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Internal circle uplifts, transversality and stratified **G**-structures

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Abstract: We study stratified G-structures in $\mathcal{N}=2$ compactifications of M-theory on eight-manifolds M using the uplift to the auxiliary nine-manifold $\hat{M} = M \times S^1$. We show that the cosmooth generalized distribution $\hat{\mathcal{D}}$ on \hat{M} which arises in this formalism may have pointwise transverse or non-transverse intersection with the pull-back of the tangent bundle of M, a fact which is responsible for the subtle relation between the spinor stabilizers arising on M and M and for the complicated stratified G-structure on M which we uncovered in previous work. We give a direct explanation of the latter in terms of the former and relate explicitly the defining forms of the SU(2) structure which exists on the generic locus \mathcal{U} of M to the defining forms of the SU(3) structure which exists on an open subset $\hat{\mathcal{U}}$ of \hat{M} , thus providing a dictionary between the eight- and nine-dimensional formalisms.

KEYWORDS: Differential and Algebraic Geometry, Flux compactifications, M-Theory

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Introduction

General $\mathcal{N}=2$ flux compactifications of eleven-dimensional supergravity [1] on eightmanifolds M have two independent internal supersymmetry generators ξ_1, ξ_2 which are global sections of the rank sixteen bundle S of Majorana spinors on M. The class of such compactifications is little explored, with the notable exception of compactifications down to Minkowski 3-space [2], which arise when imposing the Weyl condition on ξ_1 and ξ_2 and which, as a consequence of no-go theorems, can only support a flux at the quantum,

rather than classical, level. Relaxing this condition leads to backgrounds which can support classical fluxes and which have a surprisingly rich geometry. Some aspects of such backgrounds were discussed in [3] using a formalism which uses the auxiliary nine-manifold $\hat{M} \stackrel{\text{def.}}{=} M \times S^1$ and the canonical lifts $\hat{\xi}_1, \hat{\xi}_2$ to \hat{M} of the internal supersymmetry generators (see also [4]). In that approach, one finds that \hat{M} is endowed with a stratified G-structure whose strata are defined by the isomorphism type of the stabilizer group inside (Spin(9)) of the pair of lifted spinors at various points of M. The strata of M correspond [3] to stabilizers isomorphic with SU(3), G_2 or SU(4). On the other hand, it was shown in [5] that the stabilizer stratification induced by ξ_1 and ξ_2 on M has SU(2), SU(3), G₂ and SU(4) strata, whose description is considerably more complex. This stratification of M coincides with a certain coarsening of the preimage of the connected refinement of the canonical Whitney stratification [6, 7] of a four-dimensional compact semi-algebraic [8, 9] body $\mathfrak{P} \subset \mathbb{R}^4$ through a certain map $B: M \to \mathbb{R}^4$ whose image is contained in \mathfrak{P} . As shown in [5], this complicated stratification generalizes what happens in the much simpler case of $\mathcal{N}=1$ M-theory flux compactifications on eight-manifolds [10-13] (which extend the classically fluxless case of [14-16]), where the relevant semi-algebraic body is the interval [-1,1], endowed with its Whitney stratification.

The complexity of the picture found in [5] may come as a surprise given the relative simplicity of the stabilizer stratification of M. The purpose of this note is to explain this difference. Embedding M into \hat{M} as a hypersurface j(M) located at some fixed point of S^1 , we show that the cosmooth [17] generalized distribution [18–21] \mathcal{D} of [5] (which is the polar distribution defined by three 1-forms $V_1, V_2, V_3 \in \Omega^1(M)$ coincides with the intersection of TM with the restriction $j^*(\hat{\mathcal{D}}) \equiv \hat{\mathcal{D}}|_{j(M)}$ of the polar distribution $\hat{\mathcal{D}}$ which is defined on \hat{M} by three 1-forms $\hat{V}_1, \hat{V}_2, \hat{V}_3 \in \Omega^1(\hat{M})$. The latter can be expressed as bilinears in $\hat{\xi}_1$ and ξ_2 . The algebraic constraints satisfied by V_1, V_2 and V_3 as a result of Fierz identities for ξ_1 and ξ_2 are equivalent with the algebraic constraints satisfied by \hat{V}_1, \hat{V}_2 and \hat{V}_3 as a result of Fierz identities for $\hat{\xi}_1$ and $\hat{\xi}_2$. The intersection $\mathcal{D} = j^*(\hat{\mathcal{D}}) \cap TM$ may be pointwise transverse or non-transverse, giving rise to a disjoint union decomposition $M = \mathcal{T} \sqcup \mathcal{N}$, where \mathcal{T} is the transverse locus and \mathcal{N} is the non-transverse locus of M. While \mathcal{D} and $j^*(\hat{\mathcal{D}})$ coincide when restricted to \mathcal{N} , the ranks of their restrictions to \mathcal{T} differ by one. The fact that \mathcal{T} may be nonempty turns out to be responsible for the difference between the stabilizer stratifications of M and M and explains the increased complexity of the former when compared to the latter. In the special case when the transverse locus is empty (which turns out to be the case considered in [3]), the equality $\mathcal{D} = j^*(\hat{\mathcal{D}})$ holds globally on M and the stabilizer stratification of M is obtained directly from that of \hat{M} by intersecting every stratum of the latter with j(M). In the generic case when $\mathcal{T} \neq \emptyset$, the relation between the stabilizer stratifications of M and \hat{M} can be understood using a version of known facts [22–27] regarding G-structures induced on orientable hypersurfaces of a G-structured manifold. On the open stratum $\mathcal{U} \subset M$ which carries an SU(2) structure (the "generic locus" of [5]), this observation allows one to give an explicit formula for the defining forms of the SU(2) structure in terms of the defining forms of the SU(3) structure which exists [3] on an open subset \mathcal{U} of M.

The note is organized as follows. Section 1 briefly recalls some results of [5], to which we refer the reader for further information. Section 2 discusses the stabilizer stratification of \hat{M} and compares its intersection with j(M) with the B-preimage of the connected refinement of the canonical Whitney stratification of \mathfrak{P} . Section 3 takes up the issue of transversality of the pointwise intersection of $j^*(\hat{\mathcal{D}})$ with TM and shows how the transverse or nontransverse character of this intersection explains the increased complexity of the stabilizer stratification of M as compared to that of \hat{M} . The same section shows how the stratified G-structure of M can be obtained by reducing that of \hat{M} along this intersection. Section 4 expresses the defining form of the SU(2) structure which exists on the generic locus of M in terms of the defining forms of the SU(3) structure which exists on an open subset of \hat{M} , while section 5 concludes.

Notations and conventions. We use the same notations and conventions as reference [5], to which we refer the reader for details. An equality which holds for any point of a subset A of a manifold is written as $=_A$.

1 Brief summary of the eight-dimensional formalism

Let S denote the rank 16 vector bundle of Majorana spinors on M (which is endowed with the admissible [28, 29] scalar product \mathscr{B}) and ν denote the volume form of (M, g). Let $\gamma : \wedge T^*M \to \operatorname{End}(S)$ be the structure morphism of S. Given two Majorana spinors $\xi_1, \xi_2 \in \Gamma(M, S)$ which are \mathscr{B} -orthonormal everywhere, we define the 0- and 1-forms:

$$b_{i} = \mathcal{B}(\xi_{i}, \gamma(\nu)\xi_{i}), \quad b_{3} \stackrel{\text{def.}}{=} \mathcal{B}(\xi_{1}, \gamma(\nu)\xi_{2})$$

$$V_{i} = {}_{U}\mathcal{B}(\xi_{i}, \gamma_{a}\xi_{i})e^{a}, \quad V_{3} \stackrel{\text{def.}}{=} \mathcal{B}(\xi_{1}, \gamma_{a}\xi_{2})e^{a}, \quad W \stackrel{\text{def.}}{=} {}_{U}\mathcal{B}(\xi_{1}, \gamma_{a}\gamma(\nu)\xi_{2})e^{a}$$

$$(1.1)$$

with i = 1, 2 and the linear combinations:

$$b_{\pm} \stackrel{\text{def.}}{=} \frac{1}{2} (b_1 \pm b_2) , \ V_{\pm} \stackrel{\text{def.}}{=} \frac{1}{2} (V_1 \pm V_2) .$$
 (1.2)

It is convenient to consider the smooth map:

$$b \stackrel{\text{def.}}{=} (b_+, b_-, b_3) : M \to \mathbb{R}^3$$
.

The Fierz identities for ξ_1, ξ_2 imply [5] that (1.1) satisfy the constraints:

$$||V_{-}||^{2} + b_{-}^{2} = ||V_{3}||^{2} + b_{3}^{2}, \qquad ||V_{+}||^{2} + b_{+}^{2} = 1 - (||V_{3}||^{2} + b_{3}^{2})$$

$$\langle V_{+}, V_{-} \rangle + b_{+}b_{-} = \langle V_{+}, V_{3} \rangle + b_{+}b_{3} = \langle V_{-}, V_{3} \rangle + b_{-}b_{3} = 0$$

$$||W||^{2} + ||V_{3}||^{2} = 1 + b_{-}^{2} - b_{+}^{2}$$

$$\langle W, V_{+} \rangle = 0, \quad \langle W, V_{-} \rangle = b_{3}, \quad \langle W, V_{3} \rangle = -b_{-}.$$

$$(1.3)$$

In view of the first two relations, we define:

$$\beta \stackrel{\text{def.}}{=} \sqrt{||V_-||^2 + b_-^2} = \sqrt{||V_3||^2 + b_3^2} = \sqrt{1 - b_+^2 - ||V_+||^2} : M \to \mathbb{R} . \tag{1.4}$$

¹The notation $=_U$ means that a relation holds on any open subset U of M which supports a local coframe $(e^a)_{a=1...8}$ of M.

Consider the cosmooth generalized distributions:

$$\mathcal{D} \stackrel{\text{def.}}{=} \ker V_{+} \cap \ker V_{-} \cap \ker V_{3} \subset TM , \quad \mathcal{D}_{0} \stackrel{\text{def.}}{=} \mathcal{D} \cap \ker W \subset \mathcal{D} . \tag{1.5}$$

As shown in [5], the rank stratifications of M induced by \mathcal{D} and \mathcal{D}_0 have the same open stratum, the so-called *generic locus* of M:

$$\mathcal{U} \stackrel{\text{def.}}{=} \{ p \in M | \text{rk} \mathcal{D}(p) = 5 \} = \{ p \in M | \text{rk} \mathcal{D}_0(p) = 4 \}$$

while the complement $\mathcal{W} \stackrel{\text{def.}}{=} M \setminus \mathcal{U}$ (the non-generic locus) decomposes as:

$$W = W_2 \sqcup W_1 \sqcup W_0 = \mathcal{Z}_2 \sqcup \mathcal{Z}_1 \sqcup \mathcal{Z}_0 , \qquad (1.6)$$

where:

$$\mathcal{W}_k \stackrel{\text{def.}}{=} \{ p \in \mathcal{W} | \text{rk} \mathcal{D}(p) = 8 - k \} , \quad \mathcal{Z}_k \stackrel{\text{def.}}{=} \{ p \in \mathcal{W} | \text{rk} \mathcal{D}_0(p) = 8 - k \}$$
 (1.7)

and $\mathcal{Z}_3 = \emptyset$. The rank stratifications of M induced by \mathcal{D} and \mathcal{D}_0 are the disjoint union decompositions:

$$M = \mathcal{U} \sqcup \mathcal{W}_2 \sqcup \mathcal{W}_1 \sqcup \mathcal{W}_0 , \quad M = \mathcal{U} \sqcup \mathcal{Z}_2 \sqcup \mathcal{Z}_1 \sqcup \mathcal{Z}_0 .$$
 (1.8)

It was shown in [5] that these stratifications can be described as different coarsenings of the B-preimage of the connected refinement of the canonical Whitney stratification of a semi-algebraic body $\mathfrak{P} \subset \mathbb{R}^4$, where B is the map defined through:

$$B = (b, \beta) : M \to \mathbb{R}^4,$$

a map whose image is contained in \mathfrak{P} . In particular, we have $\mathcal{U} = B^{-1}(\operatorname{Int}\mathfrak{P})$ and $\mathcal{W} = B^{-1}(\partial \mathfrak{P})$, while:

$$\mathcal{Z}_0 = \mathcal{W}_0$$
, $\mathcal{Z}_1 = \mathcal{W}_1^1$, $\mathcal{Z}_2 = \mathcal{W}_1^0 \sqcup \mathcal{W}_2$,

where W_1^0 and W_1^1 are defined in loc. cit. and satisfy $W_1^0 \sqcup W_1^1 = W_1$. We refer the reader to [5] for the description of \mathfrak{P} and of its Whitney stratification, which we will freely use below. The description of W_k and \mathcal{Z}_k as B-preimages of disjoint unions of various Whitney strata of the frontier of \mathfrak{P} can be found in loc. cit. It was also shown in [5] that the rank stratification of \mathcal{D}_0 coincides with the stabilizer stratification of M, whose strata are defined by the isomorphism type of the common stabilizer group $H_p \stackrel{\text{def.}}{=} \operatorname{Stab}_{\operatorname{Spin}(T_pM,g_p)}(\xi_1(p),\xi_2(p))$ as $p \in M$. These isomorphism types are $\operatorname{SU}(2)$, $\operatorname{SU}(3)$, G_2 or $\operatorname{SU}(4)$ according to whether p belongs to \mathcal{U} , \mathcal{Z}_2 , \mathcal{Z}_1 or \mathcal{Z}_0 . The stabilizer stratification is the main datum describing the "stratified G-structure" which is induced by ξ_1 and ξ_2 on M (see [5]).

2 Circle uplifts to an auxiliary nine-manifold

2.1 The nine-manifold \hat{M}

Following [11], consider the 9-manifold $\hat{M} \stackrel{\text{def.}}{=} M \times S^1$, endowed with the direct product metric \hat{g} , where S^1 has unit radius. Let $s \in [0, 2\pi)$ denote an angular coordinate on S^1

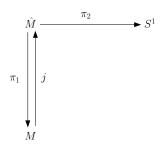


Figure 1. The canonical projections π_1, π_2 of \hat{M} and the section j of π_1 .

and π_1 and π_2 denote the canonical projections of \hat{M} onto M and S^1 , respectively (see figure 1). Consider the embedding $j: M \hookrightarrow \hat{M}$ of M in \hat{M} as the hypersurface given by the equation s = 0:

$$j(p) = (p,0)$$
, $\forall p \in M$.

This gives a section of the map $\pi_1: \hat{M} \to M$, thus $\pi_1 \circ j = \mathrm{id}_M$, which implies that the pull-back map $j^*: \Omega(\hat{M}) \to \Omega(M)$ satisfies $j^* \circ \pi_1^* = \mathrm{id}_{\Omega(M)}$. The differential $j_* \stackrel{\mathrm{def.}}{=} \mathrm{d}j: TM \hookrightarrow T\hat{M}|_{j(M)}$ is injective and identifies TM with the corank one sub-bundle $j_*(TM)$ of the restriction of $T\hat{M}$ to j(M). To simplify notation, we identify M with j(M) and TM with $j_*(TM) \subset T\hat{M}|_{j(M)}$. The unit circle S^1 is endowed with the exact one-form $\mathrm{d}s$, dual via the musical isomorphism to the Killing vector field $\frac{\partial}{\partial s}$ which generates rotations of S^1 . Let $\theta \stackrel{\mathrm{def.}}{=} \pi_2^*(\mathrm{d}s) = \mathrm{d}(s \circ \pi_2) \in \Omega^1(\hat{M})$ be the normalized Killing 1-form dual to the Killing vector field which generates S^1 -rotations of \hat{M} . We orient \hat{M} by considering the volume form:

$$\hat{\nu} \stackrel{\text{def.}}{=} \theta \wedge \pi_1^*(\nu) \Longrightarrow \pi_1^*(\nu) = \iota_\theta \hat{\nu} . \tag{2.1}$$

Notice that $\iota_{\theta}\pi_1^*(\nu) = 0$ and that $\hat{\nu}$ is rotationally-invariant, since so is the metric \hat{g} of \hat{M} . Let \hat{S} denote the positive signature bundle of real spinors on \hat{M} and $\hat{\gamma}: \wedge T^*\hat{M} \to \operatorname{End}(\hat{S})$ be its structure morphism. As explained in [4], the vector bundle \hat{S} can be identified with the pull-back $\pi_1^*(S)$. The positive signature condition means that $\hat{\gamma}(\hat{\nu}) = +\operatorname{id}_{\hat{S}}$, which amounts to:

$$\hat{\gamma}(\theta) = \pi_1^*(\gamma(\nu)) \ . \tag{2.2}$$

There exists a natural $\mathcal{C}^{\infty}(M,\mathbb{R})$ -linear injection:

$$\Gamma(M,S)\ni \xi\hookrightarrow \hat{\xi}\in \Gamma(\hat{M},\hat{S})$$

which is constructed as explained in [4] and whose image equals the space of those global sections of \hat{S} which are invariant under S^1 -rotations of \hat{M} . We say that $\hat{\xi}$ (which can be identified with $\pi_1^*(\xi)$) is the canonical lift to \hat{M} of the Majorana spinor $\xi \in \Gamma(M, S)$. The bundle \hat{S} admits a canonical scalar product $\hat{\mathcal{B}}$ which is invariant under S^1 -rotations of \hat{M} and hence satisfies (see [4]):

$$\hat{\mathscr{B}}(\hat{\xi}, \hat{\xi}') = \pi_1^*(\mathscr{B}(\xi, \xi')) = \mathscr{B}(\xi, \xi') \circ \pi_1 , \quad \forall \xi, \xi' \in \Gamma(M, S) . \tag{2.3}$$

2.2 The distribution \hat{D}

Let ξ_1, ξ_2 be an everywhere-orthonormal pair of global sections of S and let $\hat{\xi}_1, \hat{\xi}_2$ be their canonical lifts to \hat{M} . Relations (2.3) show that $\hat{\xi}_1$ and $\hat{\xi}_2$ are everywhere-orthonormal on \hat{M} :

$$\hat{\mathscr{B}}(\hat{\xi}_i, \hat{\xi}_j) = \delta_{ij} , \quad \forall i, j = 1, 2 .$$

Consider the following one-forms defined on \hat{M} , where k = 1, 2, 3:

$$\hat{V}_k \stackrel{\text{def.}}{=} \pi_1^*(V_k) + (b_k \circ \pi_1)\theta , \quad \hat{V}_{\pm} = \frac{1}{2}(\hat{V}_1 \pm \hat{V}_2) = \pi_1^*(V_{\pm}) + (b_{\pm} \circ \pi_1)\theta . \tag{2.4}$$

Relations (2.2) and (2.3) imply that \hat{V}_k coincide with the natural 1-forms constructed from the canonical lifts $\hat{\xi}_i$ of the Majorana spinors ξ_i :

$$\hat{V}_1 =_{\hat{U}} \hat{\mathscr{B}}(\hat{\xi}_1, \hat{\gamma}_m \hat{\xi}_1) \hat{e}^m , \quad \hat{V}_2 =_{\hat{U}} \hat{\mathscr{B}}(\hat{\xi}_2, \hat{\gamma}_m \hat{\xi}_2) \hat{e}^m , \quad \hat{V}_3 =_U \hat{\mathscr{B}}(\hat{\xi}_1, \hat{\gamma}_m \hat{\xi}_2) \hat{e}^m , \quad (2.5)$$

where \hat{e}^m is any local coframe of \hat{M} defined above an open subset $\hat{U} \subset \hat{M}$ and $\hat{\gamma}^m \stackrel{\text{def.}}{=} \hat{\gamma}(\hat{e}^m)$. The one-forms (2.4) are invariant under S^1 -rotations of \hat{M} , so their Lie derivatives with respect to $\frac{\partial}{\partial s}$ vanish. Since $\pi_1^*(V_k)$ are orthogonal to θ , we have:

$$\langle \hat{V}_k, \hat{V}_l \rangle = (\langle V_k, V_l \rangle + b_k b_l) \circ \pi_1 , \quad \forall k, l = 1, 2, 3 , \qquad (2.6)$$

where we used the normalization property $||\theta||^2 = 1$. Relations (2.6) imply that the first two rows of (1.3) are equivalent with the following system:

$$||\hat{V}_{-}||^{2} = ||\hat{V}_{3}||^{2} , \quad ||\hat{V}_{+}||^{2} = 1 - ||\hat{V}_{3}||^{2} \langle \hat{V}_{+}, \hat{V}_{-} \rangle = \langle \hat{V}_{+}, \hat{V}_{3} \rangle = \langle \hat{V}_{-}, \hat{V}_{3} \rangle = 0$$
(2.7)

which can also be written as:

$$||\hat{V}_1|| = ||\hat{V}_2|| = 1 , \quad ||\hat{V}_3||^2 = \frac{1}{2} (1 - \langle \hat{V}_1, \hat{V}_2 \rangle) \langle \hat{V}_1, \hat{V}_3 \rangle = \langle \hat{V}_2, \hat{V}_3 \rangle = 0$$
(2.8)

Relation (1.4) implies:

$$||\hat{V}_{-}|| = ||\hat{V}_{3}|| = \sqrt{1 - ||\hat{V}_{+}||^{2}} = \hat{\beta} ,$$
 (2.9)

where $\hat{\beta} \stackrel{\text{def.}}{=} \beta \circ \pi_1$. Relations (2.8) coincide² with [3], eqs. (2.5), (2.16), where they were obtained through direct computation starting from (2.5) and using Fierz identities for two spinors in nine dimensions. The common kernel of \hat{V}_k defines a cosmooth generalized distribution on \hat{M} :

$$\hat{\mathcal{D}} \stackrel{\text{def.}}{=} \ker \hat{V}_1 \cap \ker \hat{V}_2 \cap \ker \hat{V}_3 = \ker \hat{V}_+ \cap \ker \hat{V}_- \cap \ker \hat{V}_3 \subset T\hat{M} . \tag{2.10}$$

This distribution is invariant with respect to rotations of \hat{M} . However, notice that $\hat{\mathcal{D}}$ need *not* be orthogonal to the rotation generator θ^{\sharp} and hence it cannot be written as the π_1 -pullback of a distribution defined on M.

²We mention that the vector fields denoted here by $\hat{V}_{1,2,3}$ are denoted by $V_{1,2,3}$ in loc. cit., while the vector fields denoted here by \hat{V}_{\pm} correspond to half of the vector fields denoted by V_{\pm} in loc. cit., i.e. $\hat{V}_{\pm}^{here} = \frac{1}{2}V_{\pm}^{there}$. Compare [3], eq. (2.26) with our relation $\hat{V}_{\pm} = \frac{1}{2}(\hat{V}_1 \pm \hat{V}_2)$.

2.3 The distribution $\hat{\mathcal{D}}_0$

One can also lift $W \in \Omega^1(M)$ to the following one-form defined on \hat{M} , which is everywhere orthogonal to θ :

$$\hat{W} \stackrel{\text{def.}}{=} \pi_1^*(W) =_{\hat{U}} \hat{\mathscr{B}}(\hat{\xi}_1, \hat{\gamma}_m \hat{\gamma}(\theta) \hat{\xi}_2) \hat{e}^m . \tag{2.11}$$

The last equality follows by choosing \hat{e}^m such that $\hat{e}^9 = \theta$ and noticing that $\hat{\gamma}(\theta)^2 = \mathrm{id}_{\hat{S}}(\hat{s}_1, \hat{e}_2) = 0$ in the Kähler-Atiyah algebra of (\hat{M}, \hat{g}) and hence $\hat{\mathcal{B}}(\hat{\xi}_1, \hat{\gamma}_9 \hat{\gamma}(\theta) \hat{\xi}_2) = \hat{\mathcal{B}}(\hat{\xi}_1, \hat{\xi}_2) = 0$. The system (1.3) is equivalent with (2.7) taken together with the following supplementary equations:

$$||\hat{W}||^2 = 1 + (\rho^2 - \beta^2 - b_+^2) \circ \pi_1, \ \langle \hat{W}, \hat{V}_+ \rangle = 0, \ \langle \hat{W}, \hat{V}_- \rangle = b_3 \circ \pi_1, \ \langle \hat{W}, \hat{V}_3 \rangle = -b_- \circ \pi_1, \ (2.12)$$

where:

$$\rho \stackrel{\text{def.}}{=} \sqrt{b_{-}^2 + b_3^2} \ . \tag{2.13}$$

The 1-forms \hat{V}_k and \hat{W} define a generalized distribution $\hat{\mathcal{D}}_0$ on \hat{M} which is rotationally-invariant:

$$\hat{\mathcal{D}}_0 \stackrel{\text{def.}}{=} \hat{\mathcal{D}} \cap \ker \hat{W} \subset \hat{\mathcal{D}} . \tag{2.14}$$

Once again, this distribution need not be orthogonal to θ^{\sharp} (i.e. it need not be contained in $\ker \theta$) and hence it cannot be written as the π_1 -pullback of a distribution defined on M.

2.4 The stabilizer groups for M and \hat{M}

Since the natural action of $\operatorname{Spin}(T_{\hat{p}}\hat{M}, \hat{g}_p) \simeq \operatorname{Spin}(9)$ on \hat{S}_p induces an adjoint action on $\operatorname{End}(\hat{S}_{\hat{p}})$ with respect to which $\hat{\gamma}_m(\hat{p})$ transform as the components of a one-form, it follows that the common stabilizer:

$$\hat{H}_{\hat{p}} \stackrel{\text{def.}}{=} \operatorname{Stab}_{\operatorname{Spin}(T_{\hat{n}}\hat{M}, \hat{g}_{\hat{p}})}(\hat{\xi}_{1}(\hat{p}), \hat{\xi}_{2}(\hat{p})) \ \ (\hat{p} \in \hat{M})$$

satisfies:

$$\hat{\mathfrak{q}}_{\hat{p}}(\hat{H}_{\hat{p}}) \subset \text{Stab}_{SO(T_{\hat{p}}\hat{M}, \hat{g}_{\hat{p}})}(\hat{V}_{+}(\hat{p}), \hat{V}_{-}(\hat{p}), \hat{V}_{3}(\hat{p})) , \qquad (2.15)$$

where $\hat{\mathfrak{q}}_{\hat{p}}$: Spin $(T_{\hat{p}}\hat{M}, \hat{g}_{\hat{p}}) \to \mathrm{SO}(T_{\hat{p}}\hat{M}, \hat{g}_{\hat{p}})$ is the covering map. Notice that $\mathrm{SO}(T_{\hat{p}}\hat{M}, \hat{g}_{\hat{p}})$ does not stabilize $\theta(\hat{p})$. On the other hand, the common stabilizer:

$$H_p \stackrel{\text{def.}}{=} \operatorname{Stab}_{\operatorname{Spin}(T_pM, g_p)}(\xi_1(p), \xi_2(p)) \quad (p \in M)$$

of $\xi_1(p)$ and $\xi_2(p)$ inside Spin (T_pM, g_p) satisfies [5]:

$$\mathfrak{q}_p(H_p) \subset \text{Stab}_{SO(T_pM,q_p)}(V_+(p), V_-(p), V_3(p), W(p)) \quad (p \in M) ,$$
 (2.16)

where $\mathfrak{q}_p: \mathrm{Spin}(T_pM, g_p) \to \mathrm{SO}(T_pM, g_p)$ is the covering map. The relation:

$$\operatorname{Stab}_{\operatorname{SO}(T_p\hat{M},\hat{g}_p)}(\theta(p)) = \operatorname{SO}(T_pM,g_p) , \quad \forall p \in M \equiv j(M)$$

implies that the following holds for any point $p \in M \equiv j(M)$:

$$Stab_{SO(T_{p}\hat{M},\hat{g}_{p})}(\hat{V}_{+}(p),\hat{V}_{-}(p),\hat{V}_{3}(p),\hat{W}(p),\theta(p))$$

$$\simeq Stab_{SO(T_{p}M,g_{p})}(V_{+}(p),V_{-}(p),V_{3}(p),W(p))$$
(2.17)

The stabilizers $\hat{H}_{\hat{p}}$ were discussed in [3] (they can be isomorphic with SU(4), G₂ or SU(3)), while H_p were computed in [5] (they can be isomorphic with SU(4), G₂, SU(3) or SU(2)). As we shall see in what follows, the isomorphism type of $\hat{H}_{\hat{p}}$ defines a stratification of \hat{M} which can be characterized as the pull-back through a smooth and rotationally-invariant map $\hat{\alpha} \in \mathcal{C}^{\infty}(\hat{M}, \mathbb{R})$ of the connected refinement of the canonical Whitney stratification of a closed interval.

2.5 The stratifications of \hat{M} and M induced by \hat{D}

The rank function of $\hat{\mathcal{D}}$ gives a decomposition:

$$\hat{M} = \hat{\mathcal{U}} \sqcup \hat{\mathcal{W}} , \qquad (2.18)$$

where:

$$\hat{\mathcal{U}} \stackrel{\text{def.}}{=} \{ \hat{p} \in \hat{M} | \operatorname{rk} \hat{\mathcal{D}}(\hat{p}) = 6 \} , \quad \hat{\mathcal{W}} \stackrel{\text{def.}}{=} \{ \hat{p} \in \hat{M} | \operatorname{rk} \hat{\mathcal{D}}(\hat{p}) > 6 \} . \tag{2.19}$$

The locus \hat{W} decomposes further according to the corank of \hat{D} inside $T\hat{M}$:

$$\hat{\mathcal{W}} = \hat{\mathcal{W}}_2 \sqcup \hat{\mathcal{W}}_1$$
.

where:

$$\hat{\mathcal{W}}_2 \stackrel{\text{def.}}{=} \{ \hat{p} \in \hat{M} | \operatorname{rk} \hat{\mathcal{D}}_{\hat{p}} = 7 \} , \quad \hat{\mathcal{W}}_1 \stackrel{\text{def.}}{=} \{ \hat{p} \in \hat{M} | \operatorname{rk} \hat{\mathcal{D}}_{\hat{p}} = 8 \} . \tag{2.20}$$

Notice that we always have $\operatorname{rk}\hat{\mathcal{D}}(\hat{p}) < 9$, since $||\hat{V}_1|| = ||\hat{V}_2|| = 1$ by (2.8) and hence the space spanned by $\hat{V}_1(\hat{p}), \hat{V}_2(\hat{p})$ and $\hat{V}_3(\hat{p})$ has dimension at least one. We thus have a disjoint union decomposition:

$$\hat{M} = \hat{\mathcal{U}} \sqcup \hat{\mathcal{W}}_2 \sqcup \hat{\mathcal{W}}_1 \ . \tag{2.21}$$

Also notice that $\hat{\mathcal{U}}, \hat{\mathcal{W}}_1, \hat{\mathcal{W}}_2$ and $\hat{\mathcal{W}}$ are invariant under rotations of the circle and hence they have the forms:

$$\hat{\mathcal{U}} = \pi_1^{-1}(\mathcal{U}') = \mathcal{U}' \times S^1 , \qquad \hat{\mathcal{W}} = \pi_1^{-1}(\mathcal{W}') = \mathcal{W}' \times S^1
\hat{\mathcal{W}}_1 = \pi_1^{-1}(\mathcal{W}'_1) = \mathcal{W}'_1 \times S^1 , \quad \hat{\mathcal{W}}_2 = \pi_1^{-1}(\mathcal{W}'_2) = \mathcal{W}'_2 \times S^1 ,$$

where $\mathcal{U}', \mathcal{W}'_1, \mathcal{W}'_2$ and $\mathcal{W}' = \mathcal{W}'_1 \sqcup \mathcal{W}'_2$ are subsets of M which give a decomposition (see figure 2):

$$M = \mathcal{U}' \sqcup \mathcal{W}' = \mathcal{U}' \sqcup \mathcal{W}'_2 \sqcup \mathcal{W}'_1 . \tag{2.22}$$

As we shall see below, this decompositions of M induced by $\hat{\mathcal{D}}$ is generally quite different from the first decomposition in (1.8) (which is induced by \mathcal{D}). Using (2.8), the Gram determinant formula gives:

$$||\hat{V}_1 \wedge \hat{V}_2 \wedge \hat{V}_3||^2 = \det \begin{bmatrix} 1 & \hat{\alpha} & 0\\ \hat{\alpha} & 1 & 0\\ 0 & 0 & \frac{1-\hat{\alpha}}{2} \end{bmatrix} = \frac{1}{2}(1+\hat{\alpha})(1-\hat{\alpha})^2 , \qquad (2.23)$$

where we introduced the function (this is denoted by α in [3]):

$$\hat{\alpha} \stackrel{\text{def.}}{=} \langle \hat{V}_1, \hat{V}_2 \rangle \in \mathcal{C}^{\infty}(\hat{M}, [-1, 1]) . \tag{2.24}$$

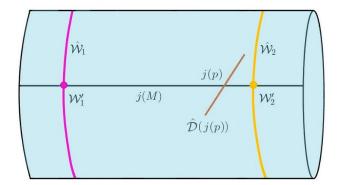


Figure 2. The decomposition of M induced by $\hat{\mathcal{D}}$. The figure shows the particular case when each of the loci $\hat{\mathcal{W}}_1$ and $\hat{\mathcal{W}}_2$ (depicted in magenta and yellow respectively) is connected. The open stratum $\hat{\mathcal{U}}$ (depicted in cyan) defined by $\hat{\mathcal{D}}$ is the complement of $\hat{\mathcal{W}} = \hat{\mathcal{W}}_1 \sqcup \hat{\mathcal{W}}_2$ inside \hat{M} . The intersection of $\hat{\mathcal{W}}_k$ with j(M) determines loci $\mathcal{W}'_k \subset M$, which in this low-dimensional rendering are depicted as dots. The intersection of $\hat{\mathcal{U}}$ with j(M) determines the locus $\mathcal{U}' \subset M$, which is the complement of the union $\mathcal{W}' = \mathcal{W}'_1 \sqcup \mathcal{W}'_2$ in M. In brown, we depicted the space $\hat{\mathcal{D}}(j(p)) \subset T_{j(p)}\hat{M}$ for a point $p \in M$.

Notice that $\hat{\alpha}$ is invariant under rotations of the circle and hence:

$$\hat{\alpha} = \alpha \circ \pi_1$$
 for some function $\alpha \in \mathcal{C}^{\infty}(M, \mathbb{R})$.

Relation (2.23) implies that the decomposition (2.18) of \hat{M} coincides with the $\hat{\alpha}$ -preimage of the canonical Whitney stratification of the closed interval [-1,1]:

$$\hat{\mathcal{U}} = \hat{\alpha}^{-1}((-1,1)) = \{\hat{p} \in \hat{M} | \ \hat{\alpha}(\hat{p}) \in (-1,1)\}, \quad \hat{\mathcal{W}} = \hat{\alpha}^{-1}(\{-1,1\}) = \{\hat{p} \in \hat{M} | \ |\hat{\alpha}(\hat{p})| = 1\},$$

while the first decomposition of M given in (2.22) coincides with the α -preimage of the same stratification:

$$\mathcal{U}' = \alpha^{-1}((-1,1)) = \{ p \in M | \alpha(p) \in (-1,1) \}, \quad \mathcal{W}' = \alpha^{-1}(\{-1,1\}) = \{ p \in M | |\alpha(p)| = 1 \}.$$

The following result (cf. [3]) shows that the rank stratification of \hat{M} induced by $\hat{\mathcal{D}}$ coincides with the $\hat{\alpha}$ -preimage of the connected refinement of the Whitney stratification of the interval, while the stratification of M given by the second decomposition in (2.22) coincides with the α -preimage of the same.

Proposition. Let $\hat{p} \in \hat{W}$.

- For $\hat{\alpha}(\hat{p}) = +1$, we have $\hat{V}_3(\hat{p}) = 0$ and $\hat{V}_1(\hat{p}) = \hat{V}_2(\hat{p})$ with $||\hat{V}_1(\hat{p})|| = 1$. Thus $\operatorname{rk}\hat{\mathcal{D}}(\hat{p}) = 8$.
- For $\hat{\alpha}(\hat{p}) = -1$, we have $\hat{V}_2(\hat{p}) = -\hat{V}_1(\hat{p})$ with $||\hat{V}_1(\hat{p})|| = ||\hat{V}_3(\hat{p})|| = 1$ and $\hat{V}_3(\hat{p}) \perp \hat{V}_1(\hat{p})$. Thus $\operatorname{rk}\hat{\mathcal{D}}(\hat{p}) = 7$.

$\hat{lpha}(\hat{p})$	$\beta(\pi_1(\hat{p}))$	B^{-1} -stratum	$\operatorname{rk}\hat{\mathcal{D}}(\hat{p})$	$\hat{H}_{\hat{p}}$	
+1	0	$0 \qquad \hat{\mathcal{W}}_1 \qquad \mathcal{W}'_1$		8	SU(4)
-1	1	$\hat{\mathcal{W}}_2$	\mathcal{W}_2'	7	G_2
$\in (-1,1)$	$\in (0,1)$	Û	U'	6	SU(3)

Table 1. The stabilizer stratification of \hat{M} . The second column of the table uses relation (2.26).

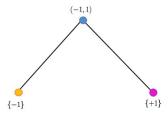


Figure 3. Hasse diagram of the incidence poset (see [5], appendix C) of the connected refinement of the Whitney stratification of the interval [-1,1]. The $\hat{\alpha}$ -preimages of the strata depicted in magenta, yellow and cyan correspond to the SU(4), G₂ and SU(3) loci of \hat{M} respectively.

In particular, we have:

$$\hat{\mathcal{W}}_1 = \hat{\alpha}^{-1}(\{+1\}) = \{\hat{p} \in \hat{M} | \hat{\alpha}(\hat{p}) = +1\}, \ \hat{\mathcal{W}}_2 = \hat{\alpha}^{-1}(\{-1\}) = \{\hat{p} \in \hat{M} | \hat{\alpha}(\hat{p}) = -1\}$$
$$\mathcal{W}'_1 = \alpha^{-1}(\{+1\}) = \{p \in M | \alpha(p) = +1\}, \ \mathcal{W}'_2 = \alpha^{-1}(\{-1\}) = \{p \in M | \alpha(p) = -1\} \ (2.25)$$

Proof. Follows immediately from (2.8).

The following statement given in [3] follows from known facts about stabilizers of actions of Lie groups on spheres³:

Proposition. The isomorphism type of $\hat{H}_{\hat{p}}$ is given by (see table 1):

- $\hat{H}_{\hat{p}} \simeq \mathrm{SU}(4)$ for $\hat{p} \in \hat{\mathcal{W}}_1 = \hat{\alpha}^{-1}(\{+1\})$
- $\hat{H}_{\hat{p}} \simeq G_2$ for $\hat{p} \in \hat{W}_2 = \hat{\alpha}^{-1}(\{-1\})$
- $\hat{H}_{\hat{p}} \simeq \mathrm{SU}(3)$ for $\hat{p} \in \hat{\mathcal{U}} = \hat{\alpha}^{-1}((-1,1))$.

In particular, the stabilizer stratification of \hat{M} coincides with the rank stratification of $\hat{\mathcal{D}}$ and hence with the $\hat{\alpha}$ -preimage of the canonical Whitney stratification of the interval [-1,1] (see figure 3).

³The stabilizer of a single non-vanishing spinor in the Majorana representation $\Delta_9 \simeq \mathbb{R}^{16}$ of Spin(9) is a subgroup isomorphic with Spin(7), belonging to a certain conjugacy class of subgroups of Spin(9) which is usually denoted by Spin_Δ(7) (see, for example, [30]). With respect to this subgroup, we have the decomposition $\Delta_9 = \Lambda_7 \oplus \Delta_7 \oplus \mathbb{R}$, where $\Lambda_7 \simeq \mathbb{R}^7$ and $\Delta_7 \simeq \mathbb{R}^8$ are the vector and real spinor representations of Spin(7), respectively. Stabilizing $\hat{\xi}_1(\hat{p})$ first, we can take $\hat{\xi}_1(\hat{p}) \in \mathbb{R}$ and $\hat{\xi}_2(\hat{p}) \in \Lambda_7 \oplus \Delta_7$. Thus $\hat{H}_{\hat{p}} \simeq \operatorname{Stab}_{\operatorname{Spin}_{\Delta}(7)}(\hat{\xi}_2(\hat{p}))$ is isomorphic with SU(4) $\simeq \operatorname{Spin}(6)$, G₂ or SU(3). The first case arises when $\hat{\xi}_2(\hat{p}) \in \Lambda_7$, the second when $\hat{\xi}_2(\hat{p}) \in \Delta_7$ and the third when $\hat{\xi}_2(\hat{p})$ has non-vanishing projection on both Λ_7 and Δ_7 . In the second and third case, we used the fact that Spin(7) acts transitively on the unit sphere $S^7 \subset \Delta_7$ with stabilizer G₂ and the fact that G₂ acts transitively on $S^6 \subset \Lambda_7$ with stabilizer SU(3).

2.6 Comparison with the stratification of M induced by the connected refinement of the Whitney stratification of \mathfrak{P}

Let $\beta: M \to \mathbb{R}$ be the function defined in (1.4).

Proposition. We have:

$$\alpha = \langle V_1, V_2 \rangle + b_1 b_2 = 1 - 2\beta^2 \in \mathcal{C}^{\infty}(M, [-1, 1])$$
(2.26)

and hence $\beta(M) \subset [0,1]$ and:

$$\mathcal{U}' = \beta^{-1}((0,1)) , \quad \mathcal{W}'_1 = \beta^{-1}(\{0\}) , \quad \mathcal{W}'_2 = \beta^{-1}(\{+1\}) .$$
 (2.27)

Moreover, the following relations express W'_1, W'_2, W' and U' in terms of the strata introduced in [5], subsection 5.3:

$$\mathcal{W}_1' = B^{-1}(\mathfrak{I}) = \mathcal{W}_0 \sqcup \mathcal{W}_1^0, \quad \mathcal{W}_2' = B^{-1}(\mathfrak{D}) = \mathcal{W}_1^1 \sqcup \mathcal{W}_2^{2+}$$
 (2.28)

$$\mathcal{W}' = \mathcal{W}_0 \sqcup \mathcal{W}_1 \sqcup \mathcal{W}_2^{2+}, \qquad \mathcal{U}' = B^{-1}(\operatorname{Int}\mathfrak{P}) \sqcup B^{-1}(\mathfrak{A}) \sqcup B^{-1}(\partial_3\mathfrak{P}) = \mathcal{U} \sqcup \mathcal{W}_2^{2-} \sqcup \mathcal{W}_2^3.$$

Proof. Relation (2.26) follows from (2.24) and (2.6), where the last equality in (2.26) follows by subtracting the second equation of (1.3) from the first and using (1.4) and (1.2). Relations (2.27) follow immediately from (2.25) upon using (2.26). The equalities in (2.28) follow immediately from the last two equations in (2.27) upon using the last Proposition in [5], subsection 4.2 and the results of [5], subsection 5.3. \blacksquare

3 Transversality

3.1 Recovering ${\cal D}$ from $\hat{{\cal D}}$

To understand the relation between the rank stratifications of \mathcal{D} and $\hat{\mathcal{D}}$, notice that (2.4), together with the obvious equality $j_*(TM) = \ker \theta|_{j(M)}$, imply that \mathcal{D} can be recovered from $\hat{\mathcal{D}}$ through the relation $j_*(\mathcal{D}) = (\hat{\mathcal{D}}|_{j(M)}) \cap j_*(TM)$. Identifying M with j(M) (and hence TM with $j_*(TM)$), we can write this relation as (see figure 2):

$$\mathcal{D} = \hat{\mathcal{D}}|_{M} \cap TM \ . \tag{3.1}$$

Also notice that \mathcal{U}' and \mathcal{W}' coincide with the generic and degeneration loci of the restricted distribution $\hat{\mathcal{D}}|_{M}$:

$$\mathcal{U}' = \{ p \in M | \operatorname{rk} \hat{\mathcal{D}}(p) = 6 \} , \quad \mathcal{W}' = \{ p \in M | \operatorname{rk} \hat{\mathcal{D}}(p) > 6 \} .$$

3.2 The transverse and non-transverse loci of M

Recall that two subspaces K_1 and K_2 of a vector space K satisfy $\dim(K_1+K_2) = \dim K_1 + \dim K_2 - \dim(K_1 \cap K_2)$ i.e. $\operatorname{codim}(K_1+K_2) = \operatorname{codim}K_1 + \operatorname{codim}K_2 - \operatorname{codim}(K_1 \cap K_2)$, where codim denotes the codimension relative to K. Since $\dim(K_1 \cap K_2) \leq \min(\dim K_1, \dim K_2)$, we have $\max(\operatorname{codim}K_1, \operatorname{codim}K_2) \leq \operatorname{codim}(K_1 \cap K_2) \leq \operatorname{codim}K_1 + \operatorname{codim}K_2$. The subspaces are called $\operatorname{transverse}$ when $\operatorname{codim}(K_1 \cap K_2) = \operatorname{codim}K_1 + \operatorname{codim}K_2$, which is equivalent with $\operatorname{codim}(K_1+K_2) = 0$ i.e. with $K_1+K_2 = K$. This condition defines a symmetric binary relation (the transversality relation) on the set of all subspaces of K. For $p \in M$, let \pitchfork_p denote the transversality relation between subspaces of $T_{j(p)}\hat{M}$, and $\not \pitchfork_p$ denote its negation (the non-transversality relation).

Definition. The *transverse locus* is the following subset of M:

$$\mathcal{T} \stackrel{\text{def.}}{=} \{ p \in M | \hat{\mathcal{D}}(p) \pitchfork_p T_p M \} , \qquad (3.2)$$

while its complement in M is called the *non-transverse locus*:

$$\mathcal{N} \stackrel{\text{def.}}{=} \{ p \in M | \hat{\mathcal{D}}(p) \not \bowtie_p T_p M \} , \qquad (3.3)$$

where we identify $p \in M$ with $j(p) \in \hat{M}$ and T_pM with the subspace $j_{*,p}(T_pM)$ of $T_{j(p)}\hat{M}$.

3.3 Characterizing the transverse and non-transverse loci

Proposition. Let $p \in M \equiv j(M)$. Then:

$$\dim \mathcal{D}(p) \in \{\dim \hat{\mathcal{D}}(p), \dim \hat{\mathcal{D}}(p) - 1\} \ . \tag{3.4}$$

Moreover, the following statements are equivalent:

- (a) $p \in \mathcal{N}$
- (b) dim $\mathcal{D}(p)$ = dim $\hat{\mathcal{D}}(p)$
- (c) $\mathcal{D}(p) = \hat{\mathcal{D}}(p)$
- (d) $\hat{\mathcal{D}}(p) \subset T_p M$
- (e) $\theta(p) \in \langle \hat{V}_1(p), \hat{V}_2(p), \hat{V}_3(p) \rangle$.

In particular, we have dim $\mathcal{D}(p) = \dim \hat{\mathcal{D}}(p) - 1$ iff $p \in \mathcal{T}$.

Proof. Since $T_p\hat{M}$ has dimension nine while T_pM has dimension eight (thus $\operatorname{codim} T_pM = 1$), relation (3.1) implies $\operatorname{codim} \mathcal{D}(p) \leq \operatorname{codim} \hat{\mathcal{D}}(p) + 1$, i.e. $\dim \mathcal{D}(p) \geq \dim \hat{\mathcal{D}}(p) - 1$, with equality iff $\hat{\mathcal{D}}(p)$ and T_pM are transverse inside $T_p\hat{M}$. Since $\mathcal{D}(p) = \hat{\mathcal{D}}(p) \cap T_pM$, we have $\dim \mathcal{D}(p) \leq \dim \hat{\mathcal{D}}(p)$. This gives (3.4) and shows that:

$$\hat{\mathcal{D}}(p) \pitchfork T_p M$$
 iff $\dim \mathcal{D}(p) = \dim \hat{\mathcal{D}}(p) - 1$.

The non-transverse case corresponds to $\dim \mathcal{D}(p) = \dim \hat{\mathcal{D}}(p)$, which is equivalent with $\mathcal{D}(p) = \hat{\mathcal{D}}(p)$ since $\mathcal{D}(p)$ is a subspace of $\hat{\mathcal{D}}(p)$. Since $\mathcal{D}(p) = \hat{\mathcal{D}}(p) \cap T_pM \subset T_pM$, the equality $\mathcal{D}(p) = \hat{\mathcal{D}}(p)$ holds iff $\hat{\mathcal{D}}(p) \subset T_pM$. Since $T_pM = \ker \theta(p)$ and $\hat{\mathcal{D}}(p) = \bigcap_{i=1}^3 \ker \hat{V}_i(p)$, this happens if $\bigcap_{i=1}^3 \ker \hat{V}_i(p) \subset \ker \theta(p)$, which by duality (taking polars) happens iff $\theta(p) \in \langle \hat{V}_1(p), \hat{V}_2(p), \hat{V}_3(p) \rangle$.

Corollary. Let $p \in M \equiv j(M)$. Then the following statements are equivalent:

- (a) $p \in \mathcal{N}$.
- (b) There exist $\lambda_1, \lambda_2, \lambda_3 \in \mathbb{R}$ such that:

$$\lambda_1 V_1(p) + \lambda_2 V_2(p) + \lambda_3 V_3(p) = 0$$
 and $\lambda_1 b_1(p) + \lambda_2 b_2(p) + \lambda_3 b_3(p) = 1$.

In particular, the non-transverse locus is contained in the degeneration locus of \mathcal{D} and hence the generic locus of \mathcal{D} is contained in the transverse locus:

$$\mathcal{N} \subset \mathcal{W} \ , \ \mathcal{U} \subset \mathcal{T} \ .$$
 (3.5)

\$\psi\-locus	$\hat{\mathcal{D}}$ -stratum	B^{-1} -stratum	\mathcal{D}_0 -stratum	$\mathrm{rk}\hat{\mathcal{D}}$	$\mathrm{rk}\mathcal{D}$	$\mathrm{rk}\mathcal{D}_0$	transversality	\hat{H}_p	H_p
$\partial_0 \mathfrak{P} = \partial \mathfrak{I}$	\mathcal{W}_1'	\mathcal{W}_0	\mathcal{Z}_0	8	8	8	\mathcal{N}	SU(4)	SU(4)
$\partial_1^0 \mathfrak{P} = \operatorname{Int} \mathfrak{I}$	\mathcal{W}_1'	\mathcal{W}_1^0	\mathcal{Z}_2	8	7	6	\mathcal{T}	SU(4)	SU(3)
$\partial_1^1 \mathfrak{P} = \partial \mathfrak{D}$	\mathcal{W}_2'	\mathcal{W}_1^1	\mathcal{Z}_1	7	7	7	$\mathcal N$	G_2	G_2
$\mathrm{Int}\mathfrak{D}\subset\partial_2\mathfrak{P}$	\mathcal{W}_2'	\mathcal{W}_2^{2+}	\mathcal{Z}_2	7	6	6	\mathcal{T}	G_2	SU(3)
$\mathfrak{A}\sqcup\partial_3\mathfrak{P}$	\mathcal{U}'	$\mathcal{W}_2^{2-}\sqcup\mathcal{W}_2^3$	\mathcal{Z}_2	6	6	6	\mathcal{N}	SU(3)	SU(3)
$Int \mathfrak{P}$	\mathcal{U}'	И	И	6	5	4	\mathcal{T}	SU(3)	SU(2)

Table 2. The ranks of $\hat{\mathcal{D}}|_M$, \mathcal{D} and \mathcal{D}_0 on various loci of M and the character of the intersection $\hat{\mathcal{D}}|_M \cap TM$. The stabilizer groups on \hat{M} and M are shown in the last two columns.

Proof. Follows immediately from (2.4) and from the characterization of non-transversality given at point (e) of the previous proposition, using the fact that $\theta(p)$ is orthogonal to $V_k(p)$.

3.4 Expressing \mathcal{T} and \mathcal{N} through the preimage of the connected refinement of the Whitney stratification of \mathfrak{P}

Proposition. The transverse and non-transverse loci are given by the following unions of the strata introduced in [5], subsection 5.3:

$$\mathcal{T} = \mathcal{W}_1^0 \sqcup \mathcal{W}_2^{2+} \sqcup \mathcal{U} , \quad \mathcal{N} = \mathcal{W}_0 \sqcup \mathcal{W}_1^1 \sqcup \mathcal{W}_2^{2-} \sqcup \mathcal{W}_2^3$$
 (3.6)

and we have the relations:

$$\mathcal{U}' \cap \mathcal{T} = \mathcal{U} , \qquad \qquad \mathcal{U}' \cap \mathcal{N} = \mathcal{W}_2^{2-} \sqcup \mathcal{W}_2^3$$

$$\mathcal{W}_1' \cap \mathcal{T} = \mathcal{W}_1^0 , \qquad \qquad \mathcal{W}_1' \cap \mathcal{N} = \mathcal{W}_0$$

$$\mathcal{W}_2' \cap \mathcal{T} = \mathcal{W}_2^{2+} , \qquad \qquad \mathcal{W}_2' \cap \mathcal{N} = \mathcal{W}_1^1 .$$

$$(3.7)$$

Proof. Follows immediately by comparing the ranks of $\hat{\mathcal{D}}|_{M}$ and \mathcal{D} on various loci and using relations (2.28), the characterization of non-transversality given in the previous subsection and the results summarized in tables 5 and 6 of [5]. \blacksquare The situation is summarized in table 2.

Remark. The proposition implies:

$$\mathcal{U} = \{ p \in M | \operatorname{rk} \hat{\mathcal{D}}(p) = 6 \text{ and } \hat{\mathcal{D}}(p) \text{ intersects } T_p M \text{ transversely} \} = \mathcal{U}' \cap \mathcal{T}$$

 $\mathcal{W} = \{ p \in M | \operatorname{rk} \hat{\mathcal{D}}(p) > 6 \text{ or } \hat{\mathcal{D}}(p) \text{ intersects } T_p M \text{ non - transversely} \} = \mathcal{W}' \cup \mathcal{N} .$

In particular, the SU(2) stratum \mathcal{U} of M is the intersection of the SU(3) stratum $\hat{\mathcal{U}}$ of \hat{M} with the locus $j(\mathcal{T}) \subset j(M)$, while the degeneration points of \mathcal{D} (the points of the locus $\mathcal{W} \subset M$) are of three kinds:

• The points $p \in \mathcal{W}'_1 = \mathcal{W}_0 \sqcup \mathcal{W}^0_1$ (where $\beta = 0$ i.e. $\alpha = +1$), which form the intersection of the SU(4) stratum $\hat{\mathcal{W}}_1$ of \hat{M} with j(M). At such points, we have $H_p \simeq \text{SU}(4)$ or SU(3) according to whether $p \in \mathcal{N}$ or $p \in \mathcal{T}$.

- The points of $W_2' = W_1^1 \sqcup W_2^{2+}$ (where $\beta = 1$ i.e. $\alpha = -1$), which form the intersection of the G_2 stratum \hat{W}_2 of \hat{M} with j(M). At such points, we have $H_p \simeq G_2$ or SU(3) according to whether $p \in \mathcal{N}$ or $p \in \mathcal{T}$.
- The points of $W \setminus W' = W_2^{2-} \sqcup W_2^3$, which form the intersection of the SU(3) stratum $\hat{\mathcal{U}}$ of \hat{M} with the locus $j(\mathcal{N}) \subset j(M)$. At such points, we have $H_p \simeq \mathrm{SU}(3)$.

3.5 The case $\mathcal{T} = \emptyset$

The previous proposition immediately implies the following:

Corollary. The condition $\mathcal{T} = \emptyset$ is equivalent with the conditions $\mathcal{W}_1^0 = \mathcal{W}_2^{2+} = \mathcal{U} = \emptyset$. When this condition is satisfied, we have $\mathcal{W}_1' = \mathcal{Z}_0 = \mathcal{W}_0$, $\mathcal{W}_2' = \mathcal{Z}_1 = \mathcal{W}_1^1$ and $\mathcal{U}' = \mathcal{Z}_2 = \mathcal{W}_2^{2-} \sqcup \mathcal{W}_2^3$. In this case, we have $M = \mathcal{N} = \mathcal{W}_0 \sqcup \mathcal{W}_1^1 \sqcup \mathcal{W}_2^{2-} \sqcup \mathcal{W}_2^3$ and $\hat{H}_p \simeq H_p$ for any $p \in M$, both groups being isomorphic with SU(4), G₂ or SU(3) according to whether $p \in \mathcal{W}_0$, $p \in \mathcal{W}_1^1$ or $p \in \mathcal{W}_2^{2-} \sqcup \mathcal{W}_2^3$.

Notice that $\mathcal{T} = \emptyset$ implies $B^{-1}(\operatorname{Int}\mathfrak{P}) = \mathcal{U} = \emptyset$ and hence requires that the image of B be contained in the frontier $\partial \mathfrak{P}$ of \mathfrak{P} . More precisely, we have:

$$\mathcal{T} = \emptyset \text{ iff } B(M) \subset \partial \mathfrak{I} \sqcup \partial \mathfrak{D} \sqcup \mathfrak{A} \sqcup \partial_3 \mathfrak{P} .$$

Remark. Reference [3] uses the assumption (see equation (3.9) of loc. cit.) that $\theta(p)$ is a linear combination of $\hat{V}_1(p)$, $\hat{V}_2(p)$ and $\hat{V}_3(p)$ for every point $p \in M$. By the characterization given at point (e) of the Proposition of subsection 3.3, this assumption is equivalent with the requirement that the transverse locus \mathcal{T} be empty and hence that we are in the setting of the Corollary above. By the Corollary of subsection 3.3, the condition $\mathcal{T} = \emptyset$ requires, in particular, that the 1-forms $V_1(p), V_2(p)$ and $V_3(p)$ be linearly dependent at every point $p \in M$ (cf. [5], appendix G). In was shown in [5] that, generically, we have $\mathcal{U} \neq \emptyset$ and hence the transverse locus is not empty in the generic case.

3.6 Relation between the stabilizer stratifications of M and \hat{M}

It is known that an orientable hypersurface in an 8-manifold with SU(4) structure carries a naturally induced SU(3) structure (see, for example, [22], section 4). An orientable hypersurface in a 7-manifold with G_2 structure carries a naturally induced SU(3) structure (see, for example, [23–25]). Finally, an orientable hypersurface of a manifold with SU(3) structure carries a naturally induced SU(2) structure [26]. Since these statements are purely algebraic, they extend immediately to the case of Frobenius distributions. Using these facts and the results above, we can understand how the stratified G-structure of \hat{M} induces the stratified G-structure of M. Namely, we have (see table 2):

- The restriction $\mathcal{D}|_{\mathcal{N}}$ coincides with $\hat{\mathcal{D}}|_{\mathcal{N}}$ and hence $\mathcal{D}|_{\mathcal{N}}$ carries the same structure group (namely SU(4), G₂ or SU(3)) as $\hat{\mathcal{D}}|_{\mathcal{N}}$ on the components \mathcal{W}_0 , \mathcal{W}_1^1 and $\mathcal{W}_2^{2-} \sqcup \mathcal{W}_2^3$ respectively of the non-transverse locus.
- The restriction $\mathcal{D}|_{\mathcal{T}}$ is an orientable and corank one generalized sub-distribution of $\hat{\mathcal{D}}|_{\mathcal{T}}$ and hence $\mathcal{D}|_{\mathcal{T}}$ carries the structure group SU(3), SU(3) and SU(2) on the

components W_1^0 , W_2^{2+} and \mathcal{U} respectively of the transverse locus \mathcal{T} on which $\hat{\mathcal{D}}|_{\mathcal{T}}$ has the structure group SU(4), G_2 and SU(3) respectively.

These observations give a different way to understand the results of [5], provided that one knows the codimension of $\mathcal{D}(p)$ inside $\hat{\mathcal{D}}(p)$ on the various strata (which follows from loc. cit.).

4 Explicit relation between the SU(3) structure on $\hat{\mathcal{U}}$ and the SU(2) structure on \mathcal{U}

Since j identifies $\mathcal{U} = \mathcal{U}' \cap \mathcal{T}$ with $\hat{\mathcal{U}} \cap j(\mathcal{T})$, the restriction of $\hat{\mathcal{D}}$ to the locus $\mathcal{U} \equiv j(\mathcal{U}) \subset \hat{\mathcal{U}}$ is a regular Frobenius distribution of rank six. Since \hat{M} is oriented with volume form (2.1), we can orient $\hat{\mathcal{D}}|_{\mathcal{U}}$ using the volume form:

$$\hat{\nu}_{\perp} \stackrel{\text{def.}}{=} \frac{1}{||\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}||} \iota_{\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}} \hat{\nu}|_{\mathcal{U}} . \tag{4.1}$$

4.1 The projection of θ along $\hat{\mathcal{D}}$ on the generic locus

The one-form $\theta|_{\mathcal{U}}$ decomposes uniquely as:

$$\theta|_{\mathcal{U}} = \theta_{\perp} + \theta_{\parallel} , \qquad (4.2)$$

where $\theta_{\perp} \in \Omega^1_{\mathcal{U}}(\hat{\mathcal{D}}) = \langle \hat{V}_+|_{\mathcal{U}}, \hat{V}_-|_{\mathcal{U}}, \hat{V}_3|_{\mathcal{U}} \rangle^{\perp}$ and $\theta_{\parallel} \in \Omega^1_{\mathcal{U}}(\hat{\mathcal{D}}^{\perp}) = \langle \hat{V}_+|_{\mathcal{U}}, \hat{V}_-|_{\mathcal{U}}, \hat{V}_3|_{\mathcal{U}} \rangle$ (see figure 4). Since \mathcal{U} is a subset of \mathcal{T} , the characterization at point (e) of the Proposition of subsection 3.3 gives $\theta_{\parallel} \neq \langle \hat{V}_+|_{\mathcal{U}}, \hat{V}_-|_{\mathcal{U}}, \hat{V}_3|_{\mathcal{U}} \rangle$ and hence $\theta_{\perp} \neq 0$ and we can define the unit norm one-form:

$$\mathbf{n} \stackrel{\text{def.}}{=} \frac{\theta_{\perp}}{||\theta_{\perp}||} \in \Omega^{1}_{\mathcal{U}}(\hat{\mathcal{D}}) \ . \tag{4.3}$$

We orient the rank five Frobenius distribution $\mathcal{D}|_{\mathcal{U}}$ such that its volume form is given by:

$$\nu_{\perp} = -\frac{1}{\|V_{+} \wedge V_{-} \wedge V_{3}\|} \iota_{V_{+} \wedge V_{-} \wedge V_{3}} \nu . \tag{4.4}$$

Proposition. We have $\mathcal{D}|_{\mathcal{U}} = (\ker \theta_{\perp}) \cap \hat{\mathcal{D}}|_{\mathcal{U}}$, i.e. the normalized vector field $\mathbf{n}^{\sharp} \in \Gamma(\mathcal{U}, \hat{\mathcal{D}})$ is everywhere orthogonal to $\mathcal{D}|_{\mathcal{U}}$ inside $\hat{\mathcal{D}}|_{\mathcal{U}}$, where $^{\sharp}$ denotes the musical isomorphism of (\hat{M}, \hat{g}) . Moreover, we have:

$$||\theta_{\perp}|| = \frac{||V_{+} \wedge V_{-} \wedge V_{3}||}{||\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}||}$$
(4.5)

and:

$$\nu_{\perp} = -\iota_{\mathbf{n}} \hat{\nu}_{\perp} . \tag{4.6}$$

Furthermore, we have:

$$\theta_{\parallel} = \frac{b_{+}}{1 - \beta^{2}} \hat{V}_{+} + \frac{b_{-}}{\beta^{2}} \hat{V}_{-} + \frac{b_{3}}{\beta^{2}} \hat{V}_{3} \quad (\text{on } \mathcal{U})$$

$$(4.7)$$

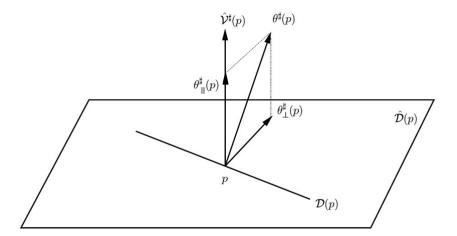


Figure 4. Construction of $\theta_{\perp}(p)$ for $p \in \mathcal{U} \equiv j(\mathcal{U}) \subset j(M) \subset \hat{M}$. The vectors $\theta^{\sharp}(p) \in T_p \hat{M}$ and $\theta_{\perp}^{\sharp}(p) \in T_p \hat{M}$ shown in the figure are obtained by applying the musical isomorphism of (\hat{M}, \hat{g}) to the 1-forms $\theta(p)$ and $\theta_{\perp}(p)$. The vertical arrow represents the space $\hat{\mathcal{V}}^{\sharp}(p)$ spanned by the vectors $\hat{V}_{1}^{\sharp}(p), \hat{V}_{2}^{\sharp}(p)$ and $\hat{V}_{3}^{\sharp}(p)$ inside $T_p \hat{M}$. The vectors $\theta_{\perp}^{\sharp}(p)$ and $\theta_{\parallel}^{\sharp}(p)$ are the orthogonal projections of $\theta^{\sharp}(p)$ onto $\hat{\mathcal{D}}(p)$ and $\hat{\mathcal{V}}^{\sharp}(p)$ respectively. The subspace $\mathcal{D}(p)$ of $T_p \hat{M}$ coincides with the intersection of $\hat{\mathcal{D}}(p)$ with $T_p M = \ker \theta(p) \subset T_p \hat{M}$ and hence it is orthogonal to the vector $\theta^{\sharp}(p) \in T_p \hat{M}$. It is also orthogonal to the subspace $\hat{\mathcal{V}}^{\sharp}(p) \subset T_p \hat{M}$.

and:

$$||\theta_{\perp}||^2 = 1 - \frac{b_+^2}{1 - \beta^2} - \frac{\rho^2}{\beta^2} \quad (\text{on } \mathcal{U}) ,$$
 (4.8)

where ρ was defined in (2.13).

Proof. Since $\mathcal{D} \subset TM$, we have $\mathcal{D}|_{\mathcal{U}} \subset \ker \theta|_{\mathcal{U}}$ and hence θ vanishes on $\mathcal{D}|_{\mathcal{U}}$. Since θ_{\parallel} is a linear combination of $\hat{V}_1|_{\mathcal{U}}, \hat{V}_2|_{\mathcal{U}}$ and $\hat{V}_3|_{\mathcal{U}}$ and since $\hat{\mathcal{D}} = \bigcap_{i=1}^3 \ker \hat{V}_i$, we have $\hat{\mathcal{D}}|_{\mathcal{U}} \subset \ker \theta_{\parallel}$ and hence θ_{\parallel} vanishes on $\hat{\mathcal{D}}|_{\mathcal{U}}$ and thus also on $\mathcal{D}|_{\mathcal{U}} \subset \hat{\mathcal{D}}|_{\mathcal{U}}$. Using relation (4.2), the fact that $\theta|_{\mathcal{U}}$ and θ_{\parallel} vanish on $\mathcal{D}|_{\mathcal{U}}$ implies that θ_{\perp} vanishes on $\mathcal{D}|_{\mathcal{U}}$ and hence that θ_{\perp}^{\sharp} and \mathbf{n}^{\sharp} are orthogonal to $\mathcal{D}|_{\mathcal{U}}$. Relations (4.4) and (2.1) give:

$$\nu_{\perp} = -\frac{1}{||V_{+} \wedge V_{-} \wedge V_{3}||} \iota_{V_{+} \wedge V_{-} \wedge V_{3} \wedge \theta} \hat{\nu}|_{\mathcal{U}} = \frac{||\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}||}{||V_{+} \wedge V_{-} \wedge V_{3}||} \iota_{\theta_{\perp}} \hat{\nu}_{\perp} , \qquad (4.9)$$

where in the second equality we used the relation (4.1) and the equality:

$$V_+ \wedge V_- \wedge V_3 \wedge \theta = \hat{V}_+ \wedge \hat{V}_- \wedge \hat{V}_3 \wedge \theta = -\theta_\perp \wedge \hat{V}_+ \wedge \hat{V}_- \wedge \hat{V}_3 \ ,$$

which follows from the decompositions (2.4) and (4.2) upon noticing that $\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3} \wedge \theta_{\parallel} = 0$. Relations (4.5) and (4.6) now follow from (4.9) upon noticing that $||\nu_{\perp}|| = ||\hat{\nu}_{\perp}|| = 1$ and $||\iota_{\theta_{\perp}}\hat{\nu}_{\perp}|| = ||\theta_{\perp}|| ||\hat{\nu}_{\perp}|| = ||\theta_{\perp}||$. The decomposition (4.2) means that θ_{\parallel} is the projection of θ onto $\langle \hat{V}_{+}|_{\mathcal{U}}, \hat{V}_{-}|_{\mathcal{U}}, \hat{V}_{3}|_{\mathcal{U}} \rangle$. Writing $\theta_{\parallel} = a_{+}\hat{V}_{+}|_{\mathcal{U}} + a_{-}\hat{V}_{-}|_{\mathcal{U}} + a_{3}\hat{V}_{3}|_{\mathcal{U}}$ with $a_{r} \in \mathcal{C}^{\infty}(\mathcal{U}, \mathbb{R})$, we have $\langle \theta, \hat{V}_{r} \rangle_{|\mathcal{U}} = \langle \theta_{\parallel}, \hat{V}_{r} \rangle_{|\mathcal{U}} = a_{r}||\hat{V}_{r}||^{2}|_{\mathcal{U}}$, where we used the fact that $\langle \hat{V}_{r}, \hat{V}_{s} \rangle = ||\hat{V}_{r}||^{2}\delta_{rs}$

for all $r, s \in \{+, -, 3\}$ (see (2.7)). On the other hand, relations (2.4) give $\langle \theta, \hat{V}_r \rangle |_{\mathcal{U}} = b_r$. Thus $a_r = \frac{b_r}{||\hat{V}_r||^2}$ on \mathcal{U} , i.e.:

$$a_{+} = \frac{b_{+}}{||\hat{V}_{+}||^{2}} = \frac{b_{+}}{1 - \beta^{2}}, \quad a_{-} = \frac{b_{-}}{||\hat{V}_{-}||^{2}} = \frac{b_{-}}{\beta^{2}}, \quad a_{3} = \frac{b_{3}}{||\hat{V}_{3}||^{2}} = \frac{b_{3}}{\beta^{2}} \quad (\text{on } \mathcal{U}),$$

where we used (2.9). This immediately gives (4.7) and (4.8). Notice that relation (4.8) can also be derived from (4.5) by using the expression for the Gram determinant $||V_{+} \wedge V_{-} \wedge V_{3}||^{2}$ given in [5], section 4.2 and the relation $||\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}||^{2} = ||\hat{V}_{+}||^{2}||\hat{V}_{-}||^{2}||\hat{V}_{3}||^{2} = \beta^{4}(1-\beta^{2})$ (which follows from (2.9)). Indeed, we have:

$$||\theta_{\perp}||^{2} = \frac{||V_{+} \wedge V_{-} \wedge V_{3}||^{2}}{||\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}||^{2}} = -\frac{\beta^{2}(\beta^{4} - \beta^{2}(1 - b_{+}^{2} + \rho^{2}) + \rho^{2})}{\beta^{4}(1 - \beta^{2})}$$
$$= \frac{\beta^{2}(1 - \beta^{2}) - \beta^{2}b_{+}^{2} - \rho^{2}(1 - \beta^{2})}{\beta^{2}(1 - \beta^{2})},$$

which recovers (4.8).

Remark. Relations (4.2), (4.3), (4.7) and (4.8) give:

$$\theta =_{\mathcal{U}} \frac{b_{+}}{1 - \beta^{2}} \hat{V}_{+} + \frac{b_{-}}{\beta^{2}} \hat{V}_{-} + \frac{b_{3}}{\beta^{2}} \hat{V}_{3} + \sqrt{1 - \frac{b_{+}^{2}}{1 - \beta^{2}} - \frac{\rho^{2}}{\beta^{2}}} \mathbf{n} . \tag{4.10}$$

Substituting (2.4) into this relation allows us to express $\theta|_{\mathcal{U}}$ in terms of V_+, V_-, V_3 and \mathbf{n} :

$$\theta =_{\mathcal{U}} \frac{\frac{b_{+}}{1-\beta^{2}}V_{+} - \frac{b_{-}}{\beta^{2}}V_{-} - \frac{b_{3}}{\beta^{2}}V_{3}}{1 - \frac{b_{+}^{2}}{1-\beta^{2}} - \frac{\rho^{2}}{\beta^{2}}} + \frac{\mathbf{n}}{\sqrt{1 - \frac{b_{+}^{2}}{1-\beta^{2}} - \frac{\rho^{2}}{\beta^{2}}}}$$
(4.11)

Relation (4.10) should be compared with equation (3.9) of reference [3], which holds only on the non-transverse locus \mathcal{N} (and on its lift to \hat{M}). By contrast, equation (4.10) holds on the generic locus \mathcal{U} , which is contained in the transverse locus.

4.2 Relation between SU(2) and SU(3) structures

An SU(2) structure on the oriented rank five Frobenius distribution $\mathcal{D}|_{\mathcal{U}}$ which is compatible with the metric $g|_{\mathcal{D}}$ and with the orientation of \mathcal{D} can be described by a normalized one-form $\boldsymbol{\alpha} \in \Omega^1_{\mathcal{U}}(\mathcal{D})$ and three mutually orthogonal 2-forms $\boldsymbol{\omega}_1, \boldsymbol{\omega}_2, \boldsymbol{\omega}_3 \in \Omega^2_{\mathcal{U}}(\mathcal{D})$ satisfying the equations (see [26]):

$$\iota_{\alpha}\omega_{k} = 0$$

$$\langle \omega_{k}, \omega_{l} \rangle = 2\delta_{kl}$$

$$\omega_{k} \wedge \omega_{l} = \delta_{kl}\mathbf{v} ,$$
(4.12)

where k, l = 1, 2, 3 and **v** is a non-vanishing four-form which satisfies:

$$\iota_{\boldsymbol{\alpha}}\nu_{\perp} = \frac{1}{2}\mathbf{v}$$
 i.e. $\boldsymbol{\alpha} \wedge \mathbf{v} = 2\nu_{\perp}$.

Namely, we have $\mathcal{D}_0|_{\mathcal{U}} = \ker \alpha$ and $(\omega_1, \omega_2, \omega_3)$ is an orthogonal basis of the free $\mathcal{C}^{\infty}(\mathcal{U}, \mathbb{R})$ module $\Omega_{\mathcal{U}}^{2+}(\mathcal{D}_0)$ of $\mathcal{D}_0|_{\mathcal{U}}$ -longitudinal self-dual 2-forms. As explained in [26], this basis can
be chosen such that it forms a positively-oriented frame of the rank three bundle $\wedge^{2+}\mathcal{D}_0^*$,
where the latter is endowed with the orientation naturally induced from that of \mathcal{D}_0 (which
is given by the volume form $\frac{1}{2}\mathbf{v}$).

On the other hand, an SU(3) structure on the oriented rank six Frobenius distribution $\hat{\mathcal{D}}|_{\mathcal{U}}$ which is compatible with the metric $\hat{g}|_{\mathcal{D}}$ and with the orientation of $\hat{\mathcal{D}}$ is determined [23] by an almost complex structure $\mathbf{I} \in \Gamma(\mathcal{U}, \operatorname{End}(\hat{\mathcal{D}}))$ which is compatible with the metric and orientation of $\hat{\mathcal{D}}$, together with a complex-valued three-form $\mathbf{\Omega} \in \Omega^2_{\mathcal{U}}(\hat{\mathcal{D}}) \otimes \mathbb{C}$ which is of unit norm and has type (3,0) with respect to \mathbf{I} . The almost complex structure defines a two-form $\mathbf{J} \in \Omega^2_{\mathcal{U}}(\hat{\mathcal{D}})$ through the relation:

$$\mathbf{J}(X,Y) \stackrel{\text{def.}}{=} \hat{g}(X,\mathbf{I}Y) , \quad \forall X,Y \in \Gamma(\mathcal{U},\hat{\mathcal{D}})$$
(4.13)

and this form satisfies:

$$\hat{\nu}_{\perp} =_{\mathcal{U}} \frac{1}{6} \mathbf{J} \wedge \mathbf{J} \wedge \mathbf{J} . \tag{4.14}$$

The phase of the normalized (3,0)-form Ω is fixed through the convention:

$$\mathbf{\Omega} \wedge \bar{\mathbf{\Omega}} =_{\mathcal{U}} -8\mathrm{i}\hat{\nu}_{\perp} , \qquad (4.15)$$

Decomposing Ω into its real and imaginary parts:

$$\mathbf{\Omega} = \boldsymbol{\varphi} + i\boldsymbol{\rho} \text{ with } \boldsymbol{\varphi}, \boldsymbol{\rho} \in \Omega^3_{\mathcal{U}}(\hat{\mathcal{D}}) , \qquad (4.16)$$

relation (4.15) amounts to:

$$\varphi \wedge \rho =_{\mathcal{U}} 4\hat{\nu}_{\perp} . \tag{4.17}$$

The following proposition gives the relation between SU(3) structures on the rank six Frobenius distribution $\hat{\mathcal{D}}|_{\mathcal{U}} \stackrel{\text{def.}}{=} j^*(\hat{\mathcal{D}})|_{\mathcal{U}}$ and SU(2) structures on its corank one sub-distribution $\mathcal{D}|_{\mathcal{U}} \subset \hat{\mathcal{D}}|_{\mathcal{U}}$.

Proposition. There is a bijective correspondence between SU(3) structures on $\hat{\mathcal{D}}|_{\mathcal{U}}$ which are compatible with the metric and orientation of $\hat{\mathcal{D}}|_{\mathcal{U}}$ and SU(2) structures on $\mathcal{D}|_{\mathcal{U}}$ which are compatible with the metric and orientation of $\mathcal{D}|_{\mathcal{U}}$. This correspondence is given as follows, where \mathbf{n} was defined in (4.3):

(a) Given a metric- and orientation-compatible SU(3) structure on $\hat{\mathcal{D}}|_{\mathcal{U}}$ with 2-form $\mathbf{J} \in \Omega^2_{\mathcal{U}}(\hat{\mathcal{D}})$ and complex 3-form $\mathbf{\Omega} \in \Omega^3_{\mathcal{U}}(\hat{\mathcal{D}}) \otimes \mathbb{C}$, the following formulas give the canonical forms defining the corresponding metric- and orientation-compatible SU(2) structure on $\mathcal{D}|_{\mathcal{U}}$, where i is the imaginary unit:

$$\boldsymbol{\alpha} = -\iota_{\mathbf{n}} \mathbf{J}|_{\mathcal{D}} \in \Omega^{1}_{\mathcal{U}}(\mathcal{D}) , \quad \boldsymbol{\omega}_{1} = \mathbf{J}|_{\mathcal{D}} \in \Omega^{2}_{\mathcal{U}}(\mathcal{D}) ,$$
$$\boldsymbol{\omega}_{2} + \mathrm{i}\boldsymbol{\omega}_{3} = -\mathrm{i} \ \iota_{\mathbf{n}} \mathbf{\Omega}|_{\mathcal{D}} \in \Omega^{2}_{\mathcal{U}}(\mathcal{D}) .$$

(b) Given a metric- and orientation-compatible SU(2) structure on $\mathcal{D}|_{\mathcal{U}}$ which is defined by the canonical forms $\boldsymbol{\alpha} \in \Omega^1_{\mathcal{U}}(\mathcal{D})$ and $\boldsymbol{\omega}_k \in \Omega^2_{\mathcal{U}}(\mathcal{D})$ (where k = 1, 2, 3), the following forms define the corresponding metric- and orientation-compatible SU(3) structure on $\hat{\mathcal{D}}|_{\mathcal{U}}$:

$$\mathbf{J} = \boldsymbol{\omega}_1 + \boldsymbol{\alpha} \wedge \mathbf{n} \in \Omega_{\mathcal{U}}^2(\hat{\mathcal{D}}) , \qquad (4.18)$$

$$\mathbf{\Omega} = (\boldsymbol{\omega}_2 + \mathrm{i}\boldsymbol{\omega}_3) \wedge (\boldsymbol{\alpha} + \mathrm{i}\mathbf{n}) \in \Omega_{\mathcal{U}}^3(\hat{\mathcal{D}}) \otimes \mathbb{C} . \tag{4.19}$$

Proof. This is an obvious adaptation of [26], proposition 1.4 to the case of Frobenius distributions. Notice that the signs agree with our choices of orientation. Indeed, we have:

$$\boldsymbol{\alpha} \wedge \mathbf{v} = \boldsymbol{\alpha} \wedge \boldsymbol{\omega}_1 \wedge \boldsymbol{\omega}_1 =_{\mathcal{U}} -(\iota_{\mathbf{n}} \mathbf{J}) \wedge \mathbf{J} \wedge \mathbf{J}|_{\mathcal{D}} = -\frac{1}{3} \iota_{\mathbf{n}} (\mathbf{J} \wedge \mathbf{J} \wedge \mathbf{J})|_{\mathcal{D}} =_{\mathcal{U}} -2\iota_{\mathbf{n}} \hat{\nu}_{\perp} = 2\nu_{\perp}.$$

4.3 Recovering the SU(2) structure on the generic locus of M

Reference [3] constructs an SU(3) structure on the rank six Frobenius distribution which is obtained by restricting $\hat{\mathcal{D}}$ to the open subset $\hat{\mathcal{U}} \subset \hat{M}$, a set which (by the results of section 3) contains the $\pi_1^{-1}(\mathcal{U})$ of the generic locus. This SU(3) structure is described in loc. cit through certain differential forms denoted there by:

$$K \in \Omega^2_{\hat{\mathcal{U}}}(\hat{\mathcal{D}})$$
 and $\varphi, \rho \in \Omega^3_{\hat{\mathcal{U}}}(\hat{\mathcal{D}})$.

As shown in appendix A, the canonically-normalized forms of that SU(3) structure are given by:

$$\hat{J} =_{\mathcal{U}} \frac{1}{\sqrt{1-\beta^2}} \left[K - \frac{1}{\beta^2} (\hat{V}_- \wedge \hat{V}_3) \right] \in \Omega^2_{\hat{\mathcal{U}}}(\hat{\mathcal{D}})$$

$$\hat{\Omega} = \hat{\varphi} + i\hat{\rho} \in \Omega^3_{\hat{\mathcal{D}}}(\hat{\mathcal{D}}) \otimes \mathbb{C} , \qquad (4.20)$$

where:

$$\hat{\varphi} \stackrel{\text{def.}}{=} \frac{1}{\sqrt{1-\hat{\alpha}}} \varphi = \frac{1}{\hat{\beta}\sqrt{2}} \varphi , \quad \hat{\rho} \stackrel{\text{def.}}{=} \frac{1}{\sqrt{1-\hat{\alpha}}} \sqrt{\frac{2}{1+\hat{\alpha}}} \rho = \frac{1}{\hat{\beta}\sqrt{2(1-\hat{\beta}^2)}} \rho . \tag{4.21}$$

Restricting everything to the subset $\mathcal{U} \equiv j(\mathcal{U}) \subset \hat{\mathcal{U}} \subset M$, we obtain an SU(3) structure on the restricted Frobenius distribution $\hat{\mathcal{D}}|_{\mathcal{U}}$, whose canonically-normalized forms are given by:

$$\mathbf{J} = \hat{J}|_{\mathcal{U}} , \quad \mathbf{\Omega} = \hat{\Omega}|_{\mathcal{U}} .$$

By definition, the 1-form $\theta_{\perp} \in \Omega^{1}(\mathcal{U})$ is the component of $\theta|_{\mathcal{U}}$ which is orthogonal to the subbundle $\langle \hat{V}_{+}|_{\mathcal{U}}, \hat{V}_{-}|_{\mathcal{U}}, \hat{V}_{3}|_{\mathcal{U}} \rangle$ of $T^{*}\hat{M}|_{\mathcal{U}}$ generated by the 1-forms $\hat{V}_{+}|_{\mathcal{U}}, \hat{V}_{-}|_{\mathcal{U}}$ and $\hat{V}_{3}|_{\mathcal{U}}$. Hence the 1-form \mathbf{n} (which is defined through (4.3)) is also orthogonal to this sub-bundle and thus $\iota_{\mathbf{n}}\hat{V}_{k} = 0$ for all k. On the other hand, we have $\mathcal{D}|_{\mathcal{U}} = \ker \theta \cap \hat{\mathcal{D}}|_{\mathcal{U}} = \ker \mathbf{n} \cap \hat{\mathcal{D}}|_{\mathcal{U}} \subset \ker \mathbf{n}$

and hence ω_k and α (which are longitudinal to the Frobenius distribution $\mathcal{D}|_{\mathcal{U}}$) are also orthogonal to \mathbf{n} . These observations show that we have the relations:

$$\iota_{\mathbf{n}}\hat{V}_k = \iota_{\mathbf{n}}\boldsymbol{\omega}_k = \iota_{\mathbf{n}}\boldsymbol{\alpha} = 0 , \quad \forall k = 1, 2, 3 .$$
 (4.22)

Using (4.22), relation (4.18) implies:

$$\alpha = -\iota_{\mathbf{n}} \mathbf{J} = -\iota_{\mathbf{n}} \hat{J}|_{\mathcal{U}}$$
.

Substituting the first relation of (4.20), this gives:

$$\alpha = -\frac{1}{\sqrt{1-\beta^2}} \iota_{\mathbf{n}} K|_{\mathcal{U}} . \tag{4.23}$$

Now (4.18) and (4.20) give:

$$\boldsymbol{\omega}_1 = \mathbf{J} + \mathbf{n} \wedge \boldsymbol{\alpha} = \frac{1}{\sqrt{1 - \beta^2}} \left[K - \mathbf{n} \wedge (\iota_{\mathbf{n}} K) - \frac{1}{\beta^2} \hat{V}_- \wedge \hat{V}_3 \right] |_{\mathcal{U}}. \tag{4.24}$$

Relation (4.19) expands as:

$$\mathbf{\Omega} = (\boldsymbol{\omega}_2 + \mathrm{i}\boldsymbol{\omega}_3) \wedge \boldsymbol{\alpha} + (\mathrm{i}\boldsymbol{\omega}_2 - \boldsymbol{\omega}_3) \wedge \mathbf{n} = (\boldsymbol{\omega}_2 \wedge \boldsymbol{\alpha} - \boldsymbol{\omega}_3 \wedge \mathbf{n}) + \mathrm{i}(\boldsymbol{\omega}_3 \wedge \boldsymbol{\alpha} + \boldsymbol{\omega}_2 \wedge \mathbf{n}) \ .$$

Comparing this with the second relation in (4.20) gives:

$$\hat{\varphi}|_{\mathcal{U}} \stackrel{\mathrm{def.}}{=} \varphi = \alpha \wedge \omega_2 - \mathbf{n} \wedge \omega_3 \;, \; \; \hat{\rho}|_{\mathcal{U}} \stackrel{\mathrm{def.}}{=} \rho = \alpha \wedge \omega_3 + \mathbf{n} \wedge \omega_2 \;.$$

Using (4.21) and (4.22), these equations imply:

$$\boldsymbol{\omega}_2 = \iota_{\mathbf{n}} \hat{\rho} |_{\mathcal{U}} = \frac{1}{\beta \sqrt{2(1-\beta^2)}} \iota_{\mathbf{n}} \rho |_{\mathcal{U}} , \quad \boldsymbol{\omega}_3 = -\iota_{\mathbf{n}} \hat{\varphi} |_{\mathcal{U}} = -\frac{1}{\beta \sqrt{2}} \iota_{\mathbf{n}} \varphi |_{\mathcal{U}} . \tag{4.25}$$

Relations (4.23), (4.24) and (4.25) express the defining forms of the SU(2) structure on the generic locus $\mathcal{U} \subset M$ in terms of the defining forms of the SU(3) structure which exists on the locus $\hat{\mathcal{U}} \subset \hat{M}$.

5 Conclusions and further directions

We analyzed the stabilizer stratifications of internal eight-manifolds M which can arise in $\mathcal{N}=2$ M-theory flux compactifications down to three dimensions using the formalism based on the auxiliary nine-manifold $\hat{M} \stackrel{\text{def.}}{=} M \times S^1$, which can be viewed as a trivial circle bundle over M with projection π_1 . We showed how the complicated stratified G-structure of M which was determined in [5] relates to the much simpler stratified G-structure of \hat{M} . The increased complexity of the former arises from the fact that the cosmooth generalized distribution $\hat{\mathcal{D}}$ whose rank determines the stabilizer stratification of \hat{M} may have pointwise transverse or non-transverse intersection with the π_1 -pull-back of the tangent bundle of M. We also gave an explicit construction of the defining forms of the SU(2) structure which exists on the generic locus $\mathcal{U} \subset M$ in terms of the defining forms of the SU(3) structure which exists on the locus $\hat{\mathcal{U}} \subset \hat{M}$.

An important aspect of our analysis is that the simplification obtained by uplifting to the nine-dimensional cylinder \hat{M} is only apparent. While the stabilizer stratification of \hat{M} is indeed simpler than that of M, a large part of the complexity of the stratified G-structure of M is 'hidden' in the character of the intersection of $\hat{\mathcal{D}}|_{M}$ and TM. Therefore, passing from M to \hat{M} does not simplify the problem in any fundamental way, but merely divides differently the complexity of the stabilizer stratification of M: part of that complexity is encoded by the simpler stabilizer stratification of \hat{M} while the remainder is captured by the character of the intersection $\hat{\mathcal{D}}|_{M} \cap TM$. In particular, the expectation that the analysis of stratified G-structures of flux compactifications simplifies upon passing to some uplifted description fails to materialize in our case. Part of the reason for this phenomenon is the high dimensionality (namely eight) of the internal space M and one may speculate that this relates to the problem of "dual gravitons" which is relevant for such backgrounds of M-theory.

One could also consider higher dimensional uplifts, for example to a ten-dimensional manifold of the form $\hat{M}' \stackrel{\text{def.}}{=} M \times \Sigma$, where Σ is a (compact) Riemann surface. Such higher uplifts may lead to even simpler stabilizer stratifications of \hat{M}' . However, the character of the intersection of j(M) with this stratification would be more complex, since the number of essentially distinct cases grows with the dimension of the uplift. Hence uplifting to higher dimensions simplifies one aspect of the problem (namely, the stabilizer stratification of the uplift) while complicating the other (namely, the analysis of the intersection of j(M) with the uplift stratification). Since one is ultimately interested in describing the stabilizer stratification of M rather than that of the auxiliary space \hat{M}' , it is unclear that there is much gain in such repackaging of the complexity. In our opinion, the best approach is that of [5], which gives a direct and complete solution using the tools of stratification theory and semi-algebraic geometry, without introducing any auxiliary space constructions.

It is natural to wonder what insight could be gained by replacing the cylinder \hat{M} with a topologically non-trivial S^1 -bundle over M. Since the character of the intersection $\hat{\mathcal{D}}|_M \cap TM$ is determined pointwise, it is clear that modifying the global topology of \hat{M} will affect the topology of its stratification, without changing the stratified G-structure of M (which is the physically relevant object), hence without leading to any true simplification of the problem. In general, questions regarding the precise relation between the topology of possible uplifts and the topology of the relevant stratifications require detailed analysis which falls outside the scope of the present work.

A related problem is whether (as suggested by the results of [31, 32]) one can find a compact manifold \hat{M}' (of dimension higher than nine) which fibers over M, such that the stratified G-structure of M uplifts to a globally-defined reduction of structure group of \hat{M}' . In full generality, the answer to this question is non-obvious, since the topology of such \hat{M}' would have to depend rather non-trivially on the topology of the stratified G-structure of M. Another interesting question is to find a physics interpretation of the interaction between uplifts, stratified G-structures and intersection theory which appears to govern many of the phenomena uncovered in this paper and in the closely related work of [31, 32]. This requires further conceptual development on which we hope to report in future work.

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A Canonically-normalized forms of the SU(3) structure on \hat{M}

Reference [3] constructs a two-form $J \in \Omega^2_{\hat{\mathcal{U}}}(\hat{\mathcal{D}})$ given by equation (2.29) of loc. cit. When translated into our notations, that equation amounts to:

$$J =_{\hat{\mathcal{U}}} K - \frac{2}{1 - \hat{\alpha}} \hat{V}_{-} \wedge \hat{V}_{3} = K - \frac{1}{\hat{\beta}^{2}} \hat{V}_{-} \wedge \hat{V}_{3} , \qquad (A.1)$$

where (as in [3]):

$$K \stackrel{\text{def.}}{=} \frac{1}{2} \hat{\mathscr{B}}(\hat{\xi}_1, \hat{\gamma}_{m_1 m_2} \hat{\xi}_2) \hat{e}^{m_1} \wedge \hat{e}^{m_2} \in \Omega^2(\hat{M})$$
.

To arrive at (A.1), we used relation (2.26) and the fact that $\hat{V}_{\pm}^{\text{here}} = \frac{1}{2}V_{\pm}^{\text{there}}$. By the construction given in [3] (see the derivation of eq. (2.29) of loc. cit. and the discussion preceding it), the 2-form J coincides with the orthogonal projection of K onto $\Omega^2(\hat{\mathcal{D}}) \subset \Omega^2(\hat{M})$. We thus have $\iota_{\hat{V}_k}J = 0$ for all k = 1, 2, 3 and hence J is a two-form defined on \hat{M} which is longitudinal to the distribution $\hat{\mathcal{D}}$. Define $I \in \Gamma(\hat{\mathcal{U}}, \operatorname{End}(T\hat{M}))$ through:

$$J(X,Y) \stackrel{\text{def.}}{=} \hat{g}(X,IY) , \quad \forall X,Y \in \Gamma(\hat{\mathcal{U}},T\hat{M}) .$$
 (A.2)

In a local frame \hat{e}_m of \hat{M} defined over an open subset $U \subset \hat{M}$, we have $I\hat{e}_n = I_n^{\ p}\hat{e}_p$ and $J(\hat{e}_m, \hat{e}_n) = J_{mn} = -J_{nm}$, hence (A.2) becomes:

$$J_{mn} = -J_{nm} =_U I_n^{\ p} \hat{g}_{pm} \ , \label{eq:Jmn}$$

where $\hat{g}_{mp} = \hat{g}_{pm} = \hat{g}(\hat{e}_m, \hat{e}_p)$. Thus $I_m{}^n = -J_{mp}\hat{g}^{pn} = -J_m{}^n$ and $I^2(\hat{e}_m) = I_m{}^n I(\hat{e}_n) = I_m{}^n I_n{}^p \hat{e}_p = J_{mn}J^{np}\hat{e}_p$. Hence equation (2.36) of [3] implies:

$$I^{2}|_{\hat{\mathcal{D}}} =_{\hat{\mathcal{U}}} -\frac{1+\hat{\alpha}}{2} \mathrm{id}_{\hat{\mathcal{D}}} . \tag{A.3}$$

Therefore, the quantity:

$$\hat{I} \stackrel{\text{def.}}{=} \sqrt{\frac{2}{1+\hat{\alpha}}} I = \frac{1}{\sqrt{1-\hat{\beta}^2}} I \in \Gamma(\hat{\mathcal{U}}, T\hat{M})$$
(A.4)

satisfies $\hat{I}^2|_{\hat{\mathcal{D}}} =_{\hat{\mathcal{U}}} -\mathrm{id}_{\hat{\mathcal{D}}}$ and hence it gives an almost complex structure on the rank six Frobenius distribution which is obtained by restricting $\hat{\mathcal{D}}$ to $\hat{\mathcal{U}}$. The two-form associated to this almost complex structure is given by:

$$\hat{J} = \sqrt{\frac{2}{1+\hat{\alpha}}}J = \frac{1}{\sqrt{1-\hat{\beta}^2}}J = \frac{1}{\sqrt{1-\hat{\beta}^2}}\left[K - \frac{1}{\hat{\beta}^2}\hat{V}_- \wedge \hat{V}_3\right] \in \Omega^2_{\hat{\mathcal{U}}}(\hat{\mathcal{D}})$$
(A.5)

and satisfies the analogue of the normalization condition (4.14) (on $\hat{\mathcal{U}}$) by virtue of equation⁴ (2.40) of [3]. Loc. cit. also constructs two real 3-forms φ and ρ on $\hat{\mathcal{U}}$ which are orthogonal to \hat{V}_+, \hat{V}_- and \hat{V}_3 on $\hat{\mathcal{U}}$ and hence belong to the space $\Omega^3_{\hat{\mathcal{U}}}(\hat{\mathcal{D}})$ (see page 10 of [3]). These forms satisfy relation (2.39) of [3], which in our notations reads:

$$\varphi \wedge \rho =_{\hat{\mathcal{U}}} 4 \hat{*} (\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}) = 4(1 - \hat{\alpha}) \sqrt{\frac{1 + \hat{\alpha}}{2}} \hat{\nu}_{\perp} , \qquad (A.6)$$

where we used (2.23) and the fact that $\hat{V}_{\pm}^{\text{here}} = \frac{1}{2}V_{\pm}^{\text{there}}$. Defining:

$$\hat{\varphi} \stackrel{\text{def.}}{=} \frac{1}{\sqrt{1-\hat{\alpha}}} \varphi = \frac{1}{\hat{\beta}\sqrt{2}} \varphi$$

$$\hat{\rho} \stackrel{\text{def.}}{=} \frac{1}{\sqrt{1-\hat{\alpha}}} \sqrt{\frac{2}{1+\hat{\alpha}}} \rho = \frac{1}{\hat{\beta}\sqrt{2(1-\hat{\beta}^2)}} \rho , \qquad (A.7)$$

relation (A.6) reduces to the analogue of (4.17), which holds on $\hat{\mathcal{U}}$. Loc. cit. also defines a complex-valued 3-form $\Omega \in \Omega^3_{\hat{\mathcal{U}}}(\hat{\mathcal{D}}) \otimes \mathbb{C}$ through [3], eq. (2.41), which reads:

$$\Omega \stackrel{\text{def.}}{=} \varphi + i \sqrt{\frac{2}{1 + \hat{\alpha}}} \rho$$
.

Defining:

$$\hat{\Omega} \stackrel{\text{def.}}{=} \frac{1}{\sqrt{1-\hat{\alpha}}} \Omega = \frac{1}{\hat{\beta}\sqrt{2}} \Omega = \hat{\varphi} + i\hat{\rho} , \qquad (A.8)$$

relation (2.42) of [3] becomes the condition that $\hat{\Omega}$ is \hat{I} -pseudoholomorphic:

$$\hat{I}_{(1)}\hat{\Omega} = -\mathrm{i}~\hat{\Omega}~~\mathrm{(i.e.}~\hat{I}_{(1)}\hat{\varphi} = \hat{\rho})~,$$

where $\hat{I}_{(1)}$ denotes the action of \hat{I} on the first "slot" of $\hat{\Omega}$. On the other hand, the analogue of relation (4.17) shows that $\hat{\Omega}$ satisfies the analogue of (4.15) on $\hat{\mathcal{U}}$. Combining everything, we conclude that \hat{J} and $\hat{\Omega}$ are the canonically-normalized forms of the SU(3) structure which was constructed in [3] on the rank six Frobenius distribution obtained by restricting $\hat{\mathcal{D}}$ to the locus $\hat{\mathcal{U}} \subset \hat{M}$.

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⁴Notice that there is a typo in [3], eq. (2.40), in that the right hand side of that equation should equal $\frac{3(1+\alpha)}{4(1-\alpha)}*(V_{+} \wedge V_{-} \wedge V_{3})$ (in the notations of loc. cit.). With this correction, that equation is equivalent in our notations with $J \wedge J \wedge J = \frac{3(1+\alpha)}{(1-\hat{\alpha})}*(\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3})$, where we used the fact that $\hat{V}_{\pm}^{\text{here}} = \frac{1}{2}V_{\pm}^{\text{there}}$. Relation (2.23) implies $*(\hat{V}_{+} \wedge \hat{V}_{-} \wedge \hat{V}_{3}) = (1-\hat{\alpha})\sqrt{\frac{1+\hat{\alpha}}{2}}\hat{\nu}_{\perp}$ and hence $J \wedge J \wedge J = 6\left(\frac{1+\hat{\alpha}}{2}\right)^{3/2}\hat{\nu}_{\perp}$ i.e. $\hat{J} \wedge \hat{J} \wedge \hat{J} = 6\hat{\nu}_{\perp}$. Here * denotes the Hodge operator of (\hat{M}, \hat{g}) .

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