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Linear Algebra and its Applications 395 (2005) 361–365

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## Some stability properties of T. Chan's preconditioner

Che-Man Cheng\*, Xiao-Qing Jin<sup>1</sup>*Department of Mathematics, Faculty of Science & Technology, University of Macau, Macao, China*

Received 23 April 2004; accepted 9 September 2004

Submitted by E. Tyrtyshnikov

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### Abstract

A matrix is said to be stable if the real parts of all the eigenvalues are negative. In this paper, for any matrix  $A_n$ , we give some sufficient and necessary conditions for the stability of T. Chan's preconditioner  $c_U(A_n)$ .

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*AMS classification:* 65F10; 65F15

*Keywords:* T. Chan's preconditioner; Stability

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### 1. Introduction

In 1988, T. Chan [5] proposed a circulant preconditioner for solving Toeplitz systems. In 1991, R. Chan et al. [3] showed that T. Chan's preconditioner can be defined not only for Toeplitz matrices but also for general matrices. We begin with the general case. Given a unitary matrix  $U \in \mathbb{C}^{n \times n}$ , define

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\* Corresponding author.

*E-mail addresses:* [fstcmc@umac.mo](mailto:fstcmc@umac.mo) (C.-M. Cheng), [xqjin@umac.mo](mailto:xqjin@umac.mo) (X.-Q. Jin).

<sup>1</sup> The research of this author is supported by the research grant No. RG064/03-04S/JXQ/FST from the University of Macau.

$$\mathcal{M}_U \equiv \{U^* A_n U \mid A_n \text{ is any } n\text{-by-}n \text{ diagonal matrix}\}. \tag{1}$$

For any matrix  $A_n \in \mathbb{C}^{n \times n}$ , T. Chan’s preconditioner  $c_U(A_n) \in \mathcal{M}_U$  satisfies

$$\|c_U(A_n) - A_n\| = \min_{W_n \in \mathcal{M}_U} \|W_n - A_n\|,$$

where  $\|\cdot\|$  is the Frobenius norm. Let  $F$  denote the Fourier matrix whose entries are given by

$$(F)_{j,k} = \frac{1}{\sqrt{n}} e^{2\pi i(j-1)(k-1)/n}, \quad i \equiv \sqrt{-1}, \quad 1 \leq j, k \leq n. \tag{2}$$

If  $U = F$  in (1), then  $\mathcal{M}_U$  is the set of all circulant matrices, see [6].

It has been proved that T. Chan’s preconditioner is a good preconditioner for solving a large class of linear systems, see [4,5,9]. In this paper, we will study some stability properties of T. Chan’s preconditioner. The stability property is essential in control theory and dynamical systems [1].

**Definition 1.** A matrix is said to be stable if the real parts of all the eigenvalues are negative.

Now, we introduce some symbols and review some results. For any matrix  $E \in \mathbb{C}^{n \times n}$ , let  $\lambda_j(E)$  be the  $j$ th eigenvalue of  $E$  and  $\delta(E)$  denote the diagonal matrix whose diagonal is equal to the diagonal of  $E$ . For T. Chan’s preconditioner, we have the following important lemma, see [3,8,9,12].

**Lemma 1.** Let  $A_n \in \mathbb{C}^{n \times n}$ ,  $U \in \mathbb{C}^{n \times n}$  be unitary and  $c_U(A_n)$  be T. Chan’s preconditioner. Then

(i)  $c_U(A_n)$  is uniquely determined by  $A_n$  and is given by

$$c_U(A_n) \equiv U^* \delta(U A_n U^*) U.$$

(ii) If  $A_n$  is Hermitian, then  $c_U(A_n)$  is also Hermitian. Moreover, we have

$$\min_j \lambda_j(A_n) \leq \min_j \lambda_j(c_U(A_n)) \leq \max_j \lambda_j(c_U(A_n)) \leq \max_j \lambda_j(A_n).$$

From Lemma 1(ii), it is easy to see that if  $A_n$  is Hermitian and stable, then so is  $c_U(A_n)$ . In [11], Jin et al. show that if  $A_n$  is normal and stable, then  $c_U(A_n)$  is also normal and stable. The result is further generalized in [2] by Cai and Jin. They prove that if  $A_n$  is  $*$ -congruent to a stable diagonal matrix, i.e.,  $A_n = Q^* D Q$  where  $Q$  is a nonsingular matrix and  $D$  is a stable diagonal matrix, then  $c_U(A_n)$  is stable.

Now, the problem we are facing is that for any given matrix  $A_n$ , how to judge its T. Chan’s preconditioner  $c_U(A_n)$  is stable? In this paper, we try to give some sufficient and necessary conditions for the stability of  $c_U(A_n)$ .

## 2. Main results

Let  $A_n \in \mathbb{C}^{n \times n}$ . A well-known fact [7] is that  $A_n$  can be decomposed as

$$A_n = H + iK,$$

where  $H$  and  $K$  are Hermitian matrices given by

$$H \equiv \frac{1}{2}(A_n + A_n^*), \quad K \equiv \frac{1}{2i}(A_n - A_n^*)$$

and are called the Hermitian part and skew-Hermitian part of  $A_n$ , respectively. We have the following main results.

**Theorem 1.** *Let  $A_n \in \mathbb{C}^{n \times n}$  and suppose that  $A_n = H + iK$  where  $H$  and  $K$  are Hermitian. Then  $T$ . Chan's preconditioner  $c_U(A_n)$  is stable for any unitary matrix  $U \in \mathbb{C}^{n \times n}$  if and only if  $H$  is negative definite.*

**Proof.** For any unitary matrix  $U$ , we have by Lemma 1(i),

$$c_U(A_n) = U^* \delta(U A_n U^*) U.$$

With  $A_n = H + iK$ , we obtain

$$\begin{aligned} c_U(A_n) &= U^* \delta(U(H + iK)U^*) U \\ &= U^* \delta(UHU^* + iUKU^*) U \\ &= U^* [\delta(UHU^*) + i\delta(UKU^*)] U. \end{aligned}$$

As  $UHU^*$  and  $UKU^*$  are Hermitian matrices, their diagonal elements are real. Thus, we see that the real parts of the eigenvalues of  $c_U(A_n)$  are just the diagonal elements of  $UHU^*$ . Now if  $H$  is negative definite, then, for any unitary matrix  $U$ ,  $UHU^*$  has all the diagonal elements being negative and consequently  $c_U(A_n)$  is stable.

Conversely, if  $H$  has a nonnegative eigenvalue, by choosing a unitary matrix  $V$  such that  $VHV^*$  is diagonal, we see that  $VHV^*$  has a nonnegative diagonal element and consequently,  $c_V(A_n)$  is not stable.  $\square$

**Theorem 2.** *Let  $A_n \in \mathbb{C}^{n \times n}$  and suppose that  $A_n = H + iK$  where  $H$  and  $K$  are Hermitian. Then there exists a unitary matrix  $U \in \mathbb{C}^{n \times n}$  such that  $c_U(A_n)$  is stable if and only if*

$$\operatorname{tr}(H) = \operatorname{Re}[\operatorname{tr}(A_n)] < 0,$$

where  $\operatorname{Re}[\cdot]$  denotes the real part of a complex number and  $\operatorname{tr}(\cdot)$  denotes the trace of a matrix.

**Proof.** “ $\Rightarrow$ ”: Suppose  $c_U(A_n)$  is stable. Then we see from the proof of Theorem 1 that  $UHU^*$  has all the diagonal elements being negative and so

$$\operatorname{Re}[\operatorname{tr}(A_n)] = \operatorname{tr}(H) = \operatorname{tr}(UHU^*) < 0.$$

“ $\Leftarrow$ ”: In view of the proof of Theorem 1, it suffices to show that there exists a unitary matrix  $V$  such that  $VHV^*$  has all diagonal entries being negative, as these diagonal entries are the real parts of the eigenvalues of  $c_V(A_n)$ .

Note that if

$$D = \operatorname{diag}(\mu_1, \dots, \mu_n)$$

is a diagonal matrix and  $U$  is any unitary matrix, then the diagonal of  $UDU^*$ , say

$$[d_{11}, d_{22}, \dots, d_{nn}]^T,$$

is given by

$$\begin{bmatrix} d_{11} \\ \vdots \\ d_{nn} \end{bmatrix} = (U \circ \bar{U}) \begin{bmatrix} \mu_1 \\ \vdots \\ \mu_n \end{bmatrix},$$

where “ $\circ$ ” denotes the Hadamard product. We remark that for  $P = [p_{ij}] \in \mathbb{C}^{m \times n}$ ,  $Q = [q_{ij}] \in \mathbb{C}^{m \times n}$ , their Hadamard product is given by

$$P \circ Q = [p_{ij}q_{ij}] \in \mathbb{C}^{m \times n}.$$

As  $H$  is Hermitian, let  $W$  be a unitary matrix that diagonalizes  $H$ , i.e.,

$$WHW^* = \operatorname{diag}(\lambda_1, \dots, \lambda_n).$$

Let  $V = FW$  where  $F$  is the Fourier matrix given by (2), and let

$$[h_{11}, h_{22}, \dots, h_{nn}]^T$$

be the diagonal of  $VHV^*$ . Then

$$\begin{aligned} \begin{bmatrix} h_{11} \\ \vdots \\ h_{nn} \end{bmatrix} &= (F \circ \bar{F}) \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{bmatrix} = \frac{1}{n} \begin{bmatrix} 1 & \dots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{bmatrix} \\ &= \frac{\sum_{j=1}^n \lambda_j}{n} \mathbf{1}_n = \frac{\operatorname{tr}(H)}{n} \mathbf{1}_n, \end{aligned}$$

where  $\mathbf{1}_n = [1, 1, \dots, 1]^T$ . As  $\operatorname{tr}(H) < 0$ , we see that

$$c_V(A_n) = V^*[\delta(VHV^*) + i\delta(VKV^*)]V$$

is stable.  $\square$

We include here an application of Theorem 1. The details can be found in [2]. When solving by a boundary value method scheme the initial value problem associated to a system of first order linear differential equations

$$\mathbf{y}'(t) = J\mathbf{y}(t) + \mathbf{g}(t),$$

one needs to solve a linear system  $My = b$ . A preconditioner  $S$  for the system  $My = b$  is defined in term of  $c_F(J)$ . This preconditioner  $S$  is invertible when  $c_F(J)$  is stable. In [2],  $J$  is assumed to be  $*$ -congruent to a stable normal matrix to assure the stability of  $c_F(J)$ . Here, by Theorem 1, one obtains the stability of  $c_F(J)$  by assuming negative the eigenvalues of the Hermitian part of  $J$ , which is a simpler condition. For the asymptotically stable solution of some system of functional differential equations [10], it is known that the Hermitian part of the system has negative eigenvalues and consequently we may use the preconditioner  $S$  to speed up the computation.

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