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# New multiplied common fixed point theorems in Menger PM-spaces

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## Abstract

In this work, we introduce a new  $\varphi$ -contractive mapping; following that, we obtain some multiplied common fixed point theorems for a pair of mappings  $T : X \times X \times \cdots \times X \rightarrow X$  and  $A : X \rightarrow X$ . The main results of this paper are a generalization of the main results of Kutbi *et al.* (Fixed Point Theory Appl. 2015(1):32, 2015). As an illustration, we give an example to demonstrate the validity of the obtained results.

**MSC:** Primary 47H10; secondary 46S10

**Keywords:** multiplied common fixed point; Menger PM-spaces;  $\varphi$ -contractive mapping

## 1 Introduction

In 1942, Menger [1] initiated the study of probabilistic metric spaces. Since then, many scholars have studied the existence of fixed points or solutions of nonlinear equations under various types of conditions in Menger spaces (see [2–8]). Precisely, Sehgal and Bharucha-Reid [9] introduced probabilistic  $q$ -contractions and proved corresponding unique fixed point results by giving a generalization of the classical Banach fixed point principle. Then, we point out an important theoretical development in the way of defining the concept of contractive mapping in Menger spaces. In 1984, Khan *et al.* [10] introduced the concept of altering distance function. Choudhury and Das [11] defined a generalized contractive condition with the help of such functions and established an unique fixed point result. In 2010, Jachymski [12] established a fixed point theorem for probabilistic  $\varphi$ -contractions. Dutta *et al.* [13] defined nonlinear generalized contractive type mappings in Menger PM-spaces and proved their theorems under the mapping in  $G$ -complete Menger PM-spaces. Recently, [14–18] have studied some new fixed point theorems in Menger PM-spaces and fuzzy metric spaces.

Coupled and tripled fixed point results were studied in [19–21]. In this paper, from the idea of  $\psi$ -contractive type mappings in [16], we introduce a new  $\varphi$ -contractive mapping. Following this, we obtain some multiplied common fixed point theorems for a pair of mappings  $T : X \times X \times \cdots \times X \rightarrow X$  and  $A : X \rightarrow X$ , which is a generalization of [16]. As an illustration, we give an example to demonstrate the validity of the obtained results.

## 2 Preliminaries

Let  $\mathbb{R}$  denote the set of reals,  $\mathbb{R}^+$  the nonnegative reals and  $\mathbb{Z}^+$  be the set of all positive integers. A mapping  $F : \mathbb{R} \rightarrow \mathbb{R}^+$  is called a distribution function if it is nondecreasing and left-continuous with  $\inf_{t \in \mathbb{R}} F(t) = 0$  and  $\sup_{t \in \mathbb{R}} F(t) = 1$ . We will denote by  $\mathcal{D}$  the set of all distribution functions, while  $H$  will always denote the specific distribution function defined by

$$H(t) = \begin{cases} 0, & t \leq 0, \\ 1, & t > 0. \end{cases}$$

A mapping  $\Delta : [0, 1] \times [0, 1] \rightarrow [0, 1]$  is called a triangular norm (for short, a  $t$ -norm) if the following conditions are satisfied:  $\Delta(a, 1) = a$ ;  $\Delta(a, b) = \Delta(b, a)$ ;  $a \geq b, c \geq d \Rightarrow \Delta(a, c) \geq \Delta(b, d)$ ;  $\Delta(a, \Delta(b, c)) = \Delta(\Delta(a, b), c)$ .

Three examples of  $t$ -norm are  $\Delta_m(a, b) = \min\{a, b\}$ ,  $\Delta_p(a, b) = ab$  and  $\Delta_L = \max\{a + b - 1, 0\}$ , these  $t$ -norms are related in the following way:  $\Delta_L \leq \Delta_p \leq \Delta_m$ .

**Definition 2.1** [22] A Menger PM-space is a triple  $(X, F, \Delta)$  where  $X$  is a nonempty set,  $\Delta$  is a continuous  $t$ -norm and  $F$  is a mapping from  $X \times X$  into  $\mathcal{D}^+$  such that, if  $F_{x,y}$  denotes the value of  $F$  at the pair  $(x, y)$ , the following conditions hold:

- (PM-1)  $F_{x,y}(t) = H(t)$  if and only if  $x = y, t > 0$ ;
- (PM-2)  $F_{x,y} = F_{y,x}$  for all  $x, y \in X$ ;
- (PM-3)  $F_{x,y}(t + s) \geq \Delta(F_{x,z}(t), F_{z,y}(s))$  for all  $x, y, z \in X$  and  $s, t \geq 0$ .

**Definition 2.2** [23] Let  $(X, F, \Delta)$  be a Menger PM-space. Then

- (i) a sequence  $\{x_n\}$  is said to be convergent to  $x \in X$  if for every  $\epsilon > 0$  and  $\lambda > 0$ , there exists a positive integer  $Z^+$  such that  $F_{x_n,x}(\epsilon) > 1 - \lambda$  whenever  $n \geq Z^+$ ;
- (ii) a sequence  $\{x_n\}$  in  $X$  is called a *Cauchy* sequence if for every  $\epsilon > 0$  and  $\lambda > 0$ , there exists a positive integer  $Z^+$  such that  $F_{x_n,x_m}(\epsilon) > 1 - \lambda$  whenever  $n, m \geq Z^+$ ;
- (iii) a Menger PM-space is said to be  $M$ -complete if every *Cauchy* sequence in  $X$  is convergent to a point in  $X$ ;
- (iv) a sequence  $\{x_n\}$  is said to be a  $G$ -*Cauchy* sequence if  $\lim_{n \rightarrow \infty} F_{x_n,x_{n+m}}(t) = 1$  for each  $m \in \mathbb{Z}^+$  and  $t > 0$ ;
- (v) the space  $(X, F, \Delta)$  is called  $G$ -complete if every  $G$ -*Cauchy* sequence in  $X$  is convergent to a point in  $X$ .

According to [2], the  $(\epsilon, \lambda)$ -topology in a Menger PM-space  $(X, F, \Delta)$  is introduced by the family of neighborhoods  $N_x$  of a point  $x \in X$  given by  $N_x = \{N_x(\epsilon, \lambda) : \epsilon > 0, \lambda \in (0, 1)\}$ , where  $N_x(\epsilon, \lambda) = \{y \in X : F_{x,y}(\epsilon) > 1 - \lambda\}$ . Then  $(\epsilon, \lambda)$ -topology is a Hausdorff topology.

**Definition 2.3** [11] A function  $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is said to be a  $\phi$ -function if it satisfies the following conditions:

- (i)  $\phi(t) = 0$  if and only if  $t = 0$ ;
- (ii)  $\phi(t)$  is strictly increasing and  $\phi(t) \rightarrow \infty$  as  $t \rightarrow \infty$ ;
- (iii)  $\phi$  is left-continuous in  $(0, \infty)$ ;
- (iv)  $\phi$  is continuous at 0.

**Definition 2.4** Let  $X$  be a nonempty set. Let  $T : \underbrace{X \times X \times \dots \times X}_{m\text{-times}} \rightarrow X$  and  $A : X \rightarrow X$  be two mappings.  $A$  is said to be commutative with  $T$  if  $AT(x, y, \dots, z) = T(Ax, Ay, \dots, Az)$  for

all  $x, y, \dots, z \in X$ . A point  $u \in X$  is called a multiplied common fixed point of  $T$  and  $A$  if  $u = Au = T(u, u, \dots, u)$ .

### 3 Main results

In this section, we denote by  $\Phi$  the class of all nondecreasing functions  $\varphi : R^+ \rightarrow R^+$  such that  $\varphi$  is continuous at 0,  $\varphi(0) = 0$  and  $\varphi^n(a_n) \rightarrow 0$  whenever  $a_n \rightarrow 0$  as  $n \rightarrow \infty$ .

**Theorem 3.1** *Let  $(X, F, \Delta)$  be a  $G$ -complete Menger space with  $\Delta$  a continuous  $t$ -norm. Let  $T : \underbrace{X \times X \times \dots \times X}_{m\text{-times}} \rightarrow X$  and  $A : X \rightarrow X$  be two mappings satisfying the following inequality:*

$$\begin{aligned} & \frac{1}{F_{T(x,y,\dots,z),T(p,q,\dots,r)}(\phi(ct))} - 1 \\ & \leq \varphi \left\{ \frac{\left(\frac{1}{F_{Ax,Ap}(\phi(t))} - 1\right) + \left(\frac{1}{F_{Ay,Aq}(\phi(t))} - 1\right) + \dots + \left(\frac{1}{F_{Az,Ar}(\phi(t))} - 1\right)}{m} \right\} \end{aligned} \tag{3.1}$$

for all  $x, y, \dots, z, p, q, \dots, r \in X$ ,  $c \in (0, 1)$ ,  $\varphi \in \Phi$ ,  $\phi$  is a  $\phi$ -function,  $t > 0$ , such that  $F_{Ax,Ap}(\phi(t)) > 0, F_{Ay,Aq}(\phi(t)) > 0, \dots, F_{Az,Ar}(\phi(t)) > 0$ , where  $T(X \times X \times \dots \times X) \subset A(X)$ ,  $A$  is continuous and commutative with  $T$ . Then there exists a unique multiplied common fixed point of  $A$  and  $T$ , i.e., there exists a unique  $u \in X$  such that  $u = Au = T(u, u, \dots, u)$ .

*Proof* Let  $\{x_n\}_{n=1}^\infty, \{y_n\}_{n=1}^\infty, \dots, \{z_n\}_{n=1}^\infty$  be  $m$ -times sequences in  $X$  such that  $Ax_{n+1} = T(x_n, y_n, \dots, z_n)$  and  $Ay_{n+1} = T(y_n, \dots, z_n, x_n)$ ,  $Az_{n+1} = T(z_n, x_n, y_n, \dots)$ . From  $\sup_{t \in R} F_{Ax_0, Ax_1}(t) = 1, \sup_{t \in R} F_{Ay_0, Ay_1}(t) = 1, \dots, \sup_{t \in R} F_{Az_0, Az_1}(t) = 1$  and the definition of  $\phi$ , one can find  $t > 0$  such that  $F_{Ax_0, Ax_1}(\phi(\frac{t}{c})) > 0, F_{Ay_0, Ay_1}(\phi(\frac{t}{c})) > 0, \dots, F_{Az_0, Az_1}(\phi(\frac{t}{c})) > 0$ . From (3.1), we have

$$\begin{aligned} & \frac{1}{F_{Ax_1, Ax_2}(\phi(t))} - 1 \\ & = \frac{1}{F_{T(x_0, y_0, \dots, z_0), T(x_1, y_1, \dots, z_1)}(\phi(t))} - 1 \\ & \leq \varphi \left\{ \frac{\left(\frac{1}{F_{Ax_0, Ax_1}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ay_0, Ay_1}(\phi(\frac{t}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{Az_0, Az_1}(\phi(\frac{t}{c}))} - 1\right)}{m} \right\}. \end{aligned} \tag{3.2}$$

Similarly, we have

$$\begin{aligned} & \frac{1}{F_{Ay_1, Ay_2}(\phi(t))} - 1 \\ & \leq \varphi \left\{ \frac{\left(\frac{1}{F_{Ay_0, Ay_1}(\phi(\frac{t}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{Az_0, Az_1}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ax_0, Ax_1}(\phi(\frac{t}{c}))} - 1\right)}{m} \right\}, \end{aligned} \tag{3.3}$$

...

$$\begin{aligned} & \frac{1}{F_{Az_1, Az_2}(\phi(t))} - 1 \\ & \leq \varphi \left\{ \frac{\left(\frac{1}{F_{Az_0, Az_1}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ax_0, Ax_1}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ay_0, Ay_1}(\phi(\frac{t}{c}))} - 1\right) + \dots}{m} \right\}. \end{aligned} \tag{3.4}$$

Suppose that  $P_0(t) = \frac{(\frac{1}{F_{Ax_0, Ax_1}(\phi(t))} - 1) + (\frac{1}{F_{Ay_0, Ay_1}(\phi(t))} - 1) + \dots + (\frac{1}{F_{Az_0, Az_1}(\phi(t))} - 1)}{m}$ , from (3.2), (3.3) and (3.4) we deduce that  $F_{Ax_1, Ax_2}(\phi(t)) > 0, F_{Ay_1, Ay_2}(\phi(t)) > 0, \dots, F_{Az_1, Az_2}(\phi(t)) > 0$ , and so  $F_{Ax_1, Ax_2}(\phi(\frac{t}{c})) > 0, F_{Ay_1, Ay_2}(\phi(\frac{t}{c})) > 0, \dots, F_{Az_1, Az_2}(\phi(\frac{t}{c})) > 0$ , then we have

$$\begin{aligned} & \frac{1}{F_{Ax_2, Ax_3}(\phi(t))} - 1 \\ &= \frac{1}{F_{T(x_1, y_1, \dots, z_1), T(x_2, y_2, \dots, z_2)}(\phi(t))} - 1 \\ &\leq \varphi \left\{ \frac{(\frac{1}{F_{Ax_1, Ax_2}(\phi(\frac{t}{c}))} - 1) + (\frac{1}{F_{Ay_1, Ay_2}(\phi(\frac{t}{c}))} - 1) + \dots + (\frac{1}{F_{Az_1, Az_2}(\phi(\frac{t}{c}))} - 1)}{m} \right\} \\ &\leq \varphi \left\{ \frac{\varphi(P_0(\frac{t}{c^2})) + \varphi(P_0(\frac{t}{c^2})) + \dots + \varphi(P_0(\frac{t}{c^2}))}{m} \right\} = \varphi^2 \left\{ P_0\left(\frac{t}{c^2}\right) \right\}. \end{aligned}$$

Similarly, we have

$$\begin{aligned} & \frac{1}{F_{Ay_2, Ay_3}(\phi(t))} - 1 \leq \varphi^2 \left\{ P_0\left(\frac{t}{c^2}\right) \right\}, \\ & \dots, \\ & \frac{1}{F_{Az_2, Az_3}(\phi(t))} - 1 \leq \varphi^2 \left\{ P_0\left(\frac{t}{c^2}\right) \right\}. \end{aligned}$$

Repeating the above procedure, we get

$$\frac{1}{F_{Ax_n, Ax_{n+1}}(\phi(t))} - 1 \leq \varphi^n \left\{ P_0\left(\frac{t}{c^n}\right) \right\}. \tag{3.5}$$

If we change  $Ax_0, Ay_0, \dots, Az_0$  with  $Ax_r, Ay_r, \dots, Az_r$  in (3.5), then for all  $n > r$  we get

$$\frac{1}{F_{Ax_n, Ax_{n+1}}(\phi(c^r t))} - 1 \leq \varphi^{n-r} \left\{ P_r\left(\frac{c^r t}{c^{n-r}}\right) \right\}.$$

Since  $\varphi^n(a_n) \rightarrow 0$  whenever  $a_n \rightarrow 0$  as  $n \rightarrow \infty$ , therefore the above inequality implies that

$$\lim_{n \rightarrow \infty} F_{Ax_n, Ax_{n+1}}(\phi(c^r t)) = 1. \tag{3.6}$$

Now, let  $\epsilon$  be given, using the properties of  $\phi$ -function, we can find  $r \in Z^+$  such that  $\phi(c^r t) < \epsilon$ . Then we have

$$\lim_{n \rightarrow \infty} F_{Ax_n, Ax_{n+1}}(\epsilon) \geq \lim_{n \rightarrow \infty} F_{Ax_n, Ax_{n+1}}(\phi(c^r t)) = 1. \tag{3.7}$$

By using a triangle inequality, we obtain

$$F_{Ax_n, Ax_{n+p}}(\epsilon) \geq \underbrace{\Delta \left( F_{Ax_n, Ax_{n+1}}\left(\frac{\epsilon}{p}\right), \Delta \left( F_{Ax_{n+1}, Ax_{n+2}}\left(\frac{\epsilon}{p}\right), \dots, F_{Ax_{n+p-1}, Ax_{n+p}}\left(\frac{\epsilon}{p}\right) \right) \right)}_{p\text{-times}}.$$

Let  $n \rightarrow \infty$  and make use of (3.7), for any integer  $p$ , we get

$$\lim_{n \rightarrow \infty} F_{Ax_n, Ax_{n+p}}(\epsilon) = 1 \quad \text{for every } \epsilon > 0.$$

Hence  $\{Ax_n\}$  is a *G-Cauchy* sequence. Similarly, we can obtain that  $\{Ay_n\}, \dots, \{Az_n\}$  are *G-Cauchy* sequences. Since  $(X, F, \Delta)$  is *G-complete*, therefore  $\lim_{n \rightarrow \infty} Ax_n = u, \lim_{n \rightarrow \infty} Ay_n = v, \dots, \lim_{n \rightarrow \infty} Az_n = w$  for some  $u, v, \dots, w \in X$ .

Now we show that  $Au = T(u, v, \dots, w)$ .

By the continuity of  $A$ , we can obtain that  $\lim_{n \rightarrow \infty} AAx_n = Au, \lim_{n \rightarrow \infty} AAy_n = Av, \dots, \lim_{n \rightarrow \infty} AAz_n = Aw$ . Then the commutativity of  $A$  with  $T$  implies that  $AAx_{n+1} = T(Ax_n, Ay_n, \dots, Az_n)$ . From (3.1), we obtain

$$\begin{aligned} & \frac{1}{F_{AAx_{n+1}, T(u, v, \dots, w)}(\phi(t))} - 1 \\ &= \frac{1}{F_{T(Ax_n, Ay_n, \dots, Az_n), T(u, v, \dots, w)}(\phi(t))} - 1 \\ &\leq \varphi \left\{ \frac{\left(\frac{1}{F_{AAx_n, Au}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{AAy_n, Av}(\phi(\frac{t}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{AAz_n, Aw}(\phi(\frac{t}{c}))} - 1\right)}{m} \right\}. \end{aligned}$$

Letting  $n \rightarrow \infty$ , since  $\varphi(0) = 0$ , we have  $\lim_{n \rightarrow \infty} AAx_{n+1} = T(u, v, \dots, w)$ , from the above inequality, we get  $Au = T(u, v, \dots, w)$ . Similarly, we have  $Av = T(v, \dots, w, u), \dots, Aw = T(w, u, v, \dots)$ .

Next we will show that  $Au = u$ . From (3.1), we have

$$\begin{aligned} & \frac{1}{F_{Ax_1, Au}(\phi(t))} - 1 \\ &= \frac{1}{F_{T(x_0, y_0, \dots, z_0), T(u, v, \dots, w)}(\phi(t))} - 1 \\ &\leq \varphi \left\{ \frac{\left(\frac{1}{F_{Ax_0, Au}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ay_0, Av}(\phi(\frac{t}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{Az_0, Aw}(\phi(\frac{t}{c}))} - 1\right)}{m} \right\}, \end{aligned} \tag{3.8}$$

$$\begin{aligned} & \frac{1}{F_{Ay_1, Av}(\phi(t))} - 1 \\ &\leq \varphi \left\{ \frac{\left(\frac{1}{F_{Ay_0, Av}(\phi(\frac{t}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{Az_0, Aw}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ax_0, Au}(\phi(\frac{t}{c}))} - 1\right)}{m} \right\}, \end{aligned} \tag{3.9}$$

...

$$\begin{aligned} & \frac{1}{F_{Az_1, Aw}(\phi(t))} - 1 \\ &\leq \varphi \left\{ \frac{\left(\frac{1}{F_{Az_0, Aw}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ax_0, Au}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ay_0, Av}(\phi(\frac{t}{c}))} - 1\right) + \dots}{m} \right\}. \end{aligned} \tag{3.10}$$

Suppose that  $Q_0(t) = \frac{\left(\frac{1}{F_{Ax_0, Au}(\phi(t))} - 1\right) + \left(\frac{1}{F_{Ay_0, Av}(\phi(t))} - 1\right) + \dots + \left(\frac{1}{F_{Az_0, Aw}(\phi(t))} - 1\right)}{m}$ . Combining (3.8), (3.9) with (3.10), we obtain

$$\begin{aligned} & \frac{1}{F_{Ax_2, Au}(\phi(t))} - 1 \\ &\leq \varphi \left\{ \frac{\left(\frac{1}{F_{Ax_1, Au}(\phi(\frac{t}{c}))} - 1\right) + \left(\frac{1}{F_{Ay_1, Av}(\phi(\frac{t}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{Az_1, Aw}(\phi(\frac{t}{c}))} - 1\right)}{m} \right\} \end{aligned}$$

$$\begin{aligned} &\leq \varphi \left\{ \frac{\varphi(Q_0(\frac{t}{c^2})) + \varphi(Q_0(\frac{t}{c^2})) + \dots + \varphi(Q_0(\frac{t}{c^2}))}{m} \right\} = \varphi^2 \left\{ Q_0 \left( \frac{t}{c^2} \right) \right\}, \\ \frac{1}{F_{Ay_2,Av}(\phi(t))} - 1 &\leq \varphi^2 \left\{ Q_0 \left( \frac{t}{c^2} \right) \right\}, \\ &\dots, \\ \frac{1}{F_{Az_2,Aw}(\phi(t))} - 1 &\leq \varphi^2 \left\{ Q_0 \left( \frac{t}{c^2} \right) \right\}. \end{aligned}$$

Repeating the above procedure, we obtain

$$\frac{1}{F_{Ax_n,Au}(\phi(t))} - 1 \leq \varphi^n \left\{ Q_0 \left( \frac{t}{c^n} \right) \right\}. \tag{3.11}$$

Since  $\varphi^n(a_n) \rightarrow 0$  whenever  $a_n \rightarrow 0$  as  $n \rightarrow \infty$ , we have  $\lim_{n \rightarrow \infty} Ax_n = Au$ , which implies that  $Au = u = T(u, v, \dots, w)$ . Similarly, we have  $Av = v = T(v, \dots, w, u), \dots, Aw = w = T(w, u, v, \dots)$ .

Finally, we show that  $u = v = \dots = w$ .

For a better expression, we denote  $u = e_1, v = e_2, \dots, w = e_m$ , then  $Ae_1 = e_1 = T(e_1, e_2, e_3, \dots, e_{m-1}, e_m), Ae_2 = e_2 = T(e_2, e_3, \dots, e_{m-1}, e_m, e_1), \dots, Ae_m = e_m = T(e_m, e_1, e_2, e_3, \dots, e_{m-1})$ .

First, we prove that  $F_{e_1,e_2}(\phi(s)) > 0$  for all  $s > 0$ . By the definition of  $\phi$ , we have  $\phi(\frac{s}{c^n}) \rightarrow \infty$  as  $n \rightarrow \infty$ . Since  $\sup_{n \in \mathbb{Z}^+} F_{e_1,e_2}(\phi(\frac{s}{c^n})) = 1, \sup_{n \in \mathbb{Z}^+} F_{e_2,e_3}(\phi(\frac{s}{c^n})) = 1, \dots, \sup_{n \in \mathbb{Z}^+} F_{e_m,e_1}(\phi(\frac{s}{c^n})) = 1$ , we deduce that there exists  $n \in \mathbb{Z}^+$  such that  $F_{e_1,e_2}(\phi(\frac{s}{c^n})) > 0, F_{e_2,e_3}(\phi(\frac{s}{c^n})) > 0, \dots, F_{e_m,e_1}(\phi(\frac{s}{c^n})) > 0$ . Using (3.1), we obtain

$$\begin{aligned} &\frac{1}{F_{e_1,e_2}(\phi(\frac{s}{c^{n-1}}))} - 1 \\ &= \frac{1}{F_{T(e_1,e_2,\dots,e_{m-1},e_m),T(e_2,\dots,e_{m-1},e_m,e_1)}(\phi(\frac{s}{c^{n-1}}))} - 1 \\ &\leq \varphi \left\{ \frac{(\frac{1}{F_{e_1,e_2}(\phi(\frac{s}{c^n}))} - 1) + \dots + (\frac{1}{F_{e_{m-1},e_m}(\phi(\frac{s}{c^n}))} - 1) + (\frac{1}{F_{e_m,e_1}(\phi(\frac{s}{c^n}))} - 1)}{m} \right\}, \end{aligned}$$

which implies that  $F_{e_1,e_2}(\phi(\frac{s}{c^{n-1}})) > 0$ . Similarly, we can obtain that  $F_{e_2,e_3}(\phi(\frac{s}{c^{n-1}})) > 0, \dots, F_{e_m,e_1}(\phi(\frac{s}{c^{n-1}})) > 0$ . By repeating a similar reasoning  $n$ -times, we deduce that  $F_{e_1,e_2}(\phi(s)) > 0, F_{e_2,e_3}(\phi(s)) > 0, \dots, F_{e_m,e_1}(\phi(s)) > 0$  for all  $s > 0$ .

Second, we show that  $F_{e_1,e_2}(\phi(s)) = 1$ . In fact, for every  $s > 0$ , we have  $F_{e_1,e_2}(\phi(\frac{s}{c^n})) > 0$  for all  $1 \leq i \leq n$  and  $n \in \mathbb{Z}^+$ . Then, by using (3.1), we get

$$\begin{aligned} &\frac{1}{F_{e_1,e_2}(\phi(s))} - 1 \\ &= \frac{1}{F_{T(e_1,e_2,\dots,e_{m-1},e_m),T(e_2,\dots,e_{m-1},e_m,e_1)}(\phi(s))} - 1 \\ &\leq \varphi \left\{ \frac{(\frac{1}{F_{e_1,e_2}(\phi(\frac{s}{c^n}))} - 1) + \dots + (\frac{1}{F_{e_{m-1},e_m}(\phi(\frac{s}{c^n}))} - 1) + (\frac{1}{F_{e_m,e_1}(\phi(\frac{s}{c^n}))} - 1)}{m} \right\}, \\ &\frac{1}{F_{e_2,e_3}(\phi(s))} - 1 \\ &= \frac{1}{F_{T(e_2,e_3,\dots,e_m,e_1),T(e_3,e_4,\dots,e_1,e_2)}(\phi(s))} - 1 \end{aligned}$$

$$\leq \varphi \left\{ \frac{\left(\frac{1}{F_{e_2, e_3}(\phi(\frac{s}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{e_m, e_1}(\phi(\frac{s}{c}))} - 1\right) + \left(\frac{1}{F_{e_1, e_2}(\phi(\frac{s}{c}))} - 1\right)}{m} \right\},$$

...

$$\frac{1}{F_{e_m, e_1}(\phi(s))} - 1$$

$$= \frac{1}{F_{T(e_m, e_1, \dots, e_{m-2}, e_{m-1}), T(e_1, e_2, \dots, e_{m-1}, e_m)}(\phi(s))} - 1$$

$$\leq \varphi \left\{ \frac{\left(\frac{1}{F_{e_m, e_1}(\phi(\frac{s}{c}))} - 1\right) + \left(\frac{1}{F_{e_1, e_2}(\phi(\frac{s}{c}))} - 1\right) + \dots + \left(\frac{1}{F_{e_{m-1}, e_m}(\phi(\frac{s}{c}))} - 1\right)}{m} \right\}.$$

Suppose that  $E(s) = \frac{\left(\frac{1}{F_{e_1, e_2}(\phi(s))} - 1\right) + \left(\frac{1}{F_{e_2, e_3}(\phi(s))} - 1\right) + \dots + \left(\frac{1}{F_{e_m, e_1}(\phi(s))} - 1\right)}{m}$ , then  $E(s) \leq \varphi\{E(\frac{s}{c})\}$ . By  $n$ -iterations we get

$$\frac{1}{F_{e_1, e_2}(\phi(s))} - 1 \leq \varphi \left\{ E\left(\frac{s}{c}\right) \right\} \leq \varphi^2 \left\{ E\left(\frac{s}{c^2}\right) \right\} \leq \dots \leq \varphi^n \left\{ E\left(\frac{s}{c^n}\right) \right\}. \tag{3.12}$$

Thus, since  $\varphi^n(a_n) \rightarrow 0$  whenever  $a_n \rightarrow 0$  as  $n \rightarrow \infty$ , we get  $F_{e_1, e_2}(\phi(s)) = 1$ . It follows that  $F_{e_1, e_2}(t) = H(t)$  for all  $t > 0$ . In fact, if  $t$  is not in range of  $\phi$ , since  $\phi$  is continuous at 0, there exists  $s > 0$  such that  $\phi(s) < t$ . This implies that  $F_{e_1, e_2}(t) \geq F_{e_1, e_2}(\phi(s)) = 1$ , then  $e_1 = e_2$ . Similarly, we have  $e_2 = e_3, \dots, e_m = e_1$ , i.e.,  $u = v = \dots = w$ . Thus,  $u \in X$  is the unique multiplied common fixed point of  $A$  and  $T$ . □

Taking  $m = 1$  in Theorem 3.1, then  $T : X \rightarrow X, A = I_x$  (the identity mapping on  $X$ ). It is obvious that  $T(X) \subset A(X), A$  is continuous and commutative with  $T$ , which also satisfies the conditions in Theorem 3.1, then we have the following consequence.

**Corollary 3.1** *Let  $(X, F, \Delta)$  be a  $G$ -complete Menger space with  $\Delta$  a continuous  $t$ -norm. Let  $T : X \rightarrow X$  satisfying the following inequality:*

$$\frac{1}{F_{Tx, Ty}(\phi(ct))} - 1 \leq \varphi \left\{ \frac{1}{F_{x, y}(\phi(t))} - 1 \right\}$$

for all  $x, y \in X, c \in (0, 1), \varphi \in \Phi, \phi$  is a  $\phi$ -function,  $t > 0$ , such that  $F_{x, y}(\phi(t)) > 0$ . Then  $T$  has a unique fixed point, i.e., there exists  $u \in X$  such that  $u = Au = Tu$ .

**Remark 3.1** Corollary 3.1 is Theorem 2.1 of [16].

**Theorem 3.2** *Let  $(X, F, \Delta)$  be a  $G$ -complete Menger space with  $\Delta$  a continuous  $t$ -norm and  $\Delta \leq \Delta_p$ . Let  $T : \underbrace{X \times X \times \dots \times X}_{m\text{-times}} \rightarrow X$  and  $A : X \rightarrow X$  be two mappings satisfying the following inequality:*

$$\frac{1}{F_{T(x, y, \dots, z), T(p, q, \dots, r)}(\phi(ct))} - 1$$

$$\leq \varphi \left\{ \sqrt[m]{\Delta \left( \frac{1}{F_{Ax, Ap}(\phi(t))} - 1, \Delta \left( \frac{1}{F_{Ay, Aq}(\phi(t))} - 1, \dots, \frac{1}{F_{Az, Ar}(\phi(t))} - 1 \right) \right)} \right\}$$

for all  $x, y, \dots, z, p, q, \dots, r \in X$ ,  $c \in (0, 1)$ ,  $\varphi \in \Phi$ ,  $\phi$  is a  $\phi$ -function,  $t > 0$ , such that  $F_{Ax, Ap}(\phi(t)) > 0, F_{Ay, Aq}(\phi(t)) > 0, \dots, F_{Az, Ar}(\phi(t)) > 0$ , where  $T(X \times X \times \dots \times X) \subset A(X)$ ,  $A$  is continuous and commutative with  $T$ . Then there exists a unique multiplied common fixed point of  $A$  and  $T$ , i.e.,  $u \in X$  such that  $u = Au = T(u, u, \dots, u)$ .

*Proof* Since  $\Delta \leq \Delta_p$ , we get

$$\begin{aligned} & \frac{1}{F_{T(x,y,\dots,z),T(p,q,\dots,r)}(\phi(ct))} - 1 \\ & \leq \varphi \left\{ \sqrt[m]{\Delta \left( \frac{1}{F_{Ax,Ap}(\phi(t))} - 1, \Delta \left( \frac{1}{F_{Ay,Aq}(\phi(t))} - 1, \dots, \frac{1}{F_{Az,Ar}(\phi(t))} - 1 \right) \right)} \right\} \\ & \leq \varphi \left\{ \sqrt[m]{\left( \frac{1}{F_{Ax,Ap}(\phi(t))} - 1 \right) \left( \frac{1}{F_{Ay,Aq}(\phi(t))} - 1 \right) \cdots \left( \frac{1}{F_{Az,Ar}(\phi(t))} - 1 \right)} \right\} \\ & \leq \varphi \left\{ \frac{\left( \frac{1}{F_{Ax,Ap}(\phi(t))} - 1 \right) + \left( \frac{1}{F_{Ay,Aq}(\phi(t))} - 1 \right) + \cdots + \left( \frac{1}{F_{Az,Ar}(\phi(t))} - 1 \right)}{m} \right\}. \end{aligned}$$

Then we can complete the proof by Theorem 3.1. □

#### 4 An illustration

**Example 4.1** Let  $X = [0, 1]$ ,  $d$  be the usual metric on  $X$ . Define  $T : \underbrace{X \times X \times \dots \times X}_{m\text{-times}} \rightarrow X$  as  $T(x_1, x_2, \dots, x_m) = \frac{x_1 + x_2 + \dots + x_m}{3m}$ ,  $A : X \rightarrow X$  as  $Ax = \frac{x}{2}$  and

$$F_{x,y}(t) = \begin{cases} \frac{t}{t+d(x,y)}, & t > 0, \\ 0, & t = 0 \end{cases}$$

for all  $x_1, x_2, \dots, x_m, x, y \in X$ , where  $T(X \times X \times \dots \times X) \subset A(X)$ . Then  $(X, F, \Delta_m)$  is a complete Menger PM-space,  $\Delta_m$  is a continuous  $t$ -norm. Define  $\varphi \in \Phi$  by  $\varphi(t) = \frac{99t}{100}$  and  $\phi(t) = \frac{t}{5}$  for all  $t > 0$ ,  $c = \frac{9}{10}$ . We obtain

$$\begin{aligned} & \frac{1}{F_{T(x_1,x_2,\dots,x_m),T(y_1,y_2,\dots,y_m)}(\phi(ct))} - 1 = \frac{|T(x_1, x_2, \dots, x_m) - T(y_1, y_2, \dots, y_m)|}{\phi(ct)} \\ & = \frac{50|(x_1 + x_2 + \dots + x_m) - (y_1 + y_2 + \dots + y_m)|}{27mt}, \\ & \varphi \left\{ \frac{\left( \frac{1}{F_{Ax_1, Ay_1}(\phi(t))} - 1 \right) + \left( \frac{1}{F_{Ax_2, Ay_2}(\phi(t))} - 1 \right) + \cdots + \left( \frac{1}{F_{Ax_m, Ay_m}(\phi(t))} - 1 \right)}{m} \right\} \\ & = \varphi \left\{ \frac{|Ax_1 - Ay_1| + |Ax_2 - Ay_2| + \cdots + |Ax_m - Ay_m|}{m\phi(t)} \right\} \\ & = \frac{99(|x_1 - y_1| + |x_2 - y_2| + \cdots + |x_m - y_m|)}{40mt}. \end{aligned}$$

It is obvious that

$$\begin{aligned} & \frac{1}{F_{T(x_1,x_2,\dots,x_m),T(y_1,y_2,\dots,y_m)}(\phi(ct))} - 1 \\ & \leq \varphi \left\{ \frac{\left( \frac{1}{F_{Ax_1, Ay_1}(\phi(t))} - 1 \right) + \left( \frac{1}{F_{Ax_2, Ay_2}(\phi(t))} - 1 \right) + \cdots + \left( \frac{1}{F_{Ax_m, Ay_m}(\phi(t))} - 1 \right)}{m} \right\} \end{aligned}$$



for all  $t > 0$ . Thus all the conditions of Theorem 3.1 are satisfied. Therefore, 0 is the unique multiplied common fixed point of  $A$  and  $T$ .

#### Competing interests

The authors declare that they have no competing interests.

#### Authors' contributions

All authors contributed equally. All authors read and approved the final manuscript.

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