EXISTENCE AND UNIQUENESS RESULTS FOR
A COUPLED PROBLEM RELATED TO THE
STATIONARY NAVIER-STOKES SYSTEM

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ABSTRACT. – In this paper, we consider some systems which are close to the stationary Navier-Stokes equations. The structure of these systems is the following: An \( N \)-dimensional equation for motion, the incompressibility condition and a scalar equation involving an additional unknown, \( k = k(x) \). Among other things, they serve to model the behavior of certain turbulent flows. Our main interest concerns existence and uniqueness. The main difficulties are due to the structure of the scalar equation; in particular, the right side is typically in \( L^1 \) and, furthermore, there are nonlinear terms of the kind \( \nabla \cdot (\mu(k)\nabla k) \) and \( \nabla \cdot (B(k)) \), where \( \mu \) and \( B \) are general continuous functions.

Notation

- \( L^1 = L^1(\Omega), \quad H_0^1 = H_0^1(\Omega), \) etc.
- \( | \cdot | \) (resp. \( \| \cdot \| \)) denotes the usual norm in \( L^2 \) (resp. \( H_0^1 \)).
- \( H^{-1} = H^{-1}(\Omega) \) is the dual space of \( H_0^1 \); \( \| \cdot \|_* \) denotes the usual norm in \( H^{-1} \).
- \( \gamma_+ = \max(\gamma, 0) \) for any real \( \gamma \).
- \( T_M(s) = s \) if \( s \in [-M, M] \); \( T_M(s) = M \sign s \) otherwise.
- \( L_n \) is the piecewise linear even function satisfying \( L_n(s) = 1 \) if \( s \in [0, n] \), \( L_n(s) = -\frac{s}{n} + 2 \) if \( s \in [n, 2n] \) and \( L_n(s) = 0 \) if \( s > 2n \).
- \( S : D = \sum_{i,j=1}^N S_{ij} D_{ij} \) for any \( S = \{ S_{ij} \} \) and \( D = \{ D_{ij} \} \).
- \( N' \) is the conjugate exponent of \( N \), i.e. \( N' = \frac{N}{N-1} \).
- For each \( p \in [1, \infty] \), \( p^* \) is the associated Sobolev embedding exponent: \( p^* = \frac{Np}{N-p} \) if \( p < N \); \( 1 < p^* < \infty \) is arbitrary if \( p = N \) and \( p^* = \infty \) otherwise. In particular, \((N')^* = \frac{N}{N-2} \) if \( N \leq 3 \).

1. Introduction. Description of the problem

This paper is concerned with some nonlinear partial differential systems stemming from fluid mechanics. These are variants of the stationary Navier-Stokes equations and read as follows:

\[
\begin{aligned}
- \nabla \cdot (\nu Du + k\Phi'(Du)) + (u \cdot \nabla)u + \nabla p &= f, \\
- \nabla \cdot u &= 0, \\
- \nabla \cdot \left(\mu(k)\nabla k + B(k)\right) + u \cdot \nabla k &= \nu'|Du|^2 + k\Phi'(Du) : Du \\
- k\frac{1}{2}k\psi^0(Du). 
\end{aligned}
\]

In (1), it is assumed that \(Du = \nabla u + \nu u\). The functions \(D \mapsto \Phi(D), D \mapsto \psi^0(D), k \mapsto \mu(k)\) and \(k \mapsto B(k)\) are given. Once an open set \(\Omega \subset \mathbb{R}^n\) and the data \(\nu > 0\), \(\nu' \in [0, \nu]\) and \(f\) are fixed, we search for a solution \(\{u, p, k\}\) to (1), together with appropriate boundary value conditions.

Systems like (1) are motivated by turbulence modelling. More precisely, let \(U = U(x, t)\) and \(P = P(x, t)\) be respectively the velocity field and pressure distribution of a viscous incompressible fluid in turbulent regime. Then, the couple \((U, P)\) must satisfy the instationary Navier-Stokes equations. Denoting by \(u\) and \(p\) the corresponding time-averaged variables (that is to say, \(\bar{u} = \bar{U}\) and \(\bar{p} = \bar{P}\)) and setting

\[
U = u + u', \quad P = p + p',
\]

it is customary to replace the search of a solution to (1) by the analysis of a system that should be satisfied by \(u\) and \(p\). After some computations, one finds:

\[
- \nabla \cdot (\nu Du + R) + (u \cdot \nabla)u + \nabla p = f, \quad \nabla \cdot u = 0,
\]

where \(f\) is the time-averaged external forces field acting on the fluid particles and \(R\) is the so called Reynolds tensor:

\[
R = \{R_{ij}\}, \quad \text{with} \quad R_{ij} = -u_i'u_j'.
\]

Since in (2) we still find the unknown variables \(u_i'\), it is reasonable to introduce closing hypotheses relating \(R\) to \(u\). In the case of usual one-equation models, one imposes the following hypothesis of the Boussinesq kind:

\[
R = \nu_T Du, \quad \text{where} \quad \nu_T = F(k), \quad \text{(an algebraic relation)}.
\]

Here, \(k = \frac{3}{2}|u'|^2\) is the mean turbulent kinetic energy. The problem is thus closed using (2), (3) and an additional PDE for \(k\).

Unfortunately, when one tries to deduce an equation for \(k\), one finds again terms in which the turbulent perturbations \(u_i'\) (and \(k'\)) appear. More precisely, one has:

\[
- \nabla \cdot \left(\nu \nabla k + \left(-\left(p' + k'\right)u'\right)\right) + u \cdot \nabla k = R : Du - \frac{\nu}{2}|Du'|^2.
\]
Consequently, one has to replace (4) by an approximation. This is made by introducing new closing hypotheses:

- There is general agreement in the approximation of the dissipation term \( \frac{\nu}{2} |Du'|^2 \). It is usually replaced by a constant times \( k^{3/2} \).
- Of course, (3) is used again in order to approximate the production term \( R : Du \).
- The approximation of \( -(p' + k')u' \) has been achieved by several authors in different ways. In most papers, this term is replaced by \( cv_T \nabla k \), where \( c \) is an experimental constant (for instance, see [13], [12] and the references therein). In others, it is replaced by a vector \( B(k) \) (see [7]).

Hence, it is clear that equations like (1) can be used to describe the behavior of certain turbulent flows. Another motivation for (1) can be found in non-Newtonian mechanics. In this setting, \( \{u, p\} \) are the true velocity field and pressure, \( k \) is the temperature and it is assumed that the stress tensor \( \tau \) depends on \( Du \) and \( k \) as follows:

\[
\tau = \nu Du + k\Phi'(Du).
\]

2. The main results

In the sequel, we will consider a simplified version of (1):

\[
\begin{cases}
- \nu \Delta u - \nabla \cdot (k\Phi'(\nabla u)) + (u \cdot \nabla)u + \nabla p = f, \\
\nabla \cdot u = 0, \\
- \nabla \cdot (\mu(k)\nabla k + B(k)) + u \cdot \nabla k = \nu|\nabla u|^2 + k\Phi'(\nabla u) : \nabla u.
\end{cases}
\]

This is made for convenience only; the results in this section also hold for (1) with appropriate changes. In (6), the first, second and third equations will be respectively known as the motion equation, the incompressibility condition and the energy equation. Our assumptions are the following:

- \( \Omega \subset \mathbb{R}^N \) is a bounded, connected, open and regular set; \( \nu > 0 \) and \( f \in H^{-1} \).
- \( D \mapsto \Phi(D) \) is \( C^1 \), \( \Phi'(0) = 0 \), \( |\Phi'(D)| \leq \text{Const.} \) and \( D \mapsto \Phi'(D) : D \) is convex (consequently, it is also locally Lipschitz-continuous). In particular, \( D \mapsto \Phi(D) \) is convex and one has \( (\Phi'(D_1) - \Phi'(D_2)) : (D_1 - D_2) \geq 0 \) for all \( D_1 \) and \( D_2 \).
- \( k \mapsto \mu(k) \) and \( k \mapsto B(k) \) are continuous functions; furthermore, \( \mu(k) \geq \mu_0 > 0 \) for all \( k \).

We want to solve (6) together with Dirichlet conditions for \( u \) and \( k \):

\[
\begin{align*}
\psi \in L^1; & \quad T_M(\psi) \in H^1_0, \quad \forall M > 0, \quad \lim_{n \to \infty} \frac{1}{n} \int_{n \leq |\psi| \leq 2n} |\nabla \psi|^2 \, dx = 0 \\
(\text{see the Notation}).
\end{align*}
\]
THEOREM 1. Under the previous assumptions, there exists \( \{u, p, k\} \), with \( u \in V, p \in L^2 \) and \( k \in \mathcal{L} \) such that:

1. The couple \( \{u, p\} \) solves the first two equations in (6) in the usual weak or distributional sense.

2. \( k \geq 0 \) and solves the third equation in (6) in the following sense:

\[
\begin{aligned}
- \nabla \cdot (\beta(k)(\mu(k)\nabla k + B(k))) + \beta'(k)\nabla k \cdot (\mu(k)\nabla k + B(k)) \\
+ \beta(k)(u \cdot \nabla k) = \beta(k)(\nu|\nabla u|^2 + k\Phi'(\nabla u) \cdot \nabla u)
\end{aligned}
\]

in \( \mathcal{D}'(\Omega) \) for every \( \beta \in W^{1,\infty}(\mathbb{R}) \) with compact support.

A triplet \( \{u, p, k\} \) as above will be called a weak-renormalized solution to (6). Renormalized solutions to PDE's seem to have been introduced by R. DiPerna and P. L. Lions in [8], in the framework of the Boltzmann equation. They have been used in connection with various nonlinear elliptic equations by P. Benilan et al. [3], L. Boccardo et al. [6] and P. L. Lions and F. Murat [10] (see also [11]). In the analysis of existence results for problems similar to (1) and (6), weak-renormalized solutions were considered by R. Lewandowski [9] (see also [2]). That we look for a renormalized solution \( k \) is motivated by the structure of the right side of the energy equation in (6) (typically in \( L^1 \)) and also by our interest in keeping \( \mu \) and \( B \) as general as possible.

Let us denote by \( \bar{\mu} \) the following function:

\[
\bar{\mu}(s) = \int_0^s \mu(\sigma) \, d\sigma \quad \forall s \in \mathbb{R}.
\]

Assume that, in theorem 1, one has \( B \equiv 0 \). Then it is not difficult to see that the solution \( \{u, p, k\} \) furnished by theorem 1 satisfies

\[
\bar{\mu}(k) \in \bigcap_{q < N'} W^{3,q}_0, \quad \nabla \bar{\mu}(k) = \mu(k)\nabla k
\]

and also the following:

\[
\begin{aligned}
\int_{\Omega} \mu(k)\nabla k \cdot \nabla \phi + \int_{\Omega} (u \cdot \nabla k)\phi = \int_{\Omega} (\nu|\nabla u|^2 + k\Phi'(\nabla u) \cdot \nabla u)\phi
\end{aligned}
\]

\( \forall \phi \in \mathcal{D}(\Omega) \).

In this case, it will be said that \( \{u, p, k\} \) is a weak solution to (6).

THEOREM 2. Assume that, in theorem 1, \( B \equiv 0 \) and \( D \to \Phi'(D) : D \) is globally Lipschitz-continuous. Then, there exists \( \nu_0 > 0 \) such that, when \( \nu \geq \nu_0 \), there exists at most one weak solution \( \{u, p, k\} \) to (6) with \( k \geq 0 \).

Before giving the proofs of these results, let us make some remarks:

1. A very interesting question remains: When \( \nu \) is large and \( B \) is not zero, is it still possible to prove the uniqueness of a renormalized solution?
2. There are several other possible conditions for uniqueness, different from the assumption $\nu \geq \nu_0$. For instance, for fixed $\nu$, one can also obtain at most one weak solution $\{u, p, k\}$ to (6) with $k \geq 0$ if $\|f\|_*$ is sufficiently small.

3. Results similar to those above can be proved for the instationary variant of (6). This will be analyzed in a forthcoming paper.

4. Several more or less obvious generalizations are possible. In particular, we find an interesting situation when we simply assume $\mu(k) \geq 0$ in (6). This case is far from trivial and will also be the subject of future work.

3. The proof of Theorem 1

In this section, $C$ denotes a constant which may depend on $N$, $\Omega$ and the data in (6). The proof of Theorem 1 consists of six steps:

**FIRST STEP.**  – The introduction of a family of approximations.

For each $\varepsilon > 0$, we consider the following approximation to (6):

$$\begin{cases}
\nu \Delta u^\varepsilon - \nabla \cdot (T^\varepsilon_1(k^\varepsilon) + \Phi'(\nabla u^\varepsilon)) + (u^\varepsilon \cdot \nabla)u^\varepsilon - \nabla p^\varepsilon = f, \\
\nabla \cdot u^\varepsilon = 0, \\
- \nabla \cdot \left( T^\varepsilon_1(\mu(k^\varepsilon)) \nabla k^\varepsilon + B(T^\varepsilon_1(k^\varepsilon)) \right) + u^\varepsilon \cdot \nabla k^\varepsilon = T^\varepsilon \cdot \nabla u^\varepsilon.
\end{cases}$$

(11)

Here, we have used the following notation:

$$\tau^\varepsilon = \nu \nabla u^\varepsilon + T^\varepsilon_1(k^\varepsilon) + \Phi'(\nabla u^\varepsilon).$$

Of course, these equations are required to be satisfied in $\Omega$, together with homogeneous Dirichlet conditions for $u^\varepsilon$ and $k^\varepsilon$ on $\partial \Omega$. The existence of a triplet $\{u^\varepsilon, p^\varepsilon, k^\varepsilon\}$ can be established using (for instance) a Galerkin method. In fact, some nontrivial difficulties are found with this technique that can be solved arguing as in the following steps. One finds that the solution belongs to the space $V \times L^2 \times H^1_0(\Omega)$ and, also, that $k^\varepsilon \geq 0$.

**SECOND STEP.**  – *A priori* estimates and weak convergence.

Using $u^\varepsilon$ as a test function in the first equation in (11), one finds:

$$\int_\Omega \tau^\varepsilon : \nabla u^\varepsilon \leq C.$$

(12)

In particular,

$$\|u^\varepsilon\| \leq C.$$

(13)

In the energy equation in (11), let us use $T_M(k^\varepsilon)$ as test function. This gives:

$$\|T_M(k^\varepsilon)\|^2 \leq C \cdot M.$$

(14)
On the other hand, if we choose $\xi_n(k^\varepsilon) = T_{2n}(k^\varepsilon) - T_n(k^\varepsilon)$ as test function in the same equation, it is not difficult to check that

\[(15) \quad \frac{1}{n} \int_{n \leq k^\varepsilon \leq 2n} T_1(\mu(k^\varepsilon)) |\nabla k^\varepsilon|^2 \leq \int_{k^\varepsilon \geq n} T_1(\tau^\varepsilon : \nabla u^\varepsilon),\]

whence

\[(16) \quad \frac{1}{n} \int_{n \leq k^\varepsilon \leq 2n} |\nabla k^\varepsilon|^2 \leq C.\]

From (14) and (16), arguing as in [5] and [11], one deduces the following:

\[(17) \quad \|k^\varepsilon\|_{W_0^{1,q}} \leq C_q, \quad \forall q < N'.\]

Consequently, passing to a subsequence if necessary, it can be assumed that

- $u^\varepsilon \to u$ weakly in $V$, strongly in $L^r$ $\forall r < 2^*$ and a.e.,
- $k^\varepsilon \to k$ weakly in $W_0^{1,q}$ $\forall q < N'$, strongly in $L^p$ $\forall p < (N')^*$ and a.e.,
- $T_M(k^\varepsilon) \to T_M(k)$ weakly in $H_0^1$ $\forall M > 0$.

Obviously, one has $k \geq 0$.

**Third Step.** — $u$ is, together with some $p$, a solution to the motion equation. For each $\varepsilon > 0$, $u^\varepsilon$ is a solution to the following variational inequality:

\[
\begin{aligned}
\left\{ \begin{array}{l}
\nu \int_{\Omega} \nabla u^\varepsilon : \nabla v + \int_{\Omega} (u^\varepsilon \cdot \nabla) u^\varepsilon \cdot v + \int_{\Omega} T_1(k^\varepsilon) \Phi(\nabla v) \\
\quad \geq \nu \int_{\Omega} |\nabla u^\varepsilon|^2 + \int_{\Omega} T_1(k^\varepsilon) \Phi(\nabla u^\varepsilon) + \langle f, v - u^\varepsilon \rangle, \quad \forall v \in V, \quad u^\varepsilon \in V.
\end{array} \right.
\end{aligned}
\]

Taking limits as $\varepsilon \to 0$, one obtains:

\[
\nu \int_{\Omega} \nabla u : \nabla v + \int_{\Omega} (u \cdot \nabla) u \cdot v + \int_{\Omega} k \Phi(\nabla v) \\
\quad \geq \nu \liminf_{\varepsilon \to 0} \int_{\Omega} |\nabla u^\varepsilon|^2 + \liminf_{\varepsilon \to 0} \int_{\Omega} T_1(k^\varepsilon) \Phi(\nabla u^\varepsilon) + \langle f, v - u \rangle.
\]

The first term in the right is bounded from below by

\[
\nu \int_{\Omega} |\nabla u|^2.
\]

In what concerns the second term, let us first notice that:

\[
\int_{\Omega} T_1(k^\varepsilon) \Phi(\nabla u^\varepsilon) = \int_{\Omega} (T_1(k^\varepsilon) - k) \Phi(\nabla u^\varepsilon) + \int k \Phi(\nabla u^\varepsilon)
\]

Thus, taking into account that the function

\[
v \mapsto \int k \Phi(\nabla v)
\]
is lower semicontinuous, we find:

$$\liminf_{\varepsilon \to 0} \int_{\Omega} T_{\varepsilon}'(k\varepsilon)\Phi(\nabla u^\varepsilon) \geq \liminf_{\varepsilon \to 0} \int_{\Omega} (T_{\varepsilon}'(k\varepsilon) - k)\Phi(\nabla u^\varepsilon) + \liminf_{\varepsilon \to 0} \int_{\Omega} k\Phi(\nabla u^\varepsilon) \geq \int_{\Omega} k\Phi(\nabla u).$$

Consequently, $u$ is a solution to the variational inequality:

$$\begin{cases}
\nu \int_{\Omega} \nabla u : (\nabla v - \nabla u) + \int_{\Omega} (u \cdot \nabla)u \cdot (v - u) + \int_{\Omega} k\Phi(\nabla v) \\
- \int_{\Omega} k\Phi(\nabla u) \geq \langle f, v - u \rangle, \quad \forall v \in V, \quad u \in V.
\end{cases} \tag{18}$$

Now, taking in (18) the function $v$ of the form $u + tw$, where $w \in V$ and $t \in \mathbb{R}$ and letting $t \to 0$, it is a standard matter to prove that $u$ solves, together with some $p \in L^2$, the first two equations in (6) in the usual weak sense.

**Fourth step.** $u^\varepsilon$ converges strongly in $V$.

From the motion equation in (6), it is clear that

$$\int_{\Omega} (\nu|\nabla u|^2 + k\Phi'(\nabla u) : \nabla u) = \langle f, u \rangle.$$ 

On the other hand, choosing $u^\varepsilon$ as test function in the first equation in (11), one has:

$$\int_{\Omega} (\nu|\nabla u^\varepsilon|^2 + T_{\varepsilon}'(k\varepsilon)\Phi'(\nabla u^\varepsilon) : \nabla u^\varepsilon) = \langle f, u^\varepsilon \rangle.$$ 

Consequently,

$$\lim_{\varepsilon \to 0} \int_{\Omega} (\nu|\nabla u^\varepsilon|^2 + T_{\varepsilon}'(k\varepsilon)\Phi'(\nabla u^\varepsilon) : \nabla u^\varepsilon) = \int_{\Omega} (\nu|\nabla u|^2 + k\Phi'(\nabla u) : \nabla u),$$

whence it is also clear that

$$\lim_{\varepsilon \to 0} \int_{\Omega} (\nu|\nabla u^\varepsilon|^2 + k\Phi'(\nabla u^\varepsilon) : \nabla u^\varepsilon) = \int_{\Omega} (\nu|\nabla u|^2 + k\Phi'(\nabla u) : \nabla u),$$

(recall that $\Phi'$ is uniformly bounded). Hence,

$$0 = \lim_{\varepsilon \to 0} \left( \int_{\Omega} (\nu|\nabla u^\varepsilon|^2 + k\Phi'(\nabla u^\varepsilon) : \nabla u^\varepsilon) - \int_{\Omega} (\nu|\nabla u|^2 + k\Phi'(\nabla u) : \nabla u) \right)$$

$$\geq \limsup_{\varepsilon \to 0} \left( \nu \int_{\Omega} |\nabla (u^\varepsilon - u)|^2 \right)$$

$$+ \liminf_{\varepsilon \to 0} \left( \int_{\Omega} k\Phi'(\nabla u^\varepsilon) : \nabla u^\varepsilon - \int_{\Omega} k\Phi'(\nabla u) : \nabla u \right).$$
Here, the last term is $\geq 0$, in view of the lower semicontinuity of the function
\[ v \mapsto \int_{\Omega} k\Phi'(\nabla v) : \nabla v. \]

Thus,
\[ \lim_{\varepsilon \to 0} \int_{\Omega} |\nabla(u^\varepsilon - u)|^2 = 0. \]

**Fifth step.** — For all $M > 0$, $T_M(k^\varepsilon)$ converges strongly in $H^1_0$.

We will use an argument due to P. L. Lions and F. Murat (see [10], [11]). Let us see that:

\[ T_\varepsilon(\mu(k^\varepsilon))^{1/2} \nabla T_M(k^\varepsilon) \rightarrow \mu(k)^{1/2} \nabla T_M(k) \quad \text{strongly in } L^2 : \quad \forall M > 0, \tag{19} \]

(observe that $\mu(k)^{1/2} \nabla T_M(k)$ has a sense). Of course, (19) will suffice for our purposes.

It has already been proved that
\[ T_\varepsilon(\tau^\varepsilon : \nabla u^\varepsilon) \rightarrow \tau : \nabla u \quad \text{strongly in } L^1 \text{ and a.e.} \]

Here, we have introduced $T = \sqrt{\nu} u + k\Phi'(|\nabla u|)$. Choosing $T_M(k^\varepsilon)$ as test function in the energy equation in (11), one finds:
\[
\int_{\Omega} T_\varepsilon(\mu(k^\varepsilon)) \nabla k^\varepsilon \cdot \nabla T_M(k^\varepsilon) + \int_{\Omega} B(T_\varepsilon(k^\varepsilon)) \cdot \nabla T_M(k^\varepsilon) \\
+ \int_{\Omega} (u^\varepsilon \cdot \nabla k^\varepsilon) T_M(k^\varepsilon) - \int_{\Omega} T_\varepsilon(\tau^\varepsilon : \nabla u^\varepsilon) T_M(k^\varepsilon).
\]

After dropping the vanishing terms and letting $\varepsilon \to 0$, one easily obtains:

\[ \lim_{\varepsilon \to 0} \int_{\Omega} T_\varepsilon(\mu(k^\varepsilon)) |\nabla T_M(k^\varepsilon)|^2 = \int_{\Omega} (\nu \cdot \nabla u) T_M(k). \tag{20} \]

On the other hand, using $u_n^\varepsilon = T_M(k)L_n(k^\varepsilon)$ as a test function in the energy equation in (11) (see the meaning of $L_n$ in the Notation), one also has:

\[ \int_{\Omega} \left( T_\varepsilon(\mu(k^\varepsilon)) \nabla k^\varepsilon \cdot \nabla T_M(k) \right) L_n(k^\varepsilon) \\
+ \int_{\Omega} \left( T_\varepsilon(\mu(k^\varepsilon)) \nabla k^\varepsilon \cdot \nabla L_n(k^\varepsilon) \right) T_M(k) \\
+ \int_{\Omega} \left( B(T_\varepsilon(k^\varepsilon)) \cdot \nabla T_M(k) \right) L_n(k^\varepsilon) \\
+ \int_{\Omega} \left( B(T_\varepsilon(k^\varepsilon)) \cdot \nabla L_n(k) \right) T_M(k) \\
+ \int_{\Omega} (u^\varepsilon \cdot \nabla k^\varepsilon) T_M(k) L_n(k^\varepsilon) = \int_{\Omega} T_\varepsilon(\tau^\varepsilon : \nabla u^\varepsilon) T_M(k) L_n(k^\varepsilon). \tag{21} \]
In the sequel, we first keep $n$ fixed and let $\varepsilon \to 0$; then, we will let $n \to \infty$. We will analyze the behavior of each term in (21). We see that the first term converges to:

$$\int_{\Omega} (\mu(T_{2n}(k)) \nabla k \cdot \nabla T_{M}(k)) L_{n}(k)$$

as $\varepsilon \to 0$; but, for large $n$, this is just

$$\int_{\Omega} \mu(k) |\nabla T_{M}(k)|^2.$$

The second term satisfies:

$$\lim_{\varepsilon \to 0} \sup_{\varepsilon} \left| \int_{\Omega} (T_{\frac{1}{\varepsilon}}(\mu(k^{\varepsilon})) \nabla k^{\varepsilon} \nabla L_{n}(k^{\varepsilon})) T_{M}(k) \right|$$

$$\leq \lim_{\varepsilon \to 0} \sup_{\varepsilon} \frac{M}{n} \int_{n \leq k \leq 2n} T_{\frac{1}{\varepsilon}}(\mu(k^{\varepsilon})) |\nabla k^{\varepsilon}|^2$$

$$\leq \lim_{\varepsilon \to 0} \sup_{\varepsilon} M \int_{k \geq n} T_{\frac{1}{\varepsilon}}(\tau^{\varepsilon} : \nabla u^{\varepsilon}) \leq M \int_{k \geq n} \tau : \nabla u$$

and this last integral converges to 0 as $n \to \infty$.

In the third term, we can replace $k^{\varepsilon}$ by $T_{2n}(k^{\varepsilon})$. Hence, this term converges to

$$\int_{\Omega} (B(T_{2n}(k)) \cdot \nabla T_{M}(k)) L_{n}(k)$$

as $\varepsilon \to 0$. When $n$ is sufficiently large, we see from Gauss' formula that this integral vanishes. In a similar way, it can be seen that the fourth and fifth terms also converge to 0.

Finally, notice that, in the right side, $T_{\frac{1}{\varepsilon}}(\tau^{\varepsilon} : \nabla u^{\varepsilon})$ converges strongly in $L^1$ and $T_{M}(k)L_{n}(k^{\varepsilon})$ converges weakly-* in $L^\infty$. For large $n$, this integral converges to

$$\int_{\Omega} (\tau : \nabla u) T_{M}(k).$$

Hence,

$$\int_{\Omega} \mu(k) |\nabla T_{M}(k)|^2 = \int_{\Omega} (\tau : \nabla u) T_{M}(k)$$

and, in view of (20), one has:

$$\lim_{\varepsilon \to 0} \int_{\Omega} T_{\frac{1}{\varepsilon}}(\mu(k^{\varepsilon})) |\nabla T_{M}(k^{\varepsilon})|^2 = \int_{\Omega} \mu(k) |\nabla T_{M}(k)|^2.$$

Obviously, this leads to (19).

It is interesting to remark that, in the instationary analog of (6) the kind of argument used in this step is not valid. One has instead to argue as in [4], in a completely different way.
SIXTH STEP. – $k$ is a renormalized solution to the energy equation.

Let us choose $\varphi \in D(\Omega)$ and $\beta \in W^{1,\infty}(\mathbb{R})$, with support in $[-M, M]$. Using $\beta(k^\varepsilon)\varphi$ as test function in the energy equation in (11), we find the following:

$$
\int_{\Omega} T_1(\mu(k^\varepsilon))\nabla k^\varepsilon \cdot \nabla (\beta(k^\varepsilon)\varphi) + \int_{\Omega} B \left( T_1(k^\varepsilon) \right) \cdot \nabla (\beta(k^\varepsilon)\varphi)
+ \int_{\Omega} (u^\varepsilon \cdot \nabla k^\varepsilon) \beta(k^\varepsilon)\varphi = \int_{\Omega} T_1(\tau^\varepsilon : \nabla u^\varepsilon) \beta(k^\varepsilon)\varphi.
$$

In all these integrals, $k^\varepsilon$ can be replaced by $T_M(k^\varepsilon)$. After writing $\nabla (\beta(k^\varepsilon)\varphi)$ as the sum of $\varphi \nabla \beta(k^\varepsilon) + \beta(k^\varepsilon) \nabla \varphi$, using the fact that $\nabla T_M(k^\varepsilon)$ converges strongly, it is not difficult to take limits as $\varepsilon \to 0$. One obtains:

$$
\int_{\Omega} \mu(k)\nabla k \cdot \nabla (\beta(k)\varphi) + \int_{\Omega} B(k) \cdot \nabla (\beta(k)\varphi)
+ \int_{\Omega} (u \cdot \nabla k) \beta(k)\varphi = \int_{\Omega} (\tau : \nabla u) \beta(k)\varphi.
$$

This shows that $k$ is a solution to the energy equation in (6) in the sense of (8).

4. The proof of Theorem 2

For simplicity, we present the proof in the specific case $N = 3$ but, for $N = 2$, the arguments hold as well. The ingredients of our proof will be the proof of the uniqueness result for the stationary Navier-Stokes equations and the $W^{1,q}$ estimates for the solutions to Poisson equations (see [1]).

Let $\{u_i, k_i, p_i\}$ be, for each $i = 1, 2$, a weak solution to (6) with $k_i \geq 0$. Let us set $u = u_1 - u_2$, $k = k_1 - k_2$ and $p = p_1 - p_2$. We are going to find a positive viscosity $\nu_0$ such that, whenever $\nu \geq \nu_0$, one necessarily has $\{u_1, k_1\} = \{u_2, k_2\}$. This will prove Theorem 2. In the sequel, $C$ is a constant which may depend on $N, \Omega, f, \Phi$ and $\mu_0$, but not on $\nu$.

First, observe that

$$
\|u_i\| \leq \frac{C}{\nu}.
$$

This is a simple consequence of the fact that $\{u_i, k_i, p_i\}$ solves (6). It is also easy to check that

$$
- \nu \Delta u + (u \cdot \nabla)u_1 + (u_2 \cdot \nabla)u + \nabla p = \nabla \cdot (k\Phi'(\nabla u_1)) + \nabla \cdot (k_2\Phi'(\nabla u_1) - \Phi'(\nabla u_2)).
$$

Using $u$ as test function in this equality and recalling that $D \mapsto \Phi'(D)$ is monotone, one sees that

$$
\nu \|u\|^2 \leq - \int_{\Omega} k\Phi'(\nabla u_1) : \nabla u - \int_{\Omega} (u \cdot \nabla)u_1 \cdot u.
$$
In the right side of (23), the first integral can be bounded by $C|k| \cdot \|u\|$, since $\Phi'$ is uniformly bounded. The second one is bounded by $\frac{C}{\nu} \|u\|^2$ in view of (22). Consequently, Theorem 2 will be proved if we are able to prove that, for all large $\nu$, the following holds:

\begin{equation}
|k| \leq C \|u\|.
\end{equation}

Indeed, this would give

$$\nu \|u\|^2 \leq \left( C + \frac{C}{\nu} \right) \|u\|,$$

whence $u = 0$ (and $k = 0$) if $\nu$ is large. In order to prove (24), we first notice that

\begin{equation}
|k| = |\tilde{\mu}^{-1}(v_1) - \tilde{\mu}^{-1}(v_2)| \leq C|v| \leq C\|v\| \leq C\|\nabla v\|_{L^{5/5}}
\end{equation}

Observe that the exponent $\frac{6}{5}$ is optimal in (25). We will use the following lemma, whose proof will be given below:

**Lemma 1.** Under the assumptions of theorem 2, one has:

\begin{equation}
\|\nabla v\|_{L^{5/5}} \leq \left( C + \frac{C}{\nu^{1/2}} \right) \|u\| + \frac{C}{\nu} |k|.
\end{equation}

Obviously, from (25) and (26), we have:

$$\left( 1 - \frac{C}{\nu} \right) |k| \leq \left( C + \frac{C}{\nu^{1/2}} \right) \|u\|.$$

Consequently, (24) holds for all large $\nu$.

**Proof of Lemma 1.** We first notice that, for each $q < N = \frac{3}{2}$, there exists a constant $C_q$ such that

\begin{equation}
\|k_i\|_{W_{\psi, a}^{1, q}} \leq \frac{C_q}{\nu^{1/2}}.
\end{equation}

Indeed, from the energy equation satisfied by $k_i$, we easily deduce

$$|\nabla T_M(k_i)|^2 \leq \frac{CM}{\nu}, \quad \forall M > 0$$

and also

$$\frac{1}{n} \int_{n \leq k_i \leq 2n} |\nabla k_i|^2 \leq \frac{C}{\nu} \quad \forall n \geq 1.$$
Let us set

\[
\begin{align*}
\hat{H} &= -u \cdot \nabla u_1 + \nu \nabla u : (\nabla u_1 + \nabla u_2) + k \Phi'(\nabla u_1) : \nabla u_1 \\
&+ k_2 (\Phi'(\nabla u_1) : \nabla u_1 - \Phi'(\nabla u_2) : \nabla u_2)
\end{align*}
\]

and \( H = \hat{H} - u_2 \cdot \nabla k \). One has \( \hat{H} \in L^1 \subset W^{-1,a} \) for all \( a < \frac{3}{2} \) and \( u_2 \cdot \nabla k = \nabla \cdot (k u_2) \in W^{-1,b} \) for all \( b < 2 \). We have \( -\Delta v = H \) in \( \Omega \). This, the fact that \( v \in \bigcap_{q < \frac{3}{2}} W_0^{1,q} \) and the regularity of \( \partial \Omega \) yield the following for all \( a \in (1, \frac{3}{2}) \):

\[
\|\nabla v\|_{L^a} \leq C(a) \|H\|_{W^{-1,a}}.
\]

(see [1]). Consequently, in view of (22), (27) and the fact that \( D \mapsto \Phi'(D) : D \) is globally Lipschitz-continuous, one finds:

\[
\begin{align*}
\|\nabla v\|_{L^{6/5}} &\leq C\|H\|_{W^{-1,6/5}} \leq C\|\hat{H}\|_{L^1} + \|k u_2\|_{L^{6/5}} \\
&\leq C\|u\|_{L^4} \|\nabla k_1\|_{L^{6/5}} + C\|u\| + C|k_2| \cdot \|u\| + \frac{C}{\nu}|k| \\
&\leq \left( C + \frac{C}{\nu^{1/2}} \right) \|u\| + \frac{C}{\nu}|k|.
\end{align*}
\]

This proves the lemma.

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