

# Two-Minor Stable Matrices and the Open Leontief Model

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## ABSTRACT

Two-minor stable matrices are square matrices such that all  $(2,2)$  minors with no elements on the main diagonal are zero. The effects of taxes and subsidies on the competitive prices of output in Leontief's input-output model are examined by e.g. Metzler, Allen and Atsumi. We reexamine these studies and give results under more "normal" assumptions. Using two-minor stable matrices, the question is answered under what conditions the prices of the nontaxed and nonsubsidized goods do not change.

## 1. INTRODUCTION

The static input-output Leontief model  $(I - T)x = d$  will be considered. It consists of  $n$  industries producing  $n$  commodities. The vector  $x = (x_1, \dots, x_n)'$  is the annual output of the  $n$  industries, and  $d = (d_1, \dots, d_n)'$  the final demand vector.  $T$  will invariably be used for a nonnegative irreducible  $(n, n)$  matrix with  $n \in \mathbb{N}$  (the set of natural numbers  $\geq 1$ ). For any  $n \in \mathbb{N}$  we write  $\langle n \rangle = \{1, 2, \dots, n\}$ , and use the following notation for any  $x = (x_1, \dots, x_n)' \in \mathbb{R}^n$ :

$$\begin{aligned}x \geq 0 & \quad \text{if } x_i \geq 0 \text{ for each } i \in \langle n \rangle; \\x > 0 & \quad \text{if } x \geq 0 \text{ and } x \neq 0; \\x \gg 0 & \quad \text{if } x_i > 0 \text{ for each } i \in \langle n \rangle.\end{aligned}$$

Similar notation is used for matrices. The symbol  $r$  will denote the Perron-Frobenius root of  $T$ . Throughout this paper  $r < 1$ .

We also consider the "dual" equation system  $(I - T')p = v$ , with  $p$  the price vector and  $v$  the vector of the value added of the commodities.

The two systems  $(I - T)x = d$  and  $(I - T')p = v$  will describe the situation of the equilibrium attained after imposing a sales tax  $t_i$  ( $> 0$ ) on commodity  $i$  and a subsidy  $s_j$  ( $> 0$ ) on commodity  $j$ , such that  $t_i x_i = s_j x_j$ , i.e., the amount of the tax is equal to the amount of the subsidy ( $i \neq j$ ). For a more extensive description see Allen [1], Atsumi [2], Metzler [4], and Sierksma [7]. We shall take  $d$  and  $v$  both  $> 0$ , which means that the systems are "open." It then follows from a well-known theorem (see e.g. Berman and Plemmons [3] and Seneta [6]) that  $x \gg 0$ ,  $p \gg 0$ , and  $\text{Adj}(I - T) \gg 0$  and is nonsingular.

## 2. THE CHANGE OF THE PRICE VECTOR

Let  $\Delta v = (t, -s, 0, \dots, 0)'$  the change of the vector of the value added, and let  $\Delta p$  be the change of the price vector such that

$$(I - T') \Delta p = \Delta v,$$

$t$  being a sales tax on commodity 1 and  $s$  a subsidy on commodity 2. The following theorem shows that the price  $p_1$  of the taxed commodity rises or does not change and that the price  $p_2$  of the subsidized commodity decreases or remains constant. Note that Atsumi proves  $\Delta p_1 > 0$ ,  $\Delta p_2 < 0$  but needs the stronger condition  $d \gg 0$ . Below we examine the cases  $\Delta p_1 = 0$  or  $\Delta p_2 = 0$ .

**THEOREM 1.** *If  $\Delta p_1$  and  $\Delta p_2$  are the changes of the prices after imposing a sales tax on commodity 1 and a subsidy on commodity 2, respectively, then*

$$\Delta p_1 \geq 0 \quad \text{and} \quad \Delta p_2 \leq 0.$$

*Proof.* Let  $X$  be the diagonal matrix with  $x$  on the main diagonal. As  $x \gg 0$ , it follows that  $X$  is nonsingular. Taking  $T^\circ = X^{-1}TX$ , it follows that  $(I - T^\circ)(X \Delta p) = X \Delta v$  and that  $(I - T^\circ)1 = X^{-1}d > 0$  with  $1 = (1, \dots, 1)'$ . Metzler's theorem (see e.g. [7, Theorem 12]) then says  $0 < c_{ij}^\circ \leq c_{ii}^\circ$  with  $\{c_{ji}^\circ\} = \text{Adj}(I - T^\circ)$ . We then find  $x_1 \Delta p_1 = (x_1 t / |I - T|)(c_{11}^\circ - c_{12}^\circ) \geq 0$  and  $x_2 \Delta p_2 = (x_2 s / |I - T|)(c_{21}^\circ - c_{22}^\circ) \leq 0$ , so that in fact  $\Delta p_1 \geq 0$  and  $\Delta p_2 \leq 0$ . ■

Throughout this paper we denote  $\{c_{ji}\} = \text{Adj}(I - T)$ . The next theorem gives upper and lower bounds for the ratio  $s/t$ .

**THEOREM 2.**  $c_{21}/c_{22} \leq s/t \leq c_{11}/c_{12}$ .

*Proof.* From  $\Delta p = (I - T')^{-1} \Delta v = (1/|I - T|)\{c_{ij}\}(t, -s, 0, \dots, 0)$  it follows that

$$0 \leq \Delta p_1 = \frac{1}{|I - T|} (tc_{11} - sc_{12}) \quad \text{and} \quad 0 \geq \Delta p_2 = \frac{1}{|I - T|} (tc_{21} - sc_{22}).$$

Hence,  $tc_{11} - sc_{12} \geq 0$  and  $tc_{21} - sc_{22} \leq 0$ , which gives the desired result. ■

**THEOREM 3.** *For any  $i \in \langle n \rangle$  the following holds:*

$$\Delta p_i = 0 \quad \Leftrightarrow \quad \frac{s}{t} = \frac{c_{i1}}{c_{i2}}.$$

*Proof.* Direct consequence of  $\Delta p_i = (1/|I - T|)(tc_{i1} - sc_{i2})$ ,  $i \in \langle n \rangle$ . ■

**COROLLARY 4.** *All prices, except for the taxed and subsidized goods, remain constant if and only if*

$$\frac{s}{t} = \frac{c_{31}}{c_{32}} = \dots = \frac{c_{n1}}{c_{n2}}.$$

*Proof.* Direct consequence of Theorem 3. ■

Note that either  $\Delta p_1 \neq 0$  or  $\Delta p_2 \neq 0$  or both in case all other prices remain constant; otherwise  $\text{Adj}(I - T)$  would be singular. Also note that

$$\frac{c_{21}}{c_{22}} \leq \frac{c_{i1}}{c_{i2}} \leq \frac{c_{11}}{c_{12}}$$

for each  $i \geq 3$ , with one of the two inequalities *strict* for at least one  $i$ ; see e.g. [7, Theorem 29].

### 3. TWO-MINOR STABLE MATRICES

In this section we characterize the matrices  $T$  such that for the models  $(I - T)x = d$  and  $(I - T')p = v$  the following holds: On imposing some tax and subsidy system on *any* two industries, the prices of the nontaxed and nonsubsidized goods have to stay the same. Below this question is described in detail.

We need the following concept. A *2-minor stable matrix* is a matrix such that all  $(2, 2)$  minors with no element on the main diagonal are zero. That is, any  $(n, n)$  matrix  $A = \{a_{ij}\}$  is called 2-minor stable iff

$$a_{ik}a_{jl} - a_{il}a_{jk} = 0$$

for each  $i, j, k, l$  with no two indices equal in case  $n \geq 4$ , and for  $n = 3$  iff  $a_{12}a_{23}a_{31} - a_{13}a_{32}a_{21} = 0$ . It is known that  $c_{ii}c_{kl} - c_{ki}c_{il} \geq 0$  for each  $i, k, l$  with  $k \neq l \neq i \neq k$ ; (see e.g. [7, Theorem 29] and [8, Corollary 4]); however, all off-diagonal 2-minors can be positive, negative, or zero.

Note that all matrices of class  $M(x)$  are 2-minor stable; for any  $x \in \mathbb{R}$  an  $(n, n)$  matrix  $A = \{a_{ij}\}$  is of class  $M(x)$  iff  $a_{jj} - a_{ij} = x$  for each  $i, j \in \langle n \rangle$  with  $i \neq j$ : see [7, p. 189]. In [8],  $(2, 2)$  minors are studied with at most one main diagonal element not from the original main diagonal.

**THEOREM 5.** *Let  $A$  be an  $(n, n)$  matrix with  $A \gg 0$  and  $n \geq 3$ . The following assertions are equivalent:*

- (i)  *$A$  is 2-minor stable;*
- (ii)  *$a_{\alpha i}a_{i\beta}/a_{\alpha\beta} = a_{\gamma i}a_{i\delta}/a_{\gamma\delta}$  for each  $\alpha, \beta, i$  and  $\gamma, \delta, i$  with no two indices equal in each triple.*

*Proof.* For  $n = 3$  the theorem holds by definition. So let  $n \geq 4$ .

(i)  $\Rightarrow$  (ii): Take any  $\alpha, \beta, \gamma, \delta, i \in \langle n \rangle$ . We distinguish three cases.

(1)  $\gamma \neq \beta$ . Then  $a_{\alpha i}a_{i\beta}/a_{\alpha\beta} = a_{\gamma i}a_{i\beta}/a_{\gamma\beta} = a_{\gamma i}a_{i\delta}/a_{\gamma\delta}$ .

(2)  $\delta \neq \alpha$ . Similar to (1).

(3)  $\gamma = \beta$  and  $\delta = \alpha$ . Then  $a_{\alpha i}a_{i\beta}/a_{\alpha\beta} = a_{\tau i}a_{i\beta}/a_{\tau\beta} =$  (for  $\tau \neq \alpha, \beta, i$ )  $a_{\tau i}a_{i\alpha}/a_{\tau\alpha} = a_{\beta i}a_{i\alpha}/a_{\beta\alpha}$ .

(ii)  $\Rightarrow$  (i): Set  $\delta = \beta$  in (ii). ■

Let  $\text{Adj}(I - T) = \{c_{ji}\}$  be 2-minor stable; Theorem 5 enables us to define

$$c_{ii}^* = \frac{c_{ki}c_{il}}{c_{kl}}$$

for  $k \neq l \neq i \neq k$  and independent on  $k$  and  $l$ . So the matrix

$$\begin{bmatrix} c_{11}^* & c_{12} & \cdots & c_{1n} \\ c_{21} & c_{22}^* & \cdots & c_{2n} \\ \vdots & & & \vdots \\ c_{n1} & c_{n2} & \cdots & c_{nn}^* \end{bmatrix}$$

has all 2-minors equal to zero. Note that, for all  $i$ ,  $c_{ii}^* \geq 0$ .

**THEOREM 6.** *T is 2-minor stable iff  $\text{Adj}(I - T)$  is.*

*Proof.* For  $n = 3$  the theorem follows by a straightforward calculation. So we may assume that  $n \geq 4$ . To show this theorem we use [5, Proposition 1], which states that for any nonsingular  $(n, n)$  matrix  $H$  and any  $\alpha \subset \langle n \rangle$ ,  $\text{rank } H(\alpha, \alpha^c) = \text{rank } H^{-1}(\alpha, \alpha^c)$ , where  $\alpha$  and  $\alpha^c$  denote respectively the rows and columns included in each submatrix, and  $\alpha^c$  means the complement of  $\alpha$ . For example, if  $\alpha = \{1, 2\}$ ,  $\alpha^c = \{3, \dots, n\}$ , and  $\text{rank } H(\alpha, \alpha^c) = 1$ , this is equivalent to saying that  $h_{1k}h_{2m} - h_{1m}h_{2k} = 0$  for all  $k, m = 3, \dots, n$  iff  $h_{1k}^{-1}h_{1m}^{-1} - h_{1m}^{-1}h_{1k}^{-1} = 0$  for all  $k, m = 3, \dots, n$ , with  $H = \{h_{ij}\}$  and  $H^{-1} = \{h_{ij}^{-1}\}$ . A similar statement holds for  $\alpha = \{i, j\}$ ,  $1 \leq i < j \leq n$ . Putting all of these statements together implies that  $H$  is 2-minor stable iff  $H^{-1}$  is 2-minor stable. Since  $I - T$  is nonsingular, the following chain of equivalences holds:  $T$  is 2-minor stable  $\Leftrightarrow I - T$  is 2-minor stable  $\Leftrightarrow (I - T)^{-1}$  is 2-minor stable  $\Leftrightarrow \text{Adj}(I - T)$  is 2-minor stable.<sup>1</sup> ■

**THEOREM 7.** *Let T be 2-minor stable. If  $c_{ii} - c_{ii}^* = 0$  for some  $i \in \langle n \rangle$ , then  $c_{jj} - c_{jj}^* > 0$  for each  $j \neq i$ . That is, the minors  $c_{ii}c_{kl} - c_{ki}c_{il}$  are zero for at most one  $i$ .*

*Proof.* Without loss of generality we may assume that  $c_{11} - c_{11}^* = 0$ . It then follows that  $\{c_{ji}\}$  is equivalent to

$$\begin{bmatrix} c_{11} & 0 & \cdots & 0 \\ 0 & c_{22} - c_{22}^* & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & c_{nn} - c_{nn}^* \end{bmatrix}.$$

This can be seen as follows. Take any  $i \geq 2$ , and consider the first and the  $i$ th row of  $\{c_{ji}\}$ . For any  $k \neq 1, i$  multiply the first row by  $c_{ki}$  and the  $i$ th row by  $c_{k1}$ , and then subtract these rows. Using the fact that  $\text{Adj}(I - T)$  is 2-minor stable and the definition of  $c_{ii}^*$ , we find the row  $(0, \dots, c_{ii}, \dots, c_{ii}^*, \dots, 0)$ . The zeros in the first row follow from using the first column and the fact that  $c_{11} > 0$ .

<sup>1</sup>This proof was given by W. W. Barrett (private communication).

As the rank of  $\{c_{ji}\}$  is  $n$ , it follows that  $c_{ii} - c_{ii}^* \neq 0$ . As  $c_{ii} - c_{ii}^* \geq 0$  (see above), we have in fact  $c_{ii} - c_{ii}^* > 0$  for each  $i \geq 2$ . So for at most one  $i \in \langle n \rangle$  we have  $c_{ii} = c_{ii}^*$ . ■

Note that the above theorem is also clear from the following: Suppose  $c_{11} - c_{11}^* = c_{22} - c_{22}^* = 0$ . Taking  $\Delta v = (c_{32}, -c_{31}, 0, \dots, 0)'$ , it follows from Theorem 3 that  $\Delta p = (1/|I - T|)\{c_{ij}\} \Delta v = 0$ , which is impossible.

**THEOREM 8.** *For the systems  $(I - T)x = d$  and  $(I - T')p = v$  the following assertions are equivalent:*

- (i)  $T$  is 2-minor stable;
- (ii) For each  $i, j \in \langle n \rangle$  with  $i \neq j$  there is a tax and subsidy system  $t_i, s_j$  such that  $\Delta p_k = 0$  for each  $k \neq i, j$ .

*Proof.* (i)  $\Rightarrow$  (ii): Take any  $i$  and  $j$ . Without loss of generality we may take  $i = 1, j = 2$ , and write  $t_1 = t, s_2 = s$ ; hence  $(I - T')\Delta p = (t, -s, 0, \dots, 0)'$ , or  $\Delta p = (1/|I - T|)\{c_{ij}\}(t, -s, 0, \dots, 0)'$ . For any  $k \in \langle n \rangle$  we then have  $\Delta p_k = (1/|I - T|)(c_{k1}t - c_{k2}s)$ . As  $\text{Adj}(I - T)$  is 2-minor stable, it follows that  $c_{31}/c_{32} = \dots = c_{n1}/c_{n2}$ . Taking  $s/t = c_{31}/c_{32}$ , it follows for  $k \geq 3$  that  $\Delta p_k = (1/|I - T|)(c_{k1}t - c_{k2}s) = 0$ .

(ii)  $\Rightarrow$  (i): Left to the reader. ■

**THEOREM 9.** *Let  $T$  be 2-minor stable. Then the following holds.*

- (1) *If  $c_{kk} - c_{kk}^* = 0$  for some  $k \in \langle n \rangle$ , then*

$$x = \frac{\alpha_k}{|I - T|} \begin{pmatrix} c_{k1} \\ \vdots \\ c_{kn} \end{pmatrix} \quad \text{and} \quad d = \alpha_k e_k, \quad \text{with} \quad \alpha_k > 0.$$

- (2) *If  $c_{ii} - c_{ii}^* > 0$  for each  $i \in \langle n \rangle$ , then*

$$x = \frac{\beta_k}{|I - T|} \chi \begin{pmatrix} c_{k1} \\ \vdots \\ c_{kk}^* \\ \vdots \\ c_{kn} \end{pmatrix} \quad \text{and} \quad d = \beta_k \begin{pmatrix} c_{11} \\ c_{11} - c_{11}^* \\ \vdots \\ c_{kk}^* \\ c_{kk} - c_{kk}^* \\ \vdots \\ c_{nn} \\ c_{nn} - c_{nn}^* \end{pmatrix}$$

for each  $k \in \langle n \rangle$ ,  $\beta_k > 0$ , and

$$\chi = 1 + \sum_{i=1}^n \frac{c_{ii}^*}{c_{ii} - c_{ii}^*} = 1 - n + \sum_{i=1}^n \frac{c_{ii}}{c_{ii} - c_{ii}^*}.$$

*Proof.* According to Theorem 8, we can choose, for each  $i, j \in \langle n \rangle$  with  $i \neq j$ ,  $s_j$  and  $t_i$  with  $x_i/x_j = s_j/t_i$  such that  $\Delta p_k = 0$  for each  $k \neq i, j$ . Theorem 3 implies that  $s_j/t_i = c_{ki}/c_{kj}$  and therefore  $c_{kj}x_i - c_{ki}x_j = 0$  for each  $i, j, k \in \langle n \rangle$  with  $k \neq i < j \neq k$ . The matrix of coefficients of  $x = (x_1, \dots, x_n)$  consists of  $(n-2) \binom{n}{2}$  rows and  $n$  columns. The rows belonging to the equations  $c_{\alpha j}x_i - c_{\alpha i}x_j = 0$  and  $c_{\beta j}x_i - c_{\beta i}x_j = 0$ , with  $\alpha, \beta, i, j \in \langle n \rangle$  and no two indices equal, are linearly dependent because of the 2-minor stability. For each pair  $i < j$  we choose one equation as follows: if  $i = 1$  and  $j = 2$  take  $k = 3$ , if  $i = 1$  and  $j > 2$  take  $k = 2$ ; if  $i \geq 2$  take  $k = 1$ . The rows of this matrix of coefficients, which we call  $B$ , are ordered lexicographically in  $i$  and  $j$  with  $i < j$ . For example, for  $n = 4$  we have

$$B = \begin{bmatrix} c_{32} & -c_{31} & 0 & 0 \\ c_{23} & 0 & -c_{21} & 0 \\ c_{24} & 0 & 0 & -c_{21} \\ 0 & c_{13} & -c_{12} & 0 \\ 0 & c_{14} & 0 & -c_{12} \\ 0 & 0 & c_{14} & -c_{13} \end{bmatrix}.$$

Clearly, the first  $n - 1$  rows of  $B$  are linearly independent, and each other row is linearly dependent on two of the first  $n - 2$  rows. Hence,  $B$  has rank  $n - 1$ . We then find  $n$  solutions, namely

$$x = \eta_1 \begin{bmatrix} c_{11}^* \\ c_{12} \\ \vdots \\ c_{1n} \end{bmatrix} = \dots = \eta_n \begin{bmatrix} c_{n1} \\ \vdots \\ c_{nn-1} \\ c_{nn}^* \end{bmatrix}$$

with  $\eta_1, \dots, \eta_n > 0$ .

From  $x = (1/|I - T|)\{c_{ji}\}d$  and  $x_i/x_j = c_{ki}/c_{kj}$  for some  $k \neq i, j$  it follows that  $(\sum_{\alpha=1}^n c_{\alpha i} d_{\alpha}) / (\sum_{\alpha=1}^n c_{\alpha j} d_{\alpha}) = c_{ki}/c_{kj}$ ; see also Atsumi [2, p. 36]. Hence,  $\sum_{\alpha=1}^n (c_{\alpha i} c_{kj} - c_{\alpha j} c_{ki}) d_{\alpha} = 0$ , and as  $\text{Adj}(I - T)$  is 2-minor stable, we

have

$$(c_{ii}c_{kj} - c_{ij}c_{ki})d_i - (c_{jj}c_{ki} - c_{ji}c_{kj})d_j = 0$$

for each  $i, j \in \langle n \rangle$  with  $i \neq j$  and  $k \neq i, j$ . So  $d$  satisfies an equation system  $Cd = 0$  with  $C$  a  $\left(\binom{n}{2}, n\right)$  matrix defined similarly to  $B$ . For example, for  $n = 4$  we have

$$C = \begin{bmatrix} c_{11}c_{32} - c_{31}c_{12} - (c_{22}c_{31} - c_{32}c_{21}) & 0 & 0 & 0 \\ c_{11}c_{23} - c_{21}c_{13} & 0 & -(c_{33}c_{21} - c_{23}c_{31}) & 0 \\ c_{11}c_{24} - c_{21}c_{14} & 0 & 0 & -(c_{44}c_{21} - c_{24}c_{41}) \\ 0 & c_{22}c_{13} - c_{12}c_{23} & c_{33}c_{12} - c_{13}c_{32} & 0 \\ 0 & c_{22}c_{14} - c_{12}c_{24} & 0 & -(c_{44}c_{12} - c_{14}c_{42}) \\ 0 & 0 & c_{33}c_{14} - c_{13}c_{34} & -(c_{44}c_{13} - c_{14}c_{43}) \end{bmatrix}.$$

Note that

$$C = B \operatorname{adj}(I - T).$$

On the other hand, because for each  $i, \alpha, \beta \in \langle n \rangle$  with  $i \neq \alpha \neq \beta \neq i$  we have

$$c_{ii}c_{\alpha\beta} - c_{\alpha i}c_{i\beta} = c_{\alpha\beta} \left( c_{ii} - \frac{c_{\alpha i}c_{i\beta}}{c_{\alpha\beta}} \right) = c_{\alpha\beta}(c_{ii} - c_{ii}^*),$$

it follows that

$$C = B \begin{bmatrix} c_{11} - c_{11}^* & 0 & \cdots & 0 \\ 0 & c_{22} - c_{22}^* & & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & c_{nn} - c_{nn}^* \end{bmatrix}.$$

According to Theorem 6 we cannot have more than one  $c_{ii} - c_{ii}^*$  equal to 0. So if  $c_{kk} - c_{kk}^* = 0$  for some  $k \in \langle n \rangle$ , then, because  $e_k$  is a solution and  $\operatorname{rank} C = n - 1$ ,

$$d = \alpha_k e_k \quad \text{with} \quad \alpha_k > 0.$$

From  $(I - T)x = d$  it follows that  $x = (1/|I - T|)\operatorname{Adj}(I - T)d$ , so we must have in case  $c_{kk}^* = c_{kk}$  that  $\eta_k = \alpha_k/|I - T|$ . This proves (1).



If  $c_{ii} - c_{ii}^* > 0$  for each  $i \in \langle n \rangle$ , we have

$$B((c_{11} - c_{11}^*)d_1, \dots, (c_{nn} - c_{nn}^*)d_n)' = 0.$$

Therefore we find

$$d = \beta_1 \begin{bmatrix} \frac{c_{11}^*}{c_{11} - c_{11}^*} \\ \frac{c_{12}}{c_{22} - c_{22}^*} \\ \vdots \\ \frac{c_{1n}}{c_{nn} - c_{nn}^*} \end{bmatrix} = \dots = \beta_n \begin{bmatrix} \frac{c_{n1}}{c_{11} - c_{11}^*} \\ \vdots \\ \frac{c_{nn}^*}{c_{nn} - c_{nn}^*} \end{bmatrix},$$

with  $\beta_1, \dots, \beta_n \in 0$ . Taking  $X$  as before, with  $X1 = x$ , it follows from  $(I - T)x = d$  that  $[X^{-1}\{c_{ji}\}X][X^{-1}d] = |I - T|1$ , and

$$X^{-1}\{c_{ij}\}X = \begin{bmatrix} c_{11} & \frac{x_2}{x_1}c_{21} & \dots & \frac{x_n}{x_1}c_{n1} \\ \frac{x_1}{x_2}c_{12} & c_{22} & \dots & c_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{x_1}{x_n}c_{1n} & c_{2n} & \dots & c_{nn} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{22}^* & \dots & c_{nn}^* \\ c_{11}^* & c_{22} & \dots & c_{nn}^* \\ \vdots & \vdots & \ddots & \vdots \\ c_{11}^* & c_{22}^* & \dots & c_{nn} \end{bmatrix}.$$

Moreover,

$$X^{-1}d = \frac{\beta_k}{\eta_k} \left( \frac{1}{c_{11} - c_{11}^*}, \dots, \frac{1}{c_{nn} - c_{nn}^*} \right)'$$

with  $k \in \langle n \rangle$ . Taking e.g. the first row of  $X^{-1}\{c_{ji}\}X$ , we find that

$$\begin{aligned} \eta_k &= \frac{1}{|I - T|} \left( \frac{c_{11}}{c_{11} - c_{11}^*} + \frac{c_{22}^*}{c_{22} - c_{22}^*} + \dots + \frac{c_{nn}^*}{c_{nn} - c_{nn}^*} \right) \beta_k \\ &= \frac{\beta_k}{|I - T|} \chi, \end{aligned}$$

which proves (2). ■

As an illustration consider the following example:

$$T = \begin{pmatrix} 0.69 & 0.08 & 0.07 \\ 0.05 & 0.86 & 0 \\ 0.10 & 0 & 0.74 \end{pmatrix}.$$

Then

$$\text{Adj}(I - T) = \begin{pmatrix} 0.0364 & 0.0208 & 0.0098 \\ 0.0130 & 0.0736 & 0.0035 \\ 0.0140 & 0.0080 & 0.0394 \end{pmatrix}$$

and  $|I - T| = 0.009264$ .

Clearly  $T$  is 2-minor stable; hence so is  $\text{Adj}(I - T)$ . Moreover,  $c_{11}^* = c_{11} = 0.0364$ ,  $c_{22}^* = 0.0074$ ,  $c_{33}^* = 0.0038$ .

Let  $s_2/t_1 = c_{31}/c_{32} = 2.8$ . Then  $\Delta p_1 = 0$ ,  $\Delta p_2 = -20t_1 < 0$ ,  $\Delta p_3 = 0$ ; and  $d = \alpha(1, 0, 0)$ ,  $x = \alpha(3.92, 1.40, 1.51)'$  with  $\alpha > 0$ . So it may happen that even within the taxed and subsidized sector, one of the prices does not change. Also note that in this case prices stay the same or go down.

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