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Renormalization of the Orientable Non-commutative Gross–Neveu Model

Fabien Vignes-Tourneret

Abstract. We prove that the non-commutative Gross–Neveu model on the two-dimensional Moyal plane is renormalizable to all orders. Despite a remaining UV/IR mixing, renormalizability can be achieved. However, in the massive case, this forces us to introduce an additional counterterm of the form $\bar{\psi} \gamma^0 \gamma^1 \psi$. The massless case is renormalizable without such an addition.

1. Introduction

From the rebirth of non-commutative quantum field theories [3, 27, 28], people were faced to a major difficulty. A new (with respect to the usual commutative theories) kind of divergences appeared in non-commutative field theory [1, 23]. This UV/IR mixing incited people to declare such theories non-renormalizable. Nevertheless H. Grosse and R. Wulkenhaar found recently the way to overcome such a problem by modifying the propagator. Such a modification will be now called “vulcanization”. They proved the perturbative renormalizability, to all orders, of the non-commutative Φ^4 theory on the four-dimensional Moyal space [14, 15]. Their proof is written in the matrix basis. This is a basis for the Schwartz class functions where the Moyal product becomes a simple matrix product [8, 13]. A Moyal based interaction has a non-local oscillating kernel. The main advantage of the matrix basis is that the interaction is then of the type $\text{Tr } \Phi^4$. This form is much easier to use to get useful bounds. The main drawback is the very complicated propagator (see [17] for a complete study of the Gross–Neveu propagator in the matrix basis). This is one of the reasons which lead us to recover in a simplified manner the renormalizability of the non-commutative Φ^4 theory in x -space [16]. The direct space has several advantages. First of all, the propagator may be computed exactly (and used). It has a Mehler-like form in the Φ^4 , LSZ and Gross–Neveu theories [16, 17, 29]. The x -space allows to compare the behavior of commutative

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and non-commutative theories. It seems to allow a simpler handling of symmetries like parity of integrals. This point is very useful for the renormalization of the Gross–Neveu model. We also plan to extend renormalizability proofs into the non-perturbative domain thanks to constructive techniques developed in x -space. Finally, when we will be able to do Physics with such non-commutative models, we would like to have some experience with our physical space. Of course x -space has also drawbacks. It forces to deal with non absolutely convergent integrals. We have to take care of oscillations. Until now it is much more difficult to get the exact topological power counting of the known non-commutative field theories in direct space than in the matrix basis. The non-commutative parametric representation would certainly provide an other way to get the full power counting [18].

Apart from the Φ_4^4 , the modified Bosonic LSZ model [16] and supersymmetric theories, we now know several renormalizable non-commutative field theories. Nevertheless they either are super-renormalizable (Φ_2^4 [13]) or (and) studied at a special point in the parameter space where they are solvable ($\Phi_2^3, \Phi_4^3, \Phi_6^3$ [10–12], the LSZ models [20–22]). Although only logarithmically divergent for parity reasons, the non-commutative Gross–Neveu model is a just renormalizable quantum field theory as Φ_4^4 . One of its main interesting features is that it can be interpreted as a non-local Fermionic field theory in a constant magnetic background. Then apart from strengthening the “vulcanization” procedure to get renormalizable non-commutative field theories, the Gross–Neveu model may also be useful for the study of the quantum Hall effect. It is also a good first candidate for a constructive study [25] of a non-commutative field theory as Fermionic models are usually easier to construct. Moreover its commutative counterpart being asymptotically free and exhibiting dynamical mass generation [9, 19, 24], a study of the physics of this model would be interesting.

In this paper, we prove the renormalizability of the non-commutative Gross–Neveu model to all orders. For only technical reasons, we restrict ourselves to the orientable case. An interesting feature of the model is a kind of remaining UV/IR mixing. Some (logarithmically) divergent graphs entering the four-point function are not renormalizable by a “local” counterterm¹. Nevertheless these “critical” components only appear as sub-divergences of two-point graphs. It turns out that the renormalization of the two-point function makes the (four-point) critical graphs finite. In the massive case, we have to add to the Lagrangian a counterterm of the form $\bar{\psi}\gamma^0\gamma^1\psi$. The massless model is also renormalizable without such a counterterm.

In Section 2, we present the model and fix the notations. We state our main result. Section 3 is devoted to the main technical difficulty of the proof. Here is explained how to exploit properly the vertex oscillations in order to get the power counting. In Section 4, we compute this power counting with a multiscale analysis. In Section 5, we prove that all the divergent subgraphs can be renormalized by

¹By “local” we mean “of the form of the initial vertex”.

counterterms of the form of the initial Lagrangian. Finally, appendices follow about technical details and additional properties.

2. Model and notations

The non-commutative Gross–Neveu model (GN_Θ^2) consists in a Fermionic quartically interacting field theory on the (two-dimensional) Moyal plane \mathbb{R}_Θ^2 . The algebra \mathcal{A}_Θ of “functions on \mathbb{R}_Θ^2 ” may be defined as $\mathcal{S}(\mathbb{R}^2)$ (it may also be extended to an algebra of tempered distributions, see [6–8, 30] for rigorous descriptions) endowed with the associative non-commutative Moyal product:

$$(f \star_\Theta g)(x) = (2\pi)^{-2} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} dy dk f(x + \frac{1}{2}\Theta k) g(x + y) e^{ik \cdot y}. \quad (2.1)$$

The skew-symmetric matrix Θ is

$$\Theta = \begin{pmatrix} 0 & -\theta \\ \theta & 0 \end{pmatrix} \quad (2.2)$$

where θ is a real parameter of dimension length². The action of the non-commutative Gross–Neveu model is

$$S[\bar{\psi}, \psi] = \int dx \left(\bar{\psi} (-i\cancel{\partial} + \Omega\cancel{x} + m + i\delta m \theta \gamma \Theta^{-1} \gamma) \psi + V_o(\bar{\psi}, \psi) + V_{\text{no}}(\bar{\psi}, \psi) \right)(x) \quad (2.3)$$

where $\tilde{x} = 2\Theta^{-1}x$ and $V = V_o + V_{\text{no}}$ is the interaction part given later. The term in δm will be treated perturbatively as a counterterm. It appears from the two-loop order (see Section 5.2.2). Throughout this paper we use the Euclidean metric and the Feynman convention $\cancel{\partial} = \gamma^\mu a_\mu$. The matrices γ^0 and γ^1 constitute a two-dimensional representation of the Clifford algebra $\{\gamma^\mu, \gamma^\nu\} = -2\delta^{\mu\nu}$. Note that with such a convention the γ^μ 's are skew-Hermitian: $\gamma^{\mu\dagger} = -\gamma^\mu$.

Propagator. The propagator of the theory is given by the following lemma:

Lemma 2.1 (Propagator 1 [17]). *The propagator of the Gross–Neveu model is*

$$\begin{aligned} C(x, y) &= \int d\mu_C(\bar{\psi}, \psi) \psi(x) \bar{\psi}(y) = (-i\cancel{\partial} + \Omega\cancel{x} + m)^{-1}(x, y) \quad (2.4) \\ &= \int_0^\infty dt C(t; x, y), \\ C(t; x, y) &= -\frac{\Omega}{\theta\pi} \frac{e^{-tm^2}}{\sinh(2\tilde{\Omega}t)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t)(x-y)^2 + i\Omega x \wedge y} \quad (2.5) \\ &\quad \times \left\{ i\tilde{\Omega} \coth(2\tilde{\Omega}t)(\cancel{x} - \cancel{y}) + \Omega(\cancel{x} - \cancel{y}) - m \right\} e^{-2i\Omega t \gamma \Theta^{-1} \gamma} \end{aligned}$$

with $\tilde{\Omega} = 2\Omega/\theta$ and $x \wedge y = 2x\Theta^{-1}y$.

We also have $e^{-2i\Omega t \gamma \Theta^{-1} \gamma} = \cosh(2\tilde{\Omega}t)\mathbb{1}_2 - i\frac{\theta}{2} \sinh(2\tilde{\Omega}t)\gamma\Theta^{-1}\gamma$.

The propagator may also be considered as diagonal in some *color* space indices if we want to study N copies of spin 1/2 fermions.

Interactions. Concerning the interaction part V , first remind that $\forall f_1, f_2, f_3, f_4 \in \mathcal{A}_\Theta$,

$$\int dx (f_1 \star f_2 \star f_3 \star f_4)(x) = \frac{1}{\pi^2 \det \Theta} \int \prod_{j=1}^4 dx_j f_j(x_j) \delta(x_1 - x_2 + x_3 - x_4) e^{-i\varphi}, \tag{2.6}$$

$$\varphi = \sum_{i < j=1}^4 (-1)^{i+j+1} x_i \wedge x_j. \tag{2.7}$$

This product is non-local and only cyclically invariant. Then, in contrast to the commutative Gross–Neveu theory for which there is only one possible (local) interaction, the GN_Θ^2 model exhibits, at least, six different ones: the *orientable* interactions

$$V_o = \frac{\lambda_1}{4} \sum_{a,b} \int dx (\bar{\psi}_a \star \psi_a \star \bar{\psi}_b \star \psi_b)(x) \tag{2.8a}$$

$$+ \frac{\lambda_2}{4} \sum_{a,b} \int dx (\psi_a \star \bar{\psi}_a \star \psi_b \star \bar{\psi}_b)(x) \tag{2.8b}$$

$$+ \frac{\lambda_3}{4} \sum_{a,b} \int dx (\bar{\psi}_a \star \psi_b \star \bar{\psi}_a \star \psi_b)(x), \tag{2.8c}$$

where ψ 's alternate with $\bar{\psi}$'s and the *non-orientable* interactions

$$V_{\text{no}} = \frac{\lambda_4}{4} \sum_{a,b} \int dx (\bar{\psi}_a \star \bar{\psi}_b \star \psi_a \star \psi_b)(x) \tag{2.9a}$$

$$+ \frac{\lambda_5}{4} \sum_{a,b} \int dx (\bar{\psi}_a \star \bar{\psi}_b \star \psi_b \star \psi_a)(x) \tag{2.9b}$$

$$+ \frac{\lambda_6}{4} \sum_{a,b} \int dx (\bar{\psi}_a \star \bar{\psi}_a \star \psi_b \star \psi_b)(x). \tag{2.9c}$$

All these interactions have the same x -kernel thanks to (2.6). The indices a, b are spin indices taking value in $\{0, 1\}$ (or $\{\uparrow, \downarrow\}$). They may be additionally color indices between 1 and N . For only technical reasons, we will restrict ourselves to orientable interactions. Such a qualification will become clear in the next section. This paper is mainly devoted to the proof of

Theorem 2.2 (BPHZ Theorem for GN_Θ^2). *The quantum field theory defined by the action (2.3) with $V = V_o$ is renormalizable to all orders of perturbation theory.*

Multi-scale analysis. In the following we use a multi-scale analysis [25]. The first step consists in slicing the propagator as

$$C_l = \sum_{i=0}^{\infty} C_l^i, C_l^i = \begin{cases} \int_{M^{-2i}}^{M^{-2(i-1)}} dt C_l(t; \) & \text{if } i \geq 1 \\ \int_1^{\infty} dt C_l(t; \) & \text{if } i = 0. \end{cases} \tag{2.10}$$

We have an associated decomposition of any amplitude of the theory as

$$A_G = \sum_{\mu} A_G^{\mu} \tag{2.11}$$

where $\mu = \{i_l\}$ runs over all possible attributions of a positive integer i_l for each line l in G . This index represents the “scale” of the line l . The usual ultraviolet divergences of field theory becomes, in the multi-scale framework, the divergence of the sum over attributions μ of indices. To work with well-defined quantities, we put an ultraviolet cut-off $\rho: i \in \{0, \dots, \rho\}$. In each slice, the following lemma gives a bound on the propagator.

Lemma 2.3. *For all $i \in \mathbb{N}$, there exists $K, k \in \mathbb{R}_+$ such that*

$$|C^i(x, y)| \leq K M^i e^{-kM^i|x-y|}. \tag{2.12}$$

This bound also holds in the case $m = 0$.

To any assignment μ and scale i are associated the standard connected components $G_k^i, k \in \{1, \dots, k(i)\}$ of the subgraph G^i made of all lines with scales $j \geq i$. These tree components are partially ordered according to their inclusion relations and the (abstract) tree describing these inclusion relations is called the Gallavotti–Nicolò tree [5]; its nodes are the G_k^i ’s and its root is the complete graph G .

More precisely for an arbitrary subgraph g one defines:

$$i_g(\mu) = \inf_{l \in g} i_l(\mu), \quad e_g(\mu) = \sup_{l \text{ external line of } g} i_l(\mu). \tag{2.13}$$

The subgraph g is a G_k^i for a given μ if and only if $i_g(\mu) \geq i > e_g(\mu)$. As is well known in the commutative field theory case, the key to optimize the bound over spatial integrations is to choose the real tree \mathcal{T} compatible with the abstract Gallavotti–Nicolò tree, which means that the restriction \mathcal{T}_k^i of \mathcal{T} to any G_k^i must still span G_k^i . This is always possible (by a simple induction from leaves to root).

Let us define $i_{\nu}(\mu)$ as the index of the line of highest scale hooked to the vertex ν . Then any (amputated) N -point function S has an “effective” expansion:

$$S_N(x_1, \dots, x_N; \rho) = \sum_{N\text{-point graphs } G} \sum_{\mu(G)} \prod_{\nu \in G} \lambda_{i_{\nu}} A_G^{\mu}(x_1, \dots, x_N; \rho). \tag{2.14}$$

Strictly speaking, we prove here that all the orders of the effective series are finite as the cut-off goes to infinity and that there exists a constant $K \in \mathbb{R}$ such that:

$$\lim_{\rho \rightarrow \infty} \int_{\mathbb{R}^{2N}} \prod_{i=1}^N dx_i f_i(x_i) |A_G^\mu(x_1, \dots, x_N; \rho)| \leq K^{n(G)} \tag{2.15}$$

where the $f_i, i \in \llbracket 1, N \rrbracket$ are test functions and $n(G)$ is the number of vertices of G .

2.1. Orientation and graph variables

The delta function in (2.6) implies that the vertex is parallelogram shaped. To simplify the graphs, we will nevertheless draw it either as a lozenge (Fig. 1) or as a square.

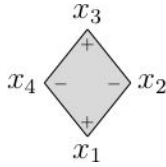


FIGURE 1. A vertex

We associate a sign, + or -, to each of the four positions at a vertex. This sign changes from a position to its neighboring one and reflects the signs entering the delta function. For example, the delta function associated to the vertex of Figure 1 has to be thought to be $\delta(x_1 - x_2 + x_3 - x_4)$ and not $\delta(-x_1 + x_2 - x_3 + x_4)$. The vertex being cyclically invariant, we can freely choose the sign of one among the four positions. The three other signs are then fixed. Let us call **orientable** a line joining a point + to a point -.

On the contrary if it joins two + (or -), we call it **clashing**. By definition, a graph is orientable if all its lines are orientable. We will draw orientable lines with an arrow from its - to its + end. The - positions are then defined as outcoming a vertex and the + ones as incoming.

Let a graph G . We first choose a (optimal) spanning rooted tree \mathcal{T} . The complete orientation of the graph, which corresponds to the choice of the signs at each vertex, is fixed by the orientation of the tree. For the root vertex, we choose an arbitrary position to which we give a + sign. If the graph is not a vacuum graph, it is convenient to choose an external field for this reference position. We orient then all the lines of the tree and all the remaining half-loop lines or “loop fields”, following the cyclicity of the vertices. This means that starting from an arbitrary reference orientation at the root and inductively climbing into the tree, at each vertex we follow the cyclic order to alternate incoming and outcoming lines as in Figure 2a (where the vertices are pictured as points). Let us remark that with such a procedure, a tree is always orientable (and oriented). The loop lines may now be orientable or not.

Definition 2.1 (Sets of lines). We define

- \mathcal{T} = {tree lines} ,
- \mathcal{L} = {loop lines} = $\mathcal{L}_0 \cup \mathcal{L}_+ \cup \mathcal{L}_-$ with
- \mathcal{L}_0 = {loop lines (+, -) or (-, +)} ,
- \mathcal{L}_+ = {loop lines (+, +)} ,
- \mathcal{L}_- = {loop lines (-, -)} .

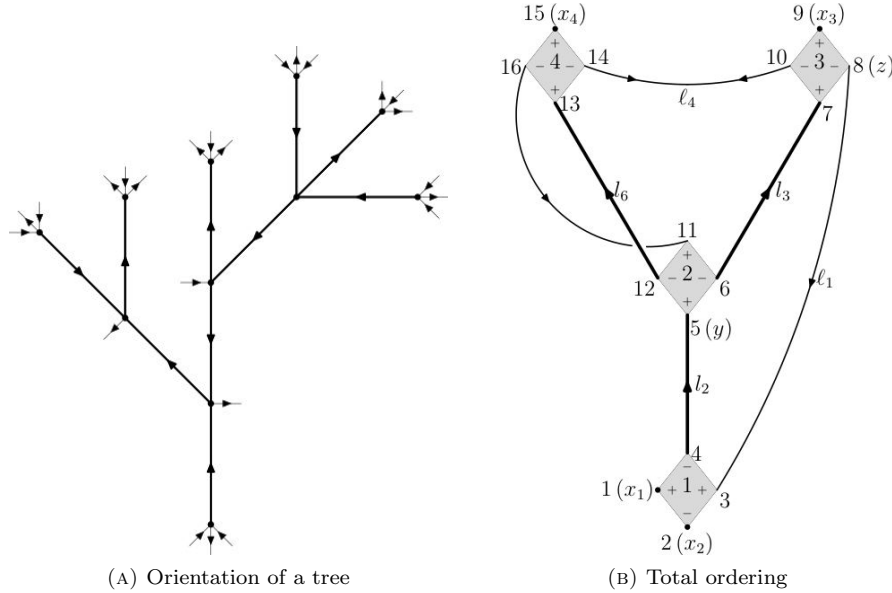


FIGURE 2. Orientability and ordering

It is convenient to equip each graph with a total ordering among the vertex variables. We start from the root and turn around the tree in the trigonometrical sense. We number all the vertex positions in the order they are met. See Figure 2b. Then it is possible to order the lines and external positions.

Definition 2.2 (Order relations). Let $i < j$ and $p < q$. For all lines $l = (i, j)$, $l' = (p, q) \in \mathcal{T} \cup \mathcal{L}$, for all external position x_k , we define

$$\begin{aligned}
 l &\prec l' && \text{if } i < j < p < q \\
 l &\prec k && i < j < k \\
 l &\subset l' && p < i < j < q \\
 k &\subset l && i < k < j: \text{“}l \text{ contracts above } x_k\text{”} \\
 l &\bowtie l' && i < p < j < q.
 \end{aligned}$$

We extend these definitions to the sets of lines introduced in Definition 2.1. For example, we write $\mathcal{L}_0 \bowtie \mathcal{L}_+$ instead of $\{(\ell, \ell') \in \mathcal{L}_0 \times \mathcal{L}_+, \ell \bowtie \ell'\}$. We also define the following set. Let S_1 and S_2 two sets of lines,

$$S_1 \bowtie S_2 = \{(l, l') \in S_1 \times S_2, l \bowtie l' \text{ or } l \bowtie l'\}. \tag{2.16}$$

For example, in Figure 2b, $\ell_1 \prec \ell_4$, $\ell_2 \subset \ell_1$, $\ell_3 \succ x_1$. Note also that with such sign conventions, orientable lines always join an even (-) to an odd (+) numbered position. It is now convenient to define new variables. These are relative to the lines of the graph whereas the variables used until now were vertex variables. Each orientable line l joins an outgoing position x_{l-} to an incoming one x_{l+} . We

define $\mathbf{u}_l = x_{l+} - x_{l-}$ as the difference between the incoming and the outgoing position. For the clashing lines, u_l is also the difference between its two ends but the sign is arbitrary and chosen in Definition 2.3. The u_l are the *short* variables. The *long* ones are defined as the sum of the two ends of the lines. We write them $\mathbf{v}_l = x_{l+} + x_{l-}$ for tree lines and $\mathbf{w}_l = x_{l+} + x_{l-}$ for the loops.

Definition 2.3 (Short and long variables). Let $i < j$. For all line $l = (i, j) \in \mathcal{T} \cup \mathcal{L}$,

$$u_l = \begin{cases} (-1)^{i+1} s_i + (-1)^{j+1} s_j & \forall l \in \mathcal{T} \cup \mathcal{L}_0, \\ s_i - s_j & \forall l \in \mathcal{L}_+, \\ s_j - s_i & \forall l \in \mathcal{L}_-. \end{cases} \tag{2.17}$$

$$v_l = s_i + s_j \quad \forall l \in \mathcal{T} \tag{2.18}$$

$$w_l = s_i + s_j \quad \forall l \in \mathcal{L}. \tag{2.19}$$

Complex quantum field theory on Moyal spaces bears naturally two different orientations. The first one is defined from the cyclic sign of the vertices. This is the one we defined with the tree. The second one is related to the complex feature of the theory: a field only contracts to its complex conjugate. For the Gross–Neveu model, a line can also be oriented from its ψ end to its $\bar{\psi}$ end. Then we are lead to define two different signs for a same line.

Definition 2.4 (Signs of a line). Let $i < j$. For all line $l = (i, j) \in \mathcal{T} \cup \mathcal{L}$,

$$\begin{aligned} \varepsilon(l) &= +1 & \forall l \in \mathcal{T} \cup \mathcal{L}_0 & \text{ if } i \text{ even} \\ &= +1 & \mathcal{L}_- & \\ &= -1 & \mathcal{T} \cup \mathcal{L}_0 & \text{ if } i \text{ odd} \\ &= -1 & \mathcal{L}_+ & \end{aligned}$$

$$\begin{aligned} \epsilon(l) &= +1 & \text{if } \psi(x_i)\bar{\psi}(x_j) \\ &= -1 & \text{if } \bar{\psi}(x_i)\psi(x_j). \end{aligned}$$

Corollary 2.4 (Propagator 2). From the Definitions 2.3 and 2.4, the propagator corresponding to a line l may be written as

$$C_l(u_l, v_l) = \int_0^\infty dt_l C(t_l; u_l, v_l) \tag{2.20}$$

$$\begin{aligned} C(t_l; u_l, v_l) &= \frac{\Omega}{\theta\pi} \frac{e^{-t_l m^2}}{\sinh(2\tilde{\Omega}t_l)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) u_l^2 - i\frac{\Omega}{2} \epsilon(l)\varepsilon(l) u_l \wedge v_l} \\ &\times \left\{ i\tilde{\Omega} \coth(2\tilde{\Omega}t_l) \epsilon(l)\varepsilon(l) \not{u}_l + \Omega \epsilon(l)\varepsilon(l) \not{v}_l + m \right\} e^{-2i\Omega t_l \gamma \Theta^{-1} \gamma} \end{aligned} \tag{2.21}$$

with $\tilde{\Omega} = \frac{2\Omega}{\theta}$ and where v_l will be replaced by w_l if the propagator corresponds to a loop line.

2.2. Position routing

We give here a rule to solve in an optimal way the vertex delta functions. In particular this will allow us to factorize the global delta function (see (2.6)) for each four-point subgraph. There is no canonical way to do it but we can reject the arbitrariness of the process into the choice of a tree. Then it is convenient to introduce a **branch** system. To each tree line l we associate a branch $\mathbf{b}(l)$ containing the vertices *above* l . Let us define *above*. At each vertex ν , there exists a unique tree line going down towards the root. We denote it by l_ν . *A contrario*, to each tree line l corresponds a unique vertex ν such that $l_\nu = l$. We also define \mathcal{P}_ν as the unique set of tree lines joining ν to the root. Then the branch $b(l)$ is the set of vertices defined by

$$b(l) = \{\nu \in G \mid l \in \mathcal{P}_\nu\}. \tag{2.22}$$

On Figure 2b, the branch $b(l_2) = \{2, 3, 4\}$. We can now replace the set of vertex delta functions by a new set associated to the branches. Let a graph G with n vertices. A tree is made of $n - 1$ lines which give raise to $n - 1$ branches. At each vertex ν , we replace $\delta_\nu(\sum_{i=1}^4 (-1)^{i+1} x_{\nu_i})$ by $\delta_{l_\nu}(\sum_{\nu' \in b(l_\nu)} \sum_{i=1}^4 (-1)^{i+1} x_{\nu'_i})$. To complete this new system of delta functions, we add to these $n - 1$ first ones the “root” delta given by $\delta_G(\sum_{\nu' \in G} \sum_{i=1}^4 (-1)^{i+1} x_{\nu'_i})$. We have now a new equivalent set of n delta functions.

Let us precise the arguments of the branch delta functions in terms of short and long variables. To this aim, we define the set $\mathbf{b}(l)$ of lines contracting inside a given branch $b(l)$:

$$\mathbf{b}(l) = \left\{ l' = (x_\nu, x_{\nu'}) \in G \mid \nu, \nu' \in b(l) \right\}. \tag{2.23}$$

There also exists lines $l = (x_\nu, x_{\nu'})$ with $\nu \in b(l)$ and $\nu' \notin b(l)$. Moreover $b(l)$ may contain external positions. We denote by $\mathcal{X}(l)$ the set made of the external positions in the branch $b(l)$ and of the ends (in $b(l)$) of lines joining $b(l)$ to an other branch. From the definition 2.3 of short and long variables, for fixed ν , we have

$$\begin{aligned} \sum_{\nu' \in b(l_\nu)} \sum_{i=1}^4 (-1)^{i+1} x_{\nu'_i} &= \sum_{l \in (\mathcal{T} \cup \mathcal{L}_0) \cap \mathbf{b}(l_\nu)} u_l + \sum_{l \in \mathcal{L}_+ \cap \mathbf{b}(l_\nu)} w_l \\ &\quad - \sum_{l \in \mathcal{L}_- \cap \mathbf{b}(l_\nu)} w_l + \sum_{e \in \mathcal{X}(l_\nu)} \eta(e) x_e \end{aligned} \tag{2.24}$$

where $\eta(e) = 1$ if the position i is incoming and -1 if not. For example, the delta function associated to the branch $b(l_2)$ in the Figure 2b is

$$\delta(y - z + x_3 + x_4 + u_{l_3} + u_{l_5} + u_{l_6} - w_{l_4}). \tag{2.25}$$

In the same manner, the delta function of the complete branch is

$$\delta(x_1 - x_2 + x_3 + x_4 + u_{l_1} + u_{l_2} + u_{l_3} + u_{l_5} + u_{l_6} - w_{l_4}). \tag{2.26}$$

Let us emphasize the particular case of δ_G

$$\delta_G \left(\sum_{l \in \mathcal{T} \cup \mathcal{L}_0} u_l + \sum_{\ell \in \mathcal{L}_+} w_\ell - \sum_{\ell \in \mathcal{L}_-} w_\ell + \sum_{e \in \mathcal{E}(G)} \eta(e)x_e \right) \tag{2.27}$$

where $\mathcal{E}(G)$ is the set of external points in G . Remark that for an orientable graph G ($\mathcal{L}_+ = \mathcal{L}_- = \emptyset$), the root delta function (2.27) only contains the external points and the sum of all the u_l variables in G .

Remark. In the Φ^4 model [16], these delta functions were used to solve all the long tree variables $v_l, l \in \mathcal{T}$. This is the optimal choice. Integrations over the long variables v_l (or w_l) cost M^{2i} . Moreover the tree being chosen optimal, the v_l are the most “expensive” long variables. From (2.24), we have

$$\delta_{b(l)} \left(\sum_{l' \in (\mathcal{T} \cup \mathcal{L}_0) \cap \mathfrak{b}(l)} u_{l'} + \sum_{\ell \in \mathcal{L}_+ \cap \mathfrak{b}(l)} w_\ell - \sum_{\ell \in \mathcal{L}_- \cap \mathfrak{b}(l)} w_\ell + \sum_{e \in \mathcal{X}(l)} \eta(e)x_e \right). \tag{2.28}$$

There exists $e_l \in \mathcal{X}(l)$ such that $x_{e_l} = \frac{1}{2}(\eta(e_l)u_l + v_l)$ (see definition 2.3). This external point is an end of the line l . Thus $\delta_{b(l)}$ gives

$$v_l = -\eta(e_l)u_l - 2\eta(e_l) \times \left(\sum_{l' \in (\mathcal{T} \cup \mathcal{L}_0) \cap \mathfrak{b}(l)} u_{l'} + \sum_{\ell \in \mathcal{L}_+ \cap \mathfrak{b}(l)} w_\ell - \sum_{\ell \in \mathcal{L}_- \cap \mathfrak{b}(l)} w_\ell + \sum_{e \in \mathcal{X}(l) \setminus \{e_l\}} \eta(e)x_e \right).$$

We have then used $n - 1$ delta functions (one per tree line). The last one is kept. It is the equivalent of the global momentum conservation in usual field theories.

Here we won't solve the branch delta functions. Instead we express them as oscillating integrals. In the orientable case, we have

$$\delta_{b(l)} \left(\sum_{l' \in \mathfrak{b}(l)} u_{l'} + \sum_{e \in \mathcal{X}(l)} \eta(e)x_e \right) = \int \frac{d^2 p_l}{(2\pi)^2} e^{i p_l \cdot (\sum_{l' \in \mathfrak{b}(l)} u_{l'} + \sum_{e \in \mathcal{X}(l)} \eta(e)x_e)}. \tag{2.29}$$

After some manipulations on these oscillations (see Section 3.2), we will get decreasing functions for the v_l 's and p_l 's. For each tree line l , we will integrate over v_l and p_l , the final result being bounded by $\mathcal{O}(1)$.

3. From oscillations to decreasing functions

In the preceding section, we decided to express all the vertex delta functions as oscillating integrals. Then we have 2 independent variables per internal propagator. One is integrated over with the exponential decrease of the propagator (see 2.4). The other uses the propagator and vertices oscillations. Then it is useful to precise the oscillations in terms of the u 's and $v(w)$'s variables. This is done in Section 3.1.

We will see how to use the oscillations to get enough decreasing functions in Section 3.2.

3.1. The rosette factor

We have seen in the preceding section that the oscillations are expressed in terms of the vertex variables whereas the propagators are naturally expressed with short and long line variables. It is not very convenient to deal with two equivalent sets of variables. We are then going to express the vertex oscillations with the line variables.

In the following we call **rosette factor** the set of all the vertex oscillations plus the root delta function. We also distinguish tree lines l and loop lines ℓ^2 . The first step to a complete rewriting of the vertex oscillations is a “tree reduction”. It consists in expressing all tree variables in terms of u and v variables. Let a graph G of order n . It has $2(n - 1)$ tree positions. The remaining $2n + 2$ loop and external variables are subsequently written s_j . By using the cyclic symmetry of the vertices and the delta functions, we get (see [16] for a proof):

Lemma 3.1 (Tree reduction). *The rosette factor after the first Filk move is [4,16]:*

$$\delta \left(s_1 - s_2 + \dots - s_{2n+2} + \sum_{l \in \mathcal{T}} u_l \right) \exp v\varphi \tag{3.1}$$

where

$$\begin{aligned} \varphi = & \sum_{i,j=0|i<j}^{2n+2} (-1)^{i+j+1} s_i \wedge s_j + \frac{1}{2} \sum_{l \in \mathcal{T}} \varepsilon(l) v_l \wedge u_l + \sum_{\mathcal{T} \prec \mathcal{T}} u_{l'} \wedge u_l \\ & + \sum_{\{l \in \mathcal{T}, i \prec l\}} u_l \wedge (-1)^{i+1} s_i + \sum_{\{l \in \mathcal{T}, i \succ l\}} (-1)^{i+1} s_i \wedge u_l. \end{aligned}$$

The next step is to express all the loop variables with the corresponding u and w variables. In [16], we computed the result for *planar regular* graph ($g = 0$ and $B = 1$, see appendix A for graphologic definitions and also [14,26]). Here we need the general case³. We now denote the (true) external variables by s_{j_k} , $k \in \llbracket 1, N \rrbracket \stackrel{\text{def}}{=} [1, N] \cap \mathbb{N}$. We write $\mathcal{C}\mathcal{L}_0 \stackrel{\text{def}}{=} \mathcal{L}_+ \cup \mathcal{L}_-$.

²In case a line belongs to a set containing both tree and loop lines, we write it l .

³Strictly speaking, we only need, in this paper, the orientable case. Nevertheless the non-orientable one will follow.

Lemma 3.2. *The rosette factor of a general graph is:*

$$\delta \left(\sum_{k=1}^N (-1)^{j_k+1} s_{j_k} + \sum_{l \in T \cup \mathcal{L}_0} u_l + \sum_{\ell \in \mathcal{L}_+} w_\ell - \sum_{\ell \in \mathcal{L}_-} w_\ell \right) \exp \iota \varphi, \quad (3.2)$$

with $\varphi = \varphi_E + \varphi_X + \varphi_U + \varphi_W$,

$$\begin{aligned} \varphi_E &= \sum_{k,l=1|k<l}^N (-1)^{j_k+j_l+1} s_{j_k} \wedge s_{j_l}, \\ \varphi_X &= \sum_{k=1}^N \sum_{\substack{((T \cup \mathcal{L}_0) \prec j_k) \\ \cup (\mathcal{G} \mathcal{L}_0 \supset j_k)}} (-1)^{j_k+1} s_{j_k} \wedge u_l + \sum_{(T \cup \mathcal{L}_0) \succ j_k} u_l \wedge (-1)^{j_k+1} s_{j_k}, \\ \varphi_U &= \frac{1}{2} \sum_{\mathcal{T}} \varepsilon(l) v_l \wedge u_l + \frac{1}{2} \sum_{\mathcal{L}} \varepsilon(\ell) w_\ell \wedge u_\ell \\ &\quad + \frac{1}{2} \sum_{\mathcal{L}_0 \times \mathcal{L}_0} \varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\ &\quad + \frac{1}{2} \sum_{\mathcal{L}_0 \times \mathcal{G} \mathcal{L}_0} \varepsilon(\ell) w_\ell \wedge u_{\ell'} - \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\ &\quad + \frac{1}{2} \sum_{\mathcal{L}_0 \times \mathcal{G} \mathcal{L}_0} -\varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\ &\quad + \frac{1}{2} \sum_{\substack{(\mathcal{L}_+ \bowtie \mathcal{L}_-) \\ \cup (\mathcal{L}_+ \times \mathcal{L}_+) \cup (\mathcal{L}_- \times \mathcal{L}_-)}} u_\ell \wedge \varepsilon(\ell') w_{\ell'} + u_{\ell'} \wedge \varepsilon(\ell) w_\ell \\ &\quad + \sum_{\substack{((T \cup \mathcal{L}_0) \subset \mathcal{L}_0) \\ \cup ((T \cup \mathcal{L}_0) \succ \mathcal{G} \mathcal{L}_0)}} \varepsilon(\ell') w_{\ell'} \wedge u_l + \sum_{\substack{(\mathcal{G} \mathcal{L}_0 \subset \mathcal{G} \mathcal{L}_0) \\ \cup ((T \cup \mathcal{L}_0) \prec \mathcal{G} \mathcal{L}_0)}} u_l \wedge \varepsilon(\ell') w_{\ell'} \\ &\quad + \sum_{(T \cup \mathcal{L}_0) \prec (T \cup \mathcal{L}_0)} u_{l'} \wedge u_l + \sum_{(T \cup \mathcal{L}_0) \subset \mathcal{G} \mathcal{L}_0} u_l \wedge u_{l'} \\ &\quad + \frac{1}{2} \sum_{\substack{(\mathcal{L}_0 \times \mathcal{L}_0) \\ \cup (\mathcal{L}_+ \times \mathcal{L}_+) \cup (\mathcal{L}_- \times \mathcal{L}_-)}} u_{\ell'} \wedge u_\ell + \frac{1}{2} \sum_{\substack{(\mathcal{L}_0 \bowtie \mathcal{G} \mathcal{L}_0) \\ \cup (\mathcal{L}_+ \times \mathcal{L}_-) \cup (\mathcal{L}_- \times \mathcal{L}_+)}} u_\ell \wedge u_{\ell'}, \\ \varphi_W &= \sum_{\substack{(\mathcal{G} \mathcal{L}_0 \prec j_k) \\ \cup (\mathcal{L}_0 \supset j_k)}} \varepsilon(\ell) w_\ell \wedge (-1)^{j_k+1} s_{j_k} + \sum_{\mathcal{G} \mathcal{L}_0 \succ j_k} (-1)^{j_k+1} s_{j_k} \wedge \varepsilon(\ell) w_\ell \\ &\quad + \frac{1}{2} \sum_{\substack{(\mathcal{L}_0 \times \mathcal{L}_0) \\ \cup (\mathcal{G} \mathcal{L}_0 \times \mathcal{G} \mathcal{L}_0) \cup (\mathcal{L}_0 \bowtie \mathcal{G} \mathcal{L}_0)}} \varepsilon(\ell') w_{\ell'} \wedge \varepsilon(\ell) w_\ell + \sum_{\substack{(\mathcal{L}_0 \supset \mathcal{G} \mathcal{L}_0) \\ \cup (\mathcal{G} \mathcal{L}_0 \prec \mathcal{G} \mathcal{L}_0)}} \varepsilon(\ell') w_{\ell'} \wedge \varepsilon(\ell) w_\ell, \end{aligned}$$

where $l(\ell)$ belongs to the set on the left-hand-side.

Proof. As explained in Section 2.2, the root δ function is given by

$$\delta \left(\sum_{k=1}^N (-1)^{j_k+1} s_{j_k} + \sum_{l \in T \cup \mathcal{L}_0} u_l + \sum_{\ell \in \mathcal{L}_+} w_\ell - \sum_{\ell \in \mathcal{L}_-} w_\ell \right). \tag{3.3}$$

We express all the loop field variables with the u and w variables. Then the quadratic term in the external variables is

$$\sum_{k < l=1}^N (-1)^{j_k+j_l+1} s_{j_k} \wedge s_{j_l}. \tag{3.4}$$

Let an external variable s_{j_k} . The linear terms with respect to s_{j_k} are

$$\begin{aligned} \varphi_{j_k} &= \sum_{i < j_k} (-1)^{i+1} s_i \wedge (-1)^{j_k} s_{j_k} + \sum_{i > j_k} (-1)^{j_k} s_{j_k} \wedge (-1)^{i+1} s_i \\ &+ \sum_{T \succ j_k} (-1)^{j_k} s_{j_k} \wedge u_l + \sum_{T \prec j_k} u_l \wedge (-1)^{j_k} s_{j_k} \end{aligned} \tag{3.5}$$

where the s_i 's are all loop variables. Let a loop line $\ell = (i, j) \prec j_k$. Its contribution to φ_{j_k} is:

$$[(-1)^{i+1} s_i + (-1)^{j+1} s_j] \wedge (-1)^{j_k} s_{j_k}. \tag{3.6}$$

The result in terms of the u_ℓ and w_ℓ variables depends on the orientability of the loop line. From definitions 2.3 and 2.4, we have

$$\begin{aligned} &[(-1)^{i+1} s_i + (-1)^{j+1} s_j] \wedge (-1)^{j_k} s_{j_k} \\ &= u_\ell \wedge (-1)^{j_k} s_{j_k} && \text{if } \ell \in \mathcal{L}_0 \\ &= -\varepsilon(\ell) w_\ell \wedge (-1)^{j_k} s_{j_k} && \text{if } \ell \in \mathcal{L}_+ \cup \mathcal{L}_-. \end{aligned} \tag{3.7}$$

In the same way, if a loop line contracts above an external variable s_{j_k} , its contribution to φ_{j_k} is:

$$\begin{aligned} &[(-1)^{i+1} s_i + (-1)^j s_j] \wedge (-1)^{j_k} s_{j_k} \\ &= -\varepsilon(\ell) w_\ell \wedge (-1)^{j_k} s_{j_k} && \text{if } \ell \in \mathcal{L}_0 \\ &= u_\ell \wedge (-1)^{j_k} s_{j_k} && \text{if } \ell \in \mathcal{L}_+ \cup \mathcal{L}_-. \end{aligned} \tag{3.8}$$

Finally the linear term for s_{j_k} is

$$\begin{aligned} \varphi_{j_k} &= \sum_{\substack{((T \cup \mathcal{L}_0) \prec j_k) \\ \cup (\mathcal{L}_0 \supset j_k)}} u_l \wedge (-1)^{j_k} s_{j_k} + \sum_{(T \cup \mathcal{L}_0) \succ j_k} (-1)^{j_k} s_{j_k} \wedge u_l \\ &+ \sum_{\substack{(\mathcal{L}_0 \prec j_k) \\ \cup (\mathcal{L}_0 \supset j_k)}} (-1)^{j_k} s_{j_k} \wedge \varepsilon(\ell) w_\ell + \sum_{\mathcal{L}_0 \succ j_k} \varepsilon(\ell) w_\ell \wedge (-1)^{j_k} s_{j_k}. \end{aligned} \tag{3.9}$$

Let us now consider a loop line $\ell = (p, q)$. Its contribution to the rosette factor decomposes into a “loop-loop” term and a “tree-loop” term. We will detail

the first one, the second one being obtained with the same method. The loop-loop term is:

$$\begin{aligned}
\varphi_{ll} &= \sum_{i < p} (-1)^{i+1} s_i \wedge (-1)^p s_p + \sum_{\substack{p < i \\ i \neq q}} (-1)^p s_p \wedge (-1)^{i+1} s_i + (-1)^{p+q+1} s_p \wedge s_q \\
&\quad + \sum_{\substack{i < q \\ i \neq p}} (-1)^{i+1} s_i \wedge (-1)^q s_q + \sum_{q < i} (-1)^q s_q \wedge (-1)^{i+1} s_i \\
&= \sum_{i < p} (-1)^{i+1} s_i \wedge [(-1)^p s_p + (-1)^q s_q] + \sum_{q < i} [(-1)^p s_p + (-1)^q s_q] \wedge (-1)^{i+1} s_i \\
&\quad + \sum_{p < i < q} (-1)^{i+1} s_i \wedge [(-1)^{p+1} s_p + (-1)^q s_q] + (-1)^{p+q+1} s_p \wedge s_q. \quad (3.10)
\end{aligned}$$

An other loop line $\ell' = (i, j)$ has now six possibilities. It may follow or precede ℓ , contain or be contained in ℓ , cross it by the left or the right. Moreover the lines ℓ and ℓ' may be orientable or not. I will not exhibit all these different contributions but will explain our method thanks to two examples.

Let $(\ell, \ell') \in \mathcal{L}_0^2$ such that $\ell' \times \ell$. The line ℓ' crosses ℓ by the left as defined in 2.2. The corresponding term is:

$$\begin{aligned}
&(-1)^{i+1} s_i \wedge [(-1)^p s_p + (-1)^q s_q] + (-1)^{j+1} s_j \wedge [(-1)^{p+1} s_p + (-1)^q s_q] \\
&= (-1)^{i+1} s_i \wedge (-u_\ell) + (-1)^{j+1} s_j \wedge (-\varepsilon(\ell) w_\ell) \\
&= \frac{1}{2} (u_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell + \varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell) w_\ell \wedge \varepsilon(\ell') w_{\ell'}). \quad (3.11)
\end{aligned}$$

In the same way, if $\ell \in \mathcal{L}_0$, $\ell' \in \mathcal{L}_+$ such that $\ell \subset \ell'$, we have:

$$\begin{aligned}
&(-1)^{i+1} s_i \wedge [(-1)^p s_p + (-1)^q s_q] + [(-1)^p s_p + (-1)^q s_q] \wedge (-1)^{j+1} s_j \\
&= (-1)^{i+1} s_i \wedge (-u_\ell) + (-u_\ell) \wedge (-1)^{j+1} s_j = u_\ell \wedge u_{\ell'}. \quad (3.12)
\end{aligned}$$

We do the same for the other contributions and get:

$$\begin{aligned}
\varphi_{ll} &= \frac{1}{2} \sum_{\mathcal{L}} \varepsilon(\ell) w_\ell \wedge u_\ell \quad (3.13) \\
&\quad + \sum_{\substack{(\mathcal{L}_0 \subset \mathcal{L}_0) \\ \cup (\mathcal{L}_0 \succ \mathcal{L}_0)}} \varepsilon(\ell') w_{\ell'} \wedge u_\ell + \sum_{(\mathcal{L}_0 \prec \mathcal{L}_0) \cup (\mathcal{L}_0 \subset \mathcal{L}_0)} u_\ell \wedge \varepsilon(\ell') w_{\ell'} \\
&\quad + \frac{1}{2} \sum_{\mathcal{L}_0 \times \mathcal{L}_0} \varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell + \frac{1}{2} \sum_{\mathcal{L}_0 \times \mathcal{L}_0} \varepsilon(\ell) w_\ell \wedge u_{\ell'} - \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\
&\quad + \frac{1}{2} \sum_{\mathcal{L}_0 \times \mathcal{L}_0} -\varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell
\end{aligned}$$

$$\begin{aligned}
 & + \frac{1}{2} \sum_{\substack{(\mathcal{L}_+ \bowtie \mathcal{L}_-) \\ \cup (\mathcal{L}_+ \times \mathcal{L}_+) \cup (\mathcal{L}_- \times \mathcal{L}_-)}} u_\ell \wedge \varepsilon(\ell') w_{\ell'} + u_{\ell'} \wedge \varepsilon(\ell) w_\ell \\
 & + \frac{1}{2} \sum_{\substack{(\mathcal{L}_0 \times \mathcal{L}_0) \cup (\mathbb{G}\mathcal{L}_0 \times \mathbb{G}\mathcal{L}_0) \\ \cup (\mathcal{L}_0 \bowtie \mathbb{G}\mathcal{L}_0)}} \varepsilon(\ell') w_{\ell'} \wedge \varepsilon(\ell) w_\ell + \sum_{\substack{(\mathcal{L}_0 \supset \mathbb{G}\mathcal{L}_0) \\ \cup (\mathbb{G}\mathcal{L}_0 \prec \mathbb{G}\mathcal{L}_0)}} \varepsilon(\ell') w_{\ell'} \wedge \varepsilon(\ell) w_\ell \\
 & + \sum_{\mathcal{L}_0 \prec \mathcal{L}_0} u_{\ell'} \wedge u_\ell + \sum_{\mathcal{L}_0 \subset \mathbb{G}\mathcal{L}_0} u_\ell \wedge u_{\ell'} \\
 & + \frac{1}{2} \sum_{\substack{(\mathcal{L}_0 \times \mathcal{L}_0) \\ \cup (\mathcal{L}_+ \times \mathcal{L}_+) \cup (\mathcal{L}_- \times \mathcal{L}_-)}} u_{\ell'} \wedge u_\ell + \frac{1}{2} \sum_{\substack{(\mathcal{L}_0 \bowtie \mathbb{G}\mathcal{L}_0) \\ \cup (\mathcal{L}_+ \times \mathcal{L}_-) \cup (\mathcal{L}_- \times \mathcal{L}_+)}} u_\ell \wedge u_{\ell'}
 \end{aligned}$$

The “tree-loop” term is:

$$\begin{aligned}
 \varphi_{tl} & = \sum_{\{l' \in \mathcal{T}, l' \prec p\}} u_{l'} \wedge (-1)^p s_p + \sum_{\{l' \in \mathcal{T}, l' \succ p\}} (-1)^p s_p \wedge u_{l'} \tag{3.14} \\
 & + \sum_{\{l' \in \mathcal{T}, l' \prec q\}} u_{l'} \wedge (-1)^q s_q + \sum_{\{l' \in \mathcal{T}, l' \succ q\}} (-1)^q s_q \wedge u_{l'} \\
 & = \sum_{\{l' \in \mathcal{T}, l' \prec p\}} u_{l'} \wedge [(-1)^p s_p + (-1)^q s_q] + \sum_{\{l' \in \mathcal{T}, l' \succ q\}} [(-1)^p s_p + (-1)^q s_q] \wedge u_{l'} \\
 & + \sum_{\{l' \in \mathcal{T}, p \prec l' \prec q\}} u_{l'} \wedge [(-1)^{p+1} s_p + (-1)^q s_q] \\
 & = \sum_{\mathcal{L}_0 \succ \mathcal{T}} u_\ell \wedge u_{l'} + \sum_{\substack{(\mathcal{L}_0 \prec \mathcal{T}) \\ \cup (\mathbb{G}\mathcal{L}_0 \supset \mathcal{T})}} u_{l'} \wedge u_\ell \\
 & + \sum_{\substack{(\mathcal{L}_0 \supset \mathcal{T}) \\ \cup (\mathbb{G}\mathcal{L}_0 \prec \mathcal{T})}} \varepsilon(\ell) w_\ell \wedge u_{l'} + \sum_{\mathbb{G}\mathcal{L}_0 \succ \mathcal{T}} u_{l'} \wedge \varepsilon(\ell) w_\ell. \quad \square
 \end{aligned}$$

Corollary 3.3. *The rosette factor of an orientable graph is*

$$\delta \left(\sum_{k=1}^N (-1)^{j_k+1} s_{j_k} + \sum_{l \in \mathcal{T} \cup \mathcal{L}} u_l \right) \exp i\varphi \tag{3.15}$$

with

$$\varphi = \varphi_E + \varphi_X + \varphi_U + \varphi_W,$$

$$\varphi_E = \sum_{k,l=1|k<l}^N (-1)^{j_k+j_l+1} s_{j_k} \wedge s_{j_l},$$

$$\varphi_X = \sum_{k=1}^N \sum_{(\mathcal{T} \cup \mathcal{L}) \prec j_k} (-1)^{j_k+1} s_{j_k} \wedge u_l + \sum_{(\mathcal{T} \cup \mathcal{L}) \succ j_k} u_l \wedge (-1)^{j_k+1} s_{j_k},$$

$$\begin{aligned} \varphi_U &= \frac{1}{2} \sum_{\mathcal{T}} \varepsilon(l) v_l \wedge u_l + \frac{1}{2} \sum_{\mathcal{L}} \varepsilon(\ell) w_\ell \wedge u_\ell \\ &+ \frac{1}{2} \sum_{\mathcal{L} \times \mathcal{L}} \varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell + \sum_{(\mathcal{T} \cup \mathcal{L}) \subset \mathcal{L}} \varepsilon(\ell') w_{\ell'} \wedge u_l \\ &+ \sum_{(\mathcal{T} \cup \mathcal{L}) \prec (\mathcal{T} \cup \mathcal{L})} u_{l'} \wedge u_l + \frac{1}{2} \sum_{\mathcal{L} \times \mathcal{L}} u_{\ell'} \wedge u_\ell, \\ \varphi_W &= \sum_{\mathcal{L} \supset j_k} (-1)^{j_k} s_{j_k} \wedge \varepsilon(\ell) w_\ell + \frac{1}{2} \sum_{\mathcal{L} \times \mathcal{L}} \varepsilon(\ell') w_{\ell'} \wedge \varepsilon(\ell) w_\ell. \end{aligned}$$

Proof. It is enough to set $\mathcal{L}_+ = \mathcal{L}_- = \emptyset$ in the general expression of Lemma 3.2. \square

Corollary 3.4. *Let a planar regular graph ($g = 0$ and $B = 1$). Its rosette factor is [16]*

$$\delta \left(\sum_{k=1}^N (-1)^{k+1} x_k + \sum_{l \in \mathcal{T} \cup \mathcal{L}} u_l \right) \exp \iota \varphi \tag{3.16}$$

with

$$\begin{aligned} \varphi &= \varphi_E + \varphi_X + \varphi_U, \\ \varphi_E &= \sum_{i,j=1|i < j}^N (-1)^{i+j+1} x_i \wedge x_j, \\ \varphi_X &= \sum_{k=1}^N \sum_{(\mathcal{T} \cup \mathcal{L}) \prec k} (-1)^{k+1} x_k \wedge u_l + \sum_{(\mathcal{T} \cup \mathcal{L}) \succ k} u_l \wedge (-1)^{k+1} x_k, \\ \varphi_U &= \frac{1}{2} \sum_{\mathcal{T}} \varepsilon(l) v_l \wedge u_l + \frac{1}{2} \sum_{\mathcal{L}} \varepsilon(\ell) w_\ell \wedge u_\ell \\ &+ \sum_{(\mathcal{T} \cup \mathcal{L}) \subset \mathcal{L}} \varepsilon(\ell') w_{\ell'} \wedge u_l + \sum_{(\mathcal{T} \cup \mathcal{L}) \prec (\mathcal{T} \cup \mathcal{L})} u_{l'} \wedge u_l. \end{aligned}$$

Proof. As the graph has only one broken face, there is always an even number of fields between two external variables. In this case, j_k and k have the same parity. Thus by switching s_{j_k} into x_k , the quadratic term in the external variables is:

$$\sum_{i,j=1|i < j}^N (-1)^{i+j+1} x_i \wedge x_j. \tag{3.17}$$

Moreover the constraints $g = 0$ and $B = 1$ imply that the graph is orientable ($\mathcal{L} = \mathcal{L}_0$). Indeed, let us consider a clashing loop line ℓ joining s_i to s_{i+2p} . These

two positions have same parity. Between the two ends of ℓ are an odd number of positions. Then either ℓ contracts above an external variable and $B \geq 2$, or an other loop line crosses it and $g \geq 1$.

Finally by skipping from the result of Lemma 3.2 the terms concerning crossing lines, lines contracting above external variables and non-orientable lines, we get (3.16). \square

3.2. The masslets

Contrary to the Φ^4 case, the Gross–Neveu propagator C^i (2.21) does not contain any term of the form $\exp -M^{-2i}w^2$ (we call them *masslets*) [16]. This term is replaced by an oscillation of the type $u \wedge w$. Whereas masslets are not in the propagator, they appear after integration over the u variables:

$$\int d^2u e^{-M^{2i}u^2 + iu \wedge w} = KM^{-2i} e^{-M^{-2i}w^2}. \tag{3.18}$$

Let G a connected graph. Its amplitude is

$$A_G = \int \prod_{i=1}^N dx_i f_i(x_i) \delta_G \prod_{l \in \mathcal{T}} du_l dv_l \delta_{b(l)} C_l(u_l, v_l) \prod_{\ell \in \mathcal{L}} du_\ell dw_\ell C_\ell(u_\ell, w_\ell) e^{i\varphi}. \tag{3.19}$$

The points $x_i, i \in \llbracket 1, N \rrbracket$ are the external positions. For the delta functions, we use the notations of Section 2.2. The total vertex oscillation φ is given by the Lemma 3.2. It is convenient to split the propagator into two parts. We define, for all line $l \in G, \bar{C}_l(u_l)$ by $C_l(u_l, v_l) = \bar{C}_l(u_l) e^{-i\frac{\Omega}{2}\epsilon(l)\epsilon(l)u_l \wedge v_l}$. Once more we replace v by w for loop lines. This splitting allows to gather the propagators oscillations with the vertex ones. The total oscillation φ_Ω is simply deduced from φ by replacing the terms $\frac{1}{2}\epsilon(l)v_l \wedge u_l$ by $\frac{1}{2}(1 + \epsilon(l)\Omega)\epsilon(l)v_l \wedge u_l$. The graph amplitude becomes

$$A_G = \int \prod_{i=1}^N dx_i f_i(x_i) \delta_G \prod_{l \in \mathcal{T}} du_l dv_l \delta_{b(l)} \bar{C}_l(u_l) \prod_{\ell \in \mathcal{L}} du_\ell dw_\ell \bar{C}_\ell(u_\ell) e^{i\varphi_\Omega}. \tag{3.20}$$

In contrast with the Φ^4 theory [16], we won't solve the branch delta functions. Instead we keep δ_G but express the $n - 1$ other delta functions as oscillating integrals:

$$\delta_{b(l)} \left(\sum_{l' \in b(l)} u_{l'} + \sum_{e \in \mathcal{X}(l)} \eta(e)x_e \right) = \int \frac{d^2p_l}{(2\pi)^2} e^{ip_l \cdot (\sum_{l' \in b(l)} u_{l'} + \sum_{e \in \mathcal{X}(l)} \eta(e)x_e)}. \tag{3.21}$$

As already explained in Section 2.2, there exists $e_l \in \mathcal{X}(l)$ such that $x_{e_l} = \frac{1}{2}(\eta(e_l)u_l + v_l)$. Remark that $\eta(e_l) = \epsilon(l)$. Then

$$\sum_{l' \in b(l)} u_{l'} + \sum_{e \in \mathcal{X}(l)} \eta(e)x_e = \frac{1}{2}(u_l + \epsilon(l)v_l) + \sum_{l' \in b(l)} u_{l'} + \sum_{e \in \mathcal{X}(l) \setminus \{e_l\}} \eta(e)x_e. \tag{3.22}$$

In the following we will use an additional notation. For all line $l \in \mathcal{T}$, let us define ν_l as the unique vertex such that $l = l_{\nu}$ where l_{ν} is defined in Section 2.2. ν_l is

the vertex just above l in the tree. We write φ'_Ω for the total oscillation where we add the new oscillations resulting from the delta functions⁴. The graph amplitude is now

$$A_G = \int \prod_{i=1}^N dx_i f_i(x_i) \delta_G \prod_{l \in \mathcal{T}} du_l dv_l dp_l \bar{C}_l(u_l) \prod_{\ell \in \mathcal{L}} du_\ell dw_\ell \bar{C}_\ell(u_\ell) e^{i\varphi'_\Omega}. \quad (3.23)$$

Remark that we have omitted the factors 2π as we have done until now and will go on doing with the $\frac{-\lambda}{4\pi^2 \det \Theta}$ vertex factors. To get the masslets, we could, for example, integrate over the variables u_l . This exact computation would be the equivalent of (3.18). We should integrate $2n - N/2$ coupled Gaussian functions. We would get Gaussian functions in some variables \mathcal{W}_l which would be linear combinations of $w_{\ell'}$. Apart from the difficulty of this computation, we should then prove that the obtained decreasing functions are independent. For general graphs, it is somewhat difficult. Then instead of computing an exact result, we get round the difficulty by exploiting the oscillations before integrating over the u 's, v 's and w 's. The rest of this section is devoted to the proof of

Lemma 3.5. *Let G an orientable graph with n vertices and μ a scale attribution. For all $\Omega \in [0, 1)$, there exists $K \in \mathbb{R}$ such that the amplitude (3.23), amputated, integrated over test functions, with the μ attribution, is bounded uniformly in n by*

$$|A_G^\mu| \leq K^n \int dx_1 g_1(x_1 + \{a\}) \delta_G \prod_{i=2}^N dx_i g_i(x_i) \prod_{l \in G} da_l M^{2i} \Xi(a_l) \quad (3.24)$$

$$\prod_{l \in \mathcal{T}} du_l d\mathcal{V}_l dp_l M^{i_l} e^{-M^{2i_l} (u_l - \varepsilon(l)a_l)^2} \prod_{\mu=0}^1 \frac{1}{1 + M^{-2i_l} \mathcal{V}_{l,\mu}^2} \frac{1}{1 + M^{2i_l} p_{l,\mu}^2}$$

$$\prod_{\ell \in \mathcal{L}} du_\ell d\mathcal{W}_\ell M^{i_\ell} e^{-M^{2i_\ell} (u_\ell + \{a\})^2} \prod_{\mu=0}^1 \frac{1}{1 + M^{-2i_\ell} \mathcal{W}_{\ell,\mu}^2}$$

with $\varepsilon(l)\mathcal{V}_l = \frac{1}{2}(1 + \varepsilon(l)\Omega)\varepsilon(l)v_l + \sum_{\ell' \supset l} \varepsilon(\ell')w_{\ell'} - \frac{1}{2}\tilde{p}_l - \sum_{\ell' \in \mathcal{P}_{v_l}} \tilde{p}_{\ell'}$, (3.25)

$$\varepsilon(\ell)\mathcal{W}_\ell = \frac{1}{2}(1 + \varepsilon(\ell)\Omega)\varepsilon(\ell)w_\ell + \sum_{\ell' \supset \ell} \varepsilon(\ell')w_{\ell'} + \sum_{\ell' \times \ell} \varepsilon(\ell')w_{\ell'} \quad (3.26)$$

and $\tilde{p} = 1/2\Theta p$, g_i , $i \in [1, N]$ and Ξ are test functions such that $\|g_i\| \leq \sup_{0 \leq p \leq 2} \|f_i^{(p)}\|$.

Remind that we restrict our analysis to orientable graphs. We introduce a Schwartz class function $\xi \in \mathcal{S}(\mathbb{R}^2)$ which, conveniently scaled, is going to mimic the decrease of propagators on a scale M^{-i_l} . We want to get a decreasing function

⁴Note that the oscillation is invariant under $p_l \rightarrow -p_l$ for all $l \in G$ independently.

in v_l without integrating over u_l . We use

$$1 = \int d^2 a_l \coth(2\tilde{\Omega}t_l) \xi(a_l \coth^{1/2}(2\tilde{\Omega}t_l)). \tag{3.27}$$

The coupling between this 1 and the rest of the graph is made by an *ad hoc* change of variables. We have two constraints on such a change. On one hand we want independent decreasing functions. On the other hand, for all line l , the decrease should be of scale⁵ $M^{i_l} \simeq \coth^{1/2}(2\tilde{\Omega}t_l)$.

We are going to make masslets line by line. Let us write x_1 for the root position. Let a tree line l . We perform the change of variables

$$\begin{cases} u_l \rightarrow u_l - \varepsilon(l)a_l, \\ x_1 \rightarrow x_1 + \eta(1)\varepsilon(l)a_l. \end{cases} \tag{3.28}$$

It is not difficult to check that $\varphi'_\Omega \rightarrow \varphi'_\Omega + a_l \wedge \mathcal{V}_l + a_l \wedge (U_l + A_l + X_l)$ where \mathcal{V}_l is given by (3.25) and U_l, A_l and X_l are respectively linear combinations of u 's, a 's and external variables x 's. Please note that such a change of variables let the global root delta function unchanged. Writing only the terms in the amplitude A_G depending on a_l , we get

$$\begin{aligned} A_{G,l} &= \int da_l \int_{M^{-2i_l}}^{M^{-2(i_l-1)}} dt_l \coth(2\tilde{\Omega}t_l) \xi(a_l \coth^{1/2}(2\tilde{\Omega}t_l)) \tag{3.29} \\ &\times \left\{ i\tilde{\Omega} \coth(2\tilde{\Omega}t_l) (\varepsilon\varepsilon)(l) (\not{u}_l - \varepsilon(l)\not{a}_l) + \Omega(\varepsilon\varepsilon)(l) (\not{u}_l - \varepsilon(l)\not{a}_l) - m \right\} \\ &\times e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) (u_l - \varepsilon(l)a_l)^2} f_1(x_1 + \eta(1)\varepsilon(l)a_l) e^{i a_l \wedge (\mathcal{V}_l + U_l + A_l + X_l)} \\ &= \int da_l dt_l \coth(2\tilde{\Omega}t_l) \xi(a_l \coth^{1/2}(2\tilde{\Omega}t_l)) e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) (u_l - \varepsilon(l)a_l)^2} \\ &\times f_1(x_1 + \eta(1)\varepsilon(l)a_l) \\ &\times \left\{ i\tilde{\Omega} \coth(2\tilde{\Omega}t_l) (\varepsilon\varepsilon)(l) (\not{u}_l - \varepsilon(l)\not{a}_l) + \Omega(\varepsilon\varepsilon)(l) (\not{u}_l - \varepsilon(l)\not{a}_l) - m \right\} \\ &\times e^{i a_l \wedge (U_l + A_l + X_l)} \prod_{\mu=0}^1 \left(\frac{\coth^{1/2}(2\tilde{\Omega}t_l) + \frac{\partial}{\partial a_l^\mu}}{\coth^{1/2}(2\tilde{\Omega}t_l) + i\tilde{\mathcal{V}}_{l,\mu}} \right)^2 e^{i a_l \wedge \mathcal{V}_l}. \tag{3.30} \end{aligned}$$

We now integrate by parts over a_l . The boundary terms vanish. We give here

⁵In some cases, a line may have a masslet of a scale greater than its own index. These cases are restricted to a single class of graphs we will detail in Section 3.4.

the order of magnitude of the result. The details of the computation are given in Appendix B.

$$\begin{aligned}
 A_{G,l} \simeq & \int da_l dt_l \coth(2\tilde{\Omega}t_l) e^{ia_l \wedge \mathcal{V}_l} \prod_{\mu=0}^1 \left(\frac{1}{\coth^{1/2}(2\tilde{\Omega}t_l) + i\tilde{\mathcal{V}}_{l,\mu}} \right)^2 \\
 & \Xi(a_l \coth^{1/2}(2\tilde{\Omega}t_l)) e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l)(u_l - \varepsilon(l)a_l)^2} e^{ia_l \wedge (U_l + A_l + X_l)} \\
 & \times g_1(x_1 + \eta(1)\varepsilon(l)a_l) \mathcal{O}(\coth^{5/2}(2\tilde{\Omega}t)). \quad (3.31)
 \end{aligned}$$

Then we get the following bound

$$|A_{G,l}| \leq K M^{-i_l} e^{-kM^{2i_l}(u_l - \varepsilon(l)a_l)^2} g_1(x_1 + \eta(1)\varepsilon(l)a_l) \prod_{\mu} \frac{1}{1 + M^{-2i_l} \mathcal{V}_{l,\mu}^2}. \quad (3.32)$$

Let us now explain how to get the corresponding decreasing functions for the p_l variables. We begin by performing the change of variables $v_l \rightarrow \mathcal{V}_l$ for all tree line l . The determinant of the corresponding Jacobian matrix is $2^{-(n-1)} \prod_{l \in \mathcal{T}} (1 + \varepsilon(l)\Omega)$. It is non-vanishing for all $\Omega \in (0, 1)$. The total oscillation becomes

$$\begin{aligned}
 \varphi'_\Omega = & \varphi_E + \varphi_X + \varphi_W + \sum_{\mathcal{T}} \varepsilon(l) \mathcal{V}_l \wedge (u_l - \varepsilon(l)a_l) \\
 & + \sum_{\mathcal{T}} p_l \cdot \left(\sum_{l' \in \mathcal{L} \cap \mathfrak{b}(l)} u_{l'} + \sum_{e \in \mathcal{X}(l) \setminus \{e_l\}} \eta(e)x_e \right) \\
 & + \sum_{\mathcal{T}} (1 + \varepsilon(l)\Omega)^{-1} \varepsilon(l) \mathcal{V}_l \cdot p_l + WR_1P + PR_2P \\
 & + \frac{1}{2} \sum_{\mathcal{L}} (1 + \varepsilon(\ell)\Omega) \varepsilon(\ell) w_\ell \wedge u_\ell + \frac{1}{2} \sum_{\mathcal{L} \times \mathcal{L}} \varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\
 & + \sum_{\mathcal{L} \subset \mathcal{L}} \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\
 & + \sum_{(\mathcal{T} \cup \mathcal{L}) \prec (\mathcal{T} \cup \mathcal{L})} u_{l'} \wedge u_l + \frac{1}{2} \sum_{\mathcal{L} \times \mathcal{L}} u_{\ell'} \wedge u_\ell + AR_3A + AR_4U + AR_5X, \quad (3.33)
 \end{aligned}$$

where we used the notations of corollary 3.3 and $R_i, i \in \llbracket 1, 5 \rrbracket$ are skew-symmetric matrices. By using

$$e^{i(1+\varepsilon(l)\Omega)^{-1}\varepsilon(l)\mathcal{V}_l \cdot p_l} = \frac{M^{-i_l} + (1 + \varepsilon(l)\Omega)\varepsilon(l) \frac{\partial}{\partial \mathcal{V}_{l,\mu}}}{M^{-i_l} + i p_{l,\mu}} e^{i(1+\varepsilon(l)\Omega)^{-1}\varepsilon(l)\mathcal{V}_l \cdot p_l} \quad (3.34)$$

and integrating by parts over \mathcal{V}_l , we get a decreasing function in p_l which behaves like $(1 + M^{2i_l} p_l^2)^{-1}$. We now turn to the loop lines. We also want to get decreasing functions for them. Let a loop line $\ell = (x_\ell, x'_\ell) \in \mathcal{L}$ of G with $x_\ell \prec x'_\ell$. We make

the following change of variables⁶

$$\begin{cases} u_\ell \rightarrow u_\ell - \varepsilon(\ell)a_\ell, \\ w_\ell \rightarrow w_\ell + a_\ell, \\ x_1 \rightarrow x_1 + \eta(1)\varepsilon(\ell)a_\ell. \end{cases} \tag{3.35}$$

The changes concerning u_ℓ and w_ℓ correspond to “move” x_ℓ . It is easy to check that (3.35) implies $\varphi'_\Omega \rightarrow \varphi'_\Omega + a_\ell \wedge \mathcal{W}_\ell + a_\ell \wedge (U_\ell + A_\ell + X_\ell + P_\ell)$ where \mathcal{W}_ℓ is given by (3.26) and U_ℓ, A_ℓ, X_ℓ and P_ℓ are respectively linear combinations of u 's, a 's, external variables x 's and p 's. We can perform the same type of integration by parts than we used for the tree variables v_l and obtain bounds similar to (3.32). This proves Lemma 3.5.

Independence of the decreasing functions. Remind that the above procedure had two main goals. First of all we wanted to get decreasing functions of scale i_l for all variables v_l (w_l). This should be clear from the preceding section. The second aim was the independence of those decreasing functions. Our procedure is designed to make transparent such an independence.

In Section 2, Definition 2.2 gave a way to partially order the lines. This ordering was useful to express the vertex oscillations in terms of the u 's, v 's and w 's. But we can also define a total ordering among the lines of a graph. We say that $l < l'$ if the first end (in the trigonometric sense around the tree) of l is met before the first end of l' . Then for all line $l \in G$, $\mathcal{V}_l(\mathcal{W}_l)$ depends only on $v_{l'}$'s and $w_{l'}$'s with $l' < l$. Let $V(W)$ and $V'(W')$ the vectors containing respectively the variables $\varepsilon(l)v_l$ ($\varepsilon(\ell)w_\ell$) and $\varepsilon(l)\mathcal{V}_l$ ($\varepsilon(\ell)\mathcal{W}_\ell$). Let M^{-1} the Jacobian matrix of the change of variables $(\varepsilon v \ \varepsilon w) \rightarrow (\varepsilon \mathcal{V} \ \varepsilon \mathcal{W})$: $(V' \ W') = M(V \ W)$. The ordering introduced just above allows to prove that M is triangular. Its determinant is

$$\det M = 2^{-(2n-N/2)} \prod_{l \in G} (1 + \varepsilon(l)\Omega) . \tag{3.36}$$

Clearly $\forall \Omega \in [0, 1)$, $\det M \neq 0$ and M is invertible. The decreasing functions in $\mathcal{V}_l(\mathcal{W}_\ell)$ are consequently independent.

Remark. With the non-orientable interactions (2.9), we were not able to find a procedure making the independence of the masslets transparent.

3.3. Non-planarity

In the preceeding section, we proved that the vertex and propagators oscillations of the Gross–Neveu model allow to obtain decreasing functions similar to the masslets of the (non-commutative) Φ^4 theory. Here we improve these decreases if the graph is non-planar. For this the Lemma 3.5 is not sufficient. Before taking the module of the graph amplitude, we would like to further exploit the oscillations.

⁶This change of variables is slightly different from the one we used for the tree lines 3.28. This leads to an easier proof of the independence of the decreasing functions.

Let T^{-1} the Jacobian matrix of the change of variables $\varepsilon w \rightarrow \varepsilon \mathcal{W}$: $W' = TW$. Let us define the skew-symmetric matrix Q_W with $\varphi_W = WQ_WW$ where φ_W is given by corollary 3.3. After the change of variables $W \rightarrow W' = TW$, $\varphi_{W'} = W'Q'_{W'}W'$ with $Q'_{W'} = {}^tT^{-1}Q_W T^{-1}$. T being invertible, the rank of $Q'_{W'}$ equals Q_W 's. Remark that Q_W is the intersection matrix of the graph. We have the following result $\text{rank } Q_W = 2g$ [1, 18]. Let us consider a non-planar graph. The rank of Q_W being different from zero, there exists a loop line ℓ such that we have an oscillation $\mathcal{W}_\ell \wedge \mathcal{W}'_\ell$ with $\mathcal{W}'_\ell = \sum_{\ell'} Q'_{W, \ell \ell'} \mathcal{W}_\ell + U + A + X + P$. Thanks to Lemma 3.5, we know that \mathcal{W}_ℓ decreases on a scale M^{i_ℓ} with the function $(1 + M^{-2i_\ell} \mathcal{W}_\ell^2)^{-1}$. By an integration by parts similar to (3.30), we get a decrease in \mathcal{W}'_ℓ on a scale M^{-i_ℓ} . This decrease will be used to integrate over some $\mathcal{W}_{\ell'}$ contained in \mathcal{W}'_ℓ . The result of such an integration will be of order M^{-2i_ℓ} instead of $M^{2i_{\ell'}}$. The gain is then $M^{-2i_\ell - 2i_{\ell'}}$.

3.4. Broken faces

We remind that a broken face is a face to which belongs external points (see Appendix A for examples). When we do not consider vacuum graphs, there is always at least one broken face. By definition, it is called the external face. The broken faces produce oscillations of the type $x \wedge w$ (see Lemma 3.2). In the planar case with $B \geq 2$ broken faces, we are going to use such oscillations to get better decreases than the ones of the Lemma 3.5. Let Q_{XW} the skew-symmetric matrix representing the oscillations between the x 's and w 's variables. After the change of variables $W \rightarrow W'$, this matrix becomes

$$Q'_{XW} = Q_{XW}T^{-1}. \tag{3.37}$$

Then $\text{rank } Q'_{XW} = \text{rank } Q_{XW}$. Let I a set of consecutive natural numbers indexing some external variables $x_k, k \in I$. These ones oscillate with the variables $w_\ell, \ell \in B_I$ where B_I is the set of lines contracting above those variables. Let us now check that the variables $x_k, k \in I$ oscillate only with $\mathcal{W}_\ell, \ell \in B_I$. To this aim, let us assume that two sets X and Y of external variables oscillate with two other different sets A and B of loop lines:

$$Q_{XW} = \begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix}, \quad T = \begin{pmatrix} C & 0 \\ 0 & D \end{pmatrix} \tag{3.38}$$

$$Q'_{XW} = Q_{XW}T^{-1} = \begin{pmatrix} AC^{-1} & 0 \\ 0 & BD^{-1} \end{pmatrix}. \tag{3.39}$$

In the planar case, \mathcal{W}_ℓ is only function of $w_{\ell'}$ with $\ell' \supset \ell$. T (and T^{-1}) are then not only (lower) triangular but also bloc diagonal. The oscillations between the external variables x_k and the variables \mathcal{W}_ℓ are

$$X_I Q_{XW} T^{-1} W'_{B_I} = \sum_{k \in I} \eta(k) x_k \wedge \text{CL}(\mathcal{W}_\ell, \ell \in B_I), \tag{3.40}$$

where CL means ‘‘linear combination’’. After the masslets and non-planar cases, it should be clear that this new oscillation allows to get a decreasing function of

scale $M^{-\min_{\ell \in B_I} i_\ell}$ in the external variables. If these points are “true” external ones (of scale -1 , integrated with test functions), we will use it to improve the power counting. Usually external points are integrated over test functions (the result is of order 1) so that the gain is here $M^{-2 \min i_\ell}$.

4. Power counting

In this section, we use the previous decreases by adapting them to the multi-scale case. By Lemma 3.5, we know that it is possible to get $|\mathcal{L}|$ independent decreasing functions equivalent to the masslets of the Φ^4 theory plus $n - 1$ masslets for the tree lines coupled to $n - 1$ strong decreases. These last two types of decreasing functions are equivalent to the branch delta functions. The method we use to get the power counting now depends on the topology of the considered graph⁷.

We only consider graphs with at least two external legs. The vacuum graphs are considered in Appendix C. We use the Gallavotti–Nicolò tree. We start from its leaves and go down towards the root which means from the scale of the ultraviolet cut-off to the scale 0. Let G_k^i an orientable connected component. For all lines, we first get all the masslets by the method expounded in Section 3.2. If G_k^i is planar regular ($g = 0$, $B = 1$), we directly use Lemma 3.5. If G_k^i is non-planar ($g \geq 1$), we use the $\mathcal{W} \wedge \mathcal{W}$ oscillations. Thanks to the procedure explained in Section 3.3, we get an additional decrease in some \mathcal{W}'_ℓ , $\ell \in \mathcal{L}_k^i$, at worst of scale M^{-i} . We do the same in any non-planar “primitive” connected components (i.e., not containing sub non-planar components). The corresponding improvements are independent.

If a node of the Gallavotti–Nicolò tree is planar but has more than one broken face ($B \geq 2$), we consider its number of external legs⁸. If $N(G_k^i) \geq 6$, we directly use Lemma 3.5. When $N(G_k^i) = 4$, the number of broken faces is 1 or 2. Let us focus on the $B = 2$ case. At scale i , one or several lines contract above two external points x' and y' . In contrast with commutative field theory, the power counting of this connected component depends on the scales down to 0. Let \mathcal{P} the unique path in the Gallavotti–Nicolò tree linking G_k^i to G . If there exists a scale $i_0 < i$ and a connected component $G_{k'}^{i_0}$ on \mathcal{P} such that $N(G_{k'}^{i_0}) = 2$ then there exists lines of scales between i and i_0 joining x' to y' . Let us call I the set of such lines and i_{m-1} the scale of the first node after G_k^i on \mathcal{P} . If $\text{card } I = 1$ then G_k^i is logarithmically divergent. If $\text{card } I \geq 2$ then G_k^i will be convergent as $M^{-2(i-i_{m-1})}$. Finally if there does not exist such a $G_{k'}^{i_0}$ then G_k^i will be convergent as $M^{-2(i-i_{m-1})}$.

Let us look at the Figure 3 which is simpler than the general situation but exhibits all its important features. We define I as the insertion made of the lines e_1, e_2 and of the graph G_I . Note that I may be empty and G_I non-planar. The different scales entering I are $i_0 < i_1, \dots, i_{m-1} (< i_m = i)$. The corresponding

⁷The main result is Lemma 4.1, in particular in regard to the power counting of the *critical* function $N = 4$, $B = 2$ which manages the main technical point in providing renormalizability.

⁸It has been noticed in [2] that orientable graphs can't have $N = 2$ and $B = 2$. A simple argument on the Filk rosette [4, 16] proves it equally.

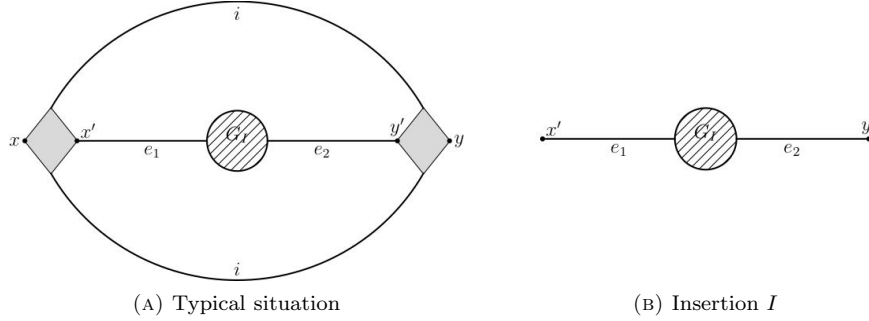


FIGURE 3. Connected component (potentially) *critical*

connected component at scale i_0 is written $G_{k'}^{i_0}$. We also write \mathcal{L}_I for the set of loop lines in the insertion I .

We first get all the scaled decreasing functions for all the tree variables v_l and p_l except the lowest tree line t in I . Then, down to scale i , we proceed for the loop masslets as we have done for Lemma 3.5. The total oscillation may be written

$$\begin{aligned}
 \varphi'_\Omega &= \varphi_E + \varphi_X + \sum_{\mathcal{T} \setminus \{t\}} \varepsilon(l) \mathcal{V}_l \wedge (u_l - \varepsilon(l) a_l) + \frac{1}{2} (1 + \varepsilon(t) \Omega) \varepsilon(t) v_t \wedge u_t \quad (4.1) \\
 &+ \sum_{\mathcal{T} \setminus \{t\}} (1 + \varepsilon(l) \Omega)^{-1} \varepsilon(l) \mathcal{V}_l \cdot p_l \\
 &+ \sum_{\mathcal{L}_k^i} \varepsilon(\ell) \mathcal{W}_\ell \wedge (u_\ell - \varepsilon(\ell) a_\ell) + W' R_1 P + P R_2 P + P R_3 U \\
 &+ \frac{1}{2} \sum_{\mathcal{L}_I} (1 + \varepsilon(\ell) \Omega) \varepsilon(\ell) w_\ell \wedge u_\ell + \frac{1}{2} \sum_{\mathcal{L}_I \times \mathcal{L}_I} \varepsilon(\ell) w_\ell \wedge u_{\ell'} + \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\
 &+ \sum_{(\mathcal{L}_I \cup \{t\}) \subset \mathcal{L}_k^i} \mathcal{W}_k^i \wedge u_l + \sum_{(\mathcal{L}_I \cup \{t\}) \subset \mathcal{L}_I} \varepsilon(\ell') w_{\ell'} \wedge u_\ell \\
 &+ \sum_{k \subset \mathcal{L}_k^i} \mathcal{W}_k^i \wedge \eta(k) x_k + \mathcal{W}_I Q_{WX} X \\
 &+ \mathcal{W}_I Q_W \mathcal{W}_I + \sum_{(\mathcal{T} \cup \mathcal{L}) \prec (\mathcal{T} \cup \mathcal{L})} u_{l'} \wedge u_l \\
 &+ \frac{1}{2} \sum_{\mathcal{L}_I \times \mathcal{L}_I} u_{\ell'} \wedge u_\ell + A R_4 A + A R_5 U + A R_6 X
 \end{aligned}$$

where we wrote $\mathcal{W}_I (\mathcal{W}_k^i)$ for a linear combination of \mathcal{W}_ℓ , $\ell \in \mathcal{L}_I (\mathcal{L}_k^i)$. Let us pick one \mathcal{W}_ℓ , $\ell \in \mathcal{L}_k^i$. We use the oscillation $\mathcal{W}_\ell \wedge (\sum_{(\mathcal{L}_I \cup \{t\}) \subset \ell} u_l + \sum_{k \subset \ell} \eta(k)x_k)$ to get a decreasing function \mathfrak{s} implementing $|\sum_{\mathcal{L}_I \cup \{t\}} u_l + \sum_{k \subset \ell} \eta(k)x_k| \leq M^{-i}$.

If there are external points overflown by the line ℓ , there exists k such that $x_k \stackrel{\text{def}}{=} z \subset \ell$. Then for all line in $\mathcal{L}_I \cup \{t\}$, we perform the change of variables (3.28) and (3.35) but with z in place of x_1 . These modifications let the function \mathfrak{s} independent the a_l , $l \in \mathcal{L}_I \cup \{t\}$. This allows to get for all line $l \in \mathcal{L}_I \cup \{t\}$ a masslet of index i_l .

If there are no external point apart from x and y in $G_{k'}^{i_0}$ (see Figure 3), the function \mathfrak{s} only depends on $\sum_{(\mathcal{L}_I \cup \{t\}) \subset \ell} u_l$ and $G_{k'}^{i_0}$ is a two-point graph. Let us write ℓ_0 for the lowest line in I , $i_{\ell_0} = i_0$. Note that it is necessarily a loop line. For all line $\ell \in \mathcal{L}_I \setminus \{\ell_0\}$, we perform

$$\begin{cases} u_\ell \rightarrow u_\ell - \varepsilon(\ell)a_\ell, \\ w_\ell \rightarrow w_\ell + a_\ell, \\ u_{\ell_0} \rightarrow u_{\ell_0} + \varepsilon(\ell)a_\ell, \\ w_{\ell_0} \rightarrow w_{\ell_0} - \varepsilon(\ell_0)\varepsilon(\ell)a_\ell. \end{cases} \tag{4.2}$$

This let $u_\ell + u_{\ell_0}$ (and \mathfrak{s}) fixed. Then for all line $\ell \in \mathcal{L}_I \setminus \{\ell_0\}$, we get a decreasing function in $\mathcal{W}_\ell - \varepsilon(\ell)\varepsilon(\ell_0)\mathcal{W}_{\ell_0}$ of index i_ℓ . All these functions are independent. For ℓ_0 , we perform

$$\begin{cases} u_{\ell_0} \rightarrow u_{\ell_0} - \varepsilon(\ell_0)a_{\ell_0}, \\ w_{\ell_0} \rightarrow w_{\ell_0} + a_{\ell_0}, \\ u_t \rightarrow u_t + \varepsilon(\ell_0)a_{\ell_0}. \end{cases} \tag{4.3}$$

We get a decreasing function allowing to integrate over \mathcal{W}_{ℓ_0} at the cost of $M^{i_t} \geq M^{i_0}$. Finally for the tree line t , we use the usual change of variables (3.28). This introduces a_t in \mathfrak{s} . The masslet we get for \mathcal{V}_t is then of order M^i . Fortunately the corresponding strong decrease for p_t is of order M^{-i} . We recover the fact that the long tree line variables do not cost anything.

Let us call **critical** a four-point connected component with $N = 4, g = 0, B = 2$ and the insertion I reduced to a single line. We are now ready to prove the following lemma.

Lemma 4.1 (Power counting). *Let G an orientable connected graph. For all $\Omega \in (0, 1)$, there exists $K \in \mathbb{R}$ such that its amputated amplitude A_G^μ integrated over test*

functions (see (3.23)) is bounded by

$$|A_G^\mu| \leq K^n \prod_{i,k} M^{-\frac{1}{2}\omega(G_k^i)} \tag{4.4}$$

$$\text{with } \omega(G_k^i) = \begin{cases} N - 4 & \text{if } (N = 2 \text{ or } N \geq 6) \text{ and } g = 0, \\ & \text{if } N = 4, g = 0 \text{ and } B = 1, \\ & \text{if } G_k^i \text{ is critical,} \\ N & \text{if } N = 4, g = 0, B = 2 \text{ and } G_k^i \text{ non-critical,} \\ N + 4 & \text{if } g \geq 1. \end{cases} \tag{4.5}$$

Remark. This bound is not optimal but sufficient to prove the perturbative renormalizability of the theory. After the study of the propagator in the matrix basis [17], we could get the true power counting in particular the genus dependence. Concerning the broken faces, the bound (4.4) is almost optimal. For the four-point function, it is. But for six (or more)-point functions, we did not try to improve our bound. Nevertheless remark that for such functions, similar situations to the four-point one may happen. The “external” points in additional broken faces may be linked by only one lower line. In this situation, the broken faces do not improve the power counting even for six (or more)-point functions. This is one of the differences between the Gross–Neveu model and the Φ^4 ’s one.

Proof. Lemma 3.5 allows to bound the amplitude of a connected orientable graph G by

$$\begin{aligned} |A_G^\mu| &\leq K^n \int dx_1 g_1(x_1 + \{a\}) \delta_G \prod_{i=2}^N dx_i g_i(x_i) \prod_{l \in G} da_l M^{2i} \Xi(a_l) \\ &\times \prod_{l \in \mathcal{T}} du_l d\mathcal{V}_l dp_l M^{i_l} e^{-M^{2i_l}(u_l - \varepsilon(l)a_l)^2} \prod_{\mu=0}^1 \frac{1}{1 + M^{-2i_l} \mathcal{V}_{l,\mu}^2} \frac{1}{1 + M^{2i_l} p_{l,\mu}^2} \\ &\times \prod_{\ell \in \mathcal{L}} du_\ell d\mathcal{W}_\ell M^{i_\ell} e^{-M^{2i_\ell}(u_\ell + \{a\})^2} \prod_{\mu=0}^1 \frac{1}{1 + M^{-2i_\ell} \mathcal{W}_{\ell,\mu}^2}, \end{aligned} \tag{4.6}$$

where $K \in \mathbb{R}$ and $g_i, i \in \llbracket 1, N \rrbracket$ and Ξ are Schwartz-class functions. The δ_G function corresponding to the root delta function is given by (see Section 2.2)

$$\delta_G \left(\sum_{i \in \mathcal{E}(G)} \eta(i)x_i + \sum_{l \in \mathcal{T} \cup \mathcal{L}} u_l \right). \tag{4.7}$$

We use it to integrate over one of the external positions. The other ones are integrated with the g_i ’s functions. The bound (4.6) on the absolute value of the

amplitude becomes

$$\begin{aligned}
 |A_G^\mu| &\leq K^n \int \prod_{l \in G} da_l M^{2i_l} \Xi(a_l) \prod_{\ell \in \mathcal{L}} du_\ell d\mathcal{W}_\ell M^{i_\ell} M^{i_\ell} e^{-M^{2i_\ell} (u_\ell + \{a\})^2} \\
 &\times \prod_{\mu=0}^1 \frac{1}{1 + M^{-2i_\ell} \mathcal{W}_{\ell,\mu}^2} \prod_{l \in \mathcal{T}} du_l d\mathcal{V}_l dp_l M^{i_l} e^{-M^{2i_l} (u_l - \varepsilon(l)a_l)^2} \\
 &\times \prod_{\mu=0}^1 \frac{1}{1 + M^{-2i_l} \mathcal{V}_{l,\mu}^2} \frac{1}{1 + M^{2i_l} p_{l,\mu}^2}. \tag{4.8}
 \end{aligned}$$

The integrations over the a_ℓ variables cost $\mathcal{O}(1)$. For all line l in the graph, integration over u_l is of order $\mathcal{O}(M^{-2i_l})$. The integration over v_l (resp. w_l) is of order $\mathcal{O}(M^{2i_l})$. But for tree lines, this is compensated by the integration over p_l which gives $\mathcal{O}(M^{-2i_l})$. Then the loops only cost $\mathcal{O}(1)$ whereas the tree lines earn $\mathcal{O}(M^{-2i_l})$. We have the following bound

$$\begin{aligned}
 |A_G^\mu| &\leq K^n \prod_{l \in G} M^{i_l} \prod_{l \in \mathcal{T}} M^{-2i_l} \\
 &\leq K^{n'} \prod_{l \in G} M^{i_l+1} \prod_{l \in \mathcal{T}} M^{-2(i_l+1)}. \tag{4.9}
 \end{aligned}$$

We may now distribute the power counting among the connected components [25]:

$$\prod_{l \in G} M^{i_l+1} = \prod_{l \in G} \prod_{i=0}^{i_l} M = \prod_{l \in G} \prod_{(i,k) \in \mathbb{N}^2 / l \in G_k^i} M = \prod_{(i,k) \in \mathbb{N}^2} \prod_{l \in G_k^i} M, \tag{4.10}$$

$$\prod_{l \in \mathcal{T}} M^{-2(i_l+1)} = \prod_{l \in \mathcal{T}} \prod_{(i,k) \in \mathbb{N}^2 / l \in G_k^i} M^{-2} = \prod_{(i,k) \in \mathbb{N}^2} \prod_{l \in \mathcal{T}_k^i} M^{-2}. \tag{4.11}$$

Then, changing K' into K , the amplitude of a connected orientable graph is bounded by

$$|A_G^\mu| \leq K^{n(G)} \prod_{(i,k) \in \mathbb{N}^2} M^{-\frac{1}{2}\omega(G_k^i)}, \tag{4.12}$$

$$\text{where } \omega(G_k^i) = N(G_k^i) - 4, \tag{4.13}$$

which proves the first part of Lemma 4.1.

If a connected component G_k^i is non-planar, there exists $\ell, \ell' \in G_k^i$ such that the integration over \mathcal{W}_ℓ gives $M^{-2i_{\ell'}} \leq M^{-2i}$ instead of M^{2i_ℓ} (see Section 3.3). The gain with respect to (4.13) is at least M^{-4i} . The superficial degree of convergence becomes $\omega(G_k^i) = N(G_k^i) + 4$.

Finally let a connected component G_k^i with four external legs and two broken faces. With the notations previously defined, if $G_{k'}^{i_0}$ has more than two external points, we use the function \mathfrak{s} to integrate over one of these external positions.

This brings M^{-2i} instead of $\mathcal{O}(1)$. Let us write \mathscr{P} for the path in the Gallavotti–Nicolò tree between G_k^i and G . The factor M^{-2i} improves the superficial degree of convergence of all the nodes in \mathscr{P} with $N = 4, B = 2$. It becomes $\omega(G_k^i) = N(G_k^i)$. If $G_{k'}^{i_0}$ is a two-point graph, we use \mathfrak{s} to integrate over the u variable of the lowest line in I . This brings M^{-2i} instead of M^{-2i_0} . The gain with respect to (4.13) is then $M^{-2(i-i_0)}$. But the integration over \mathcal{W}_{ℓ_0} costs M^{2i_t} instead of $M^{2i_{\ell_0}}$. The total gain is then only $M^{-2(i-i_t)}$. This additional factor allows to improve the power counting of all the four-point components with $B = 2$ in \mathscr{P} between G_k^i and the scale i_t . Their power counting increase from $N - 4$ to N . But note that between i_t (the scale of the lowest tree line in I) and i_0 , only loop lines may appear in the subgraphs. Then the number of external points may only *strictly* decrease in \mathscr{P} from scale i_t to scale i_0 . $G_{k'}^{i_0}$ being a two-point graph, there may be only one divergent connected component in \mathscr{P} between i_t and i_0 . It is a four-point graph with $B = 2$ at scale i_1 (the lowest scale in I above i_0). Moreover this happens only if there is only one loop line of scale i_0 . This component is *critical* (by definition) and we can't improve its power counting which remains $N - 4$. This proves Lemma 4.1. \square

5. Renormalization

Thanks to the power counting proved in Lemma 4.1, we know that the only divergent subgraphs are the planar two- and four-point ones. More precisely the only divergent two-point graphs have one broken face. The divergent four-point ones have either one broken face or are *critical* which means they have $N = 4, g = 0, B = 2$ and the two “external” points belonging to the second broken face are linked by one (and only one) line of lower scale. We are going to prove that the divergent parts of those graphs are of the form of the initial Lagrangian.

5.1. The four-point function

5.1.1. $B = 1$. Let a planar four-point subgraph with one broken face needing renormalization. It is then a node of the Gallavotti–Nicolò tree. There exists $(i, k) \in \mathbb{N}^2$ such that $N(G_k^i) = 4, g(G_k^i) = 0, B(G_k^i) = 1$. The four external points of this amputated graph are written $x_j, j \in \llbracket 1, 4 \rrbracket$. The amplitude associated to the connected component G_k^i is

$$\begin{aligned}
 A_{G_k^i}^\mu(\{x_j\}) &= \int \prod_{i=1}^4 dx_i \bar{\psi}_e(x_1) \psi_e(x_2) \bar{\psi}_e(x_3) \psi_e(x_4) \delta_{G_k^i} e^{i\varphi_\Omega} \\
 &\quad \times \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l) \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell),
 \end{aligned}
 \tag{5.1}$$

where e is the biggest external index of the subgraph G_k^i and $\psi_e, \bar{\psi}_e$ are fields of indices lower or equal to $e < i$. We will perform a first order Taylor expansion which will allow to decouple the external variables x_j from the internal ones u

and p and identify the divergent part of the amplitude. We introduce a parameter s in three different places. First of all, we expand the delta function $\delta_{G_k^i}$ as

$$\delta_{G_k^i}(\Delta + s\mathfrak{U}) \Big|_{s=1} = \delta(\Delta) + \int_0^1 ds \mathfrak{U} \cdot \nabla \delta(\Delta + s\mathfrak{U}) \tag{5.2}$$

where

$$\Delta = x_1 - x_2 + x_3 - x_4 \text{ and } \mathfrak{U} = \sum_{l \in G_k^i} u_l.$$

For orientable graphs, the fields $\bar{\psi}$ are associated to odd positions and the ψ 's to even ones. Moreover if the graph is planar regular, Corollary 3.4 gives the exact value of the root delta function, in particular the alternating signs. This corollary also gives the external oscillation φ_E . The remaining oscillation φ'_Ω is now expanded. It is given by Corollary 3.4 and by the branch delta functions oscillations. With (hopefully) self-explaining notations, it may be written

$$\begin{aligned} \varphi'_\Omega(s=1) &= \varphi_E + XQ_{XU}U + XQ_{XP}P + UQ_UU \\ &\quad + PQ_PP + UQ_UW W + PQ_PW W. \end{aligned} \tag{5.3}$$

Remark that $Q_{XW} = Q_W = 0$ for planar regular graphs. We write

$$\begin{aligned} &\exp \iota(XQ_{XU}U + XQ_{XP}P + UQ_UU + PQ_PP) \\ &= 1 + \iota \int_0^1 ds (XQ_{XU}U + XQ_{XP}P + UQ_UU + PQ_PP) \\ &\quad \times e^{\iota s(XQ_{XU}U + XQ_{XP}P) + \iota UQ_UU + \iota PQ_PP}. \end{aligned} \tag{5.4}$$

Finally we also expand the internal propagators. For all line $l \in G_k^i$,

$$\begin{aligned} \bar{C}_l(u_l, s=1) &= \frac{\Omega}{\theta\pi} \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\sinh(2\tilde{\Omega}t_l)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) u_l^2} (\iota \tilde{\Omega} \coth(2\tilde{\Omega}t_l) \epsilon(l) \epsilon(l) \psi_l \tag{5.5} \\ &\quad + s\Omega \epsilon(l) \epsilon(l) \not{u}_l + sm) (\cosh(2\tilde{\Omega}t_l) \mathbf{1}_2 - s \iota \frac{\theta}{2} \sinh(2\tilde{\Omega}t_l) \gamma \Theta^{-1} \gamma) \Big|_{s=1} \\ &= \frac{2\iota\Omega^2}{\theta^2\pi} \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\tanh(2\tilde{\Omega}t_l)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) u_l^2} \coth(2\tilde{\Omega}t_l) \epsilon(l) \epsilon(l) \psi_l \\ &\quad + \frac{\Omega}{\theta\pi} \int_0^1 ds \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\sinh(2\tilde{\Omega}t_l)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) u_l^2} \\ &\quad \times \left\{ (\Omega \epsilon(l) \epsilon(l) \not{u}_l + m) (\cosh(2\tilde{\Omega}t_l) \mathbf{1}_2 - s \iota \frac{\theta}{2} \sinh(2\tilde{\Omega}t_l) \gamma \Theta^{-1} \gamma) \right. \\ &\quad - \iota \frac{\theta}{2} \sinh(2\tilde{\Omega}t_l) (\iota \tilde{\Omega} \coth(2\tilde{\Omega}t_l) \epsilon(l) \epsilon(l) \psi_l \\ &\quad \left. + s\Omega \epsilon(l) \epsilon(l) \not{u}_l + sm) \gamma \Theta^{-1} \gamma \right\}. \end{aligned}$$

Let τA be the counterterm associated to the connected component G_k^i . It corresponds to the zeroth order terms of the three preceding expansions:

$$\begin{aligned} \tau A_{G_k^i}^\mu &= \int \prod_{i=1}^4 dx_i \bar{\psi}_e(x_1) \psi_e(x_2) \bar{\psi}_e(x_3) \psi_e(x_4) \delta(\Delta) e^{i\varphi_E} \\ &\times \int \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l, s=0) \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell, s=0) e^{i\varphi'_\Omega(s=0)}, \end{aligned} \tag{5.6}$$

where $\varphi_E = \sum_{i < j=1}^4 (-1)^{i+j+1} x_i \wedge x_j$. Then the counterterm is of the form

$$\begin{aligned} \tau A_{G_k^i}^\mu &= \int dx (\bar{\psi}_e \star \psi_e \star \bar{\psi}_e \star \psi_e)(x) \\ &\times \int \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l, s=0) \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell, s=0) e^{i\varphi'_\Omega(s=0)}. \end{aligned} \tag{5.7}$$

To prove that τA looks like the initial vertex, it remains to show that its spinorial structure is one of those of (2.8). Apart from the oscillations and the exponential decreases of the propagators, the counterterm τA involves

$$P = \prod_{l \in G} \psi_l = \prod_{l \in G} (\gamma^0 u_l^0 + \gamma^1 u_l^1) = \prod_{i=1}^{2n-N/2} P_i. \tag{5.8}$$

Each of the $2^{2n-N/2}$ terms P_i in P consist in choosing for each line $l \in G$ either $\gamma^0 u_l^0$ or $\gamma^1 u_l^1$. Each P_i has $n_i^0 u^0$ and $n_i^1 u^1$. Note that, apart from P , the counterterm τA is invariant under: $\forall l \in G, u_l^0 \rightarrow -u_l^0$ and $w_l^1 \rightarrow -w_l^1$. Then the only non vanishing P_i have even n_i^0 . With a similar argument we prove that n_i^1 is also even. Each term in τA then consists in even numbers of γ^0 and γ^1 . For the four-point function, the Taylor expansion (5.5) is possible because the number of internal lines is even (it is $2(n-1)$). We now define the notions of **chain** and **cycle**.

Definition 5.1 (Chain and cycle). We say that two fields are in the same chain

- if they both belong to a same scalar product at a vertex⁹,
- if they are linked by a propagator.

A cycle is a closed chain.

The external fields are linked by chains. The other (internal) fields belong to cycles. The γ^0 and γ^1 matrices are distributed among chains and cycles. Each cycle corresponds, up to a sign, to a term $\text{Tr}((\gamma^0)^p (\gamma^1)^q)$. It does not vanish only if p and q are even. Knowing that the total number of γ^0 is even, that the total number of γ^1 is even and that each cycle contains even numbers of γ^0 and γ^1 , the chains of the graph share an even number of γ^0 and an even number of γ^1 . There are two chains in the four-point function graphs. There are then four possibilities

⁹For example, the first two fields in the interaction (2.8a) belong to a same scalar product.

to distribute the gamma matrices among these two chains. Each may contain an even or an odd number of γ^0 or γ^1 .

Depending on the number and the type of the vertices in these two chains, they may link either a ψ to a $\bar{\psi}$ or two fields of the same kind. We are faced to twelve different spinorial structures:

$$\psi \star [(\gamma^0)^{2p} (\gamma^1)^{2q}] \bar{\psi} \star \psi \star [(\gamma^0)^{2p'} (\gamma^1)^{2q'}] \bar{\psi} = \pm \psi \star \mathbb{1} \bar{\psi} \star \psi \star \mathbb{1} \bar{\psi}, \quad (5.9a)$$

$$\psi \star [(\gamma^0)^{2p+1} (\gamma^1)^{2q}] \bar{\psi} \star \psi \star [(\gamma^0)^{2p'+1} (\gamma^1)^{2q'}] \bar{\psi} = \pm \psi \star \gamma^0 \bar{\psi} \star \psi \star \gamma^0 \bar{\psi}, \quad (5.9b)$$

$$\psi \star [(\gamma^0)^{2p} (\gamma^1)^{2q+1}] \bar{\psi} \star \psi \star [(\gamma^0)^{2p'} (\gamma^1)^{2q'+1}] \bar{\psi} = \pm \psi \star \gamma^1 \bar{\psi} \star \psi \star \gamma^1 \bar{\psi}, \quad (5.9c)$$

$$\psi \star [(\gamma^0)^{2p+1} (\gamma^1)^{2q+1}] \bar{\psi} \star \psi \star [(\gamma^0)^{2p'+1} (\gamma^1)^{2q'+1}] \bar{\psi} = \pm \psi \star \gamma^0 \gamma^1 \bar{\psi} \star \psi \star \gamma^0 \gamma^1 \bar{\psi}. \quad (5.9d)$$

In the same way, we can meet

$$\pm \bar{\psi} \star \mathbb{1} \psi \star \bar{\psi} \star \mathbb{1} \psi, \quad (5.10a)$$

$$\pm \bar{\psi} \star \gamma^0 \psi \star \bar{\psi} \star \gamma^0 \psi, \quad (5.10b)$$

$$\pm \bar{\psi} \star \gamma^1 \psi \star \bar{\psi} \star \gamma^1 \psi, \quad (5.10c)$$

$$\pm \bar{\psi} \star \gamma^0 \gamma^1 \psi \star \bar{\psi} \star \gamma^0 \gamma^1 \psi, \quad (5.10d)$$

$$\pm \bar{\psi}_a \star \psi_c \star \bar{\psi}_b \star \psi_d \mathbb{1}_{ab} \mathbb{1}_{cd}, \quad (5.11a)$$

$$\pm \bar{\psi}_a \star \psi_c \star \bar{\psi}_b \star \psi_d \gamma_{ab}^0 \gamma_{cd}^0, \quad (5.11b)$$

$$\pm \bar{\psi}_a \star \psi_c \star \bar{\psi}_b \star \psi_d \gamma_{ab}^1 \gamma_{cd}^1, \quad (5.11c)$$

$$\pm \bar{\psi}_a \star \psi_c \star \bar{\psi}_b \star \psi_d (\gamma^0 \gamma^1)_{ab} (\gamma^0 \gamma^1)_{cd}. \quad (5.11d)$$

$$(5.11e)$$

To prove that the divergence of the four-point function is of the form of the original vertices (2.8), it is convenient to rewrite them in a different way.

Non-commutative Fierz identities. A basis for $M_D(\mathbb{C})$ is given by a representation of the Clifford algebra $\{\gamma^\mu, \gamma^\nu\} = -D\delta^{\mu\nu}$ of dimension D . In dimension 2, $\mathcal{B} = \{\Gamma^0 = \mathbb{1}, \Gamma^1 = \gamma^0, \Gamma^2 = \gamma^1, \Gamma^3 = \gamma^0 \gamma^1\}$ is a basis for $M_2(\mathbb{C})$. Then let $M \in M_2(\mathbb{C})$,

$$M = -\frac{1}{2} \sum_{A,B=0}^3 \eta_{AB} \text{Tr}(M\Gamma^A) \Gamma^B, \quad (5.12)$$

$$\text{with } \eta = \text{diag}(-1, 1, 1, 1).$$

We now use such a decomposition to rewrite the interactions of the model under a different form. For example, let us consider Interaction (2.8b). If we define $M_{ab} =$

$\bar{\psi}_b \star \psi_a$ and use (5.12), we have

$$\bar{\psi}_b \star \psi_a = -\frac{1}{2} \sum_{A,B} \eta_{AB} \bar{\psi}_{b'} \star \psi_{a'} \Gamma_{b'a'}^A \Gamma_{ab}^B. \tag{5.13}$$

This allows to write

$$\int \psi_a \star \bar{\psi}_a \star \psi_b \star \bar{\psi}_b = \int \bar{\psi}_b \star \psi_a \star \bar{\psi}_a \star \psi_b = -\frac{1}{2} \sum_{A,B} \eta_{AB} \int \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \Gamma^B \psi. \tag{5.14}$$

In the same way, for Interaction (2.8c), we use the decomposition

$$M_{ba} = \bar{\psi}_a \star \psi_b = -\frac{1}{2} \sum_{A,B} \eta_{AB} \bar{\psi}_{a'} \star \psi_{b'} \Gamma_{a'b'}^A \Gamma_{ba}^B \tag{5.15}$$

and write

$$\begin{aligned} \sum_{a,b} \int \bar{\psi}_a \star \psi_b \star \bar{\psi}_a \star \psi_b &= -\frac{1}{2} \sum_{A,B} \eta_{AB} \int \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \Gamma^B \psi \\ &= -\frac{1}{2} \sum_{A,B} \int g_{AB}^3 \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \Gamma^B \psi, \end{aligned} \tag{5.16}$$

with $g_{AB}^3 = \text{diag}(-1, 1, 1, -1)$. We do the same for the three other interactions. The six possible interactions are given in Table¹⁰ 1. As a conclusion, the three orientable interactions (2.8) may be written as linear combinations of

$$\int \bar{\psi} \star \mathbb{1} \psi \star \bar{\psi} \star \mathbb{1} \psi, \tag{5.17a}$$

$$\int \bar{\psi} \star \gamma^\mu \psi \star \bar{\psi} \star \gamma_\mu \psi \quad \text{and} \tag{5.17b}$$

$$\int \bar{\psi} \star \gamma^0 \gamma^1 \psi \star \bar{\psi} \star \gamma^0 \gamma^1 \psi \tag{5.17c}$$

whereas the non-orientable ones (2.9) may be written in function of

$$\int \psi \star \mathbb{1} \bar{\psi} \star \bar{\psi} \star \mathbb{1} \psi, \tag{5.18a}$$

$$\int \psi \star \gamma^\mu \bar{\psi} \star \bar{\psi} \star \gamma_\mu \psi \quad \text{and} \tag{5.18b}$$

$$\int \psi \star \gamma^0 \gamma^1 \bar{\psi} \star \bar{\psi} \star \gamma^0 \gamma^1 \psi. \tag{5.18c}$$

In (5.17b) and (5.18b), the sum over μ is implicit.

We now show that for all $\Gamma^C \in \mathcal{B}$, $\psi \star \Gamma^C \bar{\psi} \star \psi \star \Gamma^C \bar{\psi}$, $\bar{\psi} \star \Gamma^C \psi \star \bar{\psi} \star \Gamma^C \psi$ and $\bar{\psi}_a \star \psi_c \star \bar{\psi}_b \star \psi_d \Gamma_{ab}^C \Gamma_{cd}^C$ may be expressed in function of the orientable interactions

¹⁰Remind that we restrict our proof to the orientable case.

TABLE 1. The interactions and their different formulations

Interactions of the non-commutative Gross-Neveu model	
Orientable	Non-orientable
$\bullet \sum_{a,b} \int dx (\bar{\psi}_a \star \psi_a \star \bar{\psi}_b \star \psi_b)(x)$ $= -\frac{1}{2} \sum_{A,B} \int g_{AB}^1 \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \Gamma^B \psi$	$\bullet \sum_{a,b} \int dx (\bar{\psi}_a \star \bar{\psi}_b \star \psi_b \star \psi_a)(x)$ $= -\frac{1}{2} \sum_{A,B} \int g_{AB}^1 \psi \star \Gamma^A \bar{\psi} \star \bar{\psi} \star \Gamma^B \psi$
$\bullet \sum_{a,b} \int dx (\psi_a \star \bar{\psi}_a \star \psi_b \star \bar{\psi}_b)(x)$ $= -\frac{1}{2} \sum_{A,B} \int g_{AB}^2 \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \Gamma^B \psi$	$\bullet \sum_{a,b} \int dx (\bar{\psi}_a \star \bar{\psi}_a \star \psi_b \star \psi_b)(x)$ $= -\frac{1}{2} \sum_{A,B} \int g_{AB}^2 \psi \star \Gamma^A \bar{\psi} \star \bar{\psi} \star \Gamma^B \psi$
$\bullet \sum_{a,b} \int dx (\bar{\psi}_a \star \psi_b \star \bar{\psi}_a \star \psi_b)(x)$ $= -\frac{1}{2} \sum_{A,B} \int g_{AB}^3 \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \Gamma^B \psi$	$\bullet \sum_{a,b} \int dx (\bar{\psi}_a \star \bar{\psi}_b \star \psi_a \star \psi_b)(x)$ $= -\frac{1}{2} \sum_{A,B} \int g_{AB}^3 \psi \star \Gamma^A \bar{\psi} \star \bar{\psi} \star \Gamma^B \psi$
$g^1 = \text{diag}(-2, 0, 0, 0), \quad g^2 = \eta = \text{diag}(-1, 1, 1, 1), \quad g^3 = \text{diag}(-1, 1, 1, -1)$ $\forall A \in \llbracket 1, 4 \rrbracket, \Gamma^A \in \mathcal{B} = \{\Gamma^0 = \mathbf{1}, \Gamma^1 = \gamma^0, \Gamma^2 = \gamma^1, \Gamma^3 = \gamma^0 \gamma^1\}$	

of Table 1 with the help of a symmetry of the model.

$$\int \psi \star \Gamma^C \bar{\psi} \star \psi \star \Gamma^C \bar{\psi} = \int \bar{\psi}_d \star \psi_a \star \bar{\psi}_b \star \psi_c \Gamma_{ab}^C \Gamma_{cd}^C \tag{5.19}$$

$$= -\frac{1}{2} \sum_{A,B} \eta_{AB} \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \mathfrak{t} \Gamma^C \Gamma^B \mathfrak{t} \Gamma^C \psi$$

$$\mathfrak{t} \Gamma^C \Gamma^B \mathfrak{t} \Gamma^C = \begin{cases} \Gamma^B & \text{if } \Gamma^C = \mathbf{1} \\ g_{BB'} \Gamma^{B'} & \text{with } g = \text{diag}(-1, 1, 1, -1) \text{ if } \Gamma^C = \gamma^0 \gamma^1 \\ g_{BB'} \Gamma^{B'} & \text{with } g = \text{diag}(-1, -1, 1, 1) \text{ if } \Gamma^C = \gamma^0 \\ g_{BB'} \Gamma^{B'} & \text{with } g = \text{diag}(-1, 1, -1, 1) \text{ if } \Gamma^C = \gamma^1. \end{cases} \tag{5.20}$$

Then we have

$$\int \psi \star \Gamma^C \bar{\psi} \star \psi \star \Gamma^C \bar{\psi} = -\frac{1}{2} \sum_{A,B} g_{AB} \bar{\psi} \star \Gamma^A \psi \star \bar{\psi} \star \Gamma^B \psi \tag{5.21}$$

$$\text{with } g = \begin{cases} \text{diag}(-1, 1, 1, 1) & \text{if } \Gamma^C = \mathbf{1} \\ \text{diag}(1, 1, 1, -1) & \text{if } \Gamma^C = \gamma^0 \gamma^1 \\ \text{diag}(1, -1, 1, 1) & \text{if } \Gamma^C = \gamma^0 \\ \text{diag}(1, 1, -1, 1) & \text{if } \Gamma^C = \gamma^1. \end{cases} \tag{5.22}$$

If $\Gamma^C = \mathbf{1}$ or $\gamma^0 \gamma^1$, the interaction (5.21) may be written in function of the interactions (5.17). On the contrary, if $\Gamma^C = \gamma^0$ or γ^1 independently, it is impossible. Fortunately there exists a symmetry implying that the counterterms associated to interaction (5.21) for $\Gamma^C = \gamma^0$ and γ^1 are equal. Each term P_i in the polynomial P (5.8) consists indeed to choose, for each line in the graph, either γ^0 or γ^1 . To each of these terms is canonically associated an other term $\bar{P}_i = P_j$, $j \neq i$ for which we have done exactly the inverse choice. Then to get \bar{P}_i , we consider P_i and change γ^0 into γ^1 , u_l^0 into u_l^1 and vice-versa. Each counterterm, associated to a P_i , is made of a product of gamma matrices and of integrals over the variables u_l , p_l , v_l and w_l . The rotation

$$\begin{aligned} \forall l \in G, u_l^0 &\rightarrow u_l^1 & (5.23) \\ u_l^1 &\rightarrow -u_l^0 \\ w_l^0 (v_l^0) &\rightarrow w_l^1 (v_l^1) \\ w_l^1 (v_l^1) &\rightarrow -w_l^0 (-v_l^0) \end{aligned}$$

shows that the integrals in \bar{P}_i equals the ones in P_i (the total number of u_l^1 is even). Let us have a look at the products of gamma matrices. Let $N \in \mathbb{N}$ and $\forall j \in \llbracket 0, 2N + 1 \rrbracket$, $n_j \in \mathbb{N}$.

$$\begin{aligned} P_\gamma &= \prod_{i=0}^N (\gamma^0)^{n_{2i}} (\gamma^1)^{n_{2i+1}} \\ &= \prod_{i=0}^N (-1)^{\lfloor \frac{n_{2i}}{2} \rfloor + \lfloor \frac{n_{2i+1}}{2} \rfloor} (\gamma^0)^{\frac{1-(-1)^{n_{2i}}}{2}} (\gamma^1)^{\frac{1-(-1)^{n_{2i+1}}}{2}}. \end{aligned} \tag{5.24}$$

Each product of γ^0 (resp. γ^1) has been reduced thanks to $(\gamma^0)^2 = (\gamma^1)^2 = -\mathbf{1}$. The product P_γ equals, up to a sign, an *alternating* product P_γ^a of γ^0 and γ^1 . In the same way,

$$\begin{aligned} \bar{P}_\gamma &= \prod_{i=0}^N (\gamma^1)^{n_{2i}} (\gamma^0)^{n_{2i+1}} \\ &= \prod_{i=0}^N (-1)^{\lfloor \frac{n_{2i}}{2} \rfloor + \lfloor \frac{n_{2i+1}}{2} \rfloor} (\gamma^1)^{\frac{1-(-1)^{n_{2i}}}{2}} (\gamma^0)^{\frac{1-(-1)^{n_{2i+1}}}{2}}. \end{aligned} \tag{5.25}$$

Let us remark that the signs in front of P_γ^a and \bar{P}_γ^a are the same. Let n_0^a and n_1^a the total number of γ^0 (resp. γ^1) in P_γ^a . This product P_γ^a may be

1. $\gamma^0\gamma^1 \dots \gamma^0\gamma^1, n_0^a = n_1^a.$

$$P_\gamma^a = \begin{cases} (-1)^p \mathbb{1} & \text{if } n_0^a = n_1^a = 2p \\ (-1)^p \gamma^0 \gamma^1 & \text{if } n_0^a = n_1^a = 2p + 1 \end{cases} \quad (5.26)$$

2. $\gamma^1\gamma^0 \dots \gamma^1\gamma^0, n_0^a = n_1^a.$

$$P_\gamma^a = \begin{cases} (-1)^p \mathbb{1} & \text{if } n_0^a = n_1^a = 2p \\ (-1)^p \gamma^1 \gamma^0 & \text{if } n_0^a = n_1^a = 2p + 1 \end{cases} \quad (5.27)$$

3. $\gamma^0\gamma^1 \dots \gamma^0\gamma^1\gamma^0, n_0^a = n_1^a + 1.$

$$P_\gamma^a = \begin{cases} (-1)^p \gamma^0 & \text{if } n_1^a = 2p \\ (-1)^p \gamma^1 & \text{if } n_1^a = 2p + 1 \end{cases} \quad (5.28)$$

4. $\gamma^1\gamma^0 \dots \gamma^1\gamma^0\gamma^1, n_1^a = n_0^a + 1.$

$$P_\gamma^a = \begin{cases} (-1)^p \gamma^1 & \text{if } n_0^a = 2p \\ (-1)^p \gamma^0 & \text{if } n_0^a = 2p + 1 \end{cases} \quad (5.29)$$

Let us apply those results to the chains and cycles of a graph. First of all, remark that the numbers of γ^0 and γ^1 in the alternating product have the same parity as the total numbers in P_γ . Each cycle contains an even number of γ^0 and γ^1 and then corresponds to situations of the type (5.26) or (5.27). These are exactly symmetric under the exchange $\gamma^0 \leftrightarrow \gamma^1$. When the two chains of a four-point graph contain an odd number of γ^0 and an even number of γ^1 , we are faced to situations 3 or 4. They are symmetric under the exchange $\gamma^0 \leftrightarrow \gamma^1$. The relative sign between the products P_γ^a and \bar{P}_γ^a is + and (especially) only depends on the parities of the total numbers of γ^0 and γ^1 . This sign doesn't depend on the configuration of the products of matrices i.e. it doesn't depend on the n_j in (5.24).

Then the counterterm $\psi \Gamma^C \bar{\psi} \psi \Gamma^C \bar{\psi}$ may only be of the form $\psi \mathbb{1} \bar{\psi} \psi \mathbb{1} \bar{\psi}$, $\psi \gamma^0 \gamma^1 \bar{\psi} \psi \gamma^0 \gamma^1 \bar{\psi}$ or $\psi \gamma^\mu \bar{\psi} \psi \gamma_\mu \bar{\psi}$. The result is the same for the two others $\bar{\psi} \Gamma^C \psi \bar{\psi}$, $\Gamma^C \psi$ and $\bar{\psi}_a \psi_c \bar{\psi}_b \psi_d \Gamma_{ab}^C \Gamma_{cd}^C$. The sum of the last two interactions in (5.22) is a linear combination of the initial interactions. We would check it in the same way for $\bar{\psi}_a \psi_c \bar{\psi}_b \psi_d \Gamma_{ab}^C \Gamma_{cd}^C$. This proves that τA is of the form of the initial vertices.

As expected for the four-point function, τA is logarithmically divergent. To check it, it is sufficient to redo the procedure used in Section 3.2 with the change of variables (3.28) and (3.35) but without x_1 (the external variables are decoupled from the internal ones in the counterterm). The remainder $(1 - \tau)A$ is composed of four different terms. Each improves the power counting and makes $(1 - \tau)A$ convergent as $i - e \rightarrow \infty$:

- $\mathfrak{U} \cdot \nabla \delta(\Delta + s\mathfrak{U})$. Integrating by parts over an external variable, the ∇ acts on an external field and gives at most M^e . \mathfrak{U} gives at least M^{-i} .
- $XQ_{XU}U, XQ_{XP}P$. X brings M^e and U (resp. P) M^{-i} .

- $UQUU, PQPP$ give at least M^{-2i} ,
- the expansion (5.5) of the propagators gives M^{-i} .

As a conclusion, these terms improves the power counting by $M^{-(i-e)}$ which makes $(1 - \tau)A$ convergent and irrelevant for renormalization.

5.1.2. $B = 2$, critical. The power counting proved in (4.4) let us think that the critical connected components are logarithmically divergent. Exact computations on simple graphs and the behavior of the theory in the matrix basis confirm this fact. But the divergent part of these graphs are not of the form of the initial Lagrangian and particularly not of a Moyal type. Despite such a divergence, we won't renormalize those graphs. In fact, we will prove in Section 5.2.2 that the renormalization of the corresponding two-point function is sufficient to make the complete graph convergent, including the critical sub-divergence. Let i the scale of the critical component and $j < i$ the scale of the corresponding two-point function. The remainder terms in the renormalization of this two-point function will give $M^{-(i-e)} (< M^{-(j-e)})$.

5.2. The two-point function

5.2.1. The regular case. Let a two-point planar subgraph needing renormalization. There exists $(i, k) \in \mathbb{N}^2$ such that $N(G_k^i) = 2, g(G_k^i) = 0$. The two external points of the amputated graph are written x, y . The amplitude associated to the connected component G_k^i is

$$A_{G_k^i}^\mu(x, y) = \int dx dy \bar{\psi}_e(x) \psi_e(y) \delta_{G_k^i} e^{i\varphi'_\Omega} \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l) \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell).$$

Let us proceed to a second order Taylor expansion. First of all, we expand $\delta_{G_k^i}$ as

$$\delta_{G_k^i}(x - y + s\mathfrak{U}) \Big|_{s=1} = \delta(x - y) + \mathfrak{U} \cdot \nabla \delta(x - y) + \int_0^1 ds (1 - s) (\mathfrak{U} \cdot \nabla)^2 \delta(\Delta + s\mathfrak{U}), \tag{5.30}$$

where we used the same notations as in the preceding section. The oscillation between x and y is $\exp i x \wedge y$. Thanks to the delta function, we absorb this oscillation into a redefined matrix Q_{XU} . Then we expand the oscillation:

$$\begin{aligned} \exp i(XQ_{XU}U + XQ_{XP}P + UQUU + PQPP) &= 1 + i(XQ_{XU}U + XQ_{XP}P) \\ &- \int_0^1 ds \left((1 - s)(XQ_{XU}U + XQ_{XP}P)^2 - i(UQUU + PQPP) \right) \\ &\times e^{is(XQ_{XU}U + XQ_{XP}P + UQUU + PQPP)}. \end{aligned} \tag{5.31}$$

We also expand the internal propagators. For all line $l \in G_k^i$,

$$\begin{aligned} \bar{C}_l(u_l, s = 1) &= \frac{\Omega}{\theta\pi} \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\sinh(2\tilde{\Omega}t_l)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) u_l^2} \left(i\tilde{\Omega} \coth(2\tilde{\Omega}t_l) \epsilon(l) \varepsilon(l) \psi_l \right. \\ &\quad \left. + s\Omega \epsilon(l) \varepsilon(l) \not{u}_l + m \right) \left(\cosh(2\tilde{\Omega}t_l) \mathbb{1}_2 - s \frac{\theta}{2} i \sinh(2\tilde{\Omega}t_l) \gamma \Theta^{-1} \gamma \right) \Big|_{s=1} \\ &= \frac{\Omega}{\theta\pi} \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\tanh(2\tilde{\Omega}t_l)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) u_l^2} \left(i\tilde{\Omega} \coth(2\tilde{\Omega}t_l) \epsilon(l) \varepsilon(l) \psi_l + m \right) \\ &\quad + \frac{\Omega}{\theta\pi} \int_0^1 ds \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\sinh(2\tilde{\Omega}t_l)} e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l) u_l^2} \\ &\quad \times \left\{ \Omega \epsilon(l) \varepsilon(l) \not{u}_l \left(\cosh(2\tilde{\Omega}t_l) \mathbb{1}_2 - s i \frac{\theta}{2} \sinh(2\tilde{\Omega}t_l) \gamma \Theta^{-1} \gamma \right) \right. \\ &\quad \left. - i \frac{\theta}{2} \sinh(2\tilde{\Omega}t_l) \left(i\tilde{\Omega} \coth(2\tilde{\Omega}t_l) \epsilon(l) \varepsilon(l) \psi_l + s\Omega \epsilon(l) \varepsilon(l) \not{u}_l + m \right) \gamma \Theta^{-1} \gamma \right\}. \end{aligned} \tag{5.32}$$

The conscientious reader would have noticed that the expansion (5.32) is different from the one we used for the four-point function (5.5). Here we allow the mass term to be part of the zeroth order term. The reason is that the number of internal lines in a two-point function is odd (it is $2n - 1$). For the mass counterterm, if all the propagators would have contributed by a u term, the counterterm would have vanished. In fact, the power counting is reached when one propagator uses its mass term and all the others the term ψ . This implies that the mass divergence is only logarithmic. For the wave function and $\Omega \not{x}$ counterterm, each propagator contributes with its dominant term ψ . The counterterm τA associated to the connected component G_k^i corresponds to the zeroth and first order terms of the three preceding expansions:

$$\tau A_{G_k^i}^\mu = \tau A_m + \tau A_\not{p} + \tau A_\not{x}, \tag{5.33}$$

$$\begin{aligned} \tau A_m &= \int dx dy \bar{\psi}_e(x) \psi_e(y) \delta(x - y) \int \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l, s = 0) \\ &\quad \times \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell, s = 0) e^{i\varphi'_\Omega(s=0)}, \end{aligned} \tag{5.34}$$

$$\begin{aligned} \tau A_\not{p} &= \int dx dy \bar{\psi}_e(x) \psi_e(y) \mathfrak{M} \cdot \nabla \delta(x - y) \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l, s = 0) \\ &\quad \times \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell, s = 0) e^{i\varphi'_\Omega(s=0)}, \end{aligned} \tag{5.35}$$

$$\begin{aligned} \tau A_\not{x} &= i \int dx dy \bar{\psi}_e(x) \psi_e(y) \delta(x - y) (XQ_{XU}U + XQ_{XP}P) \\ &\quad \times \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l, s = 0) \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell, s = 0) e^{i\varphi'_\Omega(s=0)}. \end{aligned} \tag{5.36}$$

The counterterm τA_m contributes to the mass renormalization. Its divergence is logarithmic for the parity reasons given above. τA_p is the wave function counterterm.

$$\begin{aligned} \tau A_p &= - \int dx \bar{\psi}_e(x) \nabla^\mu \psi_e(x) \mathfrak{U}^\mu \prod_{l \in \mathcal{T}_k^i} du_l dv_l dp_l \bar{C}_l^{i_l}(u_l, s = 0) \\ &\times \prod_{\ell \in \mathcal{L}_k^i} du_\ell dw_\ell \bar{C}_\ell^{i_\ell}(u_\ell, s = 0) e^{i\varphi'_\Omega(s=0)} \end{aligned} \tag{5.37}$$

As for the four-point function, this term contains the polynomial (5.8) here of odd degree. The gamma matrices in each monomial are distributed among cycles and a chain (see Definition 5.1). The numbers of $u^0\gamma^0$ and $u^1\gamma^1$ in each cycle are even so that the number of gamma matrices in the chain linking the external points is odd. The term $\bar{\psi}_e \mathfrak{U}^0 \partial_0 \psi_e$ is different from zero if the number of $u^0\gamma^0$ in the chain is odd. Then the number of γ^1 is even. The corresponding counterterm is of the form $\bar{\psi}_e \gamma^0 \partial_0 \psi_e$. We associate it the term $\bar{\psi}_e \mathfrak{U}^1 \partial_1 \psi_e$ where we chose the inverse monomial in P ($\forall l \in G, \gamma^0 u_l^0 \leftrightarrow \gamma^1 u_l^1$). Thanks to a rotation of the coordinates, we show that the complete counterterm looks like $\bar{\psi}_e \not{\nabla} \psi_e$. It is logarithmically divergent.

The counterterm $\tau A_{\not{x}}$, also logarithmically divergent, contributes to the renormalization of the “magnetic field” $\Omega \not{x}$. The terms entering such a contribution look like $\int \bar{\psi}_e \psi_e (x^0 u^1 - x^1 u^0) \dots$. Once more we can associate two opposite monomials and perform a rotation to prove that the counterterm is of the form $\bar{\psi}_e \not{x} \psi_e$. Remark that the terms $\int \bar{\psi}_e \psi_e (x^0 p_0 + x^1 p_1) \dots$ vanish by parity over p (beware that here p_μ is the “momentum” associated to a tree line and not a derivative). It is easy to check from (5.35) and (5.36) that the counterterms τA_p and $\tau A_{\not{x}}$ are skew-Hermitian. They are of the form $\bar{\psi} \not{p} \psi$ and $\bar{\psi} \not{x} \psi$.

The remainder terms, gathered in $(1 - \tau)A$, are convergent:

- $(\mathfrak{U} \cdot \nabla)^2 \delta$ gives M^{-2i} thanks to \mathfrak{U}^2 and M^{2e} by integration by parts over an external point,
- $(XQ_{XU}U + XQ_{XP}P)^2$ brings $M^{-2(i-e)}$,
- $UQ_UU + PQ_PP$ give at least M^{-2i} ,
- The propagators expansion gives at least M^{-i} .

Note that until now the $\bar{\psi} \gamma^0 \gamma^1 \psi$ counterterm was not useful. Moreover if we set $m = 0$ (the bare mass) it remains so under radiative correction ($\tau A_m \equiv 0$) for parity reasons over the u 's.

5.2.2. Critical components. Let us consider an orientable two-point graph at scale j with a critical subgraph at scale $i > j$ (see definition in Section 4). This two-point component is then made of a four-point subgraph at a scale i with $g = 0, B = 2$ and of a single (loop) line of scale j . We renormalize the two-point amplitude as was done in the previous paragraph. We now want to show that the remainder terms are of order $M^{-2(i-e)}$ (and not $M^{-2(j-e)}$) which implies the convergence of the complete remainder amplitude even its four-point sub-divergence.

We proceed as is explained in Section 4. Down to scale i , we get all the necessary masslets for the v 's and w 's and the corresponding functions for the p 's. Then we have an oscillation $\mathcal{W}_\ell \wedge u^j$ where $i_\ell = i$ and u^j is the u variable of the unique loop line of scale j . We use it to get a decreasing function \mathfrak{s} implementing $|u^j| \leq M^{-i}$. It remains to obtain the masslet for the variable w^j . Its associated w^j variable being now of order M^{-i} there is no mean to get a masslet of scale M^j . We can only achieve M^i . The gain we had with the u^j variable is lost by its corresponding masslet and we note once again that the critical components are divergent. But now all the u variables in the graph are bounded by M^{-i} which implies that the remainder terms, except the propagator expansions, bring $M^{-2(i-e)} = M^{-2(i-j)}M^{-2(j-e)}$. All the propagator expansions except the one concerning the lowest propagator (of scale j) give at least M^{-i} . There is one term in the expansion of the lowest propagator ($im\frac{\theta}{2} \sinh(2\tilde{\Omega}t_\ell)\gamma\Theta^{-1}\gamma$) which only brings M^{-2j} . This is not sufficient to renormalize the four-point sub-divergence. The solution consists in putting that term in the counterterm. Only for this lowest propagator, we use a different propagator expansion:

$$\begin{aligned} \bar{C}_l(u_l, s = 1) &= \frac{\Omega}{\theta\pi} \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\sinh(2\tilde{\Omega}t_l)} e^{-\frac{\theta}{2} \coth(2\tilde{\Omega}t_l)u_l^2} (i\tilde{\Omega} \coth(2\tilde{\Omega}t_l)\epsilon(l)\varepsilon(l)\psi_l \quad (5.38) \\ &\quad + s\Omega\epsilon(l)\varepsilon(l)\tilde{u}_l + m) \left(\cosh(2\tilde{\Omega}t_l)\mathbb{1}_2 - \frac{\theta}{2}i \sinh(2\tilde{\Omega}t_l)\gamma\Theta^{-1}\gamma \right) \Big|_{s=1} \\ &= \frac{\Omega}{\theta\pi} \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\tanh(2\tilde{\Omega}t_l)} e^{-\frac{\theta}{2} \coth(2\tilde{\Omega}t_l)u_l^2} (i\tilde{\Omega} \coth(2\tilde{\Omega}t_l)\epsilon(l)\varepsilon(l)\psi_l + m) \\ &\quad \times \left(\cosh(2\tilde{\Omega}t_l)\mathbb{1}_2 - \frac{\theta}{2}i \sinh(2\tilde{\Omega}t_l)\gamma\Theta^{-1}\gamma \right) \\ &\quad + \frac{\Omega}{\theta\pi} \int_0^1 ds \int_0^\infty \frac{dt_l e^{-t_l m^2}}{\sinh(2\tilde{\Omega}t_l)} e^{-\frac{\theta}{2} \coth(2\tilde{\Omega}t_l)u_l^2} \\ &\quad \times \Omega\epsilon(l)\varepsilon(l)\tilde{u}_l \left(\cosh(2\tilde{\Omega}t_l)\mathbb{1}_2 - i\frac{\theta}{2} \sinh(2\tilde{\Omega}t_l)\gamma\Theta^{-1}\gamma \right). \end{aligned}$$

This makes convergent the four-point subgraph and the two-point one. The price to pay is a counterterm of the form $i\delta m \theta \gamma \Theta^{-1} \gamma$. The proof of this last statement is given in appendix D. Remark finally that if we set $m = 0$, $\tau A_m \equiv 0$ and no $\bar{\psi}\gamma^0\gamma^1\psi$ appear.

6. Conclusion

We proved that the non-commutative Gross–Neveu model, defined by the action (2.3) with only orientable interactions, is renormalizable to all orders. We have first computed a bound on the amputated amplitude of any graph, integrated over test functions (see Lemma 4.1). This power counting is the one of a renormalizable theory. This bound can be obtained at $\Omega = 0$. Then we showed that all the necessary counterterms are of the form of the initial Lagrangian. This means that

the non-commutative Gross–Neveu model with orientable interactions is renormalizable even without the vulcanization procedure. But without general argument in favor of orientable interactions, we have to consider also non-orientable ones and then to vulcanize the Lagrangian.

The orientable Gross–Neveu model is free of (non-renormalizable) UV/IR mixing [1,23]. Nevertheless it exhibits some remaining one. It concerns some graphs of the four-point function. These ones have $g = 0$ and $B = 2$ (see Lemma 4.1). This mixing is fortunately renormalizable in the following sense: the divergent part of the critical four-point graphs is not “local” but the renormalization of the corresponding two-point function makes those four-point subgraphs finite. Of course this was not the case for the usual UV/IR mixing which prevented renormalization of non-commutative field theory before [14]. Finally note that the bounds in Lemma 4.1 may have equally been proved for the full model (with $V = V_o + V_{no}$) but restricted to orientable graphs¹¹. This suggests that the full theory could be renormalizable if restricted to orientable graphs. Of course the “locality” of the counterterms should be checked.

Appendix A. Topology of Feynman graphs

Let a graph G with n vertices and I internal lines. Interactions of quantum field theories on Moyal spaces are only cyclically invariant (see (2.6)). A good way to keep track of such a reduced invariance is to draw Feynman graphs as ribbon graphs. Moreover there exists a basis for the Schwartz class functions where the Moyal product becomes an ordinary matrix product [8, 13]. This further justifies the ribbon representation.

Let us consider the example of Figure 4. Propagators in a ribbon graph are made of double lines. Let us call L the number of loops (made of single lines) of a ribbon graph. The graph of Figure 4b has $n = 3, I = 3, L = 2$. Each ribbon graph can be drawn on a manifold of genus g . The genus is computed from the Euler characteristic $\chi = L - I + n$. For example, the graph of Figure 4b may be drawn on a manifold of genus 0. Note that some of the L loops of a graph may be “broken” by external legs. In our example, both loops are broken.

Appendix B. Integration by parts

We reproduce here the details of the computation showing that the procedure formed by the change of variables (3.28) and the integration by parts (3.30) allows

¹¹Orientable interactions only lead to orientable graphs but orientable graphs are not only made of orientable interactions. Actually non-orientable interactions produce not only all the non-orientable graphs but also orientable ones.

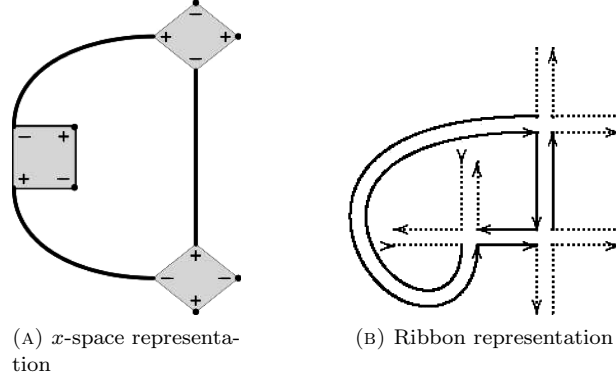


FIGURE 4. A graph with two broken faces

to get a decreasing function of the desired scale.

$$\begin{aligned}
 A_{G,l} &= \int da_l dt_l \coth(2\tilde{\Omega}t_l) \xi(a_l \coth^{1/2}(2\tilde{\Omega}t_l)) e^{-\frac{\tilde{\Omega}}{2} \coth(2\tilde{\Omega}t_l)(u_l - \varepsilon(l)a_l)^2} \\
 f_1(x_1 + \eta(1)\varepsilon(l)a_l) &\left\{ i\tilde{\Omega} \coth(2\tilde{\Omega}t_l)(\varepsilon\varepsilon)(l)(\psi_l - \varepsilon(l)\phi_l) + \Omega(\varepsilon\varepsilon)(l)(\check{\psi}_l - \varepsilon(l)\check{\phi}_l) - m \right\} \\
 &e^{i a_l \wedge (U_l + A_l + X_l)} \prod_{\mu=0}^1 \left(\frac{\coth^{1/2}(2\tilde{\Omega}t_l) + \frac{\partial}{\partial a_l^\mu}}{\coth^{1/2}(2\tilde{\Omega}t_l) + i\tilde{\mathcal{V}}_{l,\mu}} \right)^2 e^{i a_l \wedge \mathcal{V}_l} \quad (3.30)
 \end{aligned}$$

Let us write $\mathbf{c}_l = \coth(2\tilde{\Omega}t_l)$.

$$\begin{aligned}
 A_{G,l} &= \int da_l \mathbf{c}_l e^{i a_l \wedge \mathcal{V}_l} \prod_{\mu=0}^1 \left(\frac{1}{\sqrt{\mathbf{c}_l} + i\tilde{\mathcal{V}}_{l,\mu}} \right)^2 \left(\sqrt{\mathbf{c}_l} - \frac{\partial}{\partial a_l^\mu} \right)^2 \xi(a_l \sqrt{\mathbf{c}_l}) \\
 f_1(x_1 + \eta(1)\varepsilon(l)a_l) &\left\{ i\tilde{\Omega}\mathbf{c}_l(\varepsilon\varepsilon)(l)(\psi_l - \varepsilon(l)\phi_l) + \Omega(\varepsilon\varepsilon)(l)(\check{\psi}_l - \varepsilon(l)\check{\phi}_l) - m \right\} \\
 &e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l)a_l)^2 + i a_l \wedge (U_l + A_l + X_l)}.
 \end{aligned}$$

We define the following notations:

$$\{l\} = i\tilde{\Omega}\mathbf{c}_l(\varepsilon\varepsilon)(l)(\psi_l - \varepsilon(l)\phi_l) + \Omega(\varepsilon\varepsilon)(l)(\check{\psi}_l - \varepsilon(l)\check{\phi}_l) - m, \quad (B.1)$$

$$\{l\}' = -\varepsilon(l) \left(i\tilde{\Omega}\mathbf{c}_l \gamma^\mu + \tilde{\Omega}(-1)^{\mu+1} \gamma^{\mu+1} \right). \quad (B.2)$$

Let us compute the first derivative:

$$\begin{aligned} & \frac{\partial}{\partial a_l^\mu} e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \xi(a_l \sqrt{\mathbf{c}_l}) f_1(x_l + \eta(1) \varepsilon(l) a_l) \{l\} \quad (\text{B.3}) \\ &= e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \left\{ \{l\} [\tilde{\Omega} \mathbf{c}_l \varepsilon(l) (u_l - \varepsilon(l) a_l)^\mu \xi f_1 + \imath (\tilde{U}_l + \tilde{A}_l + \tilde{X}_l)_\mu \right. \\ & \quad \left. \xi f_1 + \sqrt{\mathbf{c}_l} \xi' f_1 + \eta(1) \varepsilon(l) \xi f_1'] + \{l'\} \xi f_1 \right\} \\ & \stackrel{\text{def}}{=} e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \left\{ \{l\} B_0 \Xi_0 F_0 + \{l'\} \Xi_1 F_1 \right\} + \text{subleading terms,} \quad (\text{B.4}) \end{aligned}$$

where B_0 does not depend on $a_l^{\mu+1}$ and, using a part of the exponential decrease in $u_l - \varepsilon(l) a_l$, $B_0 = \mathcal{O}(\sqrt{\mathbf{c}_l})$. Ξ_i , $i = 0, 1$ (resp. F_i) is a linear combination of ξ (resp. f_1) and its derivatives. Then let us compute the second derivative:

$$\begin{aligned} & \frac{\partial^2}{\partial (a_l^\mu)^2} e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \xi(a_l \sqrt{\mathbf{c}_l}) f_1(x_l + \eta(1) \varepsilon(l) a_l) \{l\} \quad (\text{B.5}) \\ &= e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \\ & \quad \left\{ \{l\} [(\tilde{\Omega} \mathbf{c}_l \varepsilon(l) (u_l - \varepsilon(l) a_l)^\mu \xi f_1 + \imath (\tilde{U}_l + \tilde{A}_l + \tilde{X}_l)_\mu \xi f_1 \right. \\ & \quad + \sqrt{\mathbf{c}_l} \xi' f_1 + \eta(1) \varepsilon(l) \xi f_1'] \times (\tilde{\Omega} \mathbf{c}_l \varepsilon(l) (u_l - \varepsilon(l) a_l)^\mu + \imath (\tilde{U}_l + \tilde{A}_l + \tilde{X}_l)_\mu) \\ & \quad - \tilde{\Omega} \mathbf{c}_l \varepsilon(l) \xi f_1 + \tilde{\Omega} \mathbf{c}_l^{3/2} \varepsilon(l) (u_l - \varepsilon(l) a_l)^\mu \xi' f_1 + \tilde{\Omega} \eta(1) \mathbf{c}_l (u_l - \varepsilon(l) a_l)^\mu \xi f_1' \\ & \quad + \imath \sqrt{\mathbf{c}_l} (\tilde{U}_l + \tilde{A}_l + \tilde{X}_l)_\mu \xi' f_1 + \imath \eta(1) \varepsilon(l) (\tilde{U}_l + \tilde{A}_l + \tilde{X}_l)_\mu \xi f_1' \\ & \quad + \mathbf{c}_l \xi'' f_1 + 2\sqrt{\mathbf{c}_l} \eta(1) \varepsilon(l) \xi' f_1' + \xi f_1''] + 2\{l'\} [\tilde{\Omega} \mathbf{c}_l \varepsilon(l) (u_l - \varepsilon(l) a_l)^\mu \xi f_1 \\ & \quad \left. + \imath (\tilde{U}_l + \tilde{A}_l + \tilde{X}_l)_\mu \xi f_1 + \sqrt{\mathbf{c}_l} \xi' f_1 + \eta(1) \varepsilon(l) \xi f_1'] \right\} \\ & \stackrel{\text{def}}{=} e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \left\{ \{l\} (B_1 \Xi_2^2 F_2^2 + B_2 \Xi_3 F_3) + 2\{l'\} B_3 \Xi_4 F_4 \right\} \\ & \quad + \text{subleading terms,} \quad (\text{B.6}) \end{aligned}$$

where $B_1, B_2 = \mathcal{O}(\mathbf{c}_l)$, $B_3 = \mathcal{O}(\sqrt{\mathbf{c}_l})$ and the Ξ_i 's and F_i 's are defined as above. Once more the B_i 's do not depend on $a_l^{\mu+1}$. We have

$$\begin{aligned} & \prod_{\mu=0}^1 \left(\sqrt{\mathbf{c}_l} - \frac{\partial}{\partial a_l^\mu} \right)^2 \xi f_1 \{l\} e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \quad (\text{B.7}) \\ &= \left(\mathbf{c}_l - 2\sqrt{\mathbf{c}_l} \frac{\partial}{\partial a_l^1} + \frac{\partial^2}{\partial (a_l^1)^2} \right) \left(\mathbf{c}_l \{l\} \xi f_1 - 2\sqrt{\mathbf{c}_l} (\{l\} B_0 \Xi_0 F_0 + \{l'\} \Xi_1 F_1) \right. \\ & \quad \left. + \{l\} (B_1 \Xi_2^2 F_2^2 + B_2 \Xi_3 F_3) + 2\{l'\} B_3 \Xi_4 F_4 \right) e^{-\frac{\tilde{\Omega}}{2} \mathbf{c}_l (u_l - \varepsilon(l) a_l)^2 + \imath a_l \wedge (U_l + A_l + X_l)} \\ & \quad + \text{subleading terms.} \end{aligned}$$

Remind that for all $i = 0, \dots, 3$, B_i does not depend on a_l^1 . We may now check that (B.7) is of order $\mathcal{O}(\mathbf{c}_l^{5/2})$ which gives (3.31).

Appendix C. The vacuum graphs

In this appendix, we compute the power counting of the vacuum graphs of the orientable Gross–Neveu model. Let us first remind that the translation invariance of the usual commutative field theories makes them infinite even with both ultraviolet and infrared cut-offs (we mean in a given slice). On the contrary, the vacuum graphs of the (non-commutative) Φ^4 theory are finite in a slice but the sum over their scale attribution diverges as M^{8i} .

The quartic Moyal-type interaction is translation invariant. It can indeed be written as

$$\begin{aligned} \delta(x_1 - x_2 + x_3 - x_4) \exp \iota \sum_{i < j=1}^4 (-1)^{i+j+1} x_i \wedge x_j & \quad (\text{C.1}) \\ &= \delta(x_1 - x_2 + x_3 - x_4) \exp \iota (x_1 \wedge (x_2 - x_3) + x_2 \wedge x_3) \\ &= \delta(x_1 - x_2 + x_3 - x_4) \exp \iota (x_1 - x_2) \wedge (x_2 - x_3). \end{aligned}$$

Such a regularization is then solely due to the breakdown of translation invariance by the harmonic potential term \tilde{x}^2 in the Φ^4 propagator. The Gross–Neveu propagator, whereas breaking translation invariance, allows to get translation invariant amplitudes for the vacuum graphs. We verify such an invariance by performing the change of variables $\forall i, x_i \rightarrow x_i + a$ and by checking that the result is independent a .

$$\begin{aligned} A_G &= \lambda^n \int \prod_{l \in G} du_l dv_l C_l(u_l, v_l) e^{i\varphi} & (\text{C.2}) \\ &= \lambda^n \int \prod_{l \in G} du_l dv_l C_l(u_l, v_l + 2a) e^{i\varphi}. \end{aligned}$$

In (C.2), we wrote v_l for all lines to simplify notations. We have already noticed that the vertex oscillations are translation invariant. That's why under the change of variables, φ remains unchanged. Let us consider a $\bar{\psi}\psi\bar{\psi}\psi$ type interaction. In that case, the propagator oscillations are always $\exp -i\Omega/2u_l \wedge v_l$. Then the change of variables $v_l \rightarrow v_l + 2a_l$ implies the following a dependence for any amplitude

$$\exp \iota \Omega a \wedge \sum_{l \in G} u_l = 1. \quad (\text{C.3})$$

which is 1 because the sum of all the u variables vanishes for the vacuum graphs thanks to the root delta function (2.27) (remind that we only consider orientable interactions). This proves that the vacuum graphs of the orientable Gross–Neveu model are infinite. For non-orientable interaction, this is not the case as the reader may verify on the example of Figure 5.

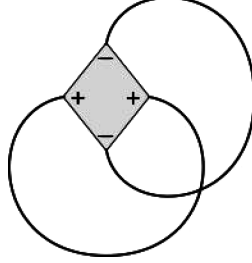


FIGURE 5. Example of non-orientable vacuum graph

Appendix D. (Un)Modified counterterms of the two-point function

Let us consider a two-point connected component $G_{k'}^j$ with a critical sub-divergent component G_k^i . We prove that, if we put the $\gamma\Theta^{-1}\gamma$ term of the lowest propagator ℓ_0 in $G_{k'}^j$ into the counterterm, the divergent part of this two-point function remains of the form of the initial Lagrangian.

For simplicity we use a lightened notation than until now: $\exp -2i\Omega t_{\ell_0} \gamma\Theta^{-1}\gamma = \cosh(2\tilde{\Omega}t_{\ell_0})\mathbb{1}_2 - i \sinh(2\tilde{\Omega}t_{\ell_0})\gamma^0\gamma^1$. As explained in Section 5.1, the propagators in a two-point function are distributed among cycles and a chain. For any given graph G , let us write \mathbf{C} for the set of all cycles and \mathbf{Ch} for the set of all chains. We also write T^μ for the number of u^μ 's coming from the Taylor expansions¹². Each cycle or chain consists in a product of propagators. Let $c \in \mathbf{C}(\mathbf{Ch})$,

$$P_c = \begin{cases} \prod_{l \in c} (i\tilde{\Omega} \coth(2\tilde{\Omega}t_l)\psi_l + m) & \text{if } \ell_0 \notin c \\ (i\tilde{\Omega} \coth(2\tilde{\Omega}t_{\ell_0})\psi_{\ell_0} + m)e^{-2i\tilde{\Omega}t_{\ell_0}\gamma^0\gamma^1} & \\ \prod_{l \in c \setminus \{\ell_0\}} (i\tilde{\Omega} \coth(2\tilde{\Omega}t_l)\psi_l + m) & \text{if } \ell_0 \in c. \end{cases} \quad (\text{D.1})$$

P_c is a sum of different terms: $P_c = \sum_{i=1}^n P_c^i$ where $n = 3^{|c|}$ if $\ell_0 \notin \mathbf{C}$ and $n = 2 \cdot 3^{|c|+1}$ if $\ell_0 \in \mathbf{C}$ ($|c| = \text{card } c$). Let us write $|\gamma^\mu|_c^i$ for the total number of γ^μ in a given term i of $c \in \mathbf{C}(\mathbf{Ch})$. In the same way, we define $|u^\mu|_c^i$. Let $i_c \in \llbracket 1, n \rrbracket$ for all $c \in \mathbf{C} \cup \mathbf{Ch}$. The tracelessness of the gamma matrices and the parity properties of the integrals over the u 's implies two constraints:

$$\forall c \in \mathbf{C}, \forall i \in \llbracket 1, 2^{|c|} \rrbracket, \forall \mu \in \{0, 1\}, |\gamma^\mu|_c^i \text{ is even}, \quad (\text{D.2})$$

$$\forall \mu \in \{0, 1\}, \sum_{c \in \mathbf{C} \cup \mathbf{Ch}} |u^\mu|_c^{i_c} + T^\mu \text{ is even}. \quad (\text{D.3})$$

¹²For example, for the mass term, the Taylor expansion brings no u 's then $T^0 = T^1 = 0$. The wave function counterterm brings $u^0\partial_0 + u^1\partial_1$. The first term has $T^0 = 1$ and $T^1 = 0$, the second the contrary.

From now on, we fix a \mathbb{N} -valued sequence $(i_c)_{c \in \mathbf{C} \cup \mathbf{Ch}}$. Remind that in a two-point function, $|\mathbf{Ch}| = 1$ and that the total number of internal lines is odd: $\sum_{c \in \mathbf{C} \cup \mathbf{Ch}} |c|$ is odd. For ℓ_0 , we will always choose its $\gamma^0 \gamma^1$ term otherwise the analysis is the same as in Section 5.2. In the following we call “mass counterterm” the expression (5.34) with the expansion (5.38), “ \not{p} (or \not{x}) counterterm” the equation (5.35) (or (5.36)) once more with the expansion (5.38).

1. Let $c_1 \in \mathbf{Ch}$. If $|c_1|$ (the number of lines in the chain) is even
 - (1.a) and $\ell_0 \in c_1$, $\sum_{c \in \mathbf{C}} |c|$ is odd. Equation (D.2) implies $\forall \mu, \sum_{c \in \mathbf{C}} |u^\mu|_c^{i_c}$ even. The total number of lines in the cycles being odd, we chose the mass for at least one line in \mathbf{C} .
 - For the mass counterterm, $T^0 = T^1 = 0$. Equation (D.3) implies $|u^\mu|_{c_1}^{i_{c_1}}$ even. This gives $|\gamma^\mu|_{c_1}^{i_{c_1}}$ both odd. The counterterm may only be proportional to $\gamma^0 \gamma^1$.
 - For the \not{p} or \not{x} counterterm, let $\mu \in \mathbb{Z}_2$, $T^\mu = 1$ and $T^{\mu+1} = 0$. $|\gamma^\mu|_{c_1}^{i_{c_1}}$ is even and $|\gamma^{\mu+1}|_{c_1}^{i_{c_1}}$ is odd. The number of lines in c_1 being even, at least one line in c_1 “chose” the mass. Then this term is of order M^{-i} . Such terms give \not{p} or \not{x} .
 - (1.b) Let $\ell_0 \notin c_1$. Equation (D.2) implies $\forall \mu, \sum_{c \in \mathbf{C}} |u^\mu|_c^{i_c}$ odd. We chose the mass term at least once.
 - Mass counterterm: $|u^\mu|_{c_1}^{i_{c_1}}$ is odd. This counterterm is proportional to $\gamma^0 \gamma^1$.
 - \not{p} (\not{x}) counterterm: $|\gamma^\mu|_{c_1}^{i_{c_1}}$ is even and $|\gamma^{\mu+1}|_{c_1}^{i_{c_1}}$ is odd. This term gives \not{p} or \not{x} but is convergent as M^{-i} since $|c_1|$ is even and at least one line in c_1 bears a mass term.
2. If $|c_1|$ is odd
 - (2.a) Let $\ell_0 \in c_1$. $\sum_{c \in \mathbf{C}} |u^\mu|_c^{i_c}$ is even.
 - Mass counterterm: $|\gamma^\mu|_{c_1}^{i_{c_1}}$'s are both odd. This gives $\bar{\psi} \gamma^0 \gamma^1 \psi$.
 - \not{p} (\not{x}) counterterm: $|\gamma^\mu|_{c_1}^{i_{c_1}}$ is even and $|\gamma^{\mu+1}|_{c_1}^{i_{c_1}}$ is odd. This term gives \not{p} or \not{x} but is convergent as $M^{-(i-j)}$. The number of lines in c_1 being odd, either all the lines in c_1 chose the u term or at least two of them chose the mass term.
 - (2.b) Let $\ell_0 \notin c_1$. $\sum_{c \in \mathbf{C}} |\gamma^\mu|_c^{i_c}$'s are both odd. Either all the lines in \mathbf{C} chose the u term (the total number of lines in \mathbf{C} is even) or at least two of them chose the mass term. The corresponding terms are of order $M^{-(i-j)}$.
 - Mass counterterm: $|\gamma^\mu|_{c_1}^{i_{c_1}}$'s are both odd. We get $\bar{\psi} \gamma^0 \gamma^1 \psi$.
 - \not{p} (\not{x}) counterterm: $|\gamma^\mu|_{c_1}^{i_{c_1}}$ is even and $|\gamma^{\mu+1}|_{c_1}^{i_{c_1}}$ is odd. This term gives \not{p} or \not{x} .

As a conclusion, the mass term only brings $\bar{\psi} \gamma^0 \gamma^1 \psi$. The \not{p} and \not{x} counterterms give $\bar{\psi} \not{p} \psi$ and $\bar{\psi} \not{x} \psi$, not present in the initial Lagrangian, but these terms are convergent

and may be let in the remainder term. A way to define the new counterterms is

$$\tau' A_m = \frac{1}{2} \text{Tr}(\tau A_m), \quad (\text{D.4})$$

$$\tau' A_{\delta m} = -\frac{1}{2} \gamma^0 \gamma^1 \text{Tr}(\gamma^0 \gamma^1 \tau A_m), \quad (\text{D.5})$$

$$\tau' A_{\not{p}} = -\frac{\not{p}}{2p^2} \text{Tr}(\not{p} \tau A_{\not{p}}), \quad (\text{D.6})$$

$$\tau' A_{\not{x}} = -\frac{\not{x}}{2\widehat{x}^2} \text{Tr}(\not{x} \tau A_{\not{x}}). \quad (\text{D.7})$$

Remark that if $m = 0$, $\tau A_m \equiv 0$. This means that if the bare mass is zero, it remains zero after radiative corrections and no $\bar{\psi} \gamma^0 \gamma^1 \psi$ appear.

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Fabien Vignes-Tourneret
Laboratoire de Physique Théorique
Bât. 210, CNRS UMR 8627
Université Paris XI
F-91405 Orsay Cedex
France
e-mail: Fabien.Vignes@th.u-psud.fr

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