# Large isoperimetric regions in the product of a compact manifold with Euclidean space ${ }^{\text {it }}$ 

Manuel Ritoré*, Efstratios Vernadakis<br>Departamento de Geometría y Topología, Universidad de Granada, E-18071 Granada, Spain

## A R T I C L E I N F O

## Article history:

Received 26 November 2015
Accepted 2 November 2016
Available online 11 November 2016
Communicated by T. Rivière

## $M S C$ :

49Q10
49Q20
Keywords:
Isoperimetric inequality
Isoperimetric regions
Riemannian cylinders
Symmetrization
Density estimates
Anisotropic scaling
Stable constant mean curvature surfaces

## A B S T R A C T

Given a compact Riemannian manifold $M$ without boundary, we show that large isoperimetric regions in $M \times \mathbb{R}^{k}$ are tubular neighborhoods of $M \times\{x\}$, with $x \in \mathbb{R}^{k}$.
© 2016 The Authors. Published by Elsevier Inc. This is an open access article under the CC BY license (http://creativecommons.org/licenses/by/4.0/).

[^0]
## 1. Introduction

We consider the isoperimetric problem of minimizing perimeter under a given volume constraint inside $N=M \times \mathbb{R}^{k}$, where $\mathbb{R}^{k}$ is the $k$-dimensional Euclidean space and $M$ is an $m$-dimensional compact Riemannian manifold without boundary. Our main result is the following:

Theorem 1.1. Let $M$ be a compact Riemannian manifold. There exists a constant $v_{0}>0$ such that any isoperimetric region in $M \times \mathbb{R}^{k}$ of volume $v \geqslant v_{0}$ is a tubular neighborhood of $M \times\{x\}$, with $x \in \mathbb{R}^{k}$.

This result, in case $k=1$, was first proven by Duzaar and Steffen [4, Prop. 2.11]. As observed by Morgan, an alternative proof for $k=1$ can be given using the monotonicity formula and properties of the isoperimetric profile of $M \times \mathbb{R}$ (see [20, Cor. 4.12] for a proof when $M$ is a convex body). Gonzalo considered the general problem in his Ph.D. Thesis [9]. In $\mathbb{S}^{1} \times \mathbb{R}^{k}$, the result follows from the classification of isoperimetric regions by Pedrosa and Ritoré [19]. Large isoperimetric regions in asymptotically flat manifolds have been recently characterized by Eichmair and Metzger [5]. It is worth mentioning that W.-T. Hsiang and W.-Y. Hsiang [12] completely solved the isoperimetric problem in products of Euclidean and hyperbolic spaces. Morgan [16], after Barthé [1], using results by Ros [22], provides a lower bound of the isoperimetric profile of a Riemannian product in terms of concave lower bounds of the isoperimetric profiles of the factors.

In our proof we use symmetrization and show in Corollary 2.2 that anisotropic scaling of symmetrized isoperimetric regions of large volume $L^{1}$-converge to a tubular neighborhood of $M \times\{0\}$. This convergence is improved in Lemma 2.4 to Hausdorff convergence of the boundaries using the density estimates on tubes from Lemma 2.3, similar to the ones obtained by Ritoré and Vernadakis [21]. Results of White [23] and Grosse-Brauckmann [11] on stable submanifolds then imply that the scaled boundaries are cylinders, see Theorem 3.2. For small dimensions, it is also possible to use a result by Morgan and Ros [18] to get the same conclusion only using $L^{1}$-convergence. Once it is shown that the symmetrized set is a tube, it is not difficult to prove that the original isoperimetric region is also a tube.

After the distribution of this manuscript, Gonzalo informed us that he had obtained a proof of Theorem 1.1 in [10]. His techniques are different from ours and similar to the ones used in [9].

Given a measurable set $E \subset N$, their perimeter and volume will be denoted by $P(E)$ and $|E|$, respectively. We refer the reader to Maggi's book [14] for background on finite perimeter sets. The $r$-dimensional Hausdorff measure of a set $E$ will be denoted by $H^{r}(E)$.

On $M \times \mathbb{R}^{k}$ we shall consider the anisotropic dilation of ratio $t>0$ defined by

$$
\varphi_{t}(p, x)=(p, t x), \quad(p, x) \in M \times \mathbb{R}^{k}
$$

Since the Jacobian of the map $\varphi_{t}$ is $t^{k}$, we have

$$
\begin{equation*}
\left|\varphi_{t}(E)\right|=t^{k}|E|, \quad \text { for any measurable set } E \subset M \times \mathbb{R}^{k} \tag{1.1}
\end{equation*}
$$

Let $\Sigma \subset M \times \mathbb{R}^{k}$ be an $(n-1)$-rectifiable set, where $n=m+k$ is the dimension of $N$. At a regular point $p \in \Sigma$, the unit normal $\xi$ can be decomposed as $\xi=a v+b w$, with $a^{2}+b^{2}=1, v$ tangent to $M$ and $w$ tangent to $\mathbb{R}^{k}$. Then the Jacobian of $\varphi_{t} \mid \Sigma$ is equal to $t^{k-1}\left(t^{2} a^{2}+b^{2}\right)^{1 / 2}$. For $t \geqslant 1$ we get

$$
\begin{equation*}
t^{k} H^{n-1}(\Sigma) \geqslant H^{n-1}\left(\varphi_{t}(\Sigma)\right) \geqslant t^{k-1} H^{n-1}(\Sigma) \tag{1.2}
\end{equation*}
$$

and the reversed inequalities when $t \leqslant 1$. Similar properties hold for the perimeter. Equality holds in the right hand side of (1.2) if and only if $a=0$, or equivalently if and only if $\xi$ is tangent to $\mathbb{R}^{k}$.

An open ball in $\mathbb{R}^{k}$ of radius $r>0$ and center $x$ will be denoted by $D(x, r)$. If it is centered at the origin, we set $D(r)=D(0, r)$. We shall also denote by $T(x, r)$ the set $M \times D(x, r)$, and by $T(r)$ the set $M \times D(r)$. Observe that $\varphi_{t}(T(x, r))=T(t x, t r)$ and that $T(x, r)$ is the tubular neighborhood of radius $r>0$ of $M \times\{x\}$.

Given any set $E \subset N$ of finite perimeter, we can replace it by a normalized set sym $E$ by requiring $\operatorname{sym} E \cap\left(\{p\} \times \mathbb{R}^{k}\right)=\{p\} \times D(r(p))$, where $H^{k}(D(r(p))$ is equal to the $H^{k}$-measure of $E \cap\left(\{p\} \times \mathbb{R}^{k}\right)$. For such a set we get

## Theorem 1.2.

1. $\mid$ sym $E|=|E|$,
2. $P(\operatorname{sym} E) \leqslant P(E)$.

The proof of Theorem 1.2 is similar to the one of symmetrization in $\mathbb{R}^{n}=\mathbb{R}^{m} \times \mathbb{R}^{k}$ with respect to one of the factors, see Burago and Zalgaller [2, § 9] (or Maggi [14] for the case $m=1$ ). The main ingredients are a corresponding inequality for the Minkowski content and approximation of finite perimeter sets by sets with smooth boundary.

Given $E \subset N$, we denote by $E^{*}$ its orthogonal projection onto $M$. If $E$ is normalized, and $u: E^{*} \rightarrow \mathbb{R}^{+}$measures the radius of the disk obtained projecting $E \cap\left(\{p\} \times \mathbb{R}^{k}\right)$ to $\mathbb{R}^{k}$, we get, assuming enough regularity on $u$, that

$$
\begin{aligned}
|E| & =\omega_{k} \int_{E^{*}} u^{k} d H^{m} \\
H^{n-1}(\partial E) & =k \omega_{k} \int_{E^{*}} u^{k-1} \sqrt{1+|\nabla u|^{2}} d H^{m}
\end{aligned}
$$

where $\omega_{k}=H^{k}(D(1))$, and $k \omega_{k}=H^{k-1}\left(\mathbb{S}^{k-1}\right)$. The above formulas imply

$$
\begin{aligned}
|T(r)| & =\omega_{k} r^{k} H^{m}(M) \\
P(T(r)) & =k \omega_{k} r^{k-1} H^{m}(M),
\end{aligned}
$$

so that

$$
\begin{equation*}
P(T(r))=k\left(\omega_{k} H^{m}(M)\right)^{1 / k}|T(r)|^{(k-1) / k} \tag{1.3}
\end{equation*}
$$

The isoperimetric profile of $M \times \mathbb{R}^{k}$ is the function $I:(0,+\infty) \rightarrow[0,+\infty)$ defined by

$$
I(v)=\inf \{P(E) ;|E|=v\}
$$

An isoperimetric region is a set $E \subset M \times \mathbb{R}^{k}$ satisfying $I(|E|)=P(E)$. Existence of isoperimetric regions in $M \times \mathbb{R}^{k}$ is guaranteed by a result of Morgan [17, p. 129], since the quotient of $M \times \mathbb{R}^{k}$ by its isometry group is compact. From his arguments, it also follows that isoperimetric regions are bounded in $M \times \mathbb{R}^{k}$ (see also [7]). From (1.3) we get

$$
\begin{equation*}
I(v) \leqslant k\left(\omega_{k} H^{m}(M)\right)^{1 / k} v^{(k-1) / k} \tag{1.4}
\end{equation*}
$$

for any $v>0$. The regularity of isoperimetric regions in Riemannian manifolds is wellknown, see Morgan [15] and Gonzalez-Massari-Tamanini [8]. The boundary is regular except for a singular set of vanishing $H^{n-7}$ measure. The following properties of the isoperimetric profile hold

Proposition 1.3. The isoperimetric profile $I$ of $M \times \mathbb{R}^{k}$ is non-decreasing and continuous.
Proof. Let $v_{1}<v_{2}$, and $E \subset N$ an isoperimetric region of volume $v_{2}$. Let $0<t<1$ so that $\left|\varphi_{t}(E)\right|=v_{1}$. By (1.2) we have

$$
I\left(v_{1}\right) \leqslant P\left(\varphi_{t}(E)\right) \leqslant P(E)=I\left(v_{2}\right)
$$

This shows that $I$ is non-decreasing.
Let us prove now the right-continuity of $I$ at $v$. Consider an isoperimetric region $E$ of volume $v$. Take a smooth vector field $Z$ with support in the regular part of the boundary of $E$ such that $\int_{E} \operatorname{div} Z \neq 0$. The flow $\left\{\varphi_{t}\right\}_{t \in \mathbb{R}}$ of $Z$ satisfies $\left.(d / d t)\right|_{t=0}\left|\varphi_{t}(E)\right| \neq 0$. Using the Inverse Function Theorem we obtain a smooth family $\left\{E_{w}\right\}$, for $w$ near $v$, with $\left|E_{w}\right|=w$ and $E_{v}=E$. The function $f(w)=P\left(E_{w}\right)$ satisfies $f \geqslant I$ and $I(v)=f(v)$. This implies that $I$ is right-continuous at $v$ since, for $v_{i} \downarrow v$, we have

$$
I(v)=f(v)=\lim _{i \rightarrow \infty} f\left(v_{i}\right) \geqslant \lim _{i \rightarrow \infty} I\left(v_{i}\right) \geqslant I(v)
$$

by the monotonicity of $I$.

To prove the left-continuity of $I$ at $v$ we take a sequence of isoperimetric regions $E_{i}$ with $v_{i}=\left|E_{i}\right| \uparrow v$ and we consider balls $B_{i}$ disjoint from $E_{i}$ so that $\left|E_{i} \cup B_{i}\right|=\left|E_{i}\right|+\left|B_{i}\right|$. Then $I(v) \leqslant P\left(E_{i} \cup B_{i}\right)=I\left(v_{i}\right)+P\left(B_{i}\right) \leqslant I(v)+P\left(B_{i}\right)$ by the monotonicity of $I$, and the left-continuity follows by taking limits since $\lim _{i \rightarrow \infty} P\left(B_{i}\right)=0$.

We shall also use the following well-known isoperimetric inequalities in $M$ and $M \times \mathbb{R}^{k}$
Lemma 1.4 ([4]). Given $0<v_{0}<H^{m}(M)$, there exists a constant $a\left(v_{0}\right)>0$ such that

$$
H^{m-1}(\partial E) \geqslant a\left(v_{0}\right) H^{m}(E)
$$

for any set $E \subset M$ satisfying $0<H^{m}(E)<v_{0}$.
Lemma 1.5. Given $v_{0}>0$, there exists a constant $c\left(v_{0}\right)>0$ so that

$$
\begin{equation*}
I(v) \geqslant c\left(v_{0}\right) v^{(n-1) / n} \tag{1.5}
\end{equation*}
$$

for any $v \in\left(0, v_{0}\right)$.
Lemma 1.5 follows from the facts that $I(v)$ is strictly positive for $v>0$ and asymptotic to the Euclidean isoperimetric profile when $v$ approaches 0 .

## 2. Large isoperimetric regions in $M \times \mathbb{R}^{k}$

In this Section we shall prove that normalized isoperimetric regions of large volume, when scaled down to have constant volume $v_{0}$, have their boundaries uniformly close to the boundary of the normalized tube of volume $v_{0}$.

If $E \subset N$ is any finite perimeter set and $T(E)$ is the tube with the same volume as $E$, we define

$$
E^{-}=E \cap T(E), \quad E^{+}=E \backslash T(E)
$$

Let $t>0$, and $\Omega=\varphi_{t}(E)$. Since $\varphi_{t}\left(E^{+}\right)=\Omega^{+},(1.1)$ implies

$$
\begin{equation*}
\frac{\left|E^{+}\right|}{|E|}=\frac{\left|\Omega^{+}\right|}{|\Omega|} \tag{2.1}
\end{equation*}
$$

A similar equality holds replacing $E^{+}$by $E^{-}$.
Proposition 2.1. Let $\left\{E_{i}\right\}_{i \in \mathbb{N}}$ be a sequence of normalized sets with volumes $\left|E_{i}\right| \rightarrow \infty$. Let $v_{0}>0$ and $0<t_{i}<1$ so that $\left|\varphi_{t_{i}}\left(E_{i}\right)\right|=v_{0}$ for all $i \in \mathbb{N}$, and let $T$ be the tube of volume $v_{0}$ around $M_{0}$.

If $\varphi_{t_{i}}\left(E_{i}\right)$ does not converge to $T$ in the $L^{1}$-topology, then there is a constant $c>0$, only depending on $\left\{E_{i}\right\}_{i \in \mathbb{N}}$, so that, passing to a subsequence, there holds

$$
\begin{equation*}
H^{n-1}\left(\partial E_{i}\right) \geqslant c\left|E_{i}\right| \tag{2.2}
\end{equation*}
$$

Proof. Assume $T=M \times D(r)$, and set $\Omega_{i}=\varphi_{t_{i}}\left(E_{i}\right)$. As $\left|\Omega_{i}\right|=|T|$, we get $2\left|\Omega_{i}^{+}\right|=$ $\left|\Omega_{i} \triangle T\right|$ and, since $\left|\Omega_{i} \triangle T\right|$ does not converge to 0 , the sequence $\left|\Omega_{i}^{+}\right|$does not converge to 0 either. Let $c_{1}>0$ be a constant so that $\lim \sup _{i \rightarrow \infty}\left(\left|\Omega_{i}^{+}\right| /\left|\Omega_{i}\right|\right)>c_{1}$. From (2.1) we obtain

$$
\begin{equation*}
\limsup _{i \rightarrow \infty} \frac{\left|E_{i}^{+}\right|}{\left|E_{i}\right|}>c_{1} \tag{2.3}
\end{equation*}
$$

Now we claim that

$$
\begin{equation*}
\liminf _{i \rightarrow \infty} H^{m}\left(\left(\Omega_{i} \cap \partial T\right)^{*}\right)<H^{m}(M) \tag{2.4}
\end{equation*}
$$

To prove (2.4) we argue by contradiction. Assume that $\liminf _{i \rightarrow \infty} H^{m}\left(\left(\Omega_{i} \cap \partial T\right)^{*}\right)=$ $H^{m}(M)$. As $\Omega_{i}$ is normalized, we have $\left(\Omega_{i} \cap \partial T\right)^{*} \subset\left(\Omega_{i} \cap T\right)^{*}$ and so $\left(T \backslash \Omega_{i}\right) \subset$ $\left(M \backslash\left(\Omega_{i} \cap \partial T\right)^{*}\right) \times D(r)$. This implies $\lim \sup _{i \rightarrow \infty}\left|T \backslash \Omega_{i}\right|=0$. Since $\left|\Omega_{i}\right|=|T|$, we get $\lim _{i \rightarrow \infty}\left|\Omega_{i} \triangle T\right|=2 \lim _{i \rightarrow \infty}\left|T \backslash \Omega_{i}\right|=0$, a contradiction that proves the claim.

Hence there exists $w \in\left(0, H^{m}(M)\right)$ so that

$$
\begin{equation*}
\liminf _{i \rightarrow \infty} H^{m}\left(\left(\Omega_{i} \cap \partial T\right)^{*}\right)<w \tag{2.5}
\end{equation*}
$$

Let $T\left(r_{i}\right)$ be the normalized tube with $\left|T\left(r_{i}\right)\right|=\left|E_{i}\right|$. As $\Omega_{i} \cap T=\varphi_{t_{i}}\left(E_{i} \cap T\left(r_{i}\right)\right)$, we have $\left(E_{i} \cap \partial T\left(r_{i}\right)\right)^{*}=\left(\Omega_{i} \cap \partial T\right)^{*}$; from (2.5) we get $\liminf _{i \rightarrow \infty} H^{m}\left(\left(E_{i} \cap \partial T\left(r_{i}\right)\right)^{*}\right)<w$, and we obtain

$$
\begin{equation*}
\liminf _{i \rightarrow \infty} H^{m}\left(\left(E_{i} \cap \partial T(s)\right)^{*}\right)<w, \quad \forall s \geqslant r_{i} \tag{2.6}
\end{equation*}
$$

This last step to go from the particular $r_{i}$ to every $s \geqslant r_{i}$ is easy to check as, for any normalized set $E=\bigcup_{p \in E^{*}}(\{p\} \times D(r(p)))$, we have $(E \cap \partial T(s))^{*}=\{p \in M: r(p) \geqslant s\}$, therefore $(E \cap \partial T(s))^{*} \subset(E \cap \partial T(r))^{*}$ whenever $s \geqslant r$.

The above arguments imply, replacing the original sequence by a subsequence, that

$$
\begin{equation*}
\left|E_{i}^{+}\right|>c_{1}\left|E_{i}\right|, \quad H^{m}\left(\left(E_{i} \cap \partial T(s)\right)^{*}\right)<w, \quad i \in \mathbb{N}, s \geqslant r_{i} . \tag{2.7}
\end{equation*}
$$

Let $a=a(w)$ be the constant in Lemma 1.4. For the elements of the subsequence satisfying (2.7) we have

$$
\begin{aligned}
H^{n-1}\left(\partial E_{i}\right) & \geqslant H^{n-1}\left(\partial E_{i} \cap\left(N \backslash T\left(r_{i}\right)\right)\right) \\
& \geqslant \int_{r_{i}}^{\infty} H^{n-2}\left(\partial E_{i} \cap \partial T(s)\right) d s
\end{aligned}
$$

$$
\begin{aligned}
& \geqslant \int_{r_{i}}^{\infty} H^{n-2}\left(\partial\left(E_{i} \cap \partial T(s)\right)\right) d s \\
& =\int_{r_{i}}^{\infty} H^{m-1}\left(\partial\left(E_{i} \cap \partial T(s)\right)^{*}\right) H^{k-1}(\partial D(s)) d s \\
& \geqslant \int_{r_{i}}^{\infty} a H^{m}\left(\left(E_{i} \cap \partial T(s)\right)^{*}\right) H^{k-1}(\partial D(s)) d s \\
& =a \int_{r_{i}}^{\infty} H^{n-1}\left(E_{i} \cap \partial T(s)\right) d s=a\left|E_{i}^{+}\right|>a c_{1}\left|E_{i}\right|
\end{aligned}
$$

thus proving the result. In the previous inequalities we have used the coarea formula for the distance function to $M \times\{0\}$; that $\partial\left(E_{i} \cap \partial T(s)\right) \subset \partial E_{i} \cap \partial T(s)$, where the first $\partial$ denotes the boundary operator in $\partial T(s)$; the fact that for an $O(k)$-invariant set $F$ we have $F \cap \partial T(s)=(F \cap \partial T(s))^{*} \times \partial D(s)$, and so $H^{r+k-1}(F \cap \partial T(s))=H^{r}((F \cap$ $\left.\partial T(s))^{*}\right) H^{k-1}(\partial D(s))$; that $\left(\partial\left(E_{i} \cap \partial T(s)\right)\right)^{*}=\partial\left(E_{i} \cap \partial T(s)\right)^{*}$; and the isoperimetric inequality on $M$ given in Lemma 1.4.

Corollary 2.2. Let $\left\{E_{i}\right\}_{i \in \mathbb{N}}$ be a sequence of normalized isoperimetric sets with volumes $\lim _{i \rightarrow \infty}\left|E_{i}\right|=\infty$. Let $v_{0}>0$ and $0<t_{i}<1$ such that $\Omega_{i}=\varphi_{t_{i}}\left(E_{i}\right)$ has volume $v_{0}$ for all $i \in \mathbb{N}$. Then $\Omega_{i} \rightarrow T$ in the $L^{1}$-topology, where $T$ is the tube of volume $v_{0}$.

Proof. Regularity results for isoperimetric regions imply that $P\left(E_{i}\right)=H^{n-1}\left(\partial E_{i}\right)$, choosing as representative of every isoperimetric set the closure of the set of density one points. If $\Omega_{i}$ does not converge to $T$ in the $L^{1}$-topology then, using (2.2) in Proposition 2.1 and (1.4), we get

$$
c\left|E_{i}\right| \leqslant P\left(E_{i}\right) \leqslant k\left(\omega_{k} H^{m}(M)\right)^{1 / k}\left|E_{i}\right|^{(k-1) / k}
$$

for a subsequence, thus yielding a contradiction by letting $i \rightarrow \infty$ since $\left|E_{i}\right| \rightarrow \infty$.
Using density estimates, we shall show now that the $L^{1}$ convergence of the scaled isoperimetric regions can be improved to Hausdorff convergence.

In a similar way to Leonardi and Rigot [13, p. 18] (see also [21] and David and Semmes [3]), given $E \subset N$, we define a function $h: \mathbb{R}^{k} \times(0,+\infty) \rightarrow \mathbb{R}^{+}$by

$$
h(x, R)=\frac{\min \{|E \cap T(x, R)|,|T(x, R) \backslash E|\}}{R^{n}}
$$

for $x \in \mathbb{R}^{k}$ and $R>0$. We remark that the quantity $h(x, R)$ is not homogeneous in the sense of being invariant by scaling since $h(x, R) \leqslant \frac{1}{2}\left(k \omega_{k} H^{m}(M)\right) R^{k-n}$, which goes to infinity when $R$ goes to 0 . When the set $E$ should be explicitly mentioned, we shall write

$$
h(E, x, R)=h(x, R)
$$

Lemma 2.3. Let $E \subset N$ be an isoperimetric region of volume $v>v_{0}$. Let $\tau>1$ such that $\Omega=\varphi_{\tau}^{-1}(E)$ has volume $v_{0}$. Choose $\varepsilon$ so that

$$
\begin{equation*}
0<\varepsilon<\min \left\{v_{0},\left(\frac{c\left(v_{0}\right) v_{0}^{1 / k}}{2 k \omega_{k} H^{m}(M)}\right)^{n},\left(\frac{c\left(v_{0}\right)}{8 n}\right)^{n}\right\} \tag{2.8}
\end{equation*}
$$

where $c\left(v_{0}\right)$ is as in (1.5).
Then, for any $x \in \mathbb{R}^{k}$ and $R \leqslant 1$ so that $h(\Omega, x, R) \leqslant \varepsilon$, we get

$$
h(\Omega, x, R / 2)=0
$$

Moreover, in case $h(\Omega, x, R)=\mid \Omega \cap T(x, R)) \mid R^{-n}$, we get $|\Omega \cap T(x, R / 2)|=0$ and, in case $h(\Omega, x, R)=|T(x, R) \backslash \Omega| R^{-n}$, we have $|T(x, R / 2) \backslash \Omega|=0$.

Proof. Using Lemma 1.5 we get a positive constant $c\left(v_{0}\right)$ so that (1.5) is satisfied (i.e., $I(w) \geqslant c\left(v_{0}\right) w^{(n-1) / n}$, for all $\left.0 \leqslant w \leqslant v_{0}\right)$.

Assume first that

$$
h(x, R)=h(\Omega, x, r)=\frac{|\Omega \cap T(x, R)|}{R^{n}} .
$$

Define

$$
m(r)=|\Omega \cap T(x, r)|, \quad 0<r \leqslant R .
$$

The function $m(r)$ is non-decreasing and, for $r \leqslant R \leqslant 1$, we get

$$
\begin{equation*}
m(r) \leqslant m(R) \leqslant|\Omega \cap T(x, R)| \leqslant \varepsilon R^{n} \leqslant \varepsilon<v_{0} \tag{2.9}
\end{equation*}
$$

by (2.8). Hence $v_{0}-m(r)>0$ for $0<r \leqslant R$.
By the coarea formula, when $m^{\prime}(r)$ exists, we get

$$
m^{\prime}(r)=\frac{d}{d r} \int_{0}^{r} H^{n-1}(\Omega \cap \partial T(x, s)) d s=H^{n-1}(\Omega \cap \partial T(x, r))
$$

Now define

$$
\lambda(r)=\frac{v_{0}^{1 / k}}{\left(v_{0}-m(r)\right)^{1 / k}}=\frac{v^{1 / k}}{|E \backslash T(\tau x, \tau r)|^{1 / k}} \geqslant 1,
$$

and

$$
\Omega(r)=\varphi_{\lambda(r)}(\Omega \backslash T(x, r))
$$

so that $|\Omega(r)|=|\Omega|$. Then

$$
E(r)=\varphi_{\tau}(\Omega(r))=\varphi_{\lambda(r)}(E \backslash T(\tau x, \tau r))
$$

and $|E(r)|=|E|$. Then, using (1.2) for $\lambda(r) \geqslant 1$ and standard properties of finite perimeter sets [14, Lemmas 12.22 and 15.12], we have

$$
\begin{align*}
I(v) & \leqslant P(E(r)) \leqslant \lambda(r)^{k}(P(E \backslash T(\tau x, \tau r))) \\
& \leqslant \frac{v_{0}}{v_{0}-m(r)}\left(P(E)-P(E \cap T(\tau x, \tau r))+2 H^{n-1}(E \cap \partial T(\tau x, \tau r))\right) \tag{2.10}
\end{align*}
$$

Since $\tau \geqslant 1$ and $E \cap \partial T(\tau x, \tau r)$ is part of a cylinder, using (1.2) again we get

$$
\begin{aligned}
P(E \cap T(\tau x, \tau r) & \geqslant \tau^{k-1} P(\Omega \cap T(x, r)) \geqslant \tau^{k-1} c\left(v_{0}\right) m(r)^{(n-1) / n} \\
H^{n-1}(E \cap \partial T(\tau x, \tau r)) & =\tau^{k-1} H^{n-1}(\Omega \cap \partial T(x, r))=\tau^{k-1} m^{\prime}(r)
\end{aligned}
$$

Replacing these expressions in (2.10), since $P(E)=I(v)$ and $\tau^{k} v_{0}=v$, we have

$$
\begin{align*}
2 m^{\prime}(r) & \geqslant m(r)^{(n-1) / n}\left(c\left(v_{0}\right)-\frac{m(r)^{1 / n}}{\tau^{k-1} v_{0}} I(v)\right) \\
& \geqslant m(r)^{(n-1) / n}\left(c\left(v_{0}\right)-\frac{m(r)^{1 / n}}{v_{0}^{1 / k}} \frac{I(v)}{v^{(k-1) / k}}\right)  \tag{2.11}\\
& \geqslant m(r)^{(n-1) / n}\left(c\left(v_{0}\right)-\frac{\varepsilon^{1 / n}}{v_{0}^{1 / k}}\left(k \omega_{k} H^{m}(M)\right)\right) \\
& \geqslant \frac{c\left(v_{0}\right)}{2} m(r)^{(n-1) / n},
\end{align*}
$$

where we have also used $m(r) \leqslant \varepsilon$, (1.4), and (2.8)
If there is $r \in[R / 2, R]$ such that $m(r)=0$ then, by the monotonicity of the function $m(r)$, we would conclude $m(R / 2)=0$ as well. So we assume $m(r)>0$ in $[R / 2, R]$. Then by (2.11), we get

$$
\frac{c\left(v_{0}\right)}{4} \leqslant \frac{m^{\prime}(t)}{m(t)^{(n-1) / n}}, \quad H^{1} \text {-a.e. }
$$

By (2.9) we get $m(R) \leqslant \varepsilon R^{n}$. Integrating between $R / 2$ and $R$,

$$
c\left(v_{0}\right) R / 8 \leqslant n\left(m(R)^{1 / n}-m(R / 2)^{1 / n}\right) \leqslant n m(R)^{1 / n} \leqslant n \varepsilon^{1 / n} R .
$$

This is a contradiction, since $\varepsilon<\left(c\left(v_{0}\right) / 8 n\right)^{n}$ by (2.8). So the proof in case $h(x, R)=$ $|\Omega \cap T(x, R)| R^{-n}$ is completed.

Now we deal with the case $h(x, R)=|T(x, R) \backslash \Omega| R^{-n}$. Define

$$
m(r)=|T(x, r) \backslash \Omega|
$$

Then $m(r)$ is a non-decreasing function and

$$
\begin{equation*}
m^{\prime}(r)=H^{n-1}\left(\Omega^{c} \cap \partial T(x, r)\right)=\frac{1}{\tau^{k-1}} H^{n-1}\left(E^{c} \cap \partial T(\tau x, \tau r)\right) \tag{2.12}
\end{equation*}
$$

since $E^{c} \cap \partial T(\tau x, \tau r)$ is part of a tube. We also have $m(r) \leqslant m(R) \leqslant \varepsilon R^{n} \leqslant \varepsilon<v_{0}$ by (2.8). Observe that

$$
\begin{equation*}
P\left(E \cup T(\tau x, \tau r) \leqslant P(E)-P(T(\tau x, \tau r) \backslash E)+2 H^{n-1}\left(E^{c} \cap \partial E(\tau x, \tau r)\right)\right. \tag{2.13}
\end{equation*}
$$

Since $\varphi_{\tau}(T(x, r) \backslash \Omega)=T(\tau x, \tau r) \backslash E$ and $\tau \geqslant 1$, we get

$$
\begin{align*}
P(T(\tau x, \tau r) \backslash E) & =P\left(\varphi_{\tau}(T(x, r) \backslash \Omega)\right) \\
& \geqslant \tau^{k-1} P(T(x, r) \backslash \Omega) \geqslant \tau^{k-1} c\left(v_{0}\right) m(r)^{(n-1) / n} \tag{2.14}
\end{align*}
$$

Now, using that $I$ is a non-decreasing function we easily obtain $P(E)=I(v) \leqslant I(\mid E \cup$ $T(\tau x, \tau r) \mid) \leqslant P(E \cup T(\tau x, \tau r))$. We estimate $P(E \cup T(\tau x, \tau r))$ from (2.13). Using (2.14) and (2.12), we get

$$
\begin{align*}
I(v)=P(E) & \leqslant P(E \cup T(\tau x, \tau r)) \\
& \leqslant I(v)-\tau^{k-1} c\left(v_{0}\right) m(r)^{(k-1) / k}+2 \tau^{k-1} m^{\prime}(r) \tag{2.15}
\end{align*}
$$

and so

$$
\frac{c\left(v_{0}\right)}{2} \leqslant \frac{m^{\prime}(r)}{m(r)^{(n-1) / n}}, \quad H^{1} \text {-a.e. }
$$

By (2.9) we get $m(R) \leqslant \varepsilon R^{n}$. Integrating between $R / 2$ and $R$,

$$
c\left(v_{0}\right) R / 4 \leqslant n\left(m(R)^{1 / n}-m(R / 2)^{1 / n}\right) \leqslant n m(R)^{1 / n} \leqslant n \varepsilon^{1 / n} R,
$$

and we get a contradiction since by (2.8) we have $\varepsilon<\left(c\left(v_{0}\right) /(8 n)\right)^{n}<\left(c\left(v_{0}\right) /(4 n)\right)^{n}$. This concludes the proof.

Let $F \subset N$, then we define $F_{r}=\{x \in N: d(x, F) \leqslant r\}$. We improve now the $L^{1}$-convergence of normalized isoperimetric regions obtained in Corollary 2.2 to Hausdorff convergence of their boundaries

Lemma 2.4. Let $\left\{E_{i}\right\}_{i \in \mathbb{N}}$ be a sequence of isoperimetric sets in $N$ with $\lim _{i \rightarrow \infty}\left|E_{i}\right|=\infty$. Let $v_{0}>0$ and $\left\{t_{i}\right\}_{i \in \mathbb{N}}$ such that $\lim _{i \rightarrow \infty} t_{i}=0$ and $\left|\Omega_{i}\right|=v_{0}$ for all $i \in \mathbb{N}$, where $\Omega_{i}=\varphi_{t_{i}}\left(E_{i}\right)$. Then for every $r>0, \partial \Omega_{i} \subset(\partial T)_{r}$, for large enough $i \in \mathbb{N}$, where $T$ is the tube of volume $v_{0}$.

Proof. Since $\left|\Omega_{i}\right|=v_{0}$, using (2.8) we can choose a uniform $\varepsilon>0$ so that Lemma 2.3 holds with this $\varepsilon$ for all $\Omega_{i}, i \in \mathbb{N}$. This means that, for any $x \in N$ and $0<r \leqslant 1$, whenever $h\left(\Omega_{i}, x, r\right) \leqslant \varepsilon$ we get $h\left(\Omega_{i}, x, r / 2\right)=0$.

As $\Omega_{i} \rightarrow T$ in $L^{1}(N)$ by Corollary 2.2 , we can choose a sequence $r_{i} \rightarrow 0$ so that

$$
\begin{equation*}
\left|\Omega_{i} \triangle T\right|<r_{i}^{n+1} \tag{2.16}
\end{equation*}
$$

Now fix some $0<r<1$. We reason by contradiction assuming that, for some subsequence, there exist

$$
\begin{equation*}
x_{i} \in \partial \Omega_{i} \backslash(\partial T)_{r} . \tag{2.17}
\end{equation*}
$$

We distinguish two cases.
First case: $x_{i} \in N \backslash T$, for a subsequence. Choosing $i$ large enough, (2.17) implies $T\left(x_{i}, r_{i}\right) \cap T=\emptyset$ and (2.16) yields

$$
\left|\Omega_{i} \cap T\left(x_{i}, r_{i}\right)\right| \leqslant\left|\Omega_{i} \backslash T\right| \leqslant\left|\Omega_{i} \triangle T\right|<r_{i}^{n+1} .
$$

So, for $i$ large enough, we get

$$
h\left(\Omega_{i}, x_{i}, r_{i}\right)=\frac{\left|\Omega_{i} \cap T\left(x_{i}, r_{i}\right)\right|}{r_{i}^{n}}<r_{i} \leqslant \varepsilon .
$$

By Lemma 2.3, we conclude that $\left|\Omega_{i} \cap T\left(x_{i}, r_{i} / 2\right)\right|=0$, a contradiction.
Second case: $x_{i} \in T$. Choosing $i$ large enough, (2.17) implies $T\left(x_{i}, r_{i}\right) \subset T$ and so

$$
\left|T\left(x_{i}, r_{i}\right) \backslash \Omega_{i}\right| \leqslant\left|T \backslash \Omega_{i}\right|, \quad \text { for every } r_{i}<r .
$$

Then, by (2.16), we get

$$
\left|T\left(x_{i}, r_{i}\right) \backslash \Omega_{i}\right| \leqslant\left|T \backslash \Omega_{i}\right| \leqslant\left|\Omega_{i} \triangle T\right|<r_{i}^{n+1}
$$

So, for $i$ large enough, we get

$$
h\left(\Omega_{i}, x_{i}, r_{i}\right)=\frac{\left|T\left(x_{i}, r_{i}\right) \backslash \Omega_{i}\right|}{r_{i}^{n}}<r_{i} \leqslant \varepsilon .
$$

By Lemma 2.3, we conclude that $\left|T\left(x_{i}, r_{i} / 2\right) \backslash \Omega_{i}\right|=0$, and we get again contradiction that proves the Lemma.

## 3. Strict $O(k)$-stability of tubes with large radius

In this Section we consider the orthogonal group $O(k)$ acting on the product $M \times \mathbb{R}^{k}$ through the second factor.

Let $\Sigma \subset M \times \mathbb{R}^{k}$ be a compact hypersurface with constant mean curvature. It is well-known that $\Sigma$ is a critical point of the area functional under volume-preserving deformations, and that $\Sigma$ is a second order minimum of the area under volume-preserving variations if and only if

$$
\begin{equation*}
\int_{\Sigma}\left(|\nabla u|^{2}-q u^{2}\right) d \Sigma \geqslant 0 \tag{3.1}
\end{equation*}
$$

for any smooth function $u: \Sigma \rightarrow \mathbb{R}$ with mean zero on $\Sigma$. In the above formula $\nabla$ is the gradient on $\Sigma$ and $q$ is the function $\operatorname{Ric}(\xi, \xi)+|\sigma|^{2}$, where $|\sigma|^{2}$ is the sum of the squared principal curvatures in $\Sigma, \xi$ is a unit vector field normal to $\Sigma$, and Ric is the Ricci curvature on $N$.

A hypersurface satisfying (3.1) is usually called stable and condition (3.1) is referred to as stability condition. In case $\Sigma$ is $O(k)$-invariant we can consider an equivariant stability condition: we shall say that $\Sigma$ is strictly $O(k)$-stable if there exists a positive constant $\lambda>0$ such that

$$
\int_{\Sigma}\left(|\nabla u|^{2}-q u^{2}\right) d \Sigma \geqslant \lambda \int_{\Sigma} u^{2} d \Sigma
$$

for any $O(k)$-invariant function $u: \Sigma \rightarrow \mathbb{R}$ with mean zero.
We consider now the tube $T(r)=M \times D(r)$. The boundary of $T(r)$ is the $O(k)$-invariant cylinder $\Sigma(r)=M \times \partial D(r)$, with $(k-1)$ principal curvatures equal to $1 / r$. Hence its mean curvature is equal to $(k-1) / r$ and the squared norm of the second fundamental form satisfies $|\sigma|^{2}=(k-1) / r^{2}$. The inner unit normal to $\Sigma(r)$ is the normal to $\partial D(r)$ in $\mathbb{R}^{k}$ (it is tangent to the factor $\mathbb{R}^{k}$ ). This implies $\operatorname{Ric}(\xi, \xi)=0$.

We have the following result
Lemma 3.1. The cylinder $\Sigma(r)$ is strictly $O(k)$-stable if and only if

$$
r^{2}>\frac{k-1}{\lambda_{1}(M)}
$$

where $\lambda_{1}(M)$ is the first positive eigenvalue of the Laplacian in $M$.
Proof. Let $\Sigma=\Sigma(r)=M \times D(r)$. Observe that an $O(k)$-invariant function with mean zero on $\Sigma$ is determined by a function $u: M \rightarrow \mathbb{R}$ with $\int_{M} u d M=0$. Hence

$$
\begin{aligned}
\int_{\Sigma}\left(|\nabla u|^{2}-q u^{2}\right) d \Sigma & =k \omega_{k} r^{k-1} \int_{M}\left(\left|\nabla_{M} u\right|^{2}-\frac{k-1}{r^{2}} u^{2}\right) d M \\
& \geqslant k \omega_{k} r^{k-1}\left(\lambda_{1}(M)-\frac{k-1}{r^{2}}\right) \int_{M} u^{2} d M
\end{aligned}
$$

$$
=\left(\lambda_{1}(M)-\frac{k-1}{r^{2}}\right) \int_{\Sigma} u^{2} d \Sigma
$$

This proves the Lemma.
Using results by White [23] and Grosse-Brauckmann [11] we get
Theorem 3.2. Let $T$ be a normalized tube so that $\Sigma=\partial T$ is a strictly $O(k)$-stable cylinder. Then there exists $r>0$ so that any $O(k)$-invariant finite perimeter set $E$ with $|E|=|T|$ and $\partial E \subset T_{r}$ has larger perimeter than $T$ unless $E=T$.

Proof. Since $\Sigma$ is strictly $O(k)$-stable, Grosse-Brauckmann [11, Lemma 5] implies that, for some $C>0, \Sigma$ has strictly positive second variation for the functional

$$
F_{C}=\operatorname{area}+H \operatorname{vol}+\frac{C}{2}(\operatorname{vol}-\operatorname{vol}(T))^{2},
$$

in the sense that the second variation of $F_{C}$ in the normal direction of a function $u$ satisfies

$$
\delta_{u}^{2} F_{C}=\int_{\Sigma}\left(|\nabla u|^{2}-q u^{2}\right) d \Sigma+C\left(\int_{\Sigma} u d \Sigma\right)^{2} \geqslant \lambda \int_{\Sigma} u^{2} d \Sigma,
$$

for any smooth $O(k)$-invariant function $u$ (see the discussion in the proof of Theorem 2 in Morgan and Ros [18]). In White's proof of Theorem 3 in [23] it is observed that a sequence of minimizers of $F_{C}$ in tubular neighborhoods of radius $1 / i$ of $\Sigma$ are almost minimizing, and hence $C^{1, \alpha}$ submanifolds that converge Hölder differentiably to $\Sigma$, contradicting the positivity of the second variation of $\Sigma$. Theorem 1.2 implies that the symmetrization of these minimizers are again minimizers. Thus we get a family of $O(k)$-minimizers of $F_{C}$ converging Hölder differentiably to $\Sigma$, thus contradicting the strict $O(k)$-stability of $\Sigma$.

## 4. Proof of Theorem 1.1

First we claim that there exists $v_{0}>0$ such that, for any isoperimetric region $E$ of volume $|E| \geqslant v_{0}$, the set $\operatorname{sym} E$ is a tube.

To prove this, consider a sequence of isoperimetric regions $\left\{E_{i}\right\}_{i \in \mathbb{N}}$ with $\lim _{i \rightarrow \infty}\left|E_{i}\right|=$ $\infty$. We know that $\left\{\operatorname{sym} E_{i}\right\}_{i \in \mathbb{N}}$ are also isoperimetric regions. Let $T=M \times D$ be a strictly $O(k)$-stable tube, that exists by Lemma 3.1. For large $i$, we scale down the sets sym $E_{i}$ so that $\Omega_{i}=\varphi_{t_{i}}^{-1}\left(\operatorname{sym} E_{i}\right)$ has the same volume as $T$. As sym $E_{i}$ is isoperimetric and $t_{i}>1$, we get from (1.4) and (1.2) that $P\left(\Omega_{i}\right) \leqslant P(T)$. By Corollary 2.2, the sets $\left\{\partial \Omega_{i}\right\}_{i \in \mathbb{N}}$ converge to $\partial T$ in Hausdorff distance. By Theorem 3.2, $\Omega_{i}=T$ for large $i$ and so sym $E_{i}$ is a tube. This proves the claim. In particular, $H^{m}\left(E \cap\left(\{p\} \times \mathbb{R}^{k}\right)\right)=H^{m}(D)$ for any $p \in M$.

Hence the isoperimetric profile satisfies $I(v)=C v^{(k-1) / k}$ for the constant $C$ in (1.3) and any $v \geqslant v_{0}$. We conclude that

$$
\begin{equation*}
I\left(t^{k} v\right)=t^{k-1} I(v), \quad \text { whenever } t^{k} v \geqslant v_{0} \tag{4.1}
\end{equation*}
$$

Let $E$ be an isoperimetric region with volume $|E|>v_{0}$, and $t<1$ so that $t^{k}|E|=v_{0}$. Then

$$
I\left(t^{k}|E|\right) \leqslant P\left(\varphi_{t}(E)\right) \leqslant t^{k-1} P(E)=t^{k-1} I(|E|)
$$

by the inequality corresponding to (1.2) when $t \leqslant 1$. By (4.1), equality holds and the unit normal $\xi$ to $\operatorname{reg}(\partial E)$, the regular part of $\partial E$, is tangent to the $\mathbb{R}^{k}$ factor. This implies that the $m$-Jacobian of the restriction $f$ of the projection $\pi_{1}: M \times \mathbb{R}^{k} \rightarrow M$ to the regular part of $\partial E$ is equal to 1 . By Federer's coarea formula for rectifiable sets [6, 3.2.22] we get

$$
H^{n-1}(\partial E)=\int_{M} H^{k-1}\left(f^{-1}(p)\right) d H^{m}(p)
$$

Assume that $\operatorname{sym} E$ is the tube $T(E)=M \times D$. The Euclidean isoperimetric inequality implies $H^{k-1}\left(f^{-1}(p)\right) \geqslant H^{k-1}(\{p\} \times \partial D)$ and so $H^{n-1}(\partial E) \geqslant H^{n-1}(\partial T(E))$, again by the coarea formula. As $P(E)=P(\operatorname{sym} E)=P(T(E))$, we get $H^{k-1}\left(f^{-1}(p)\right)=$ $H^{k-1}(\partial D)$ for $H^{m}$-a.e. $p \in M$ and so $\pi_{1}^{-1}(p)$ is equal to a disc $\{p\} \times D_{p}$ for $H^{m}$-a.e. $p \in M$.

The fact that $\xi$ is tangent to $\mathbb{R}^{k}$ in $\operatorname{reg}(\partial E)$ implies that $\operatorname{reg}(\partial E)$ is locally a cylinder of the form $U \times S$, where $U \subset M$ is an open set and $S \subset \mathbb{R}^{k}$ is a smooth hypersurface. Hence the discs $D_{p}$ are centered at the same point (i.e., $E$ is the translation of a normalized tube). This concludes the proof of the theorem.

Remark 4.1. The equivariant version of Theorem 2 in Morgan and Ros [18], together with Corollary 2.2, can be used to prove Theorem 1.1 for small dimensions.

## References

[1] F. Barthe, Log-concave and spherical models in isoperimetry, Geom. Funct. Anal. 12 (1) (2002) 32-55.
[2] Y.D. Burago, V.A. Zalgaller, Geometric Inequalities, Grundlehren Math. Wiss., vol. 285, SpringerVerlag, Berlin, 1988. Translated from the Russian by A.B. Sosinskiŭ, Springer Series in Soviet Mathematics.
[3] G. David, S. Semmes, Quasiminimal surfaces of codimension 1 and John domains, Pacific J. Math. 183 (2) (1998) 213-277.
[4] F. Duzaar, K. Steffen, Existence of hypersurfaces with prescribed mean curvature in Riemannian manifolds, Indiana Univ. Math. J. 45 (4) (1996) 1045-1093.
[5] M. Eichmair, J. Metzger, Unique isoperimetric foliations of asymptotically flat manifolds in all dimensions, Invent. Math. 194 (3) (2013) 591-630.
[6] H. Federer, Geometric Measure Theory, Grundlehren Math. Wiss., vol. 153, Springer-Verlag New York Inc., New York, 1969.
[7] M. Galli, M. Ritoré, Existence of isoperimetric regions in contact sub-Riemannian manifolds, J. Math. Anal. Appl. 397 (2) (2013) 697-714.
[8] E. Gonzalez, U. Massari, I. Tamanini, On the regularity of boundaries of sets minimizing perimeter with a volume constraint, Indiana Univ. Math. J. 32 (1) (1983) 25-37.
[9] J. Gonzalo, Large Soap Bubbles and Isoperimetric Regions in the Product of Euclidean Space with a Closed Manifold, PhD thesis, University of California, Berkeley, 1991.
[10] J. Gonzalo, Soap bubbles and isoperimetric regions in the product of a closed manifold with Euclidean space, arXiv:1312.6311, 21 Dec. 2013.
[11] K. Grosse-Brauckmann, Stable constant mean curvature surfaces minimize area, Pacific J. Math. 175 (2) (1996) 527-534.
[12] W.-T. Hsiang, W.-Y. Hsiang, On the uniqueness of isoperimetric solutions and imbedded soap bubbles in noncompact symmetric spaces. I, Invent. Math. 98 (1) (1989) 39-58.
[13] G.P. Leonardi, S. Rigot, Isoperimetric sets on Carnot groups, Houston J. Math. 29 (3) (2003) 609-637.
[14] F. Maggi, Sets of finite perimeter and geometric variational problems, in: An Introduction to Geometric Measure Theory, in: Cambridge Stud. Adv. Math., vol. 135, Cambridge University Press, Cambridge, 2012.
[15] F. Morgan, Regularity of isoperimetric hypersurfaces in Riemannian manifolds, Trans. Amer. Math. Soc. 355 (12) (2003) 5041-5052.
[16] F. Morgan, Isoperimetric estimates in products, Ann. Global Anal. Geom. 30 (1) (2006) 73-79.
[17] F. Morgan, Geometric Measure Theory, fourth edition, Elsevier/Academic Press, Amsterdam, 2009. A beginner's guide.
[18] F. Morgan, A. Ros, Stable constant-mean-curvature hypersurfaces are area minimizing in small $L^{1}$ neighborhoods, Interfaces Free Bound. 12 (2) (2010) 151-155.
[19] R.H.L. Pedrosa, M. Ritoré, Isoperimetric domains in the Riemannian product of a circle with a simply connected space form and applications to free boundary problems, Indiana Univ. Math. J. 48 (4) (1999) 1357-1394.
[20] M. Ritoré, E. Vernadakis, Isoperimetric inequalities in convex cylinders and cylindrically bounded convex bodies, Calc. Var. Partial Differential Equations 54 (1) (2015) 643-663.
[21] M. Ritoré, E. Vernadakis, Isoperimetric inequalities in Euclidean convex bodies, Trans. Amer. Math. Soc. 367 (7) (2015) 4983-5014.
[22] A. Ros, The isoperimetric problem, in: Global Theory of Minimal Surfaces, in: Clay Math. Proc., vol. 2, Amer. Math. Soc., Providence, RI, 2005, pp. 175-209.
[23] B. White, A strong minimax property of nondegenerate minimal submanifolds, J. Reine Angew. Math. 457 (1994) 203-218.


[^0]:    th Both authors have been supported by MICINN-FEDER MTM2010-21206-C02-01 and MINECO-FEDER MTM2013-48371-C2-1-P grants, and by Junta de Andalucía grants FQM-325 and P09-FQM-5088.

    * Corresponding author.

    E-mail addresses: ritore@ugr.es (M. Ritoré), stratos@ugr.es (E. Vernadakis).

