



## Stability of an integro-differential equation<sup>☆</sup>

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### ABSTRACT

In this work we study a scalar integro-differential equation and give some new conditions ensuring that the zero solution is asymptotically stable by means of the fixed-point theory. Our work extends and improves the results in the literature.

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### 1. Introduction

In this work, we consider the following integro-differential equation

$$x'(t) = - \int_{t-r(t)}^t a(t, s)x(s)ds \quad (1.1)$$

as well as the nonlinear analogue

$$x'(t) = - \int_{t-r(t)}^t a(t, s)g(x(s))ds \quad (1.2)$$

for  $t \geq 0$ , where  $r : [0, \infty) \rightarrow [0, \infty)$  is differentiable with  $t - r(t) \rightarrow \infty$  as  $t \rightarrow \infty$ ,  $a : [-r_0, \infty) \times [-r_0, \infty) \rightarrow R$ , where  $r_0 = \max_{t \geq 0} \{t - r(t)\}$ ,  $g : R \rightarrow R$  are continuous functions and  $xg(x) > 0$  if  $x \neq 0$  is sufficiently small.

Many authors (see [1–5] and the references quoted therein) have studied the stability of the above two equations and their special forms. Recently, Burton [1] considered the case that  $r(t) = r$  is a constant. Becker and Burton [2] investigated (1.1) and (1.2) with the variable delay  $r(t)$  under the assumption that the function  $t - r(t)$  is strictly increasing. In the present work, however, we rewrite (1.1) and (1.2) in a fashion different from that in [1,2] and introduce a function  $v(t)$  in constructing a fixed-point mapping. Consequently, we eliminate the condition that  $t - r(t)$  be strictly increasing and obtain less restrictive conditions for stability. For such a technique being used, our results extend and improve the results in [1,2]. We mainly use the fixed-point theory, which has been effectively employed to study the stability of functional differential equations with variable delays [6–9].

The rest of this paper is organized as follows. In Section 2 we consider the linear equation and in Section 3 we consider the nonlinear equation. In Section 4, we give some remarks and examples to illustrate that our results are stronger than that in [1,2].

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## 2. The linear equation

In order to find a new fixed-point mapping for (1.1), we write (1.1) as

$$x'(t) = B(t, t - r(t))(1 - r'(t))x(t - r(t)) + \frac{d}{dt} \int_{t-r(t)}^t B(t, s)x(s)ds, \tag{2.1}$$

where

$$B(t, s) := \int_t^s a(u, s)du, \quad \text{with } B(t, t - r(t)) = \int_t^{t-r(t)} a(u, t - r(t))du. \tag{2.2}$$

**Lemma 2.1.** *If  $x(t)$  is a solution of (1.1) on an interval  $[0, T)$  and satisfies the initial condition  $x(t) = \psi(t)$  for  $t \in [-r_0, 0]$ , then  $x(t)$  is a solution of the integral equation*

$$\begin{aligned} x(t) &= e^{-\int_0^t v(s)ds} \psi(0) - e^{-\int_0^t v(u)du} \int_{-r(0)}^0 [v(u) + B(0, u)]\psi(u)du \\ &\quad + \int_{t-r(t)}^t [v(u) + B(t, u)]x(u)du - \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s [v(u) + B(s, u)]x(u)duds \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} [v(s - r(s)) + B(s, s - r(s))](1 - r'(s))x(s - r(s))ds \end{aligned} \tag{2.3}$$

on  $[0, T)$ , where  $v : [-r_0, \infty) \rightarrow \mathbb{R}$  is an arbitrary continuous function. Conversely, if a continuous function  $x(t)$  is equal to  $\psi(t)$  for  $t \in [-r_0, 0]$  and is a solution of (2.3) on an interval  $[0, \tau)$ , then  $x(t)$  is a solution of (1.1) on  $[0, \tau)$ .

**Proof.** Multiplying both sides of (2.1) by the factor  $e^{\int_0^t v(u)du}$  and integrating from 0 to any  $t \in [0, T)$ , we get

$$\begin{aligned} x(t) &= e^{-\int_0^t v(s)ds} \psi(0) + \int_0^t e^{-\int_s^t v(u)du} v(s)x(s)ds + \int_0^t e^{-\int_s^t v(u)du} \frac{d}{ds} \int_{s-r(s)}^s B(s, u)x(u)duds \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} B(s, s - r(s))(1 - r'(s))x(s - r(s))ds. \end{aligned}$$

Performing an integration by parts, we have

$$\begin{aligned} x(t) &= e^{-\int_0^t v(s)ds} \psi(0) + \int_0^t e^{-\int_s^t v(u)du} \frac{d}{ds} \int_{s-r(s)}^s [v(u) + B(s, u)]x(u)duds \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} [v(s - r(s)) + B(s, s - r(s))](1 - r'(s))x(s - r(s))ds \\ &= e^{-\int_0^t v(s)ds} \psi(0) + e^{-\int_s^t v(u)du} \int_{s-r(s)}^s [v(u) + B(s, u)]x(u)du \Big|_0^t \\ &\quad - \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s [v(u) + B(s, u)]x(u)duds \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} [v(s - r(s)) + B(s, s - r(s))](1 - r'(s))x(s - r(s))ds, \end{aligned}$$

which leads to (2.3). Conversely, suppose that a continuous function  $x(t)$  is equal to  $\psi(t)$  on  $[-r_0, 0]$  and satisfies (2.3) on an interval  $[0, \tau)$ . Then it is differentiable on  $[0, \tau)$ . Differentiating (2.3) with the aid of Leibniz's rule, we obtain (2.1).  $\square$

Next, we will define a mapping directly from (2.3). By Lemma 2.1, a fixed point of that map will be a solution of (2.3) and (1.1). To obtain stability of the zero solution of (1.1), we need the mapping defined by (2.3) to map bounded functions into bounded functions. Let  $(C, \|\cdot\|)$  be the set of real-valued bounded continuous functions on  $[-r_0, \infty)$  with the supremum norm  $\|\cdot\|$ ; that is, for  $\phi \in C$ ,

$$\|\phi\| := \sup\{|\phi(t)| : t \in [-r_0, \infty)\}.$$

In other words, we carry out our investigations in the complete metric space  $(C, \rho)$ , where  $\rho$  denotes the supremum (uniform) metric: for  $\phi_1, \phi_2 \in C$ ,

$$\rho(\phi_1, \phi_2) = \|\phi_1 - \phi_2\|.$$

For a given continuous initial function  $\psi : [-r_0, 0] \rightarrow R$ , define the set  $C_\psi \subset C$  by

$$C_\psi := \{\phi : [-r_0, \infty) \rightarrow R \mid \phi \in C, \phi(t) = \psi(t) \text{ for } t \in [-r_0, 0]\}.$$

Let  $\|\cdot\|$  denote the supremum on  $[-r_0, 0]$  or on  $[-r_0, \infty)$ . Finally, note that  $(C_\psi, \|\cdot\|)$  is itself a complete metric space since  $C_\psi$  is a closed subset of  $C$ .

**Lemma 2.2.** Let  $v : [-r_0, \infty) \rightarrow R$  be a continuous function and  $P$  be a mapping on  $C_\psi$  as follows: for  $\phi \in C_\psi$ ,

$$(P\phi)(t) = \psi(t)$$

if  $t \in [-r_0, 0]$ , while

$$\begin{aligned} (P\phi)(t) = & e^{-\int_0^t v(s)ds} \psi(0) - e^{-\int_0^t v(u)du} \int_{-r(0)}^0 [v(u) + B(0, u)] \psi(u) du + \int_{t-r(t)}^t [v(u) + B(t, u)] \phi(u) du \\ & - \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s [v(u) + B(s, u)] \phi(u) du ds \\ & + \int_0^t e^{-\int_s^t v(u)du} [v(s-r(s)) + B(s, s-r(s))] (1-r'(s)) \phi(s-r(s)) ds \end{aligned} \tag{2.4}$$

if  $t > 0$ . Suppose that there exist constants  $k \geq 0$  and  $\alpha > 0$  such that

$$-\int_0^t v(s)ds \leq k \tag{2.5}$$

and

$$\begin{aligned} & \int_{t-r(t)}^t |v(u) + B(t, u)| du + \int_0^t e^{-\int_s^t v(u)du} |v(s)| \int_{s-r(s)}^s |v(u) + B(s, u)| du ds \\ & + \int_0^t e^{-\int_s^t v(u)du} |v(s-r(s)) + B(s, s-r(s))| |1-r'(s)| ds \leq \alpha \end{aligned} \tag{2.6}$$

for  $t \geq 0$ , then  $P : C_\psi \rightarrow C_\psi$ .

**Proof.** For  $\phi \in C_\psi$ ,  $P\phi$  is continuous and agrees with  $\psi$  on  $[-r_0, 0]$  by virtue of the definition of  $P$ . For  $t > 0$ , it follows from (2.5) and (2.6) that

$$|(P\phi)(t)| \leq e^k |\psi(0)| + e^k \int_{-r(0)}^0 |v(u) + B(0, u)| |\psi(u)| du + \alpha \|\phi\|.$$

Consequently,

$$\|P\phi\| \leq e^k \|\psi\| \left( 1 + \int_{-r(0)}^0 |v(u) + B(0, u)| du \right) + \alpha \|\phi\| < \infty. \tag{2.7}$$

Thus,  $P\phi \in C_\psi$ .  $\square$

**Definition 2.1.** The zero solution of (1.1) is said to be stable at  $t = 0$  if, for every  $\varepsilon > 0$ , there exists a  $\delta > 0$  such that  $\psi : [-r_0, 0] \rightarrow (-\delta, \delta)$  implies that  $|x(t)| < \varepsilon$  for  $t \geq -r_0$ .

**Theorem 2.1.** Suppose that there exist constants  $k \geq 0$ ,  $\alpha \in (0, 1)$  and a continuous function  $v : [-r_0, \infty) \rightarrow R$  such that (2.5) and (2.6) hold for  $t \geq 0$ . Then for each continuous function  $\psi : [-r_0, 0] \rightarrow R$ , there is an unique continuous function  $x : [-r_0, \infty) \rightarrow R$  with  $x(t) = \psi(t)$  on  $[-r_0, 0]$  that satisfies (1.1) on  $[0, \infty)$ . Moreover,  $x(t)$  is bounded on  $[-r_0, \infty)$ . Furthermore, the zero solution of (1.1) is stable at  $t = 0$ . If, in addition,

$$\int_0^t v(s)ds \rightarrow \infty \tag{2.8}$$

as  $t \rightarrow \infty$ , then  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$ .

**Proof.** Consider the space  $C_\psi$  defined by the continuous initial function  $\psi : [-r_0, 0] \rightarrow R$ . For  $\phi, \eta \in C_\psi$ ,

$$\begin{aligned} |(P\phi)(t) - (P\eta)(t)| &\leq \int_{t-r(t)}^t |v(u) + B(t, u)| |\phi(u) - \eta(u)| du \\ &\quad + \int_0^t e^{-\int_s^t v(u) du} |v(s)| \int_{s-r(s)}^s |v(u) + B(s, u)| |\phi(u) - \eta(u)| du ds \\ &\quad + \int_0^t e^{-\int_s^t v(u) du} |v(s - r(s)) + B(s, s - r(s))| |1 - r'(s)| |\phi(s - r(s)) - \eta(s - r(s))| ds \\ &\leq \left( \int_{t-r(t)}^t |v(u) + B(t, u)| du + \int_0^t e^{-\int_s^t v(u) du} |v(s)| \int_{s-r(s)}^s |v(u) + B(s, u)| du ds \right. \\ &\quad \left. + \int_0^t e^{-\int_s^t v(u) du} |v(s - r(s)) + B(s, s - r(s))| |1 - r'(s)| ds \right) \|\phi - \eta\|. \end{aligned} \tag{2.9}$$

For  $t > 0$ . By the definition of  $P$  and (2.6),  $P$  is a contraction mapping with contraction constant  $\alpha$ . By Banach's contraction mapping principle,  $P$  has a unique fixed point  $x$  in  $C_\psi$ , which is a bounded continuous function. By Lemma 2.1, it is a solution of (1.1) on  $[0, \infty)$ . It follows that  $x$  is the only bounded continuous function satisfying (1.1) on  $[0, \infty)$  and the initial condition. Similarly to the method in [2], we can show that (1.1) does not have any unbounded continuous solutions.

It is clear that the zero solution of (1.1) is stable. If  $x(t)$  is a solution with the initial function  $\psi$ , by (2.7), we have

$$(1 - \alpha)\|x\| \leq e^k \|\psi\| \left( 1 + \int_{-r(0)}^0 |v(u) + B(0, u)| du \right).$$

Then for each  $\varepsilon > 0$ , there exists a  $\delta > 0$  such that  $|x(t)| < \varepsilon$  for all  $t \geq -r_0$  if  $\|\psi\| < \delta$ .

Next we prove that the solution of (1.1) tends to zero when (2.8) holds. First we define a subset of  $C_\psi$  as follows:

$$C_\psi^0 := \{ \phi : [-r_0, \infty) \rightarrow R | \phi \in C, \phi(t) = \psi(t) \text{ for } t \in [-r_0, 0], \phi(t) \rightarrow 0 \text{ as } t \rightarrow \infty \}. \tag{2.10}$$

Since  $C_\psi^0$  is a closed subset of  $C_\psi$  and  $(C_\psi, \rho)$  is complete, the metric space  $(C_\psi^0, \rho)$  is also complete. Now we show that  $(P\phi)(t) \rightarrow 0$  as  $t \rightarrow \infty$  when  $\phi \in C_\psi^0$ . By (2.4) and (2.6), we have

$$|(P\phi)(t)| \leq e^{-\int_0^t v(s) ds} \left( |\psi(0)| + \int_{-r(0)}^0 |v(u) + B(0, u)| du \right) + \alpha \|\phi\|_{[t-r(t), t]} + |I_4| + |I_5|$$

for  $t > 0$ , where  $I_4, I_5$  denote the last two terms of (2.4), respectively. We can prove that each of the above terms tend to zero as  $t \rightarrow \infty$ . In fact, it is easy to see that the first term tends to 0 by (2.8) and the second term approaches zero as  $t \rightarrow \infty$  since  $t - r(t) \rightarrow \infty$ . For each  $\varepsilon > 0$ , there exists a  $T > 0$  such that

$$\|\phi\|_{[T-r(T), \infty)} < \varepsilon/2\alpha$$

since  $t - r(t) \rightarrow \infty$  as  $t \rightarrow \infty$ . Thus, for  $t \geq T$ ,

$$\begin{aligned} |I_4| &\leq \int_0^T |v(s)e^{-\int_s^t v(u) du} \int_{s-r(s)}^s |v(u) + B(s, u)| du ds| \|\phi\| e^{-\int_T^t v(u) du} \\ &\quad + \int_T^t |v(s)e^{-\int_s^t v(u) du} \int_{s-r(s)}^s |v(u) + B(s, u)| du ds| \|\phi\|_{[T-r(T), \infty)}. \end{aligned}$$

By (2.8), there exists a  $\tau \geq T$  such that  $\|\phi\| e^{-\int_T^t v(u) du} < \varepsilon/2\alpha$  for  $t > \tau$ . Thus, for every  $\varepsilon > 0$ , there exists a  $\tau > 0$  such that  $t > \tau$  implies  $I_4 < \varepsilon$ ; that is,  $I_4 \rightarrow 0$  as  $t \rightarrow \infty$ . Similarly, we can show that  $I_5$  tends to zero as  $t \rightarrow \infty$ . This yields  $(P\phi)(t) \rightarrow 0$  as  $t \rightarrow \infty$ , and hence  $P : C_\psi^0 \rightarrow C_\psi^0$ . Therefore,  $P$  is a contraction on  $C_\psi^0$  with a unique fixed point  $x$ . By Lemma 2.1,  $x$  is a solution of (1.1) on  $[0, \infty)$ . Hence,  $x(t)$  is the only continuous solution of (1.1) agreeing with the initial function  $\psi$ . As  $x \in C_\psi^0, x(t) \rightarrow 0$  as  $t \rightarrow \infty$ .  $\square$

### 3. The nonlinear equation

The nonlinear equation (1.2) is written as

$$x'(t) = B(t, t - r(t))(1 - r'(t))g(x(t - r(t))) + \frac{d}{dt} \int_{t-r(t)}^t B(t, s)g(x(s))ds. \tag{3.1}$$

**Lemma 3.1.** Let  $\psi : [-r_0, 0] \rightarrow R$  be a given continuous initial function. If  $x(t)$  is a solution of (1.2) on an interval  $[0, T)$  with  $x(t) = \psi(t)$  for  $t \in [-r_0, 0]$ , then  $x(t)$  is a solution of the integral equation

$$\begin{aligned} x(t) = & e^{-\int_0^t v(s)ds} \psi(0) - e^{-\int_0^t v(u)du} \int_{-r(0)}^0 [v(u) + B(0, u)]g(\psi(u))du + \int_{t-r(t)}^t [v(u) + B(t, u)]g(x(u))du \\ & - \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s [v(u) + B(s, u)]g(x(u))duds + \int_0^t e^{-\int_s^t v(u)du} [v(s-r(s)) \\ & + B(s, s-r(s))](1-r'(s))g(x(s-r(s)))ds + \int_0^t e^{-\int_s^t v(u)du} v(s)[x(s) - g(x(s))]ds. \end{aligned} \quad (3.2)$$

where  $v : [-r_0, \infty) \rightarrow R$  is an arbitrary continuous function. Conversely, if a continuous function  $x(t)$  is equal to  $\psi(t)$  for  $t \in [-r_0, 0]$  and is a solution of (3.2) on an interval  $[0, \tau)$ , then  $x(t)$  is a solution of (1.2) on  $[0, \tau)$ .

**Proof.** Multiplying both sides of (3.1) by the factor  $e^{\int_0^t v(u)du}$  and integrating from 0 to any  $t \in [0, T)$ , we obtain

$$\begin{aligned} x(t) = & e^{-\int_0^t v(s)ds} \psi(0) + \int_0^t e^{-\int_s^t v(u)du} v(s)x(s)ds + \int_0^t e^{-\int_s^t v(u)du} \frac{d}{ds} \int_{s-r(s)}^s B(s, u)x(u)duds \\ & + \int_0^t e^{-\int_s^t v(u)du} B(s, s-r(s))(1-r'(s))x(s-r(s))ds \\ = & e^{-\int_0^t v(s)ds} \psi(0) + \int_0^t e^{-\int_s^t v(u)du} v(s)x(s)ds + \int_0^t e^{-\int_s^t v(u)du} \frac{d}{ds} \int_{s-r(s)}^s [v(u) + B(s, u)]g(x(u))duds \\ & + \int_0^t e^{-\int_s^t v(u)du} B(s, s-r(s))(1-r'(s))g(x(s-r(s)))ds - \int_0^t e^{-\int_s^t v(u)du} \frac{d}{ds} \int_{s-r(s)}^s v(u)g(x(u))duds. \end{aligned}$$

Then an integration by parts yields (3.2). Conversely, suppose that a continuous function  $x(t)$  is equal to  $\psi(t)$  on  $[-r_0, 0]$  and satisfies (3.2) on an interval  $[0, \tau)$ . Then it is differentiable on  $[0, \tau)$ . Differentiating (3.2) with the aid of Leibniz's rule, we obtain (3.1).  $\square$

Define

$$C_\psi^l := \{\phi : [-r_0, \infty) \rightarrow R \mid \phi \in C, \phi(t) = \psi(t) \text{ for } t \in [-r_0, 0], |\phi(t)| \leq l\}, \quad (3.3)$$

where  $\psi : [-r_0, 0] \rightarrow [-l, l]$  is a given continuous initial function.

**Lemma 3.2.** Let  $v : [-r_0, \infty) \rightarrow R$  be a continuous function and a mapping  $P$  be defined on  $C_\psi^l$  as follows: for  $\phi \in C_\psi^l$ ,

$$(P\phi)(t) = \psi(t) \quad \text{for } t \in [-r_0, 0];$$

while for  $t > 0$

$$\begin{aligned} (P\phi)(t) = & e^{-\int_0^t v(s)ds} \psi(0) - e^{-\int_0^t v(u)du} \int_{-r(0)}^0 [v(u) + B(0, u)]g(\psi(u))du + \int_{t-r(t)}^t [v(u) + B(t, u)]g(\phi(u))du \\ & - \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s [v(u) + B(s, u)]g(\phi(u))duds \\ & + \int_0^t e^{-\int_s^t v(u)du} [v(s-r(s)) + B(s, s-r(s))](1-r'(s))g(\phi(s-r(s)))ds \\ & + \int_0^t e^{-\int_s^t v(u)du} v(s)[\phi(s) - g(\phi(s))]ds. \end{aligned} \quad (3.4)$$

Suppose that:

- (i) there exists a constant  $l > 0$  such that  $g$  satisfies a Lipschitz condition on  $[-l, l]$ ;
- (ii)  $v(t) \geq 0$  for  $t \geq 0$ ;
- (iii) there exists a continuous function  $q$  such that  $|B(t, u)| \leq q(u)$  for  $t - r(t) \leq u \leq t$ .

Then there is a metric  $d$  for  $C_\psi^l$  such that:

- (iv) the metric space  $(C_\psi^l, d)$  is complete, and
- (v)  $P$  has a contraction on  $(C_\psi^l, d)$  if  $P$  maps  $C_\psi^l$  into itself.

**Proof.** By (i) we can choose a common Lipschitz constant  $L$  for  $g(x)$  and  $x - g(x)$  on  $[-l, l]$ . For  $t \in [-r_0, \infty)$  and a constant  $k > 4$ , define

$$h(t) = kL \int_0^t [v(u) + q(u) + \omega(u)]du,$$

where

$$\omega(u) = \begin{cases} 0, & \text{if } u \in [-r_0, 0] \\ |v(u - r(u)) + B(u, u - r(u))(1 - r'(u))|, & \text{if } u \in [0, \infty). \end{cases}$$

Now let  $\mathcal{S}$  be the space of all continuous functions  $\phi : [-r_0, \infty) \rightarrow R$  such that

$$|\phi|_h := \sup\{|\phi(t)|e^{-h(t)} : t \in [-r_0, \infty)\} < \infty.$$

It is clear that  $(\mathcal{S}, |\cdot|_h)$  is a Banach space. Thus  $(\mathcal{S}, d)$  is a complete metric space, where  $d$  denotes the induced metric:  $d(\phi, \eta) = |\phi - \eta|_h$  for  $\phi, \eta \in \mathcal{S}$ . Since  $C_\psi^l$  is a closed subset of  $\mathcal{S}$  with this metric, the metric space  $(C_\psi^l, d)$  is complete and the proof of (iv) is complete.

As for (v), since  $P : C_\psi^l \rightarrow C_\psi^l$  and  $g$  satisfies a Lipschitz condition on  $[-l, l]$ , we can obtain, for  $\phi, \eta \in C_\psi^l$

$$\begin{aligned} |(P\phi)(t) - (P\eta)(t)|e^{-h(t)} &\leq \int_{t-r(t)}^t |v(u) + B(t, u)|L|\phi(u) - \eta(u)|e^{-h(t)+h(u)-h(u)} du \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s |v(u) + B(s, u)|L|\phi(u) - \eta(u)|e^{-h(t)+h(u)-h(u)} duds \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} \omega(s)L|\phi(s - r(s)) - \eta(s - r(s))|e^{-h(t)+h(s-r(s))-h(s-r(s))} ds \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} v(s)L|\phi(s) - \eta(s)|e^{-h(t)+h(s)-h(s)} ds \\ &\leq \int_{t-r(t)}^t e^{-kL \int_u^t [v(\theta)+q(\theta)]d\theta} |v(u) + B(t, u)|L|\phi(u) - \eta(u)|e^{-h(u)} du \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s e^{-kL \int_u^s [v(\theta)+q(\theta)]d\theta} |v(u) + B(s, u)|L|\phi(u) - \eta(u)|e^{-h(u)} duds \\ &\quad + \int_0^t e^{-kL \int_s^t \omega(u)du} \omega(s)L|\phi(s - r(s)) - \eta(s - r(s))|e^{-h(s-r(s))} ds \\ &\quad + \int_0^t e^{-(kL+1) \int_s^t v(u)du} v(s)L|\phi(s) - \eta(s)|e^{-h(s)} ds. \end{aligned}$$

By (iii), we have

$$|v(u) + B(t, u)| \leq v(u) + q(u)$$

for  $t - r(t) \leq u \leq t$ . Consequently,

$$|(P\phi)(t) - (P\eta)(t)|e^{-h(t)} \leq \left( \frac{1}{kL} + \frac{1}{kL} + \frac{1}{kL} + \frac{1}{kL+1} \right) L|\phi - \eta|_h \leq \frac{4}{k} |\phi - \eta|_h \tag{3.5}$$

for all  $t > 0$ . Thus  $d(P\phi, P\eta) \leq (4/k)d(\phi, \eta)$ . Since  $k > 4$ , we conclude that  $P$  is a contraction on  $(C_\psi^l, d)$ .  $\square$

**Theorem 3.1.** Suppose  $g, v$  and  $B$  satisfy conditions (i)–(iii) in Lemma 3.2 and further suppose that:

- (i)  $g$  is odd and strictly increasing on  $[-l, l]$ ;
- (ii)  $x - g(x)$  is non-decreasing on  $[0, l]$ ;
- (iii) there exists an  $\alpha \in (0, 1)$  such that, for  $t \geq 0$

$$\begin{aligned} &\int_{t-r(t)}^t |v(u) + B(t, u)|du + \int_0^t e^{-\int_s^t v(u)du} |v(s)| \int_{s-r(s)}^s |v(u) + B(s, u)|duds \\ &\quad + \int_0^t e^{-\int_s^t v(u)du} |v(s - r(s)) + B(s, s - r(s))||1 - r'(s)|ds \leq \alpha. \end{aligned}$$

Then a  $\delta \in (0, l)$  exists such that, for each continuous function  $\psi : [-r_0, 0] \rightarrow (-\delta, \delta)$ , there is a unique continuous function  $x : [-r_0, \infty) \rightarrow R$  with  $x(t) = \psi(t)$  on  $[-r_0, 0]$ , which is a solution of (1.2) on  $[0, \infty)$ . Moreover,  $x(t)$  is bounded by  $l$  on  $[-r_0, \infty)$ . Furthermore, the zero solution of (1.2) is stable at  $t = 0$ .

**Proof.** Since  $g$  is odd and satisfies the Lipschitz condition on  $[-l, l]$ ,  $g(0) = 0$  and  $g$  is (uniformly) continuous on  $[-l, l]$ . Thus we can choose a  $\delta$  that satisfies the inequality

$$\delta + g(\delta) \int_{-r(0)}^0 |v(u) + B(0, u)|du \leq (1 - \alpha)g(l). \tag{3.6}$$

Let  $\psi : [-r_0, 0] \rightarrow (-\delta, \delta)$  be a continuous function. Note that (3.6) implies  $\delta < l$  since  $g(l) \leq l$  by (ii). Thus,  $|\psi(t)| < l$  for  $-r_0 \leq t \leq 0$ . Now we show that for such a  $\psi$ ,  $P : C_\psi^l \rightarrow C_\psi^l$ . In fact, for an arbitrary  $\phi \in C_\psi^l$ , it follows from conditions (i) and (ii) that

$$\begin{aligned} |(P\phi)(t)| &\leq \delta + g(\delta) \int_{-r(0)}^0 |v(u) + B(0, u)|du + g(l) \int_{t-r(t)}^t |v(u) + B(t, u)|du \\ &\quad + g(l) \int_0^t e^{-\int_s^t v(u)du} v(s) \int_{s-r(s)}^s |v(u) + B(s, u)|duds \\ &\quad + g(l) \int_0^t e^{-\int_s^t v(u)du} |v(s - r(s)) + B(s, s - r(s))| |1 - r'(s)|ds + (l - g(l)) \int_0^t e^{-\int_s^t v(u)du} v(s)ds \end{aligned}$$

for  $t > 0$ . By (iii) and (3.6), this implies

$$\begin{aligned} |(P\phi)(t)| &\leq \delta + g(\delta) \int_{-r(0)}^0 |v(u) + B(0, u)|du + \alpha g(l) + l - g(l) \\ &\leq (1 - \alpha)g(l) + (\alpha - 1)g(l) + l = l. \end{aligned}$$

Hence,  $|(P\phi)(t)| \leq l$  for  $t \in [-r_0, \infty)$  since  $|(P\phi)(t)| = |\psi(t)| < l$  for  $t \in [-r_0, 0]$ . Therefore,  $P\phi \in C_\psi^l$ . By Lemma 3.2,  $P$  is a contraction on the complete metric space  $(C_\psi^l, d)$ . Then  $P$  has a unique fixed point  $x \in C_\psi^l$ , which is a solution of (1.2) on  $[0, \infty)$  by Lemma 3.1 and  $|x(t)| \leq l$  for all  $t \geq -r_0$ . Hence,  $x(t)$  is the only continuous function satisfying (1.2) for  $t \geq 0$  and with  $x(t) = \psi(t)$  for  $-r_0 \leq t \leq 0$ .

To obtain stability at  $t = 0$ , let  $\varepsilon > 0$  be given and choose  $m > 0$  so that  $m < \min\{\varepsilon, l\}$ . Replacing  $l$  with  $m$  beginning with (3.6), we see there is a  $\delta > 0$  such that  $\|\psi\| < \delta$ , which implies that the unique continuous solution  $x$  agreeing with  $\psi$  on  $[-r_0, 0]$  satisfies  $|x(t)| \leq m < \varepsilon$  for all  $t \geq -r_0$ .  $\square$

**Definition 3.1.** The zero solution of (1.2) is asymptotically stable if it is stable at  $t = 0$  and a  $\delta$  exists such that for any continuous function  $\psi : [-r_0, 0] \rightarrow (-\delta, \delta)$ , the solution  $x(t)$  with  $x(t) = \psi(t)$  on  $[-r_0, 0]$  tends to zero as  $t \rightarrow \infty$ .

The following theorem provides the asymptotic stability of Eq. (1.2). The proof is similar to that of Theorem 3.13 [2] and hence, we omit it.

**Theorem 3.2.** Suppose that all of the conditions in Lemma 3.2 and Theorem 3.1 hold. Furthermore, suppose that  $g$  is continuously differentiable on  $[-l, l]$  and  $g'(0) \neq 0$ . If  $\int_0^t v(s)ds \rightarrow \infty$  as  $t \rightarrow \infty$ , then the zero solution of (1.2) is asymptotically stable.

**4. Remarks and examples**

**Remark 4.1.** The work of Becker and Burton in [2] requires that  $t - r(t)$  be strictly increasing. However, in the present work, this condition is removed.

**Remark 4.2.** The conditions in [2], parallel to (2.6) and (2.8), are

$$\int_{t-r(t)}^t |G(t, u)|du + \int_0^t e^{-\int_s^t G(u,u)du} |G(s, u)|duds \leq \alpha \tag{4.1}$$

and

$$\int_0^t G(s, s)ds \rightarrow \infty \text{ as } t \rightarrow \infty, \tag{4.2}$$

where  $G(t, s) = \int_t^{f(s)} a(u, s)du$ ,  $f(t)$  is the inverse of  $t - r(t)$ . Choosing  $v(s) = G(s, s)$ , Theorems 2.1 and 3.1 reduce to Theorem 3.3 and 3.10 of [2], respectively. So our results generalize and improve those of [1,2]. See Example 4.1.

**Example 4.1.** Consider the equation

$$x'(t) = - \int_{0.4635t}^t \frac{1}{s^2 + 1} x(s)ds. \tag{4.3}$$

Following the notation in Remark 4.2, we have  $f(t) = \frac{t}{0.4635}$ , then

$$G(t, s) = \int_t^{s/0.4635} \frac{1}{s^2 + 1} du = \frac{s/0.4635 - t}{s^2 + 1}$$

for  $t \geq 0$  and  $0.4635t \leq s \leq t$ . Consequently,

$$\lim_{t \geq 0} \left\{ \int_{0.4635t}^t |G(t, u)| du + \int_0^t e^{-\int_s^t G(u,u)du} |G(s, s)| \int_{0.4635s}^s |G(s, u)| duds \right\} = 2 \left( -\frac{\ln 0.4635 + 1}{0.4635} + 1 \right) = 1.003,$$

Then there exists some  $t_0 > 0$  such that

$$\int_{0.4635t}^t |G(t, u)| du + \int_0^t e^{-\int_s^t G(u,u)du} |G(s, s)| \int_{0.4635s}^s |G(s, u)| duds > 1.002$$

for  $t \geq t_0$ . This implies that condition (4.1) does not hold. Thus, Theorem 3.3 in [2] cannot be applied to Eq. (4.3).

However, By (2.2),

$$B(t, s) = \int_t^s \frac{1}{s^2 + 1} du = \frac{s - t}{s^2 + 1}.$$

Choosing  $v(t) = \frac{t}{t^2 + 1}$ , clearly, condition (2.8) holds. Furthermore, we have

$$\begin{aligned} \int_{t-r(t)}^t |v(u) + B(t, u)| du &= \int_{0.4635t}^t \left| \frac{2u - t}{u^2 + 1} \right| du \\ &= \int_{0.4635t}^{0.5t} \frac{t - 2u}{u^2 + 1} du + \int_{0.5t}^t \frac{2u - t}{u^2 + 1} du \\ &= t(2 \arctan 0.5t - \arctan t - \arctan 0.4635t) + \ln(t^2 + 1) \\ &\quad + \ln(0.4635^2 t^2 + 1) - 2 \ln(0.25t^2 + 1) \\ &=: w(t). \end{aligned}$$

Since the function  $w(t)$  is increasing in  $[0, \infty)$  and

$$\lim_{t \rightarrow \infty} w(t) = 1/0.4635 - 3 + 2 \ln 2 + 2 \ln 0.927 = 0.3992,$$

then

$$\begin{aligned} \int_{t-r(t)}^t |v(u) + B(t, u)| du &< 0.3992, \\ \int_0^t e^{-\int_s^t v(u)du} |v(s - r(s)) + B(s, s - r(s))| |1 - r'(s)| ds &= (1/0.4635 - 2) \int_0^t e^{-\int_s^t \frac{u}{u^2 + 1} du} \frac{s}{s^2 + 1/0.4635^2} ds \\ &< 1/0.4635 - 2 = 0.1575, \end{aligned}$$

and

$$\int_0^t e^{-\int_s^t v(u)du} |v(s)| \int_{s-r(s)}^s |v(u) + B(s, u)| duds < 0.3992.$$

Let  $\alpha := 0.3992 + 0.1575 + 0.3992 = 0.9559 < 1$ , then the zero solution of (4.3) is asymptotically stable by Theorem 2.1.

### 5. Conclusion

In this work, a scalar integro-differential equation has been studied. Some sufficient conditions to ensure that the zero solution is asymptotically stable have been established. These obtained results extend and improve the results in [1,2]. Moreover, an example is given to illustrate our results.

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