

Available online at www.sciencedirect.com



Applied Mathematics Letters

Applied Mathematics Letters 17 (2004) 543-547

www.elsevier.com/locate/aml

# The General Common Nonnegative-Definite and Positive-Definite Solutions to the Matrix Equations $AXA^* = BB^*$ and $CXC^* = DD^*$

XIAN ZHANG\* Department of Mathematics, Heilongjiang University Harbin, 150080, P.R. China and

School of Mechanical and Manufacturing Engineering The Queen's University of Belfast, Stranmillis Road Belfast, BT9 5AH, United Kingdom x.zhang@qub.ac.uk

MEI-YU CHENG Department of Mathematics, Heilongjiang University Harbin, 150080, P.R. China

(Received October 2002; revised and accepted May 2003)

**Abstract**—We give necessary and sufficient conditions for the existence of a common nonnegativedefinite (positive-definite) solution to the pair of matrix equations  $AXA^* = BB^*$  and  $CXC^* = DD^*$ , and derive a representation of the general common nonnegative-definite (positive-definite) solution to these two equations when they have such common solutions. This paper can be viewed as a supplementary version of that derived by Young *et al.* [1] since Groß [2] has given a counterexample to point out a mistake in their basic Theorem 1. The presented example shows the advantage of the proposed approach. © 2004 Elsevier Ltd. All rights reserved.

**Keywords**—Nonnegative-definite solution, Positive-definite solution, Matrix equation, Generalized inverse, Nullspace, Column space.

### 1. INTRODUCTION

Let  $\mathbb{C}^{m \times n}$  be the set of all  $m \times n$  complex matrices. We denote by  $\mathbb{U}_n$  the subset of  $\mathbb{C}^{n \times n}$  consisting of all unitary matrices. For  $X \in \mathbb{C}^{m \times n}$ , let  $X^*$ ,  $\mathcal{N}(X)$ , and  $\mathcal{R}(X)$  be the conjugate transpose, the nullspace, and the column space of X, respectively. We denote by  $I_n$  and O the  $n \times n$  identity matrix and the zero matrix, respectively.

Some authors have established the problem for determining the general Hermitian nonnegativedefinite solution to the matrix equation

$$AXA^* = BB^*,\tag{1}$$

\*Author to whom all correspondence should be addressed.

Typeset by  $\mathcal{A}_{\mathcal{M}}S$ -TEX

This work was supported in part by the Chinese NSF, NSF of Heilongjiang Province, and the fund of Heilongjiang Education Committee for Overseas Scholars.

The authors are grateful to the reviewer for their helpful comments and suggestions.

<sup>0893-9659/04/\$ -</sup> see front matter © 2004 Elsevier Ltd. All rights reserved. doi:10.1016/j.aml.2003.05.010

with known matrices  $A, B \in \mathbb{C}^{m \times n}$ . For instance, Baksalary [3], Groß [2], Khatri and Mitra [4], and Zhang and Cheng [5] have derived the general Hermitian nonnegative-definite solution to the matrix equation (1), respectively. Moreover, Dai and Lancaster [6] have studied the similar problem and emphasized the importance of (1) within the real setting. More generally, Young *et al.* [1] have obtained a representation of the general common Hermitian nonnegative-definite solution to the pair of matrix equations (1) and

$$CXC^* = DD^*, \tag{2}$$

with known matrices  $C, D \in \mathbb{C}^{p \times n}$ . But Groß [2] has given a counterexample to point out that their representation is not true. However, up to now, nobody (we knew) has obtained a correct representation for the general common Hermitian nonnegative-definite solution to the pair of matrix equations (1) and (2).

The first aim of this paper is to determine the general common nonnegative-definite solution to the pair of matrix equations (1) and (2). To guarantee the consistencies of the matrix equations (1) and (2), in the following we assume

$$\mathcal{R}(B) \subseteq \mathcal{R}(A), \qquad \mathcal{R}(D) \subseteq \mathcal{R}(C).$$
 (3)

The problem for determining the general common nonnegative-definite solution to the pair of matrix equations (1) and (2) can be precisely stated as follows.

PROBLEM 1. Given matrices  $A, B \in \mathbb{C}^{m \times n}$  and  $C, D \in \mathbb{C}^{p \times n}$  satisfying (3). Determine necessary and sufficient conditions for the existence of a common Hermitian nonnegative-definite solution to the pair of matrix equations (1) and (2). Furthermore, give a representation of the general common Hermitian nonnegative-definite solution to these two equations when they have such common solutions.

The second aim of this paper is to determine the general common positive-definite solution to the pair of matrix equations (1) and (2), i.e., specify the freedoms in the common Hermitian nonnegative-definite solutions to the pair of matrix equations (1) and (2) such that they are positive-definite. The problem can be precisely stated as follows.

PROBLEM 2. Given matrices  $A, B \in \mathbb{C}^{m \times n}$  and  $C, D \in \mathbb{C}^{p \times n}$  satisfying (3). Determine necessary and sufficient conditions for the existence of a common Hermitian positive-definite solution to the pair of matrix equations (1) and (2). Furthermore, give a representation of the general common Hermitian positive-definite solution to these two equations when they have such common solutions.

The solutions to Problems 1 and 2 are, respectively, established in Sections 2 and 3. In Section 4, an example is presented to illustrate the proposed solutions.

### 2. SOLUTION TO PROBLEM 1

This section considers solution of Problem 1 proposed in Section 1. We first introduce the following three lemmas.

LEMMA 1. (See [1, Lemma 2; 7, p. 17].) Given matrices  $F, G \in \mathbb{C}^{m \times n}$ . Then  $FF^* = GG^*$  if and only if G = FT for some  $T \in \mathbb{U}_n$ .

LEMMA 2. (See [8, p. 270].) Given matrices  $M \in \mathbb{C}^{m \times p}$  and  $N \in \mathbb{C}^{m \times n}$ . Let  $M^-$  be an arbitrary but fixed generalized inverse of M. Then the matrix equation MX = N has a solution if and only if  $MM^-N = N$ . When this condition is met, the general solution to the equation is given by

$$X = M^- N + (I - M^- M) Y,$$

where Y is free to vary over  $\mathbf{C}^{p \times n}$ .

LEMMA 3. (See [2, p. 124; 3, Theorem 1].) Given matrices  $A, B \in \mathbb{C}^{m \times n}$  satisfying  $\mathcal{R}(B) \subseteq \mathcal{R}(A)$ . Let  $A^-$  be an arbitrary but fixed generalized inverse of A. Then a representation of the general Hermitian nonnegative-definite solution to the matrix equation (1) is given by

$$X = [A^{-}B + (I_n - A^{-}A)Y] [A^{-}B + (I_n - A^{-}A)Y]^*,$$
(4)

where Y is free to vary over  $\mathbf{C}^{n \times n}$ .

Based on Lemmas 1–3, the following lemma can be immediately derived.

LEMMA 4. Suppose  $A, B \in \mathbb{C}^{m \times n}$  and  $C, D \in \mathbb{C}^{p \times n}$  satisfying (3). Let  $A^-$  and  $[C(I_n - A^- A)]^-$  be arbitrary but fixed generalized inverses of A and  $C(I_n - A^- A)$ , respectively. Then the matrix X possessing the form (4) is a solution to the matrix equation (2) if and only if the matrix Y possesses the form

$$Y = [C(I_n - A^- A)]^- (DT - CA^- B) + W - [C(I_n - A^- A)]^- C(I_n - A^- A)W,$$
(5)

where W is free to vary over  $\mathbf{C}^{n \times n}$ , and  $T \in \mathbf{U}_n$  satisfies

$$\left[C(I_n - A^{-}A)\right] \left[C(I_n - A^{-}A)\right]^{-} \left(DT - CA^{-}B\right) = DT - CA^{-}B.$$
(6)

**PROOF.** The "only if" part. Suppose the matrix X possessing the form (4) is a solution to the matrix equation (2). Then

$$\left[CA^{-}B + C(I_n - A^{-}A)Y\right] \left[CA^{-}B + C(I_n - A^{-}A)Y\right]^* = DD^*.$$

Using Lemma 1 derives

$$CA^{-}B + C(I_n - A^{-}A)Y = DT$$

for some  $T \in \mathbf{U}_n$ . This, together with Lemma 2, implies relations (5) and (6).

The "if" part. Suppose the matrix Y possesses the form (5) with (6). It follows from (4) that

$$CXC^* = \left[CA^-B + C(I_n - A^-A)Y\right] \left[CA^-B + C(I_n - A^-A)Y\right]^*.$$
(7)

Substituting (5) into (7), we have

$$CXC^* = ZZ^* \tag{8}$$

with

$$Z = CA^{-}B + C(I_n - A^{-}A) \left[ C(I_n - A^{-}A) \right]^{-} \left( DT - CA^{-}B \right).$$
(9)

Combining (9) and (6) yields Z = DT. This, together with (8), implies that the matrix X possessing the form (4) is a solution to the matrix equation (2).

The proof is completed.

Combining Lemmas 3 and 4, the solution to Problem 1 can be stated as follows.

THEOREM 1. Suppose the hypotheses of Lemma 4 are satisfied. Then the pair of matrix equations (1) and (2) has a common Hermitian nonnegative-definite solution if and only if there exists  $T \in \mathbf{U}_n$  such that (6) holds. When the condition is met, the general common Hermitian nonnegative-definite solution to these two equations is given by (4) with (5), where W is free to vary over  $\mathbf{C}^{n \times n}$ , and  $T \in \mathbf{U}_n$  is an arbitrary parameter matrix satisfying (6).

### 3. SOLUTION TO PROBLEM 2

This section considers solution of Problem 2 proposed in Section 1. We first present the following two lemmas.

LEMMA 5. Given matrices  $M \in \mathbb{C}^{m \times n}$  and  $N \in \mathbb{C}^{m \times p}$ . Let  $M^-$  be an arbitrary but fixed generalized inverse of M. Further, assume

$$MM^-N = N. (10)$$

Then

$$\mathcal{R}\left(M^{-}NG\right)\cap\mathcal{R}\left((I_{n}-M^{-}M)H\right)=\{0\},$$
(11)

for any  $G \in \mathbf{C}^{p \times q}$  and  $H \in \mathbf{C}^{m \times q}$ .

PROOF. If 
$$y \in \mathcal{R}(M^-NG) \cap \mathcal{R}((I_n - M^-M)H)$$
, then  
 $y = M^-NGa$ 
(12)

 $\operatorname{and}$ 

$$y = (I_n - M^- M)Hb \tag{13}$$

for some vectors a and b. It follows from (13) that My = 0. This, together with (12) and (10), gives y = 0. Therefore, (11) holds.

LEMMA 6. Suppose the hypotheses of Lemma 4 are satisfied, and the matrix X possesses the form (4) with (5) and (6). Then rank X = n if and only if

$$\operatorname{rank} B = \operatorname{rank} A,\tag{14}$$

$$\operatorname{rank} \begin{bmatrix} A^- A & Y \end{bmatrix} = n,\tag{15}$$

and

$$\mathcal{R}\left(\left(A^{-}B\right)^{*}\right) \cap \mathcal{R}\left(Y^{*}\left(I_{n}-A^{-}A\right)^{*}\right) = \{0\}.$$
(16)

**PROOF.** First, it follows from (4) that

$$\operatorname{rank} X = \operatorname{rank} (A^{-}B + (I_n - A^{-}A)Y)$$
  

$$\leq \operatorname{rank} (A^{-}B) + \operatorname{rank} ((I_n - A^{-}A)Y)$$
  

$$= \operatorname{rank} B + \operatorname{rank} ((I_n - A^{-}A)Y)$$
  

$$\leq \operatorname{rank} B + \operatorname{rank} (I_n - A^{-}A)$$
  

$$= \operatorname{rank} B + n - \operatorname{rank} A.$$

Therefore, rank X = n if and only if (14),

$$\operatorname{rank}\left(A^{-}B + (I_{n} - A^{-}A)Y\right) = \operatorname{rank}\left(A^{-}B\right) + \operatorname{rank}\left(\left(I_{n} - A^{-}A\right)Y\right)$$
(17)

and

$$\operatorname{rank}\left(\left(I_n - A^{-}A\right)Y\right) = \operatorname{rank}\left(I_n - A^{-}A\right)$$
(18)

are satisfied.

Second, applying Theorem 3.4.17 from [9], relation (18) is equivalent to

$$\mathcal{N}(Y^*) \cap \mathcal{R}\left(\left(I_n - A^- A\right)^*\right) = \{0\},\$$

or equivalently,

$$\mathcal{R}(Y) \cap \mathcal{N}\left(I_n - A^- A\right) = \{0\}.$$
(19)

L

Since  $\mathcal{N}(I_n - A^- A) = \mathcal{R}(A^- A)$ , relation (19) is equivalent to (15).

Third, Lemma 5, [10], and (3), imply that (17) is equivalent to (16).

Combining the above three aspects completes the proof.

Based on Lemmas 5 and 6, the solution to Problem 2 can be stated as follows.

THEOREM 2. Suppose the hypotheses of Lemma 4 are satisfied, and the matrix X possesses the form (4) with (5) and (6). Then X is a common Hermitian positive-definite solution to the pair of matrix equations (1) and (2) if and only if relations (14)-(16) are satisfied.

## 4. THE EXAMPLE

Consider the pair of matrix equations (1) and (2) with the parameter matrices (see [2])

$$A = \begin{bmatrix} 1 & 1 \end{bmatrix}, \quad C = \begin{bmatrix} 0 & 1 \end{bmatrix}, \quad B = D = \begin{bmatrix} 1 & 0 \end{bmatrix}.$$

Obviously, m = p = 1, n = 2, and (3) is satisfied. By choosing

$$A^- = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \end{bmatrix}^*,$$

we derive

$$C(I_2 - A^- A) = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \end{bmatrix}.$$

Again choosing

$$[C(I_2 - A^- A)]^- = [-1 \ 1]^*,$$

we have that (6) holds for any  $T \in \mathbf{U}_2$ . We write

$$T = \begin{bmatrix} t_1 & t_2 \\ t_3 & t_4 \end{bmatrix},$$

where  $t_i \in \mathbf{C}$ , i = 1, 2, 3, 4, satisfy

$$|t_1|^2 + |t_2|^2 = 1,$$
  $|t_3|^2 + |t_4|^2 = 1,$   $t_1\bar{t}_3 + t_2\bar{t}_4 = 0.$ 

Using Theorem 1, we derive that the general common nonnegative-definite solution to the pair of matrix equations is given by

$$X = \begin{bmatrix} (1-t_1)(1-\bar{t}_1) + |t_2|^2 & (1-t_1)\bar{t}_1 - |t_2|^2 \\ t_1(1-\bar{t}_1) - |t_2|^2 & 1 \end{bmatrix} = \begin{bmatrix} 2-2\operatorname{Re}(t_1) & \bar{t}_1 - 1 \\ t_1 - 1 & 1 \end{bmatrix}.$$
 (20)

Furthermore, using Theorem 2, we derive that the general common positive-definite solution to the pair of matrix equations is given by

$$X = \begin{bmatrix} 2 - 2\operatorname{Re}(t_1) & \bar{t}_1 - 1 \\ t_1 - 1 & 1 \end{bmatrix}, \quad |t_1| < 1.$$

REMARK 1. Let  $t_1 = -z$  and  $t_2 = u$  in (20). Then (20) turns into [2, equation (2.5)]. However, reference [2] did not give a representation of the general common nonnegative-definite solution to the pair of matrix equations (1) and (2) when the parameter matrices A, B, C, and D are arbitrarily chosen.

#### REFERENCES

- 1. D.M. Young, J.W. Seaman, Jr. and L.M. Meaux, Independence distribution preserving covariance structures for the multivariate model, J. Multivariate Anal. 68, 165-175, (1999).
- J. Groß, Nonnegative-define and positive solutions to the matrix equation AXA\* = B—Revisited, Linear Algebra Appl. 321, 123-129, (2000).
- 3. J.K. Baksalary, Nonnegative definite and positive definite solutions to the matrix equation  $AXA^* = B$ , Linear and Multilinear Algebra 16, 133-139, (1984).
- C.G. Khatri and S.K. Mitra, Hermitian and nonnegative definite solutions of linear matrix equations, SIAM J. Appl. Math. 31, 579-585, (1976).
- 5. X. Zhang and M.-Y. Cheng, The rank-constrained Hermitian nonnegative-definite and positive-definite solutions to the matrix equation  $AXA^* = B$ , Linear Algebra Appl. **370**, 163–174, (2003).
- H. Dai and P. Lancaster, Linear matrix equations from an inverse problem of vibration theory, *Linear Algebra Appl.* 246, 31-47, (1996).
- 7. C.R. Rao and S.K. Mitra, Generalized Inverse of Matrices and Its Applications, John Wiley, New York, (1971).
- J.N. Buxton, R.F. Churchouse and A.B. Tayler, *Matrices Methods and Applications*, Clarendon Press, Oxford, (1990).
- 9. A.R. Rao and P. Bhimasankaram, Linear Algebra, Tata McGraw-Hill, New Delhi, (1992).
- 10. G. Marsaglia and G.P.H. Styan, When does rank(A+B) = rank A + rank B?, Canad. Math. Bull. 15, 451–452, (1972).