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The complexity of the *T*-coloring problem for graphs with small degree

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Abstract

In the paper we consider a generalized vertex coloring model, namely T-coloring. For a given finite set T of nonnegative integers including 0, a proper vertex coloring is called a T-coloring if the distance of the colors of adjacent vertices is not an element of T. This problem is a generalization of the classic vertex coloring and appeared as a model of the frequency assignment problem. We present new results concerning the complexity of T-coloring with the smallest span on graphs with small degree Δ . We distinguish between the cases that appear to be polynomial or NP-complete. More specifically, we show that our problem is polynomial on graphs with $\Delta \leq 2$ and in the case of k-regular graphs it becomes NP-hard even for every fixed T and every k > 3. Also, the case of graphs with $\Delta = 3$ is under consideration. Our results are based on the complexity properties of the homomorphism of graphs. © 2003 Published by Elsevier B.V.

Keywords: Vertex coloring; T-coloring; T-span; Homomorphism; NP-completeness

1. Introduction

We consider the T-coloring problem, as a generalized classical vertex coloring problem, which is one of the variants of the channel assignment problem in broadcast networks [8,16]. In this problem one wishes to assign to each transmitter $x_i \in \{x_1, \ldots, x_n\}$, located in a region, a frequency $f(x_i)$ avoiding interference between transmitters, i.e.

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¹ Supported by FNP.

two interfering transmitters (because of proximity, meteorological or other reasons) must be assigned frequencies so that the distance between them does not belong to the forbidden set T of nonnegative integers including 0. The most common objective is to minimize the span of a frequency band. For more about applications of this problem the reader is referred to [2,3,14,15].

Let G = (V, E) be a simple loopless graph with vertex set V = V(G) and edge set E = E(G). By $\Delta(G)$ we mean the maximum degree $\rho(v)$ over all vertices v of graph G, by $\chi(G)$ and $\omega(G)$ we denote the chromatic number and the clique number of graph G, respectively. Let G(W) denote the subgraph of graph G induced by $W \subset V$.

Definition 1. Let T be a finite set of nonnegative integers satisfying $0 \in T$. By a T-coloring of graph G we mean a vertex coloring $c: V \to \mathbb{N}$ satisfying $|c(v) - c(w)| \notin T$, whenever $\{v, w\} \in E$. The T-span is defined as $\operatorname{sp}_T(G) = \min_c \operatorname{sp}_T(G, c)$, where $\operatorname{sp}_T(G, c) = \max_c c(V) - \min_c c(V)$ and c is a proper vertex T-coloring of graph G. A T-coloring c is said to be optimal if $\operatorname{sp}_T(G, c) = \operatorname{sp}_T(G)$.

Following [13] we introduce the notion of T-graphs.

Definition 2. For a given set T, we define an infinite T-graph G_T , with vertex set $V(G_T) = \mathbb{N} \cup \{0\}$ and edge set $E(G_T) = \{\{x, y\} : |x - y| \notin T\}$. By G_T^{d+1} we mean the subgraph of G_T induced by $\{0, \dots, d\}$.

Given a graph G, set T and positive integer k, the problem of verifying the inequality $\operatorname{sp}_T(G) \leq k$ we call the T-Span Problem. This differs from the T-Coloring Problem, which requires an optimal T-coloring as its output. The notion of a T-coloring was introduced in [8]. The problem has been studied extensively (see [3,4,12,13–18]). The majority of results concern lower and upper bounds on $sp_T(G)$, see [3,11,17]. The first complexity result comes independently from [6,12], where the authors showed NP-completeness in the strong sense of the T-SPAN PROBLEM on complete graphs (so even a pseudopolynomial algorithm for the T-SPAN PROBLEM cannot exist unless P=NP). We call the above problems Fixed T-Span Problem and Fixed T-Coloring Problem if set T is fixed. Furthermore, in [7] the authors have developed a linear algorithm for solving the Fixed T-Coloring Problem on complete graphs (but exponential with respect to max T). So far, the problem on graphs with "small" degree has been still open. Therefore, in Sections 2 and 3 we deal with some new properties of homomorphisms and in Section 5 we show NP-completeness of the Fixed T-Span Problem on subcubic graphs (i.e. with $\Delta \leq 3$), and r-regular graphs (i.e. with all vertices of degree r) with $r \ge 3$. In Section 4 we show a polynomial time algorithm for the T-Coloring PROBLEM on graphs with $\Delta \leq 2$.

2. Simple properties of graph homomorphisms

The idea of graph homomorphism is a generalization of vertex coloring. Moreover, it generalizes the T-coloring problem as well.

Definition 3. For two simple graphs G and H a graph homomorphism is a function $h: V(G) \to V(H)$ such that $\{h(v), h(w)\} \in E(H)$, whenever, $\{v, w\} \in E(G)$ for all $v, w \in V(G)$.

We write $G \to H$ if there exists a homomorphism from G to H. Furthermore, if the homomorphism is onto, then it is called an *epimorphism*. In addition, if there exists h^{-1} and it is a homomorphism from H to G, then we call it an *isomorphism* and graphs G and H are said to be isomorphic, in symbols $G \simeq H$. We write $H \subset G$ if H is isomorphic to any subgraph of G.

There is a straightforward equivalence between the properties of T-span and the existence of homomorphism from G to G_T^{d+1} (see [13]).

Proposition 4. Given a graph G, any set T and a nonnegative integer d we have $\operatorname{sp}_T(G) \leq d$ if and only if $G \to G_T^{d+1}$.

Let us note that if $T = \{0\}$, then the T-coloring problem reduces to the well-known vertex coloring problem, and moreover $G_T^{d+1} \simeq K_{d+1}$. Thus we get

Corollary 5. Given a graph G and a positive integer d we have $\chi(G) \leq d$ if and only if $G \to K_d$.

The composition of graph homomorphisms is still a graph homomorphism. Moreover, an image of a complete graph under a homomorphism is a complete graph with the same number of vertices so

Corollary 6. *If* $K_n \to G$ *then* $K_n \tilde{\subset} G$.

And

Proposition 7. If $h: V(G) \to V(H)$ is a homomorphism then $\psi(G) \leq \psi(H(h(V(G))))$, where ψ is any of the functions from the list $\{\chi, \omega, \operatorname{sp}_T\}$.

From the above is easy to see that if $G \to H$ and H is bipartite, then graph G is bipartite. Concluding this section note an important upper bound proved in [17].

Theorem 8 (Tesman [17]). For any given graph G and set T the following inequality holds

$$\operatorname{sp}_{T}(G) \leq |T| \cdot (\chi(G) - 1).$$

Let us also recall that

Theorem 9 (Brooks). If G is a connected graph that is neither a complete graph nor an odd cycle, then $\gamma(G) \leq \Delta(G)$.

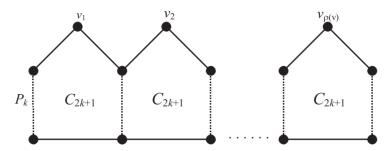


Fig. 1. Graph A_n^k replacing the vertex v.

3. Homomorphisms into odd cycles

The problem of graph homomorphism is considered in [1,5]. Let H be a fixed graph, the decision problem of the existence of a homomorphism from G to H will be denoted Hom(H), where G is any graph from the specified family. The most important result comes from [9].

Theorem 10 (Hell and Nesetril [9]). The problem Hom(H) on arbitrary graphs is polynomial, whenever H is bipartite, otherwise it is NP-complete.

In this section we prove that the problem $\operatorname{Hom}(C_{2k+1})$ on subcubic graphs is NP-complete for every positive integer $k \geq 2$, in contrast to the problem $\operatorname{Hom}(C_3)$, which is polynomial. Moreover, we prove analogous result for 3-regular graphs and NP-completeness of the problem $\operatorname{Hom}(C_{2k+1})$ on r-regular graphs, for every $r \geq 4$ and $k \geq 1$.

We start with a general construction. Let G be an arbitrary graph and k be any positive integer greater than 1. We replace each vertex $v \in V(G)$ of degree $\rho(v)$ with the graph A_v^k shown in Fig. 1 (the dotted vertical lines in Fig. 1 mean path P_k). We replace also every edge $\{v,w\} \in E(G)$ with the edge $\{v_i,w_j\}$ such that no two inserted edges are incident. Let G_k' be the graph constructed from G as above. It is easy to see that G_k' is always a subcubic graph.

Theorem 11. The problem $\text{Hom}(C_{2k+1})$, $k \ge 2$ is NP-complete on subcubic graphs.

Proof. By Theorem 10 it suffices to show $G \to C_{2k+1}$ iff $G'_k \to C_{2k+1}$. First, observe that $A^k_v \to C_{2k+1}$ and moreover for every homomorphism $h_v: V(A^k_v) \to V(C_{2k+1})$ we have $|h_v(\{v_1, \ldots, v_{\rho(v)}\})| = 1$. Otherwise, we have $h_v(v_i) \neq h_v(v_{i+1})$ for some $i \in \{1, \ldots, \rho(v) - 1\}$, hence $h_v(v_i) = h_v(x)$, where $\{v_i, s\}, \{v_{i+1}, s\}, \{s, x\} \in E(A^k_v)$ and $x \notin \{v_1, \ldots, v_{\rho(v)}\}$. Thus C_{2l-1} is subgraph of $C_{2k+1}(h(V(A^k_v)))$ for some l < k, which is impossible. So, constructing a homomorphism $g: V(G) \to V(C_{2k+1})$ from a homomorphism $g': V(G'_k) \to V(C_{2k+1})$ is straightforward.

Conversely, let $g: V(G) \to V(C_{2k+1})$ be a homomorphism, then we let $g'(v_i) = g(v)$ and for $w \in V(A_v^k) \setminus \{v_1, \dots, v_{\rho(v)}\}$ $g'(w) = \tau_v \circ h_v(w)$, where $h_v: V(A_v^k) \to V(C_{2k+1})$ is a

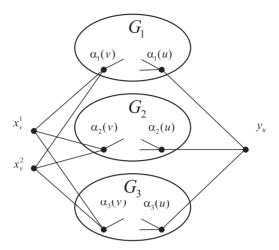


Fig. 2. A graph G'.

homomorphism and τ_v is any automorphism of C_{2k+1} such that $\tau_v(h_v(v_i)) = g(v)$. One can check that $g': V(G'_k) \to V(C_{2k+1})$ is a homomorphism. \square

Theorem 12. The problem $\text{Hom}(C_{2k+1})$, $k \ge 2$ is NP-complete on 3-regular graphs.

Proof. It suffices to show the equivalence $G \to C_{2k+1}$ iff $G' \to C_{2k+1}$ for any subcubic connected graph G, where $k \ge 2$ and G' is a cubic graph defined as follows. Let α_i be an isomorphism from graph G to its ith isomorphic copy G_i , for i=1,2,3, which are vertex disjoint. Let $V_j \subset V(G)$ be the set of vertices of degree j. We define $V(G') = \bigcup_{i=1}^3 V(G_i) \cup \bigcup_{v \in V_1} \{x_v^1, x_v^2\} \cup \bigcup_{u \in V_2} \{y_u\}$ and $E(G') = \bigcup_{i=1}^3 E(G_i) \cup \bigcup_{v \in V_1} \bigcup_{i=1}^3 \{\{x_v^1, \alpha_i(v)\}, \{x_v^2, \alpha_i(v)\}\} \cup \bigcup_{u \in V_2} \bigcup_{i=1}^3 \{\{y_u, \alpha_i(u)\}\}$ (see Fig. 2). Assuming that x_j^j and y_u are different vertices for j=1,2 and $v,u \in V(G)$, it is obvious that G' is a cubic graph.

Now, suppose $g: V(G) \to V(C_{2k+1})$ is a homomorphism. Let $g': V(G') \to V(C_{2k+1})$ be defined g'(w) = g(v) for $w \in \{\alpha_1(v), \alpha_2(v), \alpha_3(v)\}$ and $v \in V(G)$, $g'(x_v^i) = g(z)$ for $\{z, v\} \in E(G)$, $g'(y_v) = g(z)$ for any z adjacent to v. Thus g' is a well-defined homomorphism. Conversely, if g' is a homomorphism from G' to C_{2k+1} then $g = g' \circ \alpha_1$ is a homomorphism from G to C_{2k+1} . \square

Theorem 13. The problem $\text{Hom}(C_{2k+1})$ is NP-complete on r-regular graphs for every fixed integer $k \ge 1$ and $r \ge 4$.

Proof. By induction on $r \ge 4$, consider r+1 isomorphic copies of any r regular graph. Using the analogous method as that in Theorem 12 we can show that the problem $\text{Hom}(C_{2k+1})$ is NP-complete for any $k \ge 2$ and for all $r \ge 4$. In [10] the author proved NP-completeness of edge 3-chromaticity of 3-regular graphs. Since line

graphs of 3-regular graphs are 4-regular, the problem of 3-chromaticity of 4-regular graphs is NP-complete. The construction from Theorem 12 is carried over to the case $H_{om}(C_3)$ on r-regular graphs with $r \ge 4$. \square

4. Polynomial algorithm for cycles

We show a polynomial-time algorithm for graphs with $\Delta \leq 2$.

Theorem 14. The T-Coloring Problem on graphs with degree not exceeding 2 can be solved in time $O(n|T|^2 \log |T|)$.

Proof. Bipartite graphs can be optimally colored with 1 and min $\mathbb{N} \setminus T + 1$, thus all we need is considering odd cycles. Let T be any set and a be an arbitrary integer. We ask if $\operatorname{sp}_T(C_{2k+1}) \leq a-1$. By Theorem 8 we have $\operatorname{sp}_T(C_{2k+1}) \leq 2|T|$. Thus using the standard bisection method we need only check $1 + \log_2 |T|$ inequalities to find $\operatorname{sp}_T(C_{2k+1})$.

In the following, we sketch the idea of the algorithm. Let $TAB(v_i)[1...a]$ be a table of logical values associated with vertex v_i and defined as follows: $TAB(v_i)[j] = TRUE$ if and only if there exists a T-coloring of path $v_1, ..., v_i$ using colors not greater than a such that v_1 is colored with 1 and v_i is colored with j. So, $TAB(v_1)$ has value TRUE only on its first position and $TAB(v_{i+1})[y] = TRUE$ if and only if there exists $z \in \{1, ..., a\}$ such that $|z - y| \notin T$ and $TAB(v_i)[z] = TRUE$. We see that there exists a T-coloring iff $TAB(v_{2k+1})[j] = TRUE$ for some $j - 1 \notin T$, so constructing the T-coloring is straightforward. It is obvious that the complexity of the above algorithm is $O(k|T|^2 \log |T|)$. \square

5. Main results

Based on Theorem 11 we can prove the main result of this paper. Before doing this, we introduce the following notion.

Definition 15. For a given set T, by d_T we mean the number such that $G_T^{d_T}$ is bipartite and $G_T^{d_T+1}$ is not bipartite.

Lemma 16. For any set T the following inequality holds:

$$d_T \leq \operatorname{sp}_T(K_3)$$

and, moreover, d_T can be determined in polynomial time.

Proof. Let us notice that $\chi(G_T^{d_T+1}) = \chi(G_T^{d_T}) + 1 = 3$. Thus from Corollary 5 it follows $G_T^{d_T+1} \to K_3$, hence by Proposition 7 $\operatorname{sp}_T(G_T^{d_T+1}) \leqslant \operatorname{sp}_T(K_3)$. By Proposition 4 $\operatorname{sp}_T(G_T^{d_T+1}) \leqslant d_T$. Assuming $\operatorname{sp}_T(G_T^{d_T+1}) \leqslant d_T - 1$ we get at once $G_T^{d_T+1} \to G_T^{d_T}$ but this contradicts the definition of d_T . So, we get $d_T = \operatorname{sp}_T(G_T^{d_T+1}) \leqslant \operatorname{sp}_T(K_3)$. By

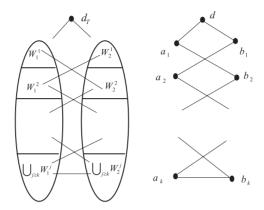


Fig. 3. A graph $G_T^{d_T+1}$ (left) and a cycle C_{2k+1} (right).

Theorem 8 sp_T(K_3) $\leq 2|T|$, hence using the bisection method we can determine the greatest d_T such that $G_T^{d_T}$ is bipartite. This can be done in time $O(|T|^2 \log |T|)$. \square

Lemma 17. Given any set T, we have $d_T = \operatorname{sp}_T(K_3)$ if and only if $K_3 \subset G_T^{d_T+1}$.

Proof. By Corollary 6 $K_3 \tilde{\subset} G_T^{d_T+1}$ is equivalent to $K_3 \to G_T^{d_T+1}$. Assume $K_3 \tilde{\subset} G_T^{d_T+1}$, then by Proposition 4 sp_T(K_3) $\leq d_T$, hence from Lemma 16 it follows that $d_T = \operatorname{sp}_T(K_3)$. The converse implication is straightforward by Proposition 4. \square

Let us denote by C_T the shortest odd-length cycle in graph $G_T^{d_T+1}$.

Lemma 18. There exists a homomorphism $h: V(G_T^{d_T+1}) \to V(C_T)$.

Proof. We only have to construct a homomorphism on the vertices of the connected component of $G_T^{d_T+1}$ containing vertex d_T , because the other components are bipartite. So let V_1 and V_2 be a bipartition of a bipartite graph obtained from this component by removing d_T and let W_i^j , i=1,2 and $j \ge 1$, be the vertex subset of V_i of distance j from vertex d_T in the graph $G_T^{d_T+1}$. Finally, let $W_1^0 = W_2^0 = \{d_T\}$. Let $C_{2k+1} = (\{d,a_1,b_1,\ldots,a_k,b_k\},\{\{d,a_1\},\{d,b_1\},\{a_1,b_2\},\{b_1,a_2\},\ldots,\{a_{k-1},b_k\},\{b_{k-1},a_k\},\{a_k,b_k\}\})$ be any cycle isomorphic to C_T . Let us define $h(d_T) = d$, $h(W_1^j) = \{a_j\}$ and $h(W_2^j) = \{b_j\}$ for $j = 1,\ldots,k$ and $h(W_j^i) = h(W_i^k)$ for j > k, i = 1,2 (see Fig. 3).

The construction of h is correct because any vertex from W_i^j , j > 0, can have neighbours only in the sets $W_{3-i}^{j\pm 1}$ and W_{3-i}^j , and the latter case is impossible for j < k. \square

Lemma 19. For any graph G the following equivalence holds: $G \to G_T^{d_T+1}$ if and only if $G \to C_T$.

Proof. Let $G \to G_T^{d_T+1}$, hence from Lemma 18 it follows $G \to C_T$. Conversely, assume that $G \to C_T$. By definition $C_T \tilde{\subset} G_T^{d_T+1}$, thus we get $G \to G_T^{d_T+1}$. \square

Theorem 20. The T-Span Problem can be solved in polynomial time on subcubic graphs for all sets T satisfying $K_3 \tilde{\subset} G_T^{d_T+1}$. The Fixed T-Span Problem is NP-complete on cubic graphs for all sets T not satisfying $K_3 \tilde{\subset} G_T^{d_T+1}$.

Proof. Let T be a fixed set and k be any positive integer. By Theorem 8 the case $G=K_4$ is polynomial and can be solved in $O(|T|^3)$ time (by Proposition 4 it reduces to the problem of finding the smallest d such that $K_4 \tilde{\subset} G_T^d$; by Theorem 8 $K_4 \tilde{\subset} G_T^{3|T|+1}$ and the fact that 0 is a vertex of a maximal clique of G_T^d , it reduces to searching all the triples of vertices of $G_T^{3|T|+1}$). For any subcubic graph $G \neq K_4$ we ask if $\operatorname{sp}_T(G) \leqslant k$. Suppose that $K_3 \tilde{\subset} G_T^{d_T+1}$. Brooks' theorem implies $G \to K_3$, thus by Lemma 17 and Proposition 7 $\operatorname{sp}_T(G) \leqslant d_T$. According to Proposition 4 we have $\operatorname{sp}_T(G) < d_T$ iff G is bipartite, hence to solve T-Span Problem for graph G we only need to check if G is bipartite (O(n+m) time) and if it is so then $\operatorname{sp}_T(G)$ equals the smallest positive integer not belonging to T (which we can find in O(|T|) time). Otherwise, $\operatorname{sp}_T(G) = d_T$,

Now assume that K_3 is not isomorphic to any subgraph of $G_T^{d_T+1}$ and let $k=d_T$. From Proposition 4 we have $\operatorname{sp}_T(G) \leq k$ iff $G \to G_T^{d_T+1}$. By Lemma 19 we get $\operatorname{sp}_T(G) \leq k$ iff $G \to C_T$ and, moreover, C_T is an odd cycle of length greater than 4. By Theorem 12 the problem $\operatorname{Hom}(C_T)$ on cubic graphs is NP-complete and so is the Fixed T-Span Problem. \square

computable in time $O(|T|^2 \log |T|)$.

Corollary 21. The T-Span Problem is NP-complete in the strong sense on 3-regular graphs.

Proof. By Theorem 20 and Lemma 17 it suffices to verify that for $T = \{0, 2, 3\}$ we have $d_T = 4 < \operatorname{sp}_T(K_3) = 5$. \square

It is worth observing that if for some set T we put $k=d_T$, then by Lemma 19 for any graph G the question if $\operatorname{sp}_T(G) \leqslant k$ is equivalent to $G \to C_T$. So, if for every $k \geqslant 1$ the problem $\operatorname{Hom}(C_{2k+1})$ is NP-complete on a class $\mathscr G$, then the Fixed T-Span Problem on the class $\mathscr G$ is NP-complete as well. Thus from Theorem 13 we have the following:

Theorem 22. For every set T and integer $r \ge 4$ the Fixed T-Span Problem is NP-complete on r-regular graphs.

Corollary 23. The T-Span Problem is NP-complete in the strong sense on r-regular graphs for any $r \ge 3$.

Table 1 Now we sum up all the above results in the following table. Recall that the numbers appearing in the third column are polynomially computable functions of T.

Graph Problem Property of T Complexity Reference $\Delta \leq 2$ T-COLORING PROBLEM $O(n|T|^2 \log |T|)$ Theorem 14 $\omega(G_T^{d_T+1}) \geqslant 3$ $O(n^2 + |T|^3)$ $\Delta \leq 3$ T-COLORING PROBLEM Theorem 20 $\omega(G_T^{d_T+1}) \leq 2$ FIXED T-SPAN PROBLEM NPC Theorem 20 3-regular FIXED T-SPAN PROBLEM NPC Theorem 22 r-regular, any

Table 1
The complexity of the T-SPAN PROBLEM and T-COLORING PROBLEM on graphs with bounded degree

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 $r \ge 4$

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