# Conformality of a differential with respect to Cheeger-Gromoll type metrics 

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#### Abstract

We investigate conformality of the differential of a mapping between Riemannian manifolds if the tangent bundles are equipped with a generalized metric of CheegerGromoll type.


Keywords Conformal mappings • Cheeger-Gromoll type metrics •
Second standard immersion
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## 1 Introduction and preliminaries

Generalized metrics of Cheeger-Gromoll type or $(p, q)$-metrics $h_{p, q}$, being a generalization of Sasaki metric $h_{S}$ [5] and Cheeger-Gromoll metric $h_{C G}$ [4], have been recently introduced by Benyounes et al. in [1] in the context of harmonic sections. In [2], the same authors studied the geometry of the tangent bundle equipped with this kind of metric. It is worth noticing that Munteanu in [7] investigated independently the geometry of tangent bundle equipped with a certain deformation of Cheeger-Gromoll metric other that in [1]. Yet in [6], Walczak and the first named author considered ( $p, q$ )-metrics in the context of Riemannian submersions and Gromov-Hausdorff topology.

In this paper we introduced ( $p, q, \alpha$ )-metrics which are more general than $(p, q)$-metrics. (In contrast to [1] we do not assume that $p, q$ and $\alpha$ are constant). We investigate relations between conformality of a map $\varphi:(M, g) \rightarrow\left(M^{\prime}, g^{\prime}\right)$ between Riemannian manifolds and its differential $\Phi=\varphi_{*}:(T M, h) \rightarrow\left(T M^{\prime}, h^{\prime}\right)$ between their tangent bundles equipped with $(p, q, \alpha)$-metric $h$ and $(r, s, \beta)$-metric $h^{\prime}$, respectively.

[^0]Interesting enough, there is essential difference between the cases $\operatorname{dim} M=2$ and $\operatorname{dim} M \geq 3$.

We prove that in the second case (Theorem 1) $\Phi$ is conformal if and only if $\varphi$ is a homothety and totally geodesic immersion and some special relations between triples ( $p, q, \alpha$ ) and $(r, s, \beta)$ hold. In this case $\Phi$ is also a homothety with the same dilatation as $\varphi$.

However, in the first case it may happen that $\Phi$ is conformal, although $\varphi$ is not a totally geodesic immersion (Theorem 2). Then $\Phi$ is no longer a homothety. An example of such a map is given.

### 1.1 Cheeger-Gromoll type metrics

Consider a Riemannian manifold $(M, g)$, and let $\pi: T M \rightarrow M$ be its tangent bundle. The Levi-Civita connection $\nabla$ of $g$, gives a natural splitting $T(T M)=\mathcal{H} \oplus \mathcal{V}$ of the second tangent bundle $\pi_{*}: T(T M) \rightarrow T M$, where the vertical distribution $\mathcal{V}$ is the kernel of $\pi_{*}$, and the horizontal distribution is the kernel of, so called, connection map $K$. If $X, Z \in T_{x} M$ then by $X_{Z}^{v}$ we denote the vertical lift of $X$ to the point $Z$, i.e., $X_{Z}^{v}$ is a tangent vector to the curve $t \mapsto Z+t X$ at $t=0$. Every $A \in T_{Z}(T M)$ can be uniquely written as $A=\mathcal{H} A+\mathcal{V} A$, where $\mathcal{H} A \in \mathcal{H}_{Z}$ and $\mathcal{V} A \in \mathcal{V}_{Z}$ denote its horizontal and vertical part respectively. The vertical part of $A$ is given by $(K A)_{Z}^{v}$.

Recall that $K$ is a smooth $\mathbb{R}$-linear bundle morphism determined by the conditions:
(K1) For every $Z \in T M, K: T_{Z}(T M) \rightarrow T_{\pi(Z)} M$ is the canonical isomorphism, i.e., $K\left(X_{Z}^{v}\right)=X$.
(K2) For every vector field $X$ on $M$ and every $v \in T_{x} M, K\left(X_{*} v\right)=\nabla_{v} X$.
Notice that (K1) and (K2) imply the following properties
(K3) For every Riemannian manifold ( $M^{\prime}, g^{\prime}$ ) and every $X, Z \in T_{x} M$ and every map $\varphi: M \rightarrow M^{\prime}, \varphi_{* *} X_{Z}^{v}=\left(\varphi_{*} X\right)_{\varphi_{*}(Z)}^{v}$.
(K4) For every curve $\gamma$ in $M$ and every vector field $\xi$ along $\gamma, K(\dot{\xi})=\nabla_{\dot{\gamma}} \xi$.
Let $p, q, \alpha$ be smooth functions on $M$. Assume $q$ is non-negative and $\alpha$ is positive. Define ( $p, q, \alpha$ )-metric $h=h_{p, q, \alpha}$ on $T M$ as follows: For every $A, B \in T_{Z}(T M), Z \in T_{x} M$,

$$
h(A, B)=g\left(\pi_{*} A, \pi_{*} B\right)+\omega_{\alpha}(Z)^{p}(g(K A, K B)+q g(K A, Z) g(K B, Z)),
$$

where $\omega_{\alpha}(Z)=(1+\alpha g(Z, Z))^{-1}$. Here all functions $p, q, \alpha$ are evaluated at $x$. For any $p, q, \alpha$, the Riemannian metric $h_{p, q, \alpha}$ is a special case of a metric considered in [7]. Notice that if $p, q, \alpha$ are constants and $\alpha=1$ then $h_{p, q, \alpha}$ becomes a metric from [1]. In particular, $h_{0,0,1}$ (resp. $h_{1,1,1}$ ) is Sasaki metric $h_{S}$ [5] (resp. Cheeger-Gromoll metric $h_{C G}$ [4]).

### 1.2 Conformal mappings and metrics

Recall that a map $\varphi:(M, g) \rightarrow\left(M^{\prime}, g^{\prime}\right)$ between Riemannian manifolds is conformal if $\varphi^{*} g^{\prime}=\lambda g$ for some positive function $\lambda$ on $M$. The function $\lambda$ is called a dilatation. A conformal mapping with constant dilatation is called a homothety. If $\operatorname{dim} M<\operatorname{dim} M^{\prime}$ a conformal mapping $\varphi$ is often called weakly conformal.

Let $\lambda$ be a strictly positive $C^{\infty}$-function on $M$, and $g^{\lambda}=\lambda g$. The Levi-Civita connections $\nabla$ and $\nabla^{\lambda}$ of $g$ and $g^{\lambda}$ are related as follows: $\nabla^{\lambda}=\nabla+S_{M}^{g, \lambda}$ where $S=S_{M}^{g, \lambda}$ is a symmetric
(1, 2)-tensor field given by (compare [3], p. 64):

$$
S(X, Y)=\frac{1}{2 \lambda}((X \lambda) Y+(Y \lambda) X-g(X, Y) \operatorname{grad} \lambda), \quad X, Y \in \Gamma(M, T M)
$$

Suppose $\varphi: M \rightarrow M^{\prime}$ is an immersion, e.g., conformal mapping. Then for every $x \in M$ we may choose an open neighbourhood $U_{x}$ of $x$ such that $L_{x^{\prime}}=\varphi\left(U_{x}\right)\left(x^{\prime}=\varphi(x)\right)$ is a regular submanifold of $M^{\prime}$. Let $j: L_{x^{\prime}} \rightarrow M^{\prime}$ be the inclusion map, and let $\bar{g}=j^{*} g^{\prime}$ be the induced metric tensor on $L_{x^{\prime}}$. Moreover, let $\Pi$ denote the second fundamental form of $L_{x^{\prime}}$. We say that the immersion $\varphi:(M, g) \rightarrow\left(M^{\prime}, g^{\prime}\right)$ is totally geodesic if for every $x \in M, L_{x^{\prime}}$ is a totally geodesic submanifold of $\left(M^{\prime}, g^{\prime}\right)$. One can prove the following

Lemma 1 Suppose $\varphi:(M, g) \rightarrow\left(M^{\prime}, g^{\prime}\right)$ is a conformal mapping with a dilatation $\lambda$. Choose $x \in M$ and put $x^{\prime}=\varphi(x)$. Let $\gamma:(-\epsilon, \epsilon) \rightarrow L_{x^{\prime}}$ be a curve in $M$ and $\xi$ be a vector field along $\gamma$. Put $\gamma^{\prime}=\varphi \circ \gamma$ and $\xi^{\prime}=\varphi_{*} \xi$. Then

$$
\bar{\nabla}_{\dot{\gamma}^{\prime}} \xi^{\prime}=\varphi_{*} \nabla_{\dot{\gamma}} \xi+\varphi_{*} S(\dot{\gamma}, \xi)
$$

where $S=S_{M}^{g, \lambda}$, and $\nabla$ and $\bar{\nabla}$ are the Levi-Civita connections of $g$ and $\bar{g}$ respectively.
Adopt the notations from Lemma 1. Put $Z=\xi(0), Z^{\prime}=\xi^{\prime}(0), v=\dot{\gamma}(0)$ and $v^{\prime}=\dot{\gamma}^{\prime}(0)$. Suppose that a vector $A \in T_{Z}(T M)$ is tangent to the curve $\xi$ (it is convenient to think of vector fields along curves as of curves in the tangent bundle), i.e., $A=\dot{\xi}(0)$. Next, let $K$ and $K^{\prime}$ denote connection maps induced from $\nabla$ and $\nabla^{\prime}$ respectively. Moreover put $\Phi=\varphi_{*}: T M \rightarrow T M^{\prime}$. As a direct consequence of Lemma 1, the equation $\nabla^{\prime}=\nabla+\Pi$ and properties of connection map we get

Lemma 2 The vectors $K(A)$ and $K^{\prime}\left(\Phi_{*} A\right)$ are related as follows:

$$
K^{\prime}\left(\Phi_{*} A\right)=\varphi_{*} K(A)+\varphi_{*} S(v, Z)+\Pi\left(v^{\prime}, Z^{\prime}\right)
$$

In particular, if $A$ is horizontal then $K^{\prime}\left(\Phi_{*} A\right)=\varphi_{*} S(v, Z)+\Pi\left(v^{\prime}, Z^{\prime}\right)$.
Remark 1 If $\operatorname{dim} M=\operatorname{dim} M^{\prime}$ then the term $\Pi$ is omitted.
Let $U=U_{x}$ and $L^{\prime}=L_{x^{\prime}}$ and let $\pi^{\prime}: T L^{\prime} \rightarrow L^{\prime}$ be a natural projection. Since $\varphi: U \rightarrow L^{\prime}$ is a conformal diffeomorphism, so is its inverse. In particular $\Phi: T U \rightarrow T L^{\prime}$ is a diffeomorphism. Therefore we have

Corollary 1 Take $A^{\prime} \in T_{Z^{\prime}}\left(T L^{\prime}\right)$ such that $v^{\prime}=\pi^{\prime}{ }_{*} A$. Then

$$
K\left(\Phi_{*}^{-1} A^{\prime}\right)=\varphi_{*}^{-1} K^{\prime}\left(A^{\prime}\right)+\varphi_{*}^{-1} S^{\prime}\left(v^{\prime}, Z^{\prime}\right)-\varphi_{*}^{-1} \Pi\left(v^{\prime}, Z^{\prime}\right),
$$

or equivalently

$$
K\left(\Phi_{*}^{-1} A^{\prime}\right)=\varphi_{*}^{-1} \bar{K}\left(A^{\prime}\right)+\varphi_{*}^{-1} S^{\prime}\left(v^{\prime}, Z^{\prime}\right),
$$

where $S^{\prime}=S_{L^{\prime}}^{\bar{g}, \mu}$ with $\mu=(1 / \lambda) \circ \varphi^{-1}$, and $\bar{K}$ is the connection map induced from $\bar{\nabla}$.
Corollary 2 Suppose $\varphi:(M, g) \rightarrow\left(M^{\prime}, g^{\prime}\right)$ is a conformal mapping and $M$ is connected. $\Phi_{*}$ maps horizontal vectors onto horizontal vectors if and only if $\varphi$ is a totally geodesic homothety.

Proof $(\Rightarrow)$ If $\Phi_{*}$ maps horizontal vectors onto horizontal vectors then by Lemma 2, $\varphi_{*}$ $S+\Pi$ vanishes identically. Since $\varphi_{*} S$ and $\Pi$ are always orthogonal and a conformal mapping is an immersion it follows that $S$ and $\Pi$ vanish identically. Applying the definition of $S$ with $X=Y=\operatorname{grad} \lambda$, we get that $\operatorname{grad} \lambda$ is the zero vector field. Consequently, $\lambda$ is constant and therefore $\varphi$ is a homothety. Since $\Pi$ vanishes, $\varphi$ is totally geodesic.
$(\Leftarrow)$ Obvious.

### 1.3 Algebraic lemmas

Suppose two finite dimensional real vector spaces $V$ and $W$ equipped with inner products $\langle,\rangle_{V}$ and $\langle,\rangle_{W}$ are given. Let $B: V \times V \rightarrow W$ be a symmetric, bilinear form on $V$. Moreover, let $C \geq 0$. Consider a condition

$$
\begin{equation*}
\langle B(X, Z), B(Y, Z)\rangle_{W}=C\langle X, Y\rangle_{V}\langle Z, Z\rangle_{V} . \tag{1}
\end{equation*}
$$

for every $X, Y, Z \in V$. Then, if $X, Y$ are orthogonal

$$
\begin{equation*}
\langle B(X, X), B(Y, Y)\rangle_{W}=-C\langle X, X\rangle_{V}\langle Y, Y\rangle_{V} . \tag{2}
\end{equation*}
$$

Lemma 3 Assume that B satisfies the condition (1). If $\operatorname{dim} V \geq 3$ then $C=0$. In particular, $B$ vanishes.

Proof Suppose that $C \neq 0$. Take an orthonormal pair $X, Y$. Let $\xi=B(X, X)$ and $\zeta=$ $B(Y, Y)$. By (1) we have

$$
\begin{equation*}
\langle\xi, \xi\rangle=\langle\zeta, \zeta\rangle=C>0 . \tag{3}
\end{equation*}
$$

In particular, $\xi \neq 0$ and $\zeta \neq 0$. Applying (2) we see that

$$
\langle\xi, \zeta\rangle=-C .
$$

Using above and (3) one can obtain that $\xi=-\zeta$. Next, since $\operatorname{dim} V \geq 3$ we may find $Z \in V$ such that $X, Y, Z$ is an orthonormal triple. Let $\eta=B(Z, Z)$. Then, by above $\xi=-\zeta=\eta=-\xi$, which contradicts the fact that $\xi \neq 0$.

Notice that the assumption $\operatorname{dim} V \geq 3$ is essential. Namely we have
Lemma 4 (a) A symmetric bilinear form $B: \mathbb{R}^{2} \times \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ satisfies (1) if and only if there exists an angle $\theta$ such that

$$
\begin{equation*}
B(X, Y)= \pm \sqrt{C} e^{i \theta} X Y \quad \text { or } \quad B(X, Y)= \pm \sqrt{C} e^{i \theta} \bar{X} \bar{Y}, \tag{4}
\end{equation*}
$$

where we identify $\mathbb{R}^{2}$ with $\mathbb{C}$.
(b) If $\operatorname{dim} V=2$ and a non-zero symmetric bilinear form $B: V \times V \rightarrow W$ satisfies the condition (1) then there exists a 2-dimensional subspace $U$ of $W$ such that the image of $B$ is equal to $U$ and with respect to orthonormal bases of $V$ and $U, B$ is of the form (4).

Proof (a) Elementary exercise. (b) Take an orthonormal basis $X, Y$ of $V$. Since $B \neq 0$, we have $C \neq 0$. Consequently, $\xi=B(X, X), \zeta=B(Y, Y)$ and $\eta=B(X, Y)$ are nonzero vectors of $W$ of length $\sqrt{C}$. By (1) we see that $\langle\xi, \eta\rangle=\langle\zeta, \eta\rangle=0$. Moreover, $\langle\xi, \zeta\rangle=-C$,
by (2). It follows that $\xi=-\zeta$. Consequently, the image $U$ of $B$ is a two-dimensional subspace spanned by $\xi, \eta$.

Now taking orthonormal bases of $V$ and $U$, e.g., $X, Y$ and $\xi / \sqrt{C}, \eta / \sqrt{C}$, we reduce (b) to (a).

## 2 Conformality of a differential

In this section all manifolds are connected. Let $(M, g)$ and $\left(M^{\prime}, g^{\prime}\right)$ be Riemannian manifolds of dimensions $m$ and $m^{\prime}$, respectively. We assume that $m, m^{\prime} \geq 2$. Denote by $\nabla$ and $\nabla^{\prime}$ the Levi-Civita connections of $g$ and $g^{\prime}$, respectively. Equip their tangent bundles $\pi: T M \rightarrow M$ and $\pi^{\prime}: T M^{\prime} \rightarrow M^{\prime}$ with $(p, q, \alpha)$-metric $h$ and $(r, s, \beta)$-metric $h^{\prime}$, respectively.

Let $\varphi: M \rightarrow M^{\prime}$ and $\Phi=\varphi_{*}: T M \rightarrow T M^{\prime}$. Put $g=\langle$,$\rangle and g^{\prime}=\langle,\rangle^{\prime}$. Denote by $|\cdot|$ and $|\cdot|^{\prime}$ the norms induced by $g$ and $g^{\prime}$, respectively. Moreover, denote by $\|\cdot\|$ and $\|\cdot\|^{\prime}$ the norms induced by $h$ and $h^{\prime}$, respectively.

In the paper we use the following notation: If $\varphi(\operatorname{resp} . \Phi)$ is conformal mapping then its dilatation will be always denoted by $\lambda$ (resp. $\Lambda$ ).

### 2.1 Technical lemmas

Lemma 5 Suppose that $\varphi$ and $\Phi$ are conformal mappings. Then for any $Z \in T_{x} M$ and $x^{\prime}=\varphi(x)$,

$$
\begin{align*}
\Lambda(Z) & =\lambda(x) \frac{\left(1+\alpha(x)|Z|^{2}\right)^{p(x)}}{\left(1+\lambda(x) \beta\left(x^{\prime}\right)|Z|^{2}\right)^{r\left(x^{\prime}\right)}}  \tag{5}\\
q(x) & =\lambda(x) s\left(x^{\prime}\right) \tag{6}
\end{align*}
$$

Proof Let $X, Z \in T_{x} M$. Applying conformality of $\Phi$ and (K3) we have: $\left\|\left(\varphi_{*} X\right)_{\varphi_{*}}^{v} Z\right\|^{2}=$ $\left\|\Phi_{*} X_{Z}^{v}\right\|^{\prime 2}=\Lambda(Z)\left\|X_{Z}^{v}\right\|^{2}$. Using now the definitions of $h$ and $h^{\prime}$ and conformality of $\varphi$, one can easily get

$$
\begin{equation*}
\lambda(x) \frac{|X|^{2}+\lambda(x) s\left(x^{\prime}\right)\langle X, Z\rangle^{2}}{\left(1+\lambda(x) \beta\left(x^{\prime}\right)|Z|^{2}\right)^{r\left(x^{\prime}\right)}}=\Lambda(Z) \frac{|X|^{2}+q(x)\langle X, Z\rangle^{2}}{\left(1+\alpha(x)|Z|^{2}\right)^{p(x)}} . \tag{7}
\end{equation*}
$$

Taking nonzero vector $X$ orthogonal to $Z$, (7) becomes (5). Next, let $Z \neq 0$. Putting $X=Z$ in (7) and comparing the result with (5) we get (6).

Lemma 6 If $\Phi$ is conformal then so is $\varphi$. Moreover $\lambda(x)=\Lambda\left(0_{x}\right), x \in M$.
Proof Let $x \in M$ and $Z=0_{x} \in T_{x} M$. By (K3) and conformality of $\Phi$, for every $X, Y \in T_{x} M$

$$
\begin{aligned}
\left\langle\varphi_{*} X, \varphi_{*} Y\right\rangle^{\prime} & =h^{\prime}\left(\left(\varphi_{*} X\right)_{\varphi_{*} Z}^{v},\left(\varphi_{*} Y\right)_{\varphi_{*} Z}^{v}\right) \\
& =\Lambda(Z) h\left(X_{Z}^{v}, Y_{Z}^{v}\right)=\Lambda(Z)\langle X, Y\rangle
\end{aligned}
$$

Lemma 7 Adopt the notation from Sect. 1.2. Suppose that $\varphi$ and $\Phi$ are conformal mappings. Then
(a) $\varphi$ is a homothety.
(b) For every $x \in M$ one of the following conditions holds:

$$
\begin{align*}
& p(x)=r\left(x^{\prime}\right)=0,  \tag{8}\\
& p(x)=r\left(x^{\prime}\right) \neq 0 \text { and } \lambda \beta\left(x^{\prime}\right)=\alpha(x),  \tag{9}\\
& p(x)=r\left(x^{\prime}\right)=1 \text { and } \lambda \beta\left(x^{\prime}\right) \neq \alpha(x),  \tag{10}\\
& p(x)=1 \text { and } r\left(x^{\prime}\right)=0 . \tag{11}
\end{align*}
$$

(c) Iffor every $x \in M$ either (8) or (9) holds then $\Phi$ is also a homothety with the dilatation $\Lambda=\lambda$. Moreover, $\varphi$ is totally geodesic.
(d) If (10) or (11) holds globally then for every $v, w, Z \in T_{x} M$

$$
\begin{equation*}
\left\langle\Pi\left(\varphi_{*} v, \varphi_{*} Z\right), \Pi\left(\varphi_{*} w, \varphi_{*} Z\right)\right\rangle^{\prime}=C\langle v, w\rangle\langle Z, Z\rangle, \tag{12}
\end{equation*}
$$

where $C=\lambda\left(\alpha(x)-\lambda \beta\left(x^{\prime}\right)\right) \neq 0$ in the case (10), and $C=\lambda \alpha(x) \neq 0$ in the case (11). In particular, $\varphi$ is not totally geodesic.

Proof Assume that $v \neq 0$. Take vectors $A \in T_{Z}(T M)$ and $A^{\prime} \in T_{Z^{\prime}}\left(T L^{\prime}\right)$ as in Lemma 1 and Corollary 1 . Moreover we may assume that $A$ and $A^{\prime}$ are horizontal with respect to $\nabla$ and $\bar{\nabla}$, respectively, i.e., $K(A)=0$ and $\bar{K}\left(A^{\prime}\right)=0$.

Put $U=U_{x}$ and $L^{\prime}=L_{x^{\prime}}$. Let $J: T L^{\prime} \rightarrow T M^{\prime}$ be the inclusion map. Put $\bar{h}=J^{*} h^{\prime}$. Since $\varphi:(U, g) \rightarrow\left(L^{\prime}, \bar{g}\right)$ and $\Phi:(T U, h) \rightarrow(T L, \bar{h})$ are conformal diffeomorphisms, so are $\varphi^{-1}:\left(L^{\prime}, \bar{g}\right) \rightarrow(U, g)$ and $\Phi^{-1}:\left(T L^{\prime}, \bar{h}\right) \rightarrow(T U, h)$. Dilatations of $\varphi^{-1}$ and $\Phi^{-1}$ are equal to $\mu=(1 / \lambda) \circ \varphi^{-1}$ and $\hat{\mu}=(1 / \Lambda) \circ \Phi^{-1}$, respectively. Thus we have

$$
\begin{aligned}
\left\|\Phi_{*} A\right\|^{\prime 2} & =\Lambda(Z)\|A\|^{2} \\
\left\|\Phi_{*}^{-1} A^{\prime}\right\|^{2} & =\hat{\mu}\left(Z^{\prime}\right)\left\|A^{\prime}\right\|^{\prime 2}
\end{aligned}
$$

Put for a while $S=S(v, Z), S^{\prime}=S^{\prime}\left(v^{\prime}, Z^{\prime}\right)$ and $\Pi^{\prime}=\Pi\left(v^{\prime}, Z^{\prime}\right)$. Since $\pi_{*} A=v$, $\pi^{\prime}{ }_{*} A^{\prime}=v^{\prime}, K(A)=0, K^{\prime}\left(A^{\prime}\right)=\bar{K}\left(A^{\prime}\right)+\Pi^{\prime}=\Pi^{\prime}$ and $Z^{\prime}$ is orthogonal to $\Pi^{\prime}$, we have

$$
\begin{aligned}
\|A\|^{2} & =|v|^{2} \\
\left\|A^{\prime}\right\|^{2} & =\left|v^{\prime}\right|^{\prime 2}+\omega_{\beta}\left(Z^{\prime}\right)^{r}\left|\Pi^{\prime}\right|^{2}
\end{aligned}
$$

Next applying Lemma 1 and Corollary 1, the equalities $\pi^{\prime}{ }_{*} \Phi_{*} A=v^{\prime}$ and $\pi_{*} \Phi_{*}^{-1} A^{\prime}=v$, and the fact that $\varphi_{*} S$ is orthogonal to $\Pi^{\prime}$ we get

$$
\begin{aligned}
\left\|\Phi_{*} A\right\|^{\prime 2} & =\left|v^{\prime}\right|^{2}+\omega_{\beta}\left(Z^{\prime}\right)^{r}\left(\lambda(x)|S|^{2}+s \lambda^{2}(x)\langle S, Z\rangle^{2}+\left|\Pi^{\prime}\right|^{\prime 2}\right) \\
\left\|\Phi_{*}^{-1} A^{\prime}\right\|^{2} & =|v|^{2}+\omega_{\alpha}(Z)^{p}\left(\mu\left(x^{\prime}\right)\left|S^{\prime}\right|^{\prime 2}+q \mu^{2}\left(x^{\prime}\right)\left\langle S^{\prime}, Z^{\prime}\right\rangle^{\prime 2}\right)
\end{aligned}
$$

Combining now above equalities and using the definitions of $\mu$ and $\hat{\mu}$ we get

$$
\begin{align*}
& \Lambda|v|^{2}=\left|v^{\prime}\right|^{\prime 2}+\omega_{\beta}\left(Z^{\prime}\right)^{r}\left(\lambda|S|^{2}+\lambda^{2}\langle S, Z\rangle^{2}+\left|\Pi^{\prime}\right|^{2}\right)  \tag{13}\\
& \frac{1}{\Lambda}\left(\left|v^{\prime}\right|^{\prime 2}+\omega_{\beta}\left(Z^{\prime}\right)^{r}\left|\Pi^{\prime}\right|^{\prime 2}\right)=|v|^{2}+\omega_{\alpha}(Z)^{p}\left(\frac{1}{\lambda}\left|S^{\prime}\right|^{\prime 2}+\frac{1}{\lambda^{2}}\left\langle S^{\prime}, Z^{\prime}\right\rangle^{\prime 2}\right) \tag{14}
\end{align*}
$$

where $\lambda=\lambda(x)$ and $\Lambda=\Lambda(Z)$. Multiplying equations (13) and (14) side by side we conclude that

$$
0=\omega_{\beta}\left(Z^{\prime}\right)^{r} \lambda|v|^{2}|S|^{2}+\text { non-negative expression. }
$$

Since $v \neq 0, S(v, Z)=0$. Since $x \in M, v, Z \in T_{x} M$ were arbitrary the tensor field $S$ vanishes identically. Therefore, $\lambda$ is a constant function and thus $\varphi$ is a homothety. Hence (a) is proved.

Substituting $S=0$ in (13) we get

$$
\left|\Pi\left(v^{\prime}, Z^{\prime}\right)\right|^{\prime 2}=\frac{\Lambda(Z)-\lambda}{\omega_{\beta}\left(Z^{\prime}\right)^{r}}|v|^{2}
$$

Applying Lemma 5 we get

$$
\begin{equation*}
\left|\Pi\left(\varphi_{*} v, \varphi_{*} Z\right)\right|^{\prime 2}=\lambda\left(\left(1+\alpha|Z|^{2}\right)^{p}-\left(1+\lambda \beta|Z|^{2}\right)^{r}\right)|v|^{2} . \tag{15}
\end{equation*}
$$

Using the facts that the map $(v, Z) \mapsto\left|\Pi\left(\varphi_{*} v, \varphi_{*} Z\right)\right|^{\prime 2}$ is non negative and symmetric with respect to $v, Z$, we conclude (b).

If (8) or (9) holds then by (5) it follows that $\Lambda=\lambda$. Moreover, in these cases (15) becomes $\left|\Pi\left(\varphi_{*} v, \varphi_{*} Z\right)\right|^{2}=0$. This proves (C).

If (10) or (11) holds then it is an elementary computation to check that $\Pi$ satisfies (12), proving (d).

Lemma 8 Suppose that $\operatorname{dim} M \geq 3$ or $\operatorname{dim} M^{\prime} \leq \operatorname{dim} M+1$. Then under the assumptions of Lemma 7 we have: $\varphi$ is totally geodesic homothety, $\Phi$ is a homothety and its dilatation $\Lambda$ is equal to $\lambda$.

Proof It suffices to show that under the assumptions the conditions (10) and (11) cannot hold. Then the assertion follows from Lemma 7 (a) and (c). Suppose that (10) or (11) holds. Then by Lemma 7 (d) it follows that the symmetric bilinear form $B: T_{x} M \times T_{x} M \rightarrow T_{x^{\prime}} M^{\prime}$ given by $B(v, w)=\Pi\left(\varphi_{*} v, \varphi_{*} w\right)$ satisfies the condition (1) with $C \neq 0$. If $\operatorname{dim} M \geq 3$ then we have a contradiction with Lemma 3, if $\operatorname{dim} M^{\prime} \leq \operatorname{dim} M+1$ then we have a contradiction with Lemma 4.

### 2.2 Main results

We begin with some definitions. Suppose $\bar{M}$ is a submanifold of a Riemannian manifold ( $M^{\prime}, g^{\prime}$ ). Suppose that a real-valued non-negative function $C$ on $\bar{M}$ is given. We say that $\bar{M}$ is optimal with a coefficient $C$ if for every $x^{\prime} \in \bar{M}$ the second fundamental form $\Pi$ of $\bar{M}$ at $x^{\prime}$ satisfies (1) with the constant $C\left(x^{\prime}\right)$ that is

$$
\langle\Pi(u, w), \Pi(v, w)\rangle=C\left(x^{\prime}\right)\langle u, v\rangle\langle w, w\rangle, \quad u, v, w \in T_{x^{\prime}} \bar{M} .
$$

In particular, every totally geodesic submanifold is optimal with the coefficient 0 . By Lemma 3 and Lemma 4 it follows that if $\operatorname{dim} \bar{M} \geq 3$ or $\operatorname{codim} \bar{M} \leq 1$ then each optimal submanifold is totally geodesic.

Remark 2 Observe that if $\varphi: M \rightarrow \bar{M}$ is a conformal diffeomorphism such that (12) holds then $\bar{M}$ is optimal with the coefficient $C /\left(\lambda \circ \varphi^{-1}\right)^{2}$.

Proposition 1 Suppose $\operatorname{dim} \bar{M}=2$. Denote by $\kappa^{\prime}$ and $\bar{\kappa}$ the sectional curvatures of $M^{\prime}$ and $\bar{M}$, and let $\sigma=T_{x^{\prime}} \bar{M}$. If $\bar{M}$ is optimal submanifold of $M^{\prime}$ with a coefficient $C$ then $\bar{M}$ is minimal submanifold of $M^{\prime}$ and $\bar{\kappa}(\sigma)=\kappa^{\prime}(\sigma)-2 C\left(x^{\prime}\right)$. In particular, if $C$ is constant and $M^{\prime}$ is a space of constant curvature then so is $\bar{M}$.

Proof The fact that $\bar{M}$ is minimal follows immediately from Lemma 4: it suffices to calculate the trace of the bilinear form given by (4). The second statement follows from (1), (2) and the Gauss Equation.

Suppose now that two Riemannian manifolds ( $M, g$ ) and ( $M^{\prime}, g^{\prime}$ ) are given and $\operatorname{dim} M \leq$ $\operatorname{dim} M^{\prime}$. Equip their tangent bundles $T M$ and $T M^{\prime}$ with $(p, q, \alpha)$-metric $h$ and $(r, s, \beta)$-metric $h^{\prime}$ respectively. Suppose next that the functions $p, q, r, s, \alpha, \beta$ are constant, and $\varphi: M \rightarrow$ $M^{\prime}$ is an imbedding (injective immersion). Let $\bar{M}=\varphi(M)$.

Theorem 1 Let $\operatorname{dim} M \geq 3$ or $\operatorname{dim} M^{\prime} \leq \operatorname{dim} M+1$.
(I) Suppose that $\varphi$ is a conformal mapping with a dilatation $\lambda$. Then $\Phi=\varphi_{\underline{*}}: T M \rightarrow$ $T M^{\prime}$ is conformal if and only if $q=\lambda\left(s \circ \varphi^{-1}\right), \varphi$ is a homothety, $\bar{M}$ is totally geodesic and for every $x \in M\left(x^{\prime}=\varphi(x)\right)$ one of the conditions (8) or (9) holds.
(II) If $\Phi$ is a conformal mapping then $\varphi$ and $\Phi$ are homotheties and $\Lambda=\lambda$.

Theorem 2 Let $\operatorname{dim} M=2$ and $\operatorname{dim} M^{\prime} \geq \operatorname{dim} M+2$.
(III) Suppose that $\varphi$ is a conformal mapping with a dilatation $\lambda$. Then $\Phi=\varphi_{*}: T M \rightarrow$ $T M^{\prime}$ is conformal if and only if $\varphi$ is a homothety, $q=\lambda\left(s \circ \varphi^{-1}\right), \bar{M}$ is optimal with the coefficient

$$
C=\frac{1}{\lambda}\left((p \alpha) \circ \varphi^{-1}-\lambda \beta r\right)
$$

and for every $x \in M\left(x^{\prime}=\varphi(x)\right)$ one of the properties (8)-(11) is satisfied.
(IV) Suppose $\Phi$ is a conformal mapping. Then $\varphi$ a homothety and
(IV1) If for every $x \in M$ one of the conditions (8) or (9) holds then $\Phi$ is also a homothety and $\Lambda=\lambda$.
(IV2) If one of the conditions (10) or (11) holds globally then $\varphi$ is a minimal immersion and for every plane $\sigma=\varphi_{*}\left(T_{x} M\right), x \in M$, the Gauss curvature $\kappa(\sigma)$ of $M$ is

$$
\begin{equation*}
\kappa(\sigma)=\lambda \kappa^{\prime}(\sigma)-2 C(\varphi(x)) \lambda, \tag{16}
\end{equation*}
$$

where $\kappa^{\prime}(\sigma)$ is the Gauss curvature of $M^{\prime}$. Moreover, $\Phi$ is not a homothety. Its dilatation $\Lambda$ is

$$
\begin{equation*}
\Lambda(Z)=\lambda \frac{1+\alpha(x) g(Z, Z)}{1+\lambda \beta\left(x^{\prime}\right) r\left(x^{\prime}\right) g(Z, Z)}, \quad Z \in T_{x} M, x^{\prime}=\varphi(x) . \tag{17}
\end{equation*}
$$

Proof of Theorem 1 and Theorem 2 (I, III $\Rightarrow$ ) Suppose $\varphi$ and $\Phi$ are conformal mappings. By Lemma 7, $\varphi$ is a homothety and for every $x \in M\left(x^{\prime}=\varphi(x)\right)$ one of the conditions (8)-(11) holds. By Lemma 5, $q=\lambda\left(s \circ \varphi^{-1}\right)$. If $\operatorname{dim} M \geq 3$ or $\operatorname{dim} M^{\prime} \leq \operatorname{dim} M+1$, by Lemma 7 (d) and Lemma 8 conditons (10) and (11) cannot hold. Therefore Lemma 7 (c) implies that $\bar{M}$ is totally geodesic. Moreover, if (10) or (11) is satisfied then by Lemma 7 (d) and Remark 2, $\bar{M}$ is optimal with the coefficient $C=(1 / \lambda)\left((p \alpha) \circ \varphi^{-1}-\lambda \beta r\right)$.
( I III $\Leftarrow$ ) Taking horizontal (resp. vertical) $A \in T_{Z} T M$, computing $h^{\prime}\left(\Phi_{*} A, \Phi_{*} A\right)$ and applying relations between $p, q, r, s, \alpha, \beta$ and $\lambda$ one can conclude that $\Phi$ is conformal.
(II) Suppose $\Phi$ is conformal. By Lemma 6, $\varphi$ is also conformal. Therefore (I) and Lemma 5 imply that $\Phi$ and $\varphi$ are homotheties and $\Lambda=\lambda$.
(IV) As above we conclude that $\varphi$ is conformal.
(IV1) It is a consequence of Lemma 7 (c).
(IV2) Suppose for every $x \in M$ one of the conditions (10) or (11) holds. By Proposition 1, (I) and the fact that the curvature under the action of a homothety with dilatation $\lambda$ is scaled by $1 / \lambda, \varphi$ is a minimal immersion and (16) holds. Conditions (10), (11) and equation (5) imply (17).

As a direct consequence of of Theorem 1 we obtain
Corollary 3 Suppose $\operatorname{dim} M \geq 3$ or $\operatorname{dim} M^{\prime} \leq \operatorname{dim} M+1$. Let $\varphi:(M, g) \rightarrow\left(M^{\prime}, g^{\prime}\right)$ be an imbedding. Then we have:
(a) $\Phi:\left(T M, h_{S}\right) \rightarrow\left(T M^{\prime}, h^{\prime}\right)$ is conformal if and only if $\varphi$ is totally geodesic homothety.
(b) $\Phi:\left(T M, h_{C G}\right) \rightarrow\left(T M^{\prime}, h^{\prime}{ }_{C G}\right)$ is conformal if and only if $\varphi$ is totally geodesic isometric imbedding.
(c) $\Phi:\left(T M, h_{C G}\right) \rightarrow\left(T M^{\prime}, h_{S}^{\prime}\right)$ is never conformal.

### 2.3 An example to Theorem 2

It is important to show that there is essential difference between Theorems 1 and 2. To do this we give an example of 2-dimensional manifold $M, 4$-dimensional manifold $M^{\prime}$ and an immersion $\varphi: M \rightarrow M^{\prime}$ such that $\bar{M}=\varphi(M)$ is optimal but not totally geodesic.

Let $\Sigma^{d}(\rho)$ denote Euclidean $d$-dimensional sphere of radius $\rho$ centred at the origin in $\mathbb{R}^{d+1}$. Recall (see [3], Chapter $4 \S 5$ page 139) that the second standard immersion of $\Sigma^{2}(1)$ it is a map $\varphi: \Sigma^{2}(1) \rightarrow \Sigma^{4}(1 / \sqrt{3})$ defined as follows: Consider harmonic homogeneous polynomials $u_{i}, i=1, \ldots, 5$, in $\mathbb{R}^{3}$ given by

$$
\begin{aligned}
& u_{1}=x_{2} x_{3}, \quad u_{2}=x_{1} x_{3}, \quad u_{3}=x_{1} x_{2}, \\
& u_{4}=\frac{1}{2}\left(x_{1}^{2}-x_{2}^{2}\right), \quad u_{5}=\frac{\sqrt{3}}{6}\left(x_{1}^{2}+x_{2}^{2}-2 x_{3}^{2}\right),
\end{aligned}
$$

and let $u=\left(u_{1}, \ldots, u_{5}\right)$. We define $\varphi$ to be the restriction $u \mid \Sigma^{2}(1)$. Then $\varphi: \Sigma^{2}(1) \rightarrow$ $\Sigma^{4}(1 / \sqrt{3})$ is an isometric immersion (but not imbedding). Nevertheless, $\bar{M}=\varphi\left(\Sigma^{2}(1)\right)$ is a minimal submanifold of $\Sigma^{4}(1 / \sqrt{3})$. We show that $\bar{M}$ is optimal with the constant coefficient $C=1$.

Lemma 9 Suppose $(M, g)$ is a Riemannian manifold and $u: M \rightarrow \mathbb{R}^{d+1}$. Assume that the image $\bar{M}=u(M)$ is contained in $\Sigma=\Sigma^{d}(\rho)$ and $u: M_{-} \rightarrow \Sigma$ is an imbedding. Denote by $\Pi$ and $\bar{\Pi}$ the second fundamental form of $\bar{M}$ in $\Sigma$ and $\bar{M}$ in $\mathbb{R}^{d+1}$, respectively. Then for every $x^{\prime} \in \Sigma$ and for every basis $\left(e_{i}\right)$ of $T_{x^{\prime}} \bar{M}$

$$
\left\langle\Pi\left(e_{i}, e_{k}\right), \Pi\left(e_{j}, e_{l}\right)\right\rangle=\left\langle\bar{\Pi}\left(e_{i}, e_{k}\right), \bar{\Pi}\left(e_{j}, e_{l}\right)\right\rangle-\frac{1}{\rho^{2}}\left\langle e_{i}, e_{k}\right\rangle\left\langle e_{j}, e_{l}\right\rangle,
$$

where $\langle$,$\rangle is the canonical inner product in \mathbb{R}^{d+1}$.
Proof Elementary exercise.
Proposition 2 If $\varphi$ is the second standard immersion then the submanifold $\bar{M}=\varphi\left(\Sigma^{2}(1)\right)$ is optimal with the constant coefficient $C=1$.

Proof Let $M=\Sigma^{2}(1)$ and $\Sigma=\Sigma^{4}(1 / \sqrt{3})$. Adopt the notations from Lemma 9 . Denote by $\tilde{\varphi}$ the restriction of $\varphi$ to lower half sphere $\Sigma_{-}^{2}(1)$. Since $\varphi\left(\Sigma^{2}(1)\right)$ coincides with the closure of $\tilde{\varphi}\left(\Sigma_{-}^{2}(1)\right)$, it suffices to prove that $\bar{M}_{-}=\tilde{\varphi}\left(\Sigma_{-}^{2}(1)\right)$ is optimal with the coefficient one.

Let $f$ be the stereographic projection $\Sigma^{2}(1) \rightarrow \mathbb{R}^{2}$ from the north pole. Put $\psi=f \circ \tilde{\varphi}^{-1}$. Fix $x^{\prime}=\psi^{-1}(t)$, where $t=\left(t_{1} ; t_{2}\right) \in \mathbb{R}^{2},|t|<1$. Let $e_{i}=\left(\partial / \partial \psi_{i}\right)\left(x^{\prime}\right)$. Put $t^{2}=t_{1}^{2}+t_{2}^{2}$ and $t^{4}=\left(t^{2}\right)^{2}$. Since $\varphi$ is an isometric immersion and $f$ is the stereographic projection we have

$$
\left\langle e_{i}, e_{j}\right\rangle=\frac{4 \delta_{i j}}{\left(t^{2}+1\right)^{2}}, \quad i, j=1,2,
$$

where $\delta_{i j}$ is the Kronecker symbol. In the light of Lemma 9 (with $\rho=1 / \sqrt{3}$ ), to finish the proof it suffices to show that

$$
\begin{align*}
\left\langle\bar{\Pi}\left(e_{i}, e_{k}\right), \bar{\Pi}\left(e_{j}, e_{k}\right)\right\rangle & =\left(3 \delta_{i k}+1\right) \frac{16 \delta_{i j}}{\left(t^{2}+1\right)^{4}} \\
& =\left(3 \delta_{i k}+1\right)\left\langle e_{i}, e_{j}\right\rangle^{2}, \quad i, j, k=1,2 \tag{18}
\end{align*}
$$

After elementary but laborious calculations we get

$$
\begin{aligned}
\bar{\Pi}\left(e_{1}, e_{1}\right)= & \frac{4}{\left(t^{2}+1\right)^{4}} 4 t_{2}\left(1-t^{2}-2 t_{1}^{2}\right) ; 8 t_{1}\left(1-t_{1}^{2}\right) ; 4 t_{1} t_{2}\left(t_{1}^{2}-t_{2}^{2}-3\right) \\
& t^{4}-8 t_{1}^{2} t_{2}^{2}+6 t_{2}^{2}-6 t_{1}^{2}+1 ; \sqrt{3}\left(t^{4}-2 t^{2}-4 t_{1}^{2}+1\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\bar{\Pi}\left(e_{2}, e_{2}\right)= & \frac{4}{\left(t^{2}+1\right)^{4}} 8 t_{2}\left(1-t_{2}^{2}\right) ; 4 t_{1}\left(1-t^{2}-2 t_{2}^{2}\right) ; 4 t_{1} t_{2}\left(t_{2}^{2}-t_{1}^{2}-3\right) ; \\
& 6 t_{2}^{2}-6 t_{1}^{2}+8 t_{1}^{2} t_{2}^{2}-t^{4}-1 ; \sqrt{3}\left(t^{4}-2 t^{2}-4 t_{2}^{2}+1\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\bar{\Pi}\left(e_{1}, e_{2}\right)= & \frac{4}{\left(t^{2}+1\right)^{4}} 2 t_{1}\left(t^{2}-4 t_{2}^{2}+1\right) ; 2 t_{2}\left(t^{2}-4 t_{1}^{2}+1\right) \\
& 8 t_{1}^{2} t_{2}^{2}-t^{4}+1 ; 4 t_{1} t_{2}\left(t_{1}^{2}-t_{2}^{2}\right) ;-4 \sqrt{3} t_{1} t_{2}
\end{aligned}
$$

Now one can check that (18) holds.
Now let $\mathbb{R} P^{2}$ denote the real 2-dimensional projective space. We treat $\mathbb{R} P^{2}$ as a Riemannian manifold whose metric $g$ is given by the standard two-sheeted covering map $\hat{\pi}: \Sigma^{2}(1) \rightarrow \mathbb{R} P^{2}$. Put $\hat{\varphi}(\hat{x})=\varphi(x)$ if $\hat{x}=\hat{\pi}(x)$. Since $\varphi(x)=\varphi(-x)$, the map $\hat{\varphi}$ is well defined. Moreover, $\hat{\varphi}: \mathbb{R} P^{2} \rightarrow \Sigma^{4}(1 / \sqrt{3})$ is an imbedding. It is called the first standard imbedding of $\mathbb{R} P^{2}$ into $\Sigma^{4}(1 / \sqrt{3})$.

Take constants $q, \alpha>0$. Suppose Cheeger-Gromoll type metrics $h$ and $h^{\prime}$ on $T\left(\mathbb{R} P^{2}\right)$ and $T\left(\Sigma^{4}(1 / \sqrt{3})\right)$ are given. If
(1) $h=h_{1, q, \alpha+1}$ and $h^{\prime}=h_{1, q, \alpha}^{\prime}$, or
(2) $h=h_{1, q, 1}$ and $h^{\prime}=h^{\prime}{ }_{0, q, 1}^{\prime}$
then $\hat{\varphi}_{*}$ is a conformal mapping, but not a homothety. Its dilatation is $\Lambda(Z)=(1+(\alpha+1)$ $g(Z, Z)) /(1+\alpha g(Z, Z))$ in the case of $(1)$ and $\Lambda(Z)=1+g(Z, Z)$ in the case of (2).

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