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## Joint numerical range and its generating hypersurface

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### ABSTRACT

In this paper, we study the joint numerical range of  $m$ -tuples of Hermitian matrices via their generating hypersurfaces. An example is presented which shows the invalidity of an analogous Kippenhahn theorem for the joint numerical range of three Hermitian matrices.

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## 1. Introduction

Let  $T$  be an  $n \times n$  complex matrix. The classical numerical range of  $T$  is defined as the set

$$W(T) = \{ \xi^* T \xi : \xi \in \mathbf{C}^n, \xi^* \xi = 1 \}.$$

The numerical range  $W(T)$  provides various information on the structure of the matrix  $T$  and localization of the eigenvalues of  $T$  (cf. [8]). One of the important generalizations of classical numerical range is the joint numerical range. Suppose that  $n$  and  $m$  are positive integers and  $(H_1, H_2, \dots, H_m)$  is an ordered  $m$ -tuple of  $n \times n$  Hermitian matrices. The *joint numerical range* of  $H_1, H_2, \dots, H_m$  is defined as the set

$$W(H_1, H_2, \dots, H_m) = \{ (\xi^* H_1 \xi, \xi^* H_2 \xi, \dots, \xi^* H_m \xi) \in \mathbf{R}^m : \xi \in \mathbf{C}^n, \xi^* \xi = 1 \}.$$

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The joint numerical range is not necessarily convex (cf. [6,11–13]). If  $m = 2$  then the range is convex (cf. [7,15]). It is also known that if  $m = 3$  and  $n \geq 3$ , the range  $W(H_1, H_2, H_3)$  is convex too (cf. [2,3]). The structure of the joint numerical range  $W(H_1, H_2, (H_1 + iH_2)^*(H_1 + iH_2))$  is closely related with the so called  $q$ -numerical range of the  $n \times n$  matrix  $T = H_1 + iH_2$  (cf. [5]).

We introduce a homogeneous polynomial

$$\begin{aligned}
 F(y_0, y_1, y_2, \dots, y_m) &= F(y_0, y_1, y_2, \dots, y_m : H_1, H_2, \dots, H_m) \\
 &= \det(y_0 I_n + y_1 H_1 + y_2 H_2 + \dots + y_m H_m)
 \end{aligned}
 \tag{1}$$

associated with the  $m$ -tuple of Hermitian matrices  $(H_1, H_2, \dots, H_m)$ . This form is *hyperbolic* with respect to the point  $(1, 0, 0, \dots, 0) \in \mathbf{R}^{m+1}$  (cf. [1]), that is,

- (i)  $F(1, 0, \dots, 0) \neq 0$ .
- (ii) Every root of the equation  $F(t, y_1, y_2, \dots, y_m) = 0$  in  $t$  is real for an arbitrary fixed  $(y_1, y_2, \dots, y_m) \in \mathbf{R}^m$ .

Suppose that

$$F(y_0, y_1, y_2, \dots, y_m) = \prod_{j=1}^p F_j(y_0, y_1, y_2, \dots, y_m)^{m_j},$$

and

$$F_0(y_0, y_1, y_2, \dots, y_m) = \prod_{j=1}^p F_j(y_0, y_1, y_2, \dots, y_m),
 \tag{2}$$

are respectively the irreducible decomposition and reduced polynomial of the form  $F$  in the polynomial ring  $\mathbf{C}[y_0, y_1, \dots, y_m]$ , where  $F_j$  are mutually distinct irreducible factors and  $m_j$  are their multiplicities. It is known that each factor  $F_j$  has a non-zero scalar  $c_j$  for which  $c_j F_j$  is a real polynomial. Hence we may assume that  $F_j$ 's are real polynomials. It is also known that all factors  $F_j$  are hyperbolic with respect to  $(1, 0, \dots, 0)$ . We consider the algebraic variety

$$S_F = S_{F_0} = \{(y_0, y_1, \dots, y_m) \in \mathbf{C}P^m : F_0(y_0, y_1, \dots, y_m) = 0\},$$

where  $[(y_0, y_1, \dots, y_m)]$  is the equivalence class containing  $(y_0, y_1, \dots, y_m) \in \mathbf{C}^{m+1} - (0, \dots, 0)$  under the relation  $(y_0, y_1, \dots, y_m) \sim (z_0, z_1, \dots, z_m)$  if  $(y_0, y_1, \dots, y_m) = k(z_0, z_1, \dots, z_m)$  for some nonzero complex number  $k$ . The dual surface  $S_F^\wedge$  of the form  $F(1)$  is the set of points  $(x_0, x_1, x_2, \dots, x_m) = (1, x_1, x_2, \dots, x_m)$  for which the hyperplane  $y_1 x_1 + y_2 x_2 + \dots + y_m x_m + y_0 x_0 = 0$  is tangent to  $S_F$  at a non-singular point of  $S_F$ . The real affine part  $S_F^\wedge(\mathbf{R})$  of  $S_F^\wedge$  is called the *boundary generating hypersurface* of  $W(H_1, H_2, \dots, H_m)$ . The main aim of this paper is the treatment of the joint numerical range  $W(H_1, H_2, \dots, H_m)$  via the hypersurface  $S_F$  and the boundary generating hypersurface  $S_F^\wedge$ .

### 2. Boundary generating hypersurface

Let  $F(y_0, y_1, y_2, \dots, y_m)$  be an irreducible homogeneous polynomial. A point  $(1, x_1, \dots, x_m) \in \mathbf{R}^{m+1}$  is a singular real point of the surface  $S_F$  if

$$F(1, x_1, x_2, \dots, x_m) = F_{y_i}(1, x_1, x_2, \dots, x_m) = 0,$$

where  $F_{y_i}$  denotes the partial derivative of  $F$  with respect to  $y_i$ ,  $i = 0, 1, \dots, m$ .

At first, we obtain a result for  $m = 2$ .

**Theorem 2.1.** *Let  $F_0(y_0, y_1, y_2)$  be the reduced real form (2) for  $m = 2$ . If  $(a_0, a_1, a_2)$  is a real singular point of the curve  $S_{F_0}$  then the curve  $S_{F_0}$  is expressed as the union of analytically parametrized arcs*

$$(a_0^{(j)}, a_1^{(j)}, a_2^{(j)}) = (f_j(t), g_j(t), h_j(t)), \quad j = 1, 2, \dots, \ell, \quad |t| < \epsilon$$

near the points  $(a_0, a_1, a_2)$  satisfying

$$(f_j(0), g_j(0), h_j(0)) = (a_0, a_1, a_2) \quad \text{and} \quad (f'_j(0), g'_j(0), h'_j(0)) \neq (0, 0, 0).$$

**Proof.** We prove this theorem by the Newton–Puiseux method. By a real transformation, we may assume that  $(a_0, a_1, a_2) = (a_0, 1, 0)$  and  $F(y_0, 1, 0) = (y_0 - a_0)^\ell (y_0 - t_1) \cdots (y_0 - t_q)$  for some real numbers  $t_j \neq a_0, j = 1, \dots, q$ . By the Newton–Puiseux method, we solve the equation

$$F(y_0, 1, y_2) = y_0^{\ell+q} + f_1(y_2)y_0^{\ell+q-1} + \cdots + f_{\ell+q}(y_2) = 0$$

in  $y_0$ . Then the solutions are expressed in Puiseux series. We are interested in  $\ell$  solutions corresponding to  $y_0 = a_0$  for  $y_2 = 0$ . Each of the  $\ell$  solutions is expressed as a fractional power series

$$y_0 = g_j(y_2) = a_0 + b_1^{(j)}y_2^{1/p} + b_2^{(j)}y_2^{2/p} + b_3^{(j)}y_2^{3/p} + \cdots, \tag{3}$$

where  $p$  is a natural number and  $b_k^{(j)}$  are real coefficients (cf. [16, pp. 98–106]). As a function of  $y_2^{1/p}$ , the series (3) converges absolutely on some disc  $|y_2^{1/p}| < \epsilon$ . We assume that the greatest common divisor of  $\{k \in \mathbf{N} : b_k^{(j)} \neq 0\} \cup \{p\}, j = 1, 2, \dots, \ell$ , is 1. If  $p = 1$  for every  $1 \leq j \leq \ell$ , then by taking the variable  $t = y_2$ , we have nothing to prove. We assume that  $p \geq 2$  for some  $j$ . Then we have the following equation for every  $p$ th root  $\eta$  of 1:

$$F(a_0 + b_1^{(j)}\eta t + b_2^{(j)}\eta^2 t^2 + b_3^{(j)}\eta^3 t^3 + \cdots, 1, t^p) = 0$$

(cf. [16, p. 107]). By the hyperbolicity of  $F$ , the series

$$a_0 + b_1^{(j)}\eta t + b_2^{(j)}\eta^2 t^2 + b_3^{(j)}\eta^3 t^3 + \cdots$$

takes real value for every  $t \in \mathbf{R}$ . By repeating differentiation of this relation with respect to  $t$ , it implies that  $b_k^{(j)} \exp(i2kh\pi/p) \in \mathbf{R}$  for every  $k \in \mathbf{N}$  and  $h \in \mathbf{Z}$ . Hence  $2k$  is a multiple of  $p$  for every  $k$  with  $b_k^{(j)} \neq 0$ . We set  $\zeta = 1$  if  $p$  is odd and  $\zeta = 2$  if  $p$  is even. Then the above relation implies that  $p/\zeta$  is a common divisor of  $\{k \in \mathbf{N} : b_k^{(j)} \neq 0\}$ . By the assumption on the coefficients  $b_k^{(j)}$ , we have  $p = 2$  and  $b_{2k-1}^{(j)} \neq 0$  for some  $k \in \mathbf{N}$ . Under this condition, we obtain that

$$F(a_0 + b_1^{(j)}t + b_2^{(j)}t^2 + b_3^{(j)}t^3 + \cdots, 1, t^2) = 0,$$

$$F(a_0 + ib_1^{(j)}t - b_2^{(j)}t^2 - ib_3^{(j)}t^3 + \cdots, 1, (it)^2) = 0$$

for every  $t \in \mathbf{R}$ . By the hyperbolicity of  $F$ , we have  $b_k^{(j)} \in \mathbf{R}$  and  $i^k b_k^{(j)} \in \mathbf{R}$  for every  $k$ , and hence  $b_{2k-1} = 0$ , a contradiction. Thus we conclude that  $p = 1$  for every  $1 \leq j \leq \ell$ .  $\square$

Theorem 2.1 is related to Rellich’s theorem (cf. [9,14]). However the above proof does not depend on the properties of Hermitian matrices.

For general  $m$  and  $n$ , we consider the convex hull  $\text{conv}(W(H_1, H_2, \dots, H_m))$  of the compact set  $W(H_1, H_2, \dots, H_m)$ . By the separation theorem for compact convex sets, we have that

$$\begin{aligned} &\text{conv}(W(H_1, H_2, \dots, H_m)) \\ &= \{(x_1, x_2, \dots, x_m) \in \mathbf{R}^m : c_1x_1 + c_2x_2 + \cdots + c_mx_m \leq g(c_1, c_2, \dots, c_m), \\ &\quad (c_1, c_2, \dots, c_m) \text{ is a unit vector in } \mathbf{R}^m\}, \end{aligned}$$

where

$$\begin{aligned} &g(c_1, c_2, \dots, c_m) \\ &= \max\{c_1y_1 + c_2y_2 + \cdots + c_my_m : (y_1, y_2, \dots, y_m) \in W(H_1, H_2, \dots, H_m)\} \\ &= \max\{\xi^*(c_1H_1 + c_2H_2 + \cdots + c_mH_m)\xi : \xi \in \mathbf{C}^n, \xi^*\xi = 1\} \\ &= \max \sigma(c_1H_1 + c_2H_2 + \cdots + c_mH_m). \end{aligned}$$

The dual set of the convex hull of the joint numerical range is defined and denoted as

$$\begin{aligned} & \text{conv}(W(H_1, H_2, \dots, H_m))^\wedge \\ &= \{(y_1, y_2, \dots, y_m) \in \mathbf{R}^m : x_1y_1 + x_2y_2 + \dots + x_my_m + 1 \geq 0, \\ & \quad (x_1, x_2, \dots, x_m) \in W(H_1, H_2, \dots, H_m)\} \\ &= \{(y_1, y_2, \dots, y_m) \in \mathbf{R}^m : \xi^*(y_1H_1 + y_2H_2 + \dots + y_mH_m + I_n)\xi \geq 0, \xi \in \mathbf{C}^n\} \\ &= \{(y_1, y_2, \dots, y_m) \in \mathbf{R}^m : y_1H_1 + y_2H_2 + \dots + y_mH_m + I_n \text{ is positive semidefinite.} \end{aligned}$$

This dual set is a closed convex set, and every point  $(y_1, y_2, \dots, y_m)$  on the boundary of  $\text{conv}(W(H_1, H_2, \dots, H_m))^\wedge$  satisfies

$$\det(I_n + y_1H_1 + y_2H_2 + \dots + y_mH_m) = 0. \tag{4}$$

We consider the open set

$$\Omega = \{(y_1, y_2, \dots, y_m) \in \mathbf{R}^m : F(1, y_1, y_2, \dots, y_m : H_1, H_2, \dots, H_m) \neq 0\}.$$

The interiors of  $\text{conv}(W(H_1, H_2, \dots, H_m))^\wedge$  are contained in  $\Omega$ , and by Corollary 3.2 in [1], the set of the interiors coincides with the connected component  $\Omega_0$  of  $\Omega$  containing the origin  $(0, \dots, 0)$ . Moreover we have that

$$\text{conv}(W(H_1, H_2, \dots, H_m))^\wedge = \text{closure}(\Omega_0) = \text{conv}(\partial\Omega_0), \tag{5}$$

$$\text{conv}(W(H_1, H_2, \dots, H_m)) = \text{conv}(\partial\Omega_0)^\wedge. \tag{6}$$

These facts provide an algebraic method to determine all supporting hyperplanes of  $\text{conv}(W(H_1, \dots, H_m))$ .

**Theorem 2.2.** *Let  $F_0(y_0, y_1, y_2, \dots, y_m)$  be the reduced real form (2). Suppose that  $(a_0, a_1, \dots, a_m) \in \mathbf{R}^{m+1}$  is a non-singular real point of  $S_{F_0}$  with  $(a_1, \dots, a_m) \neq (0, \dots, 0)$  and  $\alpha_0y_0 + \alpha_1y_1 + \dots + \alpha_my_m = 0$  is the equation of the tangent hyperplane of  $S_{F_0}$  at this point. Then this hyperplane does not pass through any point of  $\Omega_0$ .*

**Proof.** Suppose, on the contrary, the hyperplane passes through a point of  $\Omega_0$ . Since the form  $F_0$  is hyperbolic with respect to every point of  $\Omega_0$  (cf. [1, p. 133]), we may assume that the hyperplane passes through the point  $(1, 0, \dots, 0)$  by using a real projective transformation. We may also assume that  $(a_0, a_1, a_2, \dots, a_m) = (1, 1, 0, \dots, 0)$ . The line joining the two points  $(a_0, a_1, \dots, a_m) = (1, 0, \dots, 0)$  and  $(1, 1, 0, \dots, 0)$  is contained in the tangent hyperplane. Define a polynomial  $f(t, y_2, \dots, y_m)$  by

$$f(t, y_2, \dots, y_m) = F_0(t, 1, y_2, \dots, y_m).$$

It is obvious that  $f(1, 0, \dots, 0) = 0$  and  $f_t(1, 0, \dots, 0) = 0$ . Since  $(a_0, a_1, \dots, a_m) = (1, 1, 0, \dots, 0)$  is a non-singular point of  $S_{F_0}$ , it follows that  $f_{y_j}(1, 0, \dots, 0) \neq 0$  for some  $2 \leq j \leq m$ . By using a rotation, we may assume that  $j = 2$ . Then the ternary form  $\tilde{F}(t, y_1, y_2) = F_0(t, y_1, y_2, 0, \dots, 0)$  is hyperbolic with respect to  $(1, 0, 0)$ , and the point  $(a_0, a_1, a_2) = (1, 1, 0)$  is a non-singular point of  $S_{\tilde{F}}$  and the tangent line of  $S_{\tilde{F}}$  at this point is  $y_2 = 0$ . Set  $n = \text{deg}(F_0)$ . By the hyperbolicity, the equation

$$\tilde{f}(t, y) = F_0(t, 1, y, 0, \dots, 0) = 0$$

in  $t$  has  $n$  real solutions counting multiplicity for every  $y \in \mathbf{R}$ . It implies geometrically that the real affine algebraic curve  $\tilde{f}(t, y) = 0$  and the real line  $y = y_0$  intersect at  $n$  points counting multiplicity for every  $y_0 \in \mathbf{R}$ . By Theorem 2.1, even if the line  $y = 0$  has singular points of the curve  $\tilde{f}(t, y) = 0$ , the real affine curve  $\tilde{f}(t, y) = 0$  is expressed as the union of analytic arcs near the singular points. So we can treat such a case in the same fashion. By the assumption

$$\tilde{f}(t, 0) = (t - \alpha_1)^{m_1} (t - \alpha_2)^{m_2} \dots (t - \alpha_k)^{m_k},$$

where  $\alpha_1, \alpha_2, \dots, \alpha_k$  are distinct real numbers and  $\alpha_1 = 1$ , the numbers  $m_1, m_2, \dots, m_k$  are positive integers satisfying  $m_1 \geq 2, m_1 + m_2 + \dots + m_k = n$ . If  $(t_j, 0)$  is a non-singular point of the curve

$\tilde{f}(t, y) = 0$ , we define two numbers  $N_+(m_j) = 1$  and  $N_-(m_j) = 1$  for odd number  $m_j, j = 1, \dots, k$ . If  $m_j$  is even, the implicit function  $y = y_j(t)$  defined by  $\tilde{f}(t, y) = 0$  near  $t = \alpha_j$  satisfies

$$\frac{d^{m_j}y}{dt^{m_j}}(\alpha_j) > 0, \quad \text{or} \quad \frac{d^{m_j}y}{dt^{m_j}}(\alpha_j) < 0.$$

If  $\frac{d^{m_j}y}{dt^{m_j}}(\alpha_j) > 0$ , we set  $N_+(m_j) = 2$  and  $N_-(m_j) = 0$ . If  $\frac{d^{m_j}y}{dt^{m_j}}(\alpha_j) < 0$ , we set  $N_+(m_j) = 0$  and  $N_-(m_j) = 2$ . In the case  $(t_j, 0)$  is a singular point of the curve  $\tilde{f}(t, y) = 0$ , we express the curve  $\tilde{f}(t, y) = 0$  as the union of analytic arcs, and set  $\tilde{m}_j$  the multiplicity of the intersection of the arc and the line  $y = 0$  at  $(t_j, 0)$ . We define  $N_+(m_j), N_-(m_j)$  as the sum of the numbers  $\tilde{N}_+(\tilde{m}_j), \tilde{N}_-(\tilde{m}_j)$  defined for each arc as in the above fashion. Then the number of the intersection points of the curve  $\tilde{f}(t, y) = 0$  and the curve  $y = y_0$  is

$$N_+(m_1) + N_+(m_2) + \dots + N_+(m_k) \tag{7}$$

if  $y_0 > 0$  is sufficiently small, and

$$N_-(m_1) + N_-(m_2) + \dots + N_-(m_k) \tag{8}$$

if  $y_0 < 0$  and  $|y_0|$  is sufficiently small. One of the numbers (7) and (8) is strictly less than  $n$ , a contradiction to the hyperbolicity of  $\tilde{F}$ .  $\square$

By the argument used in the proof of Theorem 2.2, we obtain the following corollary.

**Corollary 2.3.** *Let  $F_0(y_0, y_1, y_2)$  be the reduced real form (2) for  $m = 2$ . If  $(a_0, a_1, a_2)$  is a non-singular real point of the curve  $S_{F_0}$  then any tangent line of the curve  $S_{F_0}$  at  $(a_0, a_1, a_2)$  does not pass through any point of  $\Omega_0$ .*

In particular, we improve the result of Theorem 2.2 for  $m = 2$ .

**Theorem 2.4.** *Let  $F_0(y_0, y_1, y_2)$  be the reduced real form (2) for  $m = 2$ . Suppose that  $\alpha_0 y_0 + \alpha_1 y_1 + \alpha_2 y_2 = 0$  is the common real tangent of a pair of imaginary non-singular point  $(a_0, a_1, a_2)$  of the curve  $S_{F_0}$  and its conjugate, or  $\alpha_0 y_0 + \alpha_1 y_1 + \alpha_2 y_2 = 0$  is a real tangent of imaginary singular point  $(a_0, a_1, a_2)$  and its conjugate. Then the tangent line does not pass through any point of  $\Omega_0$ .*

**Proof.** We may assume that the tangent line passes through the point  $(y_0, y_1, y_2) = (1, 0, 0)$ . By a real transformation, we assume that the equation of the tangent line is given by  $y_1 = 0$  and the point of  $S_{F_0}$  is  $(a_0, 0, a_2)$ . If  $a_0 = 0$ , then the point is given by  $(0, 0, 1)$  which is real, contradicting the assumption. Thus we have that  $a_0 \neq 0$ . Since  $F_0(1, 0, 0) \neq 0$ , the coordinate  $a_2$  does not vanish. So we may assume that  $a_2 = 1$  and  $a_0$  is imaginary. But this implies that the equation  $F_0(t, 0, 1) = 0$  in  $t$  has an imaginary solution which contradicts the hyperbolicity of  $F_0$ .  $\square$

**Corollary 2.5.** *Let  $F(y_0, y_1, y_2)$  be the polynomial (1) for  $m = 2$ . If  $(x_0, x_1, x_2) = (1, x_1, x_2)$  is a real affine point of  $S_F^\wedge$  for the form  $F(y_0, y_1, y_2)$  then the point  $(x_1, x_2)$  belongs to the numerical range  $W(H_1, H_2)$ .*

**Proof.** If the point  $(x_1, x_2)$  does not belong to the compact convex set  $W(H_1, H_2)$ , then by the duality of the closed convex sets, there exists a point  $(\tilde{y}_1, \tilde{y}_2)$  of the closure of the convex set  $\Omega_0$  such that

$$x_1 \tilde{y}_1 + x_2 \tilde{y}_2 + 1 < 0.$$

Further, the point  $(y_1^{(0)}, y_2^{(0)}) = (0, 0) \in \Omega_0$  satisfies

$$x_1 y_1^{(0)} + x_2 y_2^{(0)} + 1 = 1.$$

By the convexity of the open set  $\Omega_0$ , there exists a point  $(\hat{y}_1, \hat{y}_2)$  in the line segment joining the above two points satisfying

$$x_1\hat{y}_1 + x_2\hat{y}_2 + 1 = 0.$$

The point  $(\hat{y}_1, \hat{y}_2)$  belongs to  $\Omega_0$ , which contradicts Corollary 2.3 and Theorem 2.4.  $\square$

The result of Corollary 2.5 was obtained by Kippenhahn in [10]. However, its proof is rather intuitive. The proof provided here is more rigorous.

We come back to a general situation. For each irreducible form  $F_j$ , we consider the linear reduction of variables. If

$$F_j(y_0, y_1, \dots, y_{m-1}, y_m) = F_j(y_0 + \alpha_0 y_m, y_1 + \alpha_1 y_m, \dots, y_{m-1} + \alpha_{m-1} y_m, 0)$$

or equivalently

$$\partial F_j / \partial y_m = \alpha_0 \partial F_j / \partial y_0 + \dots + \alpha_{m-1} \partial F_j / \partial y_{m-1}.$$

Then the number of essential variables for  $F_j$  is less than  $m$ . We consider whether there exist non-zero coefficients  $(\alpha_0, \alpha_1, \dots, \alpha_m)$  for which

$$\alpha_0 \partial F_j / \partial y_0 + \dots + \alpha_m \partial F_j / \partial y_m = 0.$$

Such a reduction example actually appeared in [6]. The dual algebraic object  $S_F^\wedge$  of  $S_F$  is defined as the union of the dual algebraic varieties  $S_{F_j}^\wedge$ . Each algebraic variety

$$S_{F_j}^\wedge = \{(x_0, x_1, \dots, x_m) \in \mathbf{CP}^m : G_{j,k}(x_0, x_1, \dots, x_m) = 0, k = 0, 1, 2, \dots, \ell_j\}$$

is characterized by irreducible form  $G_{j,0}$  and linear forms  $G_{j,1}, \dots, G_{j,\ell_j}$  satisfying

$$G_{j,k}(a_0, a_1, \dots, a_m) = 0, \quad k = 0, 1, \dots, \ell_j$$

for every tangent hyperplane  $a_0 y_0 + a_1 y_1 + \dots + a_m y_m = 0$  at a non-singular point of  $S_{F_j}$ .

**Theorem 2.6.** *Let  $F(y_0, y_1, y_2, \dots, y_m)$  be the polynomial (1). Suppose that  $(x_0, x_1, \dots, x_m) = (1, x_1, \dots, x_m)$  is a real affine point of  $S_F^\wedge$  for which  $x_1 y_1 + \dots + x_m y_m + 1 = 0$  is a tangent hyperplane of  $S_F$  at some non-singular real point of  $S_F$ . Then the point  $(x_1, \dots, x_m)$  belongs to the convex hull of  $W(H_1, \dots, H_m)$ .*

**Proof.** If the point  $(x_1, \dots, x_m)$  does not belong to the convex hull of  $W(H_1, \dots, H_m)$ , by the duality of the closed convex sets, there exists a point  $(\tilde{y}_1, \dots, \tilde{y}_m)$  of the closure of the convex set  $\Omega_0$  such that

$$x_1 \tilde{y}_1 + \dots + x_m \tilde{y}_m + 1 < 0.$$

Further, the point  $(y_1^{(0)}, \dots, y_m^{(0)}) = (0, \dots, 0) \in \Omega_0$  satisfies

$$x_1 y_1^{(0)} + \dots + x_m y_m^{(0)} + 1 = 1.$$

By the convexity of the open set  $\Omega_0$ , there exists a point  $(\hat{y}_1, \dots, \hat{y}_m)$  in the line segment joining the above two points satisfying

$$x_1 \hat{y}_1 + \dots + x_m \hat{y}_m + 1 = 0.$$

The point  $(\hat{y}_1, \dots, \hat{y}_m)$  belongs to  $\Omega_0$ , which contradicts Theorem 2.2.  $\square$

### 3. Example

If the polynomial  $F$  is a non-linear irreducible form and the hypersurface  $S_F$  has no singular point, then  $S_F^\wedge$  is defined by a single form  $G \in \mathbf{C}[x_0, x_1, \dots, x_m]$  and its degree is  $n(n-1)^{m-1}$  (cf. [4, p. 253]). In this case, the multiplicity of the maximal eigenvalue of the Hermitian matrix  $y_1 H_1 + y_2 H_2 + \dots + y_m H_m$  is 1 for every unit vector  $(y_1, y_2, \dots, y_m) \in \mathbf{R}^m$ . Provided that  $n \geq 3$ , it implies the convexity of the joint numerical range  $W(H_1, H_2, \dots, H_m)$  by Theorem 5.1 in [6] and the range coincides with the closed domain surrounded by the boundary generating hypersurface  $S_F^\wedge(\mathbf{R})$ .

Suppose that  $(x_0, x_1, x_2, x_3) = (1, x_1, x_2, x_3)$  is a real affine point of  $S_F^\wedge$  and  $(x_0, x_1, x_2, x_3)$  lies on the hyperplane  $y_1x_1 + y_2x_2 + y_3x_3 + y_0x_0 = 0$  where  $(y_0, y_1, y_2, y_3)$  is a real singular point of  $S_F$ . It may occur that the point  $(x_1, x_2, x_3)$  does not belong to the convex hull of  $W(H_1, H_2, H_3)$ . We provide such an example in the below, which shows an analogous property of Kippenhahn’s result does not hold for  $m = 3$ .

**Example.** Let

$$H_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad H_2 = \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix} \quad \text{and} \quad H_3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Then the form  $F(y_0, y_1, y_2, y_3)$  (1) associated to these Hermitian matrices is given by

$$F(y_0, y_1, y_2, y_3) = y_0^3 + y_0^2y_3 - 2y_0y_1^2 - y_0y_2^2 - y_1^3 - y_1^2y_2 + y_1y_2^2.$$

The cubic surface  $S_F$  has a biplanar double point at  $(y_0, y_1, y_2, y_3) = (0, 0, 0, 1)$  and an ordinary double point at  $(y_0, y_1, y_2, y_3) = (1, -1, 0, -1/2)$  (cf. [4]). The boundary of the joint numerical range has a flat portion on the plane

$$-x_1 - \frac{1}{2}x_3 + 1 = 0$$

and its projection on the  $(x_1, x_2)$  plane is the elliptical disc bounded by the curve

$$20x_1^2 - 32x_1 + x_2^2 + 12 = 0.$$

However the plane  $x_3 = 0$  supports the range  $W(H_1, H_2, H_3)$  and its intersection with the range is not a single point, it is a line segment

$$\{(x_1, 0, 0) : -1 \leq x_1 \leq 1\}.$$

One end point  $(1, 0, 0)$  of the above line belongs also to the flat portion. The equation of the dual surface of the cubic surface  $S_F$  is given by

$$G(1, x_1, x_2, x_3) = 20x_3^4 - 8x_1x_3^3 - 24x_2^3 + 4x_1^2x_3^2 + 8x_2^2x_3^2 + 8x_1x_3^2 + 4x_3^2 - 4x_1x_2^2x_3 - 4x_2^2x_3 + x_2^4.$$

Since  $G(1, x_1, x_2, 0) = x_2^4$ , the line  $x_2 = 0$  on the plane  $x_3 = 0$  is contained in the quartic surface  $S_F^\wedge(\mathbf{R})$ . Thus this surface contains a point  $(x_1, x_2, x_3) = (2, 0, 0) \notin W(H_1, H_2, H_3)$ .

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