JOURNAL OF COMPUTATIONAL AND APPLIED MATHEMATICS

# Exponential stability for one-dimensional problem of swelling porous elastic soils with fluid saturation 

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#### Abstract

This paper concerns the one-dimensional linear theory of swelling porous elastic soils in the case of fluid saturation. The formulation belongs to the theory of mixtures for porous elastic solids filled with fluid. It proposes some new mathematical difficulties. We prove the exponential stability for the initial-boundary value problem determined by the homogeneous Dirichlet boundary conditions. (c) 2002 Elsevier Science B.V. All rights reserved.


Keywords: Mixtures; Exponential stability

## 1. Introduction

It is accepted that the swelling of soils, drying of fibers, wood, paper, plants, etc. are problems concerning porous media theory. There have been, in fact, several recent articles introducing continuum theories for fluids infiltrating elastic porous media, see e.g. Payne et al. [5] and other references therein. It is only by analysing such theories mathematically that we shall be in a position to assess their suitability for use in a given physical problem. In this paper we concentrate on Eringen's theory presented in [3]. We recall that in the introduction Eringen pointed out that "I believe the present theory can provide basis for the treatment of various practical problems in the field of swelling, oil explanations, slurred and consolidation problems by further simplifications and/or extensions of the theory". It is worth noting that the formulation belongs to the theory of mixtures for porous elastic solids filled with fluid. Heat conduction was also included. In the present paper we are concerned with the linear equations proposed in this theory. When swelling, consolidation and many other problems, such as motion of gas, liquid and solid are small then linear equations can be adequate for the treatment of these problems. Some results concerning this problem have been obtained recently $[6,7]$.

In this paper, we restrict our attention to the homogeneous displacement-boundary conditions although other conditions could be also considered.

The purpose of this article is to obtain exponential stability for a one-dimensional linear problem in Eringen's theory [3]. Thus, it is worth recalling several results concerning exponential stability in other theories $[1,4]$. We restrict our attention to the case of fluid saturation. Such studies are important in view to assess whether a given theory is mathematically acceptable. It is worth noting that in dimensions two or three the equations are more complicated. Thus, our approach cannot be used in dimension $>1$.

In Section 2, we recall the problem we study in this paper. In Section 3, we use the energy method to prove the exponential stability of solutions in the isothermal case. The extension of this results to the nonisothermal case is sketched in Section 4. In the last section, we use the Hurtwitz theorem to prove exponential stability of solutions when $a_{2} \neq 0$ and $\xi=0$ (see (2.1), (2.2)).

## 2. Preliminaries

The field equations of the linear theory of swelling porous elastic soils in the case of fluid saturation are (see [3], p. 1345)

$$
\begin{align*}
& \rho_{z} \ddot{z}=a_{1} z_{x x}+a_{2} u_{x x}+\beta_{1} T_{x}-\xi(\dot{z}-\dot{u})+\mu_{z} \dot{z}_{x x}  \tag{2.1}\\
& \rho_{u} \ddot{u}=a_{2} z_{x x}+\mu u_{x x}+\beta_{2} T_{x}+\xi(\dot{z}-\dot{u})  \tag{2.2}\\
& c \dot{T}=\beta_{1} \dot{z}_{x}+\beta_{2} \dot{u}_{x}+k T_{x x} . \tag{2.3}
\end{align*}
$$

Eqs. (2.1)-(2.3) constitute a system of three partial differential equations with three unknown functions $(z, u, T)$ that represent the displacements of fluid and solid elastic material, respectively, and the temperature. The constants $\rho_{z}, \rho_{u}$ are the densities of each constituent and $c$ is the heat capacity. The parameters $a_{1}, a_{2}, a_{3}, \beta_{1}, \beta_{2}, \xi, \mu, \mu_{z}$ and $k$ are the constitutive constants in this theory.

To define a problem we need boundary and initial conditions. When the system (2.1)-(2.3) is considered the initial conditions are

$$
\begin{align*}
& z(x, 0)=z^{0}, \quad u(x, 0)=u^{0}, \quad T(x, 0)=T^{0}, \quad x \in[0, L],  \tag{2.4}\\
& \dot{z}(x, 0)=y^{0}, \quad \dot{u}(x, 0)=v^{0}, \quad x \in[0, L], \tag{2.5}
\end{align*}
$$

and the homogeneous boundary conditions are

$$
\begin{equation*}
z(x, t)=u(x, t)=T(x, t)=0, \quad x=0, L . \tag{2.6}
\end{equation*}
$$

It is worth noting that the existence of solutions of the problem determined by (2.1)-(2.6) can be obtained directly by means of the semigroup theory.

From a mathematical point of view system (2.1)-(2.3), propose new stimulating questions. For instance, does the dissipation of the fluid imply the exponential stability even in the isothermal case?

## 3. Isothermal case

The aim of this section is to obtain an exponential stability result in the isothermal case. To this end we use the energy methods (see $[2,4]$ ). In this section, we assume that

$$
\begin{equation*}
\rho_{z}>0, \quad \rho_{u}>0, \quad \mu_{z}>0, \quad \xi>0 \tag{3.1}
\end{equation*}
$$

and that the matrix

$$
\left(\begin{array}{cc}
a_{1} & a_{2}  \tag{3.2}\\
a_{2} & \mu
\end{array}\right)
$$

is definite positive.
The system of equations we consider here introduces new mathematical difficulties in order to use the usual energy method.

If we define the energy function

$$
\begin{equation*}
E_{1}(t)=\frac{1}{2} \int_{0}^{L}\left(\rho_{z}(\dot{z})^{2}+\rho_{u}(\dot{u})^{2}+a_{1}\left(z_{x}\right)^{2}+2 a_{2} z_{x} u_{x}+\mu\left(u_{x}\right)^{2}\right) \mathrm{d} l \tag{3.3}
\end{equation*}
$$

the evolutionary equations and the boundary conditions imply that

$$
\begin{equation*}
\frac{\mathrm{d} E_{1}(t)}{\mathrm{d} t}=-\int_{0}^{L}\left(\xi(\dot{z}-\dot{u})^{2}+\mu_{z}\left(\dot{z}_{x}\right)^{2}\right) \mathrm{d} l . \tag{3.4}
\end{equation*}
$$

In view of the arithmetic geometric inequality and the Poincare inequality, we may conclude the existence of three positive constants $m_{1}, m_{2}, m_{3}$ (see the appendix) such that

$$
\begin{equation*}
\frac{\mathrm{d} E_{1}(t)}{\mathrm{d} t} \leqslant-\int_{0}^{L}\left(m_{1}(\dot{z})^{2}+m_{2}(\dot{u})^{2}+m_{3}\left(\dot{z}_{x}\right)^{2}\right) \mathrm{d} l . \tag{3.5}
\end{equation*}
$$

Now, let us consider the functions

$$
\begin{equation*}
W_{z}(t)=\int_{0}^{L} \rho_{z} \dot{z} z \mathrm{~d} l, \quad W_{u}(t)=\int_{0}^{L} \rho_{u} \dot{u} u \mathrm{~d} l . \tag{3.6}
\end{equation*}
$$

We have

$$
\begin{equation*}
\frac{\mathrm{d} W_{z}(t)}{\mathrm{d} t}=-\int_{0}^{L}\left(a_{1} z_{x}^{2}+a_{2} u_{x} z_{x}+\xi(\dot{z}-\dot{u}) z+\mu_{z} \dot{z}_{x} z_{x}\right) \mathrm{d} l+\int_{0}^{L} \rho_{z}(\dot{z})^{2} \mathrm{~d} l, \tag{3.7}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\mathrm{d} W_{u}(t)}{\mathrm{d} t}=-\int_{0}^{L}\left(a_{2} z_{x} u_{x}+\mu u_{x}^{2}-\xi(\dot{z}-\dot{u}) u\right) \mathrm{d} l+\int_{0}^{L} \rho_{u}(\dot{u})^{2} \mathrm{~d} l . \tag{3.8}
\end{equation*}
$$

Thus, if we denote

$$
\begin{equation*}
W(t)=W_{z}(t)+W_{u}(t)+\frac{1}{2} \int_{0}^{L}\left(\xi(z-u)^{2}+\mu_{z} z_{x}^{2}\right) \mathrm{d} l \tag{3.9}
\end{equation*}
$$

it follows that:

$$
\begin{equation*}
\frac{\mathrm{d} W(t)}{\mathrm{d} t}=-\int_{0}^{L}\left(a_{1} z_{x}^{2}+2 a_{2} u_{x} z_{x}+\mu u_{x}^{2}-\rho_{z}(\dot{z})^{2}-\rho_{u}(\dot{u})^{2}\right) \mathrm{d} l . \tag{3.10}
\end{equation*}
$$

From the definition of the functions $E_{1}$ and $W$ and after a use of the Poincare inequality, we may obtain the existence of a constant $N_{0}$ such that for all $N_{1} \geqslant N_{0}$ we may obtain two positive constants $N_{2}\left(N_{1}\right), N_{3}\left(N_{1}\right)$ (see the appendix) such that

$$
\begin{equation*}
N_{2} E_{1} \leqslant N_{1} E_{1}+W \leqslant N_{3} E_{1} \tag{3.11}
\end{equation*}
$$

From (3.5) and (3.10), we can always select $M_{0}$ such that for all $M_{1} \geqslant M_{0}$ we may obtain a positive constant $M_{2}\left(M_{1}\right)$ (see the appendix) such that

$$
\begin{equation*}
M_{1} \frac{\mathrm{~d} E_{1}}{\mathrm{~d} t}+\frac{\mathrm{d} W}{\mathrm{~d} t} \leqslant-M_{2} E_{1} \tag{3.12}
\end{equation*}
$$

The last two inequalities imply that we may always select two positive constants $\phi, \varphi$ such that

$$
\begin{equation*}
\phi \frac{\mathrm{d} E_{1}}{\mathrm{~d} t}+\frac{\mathrm{d} W}{\mathrm{~d} t} \leqslant-\varphi\left(\phi E_{1}+W\right) \tag{3.13}
\end{equation*}
$$

A quadrature implies that

$$
\begin{equation*}
\left(\phi E_{1}+W\right)(t) \leqslant\left(\phi E_{1}+W\right)(0) \exp (-\varphi t) \tag{3.14}
\end{equation*}
$$

Using again inequality (3.11) we may obtain a constant $R$ such that

$$
\begin{equation*}
E_{1}(t) \leqslant R E_{1}(0) \exp (-\varphi t) \tag{3.15}
\end{equation*}
$$

that is the result of exponential stability.
Remark. To obtain the exponential stability we have used the combination of two damping processes. We have assumed that $\mu_{z}$ and $\xi$ are strictly positive. Now, we see that if at least one of these conditions is not satisfied we can always find solutions that are not damped.

For instance, if $\mu_{z}=0$ and

$$
\frac{a_{1}+a_{2}}{\rho_{z}}=\frac{a_{2}+\mu}{\rho_{u}}
$$

we may select initial conditions such that $z^{0}=u^{0}$ and $y^{0}=v^{0}$. In this case, the solutions are $z=u$ and correspond to the solutions of the wave equation

$$
\rho_{u} \ddot{u}=\left(a_{2}+\mu\right) u_{x x} .
$$

It is worth recalling Ref. [1], where asymptotic stability is obtained for systems of this kind.
If we assume that $\xi=0$ and restrict our attention to the case $a_{2}=0$, the system is composed of two separated equations. The equation for $u$ is again the undamped wave equation. Then the solutions do not tend to zero. A natural question is to know if there exists exponential stability when $a_{2} \neq 0$. This will be the aim of the last section.

## 4. Nonisothermal case

It is well known that the combination of the thermal effects with the elastic effects determines exponential stability [4]. In the last section we have seen that the same thing holds in the kind of mixture we consider. Thus, it is natural to expect the same behaviour when we consider the two
effects at the same time. We only sketch the proof in this case. It is worth noting that in this case, we also assume that $c>0$ and $k>0$.

If we define the function

$$
\begin{equation*}
E_{1}(t)=\frac{1}{2} \int_{0}^{L}\left(\rho_{z}(\dot{z})^{2}+\rho_{u}(\dot{u})^{2}+a_{1} z_{x}^{2}+2 a_{2} z_{x} u_{x}+\mu u_{x}^{2}+c T^{2}\right) \mathrm{d} l, \tag{4.1}
\end{equation*}
$$

we obtain

$$
\begin{equation*}
\frac{\mathrm{d} E_{1}(t)}{\mathrm{d} t} \leqslant-\int_{0}^{L}\left(m_{1}(\dot{z})^{2}+m_{2}(\dot{u})^{2}+m_{3}\left(\dot{z}_{x}\right)^{2}+m_{4} T^{2}+m_{5} T_{x}^{2}\right) \mathrm{d} l \tag{4.2}
\end{equation*}
$$

where $m_{4}$ and $m_{5}$ are also positive. If we define $W$ as in (3.9), it follows:

$$
\begin{equation*}
\frac{\mathrm{d} W(t)}{\mathrm{d} t}=-\int_{0}^{L}\left(a_{1} z_{x}^{2}+2 a_{2} u_{x} z_{x}+\mu u_{x}^{2}-\rho_{z}(\dot{z})^{2}-\rho_{u}(\dot{u})^{2}+\beta_{1} T_{x} z+\beta_{2} T_{x} u\right) \mathrm{d} l . \tag{4.3}
\end{equation*}
$$

It is clear that in this situation, it is easy to reproduce the arguments to prove the exponential stability of the solutions.

## 5. Isothermal problem: limiting case $\xi=0$ and $a_{2} \neq 0$

The aim of this section is to prove the exponential stability of the solutions of the isothermal problem in the particular case that $\xi=0$ and $a_{2} \neq 0$. To make the calculations easier, we assume that $L=\pi$.

The solutions in this case will be combinations of functions of the form

$$
\begin{equation*}
z=A \exp (\omega t) \sin n x, \quad u=B \exp (\omega t) \sin n x . \tag{5.1}
\end{equation*}
$$

Imposing (5.1) as a solution of Eqs. (2.1) and (2.2) we obtain the following homogeneous system with the unknowns $A, B$ :

$$
\begin{equation*}
A \rho_{z} \omega^{2}=-A a_{1} n^{2}-B a_{2} n^{2}-A \mu_{z} \omega n^{2}, \quad B \rho_{u} \omega^{2}=-A a_{2} n^{2}-B \mu n^{2} . \tag{5.2}
\end{equation*}
$$

Our aim is to obtain a nontrivial solution. We impose that the determinant of the system is equal to zero. Here, $\omega$ is a solution of the equation

$$
\begin{equation*}
\left(\rho_{z} x^{2}+a_{1} n^{2}+\mu_{z} n^{2} x\right)\left(\rho_{u} x^{2}+\mu n^{2}\right)-a_{2}^{2} n^{4}=0 \tag{5.3}
\end{equation*}
$$

We can write this equation in the form

$$
\begin{equation*}
\rho_{u} \rho_{z} x^{4}+\mu_{z} \rho_{u} n^{2} x^{3}+\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2} x^{2}+\mu_{z} \mu n^{4} x+\left(a_{1} \mu-a_{2}^{2}\right) n^{4}=0 . \tag{5.4}
\end{equation*}
$$

In order to prove the exponential stability, it will be sufficient to prove that all the solutions of Eq. (5.4) have negative real part that is less or equal than $-\varepsilon$, where $\varepsilon$ is a positive number. This is equivalent to prove that all the solutions of the equation

$$
\begin{align*}
& \rho_{u} \rho_{z}(x-\varepsilon)^{4}+\mu_{z} \rho_{u} n^{2}(x-\varepsilon)^{3}+\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2}(x-\varepsilon)^{2}+\mu_{z} \mu n^{4}(x-\varepsilon) \\
& \quad+\left(a_{1} \mu-a_{2}^{2}\right) n^{4}=0 \tag{5.5}
\end{align*}
$$

have a negative real part.

To show it, we use the Hurwitz theorem that says that the necessary and sufficient condition to guarantee that the solutions of the equation

$$
\begin{equation*}
l_{4} x^{4}+l_{3} x^{3}+l_{2} x^{2}+l_{1} x+l_{0}=0 \tag{5.6}
\end{equation*}
$$

have a negative real part given by

$$
\Lambda_{0}=l_{0}>0, \quad \Lambda_{1}=l_{1}>0, \quad \Lambda_{2}=\operatorname{det}\left(\begin{array}{cc}
l_{1} & l_{3}  \tag{5.7}\\
l_{0} & l_{2}
\end{array}\right)>0, \quad \Lambda_{3}=\operatorname{det}\left(\begin{array}{ccc}
l_{1} & l_{3} & 0 \\
l_{0} & l_{2} & l_{4} \\
0 & l_{1} & l_{3}
\end{array}\right)>0
$$

and

$$
\Lambda_{4}=\operatorname{det}\left(\begin{array}{cccc}
l_{1} & l_{3} & 0 & 0  \tag{5.8}\\
l_{0} & l_{2} & l_{4} & 0 \\
0 & l_{1} & l_{3} & 0 \\
0 & l_{0} & l_{2} & l_{4}
\end{array}\right)>0
$$

In our case we can write Eq. (5.5) as

$$
\begin{align*}
& \rho_{u} \rho_{z} x^{4}+\left(\mu_{z} \rho_{u} n^{2}+P_{3}(\varepsilon)\right) x^{3}+\left[\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2}+P_{2}\left(\varepsilon, n^{2}\right)\right] x^{2} \\
& +\left[\mu_{z} \mu n^{4}+P_{1}\left(\varepsilon, n^{2}\right)\right] x+\left(a_{1} \mu-a_{2}^{2}\right) n^{4}+P_{0}\left(\varepsilon, n^{4}\right)=0, \tag{5.9}
\end{align*}
$$

where

$$
\begin{aligned}
& P_{3}=-4 \rho_{u} \rho_{z} \varepsilon, \quad P_{2}=6 \rho_{u} \rho_{z} \varepsilon^{2}-3 \varepsilon \mu_{z} \rho_{u} n^{2} \\
& P_{1}=-4 \varepsilon^{3} \rho_{u} \rho_{z}+3 \varepsilon^{2} \mu_{z} \rho_{u} n^{2}-2 \varepsilon\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2} \\
& P_{0}=\rho_{u} \rho_{z} \varepsilon^{4}-\mu_{z} \rho n^{2} \varepsilon^{3}+\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2} \varepsilon^{2}-\mu_{z} \mu \varepsilon n^{4}
\end{aligned}
$$

Our intention is to obtain the existence of $\varepsilon$ uniformly for every $n \geqslant 1$. We have

$$
\begin{align*}
\Lambda_{0} & =\left(a_{1} \mu-a_{2}^{2}\right) n^{4}+P_{0} \geqslant\left(a_{1} \mu-a_{2}^{2}\right) n^{4}-\rho_{u} \rho_{z} \varepsilon^{4}-\mu_{z} \rho n^{2} \varepsilon^{3}-\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2} \varepsilon^{2}-\mu_{z} \mu \varepsilon n^{4} \\
& \geqslant n^{4}\left[\left(a_{1} \mu-a_{2}^{2}\right)-\rho_{u} \rho_{z} \varepsilon^{4}-\mu_{z} \rho \varepsilon^{3}-\left(a_{1} \rho_{u}+\mu \rho_{z}\right) \varepsilon^{2}-\mu_{z} \mu \varepsilon\right] . \tag{5.10}
\end{align*}
$$

It is clear that we can select $\varepsilon_{1}$ such that

$$
\begin{equation*}
\left(a_{1} \mu-a_{2}^{2}\right)-\rho_{u} \rho_{z} \varepsilon_{1}^{4}-\mu_{z} \rho \varepsilon_{1}^{3}-\left(a_{1} \rho_{u}+\mu \rho_{z}\right) \varepsilon_{1}^{2}-\mu_{z} \mu \varepsilon_{1}>0 \tag{5.11}
\end{equation*}
$$

In a similar way

$$
\begin{align*}
\Lambda_{1} & \geqslant \mu_{z} \mu n^{4}-4 \varepsilon^{3} \rho_{u} \rho_{z}-3 \varepsilon^{2} \mu_{z} \rho_{u} n^{2}-2 \varepsilon\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2} \\
& \geqslant n^{4}\left[\mu_{z} \mu-4 \varepsilon^{3} \rho_{u} \rho_{z}-3 \varepsilon^{2} \mu_{z} \rho_{u}-2 \varepsilon\left(a_{1} \rho_{u}+\mu \rho_{z}\right)\right] . \tag{5.12}
\end{align*}
$$

We can select $\varepsilon_{2}$ such that

$$
\begin{equation*}
\mu_{z} \mu-4 \varepsilon_{2}^{3} \rho_{u} \rho_{z}-3 \varepsilon_{2}^{2} \mu_{z} \rho_{u}-2 \varepsilon_{2}\left(a_{1} \rho_{u}+\mu \rho_{z}\right)>0 \tag{5.13}
\end{equation*}
$$

Some easy calculations allow us to see that

$$
\begin{equation*}
\Lambda_{2}=\mu^{2} \mu_{z} \rho_{z} n^{6}+a_{2}^{2} \mu_{z} \rho_{u} n^{6}-Q_{2}\left(\varepsilon, n^{6}\right), \tag{5.14}
\end{equation*}
$$

where

$$
Q_{2}=P_{1}\left(a_{1} \rho_{u}+\mu \rho_{z}\right) n^{2}+P_{2} \mu_{z} \mu n^{4}+P_{2} P_{1}-P_{3} P_{0}-\left(a_{1} \mu-a_{2}^{2}\right) n^{4} P_{3}-\mu_{z} \rho_{u} n^{2} P_{0} .
$$

We can repeat the previous argument to prove that there exists $\varepsilon_{3}$ such that $\Lambda_{2}>0$. Similar arguments give

$$
\begin{equation*}
\Lambda_{3}=n^{8} \mu_{z}^{2} \rho_{u}^{2} a_{2}^{2}-Q_{3}\left(\varepsilon, n^{8}\right) \tag{5.15}
\end{equation*}
$$

and

$$
\begin{equation*}
\Lambda_{4}=n^{8} \mu_{z}^{2} \rho_{u}^{3} \rho_{z} a_{2}^{2}-Q_{4}\left(\varepsilon, n^{8}\right) . \tag{5.16}
\end{equation*}
$$

Here, $Q_{3}$ and $Q_{4}$ are two polynomials that can be treated in a way similar to that used in the study of $\Lambda_{0}, \Lambda_{1}$ and $\Lambda_{2}$, but we do not include the total expression to save cumbersome calculations. Nevertheless, it is important to note that we can do that because $a_{2} \neq 0$. The relevant thing is to see that we can repeat the previous arguments and that we can find $\varepsilon$ sufficiently small to guarantee that conditions (5.7) and (5.8) are satisfied. Thus, for $\varepsilon$ sufficiently small $\Lambda_{i}>0, i=0, \ldots, 4, n \geqslant 1$. Thus, the solutions of Eq. (5.4) lie on the left of the line $\operatorname{Re}\{z\}=-\varepsilon$. This implies the exponential stability of solutions.

From the analysis, we can conclude that the condition $L=\pi$ is not restrictive. We can adapt the same method in the general case. Thus, we can obtain exponential stability in the general case.

It is natural to expect exponential stability for the nonisothermal case.

## Acknowledgement

This work is supported by the Project BFM2000-0809.

## Appendix

The aim of this appendix is to obtain numerical values for the parameters $m_{i}, M_{i}$ and $N_{i}$. From equality (3.4) and Poincaré's inequality, we have

$$
\begin{aligned}
\frac{\mathrm{d} E_{1}}{\mathrm{~d} t} \leqslant & -\int_{0}^{L}\left(\xi(\dot{z})^{2}+\xi(\dot{u})^{2}-2 \xi \dot{u} \dot{z}+\frac{\mu_{z} \pi^{2}}{2 L^{2}}(\dot{z})^{2}+\frac{\mu_{z}}{2}\left(\dot{z}_{x}\right)^{2}\right) \mathrm{d} l \\
= & -\int_{0}^{L}\left(\left(\xi+\frac{\mu_{z} \pi^{2}}{2 L^{2}}\right)(\dot{z})^{2}+\xi(\dot{u})^{2}-2 \xi \dot{u} \dot{z}+\frac{\mu_{z}}{2}\left(\dot{z}_{x}\right)^{2}\right) \mathrm{d} l \\
= & -\int_{0}^{L}\left(\left(\sqrt{\xi+\frac{\mu_{z} \pi^{2}}{4 L^{2}}} \dot{z}-\frac{\xi \dot{u}}{\sqrt{\xi+\left(\mu_{z} \pi^{2} / 4 L^{2}\right)}}\right)^{2}+\frac{\mu_{z} \pi^{2}}{4 L^{2}}(\dot{z})^{2}\right. \\
& \left.+\left(\xi-\frac{\xi^{2}}{\xi+\frac{\mu_{z} \pi^{2}}{4 L^{2}}}\right)(\dot{u})^{2}+\frac{\mu_{z}}{2}\left(\dot{z}_{x}\right)^{2}\right) \mathrm{d} l
\end{aligned}
$$

$$
\leqslant-\int_{0}^{L}\left(\frac{\mu_{z} \pi^{2}}{4 L^{2}}(\dot{z})^{2}+\left(\xi-\frac{\xi^{2}}{\xi+\left(\mu_{z} \pi^{2} / 4 L^{2}\right)}\right)(\dot{u})^{2}+\frac{\mu_{z}}{2}\left(\dot{z}_{x}\right)^{2}\right) \mathrm{d} l .
$$

Thus, we can take

$$
m_{1}=\frac{\mu_{z} \pi^{2}}{4 L^{2}}, \quad m_{2}=\xi-\frac{\xi^{2}}{\xi+\left(\mu_{z} \pi^{2} / 4 L^{2}\right)}, \quad m_{3}=\frac{\mu_{z}}{2}
$$

In order to find some values for the parameters $N_{i}$, it is convenient to bound $|W|$ by means of $E_{1}$. We have

$$
\begin{aligned}
|W| & \leqslant \int_{0}^{L}\left(\frac{1}{2} \rho_{z} z^{2}+\frac{1}{2} \rho_{z}(\dot{z})^{2}+\frac{1}{2} \rho_{u} u^{2}+\frac{1}{2} \rho_{u}(\dot{u})^{2}+\xi z^{2}+\xi u^{2}+\frac{1}{2} \mu_{z} z_{x}^{2}\right) \mathrm{d} l \\
& \leqslant \int_{0}^{L}\left(\frac{L^{2}}{2 \pi^{2}} \rho_{z} z_{x}^{2}+\frac{1}{2} \rho_{z}(\dot{z})^{2}+\frac{L^{2}}{2 \pi^{2}} \rho_{u} u_{x}^{2}+\frac{1}{2} \rho_{u}(\dot{u})^{2}+\frac{L^{2}}{\pi^{2}} \xi z_{x}^{2}+\frac{L^{2}}{\pi^{2}} \xi u_{x}^{2}+\frac{1}{2} \mu_{z} z_{x}^{2}\right) \mathrm{d} l \\
& \leqslant \max \left(1, m^{-1}\left(\rho_{z} \frac{L^{2}}{\pi^{2}}+2 \xi \frac{L^{2}}{\pi^{2}}+\mu_{z}\right), m^{-1}\left(\rho_{u} \frac{L^{2}}{\pi^{2}}+2 \xi \frac{L^{2}}{\pi^{2}}\right)\right) E_{1}(t),
\end{aligned}
$$

where $m$ is the smallest eigenvalue of the matrix (3.2). If we take

$$
N_{1}=2 \max \left(1, m^{-1}\left(\rho_{z} \frac{L^{2}}{\pi^{2}}+2 \xi \frac{L^{2}}{\pi^{2}}+\mu_{z}\right), m^{-1}\left(\rho_{u} \frac{L^{2}}{\pi^{2}}+2 \xi \frac{L^{2}}{\pi^{2}}\right)\right),
$$

we can take

$$
N_{2}=N_{1} / 2, \quad N_{3}=3 N_{1} / 2
$$

To obtain the values for the parameters $M_{1}$ and $M_{2}$, we can consider

$$
\begin{aligned}
M_{1} \frac{\mathrm{~d} E_{1}}{\mathrm{~d} t}+\frac{\mathrm{d} W}{\mathrm{~d} t} \leqslant & -\int_{0}^{L}\left(a_{1} z_{x}^{2}+2 a_{2} u_{x} z_{x}+\mu u_{x}^{2}+m_{3} M_{1}\left(\dot{z}_{x}\right)^{2}\right. \\
& \left.+\left(M_{1} m_{1}-\rho_{z}\right)(\dot{z})^{2}+\left(M_{1} m_{2}-\rho_{u}\right)(\dot{u})^{2}\right) \mathrm{d} l .
\end{aligned}
$$

Thus, we can take

$$
M_{1}=\max \left(\frac{\rho_{z}}{m_{1}}, \frac{\rho_{u}}{m_{2}}\right)+1
$$

and

$$
M_{2}=\min \left(2, \frac{2\left(M_{1} m_{1}-\rho_{z}\right)}{\rho_{z}}, \frac{2\left(M_{1} m_{2}-\rho_{u}\right)}{\rho_{u}}\right)
$$

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