# Notes on Lacunary Interpolation with Splines IV. $(0,2)$ Interpolation with Splines of Degree 6 

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## 1. Introduction

In 1957 Turan and Balazs [1] initiated the study of "lacunary interpolation." Several authors have studied the use of splines to solve such interpolation problems (see, e.g., Meir and Sharma [7]; Swartz and Varga [10]; Varma [11]; Mishra and Mathur [8]). All of these methods are global and require the solution of a large system of equations.

Recently, Fawzy [2-5] presented several local methods for solving lacunary interpolation problems using piecewise polynomials with certain continuity properties.

In this paper we study the following ( 0,2 )-interpolation problem:
Problem 1: Given $\Delta:\left\{x_{i}=i h\right\}_{i=0}^{n}$ and real numbers $\left\{f_{i}, f_{i}^{\prime \prime}\right\}_{i=0}^{n}$, find $S$ such that

$$
\begin{equation*}
S\left(x_{i}\right)=f_{i}, \quad S^{\prime \prime}\left(x_{i}\right)=f_{i}^{\prime \prime}, \quad i=0,1, \ldots, n . \tag{1.1}
\end{equation*}
$$

The purpose of this paper is to construct a spline method for solving problem 1 using piecewise polynomials of degree 6 such that for all functions $f \in C^{6}$, the order of approximation is the same as the best order of approximation using 6th degree splines.

## 2. Construction of the Spline Interpolant

We shall construct a solution $S$ of problem 1 in the form:

$$
\begin{equation*}
S_{\Delta}(x)=S_{k}(x)=\sum_{j=0}^{6} \frac{S_{k}^{(j)}}{j!}\left(x-x_{k}\right)^{j}, \quad x \in\left[x_{k}, x_{k+1}\right] \tag{2.1}
\end{equation*}
$$

where $k=0,1, \ldots, n-1$.

We shall define each of the $S_{k}^{(j)}$ explicitly in terms of the data. In particular we choose

$$
\begin{equation*}
S_{k}^{(0)}=f_{k}, \quad S_{k}^{(2)}=f_{k}^{(2)}, \quad k=0,1, \ldots, n-1 . \tag{2.2}
\end{equation*}
$$

For $k=1,2, \ldots, n-3$, we take

$$
\begin{align*}
& S_{k}^{(6)}=\frac{1}{h^{4}}\left\{f_{k+3}^{\prime \prime}-4 f_{k+2}^{\prime \prime}+6 f_{k+1}^{\prime \prime}-4 f_{k}^{\prime \prime}+f_{k}^{\prime \prime} \quad 1\right\}  \tag{2.3}\\
& S_{k}^{(5)}=\frac{1}{h^{3}}\left\{f_{k+2}^{\prime \prime}-3 f_{k+1}^{\prime \prime}+3 f_{k}^{\prime \prime}-f_{k-1}^{\prime \prime}\right\}-\frac{h}{2} S_{k}^{(6)}  \tag{2.4}\\
& S_{k}^{(4)}=\frac{1}{h^{2}}\left\{f_{k+1}^{\prime \prime}-2 f_{k}^{\prime \prime}+f_{k-1}^{\prime \prime}\right\}-\frac{h^{2}}{12} S_{k}^{(6)}  \tag{2.5}\\
& S_{k}^{(3)}=\frac{1}{h}\left\{f_{k+1}^{\prime \prime}-f_{k}^{\prime \prime}-\sum_{r=2}^{4} \frac{h^{\prime}}{r!} S_{k}^{(r+2)}\right\} \tag{2.6}
\end{align*}
$$

and

$$
\begin{equation*}
S_{k}^{(1)}=\frac{1}{h}\left\{f_{k+1}-f_{k}-\frac{h^{2}}{2} f_{k}^{\prime \prime}-\sum_{r=3}^{6} \frac{h^{r}}{r!} S_{k}^{(r)}\right\} \tag{2.7}
\end{equation*}
$$

For $k=0$, we choose

$$
\begin{align*}
& S_{0}^{(6)}=S_{1}^{(6)}  \tag{2.8}\\
& S_{0}^{(5)}=S_{1}^{(5)}-h S_{1}^{(6)}  \tag{2.9}\\
& S_{0}^{(4)}=S_{1}^{(4)}-h S_{1}^{(5)}-\frac{h^{2}}{2} S_{1}^{(6)}  \tag{2.10}\\
& S_{0}^{(3)}=\frac{1}{h}\left\{f_{1}^{\prime \prime}-f_{0}^{\prime \prime}-\sum_{r=2}^{4} \frac{h^{r}}{r!} S_{0}^{(r+2)}\right\} \tag{2.11}
\end{align*}
$$

and

$$
\begin{equation*}
S_{0}^{(1)}=\frac{1}{h}\left\{f_{1}-f_{0}-\frac{h^{2}}{2} f_{0}^{\prime \prime}-\sum_{r=3}^{6} \frac{h^{r}}{r!} S_{0}^{(r)}\right\} \tag{2.12}
\end{equation*}
$$

Finally, for $k=n-2$ and $n-1$, we take

$$
\begin{equation*}
S_{k}^{(j)}=S_{k}^{(j)}\left(x_{k}\right), \quad j=1,3,4,5, \text { and } 6 \tag{2.13}
\end{equation*}
$$

Clearly, the function $S$ defined in (2.1)-(2.13) solves the ( 0,2 )-interpolation problem 1. Moreover, by construction it is clear that $S$ is a piecewise polynomial of degree 6 .

The $S_{k}^{(3)}$ have been chosen to make $S_{\Delta}^{\prime \prime}$ right continuous, i.e.,

$$
D_{L}^{2} S_{k}\left(x_{k+1}\right)=D_{R}^{2} S_{k+1}\left(x_{k+1}\right)
$$

while the $S_{k}^{(1)}$ have been chosen to make $S$ continuous. Thus,

$$
\begin{equation*}
S \in C^{(0,2)}\left[x_{0}, x_{n}\right]=\left\{f \in C\left[x_{0}, x_{n}\right]: D_{R}^{2} f \in C\left[x_{0}, x_{n}\right]\right\}, \tag{2.14}
\end{equation*}
$$

where $D_{R}$ is the right derivative.
Indeed, $S$ is the unique piecewise polynomial of degree 6 in

$$
C^{(0,2)}\left[x_{0}, x_{n}\right] \cap C^{6}\left[x_{n-3}, x_{n}\right]
$$

satisfying the interpolation conditions (1.1).
$S$ is a special kind of $g$-spline; we refer to it as a lacunary $g$-spline.

## 3. Error Bounds

Suppose $f \in C^{6}\left[x_{0}, x_{n}\right]$. Then, using the Taylor and dual Taylor expansions it is easy to establish the following lemma estimating how well the $S_{k}^{(j)}$ approximate $f^{(j)}\left(x_{k}\right)$ in terms of the modulus of continuity $\omega\left(D^{6} f ; h\right)$ of $f^{(6)}(x)$.

Lemma 3.1. For $j=1,3,4,5,6$, we have

$$
\begin{equation*}
\left|S_{k}^{(j)}-f^{(j)}\left(x_{k}\right)\right| \leqslant c_{k j} h^{6} \quad{ }^{j} \omega\left(D^{6} f ; h\right) \tag{3.1}
\end{equation*}
$$

where the constants $c_{k j}$ are given in the following table:

|  | $c_{k 1}$ | $c_{k 3}$ | $c_{k 4}$ | $c_{k 5}$ | $c_{k 6}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $k=0$ | $\frac{3365}{4320}$ | $\frac{301}{36}$ | $\frac{467}{36}$ | $\frac{59}{6}$ | $\frac{17}{3}$ |
| $k=n-2$ | $\frac{221}{1440}$ | $\frac{31}{24}$ | $\frac{29}{36}$ | $\frac{25}{6}$ | $\frac{14}{3}$ |
| $k=n-1$ | $\frac{4951}{4320}$ | $\frac{119}{24}$ | $\frac{263}{36}$ | $\frac{53}{6}$ | $\frac{17}{3}$ |
| $k=n-3$ | $\frac{4543}{864}$ | $\frac{141}{8}$ | $\frac{683}{36}$ | $\frac{29}{2}$ | $\frac{20}{3}$ |

Theorem 3.1. Let $f \in C^{6}\left[x_{0}, x_{n}\right]$ and let $S_{\Delta}$ be the unique lacunary $g$-spline constructed in (2.1)-(2.13). Then, for all $0 \leqslant j \leqslant 6$,

$$
\begin{equation*}
\left\|D^{j}\left(f-S_{\Delta}\right)\right\|_{L_{\infty x}\left[x_{k}, x_{k+1}\right]} \leqslant c_{k j}^{*} h^{6-j} \omega\left(D^{6} f ; h\right) \tag{3.2}
\end{equation*}
$$

where the constants $c_{k j}^{*}$ are given in the following table:

|  | $c_{k 0}^{*}$ | $c_{k 1}^{*}$ | $c_{k 2}^{*}$ | $c_{k 3}^{*}$ | $c_{k 4}^{*}$ | $c_{k 5}^{*}$ | $c_{k 6}^{*}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $k=0$ | $\frac{1,009}{360}$ | $\frac{32,569}{4,320}$ | $\frac{301}{18}$ | $\frac{979}{36}$ | $\frac{923}{36}$ | $\frac{31}{2}$ | $\frac{17}{3}$ |
| $1 \leqslant k \leqslant n-3$ | $\frac{479}{1,080}$ | $\frac{4,951}{4,320}$ | $\frac{31}{12}$ | $\frac{119}{24}$ | $\frac{263}{36}$ | $\frac{53}{6}$ | $\frac{14}{3}$ |
| $k=n-2$ | $\frac{1,261}{540}$ | $\frac{23,033}{4,320}$ | $\frac{743}{72}$ | $\frac{141}{8}$ | $\frac{683}{36}$ | $\frac{29}{2}$ | $\frac{17}{3}$ |
| $k=n-1$ | $\frac{19,691}{2,160}$ | $\frac{4,871}{288}$ | $\frac{1073}{36}$ | $\frac{1079}{24}$ | $\frac{1325}{36}$ | $\frac{127}{6}$ | $\frac{20}{3}$ |

Proof. We sketch the proof of the theorem for $1 \leqslant k \leqslant n-3$, while for $k=0, n-2$ and $n-1$, similar procedures lead to the required results.

Suppose $1 \leqslant k \leqslant n-3$, and that $x_{k} \leqslant x \leqslant x_{k+1}$. Then, using the Taylor expansion of $f$, we have

$$
\begin{aligned}
\left|f(x)-S_{\Delta}(x)\right| & =\left|f(x)-S_{k}(x)\right| \\
& \leqslant \sum_{j=0}^{5} \frac{\left|f^{(j)}\left(x_{k}\right)-S_{k}^{(j)}\right|}{j!} h^{j}+\frac{\left|f^{(6)}\left(\xi_{k}\right)-S_{k}^{(6)}\right|}{6!} h^{6} \\
& \leqslant \sum_{j=0}^{6} \frac{\left|f^{(j)}\left(x_{k}\right)-S_{k}^{(j)}\right|}{j!} h^{j}+\frac{\left|f^{(6)}\left(\xi_{k}\right)-f^{(6)}\left(x_{k}\right)\right|}{6!} h^{6},
\end{aligned}
$$

where $x_{k}<\xi_{k}<x_{k+1}$. Using Lemma 3.1 and the definition of the modulus of continuity of $f^{(6)}(x)$, we easily obtain the required result. The other results for derivatives can be easily obtained by following the same technique.

## 4. Numerical Results

The method is tested by the following example:

$$
f(x)=1+x e^{x}, \quad x_{0}=0, x_{n}=1.0, h=0.1
$$

The following results are obtained for $x=0,55$ :

|  | Exact value | Numerical value | Error |
| :--- | :---: | :---: | :---: |
| $f$ | 1.953289160 | 1.953289159 | $1(10)^{-9}$ |
| $f^{\prime}$ | 2.686542178 | 2.686542177 | $1(10)^{-9}$ |
| $f^{\prime \prime}$ | 4.419795196 | 4.419796802 | $1.606(10)^{-6}$ |
| $f^{(3)}$ | 6.153048214 | 6.153042055 | $6.159(10)^{-6}$ |
| $f^{(4)}$ | 7.886301232 | 7.884871125 | $1.430107(10)^{-3}$ |
| $f^{(5)}$ | 9.61955425 | 9.635925000 | $1.637075(10)^{-2}$ |
| $f^{(6)}$ | 11.35280727 | 12.0521 | $6.9929273(10)^{-1}$ |

## 5. Remarks

(i) The method defined here, in contrast to the methods of [7], [10], and [11], does not require any end conditions.
(ii) Similar lacunary methods were constructed for degrees $r=2,3,4,5$ in [3] and [4]. These earlier methods give optimal order of approximation for functions in $C^{r}\left[x_{0}, x_{n}\right]$, but not for $r=6$.
(iii) Other lacunary interpolation problems, e.g., $(0,3),(0,4)$, $(0,1,3),(0,2,3)$, and $(0,2,4)$, with similar constructions and optimal approximation results are submitted for publication in other journals.
(iv) Details for the computations of the constants $c_{k j}$ and $c_{k j}^{*}$ can be found in [2], [3], and [4]. The constants presented here are not guaranteed to be the best.

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