

Available online at www.sciencedirect.com

J. Math. Anal. Appl. 296 (2004) 190-208

Journal of MATHEMATICAL ANALYSIS AND APPLICATIONS

www.elsevier.com/locate/jmaa

Boundary layer techniques for solving the Helmholtz equation in the presence of small inhomogeneities

Habib Ammari^{a,*,1}, Hyeonbae Kang^{b,2}

^a Centre de Mathématiques Appliquées, École Polytechnique & CNRS, 91128 Palaiseau cedex, France
 ^b School of Mathematical Sciences, Seoul National University, Seoul 151-747, Republic of Korea

Received 6 November 2002

Available online 1 June 2004

Submitted by W.L. Wendland

Abstract

We consider solutions to the Helmholtz equation in two and three dimensions. Based on layer potential techniques we provide for such solutions a rigorous systematic derivation of complete asymptotic expansions of perturbations resulting from the presence of diametrically small inhomogeneities with constitutive parameters different from those of the background medium. It is expected that our results will find important applications for developing effective algorithms for reconstructing small dielectric inhomogeneities from backgroundary measurements.

© 2004 Elsevier Inc. All rights reserved.

Keywords: Helmholtz equation; Small inhomogeneities; Asymptotic expansions; Generalized polarization tensors

1. Introduction

Let Ω be a bounded domain in \mathbb{R}^d , d = 2 or 3, with a connected Lipschitz boundary $\partial \Omega$. Let ν denote the unit outward normal to $\partial \Omega$. Suppose that Ω contains a small inhomogeneity D of the form $D = z + \delta B$, where B is a bounded Lipschitz domain in \mathbb{R}^d

^{*} Corresponding author.

E-mail addresses: ammari@cmapx.polytechnique.fr (H. Ammari), hkang@math.snu.ac.kr (H. Kang).

¹ Partly supported by ACI Jeunes Chercheurs (0693) from the Ministry of Education and Scientific Research, France.

² Partly supported by KOSEF 98-0701-03-5.

⁰⁰²²⁻²⁴⁷X/\$ – see front matter @ 2004 Elsevier Inc. All rights reserved. doi:10.1016/j.jmaa.2004.04.003

containing the origin and δ is the order of magnitude of the diameter of the inhomogeneity. We assume that the domain *D* is separated apart from the boundary, i.e., there exists a constant $c_0 > 0$ such that $dist(z, \partial \Omega) \ge c_0 > 0$. Let *u* denote the solution to the Helmholtz equation

$$\nabla \cdot \left(\frac{1}{\mu_{\delta}} \nabla u\right) + \omega^2 \varepsilon_{\delta} u = 0 \quad \text{in } \Omega,$$
(1.1)

with the boundary condition u = f on $\partial \Omega$, where $\omega > 0$ is a given frequency. Here μ_{δ} and ε_{δ} denote the constitutive parameters of the inhomogeneity defined by

$$\mu_{\delta}(x) = \begin{cases} \mu_0, & x \in \Omega \setminus \bar{D}, \\ \mu, & x \in D, \end{cases}$$
(1.2)

$$\varepsilon_{\delta}(x) = \begin{cases} \varepsilon_0, & x \in \Omega \setminus \bar{D}, \\ \varepsilon, & x \in D, \end{cases}$$
(1.3)

where μ , μ_0 , ε , and ε_0 are positive constants. If we allow the degenerate case $\delta = 0$, then the functions $\mu_{\delta}(x)$ and $\varepsilon_{\delta}(x)$ equal the constants μ_0 and ε_0 . Problem (1.1) can be written as

$$\begin{cases} (\Delta + \omega^2 \varepsilon_0 \mu_0) u = 0 & \text{in } \Omega \setminus \bar{D}, \\ (\Delta + \omega^2 \varepsilon_0) u = 0 & \text{in } D, \\ \frac{1}{\mu} \frac{\partial u}{\partial \nu}|_{-} - \frac{1}{\mu_0} \frac{\partial u}{\partial \nu}|_{+} = 0 & \text{on } \partial D, \\ u|_{-} - u|_{+} = 0 & \text{on } \partial D, \\ u = f & \text{on } \partial \Omega. \end{cases}$$
(1.4)

Here the subscripts + and – indicate the limit from outside and from inside D, respectively. In order to insure well-posedness (also for the δ -dependent case for δ sufficiently small [15]) we shall assume that $\omega^2 \varepsilon_0 \mu_0$ is not an eigenvalue for the operator $-\Delta$ in $L^2(\Omega)$ with the Dirichlet boundary conditions.

The main achievement of this paper is a rigorous derivation, based on layer potential techniques, of a complete asymptotic expansion of $\frac{\partial u}{\partial v}|_{\partial \Omega}$ as $\delta \to 0$ for d = 2, 3. The leading order term in this asymptotic formula has been derived by Vogelius and Volkov [15], see also [5,10] for previous results on the conductivity problem and [4] where the second order term in the asymptotic expansions of solutions to the Helmholtz equation is obtained.

The proof of our asymptotic expansion is radically different from the variational ones in [4,15]. It is based on layer potential techniques and a new decomposition formula of the solution to the Helmholtz equation. Our decomposition formula generalizes that due to Kang and Seo [12] for the conductivity problem. In that case the steady-state voltage potential is decomposed into a harmonic part and a refraction part.

It is expected that our results will find important applications for developing effective algorithms for reconstructing small dielectric inhomogeneities from boundary measurements which can be applied in medical imagining, breast cancer, tumor, and land mine. By use of higher-order terms in the asymptotic expansions of the boundary perturbations due to the presence of the dielectric inhomogeneities the reconstruction technique described in [2] could be carried out to recuperate the locations of the inhomogeneities with a higher resolution and capture further properties of their geometries (namely, their generalized polarization tensors defined in [1]).

In our recent paper [2] we have used the leading order term in the expansion derived in this paper for efficiently determining the locations and/or shapes of the small dielectric inhomogeneities from boundary measurements at a fixed frequency by reducing the reconstruction problem of the small inhomogeneities to the calculation of an inverse Fourier transform. Our algorithm uses plane wave sources for identifying the small electromagnetic inhomogeneities. A different approach based on projections on three planes was proposed and successfully tested by Volkov in [16].

The extension of the techniques used in [4,15] to construct complete asymptotic expansions seems to be laborious. The present work represents a natural completion of [1]. It is organized as follows. In Section 2 we prove one preliminary result on the unique solvability of a system of two integral equations. In Section 3 we give slightly different representations of the solution of (1.4). In Section 4 we provide a rigorous derivation of high-order terms in its asymptotic expansion. Our derivations are valid for inhomogeneities with Lipschitz boundaries.

2. Preliminary result

Let $k_0 := \omega \sqrt{\varepsilon_0 \mu_0}$ and $k := \omega \sqrt{\varepsilon \mu}$. Let $\Phi_k(x)$ be the fundamental solution for $\Delta + k^2$, that is for $x \neq 0$,

$$\Phi_k(x) = \begin{cases} -\frac{i}{4}H_0^1(k|x-y|), & d=2, \\ -\frac{e^{ik|x-y|}}{4\pi|x-y|}, & d=3, \end{cases}$$

where H_0^1 is the Hankel function of the first kind of order 0 [7]. We have,

$$-\frac{i}{4}H_0^1(k|x-y|) = \frac{1}{2\pi}\log|x-y| + \tau + \sum_{n=1}^{+\infty} (b_n\log k|x-y| + c_n)(k|x-y|)^{2n},$$
(2.1)

where the constant $\tau = (1/2\pi) \log k + \gamma - i/4$, γ is the Euler constant. Let for $x \neq 0$,

$$\Phi(x) = \Phi_0(x) = \begin{cases} \frac{1}{2\pi} \log |x - y|, & d = 2, \\ \frac{1}{4\pi |x - y|}, & d = 3. \end{cases}$$

For a bounded domain D in \mathbb{R}^d and k > 0 let \mathcal{S}_D^k and \mathcal{D}_D^k be the single and double layer potentials defined by Φ_k , that is,

$$S_D^k \varphi(x) = \int_{\partial D} \Phi_k(x - y)\varphi(y) \, d\sigma(y), \quad x \in \mathbb{R}^d,$$
$$\mathcal{D}_D^k \varphi(x) = \int_{\partial D} \frac{\partial \Phi_k(x - y)}{\partial \nu(y)} \varphi(y) \, d\sigma(y), \quad x \in \mathbb{R}^d \setminus \partial D.$$

It is well known, see [7, Theorem 3.1], that

H. Ammari, H. Kang / J. Math. Anal. Appl. 296 (2004) 190–208

193

$$\frac{\partial(\mathcal{S}_D^k\varphi)}{\partial\nu}\Big|_{\pm}(x) = \left(\pm\frac{1}{2}I + \left(\mathcal{K}_D^k\right)^*\right)\varphi(x), \quad \text{a.e. } x \in \partial D,$$
(2.2)

$$\left(\mathcal{D}_{D}^{k}\varphi\right)\big|_{\pm} = \left(\mp \frac{1}{2}I + \mathcal{K}_{D}^{k}\right)\varphi(x), \quad \text{a.e. } x \in \partial D,$$

$$(2.3)$$

for $\varphi \in L^2(\partial \Omega)$, where \mathcal{K}_D^k is the operator defined by

$$\mathcal{K}_{D}^{k}\varphi(x) = \mathbf{p.v.} \int_{\partial D} \frac{\partial \Phi_{k}(x, y)}{\partial v(y)} \varphi(y) \, d\sigma(y), \tag{2.4}$$

and $(\mathcal{K}_D^k)^*$ is the L^2 -adjoint of \mathcal{K}_D^k . The operator \mathcal{K}_D^k is known to be bounded on $L^2(\partial D)$ [6].

Theorem 2.1. Suppose that k_0^2 is not a Dirichlet eigenvalue for $-\Delta$ on D. For each $(F, G) \in H^1(\partial D) \times L^2(\partial D)$, there exists a unique solution $(f, g) \in L^2(\partial D) \times L^2(\partial D)$ to the integral equation

$$\begin{cases} \mathcal{S}_{D}^{k} f - \mathcal{S}_{D}^{k_{0}} g = F, \\ \frac{1}{\mu} \frac{\partial (\mathcal{S}_{D}^{k} f)}{\partial \nu} \Big|_{-} - \frac{1}{\mu_{0}} \frac{\partial (\mathcal{S}_{D}^{k_{0}} g)}{\partial \nu} \Big|_{+} = G, \end{cases}$$
 $on \ \partial D.$ (2.5)

There exists a constant C independent of F and G such that

$$\|f\|_{L^{2}(\partial D)} + \|g\|_{L^{2}(\partial D)} \leqslant C \big(\|F\|_{H^{1}(\partial D)} + \|G\|_{L^{2}(\partial D)}\big).$$
(2.6)

Proof. We only give the proof for $\mu_0 \neq \mu$ leaving the modification of the arguments presented here in the general case to the reader. Let $X := L^2(\partial D) \times L^2(\partial D)$ and $Y := H^1(\partial D) \times L^2(\partial D)$, and define an operator $T : X \to Y$ by

$$T(f,g) := \left(\mathcal{S}_D^k f - \mathcal{S}_D^{k_0} g, \frac{1}{\mu} \frac{\partial(\mathcal{S}_D^k f)}{\partial \nu} \Big|_{-} - \frac{1}{\mu_0} \frac{\partial(\mathcal{S}_D^{k_0} g)}{\partial \nu} \Big|_{+} \right)$$

We also define T_0 by

$$T_0(f,g) := \left(\mathcal{S}_D^0 f - \mathcal{S}_D^0 g, \frac{1}{\mu} \frac{\partial (\mathcal{S}_D^0 f)}{\partial \nu} \Big|_{-} - \frac{1}{\mu_0} \frac{\partial (\mathcal{S}_D^0 g)}{\partial \nu} \Big|_{+} \right).$$

One can easily see that $S_D^{k_0} - S_D^0 : L^2(\partial D) \to H^1(\partial D)$ is a compact operator, and so is $\frac{\partial}{\partial \nu} S_D^{k_0}|_{\pm} - \frac{\partial}{\partial \nu} S_D^0|_{\pm} : L^2(\partial D) \to L^2(\partial D)$. Therefore, $T - T_0$ is a compact operator from X into Y. If $\mu_0 \neq \mu$, then it is proved in [9] that $T_0 : X \to Y$ is invertible (see also [13]). Thus by the Fredholm alternatives, it is enough to prove that T is injective.

Suppose that T(f, g) = 0. Then the function *u* defined by

$$u(x) := \begin{cases} S_D^{k_0} g(x), & \text{if } x \in \mathbb{R}^d \setminus D \\ S_D^k f(x), & \text{if } x \in D, \end{cases}$$

is the unique solution of the transmission problem

$$\begin{cases} (\Delta + \omega^2 \varepsilon_0 \mu_0) u = 0 & \text{in } \mathbb{R}^d \setminus \bar{D}, \\ (\Delta + \omega^2 \varepsilon_\mu) u = 0 & \text{in } D, \\ \frac{1}{\mu} \frac{\partial u}{\partial \nu}|_{-} - \frac{1}{\mu_0} \frac{\partial u}{\partial \nu}|_{+} = 0 & \text{on } \partial D, \\ u|_{-} - u|_{+} = 0 & \text{on } \partial D, \end{cases}$$

subject to the radiation condition

$$\frac{x}{|x|} \cdot \nabla u(x) - ik_0 u(x) = O(|x|^{-(d+1)/2}), \quad |x| \to \infty.$$
(2.7)

By the uniqueness of a solution to the interface problem for the Helmholtz equation, see for instance [7], we conclude that f = g = 0. This completes the proof of solvability of (2.5). The estimate (2.6) is a consequence of solvability and the closed graph theorem. \Box

Note that in the three-dimensional case, using classical results on the low wave number asymptotics for the Helmholtz equation and single layer potential [14], it can easily be proved that f and g have limits in $L^2(\partial D)$ as k_0 and k go to zero, and thus the constant C in (2.6) can be chosen independently of k_0 and k. This remark will be of use to us in establishing Proposition 4.1 in the three-dimensional case.

3. Representation of solutions

In this section we present two representations of the solution of (1.4). A similar representation formula for the transmission problem for the harmonic equation was found in [12,13].

Theorem 3.1. Suppose that k_0^2 is not a Dirichlet eigenvalue for $-\Delta$ on D. Let u be the solution of (1.4) and $g := \frac{\partial u}{\partial v}|_{\partial\Omega}$. Define

$$H(x) := -\mathcal{S}_{\Omega}^{k_0}(g)(x) + \mathcal{D}_{\Omega}^{k_0}(f)(x), \quad x \in \mathbb{R}^d \setminus \partial\Omega,$$
(3.1)

and $(\varphi, \psi) \in L^2(\partial D) \times L^2(\partial D)$ be the unique solution of

$$\begin{cases} S_D^k \varphi - S_D^{k_0} \psi = H \\ \left| \frac{1}{\mu} \frac{\partial (S_D^k \varphi)}{\partial \nu} \right|_- - \frac{1}{\mu_0} \frac{\partial (S_D^{k_0} \psi)}{\partial \nu} \right|_+ = \frac{1}{\mu_0} \frac{\partial H}{\partial \nu} \end{cases}$$
 (3.2)

Then u can be represented as

$$u(x) = \begin{cases} H(x) + \mathcal{S}_D^{k_0} \psi(x), & x \in \Omega \setminus \bar{D}, \\ \mathcal{S}_D^k \varphi(x), & x \in D. \end{cases}$$
(3.3)

Moreover, there exists C > 0 independent of H such that

$$\|\varphi\|_{L^2(\partial D)} + \|\psi\|_{L^2(\partial D)} \leqslant C \left(\|H\|_{L^2(\partial D)} + \|\nabla H\|_{L^2(\partial D)} \right).$$

$$(3.4)$$

Proof. Note that *u* defined by (3.3) satisfies the differential equations and the transmission condition on ∂D in (1.4). Thus in order to prove (3.3), it suffices to prove $\frac{\partial u}{\partial v} = g$ on $\partial \Omega$. Let $f := u|_{\partial \Omega}$ and consider the following two phase transmission problem:

$$\begin{cases} (\Delta + k_0^2)v = 0 & \text{in } (\Omega \setminus \bar{D}) \cup (\mathbb{R}^d \setminus \bar{\Omega}), \\ (\Delta + k^2)v = 0 & \text{in } D, \\ v|_- - v|_+ = 0, \ \frac{1}{\mu} \frac{\partial v}{\partial v}|_- - \frac{1}{\mu_0} \frac{\partial v}{\partial v}|_+ = 0 & \text{on } \partial D, \\ v|_- - v|_+ = f, \ \frac{\partial v}{\partial v}|_- - \frac{\partial v}{\partial v}|_+ = g & \text{on } \partial \Omega, \\ \frac{x}{|x|} \cdot \nabla v(x) - ik_0 v(x) = O(|x|^{-(d+1)/2}), \quad |x| \to \infty. \end{cases}$$
(3.5)

We claim that (3.5) has a unique solution. In fact, if f = g = 0, then one can show as before that v = 0 in $\mathbb{R}^d \setminus \overline{D}$. Thus $v = \frac{\partial v}{\partial v}|_{-} = 0$ on ∂D . By the unique continuation for the operator $\Delta + k^2$, we have v = 0 in D, and hence $v \equiv 0$ in \mathbb{R}^d . Note that v_j , j = 1, 2, defined by

$$v_1(x) = \begin{cases} u(x), & x \in \Omega, \\ 0, & x \in \mathbb{R}^d \setminus \bar{\Omega}, \end{cases} \qquad v_2(x) = \begin{cases} H(x) + \mathcal{S}_D^{k_0} \psi(x), & x \in \Omega \setminus \bar{D}, \\ \mathcal{S}_D^k \varphi(x), & x \in D, \end{cases}$$

are two solutions of (3.5), and hence $v_1 \equiv v_2$. This completes the proof. \Box

Proposition 3.2. For each integer n there exists C_n independent of D such that

$$\|H\|_{\mathcal{C}^{n}(\bar{D})} \leqslant C_{n} \|f\|_{H^{1/2}(\partial\Omega)}.$$
(3.6)

Proof. Let $g := \frac{\partial u}{\partial v}|_{\partial \Omega}$. By the definition (3.1), it is easy to see that

$$\|H\|_{\mathcal{C}^{n}(\bar{D})} \leq C(\|g\|_{H^{-1/2}(\partial\Omega)} + \|f\|_{H^{1/2}(\partial\Omega)}),$$

where C depends only on n and dist $(D, \partial \Omega)$. Therefore, it is enough to show that

 $\|g\|_{H^{-1/2}(\partial\Omega)} \leqslant C \|f\|_{H^{1/2}(\partial\Omega)}$

for some C independent of D.

Let φ be a \mathcal{C}^{∞} function which is 0 in a neighborhood of D and 1 in a neighborhood of $\partial \Omega$. Let $v \in H^{1/2}(\partial \Omega)$ and define $\tilde{v} \in H^1(\Omega)$ to be the unique solution to $\Delta \tilde{v} = 0$ in Ω and $\tilde{v} = v$ on $\partial \Omega$. Let \langle , \rangle denote $H^{-1/2} - H^{1/2}$ pairing on $\partial \Omega$. Then

$$\begin{split} \langle g, v \rangle &= \int_{\Omega} \Delta(\varphi u) \tilde{v} \, dx + \int_{\Omega} \nabla(\varphi u) \cdot \nabla \tilde{v} \, dx \\ &= \int_{\Omega} \Delta \varphi u \tilde{v} \, dx + 2 \int_{\Omega} \nabla \varphi \cdot \nabla u \tilde{v} \, dx - k_0^2 \int_{\Omega} \varphi u \tilde{v} \, dx + \int_{\Omega} \nabla(\varphi u) \cdot \nabla \tilde{v} \, dx. \end{split}$$

Therefore, it follows from the Cauchy-Schwartz inequality that

 $\left|\langle g,v\rangle\right|\leqslant C\|u\|_{H^1(\varOmega\setminus\bar{D})}\|\tilde{v}\|_{H^1(\Omega)}\leqslant C\|u\|_{H^1(\Omega\setminus\bar{D})}\|v\|_{H^{1/2}(\partial\Omega)}.$

Since $v \in H^{1/2}(\partial \Omega)$ is arbitrary, we get

$$\|g\|_{H^{-1/2}(\partial\Omega)} \leqslant C \|u\|_{H^1(\Omega \setminus \overline{D})}.$$
(3.7)

Note that the constant *C* depends only on dist($D, \partial \Omega$). On the other hand, since ω^2 is not a Dirichlet eigenvalue for the Helmholtz equation (1.4) in Ω , we can prove that

 $\|u\|_{H^1(\Omega)} \leqslant C \|f\|_{H^{1/2}(\partial\Omega)},$

where C depends only on $\mu_0, \mu, \varepsilon_0$, and ε . It then follows from (3.7) that

 $\|g\|_{H^{-1/2}(\partial\Omega)} \leqslant C \|f\|_{H^{1/2}(\partial\Omega)}.$

This completes the proof. \Box

We now transform the representation (3.3) into the one using the Green function and the background solution. The background solution u_0 is the solution of

$$\begin{cases} (\Delta + k_0^2) u_0 = 0 & \text{in } \Omega, \\ u_0 = f & \text{on } \partial \Omega. \end{cases}$$
(3.8)

Let G(x, y) be the Dirichlet Green function for $\Delta + k_0^2$ in Ω , i.e., for each $y \in \Omega$, G is the solution of

$$\begin{cases} (\Delta + k_0^2) G(x, y) = \delta_y(x), & x \in \Omega, \\ G(x, y) = 0, & x \in \partial \Omega. \end{cases}$$

Then,

$$u_0(x) = \int_{\partial \Omega} \frac{\partial G}{\partial v_y}(x, y) f(y) \, d\sigma(y), \quad x \in \Omega.$$

Define one more notation: For a Lipschitz domain $D \subset \Omega$ and $\varphi \in L^2(\partial D)$, we define

$$G_D\varphi(x) := \int_{\partial D} G(x, y)\varphi(y) \, d\sigma(y), \quad x \in \bar{\Omega}.$$

Our second representation is the following theorem.

Theorem 3.3. Let ψ be the function defined in (3.2). Then

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \frac{\partial (G_D \psi)}{\partial \nu}(x), \quad x \in \partial \Omega.$$
(3.9)

We need a few facts to prove Theorem 3.3. We first observe an easy identity: if $x \in \mathbb{R}^d \setminus \Omega$ and $z \in \Omega$,

$$\int_{\partial \Omega} \Phi_{k_0}(x-y) \frac{\partial G(z,y)}{\partial \nu(y)} \Big|_{\partial \Omega} d\sigma(y) = \Phi_{k_0}(x,z), \quad x \in \mathbb{R}^d \setminus \Omega, \ z \in \Omega.$$
(3.10)

As a consequence of (3.10), we have

$$\left(\frac{1}{2}I + \left(\mathcal{K}_{\Omega}^{k_{0}}\right)^{*}\right)\left(\frac{\partial G(\cdot, y)}{\partial \nu(y)}\Big|_{\partial\Omega}\right)(x) = \frac{\partial \Phi_{k_{0}}(x, y)}{\partial \nu(x)}, \quad x \in \partial\Omega.$$
(3.11)

Lemma 3.4. If k_0^2 is not a Dirichlet eigenvalue for $-\Delta$ on Ω , then $\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_0})^* : L^2(\partial\Omega) \to L^2(\partial\Omega)$ is injective.

Proof. Suppose that $\varphi \in L^2(\partial \Omega)$ and $(\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_0})^*)\varphi = 0$. Define $u(x) := \mathcal{S}_{\Omega}^{k_0}\varphi(x), x \in \mathbb{R}^d \setminus \overline{\Omega}$. Then *u* is a radiating solution of $(\Delta + k_0^2)u = 0$ in $\mathbb{R}^d \setminus \overline{\Omega}$, and satisfies $\frac{\partial u}{\partial v}|_{\partial \Omega} = (\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_0})^*)\varphi = 0$. Therefore, by the uniqueness for the exterior Neumann problem [7], we obtain $\mathcal{S}_{\Omega}^{k_0}\varphi(x) = 0, x \in \mathbb{R}^d \setminus \overline{\Omega}$. Since k_0^2 is not a Dirichlet eigenvalue for $-\Delta$ on Ω , we can prove that $\varphi = 0$ in the same way as before. This completes the proof. \Box

We are now ready to prove Theorem 3.3.

Proof of Theorem 3.3. Let $g := \frac{\partial u}{\partial v}|_{\partial \Omega}$ and $g_0 := \frac{\partial u_0}{\partial v}$ for convenience. By the divergence theorem, we get

$$u_0(x) = -\mathcal{S}_{\Omega}^{k_0}(g_0)(x) + \mathcal{D}_{\Omega}^{k_0}(f)(x), \quad x \in \Omega.$$

It then follows from (3.1) that

$$H(x) = -\mathcal{S}_{\Omega}^{k_0}(g)(x) + \mathcal{S}_{\Omega}^{k_0}(g_0)(x) + u_0(x), \quad x \in \Omega$$

By substituting (3.3) into above equation, we obtain

$$H(x) = -\mathcal{S}_{\Omega}^{k_0} \left(\frac{\partial H}{\partial \nu} \bigg|_{\partial \Omega} + \frac{\partial (\mathcal{S}_D^{k_0} \psi)}{\partial \nu} \bigg|_{\partial \Omega} \right)(x) + \mathcal{S}_{\Omega}^{k_0}(g_0)(x) + u_0(x), \quad x \in \Omega.$$
(3.12)

We then get from (2.2),

$$\frac{\partial H}{\partial \nu} = -\left(-\frac{1}{2}I + \left(\mathcal{K}_{\Omega}^{k_{0}}\right)^{*}\right)\left(\frac{\partial H}{\partial \nu}\Big|_{\partial\Omega} + \frac{\partial(\mathcal{S}_{D}^{k_{0}}\psi)}{\partial\nu}\Big|_{\partial\Omega}\right) + \left(\frac{1}{2}I + \left(\mathcal{K}_{\Omega}^{k_{0}}\right)^{*}\right)(g_{0})$$

on $\partial\Omega$. (3.13)

By (3.11), we get for $x \in \partial \Omega$,

$$\frac{\partial (\mathcal{S}_{D}^{k_{0}}\psi)}{\partial \nu}(x) = \int_{\partial D} \frac{\partial \Phi_{k_{0}}(x, y)}{\partial \nu(x)} \psi(y) \, d\sigma(y) = \left(\frac{1}{2}I + \left(\mathcal{K}_{\Omega}^{k_{0}}\right)^{*}\right) \left(\frac{\partial (G_{D}\psi)}{\partial \nu}\Big|_{\partial\Omega}\right)(x).$$
(3.14)

Thus we obtain

$$\left(-\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_{0}})^{*} \right) \left(\frac{\partial (\mathcal{S}_{D}^{k_{0}}\psi)}{\partial \nu} \right|_{\partial \Omega} \right)$$

= $\left(\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_{0}})^{*} \right) \left(\left(-\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_{0}})^{*} \right) \left(\frac{\partial (G_{D}\psi)}{\partial \nu} \right|_{\partial \Omega} \right) \right) \text{ on } \partial \Omega.$

It then follows from (3.13) that

H. Ammari, H. Kang / J. Math. Anal. Appl. 296 (2004) 190-208

$$\left(\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_0})^*\right) \left(\frac{\partial H}{\partial \nu}\Big|_{\partial \Omega} + \left(-\frac{1}{2}I + (\mathcal{K}_{\Omega}^{k_0})^*\right) \left(\frac{\partial (G_D\psi)}{\partial \nu}\Big|_{\partial \Omega}\right) - g_0\right) = 0$$

on $\partial \Omega$,

and hence, by Lemma 3.4, we obtain

$$\frac{\partial H}{\partial \nu}\Big|_{\partial \Omega} + \left(-\frac{1}{2}I + \left(\mathcal{K}_{\Omega}^{k_{0}}\right)^{*}\right)\left(\frac{\partial (G_{D}\psi)}{\partial \nu}\Big|_{\partial \Omega}\right) - g_{0} = 0 \quad \text{on } \partial\Omega.$$
(3.15)

By substituting this equation into (3.3), we get

$$\frac{\partial u}{\partial \nu} = \frac{\partial u_0}{\partial \nu} - \left(-\frac{1}{2}I + \left(\mathcal{K}_{\Omega}^{k_0}\right)^* \right) \left(\frac{\partial (G_D \psi)}{\partial \nu} \Big|_{\partial \Omega} \right) + \frac{\partial (\mathcal{S}_D^{k_0} \psi)}{\partial \nu} \quad \text{on } \partial \Omega.$$

By (3.14), we have (3.9) and the proof is complete. \Box

Observe that, by
$$(2.2)$$
, (3.15) is equivalent to

$$\frac{\partial}{\partial \nu} \left(H + \mathcal{S}_{\Omega}^{k_0} \left(\frac{\partial (G_D \psi)}{\partial \nu} \Big|_{\partial \Omega} \right) - u_0 \right) \Big|_{-} = 0 \quad \text{on } \partial \Omega.$$

On the other hand, by (3.10), $S_{\Omega}^{k_0}(\frac{\partial (G_D \psi)}{\partial \nu}|_{\partial \Omega})(x) = S_{\Omega}^{k_0} \psi(x), x \in \partial \Omega$. Thus, by (3.3), we obtain

$$H(x) + S_{\Omega}^{k_0} \left(\frac{\partial (G_D \psi)}{\partial \nu} \Big|_{\partial \Omega} \right)(x) - u_0(x) = 0, \quad x \in \partial \Omega.$$

Then, by the unique continuation for $\Delta + k_0^2$, we obtain the following lemma.

Lemma 3.5.

$$H(x) = u_0(x) - S_{\Omega}^{k_0} \left(\frac{\partial (G_D \psi)}{\partial \nu} \Big|_{\partial \Omega} \right)(x), \quad x \in \Omega.$$
(3.16)

4. Derivation of asymptotic formula

Suppose that the domain *D* is of the form $D = \delta B + z$, and let *u* be the solution of (1.4). u_0 is the background solution as before. In this section we derive an asymptotic expansion of $\frac{\partial u}{\partial v}|_{\partial \Omega}$ as $\delta \to 0$ in terms of u_0 . We first derive an estimate of the form (3.4) with the constant *C* independent of δ .

Proposition 4.1. Let $D = \delta B + z$ and $(\varphi, \psi) \in L^2(\partial D) \times L^2(\partial D)$ be the unique solution of (3.2). There exists δ_0 such that for all $\delta \leq \delta_0$, there exists C independent of δ such that

$$\|\varphi\|_{L^{2}(\partial D)} + \|\psi\|_{L^{2}(\partial D)} \leqslant C \left(\delta^{-1} \|H\|_{L^{2}(\partial D)} + \|\nabla H\|_{L^{2}(\partial D)}\right).$$
(4.1)

Proof. After the scaling $x = z + \delta y$, (3.2) takes the form for d = 2, 3,

$$\begin{cases} \mathcal{S}_{B}^{k\delta}\varphi_{\delta} - \mathcal{S}_{B}^{k_{0}\delta}\psi_{\delta} = \frac{1}{\delta}H_{\delta}, \\ \frac{1}{\mu}\frac{\partial(\mathcal{S}_{B}^{k\delta}\varphi_{\delta})}{\partial\nu}\Big|_{-} - \frac{1}{\mu_{0}}\frac{\partial(\mathcal{S}_{B}^{k_{0}\delta}\psi_{\delta})}{\partial\nu}\Big|_{+} = \frac{1}{\delta\mu_{0}}\frac{\partial H_{\delta}}{\partial\nu}, \end{cases}$$
(4.2)

where $\varphi_{\delta}(y) = \varphi(z + \delta y)$, $y \in \partial B$, etc., and the single layer potentials $S_B^{k\delta}$ and $S_B^{k_0\delta}$ are defined by fundamental solutions $\Phi_{k\delta}$ and $\Phi_{k_0\delta}$, respectively. If d = 3, it then follows from Theorem 2.1 and the remark just after that for δ small enough the following estimate holds:

$$\|\varphi_{\delta}\|_{L^{2}(\partial B)} + \|\psi_{\delta}\|_{L^{2}(\partial B)} \leqslant C\delta^{-1} \|H_{\delta}\|_{H^{1}(\partial B)}, \tag{4.3}$$

for some *C* independent of δ (but depending on *B*). By scaling back, we obtain (4.1). This argument cannot be applied to the two-dimensional case because of the fact that the fundamental solutions $\Phi_{k\delta}$ and $\Phi_{k_0\delta}$ do not converge to Φ_0 as δ goes to zero.

In the two-dimensional case, we further consider the system of integral equations

$$\begin{cases} \mathcal{S}_{B}^{0}\tilde{\varphi}_{\delta} + \tau \int_{\partial B}\tilde{\varphi}_{\delta} - \mathcal{S}_{B}^{0}\tilde{\psi}_{\delta} - \tau \int_{\partial B}\tilde{\psi}_{\delta} = \frac{1}{\delta}H_{\delta}, \\ \frac{1}{\mu}\frac{\partial(\mathcal{S}_{B}^{0}\tilde{\varphi}_{\delta})}{\partial\nu}\Big|_{-} - \frac{1}{\mu_{0}}\frac{\partial(\mathcal{S}_{B}^{0}\tilde{\psi}_{\delta})}{\partial\nu}\Big|_{+} = \frac{1}{\delta\mu_{0}}\frac{\partial H_{\delta}}{\partial\nu}, \end{cases}$$
(4.4)

Here the constant τ is defined in (2.1). Recall that according to [11] the integral equation

$$\mathcal{S}_B^0 h + \tau \int\limits_{\partial B} h = g$$

has a unique solution $h \in L^2(\partial B)$ for any $g \in H^1(\partial B)$. Moreover, there exists a constant *C* independent of δ such that

$$\left\| \mathcal{S}_{B}^{k\delta}h - \mathcal{S}_{B}^{0}h - \tau \int_{\partial B} h \right\|_{H^{1}(\partial B)} \leq C \left(\delta^{2} |\log \delta| \right) \|h\|_{L^{2}(\partial B)}$$

Applying the results of [11], we can immediately prove that $(\tilde{\varphi}_{\delta} - \varphi_{\delta})/\|\varphi_{\delta}\|_{L^{2}(\partial B)}$ and $(\tilde{\psi}_{\delta} - \psi_{\delta})/\|\psi_{\delta}\|_{L^{2}(\partial B)}$ converge to zero as δ goes to zero. But

$$\|\tilde{\varphi}_{\delta}\|_{L^{2}(\partial B)}+\|\tilde{\psi}_{\delta}\|_{L^{2}(\partial B)}\leqslant C\delta^{-1}\|H_{\delta}\|_{H^{1}(\partial B)},$$

for some constant *C* independent of δ and thus, after scaling back, (4.1) holds. \Box

Let H be the function defined in (3.1). Fix an integer n and define

$$H_n(x) = \sum_{|\alpha|=0}^n \frac{\partial^{\alpha} H(z)}{\alpha!} (x-z)^{\alpha}$$

and let (φ_n, ψ_n) be the unique solution of

$$\begin{cases} \mathcal{S}_{D}^{k}\varphi_{n} - \mathcal{S}_{D}^{k_{0}}\psi_{n} = H_{n+1}, \\ \frac{1}{\mu}\frac{\partial(\mathcal{S}_{D}^{k}\varphi_{n})}{\partial\nu}\Big|_{-} - \frac{1}{\mu_{0}}\frac{\partial(\mathcal{S}_{D}^{k_{0}}\psi_{n})}{\partial\nu}\Big|_{+} = \frac{1}{\mu_{0}}\frac{\partial H_{n+1}}{\partial\nu}, \end{cases}$$
 on $\partial D.$ (4.5)

Then $(\varphi - \varphi_n, \psi - \psi_n)$ is the unique solution of (4.5) with the right-hand sides defined by $H - H_{n+1}$. Therefore, by (4.1), we get

$$\|\varphi - \varphi_n\|_{L^2(\partial D)} + \|\psi - \psi_n\|_{L^2(\partial D)} \leq C \Big(\delta^{-1} \|H - H_{n+1}\|_{L^2(\partial D)} + \|\nabla (H - H_{n+1})\|_{L^2(\partial D)} \Big).$$

$$(4.6)$$

By the definition of H_{n+1} , we have

$$\|H - H_{n+1}\|_{L^{2}(\partial D)} \leq C |\partial D|^{1/2} \|H - H_{n+1}\|_{L^{\infty}(\partial D)} \leq C |\partial D|^{1/2} \delta^{n+2} \|H\|_{\mathcal{C}^{n+2}(\bar{D})},$$

and

$$\left\|\nabla (H-H_{n+1})\right\|_{L^2(\partial D)} \leq C |\partial D|^{1/2} \delta^{n+1} \|H\|_{\mathcal{C}^{n+1}(\bar{D})}.$$

It then follows from (4.6) and Proposition 3.2 that

$$\|\varphi - \varphi_n\|_{L^2(\partial D)} + \|\psi - \psi_n\|_{L^2(\partial D)} \le C |\partial D|^{1/2} \delta^{n+1}.$$
(4.7)

By (3.9), we obtain

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \frac{\partial (G_D \psi_n)}{\partial \nu}(x) + \frac{\partial (G_D (\psi - \psi_n))}{\partial \nu}(x), \quad x \in \partial \Omega.$$
(4.8)

Since dist $(D, \partial \Omega) \ge c_0$, $\sup_{x \in \partial \Omega, y \in \partial D} |\frac{\partial G}{\partial \nu}(x, y)| \le C$ for some *C*. Hence, for each $x \in \partial \Omega$, we have from (4.7),

$$\left|\frac{\partial (G_D(\psi - \psi_n))}{\partial \nu}(x)\right| \leq \left[\int\limits_{\partial D} \left|\frac{\partial G(x, y)}{\partial \nu(x)}\right|^2 d\sigma(y)\right]^{1/2} \|\psi - \psi_n\|_{L^2(\partial D)}$$
$$\leq C |\partial D|^{1/2} |\partial D|^{1/2} \delta^{n+1} \leq C' \delta^{n+d},$$

where *C* and *C'* are independent of $x \in \partial \Omega$ and δ . Thus we conclude that

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \frac{\partial (G_D \psi_n)}{\partial \nu}(x) + O(\delta^{n+d}), \quad \text{uniformly in } x \in \partial \Omega.$$
(4.9)

For each multi-index α , define $(\varphi_{\alpha}, \psi_{\alpha})$ to be the unique solution to

$$\begin{cases} \mathcal{S}_{B}^{k\delta}\varphi_{\alpha} - \mathcal{S}_{B}^{k_{0}\delta}\psi_{\alpha} = x^{\alpha}, \\ \frac{1}{\mu}\frac{\partial(\mathcal{S}_{B}^{k\delta}\varphi_{\alpha})}{\partial\nu}\Big|_{-} - \frac{1}{\mu_{0}}\frac{\partial(\mathcal{S}_{B}^{k_{0}\delta}\psi_{\alpha})}{\partial\nu}\Big|_{+} = \frac{1}{\mu_{0}}\frac{\partial x^{\alpha}}{\partial\nu}, \end{cases}$$
 (4.10)

Then, we claim that

$$\varphi_n(x) = \sum_{|\alpha|=0}^{n+1} \delta^{|\alpha|-1} \frac{\partial^{\alpha} H(z)}{\alpha!} \varphi_{\alpha} \left(\delta^{-1}(x-z) \right),$$

$$\psi_n(x) = \sum_{|\alpha|=0}^{n+1} \delta^{|\alpha|-1} \frac{\partial^{\alpha} H(z)}{\alpha!} \psi_{\alpha} \left(\delta^{-1}(x-z) \right).$$

In fact, they follow from the uniqueness of the solution to the integral equation (2.5) and the relation

$$S_D^{k_0} \left(\sum_{|\alpha|=0}^{n+1} \delta^{|\alpha|-1} \frac{\partial^{\alpha} H(z)}{\alpha!} \varphi_{\alpha} \left(\delta^{-1} (\cdot - z) \right) \right) (x)$$
$$= \sum_{|\alpha|=0}^{n+1} \delta^{|\alpha|} \frac{\partial^{\alpha} H(z)}{\alpha!} \left(S_B^{k_0 \delta} \varphi_{\alpha} \right) \left(\delta^{-1} (x - z) \right),$$

for $x \in \partial D$. It then follows from (4.9) that

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \sum_{|\alpha|=0}^{n+1} \delta^{|\alpha|-1} \frac{\partial^{\alpha} H(z)}{\alpha!} \frac{\partial}{\partial \nu} G_D(\psi_{\alpha}(\delta^{-1}(\cdot - z)))(x) + O(\delta^{n+d}),$$
(4.11)

uniformly in $x \in \partial \Omega$. Note that

$$G_D(\psi_\alpha(\delta^{-1}(\cdot - z)))(x) = \int_{\partial D} G(x, y)\psi_\alpha(\delta^{-1}(y - z)) d\sigma(y)$$
$$= \delta^{d-1} \int_{\partial B} G(x, \delta w + z)\psi_\alpha(w) d\sigma(w).$$

Moreover, for x near $\partial \Omega$, $z \in \Omega$, $w \in \partial B$, and sufficiently small δ , we have

$$G(x, \delta w + z) = \sum_{|\beta|=0}^{\infty} \frac{\delta^{|\beta|}}{\beta!} \partial_z^{\beta} G(x, z) w^{\beta}.$$

Therefore, we get

$$G_D(\psi_\alpha(\delta^{-1}(\cdot-z)))(x) = \sum_{|\beta|=0}^{\infty} \frac{\delta^{|\beta|+d-1}}{\beta!} \partial_z^\beta G(x,z) \int_{\partial B} w^\beta \psi_\alpha(w) \, d\sigma(w).$$

Define, for multi-indices α and β in \mathbb{N}^d ,

$$W_{\alpha\beta} := \int_{\partial B} w^{\beta} \psi_{\alpha}(w) \, d\sigma(w). \tag{4.12}$$

Then we obtain the following theorem from (4.11).

Theorem 4.2. *The following pointwise asymptotic expansion on* $\partial \Omega$ *holds for d* = 2, 3:

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \delta^{d-2} \sum_{|\beta|=0}^{n+1} \sum_{|\alpha|=0}^{n-|\beta|+1} \frac{\delta^{|\alpha|+|\beta|}}{\alpha!\beta!} \partial^{\alpha} H(z) \frac{\partial \partial_z^{\beta} G(x,z)}{\partial \nu(x)} W_{\alpha\beta} + O\left(\delta^{n+d}\right),$$
(4.13)

where the remainder $O(\delta^{d+n})$ is dominated by $C\delta^{d+n} ||f||_{H^{1/2}(\partial\Omega)}$ for some C independent of $x \in \partial\Omega$.

In view of (3.9), we obtain the following expansion:

$$\frac{\partial(G_D\psi)}{\partial\nu}(x) = \delta^{d-2} \sum_{|\beta|=0}^{n+1} \sum_{|\alpha|=0}^{n-|\beta|+1} \frac{\delta^{|\alpha|+|\beta|}}{\alpha!\beta!} \partial^{\alpha} H(z) \frac{\partial\partial_z^{\beta} G(x,z)}{\partial\nu(x)} W_{\alpha\beta} + O\left(\delta^{n+d}\right).$$
(4.14)

Observe that ψ_{α} , and hence $W_{\alpha\beta}$ depends on δ , and so does *H*. Thus the formula (4.13) is not a genuine asymptotic formula. However, since it is simple and has some potential applicability in solving the inverse problem for Helmholtz equation, we made a record of it as a theorem.

Observe that by the definition (4.10) of ψ_{α} , $\|\psi_{\alpha}\|_{L^{2}(\partial B)}$ is bounded, and hence

$$|W_{\alpha\beta}| \leqslant C_{\alpha\beta}, \quad \forall \alpha, \beta, \tag{4.15}$$

where $C_{\alpha\beta}$ is independent of δ . Since δ is small, one can derive an asymptotic expansion of $(\varphi_{\alpha}, \psi_{\alpha})$ using their definition (4.10). Let us briefly explain this. Let us for simplicity assume that d = 3. Let

$$T_{\delta} \begin{bmatrix} f \\ g \end{bmatrix} := \begin{bmatrix} S_B^{k\delta} f - S_B^{k0\delta} g \\ \frac{1}{\mu} \frac{\partial (S_B^{k\delta} f)}{\partial \nu} \Big|_{-} - \frac{1}{\mu_0} \frac{\partial (S_B^{k0\delta} g)}{\partial \nu} \Big|_{+} \end{bmatrix}$$

and let T_0 be the operator when $\delta = 0$. Then the solution $(\varphi_{\alpha}, \psi_{\alpha})$ of the integral equation (4.10) is given by

$$\begin{bmatrix} \varphi_{\alpha} \\ \psi_{\alpha} \end{bmatrix} = \left[I + T_0^{-1} (T_{\delta} - T_0) \right]^{-1} T_0^{-1} \left[\frac{x^{\alpha}}{\frac{1}{\mu_0} \frac{\partial x^{\alpha}}{\partial \nu}} \right].$$
(4.16)

By expanding $T_{\delta} - T_0$ in a power series of δ , one can derive the expansions of ψ_{α} and $W_{\alpha\beta}$. Let, for $\alpha, \beta \in \mathbb{N}^d$, $(\hat{\varphi}_{\alpha}, \hat{\psi}_{\alpha})$ be the leading term of the expansion of $(\varphi_{\alpha}, \psi_{\alpha})$. Then $(\hat{\varphi}_{\alpha}, \hat{\psi}_{\alpha})$ is solution of the integral equation

$$\begin{cases} \mathcal{S}_{B}^{0}\hat{\varphi}_{\alpha} - \mathcal{S}_{B}^{0}\hat{\psi}_{\alpha} = x^{\alpha}, \\ \frac{1}{\mu}\frac{\partial(\mathcal{S}_{B}^{0}\hat{\varphi}_{\alpha})}{\partial\nu}\Big|_{-} - \frac{1}{\mu_{0}}\frac{\partial(\mathcal{S}_{B}^{0}\hat{\psi}_{\alpha})}{\partial\nu}\Big|_{+} = \frac{1}{\mu_{0}}\frac{\partial x^{\alpha}}{\partial\nu}, \end{cases} \text{ on } \partial B.$$

$$(4.17)$$

As a simplest case, let us now take n = 1 in (4.13) to find the leading order term in the asymptotic expansion of $\frac{\partial u}{\partial v}|_{\partial\Omega}$ as $\delta \to 0$. We first investigate the dependence of $W_{\alpha\beta}$ on δ for $|\alpha| \leq 1$ and $|\beta| \leq 1$. If $|\alpha| \leq 1$, then both sides of the first equation in (4.17) is harmonic in *B*, and hence

$$\mathcal{S}_B^0 \hat{\varphi}_\alpha - \mathcal{S}_B^0 \hat{\psi}_\alpha = x^\alpha \quad \text{in } B.$$

Therefore we get

$$\frac{\partial (\mathcal{S}_B^0 \hat{\varphi}_\alpha)}{\partial \nu} \bigg|_{-} - \frac{\partial (\mathcal{S}_B^0 \hat{\psi}_\alpha)}{\partial \nu} \bigg|_{-} = \frac{\partial x^\alpha}{\partial \nu} \quad \text{on } \partial B.$$

This identity together with the second equation in (4.17) yields

$$\frac{\mu}{\mu_0} \frac{\partial (\mathcal{S}^0_B \hat{\psi}_\alpha)}{\partial \nu} \bigg|_+ - \frac{\partial (\mathcal{S}^0_B \hat{\psi}_\alpha)}{\partial \nu} \bigg|_- = \left(1 - \frac{\mu}{\mu_0}\right) \frac{\partial x^\alpha}{\partial \nu}.$$

In view of the relation (2.2), we have

$$\frac{\mu}{\mu_0} \left(\frac{1}{2}I + \mathcal{K}_B^*\right) \hat{\psi}_{\alpha} - \left(-\frac{1}{2}I + \mathcal{K}_B^*\right) \hat{\psi}_{\alpha} = \left(1 - \frac{\mu}{\mu_0}\right) \frac{\partial x^{\alpha}}{\partial \nu},$$

where \mathcal{K}_B^* is the operator defined in (2.4) when k = 0. Therefore, we have

H. Ammari, H. Kang / J. Math. Anal. Appl. 296 (2004) 190-208

$$\hat{\psi}_{\alpha} = (\lambda I - \mathcal{K}_{B}^{*})^{-1} \left(\frac{\partial x^{\alpha}}{\partial \nu} \Big|_{\partial B} \right), \qquad \lambda := \frac{\mu/\mu_{0} + 1}{2(1 - \mu/\mu_{0})} = \frac{\mu_{0}/\mu + 1}{2(\mu_{0}/\mu - 1)}, \qquad (4.18)$$

203

where invertibility of the operator $\lambda I - \mathcal{K}_B^*$ is proved in [8]. Observe that if $|\alpha| = 0$, then

$$\hat{\psi}_{\alpha} = 0 \quad \text{and} \quad \mathcal{S}^0_B \hat{\varphi}_{\alpha} = 1.$$
 (4.19)

Hence we obtain $\psi_{\alpha} = O(\delta)$ and $S_B^{k\delta}\varphi_{\alpha} = 1 + O(\delta)$. Moreover, since $S_B^{k\delta}\varphi_{\alpha}$ depends on δ analytically and $(\Delta + k^2\delta^2)S_B^{k\delta}\varphi_{\alpha} = 0$ in *B*, we conclude that

$$\psi_{\alpha} = O(\delta) \quad \text{and} \quad \mathcal{S}_{B}^{k\delta}\varphi_{\alpha} = 1 + O(\delta^{2}), \quad |\alpha| = 0.$$
 (4.20)

It also follows from (4.18) that if $|\alpha| = |\beta| = 1$, then

$$W_{\alpha\beta} = \int_{\partial B} x^{\beta} \left(\lambda I - \mathcal{K}_{B}^{*}\right)^{-1} \left(\frac{\partial x^{\alpha}}{\partial \nu}\Big|_{\partial B}\right)(x) \, d\sigma + O(\delta).$$
(4.21)

According to [1], the first quantity in the right-hand side of (4.18) is the polarization tensor defined by $M = M(\mu/\mu_0) := (m_{\alpha\beta}(\mu/\mu_0))$ where

$$m_{\alpha\beta}\left(\frac{\mu}{\mu_0}\right) = \left(1 - \frac{\mu}{\mu_0}\right) \left(\delta_{\alpha\beta}|B| + \left(\frac{\mu}{\mu_0} - 1\right) \int_{\partial B} y^{\beta} \frac{\partial \theta_{\alpha}}{\partial \nu}\Big|_+(y) \, d\sigma(y)\right), \quad (4.22)$$

and θ_{α} is the unique solution of the following transmission problem:

$$\begin{cases} \Delta \theta_{\alpha}(x) = 0, & x \in B \cup \mathbb{R}^{d} \setminus \bar{B}, \\ \theta_{\alpha}|_{+} - \theta_{\alpha}|_{-} = 0 & \text{on } \partial B, \\ \frac{\partial \theta_{\alpha}}{\partial \nu}|_{+} - \frac{\mu}{\mu_{0}} \frac{\partial \theta_{\alpha}}{\partial \nu}|_{-} = \nu_{\alpha} & \text{on } \partial B, \\ \theta_{\alpha}(x) \to 0 & \text{as } |x| \to \infty. \end{cases}$$

Here $v_{\alpha} = v \cdot \alpha$ is the α -component of the normal vector v. In summary, we obtained that

$$W_{\alpha\beta} = m_{\alpha\beta} \left(\frac{\mu}{\mu_0}\right) + O(\delta), \quad |\alpha| = |\beta| = 1.$$
(4.23)

Suppose that either $\alpha = 0$ or $\beta = 0$. By (2.2) and (4.10), we have

$$\psi_{\alpha} = \frac{\partial (\mathcal{S}_{B}^{k_{0}\delta}\psi_{\alpha})}{\partial \nu}\Big|_{+} - \frac{\partial (\mathcal{S}_{B}^{k_{0}\delta}\psi_{\alpha})}{\partial \nu}\Big|_{-} = \frac{\mu_{0}}{\mu} \frac{\partial (\mathcal{S}_{B}^{k\delta}\varphi_{\alpha})}{\partial \nu}\Big|_{-} - \frac{\partial x^{\alpha}}{\partial \nu} - \frac{\partial (\mathcal{S}_{B}^{k_{0}\delta}\psi_{\alpha})}{\partial \nu}\Big|_{-}.$$
(4.24)

It then follows from divergence theorem that

$$\int_{\partial B} x^{\beta} \psi_{\alpha} \, d\sigma = -k^{2} \delta^{2} \frac{\mu_{0}}{\mu} \int_{B} x^{\beta} S_{B}^{k\delta} \varphi_{\alpha} \, dx + k_{0}^{2} \delta^{2} \int_{B} x^{\beta} S_{B}^{k_{0}\delta} \psi_{\alpha} \, dx + \frac{\mu_{0}}{\mu} \int_{\partial B} \frac{\partial x^{\beta}}{\partial \nu} S_{B}^{k\delta} \varphi_{\alpha} \, d\sigma - \int_{\partial B} \frac{\partial x^{\beta}}{\partial \nu} S_{B}^{k_{0}\delta} \psi_{\alpha} \, d\sigma.$$
(4.25)

From (4.25), we can observe the following:

$$W_{\alpha\beta} = -k^2 \delta^2 \frac{\mu_0}{\mu} |B| + O(\delta^3) = -\delta^2 \omega^2 \epsilon \mu_0 |B| + O(\delta^3), \quad |\alpha| = |\beta| = 0, \quad (4.26)$$

$$W_{\alpha\beta} = O(\delta^2), \quad |\alpha| = 1, \ |\beta| = 0,$$
 (4.27)

$$W_{\alpha\beta} = O(\delta^2), \quad |\alpha| = 0, \ |\beta| = 1.$$
 (4.28)

In fact, (4.26) and (4.28) follows from (4.20) and (4.25), and (4.27) immediately follows from (4.25). As a consequence of (4.27), (4.28), and (4.14), we obtain

$$\frac{\partial (G_D \psi)}{\partial \nu}(x) = O(\delta^d), \quad \text{uniformly on } x \in \partial \Omega.$$

Since the center z is apart from $\partial \Omega$, it follows from (3.16) that

$$|H(z) - u_0(z)| + |\nabla H(z) - \nabla u_0(z)| = O(\delta^d).$$
(4.29)

We now consider the case $|\alpha| = 2$ and $|\beta| = 0$. In this case, one can show using (4.24) that

$$\int_{\partial B} \psi_{\alpha} \, d\sigma = - \int_{B} \Delta x^{\alpha} \, dx + O\left(\delta^{2}\right).$$

Therefore, if $|\beta| = 0$, then

$$\sum_{|\alpha|=2} \frac{1}{\alpha!\beta!} \partial^{\alpha} H(z) W_{\alpha\beta} = -\Delta H(z)|B| + O(\delta^2) = k_0^2 H(z)|B| + O(\delta^2).$$
(4.30)

So (4.13) together with (4.23)–(4.30) yields the following expansion formula: for d = 3 and for any $x \in \partial \Omega$,

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \delta^d \left(\nabla u_0(z) M \left(\frac{\mu}{\mu_0} \right) \frac{\partial \nabla_z G(x, z)}{\partial \nu(x)} + \omega^2 \mu_0(\epsilon - \epsilon_0) |B| u_0(z) \frac{\partial G(x, z)}{\partial \nu(x)} \right) + O\left(\delta^{d+1}\right),$$
(4.31)

where $M = (m_{\alpha\beta})$ is the polarization tensor defined in (4.22).

Before returning to (4.13) let us make the following important remark. In [1] new concepts of higher order polarization tensors are introduced. These concepts generalize that of classical Pólya-Szegö polarization tensors. These generalized polarization tensors (GPT's) appear naturally in higher order asymptotics of the steady-state voltage potentials under the perturbation of conductor by dielectric inhomogeneities of small diameter. They seem to carry out significant information on the small dielectric inhomogeneities [3]. In this paper, the tensors $W_{\alpha\beta}$ play similar role. As defined in [1] the GPT's are given for $\alpha, \beta \in \mathbb{N}^d$ by

$$M_{\alpha\beta} := \int_{\partial B} w^{\beta} \hat{\psi}_{\alpha}(w) \, d\sigma(w)$$

where $\hat{\psi}_{\alpha}$ is defined by (4.17). The following result makes the connection between $W_{\alpha\beta}$ and $M_{\alpha\beta}$. Its proof is immediate.

Lemma 4.3. Suppose that a_{α} are constants such that $\sum_{\alpha} a_{\alpha} w^{\alpha}$ is a harmonic polynomial. Then

$$\sum_{\alpha} a_{\alpha} W_{\alpha\beta} \to \sum_{\alpha} a_{\alpha} M_{\alpha\beta} \quad as \ \delta \to 0.$$

We also note that in the two-dimensional case we should replace the operator T_{δ} by

$$\tilde{T}_{\delta} \begin{bmatrix} f \\ g \end{bmatrix} := \begin{bmatrix} \mathcal{S}_{B}^{k\delta} f + \tau \int_{\partial B} f - \mathcal{S}_{B}^{k_{0}\delta} g - \tau \int_{\partial B} g \\ \frac{1}{\mu} \frac{\partial(\mathcal{S}_{B}^{k\delta} f)}{\partial \nu} \Big|_{-} - \frac{1}{\mu_{0}} \frac{\partial(\mathcal{S}_{B}^{k_{0}\delta} g)}{\partial \nu} \Big|_{+} \end{bmatrix},$$

and T_0 by \tilde{T}_0 (the \tilde{T}_δ operator when $\delta = 0$). The results of [11] allow us again to handle the problem in the two-dimensional case. Instead of equation $S_B^0 \hat{\varphi}_\alpha = 1$ for $|\alpha| = 0$ in (4.19) we deal in this case with the well-posed equation $S_B^0 \hat{\varphi}_\alpha - \tau \int_{\partial B} \hat{\varphi}_\alpha = 1$. The zero mean-value property of $\hat{\psi}_\alpha$ for $|\alpha| = 1$ can also be easily be deduced from the system of integral equations satisfied by $(\hat{\varphi}_\alpha, \hat{\psi}_\alpha)$ using the fact that x^α is harmonic for $|\alpha| = 1$. So, in the two-dimensional case, we obtain the following expansion formula of Vogelius–Volkov [15]: for any $x \in \partial \Omega$,

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \delta^2 \left(\nabla u_0(z) M\left(\frac{\mu}{\mu_0}\right) \frac{\partial \nabla_z G(x, z)}{\partial \nu(x)} + \omega^2 \mu_0(\epsilon - \epsilon_0) |B| u_0(z) \frac{\partial G(x, z)}{\partial \nu(x)} \right) + o(\delta^2),$$
(4.32)

where $M = (m_{\alpha\beta})$ is the polarization tensor defined in (4.22). In fact, in [15], the formula is expressed in terms of 'free space' Green function Φ_k instead of the Green function *G*. However, those two formula are the same as one can see using the relation (3.11).

Observing now that the formula (4.13) still contains $\partial^{\alpha} H$ factors, the remaining task is to convert (4.13) to a formula given solely by u_0 and its derivatives. Substitution of (4.14) into (3.16) yields that, for any $x \in \Omega$,

$$H(x) = u_0(x) - \delta^{d-2} \sum_{|\beta|=0}^{n+1} \sum_{|\alpha|=0}^{n+1-|\beta|} \frac{\delta^{|\alpha|+|\beta|}}{\alpha!\beta!} \partial^{\alpha} H(z) S_{\Omega}^{k_0} \left(\frac{\partial \partial_z^{\beta} G(x,z)}{\partial \nu(x)}\right) W_{\alpha\beta} + O\left(\delta^{n+d}\right).$$
(4.33)

In (4.33) the remainder $O(\delta^{n+d})$ is uniform in the \mathcal{C}^n norm on any compact subset of Ω for any *n* and therefore

$$\left(\partial^{\gamma}H\right)(z) + \delta^{d-2}\sum_{|\beta|=0}^{n+1}\sum_{|\alpha|=0}^{n+1-|\beta|}\delta^{|\alpha|+|\beta|}\partial^{\alpha}H(z)P_{\alpha\beta\gamma} = \left(\partial^{\gamma}u_{0}\right)(z) + O\left(\delta^{d+n}\right),$$
(4.34)

for all $\gamma \in \mathbb{N}^d$ with $|\gamma| \leq n + 1$ where

$$P_{\alpha\beta\gamma} = \frac{1}{\alpha!\beta!} W_{\alpha\beta} \partial^{\gamma} S_{\Omega}^{k_0} \left(\frac{\partial \partial_z^{\beta} G(\cdot, z)}{\partial \nu(x)} \right) \Big|_{x=z}.$$
(4.35)

Following [1], define the operator \mathcal{P}_{δ} by

$$\mathcal{P}_{\delta}: (w_{\gamma})_{\gamma \in \mathbb{N}^{d}, |\gamma| \leq n} \mapsto \left(w_{\gamma} + \delta^{d-2} \sum_{|\beta|=0}^{n+1} \sum_{|\alpha|=0}^{n+1-|\beta|} \delta^{|\alpha|+|\beta|} w_{\alpha} P_{\alpha\beta\gamma} \right)_{\gamma \in \mathbb{N}^{d}, |\gamma| \leq n}$$

Observe from (4.16) that \mathcal{P}_{δ} can be written as

$$\mathcal{P}_{\delta} = I + \delta^{d} \mathcal{P}_{1} + \dots + \delta^{n+d-1} \mathcal{P}_{n-1} + O\left(\delta^{n+d}\right).$$

Defining as in [1] Q_p , p = 1, ..., n - 1, by

$$(I + \delta^{d} \mathcal{P}_{1} + \dots + \delta^{n+d-1} \mathcal{P}_{n-1})^{-1} = I + \delta^{d} \mathcal{Q}_{1} + \dots + \delta^{n+d-1} \mathcal{Q}_{n-1} + O(\delta^{n+d}),$$
(4.36)

we finally obtain that

$$\left(\left(\partial^{\alpha}H\right)(z)\right)_{\alpha\in\mathbb{N}^{d},\,|\alpha|\leqslant n+1} = \left(I + \sum_{p=1}^{n} \delta^{d+p-1}\mathcal{Q}_{p}\right)\left(\left(\partial^{\alpha}u_{0}\right)(z)\right)_{\alpha\in\mathbb{N}^{d},\,|\alpha|\leqslant n+1} + O\left(\delta^{d+n}\right),\tag{4.37}$$

which yields the main result of this paper.

Theorem 4.4. *The following pointwise asymptotic expansion on* $\partial \Omega$ *holds for d* = 2, 3:

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \delta^{d-2} \sum_{|\beta|=0}^{n+1} \sum_{|\alpha|=0}^{n+1-|\beta|} \frac{\delta^{|\alpha|+|\beta|}}{\alpha!\beta!} \times \left[\left(\left(I + \sum_{p=1}^{n+2-|\alpha|-|\beta|-d} \delta^{d+p-1} \mathcal{Q}_p \right) (\partial^{\gamma} u_0(z)) \right)_{\alpha} \frac{\partial \partial_z^{\beta} G(x,z)}{\partial \nu(x)} W_{\alpha\beta} \right] \\
+ O(\delta^{n+d}),$$
(4.38)

where the remainder $O(\delta^{d+n})$ is dominated by $C\delta^{d+n} ||f||_{H^{1/2}(\partial\Omega)}$ for some C independent of $x \in \partial\Omega$.

When n = d, we have a simpler formula

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \delta^{d-2} \sum_{|\beta|=0}^{d+1} \sum_{|\alpha|=0}^{d+1-|\beta|} \frac{\delta^{|\alpha|+|\beta|}}{\alpha!\beta!} \partial^{\alpha} u_0(z) \frac{\partial \partial_z^{\beta} G(x,z)}{\partial \nu(x)} W_{\alpha\beta} + O\left(\delta^{2d}\right).$$
(4.39)

Let us now consider the case when there are several well-separated inclusions. The inhomogeneity *D* takes the form $\bigcup_{s=1}^{m} (\delta B_s + z_s)$. The magnetic permeability and electric permittivity of the inclusion $\delta B_s + z_s$ are μ_s and ϵ_s , s = 1, ..., m. By iterating the formula (4.39), we can derive the following theorem.

Theorem 4.5. *The following pointwise asymptotic expansion on* $\partial \Omega$ *holds for d* = 2, 3:

$$\frac{\partial u}{\partial \nu}(x) = \frac{\partial u_0}{\partial \nu}(x) + \delta^{d-2} \sum_{s=1}^m \sum_{|\beta|=0}^{d+1} \sum_{|\alpha|=0}^{d+1-|\beta|} \frac{\delta^{|\alpha|+|\beta|}}{\alpha!\beta!} \partial^{\alpha} u_0(z) \frac{\partial \partial_z^{\beta} G(x,z)}{\partial \nu(x)} W^s_{\alpha\beta} + O\left(\delta^{2d}\right).$$
(4.40)

Here $W^s_{\alpha\beta}$ is defined by (4.12) with B, μ, ϵ replaced by B_s, μ_s, ϵ_s .

We conclude this paper by making one final remark. In this paper, we only derive the asymptotic formula for the solution to the Dirichlet problem. However, by the same method, one can derive an asymptotic formula for the Neumann problem as well.

Acknowledgments

The authors are very grateful to the referees for their careful reading to a first version of this paper and all the corrections they have pointed out to them.

References

- H. Ammari, H. Kang, High-order terms in the asymptotic expansions of the steady-state voltage potentials in the presence of conductivity inhomogeneities of small diameter, SIAM J. Math. Anal. 34 (2003) 1152–1166.
- [2] H. Ammari, H. Kang, A new method for reconstructing electromagnetic inhomogeneities of small volume, Inverse Problems 19 (2003) 63–71.
- [3] H. Ammari, H. Kang, Properties of the generalized polarization tensors, Multiscale Modeling and Simulation: A SIAM Interdiscip. J. 1 (2003) 335–348.
- [4] H. Ammari, A. Khelifi, Electromagnetic scattering by small dielectric inhomogeneities, J. Math. Pures Appl. (9) 82 (2003) 749–842.
- [5] D.J. Cedio-Fengya, S. Moskow, M.S. Vogelius, Identification of conductivity imperfections of small diameter by boundary measurements: Continuous dependence and computational reconstruction, Inverse Problems 14 (1998) 553–595.
- [6] R.R. Coifman, A. McIntosh, Y. Meyer, L'intégrale de Cauchy définit un opérateur bourné sur L² pour les courbes Lipschitziennes, Ann. of Math. (2) 116 (1982) 361–387.
- [7] D. Colton, R. Kress, Inverse Acoustic and Electromagnetic Scattering Theory, in: Appl. Math. Sci., vol. 93, Springer-Verlag, New York, 1992.
- [8] L. Escauriaza, E.B. Fabes, G. Verchota, On a regularity theorem for weak solutions to transmission problems with internal Lipschitz boundaries, Proc. Amer. Math. Soc. 115 (1992) 1069–1076.
- [9] L. Escauriaza, J.K. Seo, Regularity properties of solutions to transmission problems, Trans. Amer. Math. Soc. 338 (1993) 405–430.
- [10] A. Friedman, M.S. Vogelius, Identification of small inhomogeneities of extreme conductivity by boundary measurements: a theorem on continuous dependence, Arch. Rational Mech. Anal. 105 (1989) 299–326.
- [11] S.I. Hariharan, R.C. MacCamy, Low frequency acoustic and electromagnetic scattering, Appl. Numer. Math. 2 (1986) 29–35.
- [12] H. Kang, J.K. Seo, Layer potential techniques for the inverse conductivity problems, Inverse Problems 12 (1996) 267–278.
- [13] H. Kang, J.K. Seo, Recent progress in the inverse conductivity problem with single measurement, in: Inverse Problems and Related Fields, CRC Press, Boca Raton, FL, 2000, pp. 69–80.
- [14] R.E. Kleinman, T.B.A. Senior, Rayleigh scattering, in: V.K. Varadan, V.V. Varadan (Eds.), Low and High Frequency Asymptotics, North-Holland, Amsterdam, 1986, pp. 1–70.

H. Ammari, H. Kang / J. Math. Anal. Appl. 296 (2004) 190-208

- [15] M.S. Vogelius, D. Volkov, Asymptotic formulas for perturbations in the electromagnetic fields due to the [16] D. Volkov, Numerical methods for locating small dielectric inhomogeneities, Wave Motion 38 (2003) 189–
- 206.