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A Kaehler structure on the nonzero tangent bundle of a space form*

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Abstract: We obtain a Kaehler structure on the bundle of nonzero tangent vectors to a Riemannian manifold of constant positive sectional curvature. This Kaehler structure is determined by a Lagrangian depending on the density energy only.

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Introduction

It is well known (see [2, 9, 15]) that the tangent bundle TM of a Riemannian manifold (M, g) has a structure of almost Kaehlerian manifold with an almost complex structure determined by the isomorphic vertical and horizontal distributions VTM, HTM on TM (the last one being determined by the Levi-Civita connection on M) and the Sasaki metric on TM (see also [14, 16]). However, this structure is Kaehler only in the case where the base manifold is locally Euclidean. On the other hand, Calabi (see [1]) defined a new Riemannian metric on the cotangent bundle of a Kaehler manifold, by using a special Lagrangian defined by a smooth real valued function depending on the density energy only and has obtained a new almost complex structure, which together with the original one determines a structure of hyper-Kaehler manifold on the cotangent bundle of a Kaehler manifold of holomorphic constant positive sectional curvature.

In the present paper we have been inspired by the idea of Calabi to consider a regular Lagrangian on a Riemannian manifold (M, g) defined by a smooth function L depending on the energy density only. An interesting result is that the usual nonlinear connection determined by the Euler–Lagrange equations associated to L (see [4, 10, 11]) does coincide with the nonlinear connection defined by the Levi-Civita connection of g , thus the horizontal distribution HTM used in this paper is the standard one. Then we have obtained a Riemannian metric G on the tangent bundle TM such that the vertical and horizontal distributions VTM, HTM are

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orthogonal to each other but they are no longer isometric. Then we have considered an almost complex structure J on TM related to the above Riemannian metric G such that (TM, J, G) is an almost Kaehlerian manifold (Theorem 2). From the integrability conditions of the almost complex structure J we have obtained our main result: If (M, g) has positive constant sectional curvature then we may obtain a certain smooth function L on the subset T_0M of the nonzero tangent vectors to M such that the structure (T_0M, J, G) is Kaehlerian (Theorem 3). Next we have obtained the Levi-Civita connection $\tilde{\nabla}$ of G and its curvature tensor field showing that the Kaehlerian manifold (T_0M, J, G) cannot be an Einstein manifold and cannot have constant holomorphic sectional curvature (see [2, 6, 9, 15], for the expression of the Levi-Civita connection of the Sasaki metric and that of its curvature tensor field). Next, the covariant derivative of the curvature tensor field K with respect to the Levi-Civita connection $\tilde{\nabla}$ of G is studied and we obtain that the components of the covariant derivative of K with respect to $\tilde{\nabla}$ are expressed as linear combinations of the components K_{ijk}^h and S_{ijk}^h of the curvature tensor field K .

The manifolds, tensor fields and geometric objects we consider in this paper are assumed to be differentiable of class C^∞ (i.e., smooth). We use computations in local coordinates but many results may be expressed in an invariant form. The well-known summation convention is used throughout this paper, the range for the indices i, j, k, l, h, s, r being always $\{1, \dots, n\}$ (see [5, 3, 12, 13]). We shall denote by $\Gamma(TM)$ the module of smooth vector fields on TM .

1. The tangent bundle and special Lagrangians.

Let (M, g) be a smooth n -dimensional Riemannian manifold and denote its tangent bundle by $\tau : TM \rightarrow M$. Recall that TM has a structure of $2n$ -dimensional smooth manifold induced from the smooth manifold structure of M . A local chart $(U, \varphi) = (U, x^1, \dots, x^n)$ on M induces a local chart $(\tau^{-1}(U), \Phi) = (\tau^{-1}(U), x^1, \dots, x^n, y^1, \dots, y^n)$ on TM where the local coordinate $x^i, y^i; i = 1, \dots, n$ are defined as follows. The first n local coordinates $x^i = x^i \circ \tau; i = 1, \dots, n$ on TM are the local coordinates in the local chart (U, φ) of the base point of a tangent vector from $\tau^{-1}(U)$. The last n local coordinates $y^i; i = 1, \dots, n$ are the vector space coordinates of the same tangent vector, with respect to the natural local basis in the corresponding tangent space defined by the local chart (U, φ) .

This special structure of TM allows us to introduce the notion of M -tensor field on it (see [7]). An M -tensor field of type (p, q) on TM is defined by sets of functions

$$T_{j_1 \dots j_q}^{i_1 \dots i_p}; \quad i_1, \dots, i_p, j_1, \dots, j_q = 1, \dots, n$$

assigned to any induced local chart $(\tau^{-1}(U), \Phi)$ on TM , such that the change rule is that of the components of a tensor field of type (p, q) on the base manifold, when a change of local charts on the base manifold is performed. Remark that any M -tensor field on TM may be thought of as an ordinary tensor field T with the expression

$$T = T_{j_1 \dots j_q}^{i_1 \dots i_p} \frac{\partial}{\partial y^{j_1}} \otimes \dots \otimes \frac{\partial}{\partial y^{j_q}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_q}.$$

However, there are many other possibilities to interpret an M -tensor field as an ordinary tensor field on TM . Remark also that any ordinary tensor field on the base manifold may be thought of

as an M -tensor field on TM , having the same type and with the components in the induced local chart on TM , equal to the local coordinate components of the given tensor field in the chosen local chart on the base manifold. In the case of a covariant tensor field on the base manifold M , the corresponding M -tensor field on the tangent bundle TM may be thought of as the pull back of the initial tensor field defined on the base manifold, by the smooth submersion $\tau : TM \rightarrow M$.

The tangent bundle TM of a Riemannian manifold (M, g) can be organized as a Riemannian or a pseudo-Riemannian manifold in many ways. The most known such structures are given by the Sasaki metric on TM defined by g (see [14, 2]) and the complete lift type pseudo-Riemannian metric defined by g (see [16, 15, 10, 11]). Recall that the Levi-Civita connection of g defines a direct sum decomposition

$$TTM = VTM \oplus HTM \quad (1)$$

of the tangent bundle to TM into the vertical distribution $VTM = \text{Ker } \tau_*$ and the horizontal distribution HTM . The vector fields $(\partial/\partial y^1, \dots, \partial/\partial y^n)$ define a local frame field for VTM and for HTM we have the local frame field $(\delta/\delta x^1, \dots, \delta/\delta x^n)$ where

$$\frac{\delta}{\delta x^i} = \frac{\partial}{\partial x^i} - \Gamma_{i0}^h \frac{\partial}{\partial y^h}; \quad \Gamma_{i0}^h = \Gamma_{ik}^h y^k$$

and $\Gamma_{ik}^h(x)$ are the Christoffel symbols defined by the Riemannian metric g .

The distributions VTM and HTM are isomorphic to each other and it is possible to derive an almost complex structure on TM which, together with the Sasaki metric, determines a structure of almost Kaehlerian manifold on TM (see [2]). Consider now the density energy (the kinetic energy or "forza viva," according to the terminology used by Levi-Civita)

$$t = \frac{1}{2} g_{ik}(x) y^i y^k \quad (2)$$

defined on TM by the Riemannian metric g of M . We shall find some interesting properties of TM by using a Lagrangian function defined as the antiderivative (indefinite integral) of a real smooth function depending on kinetic energy only, i.e.:

$$L = \int u(t) dt = \int u\left(\frac{1}{2} g_{ik}(x) y^i y^k\right) \frac{1}{2} d(g_{ik} y^i y^k), \quad (3)$$

where $u : \mathbb{R}_+ = [0, \infty) \rightarrow \mathbb{R}$ is a smooth function. In the sequel it will be necessary to make some supplementary assumptions concerning the function u , in order to assure the regularity of the Lagrangian L . As usual in Lagrange geometry (see [4, 10, 11]), we may consider the symmetric M -tensor field of type $(0, 2)$ on TM , defined by the components

$$G_{ij} = \frac{\partial^2 L}{\partial y^i \partial y^j} = u g_{ij} + u' g_{0i} g_{0j}, \quad (4)$$

where $g_{0i} = g_{hi} y^h$. The matrix (G_{ij}) has the inverse with the entries

$$G^{jk} = \frac{1}{u} g^{jk} + w y^j y^k, \quad (5)$$

where $w = -u'/(u^2 + 2tuu')$. We shall assume that $u(t) > 0$, $u'(t) > 0$ for $t \geq 0$ so that the functions G^{jk} ; $j, k = 1, \dots, n$ do always exist. The components G^{jk} define a symmetric

M -tensor field of type $(2, 0)$ on TM and the symmetric matrix G_{ij} is positive definite. It follows that, under these conditions, the Lagrangian $L = \int u(t) dt$ is regular.

A regular Lagrangian L defines a nonlinear connection on TM given by the horizontal distribution $H'TM$ spanned, locally, by the vector fields

$$\left(\frac{\delta}{\delta x^i}\right)' = \frac{\partial}{\partial x^i} - N_i^k(x, y) \frac{\partial}{\partial y^k}; \quad i = 1, \dots, n,$$

where

$$N_i^k = \frac{1}{2} \frac{\partial}{\partial y^i} \left(G^{kl} \left(\frac{\partial^2 L}{\partial y^l \partial x^h} y^h - \frac{\partial L}{\partial x^l} \right) \right)$$

(see [4, 10, 11]). We have:

Proposition 1. *If the regular Lagrangian L is given by (3) then $H'TM = HTM$.*

Proof. We have

$$\frac{\partial L}{\partial x^i} = \frac{1}{2} u \frac{\partial g_{kl}}{\partial x^i} y^k y^l = u g_{0h} \Gamma_{i0}^h,$$

where $g_{0h} = g_{jh} y^j$, $\Gamma_{i0}^h = \Gamma_{ij}^h y^j$, and

$$\frac{\partial^2 L}{\partial y^l \partial x^h} = u (g_{lk} \Gamma_{h0}^k + g_{0k} \Gamma_{hl}^k) + u' g_{0l} g_{0k} \Gamma_{h0}^k.$$

Then

$$y^h \frac{\partial^2 L}{\partial y^l \partial x^h} = (u g_{lh} + u' g_{0l} g_{0h}) \Gamma_{00}^h + u g_{0h} \Gamma_{l0}^h,$$

where $\Gamma_{00}^h = \Gamma_{ij}^h y^i y^j$, and by using (5) we get

$$G^{kl} \left(\frac{\partial^2 L}{\partial y^l \partial x^h} y^h - \frac{\partial L}{\partial x^l} \right) = \Gamma_{00}^k.$$

Then $N_i^k = \Gamma_{i0}^k$, showing that $H'TM = HTM$ and $(\delta/\delta x^i)' = \delta/\delta x^i$.

Hence the horizontal distribution HTM defined by the Levi-Civita connection ∇ of g may be used in the study of the Lagrange geometry of M , defined by the Lagrangian (3).

2. A Riemannian metric on the tangent bundle

Consider the symmetric M -tensor field of type $(0, 2)$ on TM , defined by the components

$$H_{ij} = g_{ik} G^{kl} g_{lj} = \frac{1}{u} g_{ij} + u g_{0i} g_{0j}. \quad (6)$$

Then the following Riemannian metric may be considered on TM :

$$G = G_{ij} dx^i dx^j + H_{ij} \nabla y^i \nabla y^j, \quad (7)$$

where $\nabla y^i = dy^i + \Gamma_{j0}^i dx^j$ is the absolute differential of y^i with respect to the Levi-Civita connection ∇ of g . Equivalently, we have

$$G\left(\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j}\right) = G_{ij}, \quad G\left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j}\right) = H_{ij}, \quad G\left(\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j}\right) = G\left(\frac{\delta}{\delta x^j}, \frac{\partial}{\partial y^i}\right) = 0.$$

Note that HTM, VTM are orthogonal to each other with respect to G but the Riemannian metrics induced from G on HTM, VTM are not the same, so the considered metric G on TM is no longer a metric of Sasaki type. Note also that the system of 1-forms $(dx^1, \dots, dx^n, \nabla y^1, \dots, \nabla y^n)$ defines a local frame of T^*TM , dual to the local frame $(\delta/\delta x^1, \dots, \delta/\delta x^n, \partial/\partial y^1, \dots, \partial/\partial y^n)$ adapted to the direct sum decomposition (1).

An almost complex structure J may be defined on TM by

$$J \frac{\delta}{\delta x^i} = J_i^k \frac{\partial}{\partial y^k}, \quad J \frac{\partial}{\partial y^j} = H_j^k \frac{\delta}{\delta x^k}, \quad (8)$$

where

$$\begin{aligned} J_i^k &= G_{ij} g^{jk} = u \delta_i^k + u' y^k g_{0i}, \\ H_j^k &= -H_{ij} g^{jk} = -G^{kh} g_{hi} = -\frac{1}{u} \delta_i^k - w y^k g_{0i}. \end{aligned} \quad (9)$$

Theorem 2. (TM, J, G) is an almost Kaehlerian manifold.

Proof. First of all we may check easily that $J^2(\delta/\delta x^i) = -\delta/\delta x^i$, $J^2(\partial/\partial y^i) = -\partial/\partial y^i$; thus J really defines an almost complex structure on TM . Then we have

$$\begin{aligned} G\left(J \frac{\delta}{\delta x^i}, J \frac{\delta}{\delta x^j}\right) &= G_{ik} g^{ka} G_{jh} g^{hb} G\left(\frac{\partial}{\partial y^a}, \frac{\partial}{\partial y^b}\right) \\ &= G_{ik} g^{ka} G_{jh} g^{hb} g_{ac} G^{cd} g_{db} = G_{ij} = G\left(\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j}\right). \end{aligned}$$

The relations

$$\begin{aligned} G\left(J \frac{\partial}{\partial y^i}, J \frac{\partial}{\partial y^j}\right) &= G\left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j}\right), \\ G\left(J \frac{\partial}{\partial y^i}, J \frac{\delta}{\delta x^j}\right) &= G\left(\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j}\right) = 0 \end{aligned}$$

may be obtained in a similar way, thus G is almost Hermitian with respect to J . The associated 2-form Ω is given by

$$\begin{aligned} \Omega\left(\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j}\right) &= G\left(\frac{\delta}{\delta x^i}, J \frac{\delta}{\delta x^j}\right) = G\left(\frac{\delta}{\delta x^i}, J_j^k \frac{\partial}{\partial y^k}\right) = 0, \\ \Omega\left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j}\right) &= G\left(\frac{\partial}{\partial y^i}, J \frac{\partial}{\partial y^j}\right) = G\left(\frac{\partial}{\partial y^i}, H_j^k \frac{\delta}{\delta x^k}\right) = 0, \\ \Omega\left(\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j}\right) &= G\left(\frac{\partial}{\partial y^i}, J \frac{\delta}{\delta x^j}\right) = J_j^k G\left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^k}\right) = J_j^k H_{ik} = g_{ij}. \end{aligned}$$

Hence we have

$$\Omega = g_{ij} \nabla y^i \wedge dx^j \quad (10)$$

and Ω is closed since it does coincide with the 2-form associated to the Sasaki metric on TM (see [2]).

3. The Kaehlerian structure on T_0M

In order to study the integrability of the almost complex structure defined by J on TM we need the following well-known formulas for the brackets of the vector fields $\partial/\partial y^i, \delta/\delta x^i$; $i = 1, \dots, n$:

$$\left[\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j} \right] = 0, \quad \left[\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j} \right] = -\Gamma_{ij}^h \frac{\partial}{\partial y^h}, \quad \left[\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j} \right] = -R_{0ij}^h \frac{\partial}{\partial y^h}, \quad (11)$$

where $R_{0ij}^h = R_{kij}^h y^k$ and R_{kij}^h are the local coordinate components of the curvature tensor field of ∇ on M .

Theorem 3. *The almost complex structure J on TM is integrable if and only if (M, g) has positive constant sectional curvature c and the function $u(t)$ satisfies the ordinary differential equation*

$$2t(u')^2 = c. \quad (12)$$

Proof. First of all, the following formulas can be checked by straightforward computation:

$$\begin{aligned} \nabla_i G_{jk} &= \frac{\delta}{\delta x^i} G_{jk} - \Gamma_{ij}^h G_{hk} - \Gamma_{ik}^h G_{jh} = 0, \\ \nabla_i H_{jk} &= \frac{\delta}{\delta x^i} H_{jk} - \Gamma_{ij}^h H_{hk} - \Gamma_{ik}^h H_{jh} = 0, \\ \nabla_i J_k^j &= \frac{\delta}{\delta x^i} J_k^j + \Gamma_{ih}^j J_k^h - \Gamma_{ik}^h J_h^j = 0, \\ \nabla_i H_k^j &= \frac{\delta}{\delta x^i} H_k^j + \Gamma_{ih}^j H_k^h - \Gamma_{ik}^h H_h^j = 0. \end{aligned}$$

Then, by using the definition of the Nijenhuis tensor field N_J of J we have

$$\begin{aligned} N_J \left(\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j} \right) &= \left[J \frac{\delta}{\delta x^i}, J \frac{\delta}{\delta x^j} \right] - J \left[\frac{\delta}{\delta x^i}, J \frac{\delta}{\delta x^j} \right] - J \left[J \frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j} \right] - \left[\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j} \right] \\ &= \left(J_i^h \frac{\partial J_j^k}{\partial y^h} - J_j^h \frac{\partial J_i^k}{\partial y^h} + R_{0ij}^k \right) \frac{\partial}{\partial y^k} \\ &\quad + \left(\frac{\delta}{\delta x^j} J_i^k - \frac{\delta}{\delta x^i} J_j^k + J_i^h \Gamma_{hj}^k - J_j^h \Gamma_{ih}^k \right) H_k^l \frac{\delta}{\delta x^l}. \end{aligned}$$

The coefficient of $H_k^l(\delta/\delta x^l)$ is just $\nabla_j J_i^k - \nabla_i J_j^k = 0$ so, we have to study the vanishing of the coefficient of $\partial/\partial y^k$. By using the expression (9) of J_i^k we get:

$$2t(u')^2 g_{0i} \delta_j^k - 2t(u')^2 g_{0j} \delta_i^k + R_{0ij}^k = 0.$$

It follows that the curvature tensor field of ∇ must have the expression

$$R_{hij}^k = c(\delta_i^k g_{hj} - \delta_j^k g_{hi}),$$

where c is a constant and the function $u(t)$ must satisfy the condition (12). Next, we have

$$\begin{aligned} N_J \left(\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j} \right) &= H_i^h \left(\frac{\delta}{\delta x^h} J_j^k - \frac{\delta}{\delta x^j} J_h^k + \Gamma_{hi}^k J_j^l - \Gamma_{jl}^k J_h^l \right) \frac{\partial}{\partial y^k} \\ &\quad + H_h^k H_i^l \left(-R_{0il}^h + J_i^r \frac{\partial J_j^h}{\partial y^r} - J_j^r \frac{\partial J_i^h}{\partial y^r} \right) \frac{\delta}{\delta x^k} \end{aligned}$$

and

$$\begin{aligned} N_J \left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j} \right) &= H_i^h H_j^r \left(\frac{\delta}{\delta x^k} J_r^l - \frac{\delta}{\delta x^r} J_k^l + J_r^s \Gamma_{sk}^l - \Gamma_{rs}^l J_k^s \right) H_l^h \frac{\delta}{\delta x^h} \\ &\quad + H_i^k H_j^l \left(-R_{0kl}^h - \frac{\partial J_l^h}{\partial y^r} J_k^r + \frac{\partial J_k^h}{\partial y^r} J_l^r \right) \frac{\partial}{\partial y^h}. \end{aligned}$$

Hence, the condition $N_J(\delta/\delta x^i, \delta/\delta x^j) = 0$ implies that $N_J(\partial/\partial y^i, \delta/\delta x^j) = 0$ and $N_J(\partial/\partial y^i, \partial/\partial y^j) = 0$.

It follows that (M, g) must have constant positive sectional curvature and the function u must be a solution of the differential equation (12). The general solution of the differential equation (12) may be obtained easily. Since we look for a solution u defined for $t > 0$, for which $u > 0, u' > 0$, we may take

$$u' = \sqrt{\frac{c}{2t}}, \quad u = \sqrt{2ct}. \quad (13)$$

It follows

$$L = \int u(t) dt = \frac{2t}{3} \sqrt{2ct}, \quad w = -\frac{1}{4t \sqrt{2ct}}.$$

Remark that the Lagrangian $L = \int u(t) dt$ is smooth only on the nonzero tangent vectors of M . Hence we obtain, in fact, a Kaehler structure only on the manifold $T_0 M =$ the tangent bundle to M minus the null section.

4. The Levi-Civita connection of the metric G and its curvature tensor field

It is well known that in the case of the Kaehler manifolds (M, J, g) the almost complex structure operator J is parallel with respect to the Levi-Civita connection ∇ of the corresponding Riemannian metric g . We shall obtain the explicite expression of the Levi-Civita connection $\bar{\nabla}$ of the metric G on TM in the general case where G is given by (7), then we shall consider the

particular case where (T_0M, J, G) is Kaehler, i.e., M is a space form having positive constant sectional curvature c and the function $u(t)$ is a solution of the differential equation (12).

Recall that the Levi-Civita connection ∇ on a Riemannian manifold (M, g) is obtained from the formula

$$\begin{aligned} 2g(\nabla_X Y, Z) &= X(g(Y, Z)) + Y(g(X, Z)) - Z(g(X, Y)) \\ &\quad + g([X, Y], Z) - g([X, Z], Y) - g([Y, Z], X), \\ \forall X, Y, Z \in \Gamma(M). \end{aligned}$$

We shall use this formula in order to obtain the expression of the Levi-Civita connection $\tilde{\nabla}$ on TM , determined by the conditions

$$\tilde{\nabla}G = 0, \quad \tilde{T} = 0,$$

where \tilde{T} is the torsion tensor of $\tilde{\nabla}$.

Theorem 4. *The Levi-Civita connection $\tilde{\nabla}$ of G has the following expression in the local adapted frame $(\partial/\partial y^1, \dots, \partial/\partial y^n, \delta/\delta x^1, \dots, \delta/\delta x^n)$:*

$$\begin{aligned} \tilde{\nabla}_{\frac{\partial}{\partial y^i}} \frac{\partial}{\partial y^j} &= \frac{1}{2} H^{hk} \left(\frac{\partial H_{jk}}{\partial y^i} + \frac{\partial H_{ik}}{\partial y^j} - \frac{\partial H_{ij}}{\partial y^k} \right) \frac{\partial}{\partial y^h}, \\ \tilde{\nabla}_{\frac{\delta}{\delta x^i}} \frac{\partial}{\partial y^j} &= \Gamma_{ij}^h \frac{\partial}{\partial y^h} + \frac{1}{2} \left(\frac{\partial G_{ik}}{\partial y^j} + H_{jl} R_{0ik}^l \right) G^{kh} \frac{\delta}{\delta x^h}, \\ \tilde{\nabla}_{\frac{\partial}{\partial y^i}} \frac{\delta}{\delta x^j} &= \frac{1}{2} \left(\frac{\partial G_{jk}}{\partial y^i} + H_{il} R_{0jk}^l \right) G^{kh} \frac{\delta}{\delta x^h}, \\ \tilde{\nabla}_{\frac{\delta}{\delta x^i}} \frac{\delta}{\delta x^j} &= \Gamma_{ij}^h \frac{\delta}{\delta x^h} + \frac{1}{2} \left(-R_{0ij}^h - \frac{\partial G_{ij}}{\partial y^k} H^{kh} \right) \frac{\partial}{\partial y^h}. \end{aligned}$$

Consider now the case where (T_0M, J, G) has a structure of Kaehler manifold, i.e., M has positive constant sectional curvature c and the function u is given by (13). Introduce, for convenience, the following M -tensor fields on T_0M :

$$a_{ij} = g_{ij} - \frac{1}{2t} g_{0i} g_{0j}, \quad a_i^k = \delta_i^k - \frac{1}{2t} g_{0i} y^k. \quad (14)$$

Remark that we have $a_{i0} = a_{0i} = a_{ij} y^j = 0$ and $a_{ij} = a_i^k g_{kj} = a_i^k a_{kj}$. Then we obtain

$$\begin{aligned} G_{ij} &= \sqrt{2ct} g_{ij} + \sqrt{\frac{c}{2t}} g_{0i} g_{0j} = \sqrt{2ct} \left(a_{ij} + \frac{1}{t} g_{0i} g_{0j} \right), \\ H_{ij} &= -\frac{1}{\sqrt{2ct}} g_{ij} - \frac{1}{4t\sqrt{2ct}} g_{0i} g_{0j} = -\frac{1}{\sqrt{2ct}} \left(a_{ij} + \frac{1}{4t} g_{0i} g_{0j} \right), \\ G^{jk} &= \frac{1}{\sqrt{2ct}} g^{jk} - \frac{1}{4t\sqrt{2ct}} y^j y^k, \\ H^{jk} &= \sqrt{2ct} g^{jk} + \sqrt{\frac{c}{2t}} y^j y^k, \end{aligned} \quad (15)$$

and

Theorem 5. *The Levi-Civita connection of the Kaehler manifold (T_0M, J, G) is given by*

$$\begin{aligned}\tilde{\nabla}_{\frac{\partial}{\partial y^i}} \frac{\partial}{\partial y^j} &= \left(-\frac{1}{4t} g_{0i} \delta_j^h - \frac{1}{4t} g_{0j} \delta_i^h + \frac{1}{8t^2} g_{0i} g_{0j} y^h \right) \frac{\partial}{\partial y^h}, \\ \tilde{\nabla}_{\frac{\delta}{\delta x^i}} \frac{\partial}{\partial y^j} &= \Gamma_{ij}^h \frac{\partial}{\partial y^h} + \left(\frac{1}{4t} g_{ij} y^h + \frac{1}{4t} g_{0j} \delta_i^h - \frac{1}{8t^2} g_{0i} g_{0j} y^h \right) \frac{\delta}{\delta x^h} \\ &= \Gamma_{ij}^h \frac{\partial}{\partial y^h} + \left(\frac{1}{4t} a_{ij} y^h + \frac{1}{4t} \delta_i^h g_{0j} \right) \frac{\delta}{\delta x^h}, \\ \tilde{\nabla}_{\frac{\partial}{\partial y^i}} \frac{\delta}{\delta x^j} &= \left(\frac{1}{4t} g_{ij} y^h + \frac{1}{4t} g_{0i} \delta_j^h - \frac{1}{8t^2} g_{0i} g_{0j} y^h \right) \frac{\delta}{\delta x^h} \\ &= \left(\frac{1}{4t} a_{ij} y^h + \frac{1}{4t} \delta_j^h g_{0i} \right) \frac{\delta}{\delta x^h}, \\ \tilde{\nabla}_{\frac{\delta}{\delta x^i}} \frac{\delta}{\delta x^j} &= \Gamma_{ij}^h \frac{\delta}{\delta x^h} - c(g_{ij} y^h + \delta_i^h g_{0j}) \frac{\partial}{\partial y^h}.\end{aligned}$$

Then the expression of the operator J is given by

$$J \frac{\delta}{\delta x^i} = \left(\sqrt{2ct} \delta_i^k + \sqrt{\frac{c}{2t}} g_{0i} y^k \right) \frac{\partial}{\partial y^k}, \quad J \frac{\partial}{\partial y^i} = \left(-\frac{1}{\sqrt{2ct}} \delta_i^k + \frac{1}{4t \sqrt{2ct}} g_{0i} y^k \right) \frac{\delta}{\delta x^k},$$

and it can be checked easily that $\tilde{\nabla}J = 0$.

Denote by K the curvature tensor field of the Levi-Civita connection $\tilde{\nabla}$ of the Riemannian metric G on T_0M , when (M, g) has positive constant sectional curvature c and the function $u(t)$ is given by (13). Then we get by a straightforward computation

Theorem 6. *The local coordinate expression of the curvature tensor field K of the Kaehler manifold (T_0M, J, G) is given in the adapted local frame $(\partial/\partial y^i, \delta/\delta x^i)$ by*

$$\begin{aligned}K\left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j}\right) \frac{\partial}{\partial y^k} &= \frac{1}{4t} K_{kij}^h \frac{\partial}{\partial y^h}, & K\left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j}\right) \frac{\delta}{\delta x^k} &= \frac{1}{4t} K_{kij}^h \frac{\delta}{\delta x^h}, \\ K\left(\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j}\right) \frac{\partial}{\partial y^k} &= \frac{1}{4t} S_{kij}^h \frac{\delta}{\delta x^h}, & K\left(\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j}\right) \frac{\delta}{\delta x^k} &= -\frac{c}{2} S_{kij}^h \frac{\partial}{\partial y^h}, \\ K\left(\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j}\right) \frac{\partial}{\partial y^k} &= \frac{c}{2} K_{kij}^h \frac{\partial}{\partial y^h}, & K\left(\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j}\right) \frac{\delta}{\delta x^k} &= \frac{c}{2} K_{kij}^h \frac{\delta}{\delta x^h},\end{aligned}\tag{16}$$

where we have denoted

$$\begin{aligned}K_{kij}^h &= \frac{1}{c} \left\{ R_{kij}^h - \frac{1}{2t} g_{0k} R_{0ij}^h + \frac{1}{2t} g_{ik} R_{0ij}^l y^h \right\} = a_i^h a_{jk} - a_j^h a_{ik}, \\ S_{kij}^h &= g_{ik} \delta_j^h + g_{jk} \delta_i^h - \frac{1}{2t} [g_{0i} g_{jk} y^h + g_{0j} g_{ik} y^h + g_{0i} g_{0k} \delta_j^h + g_{0j} g_{0k} \delta_i^h] \\ &\quad + \frac{1}{2t^2} g_{0i} g_{0j} g_{0k} y^h \\ &= a_i^h a_{jk} + a_j^h a_{ik}.\end{aligned}\tag{17}$$

From the above formulas, we get by a straightforward computation that the local coordinate expression of the Ricci tensor $S(Y, Z) = \text{trace}(X \longrightarrow K(X, Y)Z)$ in the local frame adapted to the direct sum decomposition (1) is given by

$$\begin{aligned} S\left(\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j}\right) &= -\frac{1}{2t} \left[g_{ij} - \frac{1}{2t} g_{0i} g_{0j} \right] = -\frac{1}{2t} a_{ij}, \\ S\left(\frac{\delta}{\delta x^i}, \frac{\delta}{\delta x^j}\right) &= -c \left[g_{ij} - \frac{1}{2t} g_{0i} g_{0j} \right] = -ca_{ij}, \\ S\left(\frac{\partial}{\partial y^i}, \frac{\delta}{\delta x^j}\right) &= 0. \end{aligned} \tag{18}$$

Comparing the obtained expressions with the expressions (15) of the components of G we obtain:

Proposition 7. *The Kaehlerian manifold (T_0M, J, G) cannot be an Einstein manifold.*

From the expression (16) of K it follows also:

Proposition 8. *The Kaehlerian manifold (T_0M, J, G) cannot have constant holomorphic sectional curvature.*

Finally, we should like to study the covariant derivative of the curvature tensor field K with respect to $\tilde{\nabla}$. To do this, it is useful to compute the expressions of the derivatives of the M -tensor fields a_{ij} and a_i^k . The following formulas are obtained by a straightforward computation:

$$\begin{aligned} \frac{\delta}{\delta x^i} a_{jk} &= \Gamma_{ij}^h a_{hk} + \Gamma_{ik}^h a_{jh}, & \frac{\delta}{\delta x^i} a_j^k &= \Gamma_{ij}^h a_h^k - \Gamma_{ih}^k a_j^h, \\ \frac{\partial}{\partial y^i} a_{jk} &= -\frac{1}{2t} g_{0j} a_{ik} - \frac{1}{2t} g_{0k} a_{ij}, & \frac{\partial}{\partial y^i} a_j^k &= -\frac{1}{2t} a_{ij} y^k - \frac{1}{2t} a_i^k g_{0j}. \end{aligned}$$

Then we have:

$$\begin{aligned} \frac{\delta}{\delta x^i} K_{ljk}^h &= -\Gamma_{ir}^h K_{ljk}^r + \Gamma_{il}^r K_{rjk}^h + \Gamma_{ij}^r K_{lrk}^h + \Gamma_{ik}^r K_{ljr}^h, \\ \frac{\delta}{\delta x^i} S_{ljk}^h &= -\Gamma_{ir}^h S_{ljk}^r + \Gamma_{il}^r S_{rjk}^h + \Gamma_{ij}^r S_{lrk}^h + \Gamma_{ik}^r S_{ljr}^h, \\ \frac{\partial}{\partial y^i} K_{ljk}^h &= -\frac{1}{2t} (a_{ir} K_{ljk}^r y^h + g_{0j} K_{lik}^h + g_{0k} K_{lji}^h + g_{0l} K_{ijk}^h), \\ \frac{\partial}{\partial y^i} S_{ljk}^h &= -\frac{1}{2t} (a_{ir} S_{ljk}^r y^h + g_{0j} S_{lik}^h + g_{0k} S_{lji}^h + g_{0l} S_{ijk}^h), \end{aligned}$$

and it follows that the components of the covariant derivative of K with respect to $\tilde{\nabla}$ are expressed as linear combinations of the components K_{ljk}^h and S_{ljk}^h . In fact, if we denote, for convenience

$$\frac{\delta}{\delta x^i} = \delta_i, \quad \frac{\partial}{\partial y^i} = \partial_i,$$

we have

$$\begin{aligned}
 (\tilde{\nabla}_{\delta_l} K)(\delta_j, \delta_k)\delta_l &= \frac{c^2}{2} \{-g_{0j}S_{lki}^h + g_{0k}S_{lji}^h + g_{0l}K_{ijk}^h - a_{ir}K_{ljk}^r y^h\} \partial_h, \\
 (\tilde{\nabla}_{\partial_l} K)(\delta_j, \delta_k)\delta_l &= \frac{c}{8t} \{-2g_{0i}K_{ljk}^h + 2g_{0j}K_{lki}^h - 2g_{0k}K_{lji}^h - 2g_{0l}K_{ijk}^h - a_{ir}K_{ljk}^r y^h\} \delta_h, \\
 (\tilde{\nabla}_{\delta_l} K)(\delta_j, \delta_k)\partial_l &= \frac{c}{8t} \{2g_{0j}S_{lki}^h - 2g_{0k}S_{lji}^h - g_{0l}K_{ijk}^h + a_{ir}K_{ljk}^r y^h\} \delta_h, \\
 (\tilde{\nabla}_{\partial_l} K)(\delta_j, \delta_k)\partial_l &= \frac{c}{8t} \{-2g_{0i}K_{ljk}^h + 2g_{0j}K_{lki}^h - 2g_{0k}K_{lji}^h - g_{0l}K_{ijk}^h - 2a_{ir}K_{ljk}^r y^h\} \partial_h, \\
 (\tilde{\nabla}_{\delta_l} K)(\partial_j, \delta_k)\delta_l &= \frac{c}{8t} \{g_{0j}K_{lki}^h + 2g_{0k}K_{lji}^h + 2g_{0l}S_{ijk}^h - a_{ir}S_{ljk}^r y^h\} \delta_h, \\
 (\tilde{\nabla}_{\partial_l} K)(\partial_j, \delta_k)\delta_l &= \frac{c}{8t} \{2g_{0i}S_{ljk}^h + g_{0j}S_{lki}^h + 2g_{0k}S_{lji}^h + 2g_{0l}S_{ijk}^h + 2a_{ir}S_{ljk}^r y^h\} \partial_h, \\
 (\tilde{\nabla}_{\delta_l} K)(\partial_j, \delta_k)\partial_l &= \frac{c}{8t} \{g_{0j}K_{lki}^h + 2g_{0k}K_{lji}^h + g_{0l}S_{ijk}^h - 2a_{ir}S_{ljk}^r y^h\} \partial_h, \\
 (\tilde{\nabla}_{\partial_l} K)(\partial_j, \delta_k)\partial_l &= \frac{1}{16t^2} \{-2g_{0i}S_{ljk}^h - g_{0j}S_{lki}^h - 2g_{0k}S_{lji}^h - g_{0l}S_{ijk}^h - a_{ir}S_{ljk}^r y^h\} \delta_h, \\
 (\tilde{\nabla}_{\delta_l} K)(\partial_j, \partial_k)\delta_l &= \frac{c}{8t} \{-g_{0j}S_{lki}^h + g_{0k}S_{lji}^h + 2g_{0l}K_{ijk}^h - a_{ir}K_{ljk}^r y^h\} \partial_h, \\
 (\tilde{\nabla}_{\partial_l} K)(\partial_j, \partial_k)\delta_l &= \frac{1}{16t^2} \{-2g_{0i}K_{ljk}^h + g_{0j}K_{lki}^h - g_{0k}K_{lji}^h - 2g_{0l}K_{ijk}^h - a_{ir}K_{ljk}^r y^h\} \delta_h, \\
 (\tilde{\nabla}_{\delta_l} K)(\partial_j, \partial_k)\partial_l &= \frac{1}{16t^2} \{g_{0j}S_{lki}^h - g_{0k}S_{lji}^h - g_{0l}K_{ijk}^h + a_{ir}K_{ljk}^r y^h\} \delta_h, \\
 (\tilde{\nabla}_{\partial_l} K)(\partial_j, \partial_k)\partial_l &= \frac{1}{16t^2} \{-2g_{0i}K_{ljk}^h + g_{0j}K_{lki}^h - g_{0k}K_{lji}^h - g_{0l}K_{ijk}^h - 2a_{ir}K_{ljk}^r y^h\} \partial_h.
 \end{aligned}$$

Similar results are obtained for the components of the covariant derivative of the Ricci tensor field S :

$$\begin{aligned}
 (\tilde{\nabla}_{\delta_l} S)(\delta_j, \delta_k) &= 0, \quad (\tilde{\nabla}_{\partial_l} S)(\delta_j, \delta_k) = \frac{c}{2t} (g_{0i}a_{jk} + g_{0j}a_{ik} + g_{0k}a_{ij}), \\
 (\tilde{\nabla}_{\delta_l} S)(\partial_j, \delta_k) &= \frac{c}{4t} (g_{0j}a_{ik} - 2g_{0k}a_{ij}), \quad (\tilde{\nabla}_{\partial_l} S)(\partial_j, \delta_k) = 0, \\
 (\tilde{\nabla}_{\delta_l} S)(\partial_j, \partial_k) &= 0, \quad (\tilde{\nabla}_{\partial_l} S)(\partial_j, \partial_k) = \frac{1}{8t^2} (2g_{0i}a_{jk} + g_{0j}a_{ik} + g_{0k}a_{ij}).
 \end{aligned}$$

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