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Free vibration analysis of pre-stressed FGM Timoshenko beams under large transverse deflection by a variational method



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ABSTRACT

A theoretical study on free vibration behavior of pre-stressed functionally graded material (FGM) beam is carried out. Power law variation of volume fraction along the thickness direction is considered. Geometric non-linearity is incorporated through von Kármán non-linear strain-displacement relationship. The governing equation for the static problem is obtained using minimum potential energy principle. The dynamic problem for the pre-stressed beam is formulated as an eigenvalue problem using Hamilton's principle. Three classical boundary conditions with immovable ends are considered for the present work, namely clamped-clamped, simply supported-simply supported and clamped-simply supported. Four different FGM beams, namely Stainless Steel–Silicon Nitride, Stainless Steel–Zirconia, Stainless Steel– Alumina and Titanium alloy–Zirconia, are considered for generation of results. Numerical results for nondimensional frequency parameters of undeformed beam are presented. The results are presented in nondimensional pressure-displacement plane for the static problem and in non-dimensional frequencydisplacement plane for the dynamic problem. Comparative frequency-displacement plots are presented for different FGMs and also for different volume fraction indices.

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1. Introduction

Functionally graded materials (FGMs) are inhomogeneous composites that have smooth and continuous variation of material properties in space. In most of the existing and potential future applications, FGM is considered mainly as a mixture of ceramic and metal in varying proportion. With the strength and toughness of metals, and the thermal and wear resistance of ceramics, FGM components possess good qualities of both the metals and ceramics. This makes it suitable for the FGM structures or components to be used in high temperature environment. FGM components are found in various applications, such as in aerospace, nuclear, automotive, civil, biomechanical, optical, electronic, mechanical, chemical and shipbuilding industries [1]. FGM components have applications in astronautic structures, such as rocket launch-pad, space vehicles [2], etc., because rocket launch-pad is subjected to tremendous thermal and mechanical loading, whereas, space vehicles are subjected to extreme thermal conditions. FGMs having excellent thermal and mechanical properties are suitable for such various astronautic

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structures. It is to be mentioned that the present work deals with FGM beams, which are often found in various structures in the fields of aerospace, mechanical, automotive, civil engineering, etc.

FGM beams are mainly designed for applications under thermal environment. But its behavior under mechanical loadings at ambient condition is also important in order to ascertain its performance when thermal loadings are absent. Knowledge of free vibration behavior of pre-stressed FGM beams under mechanical loading is important from design point of view. It is known that the amplitude of forced vibration becomes excessively large when the excitation frequency falls in the vicinity of the natural frequency of vibration of a loaded beam. To avoid such undesirable vibration levels, the natural frequency of vibration of the loaded beam must be known to the designer. Hence the present work is meant to investigate such dynamic behavior of FGM beams. The literature review of some related works by other notable researchers are given in the next few paragraphs.

Ke et al. [3] investigated the nonlinear vibration behavior of FGM beams based on Euler–Bernoulli beam theory and von Kármán geometric nonlinearity. Fallah and Aghdam [4,5] presented large amplitude free vibration analysis of FGM Euler–Bernoulli beams resting on nonlinear elastic foundation subjected to both mechanical and thermal loadings. Fu et al. [6] carried out nonlinear free vibration analysis of piezoelectric FGM beams under thermal environment employing Euler–Bernoulli beam theory. Lai et al. [7] obtained the accurate analytical solutions for large amplitude vibration of thin FGM beams using Euler–Bernoulli beam theory. Based on Euler–Bernoulli beam theory, Yaghoobi and Torabi [8] studied the nonlinear vibration behavior of geometrically imperfect FGM beams resting on nonlinear elastic foundation subjected to axial force. Hemmatnezhad et al. [9] studied the large-amplitude oscillations of FGM Timoshenko beams using finite element formulation. Rahimi et al. [10] performed free vibration analysis of FGM Timoshenko beams in the vicinity of a buckled equilibrium configuration.

Kapuria et al. [11] presented a theoretical finite element model for vibration analysis of layered FGM beams with experimental validation. Aydogdu and Taskin [12] studied free vibration behavior of simply supported FGM beams using different beam theories. Free vibration characteristics of simply supported FGM beams were investigated by Şimşek and Kocatürk [13] using Lagrange's equations under the assumptions of the Euler-Bernoulli beam theory. Thermomechanical vibration analysis of FGM beams resting on variable elastic foundation was carried out by Pradhan and Murmu [14]. Free vibration analysis of FGM beams based on a different first order shear deformation theory was carried out by Sina et al. [15]. Fundamental frequency analysis of FGM beams was carried out by Şimşek [16] using different higher-order beam theories. Giunta et al. [17] addressed free vibration behavior of functionally graded beams via several axiomatic refined theories. Using finite element method, Alshorbagy et al. [18] presented the free vibration characteristics of FGM beams with material graduation axially or transversally through the thickness based on the power law.

Free vibration characteristics of layered functionally graded beams were studied by Wattanasakulpong et al. [19] using Ritz method. Thai and Vo [20] investigated free vibration behavior of FGM beams based on various higher-order beam theories. Free vibration analysis of FGM beams for different boundary conditions was carried out by Pradhan and Chakraverty [21] using Euler–Bernoulli and Timoshenko beam theories. Free vibration behavior of axially loaded rectangular FGM beams was investigated by Nguyen et al. [22] based on the first-order shear deformation beam theory. The dynamic stiffness method was used by Su et al. [23] to investigate the free vibration behavior of FGM beams. Wattanasakulpong and Mao [24] investigated the dynamic response of Timoshenko FGM beams supported by various classical and non-classical boundary conditions.

Esfahani et al. [25] studied free vibration behavior of a thermally pre/post buckled FGM beam resting over a nonlinear hardening elastic foundation. Free vibration behavior of a thermo-electrically post-buckled rectangular FGM piezoelectric beams was studied by Komijani et al. [26]. Thermal buckling analysis of FGM beams with temperature-dependent material properties was carried out by Kiani and Eslami [27,28]. Esfahani et al. [29] carried out non-linear thermal stability analysis of temperature-dependent FGM beams resting on non-linear hardening elastic foundation. Thermo-electrical stability analysis of piezoelectric FGM beams had been carried out by Kiani et al. [30], Kargani et al. [31] and Komijani et al. [32], whereas thermal stability analysis of piezoelectric FGM beams was carried out by Kiani et al. [33].

The present work is based on Timoshenko beam theory, which considers uniform distribution of transverse shear stress across the beam thickness. It is worthwhile to mention some of the research works using higher shear deformation theories (HSDT) developed in the recent years for analysis of plate and beam structures. Tounsi et al. [34] carried out thermo-elastic bending analysis of functionally graded sandwich plates using a refined trigonometric shear deformation theory (RTSDT). The thermo-mechanical bending behavior of FGM plates resting on Winkler–Pasternak elastic foundations was studied by Bouderba et al. [35] using RTSDT. Buckling and free vibration behaviors of exponentially graded sandwich plates were investigated by Ait Amar et al. [36] using simple refined

shear deformation theory. Static and dynamic analyses of FGM and sandwich plates had been carried out by Hebali et al. [37] and Mahi et al. [38] using new hyperbolic shear deformation theory. Using higher-order shear deformation theories, wave propagation analysis in porous FGM plates, and bending and vibration analysis of FGM plates, were carried out by Ait Yahia et al. [39] and Belabed et al. [40] respectively. Recently, Bourada et al. [41] developed a refined trigonometric higher-order beam theory to investigate static and dynamic behaviors of FGM beams. In that work, the authors have included stretching deformation effect along the thickness direction and eliminated the need of shear correction factor. Bousahla et al. [42] presented a new trigonometric higher-order theory for the static analysis of FGM plates employing the physical neutral surface concept. Hamidi et al. [43] presented a sinusoidal plate theory for the thermo-mechanical bending analysis of functionally graded sandwich plates. Bessaim et al. [44] developed a new higherorder shear and normal deformation theory for investigating the bending and free vibration behavior of sandwich plates with functionally graded isotropic face sheets. Thermo-elastic bending analysis of functionally graded sandwich plates was carried out by Bouchafa et al. [45] using a refined hyperbolic shear deformation theory. Houari et al. [46], using a new higher-order shear and normal deformation theory, simulated the thermo-elastic bending of FGM sandwich plates.

From the literature review presented, it is clear that an exhaustive study on free vibration behavior of transversely loaded beam for different FGM materials and different classical boundary conditions is scarce. Most of the published works are involved with either free vibration behavior of undeformed FGM beam or large amplitude free vibration behavior of FGM beam. Hence, in the present work, free vibration frequencies of FGM beam are computed for different pre-stressed configurations under uniform transverse pressure. Pre-stressed configurations are obtained through a geometrically non-linear static analysis. The linear vibration frequency of the pre-stressed beam, hereafter termed as loaded natural frequency, is then computed through an eigenvalue problem that includes the effect of pre-stressing using the displacement fields of the static problem. The effect of geometric non-linearity is included using von Kármán non-linear strain-displacement relationship. Timoshenko beam theory is used to consider the effects of shear deformation for the static problem and of rotary inertia for the subsequent dynamic problem. Suitable energybased variational principles are used to derive the governing equations for both parts of the problem. Four different functionally graded materials and three different immovable classical boundary conditions are considered to show the pre-stressed dynamic behavior of beams.

2. Mathematical formulation

The present work aims at finding loaded natural frequency of pre-stressed FGM Timoshenko beam. A uniform rectangular beam with length L, height h and width b is considered. A beam with symbolic dimensions is shown in Fig. 1, where, x, y and z denote the coordinate axes along the length, width and thickness directions respectively. As mentioned earlier, two distinct but interrelated problems are formulated and solved to obtain the desired solution. The purpose of the first one, the static problem, is to obtain the pre-stressed configuration of the beam under the application of uniform transverse pressure. And the second problem, named as the dynamic problem, is utilized to obtain the loaded natural frequency of the deformed beam. It must be mentioned that the static configurations for different loadings are obtained through a geometrically non-linear analysis to address the large deflection effect.



Fig. 1. Beam with dimensions and coordinate axes.

2.1. Modeling of FGM beam

The present work considers continuous variation of graded material properties across the beam thickness. A continuous variation of volume fraction of ceramic (V_c) and metal (V_m) constituents across the thickness is assumed in accordance with the power-law given by $V_c = (\frac{r}{h} + \frac{1}{2})^k$ and $V_m = 1 - V_c$ respectively [47]. Here, k ($0 \le k \le \infty$) is the volume fraction index. Hence the effective material property P_f of any FGM layer is determined using the Voigt model, which is given by $P_f = P_c V_c + P_m V_m$, where P_c and P_m are the material properties of the ceramic and metal constituents respectively. So any effective material property at any layer z is given by $P_f(z) = P_m + (P_c - P_m)(\frac{r}{h} + \frac{1}{2})^k$. For the present FGM beam model, the top layer (z = +h/2) is purely ceramic and the bottom layer (z = -h/2) is purely metal. It is to be mentioned that the subscripts m and c refer to the metal and ceramic constituents respectively.

Any material property of the individual constituent is temperaturedependent and such temperature dependence is considered using the relationship P_c or, $P_m = P_0[P_{-1}T^{-1} + 1 + P_1T + P_2T^2 + P_3T^3]$, where T is the temperature in K and P_0 , P_{-1} , P_1 , P_2 and P_3 are the coefficients of temperature. The relevant effective material properties for the present problem are elastic modulus E_f , shear modulus G_f , Poisson's ratio v_f and density ρ_f . The temperature coefficients [47] of the material properties for the ceramic or metal constituents considered are given in Table 1. For the present problem, the beam is assumed to be at ambient temperature $T_0 = 300$ K, which is also considered to be the temperature at which thermal stress is zero. Hence all the required material properties are calculated at T_0 .

2.2. Static problem

The governing equation of the static problem is obtained using the minimum potential energy principle [48] given by,

Table	1
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Temperature coefficients of FGM constituents
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$$\delta(U+V) = 0 \tag{1}$$

where *U* is the strain energy developed due to external loadings, *V* is the potential energy of the external loadings, and δ is the variational operator. The strain energy *U* consists of two parts, i.e., $U = U_{ax} + U_{sh}$, where U_{ax} and U_{sh} are the strain energies due to axial strain and shear strain respectively. Using the proportionality of stress and strain (i.e., linear elastic material), and using suitable strain–displacement relationships, the strain energies can be expressed in terms of the displacement fields. The three displacement fields considered for the present problem are the following: *u*, the in-plane displacement field of beam cross section due to bending. Here *u*, *w* and ψ are defined at the mid-plane of the beam and are functions of the axial coordinate *x*.

The expressions of axial strain and shear strain are given by,

$$\varepsilon_{ax} = \frac{1}{2} \left(\frac{dw}{dx}\right)^2 + \frac{du}{dx} - Z \frac{d\psi}{dx}$$
(2)

and

$$\varepsilon_{sh} = \frac{1}{2} \left(\frac{\mathrm{d}w}{\mathrm{d}x} - \psi \right) \tag{3}$$

It is to be mentioned that the first term of Eq. (2) is von Kármán type non-linear strain-displacement relationship. Hence the strain energies U_{ax} and U_{sh} are given by,

$$U_{ax} = \frac{1}{2} \int_{0}^{L} \left\{ \frac{A_{ax}}{4} \left(\frac{dw}{dx} \right)^{4} + A_{ax} \left(\frac{du}{dx} \right)^{2} + C_{ax} \left(\frac{d\psi}{dx} \right)^{2} + A_{ax} \left(\frac{dw}{dx} \right)^{2} \frac{du}{dx} - B_{ax} \left(\frac{dw}{dx} \right)^{2} \frac{d\psi}{dx} - 2B_{ax} \frac{du}{dx} \frac{d\psi}{dx} \right\} dx$$

$$(4)$$

and

$$U_{sh} = \frac{k_{sh}}{2} \int_{0}^{L} \left\{ A_{sh} \left(\frac{dw}{dx} \right)^2 - 2A_{sh} \frac{dw}{dx} \psi + A_{sh} \psi^2 \right\} dx$$
(5)

The stiffness coefficients used in Eqs. (4) and (5) are given below:

$$(A_{ax}, B_{ax}, C_{ax}) = b \int_{\frac{h}{2}}^{+\frac{n}{2}} E_f(1, z, z^2) dz$$
 and $A_{sh} = b \int_{\frac{h}{2}}^{+\frac{n}{2}} G_f dz$. In Eq. (5), k_{sh}

is the shear correction factor, which is taken to be 5/6 for rectangular cross section. It is to be mentioned that the shear modulus G_f is given by, $G_f = \frac{E_f}{2(1+r)}$.

Constituent material	Property	P_0	P_{-1}	P_1	P_2	P_3
SUS304	E (Pa)	201.04×10^{9}	0	3.079×10^{-4}	-6.534×10^{-7}	0
	υ	0.3262	0	-2.002×10^{-4}	3.797×10^{-7}	0
	ρ (kg m ⁻³)	8166	0	0	0	0
Ti-6Al-4V	E (Pa)	122.56×10^{9}	0	$-4.586 imes 10^{-4}$	0	0
	υ	0.2884	0	1.121×10^{-4}	0	0
	ρ (kg m ⁻³)	4429	0	0	0	0
Si ₃ N ₄	E (Pa)	348.43×10^{9}	0	-3.070×10^{-4}	2.160×10^{-7}	-8.946×10^{-11}
	υ	0.2400	0	0	0	0
	ρ (kg m ⁻³)	2370	0	0	0	0
ZrO ₂	E (Pa)	244.27×10^{9}	0	-1.371×10^{-3}	1.214×10^{-6}	-3.681×10^{-10}
	υ	0.2882	0	1.133×10^{-4}	0	0
	ρ (kg m ⁻³)	3000	0	0	0	0
Al ₂ O ₃	E (Pa)	349.55×10^{9}	0	$-3.853 imes 10^{-4}$	4.027×10^{-7}	$-1.673 imes 10^{-10}$
	υ	0.2600	0	0	0	0
	ho (kg m ⁻³)	3750	0	0	0	0

1006 Table 2

List of lowest order admissible functions for the displacement fields.

Displacement field	Boundary	Conditions	Function
w	СС	$w _{x=0} = 0, w _{x=L} = 0$	$\phi_1 = (x/L) \{ 1 - (x/L) \}$
	SS		
	CS		
и	CC	$u _{x=0} = 0, u _{x=L} = 0$	$\alpha_1 = (x/L)\{1 - (x/L)\}$
	SS		
	CS		
Ψ	CC	$\psi _{x=0} = 0, \psi _{x=L} = 0$	$\beta_1 = \sin(\pi x/L)$
	SS	$\psi _{x=0} \neq 0, \psi _{x=L} \neq 0$	$\beta_1 = \cos(\pi x/L)$
	CS	$\psi\big _{x=0}=0,\psi\big _{x=L}\neq 0$	$\beta_1 = \sin(\pi x/(2L))$

The potential energy of the applied uniform transverse pressure p is given by,

$$V = -\int_{0}^{L} pwdx \tag{6}$$

where p is defined as the force per unit length of the beam.

Following Ritz method, the displacement fields are approximated as finite linear combinations of admissible functions and unknown coefficients given as,

$$w = \sum_{i=1}^{nw} d_i \phi_i, \quad u = \sum_{i=1}^{nu} d_{nw+i} \alpha_i, \quad \psi = \sum_{i=1}^{nsi} d_{nw+nu+i} \beta_i$$
(7)

Here, ϕ_i , α_i and β_i are set of orthogonal admissible functions for the displacement fields w, u and ψ respectively; and nw, nu and *nsi* are the number of functions used to approximate w, u and ψ respectively. It is to be noted that d_i is the set of unknown coefficients, which are to be determined from the governing equations. The admissible functions satisfy the boundary conditions of the beam. The lowest order functions for each of the displacement fields are selected suitably and the corresponding higher-order functions are developed numerically following Gram-Schmidt orthogonalization scheme. Three boundary conditions with immovable ends are considered for the present work. And these are clamped-clamped (CC), simply supported-simply supported (SS) and clamped-simply supported (CS). The selected lowest order admissible functions for each of the displacement fields are given in Table 2 for all the three boundary conditions considered.

Using the expression of various potential energies, given by Eqs. (4), (5) and (6) into Eq. (1) and using the approximate displacement fields, given by Eq. (7), the governing algebraic equations are obtained in the form given below:

$$[\mathbf{K}_{ij}]\{\mathbf{d}_{j}\} = \{\mathbf{f}_{i}\} \tag{8}$$

where $[\mathbf{K}_{ii}]$ and $\{\mathbf{f}_i\}$ are the stiffness matrix and load vector, respectively, each of dimension nu + nw + nsi. The elements of $[\mathbf{K}_{ij}]$ and $\{\mathbf{f}_i\}$ are given in the Appendix. It can be seen that the set of governing equations is non-linear in nature as the stiffness matrix is a function of the unknown coefficients. To solve this set of nonlinear equations, a multi-dimensional secant method known as Broyden's method [49,50] is used. The solution of Eq. (8) gives the statically deflected configuration of a pre-stressed beam. The next stage of the problem is now to determine the loaded natural frequency of the pre-stressed beam and its mathematical formulation is discussed in the next section.

2.3. Dynamic problem

The governing equation of the dynamic problem is derived using Hamilton's principle [48] given by,

$$\delta\left(\int_{t_1}^{t_2} (T_k - U - V) dt\right) = 0 \tag{9}$$

where T_k is the kinetic energy of the vibrating beam and t is the time. The present work is a free vibration problem of a prestressed beam, in which the pre-stressed configuration is already obtained in the previous step of static problem. Hence the potential energy V of the external loadings is zero in this case. Taking ρ_f as the effective density of any FGM layer, the expression of T_k is as follows:

$$T_k = \frac{1}{2} \int_0^L \left\{ D\left(\frac{\mathrm{d}w}{\mathrm{d}t}\right)^2 + D\left(\frac{\mathrm{d}u}{\mathrm{d}t}\right)^2 + F\left(\frac{\mathrm{d}\psi}{\mathrm{d}t}\right)^2 \right\} \mathrm{d}x \tag{10}$$

where the inertia coefficients D and F are given by

 $(D,F) = b \int_{h}^{+\frac{h}{2}} \rho_f(1,z^2) dz$. The expression of U remains the same as

given for the static problem.

The approximate dynamic displacement fields, which are assumed to be separable in space and time, are given by,

$$w(x,t) = \sum_{i=1}^{nw} d_i \phi_i(x) e^{i\omega t},$$

$$u(x,t) = \sum_{i=1}^{nu} d_{nw+i} \alpha_i(x) e^{i\omega t},$$

$$\psi(x,t) = \sum_{i=1}^{nsi} d_{nw+nu+i} \beta_i(x) e^{i\omega t},$$

(11)

where $i = \sqrt{-1}$ and d_i are a new set of unknown parameters for the dynamic problem. The complete set of the space part of the dynamic displacements, i.e., ϕ_i , α_i and β_i , is the same as taken for the static problem. In Eq. (11), ω denotes the natural frequency of vibration of the beam.

Using the expressions of strain energy (Eqs. (4) and (5)), kinetic energy (Eq. (10)) and dynamic displacements (Eq. (11)), the governing equation is obtained as follows:

$$[\mathbf{K}_{ij}]\{\mathbf{d}_{j}\} - \omega^{2}[\mathbf{M}_{ij}]\{\mathbf{d}_{j}\} = 0$$
(12)

where $[\mathbf{K}_{ij}]$ and $[\mathbf{M}_{ij}]$ are the stiffness matrix and mass matrix respectively. The elements of $[\mathbf{K}_{ij}]$ are the same as given in the Appendix and the elements of $[\mathbf{M}_{ii}]$ are given below:

$$[\mathbf{M}_{ij}]_{j=1,nw}^{l=1,nw} = D_0^L \phi_i \phi_j d\mathbf{x},$$

$$[\mathbf{M}_{ij}]_{j=nw+1,nw+nu}^{l=nw+1,nw+nu} = D_0^L \alpha_{i-nw} \alpha_{j-nw} d\mathbf{x},$$

$$[\mathbf{M}_{ij}]_{j=nw+nu+1,nw+nu+nsi}^{l=nw+nu+1,nw+nu+nsi} = F_0^L \beta_{i-nw-nu} \beta_{j-nw-nu} d\mathbf{x}.$$

$$(13)$$

The off-diagonal elements of $[\mathbf{M}_{ii}]$ are zero. Eq. (12) is an eigenvalue problem, in which the square root of the eigenvalues gives the natural frequency of vibration of various vibration modes and $\{\mathbf{d}_i\}$ is the corresponding eigen vectors used to obtain the vibration mode shapes. It must be noted that the stiffness matrix given in Eq. (12) is non-linear in nature. But as the dynamic problem is to be formulated at the pre-stressed beam configuration, the non-linear terms of the stiffness matrix are updated with the pre-stressed beam displacement fields obtained from the static problem [51]. Hence the solution of Eq. (12) gives the linear loaded natural frequency of vibration of the pre-stressed beam.

Table 3							
Material	properties	of th	e FGM	constituents	at	300	K

Material property	SUS304	Ti-6Al-4V	Si_3N_4	ZrO ₂	Al_2O_3
E (GPa)	207.79	105.70	322.27	168.06	320.24
υ	0.318	0.298	0.240	0.298	0.260
ho (kg m ⁻³)	8166	4429	2370	3000	3750

3. Results and discussion

The present work is carried out to determine the natural frequency of the first mode of vibration of pre-stressed FGM beams. It is to be mentioned that the frequency determined is of small amplitude vibration of pre-stressed beam. So the dynamic behavior is presented graphically in non-dimensional $\lambda - w^*$ plane, where λ is the non-dimensional loaded natural frequency of first vibration mode and w^* is the normalized maximum transverse deflection of pre-stressed beam. Hence such plots present the dynamic behavior in terms of loaded natural frequency of vibration as a function of maximum beam deflection. On the other hand, the static equilibrium path of the beam is presented graphically in $\overline{p} - w^*$ plane, where \overline{p} is the non-dimensional uniform transverse pressure. The non-dimensional parameters are defined as: $\bar{p} = p \left(\frac{L}{h}\right)^4 / (E_m b)$, $w^* = w/h$, and $\lambda = \omega L^2 \sqrt{(\rho_m A)/(E_m I)}$, where E_m is the elastic modulus of metal constituent, w is the maximum transverse deflection, ρ_m is the density of metal constituent, A(=bh) is the cross sectional area, and $I(=bh^3/12)$ is the area moment of inertia of the beam cross section about the centroidal axis. The results are generated for b = 0.02 m and h = 0.01 m.

Table 4

Comparison of non-dimensional frequency parameters.

3.1. Validation study

The non-dimensional frequency parameter $\sqrt{\lambda}$ of undeformed FGM beam is compared with the results of Ref. [9] for different volume fraction indices and also for different boundary conditions. The comparison is made for Steel–Alumina FGM beam for a length-thickness ratio L/h = 20. The material properties used for comparison purpose are as follows: $E_m = 210$ GPa, $E_c = 390$ GPa, $v_m = 0.29$, $v_c = 0.22$, $\rho_m = 7800$ kg m⁻³, and $\rho_c = 3960$ kg m⁻³. The comparison is presented in Table 4. The comparison shows good agreement of the present results with Ref. [9]. This validates the free vibration dynamic behavior of undeformed FGM beam analyzed by the present method.

The validation plots of pre-stressed Stainless Steel–Zirconia (FGM 2) beam are presented in Fig. 2(a–b) for k = 2.0. Fig. 2(a) presents the static equilibrium path in $\overline{p} - w^*$ plane, whereas Fig. 2(b) presents the pre-stressed free vibration behavior in $\lambda - w^*$ plane. The validation is carried out with finite element package ANSYS (version 10.0). The comparison plots are presented for CC, SS and CS

Boundary condition		Non-dimens	Non-dimensional frequency parameter, $\sqrt{\lambda}$						
		k = 0	<i>k</i> = 0.1	<i>k</i> = 0.2	<i>k</i> = 0.5	k = 1	<i>k</i> = 2	<i>k</i> = 5	
CC	Present	6.4864	6.2664	6.0896	5.7504	5.4617	5.2340	5.0333	
	Ref. [9].	6.4971	6.2737	6.1001	5.7575	5.4713	5.2413	5.0390	
SS	Present	4.3311	4.1980	4.0653	3.8402	3.6652	3.5203	3.3863	
	Ref. [9].	4.3371	4.1889	4.0753	3.8554	3.6742	3.5244	3.3803	
CS	Present	5.4099	5.2240	5.0820	4.8056	4.5385	4.3759	4.2091	
	Ref. [9].	5.4086	5.2228	5.0786	4.7951	4.5590	4.3688	4.1990	



Fig. 2. Validation plots of pre-stressed beam: (a) static behavior and (b) free vibration behavior.

k	L/h = 10				<i>L/h</i> = 25			
	FGM 1	FGM 2	FGM 3	FGM 4	FGM 1	FGM 2	FGM 3	FGM 4
0.0	48.595	31.128	38.477	32.142	51.212	32.872	40.537	33.943
0.1	43.041	29.308	35.828	30.774	45.334	30.915	37.723	32.470
0.2	39.411	28.051	33.864	29.715	41.448	29.597	35.751	31.378
0.5	33.475	25.815	30.290	27.617	35.312	27.260	31.870	29.106
1.0	29.326	24.070	27.502	25.862	30.803	25.413	28.969	27.268
2.0	26.288	22.657	25.320	24.425	27.742	23.896	26.728	25.802
5.0	23.853	21.563	23.445	23.102	25.246	22.712	24.771	24.430
10.0	22.697	21.198	22.499	22.358	24.001	22.348	23.799	23.581
20.0	21.953	21.052	21.847	21.802	23.204	22.190	23.099	23.055
50.0	21.390	20.984	21.350	21.350	22.579	22.135	22.552	22.547

Table 5 List of non-dimensional frequency parameters λ for CC beam.

boundary conditions. The comparative plots in Fig. 2 show very good agreement of the present method with ANSYS for both the static and dynamic behaviors. The finite element model in ANSYS is created using BEAM 188 element, and the results are generated with 30 elements. It must be noted that a layered variation of material properties is used to create the finite element model in ANSYS.

3.2. Natural frequency of vibration of undeformed FGM beam

The non-dimensional frequency parameter λ of undeformed CC beam for all the four functionally graded materials considered is presented in Table 5 for different volume fraction indices. The list presented in Table 5 includes results for L/h = 10 and L/h = 25. Similar lists for SS and CS FGM beams are presented in Tables 6 and 7 re-



Fig. 3. Non-dimensional pressure-deflection behavior for different volume fraction indices of CC beams: (a) FGM 1, (b) FGM 2, (c) FGM 3 and (d) FGM 4.



Fig. 4. Non-dimensional frequency-deflection behavior of different CC FGM beams: (a) k = 0.0, (b) k = 0.2, (c) k = 0.5, (d) k = 5.0, (e) k = 20.0 and (f) k = 50.0.

spectively. As seen from these tables, the non-dimensional frequency parameter λ decreases with increase in values of k, and this is true for all the four FGMs considered. Only exception to this occurs for FGM 2 with L/h = 25, where λ increases from k = 20 to k = 50. It is

to be mentioned that higher k values indicate more metal content in the beam. It is also seen that the non-dimensional frequency parameter increases with L/h ratio but the change is very little. The effect of L/h ratio on non-dimensional frequency of vibration remains

k	<i>L/h</i> = 10				<i>L/h</i> = 25			
	FGM 1	FGM 2	FGM 3	FGM 4	FGM 1	FGM 2	FGM 3	FGM 4
0.0	22.457	14.410	17.789	14.880	22.393	14.596	17.804	15.072
0.1	19.873	13.573	16.532	14.234	20.200	13.920	16.718	14.514
0.2	18.208	12.998	15.637	13.759	18.303	13.270	15.796	14.043
0.5	15.522	11.969	14.046	12.829	15.692	12.186	14.249	12.915
1.0	13.635	11.159	12.794	12.048	13.772	11.279	12.989	12.230
2.0	12.243	10.500	11.803	11.399	12.250	10.472	12.031	11.613
5.0	11.098	9.999	10.909	10.746	11.234	10.140	11.133	10.924
10.0	10.566	9.819	10.461	10.401	10.561	9.986	10.586	10.497
20.0	10.168	9.747	10.147	10.119	10.258	9.811	10.310	10.286
50.0	9.934	9.704	9.886	9.889	10.042	9.873	10.152	9.953

Table 6 List of non-dimensional frequency parameters λ for SS beam.

insignificant for pre-stressed beam also. Hence the results, as presented in the following section, for pre-stressed FGM beams are generated for L/h = 25.

3.3. Effect of material and volume fraction index on static and dynamic behavior

The static deflection behavior of CC beam in $\overline{p} - w^*$ plane is presented in Fig. 3(a–d) for FGM 1, FGM 2, FGM 3 and FGM 4

respectively. In each of these figures, the static equilibrium path is presented for a set of volume fraction indices, i.e., for k = 0.0, 0.1, 0.2, 0.5, 1.0, 2.0, 5.0, 10.0, 20.0, 50.0. The plots are useful in finding the non-dimensional pressure value corresponding to a static deflection level, at which the loaded natural frequency is found out. As seen from Fig. 3, the beam exhibits non-linear hardening type load-deflection behavior. This is due to stiffening effect induced in the beam as a result of generation of tensile membrane forces due to immovable ends. With increase in k, i.e., the increase in metal



Fig. 5. Non-dimensional frequency-deflection behavior of CC beams for different volume fraction indices: (a) FGM 1, (b) FGM 2, (c) FGM 3 and (d) FGM 4.

Table 7			
List of non-dimensional	frequency parameters	λ	for CS beam

k L/h = 10					<i>L/h</i> = 25				
	FGM 1	FGM 2	FGM 3	FGM 4	FGM 1	FGM 2	FGM 3	FGM 4	
0.0	34.326	22.013	27.203	22.730	35.330	22.785	28.021	23.527	
0.1	30.411	20.740	25.306	21.783	31.326	21.558	25.969	22.512	
0.2	27.831	19.853	23.940	21.017	29.007	20.403	24.488	21.737	
0.5	23.681	18.276	21.416	19.527	24.481	18.867	22.181	19.990	
1.0	20.728	17.036	19.472	18.310	21.457	17.507	20.152	18.861	
2.0	18.622	16.034	17.934	17.298	19.166	16.534	18.662	18.033	
5.0	16.889	15.252	16.615	19.373	17.299	15.773	17.022	17.098	
10.0	16.094	14.998	15.934	15.845	16.395	15.463	16.504	16.321	
20.0	15.553	14.899	15.482	15.444	19.120	15.330	16.050	16.026	
50.0	15.146	14.842	15.113	15.112	15.649	15.321	15.572	15.662	

content, FGM 1, FGM 3 and FGM 4 beam shows decreased stiffness levels as the elastic modulus of ceramic constituent is greater than its metal counterpart, as can be seen from Table 3. The trend is completely reverse for FGM 2 beam as the elastic modulus of its ceramic constituent is lesser than that of its metal part.

The loaded natural frequency versus maximum transverse deflection plots in non-dimensional $\lambda - w^*$ plane is presented in Fig. 4(a-f) for k = 0.0, 0.2, 0.5, 5.0, 20.0 and 50.0, respectively, for CC FGM beam. In each of the figures, free vibration behavior is shown for FGM 1, FGM 2, FGM 3 and FGM 4 beams. In accordance with the static behavior, the loaded natural frequency is shown to be increasing with increased deflection level as a result of enhanced stiffening effect. With regard to the comparative behavior among different FGMs considered, FGM 1 shows highest frequency of vibration with FGM 3, FGM 4 and FGM 2 coming next in order of exhibiting decreasing vibration frequency at any common



Fig. 6. Non-dimensional pressure-deflection behavior for different volume fraction indices of SS beam: (a) FGM 1, (b) FGM 2, (c) FGM 3 and (d) FGM 4.



Fig. 7. Non-dimensional frequency-deflection behavior of different SS FGM beams: (a) k = 0.0, (b) k = 0.2, (c) k = 0.5, (d) k = 5.0, (e) k = 20.0 and (f) k = 50.0.

deflection levels. This is true irrespective of the values of the volume fraction index. It is also seen that the relative differences in frequencydeflection behavior of various FGMs diminish with increase in k values. At higher k values, the dynamic behavior becomes almost identical for all the FGMs considered. It is also important to study the dynamic behavior of prestressed FGM beam for different volume fraction indices. Fig. 5(a-d) shows such non-dimensional frequency-deflection plots for FGM 1. FGM 2, FGM 3 and FGM 4, respectively, each showed comparative behavior for k = 0.0, 0.1, 1.0, 10.0, 50.0. It can be seen that the loaded



Fig. 8. Non-dimensional frequency-deflection behavior of SS beams for different volume fraction indices: (a) FGM 1, (b) FGM 2, (c) FGM 3 and (d) FGM 4.

natural frequency decreases with increase in k values for any particular deflection level. This is true for all the FGMs considered. The explanation for the variation of loaded natural frequency with kcannot be given by seeing only the static deflection behavior as shown in Fig. 3. Because in predicting the dynamic behavior, both the relative density values and the relative elastic modulus values of the constituents are to be considered.

The non-dimensional static deflection behavior for different volume fraction indices is presented in Fig. 6(a-d) for SS beams each for different functionally graded materials. Also the non-dimensional frequency-deflection plots of SS beams are shown in Fig. 7(a-f) for different k values and in Fig. 8(a-d) for different FGMs. As for CS beams, static deflection behavior is presented in Fig. 9(a-d), whereas the dynamic behavior in terms of frequency-deflection plots is shown in Fig. 10(a–f) for different k values and in Fig. 11(a–d) for different FGMs. For both these boundary conditions, the nature of static and dynamic behavior is similar in nature as described for CC beams. The relative behavior for these three different boundary conditions, although not shown in a single plot, differs obviously due to the stiffness effects contributed from the support conditions. Because it is known that CC beam exhibits the highest transverse stiffness, with CS and SS beam being next in order of decreasing stiffness levels.

4. Conclusions

An energy based mathematical model is presented to study the free vibration behavior of pre-stressed FGM Timoshenko beams. The entire work is carried out in solving two different but interrelated problems, namely the static problem and the dynamic problem. The static problem is used to determine the pre-stressed configuration of FGM beam under uniform transverse pressure. And the dynamic problem, formulated as an eigenvalue problem, is used to determine the loaded natural frequency of the pre-stressed beam. Four different FGMs, namely Stainless Steel-Silicon Nitride, Stainless Steel-Zirconia, Stainless Steel-Alumina and Titanium alloy-Zirconia, are used to generate results for different volume fraction indices. Numerical results for non-dimensional frequency parameters of undeformed beam are presented for different functionally graded materials with CC, SS and CS boundary conditions. Effects of material as well as the volume fraction index on non-dimensional frequency-deflection behavior of pre-stressed beams are studied. The results are presented for three boundary conditions, i.e., CC, SS and CS. Static equilibrium paths in non-dimensional plane are also presented in order to relate the applied pressure with loaded natural frequency through the static deflection level. The results can serve as benchmarks for further study in this field.



Fig. 9. Non-dimensional pressure-deflection behavior for different volume fraction indices of CS beam: (a) FGM 1, (b) FGM 2, (c) FGM 3 and (d) FGM 4.

Appendix

Elements of stiffness matrix and load vector

$$\begin{split} \left[\mathbf{k}_{ij}\right]_{\substack{j=1,mw}{j=1,nw}} &= \frac{A_{ax}}{2} \int_{0}^{L} \left(\sum_{k=1}^{mw} d_{k} \frac{d\phi_{k}}{dx}\right)^{2} \frac{d\phi_{i}}{dx} \frac{d\phi_{j}}{dx} dx + A_{ax} \int_{0}^{L} \left(\sum_{k=nw+1}^{nw+nu} d_{k} \frac{d\phi_{k}}{dx}\right) \frac{d\phi_{i}}{dx} \frac{d\phi_{j}}{dx} dx - B_{ax} \int_{0}^{L} \left(\sum_{k=nw+nu+1}^{nw+nu+nu} d_{k} \frac{d\beta_{k-nw-nu}}{dx}\right) \frac{d\phi_{i}}{dx} \frac{d\phi_{j}}{dx} dx \\ &+ k_{sh} A_{sh} \int_{0}^{L} \frac{d\phi_{i}}{dx} \frac{d\phi_{j}}{dx} dx, \cdots \left[\mathbf{k}_{ij}\right]_{\substack{j=1,mw}{j=nw+1,nw+nu}} = 0, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=1,mw}{j=nw+nu+1,nw+nu+nsi}} &= -k_{sh} A_{sh} \int_{0}^{L} \frac{d\phi_{i}}{dx} \beta_{j-nw-nu} dx, \quad \left[\mathbf{k}_{ij}\right]_{\substack{j=1,mw}{j=nw+1,nw+nu}} = \frac{A_{ax}}{2} \int_{0}^{L} \left(\sum_{k=1}^{mw} d_{k} \frac{d\phi_{k}}{dx}\right) \frac{d\phi_{i}}{dx} \frac{d\phi_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+1,nw+nu}{j=nw+nu+1,nw+nu}} = A_{ax} \int_{0}^{L} \frac{d\alpha_{i-nw}}{dx} \frac{d\alpha_{j-nw}}{dx} dx, \quad \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+1,nw+nu}{j=nw+nu+nu+nu+nu+nu}} = -B_{ax} \int_{0}^{L} \frac{d\alpha_{i-nw}}{dx} \frac{d\beta_{j-nw-nu}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{j=nw+nu}} = -\frac{B_{ax}}{2} \int_{0}^{L} \left(\sum_{k=1}^{mw} d_{k} \frac{d\phi_{k}}{dx}\right) \frac{d\beta_{i-nw-nu}}{dx} \frac{d\phi_{j}}{dx} dx - k_{sh} A_{sh} \int_{0}^{L} \beta_{i-nw-nu} \frac{d\phi_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{j=nw+nu}} = -B_{ax} \int_{0}^{L} \frac{d\beta_{i-nw-nu}}{dx} \frac{d\alpha_{j-nw}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{nu}} = -B_{ax} \int_{0}^{L} \frac{d\beta_{i-nw-nu}}{dx} \frac{d\phi_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{nu}} \frac{d\alpha_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{nu}} = -B_{ax} \int_{0}^{L} \frac{d\beta_{i-nw-nu}}{dx} \frac{d\alpha_{j-nw}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{nu}} \frac{d\alpha_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{nu}} \frac{d\alpha_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{nu}} \frac{d\alpha_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+1,nw+nu}{nu}} \frac{d\alpha_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu+nu+nu}{nw}} \frac{d\alpha_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j=nw+nu}{nw}} \frac{d\alpha_{j}}{dx} dx, \\ \left[\mathbf{k}_{ij}\right]_{\substack{j$$



Fig. 10. Non-dimensional frequency-deflection behavior of different CS FGM beams: (a) k = 0.0, (b) k = 0.2, (c) k = 0.5, (d) k = 5.0, (e) k = 20.0 and (f) k = 50.0.

$$[\mathbf{k}_{ij}]_{\substack{j=nw+nu+1,nw+nu+nsi\\j=nw+nu+1,nw+nu+nsi}} = C_{ax} \int_{0}^{L} \frac{\mathrm{d}\beta_{j-nw-nu}}{\mathrm{d}x} \frac{\mathrm{d}\beta_{i-nw-nu}}{\mathrm{d}x} \mathrm{d}x + k_{sh}A_{sh} \int_{0}^{L} \beta_{j-nw-nu}\beta_{i-nw-nu} \mathrm{d}x.$$

$$\{\mathbf{f}_i\}_{i=1,nw} = p \int_0^L \phi_i dx, \quad \{\mathbf{f}_i\}_{i=nw+1,nw+nu} = 0, \quad \{\mathbf{f}_i\}_{i=nw+nu+1,nw+nu+nsi} = 0.$$



Fig. 11. Non-dimensional frequency-deflection behavior of CS beams for different volume fraction indices: (a) FGM 1, (b) FGM 2, (c) FGM 3 and (d) FGM 4.

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