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Self-interacting scalar field trapped in a DGP brane: The dynamical systems perspective

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ABSTRACT

We apply the dynamical systems tools to study the linear dynamics of a self-interacting scalar field trapped on a DGP brane. The simplest kinds of self-interaction potentials are investigated: (a) constant potential, and (b) exponential potential. It is shown that the dynamics of DGP models can be very rich and complex. One of the most interesting results of this study shows that dynamical screening of the scalar field self-interaction potential, occurring within the Minkowski cosmological phase of the DGP model and that mimics 4D phantom behaviour, is an attractor solution for a constant self-interaction potential but not for the exponential one. In the latter case gravitational screening is not even a critical point of the corresponding autonomous system of ordinary differential equations.

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1. Introduction

Since the discovery that our universe can be currently undergoing a stage of accelerated expansion [1], many phenomenological models based either on Einstein General Relativity (EGR), or using alternatives like the higher dimensional brane world theories [2], have been invoked (for a recent review on the subject see Ref. [3]). The latter ones, being phenomenological in nature, are inspired by string theory.

One of the brane models that have received most attention in recent years is the so-called Dvali–Gabadadze–Porrati (DGP) brane world [4].² This model describes a brane with 4D world-volume,

that is embedded into a flat 5D bulk, and allows for infrared (IR)/large scale modifications of gravitational laws. A distinctive ingredient of the model is the induced Einstein–Hilbert action on the brane, that is responsible for the recovery of 4D Einstein gravity at moderate scales, even if the mechanism of this recovery is rather non-trivial [6]. The acceleration of the expansion at late times is explained here as a consequence of the leakage of gravity into the bulk at large (cosmological) scales, so it is just a 5D geometrical effect, unrelated to any kind of mysterious “dark energy”.

As with many IR modifications of gravity, there are ghosts modes in the spectrum of the theory [7,8].³ Nevertheless, studying the dynamics of DGP models continues being a very attractive subject of research. It is due, in part, to the very simple geometrical explanation to the “dark energy problem”, and, in part, to the fact that it is one of a very few possible consistent IR modifications of gravity that might be ever found.

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The aim of this Letter is, precisely, to study the dynamics of a self-interacting scalar field trapped on a DGP brane⁴ by invoking the dynamical systems tools, which have been proved useful to retrieve significant information about the evolution of a huge class of cosmological models (see for instance the book [10]). The simplest self-interaction potentials: (a) constant potential, and (b) exponential potential, are investigated. The constant potential is the simplest one, and, for frozen scalar field $\phi = \phi_0$, for the Minkowski cosmological phase, the corresponding model coincides with the one of Ref. [9]. The exponential potential represents a common functional form for self-interaction potentials that can be found in higher-order [11] or higher-dimensional theories [12]. These can also arise due to non-perturbative effects [13]. In addition to the scalar field we consider, also, a background fluid trapped on the DGP brane.

A dynamical study of DGP models with a scalar field trapped on the DGP brane has been already undertaken in Ref. [14] for an exponential potential, to show that crossing of the phantom barrier is indeed possible in DGP cosmology with a single scalar field (see also [15] in this regard). However, the authors of that paper do not study in detail the phase space of the model and, in correspondence, they are not able to find critical points. Their claim that scaling solutions do not exist in a universe with dust on a DGP brane, seems to be in contradiction with our results. Also, in Ref. [16] a dynamical systems study of DGP scenarios is undertaken for several self-interaction potentials. However the author of the latter reference considers only a scalar field trapped on the brane (no other kind of matter is trapped on it). Besides, phase space variables used in [16] are different from the ones used in the present study.

In a sense, the present investigation is a continuation of the one reported in paper [17], to include higher-dimensional behaviour (in the present case dictated by the DGP dynamics). In consequence, for the exponential self-interaction potential, our results will include the ones reported in [17] as a particular case.

Through the Letter we use natural units ($8\pi G = 8\pi/m_{\text{pl}}^2 = \hbar = c = 1$).

2. The model

As already mentioned, we will be concerned here with a DGP brane model where self-interacting scalar field matter is trapped on the DGP brane. The field equations are the following:

$$Q_{\pm}^2 = \frac{1}{3} \left(\rho + \frac{1}{2} \dot{\phi}^2 + V(\phi) \right),$$

$$\dot{\rho} = -3\gamma H \rho, \quad \ddot{\phi} = -3H\dot{\phi} - \partial_{\phi} V, \quad (1)$$

where ρ is the energy density of the background barotropic fluid (γ is the barotropic index), ϕ is the scalar field trapped in the DGP brane, V its self-interaction potential, and we have used the following definition:

$$Q_{\pm}^2 \equiv H^2 \pm \frac{1}{r_c} H, \quad (2)$$

with r_c being the so-called crossover scale. Depending on the choice of the signs “+” or “−” in (2), there are two possible branches of the DGP model, corresponding to two possible embeddings of the DGP brane in the Minkowski bulk. The choice “+” is for the so-called Minkowski cosmological phase of DGP that is free of ghosts, while the “−” choice is for the self-accelerating cosmological phase. The Minkowski phase of the present model belongs

in the wider class of models of Ref. [15]. For $\phi = \text{const}$, the self-accelerating phase coincides with the model of [9].

3. The phase space

Our aim is to write the system (1) as an autonomous system of ordinary differential equations. We make the following choice of dynamical variables⁵:

$$x = \frac{1}{\sqrt{6}} \frac{\dot{\phi}}{Q}, \quad y = \frac{1}{\sqrt{3}} \frac{\sqrt{V}}{Q}, \quad z = \frac{Q}{H}, \quad (3)$$

and, also, we introduce the time variable $\tau = \int H dt$. The following autonomous system of ordinary differential equations is obtained:

$$x' = -3x - \sqrt{\frac{3}{2}} (\partial_{\phi} \ln V) y^2 z + \frac{3}{2} x (\gamma (1 - x^2 - y^2) + 2x^2),$$

$$y' = \sqrt{\frac{3}{2}} (\partial_{\phi} \ln V) x y z + \frac{3}{2} y (\gamma (1 - x^2 - y^2) + 2x^2),$$

$$z' = \frac{3}{2} z \left(\frac{z^2 - 1}{z^2 + 1} \right) (\gamma (1 - x^2 - y^2) + 2x^2), \quad (4)$$

where a prime denotes derivative with respect to τ . In terms of the dynamical variable z , Eq. (2) can be rewritten as:

$$z^2 = 1 \pm \frac{1}{r_c H}. \quad (5)$$

For the Minkowski phase, since $0 \leq H \leq \infty$ (we consider just non-contracting universes), then $1 \leq z \leq \infty$. The case $-\infty \leq z \leq -1$ corresponds to the time reversal of the latter situation. For the self-accelerating phase, $-\infty \leq z^2 \leq 1$, but since we want real valued z only, then $0 \leq z^2 \leq 1$.⁶ As before, the case $-1 \leq z \leq 0$ represents time reversal of the case $0 \leq z \leq 1$ that will be investigated here. Both branches share the common subset $(x, y, z = 1)$, which corresponds to the formal limit $r_c \rightarrow \infty$ (see Eq. (2)), i.e., this represents just the standard 4D behaviour of (4D) Einstein–Hilbert theory coupled to a self-interacting scalar field.

In terms of the above introduced dynamical variables x, y, z , the “effective” dimensionless density parameters $\bar{\Omega} = \rho/3Q^2$, and $\bar{\Omega}_{\phi} = \rho_{\phi}/3Q^2$ ($\rho_{\phi} = \dot{\phi}^2/2 + V$) can be expressed in the following way:

$$\bar{\Omega} = \frac{\Omega}{z^2} = 1 - x^2 - y^2, \quad \bar{\Omega}_{\phi} = \frac{\Omega_{\phi}}{z^2} = x^2 + y^2, \quad (6)$$

where, as customary, $\Omega = \rho/3H^2$, $\Omega_{\phi} = \rho_{\phi}/3H^2$. Since both $\Omega \geq 0$, $\Omega_{\phi} \geq 0$, and $z^2 \geq 0$, then $0 \leq x^2 + y^2 \leq 1$. This means the phase space for the dynamical system driven by the evolution equations (4), for the Minkowski cosmological phase (the ghost-free “+” branch), is given by the unbounded region:

$$\Psi_+ = \{(x, y, z): 0 \leq x^2 + y^2 \leq 1, z \in [1, \infty[\}, \quad (7)$$

while, for the self-accelerating cosmological phase (the pathological “−” branch), it is given by the complementary (non-compact) region:

$$\Psi_- = \{(x, y, z): 0 \leq x^2 + y^2 \leq 1, z \in]0, 1] \}. \quad (8)$$

Notice that the points belonging in the set $(x, y, 0)$ cannot be included since, in this case ($z = 0 \Rightarrow Q = 0$) the variables x and y are undefined. In consequence, the self-accelerating solution $H = 1/r_c$ has to be studied separately, i.e., with a different choice of phase space variables (see Section 5).

⁴ Regarding the so called “normal” branch, or Minkowski cosmological phase [9] of DGP model, this is just a particular member in the wider class of models of Ref. [15].

⁵ In what follows, for brevity, we avoid writing the “±” sign.

⁶ In fact, fitting SN observations requires $H \geq r_c^{-1}$ in order to achieve late time acceleration (see, for instance, Ref. [8] and references therein). This means that z has to be real-valued.

Take a look at (4). These equations hide the differences between the “+” and “−” branches of the DGP. Nevertheless, the differences indeed exist. These are encoded in the different definition of the corresponding phase spaces (see the definitions for Ψ_+ and Ψ_- above) which, from now on, we will call as Minkowski (Ψ_+) and self-accelerating (Ψ_-) phases, respectively. Recall that points in the phase plane $\{(x, y, 1): 0 \leq x^2 + y^2 \leq 1\}$, where both Ψ_+ and Ψ_- intersect, are related to standard 4D behaviour (formal limit $r_c \rightarrow \infty$).

To finalize this section we write another useful magnitudes of observational interest in terms of the dynamical variables (3). These are, the deceleration parameter $q = -(1 + \dot{H}/H^2)$:

$$q = -1 + \frac{3z^2}{z^2 + 1}(\gamma(1 - x^2 - y^2) + 2x^2), \tag{9}$$

and the equation of state (EOS) parameter $\omega_\phi = (\dot{\phi}^2 - 2V)/(\dot{\phi} + 2V)$:

$$\omega_\phi = \frac{x^2 - y^2}{x^2 + y^2}. \tag{10}$$

4. The critical points

We study here two concrete yet generic cases. First we consider a constant potential $V = V_0$, and then we study the exponential potential $V = V_0 \exp(-\alpha\phi)$. For more general classes of potentials we have to rely on a quite different approach (see, for instance, Ref. [18]). This will be the subject of future research.

4.1. The constant potential $V = V_0$

The autonomous system of ordinary differential equations (4) simplifies to:

$$\begin{aligned} x' &= -3x + \frac{3}{2}x(\gamma(1 - x^2 - y^2) + 2x^2), \\ y' &= \frac{3}{2}y(\gamma(1 - x^2 - y^2) + 2x^2), \\ z' &= \frac{3}{2}z\left(\frac{z^2 - 1}{z^2 + 1}\right)(\gamma(1 - x^2 - y^2) + 2x^2). \end{aligned} \tag{11}$$

Before finding the critical points of this system of equations and investigating their stability, a straightforward inspection of the differential equations (11) reveals that the first two equations (differential equations for x and y variables, respectively) are decoupled from the third one. This means that there can be found critical points with $x = 0$, $y = \pm 1$ and arbitrary z s to form critical submanifolds of particular interest (see below on the critical submanifolds M_\pm). These critical points are associated with the inflationary ($q = -1$) DGP–Friedmann equation (notice that, in this case, $\Omega = 0$, $\Omega_\phi = z^2$):

$$H^2 \pm \frac{1}{r_c}H = \frac{V(\phi)}{3}. \tag{12}$$

For the Minkowski cosmological phase (“+” sign in (12)), this solution can be associated with 4D phantom-like behaviour, that is generated through dynamical (gravitational) screening of the potential energy $V(\phi)$.⁷ As we will see in the next sections, the latter solution is an attractor only for the constant potential $V = V_0$. For the exponential potential it is not even a critical point of the corresponding autonomous system of ordinary differential equations.

The critical points of the autonomous system of Eqs. (11) are summarized in Table 1, while Table 2 shows the eigenvalues of

Table 1
Properties of the critical points for the autonomous system (11).

P_i	x	y	z	Existence	$\bar{\Omega}_\phi$	ω_ϕ	q
P_1	0	0	1	Always ($\forall \gamma \in [0, 2]$)	0	undefined	$-1 + \frac{3\gamma}{2}$
P_2^\pm	± 1	0	1	”	1	1	2
P_3^\pm	0	± 1	1	”	1	-1	-1
M_\pm	0	± 1	$z \in]0, \infty[$	”	1	-1	-1

Table 2
Eigenvalues for the critical points in Table 1.

P_i	x	y	z	λ_1	λ_2	λ_3
P_1	0	0	1	$-3(2 - \gamma)/2$	$3\gamma/2$	$3\gamma/2$
P_2^\pm	± 1	0	1	$3(2 - \gamma)$	3	3
P_3^\pm	0	± 1	1	-3	-3γ	0
M_\pm	0	± 1	z	-3	-3γ	0

the corresponding Jacobian matrices. Notice, from (11), that the dynamical equations are invariant under the change of sign $z \rightarrow -z$, in consequence we have not included the points with $z = -1$ in our analysis.

There are 5 critical points P_1 , P_2^\pm , P_3^\pm and two critical submanifolds $M_\pm = (0, \pm 1, z)$ ($z \in]0, 1]$ for the self-accelerating phase, while, $z \in [1, \infty[$ for the Minkowski phase). It is obvious that critical points P_3^\pm belong in M_\pm .

Notice that for critical points P_1 , P_2^\pm , P_3^\pm , since $z = 1$ (formal limit $r_c \rightarrow \infty$), then $\bar{\Omega} = \Omega$, $\bar{\Omega}_\phi = \Omega_\phi$, i.e., these points correspond to standard 4D behaviour. Otherwise, critical points attached to the phase plane $\{(x, y, 1): 0 \leq x^2 + y^2 \leq 1\}$ are the well-known critical points for, basically, standard 4D Einstein–Hilbert gravity with a minimally coupled self-interacting scalar field with constant self-interaction potential. These points exist for both branches of the DGP model.

The matter-dominated solution P_1 ($\bar{\Omega} = \Omega = 1$) is a saddle point in Ψ_\pm . It corresponds to an accelerating solution for $\gamma < 2/3$ (decelerating otherwise, i.e. for $2/3 \leq \gamma \leq 2$). Stiff-matter dominated solutions P_2^\pm ($\bar{\Omega}_\phi = \Omega_\phi = 1$, $\omega_\phi = 1$) represent source critical points in phase space, and are always decelerating ($q = 2$).

The scalar field dominated inflationary phases ($\bar{\Omega}_\phi = \Omega_\phi = 1$, $\omega_\phi = -1$, $q = -1$) corresponding to points in the submanifolds M_\pm in Table 1 (as already said, these include the critical points P_3^\pm), represent non-hyperbolic critical points, since one of the eigenvalues of the corresponding Jacobian matrices vanishes (see Table 2). In this case the only thing we can state with certainty, on the basis of straightforward analysis of the autonomous system of Eqs. (11), is that trajectories in phase space, originating in one of the source points P_2^\pm , depending on the phase considered: the Minkowski phase or the self-accelerating one, and on the initial conditions, will inevitably approach one or several of the points $(0, \pm 1, z_{i0}) \in M_\pm$. Otherwise, points in the segments $(0, \pm 1, z)$, that are parallel to the z -axis, can be seen as attractors by the corresponding phase space trajectories. Actually, the stable subspace of the dynamical system (11), near of the critical points in the submanifolds $(0, \pm 1, z)$, is spanned by the eigenvectors:

$$v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix},$$

i.e., the stable subspace is the plane (x, y) intersecting the z -axis at a given $z = z_{i0}$. The central subspaces coincide with the open segments $(0, \pm 1, z \in]0, 1])$ for the self-accelerating phase, while, for the Minkowski phase these coincide with the semi-infinite segments $(0, \pm 1, z \in [1, \infty[)$. These segments are parallel to the z -axis and lie on the boundary of Ψ_\pm ($\partial\Psi_\pm$). Since, in this case, there

⁷ The present case ($V = V_0$) coincides with the case studied in [9].

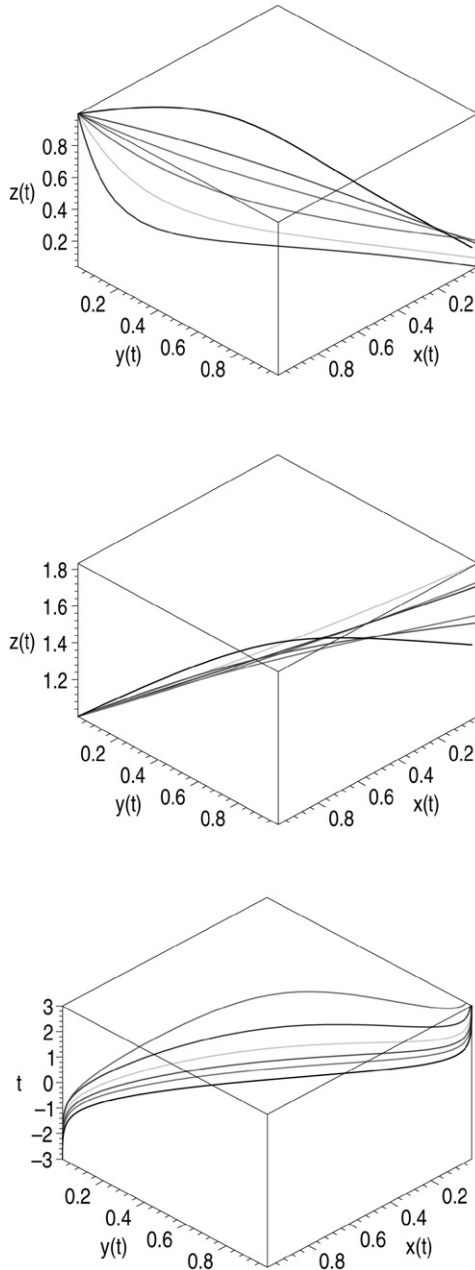


Fig. 1. Trajectories in phase space for different sets of initial conditions for the constant potential $V = V_0$. The upper figure and the figure at the center are for the self-accelerating Ψ_- and Minkowski Ψ_+ phases of the DGP model, respectively. The figure at the bottom shows the flow in time τ . Notice that trajectories in Ψ_- asymptotically approach to the self-accelerating solution $H = 1/r_c$. Meanwhile, the trajectories in Ψ_+ approach points in the segment $(0, 1, z)$.

is no unstable subspace related to M_{\pm} , and the center manifold belongs in the boundary of the phase space, this means that trajectories in phase space that evolve from the stiff-matter source $P_2^{\pm} \in (x, y, 1)$, will inevitably approach one or several points (depending on the cosmological phase being considered) in M_{\pm} , into the future ($\tau \rightarrow \infty$). As we will see quite soon, it is a fact that, only for the Minkowski phase Ψ_+ , the points in M_{\pm} are attractor critical points, so that, the corresponding submanifolds are attractor segments. These critical subspaces are an important result, since, as we will see in the next subsection, they exist only for the constant potential case, meaning that the associated cosmological solutions are generic only in this particular case.

Additional and, perhaps, more precise information can be extracted from the phase portraits. Actually, in the Fig. 1, phase

trajectories are shown for the constant potential $V = V_0$, for different sets of initial conditions. The upper figure is for the self-accelerating phase Ψ_- , while the figure in the middle is for the Minkowski phase Ψ_+ . The lower figure shows the flow of the autonomous system (11). From these figures several features are apparent:

- Phase trajectories in Ψ_- (upper figure in Fig. 1) originate from the source critical points P_2^{\pm} (only the point P_2^+ is shown), corresponding to the standard 4D kinetic energy dominated (stiff-matter) solution, and (asymptotically) approach to the point $(0, 1, 0)$ that has been removed from the phase space since phase space variables x and y blow up at the phase plane $(x, y, 0)$. The dynamics in the neighbourhood of this point has to be investigated in terms of different phase space variables. Therefore, for the self-accelerating cosmological phase Ψ_- the points $(0, \pm 1, z_i) \in M_{\pm}$ are not even critical points of the autonomous system (11).
- Phase trajectories in Ψ_+ (center figure in Fig. 1) originate from the 4D stiff-matter solution (unstable node P_2^+ in Table 1) and end up at the inflationary points $(0, 1, z_{0i}) \in M_+$, where the different z_{0i} -s are associated with the different initial conditions. Otherwise, points in M_+ are seen as attractor points by the different phase space “observers”, moving along different phase trajectories that originate at P_2^+ . These scalar field dominated critical points correspond to inflationary solutions of the DGP–Friedmann equation:

$$H^2 + \frac{1}{r_c} H = \frac{V_0}{3}.$$

That the phase trajectories in Ψ_+ (middle figure in Fig. 1), leave the phase plane $(x, y, 1)$ and probe the bulk of the phase space Ψ_+ , is a nice illustration of the fact that 4D phantom-like behaviour arising from dynamical screening of the brane cosmological constant V_0 [9], is a phenomenon of 5D nature.⁸ The new feature revealed by the present dynamical systems analysis relies on the fact that this type of behaviour—gravitational screening—is quite independent of the initial conditions, since the corresponding semi-infinite segments $M_{\pm} \in \partial\Psi_+$ are stable submanifolds.

4.2. The exponential potential $V = V_0 \exp(-\alpha\phi)$

The autonomous system of ordinary differential equations (4) takes the following form:

$$\begin{aligned} x' &= -3x + \sqrt{\frac{3}{2}}\alpha y^2 z + \frac{3}{2}x(\gamma(1-x^2-y^2) + 2x^2), \\ y' &= -\sqrt{\frac{3}{2}}\alpha x y z + \frac{3}{2}y(\gamma(1-x^2-y^2) + 2x^2), \\ z' &= \frac{3}{2}z\left(\frac{z^2-1}{z^2+1}\right)(\gamma(1-x^2-y^2) + 2x^2). \end{aligned} \quad (13)$$

Before going any further into the phase space analysis of (13), let us note that, contrary to the case with the autonomous system of differential equations (11), thanks to the term with the factor $\partial_{\phi} V(\phi) = -\alpha$ in the right-hand side of the first couple of equations, the equations in (13) form a coupled system of differential equations. The immediate consequence is that points in the subsets $(0, \pm 1, z) \in \partial\Psi_{\pm}$ are not even critical points of the autonomous system (13).

The critical points of (13) are summarized in Table 3. We have not included the points with $z = -1$, since these coincide with

⁸ This argument has been suggested to us by Roy Maartens.

Table 3
Critical points for the autonomous system (13).

P_i	x	y	z	Existence	$\bar{\Omega}_\phi$	ω_ϕ	q
P_1	0	0	1	All α, γ	0	undefined	$-1 + \frac{3\gamma}{2}$
$P_{2,3}$	± 1	0	1	All α, γ	1	1	2
P_4	$\frac{\alpha}{\sqrt{6}}$	$\sqrt{1 - \frac{\alpha^2}{6}}$	1	$\alpha^2 < 6$	1	$\frac{\alpha^2}{3} - 1$	$\frac{\alpha^2}{2} - 1$
P_5	$\sqrt{\frac{3}{2}} \frac{\gamma}{\alpha}$	$\sqrt{\frac{3(2-\gamma)\gamma}{2\alpha^2}}$	1	$\alpha^2 > 3\gamma$	$\frac{3\gamma}{\alpha^2}$	$\gamma - 1$	$-1 + \frac{3\gamma}{2}$

those with $z = 1$ under the change of sign of the exponent $\alpha \rightarrow -\alpha$. Recall that the critical points with $z = 1$ correspond to the formal limit $r_c \rightarrow \infty$, i.e., these represent standard 4D behaviour. A complete study of the critical points in Table 3 can be found in the well-known reference [17]. The main results can be summarized as follows:

- $\alpha^2 < 3\gamma$; The kinetic-dominated solutions (points $P_{2,3}$ in Table 3) are unstable nodes (sources). The matter-dominated solution (point P_1) is a saddle point. The scalar field dominated solution (point P_4) is the late-time attractor.
- $3\gamma < \alpha^2 < 6$; The kinetic-dominated solutions $P_{2,3}$ are unstable nodes. The scalar field dominated solution P_4 is a saddle. The matter-scaling solution (point P_5 in Table 3) is a stable node/spiral.
- $\alpha^2 > 6$; The kinetic-dominated solution can be either a source or a saddle. The matter-dominated solution is a saddle point. The matter-scaling solution P_5 is a stable spiral.

The main difference with the case for the constant potential $V = V_0$ of Section 4.1 is in the absence of the critical submanifolds M_\pm that can be associated with 4D phantom-like behaviour originated from 5D dynamical screening of the potential energy of the scalar field. Although 5D behaviour related to dynamical screening does actually arise in the present case (as can be seen from the Fig. 2, the phase trajectories leave the plane $(x, y, 1)$ and probe the bulk of the 3D phase space as for the constant potential), the corresponding DGP–Friedmann behaviour dictated by the equation

$$H^2 + \frac{1}{r_c} H = \frac{1}{3} V(\phi),$$

is not even a critical point, so that 5D gravitational screening that mimics 4D phantom behaviour is not a generic solution in this case. Actually, it is evident from the middle figure in Fig. 2, that the trajectories in phase space Ψ_+ (the Minkowski cosmological phase) do not even touch the segment $(0, 1, z) \in \partial\Psi_+$. In fact, for the chosen initial conditions, these seem to be repelled from that segment.

Another interesting conclusion that can be made after the phase space analysis in this subsection is that, the claim in Ref. [14] that scaling solutions do not exist in a DGP brane filled with dust, in general, is not correct. For $\alpha^2 > 3\gamma$, matter scaling solutions indeed exist, they are associated with critical points in phase space (point P_5 in Table 3), and can be, even, attractor solutions.

5. Self-accelerating solution $H = 1/r_c$

As already noted from the former analysis, for the self-accelerating phase of the DGP brane model, independent of the initial conditions, trajectories in phase space approach to the self-accelerating solution with phase space coordinate $z = 0 \Rightarrow H = 1/r_c$. However, the points with $z = 0$ are to be removed from the phase space since, otherwise, the coordinates x and y in (3) are undefined. Therefore, a new choice of phase space coordinates is mandatory to find the stability properties of the self-accelerating solution in phase space. Let us start with the DGP–Friedmann

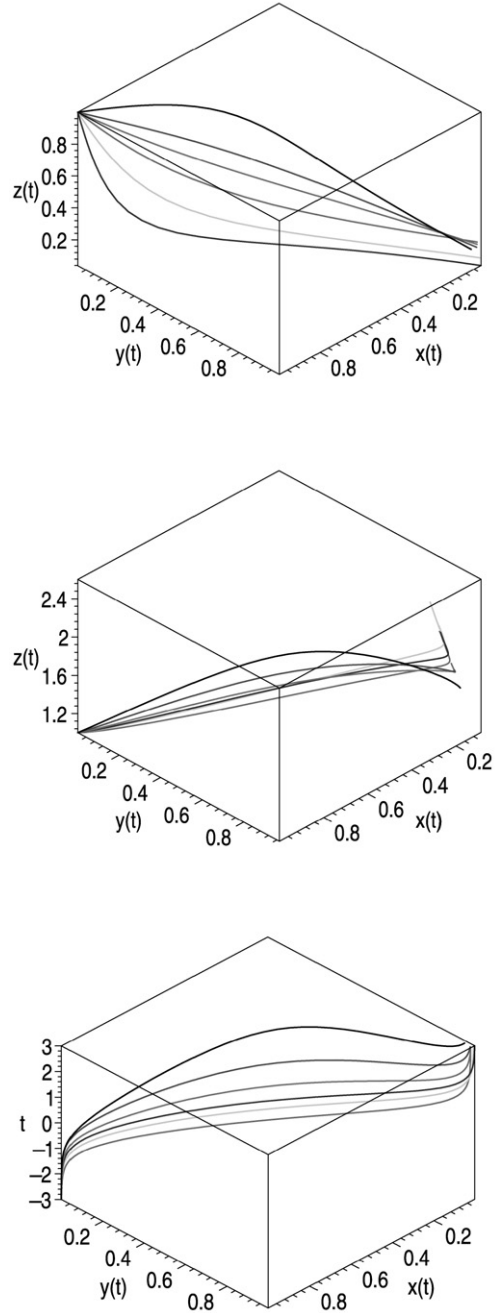


Fig. 2. Phase trajectories for different sets of initial conditions for the exponential potential $V = V_0 \exp(-\alpha\phi)$. As before the upper figure and the figure at the center are for the self-accelerating ψ_- and Minkowski ψ_+ phases of the DGP model, respectively. The flow of the autonomous system in time τ is shown in the figure at the bottom. Unlike the case for the constant potential in Section 4.1, phase trajectories in ψ_+ are repelled by the segment $(0, 1, z)$ (middle figure).

equation for the self-accelerating cosmological phase, written in the following general form

$$H^2 - \frac{1}{r_c} H = \frac{1}{3} \rho, \tag{14}$$

where ρ is now the energy density of the total matter content trapped on the DGP brane. If new phase space variables are defined:

$$x \equiv \frac{1}{r_c H}, \quad y \equiv \frac{\sqrt{\rho}}{\sqrt{3}H}, \tag{15}$$

then, the following Friedmann constraint arises:

$$1 = x + y^2 \Rightarrow y = \sqrt{1-x}, \quad (16)$$

so that, to have real valued y , the variable x is constrained to the interval $x \in [0, 1]$. This, in turn, yields that $y \in [0, 1]$ (the case $y \in [-1, 0]$ is related with a contracting phase of the cosmic evolution). In consequence the phase space is $\Psi^* = \{(x, y): x \in [0, 1], y \in [0, 1]\}$. Due to the Friedmann constraint (16), we are left with only one independent autonomous differential equation:

$$x' = 3\gamma x \left(\frac{1-x}{2-x} \right). \quad (17)$$

The corresponding critical points are the standard (4D) Friedmann solution $P_1 = (0, 1) \Rightarrow H^2 = \rho/3$ and the self-accelerating (5D) solution $P_2 = (1, 0) \Rightarrow H = 1/r_c$. To study the stability we must perturb (17) in the neighbourhood of the critical points: $x \rightarrow x_i + \epsilon$. Consider linear perturbations, i.e., we neglect terms $\sim \mathcal{O}(\epsilon^2)$, then

$$\epsilon' = 3\gamma(x_i + \epsilon) \left(\frac{1-x_i - \epsilon}{2-x_i - \epsilon} \right), \quad (18)$$

so that, for the Friedmann solution (point P_1),

$$\epsilon' = \frac{3\gamma}{2}\epsilon + \mathcal{O}(\epsilon^2) \Rightarrow \epsilon(\tau) = \epsilon(0)e^{\frac{3\gamma}{2}\tau}, \quad (19)$$

while, for the self-accelerating phase:

$$\epsilon' = -3\gamma\epsilon + \mathcal{O}(\epsilon^2) \Rightarrow \epsilon(\tau) = \epsilon(0)e^{-3\gamma\tau}. \quad (20)$$

From the analysis of (19) and (20) it is evident that the standard Friedmann solution is unstable, while the self-accelerating one is stable against small (linear) perturbations. Otherwise, in the language of the dynamical systems analysis, the latter solution is an attractor in phase space. This solution is, precisely, the one corresponding to the point $(x, y, z) = (0, 1, 0)$ in the former section, that has been removed from the corresponding phase space. Therefore, the reason why phase trajectories in Ψ_- of the former section (for both constant and exponential potentials) approach to that point, is that, in adequate phase space coordinates, the self-accelerating solution $H = 1/r_c$ is an attractor critical point.

6. Results and discussion

From the analysis in the former sections, the following important results can be summarized:

- For the constant potential the first 5 critical points (P_1, P_2^\pm and P_3^\pm) coincide with those in standard 4D Einstein–Hilbert theory coupled to a self-interacting scalar field with constant self-interaction potential. However, in principle, the phase trajectories are not constrained to the phase plane $(x, y, 1)$ as in standard 4D gravity coupled to a self-interacting scalar field, these probe the bulk of the 3D phase space. For solutions in Ψ_- , the (standard 4D) stiff-matter solution (critical points P_2^\pm in Table 1) are sources (unstable nodes), while the 4D matter-dominated solution (point P_1) is a saddle point. Phase trajectories (asymptotically) approach to the point $(0, 1, 0)$ that has been removed from the phase space to avoid singularities related to the choice of phase space variables x, y and z . This point, when studied separately—with a different choice of phase space coordinates—corresponds to the self-accelerating solution $H = 1/r_c$, which is stable against small (linear) perturbations, i.e., it is an attractor solution for phase trajectories in Ψ_- .
- There are two critical segments $M_\pm = (0, \pm 1, z)$ that belong in the boundary of the Minkowski cosmological phase $\partial\Psi_+$ and exist only for the constant potential case. Critical points in these subsets of the phase space correspond to inflationary

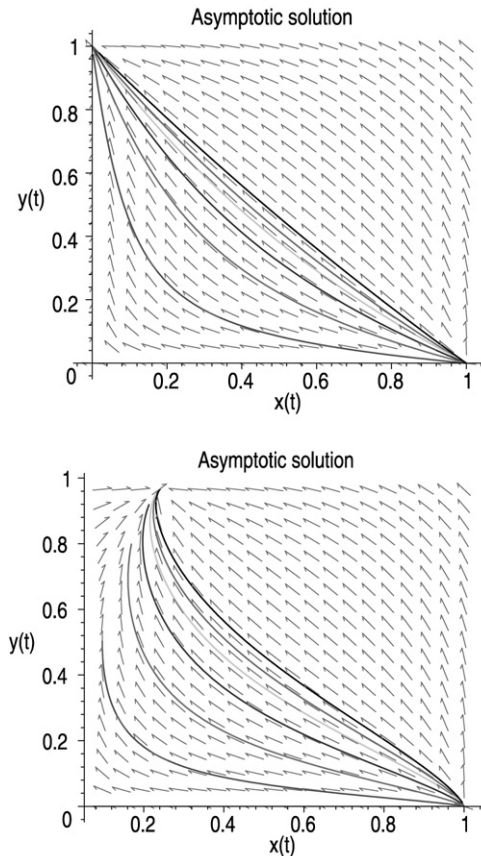


Fig. 3. Projection of phase trajectories onto a given plane (x, y, z_0) for the Minkowski phase of the DGP model, for the constant potential (upper figure), and for the exponential potential (lower figure), respectively. We chose an arbitrary $z_0 = 2$. Notice that, while the point $(x, y) = (0, 1)$ is an attractor for $V = V_0$ (upper figure), for the case $V = V_0 \exp(-\alpha\phi)$ (lower figure), it is not.

solutions and are non-hyperbolic. Only stable and center submanifolds can be attached to them. A straightforward analysis of the autonomous system of ordinary differential equations (11), shows that the stability of these critical subspaces depends on the way phase space trajectories approach to them. Phase portraits, however, reveal that points in these segments are seen by the corresponding phase trajectories as sinks or attractor points.

- In general, the dynamical behaviour of the DGP model with exponential self-interaction potential, does not differ from the standard behaviour of 4D Einstein–Hilbert gravity coupled to a self-interacting scalar field (see Ref. [17]), but for the fact that trajectories in phase space, inevitably, leave the phase plane $(x, y, 1)$ and probe the bulk of the 3D phase space due to the 5D nature of the DGP model. In this case, however, there are not critical points that can be associated with (5D) gravitational screening of the scalar field energy density.

Perhaps, the most interesting finding of the present investigation can be associated with the existence of the critical submanifolds $M_\pm = (0, \pm 1, z \in [1, \infty])$, that are distinctive of the constant potential case only. The critical points in M_\pm are associated with dynamical screening of the cosmological constant V_0 and, since these are attractors in Ψ_+ , the fate of the associated cosmological evolution is quite generic and independent of the initial conditions. Therefore, the existence of M_\pm serves as a nice illustration of dynamical screening of the cosmological constant (a phenomenon of 5D nature) in phase space. The fact that, for the exponential potential case, the semi-infinite segments $(0, \pm 1, z) \in \partial\Psi_+$ are not even

critical subspaces, came as a surprise. The immediate consequence is that, for the exponential potential, the gravitational screening is not as generic as for the constant potential.

The latter conclusion is nicely illustrated in Fig. 3, where phase trajectories have been projected onto a given phase plane (x, y, z_0) . It is seen that, for the case $V(\phi) = V_0$, trajectories in phase space converge towards the point $(0, 1)$ (recall that we fixed $z = z_0$), while for $V(\phi) = V_0 \exp(-\alpha\phi)$ these trajectories are repelled by this point.

The fact that phase trajectories probe the bulk of the 3D phase space Ψ_{\pm} means that, depending on the initial conditions, the cosmological dynamics of DGP models can be very rich and complicated. A clear illustration of this assertion is associated, precisely, with the occurrence of the attractor (self-accelerating) solution $H = 1/r_c$ in Ψ_- , and of the critical (also attractor) subspaces $M_{\pm} \in \partial\Psi_+$, for the constant potential case.

7. Conclusion

The dynamics of DGP models can be very rich and interesting. A dynamical systems approach to the subject reveals that trajectories in phase space scape from the plane $(x, y, 1)$, that is associated with standard 4D Einstein–Hilbert theory coupled to a self-interacting scalar field. This feature is associated with the 5D nature of the DGP model and originates a phenomenon called as dynamical screening, that mimics 4D phantom behaviour. While the latter phenomenon is quite generic and independent of the initial conditions if the self-interaction potential is a constant ($V = V_0$), when $V = V_0 \exp(-\alpha\phi)$, the gravitational screening indeed occurs, but it is not a generic phenomenon.

Another interesting result can be associated with the existence of matter-scaling solutions that can have, even, attractor nature. This result is in contradiction with the claim in [14] that scaling solutions do not exist in DGP universes with dust. In the case of the exponential potential, the existence of scaling solutions is expected since, the corresponding DGP model is a generalization of the Einstein–Hilbert theory coupled to a (self-interacting) scalar field with $V = V_0 \exp(-\alpha\phi)$ (the dynamics of this model has been investigated in Ref. [17]), to include 5D effects originated from induced gravity on the brane. Then, since in the formal 4D limit $r_c \rightarrow \infty$ the results of Ref. [17] are to be recovered, the critical points found in that reference—including the scaling solution—have to be, also, critical points of the corresponding DGP model.

It can be of interest to investigate the present DGP scenario for arbitrary self-interaction potentials, to show that independence of the gravitational screening of the initial conditions is distinctive only of the constant potential case. This task would entail a different approach than the one undertaken in this Letter, so that we leave it for future work.

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