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Letter

# Longitudinal scaling of elliptic flow in Landau hydrodynamics 

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#### Abstract

This study presents a generalization of the Landau hydrodynamic solution for multiparticle production applied to non-central relativistic heavy-ion collisions. The obtained results show the longitudinal scaling of elliptic flow, $v_{2}$, as a function of rapidity shifted by beam rapidity ( $y-y_{b e a m}$ ) for different energies $\left(\sqrt{s_{N N}}=62.4 \mathrm{GeV}\right.$ and 200 GeV$)$ and for different systems ( $\mathrm{Au}-\mathrm{Au}$ and $\mathrm{Cu}-\mathrm{Cu}$ ). It is argued that the elliptic flow and its longitudinal scaling are due to the initial transverse energy density distribution and initial longitudinal thickness effect.


## 1 Introduction

Experimentally observed azimuthal asymmetries of particle production in non-central heavy-ion collisions are currently of high interest, as they provide more information about the early dynamics of the high-energy nuclear reactions. Moreover, RHIC data [1] of elliptic flow for different pseudorapidities shows universal behavior for different nuclei and for different beam energies. Not all of the theoretical models are able to reproduce the observed longitudinal scaling of elliptic flow [2]. For example, the AMPT (a multiphase transport model, ver 1.11) [3] and UrQMD (ultrarelativistic quantum molecular dynamics, ver 2.3) [4] do not reproduce the experimentally observed scaling of elliptic flow. While the AMPT with string melting and the Buda-Lund model, based on an analytic solution of perfect fluid dynamics, can reproduce experimental data [5].

Landau's approximate hydrodynamic solution for particle production in relativistic heavy-ion reactions [6,7] was formulated in 1953, but even today gets a lot of attention and reproduces well the rapidity spectrum of observed particles in the relativistic nuclear collisions [8]. In recent studies $[9,10]$ the particle production function for different rapidities was slightly modified compared to the original version to the following form:

$$
\begin{equation*}
\mathrm{d} N / \mathrm{d} y \propto \exp \sqrt{\left(y_{\text {beam }}^{2}-y^{2}\right)} \tag{1}
\end{equation*}
$$

where $y_{\text {beam }}=\ln \left(\sqrt{s_{N N}} / m_{N}\right)$ is the beam rapidity. In order to make a comparison with experimental particle spectra, one has to normalize the distribution with the total

[^0]number of particles, which is unknown from the Landau solution. The key reason lies in the fact that the Landau solution does not conserve total energy, thus the total entropy of the system cannot be obtained, which leads to an unknown number of produced particles $N_{t o t}$. Anyway, the solution of perfect fluid dynamics (1) gives the right shape of the rapidity distribution for different relativistic energies. On the other hand, from the definition of the elliptic flow,
\[

$$
\begin{equation*}
v_{2}(y)=\frac{\int \mathrm{d} \phi(\mathrm{~d} N / \mathrm{d} \phi \mathrm{~d} y) \cos (2 \phi)}{\int \mathrm{d} \phi(\mathrm{~d} N / \mathrm{d} \phi \mathrm{~d} y)} \tag{2}
\end{equation*}
$$

\]

one can easily see that normalization of total particle production is not needed. So, the task is to modify the approximate solution of Landau, including the transverse angle $\phi$ dependence in the solution.

In this study the analytic solution for relativistic hydrodynamic equations will be presented. In sect. 2 the longitudinal expansion will be summarized for the sake of completeness of the study, even though the same results can be found elsewhere. The transverse part of the solution with asymmetrical pressure-gradient-driven expansion is presented in sect. 3. The last section presents the initial state and obtained results.

The presented solution is approximate, but in comparison to the computational hydrodynamics is analytic and transparent. The main assumptions of the model coincides with original Landau approximations and are as follows: i) longitudinal and transverse parts of hydrodynamic equations are solved separately; ii) the equation of state of ideal relativistic gas, $P=e / 3$, is used to solve transport equations; iii) transverse expansion does not include initial flow and is pressure gradient driven.

## 2 Longitudinal expansion

In this model we solve the equations of energy-momentum conservation:

$$
\begin{equation*}
\partial_{\mu} T^{\mu \nu}=0 \tag{3}
\end{equation*}
$$

where the energy-momentum tensor reads as

$$
\begin{equation*}
T^{\mu \nu}=(e+P) u^{\mu} u^{\nu}-P g^{\mu \nu} . \tag{4}
\end{equation*}
$$

The solution of local conservation laws (eq. (3)) with the equation of state represents the dynamics of the system by relating bulk properties of the matter, such as energy density, $e$, local pressure, $P$ and the four-flow of the fluid, $u^{\mu}=u^{0}(1, \boldsymbol{v})$. The equations of the hydrodynamic longitudinal expansion in $1+1$ dimension, along the $z$-axis reads as

$$
\begin{equation*}
\frac{\partial T^{00}}{\partial t}+\frac{\partial T^{0 z}}{\partial z}=0, \quad \frac{\partial T^{0 z}}{\partial t}+\frac{\partial T^{z z}}{\partial z}=0 \tag{5}
\end{equation*}
$$

The details on how to solve the above equations can be found in $[6,7,9-12]$, so, here, we present the derivation shortly, including only the main equations and the result, as we will need it later.

The solution of the equations of hydrodynamics (5) starts by transforming relativistic velocity field components to rapidity terms as

$$
\begin{equation*}
u^{0}=\cosh y, \quad u^{z}=\sinh y . \tag{6}
\end{equation*}
$$

From the above transformation, it naturally follows that $v_{z}=\tanh y$ and $\left(u^{z}\right)^{2}-\left(u^{0}\right)^{2}=-1$. In order to solve the hydrodynamic equations (5), the following variables are introduced:

$$
\kappa=\ln w, \quad w=e+p, \quad \chi=\psi-w u_{z} z-w u_{0} t
$$

where $\chi$ is called the Khalatvikov potential, $\psi$ is hydrodynamic potential, which is defined by the relation $w u_{i}=$ $\frac{\partial \psi}{\partial x^{2}}$, where $\psi$ is a function of coordinates and time. And, $w=e+P$ is the enthalpy. Using the relation for sound velocity as

$$
c_{s}^{2}=\frac{n}{w} \frac{\partial w}{\partial n}
$$

where $c_{s}^{2}=1 / 3$ for the ideal relativistic gas equation of state [13]. After the Legendre transformation to the hodograph plane, the Chaplygin equation for supersonic expansion reads as

$$
\begin{equation*}
c_{s}^{2} \frac{\partial^{2} \chi}{\partial \kappa^{2}}+\left(1-c_{s}^{2}\right) \frac{\partial \chi}{\partial \kappa}-\frac{\partial^{2} \chi}{\partial y^{2}}=0 \tag{7}
\end{equation*}
$$

A detailed investigation on the solution of the $(1+1)$ dimensional perfect-fluid hydrodynamics can be found in $[14-16]$. The solution for above equation reads

$$
\begin{align*}
& t=e^{-\kappa}\left(\frac{\partial \chi}{\partial \kappa} \cosh y-\frac{\partial \chi}{\partial y} \sinh y\right)  \tag{8}\\
& z=e^{-\kappa}\left(\frac{\partial \chi}{\partial \kappa} \sinh y-\frac{\partial \chi}{\partial y} \cosh y\right) \tag{9}
\end{align*}
$$

The transformation back to the $(t, z)$ coordinates is shorter with the following new variables:

$$
\begin{equation*}
y_{+}=\ln ((t+z) / \Delta), \quad y_{-}=\ln ((t-z) / \Delta) \tag{10}
\end{equation*}
$$

where $\Delta$ is the initial thickness of the system in the beam direction, $z$. Also, $\Delta$ is the initial condition after which the equation of state is assumed to be valid and evolution equations (5) are applied.

The final solution for energy density, $e\left(y_{+}, y_{-}\right)$, and rapidity, $y\left(y_{+}, y_{-}\right)$, is

$$
\begin{align*}
& e\left(y_{+}, y_{-}\right)=e_{0} \exp \left[-4 / 3\left(y_{+}+y_{-}-\sqrt{y_{+} y_{-}}\right)\right]  \tag{11}\\
& y\left(y_{+}, y_{-}\right)=\left(y_{+}-y_{-}\right) / 2 \tag{12}
\end{align*}
$$

where $z=t \tanh y$. The above solution of ( $1+1$ )-dimensional relativistic hydrodynamics equation (5) will be connected to the solution of transverse expansion, in order to obtain multiplicities of produced particles for different rapidities.

## 3 Transverse expansion

In order to solve the transverse part of hydrodynamic equations (3), we will follow the original Landau assumptions with some modifications. For simplicity, polar coordinates will be used, where the four-flow components in polar coordinates are $u_{i}=\mathrm{d} x_{i} / \mathrm{d} t, u_{0}=\left(1-\left(\frac{\mathrm{d}}{\mathrm{d} t} r^{2}+\right.\right.$ $\left.\left.r^{2} \frac{\mathrm{~d}}{\mathrm{~d} t} \phi^{2}\right)\right)^{-1 / 2}, u_{r}=u_{0} v_{r}$ and energy-momentum tensor (4) components are as follows:

$$
\begin{array}{ll}
T^{r r}=(e+P)\left(u^{0}\right)^{2} v_{r}^{2}+P, & T^{\phi \phi}=(e+P)\left(u^{0}\right)^{2} v_{\phi}^{2}+P / r^{2} \\
T^{0 r}=(e+P)\left(u^{0}\right)^{2} v_{r}, & T^{0 \phi}=(e+P)\left(u^{0}\right)^{2} v_{\phi}
\end{array}
$$

Assuming that the transverse velocity is radial, $v_{\phi}=0$, the hydrodynamic equation (3) for the transverse dynamics at the fixed transverse angle $\phi$ becomes

$$
\begin{equation*}
\frac{\partial T^{0 r}}{\partial t}+\frac{\partial T^{r r}}{\partial r}=0 . \tag{13}
\end{equation*}
$$

Inserting energy-momentum tensor expressions in the above equation and using the ideal-gas equation of state, $P=e / 3$, one gets

$$
\begin{equation*}
4 e\left(u^{0}\right)^{2} \frac{\partial v_{r}}{\partial t}+4 e\left(u^{0}\right)^{2} \frac{\partial v_{r}^{2}}{\partial r}+\frac{\partial e}{\partial r}=0 . \tag{14}
\end{equation*}
$$

Following the original Landau derivation, the fist term in the above equation is an acceleration dependence, and is assumed to be equal to $\partial v_{r} / \partial t=2 r(t) / t^{2}$. The second term is set to zero, $v_{r}$ being comparatively small. To simplify the third term, Landau used $\partial e / \partial r \approx-e / R_{A}$, because the energy density at the center has value $e$ and is zero at the edge of the system, $r=R_{A}$. In the case of peripheral collisions, we do not expect centrally symmetric energy density distribution, thus the assumption is modified as

$$
\begin{equation*}
\frac{\partial e}{\partial r}=\frac{e\left(r=R_{\phi}\right)-e(r=0)}{R_{\phi}} \tag{15}
\end{equation*}
$$

where $R_{\phi}$ is a transverse radius of the system, which changes with the angle, as the system is not centrally symmetric. We do not know the value of $e\left(R_{\phi}\right)$, so we introduce a new function, $f\left(R_{\phi}\right)=e\left(r=R_{\phi}\right) / e(r=0)$, which is a fraction of energy density at the edge of the system with respect to the energy density at the center. In this way, the function $f\left(R_{\phi}\right)$ must be less than unity for any angle $\phi$, as the energy density at the center is higher than at the edge. This modification from the original Landau assumption plays an important role, as it involves transverse asymmetry to the solution by making a different transverse pressure gradient for different $\phi$ angles. Now, from eq. (14), we express the transverse displacement dependence on time as

$$
\begin{equation*}
r(t)=\frac{\left(1-f\left(R_{\phi}\right)\right) t^{2}}{8\left(u^{0}\right)^{2} R_{\phi}} \tag{16}
\end{equation*}
$$

The last stage of the model is the so-called conic-flight stage, where energy and entropy fluxes stop changing for the fixed cone element $2 \pi r \mathrm{~d} r$. This stage coincides with the kinetic Freeze-Out (FO), as the model does not include any hadronic re-interactions after the evolution stops. With the help of formula (16) we obtain a hypersurface in space-time, after which the hydrodynamic flow stops and matter streams freely towards detectors. Here, again, we follow the original Landau model, assuming a fixed transverse distance, $r\left(t_{F O}\right)=a=2 R_{A}$, for the conic flight to start at the distance of the nuclear diameter. Thus, we obtain the value for the time, when the conic-flight starts, which reads as

$$
\begin{equation*}
t_{F O}=2 \cosh y \sqrt{\frac{2 a R_{\phi}}{\left(1-f\left(R_{\phi}\right)\right)}} \tag{17}
\end{equation*}
$$

where the relation $u^{0}=\cosh y$ was used.
The solution in the conic-flight stage is straightforward, as the energy and entropy does not change at a fixed cone element. The transverse and longitudinal solutions are matched at the time $t=t_{F O}$. Knowing that $\mathrm{d} S=s u^{0} \mathrm{~d} z$ at a given time within element $\mathrm{d} z$, and that the entropy density is $s=c e^{3 / 4}$, we can express the entropy change over rapidity from the energy density formula (11) as

$$
\begin{equation*}
\frac{\mathrm{d} S}{\mathrm{~d} y}=c e_{0}^{3 / 4} \exp \left[-\left(y_{+}+y_{-}-\sqrt{y_{+} y_{-}}\right)\right] \frac{t}{\cosh y} \tag{18}
\end{equation*}
$$

Inserting the solution for the FO time equation (17) into the entropy equation above and assuming that the number of produced particles is directly proportional to the entropy, $\mathrm{d} N \propto \mathrm{~d} S$, one can obtain the number of particles for different rapidities at a fixed angle $\phi$. However, the function $f\left(R_{\phi}\right)$ and initial thickness $\Delta$ is still needed.

## 4 Initial conditions and results

As is natural for hydrodynamics, the initial state is based on the predictions from other models. In this case the
widely accepted and analytically simple Wounded Nucleon (WN) model [17] will be used to parametrize initial conditions. It is based on the Woods-Saxon nuclear density parametrization [18], as follows:

$$
\begin{equation*}
\rho_{A}(\mathbf{r})=\frac{\rho_{0}}{1+\exp \left(\frac{\mathbf{r}-R_{A}}{d}\right)}, \tag{19}
\end{equation*}
$$

which is continuous and can be straightforwardly connected to the Landau equations. The main requirement for the initial conditions and new function $f\left(R_{\phi}\right)$ is that for the central collision case, $b=0$, the result must be equal to the original Landau one. Moreover, the WN model connects the impact parameter $b$ with the number of participating nucleons, $N_{\text {part }}$, and the number of binary collisoins, $N_{\text {coll }}$, making the comparisons with the experimental data easy.

The density of wounded nucleons in the transverse plane and in polar coordinates, $(r, \phi)$, can be obtained by:

$$
\begin{aligned}
n_{W N}(r, \phi)= & T_{A}(r, \phi)\left[1-\left(1-\frac{\sigma T_{B}(r, \phi)}{B}\right)^{B}\right] \\
& +T_{B}(r, \phi)\left[1-\left(1-\frac{\sigma T_{A}(r, \phi)}{A}\right)^{A}\right]
\end{aligned}
$$

Here and everywhere else the vector $r$ starts at the center of the almond-shaped system of interest. The thickness functions are then expressed as

$$
\begin{aligned}
& T_{A}(r, \phi)=T_{A}(x-b / 2, y)=\int \mathrm{d} z \rho_{A}(\mathbf{r}) \\
& T_{B}(r, \phi)=T_{B}(x+b / 2, y)=\int \mathrm{d} z \rho_{B}(\mathbf{r})
\end{aligned}
$$

using a Woods-Saxon parametrization (19) with $R_{A}=$ $1.12 A^{1 / 3}-0.86 A^{-1 / 3}[\mathrm{fm}], d=0.54[\mathrm{fm}]$ and $n_{0}=$ $0.17 \mathrm{fm}^{-3}$.

Now, assuming that the energy density is proportional to the WN density [19]: $e(r, \phi ; b) \propto n_{W N}(r, \phi ; b)$, the function $f\left(R_{\phi}\right)$ can be obtained. It is, by definition, the ratio of energy density at the edge of the system to the energy density at the center, for a fixed impact parameter $b$ and reads as

$$
\begin{equation*}
f\left(R_{\phi}\right)=\frac{n_{W N}\left(R_{\phi}, \phi ; b\right)-\min \left(n_{W N}\left(R_{\phi}, \phi ; b\right)\right)}{n_{W N}(0,0 ; b)} \tag{20}
\end{equation*}
$$

The radius of the system, $R_{\phi}$, is dependent on the angle $\phi$ and is obtained from the geometry of two overlapping circles as: $R_{\phi}^{2}+R_{\phi} b \cos \phi+\frac{b^{2}}{4}-R_{A}^{2}=0$. The term $\min \left(n_{W N}\left(R_{\phi}, \phi ; b\right)\right)$ is a minimal density at the edge of the system and is used in order to have the original Landau solution for $R_{\phi}=R_{A}$, so that $f\left(R_{A}\right)=0$. Because Landau originally used a "sharp sphere" picture, assuming that the energy density is zero at the edge of the system while solving (14). In the case of the Woods-Saxon model, the density (19) at the edge of the nucleus at $r=R_{A}$ is


Fig. 1. Elliptic flow dependence on (pseudo)rapidity for AuAu and $\mathrm{Cu}-\mathrm{Cu}$ for two different collision energies $\sqrt{s_{N N}}=$ 62.4 GeV and 200 GeV and for different centralities as indicated in the figure. The model outcome is on the top, while data from RHIC experiments [20] and [21] are on the bottom.
not zero, so the minimal value is subtracted. Now, the acceleration term in (14) is the same in central collision and in Landau, but for peripheral collisions the acceleration does depend on the angle $\phi$.

Finally, to calculate the elliptic flow (2) one should merge equations (10), (17), (18), (20) and the initial longitudinal thickness $\Delta$, which for the peripheral collisions is expressed as

$$
\begin{equation*}
\Delta(\phi)=\kappa_{\phi} R_{A} / \gamma \tag{21}
\end{equation*}
$$

where $\kappa_{\phi}=\sqrt{n_{W N}\left(R_{\phi}, \phi ; b\right) / \max \left(n_{W N}\left(R_{\phi}, \phi ; b\right)\right)}$. It means that the longitudinal expansion (5) starts with an azimuthally asymmetric initial thickness, which is wider where the initial nuclear density is higher. The term $\max \left(n_{W N}\left(R_{\phi}, \phi ; b\right)\right)$ is used in order to have $\kappa_{\phi}(b=0)=1$ for the central collision case. The energy dependence on the initial state is found via the Lorentz gamma factor, $\gamma=\sqrt{s_{N N}} / 2 m_{\text {proton }}$. The obtained results are shown in fig. 1 for reactions of $\mathrm{Au}-\mathrm{Au}$ at $b=6 \mathrm{fm}$ and $\mathrm{Cu}-\mathrm{Cu}$ at $b=3 \mathrm{fm}$ for two different beam energies, as observed at RHIC. One can easily see that the model does predict the longitudinal scaling, but it does not correspond well to the experimental data. The latter can be explained by the lack of realistic Freeze-Out dynamics and hadronic re-interactions in the model. Moreover, the initial state is chosen to be as simple and transparent as possible, in
order to show pure hydrodynamic effects for a system with transverse asymmetry and does not include initial-state fluctuations. The initial energy density distribution $f\left(R_{\phi}\right)$ and initial longitudinal thickness $\Delta(\phi)$ might be based on more sophisticated models, but, for now, we can conclude that Landau hydrodynamic solution and its assumptions work not only for particle multiplicity spectra, but for elliptic flow and elliptic flow longitudinal scaling as well.

The generalized solution of Landau hydrodynamics incorporates transverse asymmetries into the initial configuration and can be compared to a wide amount of experimental data, giving deeper insight into the early dynamics of the system.

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