# Stability of Travelling W aves for a Cross-D iffusion M odel 

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A cross-diffusion model of mono-species forest with two age classes is considered in this paper. By $C_{0}$-semigroup theory and a detailed spectral analysis, the asymptotic stability of travelling waves is proved. © 1997 A cademic Press

## 1. INTRODUCTION

A simple mathematical model of mono-species forest with two age classes which takes account of seed production and dispersal was first presented in [1],

$$
\left\{\begin{array}{l}
u_{t}=\delta \beta w-\gamma(v) u-f u  \tag{1.1}\\
v_{t}=f u-h v \\
w_{t}=\alpha v-\beta w+p w_{x x}
\end{array}\right.
$$

where $\gamma(v)=a(v-b)^{2}+c$ with positive $a, b, c$.
By means of an asymptotic procedure, (1.1) is then reduced to the following lower-dimensional reaction-cross-diffusion model [1]

$$
\left\{\begin{array}{l}
u_{t}=\rho v-(v-1)^{2} u-s u+v_{x x}  \tag{1.2}\\
v_{t}=u-h v
\end{array}\right.
$$

[^0]The existence and stability of standing waves of (1.2) has been obtained in [1] (however, the proof of stability in [1] is far from complete), in which a numerical analysis of the existence of the travelling waves was also given. By analytic methods, the existence of other travelling waves of (1.2) was proved in [2], and a detailed relation between speed and parameters $\rho, h, s$ was obtained.

H ere, we first briefly state the main results in [2, 1]. D efine

$$
\begin{aligned}
& \text { region } 0=\{(\rho, h) / 0<\rho<s h\}, \\
& \text { region } 1=\{(\rho, h) / s h<\rho<(s+1) h\}, \\
& \text { region } 2=\{(\rho, h) / \rho>(s+1) h\} .
\end{aligned}
$$

In region $0,(1.2)$ has only one equilibrium point ( 0,0 ); in region $1,(1.2)$ has three equilibrium points ( 0,0 ), ( $u_{-}, v_{-}$), and ( $u_{+}, v_{+}$); in region 2, (1.2) has two nonnegative equilibrium points $(0,0)$ and $\left(u_{+}, v_{+}\right)$, with

$$
v_{ \pm}=1 \pm\left(\frac{\rho-s h}{h}\right)^{1 / 2}, \quad u_{ \pm}=h v_{ \pm} .
$$

We further divide region 1 into two subregions $D_{11}$ and $D_{12}$ as

$$
\begin{gathered}
D_{11}=\left\{(\rho, h) / s h<\rho<s h+\frac{1}{9} h\right\}, \\
D_{12}=\left\{(\rho, h) / s h+\frac{1}{9} h<\rho<(s+1) h\right\} .
\end{gathered}
$$

It is shown in [1] that for $\rho=(s+1 / 9) h$, there exists a standing wave ( $U(x), V(x)$ ) of (1.2) with the explicit form

$$
\left\{\begin{array}{l}
U=h V  \tag{1.3}\\
V=\frac{4}{3}\left[1+\exp \left(-\frac{4}{3} \sqrt{h / 2} x\right)\right]^{-1}, \quad \rho=\left(s+\frac{1}{9}\right) h .
\end{array}\right.
$$

Theorem 1 [2]. For any $(\rho, h) \in D_{11} \cup D_{12}$, there exists a unique $c_{1}^{*}(\rho, h)$ such that (1.2) has a travelling wave solution $\left(U\left(x+c_{1}^{*} t\right), V(x+\right.$ $\left.c_{1}^{*} t\right)$ ) connecting $(0,0)$ and $\left(u_{+}, v_{+}\right)$, where $V$ is a monotone increasing
function and

$$
\begin{align*}
& 0>c_{1}^{*}(\rho, h)>-\frac{\sqrt{h}}{\sqrt{(s+h)^{2}+h}} \geq-\frac{1}{\sqrt{4 s+1}}, \quad(\rho, h) \in D_{11},  \tag{1.4}\\
& 0<c_{1}^{*}(\rho, h)<\frac{2 \sqrt{h}}{\sqrt{(s+h)^{2}+4 h}} \leq \frac{1}{\sqrt{s+1}}, \quad(\rho, h) \in D_{12} . \tag{1.5}
\end{align*}
$$

Furthermore, for fixed $s$ and $h, c_{1}^{*}(\rho, h)$ is monotone increasing in $\rho$. For fixed $s$ and $\rho, c_{1}^{*}(\rho, h)$ is monotone decreasing in $h$ for $(\rho, h)$ in $D_{12}$.

In [2], existence of travelling wave solutions of (1.2) connecting ( $u_{-}, v_{-}$) and $\left(u_{+}, v_{+}\right)$with $(\rho, h) \in$ region 1 was also obtained for any $c \in$ [ $\left.\bar{c}_{1}(\rho, h), 1\right)$. For $(\rho, h) \in$ region 2 , the existence of travelling waves of (1.2) for any $c \in\left[\bar{c}_{2}(\rho, h), 1\right)$ was similarly obtained in [2].

In this paper, we shall consider the stability of travelling waves obtained in Theorem 1 of [2] and (1.3), i.e., the stability of travelling waves connecting $(0,0)$ and $\left(u_{+}, v_{+}\right)$, for $(\rho, h)$ in region 1.
We note that due to the cross-diffusion term, (1.2) is no longer a parabolic system, in fact, (1.2) is related to a wave equation with dissipative term, so the theory of analytic semigroups is not valid for (1.2). Furthermore, the classical theory of stability of travelling waves for parabolic systems [3, 4] (e.g., [4, p. 215, Theorem 1.1]) cannot be applied directly to (1.2). Therefore, to deal with the problems with cross-diffusion terms we have to develop a suitable setting, subtle estimates, and spectral analysis.
In this paper, combining the theory of the $C_{0}$-semigroup [5, 7] with some basic ideas in [3], by a series of detailed spectral analysis, we show that the travelling waves obtained in Theorem 1 are exponentially stable with shift in a suitable space. In some sense, we offer a setting for dealing with more general systems in the context of the $C_{0}$-semigroup, although the needed spectral estimates and the splitting of the space is not easy to obtain for non-parabolic systems. The proof of stability is also valid for the standing wave of (1.2), which also overcomes the shortcoming of the proof in [1]. In [1], only the estimates of the eigenvalues for the linearized system are obtained.

The plan of this paper is as follows.
In Section 2, the local existence of solutions of (1.2) is proved and the main result (Stability Theorem) is stated. In Section 3, a series of detailed spectral results are proved. In Section 4, the proof of the main result is given. Some basic lemmas in Section 4 are proved in the A ppendix.

## 2. THE LOCAL EXISTENCE AND MAIN RESULTS

Consider the initial value problem

$$
\left\{\begin{array}{l}
u_{t}=\rho v-(v-1)^{2} u-s u+v_{x x}  \tag{2.1}\\
v_{t}=u-h v \\
u(0, x)=u_{0}(x) \\
v(0, x)=v_{0}(x) .
\end{array}\right.
$$

For ( $\rho, h$ ) in region 1, there exists a unique travelling wave solution ( $U(x+c t), V(x+c t)$ ) of (2.1) connecting $(0,0)$ and $\left(u_{+}, v_{+}\right)$(see Theorem 1 and (1.3)).

By introducing a new variable $\xi=x+c t$, (2.1) can be rewritten as

$$
\left\{\begin{array}{l}
u_{t}=-c u_{\xi}+\rho v-(v-1)^{2} u-s u+v_{\xi \xi}  \tag{2.2}\\
v_{t}=-c v_{\xi}+u-h v \\
u(0, \xi)=u_{0}(\xi) \\
v(0, \xi)=v_{0}(\xi) .
\end{array}\right.
$$

Obviously, $(U(\xi), V(\xi)$ ) is a stationary solution of (2.2). We define the exponential stability of $(U(x+c t), V(x+c t))$ as follows.

Definition 2.1. The travelling wave solution $(U(x+c t), V(x+c t))$ of (2.1) is said to be exponentially stable with shift according to the norm of \|| $\|_{X}$, if there exists $\delta_{0}>0$ such that for any $\left(u_{0}, v_{0}\right)$ with $\|\left(u_{0}-U, v_{0}-\right.$ $V) \|_{X} \leq \delta_{0}$, there exists a unique solution ( $u(t, \xi), v(t, \xi)$ ) of (2.2) on $(0,+\infty)$, with $(u(t, \xi)-U(\xi), v(t, \xi)-V(\xi)) \in X$ and satisfies

$$
\left\|\left(u(t, \xi)-U\left(\xi+\xi_{0}\right), v(t, \xi)-V\left(\xi+\xi_{0}\right)\right)\right\|_{X} \leq M e^{-\beta^{\prime} t}
$$

where $\xi_{0}$ is a number depending on ( $u_{0}, v_{0}$ ); $M>0$ and $\beta^{\prime}>0$ are independent of $t, \xi_{0}$, and $\left(u_{0}, v_{0}\right)$.

To prove the stability of $(U(\xi), V(\xi)$ ), we first consider the local existence of solution of (2.2) in some suitable space. Define $X=L_{2}(R) \times$ $H^{1}(R), X_{0}=H^{1}(R) \times H^{2}(R)$, and

$$
\begin{aligned}
Y & =\{(u, v) /(u-U, v-V) \in X\}, \\
Y_{0} & =\left\{(u, v) /(u-U, v-V) \in X_{0}\right\} .
\end{aligned}
$$

It is easy to prove that $(U, V) \in C^{1}(R) \times C^{2}(R)$ and that $(U, V)$ tends to $(0,0)$ at $-\infty$ and tends to $\left(u_{+}, v_{+}\right)$at $+\infty$ exponentially, respectively.

Theorem 2.1. For any $\left(u_{0}(\xi), v_{0}(\xi)\right) \in Y$ there exists a unique mild solution $(u(t, \xi), v(t, \xi)) \in C\left(\left[0, t_{0}\right), Y\right)$ of (2.2) on some $\left(0, t_{0}\right)$; furthermore, if $\left(u_{0}(\xi), v_{0}(\xi)\right) \in Y_{0}$, then

$$
(u(t, \xi), v(t, \xi)) \in C\left(\left[0, t_{0}\right), Y_{0}\right) \times C^{1}\left(\left[0, t_{0}\right), Y\right)
$$

Denote

$$
w_{1}(t, \xi)=u(t, \xi)-U(\xi), \quad w_{2}(t, \xi)=v(t, \xi)-V(\xi) .
$$

Then $\left(w_{1}(t, \xi), w_{2}(t, \xi)\right)$ satisfies

$$
\left\{\begin{array}{l}
w_{1 t}=-c w_{1 \xi}+w_{2 \xi \xi}+f_{0}\left(w_{1}, w_{2}\right)  \tag{2.3}\\
w_{2 t}=-c w_{2 \xi}+w_{1}+g_{0}\left(w_{1}, w_{2}\right) \\
w_{1}(0, \xi)=w_{10}(\xi) \\
w_{2}(0, \xi)=w_{20}(\xi)
\end{array}\right.
$$

where

$$
\left\{\begin{align*}
f_{0}\left(w_{1}, w_{2}\right)= & \rho w_{2}-s w_{1}-(V-1)^{2} w_{1}-2 U(V-1) w_{2}-U w_{2}^{2}  \tag{2.4}\\
& -2(V-1) w_{1} w_{2} \\
g_{0}\left(w_{1}, w_{2}\right)= & -h w_{2} .
\end{align*}\right.
$$

To prove Theorem 2.1, we only need to prove the local existence of solution of (2.3) and (2.4).

Let

$$
A=\left[\begin{array}{ll}
-c \frac{\partial}{\partial \xi} & \frac{\partial^{2}}{\partial \xi^{2}}  \tag{2.5}\\
1 & -c \frac{\partial}{\partial \xi}
\end{array}\right]
$$

Then (2.3) can be written as

$$
\left\{\begin{array}{l}
w_{t}=A w+F_{0}(w)  \tag{2.6}\\
w(0)=w_{0}
\end{array}\right.
$$

with

$$
w=\left[\begin{array}{l}
w_{1} \\
w_{2}
\end{array}\right], \quad F_{0}(w)=\left[\begin{array}{l}
f_{0}\left(w_{1}, w_{2}\right) \\
g_{0}\left(w_{1}, w_{2}\right)
\end{array}\right] .
$$

Lemma 2.1. The linear operator $A: X_{0} \rightarrow X$ is an infinitesimal generator of a $C_{0}$-semigroup $T(t)$ on $X$ satisfying

$$
\begin{equation*}
\|T(t)\|_{X \rightarrow X} \leq e^{t} \tag{2.7}
\end{equation*}
$$

Proof. Obviously $D(A)=X_{0}$, and $\overline{D(A)}=X$. It is only needed to prove that the resolvent set $\rho(A)$ of $A$ contains the ray $(1, \infty)$ and

$$
\begin{equation*}
\left\|(\lambda I-A)^{-1}\right\|_{X \rightarrow X} \leq \frac{1}{\lambda-1}, \quad \text { for } \lambda>1 \tag{2.8}
\end{equation*}
$$

For any $(f, g) \in X, \lambda>1$, let $w_{2}$ be the solution of

$$
\begin{equation*}
-\left(1-c^{2}\right) w_{2}^{\prime \prime}+2 c \lambda w_{2}^{\prime}+\lambda^{2} w_{2}=g^{*} \triangleq f+\lambda g+c g^{\prime} \in L^{2}(R) . \tag{2.9}
\end{equation*}
$$

By Fourier transformation, it is easy to prove that there exists a unique solution $w_{2} \in H^{2}(R)$ of (2.9).

Let $w_{1}=\lambda w_{2}+c w_{2}^{\prime}-g$. Then $\left(w_{1}, w_{2}\right) \in H^{1} \times H^{2}$ is the unique solution of the equation

$$
\begin{equation*}
(\lambda I-A)\binom{w_{1}}{w_{2}}=\binom{f}{g} \triangleq F . \tag{2.10}
\end{equation*}
$$

Furthermore, it follows from (2.10) that

$$
\begin{aligned}
\|F\|_{X}^{2}= & \|f\|_{L_{2}}^{2}+\|g\|_{L_{2}}^{2}+\left\|g^{\prime}\right\|_{L_{2}}^{2} \\
= & \int_{R}\left(\left|\lambda w_{1}+c w_{1}^{\prime}-w_{2}^{\prime \prime}\right|^{2}+\left|\lambda w_{2}-w_{1}+c w_{2}^{\prime}\right|^{2}\right. \\
& \left.\quad+\left|\lambda w_{2}^{\prime}-w_{1}^{\prime}+c w_{2}^{\prime \prime}\right|^{2}\right) d \xi \\
\geq & \lambda^{2}\left(\left\|w_{1}\right\|_{L_{2}}^{2}+\left\|w_{2}\right\|_{L_{2}}^{2}+\left\|w_{2}^{\prime}\right\|_{L_{2}}^{2}\right)-2 \lambda \operatorname{Re} \int_{R}\left(w_{1} \overline{w_{2}}\right) d \xi \\
> & (\lambda-1)^{2}\left(\left\|w_{1}\right\|_{L_{2}}^{2}+\left\|w_{2}\right\|_{L_{2}}^{2}+\left\|w_{2}^{\prime}\right\|_{L_{2}}^{2}\right), \quad \text { for } \lambda>1,
\end{aligned}
$$

thus

$$
\left\|(\lambda I-A)^{-1}\right\|_{X \rightarrow X} \leq \frac{1}{\lambda-1}, \quad \text { for } \lambda>1
$$

which completes the proof of Lemma 2.1.

Proof of Theorem 2.1. N ote that $H^{1}(R) \hookrightarrow L_{\infty}(R)$, thus

$$
F_{0}(w)=\binom{f_{0}\left(w_{1}, w_{2}\right)}{g_{0}\left(w_{1}, w_{2}\right)}: X \rightarrow X
$$

and $F_{0}(w)$ is lipschitz continuous for any $w \in X$.
By Lemma 2.1 and the theory of the $C_{0}$-semigroup [5], it follows that for any $w_{0} \in X$, there exists a unique mild solution $w(t) \in C\left(\left[0, t_{0}\right), X\right)$ of (2.6); furthermore, if $w_{0} \in D(A)=X_{0}$, then

$$
w(t) \in C\left(\left[0, t_{0}\right), X_{0}\right) \cap C^{1}\left(\left[0, t_{0}\right), X\right) .
$$

This completes the proof of Theorem 2.1.
Now we state the main result of this paper.
Theorem 2.2 (Stability Theorem). For any $(\rho, h) \in$ region 1, the travelling wave solution $(U(x+c t), V(x+c t))$ of (2.1) obtained in Theorem 1 and (1.3) is exponentially stable with shift in norm of $L_{2}(R) \times H^{1}(R)$.

## 3. SOME PRELIMINARY SPECTRAL RESULTS

For any fixed $(\rho, h) \in$ region 1 , let $(U(x+c t), V(x+c t))$ be the travelling wave solution obtained in Theorem 1 and (1.3). Denote $\xi=x+c t$. Then $(U(\xi), V(\xi))$ is a stationary solution of (2.2).

Linearizing (2.2) at ( $U(\xi), V(\xi)$ ), we obtain

$$
\left\{\begin{array}{l}
u_{t}=\rho v-(V-1)^{2} u-2 U(V-1) v-s u+v_{\xi \xi}-c u_{\xi} \triangleq L_{1}(u, v)  \tag{3.1}\\
v_{t}=u-h v-c v_{\xi} \triangleq L_{2}(u, v) .
\end{array}\right.
$$

Define an operator $L: X_{0} \rightarrow X$ as

$$
L\binom{u}{v}=\binom{L_{1}(u, v)}{L_{2}(u, v)}
$$

thus

$$
L=\left(\begin{array}{ll}
-(V-1)^{2}-s-c \frac{\partial}{\partial \xi} & \rho-2 U(V-1)+\frac{\partial^{2}}{\partial \xi^{2}}  \tag{3.2}\\
1 & -h-c \frac{\partial}{\partial \xi}
\end{array}\right) .
$$

Let $w_{1}(t, \xi)=u(t, \xi)-U(\xi), w_{2}(t, \xi)=v(t, \xi)-V(\xi)$. Then $w(t, \xi)=$ ( $\left.w_{1}(t, \xi), w_{2}(t, \xi)\right)$ satisfies

$$
\left\{\begin{array}{l}
w_{t}=L w+O\left(|w|^{2}\right)  \tag{3.3}\\
w(0, \xi)=w_{0}(\xi)
\end{array}\right.
$$

In this section, we shall obtain some detailed spectral estimates for the operator $L$.

Theorem 3.1. For any fixed $(\rho, h) \in$ region 1 , there exists $\beta_{0}>0$, such that

$$
\begin{equation*}
\sup \{\operatorname{Re} \lambda ; \lambda \in \sigma(L) \backslash\{0\}\} \leq-\beta_{0} \tag{3.4}
\end{equation*}
$$

and 0 is the simple eigenvalue of $L$, where $\sigma(L)$ denotes the spectral set of $L$.
We note that for any $\lambda \in \rho(L)=C \backslash \sigma(L)$, the following property holds: $\forall(f, g) \in X$, there exists a unique solution $(u, v) \in X_{0}$ of the problem

$$
\begin{equation*}
(\lambda I-L)\binom{u}{v}=\binom{f}{g} \tag{3.5}
\end{equation*}
$$

It follows from (3.5) that $(u, v)$ satisfies

$$
\begin{equation*}
u=(\lambda+h) v+c v^{\prime}-g \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
v^{\prime \prime}-b(\xi, \lambda) v^{\prime}+d(\xi, \lambda) v=\frac{1}{1-c^{2}}\left[f+(V-1)^{2} g+s g+c g^{\prime}\right] \tag{3.7}
\end{equation*}
$$

with

$$
\begin{array}{r}
b(\xi, \lambda)=\frac{c}{1-c^{2}}\left[2 \lambda+s+h+(V-1)^{2}\right] \\
d(\xi, \lambda)=\frac{1}{1-c^{2}}[\rho-(\lambda+h)(\lambda+s)-2 U(V-1) \\
\left.-(\lambda+h)(V-1)^{2}\right] .
\end{array}
$$

Define the operator $B(\lambda): H^{2}(R) \rightarrow L_{2}(R)$ as

$$
\begin{equation*}
B(\lambda) v=v^{\prime \prime}-b(\xi, \lambda) v^{\prime}+d(\xi, \lambda) v \tag{3.8}
\end{equation*}
$$

Equations (3.6)-(3.8) imply that

$$
\begin{equation*}
\lambda \in \rho(L), \quad \text { iff } 0 \in \rho(B(\lambda)) \tag{3.9}
\end{equation*}
$$

and

$$
\begin{equation*}
\lambda \in \sigma_{p}(L), \quad \text { iff } 0 \in \sigma_{p}(B(\lambda)) . \tag{3.10}
\end{equation*}
$$

Lemma 3.1. For any fixed $(\rho, h) \in$ region 1 , there exists $\alpha_{0}>0$, such that

$$
\begin{equation*}
\sigma_{p}(L) \backslash\{0\} \subset\left\{\lambda / \operatorname{Re} \lambda \leq-\alpha_{0}\right\}, \tag{3.11}
\end{equation*}
$$

and 0 is a simple eigenvalue of $L$.
To prove Lemma 3.1, we need the following spectral results about $B(\lambda)$.
Proposition 3.1. For any fixed $(\rho, h) \in D_{11} \cup D_{12}$, if for some $\lambda$ with $\operatorname{Re} \lambda \geq-\delta_{0}\left(a_{0}>\delta_{0}>0\right.$ small enough depending only on $\left.\rho, h, s\right)$, there exists a solution $v(\xi, \lambda) \in H^{2}(R)$ of

$$
\begin{equation*}
B(\lambda) v(\xi, \lambda)=0, \tag{3.12}
\end{equation*}
$$

then $v(\xi, \lambda)$ must decay to zero exponentially as $\xi \rightarrow \pm \infty$ with exponential rate $\sigma_{ \pm}(\lambda)$, respectively,

$$
\begin{aligned}
& \sigma_{+}(\lambda)=\operatorname{Re}\left(\frac{b_{+}(\lambda)-\sqrt{b_{+}^{2}(\lambda)-4 d_{+}(\lambda)}}{2}\right), \\
& \sigma_{-}(\lambda)=\operatorname{Re}\left(\frac{b_{-}(\lambda)+\sqrt{b_{-}^{2}(\lambda)-4 d_{-}(\lambda)}}{2}\right), \\
& b_{+}(\lambda)=b(+\infty, \lambda), \quad d_{+}(\lambda)=d(+\infty, \lambda), \\
& b_{-}(\lambda)=b(-\infty, \lambda), \quad d_{-}(\lambda)=d(-\infty, \lambda) .
\end{aligned}
$$

Proof. Note that for any fixed $(\rho, h) \in D_{11} \cup D_{12}$, there exists a $\delta_{0}>0$ small enough depending only on $\rho, h$, such that for $\operatorname{Re} \lambda \geq-\delta_{0}$,

$$
\begin{array}{ll}
\operatorname{Re} b_{+}(\lambda)<0, & \text { Re } b_{-}(\lambda)<0, \text { if } c<0, \\
\operatorname{Re~} b_{+}(\lambda)>0, & \text { Re } b_{-}(\lambda)>0, \text { if } c>0 .
\end{array}
$$

First we prove that

$$
\begin{equation*}
\operatorname{Re}\left(\sqrt{b_{+}^{2}-4 d_{+}}\right)>\left|\operatorname{Re}\left(b_{+}\right)\right|>0 . \tag{3.13}
\end{equation*}
$$

Denote

$$
b_{+}=b_{1}+i b_{2}, \quad d_{+}=d_{1}+i d_{2}, \quad \sqrt{b_{+}^{2}-4 d_{+}}=c_{1}+i c_{2}, c_{1} \geq 0,
$$

and

$$
\lambda=\lambda_{1}+i \lambda_{2}
$$

where $b_{1}, b_{2}, d_{1}, d_{2}, \lambda_{1}$, and $\lambda_{2}$ are real numbers satisfying

$$
\begin{gathered}
b_{1}=\frac{c}{1-c^{2}}\left[2 \lambda_{1}+s+h+\left(v_{+}-1\right)^{2}\right], \quad b_{2}=\frac{2 \lambda_{2} c}{1-c^{2}} \\
d_{1}=\frac{1}{1-c^{2}}\left[\rho-h s-2 u_{+}\left(v_{+}-1\right)-h(V-1)^{2}\right. \\
\left.\quad-\lambda_{1}(h+s)-\lambda_{1}\left(v_{+}-1\right)^{2}-\lambda_{1}^{2}+\lambda_{2}^{2}\right] \\
d_{2}=-\frac{\lambda_{2}}{1-c^{2}}\left[2 \lambda_{1}+s+h+\left(v_{+}-1\right)^{2}\right]=\frac{c^{2}-1}{2 c^{2}} b_{1} b_{2}
\end{gathered}
$$

N ote that

$$
\begin{equation*}
b_{1}^{2}-b_{2}^{2}-4 d_{1}=c_{1}^{2}-c_{2}^{2}, \quad b_{1} b_{2}-2 d_{2}=c_{1} c_{2} \tag{3.14}
\end{equation*}
$$

and

$$
b_{1} b_{2}-2 d_{2}=\frac{1}{c^{2}} b_{1} b_{2}, \quad d_{1}<\frac{1}{1-c^{2}} \lambda_{2}^{2}
$$

By (3.14), we have

$$
c_{1}^{2}=\frac{\left(b_{1}^{2}-b_{2}^{2}-4 d_{1}\right)+\sqrt{\left(b_{1}^{2}-b_{2}^{2}-4 d_{1}\right)^{2}+4\left(b_{1} b_{2}-2 d_{2}\right)^{2}}}{2}
$$

and

$$
c_{1}^{2}-b_{1}^{2}=\frac{-b_{1}^{2}-b_{2}^{2}-4 d_{1}+\sqrt{\left(b_{1}^{2}-b_{2}^{2}-4 d_{1}\right)^{2}+\left(4 / c^{4}\right) b_{1}^{2} b_{2}^{2}}}{2}
$$

(i) If $b_{1}^{2}+b_{2}^{2}+4 d_{1}<0$, obviously we have $c_{1}^{2}-b_{1}^{2}>0$, thus (3.13) holds.
(ii) If $b_{1}^{2}+b_{2}^{2}+4 d_{1}=0$, obviously $c_{1}^{2}-b_{1}^{2} \geq 0$. It is easy to see that if $c_{1}^{2}-b_{1}^{2}=0$, then $b_{1}=0$, which is impossible. Thus (3.13) holds
(iii) If $b_{1}^{2}+b_{2}^{2}+4 d_{1}>0$, then

$$
c_{1}^{2}-b_{1}^{2}=\frac{-\left(b_{1}^{2}+b_{2}^{2}+4 d_{1}\right)^{2}+\left(b_{1}^{2}-b_{2}^{2}-4 d_{1}\right)^{2}+\left(4 / c^{4}\right) b_{1}^{2} b_{2}^{2}}{2\left(\left(b_{1}^{2}+b_{2}^{2}+4 d_{1}\right)+\sqrt{\left(b_{1}^{2}-b_{2}^{2}-4 d_{1}\right)^{2}+\left(4 / c^{4}\right) b_{1}^{2} b_{2}^{2}}\right)} .
$$

Note that

$$
\begin{aligned}
& -\left(b_{1}^{2}+b_{2}^{2}+4 d_{1}\right)^{2}+\left(b_{1}^{2}-b_{2}^{2}-4 d_{1}\right)^{2}+\frac{4}{c^{4}} b_{1}^{2} b_{2}^{2} \\
& \\
& \quad=4 b_{1}^{2}\left(-b_{2}^{2}-4 d_{1}+\frac{1}{c^{4}} b_{2}^{2}\right) \\
& \\
& \quad>16 b_{1}^{2}\left[\left(\frac{1}{c^{4}}-1\right) \frac{\lambda_{2}^{2} c^{2}}{\left(1-c^{2}\right)^{2}}-\frac{\lambda_{2}^{2}}{1-c^{2}}\right] \geq 0,
\end{aligned}
$$

thus $c_{1}^{2}-b_{1}^{2}>0$, which completes the proof of (3.13).
Similarly, we can prove that

$$
\begin{equation*}
\operatorname{Re}\left(\sqrt{b_{-}^{2}-4 d_{-}}\right)>\left|\operatorname{Re} b_{-}\right|>0 . \tag{3.15}
\end{equation*}
$$

Therefore $v(\xi, \lambda)$ must decay to zero exponentially as $\xi \rightarrow \pm \infty$ with exponential rate $\sigma_{ \pm}$, respectively. This completes the proof of Proposition 3.1.

Let $v(\xi)$ be a solution of (3.12) for some $\lambda$. Define

$$
\begin{equation*}
\hat{v}(\xi)=v(\xi) \exp \left(-\frac{1}{2} \int_{0}^{\xi} b(s, \lambda) d s\right) . \tag{3.16}
\end{equation*}
$$

Then $\hat{v}(\xi)$ satisfies

$$
\begin{equation*}
\hat{B}(\lambda) \hat{v} \triangleq \hat{v}_{\xi \xi}-D(\xi, \lambda) \hat{v}=0, \tag{3.17}
\end{equation*}
$$

with

$$
\begin{aligned}
D(\xi, \lambda) & =-d(\xi, \lambda)-\frac{1}{2} b^{\prime}(\xi, \lambda)+\frac{1}{4} b^{2}(\xi, \lambda) \\
& =\frac{1}{\left(1-c^{2}\right)^{2}}\left[\lambda^{2}+\lambda\left(h+s+(V-1)^{2}\right)\right]+E(\xi) .
\end{aligned}
$$

It follows from Proposition 3.1 and (3.13)-(3.16) that $\hat{v}(\xi)$ decays to zero exponentially at infinity with the exponential rate $\gamma_{ \pm}=$
$\operatorname{Re}\left(\mp \sqrt{b_{ \pm}^{2}-4 d_{ \pm}} / 2\right)$, respectively, which implies that if for some $\lambda$ with $\operatorname{Re} \lambda \geq-\delta_{0}, 0 \in \sigma_{p}\left(B(\lambda)\right.$ ), then for the same $\lambda$ with $\operatorname{Re} \lambda \geq-\delta_{0}, 0 \in$ $\sigma_{p}(\hat{B}(\lambda))$.
Note that for $\rho=(s+1 / 9) h$, we have $c=0$ and $B(\lambda) \equiv \hat{B}(\lambda)$.
Proposition 3.2. If for some $\lambda$ with $\operatorname{Re} \lambda \geq-\delta_{0}, 0 \in \sigma_{p}(\hat{B}(\lambda))$, then $\lambda$ must be a real number.
Proof. If $0 \in \sigma_{p}(\hat{B}(\lambda))$, for some $\lambda$ with $\operatorname{Re} \lambda \geq-\delta_{0}$, let $v(\xi) \in H^{2}(R)$ satisfy

$$
v_{\xi \xi}-D(\xi, \lambda) v=0 .
$$

Then

$$
\int_{R}\left|v_{\xi}\right|^{2} d \xi+\int_{R} D(\xi, \lambda)|v|^{2} d \xi=0,
$$

thus

$$
\begin{aligned}
& \operatorname{Im} \int_{R} D(\xi, \lambda)|v|^{2} d \xi \\
& \quad=\frac{(\operatorname{Im} \lambda)}{\left(1-c^{2}\right)^{2}} \int_{R}\left(2 \operatorname{Re} \lambda+h+s+(V-1)^{2}\right)|v|^{2} d \xi=0,
\end{aligned}
$$

which implies Im $\lambda=0$; this completes the proof of Proposition 3.2.
In the following, we only need to prove the non-existence of positive constant $\lambda$ for $0 \in \sigma_{p}(\hat{B}(\lambda))$.
By contradiction, assume there exists a positive constant $\lambda$ for $0 \in$ $\sigma_{p}(\hat{B}(\lambda))$.
Note that

$$
\begin{equation*}
D_{\lambda}(\xi, \lambda)>0, \quad \text { for } \lambda \geq 0 \tag{3.18}
\end{equation*}
$$

and

$$
-\left(\widehat{V_{\xi}}\right)_{\xi \xi}+D(\xi, 0) \widehat{V}_{\xi}=0
$$

with $\widehat{V}_{\xi}(\xi)=V_{\xi}(\xi) \exp \left(-\frac{1}{2} \int_{0}^{\xi} b(s, 0) d s\right)>0$.
The Theorem of Sturm-Liouville assures us that $\lambda=0$ is the first simple eigenvalue for the linear eigenvalue problem

$$
\begin{equation*}
-v_{\xi \xi}+D(\xi, 0) v=\lambda v, \tag{3.19}
\end{equation*}
$$

with eigenfunction $\widehat{V}_{\xi}(\xi)$.

Thus for any $\psi(\xi) \in H^{1}(R)$, we have

$$
\begin{equation*}
\int_{R}\left(\left|\psi_{\xi}\right|^{2}+D(\xi, 0)|\psi|^{2}\right) d \xi \geq 0 \tag{3.20}
\end{equation*}
$$

On the other hand, let $v(\xi, \lambda)$ satisfy

$$
v_{\xi \xi}(\xi, \lambda)-D(\xi, \lambda) v(\xi, \lambda)=0 .
$$

Then it follows from (3.18) that

$$
\begin{aligned}
& \int_{R}\left(\left|v_{\xi}(\xi, \lambda)\right|^{2}+D(\xi, 0)|v(\xi, \lambda)|^{2}\right) d \xi \\
& \quad=\int_{R}(-D(\xi, \lambda)+D(\xi, 0))|v(\xi, \lambda)|^{2} d \xi<0
\end{aligned}
$$

which contradicts (3.20).
Therefore, there exists no positive $\lambda$ for (3.17), furthermore, 0 is a simple eigenvalue for (3.19); the same results hold for (3.12). This completes the proof of Lemma 3.1.

Lemma 3.2. For any fixed $(\rho, h) \in$ region 1 , there exists $\beta_{1}>0$ such that if $0 \in \sigma_{\text {ess }}(B(\lambda)) \forall \lambda \in S_{0}$, then $S_{0} \subset\left\{\lambda / \operatorname{Re} \lambda \leq-\beta_{1}\right\}$.

To prove Lemma 3.2, we first consider the following operator $B_{0}(\lambda)$ : $H^{2}(R) \rightarrow L_{2}(R)$,

$$
\begin{equation*}
B_{0}(\lambda)=\frac{d^{2}}{d \xi^{2}}-b_{0}(\xi, \lambda) \frac{d}{d \xi}+d_{0}(\xi, \lambda) \tag{3.21}
\end{equation*}
$$

with

$$
\begin{aligned}
& b_{0}(\xi, \lambda)= \begin{cases}b(-\infty, \lambda), & \xi<0 \\
b(+\infty, \lambda), & \xi>0\end{cases} \\
& d_{0}(\xi, \lambda)= \begin{cases}d(-\infty, \lambda), & \xi<0 \\
d(+\infty, \lambda), & \xi>0\end{cases}
\end{aligned}
$$

N ote that

$$
\begin{equation*}
0 \in \sigma_{\mathrm{ess}}(B(\lambda)) \quad \text { if and only if } 0 \in \sigma_{\mathrm{ess}}\left(B_{0}(\lambda)\right) \tag{3.22}
\end{equation*}
$$

Let

$$
\begin{equation*}
S_{-}=\left\{\lambda /-\tau^{2}-i \tau b(-\infty, \lambda)+d(-\infty, \lambda)=0, \text { for some real } \tau\right\} \tag{3.23}
\end{equation*}
$$

and

$$
\begin{equation*}
S_{+}=\left\{\lambda /-\tau^{2}-i \tau b(+\infty, \lambda)+d(+\infty, \lambda)=0, \text { for some real } \tau\right\} . \tag{3.24}
\end{equation*}
$$

By computation, we have

$$
\begin{aligned}
S_{-}= & \left\{\lambda /\left(\operatorname{Re} \lambda+\frac{h+s+1}{2}\right)^{2}+\frac{I m^{2} \lambda}{c^{2}}=a_{-}\right\} \\
& \cup\left\{\lambda / \operatorname{Re} \lambda=-\frac{s+h+1}{2}\right\},
\end{aligned}
$$

with

$$
a_{-}=\frac{(h+s+1)^{2}}{4}+\rho-(s+1) h>0
$$

and
(i) If $a_{+}=(h+\rho / h)^{2} / 4-2(\rho-s h)-2 \sqrt{h(\rho-s h)}>0$, then

$$
\begin{aligned}
S_{+}= & \left\{\lambda /\left(\operatorname{Re} \lambda+\frac{(h+\rho / h)^{2}}{2}\right)^{2}+\frac{I m^{2} \lambda}{c^{2}}=a_{+}\right\} \\
& \cup\left\{\lambda / \operatorname{Re} \lambda=-\frac{\rho / h+h}{2}\right\}
\end{aligned}
$$

(ii) If $a_{+} \leq 0$, then

$$
S_{+}=\left\{\lambda / \operatorname{Re} \lambda=-\frac{\rho / h+h}{2}\right\} .
$$

O bviously,

$$
\begin{equation*}
\sup \left\{\operatorname{Re} \lambda ; \lambda \in S_{-} \cup S_{+}\right\} \leq-\beta_{1}, \tag{3.25}
\end{equation*}
$$

with

$$
\beta_{1}=\min \left\{\sqrt{(s+1) h-\rho}, \sqrt{2(\rho-s h)+2 \sqrt{h(\rho-s h)}}, \frac{h+\rho / h}{2}\right\} .
$$

D efine

$$
\begin{equation*}
P=\left\{\lambda / \operatorname{Re} \lambda>-\beta_{1}\right\} \tag{3.26}
\end{equation*}
$$

$P$ is an open connected set in $C \backslash\left(S_{+} \cup S_{-}\right)$. It follows from [3, p. 138,

## Lemma 2] that either

(i) $0 \in \sigma\left(B_{0}(\lambda)\right)$ for all $\lambda$ in $P$, or
(ii) $0 \in \rho\left(B_{0}(\lambda)\right)$ for all $\lambda$ in $P$, except at isolated points, at which 0 is an eigenvalue.

Lemma 3.3. For any fixed $(\rho, h) \in$ region 1 , if $\operatorname{Re} \lambda>0$, then

$$
0 \in \rho\left(B_{0}(\lambda)\right), \quad \text { and } \quad\left\|B_{0}^{-1}(\lambda)\right\|_{L_{2}(R) \rightarrow H^{2}(R)} \leq C(\lambda)
$$

Proof. For $\left(v_{1}, v_{2}\right) \in H^{1}(R) \times H^{1}(R)$, define an operator $\bar{B}_{0}(\lambda)$ : $H^{1}(R) \times H^{1}(R) \rightarrow L_{2}(R) \times L_{2}(R)$ as

$$
\bar{B}_{0}(\lambda)\left[\begin{array}{l}
v_{1} \\
v_{2}
\end{array}\right] \triangleq\left[\begin{array}{l}
v_{1} \\
v_{2}
\end{array}\right]+A_{0}(\xi, \lambda)\left[\begin{array}{l}
v_{1} \\
v_{2}
\end{array}\right]
$$

with

$$
\begin{aligned}
& A_{0}(\xi, \lambda)= \begin{cases}A_{+}(\lambda), & \xi>0 \\
A_{-}(\lambda), & \xi<0,\end{cases} \\
& A_{ \pm}(\lambda)=\left[\begin{array}{ll}
0 & -1 \\
d_{ \pm}(\lambda) & -b_{ \pm}(\lambda)
\end{array}\right],
\end{aligned}
$$

and

$$
b_{ \pm}(\lambda)=b( \pm \infty, \lambda), \quad d_{ \pm}(\lambda)=d( \pm \infty, \lambda) .
$$

Let $\sigma_{+}^{ \pm}(\lambda)$ and $\sigma_{-}^{ \pm}(\lambda)$ be eigenvalues of $A_{+}(\lambda)$ and $A_{-}(\lambda)$, respectively. Then

$$
\sigma_{+}^{ \pm}=\frac{-b_{+}(\lambda) \pm \sqrt{b_{+}^{2}(\lambda)+4 d_{+}(\lambda)}}{2}
$$

and

$$
\sigma_{-}^{ \pm}=\frac{-b_{-}(\lambda) \pm \sqrt{b_{-}^{2}(\lambda)=4 d_{-}(\lambda)}}{2}
$$

For $\operatorname{Re} \lambda>0$, Proposition 3.1 assures us that

$$
\begin{equation*}
\operatorname{Re} \sigma_{ \pm}^{+}>0 \quad \text { and } \quad \operatorname{Re} \sigma_{ \pm}^{-}<0 . \tag{3.29}
\end{equation*}
$$

Let $E_{+}, E_{-}$be the projections corresponding to the eigenvalues of $A_{ \pm}(\lambda)$ in the right half-plane. Then (3.29) assures us that

$$
\begin{gathered}
R\left(E_{+}\right)=\left\{k\left(1,-\sigma_{+}^{+}\right), k \in C\right\}, \\
R\left(I-E_{-}\right)=\left\{k\left(\sigma_{-}^{+}, 1\right), k \in C\right\},
\end{gathered}
$$

and

$$
\begin{equation*}
\operatorname{dim} R\left(E_{+}\right)=\operatorname{dim} R\left(I-E_{-}\right)=1 \tag{3.30}
\end{equation*}
$$

Furthermore, (3.29) implies

$$
\begin{equation*}
R\left(E_{+}\right) \cap R\left(I-E_{-}\right)=\{0\} \tag{3.31}
\end{equation*}
$$

It follows from [3, p. 137, Lemma 1] that for $\operatorname{Re} \lambda>0, \bar{B}_{0}(\lambda)$ is invertible, and $\left\|\left(\bar{B}_{0}\right)^{-1}(\lambda)\right\|$ is bounded. Thus for any $f \in L_{2}(R)$, there exists a unique $\left(v_{1}, v_{2}\right) \in H^{1}(R) \times H^{1}(R)$, such that

$$
\bar{B}_{0}(\lambda)\binom{v_{1}}{v_{2}}=\binom{0}{f},
$$

and

$$
\begin{equation*}
\left\|\left(v_{1}, v_{2}\right)\right\|_{H^{1}(R) \times H^{1}(R)} \leq C\|f\|_{L_{2}(R)} \tag{3.32}
\end{equation*}
$$

$N$ ote that $v_{1}^{\prime}=v_{2}$. Then $v_{1}$ satisfies

$$
B_{0}(\lambda) v_{1}=f,
$$

and this with (3.32) completes the proof of Lemma 3.3.
Lemma 3.3 assures us that (3.28) holds; thus

$$
\begin{equation*}
\text { if } 0 \in \sigma_{\text {ess }}\left(B_{0}(\lambda)\right) \text {, then } \lambda \in \mathbb{C} \backslash P \text {. } \tag{3.33}
\end{equation*}
$$

Lemma 3.2 follows from (3.22), (3.26), and (3.33).
Finally Lemmas 3.1-3.2 and (3.9) imply Theorem 3.1.
Theorem 3.2. The linear operator $L: X_{0} \rightarrow X$ is an infinitesimal generator of a $C_{0}$-semigroup $T_{L}(t)$ on $X$ satisfying

$$
\begin{equation*}
\left\|T_{L}(t)\right\|_{X \rightarrow X} \leq e^{\omega_{0} t} \tag{3.34}
\end{equation*}
$$

with $\omega_{0}=\|-\rho+2 U(V-1)\|_{\infty}+1$.
Proof. Theorem 3.1 assures us that the resolvent set $\rho(L)$ of $L$ contains the ray $(0,+\infty)$.

It remains to prove that there exists $\omega_{0}>0$, such that

$$
\begin{equation*}
\left\|(\lambda I-L)^{-1}\right\|_{X \rightarrow X} \leq \frac{1}{\lambda-\omega_{0}}, \quad \text { for } \lambda>\omega_{0} \tag{3.35}
\end{equation*}
$$

For any given $(f, g) \in X, \lambda>0$, let $(u, v) \in X_{0}$ satisfy

$$
(\lambda I-L)\binom{u}{v}=\binom{f}{g}
$$

D efine

$$
\binom{f_{1}}{g_{1}} \triangleq-L\binom{u}{v}=\left(\begin{array}{l}
\left(\begin{array}{l}
\left.s+(V-1)^{2}+c \frac{\partial}{\partial \xi}\right) u \\
+\left(-\rho+2 U(V-1)-\frac{\partial^{2}}{\partial \xi^{2}}\right) v \\
-u+h v+c v^{\prime}
\end{array}\right) . . . . ~ . ~ . ~
\end{array}\right.
$$

N ote that

$$
\begin{align*}
& \int_{R}\left(|f|^{2}+|g|^{2}+\left|g^{\prime}\right|^{2}\right) d \xi \\
&=\int_{R}\left(\left|\lambda u+f_{1}\right|^{2}+\left|\lambda v+g_{1}\right|^{2}+\left|\lambda v^{\prime}+g_{1}^{\prime}\right|^{2}\right) d \xi \\
& \geq \lambda^{2} \int_{R}\left(|u|^{2}+|v|^{2}+\left|v^{\prime}\right|^{2}\right) d \xi+2 \lambda \operatorname{Re} \int_{R}\left(u \overline{f_{1}}+v \overline{g_{1}}+v^{\prime} \overline{g_{1}^{\prime}}\right) d \xi \\
& \geq \lambda^{2}\left(\|u\|^{2}+\|v\|^{2}+\left\|v^{\prime}\right\|^{2}\right)-2 C_{1} \lambda\|u\|\|v\| \\
& \geq\left(\lambda-C_{1}\right)^{2}\left(\|u\|^{2}+\|v\|^{2}+\left\|v^{\prime}\right\|^{2}\right) \quad \text { for } \lambda \geq C_{1} \tag{3.36}
\end{align*}
$$

with

$$
C_{1}=\|-\rho+2 U(V-1)\|_{\infty}+1 .
$$

Thus (3.36) implies that (3.35) holds with $\omega_{0}=C_{1}$; this completes the proof of Theorem 3.2.

Let $X_{2}$ be a subspace in $X$, and $X_{2}^{0}=X_{2} \cap X_{0}$. Define an operator $L_{2}$ : $X_{2}^{0} \rightarrow X_{2}$ as

$$
L_{2} w=L w, \quad \text { for } w \in X_{2}^{0}
$$

and define

$$
\|w\|_{X_{2}}=\|w\|_{X}
$$

In the following, we assume

$$
\begin{equation*}
\rho(L) \subset \rho\left(L_{2}\right), \quad \text { and } \quad 0 \in \rho\left(L_{2}\right) \tag{3.37}
\end{equation*}
$$

Then it follows from Theorem 3.1 that

$$
\begin{equation*}
\operatorname{Re}\left\{\sigma\left(L_{2}\right)\right\} \leq-\beta_{0} . \tag{3.38}
\end{equation*}
$$

Theorem 3.3. Under the assumption of (3.37), the $L_{2}$ generate a $C_{0}{ }^{-}$ semigroup $T_{2}(t)$ on $X_{2}$ satisfying

$$
\begin{equation*}
\left\|T_{2}(t)\right\|_{X_{2} \rightarrow X_{2}} \leq M_{0} e^{-\beta t}, \quad \text { for } t>0, \tag{3.39}
\end{equation*}
$$

for some $M_{0}>0, \beta>0$.
Note that (3.37) implies that Theorem 3.2 is valid for $L_{2}$. It remains to prove (3.39).

It follows from [7] (see also [6]) that (3.39) holds if and only if the following two conditions holds

$$
\begin{align*}
& \text { (i) } \sup \left\{\operatorname{Re} \lambda, \lambda \in \sigma\left(L_{2}\right)\right\}<0,  \tag{3.40}\\
& \text { (ii) } \sup _{\operatorname{Re} \lambda \geq 0}\left\|\left(\lambda-L_{2}\right)^{-1}\right\|_{X_{2} \rightarrow X_{2}}<+\infty \text {. } \tag{3.41}
\end{align*}
$$

By (3.37) and Theorem 3.1, obviously (3.40) holds.
In the following, we only need to prove (3.41) holds.
By Theorem 3.2 and the theory of the $C_{0}$-semigroup [5], we have

$$
\left\|\left(\lambda-L_{2}\right)^{-1}\right\| \leq \frac{1}{(\operatorname{Re} \lambda)-\omega_{0}}, \quad \operatorname{Re} \lambda>\omega_{0} .
$$

Thus

$$
\begin{equation*}
\left\|\left(\lambda-L_{2}\right)^{-1}\right\| \leq 1, \quad \text { for } \lambda \in Q_{1}=\left\{\lambda / \operatorname{Re} \lambda \geq \omega_{0}+1\right\} \tag{3.42}
\end{equation*}
$$

Note that $\{\lambda / \operatorname{Re} \lambda \geq 0\} \subset \rho\left(L_{2}\right)$. Thus for any fixed $n>0$, there exists $C_{n}$ such that

$$
\begin{equation*}
\left\|\left(\lambda-L_{2}\right)^{-1}\right\| \leq C_{n}, \quad \lambda \in P_{n}=\left\{\lambda / 0 \leq \operatorname{Re} \lambda \leq \omega_{0}+1, \| \mathrm{m} \lambda \mid \leq n\right\} . \tag{3.43}
\end{equation*}
$$

To complete the proof of Theorem 3.3, we need to prove the following results.

Lemma 3.4. There exists a constant $0<M_{0}<+\infty$, such that for any $\lambda \in Q_{2}=\left\{\lambda / 0 \leq \operatorname{Re} \lambda \leq \omega_{0}+1, \| m \lambda \mid \geq 1\right\}$,

$$
\begin{equation*}
\left\|\left(\lambda I-L_{2}\right)^{-1}\right\|_{X_{2} \rightarrow X_{2}} \leq M_{0} . \tag{3.44}
\end{equation*}
$$

Furthermore, there exists a constant $0<M_{0}^{*}<+\infty$, such that $\forall \lambda \in Q_{2}$, and $\forall(f, g) \in X_{2}$, if $(u, v)$ is a solution of

$$
\begin{equation*}
\left(\lambda I-L_{2}\right)(u, v)=(f, g), \tag{3.45}
\end{equation*}
$$

then

$$
\begin{equation*}
\|u\|_{L_{2}(R)}+\|\lambda v\|_{L_{2}(R)}+\left\|v^{\prime}\right\|_{L_{2}(R)} \leq M_{0}^{*}\left(\|(f, g)\|_{X_{2}}\right), \quad \lambda \in Q_{2} \tag{3.46}
\end{equation*}
$$

Proof. Obviously for $\lambda \in Q_{2}$, (3.46) implies (3.45), thus we only need to prove (3.46).

By contradiction, assume (3.46) doesn't hold. Then there exists $\left\{\lambda_{n}\right\} \in$ $Q_{2}$, and $\left(u_{n}, v_{n}\right) \in X_{2}^{0}$ such that

$$
\begin{equation*}
\left\|u_{n}\right\|_{L_{2}}+\left\|\lambda_{n} v_{n}\right\|_{L_{2}}+\left\|v_{n}^{\prime}\right\|_{L_{2}}=1, \quad n=1,2, \cdots ; \tag{3.47}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(\lambda_{n} I-L_{2}\right)\left(u_{n}, v_{n}\right) \rightarrow 0, \quad \text { in } X_{2}, \text { as } n \rightarrow \infty . \tag{3.48}
\end{equation*}
$$

Relation (3.43) imply that $\left\{\mathrm{Im} \lambda_{n}\right\}$ must be unbounded. A lso note that $0 \leq \operatorname{Re} \lambda_{n} \leq \omega_{0}+1$, thus we can choose a subsequence of $\left\{\lambda_{n}\right\}$, also denoted by $\left\{\lambda_{n}\right\}$, such that

$$
\begin{equation*}
\operatorname{Re} \lambda_{n} \rightarrow \lambda_{1} \geq 0, \quad \text { Im } \lambda_{n} \rightarrow+\infty, \text { as } n \rightarrow \infty ; \tag{3.49}
\end{equation*}
$$

or

$$
\begin{equation*}
\operatorname{Re} \lambda_{n} \rightarrow \lambda_{1} \geq 0, \quad \text { Im } \lambda_{n} \rightarrow-\infty, \text { as } n \rightarrow \infty . \tag{3.50}
\end{equation*}
$$

Without losing generality, let (3.49) hold.
By (3.48), we have

$$
\begin{array}{r}
\left(\lambda_{n}+s+(V-1)^{2}+c \frac{\partial}{\partial \xi}\right) u_{n}+\left(-\rho+2 U(V-1)-\frac{\partial^{2}}{\partial \xi^{2}}\right) v_{n} \rightarrow 0 \\
\text { in } L_{2}(R) \tag{3.51}
\end{array}
$$

and

$$
\begin{equation*}
-u_{n}+\left(\lambda_{n}+h+c \frac{\partial}{\partial \dot{\xi}}\right) v_{n} \rightarrow 0 \quad \text { in } H^{1}(R) \tag{3.52}
\end{equation*}
$$

M ultiply (3.51) by $\overline{u_{n}}$, then integrate it on $R$ and we have

$$
\begin{aligned}
& \operatorname{Re} \int_{R}\left[\left(\lambda_{n}+s+(V-1)^{2}\right)\left|u_{n}\right|^{2}+c u_{n}^{\prime} \overline{u_{n}}\right] d \xi \\
& \quad+\operatorname{Re} \int_{R}(-\rho+2 U(V-1)) v_{n} \overline{u_{n}} d \xi \\
& \quad+\operatorname{Re} \int_{R} v_{n}^{\prime} \overline{u_{n}^{\prime}} d \xi \rightarrow 0, \quad \text { as } n \rightarrow \infty .
\end{aligned}
$$

Note that (3.47) implies

$$
\begin{aligned}
\left|\operatorname{Re} \int_{R}(-\rho+2 U(V-1)) v_{n} \overline{u_{n}} d \xi\right| & \leq C\left\|v_{n}\right\|_{L_{2}}\left\|u_{n}\right\|_{L_{2}} \\
& \leq \frac{C}{\left|\lambda_{n}\right|}\left\|\lambda_{n} v_{n}\right\|_{L_{2}}\left\|u_{n}\right\|_{L_{2}} \leq \frac{C_{1}}{\left|\lambda_{n}\right|} .
\end{aligned}
$$

Thus

$$
\begin{equation*}
\int_{R}\left(\lambda_{1}+s+(V-1)^{2}\right)\left|u_{n}\right|^{2} d \xi+\operatorname{Re} \int_{B} v_{n}^{\prime} \overline{u_{n}^{\prime}} d \xi \rightarrow 0, \quad \text { as } n \rightarrow \infty . \tag{3.53}
\end{equation*}
$$

By (3.52), we also have

$$
\begin{equation*}
-u_{n}^{\prime}+\left(\lambda_{n}+h\right) v_{n}^{\prime}+c v_{n}^{\prime \prime} \rightarrow 0, \quad \text { in } L_{2}(R), \text { as } n \rightarrow \infty \tag{3.54}
\end{equation*}
$$

M ultiply (3.54) by $\overline{v_{n}^{\prime}}$, then integrate it over $R$ and we have

$$
\begin{equation*}
-\operatorname{Re} \int_{R} u_{n}^{\prime} v_{n}^{\prime} d \xi+\left(\lambda_{1}+h\right) \int_{R}\left|v_{n}^{\prime}\right|^{2} d \xi \rightarrow 0, \quad \text { as } n \rightarrow \infty \tag{3.55}
\end{equation*}
$$

By (3.53) and (3.55), we further have
$\int_{R}\left(\lambda_{1}+s+(V-1)^{2}\right)\left|u_{n}\right|^{2} d \xi+\left(\lambda_{1}+h\right) \int_{R}\left|v_{n}^{\prime}\right|^{2} d \xi \rightarrow 0, \quad$ as $n \rightarrow \infty$.
Thus,

$$
\begin{equation*}
\left\|u_{n}\right\|_{L_{2}} \rightarrow 0, \quad\left\|v_{n}^{\prime}\right\|_{L_{2}} \rightarrow 0, \text { as } n \rightarrow \infty \tag{3.56}
\end{equation*}
$$

R elations (3.52) and (3.56) further imply

$$
\left(\lambda_{n}+h\right) v_{n} \rightarrow 0, \quad \text { in } L_{2}(R), \text { as } n \rightarrow \infty ;
$$

thus

$$
\begin{equation*}
\left\|\lambda_{n} v_{n}\right\|_{L_{2}(R)} \rightarrow 0, \quad \text { as } n \rightarrow \infty . \tag{3.57}
\end{equation*}
$$

Relation (3.56) and (3.57) contradict (3.47), which completes the proof of Lemma 3.4 and Theorem 3.3.

## 4. THE PROOF OF THE STABILITY THEOREM

In this section, we shall give the proof of Theorem 2.2. Before proving Theorem 2.2, we need to obtain some further results about the operator $L$ except those in Section 3.

Lemma 4.1. For any fixed $(\rho, h) \in$ region $1, N(L)=$ $\operatorname{span}\left\{\left(U^{\prime}(\xi), V^{\prime}(\xi)\right)\right\}$ and

$$
\begin{equation*}
N(L) \cap \overline{R(L)}=\{0\} \tag{4.1}
\end{equation*}
$$

The proof is given in the A ppendix.
D efine

$$
L^{*}=\left[\begin{array}{ll}
-s-(V-1)^{2}+c \frac{\partial}{\partial \xi} & 1 \\
\rho-2 U(V-1)+\frac{\partial^{2}}{\partial \xi^{2}} & -h+c \frac{\partial}{\partial \xi}
\end{array}\right]
$$

Obviously, $L^{*}$ is the adjoint operator of $L$.
Note that

$$
X=N\left(L^{*}\right) \oplus \overline{R(L)}
$$

Then Lemma 4.1 implies

$$
N\left(L^{*}\right) \neq\{0\} .
$$

Furthermore, we have
Lemma 4.2. For any $(\rho, h) \in$ region 1 ,

$$
\operatorname{dim} N\left(L^{*}\right)=1
$$

The proof of Lemma 4.2 is given in the Appendix. By Lemmas 4.1-4.2, it is easy to prove the following results.
Lemma 4.3. For any $(\rho, h) \in$ region 1 ,

$$
\begin{equation*}
X=N(L) \oplus \overline{R(L)} \tag{4.2}
\end{equation*}
$$

that is, for any fixed $w \in X$, there exist a unique $w_{0} \in N(L)$ and a unique $w_{1} \in \overline{R(L)}$ such that

$$
w=w_{0}+w_{1}
$$

Note that $X=N\left(L^{*}\right) \oplus \overline{R(L)}$ and

$$
\begin{equation*}
\langle\nu, w\rangle=0, \quad \forall \nu \in N\left(L^{*}\right) \forall w \in \overline{R(L)} \tag{4.3}
\end{equation*}
$$

Lemmas 4.1-4.3 and (4.3) further imply that for $\nu_{0} \in N\left(L^{*}\right),\left\|\nu_{0}\right\|_{X}=1$,

$$
\begin{equation*}
\left\langle\nu_{0}, W_{0}\right\rangle \neq 0, \tag{4.4}
\end{equation*}
$$

where $W_{0}(\xi)=\left(U^{\prime}(\xi), V^{\prime}(\xi)\right)$.

Denote

$$
\begin{equation*}
X_{2}=\overline{R(L)}, \quad X_{2}^{0}=\overline{R(L)} \cap H^{2}(R), \tag{4.5}
\end{equation*}
$$

and define an operator $L_{2}: X_{2}^{0} \rightarrow X_{2}$ as

$$
\begin{equation*}
L_{2} w=L w, \quad w \in X_{2} . \tag{4.6}
\end{equation*}
$$

Lemma 4.4. For any $(\rho, h) \in$ region 1 , if $L_{2}$ is defined by (4.5)-(4.6), then

$$
0 \in \rho\left(L_{2}\right), \quad \text { and } \quad \rho(L) \subset \rho\left(L_{2}\right) .
$$

Proof. Lemma 4.3 implies that $L_{2}$ is an onto operator and $N\left(L_{2}\right)=\{0\}$, thus $0 \in \rho\left(L_{2}\right)$.

For any $\lambda \in \rho(L)$, and any $f \in X_{2}$, there exists a unique $w \in X_{0}$ such that

$$
(\lambda I-L) w=f
$$

By the fact that

$$
\lambda \neq 0, \quad \text { and } \quad \lambda w=L w+f \in X_{2},
$$

we have $w \in X_{2} \cap X_{0}=X_{2}^{0}$, which completes the proof of Lemma 4.4.
Lemma 4.4 assures that Theorem 3.3 holds, thus we have
Theorem 4.1. For any $(\rho, h) \in$ region 1 , operator $L_{2}$ is defined by (4.5)-(4.6). Then $L_{2}$ generate a $C_{0}$-semigroup $e^{L_{2} t}$ on $X_{2}$ satisfying

$$
\begin{equation*}
\left\|e^{L_{2} t}\right\|_{X_{2} \rightarrow X_{2}} \leq C e^{-\beta t} \quad \text { for } t>0 \tag{4.7}
\end{equation*}
$$

for some $\beta>0$.
Now we turn to the proof of the Stability Theorem.
Proof of Theorem 2.2. For any fixed $(\rho, h) \in$ region 1, let $W_{0}(\xi)=$ $(U(\xi), V(\xi))(\xi=x+c t)$ be the travelling wave solution obtained in Theorem 1 and (1.3). For any $\left(u_{0}, v_{0}\right) \in Y$, if $\left\|u_{0}-U\right\|_{L_{2}}+\left\|v_{0}-V\right\|_{H^{1}}$ $<\delta$, it follows from Theorem 2.1 that there exists a unique local solution $(u(t, \xi), v(t, \xi)) \in Y$ of (2.2).

D enote $w(t, \xi)=(u(t, \xi)-U(\xi), v(t, \xi)-V(\xi))$. Then (2.2) becomes

$$
\begin{equation*}
\frac{d w}{d t}=L w+F(w) \tag{4.8}
\end{equation*}
$$

with $F(0)=0, F^{\prime}(0)=0$. Note that for any fixed $\sigma \in R, W_{0}(\xi+\sigma)-$ $W_{0}(\xi)$ satisfies

$$
L\left(W_{0}(\xi+\sigma)-W_{0}(\xi)\right)+F\left(W_{0}(\xi+\sigma)-W_{0}(\xi)\right)=0 .
$$

A $s$ in [3], introducing two new variables $(\sigma(t), y(t, \xi)) \in R \times X_{2}$ such that

$$
\begin{equation*}
w(t, \xi)=W_{0}(\xi+\sigma(t))-W_{0}(\xi)+y(t, \xi), \tag{4.9}
\end{equation*}
$$

then (4.8) becomes
$W_{0}^{\prime}(\xi+\sigma) \frac{d \sigma}{d t}+\frac{d y}{d t}=L y+F\left(W_{0}^{*}(\xi, \sigma)+y(t, \xi)\right)-F\left(W_{0}^{*}(\xi, \sigma)\right)$,
with $W_{0}^{*}(\xi, \sigma)=W_{0}(\xi+\sigma)-W_{0}(\xi)$.
Let $\sigma(t)$ satisfy

$$
\begin{equation*}
\frac{d \sigma}{d t}=\phi(\sigma, y), \tag{4.11}
\end{equation*}
$$

with

$$
\begin{equation*}
\phi(\sigma, y)=\left\langle\nu_{0}, F\left(W_{0}^{*}(\cdot, \sigma)+y\right)-F\left(W_{0}^{*}(\cdot, \sigma)\right\rangle /\left\langle\nu_{0}, W_{0}^{\prime}(\cdot+\sigma)\right\rangle .\right. \tag{4.12}
\end{equation*}
$$

If $\sigma(t)$ is small, then (4.4) and (4.10)-(4.12) assure us that

$$
\left\langle y, \nu_{0}\right\rangle=0, \quad \text { i.e., } y \in X_{2},
$$

and $y$ satisfies

$$
\begin{equation*}
\frac{d y}{d t}=L_{2} y+G(\sigma, y), \tag{4.13}
\end{equation*}
$$

with
$G(\sigma, y)=E_{2}\left\{F\left(W_{0}^{*}(\cdot, \sigma)+y\right)-F\left(W_{0}^{*}(\cdot, \sigma)\right)-W_{0}^{\prime}(\cdot+\sigma) \phi(\sigma, y)\right\}$.
Thus $\phi$ and $G$ are $C^{1}$ functions with

$$
\begin{equation*}
|\phi(\sigma, y)|+\|G(\sigma, y)\|_{X_{2}} \leq \gamma(\rho)\|y\|_{X_{2}}, \quad \text { when }|\sigma|+\|y\|_{X_{2}} \leq \rho, \tag{4.14}
\end{equation*}
$$

and $\gamma(\rho) \rightarrow 0$ as $\rho \rightarrow 0$.
Suppose $|\sigma(0)|+\|y(0)\|_{X_{2}}$ is small; as long as $|\sigma(t)|$ remains less than $\delta>0$, by virtue of Theorem 4.1 and by the standard argument, we can
prove that

$$
\begin{equation*}
\|y(t)\|_{X_{2}} \leq K e^{-\beta^{\prime} t}\|y(0)\|_{X_{2}}, \quad 0<\beta^{\prime}<\beta \tag{4.15}
\end{equation*}
$$

and so

$$
\left|\frac{d \sigma}{d t}(t)\right|=O\left(e^{-\beta^{\prime} t}\right)
$$

Thus $|\sigma(t)|<\delta$ for all $t>0$, and there exists $\sigma_{\infty}$ such that

$$
\left|\sigma(t)-\sigma_{\infty}\right|+\|y(t)\|_{X_{2}}=O\left(e^{-\beta^{\prime} t}\right)
$$

Thus

$$
\begin{equation*}
\left\|u(t, \xi)-U\left(\xi+\sigma_{\infty}\right)\right\|_{L_{2}}+\left\|v(t, \xi)-V\left(\xi+\sigma_{\infty}\right)\right\|_{H^{1}}=O\left(e^{-\beta^{\prime} t}\right) \tag{4.16}
\end{equation*}
$$

which completes the proof of Theorem 2.2.

## APPENDIX

Proof of Lemma 4.1. Lemma 3.1 assures us that $N(L)=$ $\operatorname{span}\left\{\left(U^{\prime}(\xi), V^{\prime}(\xi)\right)\right\}$. To prove (4.1), by contradiction, assume ( $U^{\prime}, V^{\prime}$ ) $\in \overline{R(L)}$. Then there exists a sequence $\left\{\left(u_{n}, v_{n}\right)_{1}^{\infty} \subset X_{0}\right.$ satisfying

$$
L\binom{u_{n}}{v_{n}}-\binom{U^{\prime}}{V^{\prime}} \rightarrow 0, \quad \text { in } X, \text { as } n \rightarrow \infty
$$

Thus

$$
\begin{align*}
\left(-s-(V-1)^{2}-c \frac{\partial}{\partial \xi}\right) u_{n}+\left(\rho-2 U(V-1)+\frac{\partial^{2}}{\partial \xi^{2}}\right) v_{n} & \rightarrow h V^{\prime}+c V^{\prime \prime} \\
& \text { in } L_{2}(R) \tag{A.1}
\end{align*}
$$

$$
\begin{equation*}
v_{n}-h v_{n}-c v_{n}^{\prime} \rightarrow V^{\prime} \quad \text { in } H^{1}(R) \tag{A.2}
\end{equation*}
$$

Substituting (A.2) into (A.1), we have

$$
B_{0} v_{n}-\frac{\left(h+s+(V-1)^{2}\right) V^{\prime}+2 c V^{\prime \prime}}{1-c^{2}} \rightarrow 0 \quad \text { in } L_{2}(R)
$$

with $B_{0}=B(0)$.

Let $\phi_{1}=V^{\prime}$. We note that

$$
B_{0} \phi_{1}=0, \quad \text { and } \quad \phi_{1}(\xi) \neq 0, \xi \in R .
$$

Let $v_{n}(\xi)=C_{1 n}(\xi) \phi_{1}(\xi) \in H^{2}(R)$. Then $C_{1 n}(\xi)$ satisfies

$$
C_{n}^{\prime \prime} \phi_{1}+C_{n}^{\prime}\left(2 \phi_{1}^{\prime}-b \phi_{1}\right)-\frac{\left(h+s+(V-1)^{2}\right) \phi_{1}+2 c \phi_{1}^{\prime}}{1-c^{2}} \rightarrow 0
$$

$$
\begin{equation*}
\text { in } L_{2}(R) \tag{A.3}
\end{equation*}
$$

D efine

$$
\begin{gathered}
\phi_{1}^{*}=\phi_{1} \exp \left(-\int_{0}^{\xi} b(s) d s\right) \\
\left(\phi_{1}^{\prime}\right)^{*}=\phi_{1}^{\prime} \exp \left(-\int_{0}^{\xi} b(s) d s\right),
\end{gathered}
$$

and

$$
\widehat{\phi_{1}}=\phi_{1} \exp \left(-\frac{1}{2} \int_{0}^{\xi} b(s) d s\right),
$$

Lemma 3.1 implies that $\phi_{1}^{*},\left(\phi_{1}^{\prime}\right)^{*}, \widehat{\phi_{1}} \in L_{2}(R)$. M ultiplying (A.3) by $\phi_{1}^{*}$, we have

$$
\left[\begin{array}{r}
{\left[C_{n}^{\prime}\left(\widehat{\phi_{1}}\right)^{2}\right]^{\prime}-\frac{\left(h+s+(V-1)^{2}+b(\xi) c\right.}{1-c^{2}}\left(\widehat{\phi_{1}}\right)^{2}-\frac{c}{1-c^{2}}\left(\widehat{\phi_{1}}\right)^{\prime} \rightarrow 0} \\
\quad \text { in } L_{1}(R)
\end{array}\right.
$$

N ote that

$$
v_{n}^{\prime}(\xi)=C_{n}^{\prime}(\xi) \phi_{1}(\xi)+C_{n}(\xi) \phi_{1}^{\prime}(\xi) \in H^{1}(R)
$$

Then

$$
C_{n}^{\prime}(\xi)\left(\widehat{\phi_{1}}\right)^{2}(\xi)=\phi_{1}^{*}(\xi) v_{n}^{\prime}-v_{n}(\xi)\left(\phi_{1}^{\prime}\right)^{*} \in L_{1}(R) .
$$

Integrating (A.4) over $R$, we have

$$
\frac{1}{1-c^{2}} \int_{-\infty}^{+\infty}\left[\left(h+s+(V-1)^{2}+b(\xi) c\right]\left(\widehat{\phi_{1}}\right)^{2}(\xi) d \xi=0\right.
$$

i.e.,

$$
\frac{1}{1-c^{2}} \int_{-\infty}^{+\infty}\left(1+\frac{c^{2}}{1-c^{2}}\right)\left[\left(h+s+(V-1)^{2}\right]\left(\widehat{\phi_{1}}\right)^{2}(\xi) d \xi=0\right.
$$

Thus $\widehat{\phi_{1}} \equiv 0$, which is impossible. This completes the proof of Lemma 4.1.
Proof of Lemma 4.2. Since $N\left(L^{*}\right) \neq\{0\}$, let $w_{0}=\left(u_{0}, v_{0}\right) \in N\left(L^{*}\right)$. Then

$$
v_{0}=\left(s+(V-1)^{2}\right) u_{0}-c u_{0}^{\prime},
$$

and $u_{0} \in N\left(B_{0}^{*}\right)$, with $B_{0}^{*}$ the adjoint operator of $B_{0}$.
We only need to prove that 0 is the simple eigenvalue of $B_{0}^{*}$.
Define $B^{*}(\lambda)$ as

$$
B^{*}(\lambda)=\frac{d^{2}}{d \xi^{2}}+b(\xi, \lambda) \frac{d}{d \xi}+d(\xi, \lambda)
$$

O bviously, $B^{*}(\lambda)$ is the adjoint operator of $B(\lambda)$, and $B_{0}^{*}=B^{*}(0)$.
A long the lines of the proof of Lemmas 3.1-3.2, we can similarly prove the following lemma.

Lemma A.1. For any $(\rho, h) \in$ region 1 , if there exists $v \in N\left(B^{*}(\lambda)\right)$ for some $\lambda$ with $\operatorname{Re} \lambda \geq 0$, then for the same $\lambda$ there exists $v^{*} \in N\left(\widehat{B^{*}}(\lambda)\right)$ with

$$
\begin{aligned}
\widehat{B^{*}}(\lambda)=\frac{d^{2}}{d \xi^{2}}+\left(d(\xi, \lambda)-\frac{1}{2} b^{\prime}(\xi, \lambda)-\frac{1}{4} b^{2}(\xi, \lambda)\right) \triangleq & \frac{d^{2}}{d \xi^{2}} \\
& +D^{*}(\xi, \lambda)
\end{aligned}
$$

and vice versa. Furthermore, $\lambda$ must be real.
It follows from Lemma A. 1 that 0 is the simple eigenvalue of $B_{0}^{*}$ if and only if 0 is the simple eigenvalue of $\widehat{B^{*}}(0)$.

In the following, we prove that 0 is the simple eigenvalue of $\widehat{B^{*}}(0)$.
By contradiction, assume 0 is not a simple eigenvalue of $\widehat{B^{*}}(0)$. Then the first eigenvalue of $-\widehat{B^{*}}(0)$ must be negative, and denoted by $\sigma_{1}^{0}<0$.

The first eigenvalue of $-\widehat{B^{*}}(\lambda)$ is denoted by $\sigma_{1}(\lambda)$, and

$$
\sigma_{1}(\lambda)=\min _{\|v\|_{L_{2}}=1} \int_{R}\left(\left|v^{\prime}\right|^{2}+D^{*}(\xi, \lambda)|v|^{2}\right) d \xi
$$

Note that $D_{\lambda}^{*}(\xi, \lambda)>0$ for $\lambda \geq 0$, thus $\sigma_{1}(\lambda)$ is increasing in $\lambda$.
A lso note that

$$
D^{*}(\xi, \lambda) \geq M(\lambda), \quad \forall \xi \in R, \text { and } M(\lambda) \rightarrow+\infty, \text { as } \lambda \rightarrow+\infty .
$$

Then there exists $\lambda_{0}>0$, such that

$$
\sigma_{1}\left(\lambda_{0}\right)>0 .
$$

Thus the continuity of $\sigma_{1}(\lambda)$ implies that there exists $\lambda^{*}$, with $0<\lambda^{*}<\lambda_{0}$, such that

$$
\sigma_{1}\left(\lambda^{*}\right)=0,
$$

i.e., $0 \in \sigma_{p}\left(\widehat{B^{*}}\left(\lambda^{*}\right)\right.$, thus $0 \in \sigma_{p}\left(B^{*}(\lambda)\right)$, which further implies

$$
\lambda^{*} \in \sigma_{p}\left(L^{*}\right), \quad \text { with } \lambda^{*}>0 .
$$

 rem 3.1, this completes the proof of Lemma 4.2.

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