# Error expansion for the discretization of backward stochastic differential equations 

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#### Abstract

We study the error induced by the time discretization of decoupled forward-backward stochastic differential equations ( $X, Y, Z$ ). The forward component $X$ is the solution of a Brownian stochastic differential equation and is approximated by a Euler scheme $X^{N}$ with $N$ time steps. The backward component is approximated by a backward scheme. Firstly, we prove that the errors ( $Y^{N}-Y, Z^{N}-Z$ ) measured in the strong $L_{p}$-sense ( $p \geq 1$ ) are of order $N^{-1 / 2}$ (this generalizes the results by Zhang [J. Zhang, A numerical scheme for BSDEs, The Annals of Applied Probability 14 (1) (2004) 459-488]). Secondly, an error expansion is derived: surprisingly, the first term is proportional to $X^{N}-X$ while residual terms are of order $N^{-1}$.


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## 1. Introduction

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a given probability space on which is defined a $q$-dimensional standard Brownian motion $W$, whose natural filtration, augmented with $\mathbb{P}$-null sets, is denoted by $\left(\mathcal{F}_{t}\right)_{0 \leq t \leq T}$ ( $T$ is a fixed terminal time). We consider the solution $(X, Y, Z)$ to a decoupled

[^0]forward-backward stochastic differential equation (FBSDE in short). Namely, $X$ is the $\mathbb{R}^{d}$-valued process solution of
\[

$$
\begin{equation*}
X_{t}=x+\int_{0}^{t} b\left(s, X_{s}\right) \mathrm{d} s+\int_{0}^{t} \sigma\left(s, X_{s}\right) \mathrm{d} W_{s}, \tag{1}
\end{equation*}
$$

\]

and $Y$ (resp. $Z$ ) is a real-valued adapted (resp. predictable $\mathbb{R}^{q}$-valued) process solution of

$$
\begin{equation*}
-\mathrm{d} Y_{t}=f\left(t, X_{t}, Y_{t}, Z_{t}\right) \mathrm{d} t-Z_{t} \mathrm{~d} W_{t}, \quad Y_{T}=\Phi\left(X_{T}\right) \tag{2}
\end{equation*}
$$

We assume standard Lipschitz properties on the coefficients, which ensure existence and uniqueness in appropriate $L_{2}$-spaces (see Pardoux and Peng [18], or Ma and Yong [14] for numerous references). During the last decade, more and more attention has been paid to these equations, because of their natural applications in Mathematical Finance or in the probabilistic resolution of semi-linear partial differential equations (PDE in short): see El Karoui et al. [5] or Pardoux [17].

Our aim is to study the most usual time approximation of $(X, Y, Z)$. For $X$, we use the Euler scheme $X^{N}$ with $N$ discretization times $\left(t_{k}=k h\right)_{0 \leq k \leq N}\left(h=\frac{T}{N}\right.$ is the time step). For convenience, set $\Delta W_{k}=W_{t_{k+1}}-W_{t_{k}}$ ( $\Delta W_{k}^{l}$ componentwise). $X^{N}$ is defined by $X_{0}^{N}=x$ and

$$
\begin{equation*}
t \in\left[t_{k}, t_{k+1}\right], \quad X_{t}^{N}=X_{t_{k}}^{N}+b\left(t_{k}, X_{t_{k}}^{N}\right)\left(t-t_{k}\right)+\sigma\left(t_{k}, X_{t_{k}}^{N}\right)\left(W_{t}-W_{t_{k}}\right) \tag{3}
\end{equation*}
$$

The backward SDE (2) is approximated by $\left(Y^{N}, Z^{N}\right)$ defined in a backward manner by $Y_{t_{N}}^{N}=\Phi\left(X_{t_{N}}^{N}\right)$ and

$$
\begin{align*}
& Y_{t_{k}}^{N}=\mathbb{E}_{t_{k}}\left(Y_{t_{k+1}}^{N}\right)+h \mathbb{E}_{t_{k}} f\left(t_{k}, X_{t_{k}}^{N}, Y_{t_{k+1}}^{N}, Z_{t_{k}}^{N}\right),  \tag{4}\\
& h Z_{t_{k}}^{N}=\mathbb{E}_{t_{k}}\left(Y_{t_{k+1}}^{N} \Delta W_{k}^{*}\right), \tag{5}
\end{align*}
$$

where $\mathbb{E}_{t_{k}}$ is the conditional expectation w.r.t. $\mathcal{F}_{t_{k}}$ and $*$ is the transpose operator. Additional tools are needed to derive a fully implementable scheme, in particular for the computations of conditional expectations. We refer to Bouchard and Touzi [2] for Malliavin calculus techniques, or to Gobet et al. [6] and Lemor et al. [13] for empirical regression methods. In this work, we leave these further questions and we only address the error analysis between $(Y, Z)$ and $\left(Y^{N}, Z^{N}\right)$.

On the one hand, Zhang [20] proves (in a slightly different form) that the error $\max _{k \leq N} \| Y_{t_{k}}^{N}-$ $Y_{t_{k}} \|_{L_{2}} \leq C N^{-1 / 2}$. This is done under rather minimal Lipschitz assumptions on $b, \sigma, f, \Phi$. On the other hand, when $f$ does not depend on $z$ and the coefficients are smooth, one knows that $\left|Y_{0}^{N}-Y_{0}\right| \leq C N^{-1}$ (see Chevance [3]). We aim at filling the gap regarding these two different rates of convergence. In the following, we prove that

- Chevance's results are extended to the case of $f$ depending also on $z$.
- The rate $N^{-1}$ holds true also for the difference $\left|Z_{0}^{N}-Z_{0}\right|$.
- More generally, for the other discretization times $t_{k}$, we expand the error as

$$
\left|Y_{t_{k}}^{N}-Y_{t_{k}}-\alpha_{k} \cdot\left(X_{t_{k}}^{N}-X_{t_{k}}\right)\right| \leq C N^{-1} \vee\left|X_{t_{k}}^{N}-X_{t_{k}}\right|^{2}
$$

(for an explicit and bounded random vector $\alpha_{k}$ ).

- An analogous expansion is available for $Z$.

Since $\left|X_{t_{k}}^{N}-X_{t_{k}}\right|^{2}$ has the same order in $L_{p}$ than $N^{-1}$, the error on $Y$ is mainly due to the error $X_{t_{k}}^{N}-X_{t_{k}}$. Thus, Zhang's results are a consequence of this expansion, and Chevance's ones as well since $X_{0}^{N}=X_{0}$. The gap is filled.

In addition, we learn from this expansion that if one could perfectly simulate $X$ (as for Brownian motion with constant drift, geometric Brownian motion or Ornstein-Uhlenbeck process), the error on the BSDE would be of order $N^{-1}$ and not $N^{-1 / 2}$ as stated by Zhang's results. Also, if one could use a discretization scheme for $X$ of order 1 for the strong error (for instance Milshtein scheme whenever possible), the error on the BSDE would be of order $N^{-1}$ (we would need to extend our analysis to other discretization schemes, this is straightforward for the Milshtein scheme).

The paper is organized as follows. In Section 2, we define the assumptions on the coefficients, recall the connection between BSDEs and semi-linear PDEs (which is important for our analysis). Finally, we state our main results. Firstly in Theorem 6, we extend Zhang's results to $L_{p}$-norm. Secondly in Theorem 7, we expand the error on $Y$. Lastly in Theorem 8, we deal with the error on $Z$. Naturally, stronger and stronger assumptions are required for these theorems. Proofs of the three results are postponed to Sections 3-5: we combine BSDE techniques, martingale estimates and Malliavin calculus.

## Notation

- Differentiation. If $g: \mathbb{R}^{d} \mapsto \mathbb{R}^{q}$ is a differentiable function, its gradient $\nabla_{x} g(x)=$ $\left(\partial_{x_{1}} g(x), \ldots, \partial_{x_{d}} g(x)\right)$ takes values in $\mathbb{R}^{q} \otimes \mathbb{R}^{d}$. At many places, $\nabla_{x} g(x)$ will simply be denoted $g^{\prime}(x)$. If $g: \mathbb{R}^{d} \mapsto \mathbb{R}$ is a twice differentiable function, its Hessian $H_{x}(g)$ takes values in $\mathbb{R}^{d} \otimes \mathbb{R}^{d}:\left(H_{x}(g)\right)_{i, j}=\partial_{x_{i} x_{j}}^{2} g$. If $g: \mathbb{R}^{d} \times \mathbb{R}^{q} \mapsto \mathbb{R}, g_{x y}^{\prime \prime}(x, y)$ takes values in $\mathbb{R}^{d} \otimes \mathbb{R}^{q}:\left(g_{x y}^{\prime \prime}\right)_{i j}=\frac{\partial^{2} g}{\partial x_{i} \partial y_{j}}$, for $1 \leq i \leq d, 1 \leq j \leq q$.
- Function spaces. For an integer $k \geq 1$, we denote by $C_{b}^{k / 2, k, k, k}$ the set of continuously differentiable functions $\phi:(t, x, y, z) \in[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{q} \mapsto \phi(t, x, y, z)$ such that the partial derivatives $\partial_{t}^{l_{0}} \partial_{x}^{l_{1}} \partial_{y}^{l_{2}} \partial_{z}^{l_{3}} \phi(t, x, y, z)$ exist for $2 l_{0}+l_{1}+l_{2}+l_{2} \leq k$ and are uniformly bounded. The analogous set of functions that do not depend on $y$ and $z$ is denoted by $C_{b}^{k / 2, k}$. This set is denoted by $C_{b}^{(k+\alpha) / 2, k+\alpha}(\alpha \in] 0,1[)$ if in addition the highest derivatives are Hölder continuous with index $\alpha$ w.r.t. $x$ and $\alpha / 2$ w.r.t. $t$ (for a precise definition, see Ladyzenskaja et al. [12]).
- Norm. For a $d$-dimensional vector $U$, we set $|U|^{2}=\sum_{i=1}^{d} U_{i}^{2}$. For a $d \times q$-dimensional matrix $A, A_{i}$ denotes its $i$ th column, and $A^{i}$ its $i$ th row. Moreover, $|A|^{2}=\sum_{i, j=1}^{d, q} A_{i, j}^{2}$.
- Constants. Let $C$ denote a generic constant which may depend on the coefficients $b, \sigma, f, \Phi$ and on the dimensions $d$ and $q$. We will keep the same notation $K(T)$ for all finite, nonnegative, and non-decreasing functions w.r.t. $T$ : they do not depend on $x$ and $h$. The generic notation $K(T, x)$ stands for any function bounded by $K(T)\left(1+|x|^{q}\right)$, for some $q \geq 0$.
- $O(U)$ and $O_{k}(h)$. A random vector $R$ is such that $R=O(U)$ for a non-negative random variable $U$ if $|R| \leq K(T, x) U$ (in particular, $R=O(h)$ means $|R| \leq$ $K(T, x) h)$. The notation $R=O_{k}\left(h^{p}\right)$ means $|R| \leq \lambda_{k}^{N} h^{p}$, where $\lambda_{k}^{N}$ is $\mathcal{F}_{t_{k}}$-measurable, $\sup _{N} \mathbb{E}\left(\sup _{k}\left|\lambda_{k}^{N}\right|^{q}\right) \leq K(T, x)$, for $q \geq 1$.
- $\mathbb{E}_{t_{k}}$ and $\operatorname{Var}_{t_{k}}$. $\mathbb{E}_{t_{k}}$ is the conditional expectation w.r.t. $\mathcal{F}_{t_{k}}$ and $\operatorname{Var}_{t_{k}}(X)=\mathbb{E}_{t_{k}}\left(X^{2}\right)-$ $\left(\mathbb{E}_{t_{k}}(X)\right)^{2}$.
- Malliavin calculus. We use the notations of Nualart [16] for weak spaces $\mathbb{D}^{k, p}$.
- Discretization. Let $s \in\left[t_{k}, t_{k+1}\left[\right.\right.$. We define $\eta(s)=t_{k}$.


## 2. Main results

### 2.1. Hypotheses

The coefficients $b:[0, T] \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}, \sigma:[0, T] \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{d \times q}, f:[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{q} \rightarrow$ $\mathbb{R}$ and $\Phi: \mathbb{R}^{d} \rightarrow \mathbb{R}$ satisfy one of the following set of assumptions.

Hypothesis 1. The functions $b, \sigma, f$ and $\Phi$ are bounded in $x$, are uniformly Lipschitz continuous w.r.t. ( $x, y, z$ ) and Hölder continuous of parameter $\frac{1}{2}$ w.r.t. $t$. In addition, $\Phi$ is of class $C_{b}^{2+\alpha}$ for some $\alpha \in] 0,1\left[\right.$ and the matrix-valued function $a=\sigma \sigma^{*}$ is uniformly elliptic.
Hypothesis 2. Assume Hypothesis 1 and that the functions $b, \sigma$ are in $C_{b}^{\frac{3}{2}, 3}, f$ is in $C_{b}^{\frac{3}{2}, 3,3,3}, \Phi$ is in $C_{b}^{3+\alpha}$ for some $\left.\alpha \in\right] 0,1[$.
Hypothesis 3. Assume Hypothesis 1 and that the functions $b, \sigma$ are in $C_{b}^{2,4}, f$ is in $C_{b}^{2,4,4,4}, \Phi$ is in $C_{b}^{4+\alpha}$ for some $\left.\alpha \in\right] 0,1[$.

We do not assert that these smoothness and boundedness conditions are the weakest ones for our error analysis, but they are sufficient. Investigations regarding minimal assumptions would be certainly interesting but it is beyond the scope of the paper.

### 2.2. Connection between Markovian BSDEs and semi-linear parabolic PDEs

We recall classical results connecting $(Y, Z)$ and the solution and its gradient of the following semi-linear PDE on $[0, T] \times \mathbb{R}^{d}:$

$$
\begin{align*}
& \left(\partial_{t}+\mathcal{L}_{(t, x)}\right) u(t, x)+f\left(t, x, u(t, x), \nabla_{x} u(t, x) \sigma(t, x)\right)=0,  \tag{6}\\
& u(T, x)=\Phi(x)
\end{align*}
$$

where $\mathcal{L}_{(t, x)}$ is the second order differential operator

$$
\mathcal{L}_{(t, x)}=\frac{1}{2} \sum_{i, j}\left[\sigma \sigma^{*}\right]_{i j}(t, x) \partial_{x_{i} x_{j}}^{2}+\sum_{i} b_{i}(t, x) \partial_{x_{i}}
$$

(see for instance Ma and Zhang [15] or Pardoux [17]).
Proposition 4. Under Hypothesis 1, one has

$$
\begin{equation*}
\forall t \in[0, T], \quad Y_{t}=u\left(t, X_{t}\right), \quad Z_{t}=\nabla_{x} u\left(t, X_{t}\right) \sigma\left(t, X_{t}\right), \tag{7}
\end{equation*}
$$

where $u$ is the unique classic solution $C_{b}^{1,2}$ of the $\operatorname{PDE}$ (6).
In addition under Hypothesis $2, u \in C_{b}^{\frac{3}{2}, 3}$, and under Hypothesis $3, u \in C_{b}^{2,4}$.
The first result of this Proposition corresponds to Theorem 2.1 of Delarue and Menozzi [4]. The two last regularity results can be proved in the same way. In fact for this, we would only need $b, \sigma$ to be in $C_{b}^{1+\alpha / 2,2+\alpha}$; the additional smoothness is used later for Malliavin calculus computations.

### 2.3. Main results

We now turn to the statement of our results. We remind the following well-known upper bound on the Euler Scheme, which is useful in the sequel.

Proposition 5. Let $\sigma$ and $b$ be Lipschitz continuous. Then

$$
\forall p \geq 1, \quad\left[\mathbb{E}\left(\sup _{t \leq T}\left|X_{t}^{N}-X_{t}\right|^{p}\right)\right]^{\frac{1}{p}} \leq K(T, x) \frac{1}{\sqrt{N}} .
$$

In fact, for all $p \geq 1$ one has

$$
\begin{equation*}
\left[\mathbb{E}_{t_{i}}\left(\sup _{t_{i} \leq t \leq T}\left|X_{t}^{N}-X_{t}\right|^{p}\right)\right]^{\frac{1}{p}} \leq K\left(T, X_{t_{i}}\right) \frac{1}{\sqrt{N}}+\left|X_{t_{i}}^{N}-X_{t_{i}}\right| \tag{8}
\end{equation*}
$$

Our first result is an extension of the $L_{2}$-estimates in Zhang [20] to $L_{q}$-estimates (see also Gobet et al. [6]).

Theorem 6. Let us assume Hypothesis 1. Let $q>0$. We define the error

$$
e_{q}(N)=\left[\max _{0 \leq k \leq N} \mathbb{E}\left|Y_{t_{k}}-Y_{t_{k}}^{N}\right|^{q}+\mathbb{E}\left(\sum_{k=0}^{N-1} \int_{t_{k}}^{t_{k+1}}\left|Z_{t_{k}}^{N}-Z_{t}\right|^{2} \mathrm{~d} t\right)^{\frac{q}{2}}\right]^{\frac{1}{q}},
$$

where $Y^{N}$ and $Z^{N}$ are defined by (4) and (5). Then $\left|e_{q}(N)\right| \leq K(T, x) \frac{1}{\sqrt{N}}$.
By slightly strengthening the smoothness assumptions on $b, \sigma, f$ and $\Phi$, we are able to expand the error on $Y$.

Theorem 7. Let us assume Hypothesis 2. Then, the following expansion holds

$$
Y_{t_{k}}^{N}-Y_{t_{k}}=\nabla_{x} u\left(t_{k}, X_{t_{k}}\right)\left(X_{t_{k}}^{N}-X_{t_{k}}\right)+O_{k}\left(\frac{1}{N}\right)+O\left(\left|X_{t_{k}}^{N}-X_{t_{k}}\right|^{2}\right)
$$

In view of Proposition 5, $\left|X_{t_{k}}^{N}-X_{t_{k}}\right|^{2}$ and $N^{-1}$ have the same order (in $L_{p}$ ). Hence it turns out that $\nabla_{x} u\left(t_{k}, X_{t_{k}}\right)\left(X_{t_{k}}^{N}-X_{t_{k}}\right)$ is the first order term in the error $Y_{t_{k}}^{N}-Y_{t_{k}}$. Obviously, this estimate implies that of Theorem 6. As mentioned in the introduction, the evaluation of $Y_{0}$ by $Y_{0}^{N}$ has still an accuracy of order $N^{-1}$ since initial conditions for $X^{N}$ and $X$ coincide. Note that if there is no discretization error for the process $X, Y_{t_{k}}^{N}-Y_{t_{k}}=O\left(\frac{1}{N}\right)$, a fact which is not clear from Eqs. (4) and (5). A nice situation corresponds to $\sigma$ independent of $x$ (this is a very specific situation where Euler and Milshtein schemes are equal): in that case $\left\|X_{t_{k}}^{N}-X_{t_{k}}\right\|_{L_{p}}=O\left(N^{-1}\right)$ and one gets the order of accuracy $N^{-1}$ for $Y$.

For $Z$ which plays the role of a gradient relative to $Y$, we get an analogous result about the error, up to increasing by 1 the degree of smoothness of the coefficients.

Theorem 8. Let us assume Hypothesis 3. Then, the following expansion holds

$$
Z_{t_{k}}^{N}-Z_{t_{k}}=\left(\nabla_{x}\left[\nabla_{x} u \sigma\right]^{*}\left(t_{k}, X_{t_{k}}\right)\left(X_{t_{k}}^{N}-X_{t_{k}}\right)\right)^{*}+O_{k}\left(\frac{1}{N}\right)+O\left(\left|X_{t_{k}}^{N}-X_{t_{k}}\right|^{2}\right)
$$

Remark 9. The above results are sufficient to derive the weak convergence of the renormalized error process $\left[\sqrt{N}\left(Y_{t}^{N}-Y_{t}\right)\right]_{0 \leq t \leq T}$ and $\left[\sqrt{N}\left(Z_{t}^{N}-Z_{t}\right)\right]_{0 \leq t \leq T}$, except that one has to define $Y^{N}$
and $Z^{N}$ between discretization times. For $t \in\left[t_{k}, t_{k+1}[\right.$, analogously to (4) and (5) we define

$$
\begin{aligned}
Y_{t}^{N} & =\mathbb{E}_{t}\left(Y_{t_{k+1}}^{N}+\left(t_{k+1}-t\right) f\left(t, X_{t}^{N}, Y_{t_{k+1}}^{N}, Z_{t}^{N}\right)\right) \\
Z_{t}^{N} & =\frac{1}{t_{k+1}-t} \mathbb{E}_{t}\left(Y_{t_{k+1}}^{N}\left(W_{t_{k+1}}-W_{t}\right)^{*}\right)
\end{aligned}
$$

Theorems 7 and 8 can be extended to all $t \in[0, T]$. We have

$$
\begin{aligned}
Y_{t}^{N}-Y_{t} & =\nabla_{x} u\left(t, X_{t}\right)\left(X_{t}^{N}-X_{t}\right)+O_{t}\left(\frac{1}{N}\right)+O\left(\left|X_{t}^{N}-X_{t}\right|^{2}\right) \\
Z_{t}^{N}-Z_{t} & =\left(\nabla_{x}\left[\nabla_{x} u \sigma\right]^{*}\left(t, X_{t}\right)\left(X_{t}^{N}-X_{t}\right)\right)^{*}+O_{t}\left(\frac{1}{N}\right)+O\left(\left|X_{t}^{N}-X_{t}\right|^{2}\right)
\end{aligned}
$$

Theorem 3.5 of Kurtz and Protter [11] allows us to establish the weak convergence of the processes $\sqrt{N}\left(Y^{N}-Y\right)$, and $\sqrt{N}\left(Z^{N}-Z\right)$. Indeed, the process $\left[\sqrt{N}\left(X_{t}^{N}-X_{t}\right)\right]_{0 \leq t \leq T}$ weakly converges to the solution of

$$
\begin{aligned}
U_{t}= & \sum_{i=1}^{q} \int_{0}^{t} \nabla_{x} \sigma_{i}\left(s, X_{s}\right) U_{s} \mathrm{~d} W_{s}^{i}+\int_{0}^{t} \nabla_{x} b\left(s, X_{s}\right) U_{s} \mathrm{~d} s \\
& +\frac{1}{\sqrt{2}} \sum_{i, j=1}^{q} \int_{0}^{t} \sum_{k=1}^{d} \partial_{x_{k}} \sigma_{i}\left(s, X_{s}\right) \sigma_{k j}\left(s, X_{s}\right) \mathrm{d} V_{s}^{i j}
\end{aligned}
$$

where $\left(V^{i j}\right)_{1 \leq i, j \leq q}$ are independent standard Brownian motions and independent of $W$. Furthermore, the convergence is stable (see Jacod and Protter [9]). Hence, $\left[\sqrt{N}\left(X_{t}^{N}-X_{t}\right), \sqrt{N}\left(Y_{t}^{N}-\right.\right.$ $\left.\left.Y_{t}\right), \sqrt{N}\left(Z_{t}^{N}-Z_{t}\right), X_{t}\right]_{0 \leq t \leq T}$ weakly converges to $\left[U_{t}, \nabla_{x} u\left(t, X_{t}\right) U_{t},\left(\left[\nabla_{x}\left[\nabla_{x} u \sigma\right]^{*}\left(t, X_{t}\right)\right] U_{t}\right)^{*}\right.$, $\left.X_{t}\right]_{0 \leq t \leq T}$.

### 2.4. Comments

### 2.4.1. Weak error

From Theorems 7 and 8 we can derive estimates related to the weak errors on $Y$ and $Z$.
Theorem 10. Let $\psi$ be a three times continuously differentiable function with bounded derivatives. Let us assume Hypothesis 2. Then, one has

$$
\mathbb{E}\left(\psi\left(Y_{t_{k}}^{N}\right)-\psi\left(Y_{t_{k}}\right)\right)=O\left(\frac{1}{N}\right)
$$

Under Hypothesis 3, the same result applies to $Z$.
Proof. A Taylor expansion of $\psi$ yields

$$
\mathbb{E}\left(\psi\left(Y_{t_{k}}^{N}\right)-\psi\left(Y_{t_{k}}\right)\right)=\mathbb{E}\left(\left(Y_{t_{k}}^{N}-Y_{t_{k}}\right) \psi^{\prime}\left(Y_{t_{k}}\right)\right)+O\left(\left(Y_{t_{k}}^{N}-Y_{t_{k}}\right)^{2}\right)
$$

By using Theorem 7, we get

$$
\begin{aligned}
\mathbb{E} & \left(\left(Y_{t_{k}}^{N}-Y_{t_{k}}\right) \psi^{\prime}\left(Y_{t_{k}}\right)\right) \\
& =\mathbb{E}\left[\psi^{\prime}\left(Y_{t_{k}}\right) \nabla_{x} u\left(t_{k}, X_{t_{k}}\right)\left(X_{t_{k}}^{N}-X_{t_{k}}\right)+O_{k}\left(\frac{1}{N}\right)+O\left(\left|X_{t_{k}}^{N}-X_{t_{k}}\right|^{2}\right)\right], \\
& =\mathbb{E}\left(\psi^{\prime}\left(u\left(t_{k}, X_{t_{k}}\right)\right) \nabla_{x} u\left(t_{k}, X_{t_{k}}\right)\left(X_{t_{k}}^{N}-X_{t_{k}}\right)\right)+O\left(\frac{1}{N}\right) .
\end{aligned}
$$

Hypotheses on $\psi$ and $u$ enable us to apply Remark 15 (see later in Section 4) to $\mathbb{E}\left(\psi^{\prime}\left(u\left(t_{k}, X_{t_{k}}\right)\right) \nabla_{x} u\left(t_{k}, X_{t_{k}}\right)\left(X_{t_{k}}^{N}-X_{t_{k}}\right)\right)$. The result follows.

Analyzing weak errors on $Y$ and $Z$ is admittedly useful, but studying pathwise estimates can also be relevant. Actually, both estimates are complementary. For instance, practitioners in finance are interested in finding hedging strategies. This corresponds to solving BSDEs, where $Y$ and $Z$ respectively represent the value of the replicating portfolio and the hedging strategy. On the one hand, Theorems 7 and 8 are suitable tools to study these quantities for computational issues. On the other hand, Theorem 10 enables us to quantify the error on the distribution of the portfolio value, which is relevant in a risk management perspective.

### 2.4.2. Global error of the numerical resolution of BSDE

As recalled in the introduction, there exist several techniques to numerically solve BSDEs. The one we present here refers to Lemor et al. [13]; it turns out to be presumably the most efficient procedure. The authors propose a numerical scheme based on iterative regressions on function bases $p_{0, k}(\cdot), p_{1, k}(\cdot), \ldots, p_{q, k}(\cdot)$ (each being represented as a vector), whose coefficients are evaluated using $M$ extra independent simulations of $\left(X_{t_{k}}^{N}\right)_{0 \leq k \leq N-1}$ and of the Brownian increments $\left(\Delta W_{k}\right)_{0 \leq k \leq N-1}$. Let $\left(y_{k}^{N, M}\left(X_{t_{k}}^{N}\right), z_{1, k}^{N, M}\left(X_{t_{k}}^{N}\right), \ldots, z_{q, k}^{N, M}\left(X_{t_{k}}^{N}\right)\right)_{0 \leq k \leq N-1}$ denote the approximation of the solution of the discretized $\operatorname{BSDE}\left(Y_{t_{k}}^{N}, Z_{1, t_{k}}^{N}, \ldots, Z_{q, t_{k}}^{N}\right)_{0 \leq k \leq N-1}$ computed in a backward manner with the following algorithm.

- Initialization: for $k=N$ take $y_{N}^{N, M}(\cdot)=\Phi(\cdot)$.
- Iteration: for $k=N-1, \ldots, 0$, solve the $q$ least-squares problems:

$$
\alpha_{l, k}^{M}=\arg \inf _{\alpha} \frac{1}{M} \sum_{m=1}^{M}\left|y_{k+1}^{N, M}\left(X_{t_{k+1}}^{N, m}\right) \frac{\Delta W_{k}^{l, m}}{h}-\alpha \cdot p_{l, k}\left(X_{t_{k}}^{N, m}\right)\right|^{2} .
$$

Then, compute $\alpha_{0, k}^{M}$ as the minimizer of

$$
\begin{aligned}
& \left.\frac{1}{M} \sum_{m=1}^{M} \right\rvert\, y_{k+1}^{N, M}\left(X_{t_{k+1}}^{N, m}\right)+h f\left(t_{k}, X_{t_{k}}^{N, m}, y_{k+1}^{N, M}\left(X_{t_{k+1}}^{N, m}\right), \alpha_{l, k}^{M} \cdot p_{l, k}\left(X_{t_{k}}^{N, m}\right)\right) \\
& \quad-\left.\alpha \cdot p_{0, k}\left(X_{t_{k}}^{N, m}\right)\right|^{2}
\end{aligned}
$$

Thus, define $y_{k}^{N, M}(\cdot)$ and $z_{l, k}^{N, M}(\cdot)$ by

$$
y_{k}^{N, M}(\cdot)=\alpha_{0, k}^{M} \cdot p_{0, k}(\cdot), \quad z_{l, k}^{N, M}(\cdot)=\alpha_{l, k}^{M} \cdot p_{l, k}(\cdot) .
$$

Actually, the true algorithm requires the use of additional truncation operators that we have omitted for the sake of simplicity, see Lemor et al. [13] for details. The following error on the unknown regression functions $\left(y_{k}^{N, M}, z_{l, k}^{N, M}\right)_{1 \leq l \leq q, 0 \leq k \leq N-1}$

$$
\max _{0 \leq k \leq N} \mathbb{E}\left|Y_{t_{k}}^{N}-y_{k}^{N, M}\left(X_{t_{k}}^{N}\right)\right|^{2}+h \mathbb{E} \sum_{k=0}^{N-1}\left|Z_{t_{k}}^{N}-z_{k}^{N, M}\left(X_{t_{k}}^{N}\right)\right|^{2}
$$

is essentially bounded by $N C_{M, p}$, where $M$ and $p$ respectively denote the number of simulated paths and the set of functions. For suitable choices of $M$ and $p, C_{M, p}$ goes to 0 at a given rate. This result allows them to optimally tune the parameters to ensure a given accuracy. Hence, summing this numerical error and the discretization's one given by Theorems 7 and 8 leads to


Fig. 1. Evolution of $e_{2}(N), e_{3}(N), e_{4}(N)$ w.r.t. $\log (N)$.
the global error. For example, assume that $\left\|X_{t_{k}}^{N}-X_{t_{k}}\right\|_{L_{p}}=O\left(\frac{1}{N}\right)$. Then, from Theorem 7, we get $\mathbb{E}\left|Y_{t_{k}}-y_{k}^{N, M}\left(X_{t_{k}}^{N}\right)\right|^{2} \leq C\left(\frac{1}{N^{2}}+N C_{M, p}\right)$.

### 2.5. Numerical experiments

In this part, we draw some graphs to illustrate the results given by Theorems 6 and 7. To do so, one needs to explicitly know $X$ and $Y$. Let us consider a Call option pricing problem. We assume that $X$ follows the Black-Scholes model in dimension $d=1, \frac{\mathrm{~d} X_{t}}{X_{t}}=\mu \mathrm{d} t+\sigma \mathrm{d} W_{t}$, with $\sigma=0.2, \mu=0.1$ and $X_{0}=100$. The driver $f$ is defined by $f(t, x, y, z)=-r y-\theta z$, where $\theta=\frac{\mu-r}{\sigma}$ and $r=0.02$. The terminal condition $\Phi(x)$ is given by $(x-K)_{+}$, where $K=100$. The maturity of the option is $T=1$. The continuous backward equation can be solved, $Y_{t}$ is the price of a standard Call option (see El Karoui et al. [5] for a detailed computation).

We compute $X^{N}$ and $Y^{N}$ by using (3) and (4) and get

$$
\begin{aligned}
& X_{t_{k}}^{N}=X_{0} \prod_{j=0}^{k-1}\left(1+\mu h+\sigma \Delta W_{j}\right), \\
& Y_{t_{k}}^{N}=\mathbb{E}_{t_{k}}\left[\Phi\left(X_{T}^{N}\right) \prod_{j=k}^{N-1}\left(1-r h-\theta \Delta W_{j}\right)\right] .
\end{aligned}
$$

Fig. 1 refers to Theorem 6. We plot the evolution of the logarithm of $e_{2}(N), e_{3}(N)$ and $e_{4}(N)$ w.r.t. $\log (N)$.

We use 1000 simulations to approximate the $L_{p}$-norm $e_{p}(N)$ and to compute each conditional expectation $Y_{t_{k}}^{N}$, we use 1000 Monte Carlo simulations. We compute $\log \left(e_{p}(N)\right)_{p=2,3,4}$ for $N=2^{j}, j=1, \ldots, 7$. Looking at the graph, we see that the evolutions of $\log \left(e_{p}(N)\right)_{p=2,3,4}$ w.r.t. $\log (N)$ are almost linear. In view of Theorem 6, the slope should be of order $-\frac{1}{2}$. By using a linear regression method, we get the parameters $a, b$, std where $\log \left(e_{p}(N)\right)=a * \log (N)+b$, and std represents the standard deviation of the residuals. Table 1 sums up the values of $a, b$, std for $p=2,3,4$. Clearly $a$ is of order $-\frac{1}{2}$.

Fig. 2 refers to Theorem 7. We plot the evolution of $\log (a(N))$, where $a(N)=\left(\mathbb{E}\left[\mid Y_{t_{k}}^{N}-\right.\right.$ $\left.\left.Y_{t_{k}}-\left.\nabla_{x} u\left(t_{k}, X_{t_{k}}\right)\left(X_{t_{k}}^{N}-X_{t_{k}}\right)\right|^{2}\right]\right)^{\frac{1}{2}}$ w.r.t. $\log (N)$, at time $t_{k}=\frac{T}{2}$. We use 100 simulations

Table 1
Coefficients of the linear regression of $\log \left(e_{p}(N)\right), p=2,3,4$ w.r.t. $\log (N)$

|  | $a$ | $b$ | std |
| :--- | :--- | :--- | :--- |
| $L_{2}$ error | -0.5179119 | 1.14106 | 0.0384534 |
| $L_{3}$ error | -0.5321072 | 1.4078415 | 0.0367535 |
| $L_{4}$ error | -0.5891505 | 1.858531 | 0.0662573 |



Fig. 2. Evolution of $\log (a(N))$ and $\log \left(e_{2}(N)\right)$ w.r.t. $\log (N)$.
to approximate the $L_{2}$-norm and to compute each $Y_{t_{k}}^{N}$ we use $10^{6}$ Monte Carlo simulations. $N$ behaves as $2^{j}, j=1, \ldots, 7$. We note that $\log (a(N))$ actually evolves almost linearly w.r.t $\log (N)$. Regarding Theorem 7, the slope should be of order -1 . If we still use a linear regression, we get the slope $a=-0.9123248, b=-1.0172153$ and the standard deviation of the residuals equals 0.0940069 .

## 3. Proof of Theorem 6

Extra notations for all the proofs. For any process $U$ (except the Brownian increments $\Delta W_{k}$ ), we define $\Delta U_{k}=U_{t_{k}}^{N}-U_{t_{k}}$. Let $\theta_{s}$ denote $\left(s, X_{s}, Y_{s}, Z_{s}\right)$ and $f_{t_{k}}^{N}$ denote $f\left(t_{k}, X_{t_{k}}^{N}, Y_{t_{k+1}}^{N}, Z_{t_{k}}^{N}\right)$.
$\bar{Z}_{t_{k}}$ is defined as $h \bar{Z}_{t_{k}}:=\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}} Z_{s} \mathrm{~d} s$ and we put $\Delta \bar{Z}_{k}=Z_{t_{k}}^{N}-\bar{Z}_{t_{k}}$.
If $q=2$, the result has already been proved in Gobet et al. [6], under Lipschitz conditions on $b, \sigma, f, \Phi$. Thanks to the inequality $\mathbb{E}|U|^{q} \leq\left(\mathbb{E}|U|^{2 p}\right)^{\frac{q}{2 p}}$ for $2 p \geq q$, we only need to prove the theorem for $q=2 p$, where $p \in \mathbb{N}^{*}$.

First, we give some estimates which can be easily established. We have, under Hypothesis 1, $\forall s \in\left[t_{k}, t_{k+1}\right]$,

$$
\begin{equation*}
\mathbb{E}_{t_{k}}\left(\left|X_{s}-X_{t_{k}}\right|^{2 p}+\left|Y_{s}-Y_{t_{k}}\right|^{2 p}+\left|Z_{s}-\bar{Z}_{t_{k}}\right|^{2 p}\right) \leq C h^{p} . \tag{9}
\end{equation*}
$$

In the following computations, these estimates are repeatedly used.

### 3.1. Proof of $\max _{0 \leq k \leq N} \mathbb{E}\left|Y_{t_{k}}-Y_{t_{k}}^{N}\right|^{2 p}=O\left(h^{p}\right)$

We prove the following result, which is a bit more general.

Proposition 11. $\max _{i \leq k \leq N} \mathbb{E}_{t_{i} \mid}\left|Y_{t_{k}}-Y_{t_{k}}^{N}\right|^{2 p}=O_{i}\left(h^{p}\right)+\left|\Delta X_{i}\right|^{2 p}$.
By taking $i=0$, we get $\max _{0 \leq k \leq N} \mathbb{E}\left|Y_{t_{k}}-Y_{t_{k}}^{N}\right|^{2 p}=O\left(h^{p}\right)$.
Assume that we have

$$
\begin{equation*}
\left|\Delta Y_{k}\right|^{2} \leq(1+C h) \mathbb{E}_{t_{k}}\left|\Delta Y_{k+1}\right|^{2}+C h\left|\Delta X_{k}\right|^{2}+C h^{2} . \tag{10}
\end{equation*}
$$

Then, using the inequality $(a+b)^{p} \leq a^{p}\left(1+\epsilon\left(2^{p-1}-1\right)\right)+b^{p}\left(1+\frac{2^{p-1}-1}{\epsilon^{p-1}}\right)$ for $0<\epsilon<1$, we deduce

$$
\left|\Delta Y_{k}\right|^{2 p} \leq(1+C h)^{p+1} \mathbb{E}_{t_{k}}\left|\Delta Y_{k+1}\right|^{2 p}+C^{p} h^{p}\left(\left|\Delta X_{k}\right|^{2}+C h\right)^{p}\left(1+\frac{C}{h^{p-1}}\right) .
$$

Take the conditional expectation w.r.t. $\mathcal{F}_{t_{i}}$ to get $\mathbb{E}_{t_{i}}\left|\Delta Y_{k}\right|^{2 p} \leq(1+C h) \mathbb{E}_{t_{i}}\left|\Delta Y_{k+1}\right|^{2 p}+h\left(h^{p}+\right.$ $\mathbb{E}_{t_{i}}\left|\Delta X_{k}\right|^{2 p}$ ). Using (8) for $\left|\Delta X_{k}\right|$ and Gronwall's lemma yields max ${ }_{i \leq k \leq N} \mathbb{E}_{t_{i}}\left|Y_{t_{k}}-Y_{t_{k}}^{N}\right|^{2 p}=$ $O_{i}\left(h^{p}\right)+\left|\Delta X_{i}\right|^{2 p}$.
Now we prove the inequality (10). From (2) and (4) we obtain

$$
\begin{equation*}
\Delta Y_{k}=\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1}\right)+\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left(f_{t_{k}}^{N}-f\left(\theta_{s}\right)\right) \mathrm{d} s \tag{11}
\end{equation*}
$$

By applying Young's inequality, that is $(a+b)^{2} \leq(1+\gamma h) a^{2}+\left(1+\frac{1}{\gamma h}\right) b^{2}$, where $\gamma$ will be fixed later, and using the Lipschitz property of $f$, we get

$$
\begin{align*}
\left|\Delta Y_{k}\right|^{2} \leq & (1+\gamma h)\left(\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1}\right)\right)^{2}+C\left(h+\frac{1}{\gamma}\right)\left[h^{2}+\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|X_{s}-X_{t_{k}}^{N}\right|^{2} \mathrm{~d} s\right] \\
& +C\left(h+\frac{1}{\gamma}\right)\left[\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|Y_{s}-Y_{t_{k+1}}^{N}\right|^{2} \mathrm{~d} s+\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|Z_{s}-Z_{t_{k}}^{N}\right|^{2} \mathrm{~d} s\right] . \tag{12}
\end{align*}
$$

Let us introduce $\bar{Z}_{t_{k}}$ (see extra notations at the beginning of Section 3):

$$
\begin{equation*}
\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|Z_{s}-Z_{t_{k}}^{N}\right|^{2} \mathrm{~d} s=\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k}+1}\left|Z_{s}-\bar{Z}_{t_{k}}\right|^{2} \mathrm{~d} s+h \mathbb{E}_{t_{k}}\left|\bar{Z}_{t_{k}}-Z_{t_{k}}^{N}\right|^{2} . \tag{13}
\end{equation*}
$$

Thanks to the Cauchy-Schwarz inequality we have

$$
\left|\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1} \Delta W_{k}^{l}\right)\right|^{2} \leq h\left\{\mathbb{E}_{t_{k}}\left(\left|\Delta Y_{k+1}\right|^{2}\right)-\left|\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1}\right)\right|^{2}\right\} .
$$

Hence, as $h \bar{Z}_{t_{k}}=\mathbb{E}_{t_{k}}\left(\left\{Y_{t_{k+1}}+\int_{t_{k}}^{t_{k+1}} f\left(\theta_{s}\right) \mathrm{d} s\right\} \Delta W_{k}^{*}\right)$, with a bounded $f$, it follows that

$$
\begin{equation*}
h^{2}\left|\bar{Z}_{t_{k}}-Z_{t_{k}}^{N}\right|^{2} \leq d h\left(\mathbb{E}_{t_{k}}\left(\left|\Delta Y_{k+1}\right|^{2}\right)-\left|\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1}\right)\right|^{2}\right)+C h^{3} \tag{14}
\end{equation*}
$$

By plugging (13) and (14) into (12), we get

$$
\begin{aligned}
\left|\Delta Y_{k}\right|^{2} \leq & (1+\gamma h)\left(\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1}\right)\right)^{2} \\
& +C\left(h+\frac{1}{\gamma}\right)\left[h^{2}+\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|X_{s}-X_{t_{k}}^{N}\right|^{2} \mathrm{~d} s+\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|Y_{s}-Y_{t_{k+1}}^{N}\right|^{2} \mathrm{~d} s\right] \\
& +C\left(h+\frac{1}{\gamma}\right)\left[\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|Z_{s}-\bar{Z}_{t_{k}}\right|^{2} \mathrm{~d} s+\mathbb{E}_{t_{k}}\left(\left|\Delta Y_{k+1}\right|^{2}\right)-\left|\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1}\right)\right|^{2}\right] .
\end{aligned}
$$

We can write $\mathbb{E}_{t_{k}}\left|Y_{s}-Y_{t_{k+1}}^{N}\right|^{2} \leq 2 \mathbb{E}_{t_{k}}\left|Y_{s}-Y_{t_{k+1}}\right|^{2}+2 \mathbb{E}_{t_{k}}\left|\Delta Y_{k+1}\right|^{2}$. By doing the same for $X_{s}-X_{t_{k+1}}^{N}$, and taking $\gamma=C$, we obtain

$$
\begin{aligned}
\left|\Delta Y_{k}\right|^{2} \leq & (1+C h) \mathbb{E}_{t_{k}}\left|\Delta Y_{k+1}\right|^{2}+C h\left|\Delta X_{k}\right|^{2}+C h \mathbb{E}_{t_{t_{2}}}\left|\Delta Y_{k+1}\right|^{2} \\
& +C\left[h^{2}+\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|X_{s}-X_{t_{k}}\right|^{2} \mathrm{~d} s+\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|Y_{s}-Y_{t_{k+1}}\right|^{2} \mathrm{~d} s\right] \\
& +C\left[\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|Z_{s}-\bar{Z}_{t_{k}}\right|^{2} \mathrm{~d} s\right] .
\end{aligned}
$$

Using (9) yields $\left|\Delta Y_{k}\right|^{2} \leq(1+C h) \mathbb{E}_{t_{k}}\left|\Delta Y_{k+1}\right|^{2}+C h\left|\Delta X_{k}\right|^{2}+C h^{2}$.
3.2. Proof of $\mathbb{E}\left(\sum_{k=0}^{N-1} \int_{t_{k}}^{t_{k+1}}\left|Z_{t_{k}}^{N}-Z_{t}\right|^{2} \mathrm{~d} t\right)^{\frac{p}{2}}=O\left(h^{p}\right)$

First of all, we can split this summation into two terms

$$
\begin{aligned}
\mathbb{E}\left(\sum_{k=0}^{N-1} \int_{t_{k}}^{t_{k+1}}\left|Z_{t_{k}}^{N}-Z_{t}\right|^{2} \mathrm{~d} t\right)^{p} \leq & C \mathbb{E}\left(\sum_{k=0}^{N-1} \int_{t_{k}}^{t_{k+1}}\left|\bar{Z}_{t_{k}}-Z_{t}\right|^{2} \mathrm{~d} t\right)^{p} \\
& +C \mathbb{E}\left(h \sum_{k=0}^{N-1}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p}
\end{aligned}
$$

Thanks to (9), we have $\mathbb{E}\left(\sum_{k=0}^{N-1} \int_{t_{k}}^{t_{k+1}}\left|\bar{Z}_{t_{k}}-Z_{t}\right|^{2} \mathrm{~d} t\right)^{p} \leq T^{p-1} \sum_{k=0}^{N-1} \int_{t_{k}}^{t_{k+1}} \mathbb{E}\left|\bar{Z}_{t_{k}}-Z_{t}\right|^{2 p} \mathrm{~d} t=$ $O\left(h^{p}\right)$.
Scheme of the proof of $\mathbb{E}\left(h \sum_{k=0}^{N-1}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p}=O\left(h^{p}\right)$. The first key point is to slice the summation into small intervals and show that the result is true for small time intervals. The second key point is to use Rosenthal's inequality, see Theorem 2.12, page 23 of Hall and Heyde [8]. By using (14) and taking the expectation, we can write:

$$
\begin{equation*}
\mathbb{E}\left(h \sum_{k=0}^{k_{1}}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p} \leq C \mathbb{E}\left(\sum_{k=0}^{k_{1}} \operatorname{Var}_{t_{k}} \Delta Y_{k+1}\right)^{p}+C h^{p} \tag{15}
\end{equation*}
$$

We use Rosenthal's inequality to upper bound

$$
\begin{aligned}
\mathbb{E}\left(\sum_{k=0}^{k_{1}} \operatorname{Var}_{t_{k}} \Delta Y_{k+1}\right)^{p} \leq & C \mathbb{E}\left(\sum_{k=0}^{k_{1}} \Delta Y_{k+1}-\mathbb{E}_{t_{k}} \Delta Y_{k+1}\right)^{2 p} \\
\leq & C 3^{2 p-1}\left[\mathbb{E} \Delta Y_{k_{1}+1}^{2 p}+\mathbb{E} \Delta Y_{0}^{2 p}\right. \\
& \left.+\mathbb{E}\left(\sum_{k=0}^{k_{1}}\left(\Delta Y_{k}-\mathbb{E}_{t_{k}} \Delta Y_{k+1}\right)\right)^{2 p}\right]
\end{aligned}
$$

By plugging this inequality into (15) and using the previous estimate on $\left|\Delta Y_{k}\right|$, we get

$$
\begin{equation*}
\mathbb{E}\left(h \sum_{k=0}^{k_{1}}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p} \leq O\left(h^{p}\right)+C \mathbb{E}\left(\sum_{k=0}^{k_{1}}\left(\Delta Y_{k}-\mathbb{E}_{t_{k}} \Delta Y_{k+1}\right)\right)^{2 p} . \tag{16}
\end{equation*}
$$

We now tackle the term $\Delta Y_{k}-\mathbb{E}_{t_{k}} \Delta Y_{k+1}$. Using (11), we have $\sum_{k=0}^{k_{1}}\left(\Delta Y_{k}-\mathbb{E}_{t_{k}} \Delta Y_{k+1}\right)=$ $\sum_{k=0}^{k_{1}} \int_{t_{k}}^{t_{k+1}}\left(\mathbb{E}_{t_{k}}\left(f_{t_{k}}^{N}-f\left(\theta_{s}\right)\right)\right) \mathrm{d} s$. By doing the same kind of proof as before, that is using the fact that $f$ is Lipschitz and the results on $\mathbb{E}\left|\Delta X_{k}\right|^{2 p}$ and $\mathbb{E}\left|\Delta Y_{k}\right|^{2 p}$, we find

$$
\mathbb{E}\left(\sum_{k=0}^{k_{1}}\left(\Delta Y_{k}-\mathbb{E}_{t_{k}} \Delta Y_{k+1}\right)\right)^{2 p} \leq O\left(h^{p}\right)+C\left(h k_{1}\right)^{p} \mathbb{E}\left(h \sum_{k=0}^{k_{1}}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p}
$$

By plugging this term back into (16), we can write $\left(1-C\left(h k_{1}\right)^{p}\right) \mathbb{E}\left(h \sum_{k=0}^{k_{1}}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p}=O\left(h^{p}\right)$. Consequently, if we choose $k_{1} \leq \frac{1}{(2 C)^{\frac{1}{p} h}}$ we come up with $\mathbb{E}\left(h \sum_{k=0}^{k_{1}}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p}=O\left(h^{p}\right)$. This result can be extended to any summation involving at most $\Delta k$ terms, where $\Delta k \leq \frac{1}{(2 C)^{\frac{1}{p}} h}$. We can cover the interval $\{0, \ldots, N-1\}$ with a finite number of elementary intervals of size $\Delta k$ and we get $\mathbb{E}\left(h \sum_{k=0}^{N-1}\left|\Delta \bar{Z}_{k}\right|^{2}\right)^{p}=O\left(h^{p}\right)$, which completes our proof.

From this result and (9), we also deduce

$$
\begin{equation*}
\mathbb{E}\left(h \sum_{k=0}^{N-1}\left|\Delta Z_{k}\right|^{2}\right)^{p}=O\left(h^{p}\right) \tag{17}
\end{equation*}
$$

which is very useful in the following.

## 4. Proof of Theorem 7

To expand the error, we use the usual techniques of stochastic analysis, combining martingale estimates and Malliavin calculus tools.

### 4.1. Preliminary estimates

Sections 4 and 5 contain proofs with similar calculations, which are quite technical. In order to be as clear as possible, we state two results really useful in the sequel, which are related to Malliavin calculus (see Nualart [16]). The results give sufficient conditions for expectations and conditional expectations to be small w.r.t. the time step $h$. They are based on ideas from KohatsuHiga and Pettersson [10] and Gobet and Munos [7].

Proposition 12. Let $F \in \mathbb{D}^{1,2}$ with $\mathbb{E}_{t_{k}}|F|^{2}+\sup _{t_{k} \leq s \leq T} \mathbb{E}_{t_{k}}\left|D_{s} F\right|^{2}<\infty$ and let $U$ be an Itô process of the form $U_{t}=U_{0}+\int_{0}^{t} \alpha_{s} \mathrm{~d} s+\int_{0}^{\bar{t}} \beta_{s} \mathrm{~d} W_{s}$, with $\sup _{t_{k} \leq s \leq T} \mathbb{E}_{t_{k}}\left|\alpha_{s}\right|^{2}+$ $\sup _{t_{k} \leq s \leq T} \mathbb{E}_{t_{k}}\left|\beta_{s}\right|^{2}<\infty$. Then, $\forall\left(t, t^{\prime}\right)$ such that $t_{k} \leq t \leq t^{\prime} \leq t_{k+1}$,

$$
\begin{aligned}
\left|\mathbb{E}_{t_{k}}\left[F\left(U_{t}-U_{t^{\prime}}\right)\right]\right| \leq & \left(t^{\prime}-t\right)\left[\left(\mathbb{E}_{t_{k}}|F|^{2}\right)^{\frac{1}{2}}\left(\sup _{t \leq s \leq t^{\prime}} \mathbb{E}_{t_{k}}\left|\alpha_{s}\right|^{2}\right)^{\frac{1}{2}}\right. \\
& \left.+\left(\sup _{t \leq s \leq t^{\prime}} \mathbb{E}_{t_{k}}\left|D_{s} F\right|^{2}\right)^{\frac{1}{2}}\left(\sup _{t \leq s \leq t^{\prime}} \mathbb{E}_{t_{k}}\left|\beta_{s}\right|^{2}\right)^{\frac{1}{2}}\right]
\end{aligned}
$$

This proposition can be easily proved. Assume without loss of generality that $F$ and $U$ are onedimensional. From the duality formula, we have $\mathbb{E}_{t_{k}}\left[F\left(\int_{t}^{t^{\prime}} \alpha_{s} \mathrm{~d} s+\int_{t}^{t^{\prime}} \beta_{s} \mathrm{~d} W_{s}\right)\right]=\mathbb{E}_{t_{k}}\left[\int_{t}^{t^{\prime}}\left(F \alpha_{s}+\right.\right.$
$\left.\left.D_{s} F \cdot \beta_{s}\right) \mathrm{d} s\right]$. Thanks to Cauchy-Schwarz inequality and hypotheses on $\alpha$ and $\beta$, we get the result.

Definition 13. $F$ satisfies the condition $R_{k}$ if $F \in \mathbb{D}^{k, \infty}$ and if $\mathcal{C}_{k, p}(F):=\|F\|_{L_{p}}+$ $\sum_{j \leq k} \sup _{0 \leq s_{1}, \ldots, s_{j} \leq T}\left\|D_{s_{1}, \ldots, s_{j}} F\right\|_{L_{p}}<\infty$.

Proposition 14. Let $F$ satisfy the condition $R_{2}$. For simplicity we set $\mathrm{d} W_{s}^{0}=\mathrm{d}$ s. Assume that $U_{t} \in \mathbb{R}^{d}$ satisfies the following stochastic expansion property

$$
\begin{equation*}
U_{t}=\sum_{i, j=0}^{q} c_{i, j}^{U, 0}(t) \int_{0}^{t} c_{i, j}^{U, 1}(s)\left(\int_{\eta(s)}^{s} c_{i, j}^{U, 2}(r) \mathrm{d} W_{r}^{i}\right) \mathrm{d} W_{s}^{j} \tag{P}
\end{equation*}
$$

where $\left\{\left(c_{i, j}^{U, i_{1}}(t)\right)_{t \geq 0}: 0 \leq i, j \leq q, 0 \leq i_{1} \leq 2\right\}$ are adapted processes satisfying

- $\forall(i, j), 1 \leq i, j \leq q, \forall t \in[0, T], \quad c_{i, j}^{U, 0}(t)$ satisfies $R_{2}$, and $\mathcal{C}_{2, p}^{U} \quad:=$ $\sup _{0 \leq t \leq T} \sup _{1 \leq i, j \leq q} \mathcal{C}_{2, p}\left(c_{i, j}^{U, 0}(t)\right)<\infty, p \geq 1$.
- $\forall(i, j), 1 \leq i, j \leq q, \forall t \in[0, T], c_{i, j}^{U, 1}(t), c_{0, j}^{U, 0}(t), c_{i, 0}^{U, 0}(t), c_{i, 0}^{U, 1}(t)$ satisfy $R_{1}$, and $\mathcal{C}_{1, p}^{U}:=$ $\sup _{0 \leq t \leq T} \sup _{1 \leq i, j \leq q}\left\{\mathcal{C}_{1, p}\left(c_{i, j}^{U, 1}(t)\right)+\mathcal{C}_{1, p}\left(c_{0, j}^{U, 0}(t)\right)+\mathcal{C}_{1, p}\left(c_{i, 0}^{U, 0}(t)\right)+\mathcal{C}_{1, p}\left(c_{i, 0}^{U, 1}(t)\right)\right\}<\infty$, $p \geq 1$.
$\bullet \forall(i, j), 0 \leq i, j \leq q, \forall t \in[0, T], c_{i, j}^{U, 2}(t), c_{0, j}^{U, 1}(t), c_{0,0}^{U, 0}(t)$ satisfy $R_{0}$, and $\mathcal{C}_{0, p}^{U}:=$ $\sup _{0 \leq t \leq T} \sup _{0 \leq i, j \leq q}\left\{\mathcal{C}_{0, p}\left(c_{i, j}^{U, 2}(t)\right)+\mathcal{C}_{0, p}\left(c_{0, j}^{U, 1}(t)\right)+\mathcal{C}_{0, p}\left(c_{0,0}^{U, 0}(t)\right)\right\}<\infty, p \geq 1$.
Thus, there is a constant $K(T)$ which depends polynomially on $\mathcal{C}_{2, p}(F), \mathcal{C}_{2, p}^{U}, \mathcal{C}_{1, p}^{U}, \mathcal{C}_{0, p}^{U}$ (for some $p \geq 1)$ such that $\left|\mathbb{E}\left[F U_{t}\right]\right| \leq K(T) h$.

Indeed, we have

$$
\begin{aligned}
\mathbb{E}\left(F U_{t}\right)= & \sum_{i, j=0}^{q} \mathbb{E}\left(F c_{i, j}^{U, 0}(t) \int_{0}^{t} c_{i, j}^{U, 1}(s)\left(\int_{\eta(s)}^{s} c_{i, j}^{U, 2}(r) \mathrm{d} W_{r}^{i}\right) \mathrm{d} W_{s}^{j}\right) \\
= & \sum_{i, j=1}^{q} \int_{0}^{t} \int_{\eta(s)}^{s} \mathbb{E}\left(D_{r}^{i}\left[D_{s}^{j}\left\{F c_{i, j}^{U, 0}(t)\right\} c_{i, j}^{U, 1}(s)\right] c_{i, j}^{U, 2}(r)\right) \mathrm{d} r \mathrm{~d} s \\
& +\sum_{j=1}^{q} \int_{0}^{t} \int_{\eta(s)}^{s} \mathbb{E}\left[D_{s}^{j}\left\{F c_{0, j}^{U, 0}(t)\right\} c_{0, j}^{U, 1}(s) c_{0, j}^{U, 2}(r)\right] \mathrm{d} r \mathrm{~d} s \\
& +\sum_{i=1}^{q} \int_{0}^{t} \int_{\eta(s)}^{s} \mathbb{E}\left[D_{r}^{i}\left\{F c_{i, 0}^{U, 0}(t) c_{i, 0}^{U, 1}(s)\right\} c_{i, 0}^{U, 2}(r)\right] \mathrm{d} r \mathrm{~d} s \\
& +\int_{0}^{t} \int_{\eta(s)}^{s} \mathbb{E}\left(F c_{0,0}^{U, 0}(t) c_{0,0}^{U, 1}(s) c_{0,0}^{U, 2}(r)\right) \mathrm{d} r \mathrm{~d} s .
\end{aligned}
$$

Then, the result readily follows.
Remark 15. Under Hypothesis 2, we can show (see later the proof of (41)) that for each $t$, $X_{t}^{N}-X_{t}$ satisfies the expansion ( $\mathcal{P}$ ). Hence, if $F$ satisfies $R_{2}$, Proposition 14 yields

$$
\left|\mathbb{E}\left[F\left(X_{t}^{N}-X_{t}\right)\right]\right|=O(h)
$$

uniformly in $t \in[0, T]$, which is a very useful result for the sequel.
4.2. Expansion of $Y_{t_{k}}^{N}-Y_{t_{k}}$

In the following, we assume that Hypothesis 2 is in force. This implies in particular that $u$ is bounded, of class $C_{b}^{3 / 2,3}$ (see Proposition 4). We also easily prove that $\forall p \geq 1, \forall k \in$ $\{0, \ldots, N-1\}$ (see Nualart [16] e.g.)

$$
\begin{align*}
& \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|X_{t}\right|^{2 p}\right)<K(T)\left(1+\left|X_{t_{k}}\right|^{2 p}\right), \quad \sup _{t_{k} \leq s \leq T} \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|D_{s} X_{t}\right|^{p}\right) \leq C, \\
& \sup _{t_{k} \leq s, r \leq T} \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|D_{r} D_{s} X_{t}\right|^{p}\right)+\sup _{t_{k} \leq s, r, v \leq T} \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|D_{v} D_{r} D_{s} X_{t}\right|^{p}\right) \leq C, \quad(1 \tag{18}
\end{align*}
$$

$$
\begin{aligned}
& \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|X_{t}^{N}\right|^{2 p}\right)<K(T)\left(1+\left|X_{t_{k}}^{N}\right|^{2 p}\right), \sup _{N, t_{k} \leq s \leq T} \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|D_{s} X_{t}^{N}\right|^{p}\right) \leq C, \\
& \sup _{N, t_{k} \leq s, r \leq T} \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|D_{r} D_{s} X_{t}^{N}\right|^{p}\right)+\sup _{N, t_{k} \leq s, r, v \leq T} \mathbb{E}_{t_{k}}\left(\sup _{t_{k} \leq t \leq T}\left|D_{v} D_{r} D_{s} X_{t}^{N}\right|^{p}\right)
\end{aligned}
$$

$$
\begin{equation*}
\leq C \tag{19}
\end{equation*}
$$

Due to the Markov property of $\left(X_{t_{k}}^{N}\right)_{k}$, one has $Y_{t_{k}}^{N}=u^{N}\left(t_{k}, X_{t_{k}}^{N}\right)$ for some Lipschitz function $u^{N}\left(t_{k}, \cdot\right)$ (see Gobet et al. [6]) with an obvious definition of $u^{N}$. Actually, under our assumptions, this function is even three times differentiable w.r.t. $x$. Thus, the difference $\Delta Y_{k}$ can be written as follows:

$$
\Delta Y_{k}=\left(u^{N}\left(t_{k}, X_{t_{k}}^{N}\right)-u\left(t_{k}, X_{t_{k}}^{N}\right)\right)+\left(u\left(t_{k}, X_{t_{k}}^{N}\right)-u\left(t_{k}, X_{t_{k}}\right)\right) .
$$

Since $u$ is of class $C_{b}^{3 / 2,3}$, the last term of the previous inequality becomes

$$
\begin{equation*}
u\left(t_{k}, X_{t_{k}}^{N}\right)-u\left(t_{k}, X_{t_{k}}\right)=\nabla_{x} u\left(t_{k}, X_{t_{k}}\right) \Delta X_{k}+O\left(\left|\Delta X_{k}\right|^{2}\right) . \tag{20}
\end{equation*}
$$

To complete the proof, we apply the following lemma.
Lemma 16. Under Hypothesis $2,\left|u^{N}\left(t_{k}, x\right)-u\left(t_{k}, x\right)\right| \leq K(T, x) h$.
The result above is new but not so surprising. Indeed, if $f$ is identically zero, the difference is only related to the weak approximation of $\Phi\left(X_{T}\right)$ by $\Phi\left(X_{T}^{N}\right)$ : from Bally and Talay [1], one knows that this is of order $h$.

The rest of this section is devoted to the proof of the lemma. We only give the proof for $t_{k}=0$. We want to find an upper bound for $\left|u^{N}(0, x)-u(0, x)\right|=\left|\Delta Y_{0}\right|$.

For the sake of clarity, we split the proof into several steps.
Step 1: Linearization of the error. We show that

$$
\begin{equation*}
\Delta Y_{k}=\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1} \xi_{k}+h f_{x}^{\prime}\left(\theta_{t_{k}}\right) \Delta X_{k}+h \chi_{k}\right) \tag{21}
\end{equation*}
$$

with

$$
\begin{equation*}
\xi_{k}=\left(1+h f_{y}^{\prime}\left(\theta_{t_{k}}\right)+f_{z}^{\prime}\left(\theta_{t_{k}}\right) \Delta W_{k}\right) \tag{22}
\end{equation*}
$$

$$
\begin{align*}
\chi_{k}= & \int_{t_{k}}^{t_{k+1}}\left(G_{0}\left(s, X_{s}\right)+f_{y}^{\prime}\left(\theta_{t_{k}}\right) G_{y}\left(s, X_{s}\right)+f_{z}^{\prime}\left(\theta_{t_{k}}\right) G_{z}\left(s, X_{s}\right)\right) \mathrm{d} s \\
& +\int_{0}^{1}(1-\lambda)\left[\Delta X_{k}^{*} f_{x x}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta X_{k}+f_{y y}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right)\left(Y_{t_{k+1}}^{N}-Y_{t_{k}}\right)^{2}+\Delta Z_{k} f_{z z}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta Z_{k}^{*}\right. \\
& +2 \Delta X_{k}^{*} f_{x y}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right)\left(Y_{t_{k+1}}^{N}-Y_{t_{k}}\right)+2 \Delta X_{k}^{*} f_{x z}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta Z_{k}^{*} \\
& \left.+2\left(Y_{t_{k+1}}^{N}-Y_{t_{k}}\right) f_{y z}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta Z_{k}^{*}\right] \mathrm{d} \lambda \tag{23}
\end{align*}
$$

where $\theta_{t_{k}}^{\lambda}=\lambda\left(t_{k}, X_{t_{k}}^{N}, Y_{t_{k+1}}^{N}, Z_{t_{k}}^{N}\right)+(1-\lambda) \theta_{t_{k}}$ and $G_{0}, G_{y}, G_{z}$ are bounded functions. From (11) and by introducing $f\left(\theta_{t_{k}}\right)$, we have

$$
\begin{equation*}
\Delta Y_{k}=\mathbb{E}_{t_{k}}\left(\Delta Y_{k+1}+h\left(f_{t_{k}}^{N}-f\left(\theta_{t_{k}}\right)\right)+\int_{t_{k}}^{t_{k+1}}\left(f\left(\theta_{t_{k}}\right)-f\left(\theta_{s}\right)\right) \mathrm{d} s\right) \tag{24}
\end{equation*}
$$

By applying Itô's formula to $f\left(\theta_{u}\right)$ between $t_{k}$ and $s$ we show that, under Hypothesis 2, $\int_{t_{k}}^{t_{k+1}} \mathbb{E}_{t_{k}}\left(f\left(\theta_{t_{k}}\right)-f\left(\theta_{s}\right)\right) \mathrm{d} s=h \int_{t_{k}}^{t_{k+1}} E_{t_{k}}\left(G_{0}\left(s, X_{s}\right)\right) \mathrm{d} s$, where $G_{0}$ is a bounded function. In the second term, perform a second order expansion of $f$ around $\theta_{t_{k}}$ to get

$$
\begin{align*}
f_{t_{k}}^{N}-f\left(\theta_{t_{k}}\right)= & f_{x}^{\prime}\left(\theta_{t_{k}}\right) \Delta X_{k}+f_{y}^{\prime}\left(\theta_{t_{k}}\right) \Delta Y_{k+1}+f_{z}^{\prime}\left(\theta_{t_{k}}\right) \Delta Z_{k}^{*}+f_{y}^{\prime}\left(\theta_{t_{k}}\right)\left(Y_{t_{k+1}}-Y_{t_{k}}\right) \\
& +\int_{0}^{1}(1-\lambda)\left[\Delta X_{k}^{*} f_{x x}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta X_{k}+f_{y y}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right)\left(Y_{t_{k+1}}^{N}-Y_{t_{k}}\right)^{2}\right. \\
& +\Delta Z_{k} f_{z z}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta Z_{k}^{*}+2 \Delta X_{k}^{*} f_{x y}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right)\left(Y_{t_{k+1}}^{N}-Y_{t_{k}}\right)+2 \Delta X_{k}^{*} f_{x z}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta Z_{k}^{*} \\
& \left.+2\left(Y_{t_{k+1}}^{N}-Y_{t_{k}}\right) f_{y z}^{\prime \prime}\left(\theta_{t_{k}}^{\lambda}\right) \Delta Z_{k}^{*}\right] \mathrm{d} \lambda \tag{25}
\end{align*}
$$

Note that $\mathbb{E}_{t_{k}}\left(Y_{t_{k+1}}-Y_{t_{k}}\right)=\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}} G_{y}\left(s, X_{s}\right) \mathrm{d} s$. If we closely look at (25), we can see that we need to develop $\Delta Z_{k}$. By using (5), we can write

$$
Z_{t_{k}}^{N}=\frac{1}{h} \mathbb{E}_{t_{k}}\left(\Delta Y_{k+1} \Delta W_{k}^{*}\right)+\frac{1}{h} \mathbb{E}_{t_{k}}\left(u\left(t_{k+1}, X_{t_{k+1}}\right) \Delta W_{k}^{*}\right)
$$

Introducing the weak derivative of $X_{t_{k+1}}$ (see Nualart [16, p. 109]), the second term of this summation equals $\frac{1}{h} \mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}} \nabla_{x} u\left(t_{k+1}, X_{t_{k+1}}\right) D_{t} X_{t_{k+1}} \mathrm{~d} t$, where $D_{t} X_{t_{k+1}}=$ $\nabla_{x} X_{t_{k+1}}\left(\nabla_{x} X_{t}\right)^{-1} \sigma\left(t, X_{t}\right)$. Since $Z_{t_{k}}=\nabla_{x} u\left(t_{k}, X_{t_{k}}\right) \sigma\left(t_{k}, X_{t_{k}}\right)$, one gets

$$
\begin{aligned}
\Delta Z_{k}= & \frac{1}{h} \mathbb{E}_{t_{k}}\left(\Delta Y_{k+1} \Delta W_{k}^{*}\right)+\frac{1}{h} \int_{t_{k}}^{t_{k+1}} \mathbb{E}_{t_{k}}\left(\nabla_{x} u\left(t_{k+1}, X_{t_{k+1}}\right) \nabla_{x} X_{t_{k+1}}\left(\nabla_{x} X_{t}\right)^{-1} \sigma\left(t, X_{t}\right)\right. \\
& \left.-\nabla_{x} u\left(t_{k}, X_{t_{k}}\right) \sigma\left(t_{k}, X_{t_{k}}\right)\right) \mathrm{d} t
\end{aligned}
$$

The term in the second conditional expectation is equal to $\nabla_{x} u\left(t_{k+1}, X_{t_{k+1}}\right) \nabla_{x} X_{t_{k+1}}\left(\nabla_{x} X_{t}\right)^{-1}$ $\sigma\left(t, X_{t}\right) \pm \nabla_{x} u\left(t, X_{t}\right) \sigma\left(t, X_{t}\right)-\nabla_{x} u\left(t_{k}, X_{t_{k}}\right) \sigma\left(t_{k}, X_{t_{k}}\right)$. hence, two applications of Itô's formula (for the first contribution between $t$ and $t_{k+1}$, for the second one between $t_{k}$ and $t$ ) prove that

$$
\begin{equation*}
\Delta Z_{k}^{*}=\int_{t_{k}}^{t_{k+1}} \mathbb{E}_{t_{k}}\left(G_{z}\left(s, X_{s}\right)\right) \mathrm{d} s+\frac{1}{h} \mathbb{E}_{t_{k}}\left(\Delta Y_{k+1} \Delta W_{k}\right) \tag{26}
\end{equation*}
$$

for a bounded function $G_{z}$. Plugging this equality and (25) into (24) yields (21).
Step 2: Another formula of $\Delta Y_{0}$. First of all, we replace $Y_{t_{k+1}}^{N}-Y_{t_{k}}$ by $\Delta Y_{k+1}+Y_{t_{k+1}}-Y_{t_{k}}$ in the expression of $\chi_{k}$. Then, easy computations combining Proposition 11 and estimates (9) show
that

$$
\begin{equation*}
\tilde{\chi}_{k}=\mathbb{E}_{t_{k}}\left(\chi_{k}\right)=O_{k}(h)+O\left(\left|\Delta X_{k}\right|^{2}+\left|\Delta Z_{k}\right|^{2}\right) \tag{27}
\end{equation*}
$$

From (21), we deduce the following equality

$$
\begin{equation*}
\Delta Y_{0}=\mathbb{E}\left(\Delta Y_{N} \xi_{0} \cdots \xi_{N-1}+h \sum_{i=0}^{N-1}\left(f_{x}^{\prime}\left(\theta_{t_{i}}\right) \Delta X_{i}+\tilde{\chi}_{i}\right) \xi_{0} \cdots \xi_{i-1}\right) \tag{28}
\end{equation*}
$$

Now it is enough to show that all terms of this summation are $O(h)$. In the following, $\eta_{0}=1$ and $\eta_{i}=\xi_{0} \cdots \xi_{i-1}$ for $i \leq N$.
Step 3: Some results on $\eta_{N}=\xi_{0} \cdots \xi_{N-1}$.
We establish the following results on $\eta_{N}$ :
$\eta_{k}$ satisfies the condition $R_{2}$ uniformly in $k$, i.e. $\forall k, \eta_{k} \in \mathbb{D}^{2, \infty}$ and

$$
\begin{align*}
& \max _{k \leq N} \mathcal{C}_{2, p}\left(\eta_{k}\right)<\infty, \quad \forall p \geq 1,  \tag{29}\\
& \mathbb{E}\left(\max _{0 \leq k \leq N}\left|\eta_{k}\right|^{p}\right)+\sup _{r \leq T} \mathbb{E}\left(\max _{0 \leq k \leq N}\left|D_{r} \eta_{k}\right|^{p}\right)+\sup _{r, s \leq T} \mathbb{E}\left(\max _{0 \leq k \leq N}\left|D_{r} D_{s} \eta_{k}\right|^{p}\right)<\infty . \tag{30}
\end{align*}
$$

Proof of (29). We have $\eta_{0}=1$, and for $i \geq 1$

$$
\begin{equation*}
\eta_{i}=\eta_{i-1}\left(1+h f_{y}^{\prime}\left(\theta_{t_{i-1}}\right)+f_{z}^{\prime}\left(\theta_{t_{i-1}}\right) \Delta W_{i-1}\right) . \tag{31}
\end{equation*}
$$

We begin to show that $\max _{k \leq N}\left\|\eta_{k}\right\|_{L_{p}}=O(1)$ for $p \geq 1$. Since $f_{y}^{\prime}$ and $f_{z}^{\prime}$ are bounded, we easily prove that $\mathbb{E}_{t_{i-1}}\left(1+h f_{y}^{\prime}\left(\theta_{t_{i-1}}\right)+f_{z}^{\prime}\left(\theta_{t_{i-1}}\right) \Delta W_{i-1}\right)^{2 p} \leq(1+C h)$, whence $\mathbb{E}\left|\eta_{i}\right|^{2 p} \leq$ $(1+C h) \mathbb{E}\left|\eta_{i-1}\right|^{2 p}$. We deduce that $\max _{k \leq N}\left\|\eta_{k}\right\|_{L_{p}}=O(1)$.

Now, let us show that $\max _{k \leq N} \mathbb{E}\left|D_{r} \eta_{k}\right|^{p}=O(1)$, uniformly in $r$. Let $r$ be such that $t_{k-1}<r \leq t_{k} . \forall i \leq k-1, D_{r} \eta_{i}=0$. We note that $D_{r} \eta_{k}=\eta_{k-1} f_{z}^{\prime}\left(\theta_{t_{k-1}}\right)$. For $i \geq k+1$, we have

$$
\begin{align*}
D_{r} \eta_{i} & =D_{r} \eta_{i-1}+h D_{r}\left(\eta_{i-1} f_{y}^{\prime}\left(\theta_{t_{i-1}}\right)\right)+\sum_{l=1}^{q} D_{r}\left(\eta_{i-1} f_{z_{l}}^{\prime}\left(\theta_{t_{i-1}}\right)\right) \Delta W_{i-1}^{l} \\
& =\eta_{k-1} f_{z}^{\prime}\left(\theta_{t_{k-1}}\right)+h \sum_{j=k}^{i-1} D_{r}\left(\eta_{j} f_{y}^{\prime}\left(\theta_{t_{j}}\right)\right)+\sum_{l=1}^{q} \sum_{j=k}^{i-1} D_{r}\left(\eta_{j} f_{z_{l}}^{\prime}\left(\theta_{t_{j}}\right)\right) \Delta W_{j}^{l} . \tag{32}
\end{align*}
$$

Applying Burkholder-Davis-Gundy's inequality to the martingale $\sum_{j=k}^{i-1} D_{r}\left(\eta_{j} f_{z_{l}}^{\prime}\left(\theta_{t_{j}}\right)\right) \Delta W_{j}^{l}$ yields

$$
\begin{aligned}
\mathbb{E}\left|D_{r} \eta_{i}\right|^{p} \leq & C \mathbb{E}\left|\eta_{k-1}\right|^{p}+C_{p} h \sum_{j=k}^{i-1} \mathbb{E}\left|D_{r}\left(\eta_{j} f_{y}^{\prime}\left(\theta_{t_{j}}\right)\right)\right|^{p} \\
& +\left.\left.C \sum_{l=1}^{q} \mathbb{E}\left|h \sum_{j=k}^{i-1}\right| D_{r}\left(\eta_{j} f_{z_{l}}^{\prime}\left(\theta_{t_{j}}\right)\right)\right|^{2}\right|^{\frac{p}{2}} \\
\leq & C \mathbb{E}\left|\eta_{k-1}\right|^{p}+C h \sum_{j=k}^{i-1} \mathbb{E}\left|D_{r}\left(\eta_{j} f_{y}^{\prime}\left(\theta_{t_{j}}\right)\right)\right|^{p}+C \sum_{l=1}^{q} h \sum_{j=k}^{i-1} \mathbb{E}\left|D_{r}\left(\eta_{j} f_{z_{l}}^{\prime}\left(\theta_{t_{j}}\right)\right)\right|^{p}
\end{aligned}
$$

$$
\leq C\left(1+\mathbb{E}\left|\eta_{k-1}\right|^{p}\right)+C h \sum_{j=k+1}^{i-1} \mathbb{E}\left|D_{r} \eta_{j}\right|^{p},
$$

using the boundedness of the derivatives of $f, \max _{j \leq N}\left\|\eta_{j}\right\|_{q}=O$ (1), identity (7), $u, \sigma \in C_{b}^{1,2}$, and estimates (18). By applying Gronwall's lemma, we get $\max _{k \leq i \leq N} \mathbb{E}\left|D_{r} \eta_{i}\right|^{p} \leq C(1+$ $\left.\mathbb{E}\left|\eta_{k-1}\right|^{p}\right), t_{k-1}<r \leq t_{k}$.

Then, $\max _{k \leq N} \mathbb{E}\left|D_{r} \eta_{k}\right|^{p}=O(1)$, uniformly in $r \in[0, T]$. The proof concerning the derivative of order 2 can be done following the same scheme.

Proof of (30). We begin to show that $\mathbb{E}\left(\max _{k \leq N}\left|\eta_{k}\right|^{p}\right)<\infty$. The idea is to use a martingale property in order to apply Doob's inequality. Since $\eta_{i}=\eta_{i-1}+h \eta_{i-1} f_{y}^{\prime}\left(\theta_{t_{i-1}}\right)+$ $\eta_{i-1} f_{z}^{\prime}\left(\theta_{t_{i-1}}\right) \Delta W_{i-1}$, one has $\eta_{k}=1+\sum_{i=1}^{k}\left(h \eta_{i-1} f_{y}^{\prime}\left(\theta_{t_{i-1}}\right)+\eta_{i-1} f_{z}^{\prime}\left(\theta_{t_{i-1}}\right) \Delta W_{i-1}\right)$. Thus,

$$
\begin{aligned}
\mathbb{E}\left(\max _{k \leq N}\left|\eta_{k}\right|^{p}\right) \leq & C\left(1+\mathbb{E}\left(\sum_{i=1}^{N} h\left|\eta_{i-1}\right|\left|f_{y}^{\prime}\left(\theta_{t_{i-1}}\right)\right|\right)^{p}\right. \\
& \left.+\mathbb{E}\left(\max _{k \leq N}\left|\sum_{i=1}^{k} \eta_{i-1} f_{z}^{\prime}\left(\theta_{t_{i-1}}\right) \Delta W_{i-1}\right|^{p}\right)\right) .
\end{aligned}
$$

The last term is upper bounded by $C \mathbb{E}\left(h \sum_{i=1}^{N}\left|\eta_{i-1} f_{z}^{\prime}\left(\theta_{t_{i-1}}\right)\right|^{2}\right)^{\frac{p}{2}} \leq C h \sum_{i=1}^{N} \mathbb{E}\left|\eta_{i-1} f_{z}^{\prime}\left(\theta_{t_{i-1}}\right)\right|^{p}$. Using the estimate (29), we get $\mathbb{E}\left(\max _{k \leq N}\left|\eta_{k}\right|^{p}\right)<\infty$.

To prove that $\sup _{r \leq T} \mathbb{E}\left(\max _{k \leq N}\left|D_{r} \eta_{k}\right|^{p}\right)<\infty$, we proceed in the same way, by starting from (32). For the second derivative, this is analogous.
Step 4: We prove that $\mathbb{E}\left(\Delta Y_{N} \eta_{N}\right)=O(h)$.
If $\eta_{N}$ were equal to 1 , the results of Bally and Talay [1] would directly apply. Here the approach has to be different and we use techniques of Malliavin calculus. We have $\mathbb{E}\left(\Delta Y_{N} \eta_{N}\right)=$ $\mathbb{E}\left(\eta_{N} \Phi\left(X_{T}^{N}\right)-\eta_{N} \Phi\left(X_{T}\right)\right)$. Let us introduce $X_{t}^{N, \lambda}=(1-\lambda) X_{t}+\lambda X_{t}^{N}$. Thus, we have

$$
\mathbb{E}\left(\Delta Y_{N} \eta_{N}\right)=\int_{0}^{1} \mathbb{E}\left(\eta_{N} \Phi_{x}^{\prime}\left(X_{T}^{N, \lambda}\right)\left(X_{T}^{N}-X_{T}\right)\right) \mathrm{d} \lambda
$$

As $\Phi \in C^{3+\alpha}$, by using (29), (18) and (19), we note that $\eta_{N} \Phi_{x}^{\prime}\left(X_{T}^{N, \lambda}\right)$ satisfies $R_{2}$. By applying Remark 15 , we deduce that $\mathbb{E}\left(\Delta Y_{N} \eta_{N}\right)=O(h)$.
Step 5: We prove that $\mathbb{E}\left(f_{x}^{\prime}\left(\theta_{t_{i}}\right) \Delta X_{i} \eta_{i}\right)=O(h)$. This is a very similar proof to Step 4 , in a case where $\Phi(x)=x$.
Conclusion. We now work on $h \mathbb{E}\left(\sum_{i=0}^{N-1} \tilde{\chi}_{i} \eta_{i}\right)$, where $\left|\tilde{\chi}_{k}\right| \leq \lambda_{k}^{N} h+K(T, x)\left|\Delta X_{k}\right|^{2}+$ $K(T, x)\left|\Delta Z_{k}\right|^{2}$. Hence,

$$
\begin{aligned}
\left|h \sum_{i=0}^{N-1} \mathbb{E}\left(\tilde{\chi}_{i} \eta_{i}\right)\right| & \leq C \sum_{i=0}^{N-1} \mathbb{E}\left(\lambda_{i}^{N}\left|\eta_{i}\right|\right) h^{2}+K(T, x) \sum_{i=0}^{N-1} h \mathbb{E}\left(\left|\eta_{i}\right|\left(\left|\Delta X_{i}\right|^{2}+\left|\Delta Z_{i}\right|^{2}\right)\right) \\
& \leq K(T, x) h+K(T, x) \sum_{i=0}^{N-1} h \mathbb{E}\left(\left|\eta_{i}\right|\left|\Delta Z_{i}\right|^{2}\right) \\
& \leq K(T, x) h+K(T, x)\left(\mathbb{E}\left(\max _{0 \leq i \leq N-1}\left|\eta_{i}\right|\right)^{2}\right)^{\frac{1}{2}}\left(\mathbb{E}\left(h \sum_{i=0}^{N-1}\left|\Delta Z_{i}\right|^{2}\right)^{2}\right)^{\frac{1}{2}} .
\end{aligned}
$$

By using (30) on $\left(\eta_{i}\right)_{i}$ and the upper bound (17) we get that $\left|h \mathbb{E}\left(\sum_{i=0}^{N-1} \tilde{\chi}_{i} \eta_{i}\right)\right| \leq K(T, x) h$. By combining this result and the results of Step 4 and Step 5, (28) shows that $\left|\Delta Y_{0}\right| \leq K(T, x) h$. Lemma 16 is proved.

## 5. Proof of Theorem 8

As could be expected, its proof is more difficult. The main extra ingredient is the convergence of the weak derivative of the discrete $\operatorname{BSDE}\left(Y^{N}, Z^{N}\right)$, with the rate of convergence $N^{-1 / 2}$. The next paragraph is aimed at proving this result. In the following, Hypothesis 3 is in force.

### 5.1. Proof of an intermediate result

Proposition 17. Let $\quad r \in] 0$, $t_{1}\left[\right.$. Under Hypothesis 3, we have $\max _{1 \leq i \leq N} \mathbb{E}\left|D_{r} \Delta Y_{i}\right|^{2}+$ $h \mathbb{E}\left(\sum_{i=1}^{N-1}\left|D_{r} \Delta Z_{i}^{*}\right|^{2}\right)=O(h)$, uniformly in $r$.

This proposition is analogous to Theorem 6, where $q=2$, and the scheme of its proof as well. However, there is a significant difference: the BSDE solved by the weak derivatives (see (33)-(35)) has a non-Lipschitz driver, which requires extra technicalities that we detail. In what follows, we fix $r \in] 0, t_{1}$ [ and introduce some specific notations. $\widehat{X_{t}}$ stands for $D_{r} X_{t}$. In the case of $Z_{t}$, which is a row vector, $\widehat{Z}_{t}$ is a matrix whose $i$ th column is $D_{r}^{i} Z_{t}^{*}$. It is well-known (Proposition 5.3 of El Karoui et al. [5]) that $\left(\widehat{Y}_{t}, \widehat{Z}_{t}\right)_{r \leq t \leq T}$ solves

$$
\begin{equation*}
\widehat{Y_{t}}=\Phi_{x}^{\prime}\left(X_{T}\right) \widehat{X_{T}}+\int_{t}^{T}\left(f_{x}^{\prime}\left(\theta_{s}\right) \widehat{X_{s}}+f_{y}^{\prime}\left(\theta_{s}\right) \widehat{Y_{s}}+f_{z}^{\prime}\left(\theta_{s}\right) \widehat{Z_{s}}\right) \mathrm{d} s-\left(\int_{t}^{T}{\widehat{Z_{s}}}^{*} \mathrm{~d} W_{s}\right)^{*} \tag{33}
\end{equation*}
$$

Regarding $\left(\widehat{Y^{N}}, \widehat{Z^{N}}\right)$, one obtains

$$
\begin{align*}
& \left.\widehat{Y_{t_{k}}^{N}}=\mathbb{E}_{t_{k}} \widehat{Y_{t_{k+1}}^{N}}+h \nabla_{x} f_{t_{k}}^{N} \widehat{X_{t_{k}}^{N}}+h \nabla_{y} f_{t_{k}}^{N} \widehat{Y_{t_{k+1}}^{N}}+h \nabla_{z} f_{t_{k}}^{N} \widehat{Z_{t_{k}}^{N}}\right]  \tag{34}\\
& \widehat{Z_{t_{k}}^{N}}=\frac{1}{h} \mathbb{E}_{t_{k}}\left[\Delta W_{k} \widehat{Y_{t_{k+1}}^{N}}\right] \tag{35}
\end{align*}
$$

where we set $\nabla_{x} f_{t_{k}}^{N}=\nabla_{x} f\left(t_{k}, X_{t_{k}}^{N}, Y_{t_{k+1}}^{N}, Z_{t_{k}}^{N}\right)$ and analogously for $\nabla_{y} f_{t_{k}}^{N}$ and $\nabla_{z} f_{t_{k}}^{N}$. Indeed, we can start from (4) and (5) and interchange conditional expectations and weak derivatives (see Proposition 1.2.4 in Nualart [16]). Another way to get (34) and (35) is to take advantage of the Markov structure of $\left(X_{t_{k}}^{N}\right)_{k}$ to write $Y_{t_{k}}^{N}=y^{N}\left(t_{k}, X_{t_{k}}^{N}\right)$, where the function $y^{N}$ is the solution of a dynamic programming equation, and then apply the chain rule. We omit further details.

From (7), we also have

$$
\begin{equation*}
\widehat{Y}_{t}=\nabla_{x} u\left(t, X_{t}\right) \widehat{X_{t}}, \quad \widehat{Z}_{t}=\nabla_{x}\left(\nabla_{x} u \sigma\right)^{*}\left(t, X_{t}\right) \widehat{X_{t}} \tag{36}
\end{equation*}
$$

For the sake of clarity, let us write, for any process $V, \widehat{\Delta V_{k}}=D_{r} V_{t_{k}}^{N}-D_{r} V_{t_{k}}$. In particular, we have $\widehat{\Delta \bar{Z}}_{k}=D_{r}\left(Z_{t_{k}}^{N^{*}}-\bar{Z}_{t_{k}}^{*}\right)=\widehat{Z_{t_{k}}^{N}}-\widehat{\bar{Z}_{t_{k}}}$, where $\widehat{\bar{Z}_{t_{k}}}$ is defined as $h \widehat{\bar{Z}_{t_{k}}}=\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}} \widehat{Z_{s}} \mathrm{~d} s$ (see the beginning of Section 3).

### 5.1.1. Preparatory estimates

In this part we give some $L_{p}$-estimates ( $p \geq 1$ ), which are repeatedly used in the following calculations.
-

$$
\begin{equation*}
\sup _{i \leq j \leq N}\left(\mathbb{E}_{t_{i}}\left|\widehat{X_{t_{j}}^{N}}\right|^{2 p}\right) \leq C\left|\widehat{X_{i}^{N}}\right|^{2 p} \tag{37}
\end{equation*}
$$

$$
\begin{equation*}
\mathbb{E}\left(\max _{0 \leq j \leq N}\left|\widehat{X_{t_{j}}^{N}}\right|^{2 p}\right)=O(1) \tag{38}
\end{equation*}
$$

$\bullet$

$$
\begin{equation*}
\forall j \in 0 \cdots N-1, \quad\left|\widehat{Y_{t_{j}}}\right|^{2} \leq C\left|\widehat{X_{t_{j}}^{N}}\right|^{2}, \quad \mathbb{E}\left(\max _{0 \leq j \leq N}\left|\widehat{Y_{t_{j}}}\right|^{2 p}\right)=O(1) \tag{39}
\end{equation*}
$$

$$
\begin{equation*}
\mathbb{E}\left(\sup _{0 \leq t \leq T}\left|\widehat{X_{t}}\right|^{2 p}+\sup _{0 \leq t \leq T}\left|\widehat{Y}_{t}\right|^{2 p}+\sup _{0 \leq t \leq T}\left|\widehat{Z}_{t}\right|^{2 p}\right)=O(1) . \tag{40}
\end{equation*}
$$

- Let $F$ satisfy $R_{3}$. Then, $\left|\mathbb{E}\left(F\left(\widehat{X_{t}^{N}}-\widehat{X_{t}}\right)\right)\right|=O(h)$. Furthermore,

$$
\begin{equation*}
\sup _{0 \leq k \leq N} \mathbb{E}\left|\widehat{\Delta X_{k}}\right|^{2 p}=O\left(h^{p}\right) \tag{41}
\end{equation*}
$$

- Analogously to (9), $\forall s \in\left[t_{k}, t_{k+1}\right]$, we have

$$
\begin{equation*}
\mathbb{E}_{t_{k}}\left(\left|\widehat{X_{s}}-\widehat{X_{t_{k}}}\right|^{2 p}+\left|\widehat{Y_{s}}-\widehat{Y_{t_{k}}}\right|^{2 p}+\left|\widehat{Z_{s}}-\widehat{\bar{Z}_{t_{k}}}\right|^{2 p}\right)=O_{k}\left(h^{p}\right) . \tag{42}
\end{equation*}
$$

Note that $\widehat{X_{t_{1}}^{N}}=\sigma(0, x)$, and $\widehat{X_{t_{k+1}}^{N}}=\left(1+h b_{x}^{\prime}\left(t_{k}, X_{t_{k}}^{N}\right)+\sum_{i=1}^{q}\left(\sigma_{i}\right)_{x}^{\prime}\left(t_{k}, X_{t_{k}}^{N}\right) \Delta W_{k}^{i} \widehat{X_{t_{k}}^{N}}\right.$ for $1 \leq k \leq N$. Thus, we easily get $\mathbb{E}_{t_{i}}\left|\widehat{X_{t}^{N}}\right|^{2 p} \leq(1+C h) \mathbb{E}_{t_{i}}\left|\widehat{X_{t_{j-1}}^{N}}\right|^{2 p}$, and (37) follows. The proof of (38) can be done as the proof of (30).

Proof of (39). From (34), we use Young's inequality and boundedness of $\nabla f$ to get

$$
\begin{equation*}
\left|\widehat{Y_{t_{i}}^{N}}\right|^{2} \leq(1+\gamma h)\left|\mathbb{E}_{t_{i}} \widehat{Y_{t_{i+1}}^{N}}\right|^{2}+C h\left(h+\frac{1}{\gamma}\right)\left(\left.\widehat{X_{t_{i}}^{N}}\right|^{2}+\mathbb{E}_{t_{i}}\left|\widehat{Y_{t_{i+1}}^{N}}\right|^{2}+\left|\widehat{Z_{t_{i}}^{N}}\right|^{2}\right) . \tag{43}
\end{equation*}
$$

From (35) and the Cauchy-Schwarz inequality, we obtain $h\left|\widehat{Z_{t_{i}}}\right|^{2} \leq C\left(\mathbb{E}_{t_{i}}\left|\widehat{Y_{t_{i+1}}}\right|^{2}-\left|\mathbb{E}_{t_{i}} \widehat{Y_{t_{i+1}}}\right|^{2}\right)$. Hence, with an appropriate choice of $\gamma$, (43) is reduced to $\left|\widehat{Y_{i}}\right|^{2} \leq(1+C h) \mathbb{E}_{t_{i}}\left|\widehat{Y_{i+1}^{N}}\right|^{2}+$ $C h\left|\widehat{X_{t_{i}}^{N}}\right|^{2}$, and thus Gronwall's lemma yields

$$
\left|\widehat{Y_{t_{i}}^{N}}\right|^{2} \leq C \mathbb{E}_{t_{i}}\left(\left|\widehat{Y_{t_{N}}^{N}}\right|^{2}+h \sum_{j=i}^{N-1}\left|\widehat{X_{t_{j}}^{N}}\right|^{2}\right) \leq\left. C \sup _{i \leq j \leq N-1} \mathbb{E}_{t_{i}} \widehat{X_{t_{j}}^{N}}\right|^{2}
$$

Finally, estimates (37) and (38) complete the proof.
Proof of (40). $\mathbb{E}\left(\sup _{0 \leq t \leq T}\left|\widehat{X_{t}}\right|^{2 p}\right)=O(1)$ follows from (18). The other estimates come from this result and (36).

Proof of (41). Let us introduce $X_{t}^{\prime}=\nabla_{x} X_{t}\left(\nabla_{x} X_{r}\right)^{-1} \sigma(0, x)$ and write $\widehat{X_{t}^{N}}-\widehat{X_{t}}=\widehat{X_{t}^{N}}-X_{t}^{\prime}+$ $X_{t}^{\prime}-\widehat{X_{t}}$.

Since $\widehat{X_{t}}=\nabla_{x} X_{t}\left(\nabla_{x} X_{r}\right)^{-1} \sigma\left(r, X_{r}\right)$, a direct application of Proposition 12 with $U_{t}=$ $\sigma\left(t, X_{t}\right)$ gives $\mathbb{E}\left(F\left(X_{t}^{\prime}-\widehat{X_{t}}\right)\right)=O(h)$ for $F$ satisfying $R_{2}$. Moreover, simple increment estimates yield $\sup _{t \leq T} \mathbb{E}\left|X_{t}^{\prime}-\widehat{X_{t}}\right|^{2 p}=O\left(h^{p}\right)$.

It remains to study the impact of the difference $\widehat{X_{t}^{N}}-X_{t}^{\prime} \cdot\left(\widehat{X_{t}^{N}}\right)_{t \geq r}$ and $\left(X_{t}^{\prime}\right)_{t \geq r}$ are solutions of

$$
\begin{align*}
& \widehat{X_{t}^{N}}=\sigma(0, x)+\int_{r}^{t} b_{x}^{\prime}\left(\eta(s), X_{\eta(s)}^{N}\right) \widehat{X_{\eta(s)}^{N}} \mathrm{~d} s+\sum_{i=1}^{q} \int_{r}^{t}\left(\sigma_{i}\right)_{x}^{\prime}\left(\eta(s), X_{\eta(s)}^{N}\right) \widehat{X_{\eta(s)}^{N}} \mathrm{~d} W_{s}^{i} \\
& X_{t}^{\prime} \tag{44}
\end{align*}=\sigma(0, x)+\int_{r}^{t} b_{x}^{\prime}\left(s, X_{s}\right) X_{s}^{\prime} \mathrm{d} s+\sum_{i=1}^{q} \int_{r}^{t}\left(\sigma_{i}\right)_{x}^{\prime}\left(s, X_{s}\right) X_{s}^{\prime} \mathrm{d} W_{s}^{i} .
$$

For the sake of simplicity, we take $b \equiv 0$ and $d=q=1$. If we set $\sigma^{\prime}(s)=\int_{0}^{1} \sigma_{x}^{\prime}\left(s, X_{s}+\right.$ $\left.\lambda\left(X_{s}^{N}-X_{s}\right)\right) \mathrm{d} \lambda$, we observe that $\Delta X_{t}$ solves the linear equation $\Delta X_{t}=\int_{0}^{t}\left[\sigma\left(\eta(s), X_{\eta(s)}^{N}\right)-\right.$ $\left.\sigma\left(s, X_{s}^{N}\right)\right] \mathrm{d} W_{s}+\int_{0}^{t} \sigma^{\prime}(s) \Delta X_{s} \mathrm{~d} W_{s}$, whose solution is given by (see Theorem 56, p. 271 in Protter [19])

$$
\begin{aligned}
\Delta X_{t}= & \epsilon_{t} \int_{0}^{t} \epsilon_{s}^{-1}\left[\sigma\left(\eta(s), X_{\eta(s)}^{N}\right)-\sigma\left(s, X_{s}^{N}\right)\right]\left(\mathrm{d} W_{s}-\sigma^{\prime}(s) \mathrm{d} s\right) \\
= & -\epsilon_{t} \int_{0}^{t} \epsilon_{s}^{-1}\left[\int_{\eta(s)}^{s} \sigma_{x}^{\prime}\left(v, X_{v}^{N}\right) \sigma\left(\eta(v), X_{\eta(v)}^{N}\right) \mathrm{d} W_{v}\right. \\
& \left.+\left(\sigma_{t}^{\prime}\left(v, X_{v}^{N}\right)+\frac{1}{2} \sigma_{x x}^{\prime \prime}\left(v, X_{v}^{N}\right) \sigma^{2}\left(\eta(v), X_{\eta(v)}^{N}\right)\right) \mathrm{d} v\right]\left(\mathrm{d} W_{s}-\sigma^{\prime}(s) \mathrm{d} s\right)
\end{aligned}
$$

where $\epsilon_{t}=1+\int_{0}^{t} \sigma^{\prime}(s) \epsilon_{s} \mathrm{~d} W_{s}$. This proves that $\Delta X_{t}$ satisfies the property $(\mathcal{P})$. Analogously, if we define $\sigma^{\prime \prime}(s)=\int_{0}^{1} \sigma_{x x}^{\prime \prime}\left(s, X_{s}+\lambda\left(X_{s}^{N}-X_{s}\right)\right) \mathrm{d} \lambda$ and $\epsilon_{t}^{N}=1+\int_{r}^{t} \sigma_{x}^{\prime}\left(s, X_{s}^{N}\right) \epsilon_{s}^{N} \mathrm{~d} W_{s}$, simple computations lead to

$$
\begin{aligned}
\widehat{X_{t}^{N}}-X_{t}^{\prime}= & \epsilon_{t}^{N} \int_{r}^{t}\left(\epsilon_{s}^{N}\right)^{-1}\left(\left[\sigma_{x}^{\prime}\left(\eta(s), X_{\eta(s)}^{N}\right) \widehat{X_{\eta(s)}^{N}}-\sigma_{x}^{\prime}\left(s, X_{s}^{N}\right) \widehat{X_{s}^{N}}\right]+\sigma^{\prime \prime}(s) X_{s}^{\prime} \Delta X_{s}\right) \\
& \times\left(\mathrm{d} W_{s}-\sigma_{x}^{\prime}\left(s, X_{s}^{N}\right) \mathrm{d} s\right)
\end{aligned}
$$

From the above representation, it is straightforward to conclude $\sup _{t \leq T} \mathbb{E}|\widehat{\Delta X} t|^{2 p}=O\left(h^{p}\right)$. Now, let us upper bound $\mathbb{E}\left(F\left(\widehat{X_{t}^{N}}-X_{t}^{\prime}\right)\right)$ which can be decomposed into several terms.

- The contribution associated to $\epsilon_{t}^{N} \int_{r}^{t}\left(\epsilon_{s}^{N}\right)^{-1}\left[\sigma_{x}^{\prime}\left(\eta(s), X_{\eta(s)}^{N}\right) \widehat{X_{\eta(s)}^{N}}-\sigma_{x}^{\prime}\left(s, X_{s}^{N}\right) \widehat{X_{s}^{N}}\right]\left(\mathrm{d} W_{s}-\right.$ $\left.\sigma_{x}^{\prime}\left(s, X_{s}^{N}\right) \mathrm{d} s\right)$ satisfies property $(\mathcal{P})$, thus Proposition 14 yields the expected result.
- The contribution $\mathbb{E}\left(F \epsilon_{t}^{N} \int_{r}^{t}\left(\epsilon_{s}^{N}\right)^{-1} \sigma^{\prime \prime}(s) X_{s}^{\prime} \Delta X_{s} \sigma_{x}^{\prime}\left(s, X_{s}^{N}\right) \mathrm{d} s\right)$ is equal to $\int_{r}^{t} \mathbb{E}\left(F \epsilon_{t}^{N}\left(\epsilon_{s}^{N}\right)^{-1}\right.$ $\left.\sigma^{\prime \prime}(s) X_{s}^{\prime} \Delta X_{s} \sigma_{x}^{\prime}\left(s, X_{s}^{N}\right)\right) \mathrm{d} s=O(h)$ in view of Remark 15.
- In the same way, the duality relationship ensures that the last contribution $\mathbb{E}\left(F \epsilon_{t}^{N} \int_{r}^{t}\left(\epsilon_{s}^{N}\right)^{-1}\right.$ $\left.\sigma^{\prime \prime}(s) X_{s}^{\prime} \Delta X_{s} \mathrm{~d} W_{s}\right)=\int_{r}^{t} \mathbb{E}\left(D_{s}\left(F \epsilon_{t}^{N}\right)\left(\epsilon_{s}^{N}\right)^{-1} \sigma^{\prime \prime}(s) X_{s}^{\prime} \Delta X_{s}\right) \mathrm{d} s$ is a $O(h)$ (using here that $F$ satisfies $R_{3}$ ).

Proof of (42). In view of $\widehat{X_{t}}=D_{r} X_{t}=\nabla_{x} X_{t}\left(\nabla_{x} X_{r}\right)^{-1} \sigma\left(r, X_{r}\right)$, the estimate on the increments of $\widehat{X_{t}}$ becomes clear. The other ones easily follow.

### 5.1.2. Proof of $\max _{1 \leq i \leq N} \mathbb{E}|\widehat{\Delta Y}|^{2}=O(h)$

Assume that for some non-negative random variable $\Lambda_{k}=O_{k}(h)+\left|\Delta X_{k}\right|^{2}+\left|\Delta Z_{k}\right|^{2}$, one has

$$
\begin{equation*}
\left|\widehat{\Delta Y_{k}}\right|^{2} \leq(1+C h) \mathbb{E}_{t_{k}}\left|\widehat{\Delta Y_{k+1}}\right|^{2}+h\left|\widehat{\Delta X_{k}}\right|^{2}+h \Lambda_{k} O_{k}(1) . \tag{45}
\end{equation*}
$$

Take the expectation on both sides, use estimates (41) and those of Proposition 5 to get

$$
\mathbb{E}\left|\widehat{\Delta Y_{k}}\right|^{2} \leq C \mathbb{E}\left|\widehat{\Delta Y_{N}}\right|^{2}+O(h)+C h \sum_{k=0}^{N-1} \mathbb{E}\left(\left|\Delta Z_{k}\right|^{2} O_{k}(1)\right)
$$

On the one hand, as $\widehat{\Delta Y_{N}}=\Phi^{\prime}\left(X_{t_{N}}^{N}\right) \widehat{X_{t_{N}}^{N}}-\Phi^{\prime}\left(X_{t_{N}}\right) \widehat{X_{t_{N}}}$, clearly $\mathbb{E}\left|\widehat{\Delta Y_{N}}\right|^{2}=O(h)$. On the other hand, in view of (17) with $p=2$, the summation above is a $O(h)$. This proves $\max _{1 \leq k \leq N} \mathbb{E}\left|\widehat{\Delta Y_{k}}\right|^{2}=O(h)$.

Proof of (45). From (33) and (34), we obtain

$$
\begin{aligned}
\widehat{\Delta Y_{k}}= & \mathbb{E}_{t_{k}}\left(\widehat{\Delta Y_{k+1}}\right)+\mathbb{E}_{t_{k}}\left(\int _ { t _ { k } } ^ { t _ { k + 1 } } \left[\nabla_{x} f_{t_{k}}^{N} \widehat{X_{t_{k}}^{N}}-f_{x}^{\prime}\left(\theta_{s}\right) \widehat{X_{s}}\right.\right. \\
& \left.\left.+\nabla_{y} f_{t_{k}}^{N} \widehat{Y_{t_{k+1}}^{N}}-f_{y}^{\prime}\left(\theta_{s}\right) \widehat{Y}_{s}+\nabla_{z} f_{t_{k}}^{N} \widehat{Z_{t_{k}}^{N}}-f_{z}^{\prime}\left(\theta_{s}\right) \widehat{Z_{s}}\right] \mathrm{~d} s\right)
\end{aligned}
$$

Since $f \in C_{b}^{2,4,4,4}$, it follows that for any $\gamma>0$ (to be fixed later)

$$
\begin{align*}
\left|\widehat{\Delta Y_{k}}\right|^{2} \leq & (1+\gamma h)\left|\mathbb{E}_{t_{k}}\left(\widehat{\Delta Y_{k+1}}\right)\right|^{2}+C\left(h+\frac{1}{\gamma}\right) \mathbb{E}_{t_{k}}\left(\int _ { t _ { k } } ^ { t _ { k + 1 } } \left[\left|\nabla_{x} f_{t_{k}}^{N} \widehat{X_{t_{k}}^{N}}-f_{x}^{\prime}\left(\theta_{s}\right) \widehat{X_{s}}\right|^{2}\right.\right. \\
& \left.\left.+\left|\nabla_{y} f_{t_{k}}^{N} \widehat{{t_{t_{k+1}}^{N}}^{N}}-f_{y}^{\prime}\left(\theta_{s}\right) \widehat{Y_{s}}\right|^{2}+\left|\nabla_{z} f_{t_{k}}^{N} \widehat{Z_{t_{k}}^{N}}-f_{z}^{\prime}\left(\theta_{s}\right) \widehat{Z_{s}}\right|^{2}\right] \mathrm{~d} s\right)  \tag{46}\\
\leq & (1+\gamma h)\left|\mathbb{E}_{t_{k}}\left(\widehat{\Delta Y_{k+1}}\right)\right|^{2}+C\left(h+\frac{1}{\gamma}\right)\left(T_{k}^{1}+T_{k}^{2}\right), \tag{47}
\end{align*}
$$

where we put $T_{k}^{1}=\mathbb{E}_{t_{k}}\left(\int_{t_{k}}^{t_{k+1}}\left[\left|\widehat{X_{t_{k}}}-\widehat{X_{s}}\right|^{2}+\left|\widehat{Y_{t_{k+1}}}-\widehat{Y_{s}}\right|^{2}+\left|\widehat{Z_{t_{k}}^{N}}-\widehat{Z_{s}}\right|^{2}\right] \mathrm{d} s\right), T_{k}^{2}=\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}(h+$ $\left.\left|X_{s}-X_{t_{k}}^{N}\right|^{2}+\left|Y_{s}-Y_{t_{k+1}}^{N}\right|^{2}+\left|Z_{s}-Z_{t_{k}}^{N}\right|^{2}\right)\left(\left|\widehat{X_{s}}\right|^{2}+\left|\widehat{Y_{s}}\right|^{2}+\left|\widehat{Z_{s}}\right|^{2}\right) \mathrm{d} s$. To get (45), we need to simplify (47), by estimating $T_{k}^{1}$ and $T_{k}^{2}$.
Term $T_{k}^{1}$. Firstly, we write $\mathbb{E}_{t_{k}}\left|\widehat{Y_{t_{k+1}}^{N}}-\widehat{Y}_{s}\right|^{2} \leq 2 \mathbb{E}_{t_{k}}\left|\widehat{Y_{t_{k+1}}}-\widehat{Y}_{s}\right|^{2}+2 \mathbb{E}_{t_{k}}\left|\widehat{\Delta Y_{k+1}}\right|^{2}$. We do the same for $\widehat{X_{t_{k}}^{N}}-\widehat{X_{s}}$. Then, the usual increment estimates yield

$$
\mathbb{E}_{t_{k}}\left|\widehat{Y_{t_{k+1}}^{N}}-\widehat{Y}_{s}\right|^{2}+\mathbb{E}_{t_{k}}\left|\widehat{X_{t_{k}}^{N}}-\widehat{X_{s}}\right|^{2} \leq O_{k}(h)+2\left|\widehat{\Delta X_{k}}\right|^{2}+2 \mathbb{E}_{t_{k}}\left|\widehat{\Delta Y_{k+1}}\right|^{2}
$$

Secondly, analogously to (13), we have

$$
\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|\widehat{Z_{t_{k}}^{N}}-\widehat{Z_{s}}\right|^{2} \mathrm{~d} s=\mathbb{E}_{t_{k}} \int_{t_{k}}^{t_{k+1}}\left|\widehat{\bar{Z}_{t_{k}}}-\widehat{Z_{s}}\right|^{2} \mathrm{~d} s+h \mathbb{E}_{t_{k}}\left|\widehat{Z_{t_{k}}^{N}}-\widehat{\bar{Z}_{t_{k}}}\right|^{2}
$$

Finally, we obtain $T_{k}^{1} \leq \operatorname{Ch}\left(O_{k}(h)+\left|\widehat{\Delta X_{k}}\right|^{2}+\mathbb{E}_{t_{k}}\left|\widehat{\Delta Y_{k+1}}\right|^{2}+\left|\widehat{\Delta \bar{Z}_{k}}\right|^{2}\right)$.
Term $T_{k}^{2}$. Easy calculations combining (9), Proposition 11 and (40) give $T_{k}^{2} \leq\left(O_{k}\left(h^{2}\right)+\right.$ $\left.h\left|\Delta X_{k}\right|^{2}+h\left|\Delta Z_{k}\right|^{2}\right) O_{k}(1)=h \Lambda_{k} O_{k}(1)$.

Conclusion. Plugging the estimates on $T_{k}^{1}$ and $T_{k}^{2}$ into (47), we get

$$
\begin{align*}
\left|\widehat{\Delta Y_{k}}\right|^{2} \leq & (1+\gamma h)\left|\mathbb{E}_{t_{k}}\left(\widehat{\Delta Y_{k+1}}\right)\right|^{2}+C h\left(h+\frac{1}{\gamma}\right)\left|\widehat{\Delta \bar{Z}_{k}}\right|^{2} \\
& +C h\left(h+\frac{1}{\gamma}\right)\left(\left|\widehat{\Delta X_{k}}\right|^{2}+\mathbb{E}_{t_{k}}\left|\widehat{\Delta Y_{k+1}}\right|^{2}+\Lambda_{k} O_{k}(1)\right) . \tag{48}
\end{align*}
$$

Note that $h \widehat{Z_{t_{k}}}=\mathbb{E}_{t_{k}}\left(\Delta W_{k}\left(\widehat{Y_{t_{k+1}}}+\int_{t_{k}}^{t_{k+1}}\left[f_{x}^{\prime}\left(\theta_{s}\right) \widehat{X_{s}}+f_{y}^{\prime}\left(\theta_{s}\right) \widehat{Y_{s}}+f_{z}^{\prime}\left(\theta_{s}\right) \widehat{Z_{s}}\right] \mathrm{d} s\right)\right.$ ), whence $h \widehat{\Delta \bar{Z}_{t_{k}}}=\mathbb{E}_{t_{k}}\left(\Delta W_{k}\left(\widehat{\Delta Y_{k+1}}+\int_{t_{k}}^{t_{k+1}}\left[f_{x}^{\prime}\left(\theta_{s}\right) \widehat{X_{s}}+f_{y}^{\prime}\left(\theta_{s}\right) \widehat{Y}_{s}+f_{z}^{\prime}\left(\theta_{s}\right) \widehat{Z_{s}}\right] \mathrm{d} s\right)\right)$. By proceeding as before, we easily prove

$$
\begin{equation*}
h\left|\widehat{\Delta \bar{Z}_{t_{k}}}\right|^{2} \leq C\left(\mathbb{E}_{t_{k}}\left|\widehat{\Delta Y_{k+1}}\right|^{2}-\left|\mathbb{E}_{t_{k}} \widehat{\Delta Y_{k+1}}\right|^{2}\right)+O_{k}\left(h^{2}\right) \tag{49}
\end{equation*}
$$

Combining this upper bound with (48) for a good choice of $\gamma$ gives (45).
5.1.3. Proof of $h \mathbb{E}\left(\sum_{k=1}^{N-1}\left|\widehat{\Delta Z_{k}}\right|^{2}\right)=O(h)$

In view of (42), this is equivalent to proving $h \mathbb{E}\left(\sum_{k=1}^{N-1}\left|\widehat{\Delta \bar{Z}}_{k}\right|^{2}\right)=O(h)$. To establish this estimate, we start from (49) to get

$$
\begin{equation*}
h \sum_{k=1}^{N-1} \mathbb{E}\left|\widehat{\Delta \bar{Z}_{k}}\right|^{2} \leq C \sum_{k=1}^{N-1}\left(\mathbb{E}\left|\widehat{\Delta Y_{k}}\right|^{2}-\mathbb{E}\left|\mathbb{E}_{t_{k}} \widehat{\Delta Y_{k+1}}\right|^{2}\right)+C \mathbb{E}\left|\widehat{\Delta Y_{N}}\right|^{2}+O(h) \tag{50}
\end{equation*}
$$

Now, we work on $\left|\widehat{\Delta Y_{k}}\right|^{2}-\left|\mathbb{E}_{t_{k}} \widehat{\widehat{\Delta Y} Y_{k+1}}\right|^{2}$. The choice $\gamma=2 C^{2}$ in (48) leads to

$$
\begin{aligned}
\left|\widehat{\Delta Y_{k}}\right|^{2}-\left|\mathbb{E}_{t_{k}}\left(\widehat{\Delta Y_{k+1}}\right)\right|^{2} \leq & \gamma h\left|\mathbb{E}_{t_{k}}\left(\widehat{\Delta Y_{k+1}}\right)\right|^{2}+h\left(\frac{1}{2 C}+C h\right)\left|\widehat{\Delta \bar{Z}_{k}}\right|^{2} \\
& +h\left(C h+\frac{1}{2 C}\right)\left(\left|\widehat{\Delta X_{k}}\right|^{2}+\mathbb{E}_{t_{k}}\left|\widehat{\Delta Y_{k+1}}\right|^{2}+\Lambda_{k} O_{k}(1)\right) .
\end{aligned}
$$

From (41) and the result from Section 5.1.2, we have $\max _{1 \leq k \leq N} \mathbb{E}\left(\left|\widehat{\Delta X_{k}}\right|^{2}+\left|\widehat{\Delta Y_{k}}\right|^{2}\right)=O(h)$. We also have $\mathbb{E}\left(\Lambda_{k} O_{k}(1)\right)=O(h)+\mathbb{E}\left(\left|\Delta Z_{k}\right|^{2} O_{k}(1)\right)$. Consequently, for $h$ small enough, one has $\mathbb{E}\left|\widehat{\Delta Y_{k}}\right|^{2}-\mathbb{E}\left|\mathbb{E}_{t_{k}}\left(\widehat{\Delta Y_{k+1}}\right)\right|^{2} \leq \frac{2 h}{3 C} \mathbb{E}\left|\widehat{\Delta \bar{Z}_{k}}\right|^{2}+O\left(h^{2}\right)+C h \mathbb{E}\left(\left|\Delta Z_{k}\right|^{2} O_{k}(1)\right)$. Putting this estimate into (50) yields

$$
\frac{1}{3} h \sum_{k=1}^{N-1} \mathbb{E}\left|\widehat{\Delta \bar{Z}}_{k}\right|^{2} \leq O(h)+C h \sum_{k=1}^{N-1} \mathbb{E}\left(\left|\Delta Z_{k}\right|^{2} O_{k}(1)\right)
$$

Inequality (17) with $p=2$ directly shows that the sum above is a $O(h)$.

### 5.2. Expansion of $Z_{t_{k}}^{N}-Z_{t_{k}}$

We recall that $u \in C_{b}^{2,4}$ owing to Hypothesis 3. From (26), we have $\Delta Z_{k}=O(h)+$ $\frac{1}{h} \mathbb{E}_{t_{k}}\left[\left(u^{N}\left(t_{k+1}, X_{t_{k+1}}^{N}\right)-u\left(t_{k+1}, X_{t_{k+1}}\right)\right) \Delta W_{k}^{*}\right]$. Let $\left(X_{t}^{s, \bar{x}}\right)_{t \geq s}$ denote the solution of the SDE (1) starting at time $s$ from $\bar{x}$. We write $X_{t}$ for $X_{t}^{0, x}$. Note that $X_{t_{k+1}}=X_{t_{k+1}}^{t_{k}, X_{t_{k}}}$. In the same way, the Euler scheme starting at time $t_{k}$ at $\bar{x}$ is denoted by $\left(X_{t_{j}}^{N, t_{k}, \bar{x}}\right)_{j \geq k}$. With this notation we can
rewrite $\Delta Z_{k}$

$$
\begin{align*}
\Delta Z_{k}= & \frac{1}{h} \mathbb{E}_{t_{k}}\left[\left(u^{N}\left(t_{k+1}, X_{t_{k+1}}^{N, t_{k}, X_{t_{k}}^{N}}\right)-u\left(t_{k+1}, X_{t_{k+1}}\right)\right) \Delta W_{k}^{*}\right]+O(h), \\
= & \frac{1}{h} \mathbb{E}_{t_{k}}\left[\left(u\left(t_{k+1}, X_{t_{k+1}}^{t_{k}, X_{t_{k}}^{N}}\right)-u\left(t_{k+1}, X_{t_{k+1}}\right)\right) \Delta W_{k}^{*}\right] \\
& +\frac{1}{h} \mathbb{E}_{t_{k}}\left[\left(u^{N}\left(t_{k+1}, X_{t_{k+1}}^{N, t_{k}, X_{t_{k}}^{N}}\right)-u\left(t_{k+1}, X_{t_{k+1}}^{t_{k}, X_{t_{k}}^{N}}\right)\right) \Delta W_{k}^{*}\right]+O(h) . \tag{51}
\end{align*}
$$

We work on the first two terms separately by proving
Lemma 18. $\frac{1}{h} \mathbb{E}_{t_{k}}\left[\left(u\left(t_{k+1}, X_{t_{k+1}}^{t_{k}, X_{t_{k}}^{N}}\right)-u\left(t_{k+1}, X_{t_{k+1}}\right)\right) \Delta W_{k}^{*}\right] \quad=\quad O\left(\left|\Delta X_{k}\right|^{2}\right)+O(h)+$ $\left[\nabla_{x}\left(\nabla_{x} u \sigma\right)^{*}\left(t_{k}, X_{t_{k}}\right) \Delta X_{k}\right]^{*}$.

Lemma 19. $\frac{1}{h}\left|\mathbb{E}_{t_{k}}\left[\left(u^{N}\left(t_{k+1}, X_{t_{k+1}}^{N, t_{k}, X_{t_{k}}^{N}}\right)-u\left(t_{k+1}, X_{t_{k+1}}^{t_{k}, X_{t_{k}}^{N}}\right)\right) \Delta W_{k}^{*}\right]\right|=O_{k}(h)$.
The combination of these lemmas completes the proof of Theorem 8.

### 5.2.1. Proof of Lemma 18

For the sake of simplicity, let $\Delta_{N} X_{k+1}$ denote $X_{t_{k+1}}^{t_{k}, X_{t_{k}}^{N}}-X_{t_{k+1}}$ (which is different from $\Delta X_{k+1}=X_{t_{k+1}}^{N, t_{k}, X_{t_{k}}^{N}}-X_{t_{k+1}}$ ). From a Taylor-Lagrange formula, we obtain

$$
\begin{aligned}
& u\left(t_{k+1}, X_{t_{k+1}}^{t_{k}, X_{t_{k}}^{N}}\right)-u\left(t_{k+1}, X_{t_{k+1}}\right)=u_{x}^{\prime}\left(t_{k+1}, X_{t_{k+1}}\right) \Delta_{N} X_{k+1} \\
& \quad+\int_{0}^{1}(1-\lambda)\left(\Delta_{N} X_{k+1}\right)^{*} H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}+\lambda \Delta_{N} X_{k+1}\right) \Delta_{N} X_{k+1} \mathrm{~d} \lambda
\end{aligned}
$$

Thus, using the duality relationship, one has

$$
\begin{aligned}
& \mathbb{E}_{t_{k}}\left[\left(u\left(t_{k+1}, X_{t_{k+1}}^{t_{k}, X_{t_{k}}^{N}}\right)-u\left(t_{k+1}, X_{t_{k+1}}\right)\right) \Delta W_{k}^{*}\right] \\
& \quad=\int_{t_{k}}^{t_{k+1}} R_{k}^{1}(t) \mathrm{d} t+\int_{t_{k}}^{t_{k+1}} R_{k}^{2}(t) \mathrm{d} t+\int_{0}^{1}(1-\lambda) R_{k}^{3}(\lambda) \mathrm{d} \lambda
\end{aligned}
$$

with

$$
\begin{aligned}
& R_{k}^{1}(t)=\mathbb{E}_{t_{k}}\left[\left(\Delta_{N} X_{k+1}\right)^{*} H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}\right) D_{t} X_{t_{k+1}}\right], \\
& R_{k}^{2}(t)=\mathbb{E}_{t_{k}}\left[u_{x}^{\prime}\left(t_{k+1}, X_{t_{k+1}}\right) D_{t}\left(\Delta_{N} X_{k+1}\right)\right], \\
& R_{k}^{3}(\lambda)=\mathbb{E}_{t_{k}}\left[\left(\Delta_{N} X_{k+1}\right)^{*} H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}+\lambda \Delta_{N} X_{k+1}\right) \Delta_{N} X_{k+1} \Delta W_{k}^{*}\right] .
\end{aligned}
$$

Expansion of $R_{k}^{1}(t)$. Clearly $\Delta_{N} X_{k+1}=\Delta X_{k}+U_{t_{k+1}}-U_{t_{k}}$, where $U$ is an Itô process with drift term $\alpha_{s}=b\left(s, X_{s}^{t_{k}, X_{t_{k}}^{N}}\right)-b\left(s, X_{s}\right)$ and diffusion term $\beta_{s}=\sigma\left(s, X_{s}^{t_{k}, X_{t_{k}}^{N}}\right)-\sigma\left(s, X_{s}\right)$, both being bounded. Thus, we can apply Proposition 12, letting $F=H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}\right) D_{t} X_{t_{k+1}}$. Because $u \in C_{b}^{2,4}$ and in view of (18), we get

$$
R_{k}^{1}(t)=O(h)+\left(\Delta X_{k}\right)^{*} \mathbb{E}_{t_{k}}\left[H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}\right) D_{t} X_{t_{k+1}}\right]
$$

We expand the latter factor. As $D_{t} X_{t_{k+1}}=\nabla_{x} X_{t_{k+1}}\left(\nabla_{x} X_{t}\right)^{-1} \sigma\left(t, X_{t}\right)$, we have

$$
\begin{aligned}
H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}\right) D_{t} X_{t_{k+1}}= & \left(H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}\right) \sigma\left(t, X_{t}\right)-H_{x}(u)\left(t, X_{t}\right) \sigma\left(t, X_{t}\right)\right) \\
& +\left(H_{x}(u)\left(t, X_{t}\right) \sigma\left(t, X_{t}\right)-H_{x}(u)\left(t_{k}, X_{t_{k}}\right) \sigma\left(t_{k}, X_{t_{k}}\right)\right) \\
& +\left(H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}\right)\left[\nabla_{x} X_{t_{k+1}}\left(\nabla_{x} X_{t}\right)^{-1}-I\right] \sigma\left(t, X_{t}\right)\right) \\
& +H_{x}(u)\left(t_{k}, X_{t_{k}}\right) \sigma\left(t_{k}, X_{t_{k}}\right) .
\end{aligned}
$$

The first three contributions in the r.h.s. above can be handled in the same way and we give a detailed proof only for the first one. It is enough to apply Proposition 12 with $F=\sigma\left(t, X_{t}\right)$ and $U_{s}=H_{x}(u)\left(s, X_{s}\right)$. Then, $\mathbb{E}_{t_{k}}\left[F\left(U_{t_{k+1}}-U_{t}\right)\right]$ is of order $h$ with a constant involving $b, \sigma, u$ and its derivatives up to order 4. Finally, this gives

$$
R_{k}^{1}(t)=O(h)+\left(\Delta X_{k}\right)^{*} H_{x}(u)\left(t_{k}, X_{t_{k}}\right) \sigma\left(t_{k}, X_{t_{k}}\right),
$$

uniformly in $t \in\left[t_{k}, t_{k+1}\right]$.
Expansion of $R_{k}^{2}(t)$. For $t_{k} \leq t \leq t_{k+1}$, we have

$$
\begin{aligned}
D_{t}\left(\Delta_{N} X_{k+1}\right)= & {\left[\nabla_{x} X_{t_{k+1}}^{X_{t_{k}}^{N}, t_{k}}\left(\nabla_{x} X_{t}^{X_{t_{k}}^{N}, t_{k}}\right)^{-1}-I\right] \sigma\left(t, X_{t}^{X_{k}^{N}, t_{k}}\right) } \\
& -\left[\nabla_{x} X_{t_{k+1}}\left(\nabla_{x} X_{t}\right)^{-1}-I\right] \sigma\left(t, X_{t}\right)-\left(\sigma\left(t, X_{t}\right)-\sigma\left(t_{k}, X_{t_{k}}\right)\right) \\
& +\sigma\left(t, X_{t}^{X_{t_{k}}^{N}, t_{k}}\right)-\sigma\left(t_{k}, X_{t_{k}}^{N}\right)+\sigma\left(t_{k}, X_{t_{k}}^{N}\right)-\sigma\left(t_{k}, X_{t_{k}}\right) .
\end{aligned}
$$

As before, apply Proposition 12 to each of these terms but the last one, with $F=u_{x}^{\prime}\left(t_{k+1}, X_{t_{k+1}}\right)$, using $u, b, \sigma \in C_{b}^{2,4}$ and (18). It follows that $R_{k}^{2}(t)=O(h)+\mathbb{E}_{t_{k}}\left[u_{x}^{\prime}\left(t_{k+1}, X_{t_{k+1}}\right)\right]\left(\sigma\left(t_{k}, X_{t_{k}}^{N}\right)-\right.$ $\left.\sigma\left(t_{k}, X_{t_{k}}\right)\right)$. An application of Itô's formula yields

$$
\begin{aligned}
R_{k}^{2}(t) & =O(h)+\sum_{i=1}^{d} u_{x_{i}}^{\prime}\left(t_{k}, X_{t_{k}}\right)\left(\sigma^{i}\left(t_{k}, X_{t_{k}}^{N}\right)-\sigma^{i}\left(t_{k}, X_{t_{k}}\right)\right) \\
& =O\left(h+\left|\Delta X_{k}\right|^{2}\right)+\sum_{i=1}^{d} u_{x_{i}}^{\prime} \nabla_{x}\left(\left[\sigma^{i}\right]^{*}\right)\left(t_{k}, X_{t_{k}}\right) \Delta X_{k},
\end{aligned}
$$

uniformly in $t \in\left[t_{k}, t_{k+1}\right]$. Finally, simple matrix computations lead to

$$
R_{k}^{1}(t)+R_{k}^{2}(t)=O\left(h+\left|\Delta X_{k}\right|^{2}\right)+\left[\nabla_{x}\left(\nabla_{x} u \sigma\right)^{*}\left(t_{k}, X_{t_{k}}\right) \Delta X_{k}\right]^{*} .
$$

Upper bound for $R_{k}^{3}(\lambda)$. To complete the proof of Lemma 18 , note that it remains to justify that $R_{k}^{3}(\lambda)=h O\left(h+\left|\Delta X_{k}\right|^{2}\right)$ uniformly in $\lambda$. The duality formula gives

$$
R_{k}^{3}(\lambda)=\mathbb{E}_{t_{k}}\left[\int_{t_{k}}^{t_{k+1}} D_{t}\left[\left(\Delta_{N} X_{k+1}\right)^{*} H_{x}(u)\left(t_{k+1}, X_{t_{k+1}}+\lambda \Delta_{N} X_{k+1}\right) \Delta_{N} X_{k+1}\right] \mathrm{d} t\right]
$$

The term in the integral equals $\sum_{i, j=1}^{d}\left[2 D_{t}\left(\Delta_{N} X_{k+1, i}\right) \Delta_{N} X_{k+1, j} \partial_{x_{i}, x_{j}}^{2} u\left(t_{k+1}, X_{t_{k+1}}+\right.\right.$ $\left.\left.\lambda \Delta_{N} X_{k+1}\right)+\Delta_{N} X_{k+1, i} \Delta_{N} X_{k+1, j} D_{t}\left(\partial_{x_{i}, x_{j}}^{2} u\left(t_{k+1}, X_{t_{k+1}}+\lambda \Delta_{N} X_{k+1}\right)\right)\right]$. Thanks to (18) and (19) and successive applications of Proposition 12, we finally prove our assertion. We omit further details.

### 5.2.2. Proof of Lemma 19

As for Lemma 16, we only do the proof for $t_{k}=0$, i.e. we have to show $\mid \mathbb{E}_{t_{k}}\left[\left(u^{N}\left(t_{1}, X_{t_{1}}^{N, 0, x}\right)-\right.\right.$ $\left.\left.u\left(t_{1}, X_{t_{1}}^{0, x}\right)\right) \Delta W_{0}^{*}\right] \mid \leq K(T, x) h^{2}$. We have $\mathbb{E}\left[\left(u^{N}\left(t_{1}, X_{t_{1}}^{N, 0, x}\right)-u\left(t_{1}, X_{t_{1}}^{0, x}\right)\right) \Delta W_{0}^{*}\right]=$
$\mathbb{E}\left[\Delta Y_{1} \Delta W_{0}^{*}\right]$. By using (21), we come up with

$$
\begin{aligned}
\mathbb{E}\left[\Delta Y_{1} \Delta W_{0}^{*}\right]= & \mathbb{E}\left[\xi_{1} \cdots \xi_{N-1} \Delta Y_{N} \Delta W_{0}^{*}\right] \\
& +\mathbb{E}\left[h \sum_{i=1}^{N-1}\left(f_{x}^{\prime}\left(\theta_{t_{i}}\right) \Delta X_{i}+\tilde{\chi}_{i}\right) \xi_{1} \cdots \xi_{i-1} \Delta W_{0}^{*}\right]
\end{aligned}
$$

where $\tilde{\chi}_{i}=\mathbb{E}_{t_{i}}\left(\chi_{i}\right)\left(\xi_{i}\right.$ and $\chi_{i}$ are defined in (22) and (23)). In the following $\tilde{\eta}_{i}$ denotes $\xi_{1} \cdots \xi_{i-1}$ and $\tilde{\eta_{1}}=1$. We easily prove that $\left(\tilde{\eta}_{i}\right)_{1 \leq i \leq N}$ has analogous properties to $\left(\eta_{i}\right)_{0 \leq i \leq N}$. Estimates (29) and (30) remain valid for $\tilde{\eta}$ and under Hypothesis 3, the estimate (29) becomes
$\tilde{\eta_{k}}$ satisfies $R_{3}$ uniformly in $k$.
Step 1: Proof of $\mathbb{E}\left[\xi_{1} \cdots \xi_{N-1} \Delta Y_{N} \Delta W_{0}^{*}\right]=\mathbb{E}\left[\tilde{\eta_{N}} \Delta Y_{N} \Delta W_{0}^{*}\right]=O\left(h^{2}\right)$. As before, we use the duality formula:

$$
\mathbb{E}\left[\tilde{\eta_{N}} \Delta Y_{N} \Delta W_{0}^{*}\right]=\mathbb{E} \int_{0}^{t_{1}}\left(D_{t}\left[\tilde{\eta_{N}}\right] \Delta Y_{N}+\tilde{\eta_{N}} D_{t}\left[\Delta Y_{N}\right]\right) \mathrm{d} t
$$

Since $\tilde{\eta_{N}}$ satisfies (52), we proceed as in Step 4 of Lemma 16 and we get $\mathbb{E}\left(D_{t}\left[\tilde{\eta_{N}}\right] \Delta Y_{N}\right)=$ $O(h)$. Furthermore, we have

$$
D_{t}\left[\Delta Y_{N}\right]=\left(\Phi^{\prime}\left(X_{T}^{N}\right)-\Phi^{\prime}\left(X_{T}\right)\right) D_{t} X_{T}^{N}+\Phi^{\prime}\left(X_{T}\right)\left(D_{t} X_{T}^{N}-D_{t} X_{T}\right)
$$

On the one hand, analogously to previous computations, we establish $\mathbb{E}\left(\tilde{\eta} \sim\left(\Phi^{\prime}\left(X_{T}^{N}\right)-\right.\right.$ $\left.\left.\Phi^{\prime}\left(X_{T}\right)\right) D_{t} X_{T}^{N}\right)=O(h)$.

On the other hand, we prove $\mathbb{E}\left(\tilde{\eta_{N}} \Phi^{\prime}\left(X_{T}\right)\left(D_{t} X_{T}^{N}-D_{t} X_{T}\right)\right)=O(h)$. Thanks to (18) and (29), $\tilde{\eta_{N}} \Phi^{\prime}\left(X_{T}\right)$ satisfies condition $R_{3}$. Then, by applying (41), we get the result.

Step 2: Proof of $\mathbb{E}\left[h \sum_{i=1}^{N-1} f_{x}^{\prime}\left(\theta_{t_{i}}\right) \Delta X_{i} \xi_{1} \cdots \xi_{i-1} \Delta W_{0}^{*}\right]=O\left(h^{2}\right)$. This is a similar proof to the one done at Step 1, with $\Phi(x)=x$.
Step 3: Proof of $\mathbb{E}\left[h \sum_{i=1}^{N-1} \tilde{\chi}_{i} \tilde{\eta}_{i} \Delta W_{0}^{*}\right]=O\left(h^{2}\right)$. A careful inspection of the definition of $G_{0}, G_{y}$ and $G_{z}$ appearing in (23) shows that under Hypothesis 3 , these functions are continuously differentiable w.r.t. the variable $x$ (with a bounded derivative). Hence, if we write $\chi_{i}=\chi_{i}^{1}+$ $\int_{0}^{1}(1-\lambda) \chi_{i}^{2}(\lambda) \mathrm{d} \lambda$ with (see (23))

$$
\begin{aligned}
& \chi_{i}^{1}=\int_{t_{i}}^{t_{i+1}}\left(G_{0}\left(s, X_{s}\right)+f_{y}^{\prime}\left(\theta_{t_{i}}\right) G_{y}\left(s, X_{s}\right)+f_{z}^{\prime}\left(\theta_{t_{i}}\right) G_{z}\left(s, X_{s}\right)\right) \mathrm{d} s, \\
& \chi_{i}^{2}(\lambda)= \Delta X_{i}^{*} f_{x x}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta X_{i}+f_{y y}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\left(Y_{t_{i+1}}^{N}-Y_{t_{i}}\right)^{2}+\Delta Z_{i} f_{z z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta Z_{i}^{*} \\
&+2 \Delta X_{i}^{*} f_{x y}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\left(Y_{t_{i+1}}^{N}-Y_{t_{i}}\right)+2 \Delta X_{i}^{*} f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta Z_{i}^{*} \\
&+2\left(Y_{t_{i+1}}^{N}-Y_{t_{i}}\right) f_{y z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta Z_{i}^{*},
\end{aligned}
$$

we note that the random variable $\chi_{i}$ is in $\mathbb{D}^{1, \infty}$. Thus and because $\tilde{\chi}_{i}=\mathbb{E}_{t_{i}}\left(\chi_{i}\right)$, one has $\mathbb{E}\left[\tilde{\chi}_{i} \tilde{\eta}_{i} \Delta W_{0}^{*}\right]=\mathbb{E}\left[\chi_{i} \tilde{\eta}_{i} \Delta W_{0}^{*}\right]=\mathbb{E}\left[\int_{0}^{t_{1}}\left(\chi_{i} D_{t} \tilde{\eta}_{i}+\tilde{\eta}_{i} D_{t} \chi_{i}\right) \mathrm{d} t\right]$.

The upper bound $\tilde{\chi}_{i}=\mathbb{E}_{t_{i}}\left(\chi_{i}\right)=O_{i}(h)+O\left(\left|\Delta X_{i}\right|^{2}+\left|\Delta Z_{i}\right|^{2}\right)$ (see (27)) is sufficient to show $\mathbb{E}\left[\sum_{i=1}^{N-1} \chi_{i} D_{t} \tilde{\eta}_{i}\right]=O(1)$ uniformly in $t$ (follow the arguments of the conclusion of the proof of Lemma 16 and use (30) with $\tilde{\eta}$ ).

Now, it remains to establish $\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} D_{t} \chi_{i}\right]=O(1)$. On the one hand, clearly $\mathbb{E}_{t_{i}}\left[D_{t} \chi_{i}^{1}\right]=$ $O_{i}(h)$ and we conclude $\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} D_{t} \chi_{i}^{1}\right]=O(1)$ uniformly in $t$. On the other hand, $\chi_{i}^{2}$ can be decomposed into several contributions, which can be analyzed with the same arguments. Let us
detail how to handle one of them, for instance $\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} D_{t}\left(\Delta X_{i}^{*} f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta Z_{i}^{*}\right)\right]$ which has to be a $O(1)$. We do the proof for $d=q=1$. Write $D_{t}\left(\Delta X_{i} f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta Z_{i}\right)=\Delta X_{i} f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) D_{t}\left(\Delta Z_{i}\right)+$ $D_{t}\left(\Delta X_{i}\right) f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta Z_{i}+\Delta X_{i} D_{t}\left(f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\right) \Delta Z_{i}$. As $f^{\prime \prime}$ is bounded, we have

$$
\begin{aligned}
\left|\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} \Delta X_{i} f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) D_{t}\left(\Delta Z_{i}\right)\right]\right| \leq & \mathbb{E}\left[\sum_{i=1}^{N-1}\left|\tilde{\eta}_{i}\right|\left|\Delta X_{i}\right|\left|f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\right|\left|D_{t}\left(\Delta Z_{i}\right)\right|\right] \\
\leq & C\left(\mathbb{E}\left(\sum_{i=1}^{N-1}\left(\left|\tilde{\eta}_{i}\right|^{2}\left|\Delta X_{i}\right|^{2}\right)\right)\right)^{\frac{1}{2}} \\
& \times\left(\mathbb{E}\left(\sum_{i=1}^{N-1}\left|D_{t}\left(\Delta Z_{i}\right)\right|^{2}\right)\right)^{\frac{1}{2}}
\end{aligned}
$$

Thanks to Proposition 17, (52) and Proposition 5, we get that $\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} \Delta X_{i} f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\left(D_{t} \Delta Z_{i}\right)\right]$ $=O(1)$. Analogously, using (52), (17) and (41), we obtain $\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i}\left(D_{t} \Delta X_{i}\right) f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \Delta Z_{i}\right]=$ $O(1)$. It remains to demonstrate that $\left|\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} \Delta X_{i} D_{t}\left(f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\right) \Delta Z_{i}\right]\right|=O(1)$. We have

$$
\begin{aligned}
D_{t}\left(f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\right)= & f_{x z x}^{\prime \prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\left(\lambda D_{t} X_{t_{i}}^{N}+(1-\lambda) D_{t} X_{t_{i}}\right)+f_{x z y}^{\prime \prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\left(\lambda D_{t} Y_{t_{i+1}}^{N}+(1-\lambda) D_{t} Y_{t_{i}}\right) \\
& +f_{x z z}^{\prime \prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\left(\lambda D_{t} Z_{t_{i}}^{N}+(1-\lambda) D_{t} Z_{t_{i}}\right) .
\end{aligned}
$$

The most difficult term to bound among these three ones is the one which contains $D_{t} Z_{t_{i}}^{N}$. If we write $\lambda D_{t} Z_{t_{i}}^{N}+(1-\lambda) D_{t} Z_{t_{i}}=\lambda D_{t}\left(\Delta Z_{i}\right)+D_{t} Z_{t_{i}}$, we obtain

$$
\begin{aligned}
\mid \mathbb{E} & {\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} \Delta X_{i} f_{x z z}^{\prime \prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \lambda D_{t}\left(\Delta Z_{i}\right) \Delta Z_{i}\right] \mid } \\
\leq & C\left(\mathbb{E}\left(\sum_{i=1}^{N-1}\left|D_{t}\left(\Delta Z_{i}\right)\right|^{2}\right)\right)^{\frac{1}{2}}\left(\mathbb{E}\left(\sum_{i=1}^{N-1}\left(\left|\Delta X_{i}\right|^{2}\left|\tilde{\eta}_{i}\right|^{2}\left|\Delta Z_{i}\right|^{2}\right)\right)\right)^{\frac{1}{2}} \\
\leq & C\left(\mathbb{E}\left(\sum_{i=1}^{N-1}\left|D_{t}\left(\Delta Z_{i}\right)\right|^{2}\right)\right)^{\frac{1}{2}}\left(\mathbb{E}\left(\sum_{i=1}^{N-1}\left|\Delta Z_{i}\right|^{2}\right)^{2}\right)^{\frac{1}{4}} \\
& \times\left(\mathbb{E}\left(\max _{0 \leq i \leq N}\left|\tilde{\eta}_{i}\right|^{4} \max _{0 \leq i \leq N}\left|\Delta X_{i}\right|^{4}\right)\right)^{\frac{1}{4}}
\end{aligned}
$$

Applying Proposition 17, (17), Proposition 5 and (30) (with $\tilde{\eta}$ ) lead to $\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} \Delta X_{i} f_{x z}^{\prime \prime \prime}\left(\theta_{t_{i}}^{\lambda}\right) \lambda\right.$ $\left.D_{t}\left(\Delta Z_{i}\right) \Delta Z_{i}\right]=O(1)$. Proposition 5, (17), (38)-(40) and (52) enable us to prove that the other terms of $\mathbb{E}\left[\sum_{i=1}^{N-1} \tilde{\eta}_{i} \Delta X_{i} D_{t}\left(f_{x z}^{\prime \prime}\left(\theta_{t_{i}}^{\lambda}\right)\right) \Delta Z_{i}\right]$ are $O(1)$.

## References

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