

Developing digital fieldwork technologies at the British Geological Survey

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Abstract: Geological Surveys are faced with budget constraints and calls for efficiency gains; the effective application of digital techniques is often seen as a route to meeting these demands while increasing the value of outcrop studies and reducing the inherent subsurface uncertainty. The British Geological Survey may be the oldest national Survey in the world (established in 1835), however developing and implementing new, innovative and efficient technologies for fieldwork is a high priority. Efficient tools for capturing, integrating, manipulating and disseminating outcrop data and information are imperative to enable geoscientists to increase their understanding of geological processes and therefore to reduce subsurface uncertainty and risk. Systems for capturing structured digital field data and for visualising and interacting with large datasets are increasingly being utilised by geoscientists in the UK and internationally. Augmented reality and unmanned aerial vehicles are amongst the developing technologies being explored for future operational implementation. This paper describes the digital field mapping (BGS-SIGMAmobile) and visualisation (GeoVisionary) systems and refers to a case study outlining their contribution to reducing uncertainty and risk in hydrocarbon exploration.

Introduction

Geological Surveys including the British Geological Survey (BGS) have primarily utilised conventional analogue mapping techniques until relatively recently. Analogue field techniques had changed little since the original days of fieldwork by pioneers such as William Smith who created the geological map of Britain in 1815. Smith documented his field records in a notebook and marked symbols and linework on paper fieldslips in much the same way as mapping geologists did until very recently. The continuing prevalence of paper techniques was highlighted as recently as 2007-when the fourth edition of “Basic Geological Mapping” (Barnes & Lisle 2007) listed the field equipment that a geologist should possess, and described in detail the type of field notebook that is recommended i.e. “it should have good quality ‘rain-proof’ paper, a strong hard cover and good binding” whilst “at least three pencils are needed”. There is no mention of digital field mapping techniques or the prospect of their introduction in the future, although current educators are trying to address this (e.g. England et al. 2010; Pavlis et al 2010). BGS has endeavoured to develop and apply technological solutions to geoscience data and visualisation challenges; systems such as BGS-SIGMAmobile and GeoVisionary are providing solutions to geoscientists for data acquisition, field mapping, and data visualisation.

Developing a Digital Field System

Digital field mapping has been an aim of Geological Surveys for many years (Brodaric 1997; De Donatis & Bruciatelli 2006; Farrant et al. 2001). The concept is that the process of acquiring digital data in the field would have several benefits including increased efficiency

47 for capturing, manipulating, integrating, understanding and disseminating field and outcrop
48 data. Specific gains should include i) ensuring obligatory data collection – guaranteeing that
49 vital data (e.g. location information such as map grid reference) is collected either manually,
50 or automatically from a GPS; ii) standardised recording – making sure that the same sets of
51 data are collected by each member of a field team at each outcrop; iii) using standardized
52 nomenclature e.g. making use of drop-down menus where appropriate so that field teams
53 are constrained to standard dictionaries such as the “Munsell Color” chart for recording
54 colour; iv) enabling inter-operability with other data e.g. structure data collected in the field
55 can be used on-the-fly to create structure contours; v) the system should allow access to
56 ‘prior information’ that results in ‘smarter mapping’ e.g. aerial / satellite imagery, existing
57 geological fieldslips, geophysics data etc. (Jordan *et al* 2005).

58
59 Furthermore, rather than simply replicating the tasks that can be completed with the
60 analogue pen/paper/map routine, the digital system must offer additional functionality.
61 Examples of this include the ability to enter a dip/strike measurement and to automatically
62 create structure contours using an underlying DTM, or to provide the facility to compile all
63 of the field data collected (text, measurements, photos etc.) into an MS Word report.
64 Crucially, the field system must provide an efficiency gain. Time may not necessarily be
65 saved at the outcrop, however transferring validated digital field data directly to corporate
66 databases allows more time for manipulation and modelling rather than transposing /
67 digitizing, which takes resources at the office and can also potentially lead to errors.

68
69 In 2001, BGS published the user requirements for digital field data collection (Farrant
70 2001). The specifications document outlined in broad terms what the system should collect
71 for each mapping terrain. The main objective was to develop an integrated system that
72 would not only collect point structural geological data, but would also collect the full range
73 of data required by a Geological Survey including Quaternary geology, landform
74 descriptions, landslide pro formas, photographs etc. The system should be constrained by
75 dropdown menus or tick boxes where appropriate to save time, but must also provide the
76 functionality to draw sketches and write ‘free text’ so that the process of field mapping
77 would not be constrained or that some data could not be collected or that mapping became a
78 ‘box ticking’ exercise rather than a meaningful scientific endeavour. Ultimately, it was vital
79 that the system was developed with significant input from field geoscientists, who are the
80 end users.

81
82 BGS first explored the concept of digital field data collection in 1989, with the conclusion
83 that the mobile computing hardware at that time was not suitable. The development was
84 therefore postponed. External reviews of BGS such as Walton and Lee (2001)
85 recommended revisiting the prospect of digital field mapping and in the same year an
86 international workshop on digital field data capture was hosted by BGS in the knowledge
87 that other organisations such as the Geological Survey of Canada had also begun to explore
88 digital field mapping (Brodaric, 1997). North American and European Geological Surveys
89 attended and presented the status of mapping systems, if they existed, in their countries.
90 Similarly, software and hardware suppliers were invited to demonstrate their products. At
91 that time, the available systems were capable of limited point data capture using Personal
92 Digital Assistants (PDAs) and as this was not sufficient for BGS geoscientists, the
93 organisation set about designing and developing a bespoke system (Jordan, 2009).

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In 2001 BGS started testing Husky *flex21* hardware with the PocketGIS® software primarily for a granite and landscape mapping project in the Cairngorm Mountains of Scotland (Thomas *et al* 2004). Challenges with the hardware (primarily related to the battery life and screen quality) resulted in a move to PDAs operating Windows CE™ in the same year. A customized version of ESRI ArcPad™ served as the front end, whilst a bespoke BGS eMbedded Visual Basic (eVB) application containing hard-coded data structure links in a compact database format was used to collect and hold additional relational data that would otherwise have been stored in the geoscientists notebook. Hierarchical input forms were constructed to collect various levels of data; index level data were added for each field site and an “Open Notebook” button gained access to more detailed forms for various mapping modules. At the time, similar systems were in development in the U.S. (Pavlis and Little, 2001). The small screen size of the PDA (approx 6 x 8 cm) was sufficient to display a small map area along with the user’s position, which was derived from a Global Positioning System (GPS) grid reference that was served via a Bluetooth device. The field staff were equipped with a ‘digital toolbox’ containing the PDA, a Bluetooth GPS, a digital camera and various accessories.

Whilst this was a significant advance from a paper field system, the screen size was a major limiting factor. While it was arguably sufficient for point sample collection, feedback from the majority of field geologists stated that it was not suitable for geoscientists working with maps. The screen was too small to visualize enough of the mapface to gain spatial context, and furthermore, annotating the visible area of the maps with lines, polygons and text proved problematic because scrolling beyond the current view was required to delineate even the smallest of landscape features. Furthermore, each release of new PDA hardware (BGS was primarily using the Hewlett Packard iPAQ platform) brought Open CE updates which often required time-consuming modifications to the eVB code. Clegg *et al* (2006) came to the same conclusion when comparing tablet PC and PDA hardware, stating that the tablet devices were more suitable for a wide range of geological data collection tasks when using their “MAP IT” software. Nevertheless, some organisations adopted the small screen size devices and still like them for their ease of portability (Pavlis *pers comm*, 2015).

Fortuitously, by 2002, the first rugged tablet PCs entered the market, and while the early incarnations were too expensive to equip field teams and often too heavy to carry for long periods (>2.5kg), they provided a solution to both the screen size and the operating system issues. BGS began experimenting with, and developing software for, tablet PCs in the expectation that the hardware would become more widely available, more affordable and more fit-for-purpose. By 2004 the software was migrated to a ruggedised tablet PC system operating on Microsoft XP for Tablet Edition. Training courses for staff in this new ‘BGS·SIGMAmobile’ (System for Integrated Geoscience Mapping) began in 2005 (Fig. 1). At this time, a similar digital field system (GeoMap) was also being developed in the U.S. on tablet PCs based on the Strata Software’s PenMap (Birmhall *et al* 2002).

BGS·SIGMAmobile is a heavily customized version of ESRI ArcMap as the front-end with relational data held in a bespoke MSAccess2007 database. Additional functionality is provided by linking modified versions of InkWriter (software that enables handwriting recognition). Software development of BGS·SIGMAmobile system was done using a

141 variety of languages including VBA and .NET. With each new release of ESRI software,
142 BGS has also updated the field system and it currently operates with ArcMap10.1.

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144 BGS·SIGMAmobile is an integrated field system that enables a broad array of geoscientific
145 data to be recorded using tick boxes, sketches, drop-down lists, tagged free text, and
146 photographs where appropriate (Fig. 2). Spatial location and navigation is managed by
147 built-in GPS whilst the stylus enables points, lines, polygons, and comments to be added to
148 the digital map face. As with the preceding PDA system, additional relational information
149 is added using customized forms and a selection of interfaces. The system is modular, with
150 tabs for various themes or domains of geological data such as structural readings, landslides
151 information and auger/section recording etc. Furthermore, there are additional tools
152 including the ability to draw sketches, annotate photographs, produce structure contours,
153 and navigate using bearings. All of the data collected in BGS·SIGMAmobile are tagged
154 with a Unique User Identifier (UUID) enabling them to be queried and tracked through
155 corporate repositories.

156

157 It has been proposed that the preference in geological mapping is to interpret observations
158 during the mapping process (Jones *et al.* 2004; McCaffrey *et al.* 2005) however
159 BGS·SIGMAmobile primarily records observations, separate from interpretations, in order
160 to improve traceability in the derived outputs and to separate, where possible, observed data
161 with interpreted information. It is expected that this increases confidence in the data and
162 therefore reduces the uncertainty of the derived maps and models.

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164 A choice of tools for adding text, lines, and polygons to the map face is provided, ranging
165 from a basic tool that replicates the pencil and paper routine through to tools that enable
166 topologies and attributed lines to be created in the field. Advanced handwriting software is
167 used extensively to deliver legible field notes (even on the map face), however cursive text
168 can still be used for rough notes where appropriate. Drop-down menus and tick boxes are
169 used where possible and efficient to ensure that entries conform to accepted standards and
170 that the agreed nomenclature is used. Areas for free-form text are also provided to allow
171 flexibility. Novel systems have been developed and employed to ensure that the data
172 recorded is unambiguous; e.g., rather than asking a geologist to tick a box to note if they are
173 using the right hand rule when recording a structural measurement, a compass is provided
174 which is ticked to identify the dip direction. This reduces confusion regarding how the data
175 were recorded.

176

177 The tablet PC hardware was a challenge for the early releases of the system, e.g. weight,
178 screen visibility in bright light and shorter-than-advertised battery life. However technology
179 has advanced and platforms now exist that are generally suitable for use in the field by
180 geoscientists. Following trials with a SunscreenPC in 2001, the favoured hardware was the
181 Itronix GoBook and, subsequently, the GoBook DuoTouch followed by the Xplore iX104
182 series, the GETAC V100 and currently the Panasonic ToughPad. Pavlis *et al.* (2010) record
183 a similar history of equipment trials. Non-rugged systems are also available, such as the
184 Microsoft SurfacePro. In general the non-rugged systems are lighter and cheaper, but their
185 screens are not as readable in variable light conditions, and they are more prone to every-
186 day wear-and-tear and fatal damage from water/dust ingress and from drops and knocks.
187 There are a range of ruggedness ratings e.g. IP54 or IP67, so there is a choice to make

188 between the level of hardware resilience required and the cost the organisation is willing to
189 pay. There is an option to use a non-rugged system and to use a weather-proof case.

190

191 While BGS·SIGMAmobile was originally designed purely as a data collection tool, a
192 significant part of its power and functionality comes from the ability to bring a wide range
193 of data (e.g. satellite imagery, aerial photography, geophysical data, historic field slips and
194 topographic maps) to the field. This has also been recognized elsewhere e.g. Carver et al
195 (1995) when a Geographic Information System (GIS) was used in the field. This improved
196 access to data and information in the field significantly increases the knowledge-based
197 decisions of the geologists, leading to reduced uncertainty in the data collected and the
198 information derived from it.

199

200 Aside from bedrock and Quaternary geologists, the ability to record features such as
201 landslides, dimension stone information and mine information has broadened the user base
202 significantly (Evans *et al* 2013; Jordan 2010¹; Jordan & Pennington 2011).

203

204 In 2009 BGS·SIGMAmobile was released at no cost to both academic and commercial
205 users, downloadable from the BGS website. The premise for free distribution was to
206 promote its use and to encourage the growth of a developer community. The only
207 stipulation prior to download is that new developments must be supplied to BGS for
208 inclusion in subsequent free releases. This free release has led to the use of the system for
209 teaching in university departments (e.g. England *et al* 2010) and also by other Geological
210 Surveys (e.g. Henderson & Guilio 2011). Over 2000 licenses have been downloaded
211 worldwide. The system also gained recognition when it won the 2007 ESRI Central
212 Government GIS Excellence Innovation Award.

213

214 The BGS·SIGMAmobile system was the sole component in the first two releases,
215 however the version released in 2013 integrated the BGS·SIGMAdesktop functionality
216 that had previously not been released outside BGS. This provides tools for routine
217 transformation of field data into corporate standard geological models and derivative map
218 outputs. Development of the system is still ongoing as a result of both user feedback and
219 the changing face of technology. Investigations into the development of a BGS·SIGMA
220 smartphone app are currently taking place alongside system developments such as a new
221 and more streamlined data entry system.

222

223 **UAV field data collection**

224 A growing area of interest internationally is the capability of collecting geoscience field
225 data using Unmanned Aerial Vehicles (UAVs), also called Unmanned Aerial Systems
226 (UAS) or Remotely Piloted Aerial Systems (RPAS). It is argued here that UAVs can be
227 considered as field data acquisition systems because the equipment can be taken to a field
228 site in a standard vehicle (or in a rucksack, depending on the system) and generally
229 operated by a geologist, with suitable safety and regulatory training. In this respect it is no
230 different from routine geoscience instruments such as terrestrial laser scanning, and in fact
231 the latest UAV systems incorporate laser scanning technology.

232

233 UAVs, in the form of parafoils have been used in BGS since 1986, and in the last ten years
234 these have been added to with kites, fixed wing and rotary systems (Hobbs *et al.* 2010).

235 The use of ground control and differential GPS ensures that calibrated and validated
236 outputs can be delivered including orthorectified aerial photography, point clouds,
237 triangular irregular network (TIN) models and gridded elevation models. Desktop software
238 using structure from motion (sfm) technology has put stereo aerial photography processing
239 and DEM extraction in the hands of the masses. Elevation / motion and volume changes
240 can be calculated e.g. for landslides, and BGS is now routinely using UAV technology to
241 acquire multi-temporal data over landforms such as landslides (Fig. 3). RGB cameras are
242 now the ‘elder statesman’ of sensor systems on UAVs while multispectral and thermal
243 cameras are becoming ubiquitous. Miniaturized sensors such as laser scanners, gas
244 monitors and geophysical equipment are breaking into the commercial market and their
245 systematic use will significantly expand the data collection opportunities available in the
246 field at this scale.

247

248 **Developing a Virtual Field Reconnaissance System**

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250 The BGS Virtual Field Reconnaissance (VFR) project was developed to allow geologists
251 to immerse themselves in a virtual landscape providing the ability to ‘bring the field into
252 the office’. Teams gather in an immersive virtual environment and discuss complex field
253 outcrops, followed by fieldwork focused on addressing specific issues that have arisen in
254 the office.

255

256 The initial challenge set for the VFR project was to build on existing project-based virtual
257 field trip and geoscience visualisation applications, that had been created by BGS during
258 and after the Digital Geoscience Spatial Model programme from 2000 to 2004 (Riddick *et*
259 *al* 2005), and to create systematic efficiency gains in fieldwork. Primarily, this would be
260 achieved through use of newly acquired national high resolution datasets, such as the
261 Nextmap Great Britain 5m Digital Surface Model and 5m Digital Terrain Model, and
262 aerial photography, along with the wealth of digital geological data held by the BGS. A
263 Virtualis Activewall single channel active stereo visualisation system, known in BGS as the
264 immersive 3 Dimensional Visualisation Facility (i3DVF) is used by teams while the
265 system can also be used by individuals on their PCs (or a suitably equipped laptop) to
266 ensure that virtual fieldwork is available to all BGS geoscientists.

267

268 In a review of existing software with 3D visualisation capability such as ESRI, Google and
269 NASA, or 3D geological modelling software like GOCAD and GSI3D, BGS staff decided
270 that no single software package could meet the user requirement for a BGS VFR system.
271 Essential elements of the user requirement that could not all be addressed by any one of
272 those software packages included handling the volume of data and graphics output on PC
273 workstations, ease of use, use in the i3DVF, interaction with the virtual landscape and
274 integration with BGS·SIGMA. BGS’s solution was to work with Virtualis Ltd who adapted
275 their engineering model visualisation software to work with geoscience datasets and allow
276 the user to interact with them to the VFR specification. The initial pilot version was judged
277 a success so the project was continued, and since 2007 BGS and Virtualis Ltd have worked
278 together to create commercially available software for visualisation and interpretation of
279 large geospatial datasets from multiple sources. That software, GeoVisionary, which was
280 first released in July 2008, allows users to visualise terabytes of surface and subsurface
281 data in high powered immersive 3D visualisation systems, as well as on desktop PC’s and

282 laptop workstations.

283

284 GeoVisionary provides tools for digitising points, poly lines and polygons which allow the
285 user to map geological features limited only by the resolution of the terrain model and
286 imagery. Lighting angles can be changed to help identify features from the virtual terrain.
287 Structural measurements from oriented planes can be drawn in three dimensions,
288 calculated from three points picked from the terrain model. The user can compare the
289 existing geological interpretation of an area with that gained from the virtual environment
290 and decide whether or not they agree with that interpretation and therefore make better
291 decisions on where to target field work. All of the data collected in GeoVisionary can be
292 saved as ESRI 3D shapefiles for use in GIS and 3D modelling software.

293

294 BGS created custom software for ESRI ArcMap, the Arc2GV Toolbar, which links
295 GeoVisionary on the i3DVF PC and BGS·SIGMA on a tablet PC. Location data, sent
296 wirelessly from GeoVisionary, is used by BGS·SIGMA to match the 2D GIS view with the
297 virtual landscape. The data collected in the virtual field environment is immediately
298 transferred to the BGS·SIGMA device with the Arc2GV Toolbar and can be taken directly
299 to the field. On return from fieldwork, the Arc2GV link is restored and the newly collected
300 data from the field can be visualised and interpreted in the i3DVF. Using virtual reality,
301 fieldwork and GIS together in this way, has been shown to bring better quality results from
302 time spent in the field, increase the accuracy of interpretation and help build better team
303 understanding, communication and confidence (Ford *et al*, 2013). A degree of computer
304 literacy is required by the users of the system, and it is strongly advised to back-up one's
305 work in case of equipment failure or loss.

306

307 Virtualis have developed a streaming data engine, fully utilizing the latest graphics card
308 technology from nVidia that has helped to overcome one of the biggest technological
309 problems in geoscience visualisation: how to smoothly visualize huge data volumes of
310 multiple resolution data in a convincing virtual reality environment. It goes a long way
311 towards answering many of the problems with multi-scale geoscience model visualisation
312 identified by Jones *et al* (2008). In 2012 visualisation of LiDAR point cloud data and
313 volumetric (voxel) models was added to the GeoVisionary functionality list. The volume
314 and density of terrestrial LiDAR has rapidly increased in recent years. In response, the
315 point cloud capability was increased in 2014, enabling visualisation and interpretation
316 (measuring, digitizing, structural measurement) of billions of points, simultaneously with
317 all of the other data in a single GeoVisionary project (Fig. 4).

318

319 **Case Studies**

320

321 Published case studies describe the use of the BGS digital systems for field mapping in
322 terrains such as the UK (Evans *et al* 2013 and Leslie *et al* 2014) Ghana, Madagascar and
323 the United Arab Emirates (¹Jordan 2010), Norway (Henderson and Guilio, 2011) and
324 petroleum exploration in Tajikistan (Jordan *et al* 2009). These studies have highlighted
325 how the systems have been applied to various BGS mapping projects and also by
326 geologists from other organisations. Experience from the case studies has demonstrated
327 that time at the outcrop is often limited (due primarily to cost) and it is desirable to derive
328 the most value from fieldwork e.g. by (i) having as much appropriate ancillary data to

329 hand as possible to promote more informed decision-making in the field, (ii) ensuring that
330 geologists collect the full suite of mandatory data at each outcrop, (iii) standardising the
331 nomenclature that is used, (iv) providing on-the-fly functionality such as deriving
332 structure contours. All of these factors contribute significantly to reducing uncertainty in
333 the decisions made at the outcrop. The BGS studies also highlight that a well-documented
334 workflow is a prerequisite in order to ensure that i) adequate preparation of data prior to
335 fieldwork, because it is often not possible to have data sent to the field area if it has been
336 forgotten, ii) staff fully trained in the use of the systems, iii) protocols for data transfer,
337 manipulation and long-term management / storage.

338

339 It has also been demonstrated that the large amount of data now available to geologists
340 using digital techniques in the field, along with the capacity to collect new structured
341 digital data, makes the “field mapping process much more efficient and increases the
342 reliability and repeatability of collected data” (Pavlis *et al* 2010).

343

344 The case studies above emphasize the impact that new technologies have made to
345 geological mapping, and how they have contributed to reducing uncertainty. The
346 Tajikistan case study (Jordan *et al* 2009) specifically relates to outcrop studies for
347 petroleum exploration undertaken by Tethys Petroleum and BGS when a Production
348 Sharing Contract (PSC) was signed and a short timescale was available to start
349 exploration drilling in the 40,000 square kilometer Bokhtar area. GeoVisionary was used
350 to compile a 3D model using existing conventional oil company data in the area,
351 consisting of mainly elderly Soviet era geological maps, well logs and very sparse
352 dubious seismic, all on paper. Tethys had 18 months for the initial phase of geological
353 studies, seismic acquisition and reprocessing, and field rehabilitation trials, with
354 exploration drilling in the second 18 month phase and a first relinquishment after 7 years.
355 Remote sensing data were acquired and analysed in order to study the large remote area
356 efficiently. They were used to plan field geology and seismic acquisition in order to
357 complete the first phase of the exploration programme on time. A model was built in
358 GeoVisionary from Landsat images, SRTM and DTM data, and loaded into the 3D
359 visualisation facility for stereo viewing by the team of BGS and Tethys geologists. The
360 geological and structural model was further improved using higher spatial and spectral
361 resolution ASTER satellite imagery. Cross sections were prepared and seismic and well
362 logs incorporated where appropriate.

363

364 A reconnaissance field trip assessed the quality of this remote work and identified areas of
365 specific interest for the remainder of the exploration work programme. As part of the
366 reconnaissance, seismic lines were planned and the routing was checked in the field using
367 BGS•SIGMAmobile. Outcrops encountered in the field were recorded in the digital
368 system, and information from them was fed back into the 3D model. The combination of
369 the pre-field 3D visualisation and the digital field data allowed Tethys to conduct their
370 exploration on schedule and to plan the seismic campaign with confidence (Jordan *et al*
371 2009).

372

373 It is fitting to re-evaluate the Tajikistan case study in light of new technologies and to
374 consider what might be done differently now. Firstly, UAV technology was not widely
375 available in 2008 and therefore they were not incorporated into the project. The

376 technology is readily available today to collect a suite of site-specific high resolution data
377 including stereo aerial photography, thermal, hyperspectral, geophysical and LiDAR data.
378 The field tablet PCs have reduced in weight and increased in processing and graphics
379 power, so not only can they be used to collect data, but those data can be visualised at
380 the outcrop using augmented reality such as iGeology 3D
381 (<http://www.bgs.ac.uk/igeology/3d.html>). 3D visualisation systems, such as GeoVisionary
382 are now able to incorporate a wider range of datasets such as 3D point clouds and multi-
383 scalar DTMs, enabling the geologist to add more detail to the mapping and further reduce
384 the outcrop uncertainty. It is debatable whether the digital field mapping systems have
385 encountered a step-change in technology since 2008, however the user interfaces are more
386 streamlined, the systems are more stable (hardware and software), and the protocols to
387 prepare and manage the data are more complete. The range of visualisation and digital
388 mapping systems now on the market is testament to their increased integration into
389 routine mapping.

390
391

392 **Discussion & Conclusions**

393 The strategy for most Geological Surveys (including BGS) has been to develop and
394 implement digital systems that increase our understanding of the subsurface and to move
395 from printing paper geological maps to delivering focused outputs such as 3D and 4D
396 models. Validated digital field data capture provides a streamlined route for populating
397 corporate databases, from which an array of outputs can be delivered including
398 paper/digital maps, 3D models and smartphone applications.

399

400 The culture of geoscience field mapping has changed in Geological Surveys, and the
401 introduction of digital field systems has had a large input to this (Jordan *et al* 2008). It is
402 generally accepted that field mapping in Geological Surveys encompasses, and benefits
403 greatly from, digital techniques (Leslie *et al.* 2014; McCaffrey *et al.* 2005) and students are
404 also benefiting from structured digital techniques (England *et al.* 2010 and Pavlis *et al.*
405 2010). Systems developed in BGS are helping to integrate and collect complex digital data
406 in the field and subsequently to transfer those data immediately and efficiently to corporate
407 databases thereby making them instantaneously available for downstream uses such as 3D
408 modelling (Henderson & Guilio 2011).

409

410 Visualisation systems are also bringing field sites into the office and ensuring best use of
411 geologists' time through virtual field reconnaissance prior to and post fieldwork. Time
412 spent waiting for computers to load / transfer spatial data for geographic areas of interest
413 has been reduced; GeoVisionary has advanced geoscience visualisation technology by
414 placing large volumes of data at the hands of the user in near real time. Resources are freed
415 to focus on visualizing and interpreting huge volumes of raster and vector data in a single
416 environment rather than transferring them from archives or servers to visualize in separate
417 software systems in i3DVF or on desktop PC workstations.

418

419 Digital data collection and visualisation has also been put into the hands of the public e.g.
420 through smartphone applications such as *myVolcano* and *iGeology*
421 (<http://www.bgs.ac.uk/igeology/>). Furthermore, the *iGeology* 3D application is an
422 augmented reality system that projects 3D geology onto the smart phone screen, overlaid

423 onto the landscape via the camera on the device. This new level of interaction with the data
424 is currently used to promote geoscience to the public but can equally be used by
425 professionals as an additional knowledge tool to decrease uncertainty at the outcrop.

426

427 The breadth of digital tools being made available to field geoscientists by a wide range of
428 providers internationally is significant; for example ten years ago there were few integrated
429 digital geological capture systems that had the functionality of point data recording and
430 polygon mapping tools with an underlying relational database. Some of the credit for the
431 arrival of digital mapping systems goes to the timely delivery to market of the rugged
432 tablet PC; however the availability of the hardware is more than balanced by the foresight
433 of those who developed software in the expectation that these types of hardware would
434 become available.

435

436 Modern Geological Surveys also routinely utilize systems such as UAVs, although the
437 differing levels of sensor use is still stark e.g. the contrast between a basic digital camera
438 and a laser scanner. These systems are now delivering truly valuable data and their use is
439 predicted to proliferate, although care must be taken to ensure that the systems are
440 operated safely and that the results are calibrated and validated. Looking to the future,
441 there is scope to further streamline the input systems; voice recognition is still under-used
442 and the day will come when geoscientists will be able to verbally describe the outcrop and
443 a digital system will tag the words and automatically populate the database, symbolize a
444 map, and deliver the data back to base where it can be used instantaneously.

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447

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456 **References**

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579 **Figure captions**

580

581 **Fig. 1.** (a) Digital field mapping training course and (b) digital field mapping in the
582 United Arab Emirates.

583

584 **Fig. 2.** Sample Graphical User Interface to BGS·SIGMAmobile (a) ArcMap front end.
585 (b) Top level forms for structured data capture. (c) Sub-form for collecting bedrock
586 structural data. NEXTMap Britain elevation data from Intermap Technologies.

587

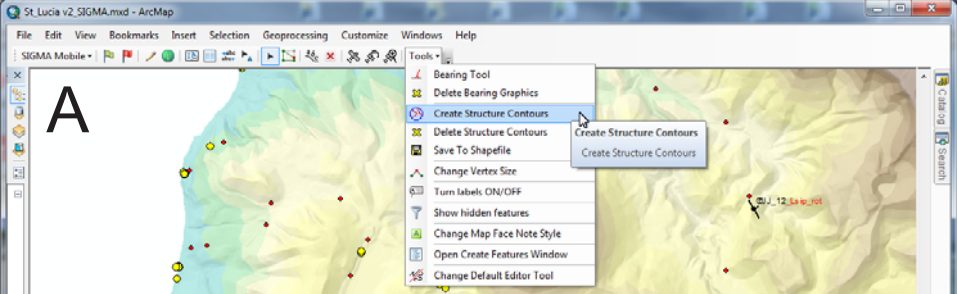
588 **Fig. 3.** Outputs derived from BGS UAV photography (a) Point cloud. (b) Textured
589 DEM derived. (c) 3D model of coastal landslide in 2013. (d) 3D model of same coastal
590 landslide in 2014.

591

592 **Fig. 4.** A terrestrial LiDAR scan of a cliff, consisting of more than 300 million points.
593 The red and green and cubes show where a point has been selected for digitisation as a
594 poly-line. At the top of the image, distance, incline and bearing are shown as readings
595 from the GeoVisionary Terrain Measuring Tool.

596

A**B**



Microsoft Access - DFDC : Database (Access 2002 - 2003 file format)

SIGMA Mobile Geodatabase 2012 v1.02

FOP Entry Form Locality No **CJJ_12** FOP **Close**

Locality Desc and Summary Label Project Scale Field Slip Geologist Info Housekeeping Management Fields Summary Label on Map

Locality Desc: **Ridge crest** Summary Label on Map: **Lsip_rot**

Easting: **-61.029** Northing: **13.845**

Make Quick Observations

MAKE A QUICK COMMENT Repeat Last Comment made PHOTO SHAFT ADIT SINK EXPOS

Make Detailed Observations

MAKE STRUCTURAL OBSERVATION MAKE KARST OBSERVATIONS

DESCRIBE A SIMPLE LOG/SECTION DESCRIBE A LOG/SECTION (FULL)

MAKE SUPERFICIAL LANDFORM OBS MAKE MAHMADE LANDFORM OBS

DESCRIBE A LANDSLIDE

Make General Comments. Describe Samples, Sketches, Photos

COMMENTS SKETCHES PHOTOS SAMPLES PRECIS

Field Tools: Show Observation Selector, Photo Transfer, Word Field Report

Desktop Tools: Show Outputs

Form View Num Lock

B

Structural Observations

STRUCTURAL OBSERVATIONS FOR **CJJ_12** Delete HIDE: 0 Hide Close Form

Measurement **Strata_Inclined_1** Strike Dip Mtd Measured

Younging Evidence **Cross-Stratification** Way Up: **Normal** DipDir Dip-Azimuth Dip

Press buttons for available types. Press Icon Buttons to Create a new reading

Bedding(SO) Foliation Axial Pln. Fold Axis Fault Igneous Lineation YoFac/Verg Mini Vein

060 / 06

Enter Strike, Dip + Dip Dir (blue) or Azimuth and Dip Directly (white)

Bedding Measurements (BM): for Normal Way Up Strata

Inclined Normal Horizontal Normal Vertical Normal General Dip

BM for Overtuned Strata **BM for Strata Way Up Unknown**

Inclined Overtun Horizontal Overtun Inclined Unknown Horizontal Unknown

BM for Underground Strata **BM for Specialised Strata**

Inclined Under General Dip Under Cross Bedding Geopetal

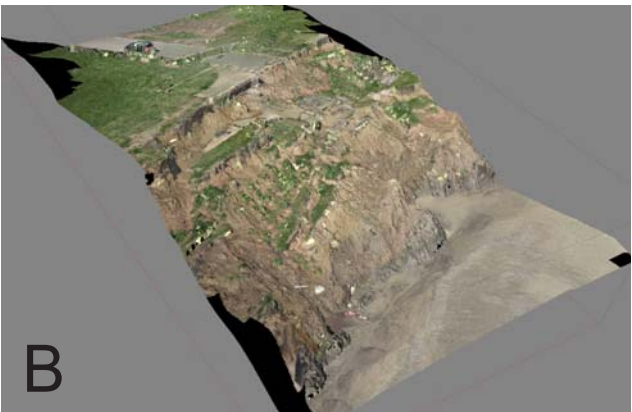
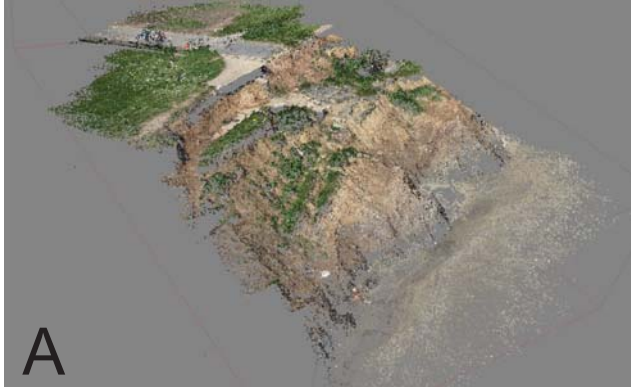
General Structure Comment

Notes on Entry

Notes on structural entry measurements will appear in this box for guidance

Record: 4 of 1 of 1 No Filter Search

C





7.20

7.24

Terrain Distance : 0.947, Distance : 0.947, Map Distance : 0.677, Incline : 89.306, Bearing : 8.604

348930.34 88831.57
50.708 -2.728
6.42 8.52
-29.35 4.93 0.60

