# Some inequalities related to the Seysen measure of a lattice 

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## A R T I C L E I N F O

## Article history:

Received 26 November 2009
Accepted 9 June 2010
Available online 4 July 2010
Submitted by H. Schneider

AMS classification:
Primary: 11H06
Secondary: 15A42, 11-04


#### Abstract

Given a lattice $L$, a basis $B$ of $L$ together with its dual $B^{*}$, the orthogonality measure $S(B)=\sum_{i}\left\|b_{i}\right\|^{2}\left\|b_{i}^{*}\right\|^{2}$ of $B$ was introduced by Seysen (1993) [9]. This measure (the Seysen measure in the sequel, also known as the Seysen metric [11]) is at the heart of the Seysen lattice reduction algorithm and is linked with different geometrical properties of the basis [ $6,7,10,11$ ]. In this paper, we derive different expressions for this measure as well as new inequalities related to the Frobenius norm and the condition number of a matrix.


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## Keywords:

Lattice
Orthogonality defect
Seysen measure
HGA inequality

## 1. Introduction, notations and previous results

An $n$-dimensional (real) lattice $L$ is defined as a subset of $\mathbb{R}^{m}, n \leqslant m$, generated by $B=\left[b_{1}|\cdots| b_{n}\right]^{t}$, where the $b_{i}$ are $n$ linearly independent vectors over $\mathbb{R}$ in $\mathbb{R}^{m}$, as

$$
L=\left\{\sum_{i=1}^{n} a_{i} b_{i} \mid a_{i} \in \mathbb{Z}\right\}
$$

In this paper, the rows of the matrix $B$ span the lattice. Any other matrix $B^{\prime}=U B$, where $U \in G L_{n}(\mathbb{Z})$, generates the same lattice. The volume $\operatorname{Vol} L$ of $L$ is the well defined real number $\left(\operatorname{det} B B^{t}\right)^{1 / 2}$. The dual lattice of $L$ is defined by the basis $B^{*}=\left(B^{+}\right)^{t}$, where $B^{+}$is the Moore-Penrose inverse, or pseudoinverse, of $B$. If $B^{*}=\left[b_{1}^{*}|\cdots| b_{n}^{*}\right]^{t}$, then since $B B^{+}=I_{n}$, we have $\left\langle b_{i}, b_{j}^{*}\right\rangle=\delta_{i, j}$. Lattice reduction theory deals with the problem of identifying and computing bases of a given lattice whose vectors are short

[^0]and almost orthogonal. There are several concepts of reduced bases, such as the concepts of Minkovsky reduced, LLL reduced [5] and Korkin-Zolotarev reduced basis [3]. In 1990, Hastad and Lagarias [1] proved that in all lattices of full rank (i.e., when $n=m$ ), there exists a basis $B$ such that both $B$ and $B^{*}$ consist in relatively short vector, i.e., $\max _{i}\left\|b_{i}\right\| \cdot\left\|b_{i}^{*}\right\| \leqslant \exp \left(O\left(n^{1 / 3}\right)\right)$. In 1993, Seysen [9] improved this upper bound to $\exp \left(O\left(\ln ^{2}(n)\right)\right)$ and suggested to use the expression $S(B):=\sum_{i}\left\|b_{i}\right\|^{2}\left\|b_{i}^{*}\right\|^{2}$. This definition also allowed him to define a new concept of reduction: a basis $B$ of $L$ is Seysen reduced if $S(B)$ is minimal among all bases of $L$ (see also [4] for a study of this reduction method). A relation between the orthogonality defect $[2,11]$
$$
\operatorname{od}(B):=1-\frac{\operatorname{det} B B^{t}}{\prod_{i=1}^{n}\left\|b_{i}\right\|^{2}} \in[0,1]
$$
and the Seysen measure $S(B)$ is given in [11] where the following bounds can be found:
\[

$$
\begin{align*}
& n \leqslant S(B) \leqslant \frac{n}{1-\operatorname{od}(B)},  \tag{1.1}\\
& 0 \leqslant \operatorname{od}(B) \leqslant 1-\frac{1}{(S(B)-n+1)^{n-1}} . \tag{1.2}
\end{align*}
$$
\]

Clearly, the smaller the Seysen measure is, the closer to orthogonal the basis is, showing that the Seysen measure describes the quality of the angle behavior of the vectors in a basis. The length of the different vectors are nevertheless not part of the direct information given by the measure, but inequality (1.2) gives

$$
\prod_{i=1}^{n}\left\|b_{i}\right\| \leqslant(S(B)-n+1)^{\frac{n-1}{2}} \cdot \operatorname{Vol} L
$$

which in turn provides the inequality

$$
\begin{equation*}
\min _{i}\left\|b_{i}\right\| \leqslant(S(B)-n+1)^{(n-1) / 2 n}(\operatorname{Vol} L)^{1 / n} . \tag{1.3}
\end{equation*}
$$

Note that such a type of inequality appears in the context of lattice reduction as

$$
\begin{array}{ll}
\min _{i}\left\|b_{i}\right\| \leqslant \sqrt{n}(\operatorname{Vol} L)^{1 / n} & \text { for Korkin Zolotarev and Minkovsky reduced bases, } \\
\min _{i}\left\|b_{i}\right\| \leqslant(4 / 3)^{(n-1) / 4}(\text { Vol } L)^{1 / n} & \text { for LLL reducedbases. }
\end{array}
$$

In this paper, we start by revisiting Seysen's bound $\exp \left(O\left(\ln (n)^{2}\right)\right)$ by computing the hidden constant in Landau's notation. Then we present new expressions for the Seysen measure, connecting the measure with the condition number and the Frobenius norm of a matrix and allowing us to improve some of the existing bounds. We will from now on suppose that $m=n$, since equality (3.6) below shows that the Seysen measure is invariant under isometric embeddings.

## 2. Explicit constant in Seysen's bound

We show in this section that the hidden constant in Seysen's bound $\exp \left(O\left(\ln (n)^{2}\right)\right)$ can be upper bounded by $1+\frac{2}{\ln 2}$. The proof is not new, but revisits some details in the original proof of Seysen [9, Theorem 7] by using explicit bounds given in [5, Proposition 4.2]. Let us define the two main ingredients of the proof. First, if $N(n, \mathbb{R})$ and $N(n, \mathbb{Z})$ are the group of lower triangular unipotent $n \times n$ matrices over $\mathbb{R}$ and $\mathbb{Z}$, respectively (i.e. matrices with 1 in the diagonal), then following [1,9], and if $\|X\|_{\infty}=\max _{i, j}\left|X_{i j}\right|$, we define $S(n)$ for all $n \in \mathbb{N}$ by

$$
S(n)=\sup _{A \in N(n, \mathbb{R})}\left(\inf _{T \in N(n, \mathbb{Z})} \max \left(\|T A\|_{\infty},\left\|(T A)^{-1}\right\|_{\infty}\right)\right) .
$$

In [9], the author proves that $S(2 n) \leqslant S(n) \cdot \max (1, n / 2)$, and concludes that $S(n)=\exp \left(O\left((\ln n)^{2}\right)\right)$. We would like to point out that the latter is not true in general, unless some other property of the
function $S$ is invoked. Indeed, an arbitrary map $s$ defined on the set of odd integers, e.g. $s(2 n+1)=$ $\exp (2 n+1)$, and extended to $\mathbb{N}$ with the rule $s(2 n)=n / 2 \cdot s(n)$ satisfies the condition $s(2 n) \leqslant s(n)$. $\max (1, n / 2)$ but we have $s(n) \neq \exp \left(O\left((\ln n)^{2}\right)\right)$ in general. This point seems to have been overlooked in [9]. However, in our case, we have the following in addition.

Lemma 2.1. $\forall n \leqslant m \in \mathbb{N}, S(n) \leqslant S(m)$.
Proof. It is not difficult to see that for all $A \in N(n, \mathbb{R})$, there exists a matrix $T_{A} \in N(n, \mathbb{Z})$ such that

$$
\inf _{T \in N(n, \mathbb{Z})} \max \left(\|T A\|_{\infty},\left\|(T A)^{-1}\right\|_{\infty}\right)=\max \left(\left\|T_{A} A\right\|_{\infty},\left\|\left(T_{A} A\right)^{-1}\right\|_{\infty}\right) .
$$

See the Remark following Definition 4 of [9] for the details. As a consequence, in order to prove the lemma, it is sufficient to show that

$$
\begin{equation*}
\sup _{A \in N(n, \mathbb{R})} \max \left(\left\|T_{A} A\right\|_{\infty},\left\|\left(T_{A} A\right)^{-1}\right\|_{\infty}\right) \leqslant \sup _{A^{\prime} \in N(n+1, \mathbb{R})} \max \left(\left\|T_{A^{\prime}} A^{\prime}\right\|_{\infty},\left\|\left(T_{A^{\prime}} A^{\prime}\right)^{-1}\right\|_{\infty}\right) . \tag{2.4}
\end{equation*}
$$

Let us consider the map $i$ from $N(n, \mathbb{R})$ to $N(n+1, \mathbb{R})$ defined by mapping a matrix $A$ to the block matrix $\operatorname{diag}(1, A)$. The map $i$ is a group homomorphism and thus $i(A)^{-1}=i\left(A^{-1}\right)=\operatorname{diag}\left(1, A^{-1}\right)$. We claim that for all $A \in N(n, \mathbb{R})$ and all $T \in N(n, \mathbb{Z})$, we have

$$
\begin{equation*}
\max \left(\|i(T A)\|_{\infty},\left\|i(T A)^{-1}\right\|_{\infty}\right)=\max \left(\|T A\|_{\infty},\left\|(T A)^{-1}\right\|_{\infty}\right) \tag{2.5}
\end{equation*}
$$

First, if $\max \left(\|i(T A)\|_{\infty},\left\|i(T A)^{-1}\right\|_{\infty}\right)=1$, then the above equality is straightforward, due to the definition of $\|\cdot\|_{\infty}$. Let us then consider the case where the maximum is not 1 . Notice that since $\|X\|_{\infty} \geqslant 1$ is true for all matrix $X$ in $N(m, \mathbb{R})$, we have that $\max \left(\|X\|_{\infty},\left\|X^{-1}\right\|_{\infty}\right) \geqslant 1$ and so $\max \left(\|i(T A)\|_{\infty}\right.$, $\left.\left\|i(T A)^{-1}\right\|_{\infty}\right)>1$. As a consequence the maximum in $\max \left(\|i(T A)\|_{\infty},\left\|i(T A)^{-1}\right\|_{\infty}\right)$ is achieved by one of the entries of $i(T A)$ or $i(T A)^{-1}$, and this entry cannot be the one in the upper left corner. The maximum is then the same for both sides of (2.5). This proves the above claim. Now, since

$$
\begin{aligned}
& \sup _{A^{\prime} \in N(n+1, \mathbb{R})} \max \left(\left\|T_{A^{\prime}} A^{\prime}\right\|_{\infty},\left\|\left(T_{A^{\prime}} A^{\prime}\right)^{-1}\right\|_{\infty}\right) \geqslant \max \left(\|i(T A)\|_{\infty},\left\|i(T A)^{-1}\right\|_{\infty}\right) \\
& \quad=\max \left(\|T A\|_{\infty},\left\|(T A)^{-1}\right\|_{\infty}\right)
\end{aligned}
$$

is true for all $A \in N(n, \mathbb{R})$, taking the supremum on the left hand side, we see that inequality (2.4) is correct.

This lemma makes the following inequalities valid:

$$
S(n)=S\left(2^{\log _{2} n}\right) \leqslant S\left(2^{\left\lceil\log _{2} n\right\rceil}\right) \leqslant 2^{\left\lceil\log _{2} n\right\rceil-2} \cdot 2^{\left\lceil\log _{2} n\right\rceil-3} \cdots 2 \cdot 1 \leqslant \exp \left(\frac{(\ln n)^{2}}{2 \ln 2}\right)
$$

The second ingredient we need is related to the Korkin-Zolotarev reduced bases of a lattice $L$. Such bases are well known, see e.g. [5], and one of their properties is the following: if $B$ is a Korkin-Zolotarev reduced basis of $L$, and if $B=H K$, where $H=\left(h_{i j}\right)$ is a lower triangular matrix and $K$ is an orthogonal matrix, then for all $1 \leqslant i \leqslant j \leqslant n$, we have

$$
h_{j j}^{2}>h_{i i}^{2}(j-i+1)^{-1-\ln (j-i+1)} .
$$

This is a direct consequence of [5, Proposition 4.2] and the fact that the concept of Korkin-Zolotarev reduction is recursive. See [9] for the details. In [9], the author concludes that $\frac{h_{i j}^{2}}{h_{j j}^{2}}=\exp \left(O\left((\ln n)^{2}\right)\right)$ but we have the more precise statement that

$$
\frac{h_{i i}^{2}}{h_{j j}^{2}} \leqslant \exp \left((\ln (j-i+1))^{2}+\ln (j-i+1)\right) \leqslant \exp \left((\ln n)^{2}+\ln n\right)
$$

Let us now revisit the proof of [9, Theorem 7] by making use of the previous inequalities. This theorem states that for every lattice $L$ there is a basis $\widetilde{B}=\left[\widetilde{b_{1}}|\cdots| \widetilde{b_{n}}\right]^{t}$ with reciprocal basis $\widetilde{B}^{*}=\left[\widetilde{b}_{1}{ }^{*}|\cdots|{\widetilde{b_{n}}}^{*}\right]^{t}$ which satisfies

$$
\left\|\widetilde{b}_{i}\right\| \cdot\left\|\tilde{b}_{i}^{*}\right\| \leqslant \exp \left(c_{2}(\ln n)^{2}\right)
$$

for all $i$ and for a fixed $c_{2}$, independent of $n$. We explicit now an upper bound for the constant $c_{2}$. Given a lattice $L$ and a Korkin-Zolotarev reduced basis $B=H K$ as above, the proof of [9, Theorem 7] shows that there exists a basis $\widetilde{B}$, constructed from $B$, such that

$$
\left\|\widetilde{b}_{i}\right\|^{2} \cdot\left\|\widetilde{b}_{i}^{*}\right\|^{2} \leqslant n^{2} \cdot \max _{k \geqslant j}\left\{\frac{h_{j j}^{2}}{h_{k k}^{2}}\right\} \cdot S(n)^{4} .
$$

Making use of the previous inequalities, we can write

$$
\left\|\widetilde{b}_{i}\right\|^{2} \cdot\left\|\widetilde{b}_{i}^{*}\right\|^{2} \leqslant n^{2} \cdot \exp \left((\ln n)^{2}+\ln n\right) \cdot \exp \left(\frac{4(\ln n)^{2}}{2 \ln 2}\right)=\exp \left(\left(\frac{2}{\ln 2}+1\right)(\ln n)^{2}+3 \ln n\right),
$$

which shows that $c_{2}<\frac{1}{\ln 2}+\frac{1}{2}+\frac{3}{2 \ln n}<\frac{1}{\ln 2}+\frac{1}{2}+\frac{3}{2 \ln 2}=\frac{5}{2 \ln 2}+\frac{1}{2}$ and gives the following proposition:

Proposition 2.2. For every lattice $L$ there is a basis $B$ which satisfies

$$
S(B) \leqslant \exp \left(\left(\frac{2}{\ln 2}+1\right)(\ln n)^{2}+4 \ln n\right) .
$$

## 3. Explicit expression for the Seysen measure

In this section, we present different expressions for the Seysen measure. First, let us recall the following known expression for the measure. Given a basis $B$ of $L$, by definition of $B^{*}$, for all $0 \leqslant j \leqslant n$, the vector $b_{j}^{*}$ is orthogonal to $L_{j}$, where $L_{j}$ is the sublattice of $L$ generated by all the vectors of $B$ except $b_{j}$. If $\beta_{j}$ is the angle between $b_{j}$ and $b_{j}^{*}$ and $\alpha_{j}$ is the angle between $b_{j}$ and $L_{j}$, we have $\cos ^{2} \beta_{i}=\sin ^{2} \alpha_{i}$ and

$$
\begin{equation*}
S(B)=\sum_{i}\left\|b_{i}\right\|^{2}\left\|b_{i}^{*}\right\|^{2}=\sum_{i} \frac{\left\langle b_{i}, b_{i}^{*}\right\rangle^{2}}{\cos ^{2} \beta_{i}}=\sum_{i} \frac{1}{\sin ^{2} \alpha_{i}} . \tag{3.6}
\end{equation*}
$$

This has already been used in [4,11]. We introduce now the following new representation, which can be used to define the Seysen measure without any references to the dual basis:

Proposition 3.1. For every lattice $L$, if $B=\left[b_{1}|\cdots| b_{n}\right]^{t}$ is a basis of $L$ with $B=D \cdot V$ where $D=$ $\operatorname{diag}\left(\left\|b_{1}\right\|, \ldots,\left\|b_{n}\right\|\right)$, then

$$
S(B)=\left\|V^{-1}\right\|^{2}
$$

where $\|\cdot\|$ is the Frobenius norm, i.e., $\|X\|=\sqrt{\sum_{i, j}\left|x_{i j}\right|^{2}}$.
Proof. Let $M=B B^{t}$. Using $\|X\|^{2}=\operatorname{tr}\left(X X^{t}\right)$ and $\operatorname{tr}(A B C)=\operatorname{tr}(C A B)$, we have

$$
\left\|V^{-1}\right\|^{2}=\operatorname{tr}\left(V^{-1}\left(V^{-1}\right)^{t}\right)=\operatorname{tr}\left(D^{2} M^{-1}\right)=\sum_{i}\left\|b_{i}\right\|^{2} \cdot\left(M^{-1}\right)_{i, i}
$$

Since $M^{-1}=\frac{1}{\operatorname{det} M} \operatorname{comat}(M)$, where comat $(M)$ is the comatrix of $M$, we have

$$
\left(M^{-1}\right)_{i, i}=\frac{1}{\operatorname{det} M} \operatorname{comat}(M)_{i, i}=\frac{\operatorname{det} M^{i, i}}{\operatorname{det} M}
$$

where $M^{i, i}$ is the square matrix obtained from $M$ by deleting the $i$ th row and the $i$ th column of $M$. So if $B^{i}$ is the matrix obtained by deleting the $i$ th row of $B$, we have

$$
\operatorname{det} M^{i, i}=\operatorname{det} B^{i}\left(B^{i}\right)^{t}=\left(\operatorname{Vol} L_{i}\right)^{2},
$$

which gives

$$
\frac{\operatorname{det} M^{i, i}}{\operatorname{det} M}=\frac{\left(\operatorname{Vol} L_{i}\right)^{2}}{(\operatorname{Vol} L)^{2}}=\frac{\left(\operatorname{Vol} L_{i}\right)^{2}}{\left(\left\|b_{i}\right\| \cdot \operatorname{Vol} L_{i} \cdot \sin \alpha_{i}\right)^{2}}=\frac{1}{\left\|b_{i}\right\|^{2} \sin ^{2} \alpha_{i}} .
$$

Finally,

$$
\left\|V^{-1}\right\|^{2}=\sum_{i}\left\|b_{i}\right\|^{2} \cdot\left(M^{-1}\right)_{i, i}=\sum_{i}\left\|b_{i}\right\|^{2} \cdot \frac{1}{\left\|b_{i}\right\|^{2} \sin ^{2} \alpha_{i}}=S(B) .
$$

Another way of looking at the previous result is with the help of the (Frobenius) condition number of an invertible matrix $X$ which is defined as $\kappa(X)=\|X\| \cdot\left\|X^{-1}\right\|$.

Corollary 3.2. With the above notation, we have $S(B)=\frac{\kappa(V)^{2}}{n}$.
By defining the matrix $U$ as $U=V V^{t}$, then $B B^{t}=D U D$, where $D$ is as above, and if $\theta_{i j}$ is the angle between $b_{i}$ and $b_{j}$, then $U=\left(\cos \theta_{i j}\right)_{i j}$. The matrix $U$ is a symmetric positive definite matrix, and the eigenvalues $\lambda_{1}, \ldots, \lambda_{n}$ of $U$ are real positive.

Corollary 3.3. With the above notation, we have $S(B)=\operatorname{tr}\left(U^{-1}\right)=\sum_{i} \frac{1}{\lambda_{i}}$.
From the equality $B B^{t}=D U D$, we have $(\operatorname{Vol} L)^{2}=\operatorname{det} U \cdot \prod_{i}\left\|b_{i}\right\|^{2}$ which in turn leads to

$$
\begin{equation*}
\prod_{i}\left\|b_{i}\right\|=(\operatorname{det} U)^{-1 / 2} \cdot \operatorname{Vol} L=\left(\prod_{i} \frac{1}{\lambda_{i}}\right)^{1 / 2} \cdot \operatorname{Vol} L \tag{3.7}
\end{equation*}
$$

The arithmetic-geometric mean inequality applied to the $\lambda_{i}{ }^{\prime}$ s, $\left(\prod_{i} 1 / \lambda_{i}\right)^{1 / n} \leqslant \frac{1}{n} \sum_{i} 1 / \lambda_{i}$, immediately gives the inequality

$$
\prod_{i}\left\|b_{i}\right\| \leqslant\left(\frac{1}{n} \sum_{i} \frac{1}{\lambda_{i}}\right)^{\frac{n}{2}} \cdot \operatorname{Vol} L=\left(\frac{S(B)}{n}\right)^{\frac{n}{2}} \cdot \operatorname{Vol} L .
$$

However, we also have the equality $\sum_{i} \lambda_{i}=\operatorname{tr} U=n$, which affords a slightly better upper bound for the geometric mean. Indeed, the harmonic-geometric-arithmetic mean inequalities applied to the $1 / \lambda_{i}$ 's imply that if $g=\left(\prod_{i} 1 / \lambda_{i}\right)^{1 / n}, h=\left(\frac{1}{n} \sum_{i} \lambda_{i}\right)^{-1}=1$ and $a=\frac{1}{n} \sum_{i} \frac{1}{\lambda_{i}}=\frac{S(B)}{n}$, then we have $h \leqslant g \leqslant a$, but we also have the following result, which is [8, Corollary 3.1].

Lemma 3.4. With the above notations, if $\alpha=1 / n$, we have

$$
\begin{aligned}
g \leqslant & \left(\frac{a-h(1-2 \alpha)-\sqrt{(a-h)\left(a-h(1-2 \alpha)^{2}\right)}}{2 \alpha}\right)^{\alpha} \\
& \times\left(\frac{a+h(1-2 \alpha)+\sqrt{(a-h)\left(a-h(1-2 \alpha)^{2}\right)}}{2(1-\alpha)}\right)^{1-\alpha} .
\end{aligned}
$$

This leads to the following inequality:
Proposition 3.5. With the above notation, we have

$$
\begin{equation*}
\prod_{i}\left\|b_{i}\right\| \leqslant e^{1 / 2} \cdot\left(\frac{S(B)+1}{n}\right)^{\frac{n-1}{2}} \cdot \operatorname{Vol} L \tag{3.8}
\end{equation*}
$$

Proof. Since $(1-2 / n)^{2} \leqslant 1$, we have

$$
(a-h)^{2} \leqslant(a-h)\left(a-h(1-2 / n)^{2}\right) \leqslant\left(a-h(1-2 / n)^{2}\right)^{2}
$$

and thus the upper bound of the previous lemma gives

$$
g \leqslant\left(\frac{a-h(1-2 / n)-(a-h)}{2 / n}\right)^{1 / n}\left(\frac{a+h(1-2 / n)+\left(a-h(1-2 / n)^{2}\right)}{2(1-1 / n)}\right)^{1-1 / n} .
$$

After suitable simplification, we obtain

$$
g \leqslant a \cdot\left(\frac{h}{a}\right)^{1 / n} \cdot\left(1+\frac{h}{a} \cdot\left(1-\frac{2}{n}\right) \cdot \frac{1}{n}\right)^{1-1 / n} \cdot\left(1+\frac{1}{n-1}\right)^{1-1 / n} .
$$

Since $\left(1+\frac{1}{n-1}\right)^{n-1}<e$, taking the $n$th power of both sides of the previous inequality gives

$$
\prod_{i} 1 / \lambda_{i}<e \cdot\left(\frac{S(B)+1-\frac{2}{n}}{n}\right)^{n-1}<e \cdot\left(\frac{S(B)+1}{n}\right)^{n-1}
$$

The result follows by applying the previous inequality to Eq. (3.7).
This is an improvement by a factor of roughly $n^{n / 2}$ of the bound given by (1.3), and can be used to strengthen the bound of the orthogonality defect (1.1):

Corollary 3.6. With the above notations, we have

$$
\operatorname{od}(B) \leqslant 1-\frac{1}{e}\left(\frac{n}{S(B)+1}\right)^{n-1}
$$

Combining the previous proposition with the explicit bound of Proposition 2.2, we have the following proposition:

Proposition 3.7. For every lattice $L$, if $B=\left[b_{1}|\cdots| b_{n}\right]^{t}$ is a Seysen reduced basis, then

$$
\min _{i}\left\|b_{i}\right\| \leqslant \exp \left(\left(\frac{1}{\ln 2}+\frac{1}{2}\right)(\ln n)^{2}+O(\ln n)\right) \cdot(\operatorname{Vol} L)^{1 / n} .
$$

## 4. Conclusion

In this article, we gave an explicit upper bound for the constant hidden inside Landau's notation of the original bound of the Seysen measure [9]. We also developed the connection between the Seysen measure and standard linear algebra concepts such as the Frobenius norm and the condition number of a matrix. This allowed us to improve known upper bounds for the Seysen measure and the orthogonality defect.

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