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New oscillation criteria for higher order delay dynamic equations on time scales

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Abstract

In this paper, we investigate the oscillation of the following higher order delay dynamic equation: $\{a_n(t)[(a_{n-1}(t)(\cdots(a_1(t)x^\Delta(t))^\Delta\cdots)^\Delta)^\Delta]^\alpha\}^\Delta + g(t,x(\tau(t))) = 0$ on any time scale $\mathbf{T}$ with $\sup\mathbf{T} = \infty$. Here $n \geq 2$, $a_k(t) \in C_{\mathrm{rd}}(\mathbf{T},(0,\infty))$ $(1 \leq k \leq n)$, $\tau : \mathbf{T} \to \mathbf{T}$ is an increasing differentiable function with $\tau(t) \leq t$ and $\lim_{t\to\infty}\tau(t) = \infty$, $g \in C(\mathbf{T} \times \mathbf{R}, \mathbf{R})$ with $g(t,x)/x^\beta \geq q(t)$ for some $q(t) \in C_{\mathrm{rd}}(\mathbf{T},(0,\infty))$ when $x \neq 0$, and $\alpha \geq 1$, $\beta \geq 1$ are two quotients of odd positive integers. We give sufficient conditions under which every solution of this equation is either oscillatory or tends to zero.
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Keywords: oscillation; dynamic equation; time scale

1 Introduction

In this paper, we investigate the oscillation of the following higher order delay dynamic equation:

$$\{a_n(t)\big[\big(a_{n-1}(t)\big(\cdots\big(a_1(t)x^\Delta(t)\big)^\Delta\cdots\big)^\Delta\big)^\Delta\big]^\alpha\}^\Delta + g\big(t,x\big(\tau(t)\big)\big) = 0 \qquad (E)$$

on some time scale $\mathbf{T}$. Here $n \geq 2$, $a_k(t) \in C_{\mathrm{rd}}(\mathbf{T},(0,\infty))$ $(1 \leq k \leq n)$, $\tau : \mathbf{T} \to \mathbf{T}$ is an increasing differentiable function with $\tau(t) \leq t$ and $\lim_{t\to\infty}\tau(t) = \infty$, $g \in C(\mathbf{T} \times \mathbf{R}, \mathbf{R})$ with $g(t,x)/x^\beta \geq q(t)$ for some $q(t) \in C_{\mathrm{rd}}(\mathbf{T},(0,\infty))$ when $x \neq 0$, and $\alpha \geq 1$, $\beta \geq 1$ are two quotients of odd positive integers. Write

$$S_k\big(t,x(t)\big) = \begin{cases} x(t), & \text{if } k = 0, \\ a_k(t)S_{k-1}^\Delta(t,x(t)), & \text{if } 1 \leq k \leq n-1, \\ a_n(t)[S_{n-1}^\Delta(t,x(t))]^\alpha, & \text{if } k = n, \end{cases}$$

then (E) reduces to the equation

$$S_n^\Delta\big(t,x(t)\big) + g\big(t,x\big(\tau(t)\big)\big) = 0. \qquad (1.1)$$

Since we are interested in the oscillatory behavior of solutions near infinity, we assume that $\sup\mathbf{T} = \infty$ and $t_0 \in \mathbf{T}$ is a constant. We define the time scale interval $[a,\infty)_{\mathbf{T}} = \{t \in \mathbf{T} : t \geq a\}$. A nontrivial real-valued function x is said to be a solution of (1.1) if $x \in C_{\mathrm{rd}}([T_x,\infty)_{\mathbf{T}},\mathbf{R})$, $T_x \geq t_0$, which has the property that $S_k(t,x) \in C_{\mathrm{rd}}^1([T_x,\infty)_{\mathbf{T}},\mathbf{R})$ for

$1 \leq k \leq n$, and satisfies (1.1) on $[T_x, \infty)_{\mathbf{T}}$. The solutions vanishing in some neighborhood of infinity will be excluded from our consideration. A solution x of (1.1) is said to be oscillatory if it is neither eventually positive nor eventually negative, otherwise it is called nonoscillatory. The theory of time scales, which has recently received a lot of attention, was introduced by Stefan Hilger in [1] in order to unify continuous and discrete analysis. The cases when a time scale $\mathbf{T}$ is equal to $\mathbf{R}$ or the set of all integers $\mathbf{Z}$ represent the classical theories of differential and difference equations. Many results concerning differential equations carry over quite easily to corresponding results for difference equations, while other results seem to be completely different from their continuous counterparts. The study of dynamic equations on time scales reveals such discrepancies, and it helps avoid proving results twice-once for differential equations and once again for difference equations. The general is to prove a result for a dynamic equation where the domain of the unknown function is a time scale $\mathbf{T}$. In this way results not only related to the set of real numbers or set of integers but those pertaining to more general time scales are obtained. Therefore, not only can the theory of dynamic equations unify the theories of differential equations and difference equations, but it also extends these classical cases to cases 'in between', *e.g.*, to the so-called q-difference equations when $\mathbf{T} = \{1, q, q^2, \ldots, q^n, \ldots\}$, which has important applications in quantum theory (see [2]). In this work, knowledge and understanding of time scales and time scale notation are assumed, for an excellent introduction to the calculus on time scales; see Bohner and Peterson [3, 4]. In recent years, there has been much research activity concerning the oscillation and asymptotic behavior of solutions of some dynamic equations on time scales.

In [5], Hassan studied the third-order dynamic equation

$$\left(a(t)\left\{\left[r(t)x^{\Delta}(t)\right]^{\Delta}\right\}^{\gamma}\right)^{\Delta} + f\left(t, x\left(\tau(t)\right)\right) = 0 \tag{1.2}$$

on a time scale $\mathbf{T}$, where $\gamma \geq 1$ is the quotient of odd positive integers, a and r are positive rd-continuous functions on $\mathbf{T}$, and the so-called delay function $\tau : \mathbf{T} \to \mathbf{T}$ satisfies $\tau(t) \leq t$ for $t \in \mathbf{T}$ and $\lim_{t \to \infty} \tau(t) = \infty$ and $f \in C(\mathbf{T} \times \mathbf{R}, \mathbf{R})$ and obtained some oscillation criteria, which improved and extended the results that have been established in [6–8].

Li *et al.* in [9] also discussed the oscillation of (1.2), where $\gamma > 0$ is the quotient of odd positive integers, $f \in C(\mathbf{T} \times \mathbf{R}, \mathbf{R})$ is assumed to satisfy $uf(t, u) > 0$ for $u \neq 0$ and there exists a positive rd-continuous function p on $\mathbf{T}$ such that $\frac{f(t,u)}{u^{\gamma}} \geq p(t)$ for $u \neq 0$. They established some new sufficient conditions for the oscillation of (1.2).

Wang and Xu in [10] extended the Hille and Nehari oscillation theorems to the third-order dynamic equation

$$\left(r_2(t)\left(\left(r_1(t)x^{\Delta}(t)\right)^{\Delta}\right)^{\gamma}\right)^{\Delta} + q(t)f\left(x(t)\right) = 0$$

on a time scale $\mathbf{T}$, where $\gamma \geq 1$ is a ratio of odd positive integers and the functions $r_i(t)$ ($i = 1, 2$), $q(t)$ are positive real-valued rd-continuous functions defined on $\mathbf{T}$.

Erbe *et al.* in [11] were concerned with the oscillation of the third-order nonlinear functional dynamic equation

$$\left(a(t)\left[\left(r(t)x^{\Delta}(t)\right)^{\Delta}\right]^{\gamma}\right)^{\Delta} + f\left(t, x\left(g(t)\right)\right) = 0$$

on a time scale $\mathbf{T}$, where γ is the quotient of odd positive integers, a and r are positive rd-continuous functions on $\mathbf{T}$, and $g : \mathbf{T} \to \mathbf{T}$ satisfies $\lim_{t\to\infty} g(t) = \infty$ and $f \in C(\mathbf{T} \times \mathbf{R}, \mathbf{R})$. The authors obtained some new oscillation criteria and extended many known results for oscillation of third-order dynamic equations.

Qi and Yu in [12] obtained some oscillation criteria for the fourth-order nonlinear delay dynamic equation

$$x^{\Delta^4}(t) + p(t)x^\gamma\big(\tau(t)\big) = 0$$

on a time scale $\mathbf{T}$, where γ is the ratio of odd positive integers, p is a positive real-valued rd-continuous function defined on $\mathbf{T}$, $\tau \in C_{\mathrm{rd}}(\mathbf{T}, \mathbf{T})$, $\tau(t) \le t$, and $\lim_{t\to\infty} \tau(t) = \infty$.

Grace *et al.* in [13] were concerned with the oscillation of the fourth-order nonlinear dynamic equation

$$x^{\Delta^4}(t) + q(t)x^\lambda(t) = 0 \tag{1.3}$$

on a time scale $\mathbf{T}$, where λ is the ratio of odd positive integers, q is a positive real-valued rd-continuous function defined on $\mathbf{T}$. They reduced the problem of the oscillation of all solutions of (1.3) to the problem of oscillation of two second-order dynamic equations and gave some conditions to ensure that all bounded solutions of (1.3) are oscillatory.

Grace *et al.* in [14] established some new criteria for the oscillation of the fourth-order nonlinear dynamic equation

$$\big(a(t)x^{\Delta^2}(t)\big)^{\Delta^2} + f\big(t, x^\sigma(t)\big) = 0, \quad t \ge t_0,$$

where a is a positive real-valued rd-continuous function satisfying $\int_{t_0}^\infty \frac{\sigma(s)}{a(s)} \Delta s < \infty$, $f : [t_0, \infty)_{\mathbf{T}} \times \mathbf{R} \to \mathbf{R}$ is continuous satisfying $\mathrm{sgn} f(t, x) = \mathrm{sgn}\, x$ and $f(t, x) \le f(t, y)$ for $x \le y$ and $t \ge t_0$. They also investigate the case of strongly superlinear and the case of strongly sublinear equations subject to various conditions.

Agarwal *et al.* in [15] were concerned with oscillatory behavior of a fourth-order half-linear delay dynamic equation with damping

$$\big(r(t)\big(x^{\Delta^3}(t)\big)^\gamma\big)^\Delta + p(t)\big(x^{\Delta^3}(t)\big)^\gamma + q(t)x^\gamma\big(\tau(t)\big) = 0 \tag{1.4}$$

on a time scale $\mathbf{T}$ with $\sup \mathbf{T} = \infty$, where λ is the ratio of odd positive integers, r, p, q are positive real-valued rd-continuous functions defined on $\mathbf{T}$, $r(t) - \mu(t)p(t) \ne 0$, $\tau \in C_{\mathrm{rd}}(\mathbf{T}, \mathbf{T})$, $\tau(t) \le t$ and $\tau(t) \to \infty$ as $t \to \infty$. They established some new oscillation criteria of (1.4).

Zhang *et al.* in [16] concerned with the oscillation of a fourth-order nonlinear dynamic equation

$$\big(p(t)x^{\Delta^3}(t)\big)^\Delta + q(t)f\big(x\big(\sigma(t)\big)\big) = 0 \tag{1.5}$$

on an arbitrary time scale $\mathbf{T}$ with $\sup \mathbf{T} = \infty$, where $p, q \in C_{\mathrm{rd}}(\mathbf{T}, (0, \infty))$ with $\int_{t_0}^\infty \frac{1}{p(s)} \Delta s < \infty$ and there exists a positive constant L such that $\frac{f(y)}{y} \ge L$ for all $y \ne 0$, they gave a new oscillation result of (1.5).

In [17], Sun *et al.* studied the following higher order dynamic equation:

$$S_n^\Delta\big(t, x(t)\big) + p(t)x^\beta(t) = 0$$

and established some new oscillation criteria.

For much research concerning the oscillation and nonoscillation of solutions of higher order dynamic equations on time scales, please refer to the literature [18–27].

2 Some lemmas

In order to obtain the main results of this paper, we need the following lemmas.

Lemma 2.1 [28] *Assume that*

$$\int_{t_0}^{\infty}\left[\frac{1}{a_n(s)}\right]^{\frac{1}{\alpha}}\Delta s = \int_{t_0}^{\infty}\frac{\Delta s}{a_i(s)} = \infty \quad \textit{for all } 1 \le i \le n-1, \tag{2.1}$$

and integer $m \in [1, n]$. *Then*:

(1) $\liminf_{t\to\infty} S_m(t, x(t)) > 0$ *implies* $\lim_{t\to\infty} S_i(t, x(t)) = \infty$ *for* $i \in [0, m-1]$.
(2) $\limsup_{t\to\infty} S_m(t, x(t)) < 0$ *implies* $\lim_{t\to\infty} S_i(t, x(t)) = -\infty$ *for* $i \in [0, m-1]$.

Lemma 2.2 [28] *Assume that* (2.1) *holds. If* $S_n^\Delta(t, x(t)) < 0$ *and* $x(t) > 0$ *for* $t \ge t_0$, *then there exists an integer* $m \in [0, n]$ *such that*:

(1) $m + n$ *is even.*
(2) $(-1)^{m+i}S_i(t, x(t)) > 0$ *for* $t \ge t_0$ *and* $i \in [m, n]$.
(3) *If* $m \ge 1$, *then there exists* $T \ge t_0$ *such that* $S_i(t, x(t)) > 0$ *for* $t \ge T$ *and* $i \in [1, m-1]$.

Lemma 2.3 [28] *Assume that* (2.1) *holds. Furthermore, suppose that*

$$\int_{t_0}^{\infty}\frac{1}{a_{n-1}(u)}\left\{\int_u^{\infty}\left[\frac{1}{a_n(s)}\int_s^{\infty}q(v)\Delta v\right]^{\frac{1}{\alpha}}\Delta s\right\}\Delta u = \infty. \tag{2.2}$$

If x *is an eventually positive solution of* (1.1), *then there exists sufficiently large* $T \ge t_0$ *such that*:

(1) $S_n^\Delta(t, x(t)) < 0$ *for* $t \ge T$.
(2) *Either* $\lim_{t\to\infty} x(t) = 0$ *or* $S_i(t, x(t)) > 0$ *for* $t \ge T$ *and* $0 \le i \le n$.

Lemma 2.4 [28] *Assume that* x *is an eventually positive solution of* (1.1). *If there exists* $T \ge t_0$ *such that*:

(1) $S_n^\Delta(t, x(t)) < 0$ *for* $t \ge T$.
(2) $S_i(t, x(t)) > 0$ *for* $t \ge T$ *and* $0 \le i \le n$.
Then

$$S_i\big(t, x(t)\big) \ge S_n^{\frac{1}{\alpha}}\big(t, x(t)\big)B_{i+1}(t, T) \quad \textit{for } 0 \le i \le n-1 \textit{ and } t \ge T \tag{2.3}$$

and there exist $T_1 > T$ *and a constant* $c > 0$ *such that*

$$x(t) \le cB_1(t, T) \quad \textit{for } t \ge T_1, \tag{2.4}$$

where

$$B_i(t, T) = \begin{cases} \int_T^t [\frac{1}{a_n(s)}]^{\frac{1}{\alpha}} \Delta s, & \text{if } i = n, \\ \int_T^t \frac{B_{i+1}(s,T)}{a_i(s)} \Delta s, & \text{if } 1 \le i \le n - 1. \end{cases} \tag{2.5}$$

Lemma 2.5 [3] *Let $f : \mathbf{R} \to \mathbf{R}$ be continuously differentiable and suppose that $g : \mathbf{T} \to \mathbf{R}$ is delta differentiable. Then $f \circ g$ is delta differentiable and*

$$(f \circ g)^\Delta(t) = g^\Delta(t) \int_0^1 f'\big(hg(t) + (1 - h)g^\sigma(t)\big) \, dh.$$

Lemma 2.6 [17] *If A, B are nonnegative numbers and $\lambda > 1$, then*

$$A^\lambda - \lambda AB^{\lambda-1} + (\lambda - 1)B^\lambda \ge 0.$$

Lemma 2.7 [29] *Assume that U, V are constants and $\gamma \ge 1$ is the quotient of odd positive integers. Then*

$$(U - V)^{1+\frac{1}{\gamma}} \ge U^{1+\frac{1}{\gamma}} + \frac{1}{\gamma} V^{1+\frac{1}{\gamma}} - \left(1 + \frac{1}{\gamma} V^{\frac{1}{\gamma}} U\right).$$

3 Main results

Throughout this paper, we assume that:

(1) $\tau \circ \sigma = \sigma \circ \tau$, where the forward jump operator $\sigma : \mathbf{T} \to \mathbf{T}$ by $\sigma(t) = \inf\{s \in \mathbf{T} : s > t\}$.

(2) $\Phi : \mathbf{T} \to (0, \infty)$ and $\phi : \mathbf{T} \to [0, \infty)$ such that $\Phi(t)$ and $a(t)\phi(t)$ are differentiable.

Write

$$h_1(t, T) = \frac{B_2(t, T)}{a_1(t)},$$

$$h_2(t, T) = h_1(t, T)B_1^{\alpha-1}\big(\sigma(t), T\big) = h_1(t, T)\big(B_1^{\alpha-1}(t, T)\big)^\sigma,$$

$$\delta_1(t, T, c_1, c_2) = \begin{cases} c_1, c_1 \text{ are any positive constant,} & \text{if } \alpha < \beta, \\ 1, & \text{if } \alpha = \beta, \\ c_2 B_1^{\beta-\alpha}(\sigma(t), T), c_2 \text{ are any positive constant,} & \text{if } \alpha > \beta, \end{cases} \tag{3.1}$$

$$\delta_2(t, T, c_1, c_2) = \begin{cases} c_1, c_1 \text{ are any positive constant,} & \text{if } \alpha < \beta, \\ 1, & \text{if } \alpha = \beta, \\ c_2 B_1^{\frac{\beta}{\alpha}-1}(\sigma(t), T), c_2 \text{ are any positive constant,} & \text{if } \alpha > \beta, \end{cases} \tag{3.2}$$

$$g_1(t, T, c_1, c_2) = \Phi^\Delta(t) + 2\beta \Phi(t)\tau^\Delta(t)h_2\big(\tau(t), T\big)\delta_1\big(\tau(t), T, c_1, c_2\big)\big(a_n(t)\phi(t)\big)^\sigma,$$

$$g_2(t, T, c_1, c_2) = \Phi^\Delta(t) + \left(1 + \frac{1}{\alpha}\right)\beta \Phi(t)\tau^\Delta(t)h_1\big(\tau(t), T\big)$$

$$\times \delta_2\big(\tau(t), T, c_1, c_2\big)\big(\big(a_n(t)\phi(t)\big)^\sigma\big)^{\frac{1}{\alpha}},$$

$$G_1(t, T, c_1, c_2) = \Phi(t)q(t) - \Phi(t)\big(a_n(t)\phi(t)\big)^\Delta + \beta \Phi(t)\tau^\Delta(t)h_2\big(\tau(t), T\big)$$

$$\times \delta_1\big(\tau(t), T, c_1, c_2\big)\big(\big(a_n(t)\phi(t)\big)^\sigma\big)^2,$$

$$G_2(t, T, c_1, c_2) = \Phi(t)q(t) - \Phi(t)\big(a_n(t)\phi(t)\big)^\Delta + \frac{\beta}{\alpha} \Phi(t)\tau^\Delta(t)h_1\big(\tau(t), T\big)$$

$$\times \delta_2\big(\tau(t), T, c_1, c_2\big)\big(\big(a_n(t)\phi(t)\big)^\sigma\big)^{1+\frac{1}{\alpha}},$$

$$g_+ = \max\{0, g\}, \qquad g_- = \min\{0, -g\},$$

$$X(t) = \left\{ a_n(t) \left[\frac{[S_{n-1}^\Delta(t, x(t))]^\alpha}{x^\beta(\tau(t))} + \phi(t) \right] \right\}^\sigma.$$

Theorem 3.1 *Suppose that* (2.1) *and* (2.2) *hold. If there exist differentiable functions* $\Phi : \mathbf{T} \to (0, \infty)$ *and* $\phi : \mathbf{T} \to [0, \infty)$ *with* $a_n(t)\phi(t)$ *being differentiable such that for all sufficiently large* $T \in [t_0, \infty)_{\mathbf{T}}$ *and for any positive constants* c_1, c_2, *there is a* $T_1 > T$ *with* $\tau(T_1) > T$ *such that*

$$\limsup_{t \to \infty} \int_{T_1}^t \left[G_1(s, T, c_1, c_2) - \frac{g_1^2(s, T, c_1, c_2)}{4\beta\Phi(s)\tau^\Delta(s)h_2(\tau(s), T)\delta_1(\tau(s), T, c_1, c_2)} \right] \Delta s = \infty, \quad (3.3)$$

then every solution of (1.1) *is either oscillatory or tends to* 0.

Proof Assume that (1.1) has a nonoscillatory solution x on $[t_0, \infty)_{\mathbf{T}}$. Then, without loss of generality, there is a sufficiently large $t_1 \geq t_0$ such that $x(t) > 0$ for $t \geq t_1$. Therefore from Lemma 2.3, we know that there exists sufficiently large $T \geq t_1$ such that:

(1) $S_n^\Delta(t, x(t)) < 0$ for $t \geq T$.

(2) Either $\lim_{t \to \infty} x(t) = 0$ or $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$.

Let $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$. Consider

$$w(t) = \Phi(t)a_n(t)\left[\frac{(S_{n-1}^\Delta(t, x(t)))^\alpha}{x^\beta(\tau(t))} + \phi(t) \right]. \quad (3.4)$$

Then $X(t) = w^\sigma(t)/\Phi^\sigma(t)$ and $w(t) > 0$ for $t \geq T$.

By the product rule and the quotient rule

$$w^\Delta(t) = \frac{\Phi(t)}{x^\beta(\tau(t))}S_n^\Delta(t, x(t)) + \left[\frac{\Phi(t)}{x^\beta(\tau(t))} \right]^\Delta S_n^\sigma(t, x(t))$$

$$+ \Phi(t)[a_n(t)\phi(t)]^\Delta + \Phi^\Delta(t)[a_n(t)\phi(t)]^\sigma.$$

Since $g(t, x(\tau(t)))/x^\beta(\tau(t)) \geq q(t)$ ($x(t) > 0$), we get

$$w^\Delta(t) \leq -\Phi(t)q(t) + \Phi(t)[a_n(t)\phi(t)]^\Delta + \Phi^\Delta(t)X(t)$$

$$- \Phi(t)\left[\frac{(x^\beta(\tau(t)))^\Delta}{x^\beta(\tau(t))} \right]\left[\frac{S_n(t, x(t))}{x^\beta(\tau(t))} \right]^\sigma. \quad (3.5)$$

Using the fact that x and τ are differentiable functions and $\tau \circ \sigma = \sigma \circ \tau$, we see that $x \circ \tau$ is a differentiable function and $(x(\tau(t)))^\Delta = x^\Delta(\tau(t))\tau^\Delta(t)$. Note $\beta \geq 1$. From Lemma 2.5, we get

$$\big(x^\beta(\tau(t))\big)^\Delta \geq \beta x^{\beta-1}(\tau(t))x^\Delta(\tau(t))\tau^\Delta(t),$$

which implies

$$w^\Delta(t) \leq -\Phi(t)q(t) + \Phi(t)[a_n(t)\phi(t)]^\Delta + \Phi^\Delta(t)X(t)$$

$$- \beta\Phi(t)\tau^\Delta(t)\frac{x^\Delta(\tau(t))}{x(\tau(t))}\left[\frac{S_n(t, x(t))}{x^\beta(\tau(t))} \right]^\sigma. \quad (3.6)$$

We choose $t_2 \geq T$ such that $\tau(t) > T$ for $t \geq t_2$. Then, from (2.3) and the fact that $S_n^{\Delta}(t, x(t)) < 0$ for $t \geq T$, we get

$$
\begin{aligned}
x^{\Delta}\big(\tau(t)\big) &\geq S_n^{\frac{1}{\alpha}}\big(\tau(t), x(t)\big)\frac{B_2(\tau(t), T)}{a_1(\tau(t))} \\
&\geq \big[S_n^{\frac{1}{\alpha}}\big(t, x(t)\big)\big]^{\sigma} h_1\big(\tau(t), T\big) \\
&= h_1\big(\tau(t), T\big)\big(a_n^{\frac{1}{\alpha}}(t)S_{n-1}^{\Delta}\big(t, x(t)\big)\big)^{\sigma} &&(3.7) \\
&= h_1\big(\tau(t), T\big)\left[\frac{S_n(t, x(t))}{x^{\beta}(\tau(t))}\right]^{\sigma}\left[\frac{x^{\beta}(\tau(t))}{S_n^{\frac{\alpha-1}{\alpha}}(\tau(t, x(t)))}\right]^{\sigma}. &&(3.8)
\end{aligned}
$$

From (2.3), we have

$$
x(t) \geq S_n^{\frac{1}{\alpha}}\big(t, x(t)\big)B_1(t, T).
$$

Thus

$$
S_n^{\frac{\alpha-1}{\alpha}}\big(\tau(t), x(t)\big) \leq \frac{x^{\alpha-1}(\tau(t))}{B_1^{\alpha-1}(\tau(t), T)},
$$

which combines with (3.8) to imply

$$
x^{\Delta}\big(\tau(t)\big) \geq h_2\big(\tau(t), T\big)\left[\frac{(S_n(t, x(t)))}{x^{\beta}(\tau(t))}\right]^{\sigma}\left[\frac{x^{\beta}(\tau(t))}{x^{\alpha-1}(\tau(t))}\right]^{\sigma}. \tag{3.9}
$$

Combining (3.9) with (3.6) and from $\frac{x^{\sigma}(\tau(t))}{x(\tau(t))} \geq 1$, we obtain that

$$
\begin{aligned}
w^{\Delta}(t) &\leq -\Phi(t)q(t) + \Phi(t)\big[a_n(t)\phi(t)\big]^{\Delta} + \Phi^{\Delta}(t)X(t) \\
&\quad - \beta\Phi(t)\tau^{\Delta}(t)h_2\big(\tau(t), T\big)\left[\frac{x^{\beta}(\tau(t))}{x^{\alpha}(\tau(t))}\right]^{\sigma}\left\{\left[\frac{S_n(t, x(t))}{x^{\beta}(\tau(t))}\right]^{\sigma}\right\}^2.
\end{aligned}
$$

Now we consider the following three cases.

Case (i). If $\alpha < \beta$, then $x^{\Delta}(t) > 0$ for $t \geq T$ and $x(t) \geq x(T) = b_1 > 0$. Thus

$$
\big(x^{\beta-\alpha}\big(\tau(t)\big)\big)^{\sigma} \geq b_1^{\beta-\alpha} = c_1 > 0 \quad \text{for } t \geq t_2.
$$

Case (ii). If $\alpha = \beta$, then

$$
\big(x^{\beta-\alpha}\big(\tau(t)\big)\big)^{\sigma} = 1 \quad \text{for } t \geq t_2.
$$

Case (iii). If $\alpha > \beta$, then from (2.4) we get that there exist $t_3 > t_2$ and a constant $c > 0$ such that

$$
x(t) \leq cB_1(t, T) \quad \text{for } t \geq t_3.
$$

Thus

$$
\big(x^{\beta-\alpha}\big(\tau(t)\big)\big)^{\sigma} \geq c_2\big(B_1^{\beta-\alpha}\big(\tau(t), T\big)\big)^{\sigma} \quad \text{for } t \geq t_3,
$$

where $c_2 = c^{\beta-\alpha} > 0$.

We obtain from the above that

$$\left(\frac{x^\beta(\tau(t))}{x^\alpha(\tau(t))}\right)^\sigma \geq \delta_1(\tau(t), T, c_1, c_2).$$

Thus

$$w^\Delta(t) \leq -\Phi(t)q(t) + \Phi(t)\big[a_n(t)\phi(t)\big]^\Delta + \Phi^\Delta(t)X(t)$$
$$- \beta\Phi(t)\tau^\Delta(t)h_2\big(\tau(t), T\big)\delta_1\big(\tau(t), T, c_1, c_2\big)\left\{\left[\frac{S_n(t, x(t))}{x^\beta(\tau(t))}\right]^\sigma\right\}^2. \tag{3.10}$$

Since

$$\left[\left(\frac{S_n(t, x(t))}{x^\beta(\tau(t))}\right)^\sigma\right]^2 = \big(X(t) - \big(a_n(t)\phi(t)\big)^\sigma\big)^2$$
$$= X^2(t) - 2\big(a_n(t)\phi(t)\big)^\sigma X(t) + \big(\big(a_n(t)\phi(t)\big)^\sigma\big)^2, \tag{3.11}$$

from (3.10) and (3.11) and the definitions of $G_1(t, T, c_1, c_2)$ and $g_1(t, T, c_1, c_2)$, we get

$$w^\Delta(t) \leq -G_1(t, T, c_1, c_2) + g_1(t, T, c_1, c_2)X(t)$$
$$- \beta\Phi(t)\tau^\Delta(t)h_2\big(\tau(t), T\big)\delta_1\big(\tau(t), T, c_1, c_2\big)X^2(t). \tag{3.12}$$

It is easy to check that

$$w^\Delta(t) \leq -G_1(t, T, c_1, c_2) + \frac{g_1^2(t, T, c_1, c_2)}{4\beta\Phi(t)\tau^\Delta(t)h_2(\tau(t), T)\delta_1(\tau(t), T, c_1, c_2)}.$$

Integrating both sides of the above inequality from t_3 to t, we get

$$\int_{t_3}^t \left[G_1(s, T, c_1, c_2) - \frac{g_1^2(s, T, c_1, c_2)}{4\beta\Phi(s)\tau^\Delta(s)h_2(\tau(s), T)\delta_1(\tau(s), T, c_1, c_2)}\right]\Delta s$$
$$\leq w(t_3) - w(t) \leq w(t_3),$$

which leads to a contradiction to (3.3). The proof is completed. □

Theorem 3.2 *Suppose that* (2.1) *and* (2.2) *hold. If there exist differentiable functions* $\Phi : \mathbf{T} \to (0, \infty)$ *and* $\phi : \mathbf{T} \to [0, \infty)$ *with* $a_n(t)\phi(t)$ *being differentiable such that for all sufficiently large* $T \in [t_0, \infty)_{\mathbf{T}}$ *and for any positive constants* c_1, c_2, *there is a* $T_1 > T$ *with* $\tau(T_1) > T$ *such that*

$$\limsup_{t \to \infty} \int_{T_1}^t \left[G_2(s, T, c_1, c_2) - \frac{\alpha^\alpha((g_2(s, T, c_1, c_2))_+)^{1+\alpha}}{(1+\alpha)^{1+\alpha}(\beta\Phi(s)\tau^\Delta(s)h_1(\tau(s), T)\delta_2(\tau(s), T, c_1, c_2))^\alpha}\right]\Delta s$$
$$= \infty, \tag{3.13}$$

then every solution of (1.1) *is either oscillatory or tends to* 0.

Proof Assume that (1.1) has a nonoscillatory solution x on $[t_0, \infty)_{\mathbf{T}}$. Then, without loss of generality, there is a sufficiently large $t_1 \geq t_0$ such that $x(t) > 0$ for $t \geq t_1$. Therefore from Lemma 2.3, we know that there exists sufficiently large $T \geq t_1$ such that:

(1) $S_n^\Delta(t, x(t)) < 0$ for $t \geq T$.

(2) Either $\lim_{t \to \infty} x(t) = 0$ or $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$.

Let $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$. From (3.7), we get

$$x^\Delta(\tau(t)) \geq \left[S_n^{\frac{1}{\alpha}}(t, x(t)) \right]^\sigma h_1(\tau(t), T)$$

$$= h_1(\tau(t), T)\left(x^{\frac{\beta}{\alpha}}(\tau(t)) \right)^\sigma \left\{ \left[\frac{S_n(t, x(t))}{x^\beta(\tau(t))} \right]^\sigma \right\}^{\frac{1}{\alpha}}. \tag{3.14}$$

Define $w(t)$ as (3.4). Choosing $t_2 \geq T$ such that $\tau(t) > T$ for $t \geq t_2$. Combining (3.14) with (3.6), we see that for $t \in [t_2, \infty)_{\mathbf{T}}$,

$$w^\Delta(t) \leq -\Phi(t)q(t) + \Phi(t)\left[a_n(t)\phi(t) \right]^\Delta + \Phi^\Delta(t)X(t)$$

$$- \beta \Phi(t)\tau^\Delta(t)h_1(\tau(t), T)\left\{ \left[\frac{S_n(t, x(t))}{x^\beta(\tau(t))} \right]^\sigma \right\}^{1+\frac{1}{\alpha}} \frac{\left(x^{\frac{\beta}{\alpha}}(\tau(t)) \right)^\sigma}{x(\tau(t))}.$$

Note $x(\tau(t)) \leq (x(\tau(t)))^\sigma$ since $x^\Delta(t) > 0$, we obtain

$$w^\Delta(t) \leq -\Phi(t)q(t) + \Phi(t)\left[a_n(t)\phi(t) \right]^\Delta + \Phi^\Delta(t)X(t)$$

$$- \beta \Phi(t)\tau^\Delta(t)h_1(\tau(t), T)\left(\left(\frac{S_n(t, x(t))}{x^\beta(\tau(t))} \right)^\sigma \right)^{1+\frac{1}{\alpha}} \left(x^{\frac{\beta-\alpha}{\alpha}}(\tau(t)) \right)^\sigma.$$

Now we consider the following three cases.

Case (i). If $\alpha < \beta$, then

$$\left(x^{\frac{\beta-\alpha}{\alpha}}(\tau(t)) \right)^\sigma \geq x^{\frac{\beta-\alpha}{\alpha}}(T) = c_1 > 0 \quad \text{for } t \geq t_2$$

since $x^\Delta(t) > 0$ for $t \geq T$.

Case (ii). If $\alpha = \beta$, then

$$\left(x^{\frac{\beta-\alpha}{\alpha}}(\tau(t)) \right)^\sigma = 1 \quad \text{for } t \geq t_2.$$

Case (iii). If $\alpha > \beta$, then we get from (2.4) that there exist $t_3 > t_2$ and a constant $c > 0$ such that

$$x(\tau(t)) \leq cB_1(\tau(t), T) \quad \text{for } t \geq t_3.$$

Thus

$$\left(x^{\frac{\beta-\alpha}{\alpha}}(\tau(t)) \right)^\sigma \geq c_2 \left(B_1^{\frac{\beta-\alpha}{\alpha}}(\tau(t), T) \right)^\sigma \quad \text{for } t \geq t_3,$$

where $c_2 = c^{\frac{\beta-\alpha}{\alpha}} > 0$.

We obtain from the above

$$\left(x^{\frac{\beta-\alpha}{\alpha}}(\tau(t)) \right)^\sigma \geq \delta_2(\tau(t), T, c_1, c_2).$$

Then

$$w^{\Delta}(t) \leq -\Phi(t)q(t) + \Phi(t)\big[a_n(t)\phi(t)\big]^{\Delta} + \Phi^{\Delta}(t)X(t)$$
$$- \beta\Phi(t)\tau^{\Delta}(t)h_1\big(\tau(t),T\big)\delta_2\big(\tau(t),T,c_1,c_2\big)\left\{\left[\frac{S_n(t,x(t))}{x^{\beta}(\tau(t))}\right]^{\sigma}\right\}^{1+\frac{1}{\alpha}}. \tag{3.15}$$

From Lemma 2.7, we have

$$\left(\left(\frac{S_n(t,x(t))}{x^{\beta}(\tau(t))}\right)^{\sigma}\right)^{1+\frac{1}{\alpha}} = \big(X(t) - \big(a_n(t)\phi(t)\big)^{\sigma}\big)^{1+\frac{1}{\alpha}}$$
$$\geq X^{1+\frac{1}{\alpha}}(t) + \frac{1}{\alpha}\big(a_n^{\sigma}(t)\phi^{\sigma}(t)\big)^{1+\frac{1}{\alpha}}$$
$$- \left(1+\frac{1}{\alpha}\right)\big(a_n^{\sigma}(t)\phi^{\sigma}(t)\big)^{\frac{1}{\alpha}}X(t). \tag{3.16}$$

Combining (3.16) with (3.15) and the definitions of $G_2(t,T,c_1,c_2)$ and $g_2(t,T,c_1,c_2)$, we get

$$w^{\Delta}(t) \leq -G_2(t,T,c_1,c_2) + g_2(t,T,c_1,c_2)X(t)$$
$$- \beta\Phi(t)\tau^{\Delta}(t)h_1\big(\tau(t),T\big)\delta_2\big(\tau(t),T,c_1,c_2\big)X^{1+\frac{1}{\alpha}}(t)$$
$$\leq -G_2(t,T,c_1,c_2) + \big(g_2(t,T,c_1,c_2)\big)_+ X(t)$$
$$- \beta\Phi(t)\tau^{\Delta}(t)h_1\big(\tau(t),T\big)\delta_2\big(\tau(t),T,c_1,c_2\big)X^{1+\frac{1}{\alpha}}(t). \tag{3.17}$$

Let

$$A^{1+\frac{1}{\alpha}} = \beta\Phi(t)\tau^{\Delta}(t)h_1\big(\tau(t),T\big)\delta_2\big(\tau(t),T,c_1,c_2\big)X^{1+\frac{1}{\alpha}}(t), \tag{3.18}$$

$$B^{\frac{1}{\alpha}} = \frac{\alpha(g_2(t,T,c_1,c_2))_+}{(1+\alpha)(\beta\Phi(t)\tau^{\Delta}(t)h_1(\tau(t),T)\delta_2(\tau(t),T,c_1,c_2))^{\frac{\alpha}{\alpha+1}}}. \tag{3.19}$$

We have from Lemma 2.6

$$\big(g_2(t,T,c_1,c_2)\big)_+ X(t) - \beta\Phi(t)\tau^{\Delta}(t)h_1\big(\tau(t),T\big)\delta_2\big(\tau(t),T,c_1,c_2\big)X^{1+\frac{1}{\alpha}}(t)$$
$$\leq \frac{\alpha^{\alpha}((g_2(t,T,c_1,c_2))_+)^{1+\alpha}}{(1+\alpha)^{1+\alpha}(\beta\Phi(t)\tau^{\Delta}(t)h_1(\tau(t),T)\delta_2(\tau(t),T,c_1,c_2))^{\alpha}}.$$

Then

$$w^{\Delta}(t) \leq -G_2(t,T,c_1,c_2) + \frac{\alpha^{\alpha}((g_2(t,T,c_1,c_2))_+)^{1+\alpha}}{(1+\alpha)^{1+\alpha}(\beta\Phi(t)\tau^{\Delta}(t)h_1(\tau(t),T)\delta_2(\tau(t),T,c_1,c_2))^{\alpha}}.$$

Integrating both sides of the above inequality from t_3 to t, we get

$$\int_{t_3}^{t}\left[G_2(s,T,c_1,c_2) - \frac{\alpha^{\alpha}((g_2(s,T,c_1,c_2))_+)^{1+\alpha}}{(1+\alpha)^{1+\alpha}(\beta\Phi(s)\tau^{\Delta}(s)h_1(\tau(s),T)\delta_2(\tau(s),T,c_1,c_2))^{\alpha}}\right]\Delta s$$
$$\leq w(t_3) - w(t) \leq w(t_3),$$

which leads to a contradiction to (3.13). The proof is completed. $\qquad\square$

4 Further results

For convenience, let $D = \{(t,s) \in \mathbf{T}^2 : t \geq s \geq t_0, t, s \in [t_0, \infty)_{\mathbf{T}}\}$. For any function $G : \mathbf{T}^2 \to \mathbf{R}$, denote by G^{Δ_s} the partial derivative of $G(t,s)$ with respect to s. Define

$$\Im^* = \left\{ G \in C_{\mathrm{rd}}\big(D, [0,\infty)\big) : G(s,s) = 0, G(t,s) > 0, G^{\Delta_s} \leq 0, t > s \geq t_0 \right\}.$$

Theorem 4.1 *Suppose that* (2.1) *and* (2.2) *hold. If there exist functions* $r, R \in \Im^*$ *and differentiable functions* $\Phi : \mathbf{T} \to (0, \infty)$ *and* $\phi : \mathbf{T} \to [0, \infty)$ *with* $a_n(t)\phi(t)$ *being differentiable such that for all sufficiently large* $T \in [t_0, \infty)_{\mathbf{T}}$ *and for any positive constants* c_1, c_2, *there is a* $T_1 > T$ *with* $\tau(T_1) > T$ *such that*

$$R^{\Delta_s}(t,s) + \frac{R(t,s)g_1(s,T,c_1,c_2)}{\Phi^\sigma(s)} = \frac{r(t,s)}{\Phi^\sigma(s)} R^{\frac{1}{2}}(t,s) \tag{4.1}$$

and

$$\limsup_{t \to \infty} \frac{1}{R(t,T_1)} \int_{T_1}^t \left[R(t,s)G_1(s,T,c_1,c_2) \right.$$
$$\left. - \frac{r^2(t,s)}{4\beta \Phi(s)\tau^\Delta(s)h_2(\tau(s),T)\delta_1(\tau(s),T,c_1,c_2)} \right] \Delta s = \infty, \tag{4.2}$$

then every solution of (1.1) *is either oscillatory or tends to* 0.

Proof Assume that (1.1) has a nonoscillatory solution x on $[t_0, \infty)_{\mathbf{T}}$. Then, without loss of generality, there is a sufficiently large $t_1 \geq t_0$ such that $x(t) > 0$ for $t \geq t_1$. Therefore from Lemma 2.3, we know that there exists sufficiently large $T \geq t_1$ such that:

(1) $S_n^\Delta(t, x(t)) < 0$ for $t \geq T$.

(2) Either $\lim_{t \to \infty} x(t) = 0$ or $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$.

Let $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$. Define $w(t)$ as (3.4). Choosing $t_2 \geq T$ such that (3.12) holds for $t \geq t_2$. Then for $t \in [t_2, \infty)_{\mathbf{T}}$

$$G_1(t, T, c_1, c_2)$$
$$\leq -w^\Delta(t) + g_1(t, T, c_1, c_2)X(t)$$
$$- \beta \Phi(t)\tau^\Delta(t)h_2\big(\tau(t), T\big)\delta_1\big(\tau(t), T, c_1, c_2\big)X^2(t). \tag{4.3}$$

In (4.3), replace t by s and multiply both sides by $R(t,s)$, integrate with respect to s from t_2 to $t > t_2$, we have

$$\int_{t_2}^t R(t,s)G_1(s, T, c_1, c_2)\Delta s$$
$$\leq -\int_{t_2}^t R(t,s)w^\Delta(s)\Delta s + \int_{t_2}^t R(t,s)g_1(s, T, c_1, c_2)X(s)\Delta s$$
$$- \int_{t_2}^t R(t,s)\beta \Phi(s)\tau^\Delta(s)h_2\big(\tau(s), T\big)\delta_1\big(\tau(s), T, c_1, c_2\big)X^2(s)\Delta s.$$

Integrating by parts and using (4.1), we get

$$
\int_{t_2}^{t} R(t,s)G_1(s, T, c_1, c_2)\Delta s
$$

$$
\leq R(t, t_2)w(t_2) + \int_{t_2}^{t} \left[r(t,s)R^{\frac{1}{2}}(t,s)X(s) \right.
$$

$$
\left. - R(t,s)\beta\Phi(s)\tau^{\Delta}(s)h_2\big(\tau(s), T\big)\delta_1\big(\tau(s), T, c_1, c_2\big)X^2(s) \right]\Delta s.
$$

This implies

$$
\int_{t_2}^{t} R(t,s)G_1(s, T, c_1, c_2)\Delta s
$$

$$
\leq R(t, t_2)w(t_2) + \int_{t_2}^{t} \frac{r^2(t,s)}{4\beta\Phi(s)\tau^{\Delta}(s)h_2(\tau(s), T)\delta_1(\tau(s), T, c_1, c_2)}\Delta s.
$$

Thus

$$
\frac{1}{R(t, t_2)}\int_{t_2}^{t}\left[R(t,s)G_1(s, T) - \frac{r^2(t,s)}{4\beta\Phi(s)\tau^{\Delta}(s)h_2(\tau(s), T)\delta_1(\tau(s), T, c_1, c_2)} \right]\Delta s \leq w(t_2),
$$

which leads to a contradiction to (4.2). The proof is completed. $\square$

Theorem 4.2 *Suppose that* (2.1) *and* (2.2) *hold. If there exist functions* $r, R \in \Im^*$ *and differentiable functions* $\Phi : \mathbf{T} \to (0, \infty)$ *and* $\phi : \mathbf{T} \to [0, \infty)$ *with* $a_n(t)\phi(t)$ *being differentiable such that for all sufficiently large* $T \in [t_0, \infty)_{\mathbf{T}}$ *and for any positive constants* c_1, c_2, *there is a* $T_1 > T$ *with* $\tau(T_1) > T$ *such that*

$$
R^{\Delta_s}(t,s) + \frac{R(t,s)g_2(s, T, c_1, c_2)}{\Phi^{\sigma}(s)} = \frac{r(t,s)}{\Phi^{\sigma}(s)}R^{\frac{\alpha}{1+\alpha}}(t,s) \tag{4.4}
$$

and

$$
\limsup_{t \to \infty} \frac{1}{R(t, T_1)}\int_{T_1}^{t}\left[R(t,s)G_2(s, T, c_1, c_2) \right.
$$

$$
\left. - \frac{\alpha^{\alpha}(r^2(t,s))^{1+\alpha}}{(1+\alpha)^{1+\alpha}(\beta\Phi(s)\tau^{\Delta}(s)h_2(\tau(s), T)\delta_1(\tau(s), T, c_1, c_2))^{\alpha}} \right]\Delta s = \infty, \tag{4.5}
$$

then every solution of (1.1) *is either oscillatory or tends to* 0.

Proof Assume that (1.1) has a nonoscillatory solution x on $[t_0, \infty)_{\mathbf{T}}$. Then, without loss of generality, there is a sufficiently large $t_1 \geq t_0$ such that $x(t) > 0$ for $t \geq t_1$. Therefore from Lemma 2.3, we know that there exists sufficiently large $T \geq t_1$ such that:

(1) $S_n^{\Delta}(t, x(t)) < 0$ for $t \geq T$.

(2) Either $\lim_{t \to \infty} x(t) = 0$ or $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$.

Let $S_i(t, x(t)) > 0$ for $t \geq T$ and $0 \leq i \leq n$. Define $w(t)$ as (3.4). Choosing $t_2 \geq T$ such that (3.17) holds for $t \geq t_2$. Then for $t \in [t_2, \infty)_{\mathbf{T}}$, we have

$$
G_2(t, T, c_1, c_2) \leq -w^{\Delta}(t) + \frac{g_2(t, T, c_1, c_2)}{\Phi^{\sigma}(t)}w^{\sigma}(t)
$$

$$
- \beta\Phi(t)\tau^{\Delta}(t)h_1\big(\tau(t), T\big)\delta_1\big(\tau(t), T, c_1, c_2\big)X^{(1+\frac{1}{\alpha})}(t). \tag{4.6}
$$

In (4.6), replace t by s and multiply both sides by $R(t,s)$ and integrate with respect to s from t_2 to $t > t_2$, it follows that

$$\int_{t_2}^{t} R(t,s) G_2(s, T, c_1, c_2) \Delta s$$

$$\leq - \int_{t_2}^{t} R(t,s) w^{\Delta}(s) \Delta s + \int_{t_2}^{t} R(t,s) \frac{g_2(s, T, c_1, c_2)}{\Phi^{\sigma}(s)} w^{\sigma}(s) \Delta s$$

$$- \int_{t_2}^{t} R(t,s) \beta \Phi(s) \tau^{\Delta}(s) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2) X^{(1+\frac{1}{\alpha})}(s) \Delta s.$$

Integrating by parts and using (4.4), we get

$$\int_{t_2}^{t} R(t,s) G_2(s, T, c_1, c_2) \Delta s$$

$$\leq R(t, t_2) w(t_2) + \int_{t_2}^{t} \Big[r_+(t,s) R^{\frac{\alpha}{1+\alpha}}(t,s) X(s)$$

$$- \beta R(t,s) \Phi(s) \tau^{\Delta}(s) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2) X^{(1+\frac{1}{\alpha})}(s) \Big] \Delta s. \tag{4.7}$$

Let

$$A^{1+\frac{1}{\alpha}} = \beta R(t,s) \Phi(s) \tau^{\Delta}(s) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2) X^{1+\frac{1}{\alpha}}(s), \tag{4.8}$$

$$B^{\frac{1}{\alpha}} = \frac{\alpha r_+(t,s)}{(1+\alpha)(\beta \Phi(s) \tau^{\Delta}(s) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2))^{\frac{\alpha}{\alpha+1}}}. \tag{4.9}$$

From Lemma 2.6, we have

$$\int_{t_2}^{t} \Big[r_+(t,s) R^{\frac{\alpha}{1+\alpha}}(t,s) X(s) - \beta R(t,s) \Phi(s) \tau^{\Delta}(s) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2) X^{1+\frac{1}{\alpha}}(s) \Big] \Delta s$$

$$\leq \int_{t_2}^{t} \frac{\alpha^{\alpha} (r_+(t,s))^{1+\alpha}}{(1+\alpha)^{1+\alpha} (\beta \Phi(s) \tau^{\Delta}(s) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2))^{\alpha}} \Delta s,$$

which implies

$$\int_{t_2}^{t} \Bigg[R(t,s) G_2(s, T, c_1, c_2)$$

$$- \frac{\alpha^{\alpha} (r_+(t,s))^{1+\alpha}}{(1+\alpha)^{1+\alpha} (\beta \Phi(s) \tau^{\Delta}(s) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2))^{\alpha}} \Bigg] \Delta s \leq R(t, t_2) w(t_2).$$

Then

$$\frac{1}{R(t, t_2)} \int_{t_2}^{t} \Bigg[R(t,s) G_2(s, T, c_1, c_2)$$

$$- \frac{\alpha^{\alpha} (r_+(t,s))^{1+\alpha}}{(1+\alpha)^{1+\alpha} (\beta \Phi(s) \tau^{\Delta}(t) h_1(\tau(s), T) \delta_2(\tau(s), T, c_1, c_2))^{\alpha}} \Bigg] \Delta s \leq w(t_2),$$

which leads to a contradiction to (4.2). The proof is completed. $\qquad\square$

5 Example

In this section, we give an example to illustrate our main results.

Example 5.1 Consider the following higher order dynamic equation:

$$S_n^\Delta\big(t, x(t)\big) + \frac{\gamma}{t^{\beta+1}} x^{\beta+1}\big(\tau(t)\big) = 0 \tag{5.1}$$

on time scale $\mathbf{T} = \{0\} \cup \{1/2^k : k = 1, 2, 3, \ldots\} \cup \{2^k : k = 1, 2, 3, \ldots\}$, where $n \geq 2$, $S_k(t)$ ($0 \leq k \leq n$) is as in (1.1) with $a_n(t) = t^\alpha$, $a_{n-1}(t) = \cdots = a_1(t) = 1$, $q(t) = \frac{\gamma}{t^{\beta+1}}$, $\gamma > 1/2^{1-\beta}$, $0 < \beta < 1$, $t_0 = 4$, and $\tau(t) = t/2$. Then $\tau^\Delta(t) = 1/2$ and the forward jump operator $\sigma(t) = 2t$ satisfies $\sigma(\tau(t)) = \tau(\sigma(t))$. Thus

$$\int_{t_0}^\infty \left(\frac{1}{a_n(s)}\right)^{\frac{1}{\alpha}} \Delta s = \int_{t_0}^\infty \frac{\Delta s}{s} = \infty,$$

$$\int_{t_0}^\infty \frac{\Delta s}{a_i(s)} = \int_{t_0}^\infty \Delta s = \infty,$$

$$\int_{t_0}^\infty \frac{1}{a_{n-1}(t)} \left\{ \int_t^\infty \left[\frac{1}{a_n(s)} \int_s^\infty q(u) \Delta u \right]^{\frac{1}{\alpha}} \Delta s \right\} \Delta t$$

$$= \int_{t_0}^\infty \left\{ \int_t^\infty \left[\frac{1}{s^\alpha} \int_s^\infty \frac{\gamma}{u^{\beta+1}} \Delta u \right]^{\frac{1}{\alpha}} \Delta s \right\} \Delta t$$

$$\geq \left(\frac{\gamma}{\beta}\right)^{\frac{1}{\alpha}} \int_{t_0}^\infty \left\{ \int_t^\infty \left[\frac{1}{s^\alpha} \int_s^\infty \frac{(u^\beta)^\Delta}{u^\beta (u^\beta)^\sigma} \Delta u \right]^{\frac{1}{\alpha}} \Delta s \right\} \Delta t$$

$$= \left(\frac{\gamma}{\beta}\right)^{\frac{1}{\alpha}} \int_{t_0}^\infty \left[\int_t^\infty \frac{\Delta s}{ss^{\frac{\beta}{\alpha}}} \right] \Delta t \geq \left(\frac{\gamma}{\beta}\right)^{\frac{1}{\alpha}} \int_{t_0}^\infty \left[\int_t^\infty \frac{\Delta s}{ss^\sigma} \right] \Delta t$$

$$= \left(\frac{\gamma}{\beta}\right)^{\frac{1}{\alpha}} \int_{t_0}^\infty \frac{1}{t} \Delta t = \infty.$$

Therefore (2.1) and (2.2) hold. Note that

$$\lim_{t\to\infty} B_n(t, T) = \lim_{t\to\infty} \int_T^t \left[\frac{1}{a_n(s)} \right]^{\frac{1}{\alpha}} \Delta s = \lim_{t\to\infty} \int_T^t \frac{1}{s} \Delta s = \infty.$$

It is easy to check that

$$\lim_{t\to\infty} B_2(t, T) = \lim_{t\to\infty} B_1\big(\sigma(t), T\big) = \infty$$

and

$$\lim_{t\to\infty} h_2(t, T) = \lim_{t\to\infty} h_1\big(\sigma(t), T\big) = \infty.$$

Then for any positive constants c_1, c_2, there is a sufficiently large t_1 such that $(B_1(\tau(t), T))^\sigma > 1$ for $t \geq t_1$, $h_1(\tau(t), T) \geq 1/c_2$, and $h_2(\tau(t), T) \geq \max\{1, 1/c_1\}$ for $t \geq t_1$,

$$h_2\big(\tau(t), T\big) \delta_1\big(\tau(t), T, c_1, c_2\big) = \begin{cases} c_1 h_2(\tau(t), T) \geq 1, & \text{if } \alpha < \beta + 1, \\ h_2(\tau(t), T) \geq 1, & \text{if } \alpha = \beta + 1, \\ c_2 h_1(\tau(t), T)(B_1^\beta(\tau(t), T))^\sigma \geq 1, & \text{if } \alpha > \beta + 1. \end{cases}$$

Choosing $\phi(t) = 0$ and $\Phi(t) = t$. Then $g_1(t, T, c_1, c_2) = \Phi^\Delta(t) = 1$ and $G_1(t, T, c_1, c_2) = \Phi(t)q(t) = \frac{\gamma}{t^\beta}$. Thus

$$
\limsup_{t \to \infty} \int_{T_1}^t \left[G_1(s, T, c_1, c_2) - \frac{g_1^2(s, T, c_1, c_2)}{4(\beta + 1)\Phi(s)\tau^\Delta(s)h_2(\tau(s), T)\delta_1(\tau(s), T, c_1, c_2)} \right] \Delta s
$$

$$
\geq \limsup_{t \to \infty} \int_{T_1}^t \left(\frac{\gamma}{s^\beta} - \frac{1}{2(\beta + 1)} \frac{1}{s} \right) \Delta s \geq \limsup_{t \to \infty} \int_{T_1}^t \frac{1}{2s} \Delta s = \infty.
$$

The conditions of Theorem 3.1 are satisfied. Then every solution of (5.1) is either oscillatory or tends to 0.

Remark 5.1 If $\beta = 0$, then the conditions of Theorem 3.1 are also satisfied and every solution of (5.1) is also either oscillatory or tends to 0.

Remark 5.2 In Example 5.1, let $R(t, s) = r(t, s) = 1$ for $t > s \geq 4$ and $R(t, t) = r(t, t) = 0$ for $t \geq 4$. Then the conditions of Theorem 4.1 are satisfied. It also follows from Theorem 4.1 that every solution of (5.1) is either oscillatory or tends to 0.

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