# General decay for a system of nonlinear viscoelastic wave equations with weak damping 

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#### Abstract

In this paper, we are concerned with a system of nonlinear viscoelastic wave equations with initial and Dirichlet boundary conditions in $\mathbb{R}^{n}(n=1,2,3)$. Under suitable assumptions, we establish a general decay result by multiplier techniques, which extends some existing results for a single equation to the case of a coupled system. MSC: 35L05; 35L55; 35L70


Keywords: viscoelastic system; general decay; weak damping

## 1 Introduction

In this paper, we are concerned with a coupled system of nonlinear viscoelastic wave equations with weak damping

$$
\left\{\begin{array}{l}
u_{t t}-\Delta u+\int_{0}^{t} g_{1}(t-\tau) \Delta u(\tau) d \tau+u_{t}=f_{1}(u, v), \quad \text { in } \Omega \times(0,+\infty),  \tag{1.1}\\
v_{t t}-\Delta v+\int_{0}^{t} g_{2}(t-\tau) \Delta v(\tau) d \tau+v_{t}=f_{2}(u, v), \quad \text { in } \Omega \times(0,+\infty), \\
u=v=0, \quad \text { on } \partial \Omega \times(0,+\infty), \\
u(\cdot, 0)=u_{0}, \quad u_{t}(\cdot, 0)=u_{1}, \quad v(\cdot, 0)=v_{0}, \quad v_{t}(\cdot, 0)=v_{1}, \quad \text { in } \Omega,
\end{array}\right.
$$

where $\Omega \subseteq \mathbb{R}^{n}(n=1,2,3)$ is a bounded domain with smooth boundary $\partial \Omega$, $u$ and $v$ represent the transverse displacements of waves. The functions $g_{1}$ and $g_{2}$ denote the kernel of a memory, $f_{1}(u, v)$ and $f_{2}(u, v)$ are the nonlinearities.

In recent years, many mathematicians have paid their attention to the energy decay and dynamic systems of the nonlinear wave equations, hyperbolic systems and viscoelastic equations.

Firstly, we recall some results concerning single viscoelastic wave equation. Kafini and Tatar [1] considered the following Cauchy problem:

$$
\begin{cases}u_{t t}-\Delta u+\int_{0}^{t} g(t-s) \Delta u(x, s) d s=0, & x \in \mathbb{R}^{n}, t>0  \tag{1.2}\\ u(x, 0)=u_{0}(x), \quad u_{t}(x, 0)=u_{1}(x), & x \in \mathbb{R}^{n}\end{cases}
$$

They established the polynomial decay of the first-order energy of solutions for compactly supported initial data and for a not necessarily decreasing relaxation function. Later Tatar
[2] studied the problem (1.2) with the Dirichlet boundary condition and showed that the decay of solutions was an arbitrary decay not necessarily at exponential or polynomial rate. Cavalcanti et al. [3] studied the following equation with Dirichlet boundary condition:

$$
\left|u_{t}\right|^{\rho} u_{t t}-\Delta u-\Delta u_{t t}+g * \Delta u-\gamma \Delta u_{t}=0 .
$$

The authors established a global existence result for $\gamma \geq 0$ and an exponential decay of energy for $\gamma>0$. They studied the interaction within the $\left|u_{t}\right|^{\rho} u_{t t}$ and the memory term $g * \Delta u$. Later on, several other results were published based on [4-6]. For more results on a single viscoelastic equation, we can refer to [7-14].

For a coupled system, Agre and Rammaha [15] investigated the following system:

$$
\left\{\begin{array}{l}
u_{t t}-\Delta u+\left|u_{t}\right|^{m-1} u_{t}=f_{1}(u, v), \quad \text { in } \Omega \times(0, T), \\
v_{t t}-\Delta v+\left|v_{t}\right|^{r-1} v_{t}=f_{2}(u, v), \quad \text { in } \Omega \times(0, T),
\end{array}\right.
$$

where $\Omega \subseteq \mathbb{R}^{n}(n=1,2,3)$ is a bounded domain with smooth boundary. They considered the following assumptions on $f_{i}(i=1,2)$ :
$\left(\mathrm{A}_{1}\right)$ Let

$$
F(u, v)=a|u+v|^{p+1}+2 b|u v|^{\frac{p+1}{2}}, \quad f_{1}(u, v)=\frac{\partial F}{\partial u}, \quad f_{2}(u, v)=\frac{\partial F}{\partial v}
$$

with $a, b>0, p \geq 3$ if $n=1,2$ and $p=3$ if $n=3 ; m, r \geq 1$.
$\left(\mathrm{A}_{2}\right)$ There exist two positive constants $c_{0}, c_{1}$ such that for all $u, v \in \mathbb{R}^{2}, F(u, v)$ satisfies

$$
c_{0}\left(|u|^{p+1}+|v|^{p+1}\right) \leq F(u, v) \leq c_{1}\left(|u|^{p+1}+|v|^{p+1}\right)
$$

Under the assumptions $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{2}\right)$, they established the global existence of weak solutions and the global existence of small weak solutions with initial and Dirichlet boundary conditions. Moreover, they also obtained the blow up of weak solutions. Mustafa [16] studied the following system:

$$
\left\{\begin{array}{l}
u_{t t}-\Delta u+\int_{0}^{t} g_{1}(t-\tau) \Delta u(\tau) d \tau+f_{1}(u, v)=0  \tag{1.3}\\
v_{t t}-\Delta v+\int_{0}^{t} g_{2}(t-\tau) \Delta v(\tau) d \tau+f_{2}(u, v)=0
\end{array}\right.
$$

in $\Omega \times(0,+\infty)$ with initial and Dirichlet boundary conditions, proved the existence and uniqueness to the system by using the classical Faedo-Galerkin method and established a stability result by multiplier techniques. But the author considered the following different assumptions on $f_{i}(i=1,2)$ from $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{2}\right)$ :
$\left(\mathrm{A}_{1}^{\prime}\right) f_{i}: \mathbb{R}^{2} \rightarrow \mathbb{R}(i=1,2)$ are $C^{1}$ functions and there exists a function $F$ such that

$$
f_{1}(x, y)=\frac{\partial F}{\partial x}, \quad f_{2}(x, y)=\frac{\partial F}{\partial y}, \quad F \geq 0, x f_{1}(x, y)+y f_{2}(x, y) \geq F(x, y)
$$

( $\mathrm{A}_{2}^{\prime}$ )

$$
\left|\frac{\partial f_{i}}{\partial x}(x, y)\right|+\left|\frac{\partial f_{i}}{\partial y}(x, y)\right| \leq d\left(1+|x|^{\beta_{i 1}-1}+|y|^{\beta_{i 2}-1}\right)
$$

for all $(x, y) \in \mathbb{R}^{2}$, where the constant $d>0$ and $\beta_{i j} \geq 1,(n-2) \beta_{i j} \leq n$ for $i, j=1,2$.

Han and Wang [17] considered the following coupled nonlinear viscoelastic wave equations with weak damping:

$$
\left\{\begin{array}{l}
u_{t t}-\Delta u+\int_{0}^{t} g_{1}(t-\tau) \Delta u(\tau) d \tau+\left|u_{t}\right|^{m-1} u_{t}=f_{1}(u, v), \quad \text { in } \Omega \times(0, T),  \tag{1.4}\\
v_{t t}-\Delta v+\int_{0}^{t} g_{2}(t-\tau) \Delta v(\tau) d \tau+\left|v_{t}\right|^{r-1} v_{t}=f_{2}(u, v), \quad \text { in } \Omega \times(0, T), \\
u=v=0, \quad \text { on } \partial \Omega \times(0, T), \\
u(\cdot, 0)=u_{0}, \quad u_{t}(\cdot, 0)=u_{1}, \quad v(\cdot, 0)=v_{0}, \quad v_{t}(\cdot, 0)=v_{1}, \quad \text { in } \Omega,
\end{array}\right.
$$

where $\Omega \subseteq \mathbb{R}^{n}$ is a bounded domain with smooth boundary $\partial \Omega$. Under the assumptions $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{2}\right)$ on $f_{i}(i=1,2)$, the initial data and the parameters in the equations, they established the local existence, global existence uniqueness and finite time blow up properties. When the weak damping terms $\left|u_{t}\right|^{m-1} u_{t},\left|v_{t}\right|^{r-1} v_{t}$ were replaced by the strong damping terms $-\Delta u_{t},-\Delta v_{t}$, Liang and Gao [18] showed that under certain assumption on initial data in the stable set, the decay rate of the solution energy is exponential when they take

$$
\begin{aligned}
& f_{1}(u, v)=\left[a|u+v|^{2(p+1)}(u+v)+b|u|^{p} u|v|^{p+2}\right], \\
& f_{2}(u, v)=\left[a|u+v|^{2(p+1)}(u+v)+b|u|^{p+2} v|v|^{p}\right],
\end{aligned}
$$

$a, b>0$ and $p>-1$ if $n=1,2,-1<p \leq 1$ if $n=3$. Moreover, they obtained that the solutions with positive initial energy blow up in a finite time for certain initial data in the unstable set. For more results on coupled viscoelastic equations, we can refer to [1921].

If we take $m=r=1$ in (1.4), the system will be transformed into (1.1). To the best of our knowledge, there is no result on general energy decay for the viscoelastic problem (1.1). Motivated by [16, 17], in this paper, we shall establish the general energy decay for the problem (1.1) by multiplier techniques, which extends some existing results for a single equation to the case of a coupled system. The rest of our paper is organized as follows. In Section 2, we give some preparations for our consideration and our main result. The statement and the proof of our main result will be given in Section 3.
For the reader's convenience, we denote the norm and the scalar product in $L^{2}(\Omega)$ by $\|\cdot\|$ and $(\cdot, \cdot)$, respectively. $C_{1}$ denotes a general constant, which may be different in different estimates.

## 2 Preliminaries and main result

To state our main result, in addition to $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{2}\right)$, we need the following assumption.
$\left(\mathrm{A}_{3}\right) g_{i}: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}, i=1,2$, are differentiable functions such that

$$
g_{i}(0)>0, \quad 1-\int_{0}^{+\infty} g_{i}(s) d s=l_{i}>0
$$

and there exist nonincreasing functions $\xi_{1}, \xi_{2}: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$satisfying

$$
g_{i}^{\prime}(t) \leq-\xi_{i}(t) g_{i}(t), \quad t \geq 0 .
$$

Now, we define the energy functional

$$
\begin{align*}
E(t)= & \frac{1}{2} \int_{\Omega}\left(u_{t}^{2}+\left(1-\int_{0}^{t} g_{1}(s) d s\right)|\nabla u|^{2}\right) d x \\
& +\frac{1}{2}\left(g_{1} \circ \nabla u\right)(t)+\frac{1}{2}\left(g_{2} \circ \nabla v\right)(t) \\
& +\frac{1}{2} \int_{\Omega}\left(v_{t}^{2}+\left(1-\int_{0}^{t} g_{2}(s) d s\right)|\nabla v|^{2}\right) d x-\int_{\Omega} F(u, v) d x \tag{2.1}
\end{align*}
$$

and the functional

$$
\begin{align*}
D(t)= & \left(1-\int_{0}^{t} g_{1}(s) d s\right)\|\nabla u(t)\|^{2}+\left(1-\int_{0}^{t} g_{2}(s) d s\right)\|\nabla v(t)\|^{2} \\
& +2\left[\left(g_{1} \circ \nabla u\right)(t)+\left(g_{2} \circ \nabla v\right)(t)\right]-4 \int_{\Omega} F(u(t), v(t)) d x, \tag{2.2}
\end{align*}
$$

where

$$
(g \circ y)(t)=\int_{0}^{t} g(t-s)\|y(t)-y(s)\|^{2} d s
$$

The existence of a global solution to the system (1.1) is established in [17] as follows

Proposition [17] Let $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{3}\right)$ hold. Assume that $D(0)=\left\|\nabla u_{0}\right\|^{2}+\left\|\nabla v_{0}\right\|^{2}-4 \int_{\Omega} F\left(u_{0}\right.$, $\left.v_{0}\right) d x>0, \frac{2^{p} C_{0}}{l}\left(\frac{E(0)}{l}\right)^{\frac{p-1}{2}}<1$ and that $\left(u_{0}, u_{1}\right) \in H_{0}^{1}(\Omega) \times L^{2}(\Omega),\left(v_{0}, v_{1}\right) \in H_{0}^{1}(\Omega) \times L^{2}(\Omega)$, where $C_{0}$ is a computable constant and $l=\min \left\{l_{1}, l_{2}\right\}$. Then the problem (1.1) has a unique global solution $(u(t), v(t))$ satisfying

$$
\left(u(t), u_{t}(t)\right) \in C\left(\mathbb{R}^{+} ; H_{0}^{1}(\Omega) \times L^{2}(\Omega)\right), \quad\left(v(t), v_{t}(t)\right) \in C\left(\mathbb{R}^{+} ; H_{0}^{1}(\Omega) \times L^{2}(\Omega)\right) .
$$

We are now ready to state our main result.

Theorem 2.1 Let $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{3}\right)$ hold. Assume that $D(0)=\left\|\nabla u_{0}\right\|^{2}+\left\|\nabla v_{0}\right\|^{2}-4 \int_{\Omega} F\left(u_{0}\right.$, $\left.v_{0}\right) d x>0, \frac{2^{p} C_{0}}{l}\left(\frac{E(0)}{l}\right)^{\frac{p-1}{2}}<1$ and that $\left(u_{0}, u_{1}\right) \in H_{0}^{1}(\Omega) \times L^{2}(\Omega),\left(v_{0}, v_{1}\right) \in H_{0}^{1}(\Omega) \times L^{2}(\Omega)$, where $C_{0}$ is a computable constant and $l=\min \left\{l_{1}, l_{2}\right\}$. Then there exist constants $C, \eta>0$ such that, for large, the solution of (1.1) satisfies

$$
\begin{equation*}
E(t) \leq C e^{-\eta \int_{0}^{t} \xi(s) d s}, \tag{2.3}
\end{equation*}
$$

where

$$
\begin{equation*}
\xi(t)=\min \left\{\xi_{1}(t), \xi_{2}(t)\right\}, \quad t \geq 0 . \tag{2.4}
\end{equation*}
$$

## 3 Proof of Theorem 2.1

In this section, we carry out the proof of Theorem 2.1. Firstly, we will estimate several lemmas.

Lemma 3.1 Let $u(t), v(t)$ be the solution of (1.1). Then the following energy estimate holds for any $t \geq 0$ :

$$
\begin{align*}
E^{\prime}(t)= & -\left(\left\|u_{t}\right\|^{2}+\left\|v_{t}\right\|^{2}\right)+\frac{1}{2}\left[\left(g_{1}^{\prime} \circ \nabla u\right)+\left(g_{2}^{\prime} \circ \nabla v\right)\right] \\
& -\frac{1}{2}\left[g_{1}(t)\|\nabla u(t)\|^{2}+g_{2}(t)\|\nabla v(t)\|^{2}\right] \leq 0 . \tag{3.1}
\end{align*}
$$

Proof Multiplying the first equation of (1.1) by $u_{t}$ and the second equation by $v_{t}$, respectively, integrating the results over $\Omega$, performing integration by parts and noting that $F_{t}(u, v)=f_{1}(u, v) u_{t}+f_{2}(u, v) v_{t}$, we can easily get (3.1). The proof is complete.

Lemma 3.2 Under the assumption $\left(\mathrm{A}_{3}\right)$, the following hold:

$$
\begin{align*}
& \int_{\Omega}\left(\int_{0}^{t} g(t-\tau)(\nabla u(t)-\nabla u(\tau)) d \tau\right)^{2} d x \leq C_{1}(g \circ \nabla u)  \tag{3.2}\\
& \int_{\Omega}\left(\int_{0}^{t}-g^{\prime}(t-\tau)(\nabla u(t)-\nabla u(\tau)) d \tau\right)^{2} d x \leq-C_{1}\left(g^{\prime} \circ \nabla u\right) \tag{3.3}
\end{align*}
$$

Proof Using Hölder's inequality, we get

$$
\begin{aligned}
\int_{\Omega} & \left(\int_{0}^{t} g(t-\tau)(\nabla u(t)-\nabla u(\tau)) d \tau\right)^{2} d x \\
& \leq \int_{\Omega}\left(\int_{0}^{t} g(\tau) d \tau\right)\left(\int_{0}^{t} g(t-\tau)(\nabla u(t)-\nabla u(\tau))^{2} d \tau\right) d x \\
& \leq\left(\int_{0}^{t} g(\tau) d \tau\right) \int_{0}^{t} g(t-\tau)\left(\int_{\Omega}(\nabla u(t)-\nabla u(\tau))^{2} d x\right) d \tau \\
& \leq C_{1}(g \circ \nabla u) .
\end{aligned}
$$

On the other hand, we repeat the above proof with $-g^{\prime}$, instead of $g$, we can get (3.3). The proof is now complete.

Lemma 3.3 Let $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{3}\right)$ hold and $u(t), v(t)$ be the solution of (1.1). Then the functional $I(t)$ defined by

$$
I(t):=\int_{\Omega}\left(u u_{t}+v v_{t}\right) d x
$$

satisfies

$$
\begin{align*}
I^{\prime}(t) \leq & -\frac{l_{1}}{2}\|\nabla u(t)\|^{2}-\frac{l_{2}}{2}\|\nabla v(t)\|^{2}+\left(1+\frac{1}{4 \delta}\right)\left(\left\|u_{t}\right\|^{2}+\left\|v_{t}\right\|^{2}\right) \\
& +\frac{C_{1}}{\delta}\left(g_{1} \circ \nabla u\right)+\frac{C_{1}}{\delta}\left(g_{2} \circ \nabla v\right)+C_{1} \int_{\Omega} F(u, v) d x \tag{3.4}
\end{align*}
$$

for all $\delta>0$.

Proof By (1.1), a direct differentiation gives

$$
\begin{align*}
I^{\prime}(t)= & \left\|u_{t}\right\|^{2}-\|\nabla u\|^{2}+\int_{\Omega} \nabla u \int_{0}^{t} g_{1}(t-\tau) \nabla u(\tau) d \tau d x-\int_{\Omega} u_{t} u d x+\int_{\Omega} f_{1} u d x \\
& +\left\|v_{t}\right\|^{2}-\|\nabla v\|^{2}+\int_{\Omega} \nabla v \int_{0}^{t} g_{2}(t-\tau) \nabla v(\tau) d \tau d x \\
& -\int_{\Omega} v_{t} v d x+\int_{\Omega} f_{2} v d x . \tag{3.5}
\end{align*}
$$

From the assumptions $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{2}\right)$, we derive

$$
\begin{aligned}
& f_{1}(u, v)=a(p+1)|u+v|^{p}+b(p+1)|u|^{\frac{p-1}{2}}|v|^{\frac{p+1}{2}}, \\
& f_{2}(u, v)=a(p+1)|u+v|^{p}+b(p+1)|u|^{\frac{p+1}{2}}|v|^{\frac{p-1}{2}},
\end{aligned}
$$

and

$$
\begin{align*}
f_{1} u+f_{2} v & =a(p+1)|u+v|^{p+1}+b(p+1)|u v|^{\frac{p+1}{2}} \\
& \leq C_{1} F(u, v) \tag{3.6}
\end{align*}
$$

By Young's inequality and (3.2), we deduce for any $\delta>0$

$$
\begin{align*}
\int_{\Omega} & \nabla u \cdot \int_{0}^{t} g_{1}(t-\tau) \nabla u(\tau) d \tau d x \\
& =\int_{\Omega} \nabla u \cdot \int_{0}^{t} g_{1}(t-\tau)(\nabla u(\tau)-\nabla u(t)+\nabla u(t)) d \tau d x \\
& =\|\nabla u\|^{2} \cdot \int_{0}^{t} g_{1}(\tau) d \tau+\int_{\Omega} \nabla u \cdot \int_{0}^{t} g_{1}(t-\tau)(\nabla u(\tau)-\nabla u(t)) d \tau d x \\
& \leq\|\nabla u\|^{2} \cdot \int_{0}^{t} g_{1}(\tau) d \tau+\delta\|\nabla u\|^{2}+\frac{1}{4 \delta} \int_{\Omega}\left(\int_{0}^{t} g_{1}(t-\tau)|\nabla u(\tau)-u(t)| d \tau\right)^{2} d x \\
& \leq\|\nabla u\|^{2} \cdot \int_{0}^{t} g_{1}(\tau) d \tau+\delta\|\nabla u\|^{2}+\frac{C_{1}}{4 \delta}\left(g_{1} \circ \nabla u\right) . \tag{3.7}
\end{align*}
$$

Similarly, we have

$$
\begin{align*}
\int_{\Omega} \nabla v \cdot \int_{0}^{t} g_{2}(t-\tau) \nabla v(\tau) d \tau d x \leq & \|\nabla v\|^{2} \cdot \int_{0}^{t} g_{2}(\tau) d \tau+\delta\|\nabla v\|^{2} \\
& +\frac{C_{1}}{4 \delta}\left(g_{2} \circ \nabla v\right) \tag{3.8}
\end{align*}
$$

Using Young's inequality and Poincaré's inequality, we obtain for any $\delta>0$

$$
\begin{equation*}
\int_{\Omega} u u_{t} d x \leq \delta\|u\|^{2}+\frac{1}{4 \delta}\left\|u_{t}\right\|^{2} \leq \delta \lambda^{2}\|\nabla u\|^{2}+\frac{1}{4 \delta}\left\|u_{t}\right\|^{2} \tag{3.9}
\end{equation*}
$$

where $\lambda$ is the first eigenvalue of $-\Delta$ with the Dirichlet boundary condition. Similarly,

$$
\int_{\Omega} \nu v_{t} d x \leq \delta\|v\|^{2}+\frac{1}{4 \delta}\left\|v_{t}\right\|^{2} \leq \delta \lambda^{2}\|\nabla v\|^{2}+\frac{1}{4 \delta}\left\|v_{t}\right\|^{2},
$$

which together with (3.5)-(3.9) gives

$$
\begin{align*}
I^{\prime}(t) \leq & -\left(l_{1}-\delta-\delta \lambda^{2}\right)\|\nabla u\|^{2}-\left(l_{2}-\delta-\delta \lambda^{2}\right)\|\nabla v\|^{2}+\left(1+\frac{1}{4 \delta}\right)\left(\left\|u_{t}\right\|^{2}+\left\|v_{t}\right\|^{2}\right) \\
& +\frac{C_{1}}{4 \delta}\left(g_{1} \circ \nabla u\right)+\frac{C_{1}}{4 \delta}\left(g_{2} \circ \nabla v\right)+C_{1} \int_{\Omega} F(u, v) d x . \tag{3.10}
\end{align*}
$$

Now, we choose $\delta>0$ so small that

$$
l_{1}-\delta-\delta \lambda^{2} \geq \frac{l_{1}}{2}, \quad l_{2}-\delta-\delta \lambda^{2} \geq \frac{l_{2}}{2}
$$

which together with (3.10) gives (3.4). The proof is complete.

Lemma 3.4 Let $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{3}\right)$ hold and $u(t), v(t)$ be the solution of $(1.1)$. Then the functional $J(t)$ defined by

$$
J(t)=J_{1}(t)+J_{2}(t),
$$

with

$$
\begin{aligned}
& J_{1}(t):=-\int_{\Omega} u_{t} \int_{0}^{t} g_{1}(t-\tau)(u(t)-u(\tau)) d \tau d x \\
& J_{2}(t):=-\int_{\Omega} v_{t} \int_{0}^{t} g_{2}(t-\tau)(v(t)-v(\tau)) d \tau d x
\end{aligned}
$$

satisfies

$$
\begin{align*}
J^{\prime}(t) \leq & -\left(\int_{0}^{t} g_{1}(\tau)-2 \delta\right)\left\|u_{t}\right\|^{2}+\delta C_{1}\|\nabla u\|^{2}+\frac{C_{1}}{\delta}\left(g_{1} \circ \nabla u\right)-\frac{C_{1}}{\delta}\left(g_{1}^{\prime} \circ \nabla u\right) \\
& -\left(\int_{0}^{t} g_{2}(\tau)-2 \delta\right)\left\|v_{t}\right\|^{2}+\delta C_{1}\|\nabla v\|^{2}+\frac{C_{1}}{\delta}\left(g_{2} \circ \nabla v\right)-\frac{C_{1}}{\delta}\left(g_{2}^{\prime} \circ \nabla v\right) . \tag{3.11}
\end{align*}
$$

Proof A direct differentiation for $J_{1}(t)$ yields

$$
\begin{align*}
J_{1}^{\prime}(t)= & -\int_{\Omega} u_{t t} \cdot \int_{0}^{t} g_{1}(t-\tau)(u(t)-u(\tau)) d \tau-\int_{\Omega} u_{t} \cdot \int_{0}^{t} g_{1}^{\prime}(t-\tau)(u(t)-u(\tau)) d \tau d x \\
& -\left(\int_{0}^{t} g_{1}(\tau) d \tau\right) \int_{\Omega} u_{t}^{2} d x \tag{3.12}
\end{align*}
$$

Using the first equation of (1.1) and integrating by parts, we obtain

$$
\begin{aligned}
J_{1}^{\prime}(t)= & \left(1-\int_{0}^{t} g_{1}(\tau) d \tau\right) \int_{\Omega} \nabla u \cdot \int_{0}^{t} g_{1}(t-\tau)(\nabla u(t)-\nabla u(\tau)) d \tau d x \\
& +\int_{\Omega}\left(\int_{0}^{t} g_{1}(t-\tau)|\nabla u(t)-\nabla u(\tau)| d \tau\right)^{2} d x \\
& +\int_{\Omega} u_{t} \cdot \int_{0}^{t} g_{1}(t-\tau)(u(t)-u(\tau)) d \tau d x
\end{aligned}
$$

$$
\begin{align*}
& -\int_{\Omega} f_{1}(u, v) \int_{0}^{t} g_{1}(t-\tau)(u(t)-u(\tau)) d \tau d x \\
& -\int_{\Omega} u_{t} \cdot \int_{0}^{t} g_{1}^{\prime}(t-\tau)(u(t)-u(\tau)) d \tau d x \\
& -\left(\int_{0}^{t} g_{1}(\tau) d \tau\right) \int_{\Omega} u_{t}^{2} d x . \tag{3.13}
\end{align*}
$$

From Young's inequality, Poincaré's inequality and Lemma 3.2, we derive

$$
\begin{align*}
& \left(1-\int_{0}^{t} g_{1}(\tau) d \tau\right) \int_{\Omega} \nabla u \cdot \int_{0}^{t} g_{1}(t-\tau)(\nabla u(t)-\nabla u(\tau)) d \tau d x \\
& \leq \delta\|\nabla u\|^{2}+\frac{C_{1}}{\delta}\left(g_{1} \circ \nabla u\right),  \tag{3.14}\\
& -\int_{\Omega} u_{t} \cdot \int_{0}^{t} g_{1}^{\prime}(t-\tau)(u(t)-u(\tau)) d \tau d x \leq \delta\left\|u_{t}\right\|^{2}-\frac{C_{1}}{\delta}\left(g_{1}^{\prime} \circ \nabla u\right),  \tag{3.15}\\
& \int_{\Omega} u_{t} \cdot \int_{0}^{t} g_{1}(t-\tau)(u(t)-u(\tau)) d \tau d x \leq \delta\left\|u_{t}\right\|^{2}+\frac{C_{1}}{\delta}\left(g_{1} \circ \nabla u\right),  \tag{3.16}\\
& \int_{\Omega} f_{1}(u, v) \int_{0}^{t} g_{1}(t-\tau)(u(t)-u(\tau)) d \tau d x \leq \int_{\Omega} f_{1}^{2}(u, v) d x+\frac{C_{1}}{\delta}\left(g_{1} \circ u\right) \\
& \leq \delta \int_{\Omega} f_{1}^{2}(u, v) d x+\frac{C_{1}}{\delta}\left(g_{1} \circ \nabla u\right) . \tag{3.17}
\end{align*}
$$

Now, we estimate the first term on the right-hand side of (3.17). Using the assumptions $\left(\mathrm{A}_{1}\right)-\left(\mathrm{A}_{2}\right)$ and Young's inequality, we arrive at

$$
\begin{align*}
& \int_{\Omega} f_{1}^{2}(u, v) d x \\
& \leq C_{1} \int_{\Omega}|u+\nu|^{2 p} d x+C_{1} \int_{\Omega}|u|^{p-1}|v|^{p+1} d x \\
& \leq C_{1}\|u\|_{L^{2 p}}^{2 p}+C_{1}\|v\|_{L^{2 p}}^{2 p}+C_{1}\|u\|_{L^{3(p-1)}}^{2 p-2}+C_{1}\|v\|_{L^{\frac{3(p+1)}{2}}}^{2 p+2} \\
& \leq C_{1}\left(\frac{8 E(0)}{l_{1}}\right)^{p-1}\|\nabla u\|^{2}+C_{1}\left(\frac{8 E(0)}{l_{2}}\right)^{p-1}\|\nabla \nu\|^{2} \\
& +C_{1}\left(\frac{8 E(0)}{l_{1}}\right)^{p-2}\|\nabla u\|^{2}+C_{1}\left(\frac{8 E(0)}{l_{2}}\right)^{p}\|\nabla v\|^{2} \\
& \leq C_{1}\|\nabla u\|^{2}+C_{1}\|\nabla v\|^{2}, \tag{3.18}
\end{align*}
$$

where we used the embedding $H_{0}^{1}(\Omega) \hookrightarrow L^{s}(\Omega)$ for $2 \leq s \leq 2 n /(n-2)$ if $n=3$ or $s \geq 2$ if $n=1,2$ and the fact $\frac{1}{2}\left(\left\|u_{t}\right\|^{2}+\left\|v_{t}\right\|^{2}\right)+\frac{1}{4} l_{1}\|\nabla u\|^{2}+\frac{1}{4} l_{2}\|\nabla v\|^{2} \leq 2 E(0)$ proved in Lemma 5.1 in [17]. Combining (3.13)-(3.18), we get

$$
\begin{align*}
J_{1}^{\prime}(t) \leq & -\left(\int_{0}^{t} g_{1}(\tau) d \tau-2 \delta\right)\left\|u_{t}\right\|^{2}+\delta C_{1}\|\nabla u\|^{2}+\delta C_{1}\|\nabla v\|^{2} \\
& +\frac{C_{1}}{\delta}\left(g_{1} \circ \nabla u\right)-\frac{C_{1}}{\delta}\left(g_{1}^{\prime} \circ \nabla u\right) . \tag{3.19}
\end{align*}
$$

The same estimate to $J_{2}(t)$, we can derive

$$
\begin{aligned}
J_{2}^{\prime}(t) \leq & -\left(\int_{0}^{t} g_{2}(\tau) d \tau-2 \delta\right)\left\|v_{t}\right\|^{2}+\delta C_{1}\|\nabla u\|^{2}+\delta C_{1}\|\nabla v\|^{2} \\
& +\frac{C_{1}}{\delta}\left(g_{2} \circ \nabla v\right)-\frac{C_{1}}{\delta}\left(g_{2}^{\prime} \circ \nabla v\right),
\end{aligned}
$$

which together with (3.19) gives (3.11). The proof is now complete.

Proof of Theorem 2.1 For $N_{1}, N_{2}>0$, we define the functional $\mathcal{K}$ by

$$
\mathcal{K}:=N_{1} E(t)+N_{2} J(t)+I(t),
$$

and let

$$
g_{0}=\min \left\{\int_{0}^{t_{0}} g_{1}(s) d s, \int_{0}^{t_{0}} g_{2}(s) d s\right\}
$$

for some fixed $t_{0}>0$.
Using Lemma 3.1 and Lemmas 3.3-3.4, a direct differentiation gives

$$
\begin{align*}
\mathcal{K}^{\prime}(t) \leq & -\left(\frac{l}{2}-N_{2} \delta C_{1}\right)\left(\|\nabla u\|^{2}+\|\nabla v\|^{2}\right)+\left(\frac{C_{1}}{\delta}+N_{2} \frac{C_{1}}{\delta}\right)\left[\left(g_{1} \circ \nabla u\right)+\left(g_{2} \circ \nabla v\right)\right] \\
& -\left(N_{1}+N_{2}-2 \delta-1-\frac{1}{4 \delta}\right)\left(\left\|u_{t}\right\|^{2}+\left\|v_{t}\right\|^{2}\right)+C_{1} \int_{\Omega} F(u, v) d x \\
& +\left(\frac{N_{1}}{2}-\frac{N_{2} C_{1}}{\delta}\right)\left[\left(g_{1}^{\prime} \circ \nabla u\right)+\left(g_{2}^{\prime} \circ \nabla v\right)\right], \tag{3.20}
\end{align*}
$$

where $l=\min \left\{l_{1}, l_{2}\right\}$.
Now, we choose $\delta=\frac{1}{4 C_{1} N_{2}}$ and $N_{1}, N_{2}$ large enough so that

$$
\begin{align*}
& c_{1}=\frac{l_{1}}{2}-N_{2} \delta C_{1}=\frac{l}{2}-\frac{l}{4}=\frac{l}{4}>0,  \tag{3.21}\\
& c_{2}=N_{1}+N_{2}-\frac{l}{2 C_{1} N_{2}}-1-\frac{C_{1} N_{2}}{l}>0,  \tag{3.22}\\
& c_{3}=\frac{N_{1}}{2}-\frac{4 C_{1}^{2} N_{2}^{2}}{l}>0 . \tag{3.23}
\end{align*}
$$

Inserting (3.21)-(3.23) into (3.20), we have

$$
\begin{align*}
\mathcal{K}^{\prime}(t) \leq & -c_{1}\left(\|\nabla u\|^{2}+\|\nabla v\|^{2}\right)-c_{2}\left(\left\|u_{t}\right\|^{2}+\left\|v_{t}\right\|^{2}\right)+c_{3}\left[\left(g_{1}^{\prime} \circ \nabla u\right)+\left(g_{2}^{\prime} \circ \nabla v\right)\right] \\
& +\left(\frac{4 C_{1}^{2} N_{2}}{l}+\frac{4 C_{1}^{2} N_{2}}{l}\right)\left[\left(g_{1} \circ \nabla u\right)+\left(g_{2} \circ \nabla v\right)\right]+C_{1} \int_{\Omega} F(u, v) d x . \tag{3.24}
\end{align*}
$$

Therefore, for two positive constants $\omega$ and $C$, we obtain

$$
\begin{equation*}
\mathcal{K}^{\prime}(t) \leq-\omega E(t)+C\left[\left(g_{1} \circ \nabla u\right)+\left(g_{2} \circ \nabla v\right)\right], \quad \text { for all } t \geq t_{0} . \tag{3.25}
\end{equation*}
$$

On the other hand, we choose $N_{1}$ even larger so that $\mathcal{K}(t)$ is equivalent to $E(t)$, i.e.,

$$
\begin{equation*}
\mathcal{K}(t) \sim E(t) . \tag{3.26}
\end{equation*}
$$

Multiplying (3.25) by $\xi(t)=\min \left\{\xi_{1}(t), \xi_{2}(t)\right\}$ and using $\left(\mathrm{A}_{3}\right)$, we get

$$
\begin{align*}
\xi(t) \mathcal{K}^{\prime}(t) \leq & -\omega \xi(t) E(t)+C \int_{\Omega} \int_{0}^{t} \xi_{1}(t-\tau) g_{1}(t-\tau)|\nabla u(t)-\nabla u(\tau)|^{2} d \tau d x \\
& +C \int_{\Omega} \int_{0}^{t} \xi_{2}(t-\tau) g_{2}(t-\tau)|\nabla v(t)-\nabla v(\tau)|^{2} d \tau d x \\
\leq & -\omega \xi(t) E(t)-C \int_{\Omega} \int_{0}^{t} g_{1}^{\prime}(t-\tau)|\nabla u(t)-\nabla u(\tau)|^{2} d \tau d x \\
& -C \int_{\Omega} \int_{0}^{t} g_{2}^{\prime}(t-\tau)|\nabla v(t)-\nabla v(\tau)|^{2} d \tau d x \\
\leq & -\omega \xi(t) E(t)-C E^{\prime}(t), \quad \text { for all } t \geq t_{0} . \tag{3.27}
\end{align*}
$$

By virtue of $\left(\mathrm{A}_{3}\right)$ and $\xi(t) \leq 0$, we have

$$
\begin{equation*}
\frac{d}{d t}(\xi(t) \mathcal{K}(t)+C E(t)) \leq-\omega \xi(t) E(t), \quad \text { for all } t \geq t_{0} \tag{3.28}
\end{equation*}
$$

Using (3.26), we can easily get

$$
\begin{equation*}
\mathcal{L}(t):=\xi(t) \mathcal{K}(t)+C E(t) \sim E(t), \tag{3.29}
\end{equation*}
$$

which together with (3.28) yields, for some positive constant $\eta$,

$$
\begin{equation*}
\mathcal{L}^{\prime}(t) \leq-\eta \xi(t) \mathcal{L}(t), \quad \text { for all } t \geq t_{0} \tag{3.30}
\end{equation*}
$$

Integrating (3.30) over ( $t_{0}, t$ ), we arrive at

$$
\begin{aligned}
\mathcal{L}(t) & \leq \mathscr{L}\left(t_{0}\right) e^{-\eta \int_{t}^{t_{0}} \xi(\tau) d \tau} \\
& \leq C e^{-\eta \int_{t}^{t_{0}} \xi(\tau) d \tau},
\end{aligned}
$$

which together with (3.29) and the boundedness of $E$ and $\xi$ yields (2.3). The proof is now complete.

## Competing interests

The authors declare that they have no competing interests

## Authors' contributions

The paper is a joint work of all authors who contributed equally to the final version of the paper. All authors read and approved the final manuscript.

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