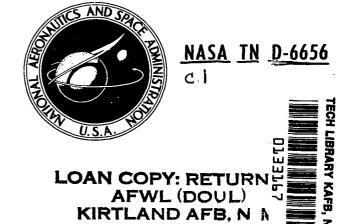
### NASA TECHNICAL NOTE



A WIND-TUNNEL EVALUATION OF ANALYTICAL TECHNIQUES FOR PREDICTING STATIC STABILITY AND CONTROL CHARACTERISTICS OF FLEXIBLE AIRCRAFT

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# A WIND-TUNNEL EVALUATION OF ANALYTICAL TECHNIQUES FOR PREDICTING STATIC STABILITY AND CONTROL CHARACTERISTICS OF FLEXIBLE AIRCRAFT

By Irving Abel Langley Research Center

#### SUMMARY

An experimental evaluation of analytical techniques for predicting certain stability and control characteristics of a large flexible aircraft is presented. Analytical methods based on both the modal approach and flexibility influence coefficients are developed to predict the aerodynamic characteristics of a flexible airplane. These methods are then applied to a flexibly scaled model of a supersonic transport configuration. Comparisons of wind-tunnel data, calculations based on the modal approach, and flexibility influence coefficients are presented over the Mach number range from 0.6 to 2.7. An examination of the results obtained from this study indicates that both analytical techniques predict reasonably well the effect of flexibility on the basic longitudinal characteristics and that both techniques give generally comparable results.

#### INTRODUCTION

Effects of aeroelasticity on aircraft design have been considered for many years. The aeroelastician has been primarily concerned with such problems as flutter, divergence, response to turbulence, and control effectiveness. The effect of flexibility on airplane stability has usually been relatively small and could be taken care of by empirical corrections to measured or calculated stability derivatives. The effect of aeroelasticity on the static aerodynamic characteristics, however, has become a major concern for large flexible aircraft that operate in both the transonic and supersonic flight regimes.

No thorough experimental evaluation of analytical approaches for predicting aeroelastic effects or stability characteristics is available. Recent papers by Roskam, Holgate, and Shimizu (ref. 1) and by Chevalier, Dornfeld, and Schwanz (ref. 2) present some comparisons between theory and experiment, but these are limited by the flexibility of the model investigated. Langley Research Center, therefore, in cooperation with The Boeing Company, undertook a program to provide a comparison of analytically determined and wind-tunnel-measured-rigid and flexible aerodynamic characteristics of a proposed supersonic transport configuration. Two independent analytical approaches were used: a modal technique by NASA and a direct influence-coefficient technique by The Boeing Company. (The analytical approaches are described in appendixes A and B.) The experimental portion of the investigation was conducted over a Mach number range from 0.6 to 2.7 and utilized separate rigid and flexibly scaled models.

This paper provides a description of the wind-tunnel models (including the structural representations used for the flexible model), a description of the analytical techniques being evaluated, and a comparison of calculated and measured results. A brief overall view of this program is given in reference 3.

The experimental results presented are not directly applicable to a full-size airplane since they do not include inertia effects associated with deformation of the structure due to load factor. The results are, in effect, "massless airplane characteristics" since the model experiences a constant (n = 1) load factor and the ratio of gravitational forces to aerodynamic forces (Froude number) was not scaled. Both analytical approaches, however, can include these inertia loadings for the free-flight case.

#### **SYMBOLS**

The moment reference center is located at 45 percent of  $\bar{c}$ .

a	speed of sound
[A]	aerodynamic influence-coefficient matrix
Ā	matrix defining deflection on right wing due to a unit load on right wing
$A_{ij}$	element of aerodynamic matrix $\begin{bmatrix} A \end{bmatrix}$ which defines pressure coefficient at panel i due to a unit angle of attack at panel j
b	wing span
$\left[\overline{\overline{B}}\right]$	matrix defining deflection on right wing due to a unit load on left wing
c	local chord length measured streamwise
$\bar{\mathbf{c}}$	reference chord
$C_{\mathbf{L}}$	lift coefficient, $\frac{\text{Lift}}{\text{qS}}$

$c_{L,o}$	lift coefficient at $\alpha = 0^{\circ}$
$\mathtt{C}_{\mathbf{L}_{\mathbf{q}}}$	lift coefficient due to pitch rate, $\frac{\partial C_L}{\partial \left(\frac{\dot{\theta}\bar{c}}{2V}\right)}$
$\mathrm{c}_{\mathrm{L}_{\alpha}}$	lift-curve slope, $\frac{\partial C_L}{\partial \alpha}\Big _{\alpha=0}$
$c_{\mathbf{L}_{\delta_e}}$	elevator effectiveness in lift, $\frac{\partial C_L}{\partial \delta_e}$
$\mathbf{c}_l$	rolling-moment coefficient, Rolling moment qSb
$\mathtt{c}_{l_{eta}}$	effective dihedral parameter, $\frac{\partial C_l}{\partial \beta}$
$\mathbf{c}_{l_{\delta_{\mathbf{a}}}}$	aileron effectiveness derivative, $\frac{\partial C_l}{\partial \delta_a}$
$C_{\mathbf{m}}$	pitching-moment coefficient, $\frac{\text{Pitching moment}}{\text{qS}\bar{c}}$
$c_{m,o}$	pitching-moment coefficient at $\alpha = 0^{O}$
$c_{m_{\mathbf{q}}}$	pitching moment due to pitch rate, $\frac{\partial C_m}{\partial \left(\frac{\dot{\bar{c}c}}{2V}\right)}$
$c_{m_{m{lpha}}}$	static stability derivative, $\frac{\partial C_m}{\partial \alpha}$
${^{Cm}}_{^{\delta}e}$	elevator effectiveness in pitch, $\frac{\partial C_m}{\partial \delta_e}$
$c_N$	normal-force coefficient, Normal force qS
$\mathbf{c_{N}}_{lpha}$	normal-force curve slope, $\frac{\partial C_N}{\partial \alpha}\Big _{\alpha=0^0}$
$c_n$	yawing-moment coefficient, Yawing moment qSb
$c_{n_{oldsymbol{eta}}}$	directional stability parameter, $\frac{\partial C_n}{\partial \beta}$
${f c_{n_{m eta}}}$	side-force coefficient, $\frac{\text{Side force}}{\text{qS}}$

 $\mathbf{C}_{\mathbf{Y}_{oldsymbol{eta}}}$  side-force parameter,  $\frac{\partial \mathbf{C}_{\mathbf{Y}}}{\partial eta}$ 

F air load (see table II)

(F) matrix defining total resultant force on each wing panel

g acceleration due to gravity

 $h_i(x,y)$  shape of ith vibration mode of model structure

H(x,y) vertical displacement of point (x,y)

i,j indices

I mass moment of inertia in pitch

 $K_i$  generalized stiffness of ith vibration mode

(L) matrix defining lift on each wing panel

L sum of  $\{L\}$ 

 $L_i$  element of matrix  $\{L\}$  defining lift on ith panel

m total number of modes including rigid-body pitch and plunge

m(x,y) mass distribution of flexible model

Δm known incremental mass

M airplane total mass; Mach number

M<sub>i</sub> generalized mass of ith vibration mode

 $\overline{\mathrm{M}}$  matrix defining pitching moment about reference axis for each wing panel

 $\overline{M}_i$  pitching moment per unit generalized coordinate

load factor, Lift Weight normal force per unit generalized coordinate  $N_i$ total lifting pressure over wing Δр pressure distribution due to downwash of ith mode per unit generalized  $\Delta p_i$ coordinate free-stream dynamic pressure,  $\frac{1}{2}\rho V^2$ q generalized coordinate of ith vibration mode  $q_i$ generalized coordinate per unit angle of attack,  $\frac{q_i}{\alpha}$  $\bar{\mathbf{q}}_{\mathbf{i}}$ ith mode generalized force  $Q_i$ S reference wing area [s]matrix defining area of each wing panel free-stream velocity w(x,y)downwash on wing W aircraft total weight  $\{\mathbf{w}\}$ matrix defining weight of each wing panel x,y,zdistances along coordinate axes X,Y,Zorthogonal coordinate system, body axes X matrix defining distance from each panel to reference axis

aerodynamic center defined by  $\left(0.45 - \frac{\partial C_{m_{\alpha}}}{\partial C_{L_{\alpha}}}\right) \bar{c}$ change in aerodynamic center due to flexibility,  $(X_{ac,rigid} - X_{ac,flex})$ ΔXac

 $x_{ac}$ 

$^{\mathbf{z}}$ mcl	coordinate of mean-camber line from wing reference plane, $\frac{z_{upper} + z_{lower}}{2}$
Z(x,y,t)	force distribution in Z-direction (eq. (A1c))
α	angle of attack measured from wing reference plane
$\{lpha\}$	matrix defining angle of attack of each wing panel
$lpha_{f r}$	reference angle of attack
$\left<\alpha_0\right>$	matrix defining initial angle of attack at each wing panel due to camber, twist, or control deflection for wind off
$\left<\Delta^{lpha}_{ m flex}\right>$	matrix defining change in angle of attack at each panel due to aerodynamic loading
β	angle of sideslip
δ	deflection per unit load
$^{\delta}a$	wing trailing-edge control displacement in roll, positive for right aileron trailing edge down
$\delta_{\mathbf{e}}$	wing trailing-edge control displacement in pitch, positive for trailing edge down
δx	ratio of modal deflection at station ${\bf x}$ to deflection at the station for which generalized mass is desired
heta	pitch angle
$[\Theta]$	structural flexibility influence-coefficient matrix
$\Theta_{ ext{j}i}$	element of structural matrix $\Theta$ which defines the angle that panel j deflects due to a unit load on panel i
η	nondimensional spanwise coordinate, $\frac{y}{b/2}$
ρ	air density

$\omega_{\mathbf{i}}$	frequency of ith structural mode
Subscripts:	
A	full-size airplane
flex	flexible model
m	model
rigid	rigid model
sy	symmetric
as	antisymmetric
Matrix nota	ation:
	square matrix
	row matrix
{}	column matrix
	square diagonal matrix

Dots above symbols indicate derivatives with respect to time.

#### DESCRIPTION OF MODELS

#### Rigid Model

The shape of the rigid model is dictated by performance and defined as the shape of the airplane "frozen" at the 1g cruise condition (M=2.7). This shape was predetermined by preliminary wind-tunnel tests at the NASA Langley Research Center and was used as a basis for all wind-tunnel tests during this investigation. A drawing of the complete model configuration is shown in figure 1. Detailed geometric properties of the model are presented in table I. Both models were built to a geometric scale factor of 0.015. The solid steel (rigid) model incorporates a slender cambered body with a  $74^{\circ}$  swept-wing planform, four simulated flow-through engine nacelles, and two vertical tails

mounted outboard on the wing. The swept-wing planform has a subsonic leading edge at the cruise Mach number except in the region of the tip where the leading-edge sweep is reduced to  $65^{\circ}$ .

#### Flexible Model

The 0.015-size flexibly scaled model was designed from the shape of the rigid model at cruise condition (M = 2.7,  $C_L = 0.09$ ,  $q_A = 25.855 \, kN/m^2$ ). This model was elastically scaled with a rigid forward fuselage and elastic wings and aft fuselage. The condition for model to aircraft similarity, according to reference 1, is

$$\left(\frac{q_{m}}{q_{A}}\right)\left(\frac{\delta_{m}}{\delta_{A}}\right)\left(\frac{S_{m}}{S_{A}}\right)^{1/2}=1.0$$

where  $(\delta_m/\delta_A)$  and  $(S_m/S_A)$  are the ratios of model to airplane deflection per unit load and reference wing area, respectively. A dynamic-pressure ratio  $(q_m/q_A)$  of 1.20 was arbitrarily selected. In order to simulate aerodynamic characteristics of the flexible airplane, it is necessary only to scale static load deflections; therefore, model weight was not scaled. A table of model scale factors is presented in table II.

The flexible model was built so that at the cruise point the shape of the rigid and flexible models is the same. In order to achieve this condition, the flexible model is constructed to a model jig shape that is defined as the shape of the model when aerodynamic loads at the cruise point are removed. (The model jig shape will differ from that of the airplane jig shape since neither airplane mass nor mass distribution is simulated.) Figure 2 shows typical comparisons of the mean-camber line between cruise shape and the corresponding jig shape at various span stations.

The flexible model was designed and constructed by The Boeing Company using a structural layout that would be quite similar to that of a full-size airplane. Structural ribs were fabricated from a balsa wood and fiber-glass sandwich with a thin aluminum cap. Plastic foam was used between structural spars to provide the proper wing contour. Finally, fiber-glass skins were bonded to the upper and lower surfaces to provide the properly scaled stiffnesses. Figure 3 shows a photograph of the flexible model during construction. A photograph of the complete flexible model prior to wind-tunnel testing is shown in figure 4.

#### Flexible-Model Properties

Because of the different structural representations required in the two analytical approaches, it was necessary to measure both a set of modal properties (mode shapes, frequencies, and generalized masses) and structural influence coefficients. Both sets of measurements were made for a sting-mounted model.

#### Modal Properties

As input to the modal analysis, it is necessary to determine a set of generalized masses, mode shapes, and natural frequencies of model vibration. For this model, the first five symmetric structural modes, generalized masses, and natural frequencies were all that could be measured.

Mode shapes and natural frequencies. Vibration properties of the model were determined using the mode-shape measuring apparatus shown in figure 5. Two small electromagnetic shakers were positioned under the model to provide excitation for each of the first five symmetric modes. (Phasing between wing tips was checked for each mode to insure only symmetric response.) At each model frequency the displacement at 56 model control points was measured using a variable reluctance pickup. The locations of these points on the wing and fuselage are shown in figure 6. A reference pickup, located near the wing tip, provided a continuous record of model displacement which is required to phase and correct raw data. Measured frequencies and nondimensional modal displacements (normalized to 1.0 at point 56) at the control points are presented in table III.

Generalized masses. In order to characterize the mass properties of the model, it is not necessary to know the mass distribution explicitly because in the analysis the mass always occurs in the form of an integral value over the structure; that is,

$$M_i = \iint m(x,y)h_i^2(x,y)dx dy$$

This integral can be evaluated for each mode by using either the known mass distribution and mode shape or by experimental methods. Since the mass distribution was not determined during construction, the direct experimental approach was used.

The experimental technique employed is described in reference 4. A brief description of this technique and its application follows:

The generalized stiffness of the ith vibration mode is defined as

$$K_i = M_i \omega_i^2$$

where  $\omega_i$  is the natural frequency of the ith structural mode. If it is assumed that by adding a small known mass  $\Delta m$ , at station x, the generalized stiffness does not change, then

$$K_i = (M_i + \Delta m \delta x^2) \overline{\omega}_i^2$$

where

δx ratio of modal deflection at station x to deflection at the station for which generalized mass is desired

 $\overline{\omega}_i$  natural frequency of ith mode with added mass  $\Delta m$ 

Therefore,

$$(M_i + \Delta m \delta x^2) \overline{\omega}_i^2 = M_i \omega_i^2$$

or

$$M_{i} = \frac{\Delta m \, \delta x^{2}}{\left(\frac{\omega_{i}}{\overline{\omega}_{i}}\right)^{2} - 1}$$

For each mode,  $\Delta m$  is known and  $\delta x$ ,  $\overline{\omega}_i$ , and  $\omega_i$  are measured. The generalized mass  $M_i$  can now be evaluated by the preceding equation. In practice, it is convenient to plot  $\Delta m \delta x^2$  as a function of  $\left(\frac{\omega_i}{\overline{\omega}_i}\right)^2$  - 1 for various values of  $\Delta m$  in order to insure that the mode has not been altered by the additional mass. If the mode has been altered, this plot will be nonlinear. The slope of this curve, evaluated near zero for the nonlinear case, is the generalized mass.

The application of this technique to the flexible model is presented in figure 7. Also presented are the approximate locations of the symmetric node lines for each mode. For each mode a minimum of three data points were obtained. All generalized masses are referenced to model control point 56.

#### Structural-Influence Coefficients

The required structural information for the influence-coefficient analysis is the matrix  $\Theta$  (eq. (B3)). This matrix defines the slope at any point on the structure due to a unit load at every other point. The flexibility influence coefficients for the flexible model were experimentally determined by The Boeing Company.

The data required to define the flexibility influence coefficients were measured using the test setup shown in figure 8. The model was rigidly attached to a test fixture. Fiftyone electrical transducers were positioned over the right wing at preselected control points to monitor displacements. Figure 9 shows the paneling scheme and location of each control point. (Control points are at panel centroids.) The deflections at stations 1 through 10 were not measured since the model was essentially rigid in this region. A pneumatic cylinder was used to apply point loads.

In order to evaluate the flexibility matrix, it is necessary to make two measurements: (1) the deflection on the right wing due to a load on the right wing, and (2) the deflection on the right wing due to a load on the left wing. These measurements were made by applying a known load at each of the 51 stations and monitoring the resulting deformation at all stations due to this load. If we define these two measured quantities as

- matrix defining deflection on the right wing due to a unit load on the right wing
- matrix defining deflection on the right wing due to a unit load on the left wing

then the symmetric deflection matrix can be expressed as

$$\begin{bmatrix} \delta_{\mathbf{s}\mathbf{y}} \end{bmatrix} = \begin{bmatrix} \overline{\mathbf{A}} \end{bmatrix} + \begin{bmatrix} \overline{\mathbf{B}} \end{bmatrix}$$

and the antisymmetric deflection matrix as

$$\left\lceil \delta_{\rm as} \right\rceil = \left[ \overline{\rm A} \right] \, - \, \left[ \overline{\rm B} \right]$$

The matrix  $\delta$  is now differentiated, by using a finite difference technique, to provide the required result  $\Theta$ ; that is, the slope at a point due to a unit load at any point on the structure. Measured values of deflection per unit load used to define matrices  $\overline{A}$  and  $\overline{B}$  are given in table IV.

#### WIND-TUNNEL METHODS AND TEST CONDITIONS

The wind-tunnel studies were conducted in the Langley 8-foot transonic pressure tunnel and in the Langley Unitary Plan wind tunnel in order to obtain data at subsonic and supersonic speeds. The stagnation dewpoint temperature was maintained sufficiently low to avoid any significant condensation effects in either tunnel.

In order to insure a turbulent boundary-layer condition, all tests of both models were conducted with boundary-layer transition strips. These strips were composed of a band of No. 60 carborundum grit located 3.05 cm aft of the forebody apex and a band of No. 80 grit located 1.52 cm streamwise from the leading edge of all external surfaces and on the inside surface of the engine nacelles.

Aerodynamic forces and moments about the  $0.45\bar{c}$  reference center were measured using a six-component strain-gage balance mounted within the models. Angle of attack was corrected for deflection of the sting and balance under aerodynamic load and for tunnel-flow angularity. Angle of attack was varied from about -10° to 5°, and sideslip angle was varied from -6° to 6°.

Wind-tunnel studies at M=0.6, 0.9, and 1.2 over a range of dynamic pressures from 11.970 to 38.304 kN/m<sup>2</sup> were conducted in the Langley 8-foot transonic pressure tunnel. This tunnel is a variable-pressure, single-return facility having a slotted test section and is capable of producing velocities in the test section up to M=1.3 without appreciable effects of choking and blockage. The nominal test conditions for this investigation are:

Mach number	Stagnation temperature, OC	Dynamic pressure, kN/m <sup>2</sup>	Reynolds number per meter
	Rig	gid model	
0.60	48.9	12.593	$6.562 \times 10^{6}$
.90	48.9	17.093	6.562
1.20	48.9	19.966	6.562
	Flex	tible model	
0.60	48.9	11.970	$6.201 \times 10^6$
.60	1	23.940	12.434
.60		32,654	16.962
.90		11.970	4.593
.90		23.940	9.186
.90		29.638	11.385
1.20		11.970	3.937
1.20		23.940	7.874
1,20	*	38.304	12.598

Wind-tunnel studies at M=2.3 and M=2.7 over a range of dynamic pressures from 11.970 to 47.880 kN/m<sup>2</sup> were conducted in the Langley Unitary Plan wind tunnel. The nominal test conditions for this investigation are:

Mach number	Stagnation temperature, <sup>O</sup> C	Dynamic pressure, kN/m <sup>2</sup>	Reynolds number per meter
	Rig	rid model	
2.3	65.6	21.738	$6.562\times10^6$
2.7	65.6	19.822	6.562
	Flex	ible model	
2.3	65.6	11.970	$3.642 \times 10^6$
2.3	1	23.940	7.251
2.7		11.970	3,970
2.7		23.940	7.940
2.7		31.122	10.335
2.7	<b>†</b>	47.880	15.879

#### AEROELASTIC ANALYSIS

Analytical calculations for the rigid model as a function of Mach number and for the flexible model as a function of Mach number and dynamic pressure have been made employing the modal method (appendix A) and structural influence coefficients (appendix B). The calculations were made for a sting-mounted, "massless" model. The term massless is used to describe the case in which only aerodynamic loads are considered acting upon the structure; that is, inertia loads such as weight times load factor are assumed to be zero.

#### Modal Method

A digital computer program, using the approach discussed in appendix A, was developed to predict aeroelastic effects on longitudinal stability and control characteristics. Calculations were made for a sting-mounted model using the first five measured symmetric modes and generalized masses (see fig. 7 and table III).

The basic free-flight equations presented in appendix A represent the sting-mounted model, if it is assumed that integrals of the form

$$\iint m(x,y)h_{\mathbf{i}}(x,y)dx dy$$

are negligibly small. In the free-flight case these integrals are exactly zero, except for the plunge mode where the integral simplifies to the total mass of the airplane, due to the orthogonality of the structural and rigid-body modes.

Subsonic aerodynamics. The subsonic generalized aerodynamic forces

$$\iint \Delta p_{i}(x,y)h_{j}(x,y)dx dy$$

were formulated through the use of kernel-function aerodynamics. The pressure distribution  $\Delta p_i(x,y)$  is obtained by a numerical method similar to that presented in reference 5. The pressure distribution is obtained by numerically solving a linear integral equation which relates the pressure distribution to the downwash.

The solution of the kernel equation for  $\Delta p_i(x,y)$  requires that the downwash be specified at known control points. Thirty-six control points were used in these calculations. These points were located at 12.1, 33.6, 56.7, 76.5, 88.5, and 96.8 percent of the panel span  $(\eta)$  and at 5.7, 21.6, 44.0, 67.7, 87.4, and 98.5 percent of the local streamwise chord (x/c). Only the wing, extended to the fuselage center line, is represented aerodynamically.

Substituting the appropriate expressions for the downwash due to rigid loading and that due to flexibility, the generalized aerodynamic forces required to solve the equations of motion (appendix A) are determined.

Supersonic aerodynamics. Supersonic generalized aerodynamic forces were evaluated through the use of a supersonic Mach-box procedure (ref. 6). As in the kernel program the pressure distribution is obtained by specifying the downwash at known control points. The 56 control points at which the flexible modes were specified (fig. 6) were also used as the downwash control points for this calculation. Only the wing, extended to the fuselage center line, was represented aerodynamically.

Once the pressure distribution due to rigid loading and each flexible mode are known, the generalized aerodynamic forces are calculated. The equations of motion (appendix A) are now solved as before.

#### Influence-Coefficient Method

A digital computer program developed by The Boeing Company, using the approach discussed in appendix B, was used to predict aeroelastic effects on longitudinal stability and control and lateral control characteristics. Calculations were made for a sting-mounted model using measured flexibility influence coefficients (see table IV).

The free-flight equations presented in appendix B represent the massless, constrained model if the weight matrix  $\{W\}$  is assumed to be 0. Equation (B4), therefore, becomes

$$\langle \mathbf{F} \rangle = \mathbf{q} [\mathbf{S}] [\mathbf{A}] \langle \alpha \rangle$$

When the panel weights are set equal to zero, the aeroelastic characteristics become a function of planform and structure at a given test condition. Comparisons of aerodynamic characteristics with and without mass effects are presented in table V.

The aerodynamic matrix [A] was formulated through the use of constant-pressure panels that can be used at subsonic and supersonic speeds (ref. 7) and which were coincident with the structural panels (fig. 9). The aerodynamic representation included the forebody, wing, and cylindrical afterbody.

Once the area matrix [S], aerodynamic matrix [A], and flexibility influence-coefficient matrix  $[\Theta]$  are evaluated, the equations in appendix B are solved for the flexible aerodynamic characteristics as a function of rigid loading and test condition.

#### RESULTS

This section compares longitudinal aerodynamic characteristics obtained with the rigid model and the flexible model and from theoretical calculations. Also included is a

presentation of lateral experimental results obtained for the flexible model and a comparison of lateral-control effectiveness with influence-coefficient calculations. The rigid model is assumed perfectly rigid, and no corrections to the data due to flexibility are included.

#### Longitudinal Aerodynamic Characteristics

A comparison of analyses and wind-tunnel data in predicting the variation of lift-curve slope  $C_{L_{\mathcal{Q}}}$  and aerodynamic center  $X_{ac}$ , in percent of the reference chord, as a function of Mach number is presented in figure 10. Measured results are given for both the rigid model (assumed independent of dynamic pressure) and the flexible model at a dynamic pressure 23.94 kN/m². The effect of dynamic pressure at all Mach numbers is to reduce  $C_{L_{\mathcal{Q}}}$  significantly and to shift the aerodynamic center in a destabilizing forward direction. Reductions in  $C_{L_{\mathcal{Q}}}$  of about 37 percent and shifts in the aerodynamic center as large as 18 percent of  $\bar{c}$  are evident at M=1.2. These phenomena are associated with structural deflections outboard on the wing which tend to reduce the local angle of attack and, subsequently, to reduce the contribution of the outboard portion of the wing to the total lift. This reduction in lift results in a lower lift-curve slope and a forward shift in the aerodynamic center. In general, correlation between analyses and experiment is reasonable.

The effect of dynamic pressure on lift-curve slope is predicted somewhat better than the effect of dynamic pressure on aerodynamic-center location. Figure 11 compares analyses and wind-tunnel data in predicting the variation of the ratio of flexible  $C_{L_{\alpha}}$  to rigid  $C_{L_{\alpha}}$  and aerodynamic-center movement between rigid and flexible models as a function of dynamic pressure. Data are presented for Mach numbers of 0.6, 0.9, 1.2, 2.3, and 2.7 over a range of dynamic pressure. The shift in aerodynamic center,

$$\Delta X_{ac} = (X_{ac,rigid} - X_{ac,flex})$$

is a measure of the movement of the aerodynamic center from its location on the rigid model as indicated in figure 10. In general, the agreement between analyses and windtunnel data in predicting the variation in  $C_{L_{\alpha}}$  is good. For most cases, the agreement between modal and influence-coefficient techniques is comparable; however, the aerodynamic-center movement with dynamic pressure is predicted better with the modal technique at M = 0.6, 0.9, and 1.2. Both techniques show good agreement with windtunnel data at M = 2.3 and M = 2.7. It should be noted that at these higher Mach numbers the shift in aerodynamic center is predicted quite well even though neither analysis predicted the absolute position of the aerodynamic center (see fig. 10).

Figure 12 presents a comparison of analyses and experiment in predicting lift and pitching-moment coefficients at  $\alpha = 0^{\circ}$  as a function of dynamic pressure. The calculated data are generated by putting into the program the camber and twist distribution

of the wing mean-camber line (fig. 2). Only flexible-model results are presented since the slope of the mean-camber line for the rigid model applies only to the design cruise point. It should be noted that calculated data at a dynamic pressure of zero correspond to a rigid configuration with the flexible-model jig-shape camber and twist.

At Mach numbers of 0.6, 0.9, and 1.2, the influence-coefficient analysis appears to predict the pitching-moment coefficients somewhat better than the modal approach. At Mach numbers of 0.6 and 0.9, both methods are directly comparable for lift coefficient. At M=1.2, the influence-coefficient method predicts both lift coefficient and pitching-moment coefficient somewhat better. The results at M=2.3 and 2.7 indicate that both methods predicted the lift coefficient quite well, but for these cases the modal method appears to predict the pitching-moment coefficient somewhat better.

The reason one method appears to give better results at one Mach number than at others is probably the aerodynamic representations utilized in both methods. The modal method uses kernel function subsonically and Mach-box aerodynamics supersonically, whereas the influence-coefficient technique uses constant-pressure panels throughout and includes fuselage effects. In all cases the trend is accurately predicted, and in most cases the increment between measured data is estimated quite well using either technique.

A comparison between wind-tunnel data and analyses in predicting control-surface effectiveness in pitch is presented in figure 13. At M = 0.6 and 0.9 only influence-coefficient analysis data are presented since the modal technique could only be applied to the supersonic case. (The kernel-function program used does not provide for inclusion of control-surface aerodynamics.) Data at Mach numbers of 1.2, 2.3, and 2.7 compare both influence-coefficient and modal analyses with experimental results. Wind-tunnel data for the rigid model were not available at these Mach numbers for the control surface under investigation.

Correlation between experiment and analyses is quite poor for predicting the absolute level. The increment in control effectiveness, however, is predicted somewhat better. It is believed that part of this problem is due to the inadequacy of both aerodynamic theories (Mach-box and constant-pressure panels) to properly predict the rigid loading because of the proximity of the control surface to both the vertical tail and the outboard engine. The problem was further aggravated by the flexibility of the control-surface attachment points. Since both analytical methods at M=1.2, 2.3, and 2.7 predict about the same rigid loading, the differences in calculations are attributed to the limited number of modes used in the modal calculation.

#### Lateral Aerodynamic Characteristics

The variation of measured lateral stability derivatives  $C_{l\beta}$ ,  $C_{n\beta}$ , and  $C_{Y\beta}$  for the flexible model as a function of angle of attack at different dynamic pressures is

111

111 1 1111 1011 1

presented in figure 14. These derivatives were estimated around  $\beta = 0^{O}$  by taking, for example,

$$C_{l_{\beta}} = \frac{\left(C_{l}\right)_{\beta=2^{O}} - \left(C_{l}\right)_{\beta=0^{O}}}{2}$$

At present the theoretical calculations have not been extended to predict these lateralstability characteristics. The general analytical approach outlined previously can be applied to the lateral case by using the appropriate antisymmetric structural and aerodynamic representations.

For the Mach number and dynamic-pressure range investigated, the flexible model exhibited positive effective dihedral  $(-C_{l_{\beta}})$  except at the larger negative angles of attack, a positive value of  $C_{n_{\beta}}$  except at the larger negative angles of attack at M=2.3 and 2.7, and a negative side-force derivative  $C_{Y_{\beta}}$ . For this configuration, dynamic pressure appears to have a less significant effect on the lateral-directional characteristics than on the longitudinal characteristics. The primary effect is a reduction in  $C_{l_{\beta}}$ , at all Mach numbers, with increasing dynamic pressure.

The effect of dynamic pressure on control-surface effectiveness in roll is presented in figure 15. Calculations using the influence-coefficient technique were made to predict this effect. At all Mach numbers the effect of an increase in dynamic pressure is to reduce appreciably the aileron effectiveness in roll. At M=1.2 and q=33 kN/m<sup>2</sup> the model exhibits zero control effectiveness. Once again, the correlation between analysis and experiment in predicting control-surface effectiveness is quite poor. As stated previously, this can be attributed to poor prediction of the rigid loading. It is interesting to note that zero effectiveness in pitch (M=1.2, fig. 13) and aileron reversal in roll (M=1.2, fig. 15) are analytically predicted reasonably close to the experimental results using the influence-coefficient analysis.

#### CONCLUDING REMARKS

Both wind-tunnel studies and analytical calculation of 0.015-size rigid and flexibly scaled models of a proposed supersonic transport configuration have been conducted at subsonic and supersonic speeds to measure the effect of flexibility on the aerodynamic characteristics. Analytical calculations using both a modal approach and structural influence-coefficient approach are presented.

Examination of the analytical and experimental data indicates that:

1. The analyses did predict reasonably well the effect of flexibility on the basic longitudinal characteristics; however, the analyses are shown to be poor in predicting control-surface derivatives in both pitch and roll.

2. Both the modal approach and the structural influence-coefficient approach yield generally comparable results.

Even though the primary purpose of this investigation was to evaluate analytical techniques, it has been shown experimentally that:

- 1. The longitudinal aerodynamic characteristics of the flexible model were affected strongly by flexibility effects which included large reductions in lift-curve slope, destabilizing shifts in the aerodynamic center, and large reductions in control effectiveness.
- 2. The lateral aerodynamic characteristics of the flexible model were not greatly affected by flexibility except for control effectiveness in roll.

Langley Research Center,

National Aeronautics and Space Administration, Hampton, Va., February 10, 1972.

#### APPENDIX A

# MODAL METHOD FOR DETERMINING LONGITUDINAL STABILITY AND CONTROL CHARACTERISTICS

A detailed analysis of the procedure for calculating aeroelastic effects on longitudinal stability and control using the modal approach is presented.

The deformation of the airplane as a function of rigid loading is determined by solving Lagrange's equations of motion. From these calculated deformations the effective wing loading is obtained which, in turn, is used to calculate the flexible stability and control characteristics.

A digital computer program, using the approach discussed in reference 8, was developed to predict aeroelastic effects on longitudinal stability and control.

Equations of motion.- Under the following assumptions

- (1) The forward speed V of the airplane is constant
- (2) Small angle-of-attack variation  $(C_N \approx C_L)$
- (3) Small structural deformation
- (4) Structural motion is slow enough that structural acceleration and structural velocity are negligibly small
- (5) Orthogonal structural modes

the linearized free-flight longitudinal equations of motion appear in a general form (in the body-axis system) as follows:

$$M_{i}\ddot{q}_{i}(t) + \omega_{i}^{2}M_{i}q_{i}(t) = Q_{i}(t)$$
(A1)

where

$$M_i = \iint m(x,y)h_i^2(x,y)dx dy$$
 (A1a)

$$Q_{i}(t) = \iint Z(x,y,t)h_{i}(x,y)dx dy$$
(A1b)

$$Z(x,y,t) = \Delta p(x,y,t) - ngm(x,y)$$
 (A1c)

$$\Delta p(x,y,t) = \sum_{j=1}^{m} \Delta p_j(x,y,t)q_j(t)$$
 (A1d)

#### APPENDIX A - Continued

Generalized forces and moments. In order to determine the generalized forces and moments  $Q_i(t)$ , it is necessary to relate the downwash w(x,y,t) to the displacement H(x,y,t) of the system. It is assumed that the displacement H(x,y,t) can be represented by a superposition of the normal modes of vibration so that

$$H(x,y,t) = h_1(x,y)q_1(t) + h_2(x,y)q_2(t) + ... + h_m(x,y)q_m(t)$$

where  $q_i$  specifies the magnitude of the displacement in the ith mode, and  $h_i(x,y)$  gives the shape of the mode. Letting  $h_1(x,y)$  be rigid-body plunge and  $h_2(x,y)$  be rigid-body pitch, then

$$h_1(x,y) = 1$$
  $h_2(x,y) = x$   $q_1(t) = z$   $q_2(t) = \theta$ 

The displacement can now be written as

$$H(x,y,t) = z + x\theta + \sum_{i=3}^{m} h_i(x,y)q_i(t)$$

The downwash w(x,y,t) associated with the displacement H(x,y,t) is given by

$$w(x,y,t) = \left(V \frac{\partial}{\partial x} + \frac{\partial}{\partial t}\right) H(x,y,t)$$

Downwash due to angle of attack. Assuming the downwash associated with  $\dot{\theta}$  is small and using assumption (4),  $\dot{q}_i = 0$  where  $i \ge 3$ , the downwash due to angle of attack may be expressed as

$$w(x,y) = V \left[ \sum_{i=3}^{m} \frac{\partial h_i(x,y)}{\partial x} q_i + \alpha \right]$$
(A2)

where

$$\alpha = \theta + \frac{\dot{z}}{V} \tag{A2a}$$

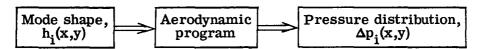
The downwash is composed of two parts; namely,

Downwash due to flexibility:  $V \sum_{i=3}^{m} \frac{\partial h_i(x,y)}{\partial x} q_i$ 

Downwash due to rigid loading:  $V_{\alpha}$ 

Once the downwash distribution is known over the wing (eq. (A2)), the pressure distribution  $\Delta p_i$  for each flexible and rigid mode can be obtained from available aerodynamic theories. In the modal framework, pressure distributions are determined in the following manner:

#### APPENDIX A - Continued



<u>Determination of structural deformation.</u> Using free-free normal modes (both rigid-body and structural) and downwash due to angle of attack, the longitudinal equations of motion (A1) can be written as

$$M\ddot{Z} = q_3 \iint \Delta p_3(x,y) dx dy + \dots + q_m \iint \Delta p_m(x,y) dx dy$$
$$+ \alpha \iint \Delta p_\alpha(x,y) dx dy - Mgn \tag{A3}$$

$$\begin{split} & I\ddot{\theta} = q_3 \iint x \; \Delta p_3(x,y) dx \; dy \; + \ldots + q_m \iint x \; \Delta p_m(x,y) dx \; dy \\ & + \alpha \iint x \; \Delta p_\alpha(x,y) dx \; dy \end{split} \tag{A4}$$

$$\omega_{3}^{2}M_{3}q_{3} = q_{3} \iint h_{3}(x,y) \Delta p_{3}(x,y)dx dy + \dots + q_{m} \iint h_{3}(x,y) \Delta p_{m}(x,y)dx dy + \alpha \iint h_{3}(x,y) \Delta p_{\alpha}(x,y)dx dy$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

$$\omega_{m}^{2}M_{m}q_{m} = q_{3} \iint h_{m}(x,y) \Delta p_{3}(x,y)dx dy + \dots + q_{m} \iint h_{m}(x,y) \Delta p_{m}(x,y)dx dy + \alpha \iint h_{m}(x,y) \Delta p_{\alpha}(x,y)dx dy$$
(A5)

where

$$\begin{split} &\omega_1=\omega_2=0\\ &M=\int\int m(x,y)h_1^2(x,y)dx\ dy=\int\int m(x,y)dx\ dy\\ &I=\int\int m(x,y)h_2^2(x,y)dx\ dy=\int\int x^2m(x,y)dx\ dy \end{split}$$

and integrals of the form

$$ng \iint m(x,y)h_i(x,y)dx dy = 0 \qquad (i = 2, 3, ..., m)$$

due to orthogonality of the free-free modes.

#### APPENDIX A - Concluded

Once the generalized masses  $M_i$ , the natural structural frequencies  $\omega_i$ , and the aerodynamic forces per unit generalized displacement  $\int \int h_i(x,y) \, \Delta p_j(x,y) dx \, dy$  are evaluated, equations (A5) are solved simultaneously for  $\bar{q}_i$ , the generalized displacement  $q_i$  per unit angle of attack  $\alpha$ .

Final form of flexible characteristics. - Defining normal force and pitching moment per unit generalized displacement as

$$N_i = \iint \Delta p_i(x,y) dx dy$$
  $\overline{M}_i = \iint x \Delta p_i(x,y) dx dy$ 

the plunge equation (A3) can be expressed in terms of  $\,\bar{q}_{i}\,$  as

$$M\ddot{Z} = \alpha \left( \bar{q}_3 N_3 + \bar{q}_4 N_4 + \dots + \bar{q}_m N_m + N_\alpha \right) - Mgn \tag{A6}$$

The aerodynamic terms in equation (A6) can be equated to the normal-force coefficient as

$$\frac{1}{2}\rho \mathbf{V}^2\mathbf{SC_N} = \alpha \left( \bar{\mathbf{q}}_3 \mathbf{N}_3 + \bar{\mathbf{q}}_4 \mathbf{N}_4 + \dots + \bar{\mathbf{q}}_m \mathbf{N}_m + \mathbf{N}_\alpha \right)$$

Differentiating with respect to  $\alpha$ , the flexible lift-curve slope is obtained as a function of the modal properties  $\bar{q}_i$  and  $N_i$  as

$$C_{L_{\alpha,\text{flex}}} \approx C_{N_{\alpha,\text{flex}}} = \frac{1}{\frac{1}{2}\rho V^{2}S} (\bar{q}_{3}N_{3} + \bar{q}_{4}N_{4} + \dots + \bar{q}_{m}N_{m}) + C_{N_{\alpha,\text{rigid}}}$$
(A7)

Using the pitching-moment equation (A4), the static stability derivative  $C_{m_{\alpha},flex}$  can be expressed in terms of  $\bar{q}_i$  and  $\overline{M}_i$  as

$$C_{m_{\alpha,flex}} = \frac{1}{\frac{1}{2}\rho V^2 S\bar{c}} \left( \bar{q}_3 \overline{M}_3 + \bar{q}_4 \overline{M}_4 + \dots + \bar{q}_m \overline{M}_m \right) + C_{m_{\alpha,rigid}}$$
(A8)

In a similar manner, the aerodynamic coefficients, such as  $C_{L,o}$ ,  $C_{m,o}$ ,  $C_{L_{\delta_e}}$ ,  $C_{m_{\delta_e}}$ ,  $C_{L_q}$ , and  $C_{m_q}$  can be evaluated by using the appropriate loading conditions, that is, by specifying the proper downwash distribution associated with each rigid loading. In order to evaluate  $C_{L,O_{flex}}$  and  $C_{m,O_{flex}}$ , for example, replace integrals of the form

$$\alpha \iint h_i(x,y) \Delta p_{\alpha}(x,y) dx dy$$

in equations (A3) to (A5) with integrals of the form

$$\iint \left. h_i(x,y) \right. \Delta p(x,y)_{camber \ and \ twist} \; dx \; dy$$

and solve as before.

#### APPENDIX B

## INFLUENCE-COEFFICIENT METHOD FOR DETERMINING LONGITUDINAL STABILITY AND CONTROL CHARACTERISTICS

A detailed analysis of the procedure developed by The Boeing Company for calculating the aeroelastic effects on longitudinal stability and control characteristics using the influence-coefficient approach is presented.

The airplane is first divided into a number of panels (see fig. 9). For each panel an aerodynamic matrix element  $A_{ij}$  is developed which relates the pressure at panel i due to a unit rotation at panel j. A structural flexibility matrix element  $\Theta_{ji}$  is obtained which relates a change in angle of attack at panel j due to a unit load at panel i. With these matrices, which define the aerodynamics and flexibility of the airplane, the following set of matrix equations can be written:

$$\langle L \rangle = q[S][A]\langle \alpha \rangle$$
 (B1)

$$\langle \alpha \rangle = \alpha_{\mathbf{r}} \langle 1 \rangle + \langle \alpha_{\mathbf{o}} \rangle + \langle \Delta \alpha_{\mathbf{flex}} \rangle$$
 (B2)

$$\langle \Delta \alpha_{\text{flex}} \rangle = \left[\Theta\right] \left\{F\right\}$$
 (B3)

$$\langle F \rangle = q[S][A] \langle \alpha \rangle - n \langle W \rangle$$
 (B4)

In order to solve for lift-curve slope, the preceding equations can be solved in the following manner:

$$\langle \alpha \rangle = \alpha_{\rm r} \langle 1 \rangle + \langle \alpha_{\rm o} \rangle + [\Theta] \langle F \rangle$$

Substitute for  $\{F\}$ , equation (B4); then

$$\langle \alpha \rangle = \alpha_{\mathbf{r}} \langle 1 \rangle + \langle \alpha_{\mathbf{o}} \rangle + [\Theta] (q[S][A] \langle \alpha \rangle - n \langle W \rangle)$$

Solving for  $\{\alpha\}$  and substituting this result into equation (B1) results in the total lift

$$\mathbf{L} = \begin{bmatrix} 1 \end{bmatrix} \left\langle \mathbf{L} \right\rangle = \mathbf{q} \begin{bmatrix} 1 \end{bmatrix} \begin{bmatrix} \mathbf{S} \end{bmatrix} \begin{bmatrix} \mathbf{A} \end{bmatrix} \left( \begin{bmatrix} 1 \end{bmatrix} - \mathbf{q} \begin{bmatrix} \Theta \end{bmatrix} \begin{bmatrix} \mathbf{S} \end{bmatrix} \begin{bmatrix} \mathbf{A} \end{bmatrix} \right)^{-1} \left( \alpha_{\mathbf{r}} \left\{ 1 \right\} + \left\langle \alpha_{\mathbf{o}} \right\} - \mathbf{n} \begin{bmatrix} \Theta \end{bmatrix} \left\langle \mathbf{W} \right\rangle \right) \right\}$$

Since the load factor n is defined as  $\frac{Lift}{Weight}$  and  $C_L = \frac{Lift}{qS}$ , the previous equation can be expressed as

$$\mathbf{C_{L}} = \frac{\left\lfloor 1 \right\rfloor \left\lceil \mathbf{S} \right\rceil \left[ \mathbf{A} \right]}{\mathbf{S}} \left\{ \left( \left\lceil 1 \right\rceil - \mathbf{q} \left[ \Theta \right] \left\lceil \mathbf{S} \right] \right] \mathbf{A} \right)^{-1} \left( \alpha_{\mathbf{r}} \left( 1 \right) + \left\langle \alpha_{\mathbf{o}} \right\rangle - \frac{\mathbf{qSC_{L}}}{\mathbf{W}} \left[ \Theta \right] \left\langle \mathbf{W} \right\rangle \right) \right\}$$

#### APPENDIX B - Concluded

Differentiating this expression with respect to  $\alpha_r$  and simplifying results in the final form of the lift-curve slope; that is,

$$C_{L_{\alpha,\text{flex}}} = \frac{\left[1\right]\left[s\right]\left[A\right]\left(\left[1\right] - q\left[\Theta\right]\left[s\right]A\right)^{-1}\left\{1\right\}}{s\left(1 + \frac{q}{W}\left[1\right]\left[s\right]A\right)\left(\left[1\right] - q\left[\Theta\right]\left[s\right]A\right)^{-1}\left[\Theta\right]\left(w\right)\right)}$$
(B5)

Since the lift  $L_i$  on each panel is known, the pitching-moment derivatives can be readily calculated from panel geometry; that is,

$$\left\langle \overline{\mathbf{M}} \right\rangle = \left[ \mathbf{X} \right] \left\langle \mathbf{L} \right\rangle$$

In a similar manner, expressions can be derived for other aerodynamic characteristics such as  $C_{L,o}$ ,  $C_{m,o}$ ,  $C_{L_{\delta_e}}$ ,  $C_{m_{\delta_e}}$ ,  $C_{L_q}$ , and  $C_{m_q}$ .

The principal advantage of the direct influence-coefficient approach is the capability for separation of inertia loading effects from aerodynamic loading effects. A comparison of these characteristics is presented in table V. The aerodynamic characteristics presented are separated into three categories: aeroelastic effects due to both flexibility and inertia, aeroelastic effects due only to flexibility (referred to as massless derivatives in ref. 1), and rigid-airplane characteristics.

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TABLE I
GEOMETRIC PROPERTIES OF MODELS

Wing												
Aspect ratio	1.630											
Span, meters	0.580											
Area, meters <sup>2</sup>	0.207											
Root chord at fuselage center line, meters	0.815											
Tip chord, meters	0.034											
Reference chord, meters	0.487											
Fuselage												
Length, meters	1.167											
Diameter at base, meters												
Vertical tails												
Area, meters <sup>2</sup>	0.005											
Thickness-chord ratio												

TABLE II
MODEL SCALE FACTORS

Quantity	Symbol	Formula	Factor
Length	${ m L_m/L_A}$	Selected	0.015
Dynamic pressure	$q_{\rm m}/q_{\rm A}$	$\left  \left\langle \frac{\rho_{m}}{\rho_{A}} \right\rangle \left\langle \frac{v_{m}}{v_{A}} \right\rangle^{2} \right $ selected	1.2
Mach number	$M_{\rm m}/M_{\rm A}$	$\left(\frac{\mathbf{v_m}}{\mathbf{v_A}}\right)\left(\frac{\mathbf{a_A}}{\mathbf{a_m}}\right)$	1.0
Air loads	$F_{ m m}/F_{ m A}$	$ \begin{vmatrix} \frac{\rho_m}{\rho_A} & \frac{v_m}{v_A} \\ \frac{\rho_m}{\rho_A} & \frac{v_m}{v_A} \end{vmatrix}^2 \text{ selected} $ $ \begin{vmatrix} \frac{v_m}{\rho_A} & \frac{a_A}{a_m} \\ \frac{q_m}{q_A} & \frac{L_m}{L_A} \end{vmatrix}^2 $ $ \begin{vmatrix} \frac{q_m}{q_m} & \frac{L_m}{L_m} \\ \frac{q_m}{q_m} & \frac{L_m}{L_m} \end{vmatrix}$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$
Deflection per unit load	$\delta_{ m m}/\delta_{ m A}$	$\left\langle \begin{matrix} \mathbf{q}_{\underline{\mathbf{A}}} \\ \mathbf{q}_{\underline{\mathbf{m}}} \end{matrix} \right\rangle \left\langle \begin{matrix} \mathbf{L}_{\underline{\mathbf{A}}} \\ \mathbf{L}_{\underline{\mathbf{m}}} \end{matrix} \right)$	55.6
Scaling rule	$: \left(\frac{\mathbf{q_m}}{\mathbf{q_A}}\right) \left(\frac{\delta_{\mathbf{m}}}{\delta_{\mathbf{A}}}\right)$	$\left(\frac{S_{\rm m}}{S_{\rm A}}\right)^{1/2} = 1.0$	

TABLE III
NONDIMENSIONAL MODE-SHAPE DATA

$ \eta = 0. $ $ c = 0. $	00 8110 m	$ \eta = 0.1 \\ c = 0.6 $	21 3139 m	$ \eta = 0.3 \\ c = 0.4 $	336 1813 m	$ \eta = 0.5 \\ c = 0.2 $		$ \eta = 0.7 \\ c = 0.1 $	65 430 m	$ \eta = 0.8 \\ c = 0.0 $	85 889 m	$ \eta = 0.9 \\ c = 0.0 $	968 9498 m
x/c	hi	x/c	hi	x/c	hi	x/c	hi	x/c	hi	x/c	hi	x/c	$h_i$
	1		, ,	1	Mode 1:	$\omega = 27.$	19 hertz,	i = 1					
0.031	-0.038	0.018	-0.010	0.026	0.041	0.038	0.132	0.055	0.401	0.054	0.580	0.061	0.854
.170	009	.154	.000	.161	.055	.171	.155	.183	.447	.180	.622	.193	.873
.308	001	.290	.012	.297	.070	.304	.201	.312	.484	.303	.654	.315	.896
.445	.018	.426	.035	.432	.093	.437	.242	.441	.519	.429	.682	.447	.916
.584	.046	.562	.061	.566	.132	.569	.300	.571	.562	.554	.718	.563	.92
.733	.079	.698	.095	.701	.178	.702	.360	.700	.606	.680	.735	.695	.92'
.860	.130	.837	.141	.836	.253	.825	.436	.830	.651	.811	.777	.822	.939
.998	.180	.982	.214	.973	.336	.967	.518	.965	.722	.940	.802	.954	1.00
	T	,		,	Mode 2:	$\omega = 42.$	87 hertz,	i = 2					
0.031	0.033	0.018	0.010	0.026	-0.009	0.038	-0.035	0.055	0.216	0.054	0.548	0.061	0.780
.170	.008	.154	.000	.161	019	.171	018	.183	.272	.180	.563	.193	.799
.308	.000	.290	004	.297	031	.304	.001	.312	.329	.303	.603	.315	.84
.445	009	.426	017	.432	035	.437	.029	.441	.393	.429	.653	.447	.86
.584	028	.562	032	.566	023	.569	.097	.571	.467	.554	.691	.563	.88
.733	033	.698	030	.701	001	.702	.185	.700	.530	.680	.741	.695	.91
.860	011	.837	008	.836	.051	.825	.286	.830	.603	.811	.805	.822	.95
.998	001	.982	001	.973	.153	.967	.417	.965	.689	.940	.855	.954	1.00
					Mode 3:	$\omega = 68.$	21 hertz,	i = 3					
0.031	-0.002	0.018	-0.005	0.026	-0.006	0.038	-0.001	0.055	0.090	0.054	0.394	0.061	0.69
.170	001	.154	002	.161	004	.171	002	.183	.134	.180	.441	.193	.73
.308	001	.290	001	.297	004	.304	003	.312	.177	.303	.486	.315	.78
.445	001	.426	004	.432	002	.437	002	.441	.226	.429	.531	.447	.80
.584	001	.562	002	.566	010	.569	001	.571	.285	.554	.582	.563	.84
.733	005	.698	009	.701	026	.702	.005	.700	.336	.680	.642	.695	.89
.860	044	.837	046	.836	066	.825	.044	.830	.401	.811	.702	.822	.93
.998	099	.982	106	.973	108	.967	.116	.965	.462	.940	.745	.954	1,00
					Mode 4:	$\omega = 103$	.09 hertz	i = 4					
0.031	-0,001	0.018	-0,001	0.026	0.011	0.038	0.044	0.055	0.046	0.054	0.280	0.061	0.67
.170	001	.154	.002	.161	.016	.171	.041	.183	.056	.180	.317	.193	.68
.308	.001	.290	.004	.297	.019	.304	.034	.312	.071	.303	.351	.315	.72
.445	.004	.426	.008	.432	.022	.437	.016	.441	.086	.429	.394	.447	.75
.584	.007	.562	.010	.566	.020	.569	001	.571	.109	.554	.443	.563	.80
.733	.005	.698	.009	.701	.006	.702	033	.700	.130	.680	.483	.695	.85
.860	.001	.837	.003	.836	033	.825	072	.830	.158	.811	.551	.822	.93
.998	001	.982	.003	.973	163	.967	087	.965	.188	.940	.618	.954	1.00
	1	r	r		Mode 5:		.65 hertz	1					
0.031	-0.004	0.018	-0.004	0.026	0.033	0.038	-0,160	0.055	-0.809	0.054	-0.372	0.061	0.16
.170	003	.154	.008	.161	.040	.171	308	.183	646	.180	263	.193	.28
.308	.014	.290	.023	.297	.018	.304	477	.312	480	.303	126	.315	.38
.445	.027	.426	.028	.432	008	.437	540	.441	298	.429	001	.447	.48
.584	.021	.562	.015	.566	120	.569	492	.571	112	.554	.077	.563	.61
.733	003	.698	023	.701	244	.702	284	.700	005	.680	.257	.695	.72
.860	181	.837	171	.836	121	.825	032	.830	.148	.811	.461	.833	.86
.998	402	.982	351	.973	.052	.967	.201	.965	.345	.940	.644	.954	1.00

TABLE IV STRUCTURAL INFLUENCE-COEFFICIENT MEASUREMENTS

(a) Matrix [A]

Load point	<u> </u>				,,			-	$\overline{}$		ed at positio				05		
oint	11	12	13	14	15	16	17	18	19	20	21	, 22	23	24	25	26	27
11	•037×10 <sup>-4</sup>	•C46×10 <sup>-4</sup>	.057×10 <sup>-4</sup>	.009×10-4	•012×10 <sup>-4</sup>	.017×10-4	•022×10 <sup>-4</sup>	•029×10 <sup>-4</sup>	•039×10 <sup>-4</sup>	.050×10-4	.058×10-4	.061×10-4	-015×10-4	-018×10 <sup>-4</sup>	-023×10-4	.030x10-4	.038x10-4
12	.051	.069	.107	.008	.010	.020	•027	•037	.058	.084	-103	.116	.018	-021	.027	•03B	.054
13	-071	-118	·205	.010	-015	.022	.030	.048	.076	.126	.171	.198	.019	.023	.029	.047	.071
14	-006	-CC6	.006	.014	.006	.006	.007	.007	•007	.007	.007	-007	-00a	.008	.009	.009	.014
15	-013	•C13	.013	.009	.016	.012	.013	.014	-014	.012	.015	.C15	.018	.016	.017	-017	.017
16	.018	-C19	-021	.010	-013	.025	•021	.023	.024	.026	•026	•026	.023	.029	.026	.027	.027
17	.029	•C29	.031	.011	.C15	.021	•036	.029	.031	.034	.035	•035	•022	.027	.034	.034	.034
18	.037	+C40	.045	.012	.016	.023	.029	.038	.041	.046	.049	•050	.023	-027	.036	•044	.047
19	+045	.C55	.068	.012	-015	•022	.026	.035	.054	.065	•074	.G79	-021	.024	.031	•043	-057
20	•059	•CE7	-119	.011	.016	.025	.031	.044	•070	.083	•130	-146	.023	.026	.034	•049	•072
21	-071	-114	-166	.013	.017	.026	.034	•049	.083	-135	-246	•335	.025	-028	.037	•056	.085
22	•063	-311	•173	.011	.014	.021	.027	.041	.076	-135	•312	.678	-020	-022	.029	•045	•075
23	.018	-018	.019	.014	.019	.023	•022	.023	.024	.025	•026	.025	•083	.039	.032	-031	.031
24	•023	•C23	.025	.017	.018	.028	-026	.027	.028	.030	.031	.030	-046	-066	.042	-037	.035
25	•033	•C23	.034	.017	.020	.027	.035	.038	.039	-041	-041	•040	-032	-043	.065	-054	-050
26	.039	-042	-049	.020	.018	.025	.033	-042	•048	.053	.054	.054	.027	.029	.048	•063	•062
27	·C49	.058	.069	.016	.019	•026	.032	-045	-062	.074	-082	-082	-028	-033	.044	-061	.063
28	-059	•C €1	.102	.015	.019	.027	.035	-038	.076	.104	.123	.133	-029	.034	-046	-066	-092
29	-068	•1C3	-136	.015	.019	.029	.037	.053	.086	.133	-180	.215	-029	.033	.045	•067	.100
30	•070	-114	•160	.014	.01B	.027	.035	.051	•090	.148	.230	.309	.027	-031	.041	•063	.100
31	.065	-113	-167	.010	.015	.021	.029	-043	-085	.152	.256	-348	-022	•025	.032	-054	.092
32	•027	•C27	•G27	.017	•020	.029	.034	.038	.038	.038	.037	.034	.037	-056	.073	-059	-053
33	•035	•C35	-035	.019	.021	.029	.037	-044	•046	.048	.047	.C45	.036	.046	.070	.073	•066
34	•046	-C50	.053	.018	.022	•030	.038	•051	•062	.068	•070	•C69	•036	-043	.062	-082	•090
35	-057	•C69	•079	.019	.023	•032	.04l	.055	.078	.095	•096	.107	•037	-043	.059	.083	.110
36	.067	•C E S	-109	.020	.025	.034	•042	.059	.091	.122	-144	.157	•039	•043	-059	-085	-119
37	•074	· 1C7	•139	.020	.025	.035	.044	•063	-100	.146	.188	.219	•039	•043	.059	-087	•127
38		.123	-164	.019	•025	.034	.043	.063	-106	.165	.234	.290	•029	.042	.057	-086	-130
39	.082	•131	-182	.018	.023	.033	.042	.062	-110	.179	.269	. 344	-036	-035	.053	.083	-131
40	-069	-128	-174	.011	.016	-024	.030	.047	-095	-170	.273	.360	.025	.023	.037	•065	-113
41	•059	•CES	-077	.024	.028	•036	.044	•061	•085	.103	.110	•110	-046	-050	.071	-100	.131
42	•063	.C78	.089	.023	.028	.037	•046	.064	•093	-115	-127	.131	.047	-051	.071	•102	.138
43	•Q65	•C & 7	.104	.022	.025	.034	-042	•060	•095	.128	-149	.160	.041	.045	.063	<b>-096</b>	•137
44	•C67	•C 57	-120	.021	<b>.</b> 025	.033	-040	.059	•099	.138	•176	-200	•02€	-042	.060	•093	.139
45	•C70	•1C6	-138	.022	•023	.031	.039	.059	-102	-154	.204	.242	-026	-038	.055	-069	.138
46	.074	-115	-154	.017	.038	•030	038	.05B	-106	.167	-235	-288	-024	•037	-053	-087	-140
47	-076	-126	.172	.018	.022	•030	.037	.058	.111	.182	.266	•337	.032	+034	.051	-086	-142
48	-071	•128	.181	.016	.018	•023	.030	.051	.105	.185	-286	.371	.025	•026	-040	-074	-132
49	-073	•134	.192	.015	.018	-025	.030	•050	-108	-194	.308	•404	.025	•025	-040	•074	,135
50	•C69	•112	-140	.017	.019	•025	.032	.054	-104	.167	•227	•271	•026	•026	-048	•089	.150
51	•070	-115	-151	.016	.019	.024	.033	.054	.108	.175	-246	-297	•027	-028	.046	-089	-151
52	•074	•122	.162	.014	•017	-025	.033	•057	.114	.184	. 265	-328	•025	•027	.048	•090	-156
53	•077	•128	-174	.015	•018	•025	•034	•056	-116	-192	.283	.354	-027	-027	-047	•087	.155
54	•078	-132	.175	.014	-017	•024	.033	.057	.116	.195	-291	.371	•026	•026	-047	.086	.158
55	•C79	-140	•190	.014	.018	•026	.035	.059	.121	.209	-317	-404	.026	-027	.048	-091	.163
56	.079	-144	•202	.018	•021	·C26	•032	•056	.123	.214	.334	•431	.027	-028	.043	-087	-157
57	•085	-150	•208	.015	.018	•025	.034	.059	-130	. 224	.348	•452	•027	•025	-047	-690	-165
58	.082	-142	-191	.013	.C18	•026	.035	.06Z	•130	.218	•321	•405	.023	-026	.050	•099	-180
59	-084	-148	-204	.016	.019	.025	-034	.061	•132	-227	.340	.437	•025	-024	.049	-096	-179
60	-066	-155	.213	.013	.018	.026	.033	.059	•138	.234	.358	•459	-023	•026	-047	-097	•180
61	.086	.159	•223	.014	.017	.025	•033	.061	•137	.242	• 376	-489	•023	-024	.047	.097	•182

TABLE IV
STRUCTURAL INFLUENCE-COEFFICIENT MEASUREMENTS - Continued

(a) Matrix [A] – Continued

Load						Panel de	eflection per	r unit load, i	neters/newt	on, measur	ed at position	on:					
point	28	29	30	31	32	33	34	35	36	37	38	39	40	.41	42	43	44
11	.047×10 <sup>-4</sup>	.055×10 <sup>-4</sup>	.058×10-4	•064×10 <sup>-4</sup>		.028×10-4	•C27X10-4	.038x10 <sup>-4</sup>	•034×10 <sup>-4</sup>	.047X10 <sup>-4</sup>	.059×10 <sup>-4</sup>			•033X10 <sup>-4</sup>	•037×10 <sup>-4</sup>	.050x10 <sup>-4</sup>	•034X10 <sup>-4</sup>
12	.074	•095	-105	.121	.025	.033	-C44	.054	-064	-102	-134	.119	.134	•042	.087	.084	• 653
13	.108		-174	.201	.026	•¢32	.C54	•065	-069	.127	.174	•195	.212	-078	.086	•099	-120
14	.009	-009	.009	.008	•009	.020	.C17	.012 .020	•002	•008	.013	.010	.007	.015	.012	•016	•022
15	.018	•018	.017	.018	-019	.031	.C30		.018	.022 .035	.025 .039	.014 .055	.017 .033	.023	•024	•022	.025 .042
16	-028	.029	-027	•029	•030	.039	.639	.041	.034	.043	.039	•058	.045	.029 .043	.034	.033 .041	•C39
17 18	.037 .050	•038	.037	.038	•034	.047	•C49	.055	.056	.070	.070	.078		. 059	.043 .065	•070	.C65
19		.054 .080	.053 .083	.057		.039	.C54	.072	.065	.080	•092	-105		.067	.070	•075	.099
20	.069 .103	.133	.147	.170	.032	.048	.CeB	.091	.103	.148	.176	.186		•100	-116	•132	.146
21	.128	.189	.240	-291	.034	.049	.C70	.105	.124	.188	.236	.292	.286	.093	.114	.142	.169
22	.125	.208	.290	.367	.026	.C32	.C 62	-103	.140	-204	.264	. 352	.353	.085	.090	.149	.184
23	.032	.033	.031	.032	.039	.C37	·C33	.038	.035	.046	.042	.063		.045	.048	.046	.039
24	.037	.038	.035	.037	.058	.C49	.043	.042	.040	.048	.045	.071	.046	.047	.056	.051	.C54
25	.051	.051	.048	.049	.076	.077	.C e1	•06£	.059	.067	.067	.050	.061	.057	.073	.074	.C76
26	.065	.066	.063	.066	•055	.065	•C69	.082	.058	-084	.080	.079	.078	.083	.087	.087	.091
27	.091	.100	.099	.107	.049	.C59	.C E1	-107	.094	-124	.132	.131	.128	.117	.123	.128	.135
28	.127	.147	.156	.175	.049		.093	-129	.139	•176	.194	.212	. 202	.130	.150	.176	.191
29	.146	.216	.250	.297	.045	.059	•C £7	-136	.166	-244	.295	. 344	. 343	.143	.174	.214	.244
30	.158	.253	.421	.596	.041	·C59	•0£3	-132	.187	.284	.439	•496	.510	.133	.169	.215	.268
31	.158	.278	.562	1.212	.031	.054	.C49	.126	-183	•323	-480	.625	.684	.145	.182	.234	.276
32	.051	.049	.043	.043	.150	.097	.0 61	•068	.049	.070	.069	.049	•062	.082	.081	.078	•¢78
33	.065	.064	.058	.057	.099	.130	. C 5 7	.087	.062	.C80	.083	•075	.073	.101	-101	.104	.091
34	.093	.095	.089	.091	.074	.099	-122	.125	.104	.123	.121	.123	.112	.142	.147	•143	.150
35	.127	.139	.137	.145	.068	•C90	-121	.166	.155	.182	.191	.197	-186	.189	-197	.209	.213
36	.160	.190	.202	.223	.065	•Q88	.123	.176	.205	.248	• 274	. 294	. 279	.207	.235	.267	.291
37	.180	. 242	.287	.331	.066	.084	.127	•182	•229	.351	•400	. 462	•457	•230	.273	.327	.383
38	.195	.290	.385	•483	.062	.080	.127	•190	-266	•406	.534	•666	.694	.231	.279	. 351	.315
39	.207	.330	.471	-617	.057	.C79	.118	.184	.271	•452	. 645		1.028	.225	•276	.369	•435
40	.194	.336	.505	.681	.039	.C50	.C 54	-168	.250	<b>.</b> 458			1.518	.208	.263	•358	-443
41	-152	.165	.155	.159	.087		.163		-214	.258	.258	•252	•231	.313	.327	.316	•323
42	.169	.189	-184	.193	.086	-114	.160	-216	•239	•297	.304	.314	.288	.315	.371	.367	•363
43	.182	.219	.224		.077	.106	-164	.218	.263	.345	.371	• 392	.367	.295	.351	•416	•448
44	•196	•256	.280		.071	.100	-144	-218	-270	•401	.457	.516	•494	.300	.361	•447	•526
45	• 20 4	.284	•337	•403	•065	.090 .076	-146	•223	-295	•451	•532	•642	•638	-290	-348	•447	.539
46	-215	.318	•407	•505	.061	.076	.162 .141	•21¢	-287	•486	.634	•792	•023	•285	•356	•465	-578
47	-226	.354	•4B0	•613	.057	.065		-224	-296	-536	•730		1.054	.280	•351	-467	.596
48	• 224	•376	•533	•702	•043	.051	.128	-213	-268	-555			1.257	•239	•343	•475	-618
49	.235	•403	-586	.763	•042	.112	.165	.210 .255	.325	-588			1.421	•263	•345	•487	•641
50	.233	•338	•405	• 494	•054	.123	.166		• 351	•552	•704	.631	-845	-338	•434	.592	.734 .671
51	•305	.358	•443	•550	-055	.111	.167	.248 .253	.364 .388	•546 •606	•743	•936	•962	•340	•432	-587	.778
52	- 248	.381	•467	.613	•055	.G71	.141	.243	.337		.815	1.043	1.103	.331	•451	-616	.725
53	-256	•401	•525	-667	•054	.078	.144	.252	.388	.630 .639			1.203	•342	•448	•613 •570	.765
54	-257	-411	.550	-702	.053	.093	.142	.256	.333	.694			1.284	•328 364	•446		.795
55	.272	• 441	•603	.782	•053	.085	.125	.246	.366			1.433	1.428 1.557	.354 .331	.455 .435	.613 .628	.802
56 57	•274	•457	-641	-842	•049	.075	.150	.260	.358				1.657	•325	• 452	•645	. 650
58	-286	-479	.674 .616	.890 .789	.050 .057	.108	.180	.296	.393				1.426	•417	.516	•711	.915
58 59	.294	•469	.657	.854	.054	.103	.159	.296	.444				1.627	.404	.537	.737	970
60	.303	- 490		.909	.053		.156	.309	.424				1.700	.382	.519	.734	.990
61	.309	.510	.698 .738	.909	.051	.087	.159	.292	476				1.859	.413		.770	.128
67	.315	.530	. / 30	*417	*091		****	100.75	• -, -	,		1.071		0713	8330	• 110	1

TABLE IV STRUCTURAL INFLUENCE-COEFFICIENT MEASUREMENTS - Continued

(a) Matrix [A] - Concluded

Load	Panel deflection per unit load, meters/newton, measured at position:																
point	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	.60	61
11	.ce2×10-4	.048×10-4	•055×10 <sup>-4</sup>	•057×10 <sup>-4</sup>	.050×10-4	.046×10-4	.057×10 <sup>-4</sup>	.054X10 <sup>-4</sup>	.066×10-4	.058×10-4	•C56×10-4	.C 63×10-4	•063×10 <sup>-4</sup>	.061×10-4	•063×10 <sup>-4</sup>	.065×10-4	•070×10 <sup>-4</sup>
12	.165	-126	.129	-163	.160	.134	.140	.151	.144	.168	-160	·167	.190	-175	.181	•191	.199
13	.146	.158	.182	-206	•215	.163	.195	.200	.210	.160	•234	.254	·258	•234	.251	•255	.274
14	•C13	•005	.010	-014	•010	.014	.003	.010	-017	•010	•GC7	.C10	.005	.OC7	•006	.010	.011
15	•C 24	.026	.023	•024	•022	• 029	.029	.027	.024	•026	•C27	•C24	.026	.027	-024	•036	•022
16	.637	.034	.035	.037	.033	.040	.047	.043	.040	•042	.043	•C42	.04C	•042	.043	+046	.043
17	.C46	.040	·045	•045	•048	•050	.060	.055	.061	-056	.C57	.C57	.057	-058	.055	-063	.060
16	•C 72	.070	•070	•C76	•074	.080	.088	.083	•O87	.088	•€86	.051	•092	•093	•093	•093	•095
19	.051	•099	•103	•103	•113	-104	•123	.123	.115	•123	.129	.125	.157	-141	•143	•144	•153
20	.163	•179	.194	.219	•227	.198	•220	.231	.213	•243	-258	•263	•277	•274	-281	•297	.308
21	.268	•237	•276	•298	•327	• 242	•293	•311	.323	•346	•368	.229	•407	•371	•384	-414	.435
22	.231	•280	•329	•364	•405	. 268	•338	•359	•403	.423	•443	.473	•513	.439	•446	•499	•531
23	.047	•049	•050	•049	.047	•055	.059	.057	•065	•058	•663	.C59	•05B	•065	-067	•065	•066
24	•656	•053	•051	•051	• 053	•062	•065	.069	•070	•065	-067	•C66	•056	.069 .093	.070 .093	•076 •095	•069 •093
25	.C74	•073	•C70	•069	.058	•082	•091	.087	-079	•087	.C85	.C83	.083 .114	.124	.126	•124	•130
26	-050	-089	.089	.093	•094	-105	•112	•116	•122	•114	.198	.199	.2CG	.220	•223	•226	.223
27	.139	•145	-147	-155	•157	•170	.188 .284	.192 .289	.200 .303	•194	•318	•329	•329	.428	.353	.360	.375
28	.206	•212	-231	-239	•252	•192	•420	.438		.309	.501	.522	.546	-536	.556	1.096	-605
29 30	.266	-319	•357	•393 •505	•423 •598	•354 •423	•516	.560	.460 .577	.480 .649	. 697	.722	757	.697	.732	.796	•826
	.214	-407	•488 •608	.707	.780	.512	.611	.679	.710	.787	.E41	• 528	.973	.859	.920	1.005	1.063
31 32	.677	•498 •077	.C71	.079	.071	.091	.098	.094		.089	.C88	330.	.093	.106	.102	.103	.101
33	.043	.092	.091	.087	.087	-108	.120	.116	.122	•113	•115	.102	.106	.131	.131	.125.	.125
34	.146	.144	.139	.147	•147	.095	.192	.108		.123	1 .186	.166	.112	.212	.214	.212	.216
35	.223	.226	.228	.234	.238	.278	305	.311	.276	.315	.319	.317	•322	.361	.372	.371	.369
36	.313	.326	.346	.355	.369	-400	.453	457	.451	.480	.491	.504	.505	.558	.563	-574	.587
37	.427	•473		•558	597	• 566	.653	.679	.698	.731	.761	.769	.803	.839	.860	.902	.932
38	.521	.617	.721	.808	878	.699	.932	.898	.936	1.006	1.064	1.122	1.172	1.148	1.193	1.270	1.337
39	.577	.743	•928	1.080	1.209	.817	•990			1.294	1.371	1.457	1.565	1.456	1.551	1.670	1.770
40	.617	.817	1.080	1.294	1.454	.871	1.084	1.234		1.507	1.633	1.756	1.882	1.663	1.803	1.960	2.098
41	.320	.319	.319	.317	•316	•405	.455	.451	.447	•449	.456	.453	.444	.533	.531	.528	.526
42	.361	.381	.388	•393	.397	.493	.552	.553	.543	.556	•569	.563	-554	-654	•656	.664	. 666
43	.462	.468	.489	•498	.511	.613	.690	.707	.683	•717	.714	.728	.741	.838	-844	.853	.871
44	.548	•587	.630	•658	.688	.764	.876	.898	.871	.931	•952	. 573	-986	1.102	1.119	1.147	1.177
45	.630	.694	.776	-838	.891	.895	1.027	1.075	1.109	1.159	1.200	1.252	1.282	1.381	1.408	1.469	1.521
46	.695	•836	.572	1.088	1.187	1.029	1.216	1.316	1.347	1.473	1.550	1.642	1.703	1.724	1.816	1.921	2.009
47	.759	•960	1.208	1.410	1.592	1.155	1.430	1.569		1.858	1.978	1.953	2.244	2.181	2.325	2.482	2.623
48	.808		1.404	1.788	2.128	1.262		1.810	1.983	2.239		2.656	2.852		2.831	3.074	3.299
49	·667		1.594	2.132	2.803	1.363	1.753	2.018	2.514	2.579	2.829	3.109	3.359	3.027	3.288	3.612	3.902
50	.874	1.008	1.143	1.245	1.347	1.440	1.618			1.832	1.950	2.C25	2.090	2.330	2.360	2.483	2.724
51	.859	1.093	1.302	1.424	1.570	1.528		1.908	1.931	2.133	2.253	2.356	2.428	2.643	2.765	2.912	3.026
52	.554	1.159	1.414	1.636	1.851	1.577	1.928	2.136		2.451	2.600	2.757	2.905	3.040	3.216	3.415	3.617
53	.982	1.236	1.557	1.844	2.092	1.637	2.011	2.271		2.722	2.514	3.150	3.332	3.450	3.649	3.894	4.096
54	.954	1.292	1.602	1.964	2.262	1.679		2.351	2.590	2.901	3.135	3.425	3.633	3.713	3.961	4.279	4.528
55	1.058	1.393	1.824	2.230	2.624	1.806	2.253	2.608		3.241	3.612	3.935	4.236	4.201	4.534	4.872	5.293
56	1.109	1.460	1.941	2.412	2.846	1.881	2.392	2.766	3.100	3.543	3.905	4.265	4.677	4.566	5.007	5.485	5.908
57	1.139	-955	2.060	2.588	3.059	1.930		2.903	3.258	3.798	4.172	4.702	5.211	4.882	5.427	6.029	6.578
58	1.215	1.597	1.978	2.379	2.751	2.161	2.719	3.081	3.381	3.849	4.133	4.607	4.927	5.716	6-142	6.526	6.891
59	1.265	1.676	2.150	2.621	3.042	2.260	2.870	3.282	3.575	4.186	4.582	5.113	5.498	6.165	7.019	7.615	8.319
60	1.268	1.729	2.275	2.800	3.287	2.357	2.941	3.446	3.851	4.470	4.871	5.462	6.072	6.528	7.566	8.750	9.833
61	1.346	1.806	2.407	3.012	3.532	2.391	3.070	3.615	4.121	4.769	5.270	5.983	6.623	6.932	8.200	9.797	11.652

TABLE IV
STRUCTURAL INFLUENCE-COEFFICIENT MEASUREMENTS - Continued

(b) Matrix [B]

Load	_					Panel d	eflection pe	r unit load,	meters/nev	ton, measur	ed at position	n:					
point -	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27
11	•046×10 <sup>-4</sup>	.c:7×10 <sup>-4</sup>	.071×10~	4 .010×10 <sup>-4</sup>	•C15X10 <sup>-4</sup>	.022×10 <sup>-4</sup>	.cz8×10 <sup>-4</sup>	.035×10 <sup>-4</sup>	.047×10-4	.059×10 <sup>-4</sup>	.067X10 <sup>-4</sup>	•071×10-4	• c15×10-4	.022×10 <sup>-4</sup>	.027×10 <sup>-4</sup>	•035×10 <sup>-4</sup>	•042×10 <sup>-4</sup>
12	•€64	.C & 9	.126	.010	.017	.026	.032	.044	•066	.094	.114	.126	•C22	.025	.031	.043	.056 .079
13	.C87	.138	.224	.012	.018	.029	.037	•059	•091	•143	-138	-214	.023	-027	.035	.054	•002
14	•006	•CC6	•006	0.000	.001	.003	•003	.003	.003	.005	.005	.005	0.000	.CO1	-001	.001	
15	.011	.C11	.011	0.000	.002	•006	.009	.009	.010	.010	.010	.010	•CC2	-004	.006 .009	.007 .010	.007 .010
16	.016	.C17	.018	•005	•006	•009	.011	•013	.014	.015	.016	•C17	-005	.006 .014	.017	.019	.021
17	•G26	•C27	•029	•005	.009	•013	.019	•022	•024	.026	.028	.028 .042	.C16	.017	.021	.023	.026
18	.035	•C 39	.050	•007	•C11		.023	.027	.033	.037	.041	.C75	.016	.019	.022	.027	.033
19	•046	.058	.075	.009	.014	.021	•026	.033	.043	-055	.065	.108	•C17	.021	.026	.034	.043
20	.059	.C83	.120	-009	-014	.023	.030	.039	.057	•078	•099	.141	.018	.021	.026	.037	.050
21	.070	.104	.159	.009 .006	.015 .010	.024 .018	.031 .024	.043 .034	.067	.100 .093	•126 •120	.135	.C13	.015	.019	.027	.040
22	.062	.057	.158 .013	•001	•002	.004	.006	.007	•112 •009	•009	.010	.010	003	001	.001	.C02	.003
	.012	.C13	.017	.001	•C03	.006	.009	.010	.012	.013	•014	.014	cci	.001	.004	•006	.006
24	.016	.C21	.022	.002	•005	.009	.013	.014	.015	.017	.018	.018	.002	.005	.007	.008	.009
25	•020	•G32	.027	.004	.007	.013	.017	.019	.021	.026	.029	.030	•CC6	.008	.010	.010	.011
26	•027 •037	.C46	•060	.005	.009	.015	.019	.023	.029	.038	•045	-048	.CC7	.010	.012	·C13	-014
28	.045	.C 61	.086	•003	•009	.016	.021	.027	.036	.051	.062	.067	.008	.011	.013	.C15	.018
29	.051	.677	-118	.005	•009	.017	.022 .	.029	.044	.066	.082	.092	.009	.011	.014	.017	.024
30	.C55	.C E5	.138	.003	803		.022	.030	.046	.073	.095	.106	.008	.011	.013	-017	.025
31	.054		.145	.C01	.CC7	.015	.021	.028	•046	.074	.097	.110	.C67	.010	.013	.C16	.024
32			+.017	.001					00B	009	010	010	•CC5	.003	.002	.001	.001
33			022						011	013	013	013	•CC2	0.000		0.000	0.000
34			039						014	019	022	C24	.GC1		0.000	•002	.002
35			065			010			021	030	038	042	CC1	001	0.000	.001	.001
			089			011		018	027	042	053	+.C50	CC2	002		002	CO8
			119			010		023	036	057	073	081	CC3	004			008
			143		007				042	067	087	C98	0C3	005		-•006	011
39	C55		156		007	013			041	070	094	106	CC4	004		003	009
	048		159	008	009				035	063	085	099	005	005			003
			052	.004	001		009	009	009	013	019	021	.CC7	.005	.008	.013	.018
		C43	065	.002	601	006	00B	009	011	020	026	C29	.CC7	.006	-010	·C14	.018
43	034	C49	079	.001	002	007	009	010	014	026	033	038	.CC5	.005	.009	.014	.017
44	C39	C59	098		C07	007			019	033	045	C50	.CC5	.005	•009	.C13	-014
45 .			119		003	CO8			~.023	042	057	065	-QC5	•006	.010	.014	.015
46 ;			130		002	010			027	048	065	C74	•GC3	-002	.005	-009	•009
47			149		005				028	054	075	C87	-0C2	•003	.009	•013	.013 .004
48			152						031		078	089	CC2		0.000	.004 .002	.001
49			163		005	013		022	035	063	086	097	CC3	005	002	.002	.021
50			109	•003	005	009			016	030	041	047	•CC2	-001	.005 .006	.014	.019
51			118	-001		008	012	013	018	035	048	054	.003 .002	.001 .001	.007	.016	.022
52	041		125	002		012	012	011	018	035	050	C60 C67	-002	001	.005	.C13	.019
53			136	.001					022	042	058	071	•GC2	001	•005	.014	.018
54			144	•002		010	013		024	045	063	071	.0C1	001	.005	.014	-017
55	047		154	-001	003	010	013	014	025	048	069	C86	cci	0.000	-008	.015	.019
			164	002		010		013	024	051	074	092	002	001	.004	.011	.014
57	055		175	-001		010			031	062	081	067	.063	-002	.011	.023	.030
58	045		151	•002		009	010	010	018	039	058	C72	.002	.002	.013	.023	.028
59			160		003	009	010	009	017	041	062	G78	.004	.002	.011	.021	.026
60			169			009	013	013	022	047	068	087	.0C3	.001	.010	.021	.033
61	052	C56	184	.001	004	010	014	014	025	053	076	1-1001		1			1

TABLE IV
STRUCTURAL INFLUENCE-COBFFICIENT MEASUREMENTS - Continued

(b) Matrix [B] - Continued

Load						Panel de	eflection per	unit load, n	neters/newt	on, measure	ed at position	n:					
point	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44
11	•058×10 <sup>-4</sup>	•061×10 <sup>-4</sup>	•064×10-4	•071×10-4	•026×10-4	•C30×10-4	•¢25×10 <sup>-4</sup>	•042×10-4	•051×10 <sup>-4</sup>	•064×10 <sup>-4</sup>	•070×10 <sup>-4</sup>	•077×10 <sup>-4</sup>	•075×10 <sup>-4</sup>	•039X10 <sup>-4</sup>	.051×10-4	•049×10 <sup>-4</sup>	•966×10
12 13	-078	•099	•109	•126	•028	•034	.034	.063	.074	-100	.119	-122	-128	.053	.064	.073	.087
14	•116	.158	.181	•212	•029	.048	-067	.083	-106	•161	.195	.216	-225	.076	•094	•111	-136
15	•002 •009	.002 .008	.003 .007	•004	001	•002 •003	•CC3	•005	003	•00Z	.001	010	•005	003	005	007	006
16	.012	.013	•013	.007 .014	•003 •006	.005	.C11	.003 .009	.003 .002	•009 •011	•006	•010	-004	•003	-005	•007	•006
17	.023	.025	.023	.026	•013	.019	.C15	.017	.015	.026	.014 .026	014 .017	.013	•005	-010	•008	.002 .009
18	.030	.034	.034	.038	.017	.016	.C21	.024	.019	.033	.036	.029	.018 .035	.016 .018	.017	-018	.019
19	.042	.052	.056	.061	.018	.021	.021	.027	.029	.042	.053	.047	.057	.019	.015	•023	.035
20	•059	.077	.085	.097	.019	.024	.C32	.038	.047	.069	.085	.07B	•094	.029	.021 .031	.026 .043	.044
21	•072	.095	.107	.124	.024	.033	.043	.043	.047	-085	.107	.117	.125	.031	.038	.050	.059
22	•062	.086	•098	.115	.011	.C19	.017	.038	.038	.076	.096	.099	.112	.017	.023	.033	.C46
23	.005	.005	.006	.007	004	003	-C03	002	.008	.003	.005	007	.008	002	004	005	03
24	•007	.009	.010	.010	002	001	0C3	.003	.009	.003	.010	.009	•009	003	003	002	C03 .012
25	.010	.011	.011	.012	.001	•003	C15	.005	.001	•005	.005	•006	.005	003	005	002	002
26	.014	•017	.018	.020	.003	•002	•CC2	-004	0.000	•011	.010	.013	.015	008	005	006	005
27	.019	•026	•029	.033	.004	•00B	001	.003	.003	.010	.019	.024	.022	010	011	006	007
28	•026	•035	.041	•047	.004	.006	-0C3	.005	-011	-019	•027	.032	.031	011	011	006	018
29	•035	•049	.057	.067	.004	.006	.009	•006	.021	•025	.037	•052	049	011	013	003	008
30	.038	.055	.065	•077	.003	CO1	.cce	.014	.010	-034	.050	.056	.054	022	018	003	.009
31 32	•038	•056	•066	.078	•002	003	•CC7	•009	.013	.035	•047	.053	.057	021	007	006	002
33	•001	.001	0.000	0.000	.010	.C10	-C10	.008	-015	.014	•009	-012	•009	.019	•022	•022	.016
34	•001			0.000	.008	-012	•C12	.015	.018	.015	.013	.015	.011	.026	•029	•027	•C27
35		001	003	005	-011	-012	•C18	.018	-021	•019	.017	•003	.011	.034	.039	.038	-040
36		008 022	012	015	.012	-016	-025	•021	.025	-016	.010	•015	.004	.045	.042	.047	.039
37		029	026	.025	-014	-017	•C19			.013	•009	•002	006	.045	.045	.045	.C45
38		038	037 047	044 057	.011	012 .012	.C18	.016	•018	•003	013		023	•042	.050	.040	.038
39		039		062	.013	-014	.009	.014 .017	.019 .015	C03 007	020	033	029	.046	•042	•043	-040
40		034		057	.012 .011	.029	.039	.018	.013		026	037	029	•045	.047	•040	. •032
41	.018	.017	.015	.015	.024	.030	.C:1	.045		001 054	003		020	.057	-048	•049	•032
42	.018		.011	.011	.026	.032	.C42	•050	.054	.037	•052 •055	•049 •030	.045 .046	.073 .078	.083	•074	.C89
43	.016	.012	.007	.006	.024	.C33	.C47	.054	•054	.051	•049	.063	.041	.079	.087	•086	•G84
44	.011		0.000	003	.026	.C37	.C40	.044	.050	•050	•045	.066	.038	.078	-083	-087	.C79
45		001	008	013	.028	.039	•G39	.055	.051	049	.044	.034	•029	.087	•088 •094	.084 .088	.095
46	•003		014	020	.035	.035	.C35	.046	.053	.041	.036	.035	.017	.085	.082	.089	.070
47	•003			030	.027	.034	•030	.043	.054	.040	.037	001	.007	.081	.089	.097	682.
48	005	018	027	034	.015	.022	•C23	.037	.044	.045	.013	.036	.003	.069	.078	.071	.061
49		022	033	041	.013	•015	•029	.043	.029	.029	.018	017	.017	.074	.073	.070	.085
50 51	.022	-017	.013	.010	.021	•035	.C35	.061	•057	.C78	.062	.095	.069	.091	.092	.124	.C87
51	.019	.013	.008	.005	•022	•023	.C42	.067	.057	.058	070	.037	•050	.085	.112	.132	.099
52	•021	.015	.007	•006	•024	•641	.C41	.075	.082	076	.056	.083	.039	.100	.110	.108	.C89
53	016	.008	.001	003	.021	.039	.C34	•053	•035	•069	•042	.085	.047	.096	.120	.122	.171
54	.015	•006	002	006	.022	.018	.C47	.059	.071	.078	.037	•052	.038	.092	.096	.102	.074
55 56	-013	•002	006	013	•023	.015	.C22	-044	•076	.077	.057	.008	.029	.104	-113	•110	-114
57		001	010	017	.025	•030	-044	.072	•069	.053	.042	.043	.053	.100	.113	.116	.119
5 8		005	014	021	.023	•033	.042	.057	.073	•C65	.056	.027	.018	.089	.099	.093	.125
59	•028	•020	.013	•009	.026	•C71	.C.E	•082	.089	•060	.081	.082	.063	-104	.130	.135	-105
60	.026	.020	•009	•005	.031	-054	•C58	•097	•102	.095	.086	.034	•048	•122	. 045	•137	.068
60 61	•025 •024	.015	•006	•002	•030	•043	•C\$8	•077	-087	•069	•076	•070	.065	.137	-145	-131	-067
~*	• 02-7	.013	-002	002	.031	•042	•C40	•106	•092	•095	.086	.087	-047	.147	.131	•137	.118

TABLE IV
STRUCTURAL INFLUENCE-COEFFICIENT MEASUREMENTS - Concluded

(b) Matrix [B] - Concluded

Load point	f	_				Panel d	eflection per	r unit load, 1	neters/newt	on, measure	d at position						
point	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61
11	.C 66×10-4	•066X10 <sup>-4</sup>	.C73×10 <sup>-4</sup>		.079X10 <sup>-4</sup>	•066×10-4	.070×10-4	.081×10-4	.073×10 <sup>-4</sup>	•083×10-4	•089×10 <sup>-4</sup>	CE3X10-4	.088×10 <sup>-4</sup>	.c79x10-4	-082×10 <sup>-4</sup>		.082×10-4
12	.161	.110	-122	.131	.140	.106	.122	.127	-135	•142	.138	-155	-163	.147	.149	•163	.163
13	-159	-184	-208	.229	. 244	- 240	.212	.223	.231	-251	• 260	.277	•282	. 254	•270	-284	• 295
14 15	.CC3	003	•002	.001 .005		002	•002			•002	.004 .005	.GC2	•002	001	.001	•00Z	•002
16	•610	.003 .006	.004 .009	•009	.003 .009	002 .005	002 .009	.002 .005	.008	•002 •005	0.000	•CC6	.002 .011	0.000	.001	001	003
17	.C22	.020	.023	.024	.021	•017	.017	.019	.025	.018	.018	.C18	.015	.0C2	.002 .016	001	-001
18	.C3G	.029	.029	.031	.031	.023	.020	.025	.024	•029	.C25	.C27	.031	.022	.022	.007	.014 .023
19	.C28	.037	.043	.051	.052	.045	.034	.038	.036	•036	.054	.C49	.042	.036	.039	.045	.031
20	.060		1.074	.083	.083	.055	.065	.069	.078	.079	.079	.C £ 7	.089	.070	.073	.084	.086
21	.CET	.089	.097	.107	.114	•063	.082	.082	.095	.097	.107	.112	.108	.C86	•097	.103	.108
22	.053	.075	.079	.094	.096	.046	.054	.069	.081	.081	.(79	-0:0	.104	.067	.074	.073	.087
23	001	C.000	•002	.CO5	.005	002	003			001	.C01	-064	•006	~.002	001	.001	.004
24	.CC2	•002	•002	-003	•002	004			002	.001	C03	.CC2	.004	~.003	001	007	.001
25	•CC3	001		0.000	-002	007		007		005		CC5	004		013	006	007
26		0.000	-001	•002	•002	010	013	013		011		CC7	005		013	012	G08
27	0.00	003	•003	-00B	.011	015									018	014	017
28	0.000	004	.013	-014	.020	018						002			019	015	010
29 30	.006	.015	.020 .030	-032	.034			005	.011	•006	.002 .020	.C20 .C23			003	002	005
30	•C24		.024	.038	.049 .044	011			0.000	.013	.017	.C23	-019 -031		0.000	•009	.021
31 32	.011 .015	.010 .020	.019	.020	.015	010 -030	021 .034	0.000 .034	013 .030	•013 •034	.C33	.011	.028	~.005 .038	.003 .040	•007	•021
33	.C21	.025	.026	.022	.024	•043	•047	.050	.048	•043	.043	.C43	.039	.054	.053	.037 .051	•042 •053
34	.C27	.035	.034	.033	.032	.054	.064	•062	.051	.057		.057	.054	.074	.074	.070	•077
35	.C40	.035	.035	.030	.031	.004	.072	.073	.062	.065	.065	.c.e	.057	.086	.086	.078	.084
36	.043	.029	.028	.024	.067	.067	.067	.062	.062	.063	.061	.C 37	.057	.097	.089	.083	.083
37	.021	.025	.017	.018	.014	-062	.066	.059	.069	.055		-C 50	.039	-086	.078	.067	.074
38	.C33	.018	-012	.007	.001	.060	.059	.058	.057	•047	.045	•C 25	.034	.079	.074	.070	.066
39	.027	.019	.011	.009	005	.061	.060	.054	.053	.052	.038	·C35	.030	.C79	.068	.057	056
40 41	-027	.022	.013	.005	002	. 056	.068	.065	.079	.041	.C39	•C46	.060	.079	.073	.019	.059
41	.C &1	.085	•083	.083	.078	•122	.134	.134	.139	.134	•143	-127	•123	.162	.157	.160	.162
42	.068	.083	-086	.OB1	.083	•126	.141	.136	.144	.137	•121	.124	-142	.167	•172	.166	.167
43	•C50	.OB7	•082	•080	.075	.127	140	.140	.132	.132	-130	.122	-129	•173	163	.163	.168
44	•CE7	.089	.083	•078	.081	-131	•136	.148	.140	•141	•137	-140	•136	•176	.179	.182	.171
45	-050	-081	-081	.070	•072	•135	.146	•141	-136	.136	.133 .123	-120	-132	•176	•171	.176	.172
46 47	.C81	•070	.074	•C62	-054	.131	•143	.142	-126	•126	.113	•118 •107	-117	.165	-167	.151	•151
48	.042	.076 .063	.070 .057	•059 •049	.056 .043	-130	•127 •124	.125	-125	.124	.113	.167	.105 .093	•165	-164	-144	-151
49	.071	.068	.049	.037	.041	•111 •111	.119	•122 •121	.085 .102	•113 •099	.C83	.CE6	.108	•130 •136	•132 •132	-141	•127
50	.C55	.102	.103	.103	.106	152	.179	.195	.176	.174	.160	.165	.167	•203	197	•142 •199	•113
51	.107	.111	.099	.108	.079	,155	.174	.156	.180	.162	.120	.148	.168	.213	195	.172	•203
52	.130	.108	.106	.098	.087	.155	.134	.195	.152	.155	.164	.157	.119	•213	.206	-210	.160 .194
53	.169	.103	.094	.095	.097	.163	.166	.180	.142	.163	.167	.156	.172	.204	.203	.189	.190
54	.059	.091	.099	.C95	.082	,150	.178	.178	.173	.173	.185	-146	.137	.199	.178	.174	.199
55	.1C6	.107	.095	.089	.085	.162	.175	.180	.151	.157	-141	-129	.109	.191	-181	-204	.193
56	.100	.094	-102	.087	.094	.154	.175	.163	.171	158	-152	.127	.110	.208	.191	.182	.197
51	.116	.112	.094	.085	.080	.162	.195	.170	.170	.170	-180	-128	.179	.193	-208	.195	.197
58	-151	.142	.123	.130	.142	.204	.221	.211	.213	-205	•181	.201	-194	.256	.246	. 264	.228
59	.149	.119	-121	.124	.101	.138	.232	.210	.209	.222	-204	-172	-176	-251	.225	.238	.226
60	-126	.134	-140	-123	.118	.201	.234	.213	.211	.202	.208	.163	-204	•274	-248	.239	.260
61	.165	-136	-140	-128	-104	-218	.267	.211	<b>∉208</b>	.229	-224	.211	.143	-264	.258	.286	-290

TABLE V

LONGITUDINAL AERODYNAMIC CHARACTERISTICS – INFLUENCE-COEFFICIENT METHOD

Characteristic	Flexible with mass	Flexible - massless	Rigid
$c_{\mathbf{L}_{oldsymbol{lpha}}}$	$\frac{\lfloor 1 \rfloor \lceil G \rceil \langle 1 \rangle}{s \left(1 + \frac{q}{W} \lfloor 1 \rfloor \lceil G \rceil \lceil \Theta \rceil \langle W \rangle \right)}$	[1][G]{1} s	1][s][A](1) s
C <sub>ma</sub>	$\frac{1}{s\bar{c}} \left( \left\lfloor 1 \right\rfloor \left[ X \right] \left[ G \right] \left\{ 1 \right\} - \frac{q \left\lfloor 1 \right\rfloor \left[ X \right] \left[ G \right] \left\{ W \right\} \left\lfloor 1 \right\rfloor \left[ G \right] \left\{ 1 \right\} \right)}{\left( W + q \left\lfloor 1 \right\rfloor \left[ G \right] \left\{ W \right\} \right)} \right)$	$\frac{[1][x][G]\{1\}}{s\bar{c}}$	[1][X][S][A]{1} sc
C <sub>L,o</sub>	$\frac{\left[1\right]\left[G\right]\left(\alpha_{0}\right)}{s\left(1+\frac{q}{W}\left[1\right]\left[G\right]\left(W\right)\right)}$	$\frac{\lfloor 1 \rfloor \lceil G \rceil \langle \alpha_{o} \rangle}{s}$	$\frac{\lfloor 1 \rfloor \lceil S \rceil \lceil A \rceil \left\langle \alpha_0 \right\rangle}{S}$
C <sub>m,o</sub>	$\frac{1}{S\overline{c}}\left( \begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\frac{\text{[1][X][G]}\{\alpha_0\}}{S\overline{c}}$	$\frac{[1][x][s][A]\langle \alpha_0\rangle}{s\bar{c}}$
${f c_{L_q}}$	$\frac{\left[1\right]\left[G\right]\left(x\right)}{sv\left(1+\frac{q}{w}\left[1\right]\left[G\right]\left(\theta\right)\left(w\right)\right)}$	<u>[1][G]{x}</u> sv	[1][s][A]{x} sv
C <sub>mq</sub>	$\frac{1}{S\bar{c}V}\left( \begin{array}{cccccccccccccccccccccccccccccccccccc$	[1][x][G]{x} sēv	ll[x][s][A]{x} sēv
	where $[G] = [S][A]([1] - q[\Theta][S][A]$	)-1	

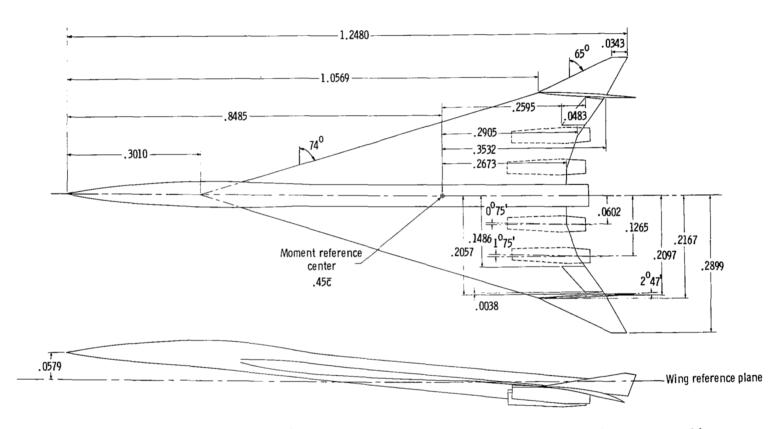


Figure 1.- Details of models. (All linear dimensions are in meters unless otherwise noted.)

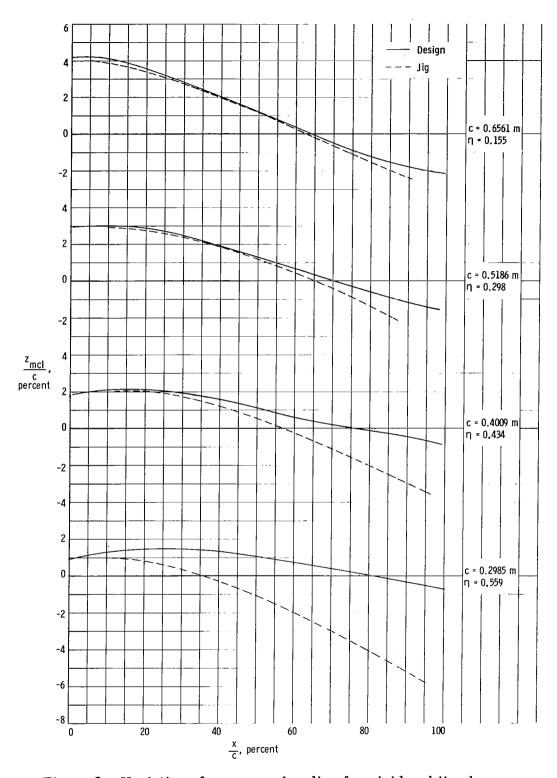


Figure 2.- Variation of mean-camber line for rigid and jig shapes.

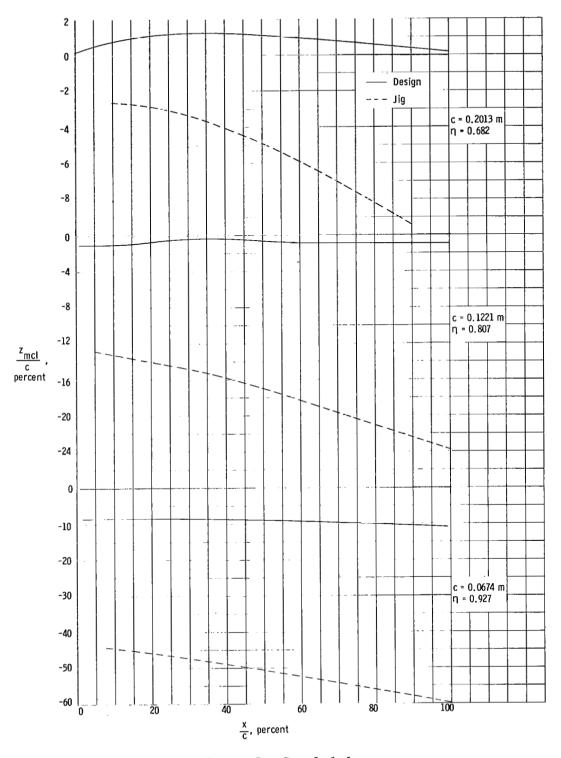
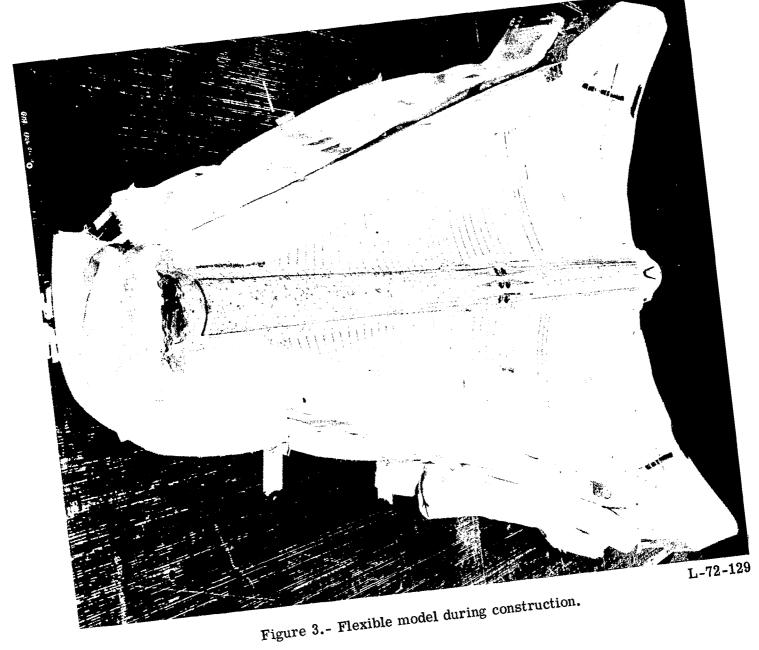


Figure 2.- Concluded.



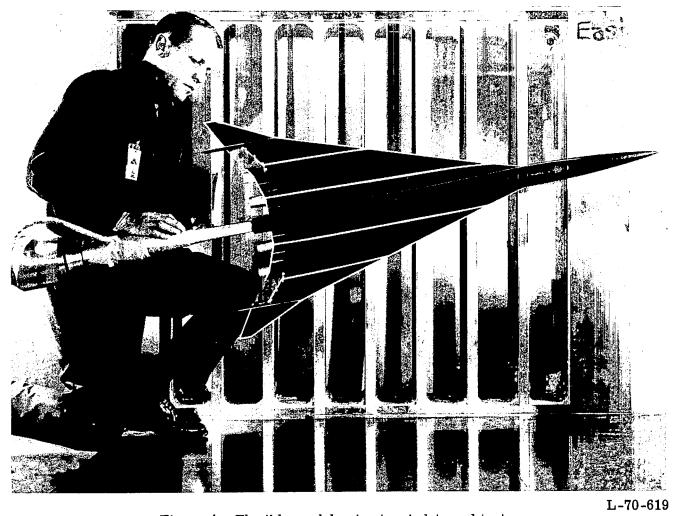


Figure 4.- Flexible model prior to wind-tunnel test.

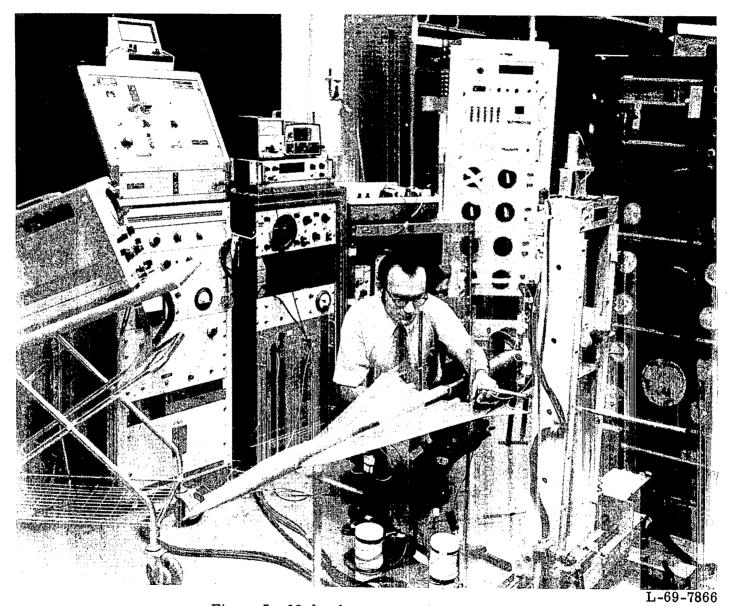


Figure 5.- Mode-shape measuring apparatus.

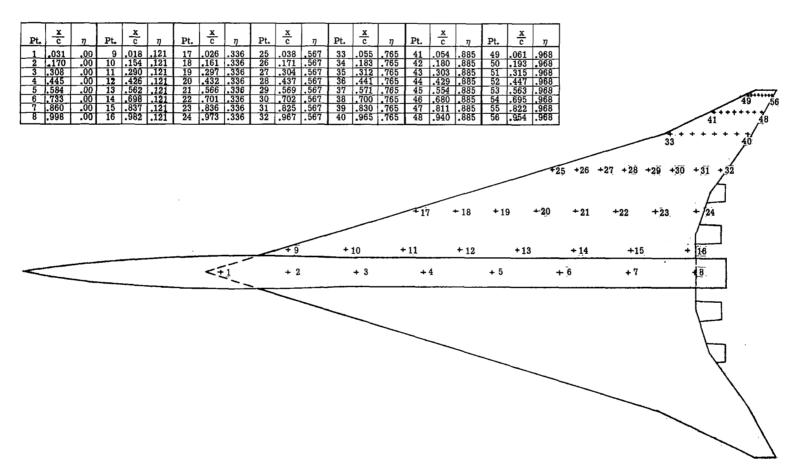
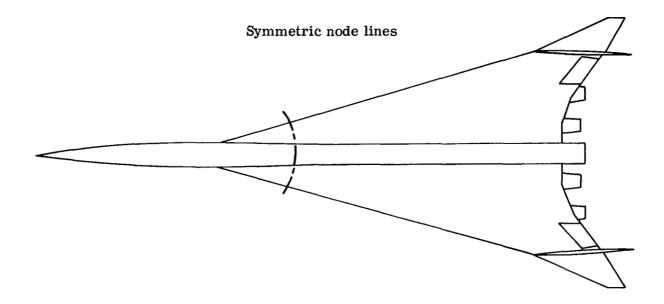
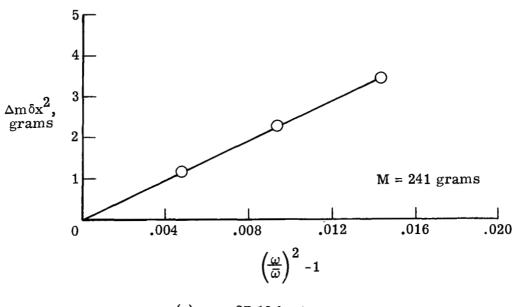


Figure 6.- Model control points for vibration test.



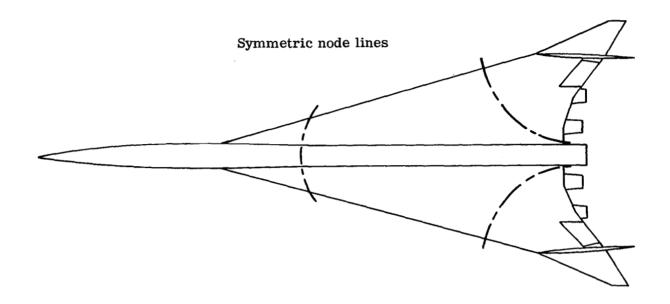
1

### Generalized mass



(a)  $\omega = 27.19 \text{ hertz.}$ 

Figure 7.- Determination of generalized mass and node lines of flexible model.



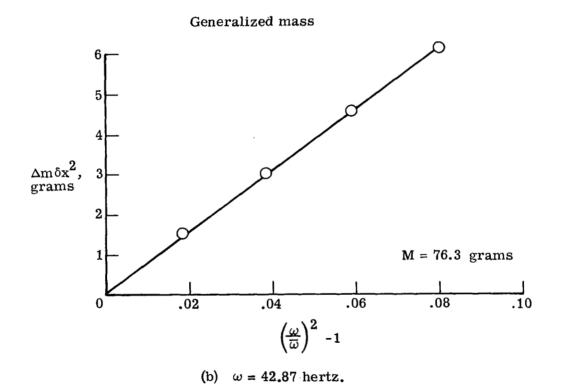
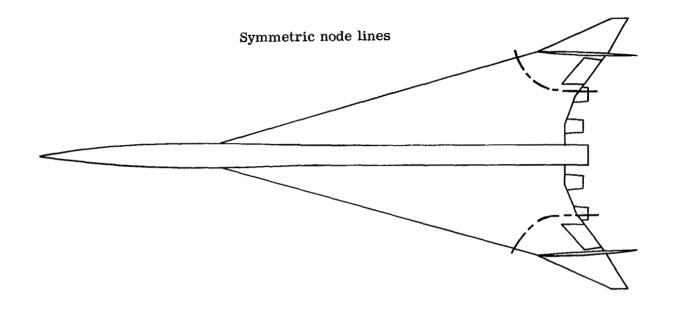


Figure 7.- Continued.



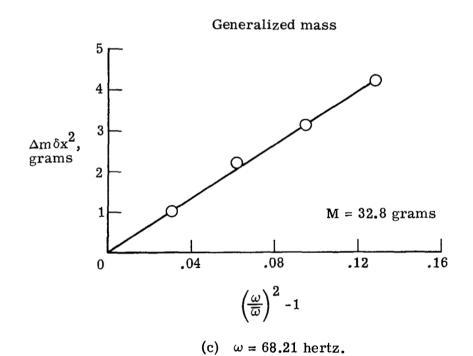
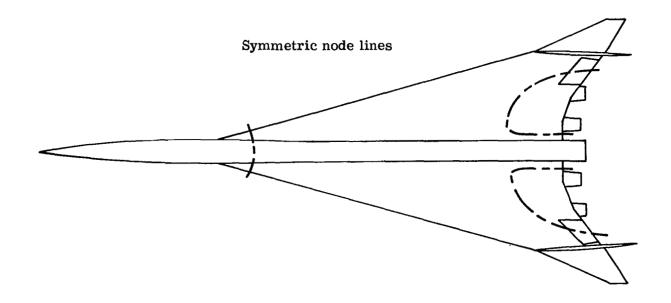
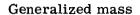
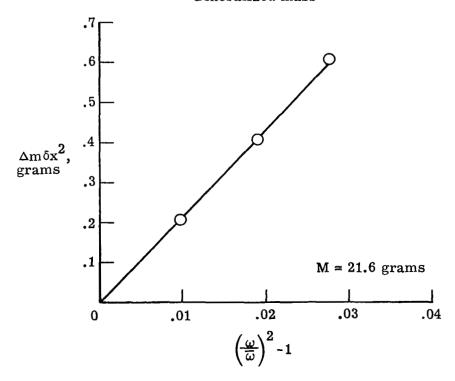


Figure 7.- Continued.

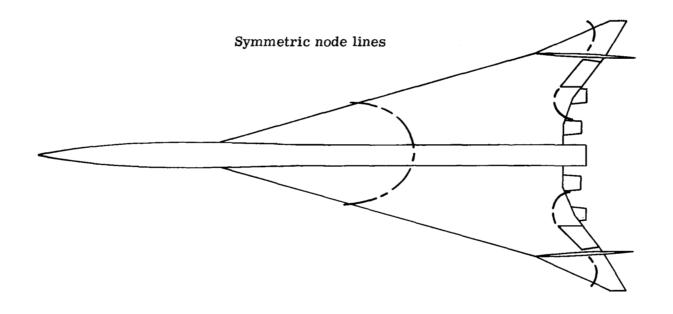




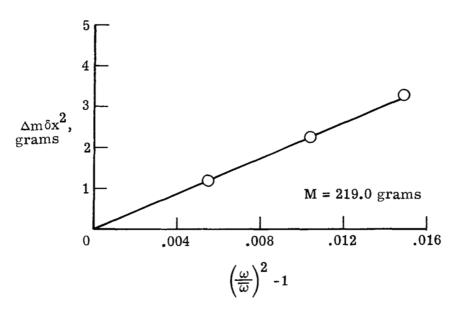


(d)  $\omega = 103.09 \text{ hertz.}$ 

Figure 7.- Continued.



### Generalized mass



(e)  $\omega = 148.65 \text{ hertz.}$ 

Figure 7.- Concluded.

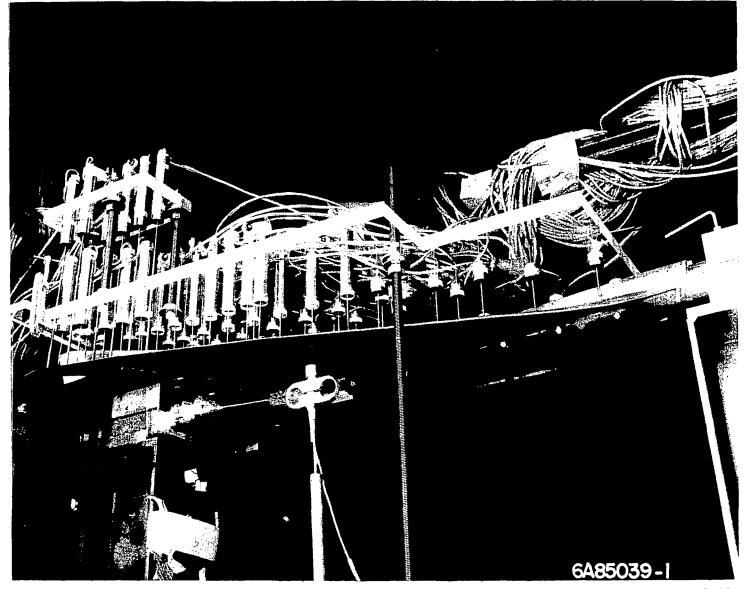


Figure 8.- Test setup for measuring structural influence coefficients.

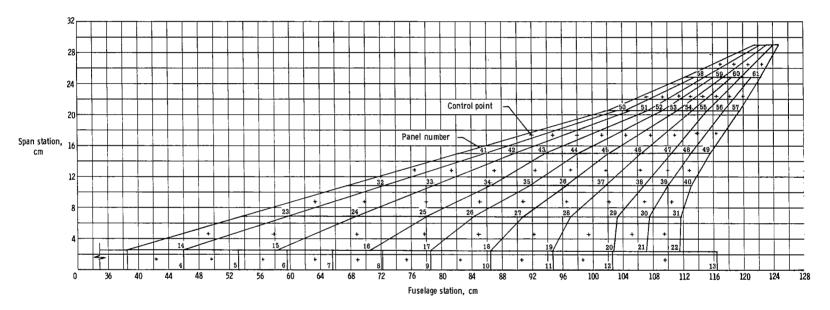


Figure 9.- Control-point location and paneling scheme for influence-coefficient analysis.

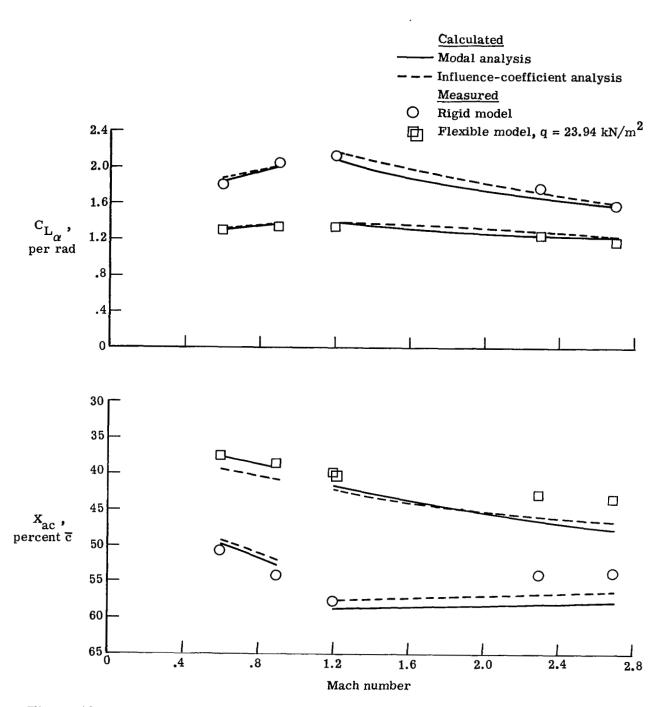


Figure 10.- Variation of lift-curve slope and aerodynamic center with Mach number.

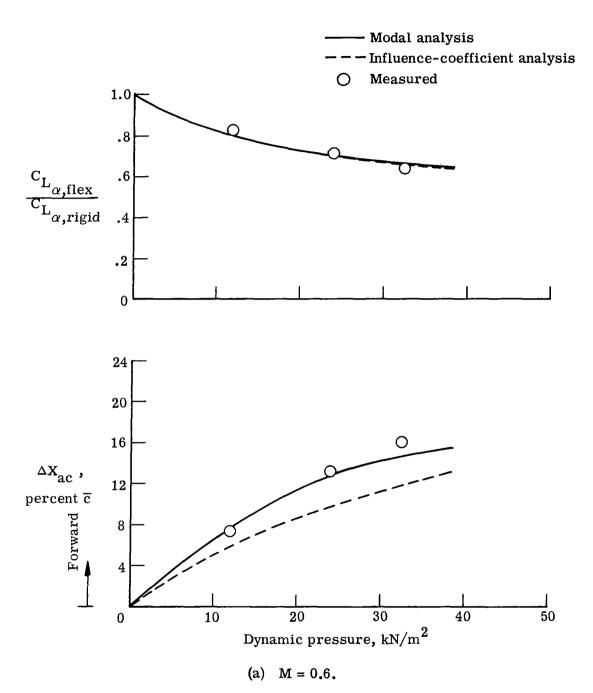


Figure 11.- Effect of dynamic pressure on measured and calculated flexible-to-rigid  ${\rm C_L}_\alpha$  and aerodynamic-center movement.

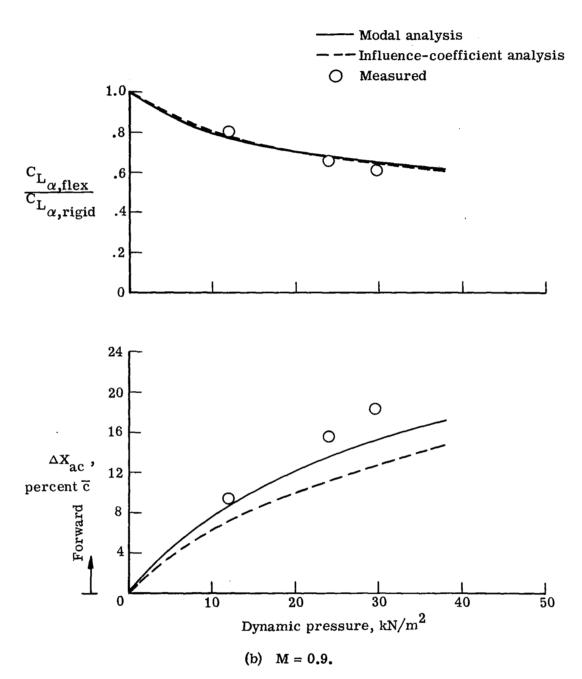


Figure 11.- Continued.

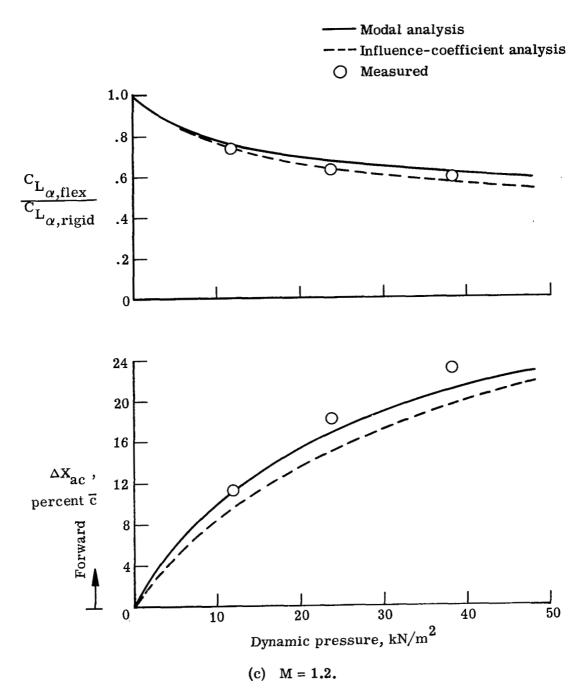


Figure 11.- Continued.

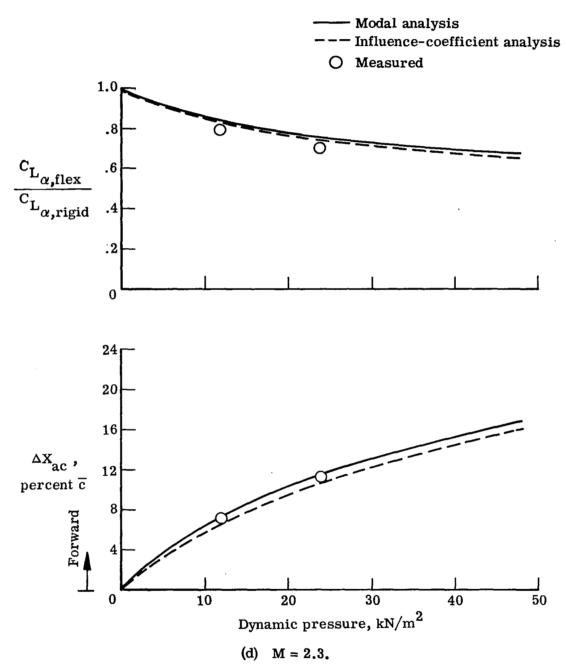


Figure 11.- Continued.

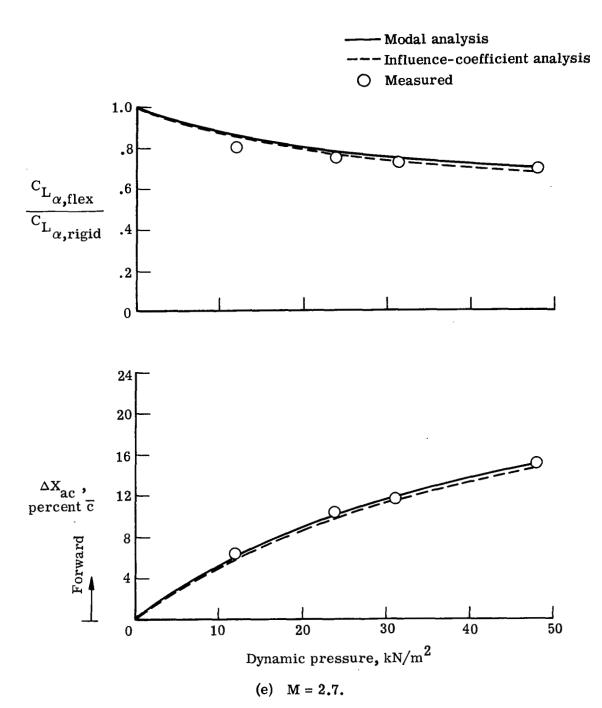


Figure 11.- Concluded.

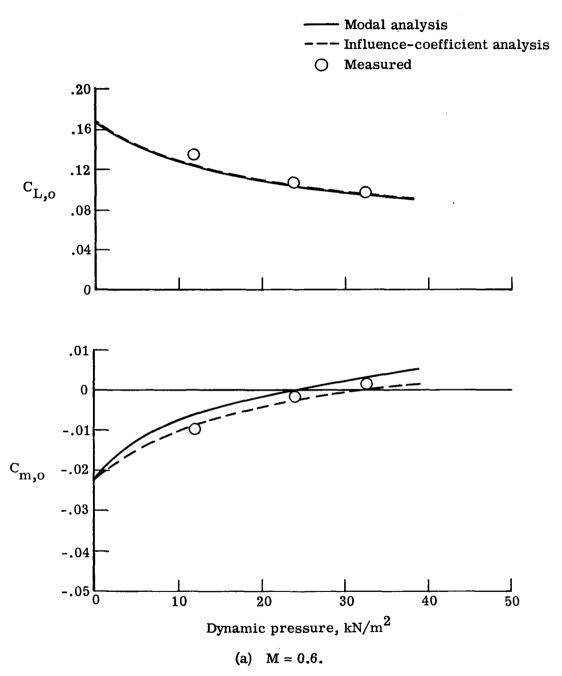
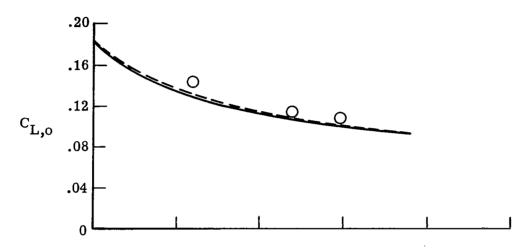


Figure 12.- Effect of dynamic pressure on measured and calculated  $C_{L,o}$  and  $C_{m,o}$ .

# Modal analysis- - Influence-coefficient analysisMeasured



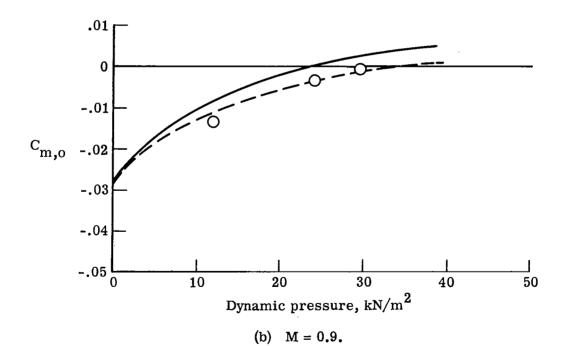
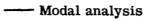
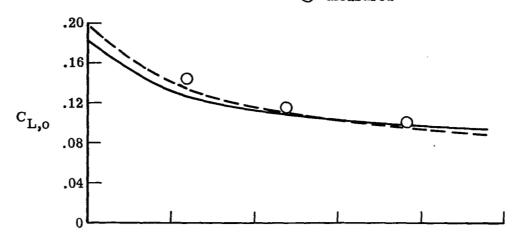
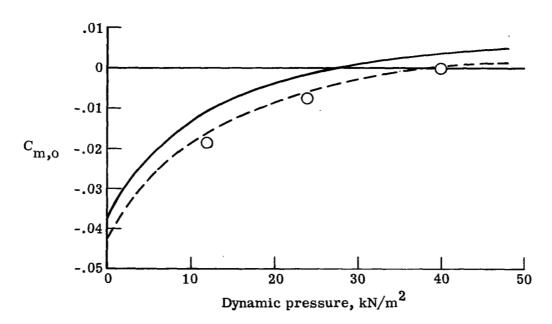


Figure 12.- Continued.



- --- Influence-coefficient analysis
  - O Measured



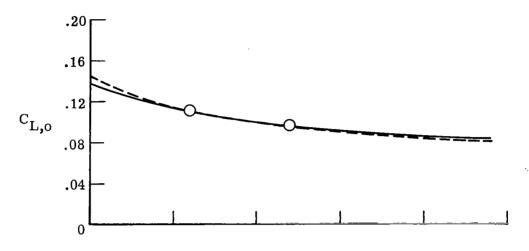


(c) M = 1.2.

Figure 12.- Continued.

### — Modal analysis

- --- Influence-coefficient analysis
  - O Measured



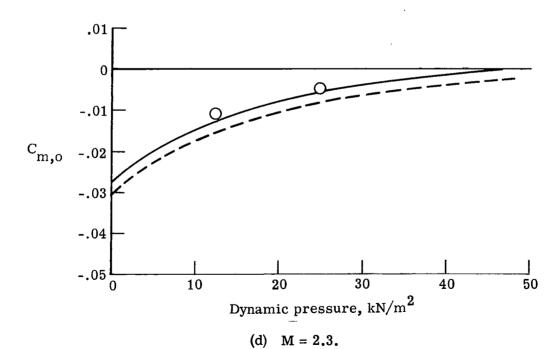
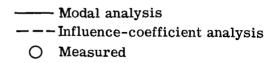
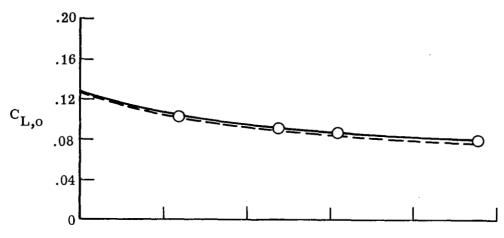
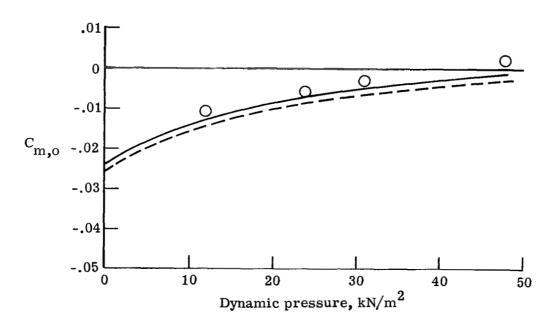


Figure 12.- Continued.



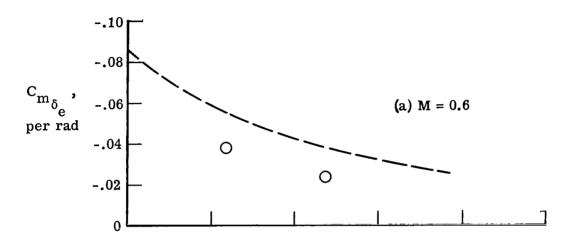




(e) M = 2.7.

Figure 12.- Concluded.

# Influence-coefficient analysisMeasured



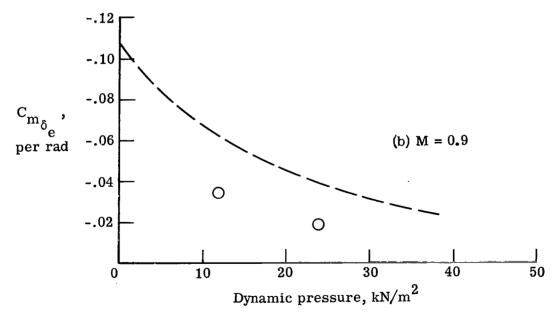


Figure 13.- Effect of dynamic pressure on pitch-control effectiveness.

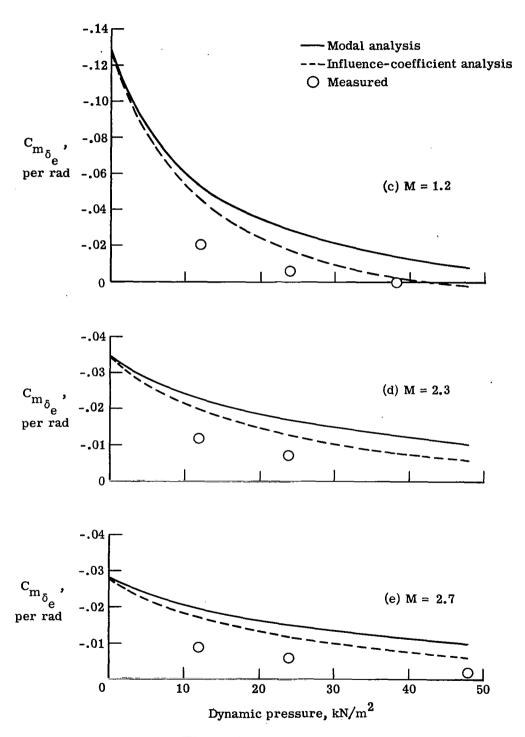


Figure 13.- Concluded.

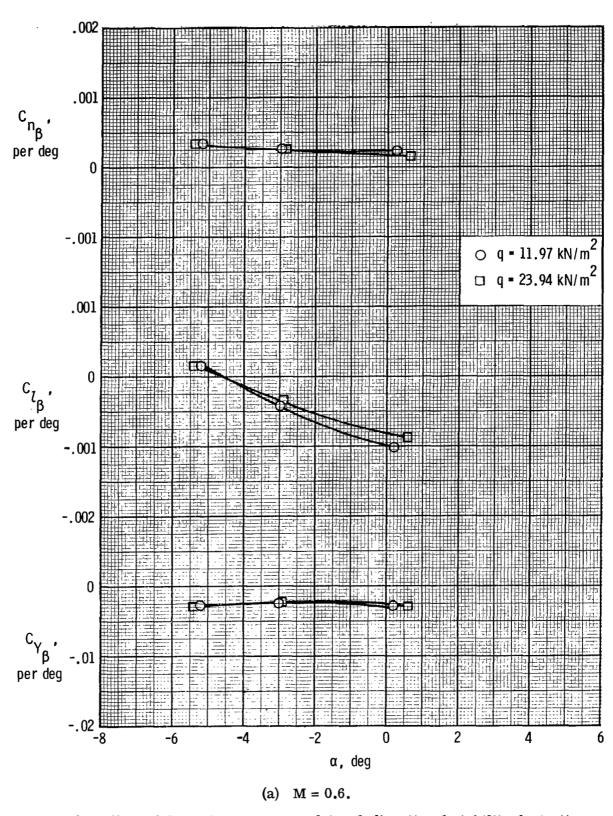


Figure 14.- Effect of dynamic pressure on lateral-directional stability derivatives.

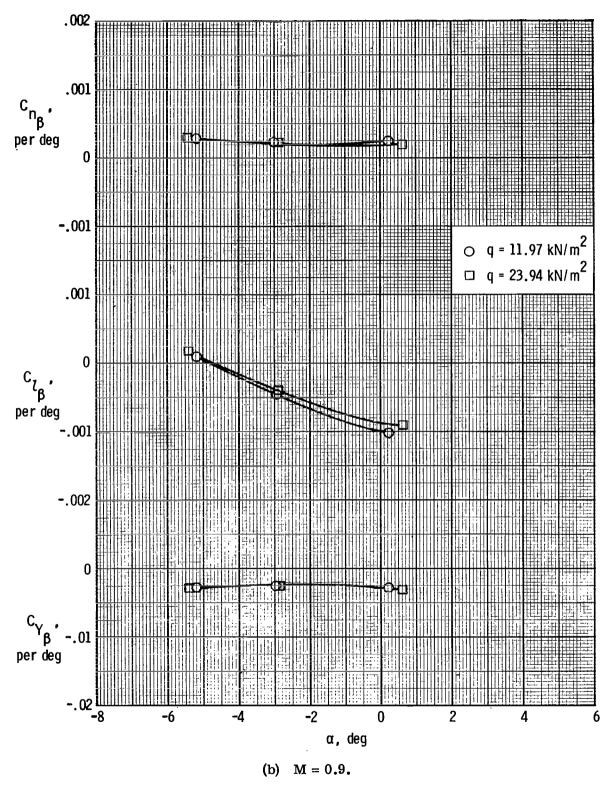


Figure 14.- Continued.

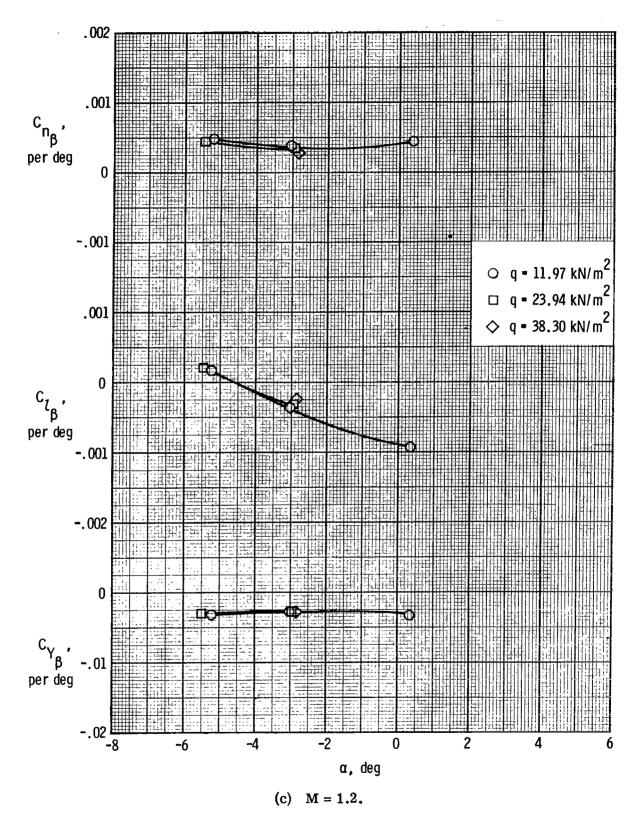


Figure 14.- Continued.

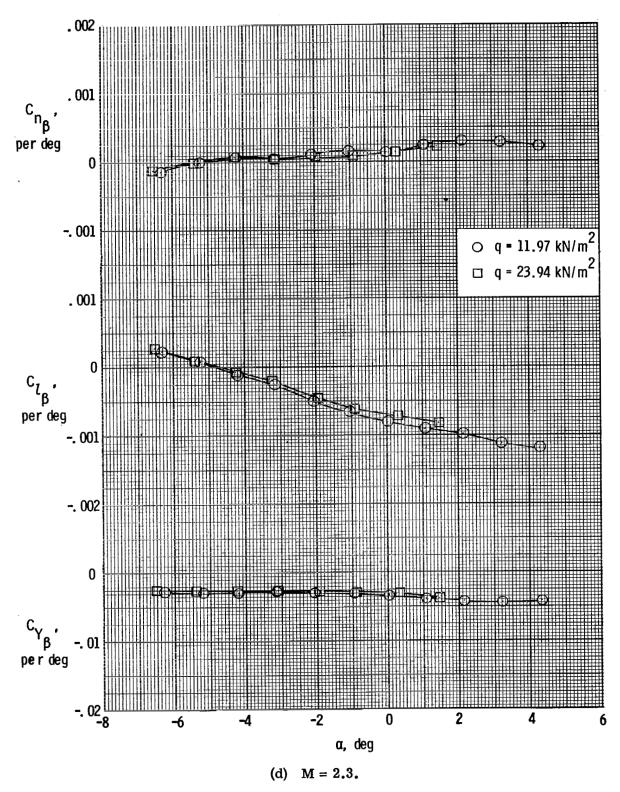


Figure 14.- Continued.

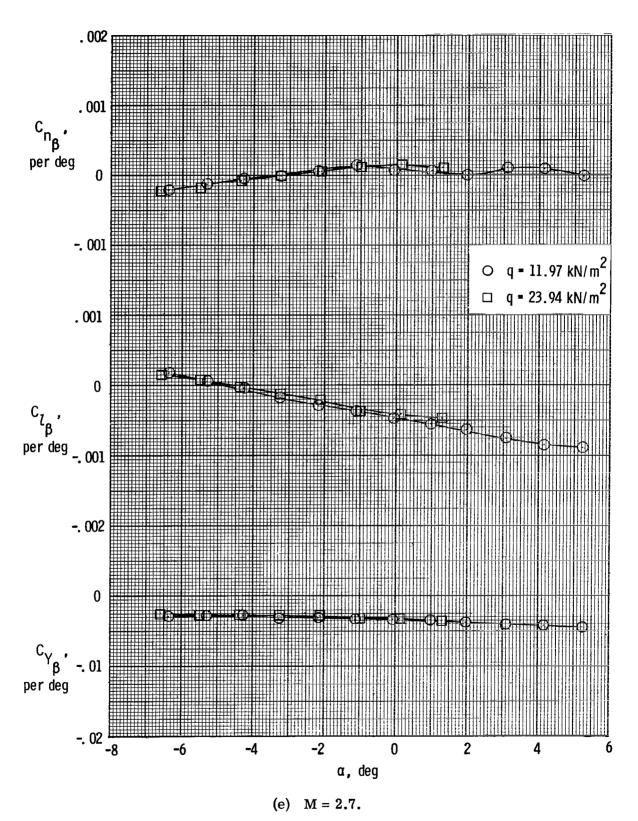
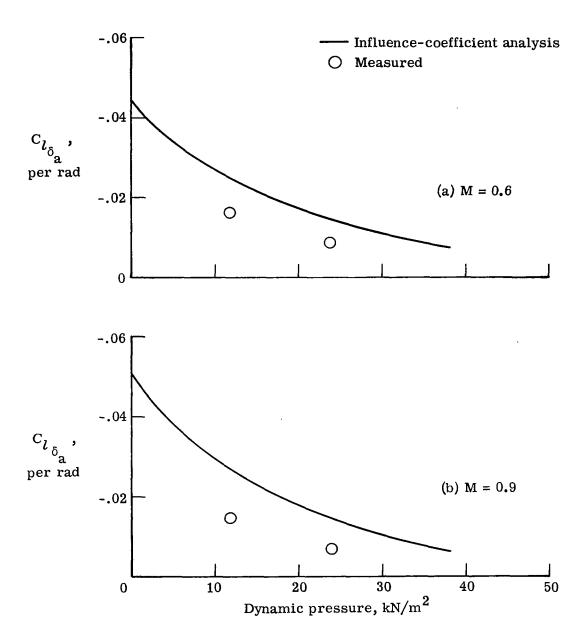


Figure 14.- Concluded.



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Figure 15.- Effect of dynamic pressure on control-surface effectiveness in roll.

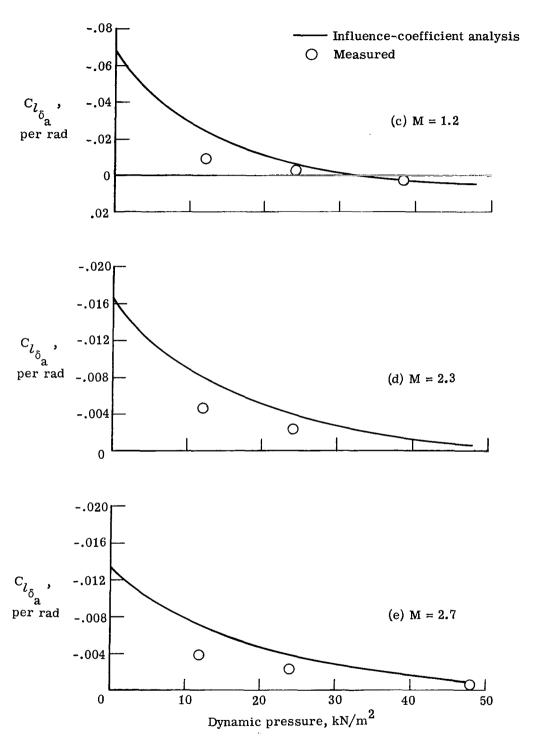


Figure 15.- Concluded.

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