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	TECHNICAL MEMORANDUM
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	EXPERIMENTAL AND CALCULATED RESULTS OF A FLUTTER
	INVESTIGATION OF SOME VERY LOW ASPECT-RATIO
	FLAT-PLATE SURFACES AT MACH NUMBERS
- * ¥	FROM 0.62 TO 3.00
i vi	By Perry W. Hanson and Gilbert M. Levey
	Langley Research Center Langley Field, Va.
	Declassified February 6, 1962
×	NATIONAL AERONAUTICS AND SPACE ADMINISTRATION
	WASHINGTON August 1959
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NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

TECHNICAL MEMORANDUM X-53

EXPERIMENTAL AND CALCULATED RESULTS OF A FLUTTER

INVESTIGATION OF SOME VERY LOW ASPECT-RATIO

FLAT-PLATE SURFACES AT MACH NUMBERS

FROM 0.62 TO 3.00

By Perry W. Hanson and Gilbert M. Levey

SUMMARY

Some very low aspect-ratio flat-plate surfaces of aluminum alloy were tested for flutter at Mach numbers from 0.62 to 3.00. Two types of plan forms, a delta and a delta with one-third span cut off, are used in this investigation. Three different panel aspect ratios, 0.728, 0.536, and 0.353, were tested for each type of plan form. Each model had a 12-inch root chord and was cantilevered from the tunnel wall.

Generally, the clipped-tip-delta plan forms were more susceptible to flutter throughout the Mach number range investigated. The lower aspect-ratio models fluttered at a higher value of the stiffnessaltitude parameter than the higher aspect-ratio models for a given type of plan form and a given Mach number.

Modal-type calculations were made for some supersonic cases by using first-order piston-theory aerodynamic forces. Generally, the theoretical flutter boundaries agreed with the experimental boundaries within 20 percent. The theory was unconservative for the delta plan forms and conservative for the clipped-tip-delta plan forms.

INTRODUCTION

The use of very low aspect-ratio surfaces is becoming increasingly prevalent in the design of missile and rocket fins, supersonic aircraft, and hypersonic gliders. Although some work has been done in this area of interest (see, for example, refs. 1 to 3), data available for the flutter characteristics of these types of surfaces at both subsonic and supersonic speeds are meager. It is evident that there is a need for more information of this kind, both to provide trend data for design criteria and to provide a basis for comparison of theory and experiment. Therefore, a systematic investigation was made of the flutter characteristics of some configurations that might be considered representative of those found on these new vehicles.

Some flat-plate semispan models of two different types of plan forms, each with three different panel aspect ratios were tested at Mach numbers from 0.62 to 3.00. The experimental results were compared with theoretical calculations in the supersonic regime with the use of the method of reference 4 based on the "piston theory" of reference 5. Mode shapes of the models used in the computations were determined by the method of reference 6.

SYMBOLS

А	panel aspect ratio (Semispan ² /Panel area)
a	velocity of sound, ft/sec
Ъ	semichord at 3/4 semispan, in.
$\frac{\omega\omega d}{a}\sqrt{\mu}$	stiffness-altitude parameter
с	local chord, in.
ff	flutter frequency, cps
fn	natural frequency of nth mode $(n = 1, 2, 3, and 4)$, cps
2	length of semispan of model, measured normal to stream direction, in.
М	Mach number
q	dynamic pressure, lb/sq ft
t	thickness, in.
W	total weight of surface, lb

x	chordwise station, measured parallel to root chord from leading edge, in.
У	spanwise station, measured perpendicular to root chord from the root
δ	leading- and trailing-edge bevel, measured perpendicular to edges, in.
μ	mass density parameter
ρ	air density, slugs/cu ft
ω α	wing torsional circular frequency, radians/sec
Subscripts	:

- ex experimental.
- th theoretical

MODEL DESCRIPTION

The six model configurations used in the investigation are shown in figure 1. They consisted of two types of plan forms: delta and delta with the outer one-third span cut off. The three delta plan forms were 70° , 75° , and 80° deltas with corresponding panel aspect ratios of 0.728, 0.536, and 0.353 for 12-inch root chords. The three clippedtip-delta plan forms also had 12-inch root chords, and the dimensions of these plan forms were chosen to give the same aspect ratios as the delta plan forms.

All the models were made from 2024-T3 aluminum-alloy sheets with the thicknesses and leading- and trailing-edge bevels as indicated in figure 1. The models were mounted in the wind-tunnel side wall and clamped between two 1/2-inch-thick steel plates over the entire root chord. These plates were made to hold the models 1/2 inch out from the wind-tunnel wall in a triangular shaped body. The method of mounting is illustrated in figure 2.

TEST PROCEDURE

The tests were conducted in the Langley 9- by 18-inch supersonic aeroelasticity tunnel. This tunnel is of the intermittent blowdown

type with fixed nozzle blocks and operates from a high-pressure source to a vacuum. The transonic tests of the delta plan forms were made with the use of a slotted-test-section nozzle with a choking device employed in the diffuser to obtain the desired Mach number in the test section.

The tests were made at constant Mach number with the dynamic pressure being increased until flutter was encountered or until the tunnel limits were reached. During each test, continuous records of wind-tunnel conditions and model behavior were recorded on an oscillograph.

Generally, the models were not damaged during flutter tests and could be used for succeeding tests. When models were damaged and new ones were made, it was found that the models could be duplicated very easily and that the natural frequencies and node lines of the new models were virtually the same as those of the previous models. The variations in natural frequencies listed in table I were probably the result of small differences in tightness of the root mount. Resistance wire straingage bridges mounted at the root of the model at about 70 percent of the chord were used to record natural frequencies listed in table I. Mode shapes of the models were obtained by the method of reference 6 for use in the piston-theory analysis and are presented in table II along with typical natural vibration node lines of the first four modes.

RESULTS AND DISCUSSION

The experimental and theoretical results are listed in table I and are shown in figure 3 in which both an experimental and a theoretical stiffness-altitude parameter $\frac{b\omega_{tr}}{a}\sqrt{\mu}$ required for flutter are plotted as a function of Mach number. The ω_{ta} is the second natural frequency f₂ which is predominantly torsional for all models. The mass-density parameter μ is the ratio of the mass of the wing to the mass of a volume of air enclosing the wing. For the delta plan forms, the volume is that of a cone with the base diameter parallel to the airstream and equal to the root chord. For the clipped-tip-delta plan forms, the volume is that of a truncated cone with the two ends parallel to the airstream with diameters equal to the root and tip chords. The air density ρ , which is used in the computation of μ , is the test-section density at flutter. In figure 3 constant-density (altitude) lines are horizontal and density decreases as $\frac{b\omega_{\alpha}}{a}\sqrt{\mu}$ increases. Constant dynamic pressure lines are radial from the origin and increase clockwise. The flutter region is below the curves and the no-flutter region is above the curves.

When figures 3(a), 3(b), and 3(c) are compared, several general observations can be made. The flutter boundaries for the delta-planform models showed little change with aspect ratio except for the lowest aspect-ratio model at the higher Mach numbers. The clipped-tip-deltaplan-form models, however, exhibited a considerable change in the flutter boundaries with aspect ratio. (See figs. 3(d), 3(e), and 3(f).) As the aspect ratio decreased, the flutter boundary was raised. For a given aspect ratio, the clipped-tip-delta plan forms fluttered at a higher value of the stiffness-altitude parameter than the deltas at all Mach numbers.

The theoretical flutter boundaries shown in figure 3 were calculated with the use of aerodynamic forces obtained from first-order piston theory and using the first three (experimentally determined) naturalvibration modes. When the theoretical and experimental flutter boundaries are compared, it is seen that the shape of the boundaries agrees very well for all the cases considered except for the lowest aspectratio delta (fig. 3(c)). The agreement between the experimental and theoretical flutter boundaries is poor at all Mach numbers for the lowest aspect-ratio model of the clipped-tip-delta models. Generally, the theoretical flutter boundaries were conservative with respect to the experimental boundaries for the clipped-tip-delta plan forms; that is, a greater density was required to flutter the models than was predicted by theory. For the delta plan forms, however, the theory was unconservative.

Figure 4 shows the variation of the ratio of theoretical flutter frequency to experimental flutter frequency with Mach number. In all cases, the theoretical flutter frequency was greater than the experimental flutter frequency. For the delta-plan-form models, the agreement between the theoretical and experimental flutter frequencies was best for the largest aspect-ratio model and became worse as the aspect ratio decreased, whereas the opposite was true for the clipped-tipdelta-plan-form models.

CONCLUDING REMARKS

An investigation conducted in the Langley 9- by 18-inch supersonic aeroelasticity tunnel of very low aspect-ratio flat-plate models with two types of plan forms and three aspect ratios for each type of plan form indicate that the clipped-tip-delta plan forms were more susceptible to flutter than the delta plan forms throughout the Mach number range investigated. For a given Mach number and a given type of plan form, the lower aspect-ratio models fluttered at a higher value of the stiffness-altitude parameter than the higher aspect-ratio models. The agreement between the experimental flutter boundaries and the theoretical flutter boundaries (as computed from first-order piston theory) was generally good. The theory was conservative for the clipped-tip deltas and unconservative for the deltas. The agreement was poorest for the lowest aspect-ratio models of both types of plan forms.

Langley Research Center, National Aeronautics and Space Administration, Langley Field, Va., May 12, 1959.

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- 6. Hanson, Perry W., and Tuovila, W. J.: Experimentally Determined Natural Vibration Modes of Some Cantilever-Wing Flutter Models by Using an Acceleration Method. NACA TN 4010, 1957.

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	Frequ	uencie	s, cps			Flu	tter cond	litions		<u>bવ્ય</u> ્સ્ a	^μ √μ	ff,th
f ₁	f2	f3	fų	f _{f,ex}	м	ρ, slug/cu ft	a, fps	q, lb/sq ft	μ	Ежр.	Theory	f _{f,ex}
			, <u> </u>			Model	1A			• ···		r —
78 72 78 79 78 79 78 79 78 79 78 75 76 75 76	183 171 186 193 186 186 192 178 181 170 173 173 173 174	325 320 350 352 331 350 342 320 305 318 320 320 325	395 367 398 396 398 402 388 367 367 372 379 375 383	166 150 157 150 140 142 148 133 150 160 153 160 161	0.63 .64 .75 .79 .88 .96 .96 1.01 1.19 1.30 1.64 2.55 3.00	0.001505 .001442 .001307 .001346 .001346 .001381 .001339 .001006 .000760 .000766 .000786 .000592 .000592 .000551 .000736	1,102 1,093 1,089 1,077 1,070 1,051 1,053 1,013 980 915 850 770 721	363 354 436 532 538 652 655 553 643 829 846 1,264 1,723	$17.17 \\ 17.93 \\ 19.80 \\ 17.58 \\ 19.20 \\ 20.18 \\ 19.30 \\ 25.67 \\ 34.00 \\ 32.98 \\ 35.12 \\ 43.67 \\ 39.70 \\ 35.10 \\ \end{array}$	0.54 .52 .60 .59 .63 .63 .63 .63 .63 .82 .78 .88 1.06 1.11 1.12	0.62 .72 .79 .90 .98	 1.15 1.07 1.07 1.08 1.06
			. <u> </u>			Model	1B		7	1		
127 128 129 128 126 127 130 123 127 125	277 275 277 275 273 273 271 275 283 267 269 273	457 457 460 467 460 458 457 462 454 450	640 627 642 646 644 635 640 650 600 600 625	222 225 214 210 264 245 250 300 238 250 (a)	0.62 .75 .86 1.14 1.25 1.26 1.30 1.64 2.00 2.55 3.00	0.003993 .003213 .002666 .002404 .002570 .002364 .002360 .002453 .001510 .001210 B.001017	1,107 1,086 1,071 1,024 1,012 1,007 988 949 870 796 &731	943 1,065 1,130 1,641 2,058 1,906 1,906 2,915 2,278 2,490 B 2,448	6.34 7.88 9.50 10.54 9.86 10.71 10.64 10.32 16.36 13.96 24.90	0.50 .56 .63 .69 .67 .69 .71 .76 .99 .99 1.47	 0.53 .57 .57 .60 .70 .84 .78 .85	 1.79 1.39 1.50 1.49 1.26 1.18 1.09
		-				Model	10				r	,
213 217 215 212 213 217 216 210 213	386 383 389 387 375 388 400 467 400	580 575 580 580 567 554 585 560 600	738 750 744 738 720 725 775 786 833	314 316 300 306 300 350 350 360 313 300	0.63 .75 .90 1.16 1.24 1.30 1.64 2.00 3.00	0.004195 .003132 .002911 .002401 .002488 .002104 .001468 .000948	1,109 1,086 1,066 1,020 997 990 928 859 748	1,025 1,038 1,340 1,681 1,675 2,058 2,435 2,092 2,392	5.16 6.91 7.43 9.01 9.89 8.70 10.27 15.25 22.82	0.62 .73 .78 .90 .93 .91 1.09 1.31 2.00	0.85 .89 .99 1.08 1.11 1.42	1.72 1.74 1.45 1.48 1.61 1.81
						Model	2A		-			
35 35 36 35 34	95 100 105 110 109	183 188 197 196 193	209 208 233 232 232 233	93 102 94 100 105	1.30 1.64 2.00 2.55 3.00	0.000628 .000581 .000724 .000799 .000655	979 918 847 777 720	509 660 1,039 1,580 1,533	38.67 41.79 33.55 30.40 37.08	0.95 1.11 1.13 1.23 1.45	0.97 1.18 1.20 1.43 1.57	1.75 1.64 1.88 1.76 1.86
						Model	2B					
60 59 60 59	122 114 125 117	225 213 229 207	325 331 332 318	115 108 117 109	1.30 1.64 2.00 3.00	0.000618 .000397 .000495 .000363	977 916 847 693	498 449 710 784	39.32 61.18 49.11 66.97	1.24 1.53 1.63 2.18	1.36 1.50 1.71 2.21	1.70 1.71 1.70 1.66
			·			Model	20	r		[
126 125 122 130 118	216 213 204 218 197	350 358 342 368 323	507 500 487 540 485	175 183 165 183 170	1.30 1.64 2.00 2.55 3.00	0.001305 .001120 .000754 .000829 .000642	982 924 858 790 714	1,062 1,286 1,110 1,677 1,472	18.61 21.69 32.18 29.30 37.81	1.49 1.69 2.12 2.34 2.67	2.24 2.55 2.87 3.18 3.51	1.21 1.13 1.20 1.14 1.12

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TABLE I.- EXPERIMENTAL AND THEORETICAL RESULTS

^aNo flutter - maximum tunnel conditions.

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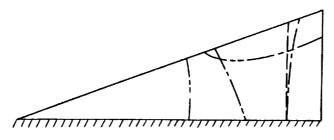
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TABLE II.- REPRESENTATIVE MODE SHAPES AND NODE LINES OF MODELS

[Deflections normalized on maximum deflection, considered positive when deflected wing is above static position]

			_	Normaliz	ed defle	ction at	y/l =					
x/c	0.10	0.20	0.30	0.40	0.50	0.60	0.70	0.80	0.90	1.00		
$f_1 = 76 \text{ cps}$												
0 .25 .50 .75 1.00	0.004 .009 .014 .023 .058	0.012 .018 .034 .082 .131	0.019 .033 .061 .152 .216	0.033 .062 .120 .235 .306	0.060 .124 .233 .353 .418	0.130 .275 .363 .465 .525	0.331 .443 .514 .587 .639	0.550 .625 .670 .715 .750	0.775 .810 .830 .850 .875	1.000 1.000 1.000 1.000 1.000		
	$f_2 = 165 \text{ cps}$											
0 .25 .50 .75 1.00	-0.019 042 100 023 .096	-0.045 135 225 060 .310	-0.116 348 443 124 .487	-0.345 600 560 160 .590	-0.719 741 555 084 .683	-0.900 800 600 .115 .745	-0.836 676 353 .321 .815	-0.415 255 .100 .550 .875	0.190 .330 .550 .770 .935	1.000 1.000 1.000 1.000 1.000		
				fz	= 291 c	ps						
0 .25 .50 .75 1.00	-0.024 155 209 .105 256	-0.170 400 230 .190 600	-0.533 729 108 .280 844	-0.780 745 .150 .360 930	-0.783 352 .486 .416 950	-0.592 .553 .587 .256 938	1.000 1.000 .525 228 850	1.000 .990 .380 500 710	0.294 .095 466 722 729	-0.864 864 864 864 864		
				\mathbf{f}_{l_4}	= 383 c	ps						
0 .25 .50 .75 1.00	0.007 .032 007 034 052	0.030 .060 020 075 315	0.062 .071 037 111 860	0.130 .035 040 150 930	0.117 038 044 161 909	-0.050 025 045 150 800	0.060 .109 .111 .060 - .538	0.360 .380 .380 .340 .250	0.940 .771 .677 .618 .600	1.000 1.000 1.000 1.000 1.000		

(a) Model 1A



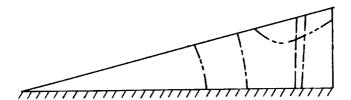
Mode	Node line
1	At root
2	
3	
4	

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TABLE II.- REPRESENTATIVE MODE SHAPES AND NODE LINES OF MODELS - Continued

,		Normalized deflection at $y/l =$												
x/c	0.10	0.20	0.30	0.40	0.50	0.60	0.70	0.80	0.90	1.00				
	$f_1 = 124 \text{ cps}$													
0 .25 .50 .75 1.00	0.001 .001 .004 .013 .030	0.002 .004 .016 .045 .085	0.007 .013 .041 .103 .152	0.015 .028 .089 .171 .223	0.034 .078 .162 .250 .305	0.095 .159 .244 .343 .401	0.200 .267 .348 .456 .512	0.327 .389 .481 .582 .624	0.561 .615 .684 .743 .757	1.000 1.000 1.000 1.000 1.000				
$f_2 = 278 \text{ cps}$														
0 .25 .50 .75 1.00	0.002 .011 .044 .046 - .072	0.012 .045 .135 .099 153	0.043 .139 .280 .118 239	0.132 .274 .382 .104 331	0.330 .553 .404 .060 432	0.754 .877 .352 037 533	1.000 .598 .193 181 643	0.633 .231 058 378 747	-0.022 242 417 630 857	-0.968 968 968 968 968				
		-		f	3 = 457	cps								
0 .25 .50 .75 1.00	0.014 .058 .141 031 .166	0.068 .254 .214 - .183 .304	0.291 .612 .211 250 .387	0.709 .813 .128 270 .454	1.000 .512 270 237 .515	0.926 .038 515 119 .572	-0.058 532 536 .066 .572	-0.560 544 262 .271 .658	-0.311 .053 .302 .500 .692	0.719 .719 .719 .719 .719 .719				
				f	4 = 630	cps								
0 .25 .50 .75 1.00	-0.007 180 005 .029 .288	-0.052 340 .036 .088 .791	-0.562 319 .164 .123 .974	-0.708 140 .166 .133 1.000	-0.458 .320 .131 .130 .954	0.225 .412 044 .100 .791	0.472 108 342 064 .495	-0.406 680 539 195 .171	-0.815 729 585 385 216	-0.524 524 524 524 524 524				

(b) Model 1B



Mode	Node line
I	At root
2	
3	
4	

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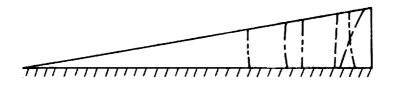
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	Normalized deflection at $y/l =$													
x/c	0.10	0.20	0.30	0.40	0.50	0.60	0.70	0.80	0.90	1.00				
	f ₁ = 242 cps													
0 .25 .50 .75 1.00	0.003 .004 .006 .010 .034	0.006 .010 .017 .050 .084	0.012 .017 .032 .117 .167	0.019 .029 .065 .220 .286	0.029 .047 .135 .320 .400	0.047 .117 .282 .435 .524	0.135 .295 .425 .545 .636	0.365 .505 .585 .675 .757	0.635 .700 .760 .820 .873	1.000 1.000 1.000 1.000 1.000				
					$f_2 = 44$	О срв								
0 .25 .50 .75 1.00	0.002 .005 .017 .050 082	0.009 .018 .077 .112 236	0.013 .048 .212 .133 370	0.036 .169 .379 .130 479	0.142 .412 .474 .080 - .605	0.463 .753 .505 021 699	0.894 .756 .323 198 791	0.768 .458 045 507 871	-0.005 320 548 759 932	-1.000 -1.000 -1.000 -1.000 -1.000				
					f ₃ = 65	О срв								
0 .25 .50 .75 1.00	0.009 .015 .078 027 .055	0.018 .047 .242 077 .154	0.039 .125 .255 178 .265	0.079 .465 .169 269 .378	0.373 .499 041 373 .499	0.608 .265 370 293 .612	0.374 257 618 066 .727	-0.610 727 434 .214 .835	-0.472 109 .183 .512 .906	1.000 1.000 1.000 1.000 1.000				

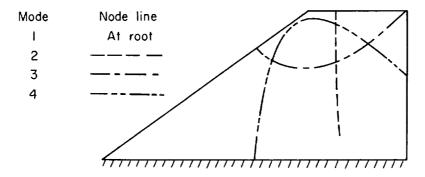
(c) Model 1C



Mode	Node line
I	At root
2	
3	
4	

x/c		Normalized deflection at $y/l =$												
x /c	0.10	0.20	0.30	0.40	0.50	0.60	0.70	0.80	0.90	1.00				
f ₁ = 36 cps														
0 .25 .50 .75 1.00	0.013 .018 .027 .039 .046	0.032 .050 .068 .095 .123	0.064 .097 .130 .171 .217	0.125 .162 .200 .256 .315	0.215 .261 .301 .358 .428	0.310 .350 .392 .462 .520	0.404 .457 .508 .569 .611	0.515 .575 .630 .680 .720	0.657 .741 .790 .814 .837	0.904 .955 .973 .994 1.000				
f ₂ = 96 cps														
0 .25 .50 .75 1.00	-0.031 073 062 006 .080	-0.115 250 180 010 .200	-0.226 495 331 .017 .380	-0.550 620 380 .060 .580	-0.785 664 367 .135 .772	-0.800 660 300 .400 .915	-0.757 636 191 .386 .916	-0.700 550 .040 .565 .950	-0.636 432 .274 .710 .982	-0.556 138 .547 .790 1.000				
				f3	= 188 c	ps								
0 .25 .50 .75 1.00	-0.042 114 073 085 169	-0.135 210 170 200 400	-0.266 301 251 314 641	-0.410 330 280 410 710	-0.491 291 223 458 709	-0.430 130 060 440 690	-0.222 .127 .161 337 642	0.300 .370 .410 0 530	0.715 .635 .620 .330 218	1.000 .900 .830 .670 .450				
				f	= 204 c	ps								
0 .25 .50 .75 1.00	0.055 .087 049 079 120	0.220 .250 100 200 200	0.424 .320 161 342 271	0.530 .290 270 410 270	0.557 .151 388 410 199	0.520 040 410 350 0	0.268 131 371 235 .327	0.100 150 190 0 .570	0.069 125 .043 .284 .789	0.118 .158 .279 .442 1.000				

(d) Model 2A



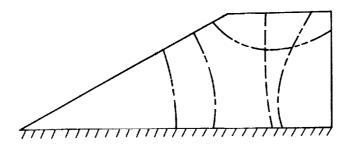
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/				Normaliz	ed defle	ction at	y/l =					
x/c	0.10	0.20	0.30	0.40	0.50	0.60	0.70	0.80	0.90	1.00		
	f ₁ = 60 cps											
0 .25 .50 .75 1.00	0.005 .009 .014 .028 .037	0.018 .032 .048 .058 .097	0.039 .068 .094 .144 .169	0.069 .116 .156 .223 .266	0.114 .185 .236 .317 .368	0.177 .270 .347 .424 .479	0.277 .384 .474 .553 .608	0.407 .510 .602 .680 .729	0.572 .678 .750 .823 .867	0.730 .833 .904 .960 1.000		
				f2	= 123 c	рв		•				
0 .25 .50 .75 1.00	-0.010 024 016 007 .049	-0.034 079 060 009 .149	-0.074 161 122 .004 .250	-0.164 290 192 .043 .348	-0.320 385 223 .095 .458	-0.473 420 208 .168 .565	-0.506 417 158 .253 .674	-0.513 387 067 .351 .784	-0.491 318 .067 .461 .897	-0.432 156 .223 .586 1.000		
				f3	= 222 c	ps						
0 .25 .50 .75 1.00	0.077 .397 .029 157 .365	0.261 .752 .058 213 .187	0.756 .812 .052 236 .831	0.935 .827 167 244 .908	0.990 .808 449 244 .948	1.000 .727 685 244 .969	0.973 349 804 244 .973	0.854 814 858 244 .960	-0.735 950 885 244 .939	-0.919 981 881 244 .904		

(e) Model 2B



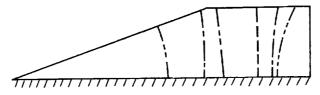
Mode	Node line
I	At root
2	
3	
4	

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,	Normalized deflection at $y/l =$									
x/c	0.10	0.20	0.30	0.40	0.50	0.60	0.70	0.80	0.90	1.00
	4			fl	= 122 cj	рБ				
0 .25 .50 .75 1.00	0.003 .006 .010 .029 .035	0.010 .016 .032 .067 .093	0.019 .029 .061 .115 .163	0.032 .054 .099 .179 .247	0.048 .093 .157 .253 .337	0.080 .144 .234 .356 .439	0.122 .215 .330 .462 .551	0.199 .324 .449 .587 .696	0.324 .455 .593 .728 .849	0.487 .599 .737 .875 1.000
$f_2 = 214$ cps										
0 .25 .50 .75 1.00	0.006 .032 .053 .003 049	0.020 .092 .056 .008 132	0.060 .167 .243 .005 222	0.123 .268 .324 022 332	0.210 .403 .404 070 487	0.375 .705 .450 140 653	0.702 .787 .432 233 760	0.875 .792 .307 375 850	0.954 .772 .115 565 929	1.000 .716 182 770 -1.000
$f_3 = 343 \text{ cps}$										
0 .25 .50 .75 1.00	0.006 .158 .030 061 .098	0.039 .380 .108 141 .250	0.130 .531 .115 224 .429	0.461 .634 .056 261 .592	0.729 .702 163 252 .714	0.850 .708 410 199 .807	0.851 .475 567 129 .872	0.808 278 647 020 .926	0.385 617 669 .168 .966	-0.515 818 568 .416 1.000
$f_{l_{\rm L}} = 518 {\rm ~cps}$										
0 .25 .50 .75 1.00	-0.017 165 .009 024 .099	-0.054 274 .081 071 .303	-0.153 300 .136 130 .453	-0.453 246 .149 191 .586	-0.629 067 .137 252 .693	-0.695 300 .084 306 .785	-0.330 .478 217 319 .856	0.429 .472 398 290 .915	0.650 049 562 219 .967	0.601 455 707 118 1.000

(f) Model 2C

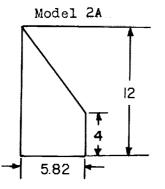


Mode	Node line
I	At root
2	
3	
4	

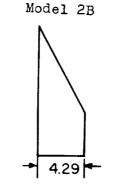
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Model 1A Model 1B Model 10 **80°** 75° 70° δ 12 Section A-A 4.37 + 3.22 + 2.12 A = 0.728A = 0.536W = 0.0794 lb W = 0.0573 lb t = 0.032 in. t = 0.032 in. $\delta = 3/32$ in. $\delta = 3/32$ in. $\delta = 1/16$ in. Delta plan form



A = 0.728W = 0.143 lb t = 0.032 in. $\delta = 3/32$ in.



A = 0.536W = 0.106 lb t = 0.032 in. $\delta = 3/32$ in.

Model 2C 2.82

> A = 0.353W = 0.0694 lb t = 0.032 in. $\delta = 3/32$ in.

A = 0.353W = 0.0322 lb t = 0.026 in.

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Clipped-tip delta plan form

Figure 1.- Model geometry.

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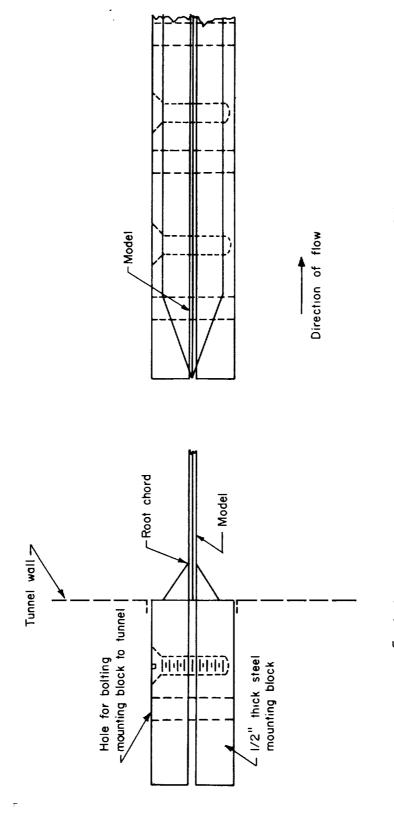
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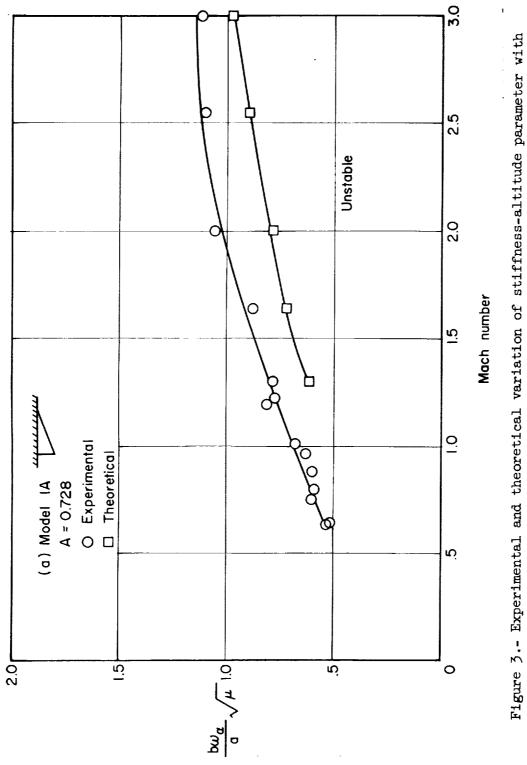


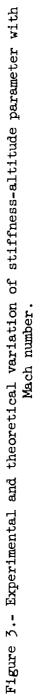
Front view

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Side view

Figure 2.- Method of mounting models.





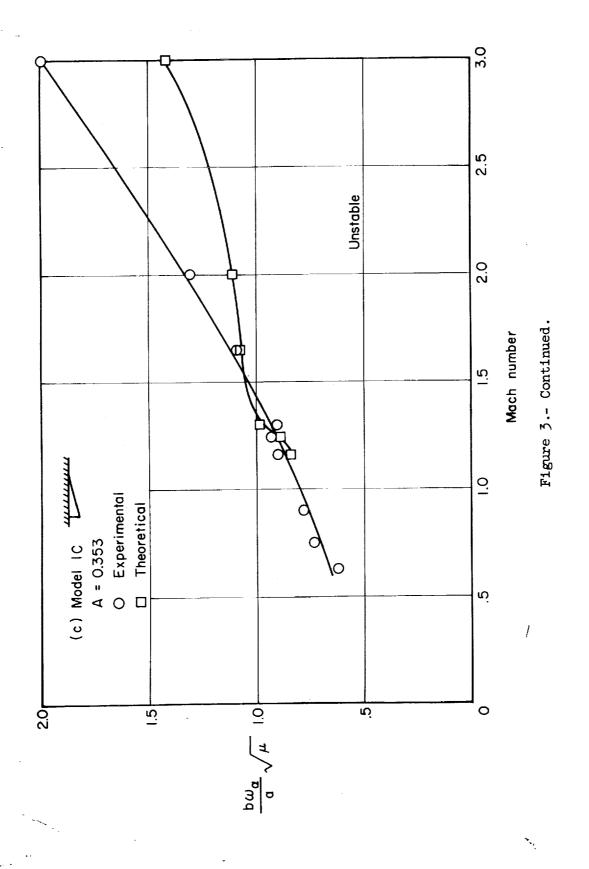
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3.0 2.5 Unstable 2.0 Figure 3.- Continued. Mach number Оþ 1.5 þ ą Р ſ n finnin 0. (b) Model 1B
A = 0.536
O Experimental
Theoretical
No flutter ഹ <u>ا.5</u> $\frac{b\omega_a}{a}\sqrt{\mu}$ 1.0 0 2.0 ທຸ

1-256

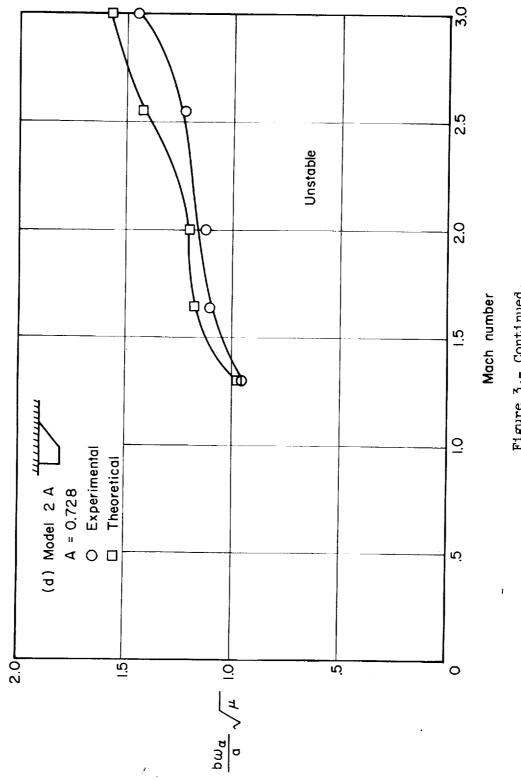
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3W



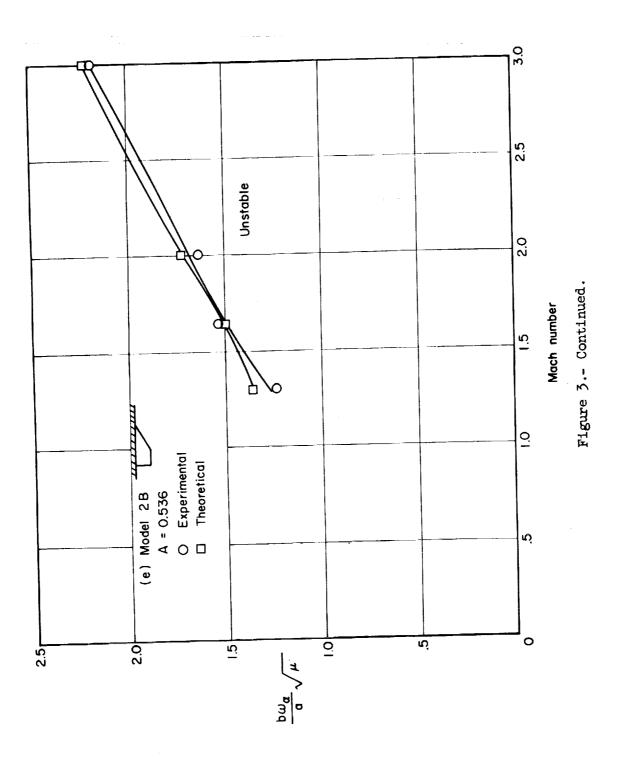
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Figure 3.- Continued.



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3,0 2.5 0 Unstable 5 0.7 Mach number О 5. b р 0. (f) Model 2C Hurr A = 0.353 O Experimental Theoretical പ 0 0 2.0 3.0 40.4 5.0 $\frac{p \omega_{\mathbf{q}}}{\sigma} \sqrt{\mu}$ ```

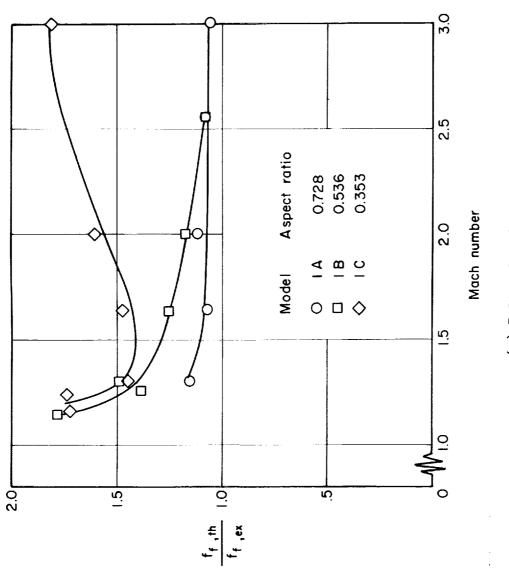
Figure 3.- Concluded.

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(a) Delta plan form.

Figure 4.- Variation of the ratio of theoretical to experimental flutter frequency with Mach number.

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22.

3.5 3.0 ı ŧ 0 2.5 Mach number Model Aspect ratio 0.728 0.536 0.353 20 O 2A □ 2B ◊ 2C фо 0 <u>ດ</u> 0. 2.05 5. 0. 0 ທຸ t ,ex f, , #

Figure 4.- Concluded.

(b) Clipped-tip-delta plan form.

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