# Rearrangement and Extremal Results for Hermitian Matrices* ${ }^{\dagger}$ 

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#### Abstract

This paper contains extreme value results for concave and convex symmetric functions of the eigenvalues of $B+P^{*} A P$ as functions of the partial isometry $P$. The matrices $A$ and $B$ are Hermitian.


## I. INTRODUCTION AND RESULTS

Let $A$ and $B$ be respectively $n$-square and $k$-square hermitian matrices. One of the central results in a recent paper [1] is the following extremal theorem:

$$
\begin{equation*}
\min _{P^{*} P=I_{k}} E_{m}\left(B+P^{*} A P\right)=E_{m}\left(\beta_{1}+\alpha_{n-k+1}, \ldots, \beta_{k}+\alpha_{n}\right) \tag{1}
\end{equation*}
$$

where $\alpha_{1} \geqslant \cdots \geqslant \alpha_{n}, \beta_{1} \geqslant \cdots \geqslant \beta_{k}$ are the eigenvalues of $A$ and $B$ respectively, $1 \leqslant m \leqslant k \leqslant n$, and $P$ is an $n \times k$ partial isometry satisfying $P^{*} P=I_{k}$. The notation $E_{m}(X)$ designates the elementary symmetric function (e.s.f.) of degree $m$ of the eigenvalues of the matrix $X$, while $E_{m}\left(x_{1}, \ldots, x_{k}\right)$ is the e.s.f. of the variables $x_{1}, \ldots, x_{k}$. The proof of (1) in [1] requires that the matrices $A$ and $B$ be positive definite, and the argument depends on computing the gradient of $E_{m}\left(B+P^{*} A P\right)$, in which the partial isometries $P$ are parametrized in some way.

In this note we show that a number of extremal results, including an extension of (1), can in fact be quite easily proved using results of Lidskii and Wielandt [12], the Cauchy interlacing inequalities [5], the Birkhoff theorem for doubly stochastic (d.s.) matrices [2], certain convexity results for symmetric functions [6,11], and some rearrangement theorems proved in the

[^0]sequel. Moreover, the hypotheses that $A$ and $B$ are positive definite can be weakened to $\alpha_{n}+\beta_{k} \geqslant 0$. The extent to which non-negativity assumptions about the eigenvalues of $A$ and $B$ can be abandoned altogether is discussed in the second part of the paper.

Theorem 1. Assume that $\alpha_{n}+\beta_{k} \geqslant 0$, and let $f\left(x_{1}, \ldots, x_{k}\right)$ be a symmetric function, concave and monotone non-decreasing in each variable for $x_{i} \geqslant 0$, $j=1, \ldots, k$. Define

$$
\varphi(P)=f\left(B+P^{*} A P\right)
$$

Then

$$
\begin{equation*}
\min _{P * P=I_{k}} \varphi(P) \geqslant \min _{\sigma} f\left(\beta+\alpha^{\sigma}\right), \tag{2}
\end{equation*}
$$

where $\beta=\left(\beta_{1}, \ldots, \beta_{k}\right)$ and $\alpha^{\sigma}=\left(\alpha_{n-k+\sigma(1)}, \ldots, \alpha_{n-k+\sigma(k)}\right), \sigma \in S_{k}$.

Proof. For a fixed partial isometry $P$, denote the eigenvalues of $P^{*} A P$ by $\nu_{1} \geqslant \nu_{2} \geqslant \cdots \geqslant \nu_{k}, \nu=\left(\nu_{1}, \ldots, \nu_{k}\right)$. The Lidskii-Wielandt result states that if $\gamma=\left(\gamma_{1}, \ldots, \gamma_{k}\right), \gamma_{1} \geqslant \cdots \geqslant \gamma_{k}$, are the eigenvalues of $B+P^{*} A P$, then

$$
\gamma=\beta+S_{0} \nu
$$

where $S_{0}$ is $k$-square d.s. Then

$$
\begin{aligned}
\varphi(P) & =f(\gamma) \\
& =f\left(\beta+S_{0} \nu\right)
\end{aligned}
$$

and we can define a function

$$
\psi(S)=f(\beta+S v)
$$

whose domain is the polyhedron $\Omega_{k}$ of $k$-square d.s. matrices. The vertices of $\Omega_{k}$ are precisely the $k$-square permutation matrices [2]. The Cauchy inequalities are

$$
\begin{equation*}
\alpha_{s} \geqslant \nu_{s} \geqslant \alpha_{n-k+s}, \quad s=1, \ldots, k \tag{3}
\end{equation*}
$$

and hence the $k$ th component of $\beta+S \nu$ satisfies

$$
\begin{aligned}
(\beta+S \nu)_{k} & =\beta_{k}+\sum_{i=1}^{k} s_{k j} \nu_{i} \\
& \geqslant \beta_{k}+\nu_{k} \\
& \geqslant \beta_{k}+\alpha_{n} \\
& \geqslant 0 .
\end{aligned}
$$

It follows that $\psi(S), S \in \Omega_{k}$, is well defined, and for any $S$ and $T$ in $\Omega_{k}$ and $0 \leqslant \theta \leqslant 1$ we compute

$$
\begin{align*}
\psi(\theta S+(1-\theta) T) & =f(\beta+(\theta S+(1-\theta) T) \nu\rangle \\
& =f(\theta(\beta+S \nu)+(1-\theta)(\beta+T \nu)) \\
& \geqslant \theta f(\beta+S \nu)+(1-\theta) f(\beta+T \nu) \\
& =\theta \psi(S)+(1-\theta) \psi(T) \tag{4}
\end{align*}
$$

The inequaltiy (4) is a consequence of the concavity of $f$. Thus $\psi: \Omega_{k} \rightarrow \mathbf{R}$ is concave, and hence from Birkhoff's theorem [2],

$$
\begin{aligned}
\psi\left(S_{0}\right) & \geqslant \min _{Q} \psi(Q) \\
& =\min _{Q} f(\beta+Q \nu)
\end{aligned}
$$

where the minimum is over all $k$-square permutation matrices $Q$. Thus from (3) and the monotonicity of $f$,

$$
\begin{aligned}
f\left(B+P^{*} A P\right) & =\varphi(P) \\
& =\psi\left(S_{0}\right) \\
& \geqslant \min _{\sigma \in S_{k}} f\left(\beta_{1}+\nu_{\sigma(1)}, \ldots, \beta_{k}+\nu_{\sigma(k)}\right) \\
& \geqslant \min _{\sigma \in S_{k}} f\left(\beta_{1}+\alpha_{n-k+\sigma(1)}, \ldots, \beta_{k}+\alpha_{n-k+\sigma(k)}\right) \\
& =\min _{\sigma \in S_{k}} f\left(\beta+\alpha^{\sigma}\right) .
\end{aligned}
$$

As a first application take

$$
f\left(x_{1}, \ldots, x_{k}\right)=E_{m}^{1 / m}\left(x_{1}^{\theta}, \ldots, x_{k}^{\theta}\right)
$$

$0 \leqslant \theta \leqslant 1$. This function is concave [6] and non-decreasing in each $x_{j}, x_{j}>0$. We have

Corollary 1. If $\alpha_{n}+\beta_{k} \geqslant 0$ and $0 \leqslant \theta \leqslant 1$, then

$$
\min _{P^{*} P=I_{k}} E_{m}\left(\left(B+P^{*} A P\right)^{\theta}\right)=E_{m}\left(\left(\beta_{1}+\alpha_{n+k+1}\right)^{*}, \ldots,\left(\beta_{k}+\alpha_{n}\right)^{\theta}\right)
$$

Proof. Let $U$ be a $k$-square unitary matrix diagonalizing $B$. Then

$$
E_{m}\left(\left(B+P^{*} A P\right)^{\theta}\right)=E_{m}\left(\left(\operatorname{diag}\left(\beta_{1}, \ldots, \beta_{k}\right)+U^{*} P^{*} A P U\right)^{\theta}\right)
$$

Clearly $P U$ runs over the set of partial isometries as $P$ does, so that by Theorem 1

$$
\begin{gather*}
\min _{P^{*} P=I_{k}} E_{m}^{1 / m}\left(\left(B+P^{*} A P\right)^{\theta}\right)=\min _{P^{*} P=I_{k}} E_{m}^{1 / m}\left(\left(\operatorname{diag}\left(\beta_{1}, \ldots, \beta_{k}\right)+P^{*} A P\right)^{\theta}\right) \\
\geqslant \min _{\sigma \in S_{k}} E_{m}^{1 / m}\left(\left(\beta_{1}+\alpha_{n-k+\sigma(1)}\right)^{\theta}, \ldots,\left(\beta_{k}+\alpha_{n-k+\sigma(k)}\right)^{\theta}\right) \tag{5}
\end{gather*}
$$

The right side of (5) is achievable by simply choosing the columns of $P$ to be a suitable selection of $k$ orthonormal eigenvectors of $A$. It is easy to confirm that the minimum in (5) is taken on for $\sigma$ the identity permutation $[1,3]$.

Consider next the symmetric rational function

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{k}\right)=\frac{E_{m}\left(x_{1}, \ldots, x_{k}\right)}{E_{m-1}\left(x_{1}, \ldots, x_{k}\right)} \tag{6}
\end{equation*}
$$

in which $1 \leqslant m-1<k$. A somewhat more difficult rearrangement theorem is required to deal with this function.

Theorem 2. The function (6) is concave and monotone non-decreasing for non-negative variables $\left(E_{m-1} \neq 0\right)$. If $c_{1} \geqslant \cdots \geqslant c_{k}, d_{1} \geqslant \cdots \geqslant d_{k}$, and at least $m-1$ of the numbers $c_{i}+d_{j}$ are positive ( $c_{k}+d_{k} \geqslant 0$ ), then for the function (6),

$$
\begin{equation*}
\min _{\sigma \in \mathrm{S}_{k}} f\left(c_{1}+d_{\sigma(1)}, \ldots, c_{k}+d_{\sigma(k)}\right)=f\left(c_{1}+d_{1}, \ldots, c_{k}+d_{k}\right) \tag{7}
\end{equation*}
$$

Proof. The proof that $f$ is concave is found in [6]. Differentiating (6) with respect to $x_{i}$, we have

$$
\begin{equation*}
\frac{\partial f}{\partial x_{i}}=\frac{E_{m-1}(x) E_{m-1}\left(\hat{x}_{i}\right)-E_{m}(x) E_{m-2}\left(\hat{x}_{j}\right)}{E_{m-1}^{2}(x)} \tag{8}
\end{equation*}
$$

where $E_{m-1}\left(\hat{x}_{j}\right)$, etc., means that $x_{f}$ is omitted. The numerator in (8) simplifies to

$$
E_{m-1}^{2}\left(\hat{x}_{i}\right)-E_{m}\left(\hat{x}_{i}\right) E_{m-2}\left(\hat{x}_{i}\right),
$$

which is always non-negative for non-negative variables.
To prove the final assertion of the theorem, we observe that unless o is the identity permutation, the arrangement of the arguments in $f\left(c_{1}+\right.$ $\left.d_{o(1)}, \ldots, c_{k}+d_{o(k)}\right)$ has the following form:

$$
\begin{equation*}
f\left(c_{1}+d_{1}, c_{2}+d_{2}, \ldots, c_{r-1}+d_{r-1}, c_{r}+d_{s}, \ldots, c_{t}+d_{r}, \ldots, c_{k}+d_{\sigma(k)}\right) \tag{9}
\end{equation*}
$$

in which $s>r \geqslant 1$ and $t>r \geqslant 1$. That is, there is a first $d$ which does not appear as a summand with the same subscripted $c$. We will show that if $d_{s}$ and $d_{r}$ are interchanged in (9) and the positions of the remaining $d$ 's are left unaltered, then the value of (9) is not increased. Write (9) as

$$
\begin{equation*}
f\left(\ldots, c_{r}+d_{s}, \ldots, c_{t}+d_{r}, \ldots\right) \tag{10}
\end{equation*}
$$

and compute that (10) is equal to

$$
\begin{gather*}
\frac{E_{m}\left(\ldots, c_{r}+d_{s}, \ldots, c_{t}+d_{r}, \ldots\right)}{E_{m-1}\left(\ldots, c_{r}+d_{s}, \ldots, c_{t}+d_{r}, \ldots\right)} \\
=\frac{\left(c_{r}+d_{s}\right)\left(c_{t}+d_{r}\right) E_{m-2}(\cdot)+\left(c_{r}+d_{s}+c_{t}+d_{r}\right) E_{m-1}(\cdot)+E_{m}(\cdot)}{\left(c_{r}+d_{s}\right)\left(c_{t}+d_{r}\right) E_{m-3}(\cdot)+\left(c_{r}+d_{s}+c_{t}+d_{r}\right) E_{m-2}(\cdot)+E_{m-1}(\cdot)} \tag{11}
\end{gather*}
$$

where $E_{m-2}(\cdot)$, etc., is the e.s.f. of those arguments other than the ones occurring in positions $r$ and $t$ The same computation shows that

$$
\begin{gather*}
f\left(\ldots, c_{r}+d_{r}, \ldots, c_{t}+d_{s}, \ldots\right) \\
=\frac{\left(c_{r}+d_{r}\right)\left(c_{t}+d_{s}\right) E_{m-2}(\cdot)+\left(c_{r}+d_{r}+c_{t}+d_{s}\right) E_{m-1}(\cdot)+E_{m}(\cdot)}{\left(c_{r}+d_{r}\right)\left(c_{t}+d_{s}\right) E_{m-3}(\cdot)+\left(c_{r}+d_{r}+c_{t}+d_{s}\right) E_{m-2}(\cdot)+E_{m-1}(\cdot)} \tag{12}
\end{gather*}
$$

Let $p=\left(c_{r}+d_{s}\right)\left(c_{t}+d_{r}\right), q=\left(c_{r}+d_{r}\right)\left(c_{t}+d_{s}\right), \gamma=c_{r}+d_{r}+c_{t}+d_{s}$ so that (11) and (12) can be respectively rewritten as

$$
\begin{equation*}
\frac{p E_{m-2}(\cdot)+\gamma E_{m-1}(\cdot)+E_{m}(\cdot)}{p E_{m-3}(\cdot)+\gamma E_{m-2}(\cdot)+E_{m-1}(\cdot)} \tag{13}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{q E_{m-2}(\cdot)+\gamma E_{m-1}(\cdot)+E_{m}(\cdot)}{q E_{m-3}(\cdot)+\gamma E_{m-2}(\cdot)+E_{m-1}(\cdot)} \tag{14}
\end{equation*}
$$

Now regard (13) as a function $h(p)$ of $p$ above, and observe that to within a
positive multiple the derivative of $\boldsymbol{h}(\boldsymbol{p})$ is

$$
\begin{align*}
&\left(p E_{m-3}(\cdot)+\gamma E_{m-2}(\cdot)+E_{m-1}(\cdot)\right) E_{m-2}(\cdot) \\
&-\left(p E_{m-2}(\cdot)+\gamma E_{m-1}(\cdot)+E_{m}(\cdot)\right) E_{m-3}(\cdot) \\
&=\gamma {\left[E_{m-2}^{2}(\cdot)-E_{m-1}(\cdot) E_{m-3}(\cdot)\right]+\left[E_{m-1}(\cdot) E_{m-2}(\cdot)-E_{m}(\cdot) E_{m-3}(\cdot)\right] } \tag{15}
\end{align*}
$$

Both of the square bracketed quantities in (15) are non-negative [4], so that $h^{\prime}(p) \geqslant 0$. But

$$
\begin{aligned}
p-q & =c_{r} c_{t}+c_{r} d_{r}+c_{t} d_{s}+d_{r} d_{s}-c_{r} c_{t}-c_{r} d_{s}-c_{t} d_{r}-d_{r} d_{s} \\
& =\left(c_{r}-c_{t}\right)\left(d_{r}-d_{s}\right) \\
& \geqslant 0
\end{aligned}
$$

Hence $h(p) \geqslant h(q)$. The preceding argument requires that $m \geqslant 3$. However, if $m=2$, then $m-1=1$ and the denominator in $f\left(c+d^{\sigma}\right)$ is independent of $\sigma$. The proof then depends on the result for $E_{2}\left(c+d^{\sigma}\right)$ found in [3].

By exactly the same argument used to prove Corollary 1 we use Theorems 1 and 2 to obtain

Corollary 2. If at least $m-1$ of the sums $\beta_{j}+\alpha_{n-k+j}, j=1, \ldots, k$, are positive ( $\beta_{k}+\alpha_{n} \geqslant 0$ ), then

$$
\min _{P^{*} P=I_{k}} \frac{E_{m}\left(B+P^{*} A P\right)}{E_{m-1}\left(B+P^{*} A P\right)}=\frac{E_{m}\left(\beta_{1}+\alpha_{n-k+1}, \ldots, \beta_{k}+\alpha_{n}\right)}{E_{m-1}\left(\beta_{1}+\alpha_{n-k+1}, \ldots, \beta_{k}+\alpha_{n}\right)}
$$

It is obvious that the result in Theorem 1 remains intact if "convex" replaces "concave" and "max" replaces "min". Thus we have

Theorem 3. If $\alpha_{n}+\beta_{k} \geqslant 0$, and $f$ is symmetric, convex, and monotone non-decreasing in each $x_{i}, x_{i} \geqslant 0$, then

$$
\max _{P^{*} P=I_{k}} f\left(B+P^{*} A P\right) \leqslant \max _{\sigma \in S_{k}} f\left(\beta+\alpha^{\sigma}\right)
$$

where $\alpha^{\sigma}=\left(\alpha_{\sigma(1)}, \ldots, \alpha_{\sigma(k)}\right)$.
Some interesting choices of $f$ are

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{k}\right)=\sum_{i=1}^{k} x_{i}^{\rho}, \quad \rho \geqslant 1 \tag{16}
\end{equation*}
$$

and

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{k}\right)=h_{m}^{1 / m}\left(x_{1}, \ldots, x_{k}\right) \tag{17}
\end{equation*}
$$

where $h_{m}$ is the $m$ th completely symmetric function of the indicated variables, i.e., the sum of all $\binom{m+k-1}{m}$ homogeneous products of degree $m$ in $x_{1}, \ldots, x_{k}$ [11].

From Theorem 3 applied to (16) we have

Corollary 3. If $\alpha_{n}+\beta_{k} \geqslant 0$ and $\rho \geqslant 1$, then

$$
\max _{P^{*} P=I_{k}} \operatorname{tr}\left(\left(B+P^{*} A P\right)^{\rho}\right)=\left(\beta_{1}+\alpha_{1}\right)^{\rho}+\cdots+\left(\beta_{k}+\alpha_{k}\right)^{\rho}
$$

In order to prove a corresponding extremal result for (17), we must determine

$$
\max _{\sigma \in S_{k}} h_{m}\left(c_{1}+d_{\sigma(1)}, \ldots, c_{k}+d_{\sigma(k)}\right)
$$

Theorem 4. If $c_{1} \geqslant \cdots \geqslant c_{k}, d_{1} \geqslant \cdots \geqslant d_{k}$, and $c_{k}+d_{k} \geqslant 0$, then

$$
\begin{equation*}
\max _{\sigma \in \mathrm{S}_{k}} h_{m}\left(c+d^{\sigma}\right)=h_{m}(c+d) \tag{18}
\end{equation*}
$$

Proof. The argument begins precisely as the proof of Theorem 2 by considering

$$
\begin{equation*}
h_{m}\left(\ldots, c_{r}+d_{s}, \ldots, c_{t}+d_{r}, \ldots\right) \tag{19}
\end{equation*}
$$

We expand (19) to obtain

$$
\begin{equation*}
\sum_{\nu=0}^{m} h_{\nu}\left(c_{r}+d_{s}, c_{t}+d_{r}\right) h_{m-\nu}(\cdot) \tag{20}
\end{equation*}
$$

Thus from (20) the question comes down to proving (18) for arbitrary $m$ and $k=2$. We do this by induction on $m$, with nothing to prove for $m=1$. Now

$$
h_{m}\left(x_{1}, x_{2}\right)=x_{1} h_{m-1}\left(x_{1}, x_{2}\right)+x_{2}^{m}
$$

and hence

$$
\begin{align*}
& \quad h_{m}\left(c_{1}+d_{1}, c_{2}+d_{2}\right)-h_{m}\left(c_{1}+d_{2}, c_{2}+d_{1}\right) \\
& =\left(c_{1}+d_{1}\right) h_{m-1}\left(c_{1}+d_{1}, c_{2}+d_{2}\right)-\left(c_{1}+d_{2}\right) h_{m-1}\left(c_{1}+d_{2}, c_{2}+d_{1}\right) \\
& +\left(c_{2}+d_{2}\right)^{m}-\left(c_{2}+d_{1}\right)^{m} \\
& \geqslant\left(d_{1}-d_{2}\right)\left[h_{m-1}\left(c_{1}+d_{1}, c_{2}+d_{2}\right)-h_{m-1}\left(c_{2}+d_{2}, c_{2}+d_{1}\right)\right] \\
& \geqslant 0 \tag{21}
\end{align*}
$$

The first inequality in (21) is the induction step; the second is due to the monotonicity of $h_{\mathrm{m}}$ for non-negative variables.

If we return to (20) and apply the $k=2$ case to each of the summands, we have

$$
\begin{aligned}
h_{m}\left(\ldots, c_{r}+d_{s}, \ldots, c_{t}+d_{r}, \ldots\right) & \leqslant \sum_{\nu=0}^{m} h_{\nu}\left(c_{r}+d_{r}, c_{t}+d_{s}\right) h_{m-\nu}(\cdot) \\
& =h_{m}\left(\ldots, c_{r}+d_{r}, \ldots, c_{t}+d_{s}, \ldots\right)
\end{aligned}
$$

In other words, if $s>r$ (so that $d_{s} \leqslant d_{\tau}$ ), then

$$
\begin{aligned}
& h_{m}\left(c_{1}+d_{1}, \ldots, c_{r-1}+d_{r-1}, c_{r}+d_{s}, \ldots, c_{t}+d_{r}, \ldots\right) \\
\leqslant & h_{m}\left(c_{1}+d_{1}, \ldots, c_{r-1}+d_{r-1}, c_{r}+d_{r}, \ldots, c_{t}+d_{s}, \ldots\right)
\end{aligned}
$$

and (18) follows.
Combining Theorems 3 and 4, we have
Corollary 4. If $\alpha_{n}+\beta_{k} \geqslant 0$, then

$$
\max _{P^{*} P=I_{k}} h_{m}\left(B+P^{*} A P\right)=f\left(\beta_{1}+\alpha_{1}, \ldots, \beta_{k}+\alpha_{k}\right) .
$$

## 2. REMARKS

For $B=0$ the extreme values of

$$
\varphi(P)=f\left(P^{*} A P\right), \quad P^{*} P=I_{k}
$$

have been determined for a wide variety of symmetric functions $f$ and matrices $A$. Perhaps the most general result of this kind appears in [7], in which $A$ is assumed to be normal, $f$ is a Schur function, and it is proved that $\varphi(P)$ is in the convex hull of the values that $f$ takes on certain $k$-samples of eigenvalues of $A$. In particular it is proved that

$$
\begin{equation*}
E_{m}\left(P^{*} A P\right) \in \mathscr{H}\left\{E_{m}\left(\alpha_{\omega(1)}, \ldots, \alpha_{\omega(k)}\right), \omega \in Q_{k, n}\right\} \tag{22}
\end{equation*}
$$

where $\mathscr{H}$ denotes convex hull and $Q_{k, n}$ is the totality of sequences $\omega$, $1 \leqslant \omega(1)<\cdots<\omega(k) \leqslant n$. Of course, the techniques of the present paper are all inapplicable even for $A$ indefinite Hermitian, much less normal, in proving a result like (22). The proof of (22) in fact depends on the representation of $E_{m}\left(P^{*} A P\right)$ as the trace of the $m$ th exterior power of $P^{*} A P$ [9].

In an elegant paper [3], M Fiedler proves that if $A$ and $B$ are indefinite hermitian $n$-square, then

$$
\begin{equation*}
\min _{\sigma \in S_{n}} \prod_{i=1}^{n}\left(\alpha_{i}+\beta_{\sigma(i)}\right) \leqslant \operatorname{det}(A+B) \leqslant \max _{\sigma \in S_{n}} \prod_{i=1}^{n}\left(\alpha_{i}+\beta_{\sigma(i)}\right) \tag{23}
\end{equation*}
$$

The essential idea of the expansion lemmas appearing in [1], as well as the rearrangement theorems for

$$
E_{m}\left(c+d^{\sigma}\right)
$$

also are found in [3]. In a paper presented at Gatlinburg V [10], the present author showed that for a class of symmetric polynomials including $E_{m}, h_{m}$, and $E_{m}+h_{m}$ a precise extension of (23) is available. These results will also appear elsewhere.

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