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Volume 163, No. 1 (2000), in the article "Verification by Augmented Finitary Abstraction," by Yonit Kesten and Amir Pnueli, pages 203–243, doi:10.1006/inco.2000.3000): On page 213, line 24, replace the formula $x_{\Box p} \Leftrightarrow \chi(p) \lor x'_{\Box p}$ with the formula $x_{\Box p} \Leftrightarrow \chi(p) \land x'_{\Box p}$.

On page 214, line 3, replace Θ_{φ} : $f_1 \wedge \neg f_3$ with Θ_{φ} : $u = 0 \wedge f_1 \wedge \neg f_3$.

On page 220, beginning of Section 6.2, replace "In the various..." with "In the previous...."

On page 223, lines 7, replace the formula

$$\sim (\exists V : V_A = \mathcal{E}^{\alpha}(V) \land p(V)) \land (\exists V : V_A = \mathcal{E}^{\alpha}(V) \land q(V)), \text{ with the formula}$$
$$\sim \exists V : V_A = \mathcal{E}^{\alpha}(V) \land p(V) \lor \exists V : V_A = \mathcal{E}^{\alpha}(V) \land q(V).$$

On page 224, line 4 replace

 $\alpha^{-}(p \wedge q)$ is equivalent to $\alpha^{-}(p) \wedge \alpha^{-}(q)$ with $\alpha^{-}(p \vee q)$ is equivalent to $\alpha^{-}(p) \vee \alpha^{-}(q)$.

On page 225, line 32, replace the formula

$$\forall V: V_A = \mathcal{E}^{\alpha}(V) \to p(V) \land \forall V: V_A = \mathcal{E}^{\alpha}(V) \to \forall V: V_A = \mathcal{E}^{\alpha}(V) \land p(V)$$

with the formula

$$\forall V: V_A = \mathcal{E}^{\alpha}(V) \to p(V) \land \exists V: V_A = \mathcal{E}^{\alpha}(V) \to \exists V: V_A = \mathcal{E}^{\alpha}(V) \land p(V).$$

On page 230, third paragraph of Section 7.2, replace "a *ranking monitor* or a ranking function . . . " with "a *ranking monitor* for a ranking function. . . . "

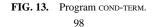
On page 241, beginning of Section 10, replace "We have presented a method or verification..." with "We have presented a method for verification...."

Replace Section 8.2 by the Section that follows:

8.2. A Characteristic Example

The whole construction will be illustrated by a single example. Consider the program COND-TERM, presented in Fig. 13.

```
y: \text{ natural} \ x: \{-1, 1\}
\ell_0: \text{ while } y > 0 \text{ do} \ \left[ \begin{array}{c} \ell_1: \ x := \pm 1 \\ \ell_2: \ y := y + x \end{array} 
ight]
\ell_3:
```





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Statement ℓ_1 of this program nondeterministically assigns to variable *x* one of the values -1, 1. Program COND-TERM does not always terminate. In particular, it will not terminate if statement ℓ_1 always assigns to *x* the value 1. Consequently, the best we can claim for this program is the property of conditional termination which can be specified by

$$\psi \colon \Diamond \Box \ (x < 0) \to \Diamond \ at _\ell_3.$$

This property states that if, from a certain point on, x remains negative, then the program will terminate. It is not difficult to see that this property is valid for program COND-TERM.

Since program COND-TERM is a sequential program, it is associated with no fairness requirement. Therefore, step 2 which shifts the fairness requirements from the system to the property is vacuous, and we have that $\mathcal{D}^- = \mathcal{D}$ and $\Psi = \psi$.

Step 3 of the proof scheme constructs a temporal tester $T_{\neg \Psi}$, which characterizes all the sequences violating ψ .

Following the construction described in Section 4, we obtain the BDS $T_{\neg\psi}$, given by

$$V: \quad \pi: \text{natural}; \quad x: \{-1, 1\}; \quad f_1, g_2, f_3: \text{boolean}; \quad u: [0..3]$$

$$\Theta_{\neg \psi}: \quad u = 0 \land f_1 \land \neg f_3$$

$$\begin{pmatrix} f_1 \quad \leftrightarrow \quad g_2 \quad \lor \quad f_1' \quad \land \\ g_2 \quad \leftrightarrow \quad x < 0 \quad \land \quad g_2' \quad \land \\ f_3 \quad \leftrightarrow \quad at_\ell_3 \quad \lor \quad f_3' \quad \land \\ f_3 \quad \leftrightarrow \quad at_\ell_3 \quad \lor \quad f_3' \quad \land \\ f_3 \quad \leftrightarrow \quad at_\ell_3 \quad \lor \quad f_3' \quad \land \\ f_3 \quad \leftrightarrow \quad at_\ell_3 \quad \lor \quad f_3' \quad \land \\ f_3 \quad \leftrightarrow \quad at_\ell_3 \quad \lor \quad f_3' \quad \land \\ g_2 \quad \leftrightarrow \quad f_3 \quad \land g_2' \quad \land \\ f_3 \quad \leftrightarrow \quad at_\ell_3 \lor \quad f_3' \quad \land \\ u = 0 \quad :1; \\ u = 1 \land (g_2 \lor \neg f_1) \quad :2; \\ u = 2 \land (x \ge 0 \lor g_2) \quad :3; \\ u = 3 \land (at_\ell_3 \lor \neg f_3):0; \\ true \quad :u; \\ esac \quad :u = 0 \\ \end{bmatrix}$$

Step 4 of the construction forms the parallel composition of $\mathcal{D} = \mathcal{D}^-$ and $T_{\neg\Psi}$ to obtain the combined BDS $\mathcal{B}_{(\mathcal{D},\neg\Psi)} = \mathcal{D} ||| T_{\neg\Psi}$. We claim that the system $\mathcal{B}_{(\mathcal{D},\neg\Psi)}$ has no computations. Assume to the contrary, that σ is a computation of $\mathcal{B}_{(\mathcal{D},\neg\Psi)}$. To be a computation, σ must contain infinitely many states in which u = 0. According to the initial condition, f_1 is initially true, while f_3 is initially false. By the transition relation for f_1 and the condition for getting out of u = 1, there must exist a position $j \ge 0$ such that $g_2 = 1$ at j. By the transition relation for g_2 , it follows that x < 0 for all positions $k \ge j$. This means that, from j on, all executions of statement ℓ_2 cause y to decrease. Since a natural number cannot decrease infinitely many times, the while loop of the program must terminate, and the execution must reach location ℓ_3 , which by $f_3 = 0$, is impossible.

According to step 5, we should be able to identify an assertion Φ which is an invariant of $\mathcal{B}_{(\mathcal{D}^-, \neg \Psi)}$, and a progress measure Δ . Indeed, for our example, an appropriate invariant assertion is

$$\Phi: (f_1 \lor g_2) \land \neg f_3 \land (u > 1 \rightarrow g_2) \land (\pi \in \{1, 2\} \rightarrow y > 0),$$

while a progress measure can be given by

$$\Delta : \begin{bmatrix} case \\ g_2 : & (0, 3y + 2at_{-}\ell_0 + at_{-}\ell_1); \\ 1 : & (1, 0); \\ esac \end{bmatrix}$$

 $B_{y>0}: \text{ boolean} \\ x: \{-1,1\} \\ \left[\begin{array}{c} \ell_0: \text{ while } B_{y>0} \text{ do} \\ \left[\begin{array}{c} \ell_1: x:=\pm 1 \\ \ell_2: B_{y>0}:= \left[\begin{array}{c} \cos e \\ x>0: 1 \\ \neg B_{y>0}: 0 \end{array}; \\ 1 \\ esac \end{array} \right] \right] \\ \left\| \right\| \\ \left\| \left[\begin{array}{c} \left[\begin{array}{c} case \\ x>0: 1 \\ \neg B_{y>0}: 0 \\ 1 \\ \vdots \end{array} \right] \right] \\ \| \| \\ \left[\left[\begin{array}{c} case \\ \alpha^{++}(\rho_{\neg\psi}) \land \\ -G_2 \land G_2' \\ at_{-}\ell_3: 0 \\ at_{-}\ell_{0,1} \\ \vdots \\ 1 \\ \vdots \end{array} \right] \right] \\ \| \| \\ \left\| \left[\begin{array}{c} case \\ \alpha^{++}(\rho_{\neg\psi}) \land \\ \alpha^{-+}(\rho_{\neg\psi}) \land \\ \alpha^{-+}(\rho_{\neg\psi}) \land \\ at_{-}(\rho_{1,1} \\ \vdots \\ 1 \\ \vdots \\ at_{-}(\rho_{1,1} \\ \vdots \\ 1 \\ \vdots \\ 1 \\ \vdots \\ at_{-}(\rho_{1,1} \\ \vdots \\ 1 \\ \vdots \\ at_{-}(\rho_{1,1} \\ \vdots \\ 1 \\ \vdots \\ at_{-}(\rho_{1,1} \\ \vdots \\ 1 \\ \vdots \\ 1 \\ \vdots \\ at_{-}(\rho_{1,1} \\ at_{-}(\rho_{1,1}$

FIG. 14. Program ABS-COND-TERM, the augmented abstracted version of program COND-TERM.

It is not difficult to see that any transition taken from a Φ -state is guaranteed not to increase Δ . If such a transition leads to a state in which u = 0 then Δ must decrease.

In step 6, we use the tester $T_{true}^{\neg\Psi}$ and the progress measure Δ to construct the progress monitor $M_{T,\Delta}$ given by

$$M_{T,\Delta}: \begin{pmatrix} V_M : \{\pi : \textbf{natural}, x : \{-1, 1\}, f_1, g_2, f_3 : \textbf{boolean}, u : [0..3], inc : \{-1, 0, 1\}\} \\ \Theta_M : u = 0 \quad \rho_M : \rho_{\neg\psi} \land inc' = diff(\Delta, \Delta') \\ \mathcal{J}: u = 0 \quad \mathcal{C}: \{(inc < 0, inc > 0)\} \end{pmatrix}.$$

Next, we form the composition $\mathcal{D} \parallel M_{T,\Delta}$, and then compute the abstraction mapping α . To obtain a finitary mapping, we introduce a fresh Boolean variable $B_{y>0}$ with the definition $B_{y>0} = (y > 0)$. Applying the abstraction α to $\mathcal{D} \parallel M_{T,\Delta}$, we obtain an abstracted finite-state system equivalent to the program presented in Fig. 14.

The variables F_1 , G_2 , F_3 are the abstract versions of f_1 , g_2 , and f_3 , respectively. Note that, like $\mathcal{D} \parallel M_{T,\Delta}$, system ABS-COND-TERM is a parallel composition of three components, the abstraction of program COND-TERM, the abstraction of the tester T_{true}^{Ψ} , and the abstraction of the monitor, taking into account its joint behavior with the other two components.

Clearly, the system ABS-COND-TERM is a finite-state system and satisfies the property

$$\psi \colon \Diamond \Box \, (x < 0) \to \Diamond \, at \, \ell_3.$$

To see that ABS-COND-TERM satisfies the property ψ , assume, to the contrary, that there exists a computation σ of ABS-COND-TERM which satisfies $\Diamond \Box (x < 0)$ but never reaches location ℓ_3 . In this case, the initial values of f_1 and f_3 must be 1 and 0, respectively. The justice requirement with respect to *u* cannot be satisfied in such a case, unless g_2 eventually assume the value 1. Once this happens, *inc* is constantly -1 from this point on. This violates the compassion requirement with respect to *inc*. It follows that σ cannot be a computation.