

2-Linked Graphs

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1. INTRODUCTION

Let $Z = (x_1, x_2, \dots, x_k, y_1, y_2, \dots, y_k)$ be an ordered set of distinct vertices of a graph G . A Z -linkage of G is a set of k pairwise disjoint paths P_1, P_2, \dots, P_k such that P_i connects x_i with y_i for $i = 1, 2, \dots, k$. We say that G is k -linked if G has at least $2k$ vertices and, for any ordered set Z of $2k$ vertices, G has a Z -linkage.

A necessary condition for G to be k -linked is that G is $(2k - 1)$ -connected. This condition is not sufficient unless $k = 1$. Larman and Mani [8] and Jung [7] proved independently that there exists a (smallest) integer $f(k)$ such that every $f(k)$ -connected graph is k -linked. The proof is based on a result of Mader [11] on subdivisions of large complete graphs.

A complete characterization of k -linked graphs is not known. A partial result for $k = 2$ was obtained by Watkins [22] and improved by Jung [7] who demonstrated that a 4-connected graph is 2-linked unless it is a non-maximal planar graph. In such a graph we can select four vertices x_1, x_2, y_1, y_2 along a facial cycle of length at least four and it follows easily that the graph has no (x_1, x_2, y_1, y_2) -linkage. In particular, $f(2) = 6$ while $f(3)$ is unknown.

In this paper we describe completely when a graph does not contain an (x_1, x_2, y_1, y_2) -linkage. This result was obtained independently by Seymour [16] but stated without proof in [16].

As applications of this characterization we obtain the result of Jung [7] on 2-linked graphs and, as pointed out in [16, 20], the characterization also yields a polynomially bounded algorithm for deciding whether or not a graph has an (x_1, x_2, y_1, y_2) -linkage and for producing such a linkage if it exists. Such an algorithm has also been obtained by Shiloach [17]. In contrast to this, Fortune, Hopcroft and Wyllie [4] have shown that the analogous 2-linkage problem for directed graphs is NP-complete.

If $Z = (x_1, x_2, \dots, x_k, y_1, y_2, \dots, y_k)$ is an ordered set of $2k$ (not necessarily distinct) vertices of a multigraph G , then a *weak Z -linkage* in G is a set of k pairwise edge-disjoint paths P_1, P_2, \dots, P_k in G such that P_i connects x_i and y_i for $i = 1, 2, \dots, k$. We say that G is *weakly k -linked* if G has at least two vertices and, for each ordered set Z of $2k$ vertices, G has a weak Z -linkage. The problem of finding weak Z -linkages may be regarded as the integer k -commodity flow problem for undirected graphs. The non-integer 2-commodity flow problem was treated by Hu [6], and a variant of the integer k -commodity flow problem for undirected graphs was shown to be NP-complete by Even, Itai and Shamir [3]. From the characterization of non-2-linked graphs we get the characterization of non-weakly-2-linked multigraphs found independently by Seymour [16] and the author [20].

The concept of k -linkage and weak k -linkage can be extended to directed graphs in the obvious way. The problem of finding an (x_1, x_2, y_1, y_2) -linkage or a weak (x_1, x_2, y_1, y_2) -linkage in a directed multigraph is NP-complete by the above-mentioned result of Fortune *et al.* [4] and the problem of characterizing k -linked directed graphs is no easier than that of characterizing k -linked undirected graphs. However, weakly k -linked directed multigraphs have a simpler characterization than weakly k -linked undirected multigraphs at least when $k = 2$. An obvious necessary condition for a directed multigraph to be weakly

k -linked is that it is k -edge-connected. This condition is also sufficient. For if $Z = (x_1, x_2, \dots, x_k, y_1, \dots, y_k)$ is an ordered set of $2k$ vertices in a k -edge-connected directed multigraph D , then we add a new vertex x_0 and k edges going from x_0 to x_1, x_2, \dots, x_k , respectively. By a result of Edmonds [2] (for a short proof, see [10]), the resulting directed multigraph has k edge-disjoint branchings from x_0 and clearly, the union of these branchings contains a weak Z -linkage.

2-Linkages in undirected graphs can be applied to electrical networks. Consider a 2-connected electrical network such that an edge x_1x_2 represents a voltage generator and all other edges represent resistances. Let one of these edges be y_1y_2 and we now consider the problem of adjusting the resistances such that the current through y_1y_2 becomes zero. Frank Nielsen (private communication) has pointed out that this is possible, by Kirchoff's rule (see e.g. [15]), if and only if the network contains an (x_1, x_2, y_1, y_2) -linkage and an (x_1, x_2, y_2, y_1) -linkage. Note that Menger's theorem guarantees the existence of at least one of these linkages.

We also consider k -linked infinite graphs. We characterize completely the infinite maximal non-2-linked graphs. In particular, every 4-connected non-planar graph is 2-linked. As pointed out by Mader [12], there are infinite non-2-linked planar graphs of arbitrarily high (finite) connectivity. However, we apply a result of Halin [5] to prove that every uncountable $2k$ -connected graph is k -linked. This result is best possible. Furthermore, we conjecture that, for each $k \geq 2$, every finite $(2k + 2)$ -connected graph is k -linked. If true this is best possible. We also conjecture that, for each odd integer k , $k \geq 3$, a finite or infinite multigraph is weakly k -linked if and only if it is k -edge-connected, and that, for each integer $k \geq 2$, an infinite directed multigraph is weakly k -linked if and only if it is k -edge-connected.

2. TERMINOLOGY

We use standard terminology. The *vertex* set of a graph G is denoted $V(G)$ and the *edge* joining two vertices x and y is denoted xy . If $A \subseteq V(G)$, then $G - A$ is the subgraph obtained from G by *deleting* A and $G(A)$ is the subgraph of G *induced* by A , i.e. $G(A) = G - [V(G) \setminus A]$.

If G is a connected graph and R, S, T are vertex sets, we say that R *separates* S from T if each of $S \setminus R$ and $T \setminus R$ are non-empty, and every $S - T$ path of G (i.e. a path with ends in S and T , respectively) contains a vertex of R .

A *plane* graph (finite or infinite) is a graph drawn in the plane such that any two edges have at most an end in common.

A *planar* graph is an abstract graph isomorphic to a plane graph.

A *facial cycle* of a plane graph is a cycle whose interior or exterior does not intersect the graph, and a facial cycle in a planar graph is a cycle which is facial in some plane representation of the graph. If the graph is 3-connected, a facial cycle is facial in any plane representation of the graph (see [19]).

Only in Sections 4 and 5 the graphs under consideration may be infinite.

3. MAXIMAL NON-2-LINKED GRAPHS

In order to characterize the graphs which contain no (x_1, x_2, y_1, y_2) -linkage and which are edge-maximal under this restriction we consider a plane graph G_0 such that the unbounded face is bounded by a 4-cycle $S_0: x_1x_2y_1y_2x_1$ and such that every other face is bounded by a 3-cycle. Suppose in addition that G_0 has no separating 3-cycle (i.e. a 3-cycle which is not a facial cycle). For each 3-cycle S of G_0 we add K^S , a possible empty complete graph disjoint from G_0 , and we join all vertices of K^S to all vertices of S . The resulting

graph G is called an (x_1, x_2, y_1, y_2) -web with frame S_0 and rib G_0 . If G_0 has more than four vertices, S_0 and the rib G_0 are uniquely determined, and it follows from well-known results on planar graphs that G_0 (and hence also G) is 3-connected and that any separating set of three vertices of G_0 is of the form $\{x_1, y_1, z\}$ or $\{x_2, y_2, z\}$. A simple argument shows that G has no (x_1, x_2, y_1, y_2) -linkage.

THEOREM 1. *Let x_1, x_2, y_1, y_2 be vertices of a graph G . If G has no (x_1, x_2, y_1, y_2) -linkage and the addition of any edge to G results in a graph containing an (x_1, x_2, y_1, y_2) -linkage, then G is an (x_1, x_2, y_1, y_2) -web. Conversely, any (x_1, x_2, y_1, y_2) -web is maximal with respect to the property of not containing an (x_1, x_2, y_1, y_2) -linkage.*

PROOF. We prove the first part of the theorem by induction on the number of vertices of G . If G has only four vertices, the statement is trivial so we proceed to the induction step. It is easy to see that G contains the cycle $S_0: x_1x_2y_1y_2x_1$. Also, G is 2-connected, for if x is a cutvertex of G and y, z are neighbours of x belonging to distinct components of $G - x$, then clearly the addition of yz to G does not create an (x_1, x_2, y_1, y_2) -linkage.

If one of the sets $\{x_1, y_1\}, \{x_2, y_2\}$ is a separating set of G , then it is easy to see that G is an (x_1, x_2, y_1, y_2) -web with rib $S_0 \cup \{x_1y_1\}$ or $S_0 \cup \{x_2y_2\}$ so assume none of these sets separate G . We can then prove that G is 3-connected. For suppose $\{x, y\}$ separates G and let H be a component of $G - \{x, y\}$ not intersecting S_0 . The maximality property of G easily implies that the edge xy is present and that $G - V(H)$ is also maximal with respect to the property of not containing an (x_1, x_2, y_1, y_2) -linkage. By the induction hypothesis, $G - V(H)$ is an (x_1, x_2, y_1, y_2) -web with rib, say, G_0 . Then G_0 contains a 3-cycle S such that every $V(H) - V(S_0)$ path intersects S . But then it is easy to see that the addition of an edge from H to S does not create an (x_1, x_2, y_1, y_2) -linkage, a contradiction to the maximality property of G .

So we can assume that G is 3-connected.

We next consider the case where G contains a set A of three vertices such that $G - A$ contains a component H not intersecting S_0 . Then the maximality of G easily implies that $G(A)$ is complete, that H is complete and that all vertices of H are joined to all vertices of A . Moreover, it is easy to see that $G - V(H)$ is maximal with respect to the property of not containing an (x_1, x_2, y_1, y_2) -linkage. So by the induction hypothesis, $G - V(H)$ is an (x_1, x_2, y_1, y_2) -web with rib, say, G_0 . Let S be the unique 3-cycle of G_0 such that every $V(H) - V(S_0)$ path intersects S . The maximality of G implies that every vertex of H is joined to every vertex of S . So $A = V(S)$ and it follows easily that G is an (x_1, x_2, y_1, y_2) -web.

So we can assume that any separating set of three vertices of G (if any) is of the form $\{x_1, y_1, z\}$ or $\{x_2, y_2, z\}$ where $z \notin V(S_0)$. We now consider the situation where G contains a separating set A with four vertices such that a component H of $G - A$ does not intersect S_0 , and H has at least two vertices. By Menger's theorem, G contains four disjoint $V(S_0) - A$ paths P_1, P_2, P_3, P_4 . Suppose w.l.g. that these paths form an $(x_1, x_2, y_1, y_2, x'_1, x'_2, y'_1, y'_2)$ -linkage. We shall prove that G contains the cycle $S'_0: x'_1x'_2y'_1y'_2x'_1$.

Let H' be the subgraph of G induced by $A \cup V(H)$. Since H has at least two vertices, H' has no vertex z which separates $\{x'_1, x'_2\}$ from $\{y'_1, y'_2\}$ for if this were the case, then either $\{x'_1, x'_2, z\}$ or $\{y'_1, y'_2, z\}$ would separate G , contrary to the assumption of the previous paragraph. So by Menger's theorem, H' contains paths P_5, P_6 forming an (x'_1, x'_2, y'_1, y'_2) -linkage or an (x'_1, x'_2, y'_2, y'_1) -linkage.

Since $\bigcup_{i=1}^6 P_i$ does not form an (x_1, x_2, y_1, y_2) -linkage, P_5, P_6 must be an (x'_1, x'_2, y'_2, y'_1) -linkage. Now it is not difficult to see that the edge $e = x'_2y'_1$ is present in G . For otherwise we add this edge to G and obtain an (x_1, x_2, y_1, y_2) -linkage consisting of the two paths

P_7, P_8 where P_7 , say, contains e . But then we obtain an (x_1, x_2, y_1, y_2) -linkage of G by replacing e by P_6 and, if necessary, a segment of P_8 by P_5 . This contradiction shows that x_2y_1' and, by symmetry, x_1y_2' are present in G . By considering the sets $\{x_2', y_1'\}$ and $\{x_1', y_2'\}$ instead of $\{x_1', x_2'\}$ and $\{y_1', y_2'\}$, respectively, we conclude as above that also $x_1'x_2'$ and $y_1'y_2'$ are present in G . Since H' has no (x_1', x_2', y_1', y_2') -linkage none of the edges $x_1'y_1'$ and $x_2'y_2'$ are present in G . Hence $G(A) = S_0'$.

Let G' denote the graph obtained by contracting H into a vertex z_0 (which is then adjacent to precisely the vertices of S_0'). It is easy to see that G' has no (x_1, x_2, y_1, y_2) -linkage so by the induction hypothesis, G' is contained in an (x_1, x_2, y_1, y_2) -web G'' with rib G_0' say. For each vertex $u \in V(S_0') \cup \{z_0\}$, G' contains four $u - V(S_0)$ paths having only u in common pair by pair, so $A \cup \{z_0\} \subseteq V(G_0')$. Since two consecutive vertices of S_0' do not separate G , each of the four 3-cycles of G_0' containing z_0 are facial cycles of G_0' and each complete graph of G'' attached to these 3-cycles is empty. Also, by the connectivity properties of G , each complete graph of G' attached to any other 3-cycle of G_0' is empty. So it follows that $G - V(H)$ has a plane representation such that S_0 and S_0' are facial cycles. By the maximality of G all other facial cycles are 3-cycles.

Now $H' = G(V(H) \cup A)$ has no (x_1', x_2', y_1', y_2') -linkage and is therefore contained in an (x_1', x_2', y_1', y_2') -web H'' . By the connectivity property of G it follows that H'' has no separating 3-cycle so H'' is planar. It now follows that G is planar and that S_0 is a facial cycle. So we have proved that G is an (x_1, x_2, y_1, y_2) -web in the case where G has a four-vertex separating set A such that a component H of $G - A$ has at least two vertices and is disjoint from S_0 .

We can therefore assume that whenever A is a set of at most four vertices separating G such that a component H of $G - A$ does not intersect S_0 , then $|A| = 4$ and H consists of a vertex of degree 4 in G , and $G - A$ does not contain another component H' disjoint from S_0 . We consider any edge e of G not joining two vertices of $V(S_0)$ and we let G' denote the graph obtained from G by contracting e . Then G' has no (x_1, x_2, y_1, y_2) -linkage, so, by the induction hypothesis, G' is contained in an (x_1, x_2, y_1, y_2) -web G'' . If K^S has more than one vertex for some facial cycle S of the rib of G'' , then the three vertices of S separate this K^S from $V(S_0)$. But then G has a set of three or four vertices which separates more than one vertex from S_0 . However, this is a contradiction to the initial assumption of this paragraph. So each K^S has at most one vertex and hence G'' is planar.

We have shown that the contraction of any edge e not in S_0 results in a planar graph. We shall show that this implies G to be planar. For suppose G is non-planar. By Kuratowski's theorem, G contains a subgraph H which is a subdivision of K_5 or $K_{3,3}$. Now $V(S_0) \subseteq V(H)$. For if x_1 , say, is not in H , then the contraction of any edge incident with x_1 and not in S_0 results in a non-planar graph (and such an edge exists since G is 3-connected). Also, if x is a vertex of degree 2 in H , then S_0 contains the two edges of H incident with x because the contraction of any such edge results in a non-planar graph. This implies that G is obtained from K_5 or $K_{3,3}$ by possibly inserting one or two vertices of degree 2 and then adding some edges such that the resulting graph is 3-connected. It is easy to see that such a graph is 2-linked.

This contradiction proves that G is planar. In order to prove that S_0 is a facial cycle it is sufficient to prove that $G - V(S_0)$ is connected. But if this is not the case, we select vertices z_1, z_2 in distinct components and consider for $i = 1, 2$ four $z_i - V(S_0)$ paths having only z_i in common pair by pair. This easily gives us an (x_1, x_2, y_1, y_2) -linkage, a contradiction.

So G is planar and S_0 is a facial cycle. By the maximality of G , G is an (x_1, x_2, y_1, y_2) -web and the proof of the first part of the theorem is complete.

In order to prove the second part we consider an (x_1, x_2, y_1, y_2) -web G with rib G_0 . We shall prove that $G \cup e$ has an (x_1, x_2, y_1, y_2) -linkage for any edge e not in G . Since G_0 has no separating 3-cycle it contains no K_4 and hence $G \cup \{e\}$ contains a path of length one,

two or three having only its ends x and y in common with G_0 such that x and y are non-adjacent in G . Now $G_0 \cup \{xy\}$ is not a spanning subgraph of an (x_1, x_2, y_1, y_2) -web and has therefore, by the first part of Theorem 1, an (x_1, x_2, y_1, y_2) -linkage. Then G also has such a linkage and the proof is complete.

COROLLARY 1 (JUNG [7]). *Let G be a 4-connected graph containing vertices x_1, x_2, y_1, y_2 . Then G has an (x_1, x_2, y_1, y_2) -linkage unless G is planar and contains a facial cycle containing x_1, x_2, y_1, y_2 in that cyclic order.*

It is possible to modify the proof of Theorem 1 such that Kuratowski's theorem is not used. It seems however, that this is not worth the effort since a very short proof of Kuratowski's theorem is presented in [19]. Also, Theorem 1 has a short proof using Jung's result [7].

As pointed out in [16, 20] we can derive the following result on edge-disjoint paths from Theorem 1 using the line graph operation.

THEOREM 2 (SEYMOUR [16], THOMASSEN [20]). *Let G be a 2-connected multigraph with vertices x_1, x_2, y_1, y_2 . Then G contains two edge-disjoint paths connecting x_1 with y_1 and x_2 with y_2 , respectively, unless G is contractible to a 4-cycle or to a graph G' (such that x_1, x_2, y_1, y_2 are contracted into x'_1, x'_2, y'_1, y'_2 , respectively) which is obtained from a 2-connected planar cubic graph by selecting a facial cycle and inserting the vertices x'_1, x'_2, y'_1, y'_2 in that cyclic order on edges of that cycle.*

Conversely, if G has this property, then it does not contain two edge-disjoint paths which connect x_1 with y_1 and x_2 with y_2 , respectively.

Alternative proofs of Theorem 2 are given in [16, 20].

Let $g(k)$ denote the smallest function such that every $g(k)$ -edge-connected multigraph is weakly k -linked. It follows easily from Menger's theorem that $g(k) \leq 2k$. Results containing this as a corollary can also be derived from the fact that every k -edge-connected directed multigraph is k -linked combined with Nash-Williams' result [13] that every $2k$ -edge-connected multigraph has a k -edge-connected orientation, and from the result of Edmonds [2], Nash-Williams [14] and Tutte [22] which implies that every $2k$ -edge-connected multigraph has k edge-disjoint spanning trees. From Theorem 2 it follows that $g(2) = 3$.

We offer the following conjecture.

CONJECTURE 1. For each odd integer $k \geq 3$, $g(k) = k$ and, for each even integer $k \geq 2$, $g(k) = k + 1$.

We have already observed that $g(k) \geq k$. To see that $g(k) > k$ when k is even, we consider the multigraph G obtained from a cycle $x_1x_2 \cdots x_k y_1 y_2 \cdots y_k x_1$ of length $2k$ by replacing each edge by a multiple edge consisting of $\frac{1}{2}k$ edges. Then G has no weak $(x_1, x_2, \dots, x_k, y_1, \dots, y_k)$ -linkage. For such a linkage would have k^2 edges and hence the linkage would be a decomposition of G into paths. But a simple parity argument shows that such a decomposition is impossible.

If a graph G is not k -linked and we add two new vertices and join them to all vertices of G , then the resulting graph is not $(k + 1)$ -linked and its connectivity exceeds the connectivity of G by two. By Theorem 1, $f(2) = 6$ and, thus, $f(k) \geq 2k + 2$ for each $k \geq 2$.

CONJECTURE 2. For each $k \geq 2$, $f(k) = 2k + 2$.

This conjecture is also of interest in connection with the problem of finding cycles through specified edges [9, 18, 23].

4. 2-LINKAGES IN INFINITE GRAPHS

In the following two sections the graphs are allowed to be infinite. If G is a graph containing vertices x_1, x_2, y_1, y_2 such that G has no (x_1, x_2, y_1, y_2) -linkage, then it is an easy consequence of Zorn's Lemma that G is a spanning subgraph of an edge-maximal graph containing no (x_1, x_2, y_1, y_2) -linkage. The purpose of this section is to characterize all such edge-maximal graphs.

We first extend Jung's result [7] to infinite graphs.

LEMMA 1. *Let G be a (possibly infinite) graph G containing a 4-cycle $S_0 : x_1x_2y_1y_2x_1$. Suppose further that G contains a subgraph H , which is a subdivision of K_5 or $K_{3,3}$, such that for every vertex z of H which has degree greater than 2 in H there are in G four $z - V(S_0)$ paths having only z in common pair by pair. Then G contains an (x_1, x_2, y_1, y_2) -linkage.*

PROOF. It is sufficient to prove the lemma for the finite subgraph G' of G consisting of S_0, H and the 20 or 24 $z - V(S_0)$ paths described in the lemma. If G' has no (x_1, x_2, y_1, y_2) -linkage, then G' is contained in an (x_1, x_2, y_1, y_2) -web G'' with rib G_0 , say. Every vertex z of H which has degree greater than 2 in H must be contained in G_0 because of the four $z - V(S_0)$ paths. But then it is easy to see that the planar graph G_0 contains a subdivision of K_5 or $K_{3,3}$, a contradiction.

We shall need a more general definition of a web. Let G_0 be a finite or countably infinite graph containing a 4-cycle $S_0 : x_1x_2y_1y_2x_1$ such that the following hold:

- (i) G_0 is planar and S_0 is a facial cycle,
- (ii) the addition to G_0 of any edge distinct from x_1y_1 and x_2y_2 results in a non-planar graph, and
- (iii) either G_0 has four vertices and five edges or G_0 is 3-connected and has no separating 3-cycle.

Now we add, for each facial 3-cycle S of G_0 a finite or infinite (possibly empty) complete graph K^S and join it completely to $V(S)$, and for every edge e of G_0 which is not contained in a 3-cycle we add a finite or infinite (possibly empty) complete graph K^e and join it completely to the ends of e . The resulting graph is called an (x_1, x_2, y_1, y_2) -web with rib G_0 . It is easy to give examples showing that G_0 need not contain any facial 3-cycle.

We can now extend Theorem 1 to infinite graphs.

THEOREM 3. *The graphs which have no (x_1, x_2, y_1, y_2) -linkage and which are edge-maximal under this condition are precisely the (x_1, x_2, y_1, y_2) -webs.*

PROOF. Suppose G is a graph with no (x_1, x_2, y_1, y_2) -linkage and suppose G is maximal under this condition. Clearly G contains the cycle $S_0 : x_1x_2y_1y_2x_1$. As in the proof of Theorem 1 we show that G is 2-connected and if A is a minimal separating set of two or three vertices such that a component H of $G - A$ does not intersect S_0 , then A induces a complete subgraph of G , H is complete and is completely joined to A , and $G - A$ has only one such component H . Moreover, in this case there is no minimal separating set $A' \neq A$ with two or three vertices such that $G - A'$ has a component H' which intersects A but not S_0 . For any such minimal set A' would not intersect H and hence H' would contain H . But H' (and hence also H) is joined completely to A' , which is clearly a contradiction. In other

words, any vertex z of A either belongs to $V(S_0)$ or is connected to $V(S_0)$ by four paths having only z in common pair by pair.

Now we define G_0 as the subgraph of G induced by $V(S_0)$ and all vertices z which are connected to $V(S_0)$ by four paths having only z in common pair by pair. From the reasoning above it follows that G_0 contains every vertex of any minimal separating set A with two or three vertices such that a component of $G - A$ does not intersect S_0 . We prove that for any vertex $z \in V(G_0) \setminus V(S_0)$ there are in G_0 four $z - V(S_0)$ paths having only z in common pair by pair. By definition of G_0 , there are such four paths P_1, P_2, P_3, P_4 in G . We select these paths such that the total number of edges in these paths is the least possible. Then these paths are contained in G_0 . For if a vertex z' of P_1 is not in G_0 , then G contains a (minimal) set A of two or three vertices separating z' from $V(S_0)$. One of these vertices is on the segment of P_1 from z' to $V(S_0)$ and another is on the segment of P_1 from z' to z . Since $G(A)$ is complete we can replace P_1 by a shorter path, a contradiction to the choice of P_1, P_2, P_3, P_4 .

From the connectivity property of G_0 established above it follows easily that G_0 either has four vertices only or else G_0 is 3-connected and has no separating 3-cycle. So G_0 satisfies condition (iii). Also, by Lemma 1, G_0 contains no subdivision of K_5 or $K_{3,3}$. By a result of Halin [2, Theorems 9.1, 9.4] any uncountable 3-connected graph contains a subdivision of $K_{3,3}$ so G_0 is countable. Now G_0 is planar by Kuratowski's theorem. Moreover, S_0 is a facial cycle of G_0 for otherwise G_0 would contain an (x_1, x_2, y_1, y_2) -linkage consisting of two paths one of which is in the interior and the other in the exterior of S_0 in some planar representation of G_0 . So G_0 satisfies condition (i).

Now consider any vertex x not in G_0 . Then there exists a (smallest) set A of two or three vertices of G such that the component of $G - A$ containing x does not intersect S_0 . Then $A \subseteq V(G_0)$, $G(A)$ is complete, and x is joined to all vertices of A . Since G_0 is 3-connected and has no separating 3-cycle, x is not joined to any other vertex of G_0 . So A consists precisely of the vertices of G_0 adjacent to x . If another vertex x' not in G_0 is joined to $A' \subseteq V(G_0)$ and $A' \subseteq A$, then the maximality property of G implies that $A' = A$ and x' and x are adjacent. Also, if A consists of two vertices u, v only, then the maximality property of G also implies that the edge uv is not contained in a 3-cycle of G_0 .

In order to prove that G is an (x_1, x_2, y_1, y_2) -web with rib G_0 it only remains to prove that G_0 satisfies condition (ii). If we add an edge e to G_0 ($e \neq x_1y_1, e \neq x_2y_2$) and $G_0 \cup \{e\}$ is still planar, then S_0 is facial cycle of this graph and hence $G_0 \cup \{e\}$ has no (x_1, x_2, y_1, y_2) -linkage. But then it is easy to see that also $G \cup \{e\}$ has no such linkage. This contradiction shows that (ii) is satisfied.

We have proved that every maximal graph with no (x_1, x_2, y_1, y_2) -linkage is an (x_1, x_2, y_1, y_2) -web. The converse is proved as in Theorem 1.

5. k -LINKAGES AND WEAK k -LINKAGES IN INFINITE GRAPHS

Larman and Mani [8] and Jung [7] proved that a $2k$ -connected graph which contains a subdivision of a complete graph with $3k$ vertices is k -linked. This also holds for infinite graphs but, as pointed out by Mader [12], there are infinite planar graphs of arbitrarily high finite connectivity which are not 2-linked. However, these graphs are countable, and by using a result of Halin [5], we can get a best possible sufficient condition, in terms of connectivity, for an uncountable graph to be k -linked.

The webs of Section 4 may be uncountable and 3-connected so we conclude, as in the remark preceding Conjecture 2 that, for each $k \geq 2$, there are uncountable $(2k - 1)$ -connected graphs which are not k -linked. So the following result is best possible.

THEOREM 4. *Every uncountable $2k$ -connected graph G is k -linked.*

PROOF. Let $Z = (x_1, x_2, \dots, x_k, y_1, y_2, \dots, y_k)$ be any ordered set of $2k$ distinct vertices of G . By a result of Halin [5, Theorems 9.1, 9.4], G contains a subdivision H of the complete bipartite graph with $2k$ vertices in one class (which we denote by A) and countably many vertices in the other class. Now we consider $2k$ disjoint $Z - A$ paths. These paths contain only finitely many vertices of H , and so we can extend the $Z - A$ paths into a Z -linkage using appropriate paths of H .

We believe that Conjecture 1 is also valid for infinite graphs and that an infinite directed multigraph is weakly k -linked if and only if it is k -edge-connected.

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