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Research Article

Continuous Dependence for the Pseudoparabolic Equation

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We determine the continuous dependence of solution on the parameters in a Dirichlet-type initial-boundary value problem for the pseudoparabolic partial differential equation.

1. Introduction

We consider the following initial-boundary value problem:

$$u_t - \alpha \Delta u_t - \beta \Delta u = f(u), \quad x \in \Omega, \quad t > 0, \quad (1.1)$$

$$u(x, 0) = u_0(x), \quad x \in \Omega, \quad (1.2)$$

$$u(x, t) = 0, \quad x \in \partial\Omega, \quad t > 0, \quad (1.3)$$

where α and β are positive constants, $\Omega \subset \mathbb{R}^n$ is a bounded domain with sufficiently smooth boundary $\partial\Omega$, and $f(u)$ is a given nonlinear function which satisfies

$$0 \geq F(u) \geq f(u) \cdot u, \quad (1.4)$$

$$|f(u)| \leq c_1(1 + |u|^p), \quad (1.5)$$

where $F(u) = \int_0^u f(s) ds$, c_1 is a positive constant, and $p \leq n/(n-2)$.

Equation (1.1) is an example of a general class of equations of Sobolev type, sometimes referred to as Sobolev-Galpern type.

A mixed-boundary value problem for the one-dimensional case of (1.1) appears in the study of nonsteady flow of second-order fluids [1] where u represents the velocity of the fluid.

Equation (1.1) can be assumed as a model for the heat conduction involving a thermodynamic temperature $\theta = u - \alpha \Delta u$ and a conductive temperature u ; see [2].

Equations of the form (1.1) have been called pseudoparabolic by Showalter and Ting [3], because well posed initial-boundary value problems for parabolic equations are also well-posed for (1.1). Moreover, in certain cases, the solution of a parabolic initial-boundary value problem can be obtained as a limit of solutions to the corresponding problem for (1.1) when α goes to zero; see [4].

In [5], Karch proved well-posedness for a Cauchy problem for the pseudoparabolic (1.1).

2. A Priori Estimates

In this section, we obtain a priori estimates for the problem (1.1)–(1.3).

Lemma 2.1. *Let $u_0 \in H_0^1(\Omega)$. Under assumption (1.4), if u is a solution of the problem (1.1)–(1.3) then one has the following estimate:*

$$\|\nabla u\|^2 \leq D_1, \quad (\text{A})$$

$$\int_0^t \|\nabla u_s\|^2 ds \leq D_2, \quad (\text{B})$$

where $D_1 > 0$ and $D_2 > 0$ depend on the initial data and parameters of (1.1).

Proof. We multiply (1.1) by u_t and integrate over Ω . We get

$$\frac{d}{dt}[E(t)] + \alpha \|\nabla u_t\|^2 + \|u_t\|^2 = 0, \quad (2.1)$$

where $E(t) = (\beta/2)\|\nabla u\|^2 - \int_{\Omega} F(u)dx$. We integrate (2.1) on the interval $(0, t)$, and from (1.4) we get

$$\frac{\beta}{2}\|\nabla u\|^2 + \alpha \int_0^t \|\nabla u_s\|^2 ds \leq E(0). \quad (2.2)$$

Hence (A) and (B) follow from (2.2). \square

3. Continuous Dependence on the Coefficient α

In this section we prove that the solution of the problem (1.1)–(1.3) depends continuously on the coefficient α in $H^1(\Omega)$ norm.

We now assume that u and v are the solutions of the following problems, respectively:

$$\begin{aligned}
 u_t - \alpha_1 \Delta u_t - \beta \Delta u &= f(u), & x \in \Omega, t > 0, \\
 u(x, 0) &= u_0(x), & x \in \Omega, \\
 u(x, t) &= 0, & x \in \partial\Omega, t > 0, \\
 v_t - \alpha_2 \Delta v_t - \beta \Delta v &= f(v), & x \in \Omega, t > 0, \\
 v(x, 0) &= u_0(x), & x \in \Omega, \\
 v(x, t) &= 0, & x \in \partial\Omega, t > 0.
 \end{aligned} \tag{3.1}$$

Let $w = u - v$, $\alpha = \alpha_1 - \alpha_2$. Then w is a solution of the problem

$$w_t - \alpha_1 \Delta w_t - \alpha \Delta v_t - \beta \Delta w = f(u) - f(v), \quad x \in \Omega, t > 0, \tag{3.2}$$

$$w(x, 0) = 0, \quad x \in \Omega, \tag{3.3}$$

$$w(x, t) = 0, \quad x \in \partial\Omega, t > 0. \tag{3.4}$$

The following theorem establishes continuous dependence of the solution of (1.1)–(1.3) on the coefficient α in $H^1(\Omega)$ norm.

Theorem 3.1. *Assume that*

$$|f(u) - f(v)| \leq K(1 + |u|^{p-1} + |v|^{p-1})|u - v|, \tag{3.5}$$

where $1 < p \leq n/(n-2)$ if $n > 2$, $p \in [1, \infty)$ if $n = 2$. Let w be the solution of the problem (3.2)–(3.4). Then w satisfies the estimate

$$\|w\|^2 + \alpha_1 \|\nabla w\|^2 \leq D(\alpha_1 - \alpha_2)^2 e^{M_1 t}. \tag{3.6}$$

Here K , D , and M_1 are positive constants.

Proof. We multiply (3.2) by w and integrate over Ω . We get

$$\frac{1}{2} \frac{d}{dt} [\|w\|^2 + \alpha_1 \|\nabla w\|^2] + \alpha \int_{\Omega} \nabla v_t \nabla w dx + \beta \|\nabla w\|^2 = \int_{\Omega} (f(u) - f(v))w dx. \tag{3.7}$$

Using the Cauchy-Schwarz inequality and (3.5), we get

$$\begin{aligned} & \frac{d}{dt} \left[\frac{1}{2} \|w\|^2 + \frac{\alpha_1}{2} \|\nabla w\|^2 \right] + \beta \|\nabla w\|^2 \\ & \leq |\alpha| \|\nabla v_t\| \|\nabla w\| + K \int_{\Omega} (1 + |u|^{p-1} + |v|^{p-1}) |w|^2 dx. \end{aligned} \quad (3.8)$$

Making use of Holder's inequality, we estimate the second term at the right-hand side of (3.8) as follows

$$K \int_{\Omega} (1 + |u|^{p-1} + |v|^{p-1}) |w|^2 dx \leq K \|w\|^2 + K_1 \left(\|u\|_{(p-1)_n}^{p-1} + \|v\|_{(p-1)_n}^{p-1} \right) \|w\|_{2n/(n-2)} \|w\|. \quad (3.9)$$

Inequality $\|w\|_{2n/(n-2)} \leq K_2 \|\nabla w\|$ is valid for all $w \in H_0^1(\Omega)$. Using the Sobolev inequality and (A), we obtain the estimate

$$\|u\|_{(p-1)_n}^{p-1} + \|v\|_{(p-1)_n}^{p-1} \leq d_1 \left(\|\nabla u\|^{p-1} + \|\nabla v\|^{p-1} \right) \leq K_3. \quad (3.10)$$

Therefore using Poincaré's inequality from (3.9) and (3.10), we get

$$K \int_{\Omega} (1 + |u|^{p-1} + |v|^{p-1}) |w| w dx \leq K_4 \|\nabla w\|^2, \quad (3.11)$$

where d_1 and K_i ($i = 1, 2, 3, 4$) are positive constants. By using (3.11) in (3.8) we get

$$\frac{d}{dt} \left[\frac{1}{2} \|w\|^2 + \frac{\alpha_1}{2} \|\nabla w\|^2 \right] + \beta \|\nabla w\|^2 \leq |\alpha| \|\nabla v_t\| \|\nabla w\| + K_4 \|\nabla w\|^2. \quad (3.12)$$

Using arithmetic-geometric mean inequality, we have

$$\frac{d}{dt} E_1(t) \leq \frac{|\alpha|^2}{2} \|\nabla v_t\|^2 + M_1 E_1(t), \quad (3.13)$$

where $E_1(t) = (1/2) \|w\|^2 + (\alpha_1/2) \|\nabla w\|^2$ and $M_1 = \max\{(2/\alpha_1)(K_4 + 1/2), 1\}$. Solving the first-order differential inequality (3.13) and from (B), we obtain

$$E_1(t) \leq \frac{D_2}{2} |\alpha|^2 e^{M_1 t}. \quad (3.14)$$

The last estimate implies the desired inequality. \square

4. Continuous Dependence on the Coefficient β

In this section we prove that the solution of the problem (1.1)–(1.3) depends continuously on the coefficient β in $H^1(\Omega)$ norm.

We now assume that u and v are the solutions of the following problems, respectively:

$$\begin{aligned}
 u_t - \alpha \Delta u_t - \beta_1 \Delta u &= f(u), & x \in \Omega, t > 0, \\
 u(x, 0) &= u_0(x), & x \in \Omega, \\
 u(x, t) &= 0, & x \in \partial\Omega, t > 0, \\
 v_t - \alpha \Delta v_t - \beta_2 \Delta v &= f(v), & x \in \Omega, t > 0, \\
 v(x, 0) &= u_0(x), & x \in \Omega, \\
 v(x, t) &= 0, & x \in \partial\Omega, t > 0.
 \end{aligned} \tag{4.1}$$

Let $w = u - v$, $\beta = \beta_1 - \beta_2$. Then w is a solution of the problem

$$w_t - \alpha \Delta w_t - \beta_1 \Delta w - \beta \Delta v = f(u) - f(v), \quad x \in \Omega, t > 0, \tag{4.2}$$

$$w(x, 0) = 0, \quad x \in \Omega, \tag{4.3}$$

$$w(x, t) = 0, \quad x \in \partial\Omega, t > 0. \tag{4.4}$$

The main result of this section is the following theorem.

Theorem 4.1. *Assume that (3.5) holds. Let w be the solution of the problem (4.2)–(4.4). Then w satisfies the estimate*

$$\|w\|^2 + \alpha \|\nabla w\|^2 \leq D_1 (\beta_1 - \beta_2)^2 e^{M_2 t}, \tag{4.5}$$

where M_2 is constant.

Proof. We multiply (4.2) by w and integrate over Ω . We get

$$\frac{1}{2} \frac{d}{dt} \left[\|w\|^2 + \alpha \|\nabla w\|^2 \right] + \beta \int_{\Omega} \nabla v \nabla w \, dx + \beta_1 \|\nabla w\|^2 = \int_{\Omega} (f(u) - f(v)) w \, dx. \tag{4.6}$$

By using Cauchy-Schwarz inequality and (3.5) in (4.6) we get

$$\begin{aligned}
 & \frac{d}{dt} \left[\frac{1}{2} \|w\|^2 + \frac{\alpha}{2} \|\nabla w\|^2 \right] + \beta_1 \|\nabla w\|^2 \\
 & \leq |\beta| \|\nabla v\| \|\nabla w\| + K \int_{\Omega} (1 + |u|^{p-1} + |v|^{p-1}) |w|^2 \, dx,
 \end{aligned} \tag{4.7}$$

and by using (3.11) in (4.7) we obtain

$$\frac{d}{dt} \left[\frac{1}{2} \|w\|^2 + \frac{\alpha}{2} \|\nabla w\|^2 \right] + \beta_1 \|\nabla w\|^2 \leq |\beta| \|\nabla v\| \|\nabla w\| + K_4 \|\nabla w\|^2. \quad (4.8)$$

Using arithmetic-geometric mean inequality, we have

$$\frac{d}{dt} E_2(t) \leq \frac{|\beta|^2}{2} \|\nabla v\|^2 + M_2 E_2(t), \quad (4.9)$$

where $E_2(t) = (1/2)\|w\|^2 + (\alpha/2)\|\nabla w\|^2$ and $M_2 = \max\{(2/\alpha)(K_4 + 1/2), 1\}$. Solving the first-order differential inequality (4.9) and from (A), we obtain

$$E_2(t) \leq \frac{D_1}{2} |\beta|^2 e^{M_2 t}. \quad (4.10)$$

Hence the proof is completed. \square

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