implies ( $m, e$ ) and ( $m, e^{*}$ ) are both in the domain of the co-ordinate system $\left\{x_{a}^{\alpha}\right\}$ so we only need consider such points. Clearly from (ii), all $x_{r}^{\alpha}\left(m, e^{*}\right)=0$. Then (2.6) shows (by virtue of condition g ) of Lemma ( D ) that all $y_{r}^{\alpha}\left(\pi_{z}\left(m, e^{*}\right)\right)=0$.

If all $e_{\alpha} x_{r}=0$, i.e. all $x_{r}^{\alpha}(m, e)=0$ then (2.6) shows (again using $g$ )) that $y_{r}^{\alpha}\left(\pi_{z}(m, e)\right)=0$, hence $\pi_{z}(m, e)=\pi_{z}\left(m, e^{*}\right)$. On the other hand, if $\pi_{z}(m, e)=\pi_{z}\left(m, e^{*}\right)$ then all $y_{r}^{\alpha}\left(\pi_{z}(m, e)\right)=0$ and an easy induction on $|\alpha|$ ( $z$ being fixed), using (2.6), and condition (e) of Lemma $\mathbf{D}$, gives that all $x_{r}^{\alpha}(m, e)=0$, i.e. all $e_{\alpha} x_{r}=0$. This proves $\left(a^{\text {iv }}\right)$ and hence (a).

The remainder of Theorem (4.1) is now easily proved for one proves easily that $w_{i}^{0} \circ L=y_{i}^{0}$ and $w_{r}^{\lambda} \circ L=y_{r}^{\alpha}$ if $\lambda=\lambda(\alpha)$ (in the notation of the beginning of this section) and if these co-ordinate systems are defined, as previously, from the same $x_{a}$ of $M$. This shows $L$ is a diffeomorphism. The remaining relation is trivial. Hence Theorem (4.1) is proved.

## §5. PARTIAL DIFFERENTIAL EQUATIONS AND THEIR CHARACTERISTICS

Definition. Let $M$ be a d-dimensional manifold, $p$ any integer satisfying $1 \leq p<d$, and $z$ any integer $\leq 1$. A system of $z$ th order partial differential equations for a $p$-dimensional submanifold of $M$ is a subset $E$ of ${ }^{z} G_{p}(M)$.

Definition. A solution of a system E, as above, is a p-dimensional submanifold $N$ of $M$ whose lift ${ }^{[z]} N$, which is a submanifold of ${ }^{2} G_{p}(M)$, lies in $E$. Here ${ }^{[z]} N$ is the natural lift of $N$ into ${ }^{2} G_{p}(M)$, i.e. it is the submanifold of ${ }^{z} G_{p}(M)$ consisting of all $\left(n,{ }^{z} P\right)$ where $n \in N$ and ${ }^{z} P$ is the zth order tangent space to $N$ at $n$.

Usually the system $E$ is given as the set of common zeros of a family $\left\{F_{\gamma}\right\}$ of functions defined on a part of ${ }^{z} G_{p}(M)$ and one then says that $E$ is defined by $\left\{F_{\gamma}\right\}$. In fact, one usually defines the system to be the family $\left\{F_{\gamma}\right\}$ and then considers two systems $\left\{F_{\gamma}\right\}$ and $\left\{G_{\gamma}\right\}$ to be equivalent if they define the same $E$. Since the notion of a solution depends only on $E$ and since, if $E$ is given, we can always find a family that defines it (e.g. by choosing all functions that vanish on $E$ ) we have defined the system to be just $E$. However most theorems in this subject depend on properties of the family of functions which vanish on $E$.

We point out the relation of our notions to the classical notions. Suppose we are given a system of $z$ th order partial differential equations in the classical sense, i.e. a family of expressions

$$
\begin{equation*}
f_{\lambda}\left(u_{1}, \ldots, u_{p}, g_{1}, \ldots, g_{q}, \ldots, \frac{\partial^{\lambda} g_{r}}{\partial u_{\lambda}}, \ldots\right)=0 \tag{*}
\end{equation*}
$$

where $\lambda$ runs through some set (usually finite and most often the integers from 1 through $q$ ), $\lambda=\left(\lambda_{1}, \ldots, \lambda_{p}\right), \sum_{i} \lambda_{i} \leq z$, and

$$
\frac{\partial^{\lambda}}{\partial u_{\lambda}}=\frac{\partial^{\lambda_{1}}}{\partial u_{1}^{\lambda_{1}}} \cdots \frac{\partial^{\lambda_{p}}}{\partial u_{p}^{\lambda_{p}}}
$$

One calls the $u_{i}$ 'independent variables', calls the $g_{j}$ 'unknown functions' and defines a 'solution' to be a set of functions $g_{j}$ for which (*) holds.

We translate this to a system in our sense. Let $M=R^{p+q}$ and $u_{1}, \ldots, u_{p+q}$ be the usual co-ordinate functions on $R^{p+q}$. This co-ordinate system for $R^{p+q}$ gives us, as in $\S 4$, a co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\lambda}\right\}$ for ${ }^{z} G_{p}(M)$ (in $\S 4$ these were denoted by $\left\{w_{i}^{0}, w_{r}^{\lambda}\right\}$. Then the above functions $f_{\gamma}$ give, via this co-ordinate system, functions $F_{\gamma}$ of ${ }^{z} G_{p}(M)$, defined by

$$
F_{\lambda}=f_{\lambda}\left(y_{1}^{0}, \ldots, y_{p}^{0}, y_{p+1}^{0}, \ldots, y_{p+q}^{0}, \ldots, y_{r}, \ldots\right)
$$

(The domain of the $F_{\gamma}$ will be that part of the domain of the co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\lambda}\right\}$ which maps, under the homomorphism defining this co-ordinate system, to points in the
 hat any solution (in our sense) $N$ of this $E$ will lie in $R^{p+q}$ as the graph of a map from part of $R^{p}$ to $R^{q}$ and thus will give $q$ functions $g_{1}, \ldots, g_{q}$ of $p$ real variables, and these $g_{j}$ will be a solution (in the classical sense) of ( ${ }^{*}$ ). In fact, if $g_{1}, \ldots, g_{q}$ are any $C^{\infty}$ functions defined on an open subset 0 of $R^{p}$ then $\left(^{*}\right)$ is just an analytic expression of the fact that the graph $N$ of the map from 0 to $R^{q}$ defined by these $g_{j}$ has its lift ${ }^{[z]} N$ in the $E$ defined above, via the $F_{\gamma}$, from the $f_{\gamma}$.

The Kuranishi factoring theorem shows every system of $z$ th order partial differential equations is 'equivalent' to some system of first-order partial differential equations. For this we first note that $I G_{p}^{z}(M)$ is 'contained' in $G_{p}\left(I G_{p}^{z-1}(M)\right.$ ) sense that if ( $m, P_{1}, \ldots, P_{z}$ ) $\in$ $I G_{p}^{z}(M)$ then $P_{z}$ is tangent to the submanifold $I G_{p}^{z-1}(M)$ of $G_{p}^{z-1}(M)$ (in its definition $P_{z}$ is only given tangent to $G_{p}^{z-1}(M)$ ). For if $A$ is any non-singular map (of an open $Q \subseteq R^{p}$ into $M$ ) with $A^{[z]}(q)=\left(m, P_{1}, \ldots, P_{z}\right)$ then $A^{[z-1]}(Q) \subseteq I G_{p}^{z-1}(M)$, hence $P_{z}=\left(A^{[z-1]}\right) *\left(R_{q}^{p}\right)$ is tangent to $I G_{p}^{z-1}(M)$. Now let $E$ be any subset of ${ }^{z} G_{p}(M)$ and $E_{1}$ the corresponding subset of $I G_{p}^{z}(M)$ under our diffeomorphism theorem. Then, by the above remarks, $E_{1} \subseteq G_{p}\left(M^{\prime}\right)$ where $M^{\prime}=I G_{p}^{z-1}(M)$. If $N$ is any solution of $E$ then $N^{[z-1]}$ will be a solution of $E_{1}$ and if $N_{1}$ is any solution of $E_{1}$ then $\pi_{1}^{G} \circ \ldots \circ \pi_{z-1}^{G}\left(N_{1}\right)$ will be a solution of $E$, by the consistency part of our diffeomorphism theorem. Thus there is a natural 1:1 correspondence between solutions of the given system $E$ and solutions of the associated first order system $E_{1}$. In the most usual way of establishing such an equivalence between a $z$ th order system and a first order system one gets not a $1: 1$ correspondence between solutions in general but only a $1: 1$ correspondence between solutions of Cauchy problems for the two. That is because one usually uses, instead of our process just described, a process which passes from $E$ to the first prolongation of $E_{1}$. In that usual process one gets a quasi-linear system which our $E_{1}$ will not, in general be; by prolonging any system one gets a quasi-linear system so if that feature is desired we can obtain it by prolongation, but losing the strict equivalence between solutions of the systems. We also remark that the classical procedure introduces
certain new independent variables which, in our procedure, appear as the co-ordinate systems of $I G_{p}^{z}(M)$ derived from co-ordinate systems of $M$.

We now wish to define the characteristics of a system $E$ of $z$ th order partial differential equations. We define this for $E \subseteq{ }^{z} G_{p}(M)$ in terms of the corresponding (under our basic diffeomorphism) $E_{1} \subseteq I G_{p}^{z}(M)$. The notion of a characteristic will depend on an ( $m, P_{1}, \ldots, P_{z}$ ) $\in E_{1}$ and a $P_{z}^{\prime}$ where $P_{z}^{\prime}$ is a $(p-1)$-dimensional subspace of $P_{z}$. Essentially, the definition says the following. The collection ( $m, P_{1}, \ldots, P_{z}$ ) and $P_{z}^{\prime}$ is non-characteristic if and only if for each 'appropriate' $\left(m^{*}, P_{1}^{*}, \ldots, P_{z-1}\right)$ and $P_{z}^{* \prime}$, which are close to ( $m, P_{1}, \ldots, P_{z-1}$ ) and $P_{z}^{\prime}$, there exists a unique $P_{z}^{*}$ containing $P_{z}^{* \prime}$ such that ( $m^{*}, P_{1}^{*}, \ldots$, $\left.P_{z}^{*}\right) \in E_{1}$; and $P_{z}^{*}$ is a differentiable function of ( $m^{*}, P_{1}^{*}, \ldots, P_{z-1}^{*}$ ) and $P_{z}^{* \prime}$. By 'appropriate' we mean here: $P_{z-1}^{* \prime} \subseteq$ some $p$-dimensional $\tilde{P}_{z}$ for which $\left(m^{*}, P_{1}^{*}, \ldots, P_{z-1}^{*}, P_{z}\right) \in I G_{p}^{z}(M)$. To express this differentiability carefully and for the proof that this notion of characteristic coincides with the classical notion we introduce the following bundles.

$$
\begin{aligned}
I^{\prime} G_{p}^{z}(M)= & {\left[\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) \mid \text { there exists an }\left(m, P_{1}, \ldots, P_{z}\right) \in I G_{p}^{z}(M)\right. \text { such that }} \\
& \left.P_{z}^{\prime} \text { is a }(p-1) \text {-dimensional subspace of } P_{z}\right] \\
I^{+} G_{p}^{z}(M)= & {\left[\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right)\left(m, P_{1}, \ldots, P_{z-1}, P_{z}\right) \in I G_{p}^{z}(M) \text { and } P_{z}^{\prime}\right. \text { is a }} \\
& \left.(p-1) \text {-dimensional subspace of } P_{z}\right] .
\end{aligned}
$$

We also define

$$
\begin{aligned}
& \pi^{\prime}: I^{\prime} G_{p}^{z}(M) \rightarrow I G_{p}^{z-1}(M):\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) \rightarrow\left(m, P_{1}, \ldots, P_{z-1}\right) \\
& \pi^{+}: I^{+} G_{p}^{z}(M) \rightarrow I G_{p}^{z}(M):\left(m, P_{1}, \ldots, P_{z}^{\prime}, P_{z}\right) \rightarrow\left(m, P_{1}, \ldots, P_{z-1}, P_{z}\right) \\
& \pi^{0}: I^{+} G_{p}^{z}(M) \rightarrow I^{\prime} G_{p}^{z}(M):\left(m, P_{1}, \ldots, P_{z}^{\prime}, P_{z}\right) \rightarrow\left(m, P_{1}, \ldots, P_{z}^{\prime}\right)
\end{aligned}
$$

We now put the differentiable structure on $I^{+} G_{p}^{z}(M)$ and $I^{\prime} G_{p}^{z}(M)$ under which these become bundles with the above maps as projections of the bundles.

Let $\left\{x_{a}\right\}$ be any co-ordinate system of $M$ and we shall consider now three associated co-ordinate systems: (1) the usual associated co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\alpha^{\prime}}\right\}$ of $G_{p}^{z-1}(M)$, (2) the usual associated co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ of $G_{p}^{z}(M)$, (3) the co-ordinate system of $G_{p-1}\left(G_{p}^{z-1}(M)\right)$ associated in the usual way with the co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\alpha^{\prime}}\right\}$ of $G_{p}^{z-1}(M)$; we denote the functions in this co-ordinate system by $z_{l}^{0}, z_{p}^{0}, z_{r}^{\left(\alpha^{\prime}, 0\right)}, z_{p}^{0, l}, z_{r}^{\left(\alpha^{\prime}, l\right)}$, where $1 \leq l \leq$ $p-1, p+1 \leq r \leq d, \quad \alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right), 0 \leq \alpha_{w} \leq p$. The explicit definition of these co-ordinate functions is:

$$
\begin{aligned}
& z_{a}^{0}=y_{a}^{0} \circ \pi \\
& z_{r}^{\left(\alpha^{\prime}, 0\right)}=y_{r}^{\alpha^{\prime}} \circ \pi \quad \pi=\pi\left[G_{p-1}\left(G_{p}^{z-1}(M)\right) \rightarrow G_{p}^{z-1}(M)\right] \\
& f_{l}^{\prime}=\frac{\partial}{\partial y_{l}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)+z_{p}^{0,1}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) \frac{\partial}{\partial y_{p}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right) \\
& \\
& \quad+\sum_{r, x^{\prime}} z_{r}^{\left(\alpha^{\prime}, l\right)}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) \frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}\left(m, P_{1}, \ldots, P_{z-1}\right)
\end{aligned}
$$

where, as usual, $f_{1}^{\prime}, \ldots, f_{p-1}^{\prime}$ are the elements of $P_{z}^{\prime}$ that project to $\frac{\partial}{\partial y_{1}^{0}}, \ldots, \frac{\partial}{\partial y_{p-1}^{0}}$ at
( $m, P_{1}, \ldots, P_{z-1}$ ) under the projection $\rho^{\prime}$ defined as usual from the base $\frac{\partial}{\partial y_{i}^{0}}, \frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}$ of the tangent space to $G_{p}^{z-1}(M)$ at ( $m, P_{1}, \ldots, P_{z-1}$ ), and projecting onto the span of the first $p-1$ of the $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)$. We denote the domains of our three co-ordinate systems by $Q^{[z-1]}, Q^{[z]}$, and $Q^{\prime}$.

If ( $\left.m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right) \in I^{+} G_{p}^{z}(M)$ we say the co-ordinate system $\left\{x_{a}\right\}$ of $M$ is suitable for $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right)$ if and only if $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right)=\pi^{0}\left(M, P_{1}, \ldots\right.$, $\left.P_{z-1}, P_{z}^{\prime}, P_{z}\right)$ is in $Q^{\prime}$ and $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}\right)=\pi^{+}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right)$ is in $Q^{[z]}$, i.e. if and only if $\left(m, P_{1}, \ldots, P_{z}, P_{z}^{\prime}, P_{z}\right) \in\left(\pi^{0}\right)^{-1}\left(Q^{\prime}\right) \cap\left(\pi^{+}\right)^{-1}\left(Q^{[z]}\right)$. The existence of a suitable co-ordinate system for any $\left(m, P^{+}\right)=\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right) \in I^{+} G_{p}^{z}(M)$ is proved as follows. Let $(m, P)=\pi^{+}\left(m, P^{+}\right)=\left(m, P_{1}, \ldots, P_{z}\right)$. Choose $(m, e)=\left(m, e_{1}^{1}, \ldots\right.$, $\left.e_{p}^{1}, \ldots, e_{1}^{z}, \ldots, e_{p}^{z}\right) \in I S_{p}^{z}(M)$ such that $\pi_{z}(m, e)=(m, P)$. Let $f_{1}, \ldots, f_{p}$ be a base for $P_{z}$ such that $f_{1}, \ldots, f_{p-1}$ is a base for $P_{z}^{\prime}$. Then $f_{j}=\sum a_{i j} \pi_{z-1} * e_{i}^{z}$. Define $(m, f)=\left(m, f_{1}^{1}, \ldots\right.$, $\left.f_{p}^{1}, \ldots, f_{1}^{z}, \ldots, f_{p}^{z}\right)$ by $f_{j}^{w}=\sum a_{i j} e_{i}^{w}$. Clearly $(m, f) \in I S_{p}^{z}(M)$. Choose a co-ordinate system $\left\{x_{a}\right\}$ of $M$ such that $f_{\alpha}=\frac{\partial}{\partial x_{\alpha}}(m)$ if $|\alpha| \leq z$, where, as usual, $\left(m,\left\{f_{\alpha}\right\}\right)=H(m, f)$. It is then trivial that this $\left\{x_{a}\right\}$ is suitable for $\left(m, P^{+}\right)$and has furthermore the property: the $\frac{\partial}{\partial y_{l}^{0}}$ and $\frac{\partial}{\partial y_{i}^{0}}$ with $1 \leq i \leq p$ and $1 \leq l \leq p-1$ span $P_{z}^{\prime}, P_{z}$.

Lemma (5.1). If $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) \in Q^{\prime},\left(m, P_{1}, \ldots, P_{z}\right) \in Q^{[z]}$, and $P_{z}^{\prime} \subseteq P_{z}$ then

$$
\begin{align*}
& z_{r}^{\left(\alpha^{\prime}, l\right)}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right)=y_{r}^{\left(\alpha^{\prime}, l\right)}\left(m, P_{1}, \ldots, P_{z}\right) \\
& \quad+z_{p}^{0,1}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) y_{r}^{\left(\alpha^{\prime}, p\right)}\left(m, P_{1}, \ldots, P_{z}\right) \tag{5.1}
\end{align*}
$$

for all $\alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right), 0 \leq \alpha_{w} \leq p, 1 \leq l \leq p-1, p+1 \leq r \leq d$.
Proof. We let $f_{1}^{\prime}, \ldots, f_{p-1}^{\prime}$ be as above and $f_{1}, \ldots, f_{p}$ be the clements of $P_{z}$ such that

$$
f_{i}=\frac{\hat{\partial}}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)+\sum_{r, \alpha^{\prime}} y_{r}^{\left(\alpha^{\prime}, i\right)}\left(m, P_{1}, \ldots, P_{z-1}\right) \frac{\partial}{\partial y_{r}^{\alpha^{\prime}}}\left(m, P_{1}, \ldots, P_{z-1}\right)
$$

Because $P_{z}^{\prime} \subseteq P_{z}$ there exist numbers $c_{i l}$ such that

$$
f_{i}^{\prime}=\sum_{i=1} c_{i l} f_{i}
$$

and because of the way the $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)$ appear in the co-ordinate expressions for the $f^{\prime}$ and $f_{i}$ we see that the $c_{i l}$ are given by

$$
c_{i I}=\delta_{i l}+z_{p}^{0, l}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right)
$$

hence

$$
f_{l}^{\prime}=f_{l}+z_{p}^{0, l}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) f_{p}
$$

Writing the co-ordinate expressions for each side and equating coefficients gives (5.1).
Lemma (5.2). If $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) \in Q^{\prime}$ then $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right) \in I^{\prime} G_{p}^{z}(M)$ if and only if the following all hold at $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right)$ :
(a) $z_{r}^{\left(\alpha^{\prime}, 0\right)}=z_{r}^{\left(\beta^{\prime}, 0\right)}$ and $z_{r}^{\left(\alpha^{\prime}, l\right)}=z_{r}^{\left(\beta^{\prime}, l\right)}$ whenever $\alpha^{\prime}$ is a permutation of $\beta^{\prime}$,
(b) $z_{r}^{\left(\alpha^{\prime \prime}, 0, l\right)}=z_{r}^{\left(\alpha^{\prime \prime}, l, 0\right)}+z_{p}^{0, l_{z}^{\left(\alpha^{\prime \prime}, p, 0\right)}}$
(c) $z_{r}^{\left(\alpha^{\prime \prime}, n, l\right)}=z_{r}^{\left(\alpha^{\prime \prime}, l, n\right)}+z_{p}^{0, l} z_{r}^{\left(\alpha^{\prime \prime}, p, n\right)}-z_{p}^{0, n} z_{r}^{\left(\alpha^{\prime \prime}, p, l\right)}$
for all $l, n, r, \alpha^{\prime \prime}, \alpha^{\prime}, \beta^{\prime}$, with $1 \leq l, n \leq p-1, p+1 \leq r \leq d, \alpha^{\prime \prime}=\left(\alpha_{1}^{\prime \prime}, \ldots, \alpha_{z-2}^{\prime \prime}\right), \alpha^{\prime}=$ $\left(\alpha_{1}, \ldots, \alpha_{z-1}\right), \beta^{\prime}=\left(\beta_{1}, \ldots, \beta_{z-1}\right)$, and $0 \leq \alpha_{w}^{\prime \prime}, \alpha_{w}, \beta_{w} \leq p$.

Proof. First suppose ( $m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}$ ) $\in I^{\prime} G_{p}^{z}(M)$, and let $P_{z}^{\prime} \subseteq P_{z}$ with ( $m, P_{1}, \ldots$, $\left.P_{z}\right) \in I G_{p}^{z}(M)$. We have $z_{r}^{\left(\alpha^{\prime}, 0\right)}=y_{r}^{\alpha^{\prime}} \circ \pi$ and since $y_{r}^{\alpha^{\prime}}=y_{r}^{\beta^{\prime}}$ at $\left(m, P_{1}, \ldots, P_{z-1}\right)$ whenever $\beta^{\prime}$ is a permutation of $\alpha^{\prime}$ (since $\left(m, P_{1}, \ldots, P_{z-1}\right) \in I G_{p}^{z-1}(M)$ ) we have $z_{r}^{\left(\alpha^{\prime}, 0\right)}=z_{r}^{\left(\beta^{\prime}, 0\right)}$ for such $\alpha^{\prime}, \beta^{\prime}$. To prove $z_{r}^{\left(\alpha^{\prime}, I\right)}=z_{r}^{\left(\beta^{\prime}, l\right)}$ for such $\alpha^{\prime}, \beta^{\prime}$ recall that $P_{z}$ is tangent to $I G_{p}^{z-1}(M)$ hence the above $f^{\prime}$, since they are in $P_{z}$, are tangent to $I G_{p}^{z-1}(M)$. Since $y_{r}^{\alpha^{\prime}}=y_{r}^{\beta^{\prime}}$ on $I G_{p}^{z-1}(M)$ (if $\beta^{\prime}$ is a permutation of $\alpha^{\prime}$ ) it then follows that $f_{i}^{\prime} y_{r}^{\alpha^{\prime}}=f_{l}^{\prime} y_{r}^{\beta^{\prime}}$ and then from the co-ordinate expressions for the $f_{l}^{\prime}$ we see that $z_{r}^{\left(\alpha^{\prime}, l\right)}=z_{r}^{\left(\beta^{\prime}, l\right)}$, proving (a).

Now we prove (b) and (c) by showing
${ }^{(*)}$ (b) plus (c) is equivalent to the statement that for every $C^{\infty}$ lift from $\omega$ of $G_{p}^{z-1}(M)=G_{p}\left(G_{p}^{z-2}(M)\right)$, both $\omega$ and $d \omega$ vanish on $P_{z}^{\prime}$.
Proof of (*). Since every such $C^{\infty}$ lift form is, by section 3 , locally expressible as a linear combination of the

$$
\omega_{r}^{\alpha^{\prime \prime}}=\sum_{i=1}^{p} y_{r}^{\left(\alpha^{\prime \prime}, i\right)} d y_{i}^{0}-d y_{r}^{\left(\alpha^{\prime \prime}, 0\right)}
$$

$\left(p+1 \leq r \leq d, \alpha^{\prime \prime}=\left(\alpha_{1}^{\prime \prime}, \ldots, \alpha_{z-2}^{\prime \prime}\right), 0 \leq \alpha_{w}^{\prime \prime} \leq p\right)$ it will be sufficient to show (b) plus (c) is equivalent to
(d) all $\omega_{r}^{\alpha^{\prime \prime}}$ and $d \omega_{r}^{\alpha^{\prime \prime}}$ vanish on $P_{z}^{\prime}$.

Let $f_{1}^{\prime}, \ldots, f_{p-1}^{\prime}$ be as above so (d) is equivalent to
(e) $\omega_{r}^{\alpha^{\prime \prime}}\left(f_{l}^{\prime}\right)=d \omega_{r}^{\alpha^{\prime \prime}}\left(f_{l}^{\prime}\right), f_{n}^{\prime}=0$ for all $\alpha^{\prime \prime}, r, l, n$.

We now obtain co-ordinate expressions for these $\omega_{r}^{\alpha^{\prime \prime}}\left(f^{\prime}\right)$ and $d \omega_{r}^{\alpha^{\prime \prime}}\left(f^{\prime}, f_{n}^{\prime}\right)$. Here we will write $y_{\sigma}^{\tau}$ for $y_{\sigma}^{\tau}\left(m, P_{1}, \ldots, P_{z-1}\right)$ and $z_{\sigma}^{\tau}$ for $z_{\sigma}^{\tau}\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}\right)$. We have

$$
\begin{aligned}
& \omega^{\alpha^{\prime \prime}}\left(f^{\prime}\right)=\sum_{i=1}^{p} y_{r}^{\left(\alpha^{\prime \prime}, i\right)} d y_{i}^{0}\left(f_{l}^{\prime}\right)-d y_{r}^{\left(\alpha^{\prime \prime}, 0\right)}\left(f_{i}^{\prime}\right) \\
& =\sum_{i=1}^{p-1} y_{r}^{\left(\alpha^{\prime \prime}, i\right)} \delta_{l i}+y_{r}^{\left(\alpha^{\prime \prime}, p\right)} z_{p}^{0, I}-z_{r}^{\left(\alpha^{\prime \prime}, 0, l\right)} \\
& =y_{r}^{\left(\alpha^{\prime \prime}, l\right)}+y_{r}^{\left(\alpha^{\prime \prime}, p\right)} z_{p}^{0, l}-z_{r}^{\left(\alpha^{\prime \prime}, 0, l\right)} \\
& =z_{r}^{\left(\alpha^{\prime \prime}, l, 0\right)}+z_{r}^{\left(\alpha^{\prime \prime}, p, 0\right)} z_{p}^{0, l}-z_{r}^{\left(\alpha^{\prime \prime}, 0, l\right)} \\
& d \omega_{r}^{\alpha^{\prime \prime}}\left(f_{l}^{\prime}, f_{n}^{\prime}\right)=\left(\sum_{i=1}^{p} d y_{r}^{\left(\alpha^{\prime \prime}, i\right)} d y_{i}^{0}\right)\left(f_{l}^{\prime}, f_{n}^{\prime}\right) \\
& =\sum_{i=1}^{p} d y_{r}^{\left(\alpha^{\prime,}\right)}\left(f_{l}^{\prime}\right) d y_{i}^{0}\left(f_{n}^{\prime}\right)-\sum_{i=1}^{p} d y_{r}^{\left(\alpha^{\prime \prime}, i\right)}\left(f_{n}^{\prime}\right) d y_{i}^{0}\left(f_{l}^{\prime}\right) \\
& =\sum_{i=1}^{p-1} z_{r}^{\left(\alpha^{\prime \prime}, i, l\right)} \delta_{i n}+z_{r}^{\left(\alpha^{\prime \prime}, p, l\right)} z_{p}^{0, n}-\sum_{i=1}^{p-1} z_{r}^{\left(\alpha^{\prime \prime}, i, n\right)} \delta_{i l}-z_{r}^{\left(\alpha^{\prime \prime}, p, h\right)} z_{p}^{0, l} \\
& =z_{r}^{\left(\alpha^{\prime \prime}, n, l\right)}+z_{r}^{\left(\alpha^{\prime \prime}, p, l\right)} z_{p}^{0, n}-z_{r}^{\left(\alpha^{\prime \prime}, 1, n\right)}-z_{r}^{\left(\alpha^{\prime \prime}, p, n\right)} z_{p}^{0, l}
\end{aligned}
$$

From these formulae it is clear that (d) is equivalent to (b) plus (c), hence $\left(^{*}\right)$ is proved. Thus we have proved that if ( $m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}$ ) $\in I^{\prime} G_{p}^{z}(M)$ then (a), (b), (c) hold.

Now suppose that (a), (b), (c) hold. Because $z_{r}^{\left(\alpha^{\prime}, 0\right)}=z_{r}^{\left(\beta^{\prime}, 0\right)}$ whenever $\beta^{\prime}$ is a permutation of $\alpha^{\prime}$ we see that $y_{r}^{\alpha^{\prime}}=y_{r}^{\beta^{\prime}}$ for such $\alpha^{\prime}, \beta^{\prime}$, hence $\left(m, P_{1}, \ldots, P_{z-1}\right) \in I G_{p}^{z-1}(M)$. Using $\left(^{*}\right)$ we see that for all $C^{\infty}$ lift forms $\omega$ of $G_{p}\left(G_{p}^{z-2}(M)\right)$ both $\omega$ and $d \omega$ vanish on $P_{z}^{\prime}$. Since the dimension of a maximal subspace on which such a set of functions vanishes is independent of the subspace we conclude that $P_{z}^{\prime}$ is contained in some $P_{z}$, of dimension $p$, on which all such $\omega$ and $d \omega$ vanish. Then $\left(m, P_{1}, \ldots, P_{z} \quad 1, P_{z}\right) \in I G_{p}^{z}(M)$, by our reduction theorem, hence $\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right) \in I^{\prime} G_{p}^{z}(M)$.

We remark that a part of (a), namely that $z_{r}^{\left(\alpha^{\prime}, l\right)}=z_{r}^{\left(\beta^{\prime}, l\right)}$ if $\beta^{\prime}$ is a permutation of $\alpha^{\prime}$, has not been used here. That is because it is dependent on the other conditions-this being essentially a consequence of our reduction theorem.

Now we shall put the differentiable structures on $I^{\prime} G_{p}^{z}(M)$ and $I^{+} G_{p}^{z}(M)$. Let ( $m, P^{+}$) be any point of $I^{+} G_{p}^{z}(M),\left(m, P^{\prime}\right)=\pi^{0}\left(m, P^{+}\right)$, and $(m, P)=\pi^{+}\left(m, P^{+}\right)$. Let $\left\{x_{u}\right\}$ be any co-ordinate system of $M$ suitable for ( $m, P^{+}$). Let $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ and $\left\{z_{i}^{0}, z_{r}^{\left(\alpha^{\prime}, 0\right)}, z_{p}^{0, l}, z_{r}^{\left(\alpha^{\prime}, l\right)}\right\}$ be the associated co-ordinate systems of $G_{p}^{z}(M)$ and $G_{p-1}\left(G_{p}^{z-1}(M)\right.$ described above, with domains $Q^{[z]}$ and $Q^{\prime}$. We define $Q^{+}=\left(\pi^{0}\right)^{-1}\left(Q^{\prime}\right) \cap\left(\pi^{+}\right)^{-1}\left(Q^{[z]}\right)$. Then we have on $Q^{+}$:

$$
\begin{align*}
& z_{i}^{0} \circ \pi^{0}=y_{i}^{0} \circ \pi^{+} \\
& z_{r}^{\left(a^{\prime}, 0\right)} \circ \pi^{0}=y_{r}^{\left(a^{\prime}, 0\right)} \circ \pi^{+}  \tag{5.3}\\
& z_{r}^{\left(\alpha^{\prime}, l\right)} \circ \pi^{0}=y_{r}^{\left(\alpha^{\prime}, l\right)} \circ \pi^{+}+\left(z_{p}^{0, l} \circ \pi^{0}\right)\left(y_{r}^{\left(\alpha^{\prime}, p\right)} \circ \pi^{+}\right)
\end{align*}
$$

for $1 \leq i \leq p, 1 \leq l \leq p-1, p+1 \leq r \leq d, \alpha^{\prime}=\left(\alpha_{1}, \ldots, \alpha_{z-1}\right), 0 \leq \alpha_{w} \leq p$. The first two lines here are trivial and the third is just (5.1) in another notation.

We shall now choose functions which will (by definition) make up a co-ordinate system for $I^{\prime} G_{p}^{z}(M)$. Their domain will be $Q^{\prime \prime}=Q^{\prime} \cap I^{\prime} G_{p}^{z}(M)$ and the functions will be obtained by choosing an 'independent set on $Q^{\prime \prime}$ from among the $z_{i}^{0}, z_{r}^{\left(\alpha^{\prime}, 0\right)}, z_{p}^{0, l}, z_{r}^{\left(\alpha^{\prime}, l\right)}$, and restricting them to $Q^{\prime \prime}$; the others among these will then be determined on $Q^{\prime \prime}$ by (5.2). First however we make a change of notation, similar to that made in section 4 in passing from the $e_{\alpha}$ to the $e_{\lambda}$. This time however we must be more careful since (5.2) does not give invariance under all permutations of the superscripts.

Recall as before that for each $\alpha=\left(\alpha_{1}, \ldots, \alpha_{z}\right)$ we have defined $\lambda(\alpha)=\left(\lambda_{1}, \ldots, \lambda_{p}\right)$ by: $\lambda_{i}=$ the number of $w$ for which $\alpha_{w}=i$. Recall we have also defined, for such $\alpha$ and $\lambda$, $|\alpha|=$ the number of $w$ such that $\alpha_{w} \neq 0,|\lambda|=\sum_{i} \lambda_{i}$, so $|\alpha|=|\lambda(\alpha)|$. We now consider all $\lambda=\left(\lambda_{1}, \ldots, \lambda_{p}\right)$ such that $|\lambda| \leq z$ and $\lambda_{p}<z$. Each such $\lambda$ is of the form $\lambda(\alpha)$ for some $\alpha$ satisfying both: (i) $\alpha_{z}<p$, (ii) $\alpha_{z} \leq \min \left(\alpha_{1}, \ldots, \alpha_{z-1}\right)$. And by (5.2) (a), if $\lambda=\lambda(\alpha)=\lambda(\beta)$ with $\alpha$ and $\beta$ both satisfying (i) and (ii) then $z_{r}^{\alpha}=z_{r}^{\beta}$ on $I^{\prime} G_{p}^{z}(M)$. Hence we may now define $z_{r}^{\lambda}$ for all $\lambda=\left(\lambda_{1}, \ldots, \lambda_{p}\right)$ such that $|\lambda| \leq z$ and $\lambda_{p}<z$, by

$$
z_{r}^{2}=z_{r}^{\alpha} \mid Q^{\prime \prime} \text { if } \lambda=\lambda(\alpha), \alpha_{z}<p, \alpha_{z} \leq \min \left(\alpha_{1}, \ldots, \alpha_{z-1}\right)
$$

where $1 \leq i \leq p, 1 \leq l \leq p-1, p+1 \leq r \leq d, \lambda=\left(\lambda_{1}, \ldots, \lambda_{p}\right)$, and $|\lambda| \leq z, \lambda_{p}<z$. We now define the functions $z_{i}^{0}, z_{p}^{0, I}, z_{r}^{\lambda}$ for such values of the indices by taking $z_{r}^{\lambda}$ as above and
taking $z_{i}^{0}$ and $z_{p}^{0,1}$ to be the restrictions of our previous $z_{i}^{0}$ and $z_{p}^{0, l}$ to $Q^{\prime \prime}$. (This introduces some inconscquential ambiguity about the domains of $z_{i}^{0}$ and $z_{p}^{0, l}$.) It is easily proved that the $\left\{z_{i}^{0}, z_{p}^{0, l}, z_{r}^{\lambda}\right\}$ provide a $1: 1$ map of $Q^{\prime \prime}$ onto an open set in Euclidean space of dimension $p+(p-1)+(d-p)\left[(p)_{z}-1\right]$. Furthermore, by facts proved in section 3 , the range of this co-ordinate system is the product of the range of $\left\{x_{a}\right\}$ by an entire Euclidean space. By this process we get for each co-ordinate system $\left\{x_{a}\right\}$ of $M$ which is suitable for any point of $I^{+} G_{p}^{z}(M)$ such a map to a Euclidean space, and the collection of all these makes $I^{\prime} G_{p}^{z}(M)$ into a manifold since it is easily checked that any two are $C^{\infty}$ related. This defines our differentiable structure on $I^{\prime} G_{p}^{z}(M)$, making it a manifold of dimension $3 p-d-1+$ $(d-p)(p)_{z}$.

Now we put the differentiable structure on $I^{+} G_{p}^{z}(M)$. Starting again with our coordinate system $\left\{x_{a}\right\}$ of $M$ we shall define what will be, by definition, a co-ordinate system of $I^{+} G_{p}^{z}(M)$, with domain $Q^{+}$. We shall use here the associated co-ordinate system $\left\{y_{i}^{0}, y_{r}^{\lambda}\right\}$ of $I G_{p}^{z}(M)$ obtained from the $\left\{y_{i}^{0}, y_{r}^{\alpha}\right\}$ associated with $\left\{x_{a}\right\}$.

We define the functions which shall constitute this co-ordinate system by

$$
\begin{align*}
w_{i}^{0} & =y_{i}^{0} \circ \pi^{+}=z_{i}^{0} \circ \pi^{0} \\
w_{r}^{\lambda} & =y_{r}^{\lambda} \circ \pi^{+}  \tag{5.4}\\
w_{p}^{0, t} & =z_{p}^{0, l} \circ \pi^{0}
\end{align*}
$$

these being defined on $Q^{+}$for $1 \leq i \leq p, 1 \leq l \leq p-1, p+1 \leq r \leq d, \lambda=\left(\lambda_{1}, \ldots, \lambda_{p}\right)$, where the $\lambda_{i}$ are integers $\geq 0$ and $|\lambda|=\sum_{i} \lambda_{i} \leq z$. Again, by section 3, the range of this coordinate system will be the range of $\left\{x_{a}\right\}$ times a full Euclidean space. One proves easily that this set of functions provides a $1: 1$ map to a Euclidean space and that the set of all such maps are $C^{\infty}$ related thus defining our differentiable structure on $I^{+} G_{p}^{z}(M)$ and making it into a manifold of dimension $2 p-1+(d-p)(p)_{z}$. From (5.3) we have, on $Q^{+}$,

$$
\begin{align*}
& z_{r}^{\lambda} \circ \pi^{0}=w_{r}^{\lambda} \quad \text { if } \quad|\lambda|<z  \tag{5.5}\\
& z_{r}^{\lambda} \circ \pi^{0}=w_{r}^{\lambda}+w_{p}^{0, l^{2}} w_{r}^{\lambda-\delta_{r}}+\delta_{p} \quad \text { if } \quad|\lambda|=z
\end{align*}
$$

where $\lambda_{p}<z$ and $l=\min \left[i \mid \lambda_{i} \neq 0\right]$. Here $\delta_{i}=$ the $i$ th canonical unit vector in $R^{p}$ : $\delta_{i}=(0, \ldots, 0,1,0, \ldots, 0)$.

From (5.4) and (5.5) we see that if we fix ( $m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}$ ) and vary $P_{z}$ containing $P_{z}^{\prime}$ then this variation is described, locally, by the co-ordinates $w_{r}^{z \delta} p(p+1 \leq r \leq d)$. For if ( $m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}$ ) is fixed then all the $w_{i}^{0}, w_{p}^{0, l}$, and $w_{r}^{\lambda}$ with $|\lambda|<z$ are fixed and so are the $z_{r}^{\lambda}$ with $|\lambda|=z$ but $\lambda_{p}<z$. The last line in (5.5) then shows that varying $P_{z}$ containing $P_{z}^{\prime}$ is equivalent to varying the $w_{r}^{z \delta} p$, including the fact that any choice of $w_{r}^{z \delta} p$ gives a (unique) $P_{z}$ containing $P_{z}^{\prime}$. Thus the dimension of the fibre of $I^{+} G_{p}^{z}(M)$ as a bundle over $I^{\prime} G_{p}^{z}(M)$ is $d-p$. On the other hand, if we fix ( $m, P_{1}, \ldots, P_{z}$ ) and vary $P_{z}^{\prime} \subseteq P_{z}$ then this variation is described, locally, by the co-ordinates $w_{p}^{0, l}(1 \leq l \leq p-1)$. So the dimension of the fibre of $I^{+} G_{p}^{z}(M)$ as a bundle over $I G_{p}^{z}(M)$ is $p-1$.

Defintion. Let E by a system of $z$ th order partial differential equations, i.e. a subset of ${ }^{z} G_{p}(M)$. Let $E_{1}$ be the corresponding subset of $I G_{p}^{z}(M)$ (corresponding that is under our
diffeomorphism of Theorem (4.1), and let $E_{1}^{+}=\left(\pi^{+}\right)^{-1}\left(E_{1}\right)$. A point $\left(m, P^{+}\right)=\left(m, P_{1}, \ldots\right.$, $\left.P_{z-1}, P_{z}^{\prime}, P_{z}\right) \in I^{+} G_{p}^{z}(M)$ is said to be non-characteristic for $E$ if and only if both:
(1) $(m . P)=\pi^{+}\left(m, P^{+}\right)$is in $E_{1}$, i.e. $\left(m, P^{+}\right) \in E_{1}^{+}$,
(2) in some neighbourhood (in $I^{+} G_{p}^{z}(M)$ ) of $\left(m, P^{+}\right), E_{1}^{+}$is locally a cross-section over $I^{\prime} G_{p}^{z}(M)$, i.e. there exists a neighbourhood $\tilde{Q}^{\prime}$ of $\left(m, P^{\prime}\right)=\pi^{0}\left(m, P^{+}\right)$and a neighbourhood $\widetilde{Q}$ of $\left(m, P^{+}\right)$and a map $\chi$ of $\tilde{Q}^{\prime}$ into $I^{+} G_{p}^{z}(M)$ such that
(a) $\chi \circ \pi^{0}=$ identity, on $\widetilde{Q}^{\prime}$;
(b) $\chi\left(m, P^{\prime}\right)=\left(m, P^{+}\right)$;
(c) $E_{1}^{+} \cap \tilde{Q}=\chi\left(\widetilde{Q}^{\prime}\right)$;
(d) $\widetilde{Q}^{\prime}=\pi^{0} \widetilde{Q}$.

As remarked above, this says ( $m, P^{+}$) is non-characteristic if and only if each ( $m^{*}, P^{* \prime}$ ) near ( $m, P^{\prime}$ ) determines a unique ( $m^{*}, P^{*}$ ) satisfying the partial differential equation (i.e. belonging to $E_{1}$ ) and $\left(m^{*}, P^{*}\right)$ is a differentiable function of $\left(m^{*}, P^{*}\right)$. This definition could be expressed directly in terms of ${ }^{z} G_{p}(M)$ (without referring to $I G_{p}^{z}(M)$ or our basic diffeomorphism) in the following way. Consider a fixed $\left(m,{ }^{z} P\right) \in E$. Consider an $\left(m_{,}{ }^{z-1} P\right) \in$ ${ }^{z-1} G_{p}(M)$ with ${ }^{z-1} P \subseteq{ }^{z} P$ and an $\left(m,{ }^{z} P^{\prime}\right) \in{ }^{z} G_{p-1}(M)$ with ${ }^{2} P^{\prime} \subseteq{ }^{z} P$; so ${ }^{z-1} P+{ }^{z} P^{\prime} \subseteq{ }^{z} P$. Then the triple $\left(m,{ }^{z-1} P+{ }^{z} P^{\prime},{ }^{z} P\right)$ is non-characteristic for $E$ if and only if each ( $m^{*},{ }^{z-1} P^{*}+{ }^{z} P^{* \prime}$ ) near to ( $m,{ }^{z-1} P+{ }^{z} P^{\prime}$ ) determines a unique ( $m^{*},{ }^{z} P^{*}$ ) with ${ }^{z-1} P^{*}+$ ${ }^{z} P^{*^{\prime}} \subseteq{ }^{z} P^{*}$ and $\left(m^{*},{ }^{z} P^{*}\right) \in E$, and if the map thereby defined is differentiable. To express this carefully one would need auxiliary bundles corresponding to $I^{\prime} G_{p}^{z}(M)$ and $I^{+} G_{p}^{z}(M)$ so this procedure is just a translation of the other.

We shall show that our definition of non-characteristic is equivalent to a classical one. 'The classical one says the system is non-characteristic at a point if one can 'solve' the system locally for all $z$ th order derivatives with respect to one of the independent variables, i.e. the system is 'equivalent' (in the sense, say, of having the same solutions as) to one of the form:

$$
\begin{aligned}
& \frac{\partial^{2} g_{1}}{\partial u_{p}^{z}}=f_{1}\left(u_{1}, \ldots, u_{p}, g_{1}, \ldots, g_{q}, \ldots, \frac{\partial^{\lambda} g_{j}}{\partial u_{\lambda}}, \ldots\right) \\
& \frac{\partial^{z} g_{q}}{\partial u_{p}^{z}}=f_{q}\left(u_{1}, \ldots, u_{p}, g_{1}, \ldots, g_{q}, \ldots, \frac{\partial^{\lambda} g_{j}}{\partial u_{\lambda}}, \ldots\right)
\end{aligned}
$$

where the $\lambda$ on the right side satisfy $|\lambda| \leq z$ and $\lambda_{p}<z$. In case $q=1$ (the most interesting case) this is the only classical definition but for $q>1$ there is at least one alternative which is more general, namely, one supposes one can solve for the highest derivatives with respect to $u_{p}$ without assuming those highest derivatives are all of the same order. We do not consider this more general version. The following lemma expresses the equivalence of our notion with the above classical notion.

Lemma (5.3). Let $E \subseteq{ }^{z} G_{p}(M)$, $E_{1}$ be the corresponding set in $I G_{p}^{z}(M)$ and $E^{+}=\left(\pi^{+}\right)^{-1}\left(E_{1}\right)$. Let $\left(m, P^{+}\right) \in E_{1}^{+}$. Then $\left(m, P^{+}\right)$is non-characteristic for $E$ if and only if
there exists a suitable co-ordinate system $\left\{x_{a}\right\}$ for $\left(m, P^{+}\right)$such that if $\left\{y_{i}^{0}, y_{r}^{\lambda}\right\}$ is the associated co-ordinate system for $I G_{p}^{z}(M)$ (or equivalently, for ${ }^{z} G_{p}(M)$ ) then $E_{1}$ (or $E$ ) is defined locally by the family of functions:

$$
y_{p+1}^{z \delta_{p}}-f_{p+1}\left(y_{i}^{0}, y_{r}^{\lambda}\right), \ldots, y_{d}^{z \delta_{p}}-f_{d}\left(y_{i}^{0}, y_{r}^{\lambda}\right)
$$

where all $\lambda$ occuring in these $f_{r}$ satisfy $|\lambda| \leq z$ and $\lambda_{p}<z$, and the $f_{r}$ are $C^{\infty}$ (on a neighbourhood of the point in $R^{e}$, with $e=p+(d-p)\left[(p)_{z}-1\right]$, whose co-ordinates are the numbers $y_{i}^{0}(m, P), y_{r}^{\lambda}(m, P)$, for $\left.(m, P)=\pi^{+}\left(m, P^{+}\right)\right)$.

Remark. When we say $E$ is locally defined by such functions we mean there exists a neighbourhood $Q$ of $(m, P)$ such that these functions are defined on $Q$ and the set of their common zeros in $Q$ is $E \cap Q$.

Proof. The only thing to prove is that if $\left(m, P^{+}\right)$is non-characteristic then it is defined by such functions, for the converse is trivial. Let $\left(m, P^{+}\right)=\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right)$, $(m, P)=\pi^{+}\left(m, P^{+}\right)=\left(m, P_{1}, \ldots, P_{z}{ }^{-}, P_{z}\right)$, and $\left(m, P^{\prime}\right)=\pi^{0}\left(m, P^{+}\right)=\left(m, P_{1}, \ldots, P_{z-1}\right.$, $P_{z}^{\prime}$ ). Choose a co-ordinate system $\left\{x_{a}\right\}$ of $M$ which is suitable for $\left(m, P^{+}\right)$and with the further properties: for the associated $\left\{y_{i}^{0}, y_{r}^{\lambda}\right\}, P_{z}$ is the span of the $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)(1 \leq i \leq p)$ and $P_{z}^{\prime}$ is the span of the first $p-1$ of these. This is possible by the remarks preceeding Lemma (5.1). We shall show that for this co-ordinate system the given $E$ is defined, locally, by functions of the required type. In the following we use the notation $\left\{y_{i}^{0}, y_{r}^{\lambda}\right\},\left\{z_{i}^{0}, z_{p}^{0, l}, z_{r}^{\lambda}\right\}$, $\left\{w_{i}^{0}, w_{p}^{0, t}, w_{r}^{\lambda}\right\}$ for the co-ordinate systems defined previously from the $x_{a}$ and also will denote their domains by $Q^{[z]}, Q^{\prime}, Q^{+}$(thus deviating slightly from previous notation in which $Q^{[z]}$ and $Q^{\prime}$ were open sets in $G_{p}^{z}(M)$ and $G_{p-1}\left(G_{p}^{z-1}(M)\right.$ ) instead of, as now, $I G_{p}^{z}(M)$ and $I^{\prime} G_{p}^{z}(M)$ ). We also use $\rho$ and $\rho^{\prime}$ for the projections of the tangent space to $G_{p}^{z-1}(M)$ at $\left(m, P_{1}, \ldots, P_{z-1}\right)$ onto the span of the first $p$, and first $p-1$, of the $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)$, defined from the base $\left\{\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right), \frac{\partial}{\partial y_{r}^{\alpha}}\left(m, P_{1}, \ldots, P_{z-1}\right)\right\}$.

We note that

$$
\pi^{+} Q^{+}=Q^{[z]}, \quad \pi^{0} Q^{+}=Q^{\prime}
$$

The first holds because if ( $m, P_{1}, \ldots, P_{z-1}, P_{z}$ ) $\in Q^{[z]}$ then we can find a ( $p-1$ )-dimensional $P_{z}^{\prime}$ contained in $P_{z}$ with $\rho^{\prime}$ non-singular on $P_{z}^{\prime}$, e.g. by choosing $P_{z}^{\prime}=$ the span of those elements in $P_{z}$ which project under $\rho$ to the first $p-1$ of the $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)$. The second holds because (5.4) and (5.5) show how to choose from the co-ordinates $z_{i}^{0}, z_{p}^{0, l}, z_{r}^{2}$ of $\left(m, P^{\prime}\right)$ values of the co-ordinates $w_{i}^{0}, w_{p}^{0, l}, w_{r}^{\lambda}$ that will define an $\left(m, P^{+}\right)$with $\pi^{+}\left(m, P^{+}\right)=$ ( $m, P^{\prime}$ ) (using here that the range of these co-ordinates is the range of the $x_{a}$ times a full Euclidean space).

We now define a local cross-section $\varphi$ of $I^{+} G_{p}^{z}(M)$ over $I G_{p}^{z}(M)$ with domain $Q^{[z]}$, by

$$
\varphi\left(m, P_{1}, \ldots, P_{z}\right)=\left(m, P_{1}, \ldots, P_{z-1}, P_{z}^{\prime}, P_{z}\right)
$$

where $P_{z}^{\prime}=$ the span of the elements of $P_{z}$ that project under $\rho$ to the first $p-1$ of the $\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)$. Clearly,
(*)

$$
\begin{gathered}
\varphi\left(Q^{[z]}\right) \subseteq Q^{+} \\
\pi^{+} \circ \varphi=\text { identity, on } Q^{[z]} \\
w_{p}^{0, l} \circ \varphi=0 \quad \text { for } 1 \leq l \leq p-1
\end{gathered}
$$

the last being proved by checking the co-ordinate expressions, given earlier, for those $f_{i} \in P_{z}$ such that $f_{i}=\frac{\partial}{\partial y_{i}^{0}}\left(m, P_{1}, \ldots, P_{z-1}\right)$.

Now let $\widetilde{Q}$ and $\widetilde{Q}^{\prime}$ and $\chi$ be as in the definition of non-characteristic for $\left(m, P^{+}\right)$and we may assume $\tilde{Q}^{\prime} \subseteq Q^{\prime}$. Define

$$
\tilde{Q}^{[z]}=\varphi^{-1}\left(\tilde{Q} \cap Q^{+}\right)
$$

We define functions $F_{r}$ on $\widetilde{Q}^{[z]}$ by

$$
F_{r}=w_{r}^{z \delta_{p}} \circ \varphi-w_{r}^{z \delta_{p}} \circ \chi \circ \pi^{0} \circ \varphi
$$

and we shall prove these $F_{r}$ satisfy the lemma. For this it is sufficient to prove the following two statements:
(1) $F_{r}=y_{r}^{z \delta_{p}}-f_{r}\left(y_{i}^{0}, y_{r}^{\lambda}\right)$ where the $f_{r}$ are $C^{\infty}$ and the only $\lambda$ occurring have $|\lambda| \leq z$ and $\lambda_{p}<z$;
(2) if $\left(m^{*}, P^{*}\right) \in{ }^{[ } \widetilde{Q}^{z]}$ then $\left(m^{*}, P^{*}\right) \in E_{1}$ if and only if all $F_{r}\left(m^{*}, P^{*}\right)=0$.

Proof of (l). First we note
(a) $w_{r}^{z \delta_{p}} \circ \varphi=y_{r}^{z \delta_{p}} \circ \pi^{+} \circ \varphi=y_{r}^{z \delta_{p}}$.

Becausc $w_{r}^{\delta_{r}} \circ \chi$ is a $C^{\infty}$ function on $\widetilde{Q}^{\prime}$ there exist $C^{\infty}$ functions $f_{r}$ on $\widetilde{Q}^{\prime}$ such that

$$
w_{r}^{z \delta_{p}} \circ \chi=f_{r}\left(z_{i}^{0}, z_{p}^{0,4}, z_{r}^{\lambda}\right)
$$

where the only $\lambda$ occuring have $|\lambda| \leq z$ and $\lambda_{p}<z$. Then using (5.4), (5.5) and (*), we have
(b) $w_{r}^{z \delta_{p}} \circ \chi \circ \pi^{0} \circ \varphi=f_{r}\left(z_{i}^{0} \circ \pi^{0} \circ \varphi, z_{p}^{0, l} \circ \pi^{0} \circ \varphi, z_{r}^{\hat{\lambda}} \circ \pi^{0} \circ \varphi\right)$

$$
\begin{aligned}
& =f_{r}\left(w_{i}^{0} \circ \varphi, w_{p}^{0, l} \circ \varphi, w_{r}^{\lambda} \circ \varphi+\left(w_{p}^{0, l} \circ \varphi\right)\left(w_{r}^{\lambda-\delta_{1}+\delta} p \circ \varphi\right)\right) \\
& =f_{r}\left(y_{i}^{0} \circ \pi^{+} \circ \varphi, 0, y_{r}^{\lambda} \circ \pi^{+} \circ \varphi\right)\left(\operatorname{by}\left(^{*}\right)\right) \\
& =f_{r}\left(y_{i}^{0}, 0, y_{r}^{\lambda}\right) .
\end{aligned}
$$

Together (a) and (b) prove (1).
Proof of (2). Let $\left(m^{*}, P^{*}\right) \in \widetilde{Q}^{[z]}$ and first suppose $\left(m^{*}, P^{*}\right) \in E_{1}$. Then $\varphi\left(m^{*}, p^{*}\right) \in$ $E_{1}^{+} \wedge Q$, which implies $\varphi\left(m^{*}, P^{*}\right)=\chi\left(m^{*}, P_{1}^{\prime}\right)$ for some ( $m^{*}, P_{1}^{\prime}$ ). Applying $\pi^{0}$ to both sides, $\pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)=\left(m^{*}, P_{1}^{\prime}\right)$, hence $\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)=\chi\left(m^{*}, P_{1}^{\prime}\right)=\varphi\left(m^{*}, P^{*}\right)$, hence all co-ordinate functions and in particular the $w_{r}^{2 \delta_{p}}$ satisfy $w_{r}^{z \delta_{p}}\left(\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right)=$ $w_{r}^{z \delta_{p}}\left(\varphi\left(m^{*}, P^{*}\right)\right)$, i.e. $F_{r}\left(m^{*}, P^{*}\right)=0$.

Now suppose $\left(m^{*}, P^{*}\right) \in \bar{Q}^{[z]}$ and all $F_{r}\left(m^{*}, P^{*}\right)=0$. This says, for all $r$,

$$
w_{r}^{z \delta_{p}}\left(\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right)=w_{r}^{z \delta_{p}}\left(\varphi\left(m^{*}, P^{*}\right)\right) .
$$

For any $r$ and $\lambda$ with $|\lambda|<z$ we have, by (5.5),

$$
\begin{aligned}
w_{r}^{\lambda}\left(\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right) & =z_{r}^{\lambda}\left(\pi^{0} \circ \chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right) \\
& =z_{r}^{\lambda}\left(\pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right)=w_{r}^{\lambda}\left(\varphi\left(m^{*}, P^{*}\right)\right.
\end{aligned}
$$

and in the same way we have

$$
w_{i}^{0}\left(\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right)=w_{i}^{0}\left(\varphi\left(m^{*}, P^{*}\right)\right)
$$

and

$$
w_{p}^{0, l}\left(\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right)=w_{p}^{0, l}\left(\varphi\left(m^{*}, P^{*}\right)\right)=0
$$

hence, now with $|\lambda|=z$ but $\lambda_{p}<z$, we get from (5.5) that

$$
w_{r}^{\lambda}\left(\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)\right)=w_{r}^{\lambda}\left(\varphi\left(m^{*}, P^{*}\right)\right) .
$$

Because all their co-ordinates are the same we then have $\chi \circ \pi^{0} \circ \varphi\left(m^{*}, P^{*}\right)=\varphi\left(m^{*}, P^{*}\right)$, proving $\varphi\left(m^{*}, P^{*}\right) \in \chi\left(Q^{\prime}\right) \in E_{1}$, hence $\left(m^{*}, P^{*}\right)=\pi^{+} \circ \varphi\left(m^{*}, P^{*}\right) \in E_{1}$.

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