# Estimation and Testing for Partially Nonstationary Vector Autoregressive Models with GARCH: WLS versus QMLE * 

Chor-yiu SIN<br>Department of Economics Hong Kong Baptist University, Hong Kong

June 4, 2004


#### Abstract

Macroeconomic or financial data are often modelled with cointegration and GARCH. Noticeable examples include those studies of price discovery, in which stock prices of the same underlying asset are cointegrated and they exhibit multivariate GARCH. Modifying the asymptotic theories developed in Li, Ling and Wong (2001) and Sin and Ling (2004), this paper proposes a WLS (weighted least squares) for the parameters of an ECM (error-correction model). Apart from its computational simplicity, by construction, the consistency of WLS is insensitive to possible mis-specification in conditional variance. Further, asymmetrically distributed deflated error is allowed, at the expense of more deliberate estimation procedures. Efficiency loss relative to QMLE (quasi-maximum likelihood estimator) is discussed within the class of LABF (locally asymptotically Brownian functional) models. The insensitivity and efficiency of WLS in finite samples are examined through Monte Carlo experiments. We also apply the WLS to an empirical example of HSI (Hang Seng Index), HSIF (Hang Seng Index Futures) and TraHK (Hong Kong Tracker Fund).


Key Words: Asymmetric distribution; Cointegration; LABF models; Multivariate GARCH; Price discovery; WLS.

JEL Codes: C32, C51, G14

[^0]
## 1 Introduction

Throughout this paper, we consider an $m$-dimensional autoregressive (AR) process $\left\{Y_{t}\right\}$, which is generated by

$$
\begin{align*}
& Y_{t}=\Phi_{1} Y_{t-1}+\cdots+\Phi_{s} Y_{t-s}+\varepsilon_{t}  \tag{1.1}\\
& E\left(\varepsilon_{t} \mid \mathcal{I}_{t-1}\right)=0 \tag{1.2}
\end{align*}
$$

where $\Phi_{j}$ 's are constant matrices, and $\mathcal{I}_{t}=\sigma\left\{\varepsilon_{s}, s=t, t-1, \ldots\right\}$.
Assuming the $\varepsilon_{t}$ 's are i.i.d., under further conditions on $\Phi_{j}$ 's (See Assumptions 2.1 and 2.2 below), Ahn and Reinsel (1990) (see also Johansen, 1996) show that, although some component series of $\left\{Y_{t}\right\}$ exhibit nonstationary $/ I(1)$ behaviour, there are $r$ linear combinations of $\left\{Y_{t}\right\}$ that are stationary $/ I(0)$. This phenomenon, which is called cointegration in the literature of economics, was first investigated by Granger (1983) (see also Engle and Granger, 1987). The partially nonstationary multivariate AR model or cointegrating time series models without GARCH have been extensively discussed over the past twenty years. Other noticeable examples include Phillips and Durlauf (1986) and Stock and Watson (1993).

Economic time series related to financial markets often exhibit time-varying variances. As far as we know, Li, Ling and Wong (2001) first investigate multivariate time series that exhibit both cointegration and time-varying variances, where the heteroskedasticity part is the random coefficient AR model and the scope of applications is thus restricted. Extending Li et al. (2001)'s estimation results, Sin and Ling (2004) construct a likelihood ratio (LR) test for reduced rank; and modify their model. They consider a multivariate GARCH with constant correlations, which was first suggested by Bollerslev (1990) and widely used in many papers in the economics and finance literature. More precisely, the conditional variance-covariance matrix, denoted as $\tilde{V}_{t-1}$, is modelled as $\tilde{D}_{t-1} \tilde{\Gamma} \tilde{D}_{t-1}$, where $\tilde{D}_{t-1}=\operatorname{diag}\left(\sqrt{\tilde{h}_{1 t-1}}, \ldots, \sqrt{\tilde{h}_{m t-1}}\right)$
and:

$$
\begin{align*}
\tilde{h}_{i t-1} & =\tilde{a}_{i 0}+\sum_{j=1}^{q} \tilde{a}_{i j} \varepsilon_{i t-j}^{2}+\sum_{k=1}^{p} \tilde{b}_{i k} \tilde{h}_{i t-1-k},  \tag{1.3}\\
\tilde{\Gamma} & \equiv\left(\tilde{\gamma}_{i j}\right)_{m \times m}, \text { a symmetric positive definite matrix with } \tilde{\gamma}_{i i}=1 . \tag{1.4}
\end{align*}
$$

This paper assumes the existence of some pseudo true parameters of this multivariate GARCH model (1.3)-(1.4), which satisfy Assumption 2.4 below. However, in view of the possible mis-specification in variance (see, for instance, the GJR model first suggested in Glosten, Jagannathan and Runkle, 1993, the extended model first suggested in Jeantheau, 1998, and the time-varying correlation model first suggested in Tse and Tsui, 2002), instead of a QMLE (quasi-maximum likelihood estimator), we consider a WLS (weighted least squares), which is computationally simpler on the one hand, and is insensitive to possible mis-specification of variance on the other hand. See Section 2 of $\operatorname{Sin}(2003)$ for a related study in the purely stationary case. Further, we also allow asymmetrically distributed deflated errors, at the expense of (i) a more involved estimation procedure; and/or (ii) a more involved asymptotic distribution. Efficiency loss relative to the QMLE is discussed within the class of LABF (locally asymptotically Brownian functional) models.

This paper proceeds as follows. Section 2 discusses the structure of the DGP (data generating process) or the model (1.1)-(1.4). Assuming a symmetric distribution, Section 3 derives the asymptotic distributions of the full rank estimator, the reduced rank estimator, and a test for reduced rank. Relaxing the symmetry assumption, Section 4 considers a modified weighting matrix (modified upon the original one $\tilde{V}_{t-1}^{-1}$ ) and thus the efficiency of the estimators may be altered. In Section 5, we maintain the original weighting matrix and consider an alternative estimation. Section 6 contains a brief discussion on the estimation procedures as well as their efficiency of the estimators discussed so far. Monte Carlo experiments and an illustrative empirical example are discussed in the subsequent sections. We conclude in the last section.

Readers who are much interested in the algorithms may jump to (3.7) for the full rank estimation, to (3.14)-(3.15) for the reduced rank estimation, (3.17) (or (3.19) for a robust version) for the test statistics for reduced rank. In Section 4, the counterparts can be found in (4.5), (4.6)-(4.7) and (4.8) (a robust version) respectively. In Section 5, they are found in (5.1), (5.3)-(5.4), and (5.5) (or (5.11) for a robust version) respectively. Throughout, $\longrightarrow \mathcal{L}$ denotes convergence in distribution, $\longrightarrow p$ denotes convergence in probability, $O_{p}(1)$ denotes a series of random numbers that are bounded in probability, and $o_{p}(1)$ denotes a series of random numbers converging to zero in probability. $\tilde{\theta}$ denotes a generic version of the (pseudo) true parameter $\theta$, while $\hat{\theta}$ denotes an initial estimator and $\dot{\theta}$ denotes a full rank or reduced rank estimator.

## 2 Basic Properties of the Models

Denote $L$ as the lag operator. Refer to (1.1)-(1.2) and define $\Phi(L)=I_{m}-\sum_{j=1}^{s} \Phi_{j} L^{j}$. We first make the following assumption:

Assumption 2.1. $|\Phi(z)|=0$ implies that either $|z|>1$ or $z=1$.
Define $W_{t}=Y_{t}-Y_{t-1}, \Pi_{j}=-\sum_{k=j+1}^{s} \Phi_{k}$ and $C=-\Phi(1)=-\left(I_{m}-\sum_{j=1}^{s} \Phi_{j}\right)$. By a Taylor's formula, $\Phi(L)$ can be decomposed as:

$$
\begin{equation*}
\Phi(z)=(1-z) I_{m}-C z-\sum_{j=1}^{s-1} \Pi_{j}(1-z) z^{j} . \tag{2.1}
\end{equation*}
$$

Thus, we can reparameterize process (1.1) as:

$$
\begin{equation*}
W_{t}=C Y_{t-1}+\sum_{j=1}^{s-1} \Pi_{j} W_{t-j}+\varepsilon_{t} . \tag{2.2}
\end{equation*}
$$

Following Ahn and Reinsel (1990) and Johansen (1996), we can decompose $C=A B$, where $A$ and $B$ are respectively $m \times r$ and $r \times m$ matrices of rank $r$. Define $d=m-r$. Denote $B_{\perp}$ as a $d \times m$ matrix of full rank such that $B B_{\perp}^{\prime}=0_{r \times d}, \bar{B}=\left(B B^{\prime}\right)^{-1} B$ and $\bar{B}_{\perp}=\left(B_{\perp} B_{\perp}^{\prime}\right)^{-1} B_{\perp}$, and $A_{\perp}$ as an $m \times d$ matrix of full rank such that $A^{\prime} A_{\perp}=0_{r \times d}$, $\bar{A}=A\left(A^{\prime} A\right)^{-1}$ and $\bar{A}_{\perp}=A_{\perp}\left(A_{\perp}^{\prime} A_{\perp}\right)^{-1}$. We impose the following conditions:

Assumption 2.2. $\left|A_{\perp}^{\prime}\left(I_{m}-\sum_{j=1}^{s-1} \Pi_{j}\right) B_{\perp}^{\prime}\right| \neq 0$.
Assumption 2.3. $\left\{\varepsilon_{t}\right\}$ is a stationary process, $E\left(v e c\left[\varepsilon_{t} \varepsilon_{t}^{\prime}\right]\right.$ vec $\left.\left[\varepsilon_{t} \varepsilon_{t}^{\prime}\right]^{\prime}\right)<\infty$.
Unlike Ahn and Reinsel (1990), we do not assume the existence of their Jordan canonical form and include some DGPs such as that in Exercise 4.3, pp.62-63 of Johansen (1996), which approach is essentially adopted here. Given Assumptions 2.1-2.2, by the proof of Theorem (4.2) in Johansen (1996),

$$
\Psi(L)\left[\begin{array}{c}
(1-L) B_{\perp} Y_{t}  \tag{2.3}\\
B Y_{t}
\end{array}\right]=\left(\bar{A}_{\perp}, \bar{A}\right)^{\prime} \varepsilon_{t},
$$

where $\Psi(z)=\left(\bar{A}_{\perp}, \bar{A}\right)^{\prime} \Phi(z)\left(\bar{B}_{\perp}^{\prime}, \bar{B}^{\prime}(1-z)^{-1}\right)$ is invertible for $|z|<1+\rho$ for some $\rho>0$. In other words, similar to Ahn and Reinsel (1990), we can consider the following transformation:

$$
\begin{equation*}
Z_{1 t}=B_{\perp} Y_{t}=Z_{1 t-1}+u_{1 t}, \text { and } Z_{2 t}=B Y_{t}=u_{2 t}, \tag{2.4}
\end{equation*}
$$

where $u_{t}=\left(u_{1 t}^{\prime}, u_{2 t}^{\prime}\right)^{\prime}=\psi(L) a_{t}, \psi(L) \equiv \Psi^{-1}(L)$ and $a_{t} \equiv\left(\bar{A}_{\perp}, \bar{A}\right)^{\prime} \varepsilon_{t}$. Note in Assumption 2.3, the i.i.d assumption in Johansen (1996) is replaced by a stationarity assumption. Given this, by (2.3)-(2.4), $Z_{1 t}$ is $I(1)$ while $Z_{2 t}$ is $I(0)$.

Further, we make the following assumptions on (1.3)-(1.4).
Assumption 2.4. For $i=1, \ldots, m$, the pseudo true parameters $a_{i 0}>0$, $a_{i 1}, \ldots, a_{i q}, b_{i 1}, \ldots, b_{i p} \geq 0, \sum_{j=1}^{q} a_{i j}+\sum_{k=1}^{p} b_{i k}<1 ;$ and $\left\{\eta_{i t} \equiv \varepsilon_{i t} / \sqrt{h_{i t-1}}\right\}$ is a stationary process.

Assumption 2.5. $\eta_{t} \equiv\left(\eta_{1 t}, \ldots, \eta_{m t}\right)^{\prime}$ is symmetrically distributed.
The stationarity assumption in Assumptions 2.3-2.4 can be weakened to heterogeneous and mixing process assumption, as in Phillips and Durlauf (1986). We keep this for simplicity. (1.2) and Assumption 2.4 imply that although $E\left(\eta_{t} \mid \mathcal{I}_{t-1}\right)=0$, in general $E\left(\eta_{t} \mid \mathcal{I}_{t-1}\right) \neq \Gamma$. In view of this possible mis-specification, we do not make primitive assumptions that render stationarity and finite fourth moments in Assumption 2.3. We will come back to this point in a subsequent section.

The symmetry assumption in Assumption 2.5 will be used in the next section. It will be relaxed in Sections 4 and 5 .

We close this section with a basic lemma, which is found useful in proving the results in the subsequent sections. Let $\left(W_{m}^{\prime}(u), W_{m}^{* \prime}(u)\right)^{\prime}$ be a $2 m$-dimensional Brownian motion (BM) with the covariance matrix:

$$
u \Omega \equiv u\left(\begin{array}{cc}
V^{*} & E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} V_{t-1}^{-1}\right) \\
E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right) & \Omega_{1}^{*}
\end{array}\right)
$$

where $V^{*}=E \varepsilon_{t} \varepsilon_{t}^{\prime}$, and $\Omega_{1}^{*}=E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime} V_{t-1}^{-1}\right)$. Let $B_{d}(u)=\Omega_{a_{1}}^{-1 / 2}\left[I_{d}, 0_{d x r}\right] \Omega_{a}^{1 / 2} V^{*-1 / 2} W_{m}(u)$, where $\Omega_{a}=E\left(a_{t} a_{t}^{\prime}\right)$ and $\Omega_{a_{1}}=\left[I_{d}, 0_{d x r}\right] \Omega_{a}\left[I_{d}, 0_{d x r}\right]^{\prime}$.

Lemma 2.1. Suppose Assumptions 2.1-2.4 hold. Then

$$
\begin{align*}
& n^{-2} \sum_{t=1}^{n} Z_{1 t-1} Z_{1 t-1}^{\prime} \otimes V_{t-1}^{-1} \longrightarrow \mathcal{L}\left(\psi_{11} \Omega_{a_{1}}^{1 / 2} \int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} \Omega_{a_{1}}^{1 / 2} \psi_{11}^{\prime}\right) \otimes \Omega_{1},  \tag{a}\\
& n^{-3 / 2} \sum_{t=1}^{n} Z_{1 t-1} U_{t-1}^{\prime} \otimes V_{t-1}^{-1} \longrightarrow \mathcal{L}\left(\psi_{11} \Omega_{a_{1}}^{1 / 2} \int_{0}^{1} B_{d}(u) d u \otimes I_{m}\right) E\left(U_{t-1}^{\prime} \otimes V_{t-1}^{-1}\right), \tag{b}
\end{align*}
$$

(c) If in addition, Assumption 2.5 holds,

$$
n^{-3 / 2} \sum_{t=1}^{n} Z_{1 t-1} U_{t-1}^{\prime} \otimes V_{t-1}^{-1}=o_{p}(1),
$$

(d) $n^{-1} \sum_{t=1}^{n} U_{t-1} U_{t-1}^{\prime} \otimes V_{t-1}^{-1} \longrightarrow{ }_{p} \Omega_{2}$,
(e) $n^{-1} \sum_{t=1}^{n} Z_{1 t-1} \otimes V_{t-1}^{-1} \varepsilon_{t} \longrightarrow \mathcal{L} v e c\left[\left(\int_{0}^{1} B_{d}(u) d W_{m}^{*}(u)^{\prime}\right)^{\prime} \Omega_{a_{1}}^{1 / 2} \psi_{11}\right]$,
(f) $\quad n^{-1 / 2} \sum_{t=1}^{n} U_{t-1} \otimes V_{t-1}^{-1} \varepsilon_{t} \longrightarrow \mathcal{L} \Omega_{2}^{* 1 / 2} \Phi$,
where $\Phi \sim N\left(0, I_{r m+(s-1) m^{2}}\right), \psi_{11} \equiv\left[I_{d}, 0\right]\left(\sum_{k=1}^{\infty} \psi_{k}\right)\left[I_{d}, 0\right]^{\prime}, \Omega_{1} \equiv E\left(V_{t-1}^{-1}\right), \Omega_{2} \equiv$ $E\left(U_{t-1} U_{t-1}^{\prime} \otimes V_{t-1}^{-1}\right), \Omega_{2}^{*} \equiv E\left(U_{t-1} U_{t-1}^{\prime} \otimes V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime} V_{t-1}^{-1}\right)$, and $U_{t-1}=\left[\left(B Y_{t-1}\right)^{\prime}, W_{t-1}^{\prime}, \cdots, W_{t-s+1}^{\prime}\right]$

## 3 Assuming Symmetric Distribution

In this section, we follow the lines in Sin and Ling (2004) and assume a symmetric distribution of the deflated error $\eta_{t}$. See Assumption 2.5 above. The procedures of the full rank estimator, the reduced rank estimator, and a test for reduced rank as well as their asymptotic distributions resemble those in Sections 3-5 in Sin and Ling (2004).

### 3.1 Full Rank Estimation

Refer to Process (2.2). In this section, we consider the full rank estimator for $\varphi \equiv \operatorname{vec}\left[C, \Pi_{1}, \ldots, \Pi_{s-1}\right]$, given some initial estimator for the pseudo true parameter of the conditional variance (see Model (1.3)-(1-4) and Assumption (2.4) above). Similar to above, the generic "variance parameter" is denoted as $\tilde{\delta}$ while the pseudo true "variance parameter" is simply denoted as $\delta$.

Given $\left\{Y_{t}: t=1, \cdots, n\right\}$, conditional on the initial values $Y_{s}=0$ for $s \leq 0$, the log-likelihood function (LF) (with a constant ignored) can be written as:

$$
\begin{equation*}
l(\tilde{\varphi}, \tilde{\delta})=\sum_{t=1}^{n} l_{t}(\tilde{\varphi}, \tilde{\delta}) \text { and } l_{t}(\tilde{\varphi}, \tilde{\delta})=-\frac{1}{2} \tilde{\varepsilon}_{t}^{\prime} \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t}-\frac{1}{2} \ln \left|\tilde{V}_{t-1}\right| \tag{3.1}
\end{equation*}
$$

where $\tilde{V}_{t-1}=\tilde{D}_{t-1} \tilde{\Gamma} \tilde{D}_{t-1}, \tilde{D}_{t-1}=\operatorname{diag}\left(\sqrt{\tilde{h}_{1 t-1}}, \ldots, \sqrt{\tilde{h}_{m t-1}}\right) . \quad \tilde{\varepsilon}_{t}, \tilde{V}_{t-1}, \tilde{D}_{t-1}$ and $\tilde{h}_{i t-1}$ 's are functions of the generic parameter $(\tilde{\varphi}, \tilde{\delta})$. Further denote $\tilde{h}_{t-1}=\left(\tilde{h}_{1 t-1}, \ldots, \tilde{h}_{m t-1}\right)^{\prime}$ and $\tilde{H}_{t-1}=\left(\tilde{h}_{1 t-1}^{-1}, \ldots, \tilde{h}_{m t-1}^{-1}\right)^{\prime}$. Define $X_{t-1} \equiv\left[Y_{t-1}^{\prime}, W_{t-1}^{\prime}, \ldots, W_{t-s+1}^{\prime}\right]^{\prime}$. The score function w.r.t. $\varphi$ can be written as:

$$
\begin{equation*}
\nabla_{\varphi} \tilde{l}_{t}=-\frac{1}{2} \nabla_{\varphi} \tilde{h}_{t-1}\left(\iota-w\left(\tilde{\varepsilon}_{t} \tilde{\varepsilon}_{t}^{\prime} \tilde{V}_{t-1}^{-1}\right)\right) \odot \tilde{H}_{t-1}+\left(X_{t-1} \otimes I_{m}\right) \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t} \tag{3.2}
\end{equation*}
$$

where $\iota=(1,1, \ldots, 1)_{m \times 1}^{\prime}$ and $w($.$) is a vector containing the diagonal elements of$ a square matrix. In Sin and Ling (2004), the score function (3.2) is used. As one can see in that paper, the algorithm for the one-step estimator is quite involved. More importantly, if the multivariate GARCH is mis-specified and for all $(\tilde{\varphi}, \tilde{\delta})$, $\operatorname{Prob}\left\{E\left[\nabla_{\varphi} \tilde{h}_{t-1}\left(\iota-w\left(\tilde{\varepsilon}_{t} \tilde{\varepsilon}_{t}^{\prime} \tilde{V}_{t-1}^{-1}\right)\right) \odot \tilde{H}_{t-1} \mid \mathcal{I}_{t-1}\right]=0\right\}<1$, it is unclear what the asymptotic properties of the one-step estimator carries. In view of that, for our $W L S$, we only consider the second part of the score function:

$$
\begin{equation*}
\tilde{f}_{t} \equiv\left(X_{t-1} \otimes I_{m}\right) \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t} \tag{3.3}
\end{equation*}
$$

Denote $Q^{*}=\operatorname{diag}\left(\left[B_{\perp}^{\prime}, B^{\prime}\right]^{\prime} \otimes I_{m}, I_{(s-1) m^{2}}\right)$ and $D^{*}=\operatorname{diag}\left(n I_{d m}, \sqrt{n} I_{r m+(s-1) m^{2}}\right)$. For any fixed positive constant $K$, let $\Theta_{n} \equiv\left\{(\tilde{\varphi}, \tilde{\delta}):\left\|D^{*} Q^{*^{\prime}-1}(\tilde{\varphi}-\varphi)\right\| \leq K\right.$ and $\|\sqrt{n}(\tilde{\delta}-\delta)\| \leq K\}$, where $(\varphi, \delta)$ is the true parameter. Using Assumptions
2.1-2.5 and a similar method as in Ling and $\operatorname{Li}(1998)$, the derivative of $\tilde{f}_{t}$ on $\Theta_{n}$ can be simplified as follows:

$$
\begin{equation*}
D^{*-1} Q^{*}\left(\sum_{t=1}^{n} \nabla_{\varphi^{\prime}} \tilde{f}_{t}\right) Q^{*^{\prime}} D^{*-1}=\sum_{t=1}^{n} D^{*-1} Q^{*} \tilde{F}_{t} Q^{*^{\prime}} D^{*-1}+o_{p}(1) \tag{3.4}
\end{equation*}
$$

where $\tilde{F}_{t} \equiv-\left(X_{t-1} X_{t-1}^{\prime} \otimes \tilde{V}_{t-1}^{-1}\right)$.
Moreover, we can show the following results hold uniformly in $\Theta_{n}$ :

$$
\begin{align*}
& \sum_{t=1}^{n} D^{*-1} Q^{*}\left(\tilde{F}_{t}-F_{t}\right) Q^{*^{\prime}} D^{*-1}=o_{p}(1),  \tag{3.5}\\
& \sum_{t=1}^{n} D^{*-1} Q^{*}\left(\tilde{f}_{t}-f_{t}\right)=\sum_{t=1}^{n} D^{*-1} Q^{*} F_{t}(\tilde{\varphi}-\varphi)+o_{p}(1), \tag{3.6}
\end{align*}
$$

where $F_{t}=-\left(X_{t-1} X_{t-1}^{\prime} \otimes V_{t-1}^{-1}\right)$ and $f_{t}=\left(X_{t-1} \otimes I_{m}\right) V_{t-1}^{-1} \varepsilon_{t}$. In view of (3.4)-(3.6), we first find an initial estimator $(\hat{\varphi}, \hat{\delta}) \in \Theta_{n}$. For instance, $\hat{\varphi}$ can be the least squares (LS) estimator while $\hat{\delta}$ may be the QMLE with the true $\varepsilon_{t}$ replaced by the LS residual $\hat{\varepsilon}_{t} \equiv W_{t}-\hat{C} Y_{t-1}-\sum_{j=1}^{s-1} \hat{\Pi}_{j} W_{t-j}$. See Section 2 of Ling, Li and McAleer (2003). Given $(\hat{\varphi}, \hat{\delta})$, we perform one iteration of the $W L S$ :

$$
\begin{equation*}
\dot{\varphi}=\hat{\varphi}-\left[\sum_{t=1}^{n} F_{t}(\hat{\varphi}, \hat{\delta})\right]^{-1}\left[\sum_{t=1}^{n} f_{t}(\hat{\varphi}, \hat{\delta})\right], \tag{3.7}
\end{equation*}
$$

where $\hat{F}_{t}=X_{t-1} X_{t-1}^{\prime} \otimes \hat{V}_{t-1}^{-1}, \hat{V}_{t-1}$ is the $\tilde{V}_{t-1}$ in Model (1.3)-(1.4) evaluated at $(\hat{\varphi}, \hat{\delta})$. The following is proved in the Appendix.

Theorem 3.1. Suppose Assumptions 2.1-2.5 hold. Then
(a) $n(\dot{C}-C) \bar{B}_{\perp}^{\prime} \longrightarrow \mathcal{L} \Omega_{1}^{-1} M^{*}$,
(b) $\sqrt{n} \operatorname{vec}\left[(\dot{C}-C) \bar{B}^{\prime},\left(\dot{\Pi}_{1}-\Pi_{1}\right), \ldots,\left(\dot{\Pi}_{s-1}-\Pi_{s-1}\right)\right] \longrightarrow_{\mathcal{L}} N\left(0, \Omega_{2}^{-1} \Omega_{2}^{*} \Omega_{2}^{-1}\right)$,
where $M^{*}=\left(\int_{0}^{1} B_{d}(u) d W_{m}^{*}(u)^{\prime}\right)^{\prime}\left(\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right)^{-1} \Omega_{a_{1}}^{-1 / 2} \psi_{11}^{-1}$, and the remaining variables are defined as in Lemma 2.1.

When $E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} \mid \mathcal{I}_{t-1}\right)=V_{t-1}, \Omega_{1}^{*}=\Omega_{1}$ and $\Omega_{2}^{*}=\Omega_{2}$. On the other hand, the asymptotic distribution of the nonstationary component argument in (a) is independent of that of the stationary component argument in (b). As one can see in the
proof, this suffices to have:

$$
n^{-3 / 2} \sum_{t=1}^{n}\left(Z_{1 t-1} \otimes I_{m}\right)\left(U_{t-1}^{\prime} \otimes V_{t-1}^{-1}\right)=o_{p}(1)
$$

which by Lemma $2.1(\mathrm{c})$, is implied by $E\left[U_{t-1}^{\prime} \otimes V_{t-1}^{-1}\right]=0$, a result depending on the variance model (1.3)-(1.4) and the symmetry assumption.

### 3.2 Reduced Rank Estimation

We first rewrite (2.2) in a reduced rank form:

$$
\begin{equation*}
W_{t}=A B Y_{t-1}+\sum_{j=1}^{s-1} \Pi_{j} W_{t-j}+\varepsilon_{t} \tag{3.8}
\end{equation*}
$$

where $A$ and $B$ are defined as in Section 2. Denote $\alpha=\left[\alpha_{1}^{\prime}, \alpha_{2}^{\prime}\right]^{\prime}$ with $\alpha_{1} \equiv \operatorname{vec}[B]$ and $\alpha_{2} \equiv \operatorname{vec}\left[A, \Pi_{1}, \ldots, \Pi_{s-1}\right]$. The LF based on the error-correction form (3.9) is the same as that in (3.1), but now it is a function of the generic parameters $\tilde{\alpha}$ and $\tilde{\delta}$. Denote $U_{t-1}^{*} \equiv\left[\left(Y_{t-1} \otimes A^{\prime}\right)^{\prime},\left(U_{t-1} \otimes I_{m}\right)^{\prime}\right]^{\prime}$, where we recall from Theorem 3.1 that $U_{t-1}=\left[\left(B Y_{t-1}\right)^{\prime}, W_{t-1}^{\prime}, \ldots, W_{t-s+1}^{\prime}\right]^{\prime}$. Similar to (3.2),

$$
\begin{equation*}
\nabla_{\alpha} \tilde{l}_{t}=\nabla_{\alpha} l_{t}(\tilde{\alpha}, \tilde{\delta})=-\frac{1}{2}\left(\nabla_{\alpha} \tilde{h}_{t-1}\right)\left(\iota-w\left(\tilde{\varepsilon}_{t} \tilde{\varepsilon}_{t}^{\prime} \tilde{V}_{t-1}^{-1}\right)\right) \odot \tilde{H}_{t-1}+\tilde{U}_{t-1}^{*} \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t} . \tag{3.9}
\end{equation*}
$$

Our $W L S$ only considers the second term in (3.9), that is:

$$
\begin{equation*}
\tilde{r}_{t}=r_{t}(\tilde{\alpha}, \tilde{\delta})=\left(\tilde{r}_{1 t}^{\prime}, \tilde{r}_{2 t}^{\prime}\right)^{\prime} \tag{3.10}
\end{equation*}
$$

where $\tilde{r}_{1 t} \equiv\left(Y_{t-1} \otimes \tilde{A}^{\prime}\right) \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t}$ and $\tilde{r}_{2 t} \equiv\left(\tilde{U}_{t-1} \otimes I_{m}\right) \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t}$.
Denote $Q^{* *} \equiv \operatorname{diag}\left(\left(B_{\perp} \otimes I_{r}\right), I_{r m+(s-1) m^{2}}\right)$ and $D^{* *} \equiv \operatorname{diag}\left(n I_{r d}, \sqrt{n} I_{r m+(s-1) m^{2}}\right)$. For any fixed positive constant $K$, let $\Xi_{n} \equiv\left\{(\tilde{\alpha}, \tilde{\delta}):\left\|D^{* *} Q^{* * \prime-1}(\tilde{\alpha}-\alpha)\right\| \leq\right.$ $K$ and $\|\sqrt{n}(\tilde{\delta}-\delta)\| \leq K\}$. Given Assumptions (2.1)-(2.5), similar to (3.4), on $\Xi_{n}$, the derivative of $\tilde{r}_{t}$ can be simplified as follows:

$$
\begin{equation*}
D^{* *-1} Q^{* *} \sum_{t=1}^{n} \nabla_{\alpha^{\prime}} \tilde{r}_{t} Q^{* * \prime} D^{* *-1}=D^{* *-1} Q^{* *} \sum_{t=1}^{n} \tilde{R}_{t} Q^{* * \prime} D^{* *-1}+o_{p}(1) \tag{3.11}
\end{equation*}
$$

where $\tilde{R}_{t}=\operatorname{diag}\left\{\tilde{R}_{1 t}, \tilde{R}_{2 t}\right\}, \tilde{R}_{1 t}=-\left(Y_{t-1} Y_{t-1}^{\prime} \otimes \tilde{A}^{\prime} \tilde{V}_{t-1}^{-1} \tilde{A}\right), \tilde{R}_{2 t}=-\left(\tilde{U}_{t-1} \tilde{U}_{t-1}^{\prime} \otimes \tilde{V}_{t-1}^{-1}\right)$.

Similar to (3.5)-(3.6), the following results hold uniformly in $\Xi_{n}$ :

$$
\begin{align*}
& D^{* *-1} Q^{* *} \sum_{t=1}^{n}\left(\tilde{R}_{t}-R_{t}\right) Q^{* * \prime} D^{* *-1}=o_{p}(1),  \tag{3.12}\\
& D^{* *-1} Q^{* *} \sum_{t=1}^{n}\left(\tilde{r}_{t}-r_{t}\right)=D^{* *-1} Q^{* *} \sum_{t=1}^{n} R_{t}(\tilde{\alpha}-\alpha)+o_{p}(1), \tag{3.13}
\end{align*}
$$

where $R_{t}$ and $r_{t}$ are $\tilde{R}_{t}$ and $\tilde{r}_{t}$ evaluated at the (pseudo) true parameters $\alpha$ and $\delta$. Given (3.12)-(3.14), we first find an initial estimator $(\hat{\alpha}, \hat{\delta})$ which, after certain normalization, belongs to $\Xi_{n}$. For instance, $\hat{\alpha}=\left[\hat{\alpha}_{1}^{\prime}, \hat{\alpha}_{2}^{\prime}\right]^{\prime}$ may be that from Johansen (1996) (see for instance, Chapter 13 there) while $\hat{\delta}$ may be that from Sub-section 3.1. Given $(\hat{\alpha}, \hat{\delta})$, we first perform one iteration of the $W L S$ for $\alpha_{1}$ :

$$
\begin{equation*}
\dot{\alpha}_{1}=\hat{\alpha}_{1}-\left[\sum_{t=1}^{n} R_{1 t}\left(\hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right]^{-1}\left[\sum_{t=1}^{n} r_{1 t}\left(\hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right] . \tag{3.14}
\end{equation*}
$$

Once we obtain the reduced rank estimator for $\alpha_{1}$ which incorporates the possible heteroskedasticity, we perform one iteration of the $W L S$ for $\alpha_{2}$ :

$$
\begin{equation*}
\dot{\alpha}_{2}=\hat{\alpha}_{2}-\left[\sum_{t=1}^{n} R_{2 t}\left(\dot{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right]^{-1}\left[\sum_{t=1}^{n} r_{2 t}\left(\dot{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right] . \tag{3.15}
\end{equation*}
$$

In view of (3.12)-(3.14), the asymptotic distributions of the normalized estimators for $\alpha_{1}$ and $\alpha_{2}$ are given as follows.

Theorem 3.2. Suppose Assumptions 2.1-2.5 hold. Then

$$
\begin{equation*}
n\left(\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-B\right) \bar{B}_{\perp}^{\prime} \longrightarrow_{\mathcal{L}}\left(A^{\prime} \Omega_{1} A\right)^{-1} A^{\prime} M^{*} \tag{a}
\end{equation*}
$$

(b) $\sqrt{n} \operatorname{vec}\left[\left(\dot{A}\left(\dot{B} \bar{B}^{\prime}\right)-A\right),\left(\dot{\Pi}_{1}-\Pi_{1}\right), \ldots,\left(\dot{\Pi}_{s-1}-\Pi_{s-1}\right)\right] \longrightarrow \mathcal{L} N\left(0, \Omega_{2}^{-1} \Omega_{2}^{*} \Omega_{2}^{-1}\right)$, where the remaining variables are defined as in Lemma 2.1.

From Theorem 3.2 above, the asymptotic distribution of the nonstationary component argument in (a) is independent of that of the stationary component argument in (b). Similar to the arguments at the end of the last sub-section, this result depends on the variance model (1.3)-(1.4) and the symmetry assumption.

### 3.3 Testing for Reduced Rank

This section applies the asymptotic distributions in Theorems 3.1 and 3.2 to construct tests for reduced rank. The null and the alternative hypotheses are:

$$
\begin{equation*}
H_{0}: \operatorname{rank}(C)=r<m \text { vs } H_{a}: \operatorname{rank}(C)=m . \tag{3.16}
\end{equation*}
$$

We first consider the Likelihood Ratio-Type (LRT) test statistic:

$$
\begin{equation*}
L R T_{G} \equiv \operatorname{vec}(\dot{C}-\dot{A} \dot{B})^{\prime}\left(-\sum_{t=1}^{n} \hat{F}_{11 t}\right) \operatorname{vec}(\dot{C}-\dot{A} \dot{B}), \tag{3.17}
\end{equation*}
$$

where we recall that $\dot{C}$ is the full rank estimator defined in Sub-section 3.1, $\dot{A}$ and $\dot{B}$ are the reduced rank estimators defined in Sub-section 3.2, while $\hat{F}_{11 t}=$ $-\left(Y_{t-1} Y_{t-1}^{\prime} \otimes \hat{V}_{t-1}^{-1}\right)$. The following lemma gives the asymptotic distribution of $L R T_{G}$.

Lemma 3.3. Suppose Assumptions 2.1-2.5 hold. Then under $H_{0}$ in (3.16), the LRT test statistic for rank,

$$
L R T_{G} \longrightarrow \mathcal{L} \operatorname{tr}\left[\left(\int_{0}^{1} B_{d}(u) d V_{d}^{*}(u)^{\prime}\right)^{\prime}\left(\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right)^{-1}\left(\int_{0}^{1} B_{d}(u) d V_{d}^{*}(u)^{\prime}\right)\right],
$$

where $V_{d}^{*}(u)=\Upsilon B_{d}(u)+\left[\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{-1 / 2} A_{\perp}^{\prime} \Omega_{1}^{-1} \Omega_{1}^{*} \Omega_{1}^{-1} A_{\perp}\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{-1 / 2}-\Upsilon^{* *} \Upsilon^{* *^{\prime}}\right]^{1 / 2}$ $V_{d}(u), \Upsilon^{* *}=\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{-1 / 2}\left(A_{\perp}^{\prime} \Omega_{1}^{-1} E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right) A_{\perp}\right)\left(A_{\perp}^{\prime} V^{*} A_{\perp}\right)^{-1 / 2}$, and $\left(B_{d}^{\prime}(u), V_{d}^{\prime}(u)\right)^{\prime}$ is a $2 d$-dimensional standard Brownian motion.

When the $\varepsilon_{t}^{\prime}$ 's are conditional homoskedastic, $E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right)=I_{m}, \Omega_{1}^{*}=\Omega_{1}=V^{*-1}$, and hence $\Upsilon=I_{d}$ and $V_{d}^{*}(u)=B_{d}(u)$. The distribution of $L R T_{G}$ is exactly the same as that in Reinsel and Ahn (1992) and Johansen (1996). When $E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} \mid \mathcal{I}_{t-1}\right)=V_{t-1}$ and $V_{t-1}$ may or may not equal to $V^{*}$, the distribution of $L R T_{G}$ can be simplified as follows.

Theorem 3.3. Suppose the assumptions in Lemma 3.3 hold. If $E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} \mid \mathcal{I}_{t-1}\right)=$ $V_{t-1}$, then

$$
\begin{equation*}
L R T_{G} \longrightarrow \mathcal{L} \operatorname{tr}\left\{\left[\zeta\left(I_{d}-\Lambda_{d}\right)^{1 / 2}+\Phi \Lambda_{d}^{1 / 2}\right]^{\prime}\left[\zeta\left(I_{d}-\Lambda_{d}\right)^{1 / 2}+\Phi \Lambda_{d}^{1 / 2}\right]\right\} \tag{3.18}
\end{equation*}
$$

where $\Lambda_{d}$ is a diagonal matrix containing the d eigenvalues of $\left(I_{d}-\Upsilon \Upsilon^{\prime}\right)$, where $\Upsilon=$ $\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{1 / 2}\left(A_{\perp}^{\prime} V^{*} A_{\perp}\right)^{-1 / 2}, \Phi \sim N\left(0, I_{d}\right)$ and is independent of $\zeta=\left(\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right)^{-1 / 2}$ - $\left(\int_{0}^{1} B_{d}(u) d B_{d}(u)^{\prime}\right)$.

On the other hand, when $E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} \mid \mathcal{I}_{t-1}\right) \neq V_{t-1}$, we may define a modified LRT test statistic:

$$
\begin{equation*}
L R T_{G}^{*} \equiv\left[\operatorname{vec}\left(\dot{C}^{*}\right)-\operatorname{vec}\left(\dot{A} \dot{B}^{*}\right)\right]^{\prime}\left[-\sum_{t=1}^{n} \hat{F}_{11 t}^{*}\left[\operatorname{vec}\left(\dot{C}^{*}\right)-\operatorname{vec}\left(\dot{A} \dot{B}^{*}\right)\right],\right. \tag{3.19}
\end{equation*}
$$

where $\operatorname{vec}\left(\dot{C}^{*}\right)=\left(-\sum_{t=1}^{n} \hat{F}_{11 t}^{*}\right)^{-1}\left(-\sum_{t=1}^{n} \hat{F}_{11 t}\right) \operatorname{vec}(\dot{C}), \dot{B}^{*}=\left(\dot{A}^{\prime} \dot{\Omega}_{1}^{*} \dot{A}\right)^{-1}\left(\dot{A}^{\prime} \dot{\Omega}_{1} \dot{A}\right) \dot{B}$, and $\hat{F}_{11 t}^{*}=-\left(Y_{t-1} Y_{t-1}^{\prime} \otimes \hat{V}_{t-1}^{-1} \hat{\varepsilon}_{t} \hat{\varepsilon}_{t}^{\prime} \hat{V}_{t-1}^{-1}\right), \hat{F}_{11 t}=-\left(Y_{t-1} Y_{t-1}^{\prime} \otimes \hat{V}_{t-1}^{-1}\right)$, where we recall from Sub-section 3.1 that $\hat{\varepsilon}_{t} \equiv W_{t}-\hat{C} Y_{t-1}-\sum_{j=1}^{s-1} \hat{\Pi}_{j} W_{t-j}$, and $\hat{V}_{t-1}$ is defined around (3.7). The following corollary gives the asymptotic distribution of $L R T_{G}^{*}$.

Corollary 3.3. Suppose the assumptions in Lemma 3.3 hold.

$$
\begin{equation*}
L R T_{G}^{*} \longrightarrow \mathcal{L} \operatorname{tr}\left\{\left[\zeta\left(I_{d}-\Lambda_{d}^{*}\right)^{1 / 2}+\Phi \Lambda_{d}^{* 1 / 2}\right]^{\prime}\left[\zeta\left(I_{d}-\Lambda_{d}^{*}\right)^{1 / 2}+\Phi \Lambda_{d}^{* 1 / 2}\right]\right\}, \tag{3.20}
\end{equation*}
$$

where $\Lambda_{d}^{*}$ is a diagonal matrix containing the $d$ eigenvalues of $\left(I_{d}-\Upsilon^{*} \Upsilon^{* \prime}\right)$, where $\Upsilon^{*}=\left(A_{\perp}^{\prime} \Omega_{1}^{*-1} A_{\perp}\right)^{-1 / 2}\left(A_{\perp}^{\prime} \Omega_{1}^{*-1} E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right) A_{\perp}\right)\left(A_{\perp}^{\prime} V^{*} A_{\perp}\right)^{-1 / 2}$, and the remaining variables are defined as in Theorem 3.3.

Some of the critical values for the distributions in (3.18) or (3.20) are tabulated in Section 5 and Appendix B of Sin and Ling (2004). Refer to Theorem 3.3 and Corollary 3.3. In actual empirical applications, one needs to estimate the $d$ eigenvalues of either $I_{d}-\Upsilon \Upsilon^{\prime}$ or those of $I_{d}-\Upsilon^{*} \Upsilon^{*}$, which involves $V^{*}, A_{\perp}, E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime} V_{t-1}^{-1}\right)$, $E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right)$, and $E\left(V_{t-1}^{-1}\right) . \quad V^{*}$ (see around (3.7) above) can be consistently estimated by $n^{-1} \sum_{t=1}^{n} \hat{\varepsilon}_{t} \hat{\varepsilon}_{t}^{\prime}$. Similarly, $A_{\perp}$ (see around (2.2) above) can be consistently estimated by $\left(I_{m}-c\left(\dot{A}^{\prime} c\right)^{-1} \dot{A}^{\prime}\right) c_{\perp}$, where $c=\left(I_{r}, 0_{r x d}\right)^{\prime}$ and $c_{\perp}=\left(0_{d x r}, I_{d}\right)^{\prime}$. See p. 48 of Johansen (1996) for details. Further, $E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime} V_{t-1}^{-1}\right), E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right)$ and $E\left(V_{t-1}^{-1}\right)$ can be consistently estimated by $n^{-1} \sum_{t=1}^{n} \hat{V}_{t-1}^{-1} \hat{\varepsilon}_{t} \hat{\varepsilon}_{t}^{\prime} \hat{V}_{t-1}^{-1}, n^{-1} \sum_{t=1}^{n} \hat{V}_{t-1}^{-1} \hat{\varepsilon}_{t} \hat{\varepsilon}_{t}^{\prime}$, and $n^{-1} \sum_{t=1}^{n} \hat{V}_{t-1}^{-1}$ respectively, where .

## 4 Allowing Asymmetric Distribution: With A Modified Weighting Matrix

In this section, we relax the symmetry assumption and consider the full rank estimation, the reduced rank estimation, as well as the test for reduced rank, par-
allel to those in Section 3. In Section 3, the only place we need symmetry is $E\left[U_{t-1}^{\prime} \otimes V_{t-1}^{-1}\right]=0$. In view of this, we consider a modified weighting matrix, which is denoted as $G_{t-1}$ when it is evaluated at the pseudo true parameters $(\alpha, \delta)$. $G_{t-1}$ is defined such that:

$$
\begin{equation*}
\nu\left(G_{t-1}\right) \equiv \nu\left(V_{t-1}^{-1}\right)-E\left[\nu\left(V_{t-1}^{-1}\right) U_{t-1}^{\prime}\right]\left[E U_{t-1} U_{t-1}^{\prime}\right]^{-1} U_{t-1} \tag{4.1}
\end{equation*}
$$

where $\nu($.$) is obtained from \operatorname{vec}($.$) by eliminating all supradiagonal elements of a$ square matrix (see Magnus, 1988, p.27). It should be noted that by construction, $E\left[\nu\left(G_{t-1}\right) U_{t-1}^{\prime}\right]=0$. Further, as $E\left(U_{t-1}\right)=0, E\left(G_{t-1}\right)=E\left(V_{t-1}^{-1}\right)$.

Refer to Sub-sections 3.1 and 3.2. Given the initial estimators $(\hat{\varphi}, \hat{\delta}) \in \Theta_{n}$ and $(\hat{\alpha}, \hat{\delta}) \in \Xi_{n}$, denote the sample analogue of $V_{t-1}^{-1}$ and $U_{t-1}$ as $\hat{V}_{t-1}^{-1}$ and $\hat{U}_{t-1}$ respectively, where similar to that in (1.3)-(1.4) and Theorem 3.1:

$$
\begin{align*}
& \hat{V}_{t-1}^{-1}=V_{t-1}^{-1}(\hat{\varphi}, \hat{\delta})  \tag{4.2}\\
& \hat{U}_{t-1}=U_{t-1}(\hat{\alpha}, \hat{\delta})=\left[\left(\hat{B} Y_{t-1}\right)^{\prime}, W_{t-1}^{\prime}, \cdots, W_{t-s+1}^{\prime}\right]^{\prime} \tag{4.3}
\end{align*}
$$

In fact, under the null that $\operatorname{rank}(C)=r, V_{t-1}^{-1}(\hat{\varphi}, \hat{\delta})$ in (4.2) can be replaced by $V_{t-1}^{-1}(\hat{\alpha}, \hat{\delta})$. Given (4.2)-(4.3), we can form a sample analogue of $G_{t-1}$, denoted as $\hat{G}_{t-1}$, where:

$$
\begin{equation*}
\nu\left(\hat{G}_{t-1}\right) \equiv \nu\left(\hat{V}_{t-1}^{-1}\right)-\left[\sum_{t=1}^{n} \nu\left(\hat{V}_{t-1}^{-1}\right) \hat{U}_{t-1}^{\prime}\right]\left[\sum_{t=1}^{n} \hat{U}_{t-1} \hat{U}_{t-1}^{\prime}\right]^{-1} \hat{U}_{t-1} \tag{4.4}
\end{equation*}
$$

Given $\hat{\varphi}$ and $\hat{G}_{t-1}($ see (4.4)), similar to (3.7) and abusing the notation, we perform one iteration of the full rank estimator:

$$
\begin{equation*}
\dot{\varphi}=\hat{\varphi}-\left[\sum_{t=1}^{n} \hat{F}_{t}\right]^{-1}\left[\sum_{t=1}^{n} \hat{f}_{t}\right] \tag{4.5}
\end{equation*}
$$

where $\hat{F}_{t}=-\left(X_{t-1} X_{t-1}^{\prime} \otimes \hat{G}_{t-1}\right), \hat{f}_{t}=\left(X_{t-1} \otimes I_{m}\right) \hat{G}_{t-1} \hat{\varepsilon}_{t}$, where as in Sub-section 3.1, $\hat{\varepsilon}_{t}=W_{t}-\hat{C} Y_{t-1}-\sum_{j=1}^{s-1} \hat{\Pi}_{j} W_{t-j}$.

In order to derive the asymptotic distribution of $\dot{\varphi}$, once again abusing the notation, we let $\left(W_{m}^{\prime}(u), W_{m}^{* \prime}(u)\right)^{\prime}$ be a $2 m$-dimensional Brownian motion (BM) with
the covariance matrix:

$$
u \Omega \equiv u\left(\begin{array}{cc}
V^{*} & E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} G_{t-1}\right) \\
E\left(G_{t-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right) & \Omega_{1}^{*}
\end{array}\right)
$$

where $V^{*}=E \varepsilon_{t} \varepsilon_{t}^{\prime}$, and $\Omega_{1}^{*}=E\left(G_{t-1} \varepsilon_{t} \varepsilon_{t}^{\prime} G_{t-1}\right)$. Let $B_{d}(u)=\Omega_{a_{1}}^{-1 / 2}\left[I_{d}, 0_{d x r}\right] \Omega_{a}^{1 / 2} V^{*-1 / 2} W_{m}(u)$, where $\Omega_{a}=E\left(a_{t} a_{t}^{\prime}\right)$ and $\Omega_{a_{1}}=\left[I_{d}, 0_{d x r}\right] \Omega_{a}\left[I_{d}, 0_{d x r}\right]^{\prime}$. The following is proved in the Appendix.

Theorem 4.1. Suppose Assumptions 2.1-2.4 hold. Then
(a) $n(\dot{C}-C) \bar{B}_{\perp}^{\prime} \longrightarrow{ }_{\mathcal{L}} \Omega_{1}^{-1} M^{*}$,
(b) $\sqrt{n} \operatorname{vec}\left[(\dot{C}-C) \bar{B}^{\prime},\left(\dot{\Pi}_{1}-\Pi_{1}\right), \ldots,\left(\dot{\Pi}_{s-1}-\Pi_{s-1}\right)\right] \longrightarrow_{\mathcal{L}} N\left(0, \Omega_{2}^{-1} \Omega_{2}^{*} \Omega_{2}^{-1}\right)$,
where $\psi_{11} \equiv\left[I_{d}, 0\right]\left(\sum_{k=1}^{\infty} \psi_{k}\right)\left[I_{d}, 0\right]^{\prime}, \Omega_{1} \equiv E\left(V_{t-1}^{-1}\right), \Omega_{2} \equiv E\left(U_{t-1} U_{t-1}^{\prime} \otimes G_{t-1}\right), \Omega_{2}^{*} \equiv$ $E\left(U_{t-1} U_{t-1}^{\prime} \otimes G_{t-1} \varepsilon_{t} \varepsilon_{t}^{\prime} G_{t-1}\right), U_{t-1}=\left[\left(B Y_{t-1}\right)^{\prime}, W_{t-1}^{\prime}, \cdots, W_{t-s+1}^{\prime}\right]^{\prime}$, and $M^{*}=$ $\left(\int_{0}^{1} B_{d}(u) d W_{m}^{*}(u)^{\prime}\right)^{\prime}\left(\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right)^{-1} \Omega_{a_{1}}^{-1 / 2} \psi_{11}^{-1}$.

It should be noted that the definitions of $\Omega_{1}^{*}, \Omega_{2}$ and $\Omega_{2}^{*}$ are essentially the same as those in Sub-section 3.1, with $V_{t-1}^{-1}$ replaced by $G_{t-1}$. The definitions of other variables (in particular that of $\Omega_{1}$ ) remain unchanged though.

Next we turn to the reduced rank estimation. Given $\hat{\alpha}$ and $\hat{G}_{t-1}$ (see (4.4)), similar to (3.14)-(3.15) and abusing the notation, we perform one iteration of the reduced rank estimators:

$$
\begin{align*}
& \dot{\alpha}_{1}=\hat{\alpha}_{1}-\left[\sum_{t=1}^{n} \hat{R}_{1 t}\right]^{-1}\left[\sum_{t=1}^{n} \hat{r}_{1 t}\right],  \tag{4.6}\\
& \dot{\alpha}_{2}=\hat{\alpha}_{2}-\left[\sum_{t=1}^{n} \dot{R}_{2 t}\right]^{-1}\left[\sum_{t=1}^{n} \dot{r}_{2 t}\right], \tag{4.7}
\end{align*}
$$

where $\hat{R}_{1 t}=-\left(Y_{t-1} Y_{t-1}^{\prime} \otimes \hat{A}^{\prime} \hat{G}_{t-1} \hat{A}\right), \dot{R}_{2 t}=-\left(\dot{U}_{t-1} \dot{U}_{t-1}^{\prime} \otimes \hat{G}_{t-1}\right)$;
$\hat{r}_{1 t}=\left(Y_{t-1} \otimes \hat{A}^{\prime}\right) \hat{G}_{t-1} \hat{\varepsilon}_{t}$, and $\dot{r}_{2 t}=\left(\dot{U}_{t-1} \otimes I_{m}\right) \hat{G}_{t-1} \dot{\varepsilon}_{t}$, where as in Sub-section 3.2, $\dot{U}_{t-1}=\left[\left(\dot{B} Y_{t-1}\right)^{\prime}, W_{t-1}^{\prime}, \ldots, W_{t-s+1}^{\prime}\right]^{\prime}$ and $\dot{\varepsilon}_{t}=W_{t}-\hat{A} \dot{B} Y_{t-1}-\sum_{j=1}^{s-1} \hat{\Pi}_{j} W_{t-j}$.

Refer to (4.6)-(4.7), the asymptotic distributions of the normalized estimators for $\alpha_{1}$ and $\alpha_{2}$ are given as follows.

Theorem 4.2. Suppose Assumptions 2.1-2.4 hold. Then

$$
\begin{equation*}
n\left(\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-B\right) \bar{B}_{\perp}^{\prime} \longrightarrow_{\mathcal{L}}\left(A^{\prime} \Omega_{1} A\right)^{-1} A^{\prime} M^{*} \tag{a}
\end{equation*}
$$

(b) $\sqrt{n} \operatorname{vec}\left[\left(\dot{A}\left(\dot{B} \bar{B}^{\prime}\right)-A\right),\left(\dot{\Pi}_{1}-\Pi_{1}\right), \ldots,\left(\dot{\Pi}_{s-1}-\Pi_{s-1}\right)\right] \longrightarrow_{\mathcal{L}} N\left(0, \Omega_{2}^{-1} \Omega_{2}^{*} \Omega_{2}^{-1}\right)$,
where the remaining variables are defined as in Theorem 4.1.
Given Theorems 4.1 and 4.2, parallel to Sub-section 3.3, we may define a modified LRT test statistic for reduced rank, where abusing notation:

$$
\begin{equation*}
L R T_{G}^{*} \equiv\left[\operatorname{vec}\left(\dot{C}^{*}\right)-\operatorname{vec}\left(\dot{A} \dot{B}^{*}\right)\right]^{\prime}\left[-\sum_{t=1}^{n} \hat{F}_{11 t}^{*}\right]\left[\operatorname{vec}\left(\dot{C}^{*}\right)-\operatorname{vec}\left(\dot{A} \dot{B}^{*}\right)\right], \tag{4.8}
\end{equation*}
$$

where $\operatorname{vec}\left(\dot{C}^{*}\right)=\left(-\sum_{t=1}^{n} \hat{F}_{11 t}^{*}\right)^{-1}\left(-\sum_{t=1}^{n} \hat{F}_{11 t}\right) \operatorname{vec}(\dot{C}), \dot{B}^{*}=\left(\dot{A}^{\prime} \dot{\Omega}_{1}^{*} \dot{A}\right)^{-1}\left(\dot{A}^{\prime} \dot{\Omega}_{1} \dot{A}\right) \dot{B}$, $\hat{F}_{11 t}=-\left(Y_{t-1} Y_{t-1}^{\prime} \otimes \hat{G}_{t-1}\right)$, and $\hat{F}_{11 t}^{*}=-\left(Y_{t-1} Y_{t-1}^{\prime} \otimes \hat{G}_{t-1} \hat{\varepsilon}_{t} \hat{\varepsilon}_{t} \hat{G}_{t-1}\right)$.

The following corollary gives the asymptotic distribution of $L R T_{G}^{*}$.
Corollary 4.3. Suppose Assumptions 2.1-2.4 hold. Then under $H_{0}$ in (3.16), the modified $L R$ test statistic for reduced rank,

$$
\begin{equation*}
L R T_{G}^{*} \longrightarrow \mathcal{L} \operatorname{tr}\left\{\left[\zeta\left(I_{d}-\Lambda_{d}^{*}\right)^{1 / 2}+\Phi \Lambda_{d}^{* 1 / 2}\right]^{\prime}\left[\zeta\left(I_{d}-\Lambda_{d}^{*}\right)^{1 / 2}+\Phi \Lambda_{d}^{* 1 / 2}\right]\right\} \tag{4.9}
\end{equation*}
$$

where $\Lambda_{d}^{*}$ is a diagonal matrix containing the d eigenvalues of $\left(I_{d}-\Upsilon^{*} \Upsilon^{* \prime}\right)$, $\Upsilon^{*}=$ $\left(A_{\perp}^{\prime} \Omega_{1}^{*-1} A_{\perp}\right)^{-1 / 2}\left(A_{\perp}^{\prime} \Omega_{1}^{*-1} E\left(G_{t-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right) A_{\perp}\right)\left(A_{\perp}^{\prime} V^{*} A_{\perp}\right)^{-1 / 2}$, where we recall that $\Omega_{1}^{*}=$ $E\left(G_{t-1} \varepsilon_{t} \varepsilon_{t}^{\prime} G_{t-1}\right)$ and the remaining variables are defined as in Theorem 4.1.

## 5 Allowing Asymmetric Distribution: Without Modifying the Weighting Matrix

Similar to the previous section, this section also relaxes the symmetry assumption and consider the full rank estimation, the reduced rank estimation, as well as the test for reduced rank, parallel to those in Section 3. Nevertheless, in order to maintain the original the weighting matrix, we consider more involved procedures and more elaborate asymptotic distributions.

Consider the full rank estimation and refer to Sub-section 3.1. Given the initial estimators $(\hat{\varphi}, \hat{\delta}) \in \Theta_{n}$, we perform a one-step iteration of the full rank estimator:

$$
\begin{equation*}
\dot{\varphi}=\hat{\varphi}-\left[\sum_{t=1}^{n} F_{t}(\hat{\varphi}, \hat{\delta})\right]^{-1}\left[\sum_{t=1}^{n} f_{t}(\hat{\varphi}, \hat{\delta})\right] . \tag{5.1}
\end{equation*}
$$

It should be noted that the procedure in (5.1) is exactly the same as that in (3.7). Nevertheless, due to the possibly asymmetric distribution, the asymptotic distribution is different, as one can see in the next theorem.

Theorem 5.1. Suppose Assumptions 2.1-2.4 hold. Then

$$
D^{*} Q^{*^{\prime}-1}(\dot{\varphi}-\varphi) \longrightarrow \mathcal{L}\left(\begin{array}{cc}
Z \otimes \Omega_{1} & \left(L \otimes I_{m}\right) \Sigma \\
\Sigma^{\prime}\left(L^{\prime} \otimes I_{m}\right) & \Omega_{2}
\end{array}\right)^{-1}\binom{W^{*}}{\Omega_{2}^{* 1 / 2} \Phi}
$$

where $Z=\psi_{11} \Omega_{a_{1}}^{1 / 2}\left(\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right) \Omega_{a_{1}}^{1 / 2} \psi_{11}^{\prime}, L=\psi_{11} \Omega_{a_{1}}^{1 / 2}\left(\int_{0}^{1} B_{d}(u) d u\right), \Sigma=E\left(U_{t-1}^{\prime} \otimes\right.$ $\left.V_{t-1}^{-1}\right), W^{*}=\left(\psi_{11} \Omega_{a_{1}}^{1 / 2} \otimes I_{m}\right) \operatorname{vec}\left[\left(\int_{0}^{1} B_{d} d W_{m}^{*}(u)^{\prime}\right)^{\prime}\right]$, and the remaining variables are defined as in Lemma 2.1.

Next we turn to the reduced rank estimation. Refer to the ECM in (3.8), as $B B_{\perp}^{\prime}=0$,

$$
\begin{aligned}
V_{t-1}^{-1 / 2} W_{t} & =V_{t-1}^{-1 / 2} \varepsilon_{t}+V_{t-1}^{-1 / 2} A B Y_{t-1}+\sum_{j=1}^{s-1} V_{t-1}^{-1 / 2} \Pi_{j} W_{t-j}+V_{t-1}^{-1 / 2} A B \bar{B}_{\perp}^{\prime} B_{\perp} Y_{t-1} \\
\Longrightarrow V_{t-1}^{-1 / 2} W_{t} & =V_{t-1}^{-1 / 2} \varepsilon_{t}+\left(B_{\perp} Y_{t-1} \otimes A^{\prime} V_{t-1}^{-1 / 2}\right) \operatorname{vec}\left(B \bar{B}_{\perp}^{\prime}\right)+\left(U_{t-1} \otimes V_{t-1}^{-1 / 2}\right) \alpha_{2},
\end{aligned}
$$

where we recall from Sections 2 and 3 that $\bar{B}_{\perp}^{\prime}=B_{\perp}^{\prime}\left(B_{\perp} B_{\perp}^{\prime}\right)^{-1}$ and $U_{t-1}=\left[\left(B Y_{t-1}\right)^{\prime}, W_{t-1}^{\prime}, \cdots, W_{t-s+1}^{\prime}\right]^{\prime}$.

However in deriving the LRT test for reduced rank, we need a $n$ - consistent estimator for $B$ itself. Note $\operatorname{vec}\left(B \bar{B}_{\perp}^{\prime}\right)=\left[\left(B_{\perp} B_{\perp}^{\prime}\right)^{-1} B_{\perp} \otimes I_{r}\right] \operatorname{vec}(B)$. Define $\hat{B}_{\perp} \equiv$ $c_{\perp}^{\prime}\left(I_{m}-\hat{B}^{\prime}\left(c^{\prime} \hat{B}^{\prime}\right)^{-1} c^{\prime}\right)$, where $c=\left(I_{r}, 0_{r x d}\right)^{\prime}$ and $c_{\perp}=\left(0_{d x r}, I_{d}\right)^{\prime}$. See p. 48 of Johansen (1996) for details. $\hat{B}_{\perp}$ is an $n-$ consistent estimator for $B_{\perp}$. Abusing the notation, a natural estimator for $\alpha$ is:

$$
\begin{equation*}
\operatorname{diag}\left(\hat{B}_{\perp}^{\prime} \otimes I_{r}, I_{r m+(s-1) m^{2}}\right)\left(\sum_{t=1}^{n} \hat{P}_{t}\right)^{-1}\left(\sum_{t=1}^{n} \hat{\phi}_{t}\right), \tag{5.2}
\end{equation*}
$$

where

$$
\hat{P}_{t}=\left(\begin{array}{cc}
\hat{B}_{\perp} Y_{t-1} Y_{t-1}^{\prime} \hat{B}_{\perp}^{\prime} \otimes \hat{A}^{\prime} \hat{V}_{t-1}^{-1} \hat{A} & \hat{B}_{\perp} Y_{t-1} \hat{U}_{t-1}^{\prime} \otimes \hat{A}^{\prime} \hat{V}_{t-1}^{-1} \\
\hat{U}_{t-1} Y_{t-1}^{\prime} \hat{B}_{\perp}^{\prime} \otimes \hat{V}_{t-1}^{-1} & \hat{U}_{t-1} \hat{U}_{t-1}^{\prime} \otimes \hat{V}_{t-1}^{-1}
\end{array}\right),
$$

$$
\hat{\phi}_{t}=\binom{\hat{B}_{\perp} Y_{t-1} \otimes \hat{A}^{\prime} \hat{V}_{t-1}^{-1} W_{t}}{\hat{U}_{t-1} \otimes \hat{V}_{t-1}^{-1} W_{t}},
$$

Following the lines in the previous sections and abusing the notation, as an alternative to (5.2), we can estimate $\alpha_{1}$ and $\alpha_{2}$ separately, where:

$$
\begin{align*}
& \dot{\alpha}_{1}=\hat{\alpha}_{1}-\left[\hat{B}_{\perp}^{\prime} \otimes I_{r}, 0_{m r x\left(r m+(s-1) m^{2}\right)}\right]\left[\sum_{t=1}^{n} P_{t}\left(\hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right]^{-1}\left[\sum_{t=1}^{n} p_{t}\left(\hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right],  \tag{5.3}\\
& \dot{\alpha}_{2}=\hat{\alpha}_{2}-\left[0_{\left(r m+(s-1) m^{2}\right) x m d}, I_{r m+(s-1) m^{2}}\right]\left[\sum_{t=1}^{n} P_{t}\left(\dot{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right]^{-1}\left[\sum_{t=1}^{n} p_{t}\left(\dot{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\delta}\right)\right], \tag{5.4}
\end{align*}
$$

where for a generic $(\tilde{\alpha}, \tilde{\delta})$,

$$
\begin{gathered}
P_{t}(\tilde{\alpha}, \tilde{\delta})=\left(\begin{array}{cc}
\tilde{B}_{\perp} Y_{t-1} Y_{t-1}^{\prime} \tilde{B}_{\perp}^{\prime} \otimes \tilde{A}^{\prime} \tilde{V}_{t-1}^{-1} \tilde{A} & \tilde{B}_{\perp} Y_{t-1} \tilde{U}_{t-1}^{\prime} \otimes \tilde{A}^{\prime} \tilde{V}_{t-1}^{-1} \\
\tilde{U}_{t-1} Y_{t-1}^{\prime} \tilde{B}_{\perp}^{\prime} \otimes \tilde{V}_{t-1}^{-1} \tilde{A} & \tilde{U}_{t-1} \tilde{U}_{t-1}^{\prime} \otimes \tilde{V}_{t-1}^{-1}
\end{array}\right), \\
p_{t}(\tilde{\alpha}, \tilde{\delta})=\binom{\tilde{B}_{\perp} Y_{t-1} \otimes \tilde{A}^{\prime} \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t}}{\tilde{U}_{t-1} \otimes \tilde{V}_{t-1}^{-1} \tilde{\varepsilon}_{t}} .
\end{gathered}
$$

Theorem 5.2. Suppose Assumptions 2.1-2.4 hold. Then

$$
D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha) \longrightarrow \mathcal{L}\left(\begin{array}{cc}
Z \otimes A^{\prime} \Omega_{1} A & \left(L \otimes A^{\prime}\right) \Sigma \\
\Sigma^{\prime}\left(L^{\prime} \otimes A\right) & \Omega_{2}
\end{array}\right)^{-1}\binom{\left(I_{d} \otimes A^{\prime}\right) W^{*}}{\Omega_{2}^{* / 2} \Phi}
$$

where $\ddot{\alpha}=\left(\ddot{\alpha}_{1}^{\prime}, \ddot{\alpha}_{2}^{\prime}\right)^{\prime}, \ddot{\alpha}_{1}=\operatorname{vec}\left(\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \dot{B}\right)$ and $\ddot{\alpha}_{2}=\operatorname{vec}\left(\dot{A}\left(\dot{B} \bar{B}^{\prime}\right), \dot{\Pi}_{1}, \ldots, \dot{\Pi}_{s-1}\right)$, and the remaining variables are defined as in Lemma 2.1 or Theorem 5.1.

Refer to the null and the alternative hypotheses in (3.16). Similar to (3.17) and abusing the notation, we first consider the Likelihood Ratio-Type (LRT) test statistic:
$L R T_{G} \equiv\left[\dot{\varphi}-\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}\right]^{\prime}\left[-\sum_{t=1}^{n} \hat{F}_{t}\right]\left[\dot{\varphi}-\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}\right]$,
where $\dot{\chi} \equiv\left(\dot{\alpha}_{1}^{\prime}, \dot{\alpha}_{22}^{\prime}\right)^{\prime}, \dot{\alpha}_{22}$ is the reduced-rank estimator for $\alpha_{22} \equiv \operatorname{vec}\left(\Pi_{1}, \ldots, \Pi_{s-1}\right)$. Compare (3.17) with (5.5). The inclusion of parameters other than $A$ and $B$ is due to the possible asymmetric distribution. Similar to the proof of Lemma 3.3, it can be shown that:

$$
\begin{aligned}
& D^{*} Q^{*^{\prime}-1}\left[\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}-\varphi\right] \\
= & D^{*} Q^{*^{\prime}-1}\left[\operatorname{diag}\left(I_{m} \otimes \dot{A}\left(\dot{B} \bar{B}^{\prime}\right), I_{(s-1) m^{2}}\right)\left(\ddot{\alpha}_{1}^{\prime}, \dot{\alpha}_{22}^{\prime}\right)-\varphi\right] \\
= & \operatorname{diag}\left(I_{d} \otimes A, I_{(s-1) m^{2}}\right) D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha)+o_{p}(1) .
\end{aligned}
$$

As a result,

$$
\begin{align*}
& {\left[D^{*} Q^{*^{\prime}-1}\left(\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}-\varphi\right)\right]^{\prime}\left[-D^{*-1} Q^{*} \sum_{t=1}^{n} \hat{t}_{t} Q^{*^{\prime}} D^{*-1}\right] } \\
& \cdot\left[D^{*} Q^{*^{\prime}-1}\left(\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}-\varphi\right)\right] \\
= & {\left[D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha)\right]^{\prime}\left[-D^{* *-1} Q^{* *} \sum_{t=1}^{n} R_{t} Q^{* *^{\prime}} D^{* *-1}\right]\left[D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha)\right]+o_{p}(1) . } \tag{5.6}
\end{align*}
$$

In a similar token,

$$
\begin{align*}
& {\left[D^{*} Q^{*^{\prime}-1}\left(\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}-\varphi\right)\right]^{\prime}\left[-D^{*-1} Q^{*} \sum_{t=1}^{n} \hat{F}_{t} Q^{*^{\prime}} D^{*-1}\right]\left[D^{*} Q^{*^{\prime}-1}(\dot{\varphi}-\varphi)\right] } \\
= & {\left[D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha)\right]^{\prime}\left[-D^{* *-1} Q^{* *} \sum_{t=1}^{n} R_{t} Q^{* *^{\prime}} D^{* *-1}\right]\left[D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha)\right]+o_{p}(1) } \tag{5.7}
\end{align*}
$$

Therefore, by Theorems 5.1 and 5.2,
$L R T_{G}$

$$
\begin{align*}
= & {\left[D^{*} Q^{*^{\prime}-1}(\dot{\varphi}-\varphi)\right]^{\prime}\left[-D^{*-1} Q^{*} \sum_{t=1}^{n} F_{t} Q^{*^{\prime}} D^{*-1}\right]\left[D^{*} Q^{*^{\prime}-1}(\dot{\varphi}-\varphi)\right] } \\
& -\left[D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha)\right]^{\prime}\left[-D^{* *-1} Q^{* *} \sum_{t=1}^{n} R_{t} Q^{* *^{\prime}} D^{* *-1}\right]\left[D^{* *} Q^{* *^{\prime}-1}(\ddot{\alpha}-\alpha)\right]+o_{p}(1) \\
\longrightarrow \mathcal{L} & \binom{w^{*}}{\Phi}^{\prime}\left(\begin{array}{cc}
z \otimes \Omega_{1}^{*-1 / 2} \Omega_{1} \Omega_{1}^{*-1 / 2} & \left(l \otimes \Omega_{1}^{*-1 / 2}\right) \Sigma \Omega_{2}^{*-1 / 2} \\
\Omega_{2}^{*-1 / 2} \Sigma^{\prime}\left(l^{\prime} \otimes \Omega_{1}^{*-1 / 2}\right) & \Omega_{2}^{*-1 / 2} \Omega_{2} \Omega_{2}^{*-1 / 2}
\end{array}\right)^{-1}\binom{w^{*}}{\Phi} \\
& -\binom{w^{*}}{\Phi}^{\prime} \mathcal{A}^{*}\left[\mathcal{A}^{*^{\prime}}\left(\begin{array}{cc}
z \otimes \Omega_{1}^{*-1 / 2} \Omega_{1} \Omega_{1}^{*-1 / 2} & \left(l \otimes \Omega_{1}^{*-1 / 2}\right) \Sigma \Omega_{2}^{*-1 / 2} \\
\Omega_{2}^{*-1 / 2} \Sigma^{\prime}\left(l^{\prime} \otimes \Omega_{1}^{*-1 / 2}\right) & \Omega_{2}^{*-1 / 2} \Omega_{2} \Omega_{2}^{*-1 / 2}
\end{array}\right) \mathcal{A}^{*}\right]^{-1} \\
& \cdot \mathcal{A}^{*}\binom{w^{*}}{\Phi}, \tag{5.8}
\end{align*}
$$

where $w^{*}=\operatorname{vec}\left[\left(\int_{0}^{1} B_{d} d w_{m}^{*}(u)^{\prime}\right)^{\prime}\right], w_{m}^{*}(u)=\Omega_{1}^{*-1 / 2} W_{m}^{*}(u)$, and $\mathcal{A}^{*}=\operatorname{diag}\left(I_{d} \otimes\right.$ $\left.\Omega_{1}^{* 1 / 2} A, \Omega_{1}^{* 1 / 2}\right), z=\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u$, and $l=\int_{0}^{1} B_{d}(u) d u$.

Denoting

$$
\left(\begin{array}{cc}
z \otimes \Omega_{1}^{*-1 / 2} \Omega_{1} \Omega_{1}^{*-1 / 2} & \left(l \otimes \Omega_{1}^{*-1 / 2}\right) \Sigma \Omega_{2}^{*-1 / 2} \\
\Omega_{2}^{*-1 / 2} \Sigma^{\prime}\left(l^{\prime} \otimes \Omega_{1}^{*-1 / 2}\right) & \Omega_{2}^{*-1 / 2} \Omega_{2} \Omega_{2}^{*-1 / 2}
\end{array}\right)
$$

as $\Omega^{* *}$, the following lemma gives the asymptotic distribution of the $L R T_{G}$ in (5.5).
Lemma 5.3. Suppose Assumptions 2.1-2.4 hold. Then under $H_{0}$ in (3.16), the $L R T$ test statistic for rank in (5.5),

$$
\begin{equation*}
L R T_{G} \longrightarrow \mathcal{L}\binom{w^{*}}{\Phi}^{\prime} \Omega^{* *-1} \mathcal{A}_{\perp}^{*}\left(\mathcal{A}_{\perp}^{* \prime} \Omega^{* *-1} \mathcal{A}_{\perp}^{*}\right)^{-1} \mathcal{A}_{\perp}^{*^{\prime}} \Omega^{* *-1}\binom{w^{*}}{\Phi} \tag{5.9}
\end{equation*}
$$

where $\mathcal{A}_{\perp}^{*}=\left(I_{d} \otimes A_{\perp}^{\prime} \Omega_{1}^{*-1 / 2}, 0_{d^{2} x\left(r m+(s-1) m^{2}\right)}\right)$.
When the $\varepsilon_{t}^{\prime}$ 's are conditional homoskedastic, $E\left(V_{t-1}^{-1} \varepsilon_{t} \varepsilon_{t}^{\prime}\right)=I_{m}$, and $\Sigma=0$, it can be shown that the distribution of $L R T_{G}$ is exactly the same as that in Reinsel and Ahn (1992) and Johansen (1996). When $E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} \mid \mathcal{I}_{t-1}\right)=V_{t-1}$ and $V_{t-1}$ may or may not equal to $I_{m}$, the distribution of $L R T_{G}$ can be simplified as follows.

Theorem 5.3. Suppose the assumptions in Lemma 5.3 hold. If $E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} \mid \mathcal{I}_{t-1}\right)=$ $V_{t-1}$, then

$$
\begin{equation*}
L R T_{G} \longrightarrow \mathcal{L}\binom{w}{\Phi}^{\prime} \Omega^{-1} \mathcal{A}_{\perp}\left(\mathcal{A}_{\perp}^{\prime} \Omega^{-1} \mathcal{A}_{\perp}\right)^{-1} \mathcal{A}_{\perp}^{\prime} \Omega^{-1}\binom{w}{\Phi} \tag{5.10}
\end{equation*}
$$

where $\Omega$ is defined as

$$
\left(\begin{array}{cc}
z \otimes I_{m} & \left(l \otimes \Omega_{1}^{-1 / 2}\right) \Sigma \Omega_{2}^{-1 / 2} \\
\Omega_{2}^{-1 / 2} \Sigma^{\prime}\left(l^{\prime} \otimes \Omega_{1}^{-1 / 2}\right) & I_{m}
\end{array}\right),
$$

and $\mathcal{A}_{\perp}^{\prime}=\left(I_{d} \otimes A_{\perp}^{\prime} \Omega_{1}^{-1 / 2}, 0_{d^{2} x\left(r m+(s-1) m^{2}\right)}\right), w=\operatorname{vec}\left[\left(\int_{0}^{1} B_{d} d w_{m}(u)^{\prime}\right)^{\prime}\right], w_{m}(u)=$ $\Omega_{1}^{-1 / 2} W_{m}^{*}(u)$.

On the other hand, when $E\left(\varepsilon_{t} \varepsilon_{t}^{\prime} \mid \mathcal{I}_{t-1}\right) \neq V_{t-1}$, we may define a modified LRT test statistic:

$$
\begin{align*}
L R T_{G}^{*} \equiv & {\left[\dot{\varphi}-\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}\right]^{\prime}\left[-\sum_{t=1}^{n} \hat{F}_{t}\right]\left[-\sum_{t=1}^{n} \hat{F}_{t}^{*}\right]^{-1} } \\
& \cdot\left[-\sum_{t=1}^{n} \hat{F}_{t}\right]\left[\dot{\varphi}-\operatorname{diag}\left(I_{m} \otimes \dot{A}, I_{(s-1) m^{2}}\right) \dot{\chi}\right], \tag{5.11}
\end{align*}
$$

where $\hat{F}_{t}^{*}=-\left(X_{t-1} X_{t-1}^{\prime} \otimes \hat{V}_{t-1}^{-1} \hat{\varepsilon}_{t} \hat{\varepsilon}_{t}^{\prime} \hat{t}_{t-1}^{-1}\right)$. The following corollary gives the asymptotic distribution of $L R T_{G}^{*}$.

Corollary 5.3. Suppose the assumptions in Lemma 5.3 hold. Then

$$
\begin{equation*}
L R T_{G}^{*} \longrightarrow \mathcal{L}\binom{w^{*}}{\Phi}^{\prime} \Omega^{*-1} \mathcal{A}_{\perp}^{*}\left(\mathcal{A}_{\perp}^{*^{\prime}} \Omega^{*-1} \mathcal{A}_{\perp}\right)^{*-1} \mathcal{A}_{\perp}^{*^{\prime}} \Omega^{*-1}\binom{w^{*}}{\Phi} \tag{5.12}
\end{equation*}
$$

where $\Omega^{*}$ is defined as

$$
\left(\begin{array}{cc}
z \otimes I_{m} & \left(l \otimes \Omega_{1}^{*-1 / 2}\right) \Sigma \Omega_{2}^{*-1 / 2} \\
\Omega_{2}^{*-1 / 2} \Sigma^{\prime}\left(l^{\prime} \otimes \Omega_{1}^{*-1 / 2}\right) & I_{m}
\end{array}\right),
$$

and all the other variables are defined above.

## 6 WLS versus QMLE: Efficiency and Computational Matters

## 7 Monte Carlo Experiments

## 8 An Empirical Example

## 9 Conclusions

Macroeconomic or financial data are often modelled with cointegration and GARCH. Noticeable examples include those studies of price discovery, in which stock prices of the same underlying asset are cointegrated and they exhibit multivariate GARCH. Modifying the asymptotic theories developed in Li, Ling and Wong (2001) and Sin and Ling (2004), this paper proposes a WLS (weighted least squares) for the parameters of an ECM (error-correction model). Apart from its computational simplicity, by construction, the consistency of WLS is insensitive to possible mis-specification in conditional variance. Further, asymmetrically distributed deflated error is allowed, at the expense of more deliberate estimation procedures. Efficiency loss relative to QMLE (quasi-maximum likelihood estimator) is discussed within the class of LABF (locally asymptotically Brownian functional) models. The insensitivity and efficiency of WLS in finite samples are examined through Monte Carlo experiments. We also apply the WLS to an empirical example of HSI (Hang Seng Index), HSIF (Hang Seng Index Futures) and TraHK (Hong Kong Tracker Fund).

## A Appendix: Critical Values

TABLE A. 1
Quantiles of the Limiting Distribution (5.3) or (5.5) $d=1$, no Constant Term

| $\alpha$-th simulated quantiles |  |  |  |  |  |  |  |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $\lambda_{1}$ | .500 | .750 | .800 | .850 | .900 | .950 | .975 | .990 |
| 0.0 | 0.602 | 1.550 | 1.891 | 2.343 | 2.995 | 4.153 | 5.357 | 7.018 |
| 0.1 | 0.575 | 1.539 | 1.869 | 2.315 | 2.978 | 4.140 | 5.365 | 6.941 |
| 0.2 | 0.553 | 1.511 | 1.850 | 2.308 | 2.964 | 4.138 | 5.362 | 6.939 |
| 0.3 | 0.533 | 1.489 | 1.824 | 2.282 | 2.941 | 4.108 | 5.305 | 6.921 |
| 0.4 | 0.515 | 1.462 | 1.800 | 2.254 | 2.914 | 4.083 | 5.286 | 6.929 |
| 0.5 | 0.499 | 1.441 | 1.770 | 2.223 | 2.883 | 4.043 | 5.242 | 6.895 |
| 0.6 | 0.490 | 1.414 | 1.743 | 2.197 | 2.845 | 4.013 | 5.225 | 6.824 |
| 0.7 | 0.481 | 1.385 | 1.718 | 2.171 | 2.811 | 3.963 | 5.174 | 6.839 |
| 0.8 | 0.470 | 1.364 | 1.693 | 2.139 | 2.782 | 3.920 | 5.097 | 6.774 |
| 0.9 | 0.461 | 1.354 | 1.674 | 2.105 | 2.746 | 3.867 | 5.047 | 6.718 |
| 1.0 | 0.455 | 1.326 | 1.649 | 2.078 | 2.711 | 3.827 | 5.068 | 6.633 |

The table values were computed from 100,000 simulations with $n=2,000$.
$\lambda_{1}$ is the eigenvalue of $\Lambda_{1}$ in (5.3) or $\Lambda_{1}^{*}$ in (5.5).

## TABLE A. 2

## Quantiles of the Limiting Distribution (5.3) or (5.5)

$$
d=2 \text {, no Constant Term }
$$

|  | $\alpha$-th simulated quantiles |  |  |  |  |  |  |  |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $\lambda_{1}$ | $\lambda_{2}$ | .500 | .750 | .800 | .850 | .900 | .950 | .975 | .990 |
| 0.0 | 0.0 | 5.508 | 7.844 | 8.522 | 9.365 | 10.479 | 12.286 | 14.065 | 16.278 |
| 0.0 | 0.1 | 5.405 | 7.739 | 8.413 | 9.267 | 10.386 | 12.237 | 13.971 | 16.144 |
| 0.0 | 0.2 | 5.298 | 7.645 | 8.313 | 9.159 | 10.312 | 12.158 | 13.886 | 16.041 |
| 0.0 | 0.3 | 5.189 | 7.541 | 8.210 | 9.062 | 10.234 | 12.073 | 13.793 | 15.986 |
| 0.0 | 0.4 | 5.068 | 7.440 | 8.112 | 8.959 | 10.119 | 11.987 | 13.722 | 15.895 |
| 0.0 | 0.5 | 4.952 | 7.330 | 8.008 | 8.865 | 10.003 | 11.887 | 13.659 | 15.802 |
| 0.0 | 0.6 | 4.839 | 7.216 | 7.909 | 8.744 | 9.906 | 11.789 | 13.542 | 15.716 |
| 0.0 | 0.7 | 4.726 | 7.112 | 7.783 | 8.647 | 9.796 | 11.676 | 13.440 | 15.623 |
| 0.0 | 0.8 | 4.619 | 6.981 | 7.668 | 8.525 | 9.680 | 11.559 | 13.354 | 15.530 |
| 0.0 | 0.9 | 4.504 | 6.867 | 7.542 | 8.410 | 9.551 | 11.446 | 13.230 | 15.435 |
| 0.0 | 1.0 | 4.393 | 6.745 | 7.417 | 8.268 | 9.443 | 11.306 | 13.172 | 15.450 |
| 0.1 | 0.1 | 5.287 | 7.635 | 8.325 | 9.172 | 10.295 | 12.140 | 13.885 | 16.105 |
| 0.1 | 0.2 | 5.178 | 7.534 | 8.229 | 9.079 | 10.217 | 12.071 | 13.817 | 15.991 |
| 0.1 | 0.3 | 5.058 | 7.440 | 8.123 | 8.979 | 10.125 | 11.987 | 13.736 | 15.920 |
| 0.1 | 0.4 | 4.945 | 7.341 | 8.023 | 8.865 | 10.018 | 11.902 | 13.612 | 15.806 |
| 0.1 | 0.5 | 4.832 | 7.224 | 7.920 | 8.750 | 9.919 | 11.818 | 13.539 | 15.643 |
| 0.1 | 0.6 | 4.718 | 7.108 | 7.791 | 8.643 | 9.808 | 11.692 | 13.422 | 15.552 |
| 0.1 | 0.7 | 4.605 | 6.987 | 7.677 | 8.533 | 9.679 | 11.578 | 13.296 | 15.482 |
| 0.1 | 0.8 | 4.498 | 6.856 | 7.559 | 8.413 | 9.561 | 11.434 | 13.179 | 15.337 |
| 0.1 | 0.9 | 4.382 | 6.749 | 7.430 | 8.290 | 9.455 | 11.284 | 13.064 | 15.247 |
| 0.1 | 1.0 | 4.278 | 6.627 | 7.307 | 8.157 | 9.307 | 11.147 | 12.950 | 15.229 |
| 0.2 | 0.2 | 5.070 | 7.445 | 8.137 | 8.987 | 10.116 | 11.973 | 13.707 | 15.898 |
| 0.2 | 0.3 | 4.945 | 7.336 | 8.037 | 8.881 | 10.028 | 11.879 | 13.601 | 15.812 |
| 0.2 | 0.4 | 4.828 | 7.225 | 7.916 | 8.761 | 9.916 | 11.791 | 13.501 | 15.647 |
| 0.2 | 0.5 | 4.711 | 7.111 | 7.807 | 8.658 | 9.819 | 11.691 | 13.383 | 15.556 |
| 0.2 | 0.6 | 4.596 | 6.998 | 7.682 | 8.532 | 9.691 | 11.566 | 13.298 | 15.405 |
| 0.2 | 0.7 | 4.488 | 6.881 | 7.560 | 8.415 | 9.579 | 11.433 | 13.191 | 15.319 |
| 0.2 | 0.8 | 4.383 | 6.753 | 7.435 | 8.288 | 9.453 | 11.293 | 13.027 | 15.191 |
| 0.2 | 0.9 | 4.266 | 6.621 | 7.309 | 8.165 | 9.322 | 11.141 | 12.902 | 15.023 |
| 0.2 | 1.0 | 4.160 | 6.502 | 7.190 | 8.031 | 9.182 | 10.985 | 12.768 | 15.020 |
| 0.3 | 0.3 | 4.830 | 7.232 | 7.929 | 8.781 | 9.931 | 11.752 | 13.491 | 15.702 |
| 0.3 | 0.4 | 4.717 | 7.118 | 7.809 | 8.657 | 9.816 | 11.669 | 13.411 | 15.609 |
| 0.3 | 0.5 | 4.598 | 7.001 | 7.688 | 8.540 | 9.693 | 11.570 | 13.285 | 15.471 |
|  |  |  |  |  |  |  |  |  |  |

TABLE A. 2 (Continued)

|  | $\alpha$-th simulated quantiles |  |  |  |  |  |  |  |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $\lambda_{1}$ | $\lambda_{2}$ | .500 | .750 | .800 | .850 | .900 | .950 | .975 | .990 |
| 0.3 | 0.6 | 4.489 | 6.877 | 7.570 | 8.415 | 9.565 | 11.432 | 13.179 | 15.318 |
| 0.3 | 0.7 | 4.369 | 6.758 | 7.442 | 8.281 | 9.442 | 11.296 | 13.051 | 15.202 |
| 0.3 | 0.8 | 4.263 | 6.636 | 7.302 | 8.160 | 9.310 | 11.158 | 12.897 | 15.021 |
| 0.3 | 0.9 | 4.152 | 6.505 | 7.187 | 8.042 | 9.163 | 11.010 | 12.743 | 14.870 |
| 0.3 | 1.0 | 4.052 | 6.374 | 7.045 | 7.882 | 9.046 | 10.819 | 12.592 | 14.853 |
| 0.4 | 0.4 | 4.600 | 7.006 | 7.695 | 8.549 | 9.707 | 11.557 | 13.290 | 15.510 |
| 0.4 | 0.5 | 4.486 | 6.877 | 7.577 | 8.420 | 9.576 | 11.438 | 13.180 | 15.374 |
| 0.4 | 0.6 | 4.373 | 6.760 | 7.444 | 8.287 | 9.440 | 11.310 | 13.061 | 15.231 |
| 0.4 | 0.7 | 4.255 | 6.631 | 7.318 | 8.148 | 9.313 | 11.171 | 12.881 | 15.087 |
| 0.4 | 0.8 | 4.150 | 6.506 | 7.179 | 8.012 | 9.176 | 11.024 | 12.733 | 14.928 |
| 0.4 | 0.9 | 4.040 | 6.378 | 7.050 | 7.883 | 9.018 | 10.847 | 12.567 | 14.747 |
| 0.4 | 1.0 | 3.941 | 6.233 | 6.911 | 7.735 | 8.875 | 10.678 | 12.395 | 14.651 |
| 0.5 | 0.5 | 4.376 | 6.751 | 7.437 | 8.298 | 9.444 | 11.322 | 13.053 | 15.298 |
| 0.5 | 0.6 | 4.261 | 6.625 | 7.299 | 8.171 | 9.310 | 11.176 | 12.919 | 15.115 |
| 0.5 | 0.7 | 4.151 | 6.497 | 7.178 | 8.016 | 9.177 | 11.049 | 12.759 | 14.954 |
| 0.5 | 0.8 | 4.036 | 6.362 | 7.039 | 7.870 | 9.030 | 10.854 | 12.567 | 14.820 |
| 0.5 | 0.9 | 3.937 | 6.235 | 6.907 | 7.727 | 8.866 | 10.693 | 12.398 | 14.612 |
| 0.5 | 1.0 | 3.836 | 6.098 | 6.758 | 7.588 | 8.685 | 10.541 | 12.202 | 14.486 |
| 0.6 | 0.6 | 4.152 | 6.495 | 7.161 | 8.015 | 9.153 | 11.035 | 12.781 | 14.993 |
| 0.6 | 0.7 | 4.045 | 6.356 | 7.027 | 7.874 | 9.015 | 10.894 | 12.580 | 14.809 |
| 0.6 | 0.8 | 3.930 | 6.214 | 6.890 | 7.719 | 8.857 | 10.713 | 12.401 | 14.622 |
| 0.6 | 0.9 | 3.828 | 6.086 | 6.749 | 7.577 | 8.698 | 10.529 | 12.218 | 14.480 |
| 0.6 | 1.0 | 3.733 | 5.959 | 6.612 | 7.428 | 8.512 | 10.358 | 12.002 | 14.298 |
| 0.7 | 0.7 | 3.936 | 6.213 | 6.885 | 7.721 | 8.847 | 10.719 | 12.432 | 14.668 |
| 0.7 | 0.8 | 3.827 | 6.082 | 6.738 | 7.564 | 8.688 | 10.555 | 12.247 | 14.435 |
| 0.7 | 0.9 | 3.724 | 5.933 | 6.598 | 7.413 | 8.520 | 10.353 | 12.036 | 14.259 |
| 0.7 | 1.0 | 3.630 | 5.811 | 6.464 | 7.251 | 8.347 | 10.151 | 11.794 | 14.091 |
| 0.8 | 0.8 | 3.728 | 5.934 | 6.586 | 7.400 | 8.526 | 10.342 | 12.053 | 14.255 |
| 0.8 | 0.9 | 3.626 | 5.791 | 6.434 | 7.240 | 8.345 | 10.144 | 11.857 | 14.064 |
| 0.8 | 1.0 | 3.528 | 5.666 | 6.303 | 7.084 | 8.154 | 9.952 | 11.588 | 13.825 |
| 0.9 | 0.9 | 3.531 | 5.655 | 6.286 | 7.071 | 8.166 | 9.932 | 11.656 | 13.770 |
| 0.9 | 1.0 | 3.446 | 5.521 | 6.142 | 6.913 | 7.972 | 9.703 | 11.390 | 13.553 |
| 1.0 | 1.0 | 3.359 | 5.378 | 5.977 | 6.734 | 7.777 | 9.471 | 11.120 | 13.264 |

The table values were computed from 100,000 simulations with $n=2,000$.
$\lambda_{1} \leq \lambda_{2}$ are the eigenvalues of $\Lambda_{2}$ in (5.3) or $\Lambda_{2}^{*}$ in (5.5).

## B Appendix: Technical Proofs

Lemma B.1. Under the assumptions in Theorem 4.2, it follows that
(a) $\left(\hat{B} \bar{B}^{\prime}\right)^{-1}(\dot{B}-\hat{B})=O_{p}\left(n^{-1 / 2}\right)$,
(b) $\hat{A}\left(\dot{B} \bar{B}^{\prime}\right)=\hat{A}\left(\hat{B} \bar{B}^{\prime}\right)+O_{p}\left(n^{-1 / 2}\right)=A+O_{p}\left(n^{-1 / 2}\right)$,
(c) $\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \hat{B} P_{1}=\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B} P_{1}+O_{p}\left(n^{-3 / 2}\right)=B P_{1}+O_{p}\left(n^{-1}\right)$,
(d) $\quad\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \hat{B} P_{2}=\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B} P_{2}+O_{p}\left(n^{-1 / 2}\right)=B P_{2}+O_{p}\left(n^{-1 / 2}\right)$.

Proof. (a). We first denote $D_{\alpha_{1}}=\operatorname{diag}\left(n I_{r d}, \sqrt{n} I_{r^{2}}\right)$ and $\hat{Q}^{* *}=\mathcal{Q}\left(I_{m} \otimes\left(\hat{B} \bar{B}^{\prime}\right)^{\prime}\right)$, with $\mathcal{Q}=\left(Q \otimes I_{r}\right)$. Also denote $\hat{\alpha}_{1}=\operatorname{vec}(\hat{B}), \check{\alpha}_{1}=\operatorname{vec}\left(\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B}\right)$ and $\dot{\alpha}_{1}=\operatorname{vec}(\dot{B})$. $\hat{\alpha}_{2}, \check{\alpha}_{2}$ and $\dot{\alpha}_{2}$ are defined accordingly. $\hat{\alpha}, \check{\alpha}$ and $\dot{\alpha}$ are also defined accordingly. Since $\hat{Q}^{* * I-1}=\left(P^{\prime} \otimes I_{r}\right)\left(I_{m} \otimes\left(\hat{B} \bar{B}^{\prime}\right)^{-1}\right)$, we have

$$
\begin{aligned}
\left(I_{m} \otimes\left(\hat{B} \bar{B}^{\prime}\right)^{-1}\right)\left(\dot{\alpha}_{1}-\hat{\alpha}_{1}\right) & =\mathcal{Q}^{\prime} D_{\alpha_{1}}^{-1} D_{\alpha_{1}}\left(P^{\prime} \otimes I_{r}\right)\left(I_{m} \otimes\left(\hat{B} \bar{B}^{\prime}\right)^{-1}\right)\left(\dot{\alpha}_{1}-\hat{\alpha}_{1}\right) \\
& =\mathcal{Q}^{\prime} D_{\alpha_{1}}^{-1}\left[D_{\alpha_{1}} \hat{Q}^{* * \prime-1}\left(\dot{\alpha}_{1}-\hat{\alpha}_{1}\right)\right]
\end{aligned}
$$

As $\mathcal{Q}^{\prime} D_{\alpha_{1}}^{-1}=O\left(n^{-1 / 2}\right)$, it suffices to show $D_{\alpha_{1}} \hat{Q}^{* * \prime-1}\left(\dot{\alpha}_{1}-\hat{\alpha}_{1}\right)=O_{p}(1)$. By (4.9),

$$
\begin{aligned}
& D_{\alpha_{1}} \hat{Q}^{* * \prime-1}\left(\dot{\alpha}_{1}-\hat{\alpha}_{1}\right) \\
& \quad=-\left[\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \hat{Q}^{* *}\left(\left.R_{1 t}\right|_{\hat{\alpha}, \dot{\delta}}\right) \hat{Q}^{* * \prime} D_{\alpha_{1}}^{-1}\right]^{-1}\left[\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \hat{Q}^{* *}\left(\left.r_{1 t}\right|_{\hat{\alpha}, \dot{\delta}}\right)\right] \\
& \quad=-\left[\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(\left.R_{1 t}\right|_{\check{\alpha}, \dot{\delta}}\right) \mathcal{Q}^{\prime} D_{\alpha_{1}}^{-1}\right]^{-1}\left[\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(\left.r_{1 t}\right|_{\check{\alpha}, \dot{\delta}}\right)\right] .
\end{aligned}
$$

By Theorem 4.1 and Theorem 3.1(c), $n\left(\check{\alpha}_{1}-\alpha_{1}\right)=O_{p}(1), \sqrt{n}\left(\check{\alpha}_{2}-\alpha_{2}\right)=O_{p}(1)$, and $\sqrt{n}(\dot{\delta}-\delta)=O_{p}(1)$. Similar to the arguments for (4.7), it follows that:

$$
\begin{equation*}
\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(\left.R_{1 t}\right|_{\check{\alpha}, \dot{\delta}}\right) \mathcal{Q}^{\prime} D_{\alpha_{1}}^{-1}=\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q} R_{1 t} \mathcal{Q}^{\prime} D_{\alpha_{1}}^{-1}+o_{p}(1) \tag{B.1}
\end{equation*}
$$

On the other hand, by a Taylor's expansion and (B.1), with $R_{1 t}^{*}$ and $r_{1 t}^{*}$ being evaluated at a mid-point of $(\check{\alpha}, \dot{\delta})$ and $(\alpha, \delta)$,

$$
\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(\left.r_{1 t}\right|_{\check{\alpha}, \dot{\delta}}\right)
$$

$$
\begin{align*}
= & \sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q} r_{1 t}+\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(R_{1 t}^{*}\right)\left(\check{\alpha}_{1}-\alpha_{1}\right)+\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(\nabla_{\alpha_{2}^{\prime}} r_{1 t}^{*}\right)\left(\check{\alpha}_{2}-\alpha_{2}\right) \\
= & \sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}_{1} r_{1 t}+\left[\sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q} R_{1 t} \mathcal{Q}^{\prime} D_{\alpha_{1}}^{-1}+o_{p}(1)\right] \frac{1}{n} D_{\alpha_{1}}\left(P^{\prime} \otimes I_{r}\right)\left[n\left(\check{\alpha}_{1}-\alpha_{1}\right)\right] \\
& +\left[\frac{1}{\sqrt{n}} \sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(\nabla_{\left.\alpha_{2}^{\prime} r_{1 t}^{*}\right)}^{*}\right)\right] \sqrt{n}\left(\check{\alpha}_{2}-\alpha_{2}\right) . \tag{B.2}
\end{align*}
$$

It is not difficult to show that $\frac{1}{\sqrt{n}} \sum_{t=1}^{n} D_{\alpha_{1}}^{-1} \mathcal{Q}\left(\nabla_{\alpha_{2}^{\prime}} r_{1 t}^{*}\right)$ is $O_{p}(1)$. So is the RHS of (B.2). By Lemmas 3.1(a)-(b), (B.1) and (B.2), (a) holds.
(b). By the $\sqrt{n}$-consistency of $\hat{A}\left(\hat{B} \bar{B}^{\prime}\right)$ for $A$, and (a) of this lemma,

$$
\hat{A}\left(\dot{B} \bar{B}^{\prime}\right)=\hat{A}\left(\hat{B} \bar{B}^{\prime}\right)+\hat{A}\left(\hat{B} \bar{B}^{\prime}\right)\left(\hat{B} \bar{B}^{\prime}\right)^{-1}(\dot{B}-\hat{B}) \bar{B}^{\prime}=\hat{A}\left(\hat{B} \bar{B}^{\prime}\right)+O_{p}(1) O_{p}\left(n^{-1 / 2}\right) .
$$

Thus, (b) holds.
(c) and (d). Denote $\check{B}=\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B}$.

$$
\begin{equation*}
\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \hat{B}=\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B} \bar{B}^{\prime}\right]^{-1}\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B}=\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B} \bar{B}^{\prime}\right]^{-1} \tilde{B} . \tag{B.3}
\end{equation*}
$$

Using the formula $d F^{-1}=-F^{-1}(d F) F^{-1}$ for the $r \times r$ matrix $F$ with $F(x)=[x \bar{B}]^{-1}$, and applying a Taylor's expansion to $\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B} \bar{B}^{\prime}\right]^{-1}$ around $\check{B} \bar{B}^{\prime}$, we have

$$
\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B} \bar{B}^{\prime}\right]^{-1}=\left[\check{B} \bar{B}^{\prime}\right]^{-1}-\left[B^{*} \bar{B}^{\prime}\right]^{-1}\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-\check{B}\right] \bar{B}^{\prime}\left[B^{*} \bar{B}^{\prime}\right]^{-1}
$$

where $B^{*}$ lies between $\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B}$ and $\check{B}$. Therefore, the RHS of (B.3) equals:

$$
\begin{align*}
& {\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B} \bar{B}^{\prime}\right]^{-1}\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B}-\left[B^{*} \bar{B}^{\prime}\right]^{-1}\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-\check{B}\right] \bar{B}^{\prime}\left[B^{*} \bar{B}^{\prime}\right]^{-1} \check{B}} \\
& \quad=\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B}-\left[B^{*} \bar{B}^{\prime}\right]^{-1}\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-\tilde{B}\right] \bar{B}^{\prime}\left[B^{*} \bar{B}^{\prime}\right]^{-1} \check{B} . \tag{B.4}
\end{align*}
$$

By (a) of this lemma, $\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-\check{B}=O_{p}\left(n^{-1 / 2}\right)$. From this, we can show that $\left[B^{*} \bar{B}^{\prime}\right]^{-1}=O_{p}(1) . \bar{B}$ and $\check{B}$ are also $O_{P}(1)$. By (B.4), (d) holds. By Theorem 4.1, $\check{B} P_{1}=O_{p}\left(n^{-1}\right)$ because $B P_{1}=0$. By (B.4),

$$
\begin{aligned}
& {\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B} \bar{B}^{\prime}\right]^{-1}\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B} P_{1}-\left[B^{*} \bar{B}^{\prime}\right]^{-1}\left[\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-\check{B}\right] \bar{B}^{\prime}\left[B^{*} \bar{B}^{\prime}\right]^{-1} \check{B} P_{1}} \\
& \quad=\left(\hat{B} \bar{B}^{\prime}\right)^{-1} \hat{B} P_{1}+O_{p}\left(n^{-3 / 2}\right) .
\end{aligned}
$$

Thus, (c) holds. This completes the proof.

Proof of Theorem 4.2. Denote $\dot{Q}_{1}^{* *}=\left(Q_{1}^{\prime} \otimes I_{r}\right)\left(I_{m} \otimes\left(\dot{B} \bar{B}^{\prime}\right)^{\prime}\right)$, $\dot{Q}_{2}^{* *}=$ $\operatorname{diag}\left(\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \otimes I_{m}, I_{(s-1) m^{2}}\right), \grave{\alpha}_{1}=\operatorname{vec}\left(\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \hat{B}\right), \grave{\alpha}_{2}=\operatorname{vec}\left[\hat{A}\left(\dot{B} \bar{B}^{\prime}\right), \hat{\Phi}_{1}^{*}, \ldots, \hat{\Phi}_{s-1}^{*}\right]$, and $\grave{\alpha}=\left[\grave{\alpha}_{1}^{\prime}, \grave{\alpha}_{2}^{\prime}\right]^{\prime}$. By Lemmas B.1(b)-(c), $(\grave{\alpha}, \dot{\delta}) \in \Xi_{n}$. Thus by (4.7),

$$
\begin{align*}
n^{-2} \sum_{t=1}^{n} \dot{Q}_{1}^{* *}\left(\left.R_{1 t}\right|_{\hat{\alpha}, \dot{\delta}} \dot{Q}_{1}^{* * \prime}\right. & =n^{-2} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right)\left(\left.R_{1 t}\right|_{\dot{\alpha}, \dot{\delta}}\right)\left(Q_{1} \otimes I_{r}\right) \\
& =n^{-2} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right) R_{1 t}\left(Q_{1} \otimes I_{r}\right)+o_{p}(1),  \tag{B.5}\\
n^{-1} \sum_{t=1}^{n} \dot{Q}_{2}^{* *}\left(\left.R_{2 t}\right|_{\hat{\alpha}, \dot{\delta}}\right)_{2}^{* * \prime} & =n^{-1} \sum_{t=1}^{n}\left(\left.R_{2 t}\right|_{\dot{\alpha}, \dot{\delta}}\right)=n^{-1} \sum_{t=1}^{n} R_{2 t}+o_{p}(1) . \tag{B.6}
\end{align*}
$$

Refer to (4.6). Due to the block-diagonality of $\tilde{R}_{t}$, by (4.8),

$$
\begin{align*}
& \frac{1}{n} \sum_{t=1}^{n} \dot{Q}_{1}^{* *}\left(\left.r_{1 t}\right|_{\hat{\alpha}, \dot{\delta}}\right)=\frac{1}{n} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right)\left(\left.r_{1 t}\right|_{\grave{\alpha}, \dot{\delta}}\right) \\
= & \frac{1}{n} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right) r_{1 t}+\left(\frac{1}{n} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right) R_{1 t}\left(Q_{1} \otimes I_{r}\right)\right)\left(P_{1}^{\prime} \otimes I_{r}\right)\left(\grave{\alpha}_{1}-\alpha_{1}\right)+o_{p}(1),  \tag{B.7}\\
& \frac{1}{\sqrt{n}} \sum_{t=1}^{n} \dot{Q}_{2}^{* *}\left(\left.r_{2 t}\right|_{\hat{\alpha}, \dot{\delta}}\right)=\frac{1}{\sqrt{n}} \sum_{t=1}^{n}\left(\left.r_{2 t}\right|_{\grave{\alpha}, \dot{\delta}}\right) \\
= & \frac{1}{\sqrt{n}} \sum_{t=1}^{n} r_{2 t}+\left(\frac{1}{\sqrt{n}} \sum_{t=1}^{n} R_{2 t}\right)\left(\grave{\alpha}_{2}-\alpha_{2}\right)+o_{p}(1) . \tag{B.8}
\end{align*}
$$

(a). Recall that $\dot{Q}_{1}^{* *-1} \hat{\alpha}_{1}=\left(P_{1}^{\prime} \otimes I_{r}\right) \grave{\alpha}_{1}$. By (4.9), (B.5) and (B.7),

$$
\begin{align*}
n \dot{Q}_{1}^{* * \prime-1} \dot{\alpha}_{1}= & n \dot{Q}_{1}^{* * \prime-1} \hat{\alpha}_{1}-\left[n^{-2} \sum_{t=1}^{n} \dot{Q}_{1}^{* *}\left(\left.R_{1 t}\right|_{\hat{\alpha}, \dot{\delta}}\right) \dot{Q}_{1}^{* * \prime}\right]^{-1}\left[n^{-1} \sum_{t=1}^{n} \dot{Q}_{1}^{* *}\left(\left.r_{1 t}\right|_{\hat{\alpha}, \hat{\delta}}\right)\right] \\
= & n\left(P_{1}^{\prime} \otimes I_{r}\right) \grave{\alpha}_{1}-\left[n^{-2} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right) R_{1 t}\left(Q_{1} \otimes I_{r}\right)\right]^{-1}\left[n^{-1} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right) r_{1 t}\right] \\
& \quad-n\left(P_{1}^{\prime} \otimes I_{r}\right)\left(\grave{\alpha}_{1}-\alpha_{1}\right)+o_{p}(1) \\
= & n\left(P_{1}^{\prime} \otimes I_{r}\right) \alpha_{1}-\left[\frac{1}{n^{2}} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right) R_{1 t}\left(Q_{1} \otimes I_{r}\right)\right]^{-1}\left[\frac{1}{n} \sum_{t=1}^{n}\left(Q_{1}^{\prime} \otimes I_{r}\right) r_{1 t}\right] \\
& \quad+o_{p}(1) . \tag{B.9}
\end{align*}
$$

Note that $\dot{Q}_{1}^{* *-1} \dot{\alpha}_{1}-\left(P_{1}^{\prime} \otimes I_{r}\right) \alpha_{1}=\operatorname{vec}\left[\left(\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \dot{B}-B\right) P_{1}\right]$. By (B.9) and Lemma 3.1(a)(b), (a) holds.
(b). By (4.10), (B.6) and (B.8),

$$
\sqrt{n} \dot{Q}_{2}^{* *-1} \dot{\alpha}_{2}=\sqrt{n} \dot{Q}_{2}^{* * 1-1} \hat{\alpha}_{2}-\left[n^{-1} \sum_{t=1}^{n} \dot{Q}_{2}^{* *}\left(\left.R_{2 t}\right|_{\hat{\alpha}, \dot{\delta}}\right) \dot{Q}_{2}^{* * \prime}\right]^{-1}\left[n^{-1 / 2} \sum_{t=1}^{n} \dot{Q}_{2}^{* *}\left(\left.r_{2 t}\right|_{\hat{\alpha}, \dot{\delta}}\right)\right]
$$

$$
\begin{align*}
& =\sqrt{n} \grave{\alpha}_{2}-\left[n^{-1} \sum_{t=1}^{n} R_{2 t}\right]^{-1}\left[n^{-1 / 2} \sum_{t=1}^{n} r_{2 t}\right]-\sqrt{n}\left(\grave{\alpha}_{2}-\alpha_{2}\right)+o_{p}(1) \\
& =\sqrt{n} \alpha_{2}-\left[n^{-1} \sum_{t=1}^{n} R_{2 t}\right]^{-1}\left[n^{-1 / 2} \sum_{t=1}^{n} r_{2 t}\right]+o_{p}(1) \tag{B.10}
\end{align*}
$$

By (B.10) and Lemma 3.1(a)-(b), (b) holds. This completes the proof.
Proof of Lemma 5.1. Let $\dot{\varphi}^{*}=\operatorname{vec}\left[C P_{1}, \dot{C} P_{2}, \dot{\Phi}_{1}^{*}, \cdots, \dot{\Phi}_{s-1}^{*}\right]$, and $l^{*}\left(\dot{\varphi}^{*}, \dot{\delta}\right)$ be $l(\dot{\varphi}, \dot{\delta})$ with $\dot{C} P_{1} Z_{1 t-1}$ replaced by $C P_{1} Z_{1 t-1}$. By Lemma 3.1, Theorem 3.1 and a Taylor's expansion, we can show that

$$
\begin{equation*}
2\left[l(\dot{\varphi}, \dot{\delta})-l^{*}\left(\dot{\varphi}^{*}, \dot{\delta}\right)\right]=\operatorname{vec}\left[n(\dot{C}-C) P_{1}\right]^{\prime}\left[\frac{1}{n^{2}} \sum_{t=1}^{n} L_{1 t}\right] \operatorname{vec}\left[n(\dot{C}-C) P_{1}\right]+o_{p}(1),( \tag{B.11}
\end{equation*}
$$

where $L_{1 t}=\left(Z_{1 t-1} Z_{1 t-1}^{\prime} \otimes V_{t}^{-1}\right)+\sum_{l=1}^{t-1}\left[Z_{1 t-l-1} Z_{1 t-l-1}^{\prime} \otimes\left(\left(\Gamma^{-1} \odot \Gamma+I_{m}\right) \odot \nu_{l} \nu_{l}^{\prime} \odot \Pi_{l t}\right)\right]$.
Denote $\ddot{A}=\dot{A}\left(\dot{B} \bar{B}^{\prime}\right)$ and $\ddot{B}=\left(\dot{B} \bar{B}^{\prime}\right)^{-1} \dot{B}$. Note $\dot{A} \dot{B}=\ddot{A} \ddot{B}$. Moreover,

$$
\ddot{A} \ddot{B}-A B=(\ddot{A}-A) B+A(\ddot{B}-B)+(\ddot{A}-A)(\ddot{B}-B) .
$$

Recall that $B P_{1}=0$. By Theorem 4.2, $(\ddot{B}-B) P_{1}=O_{p}\left(n^{-1}\right)$ and $(\ddot{A}-A)=$ $O_{p}\left(n^{-1 / 2}\right)$ under $H_{0}$. Hence,

$$
\begin{align*}
n(\ddot{A} \ddot{B}-A B) P_{1} & =n(\ddot{A}-A) B P_{1}+n A(\ddot{B}-B) P_{1}+(\ddot{A}-A) n(\ddot{B}-B) P_{1} \\
& =n A(\ddot{B}-B) P_{1}+O_{p}\left(n^{-1 / 2}\right) . \tag{B.12}
\end{align*}
$$

Let $\dot{\alpha}^{*}=\operatorname{vec}\left[A B P_{1}, \dot{A} \dot{B} P_{2}, \dot{\Phi}_{1}^{*}, \cdots, \dot{\Phi}_{s-1}^{*}\right]$, and $l^{*}\left(\dot{\alpha}^{*}, \dot{\delta}\right)$ be $l(\dot{\alpha}, \dot{\delta})$ with $\dot{A} \dot{B} P_{1} Z_{1 t-1}$ replaced by $A B P_{1} Z_{1 t-1}=C P_{1} Z_{1 t-1}$. By Lemma 3.1, Theorem 4.2, a Taylor's expansion and (A.12), we can show that:

$$
\begin{align*}
& 2\left[l(\dot{\alpha}, \dot{\delta})-l^{*}\left(\dot{\alpha}^{*}, \dot{\delta}\right)\right] \\
= & \operatorname{vec}\left[n(\ddot{A} \ddot{B}-A B) P_{1}\right]^{\prime}\left[n^{-2} \sum_{t=1}^{n} L_{1 t}\right] \operatorname{vec}\left[n(\ddot{A} \ddot{B}-A B) P_{1}\right]+o_{p}(1) \\
= & \operatorname{vec}\left[n A(\ddot{B}-B) P_{1}\right]^{\prime}\left[n^{-2} \sum_{t=1}^{n} L_{1 t}\right] \operatorname{vec}\left[n A(\ddot{B}-B) P_{1}\right]+o_{p}(1) . \tag{B.13}
\end{align*}
$$

It is straightforward to show that $l^{*}\left(\dot{\varphi}^{*}, \dot{\delta}\right)-l^{*}\left(\dot{\alpha}^{*}, \dot{\delta}\right)=o_{p}(1)$. Furthermore, by (A.11), (A.13) and Lemma 3.1, it follows that

$$
L R_{G} \quad \longrightarrow_{\mathcal{L}} \quad \operatorname{vec}\left[\Omega_{1}^{-1} M^{*}\right]^{\prime}\left[Z \otimes \Omega_{1}\right] \operatorname{vec}\left[\Omega_{1}^{-1} M^{*}\right]-\operatorname{vec}\left[D M^{*}\right]^{\prime}\left[Z \otimes \Omega_{1}\right] \operatorname{vec}\left[D M^{*}\right]
$$

$$
\begin{align*}
& =\operatorname{vec}\left[\Omega_{1}^{-1} M^{*}\right]^{\prime} \operatorname{vec}\left[\Omega_{1} \Omega_{1}^{-1} M^{*} Z\right]-\operatorname{vec}\left[D M^{*}\right]^{\prime} \operatorname{vec}\left[\Omega_{1} D M^{*} Z\right] \\
& =\operatorname{tr}\left[M^{* \prime} \Omega_{1}^{-1} M^{*} Z\right]-\operatorname{tr}\left[M^{* \prime} D \Omega_{1} D M^{*} Z\right] \\
& =\operatorname{tr}\left[\left(\Omega_{1}^{-1}-A\left(A^{\prime} \Omega_{1} A\right)^{-1} A^{\prime}\right) M^{*} Z M^{* \prime}\right] \tag{B.14}
\end{align*}
$$

where $D \equiv A\left(A^{\prime} \Omega_{1} A\right)^{-1} A^{\prime}, Z \equiv \psi_{11} \Omega_{a_{1}}^{1 / 2} \int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} \Omega_{a_{1}}^{1 / 2} \psi_{11}^{\prime}$ and $M^{*}$ is defined as in Theorem 3.1. Following the lines on p. 359 of Reinsel and Ahn (1992), we can rewrite $\Omega_{1}^{-1}-A\left(A^{\prime} \Omega_{1} A\right)^{-1} A^{\prime}$ as:

$$
\Omega_{1}^{-1}\left(\Omega_{1}-\Omega_{1} A\left(A^{\prime} \Omega_{1} A\right)^{-1} A^{\prime} \Omega_{1}\right) \Omega_{1}^{-1}=\Omega_{1}^{-1} A_{\perp}\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{-1} A_{\perp}^{\prime} \Omega_{1}^{-1}
$$

Therefore, we can rewrite the asymptotic distribution in (A.13) as:

$$
\operatorname{tr}\left[\left(\int_{0}^{1} B_{d}(u) d V_{d}^{*}(u)^{\prime}\right)^{\prime}\left(\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right)^{-1}\left(\int_{0}^{1} B_{d}(u) d V_{d}^{*}(u)^{\prime}\right)\right]
$$

where $V_{d}^{*}(u) \equiv\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{-1 / 2} A_{\perp}^{\prime} \Omega_{1}^{-1} W_{m}^{*}(u)$. Note $E\left[B_{d}(u) V_{d}^{*}(u)^{\prime}\right]=$ $u \Omega_{a 1}^{-1 / 2}\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{1 / 2}=u \Upsilon^{\prime}$. Thus, we can rewrite $V_{d}^{*}(u)$ as a linear combination of two independent $d$-dimensional standard BMs:

$$
\begin{equation*}
\Upsilon B_{d}(u)+\left[\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{-1 / 2} A_{\perp}^{\prime} \Omega_{1}^{-1} \Omega_{1}^{*} \Omega_{1}^{-1} A_{\perp}\left(A_{\perp}^{\prime} \Omega_{1}^{-1} A_{\perp}\right)^{-1 / 2}-\Upsilon \Upsilon^{\prime}\right]^{1 / 2} V_{d}(u) \tag{B.15}
\end{equation*}
$$

The proof is complete.
Proof of Theorem 5.1. When $\Omega_{1}^{*}=\Omega_{1}$, (A.15) in the proof of Lemma 5.1 can be simplified as $\Upsilon B_{d}(u)+\left[I_{d}-\Upsilon \Upsilon^{\prime}\right]^{1 / 2} V_{d}(u)$. Thus, the asymptotic distribution can be simplified as:

$$
\begin{aligned}
& \operatorname{tr}\left\{\left[\int_{0}^{1} \Upsilon B_{d}(u) d B_{d}(u)^{\prime} \Upsilon^{\prime}+\int_{0}^{1} \Upsilon B_{d}(u) d V_{d}(u)^{\prime}\left(I_{d}-\Upsilon \Upsilon^{\prime}\right)^{1 / 2}\right]^{\prime}\right. \\
\cdot & {\left.\left[\int_{0}^{1} \Upsilon B_{d}(u) B_{d}(u)^{\prime} \Upsilon^{\prime} d u\right]^{-1}\left[\int_{0}^{1} \Upsilon B_{d}(u) d B_{d}(u)^{\prime} \Upsilon^{\prime}+\int_{0}^{1} \Upsilon B_{d}(u) d V_{d}(u)^{\prime}\left(I_{d}-\Upsilon \Upsilon^{\prime}\right)^{1 / 2}\right]\right\} }
\end{aligned}
$$

However, $\Upsilon B_{d}(u) \sim N\left(0, \Upsilon \Upsilon^{\prime}\right)$. Abusing the notation, we write $\Upsilon B_{d}(u)$ as $\left(\Upsilon \Upsilon^{\prime}\right)^{1 / 2}$ $B_{d}(u)$, where $B_{d}(u)$ is (another) d-dimensional standard BM independent of $V_{d}(u)$. Therefore, cancelling some of the $\left(\Upsilon \Upsilon^{\prime}\right)^{1 / 2}$ terms, the asymptotic distribution can be expressed as:

$$
\begin{aligned}
& \operatorname{tr}\left\{\left[\int_{0}^{1} B_{d}(u) d B_{d}(u)^{\prime}\left(\Upsilon \Upsilon^{\prime}\right)^{1 / 2}+\int_{0}^{1} B_{d}(u) d V_{d}(u)^{\prime}\left(I_{d}-\Upsilon \Upsilon^{\prime}\right)^{1 / 2}\right]^{\prime}\right. \\
& \left.\left[\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right]^{-1}\left[\int_{0}^{1} B_{d}(u) d B_{d}(u)^{\prime}\left(\Upsilon \Upsilon^{\prime}\right)^{1 / 2}+\int_{0}^{1} B_{d}(u) d V_{d}(u)^{\prime}\left(I_{d}-\Upsilon \Upsilon^{\prime}\right)^{1 / 2}\right]\right\}
\end{aligned}
$$

Since $\left(I_{d}-\Upsilon \Upsilon^{\prime}\right)$ is a real symmetric matrix, we can decompose it as $\Theta \Lambda_{d} \Theta^{\prime}$, where $\Theta$ is an orthogonal matrix such that $\Theta^{\prime} \Theta=I_{d}$. In view of $\left(\Upsilon \Upsilon^{\prime}\right)^{1 / 2}=\Theta\left(I_{d}-\Lambda_{d}\right)^{1 / 2} \Theta^{\prime}$ and $\left(I_{d}-\Upsilon \Upsilon^{\prime}\right)^{1 / 2}=\Theta \Lambda_{d}^{1 / 2} \Theta^{\prime}$ and due to the orthogonality of $\Theta$, we can write the asymptotic distribution as:

$$
\begin{aligned}
& \operatorname{tr}\left\{\left[\int_{0}^{1} \Theta^{\prime} B_{d}(u) d B_{d}(u)^{\prime} \Theta\left(I_{d}-\Lambda_{d}\right)^{1 / 2} \Theta^{\prime}+\int_{0}^{1} \Theta^{\prime} B_{d}(u) d V_{d}(u)^{\prime} \Theta \Lambda_{d}^{1 / 2} \Theta^{\prime}\right]^{\prime}\right. \\
& \cdot\left[\int_{0}^{1} \Theta^{\prime} B_{d}(u) B_{d}(u)^{\prime} d u \Theta\right]^{-1} \\
& \left.\cdot\left[\int_{0}^{1} \Theta^{\prime} B_{d}(u) d B_{d}(u)^{\prime} \Theta\left(I_{d}-\Lambda_{d}\right)^{1 / 2} \Theta^{\prime}+\int_{0}^{1} \Theta^{\prime} B_{d}(u) d V_{d}(u)^{\prime} \Theta \Lambda_{d}^{1 / 2} \Theta^{\prime}\right]\right\} .
\end{aligned}
$$

Since $\Theta^{\prime} B_{d}(u) \sim N\left(0, \Theta^{\prime} \Theta\right)=N\left(0, I_{d}\right)$, similar to the previous arguments, and abusing the notation, we can write $\Theta^{\prime} B_{d}(u)$ and $\Theta^{\prime} V_{d}(u)$ as two independent standard $\mathrm{BMs} B_{d}(u)$ and $V_{d}(u)$ respectively. Cancelling the orthogonal $\Theta$, we have:

$$
\begin{aligned}
& \operatorname{tr}\left\{\left[\int_{0}^{1} B_{d}(u) d B_{d}(u)^{\prime}\left(I_{d}-\Lambda_{d}\right)^{1 / 2}+\int_{0}^{1} B_{d}(u) d V_{d}(u)^{\prime} \Lambda_{d}^{1 / 2}\right]^{\prime}\right. \\
& \left.\quad \cdot\left[\int_{0}^{1} B_{d}(u) B_{d}(u)^{\prime} d u\right]^{-1}\left[\int_{0}^{1} B_{d}(u) d B_{d}(u)^{\prime}\left(I_{d}-\Lambda_{d}\right)^{1 / 2}+\int_{0}^{1} B_{d}(u) d V_{d}(u)^{\prime} \Lambda_{d}^{1 / 2}\right]\right\} \\
& \quad= \\
& \operatorname{tr}\left\{\left[\zeta\left(I_{d}-\Lambda_{d}\right)^{1 / 2}+\Phi \Lambda_{d}^{1 / 2}\right]^{\prime}\left[\zeta\left(I_{d}-\Lambda_{d}\right)^{1 / 2}+\Phi \Lambda_{d}^{1 / 2}\right]\right\} .
\end{aligned}
$$

This completes the proof.

## REFERENCES

Ahn, S. K. and Reinsel, G.C. (1990), Estimation for Partially Nonstationary Multivariate models, Journal of American Statistical Association, 85, 813-823.

Alexakis, P. and Apergis, N. (1996), ARCH Effects and Cointegration: Is the Foreign Exchange Market Efficient?, Journal of Banking and Finance, 20, 687-697.

Anderson, T.W. (1951), Estimating Linear Restrictions on Regression Coefficients for Multivariate Normal Distributions, Annals of Mathematical Statistics, 22, 327-351. [Correction, Annals of Statistics, 8, 1980, p.1400.]

Anderson, T.W. (2002), Reduced Rank Regression in Cointegrated Models, Journal of Econometrics, 106, 203-216.

Bollerslev, T. (1990), Modeling the Coherence in the Short-Run Nominal Exchange Rates: A Multivariate Generalized ARCH Approach, Review of Economics and Statistics, 72, 498-505.

Brenner, R.J. and Kroner, K.F. (1995), Arbitrage, Cointegration, and Testing the Unbiasedness Hypothesis in Financial Markets, Journal of Financial and Quantitative Analysis, 30, 23-42.

Chan, N.H. and Wei, C.Z. (1988), Limiting Distributions of Least Squares Estimates of Unstable Autoregressive Processes, Annals of Statistics, 16, 367-401.

Engle, R.F. and Granger, C.W.J. (1987), Cointegration and Error Correction: Representation, Estimation and Testing, Econometrica, 55, 251-276.

Engle, R.F., Patton, A.J. (2004), Impacts of Trades in an Error-Correction Model of Quote Prices. Journal of Financial Markets, 7, 125.

Franses, P.H., Kofman, P. and Moser. J. (1994), Garch Effects on a Test for Cointegration, Review of Quantitative Finance and Accounting, 4, 19-26.

Glosten, L.R., Jagannathan, R. and Runkle, D.E. (1993), On the Relation between the Expected Value and the Volatility of the Nominal Excess Return on Stocks, Journal of Finance, 48, 1779-1802.

Granger, C.W.J. (1983), Cointegrated Variables and Error Correction models, Discussion Paper, Department of Economics, University of California at San Diego.

Hasbrouck, J. (1995), One security, Many markets: Determining the Contributions to Price Discovery, Journal of Finance, 50, 1175-1199.

Hasbrouck, J. (2003), Intraday Price Formation in U.S. Equity Index Markets, Journal of Finance, 58, 2375-2399.

Jeantheau, T. (1998), Strong Consistency of Estimators for Multivariate ARCH Models, Econometric Theory, 14, 70-86.

Johansen, S. (1996), Likelihood-Based Inference in Cointegrated Vector Autoregressive models. Oxford: Oxford University Press.

Kroner, K.F. and Sultan, J. (1993), Time-Varying Distributions and Dynamic Hedging with Foreign Currency Futures, Journal of Financial and Quantitative Analysis, 28, 535-551.

Li, W.K., Ling, S. and Wong, H. (2001), Estimation for Partially Nonstationary Multivariate Autoregressive models with Conditional Heteroskedasticity, Biometrika, 88, 1135-1152.

Ling, S. and Li, W.K. (1998), Limiting Distributions of Maximum Likelihood Estimators for Unstable ARMA models with GARCH Errors, Annals of Statistics, 26, 84-125.

Ling, S., Li, W.K. and McAleer, M. (2003), Estimation and Testing for Unit Root Processes with $\operatorname{GARCH}(1,1)$ Errors: Theory and Monte Carlo Study, Econometric Reviews, 22, 179-202.

Ling, S. and McAleer, M. (2003a), Asymptotic Theory for a Vector ARMA-GARCH model, Econometric Theory, 19, 280-310.

Ling, S. and McAleer, M. (2003b), On Adaptive Estimation in Nonstationary ARMA models with GARCH Errors, Annals of Statistics, 31, 642-674.

Magnus, J.R. (1988), Linear Structures. New York: Oxford University Press.
Magnus, J.R. and Neudecker, H. (1988), Matrix Differential Calculus with Applications in Statistics and Econometrics. Chichester: John Wiley and Sons.

Phillips, P.C.B. and Durlauf, S.N. (1986), Multiple Time Series Regression with Integrated Processes, Review of Economic Studies, 53, 473-495.

Reinsel, G.C. and Ahn, S.K. (1992), Vector AR models with Unit Root and Reduced Rank Structure: Estimation, Likelihood Ratio Test, and Forecasting, Journal of Time Series Analysis, 13, 133-145.

Sin, C.-y. (2003), Estimating a Linear Exponential Density when the Weighting Matrix and Mean Parameter Vector are Functionally Related, in: Fomby, T.B., Hill, R.C. (Eds.), Advances in Econometrics Volume 17-Maximum Likelihood Estimation of Misspecified Models: Twenty Years Later. Elsevier, Amsterdam, 177-197.

Sin, C.-y. and Ling, S. (2004), Estimation and Testing for Partially Nonstationary Vector Autoregressive models with GARCH, Discussion Paper, Hong Kong Baptist University, and Hong Kong University of Science and Technology.

Stock, J.H. and Watson, M.W. (1993), A Simple Estimator of Cointegrating Vectors in Higher Order Integrated System, Econometrica, 61, 783-820.

Tse, Y.K. and Tsui, A.K.C. (2002), A Multivariate Generalized Autoregressive Conditional Heteroscedasticity Model with Time-Varying Correlations, Journal of Business and Economic Statistics, 20, 351-362.


[^0]:    *Acknowledgments: I thank helpful comments from Chi-shing CHAN and Shiqing LING. This research is partially supported by the Hong Kong Research Grant Council competitive earmarked grant HKBU2014/02H. The usual disclaimers apply.

