

3×3 Orthostochastic Matrices and the Convexity of Generalized Numerical Ranges

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ABSTRACT

Let \mathcal{U}_3 be the set of all 3×3 unitary matrices, and let A and B be two 3×3 complex normal matrices. In this note, the authors first give a necessary and sufficient condition for a 3×3 doubly stochastic matrix to be orthostochastic and then use this result to consider the structure of the sets $\mathcal{W}(A) = \{\text{Diag } UAU^* : U \in \mathcal{U}_3\}$ and $W(A, B) = \{\text{Tr } UAU^*B : U \in \mathcal{U}_3\}$, where $*$ denotes the transpose conjugate.

1. INTRODUCTION

Let A and B be two $n \times n$ complex matrices, and let \mathcal{U}_n be the set of all $n \times n$ unitary matrices. Define $\mathcal{W}(A) = \{\text{Diag } UAU^* : U \in \mathcal{U}_n\}$ and $W(A, B) = \{\text{Tr } UAU^*B : U \in \mathcal{U}_n\}$, where $*$ denotes the transpose conjugate. Horn [3] proved that if A is Hermitian, then $\mathcal{W}(A)$ is convex. Au-Yeung and Sing [1] proved that if A is normal, then $\mathcal{W}(A)$ is convex if and only if the eigenvalues of A are collinear. Williams [7] characterized the structure of $\mathcal{W}(A)$ for a 3×3 normal matrix A . Westwick [6] (in an equivalent form) proved that if A is normal and the eigenvalues of A are collinear, then $W(A, B)$ is convex. He also gave an example of two 3×3 normal matrices A and B such that $W(A, B)$ is not convex.

An $n \times n$ doubly stochastic (d.s.) matrix (a_{ij}) is said to be orthostochastic (o.s.) if there exists $(u_{ij}) \in \mathcal{U}_n$ such that $a_{ij} = |u_{ij}|^2$. The purpose of this note is (1) to give a necessary and sufficient condition for a 3×3 d.s. matrix to be o.s., (2) to give another characterization of the structure of $\mathcal{W}(A)$ for a normal 3×3 matrix A and (3) to give a necessary and sufficient condition for the convexity of $W(A, B)$ in terms of the eigenvalues of A and B for 3×3 normal matrices A and B .

2. ORTHOSTOCHASTIC MATRICES AND THE CONVEXITY OF GENERALIZED NUMERICAL RANGES

We first give a necessary and sufficient condition for a d.s. matrix to be o.s.

THEOREM 1. *Let (a_{ij}) be a 3×3 real matrix such that $\sum_{i=1}^3 a_{ij} = 1$ ($i = 1, 2, 3$) and $\sum_{i=1}^3 a_{ij} = 1$ ($j = 1, 2, 3$). Then*

(1) *if (a_{ij}) is o.s., then for any $j \neq j'$ and for any l*

$$\sqrt{a_{lj}a_{lj'}} \leq \sum_{\substack{i=1 \\ i \neq l}}^3 \sqrt{a_{ij}a_{ij'}}; \quad (*)$$

(2) *conversely, if there exist $j \neq j'$ such that $a_{ij} \geq 0$, $a_{ij'} \geq 0$ ($i = 1, 2, 3$) and for any l , the inequality (*) holds, then (a_{ij}) is o.s.*

Proof. Suppose (a_{ij}) is o.s.; then there exist real numbers θ_{ij} ($i, j = 1, 2, 3$) such that $(\sqrt{a_{ij}} e^{\sqrt{-1}\theta_{ij}})$ is unitary. Hence for any $j \neq j'$

$$\sum_{i=1}^3 \sqrt{a_{ij}a_{ij'}} e^{\sqrt{-1}(\theta_{ij} - \theta_{ij'})} = 0,$$

and consequently the inequality (*) follows.

Conversely, suppose there exist $j \neq j'$ such that the inequality (*) holds for any l . For definiteness, we assume $j = 1$ and $j' = 2$. Then the nonnegative numbers $\sqrt{a_{11}a_{12}}$, $\sqrt{a_{21}a_{22}}$, $\sqrt{a_{31}a_{32}}$ form the lengths of the three sides of a triangle. Hence there exist real numbers θ and ψ such that

$$\sqrt{a_{11}a_{12}} + \sqrt{a_{21}a_{22}} e^{\sqrt{-1}\theta} + \sqrt{a_{31}a_{32}} e^{\sqrt{-1}\psi} = 0.$$

Let $u_{i1} = \sqrt{a_{i1}}$ ($i = 1, 2, 3$) and $u_{12} = \sqrt{a_{12}}$, $u_{22} = \sqrt{a_{22}} e^{\sqrt{-1}\theta}$, $u_{32} = \sqrt{a_{32}} e^{\sqrt{-1}\psi}$, and (u_{13}, u_{23}, u_{33}) be any unit vector orthogonal to (u_{11}, u_{21}, u_{31}) and (u_{12}, u_{22}, u_{32}) . Then (u_{ij}) is unitary and $a_{ij} = |u_{ij}|^2$. ■

In the following we shall use A and B to denote two complex normal matrices with eigenvalues $\lambda_1, \lambda_2, \lambda_3$ and μ_1, μ_2, μ_3 respectively. It follows from the definitions that $\mathcal{W}(A) = \{(\lambda_1, \lambda_2, \lambda_3)(a_{ij}) : (a_{ij}) \text{ is a } 3 \times 3 \text{ o.s. matrix}\}$ and $\mathcal{W}(A, B) = \{(\lambda_1, \lambda_2, \lambda_3)(a_{ij})(\mu_1, \mu_2, \mu_3)^T : (a_{ij}) \text{ is a } 3 \times 3 \text{ o.s. matrix}\}$, where T denotes the transpose. From Theorem 1, we have

COROLLARY 1. $(\gamma_1, \gamma_2, \gamma_3) \in \mathcal{O}\mathcal{W}(A)$ ($\gamma \in W(A, B)$ respectively) if and only if $(\gamma_1, \gamma_2, \gamma_3) = (\lambda_1, \lambda_2, \lambda_3)(a_{ij})$ ($\gamma = (\lambda_1, \lambda_2, \lambda_3)(a_{ij})(\mu_1, \mu_2, \mu_3)^T$ respectively), where (a_{ij}) is a d.s. matrix satisfying (*) for some $j \neq j'$ and for any l .

Obviously, if $(\gamma_1, \gamma_2, \gamma_3) \in \mathcal{O}\mathcal{W}(A)$, then each γ_i ($i=1, 2, 3$) is a convex combination of λ_1, λ_2 and λ_3 and $\gamma_1 + \gamma_2 + \gamma_3 = \lambda_1 + \lambda_2 + \lambda_3$. The following theorem gives a characterization of $\mathcal{O}\mathcal{W}(A)$.

THEOREM 2. Suppose λ_1, λ_2 and λ_3 are not collinear and $\gamma_1 = \alpha_1\lambda_1 + \alpha_2\lambda_2 + \alpha_3\lambda_3$ ($\alpha_i \geq 0, \alpha_1 + \alpha_2 + \alpha_3 = 1$). Then $(\gamma_1, \gamma_2, \gamma_3) \in \mathcal{O}\mathcal{W}(A)$, where $\gamma_2 = x\lambda_1 + y\lambda_2 + z\lambda_3, x, y, z \geq 0, x + y + z = 1$ and $\gamma_3 = \text{Tr}A - (\gamma_1 + \gamma_2)$, if and only if

- (i) $x \leq \alpha_2 + \alpha_3$ and
- (ii) $(\sqrt{\alpha_1\alpha_2x} - \sqrt{\alpha_3\alpha_0})^2 \leq (\alpha_2 + \alpha_3)^2y \leq (\sqrt{\alpha_1\alpha_2x} + \sqrt{\alpha_3\alpha_0})^2$, where $\alpha_0 = \alpha_2 + \alpha_3 - x$.

Proof. We first observe that

$$(\gamma_1, \gamma_2, \gamma_3) = (\lambda_1, \lambda_2, \lambda_3) \begin{pmatrix} \alpha_1 & x & 1 - \alpha_1 - x \\ \alpha_2 & y & 1 - \alpha_2 - y \\ \alpha_3 & z & 1 - \alpha_3 - z \end{pmatrix}$$

Now if $(\gamma_1, \gamma_2, \gamma_3) \in \mathcal{O}\mathcal{W}(A)$, then there exists an o.s. matrix (a_{ij}) such that

$$(\lambda_1, \lambda_2, \lambda_3) \begin{pmatrix} \alpha_1 & x & 1 - \alpha_1 - x \\ \alpha_2 & y & 1 - \alpha_2 - y \\ \alpha_3 & z & 1 - \alpha_3 - z \end{pmatrix} = (\lambda_1, \lambda_2, \lambda_3)(a_{ij}).$$

Since λ_1, λ_2 and λ_3 are not collinear, by comparing the coefficients we see that

$$\begin{pmatrix} \alpha_1 & x & 1 - \alpha_1 - x \\ \alpha_2 & y & 1 - \alpha_2 - y \\ \alpha_3 & z & 1 - \alpha_3 - z \end{pmatrix} = (a_{ij}).$$

Consequently, by Theorem 1, $(\gamma_1, \gamma_2, \gamma_3) \in \mathcal{O}\mathcal{W}(A)$ if and only if all the following three inequalities hold:

- (1) $\sqrt{\alpha_1x} \leq \sqrt{\alpha_2y} + \sqrt{\alpha_3z}$,
- (2) $\sqrt{\alpha_2y} \leq \sqrt{\alpha_1x} + \sqrt{\alpha_3z}$,
- (3) $\sqrt{\alpha_3z} \leq \sqrt{\alpha_1x} + \sqrt{\alpha_2y}$.

If $\alpha_2 + \alpha_3 = 0$, from (1), $x = 0$ and y can take any value between 0 and 1. So we may assume $\alpha_2 + \alpha_3 > 0$ and notice that (1), (2) and (3) together are equivalent to

$$\begin{aligned} & (\sqrt{\alpha_1 x} - \sqrt{\alpha_3 z})^2 \leq \alpha_2 y \leq (\sqrt{\alpha_1 x} + \sqrt{\alpha_3 z})^2 \\ \Leftrightarrow & -2\sqrt{\alpha_1 \alpha_3 x z} \leq \alpha_2 y - \alpha_1 x - \alpha_3 z \leq 2\sqrt{\alpha_1 \alpha_3 x z} \\ \Leftrightarrow & [\alpha_2 y - \alpha_1 x - \alpha_3(1-x-y)]^2 \leq 4\alpha_1 \alpha_3 x(1-x-y) \\ \Leftrightarrow & (\alpha_2 + \alpha_3)^2 y^2 - 2[\alpha_1 \alpha_2 x + \alpha_3(\alpha_2 + \alpha_3 - x)]y + [\alpha_1 x - \alpha_3(1-x)]^2 \leq 0 \\ & \hspace{20em} (\because \alpha_1 + \alpha_2 + \alpha_3 = 1) \\ \Leftrightarrow & [(\alpha_2 + \alpha_3)^2 y]^2 - 2[\alpha_1 \alpha_2 x + \alpha_3(\alpha_2 + \alpha_3 - x)][(\alpha_2 + \alpha_3)^2 y] \\ & + [\alpha_1 \alpha_2 x - \alpha_3(1-x) + \alpha_1 \alpha_3]^2 \leq 0 \hspace{5em} (\because \alpha_1 + \alpha_2 + \alpha_3 = 1). \end{aligned}$$

Putting $t = (\alpha_2 + \alpha_3)^2 y$, then the above inequality holds for nonnegative real numbers t if and only if

$$\alpha_3 \alpha_0 \geq 0 \quad \text{and} \quad (\sqrt{\alpha_1 \alpha_2 x} - \sqrt{\alpha_3 \alpha_0})^2 \leq t \leq (\sqrt{\alpha_1 \alpha_2 x} + \sqrt{\alpha_3 \alpha_0})^2,$$

which in turn are equivalent to (i) and (ii), since if $\alpha_3 = 0$, then

$$t = \alpha_2^2 y = \alpha_1 \alpha_2 x \Rightarrow x = \alpha_2(x+y) \leq \alpha_2. \quad \blacksquare$$

The following theorem shows that the matrix

$$C_0 = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

plays an important role in the consideration of 3×3 o.s. matrices.

THEOREM 3.¹ *A convex combination of a 3×3 o.s. matrix (a_{ij}) and C_0 is an o.s. matrix. Furthermore, the matrix C_0 is the unique o.s. matrix with this property.*

¹Theorem 3 and Corollary 2 were also obtained by M. Goldberg and E. Straus (private communication). The authors are thankful to Straus for giving the second statement of Theorem 3 with a proof which is different from the one given here.

Proof. Let $0 < \alpha < 1$. Then for any l

$$\begin{aligned} & \left[\sum_{\substack{i=1 \\ i \neq l}}^3 \sqrt{\left(\alpha a_{i1} + \frac{1-\alpha}{3}\right)\left(\alpha a_{i2} + \frac{1-\alpha}{3}\right)} \right]^2 \\ &= \sum_{\substack{i=1 \\ i \neq l}}^3 \left(\alpha a_{i1} + \frac{1-\alpha}{3}\right)\left(\alpha a_{i2} + \frac{1-\alpha}{3}\right) \\ & \quad + 2\sqrt{\left(\alpha a_{i1} + \frac{1-\alpha}{3}\right)\left(\alpha a_{i2} + \frac{1-\alpha}{3}\right)\left(\alpha a_{i'1} + \frac{1-\alpha}{3}\right)\left(\alpha a_{i'2} + \frac{1-\alpha}{3}\right)} \\ & \hspace{15em} (1 < i < i' \leq 3, \quad i, i' \neq l) \\ &> \sum_{\substack{i=1 \\ i \neq l}}^3 \left[\alpha^2 a_{i1} a_{i2} + \frac{\alpha(1-\alpha)}{3} (a_{i1} + a_{i2}) + \left(\frac{1-\alpha}{3}\right)^2 \right] + 2\alpha^2 \sqrt{a_{i1} a_{i2} a_{i'1} a_{i'2}} \\ & \hspace{15em} (1 < i < i' \leq 3, \quad i, i' \neq l) \\ &= \alpha^2 \left[\sum_{\substack{i=1 \\ i \neq l}}^3 \sqrt{a_{i1} a_{i2}} \right]^2 + \frac{\alpha(1-\alpha)}{3} \sum_{\substack{i=1 \\ i \neq l}}^3 (a_{i1} + a_{i2}) + 2\left(\frac{1-\alpha}{3}\right)^2 \\ &> \alpha^2 a_{i1} a_{i2} + \frac{\alpha(1-\alpha)}{3} \sum_{\substack{i=1 \\ i \neq l}}^3 (a_{i1} + a_{i2}) + \left(\frac{1-\alpha}{3}\right)^2 \quad [\text{by } (*)] \\ &= \alpha^2 a_{i1} a_{i2} + \frac{\alpha(1-\alpha)}{3} [2 - (a_{i1} + a_{i2})] + \left(\frac{1-\alpha}{3}\right)^2 \\ &> \alpha^2 a_{i1} a_{i2} + \frac{\alpha(1-\alpha)}{3} (a_{i1} + a_{i2}) + \left(\frac{1-\alpha}{3}\right)^2 \quad (a_{i1} + a_{i2} \leq 1) \\ &= \left[\sqrt{\left(\alpha a_{i1} + \frac{1-\alpha}{3}\right)\left(\alpha a_{i2} + \frac{1-\alpha}{3}\right)} \right]^2. \end{aligned}$$

Hence, by Theorem 1, $\alpha(a_{ij}) + (1-\alpha)C_0$ is o.s. for any $0 < \alpha < 1$.

For uniqueness, call any o.s. matrix with such property a center. Let $C = (c_{ij})$ be a center and I the 3×3 identity matrix. Then, for any $0 \leq \alpha \leq 1$, the matrix $(1 - \alpha)I + \alpha C$ is o.s., and by Theorem 1 we have

$$\sqrt{\alpha c_{12}[1 + \alpha(c_{11} - 1)]} \leq \sqrt{\alpha c_{21}[1 + \alpha(c_{22} - 1)]} + \sqrt{\alpha^2 c_{31} c_{32}}$$

and

$$\sqrt{\alpha c_{21}[1 + \alpha(c_{22} - 1)]} \leq \sqrt{\alpha c_{12}[1 + \alpha(c_{11} - 1)]} + \sqrt{\alpha^2 c_{31} c_{32}}.$$

Hence

$$\left(\sqrt{\alpha c_{21}[1 + \alpha(c_{22} - 1)]} - \sqrt{\alpha c_{12}[1 + \alpha(c_{11} - 1)]} \right)^2 \leq \alpha c_{31} c_{32}$$

for any $0 < \alpha \leq 1$. This implies $c_{21} = c_{12}$. It is obvious that if C is a center, then for any permutation matrices P_1 and P_2 , $P_1 C P_2$ is also a center. Therefore, by the above argument we have $c_{ij} = \frac{1}{3}$ for $i, j = 1, 2, 3$. ■

COROLLARY 2. For any $u \in \mathcal{O}(A)$ ($x \in W(A, B)$ respectively) and any $0 \leq \alpha \leq 1$, $\alpha(\gamma, \gamma, \gamma) + (1 - \alpha)u \in \mathcal{O}(A)$, where $\gamma = \frac{1}{3}(\lambda_1 + \lambda_2 + \lambda_3)$ ($(\alpha/3)(\lambda_1 + \lambda_2 + \lambda_3)(\mu_1 + \mu_2 + \mu_3) + (1 - \alpha)x \in W(A, B)$ respectively).

Let M_+ (M_-) denote the set of all 3×3 even (odd) permutation matrices. Define $\mathcal{V}_+ = \{(\lambda_1, \lambda_2, \lambda_3)P : P \in M_+\}$, $\mathcal{V}_- = \{(\lambda_1, \lambda_2, \lambda_3)P : P \in M_-\}$, $V_+ = \{(\lambda_1, \lambda_2, \lambda_3)P(\mu_1, \mu_2, \mu_3)^T : P \in M_+\}$, $V_- = \{(\lambda_1, \lambda_2, \lambda_3)P(\mu_1, \mu_2, \mu_3)^T : P \in M_-\}$. A permutation matrix is o.s. For a convex combination of two permutation matrices, we have the following theorems.

THEOREM 4. For any $P_1 \in M_+$, $P_2 \in M_-$ and any $0 \leq \alpha \leq 1$, $\alpha P_1 + (1 - \alpha)P_2$ is o.s.

Proof. Without loss of generality, we may assume P_1 to be the identity matrix (otherwise we consider PP_1 and PP_2 , where P is a permutation matrix). Then P_2 is obtained from P_1 by transposing two rows of P_1 . For definiteness we assume

$$P_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}.$$

Then obviously,

$$\alpha \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + (1-\alpha) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \alpha & 1-\alpha \\ 0 & 1-\alpha & \alpha \end{pmatrix}$$

is o.s. ■

COROLLARY 3. For any $u \in \mathcal{V}_+$ ($x \in V_+$ respectively), $v \in \mathcal{V}_-$ ($y \in V_-$) and any $0 < \alpha < 1$, we have $\alpha u + (1-\alpha)v \in \mathcal{W}(A)$ ($\alpha x + (1-\alpha)y \in W(A, B)$).

THEOREM 5. For any distinct P_1 and P_2 in M_+ (or in M_-) and any $0 < \alpha < 1$, $\alpha P_1 + (1-\alpha)P_2$ is not an o.s. matrix.

Proof. Without loss of generality, we may assume P_1 to be the identity matrix. For definiteness, we assume

$$P_2 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}.$$

Then for any $0 < \alpha < 1$,

$$\alpha \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + (1-\alpha) \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} \alpha & 1-\alpha & 0 \\ 0 & \alpha & 1-\alpha \\ 1-\alpha & 0 & \alpha \end{pmatrix},$$

which, by Theorem 1, is obviously not o.s. ■

Lerer [4] gave an example of a unitary matrix U such that $\mathcal{W}(U)$ is not convex. But by applying Theorem 5 and comparing coefficients, we have the following result.

COROLLARY 4. If $\lambda_1, \lambda_2, \lambda_3$ are not collinear, then for any distinct $u, v \in \mathcal{V}_+$ (or \mathcal{V}_-) and any $0 < \alpha < 1$, $\alpha u + (1-\alpha)v \notin \mathcal{W}(A)$.

For any two distinct complex numbers x and y , we shall denote by $L(x, y)$ the line passing x and y .

COROLLARY 5. If x, y are two distinct points in V_+ (V_- respectively) such that all the points in V_- (V_+ respectively) lie on one side (the open half plane) of $L(x, y)$, then $\alpha x + (1-\alpha)y \notin W(A, B)$ for any $0 < \alpha < 1$.

Proof. Suppose there exist $x, y \in V_+$ (or V_-) and $0 < \alpha < 1$ such that $\alpha x + (1 - \alpha)y \in W(A, B)$. Then there exists an o.s. matrix (a_{ij}) such that

$$\alpha x + (1 - \alpha)y = (\lambda_1, \lambda_2, \lambda_3)(a_{ij})(\mu_1, \mu_2, \mu_3)^T.$$

By Birkhoff's theorem (for example, see [5]), (a_{ij}) is a convex combination of permutation matrices. Since all the points in V_- lie on one side of $L(x, y)$, and since the triangles $\mathcal{C}(V_+)$ and $\mathcal{C}(V_-)$, [where $\mathcal{C}(X)$ is the convex hull of X] have the same center $c_0 = \frac{1}{3}(\lambda_1 + \lambda_2 + \lambda_3)(\mu_1 + \mu_2 + \mu_3)$, the third point z in V_+ (or V_- respectively) also lies on the same open half plane with the points in V_- (or V_+). Consequently, we have $(a_{ij}) = \alpha P_1 + (1 - \alpha)P_2$, where P_1 and P_2 are in M_+ (or M_-), contradicting Theorem 5. ■

THEOREM 6. $W(A, B)$ is not convex if and only if there exist distinct x and y in V_+ (or in V_-) such that all points in V_- (or V_+ respectively) lie on one side (the open half plane) of $L(x, y)$.

Proof. For any two distinct complex numbers x and y , we denote by $S(x, y)$ the line segment joining x and y . It is known [2] that $\mathcal{C}(W(A, B)) = \mathcal{C}(V_+ \cup V_-)$. By Corollary 3, we see that if $x \in V_+$ and $y \in V_-$, then $S(x, y) \subset W(A, B)$, and by Corollary 2, if $x \in W(A, B)$, then $S(x, c_0) \subset W(A, B)$, where

$$c_0 = \frac{1}{3}(\lambda_1 + \lambda_2 + \lambda_3)(\mu_1 + \mu_2 + \mu_3) = \frac{1}{6} \sum_{x \in V_+ \cup V_-} x = \frac{1}{3} \sum_{x \in V_+} x = \frac{1}{3} \sum_{x \in V_-} x.$$

Therefore, if $W(A, B)$ is not convex, then there exist distinct x and y in V_+ (or in V_-) and $0 < \alpha < 1$ such that $\alpha x + (1 - \alpha)y \notin W(A, B)$. The third point z in V_+ (in V_- respectively) cannot lie on $L(x, y)$; otherwise, $c_0 \in L(x, y)$ and consequently $S(x, y) \subset W(A, B)$. Now all points in V_- (in V_+ respectively) must lie on the same side with z (equivalently with c_0) with respect to $L(x, y)$, since if there exists x_0 in V_- (in V_+ respectively) such that x_0 lies on $L(x, y)$ or on the other side of $L(x, y)$, then $S(c_0, w) \subset W(A, B)$ for all $w \in S(x_0, x) \cup S(x_0, y)$ and consequently $S(x, y) \subset W(A, B)$.

The other part of the theorem is a consequence of Corollary 5. So the proof of the theorem is completed. ■

3. EXAMPLES

In the following figures, we use \circ to denote points in V_+ and \times to denote points in V_- .

EXAMPLE 1 (see Fig. 1).

$$A = \begin{pmatrix} 0 & & \\ & 1 & \\ & & e^{\sqrt{-1} \pi/3} \end{pmatrix},$$

$$B = \begin{pmatrix} 0 & & \\ & 1 & \\ & & e^{\sqrt{-1} 2\pi/3} \end{pmatrix},$$

$$V_+ = \{e^{\sqrt{-1} \pi/3}, e^{\sqrt{-1} 2\pi/3}, 0\},$$

$$V_- = \{1, -1, \sqrt{-3}\}.$$

$W(A, B)$ is convex.

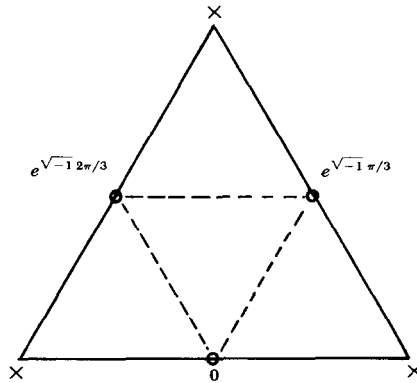


FIG. 1.

EXAMPLE 2 (see Fig. 2).

$$A = \begin{pmatrix} 0 & & \\ & 1 & \\ & & \frac{1}{2} e^{\sqrt{-1} \pi/12} \end{pmatrix},$$

$$B = \begin{pmatrix} 0 & & \\ & 1 & \\ & & e^{\sqrt{-1} \pi/3} \end{pmatrix},$$

$$V_+ = \left\{ \frac{1}{2} e^{\sqrt{-1} \pi/12}, e^{\sqrt{-1} \pi/3}, 1 + \frac{1}{2} e^{\sqrt{-1} 5\pi/12} \right\},$$

$$V_- = \left\{ 1, \frac{1}{2} e^{\sqrt{-1} 5\pi/12}, \frac{1}{2} e^{\sqrt{-1} \pi/12} + e^{\sqrt{-1} \pi/3} \right\}.$$

$W(A, B)$ is convex.

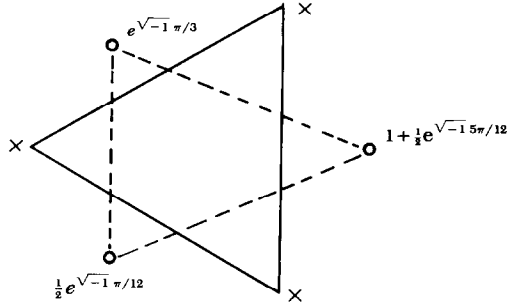


FIG. 2.

EXAMPLE 3 (see Fig. 3).

$$A = \begin{bmatrix} 0 & & \\ & 1 & \\ & & \alpha \end{bmatrix},$$

$$B = \begin{bmatrix} 0 & & \\ & 1 & \\ & & \bar{\alpha} \end{bmatrix}, \quad \alpha \text{ is not real,}$$

$$V_+ = \{ \alpha, \bar{\alpha}, 1 + \alpha\bar{\alpha} \},$$

$$V_- = \{ 1, \alpha\bar{\alpha}, \alpha + \bar{\alpha} \}.$$

$W(A, B)$ is not convex.

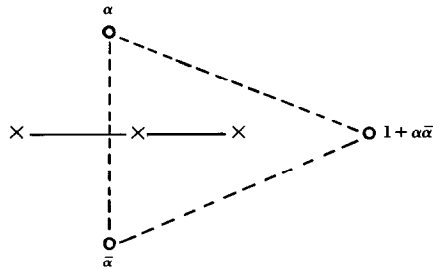


FIG. 3.

EXAMPLE 4 (see Fig. 4).

$$A = \begin{bmatrix} 0 & & \\ & 1 & \\ & & \sqrt{-1} \end{bmatrix} \quad B = \begin{bmatrix} 0 & & \\ & 1 & \\ & & \sqrt{-1} \end{bmatrix},$$

$$V_+ = \{ \sqrt{-1}, \sqrt{-1}, 0 \},$$

$$V_- = \{ 1, -1, 2\sqrt{-1} \}.$$

$W(A, B)$ is not convex. (Westwick [6] has considered this example.)

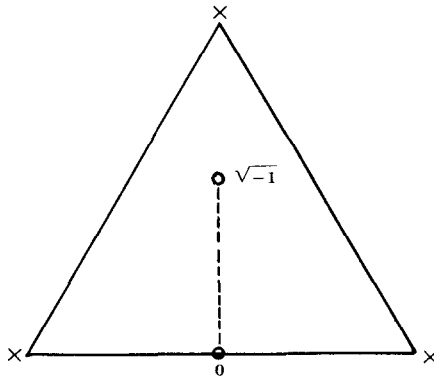


FIG. 4.

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