Preemptive Entry in Differentiated Product Markets^{*}

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Summary: Models of spatial competition are typically static, and exhibit multiple freeentry equilibria. Incumbent firms can earn rents in equilibrium because any potential entrant expects a significantly lower market share (since it must fit into a niche between incumbent firms) along with fiercer price competition. Previous research has usually concentrated on the zero-profit equilibrium, at which there is normally excessive entry, and so an entry tax would improve the allocation of resources. At the other extreme, the equilibrium with the greatest rent per firm normally entails insufficient entry, so an entry subsidy should be prescribed. A model of sequential firm entry (with an exogenous order of moves) resolves the multiplicity problem but raises a new difficulty: firms that enter earlier can expect higher spatial rents, and so firms prefer to be earlier in the entry order. This tension disappears when firms can compete for entry positions. We therefore suppose that firms can commit capital early to the market in order to lay claim to a particular location. This temporal competition dissipates spatial rents in equilibrium and justifies the sequential move structure. However, the policy implications are quite different once time is introduced. An atemporal analysis of the sequential entry process would prescribe an entry subsidy, but once proper account is taken of the entry dynamics, a tax may be preferable.

Keywords and Phrases: Product differentiation, rent dissipation, entry deterrence, entry timing, sequential entry.

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1. Introduction

Product di®erentiation is an important dimension of ⁻rm competition, from computer software and cable television to grocery stores and restaurants. Existing models of product di®erentiation are typically static, by which we mean that ⁻rms' location decisions are made simultaneously. These static models are of limited usefulness. In particular, models with endogenous location choice (in characteristics or geographical space) and potential entry typically allow multiple equilibria. This means that there is a wide range of possible ⁻rm numbers consistent with equilibrium. Roughly speaking, these range from a densest packing of ⁻rms at which all earn zero pro⁻t, to a loosest packing at which any new entrant in a niche between existing ⁻rms would just be unpro⁻table. Market performance is hard to evaluate because the socially optimal level of product diversity typically lies within the range of possible equilibrium levels. This leaves the analyst with no way of knowing whether entry or exit ought to be encouraged, so policy questions can scarcely be addressed without a way of choosing among the equilibria. The most usual assumption is that the equilibrium involves zero pro⁻t for all existing ⁻rms (see e.g. Salep, 1979). This is likely to be the wrong benchmark if ⁻rms can somehow in ^ouence the equilibrium selection.

One reaction to the multiple equilibrium problem is to conclude that \history matters" (Eaton and Lipsey, 1978). History can be modeled via a sequential location process of far-sighted ⁻rms (see e.g. Prescott and Visscher, 1979, and Neven, 1987). This lender modeling strategy, ⁻rms rationally anticipate how their actions a®ect the behavior of subsequent entrants. Early entrants recognize how their own locations a®ect the location (or product choice) decisions of later entrants and whether or not they will enter the market.¹ A major drawback to this approach is that a ⁻rm's pro⁻t depends on its position in the (exogenously speci⁻ed) order of moves: earlier entrants earn more. Thus ⁻rms would like to move higher in the order although the models do not allow them to act on this incentive.²

We explicitly introduce time to model the ability and the costs of moving before others. Specifically, we suppose that it is known far in advance that a market will open.³ Firms compete in the timing of entry into the market, with earlier entry garnering a position that has higher expected °ow pro⁻t. Timing competition dissipates the rents accruing to desirable locations: an entrant must locate su±ciently early that all such rents are exhausted via early commitment of resources to the market, otherwise some other ⁻rm would pre-empt it.⁴ Thus in equilibrium ⁻rms no longer have an incentive to move earlier in the order. Pro⁻ts are driven to zero: even though space creates rents, time destroys them. Although pro⁻ts are driven to zero, the equilibrium locations are not those of the zero-pro⁻t equilibrium of the static model. Far from it: the locations are close to the

¹By contrast, the \long-run" equilibrium of the static model is usually speci⁻ed as a set of locations such that no ⁻rm wishes to enter, exit, or choose a di[®]erent location. These decisions could be coordinated by an imaginary \auctioneer", but the process raises the obvious problem of how ⁻rms in practice ⁻gure out which is to locate where. This is also troublesome because (in all but the zero-pro⁻t equilibrium) ⁻rms that actually enter the market earn positive pro⁻ts while those that do not enter earn zero.

²The same criticism can be levelled against standard Stackelberg sequential output choice models: see Eaton and Ware (1987) and Anderson and Engers (1994).

³As we point out below, it su \pm ces that the probability that the market opens is a continuous function of time. For example, legal restrictions are removed or a market is liberalized. Alternatively, this assumption is a stylized version of a growing market without dealing with the intricacies of the growth path (see also Eaton and Lipsey, 1979).

⁴An early exposition of this mechanism is expounded in Eaton and Lipsey (1979, 1980), where the timing of a pre-emptive decision is resolved by determining the time at which the present value of entry is zero. The source of the rent is space in Eaton and Lipsey (1979) while it is capital durability in Eaton and Lipsey (1980).

opposite extreme in the static model, that at which static rents are maximized. So, ⁻rms choose the locations at which the static rents are maximal, but to claim these rents they must commit to their decisions so early that the rents are totally dissipated.

The equilibrium locations are also essentially unique, so one can make robust policy recommendations. But these should be prescribed with care. Although the equilibrium locations are those of the (atemporal) sequential-entry model, it should not be concluded (as that model would prescribe) that incentives should be given to set up more \neg rms, via entry subsidies for example. An entry subsidy will indeed cause more \neg rms to enter (suggesting a welfare improvement), but competition for rents will become keener, and subsidies will be dissipated by timing competition. The net e[®]ect may be that welfare deteriorates: the appropriate policy response in a situation with insu±cient product variety may actually be a tax on entry!

Our results imply that atemporal models may seriously understate the distortions inherent in di[®]erentiated product markets. Not only can the locations be worse than the worst possible case suggested by the standard static model, all rents can be lost as well.

After completing our work we became aware of a remarkable discussion by Vickrey of spatial competition. Vickrey (1964, Ch.6) anticipated several of the most important themes developed much later in the literature, including the circle model of Salop (1979), the sequential entry model of Prescott and Visscher (1977), and the Eaton and Lipsey (1978) result that pro⁻ts can persist despite free entry. As later did Eaton and Lipsey, 1979 and 1980, Vickrey also realized that pro⁻t might be dissipated by early entry:

in a dynamic world...there may be an advantage to establishing a rm in an opening gap somewhat ahead of the time at which the situation is currently pro table, in order to pre-empt the position and enjoy the later pro ts. The earlier losses due to the attempts at pre-emption would then have to be o[®]set against later gains. Indeed, in a situation of perfect foresight and vigorous competition, some entrepreneur would presumably jump in as soon as the expected pre-emptional loss has diminished to the point where it will just be outweighed by the prospective pro ts to be enjoyed later (Vickrey, 1964, p. 334).

Section 2 describes the properties of the model of product di®erentiation that we use. These properties are needed in the later sections. Section 3 then determines the equilibrium of the atemporal model of sequential location choice, and Section 4 uses that analysis to determine the equilibrium entry times in the full model. Section 5 shows that the equilibrium locations in the timing game are inferior even in a static sense to those of almost any simultaneous-entry equilibrium, suggesting that performance in di®erentiated product markets may be much worse than implied by the usual analysis (since one must in addition allow for the rent dissipation). The equilibrium outcomes are closest to those of the simultaneous equilibrium with the greatest rent. The performance issue is addressed in Section 6, which shows that an entry subsidy is never optimal despite the small number of ⁻rms in the market (that is, the rent dissipation e®ect dominates). Section 7 concludes with a general discussion of rent dissipation and performance in the context of product di®erentiation.

2. The Static Model.

To show how our approach contrasts with the standard static equilibrium notion we use a particular speci⁻cation of product di[®]erentiation.⁵ This is the model of spatial price discrimination most

⁵Other possible formulations are discussed in the conclusion.

recently described in Eaton and Schmitt (1994), which draws on earlier work by Lederer and Hurter (1987), and MacLeod, Norman, and Thisse (1988); it was originally introduced by Hoover (1937). Several of the properties described in this section can be found in these earlier works.

Consumers are uniformly distributed around a circle of unit circumference, S¹, and each buys one unit of the good from the ⁻rm charging the lowest delivered price (consumers purchase from the closest $\$ rm in case of a price tie).⁶ Each $\$ rm occupies a single location on the circle. Transport costs, c (t), are assumed to be a convex, increasing, and twice continuously di®erentiable function of distance (measured around the circle) and the same for all ⁻rms.⁷ These costs are borne by ⁻rms. (Later on we concentrate on the special case of linear transport costs.) Marginal production costs are constant, and henceforth zero without further loss of generality. Each ⁻rm chooses a delivered price for each point. The Bertrand (price) equilibrium (for any given set of ⁻rm locations) involves each ⁻rm serving the points to which it delivers at lowest cost, and it serves such points at a price given by the delivery cost of the next-lowest-cost supplier.⁸ This is because any higher price could be pro-tably undercut by another rm, and any lower price can be pro-tably increased without fear of another ⁻rm serving the market. The natural interpretation of the model is in geographic space; for example, cement plants (transport costs are important and ⁻rms deliver the product). The model has been interpreted in characteristics space as customization of a base product, or \°exible manufacturing" (Eaton and Schmitt, 1994). Examples include car production and clothing. We use the spatial price discrimination model to illustrate how rent dissipation ties down equilibrium locations when static models yield multiple equilibria, and how policy conclusions can be drastically altered. In the conclusions we set our results in a broader perspective.

Let there be n \neg rms, with locations $x_i \ge S^1$, i = 1; ...; n, and de \neg ne Firm $i^{0}s$ natural market, M_i ; to be the set of points that i can serve at least as cheaply as any of its rivals. We apply the standard Bertrand argument to each point in S^1 , assuming that if two or more \neg rms set identical lowest prices at a point consumers buy from the closer \neg rm (purchases are split equally in the case of two or more equally close lowest-price \neg rms). Equilibrium prices are described by the following property:

P1: In the Bertrand price schedule equilibrium, each \neg rm i sets a price equal to its delivered cost at each point outside its natural market, M_i and sets a price equal to the delivered cost of the \neg rm with the second-lowest cost at each point in M_i:

Thus each Firm i serves all customers in M_i (where distinct market areas intersect - for instance because rms' actions coincide - the customers can be assigned arbitrarily to any of the lowest-cost rms since zero prorts are earned on these customers). Each consumer buys from the closest rm, and so transport costs are minimized. Since demand is perfectly inelastic, transport costs are the only determinant of social welfare, so that the equilibrium decentralizes the socially optimal allocation of consumers to rms.

P2: For given ⁻rm locations, the equilibrium allocation is optimal.

The link between equilibrium and optimum is even stronger than P2 suggests, because it holds when locations are chosen endogenously. To see this, note that at the optimum, each -rm is

⁶The analysis is readily adapted to a linear segment instead of a circle: see the discussion at the end of Section 3. ⁷As discussed below, the convexity assumption serves to simplify the analysis, and is not necessary for the key results of this Section and the next two.

⁸There are also other Nash equilibria at which some ⁻rms price below their delivered costs. These can be ruled out by introducing a small amount of product heterogeneity, and then letting the degree of heterogeneity tend to zero: see Anderson and de Palma (1987) for more details. Alternatively, trembling-hand perfection could be applied to rule these out. The equilibrium on which we focus is the standard Bertrand equilibrium (see Tirole, 1988, p.211).

equidistant from its neighbors,⁹ and hence each ⁻rm serves the same size market:

P3: Given the locations of all other rms, the socially optimal location of a rm is at the midpoint of the largest interval between adjacent rms: hence the optimal locations for n rms has them equidistant (1=n apart) around the circle.

The following two properties are useful for the later analysis, and are used to show that the equilibrium locations are the same as the optimal ones. From P1, the equilibrium pro⁻t of a ⁻rm depends only on the distance to each of its two neighbors. Let |(;r) denote this pro⁻t, where ` is the distance to the counterclockwise neighbor, and r is the distance to the clockwise neighbor. Since consumers are uniformly distributed, |(;r)| = |(r;)|. Note too that |(;r)| = 0 if either ` or r is zero (in this case there is Bertrand competition between two ⁻rms with identical costs at each point in space).

P4: The pro⁻t function | is:

- a) increasing in each argument, and
- b) convex in each argument.

The demonstration is as follows. For r_{1} , the pro⁻t +(;r) is given by (see Figure 1):

$$\begin{cases} z_{(r_{i})=2} & z_{r=2} \\ c(x +) & c(jxj) dx + c(r_{i})=2 \end{cases}$$
 (1)

INSERT FIGURE 1.

Using Leibniz's rule, and, after cancellation,

$$\frac{@ \frac{1}{2}}{@^{2}} = \frac{\mathbf{Z}_{(r_{1})=2}}{c^{0}(x + 1)dx}$$

Hence, by the Fundamental Theorem of Calculus,

$$\frac{@!}{@`} = c(\frac{r+1}{2}) i c(\frac{1}{2}):$$
(2)

Similarly,

$$\frac{@}{@r} = c(\frac{r+1}{2}) + c(\frac{r}{2}):$$
(3)

Expressions (2) and (3) also hold for $r < \hat{}$. Part (a) then follows immediately from (2) and (3); part (b) follows from (2) and (3) since c is convex.¹⁰

We shall sometimes use linear transport costs for illustration. Normalizing the transport rate per unit distance gives |(;r)| = r=2, and pro t is then the area of a rectangle with sides r=2 and =2.

⁹Consider a rm located closer to its left (or counterclockwise) neighbor than to its right (or clockwise) one (see Figure 1). If the rm moves a distance dx to the right, total transport costs for serving the market between the rm and its left neighbor rise by the cost of serving the indi®erent consumer (the consumer point midway between the rms) on the left (times dx). Likewise, the total cost of serving the market on its right falls by the cost of serving the indi®erent consumer on the right (times dx). Thus total transport costs of serving the segment are lowest with the rm at the midpoint; moreover, total transport costs are a convex (and symmetric) function of the rm's location in the interval. The convexity property follows from the fact that each incremental move towards the center lowers total transport costs by less than the preceding move. In conjunction with P7 below, the pro⁻t of a rm is a concave function of its location in an interval between two others, zero at the endpoints and highest in the middle.

¹⁰The pro⁻t function is concave in each argument if c is concave.

P5: A $\$ rm's pro $\$ t is a strictly concave function of its location between two neighbors, which is maximized at the midpoint: for $\$ xed b > 0, $\$ (a; b $\$ a) is a strictly concave function of a with maximum at b=2:

From (2) and (3) above, the total derivative $d_i = da$ is $c([b_i a]=2)_i c(a=2)$, which is strictly decreasing for c strictly increasing. We can now characterize the pure-strategy equilibrium at which n \bar{r} ms simultaneously choose locations anticipating the price schedule equilibrium. This is a standard two-stage game with locations chosen before prices. P5 immediately implies:

P6: A best-reply location of a rm is at the midpoint of a largest interval between adjacent rms: hence the location equilibrium for n rms has them equidistant (1=n units apart), which is the social optimum (P3).

A di[®]erent method of showing the equivalence between optimum and equilibrium locations uses the following property. Since consumer demand is completely inelastic, each ⁻rm's pro⁻t is exactly equal to the reduction in transport costs it creates (see ⁻gure 1 for illustration):

P7: Given the location of the other rms, the prort of any rm equals its incremental contribution to social surplus.

This means that, given the locations of the other ⁻rms, each ⁻rm chooses the location that minimizes social costs (i.e., transport costs), and hence maximizes its contribution to social welfare. By P3, the socially optimal locations are also equilibrium ones, and this is the unique equilibrium (up to a rotation and relabelling of ⁻rms).¹¹

We next allow for free entry and exit of \neg rms by assuming that entry entails a sunk cost, F. The standard (static) de nition of equilibrium in spatial models is that no additional \neg rm should wish to enter, and no incumbent \neg rm should prefer to be at a di®erent location or out of the market. These conditions yield a fundamental multiplicity of equilibria. At each of these equilibria, \neg rms are equidistantly spaced, but the spacing can be anywhere between a minimum spacing at which all \neg rms earn zero pro \neg t, and a maximum at which a potential entrant's revenue would fall just short of F. It is localization of competition that is behind this result: any potential entrant would expect to earn revenues signi cantly lower than those earned by incumbents (indeed, one quarter of an incumbent's revenue if transport costs are linear) because an entrant must \neg t into a niche between a pair of incumbents.

If n is the number of \bar{r} ms, let W(n) denote the social welfare, with \bar{r} ms equally spaced as per P3. For the moment, treat n as a continuous variable, and so (up to a positive constant re[°] ecting the consumers' reservation price), W(n) = $_{i} 2n \frac{1}{_{0}} c(x) dx_{i} nF$: Di[®]erentiating with respect to n gives:

P8: The social welfare, W(n), is a strictly concave function of the number of \neg rms. The social optimum can be sustained as an equilibrium with entry.

Since welfare is simply the negative of total costs of serving the market, the concavity property states that successively adding rms (and optimally rearranging them) lowers total transport costs by smaller and smaller amounts. The social optimum is an equilibrium because existing rms must cover their rxed costs (otherwise social surplus would be increased by removing them), and no entrant could cover its rxed cost (otherwise it would be socially benerical to add rms).

There is typically a range of equilibrium $\$ rm numbers. Ignoring integer constraints for the time being, the upper limit on the number of $\$ rms, n_U (the densest equilibrium), is twice the lower

¹¹This in turn implies that the optimum can be sustained as an equilibrium (although as Lederer and Hurter, 1987, point out, there may be other equilibria when the location space is multi-dimensional: this observation corresponds to a result of Spence, 1976).

limit, n_{L} (the sparsest equilibrium), so $n_{U} = 2n_{L}$.¹² At the sparsest equilibrium, rms are just indi®erent about entering midway between each adjacent pair of the nL incumbents, and if they all do enter, each of the nu incumbent is indi[®]erent about leaving.

Formally, let n_{L} be de ned by:

$$\left(\frac{1}{2n_{L}};\frac{1}{2n_{L}}\right) = 2 \int_{0}^{Z_{1=4n_{L}}} c(\frac{1}{2n_{L}}; x) c(x) dx = F; \qquad (4)$$

i.e., the critical number of ⁻rms such that, if they are equispaced, an entrant is just unable to make a positive pro⁻t.¹³ Since we are interested in competition rather than monopoly, we assume that n_L, 1: this implies that there will always be at least two equilibria in the simultaneous-entry game.¹⁴ The social welfare is the same at the two extremes:

 $\begin{array}{l} \text{P9: } W(n_L) = W(n_U), \text{ where } n_U = 2n_L, \text{ with } W^0(n_L) > 0 \text{ and } W^0(n_U) \not\in 0: \\ \text{The } \text{rst part is shown as follows. } De^-\text{ne } \mathbb{C}W = W(n_L)_i W(n_U) = 2n_U \int_0^{1-2n_U} c(x)dx + n_U F_i \\ 2n_L \int_0^{1-2n_L} c(x)dx_i n_L F: \text{Since } 2 \int_0^{1-2n_U} c(1=n_U i x)_i c(x)dx = F; \text{ by de-inition of } n_L, \text{ and } n_U; \\ \text{we can write } \mathbb{C}W = n_U i \int_0^{1-n_U} c(x)dx + \int_0^{1-2n_U} c(x)dx + \int_0^{1-2n_U} c(1=n_U i x)dx \text{ . The desired} \end{array}$ result then follows from rewriting the last integral using the change of variable v $(1 = n_{U_i}) x$. The derivative property then follows from the ⁻rst part and P8.

The intuition behind this latter property is as follows. At n_L, if we add a ⁻rm midway between a pair of existing rms, welfare is unchanged: the rm's social contribution is zero since its pro-ts are zero (P7). Rearranging the ⁻rms to a symmetric position then raises welfare. At n_U, taking out a ⁻rm leaves welfare unchanged. Rearranging then raises welfare.

We now allow for the integer constraint. Clearly there is an equilibrium for each integer number of rms between n_1 and n_{11} (= $2n_1$). That is, the smallest number is given by m_1 f dn_1 e, where d:e denotes the ceiling function (the next integer up if $n_{\rm L}$ is not an integer); and the largest number is given by $m_U \leq bn_U c$, where b:c denotes the °oor function (the integer part of n_U).

INSERT FIGURE 2

P10: If n_U is an even integer, then $m_L = m_U = 2$. If n_U is not an even integer, then $m_{I} = (m_{U} + 1)=2$ if m_{U} is odd; and $m_{I} = m_{U}=2+1$ if m_{U} is even.¹⁵

The explicit restriction to integers is crucial to the analysis of sequential location choice.

As long as transport costs increase in distance, all of the properties above hold true, with the exception of Property 4(b) which requires convexity. The convenience of the convexity assumption is that it simplies the characterization of the equilibrium locations under sequential entry, although convexity is not necessary for this characterization.¹⁶

¹²When transportation costs are linear and the cost per unit distance is normalized, calculations show that the optimal number of $^{-}$ rms is (4F)^{i 1=2}, whereas the equilibrium number ranges from $n_{L} = (8F)^{i} ^{1=2}$ to $n_{U} = (2F)^{i} ^{1=2}$:

¹³Clearly a unique (positive) solution exists since the LHS ! 1 as n_{\perp} ! 0; and the LHS ! 0 as n_{\perp} ! 1, and the LHS is strictly decreasing in nL

¹⁴If (4) yields a solution 1=2 $n_{\rm L} < 1$, then 1 $n_{\rm U} < 2$, so that the only simultaneous-entry equilibrium involves one \overline{rm} . One might think that when $n_L < 1=2$, so that $n_U < 1$, then not even a monopolist can make a pro \overline{t} : in fact, the assumption of inelastic demand allows a monopolist to remain pro-table and the price competition implicit in the de-nition of n_{L} does not apply.

¹⁵The proof is straightforward. See Graham, Knuth, and Patashnik (1994) for properties of the °oor and ceiling functions.

¹⁶Although this characterization simplies the analysis, we do not think that the main economic insights would be fundamentally changed if the characterization were altered by su±ciently concave transport costs.

3. Equilibrium with Sequential Location Choice.

As a prelude to the timing game, we study the following atemporal game. Let there be a su±ciently large number of potential entrant ⁻rms.¹⁷ According to a given order of moves, ⁻rms choose whether to enter, and each entrant selects a location. All entrants then simultaneously choose prices, as described in P1. We de⁻ne an equilibrium to be a sub-game perfect Nash equilibrium such that in any sub-game, each entrant puts equal probability weight on each of its optimal location choices. That is, we assume that when a ⁻rm is indi®erent between two (or more) pro⁻t-maximizing locations, it will choose each of them with equal probability.¹⁸ This implies that pro⁻t is symmetric around the midpoint of a gap between previous entrants. Hence it su±ces in what follows to consider location choice in the half interval up to the midpoint of a gap, and actual choice will put equal weight on optimal choices in this subinterval and their mirror images in the half interval beyond the midpoint.

De ne z as the critical distance between adjacent rms such that an entrant midway between them would earn zero pro t, i.e., |(z=2; z=2) = F, or, equivalently, z satis es 2 $\binom{z=4}{0} [c(z=2; x)]_{i}$ c(x)]dx = F (clearly $z = 1 = n_{L}$ and hence is uniquely determined, see (4)). The proof of the following Proposition is in the Appendix.

PROPOSITION 1. There exists an equilibrium to the sequential-entry game. In any equilibrium, there are $m_L = dn_L e = d1=ze$ rms, which is the same number as at the simultaneous entry equilibrium with the least number of rms. The last rm locates midway in the gap of size s 2 (z; 2z] between its two neighbors, and there is equal spacing z between each adjacent pair of the other rms.

Thus there are three possible ex-post pro⁻t levels: that of the last ⁻rm (the niche ⁻rm), of its two neighbors, and of the remaining (shielded) ⁻rms.

The proof is by induction on an index of the size of the interval. This index will be shown to represent the equilibrium number of entrants in the interval. Accordingly we de ne the function $e(s) = ds = ze_i$ 1, where dedenotes the ceiling function as described above.¹⁹ Note that an interval of length s z will support no pro table entrants, and so e(s) = 0 in this case: also, increasing an interval length by exactly z will increase the number of entrants by one.²⁰

The location of the rms in the equilibrium is unique once we normalize the position of the last rm. In the equilibrium, the entering rms fan out around the circle, and each but the last one locates the critical distance z (the market length that just deters entry) from its inside neighbor. To understand why these locations are chosen, consider the choice facing the penultimate entrant. As shown in part (iii) of the Appendix, this rm will \push" the last entrant (the niche rm) as far as possible subject to preventing entry on its own inside. (Convex transport costs are su ±cient for this result. On the one hand, the penultimate rm, as \location leader", gains from the largest possible market length served when locating a distance z from its neighbor. On the other hand, it loses from not being at the center of the market it serves. With convex transport costs, the

¹⁷Su±ciently large means larger than the number of entrants given in Proposition 1.

¹⁸This randomization assumption rules out strategic use of indi[®]erence by ⁻rms to threaten previous players (see Dewatripont, 1987).

¹⁹Hence $e(1) = d1 = ze_i$ 1, so the equilibrium number of entrants on the unit circle is e(1) + 1 since the <code>rst rm</code> "converts" the circle to an interval of unit length in the sense that payo®s of entrants in the circle are exactly the same as they would be at corresponding locations in a unit interval with a <code>rm</code> at each end.

²⁰We assume that a \overline{rm} enters only if it can earn strictly positive pro \overline{ts} . Note that e(s) = bs=zc except where s=z is an integer.

former e[®]ect dominates. With linear transport costs, the penultimate entrant still strictly prefers to locate a distance z away, suggesting that our main characterization result holds even for some strictly concave transport cost functions.)

A similar argument applies for earlier \neg rms. First note that a \neg rm will never prefer entering 2z, 3z, etc. away, rather than z away: entering 3z away (for example) will simply increase the probability of neighboring the niche \neg rm since the next two \neg rms will \neg II the intervening gap of 3z and be fully protected themselves, and the entrant 3z away has less chance of being protected because it has reduced the number of successors that could shield it.²¹ Likewise, coming in at x < z away is not worthwhile since by increasing x, the \neg rm can gain more on the inside when it is protected by a future entrant, and when it is not, it gains by squeezing the niche \neg rm prefers to squeeze the niche \neg rm, so a fortiori do the previous \neg rms.

Proposition 1 shows that the number of entrants in the sequential-entry equilibrium is identical to the least number of ⁻rms in a simultaneous-entry equilibrium. This is essentially because each entrant (except the last) maximizes the distance from its neighboring predecessor.

The analysis is not changed much for a linear market space. It is readily shown that the <code>-rst</code> two entrants locate inside the market boundaries, at a distance that just deters entry outside these entrants. Thereafter, the model is just like the circle, in the sense that the <code>-rst</code> two entrants on the circle also convert the remaining market space into a linear segment bounded by <code>-rms</code>. As Vickrey noted (for his <code>-xed-price model</code>), the two <code>-rst</code> movers \insulate the remainder of the maneuvering from the e[®]ects of the ends'' (1964, p. 332).

4. Equilibrium Entry Times: Competition for Locations via Early Commitment of Capital to the Market.

It is shown in Proposition 1 that the number of entrants on the unit circle is d1=ze, which we shall call m and we assume m > 1.²² Let R denote 1 mod z; the remainder when 1 is divided by z.²³ If R = 0; the expected gross pro⁻t of entrant i is |(z; z) for all i = 1; ...; m: Otherwise, we can calculate expected pro⁻ts as weighted averages of three expressions. These expressions are: s⁻ (z; z), the pro⁻t of a ⁻rm that is shielded on both sides; H⁻ (z; [R + z] =2); the pro⁻t of a ⁻rm adjacent to the niche ⁻rm; and B⁻ ([R + z] =2; [R + z] =2), the pro⁻t of the niche ⁻rm. The expected pro⁻t of Firm i is then

Note that the rst and second entrants get the same expected prort since they are indistinguishable once the second has entered z away from the rst. Expected prort is thereafter strictly decreasing in order of entry in this case. This is because entrant i = 2; ...; m_i 1 is followed by m_i i_i 1 rms that could fully protect it, so the probability of protection is higher for earlier

²¹If 1=z is an integer then there is no niche ⁻rm and ⁻rms are indi[®]erent between entering at 2z, 3z, etc..

²²For notational simplicity and because of its new interpretation as the equilibrium number of -rms in the sequentialentry game, we now use m instead of m_L, even though they are equal.

²³Thus $R = 1_i$ b1=zc z. For properties of the mod function, in this general case when z need not be an integer, see Graham, Knuth, and Patashnik (1994).

entrants. Vickrey, who discussed a \exists xed-price model, notes a similar e[®]ect: \it is in general an advantage to be one of the earlier locators, in that an earlier seller is less likely to get crowded by the last seller, while the last and next-to-last sellers are at a de \exists nite disadvantage" (1964, p. 331). The monotone pro \exists t property allows us to solve the timing of entry game easily. Assume all \exists rms are risk neutral and that entry entails a sunk cost F, so that entry at time t before the market opens at time zero has a time-zero cost of Fe^{½t} (where ½ is the instantaneous discount rate).

We now argue that competition, via entry time, for the rents associated with being an early mover (that is, facing a low probability of being a neighbor to the niche ⁻rm) will drive expected rents to zero. Rent dissipation through early entry is similarly modeled in games of adoption of new technology such as Fudenberg and Tirole (1985), where again pro⁻t di[®]erentials are eliminated by early commitment of capital to the market.²⁴ An analogous argument is formalized in Anderson and Engers (1994), where we consider a discrete time model in which the interval between instants at which ⁻rms can move converges to zero.²⁵ Rent dissipation arises because if some ⁻rm were to enter at some time at which it earned positive pro⁻ts in any purported equilibrium, then some other ⁻rm would do better preempting it. This requires that there be enough lead time (otherwise the ⁻rst ⁻rms can earn positive pro⁻ts) and that there be enough potential entrants (more than m; otherwise pro⁻ts are still equalized, but not eliminated).

The rent-dissipation condition is that F equal $\exp(i \ \ \ t_i)$ times the present value of the rent stream earned at the time the market opens. If potential entrants are uncertain about whether the market will open, and the common degree of belief at time t that it will open is denoted by P(t), then we simply replace $\exp(i \ \ \ t_i) \exp(i \ \ \ t_i)$ in the rent dissipation condition. As long as P is continuous, the preceding analysis of entry times goes through under this transformation. In this way, we can describe situations in which there need not be a lengthy lead-time before the market opens, as long as its advent gradually becomes apparent. Note that if P has fallen to zero, then some $\ \ rms$ may have committed capital to a lost cause.²⁶

To illustrate the pattern of entry over time, consider the case of linear transport costs, for which |(;r) = r=2: Then the critical deterrence distance z is determined by $z^2=8 = F$, and the pro⁻t of a ⁻rm protected on both sides is $|_S = z^2=2 = 4F$. Recall that R denotes 1 mod z, so the pro⁻t of a neighbor to the niche ⁻rm is $|_H = (R + z)z=4 = 2F(1 + R=z)$ and the pro⁻t of the niche ⁻rm is $|_B = (R + z)^2=8$. Then, for R > 0 and i = 2; :::; m i 1, the entry time of ⁻rm i is given by equating full cost to gross pro⁻t:

$$\dot{z}_i = 4[1_i \ 2^{1_i \ m+i}] + 2^{1_i \ m+i}[2(1 + R = z)];$$

where we have set $i_i = \exp(\frac{1}{2}t_i)$: For Firm 1, $i_1 = i_2$, while for Firm m, $i_m = (1 + R = z)^2$. The equilibrium entry times (for F 1=8 so that there are at least two rms) are depicted in Figure 3.

INSERT FIGURE 3.

²⁴See Hoppe (2000) for discussion and extension.

²⁵At each instant there is a set order of moves for ⁻rms. Although the order of moves is arbitrary, nothing important rides on it because all ⁻rms earn the same expected pro⁻ts at the equilibrium to the timing game. Note that small di®erences between ⁻rms (for example, cost di®erences) tie down the identities of the ⁻rms that enter the market. An alternative approach would be to consider the symmetric mixed-strategy equilibria when entrants can move simultaneously at each instant. In a model without product di®erentiation, Sutton (1998) has shown that, as the interval between instants goes to zero, the limiting distribution of entry times is the same as in the pure-strategy equilibria in a sequential entry game.

²⁶We assume here that the only uncertainty regards whether the market will open at all: a description of the equilibrium when the opening date itself is random is more complex (except for special cases).

At F = 1=8, two rms placed diametrically opposite each other are just pro table, and deter entry. They enter at time zero (t = 0, i = 1). As F falls, rent dissipation requires earlier entry, so ¿ rises, as shown in Figure 3. Equilibrium locations are unchanged, and both ⁻rms earn the same gross pro⁻t (and so enter at the same time) until F = 1=32, when two ⁻rms can no longer deter a third, which enters midway between them. Since the pro⁻ts of the ⁻rst two are reduced by the presence of the third, they enter substantially later once the third cannot be deterred. As F falls further, the *rst* two entrants (which always earn the same expected pro*t*) close up to deter entry on the shorter arc between them. The third entrant's gross pro⁻t rises both because F falls and because the market it serves increases. The higher pro⁻t implies it must enter earlier, and its entry time gets closer to that of the other two. (Nevertheless, the -rst two always have higher gross pro⁻ts for lower F since the direct e[®]ect of falling F dominates the indirect e[®]ect of having to be closer.) For F just above 1=72, the three ⁻rms locate one third of the circumference apart and just manage to deter a fourth. The corresponding entry time is $\lambda = 4$ because the maximal gross pro⁻t that can ever be earned by deterring rms is four times that of an entrant, and this maximal prort is attained when $\bar{r}ms$ are equispaced (1 mod z = 0). Hence $\dot{c} = 4$ represents the earliest possible entry time for any number of ⁻rms, at which time they all enter simultaneously.

Now consider F just below 1=72. Then 3 rms cannot deter a fourth. The rst two can guarantee that there will be no entry between them, and so earn the greatest expected pro t (hence earliest entry time), locating just less than 1=3 apart. The next rm knows it must be adjacent to the niche rm and can fully protect only one side of its market by locating just less than 1=3 from one of the rst two rms). The niche rm then locates at the midpoint of the remaining gap. As F falls further, the rst three rms must close ranks to deter entry between them. This renders gross pro ts and hence entry times more symmetric. Covergence to symmetry continues until F is just above 1=128, when all rms locate 1=4 apart, and just deter a fth rm: all four rms enter at i = 4:

The same basic ideas apply for all smaller F. For F 2 $\frac{1}{8} \frac{1}{(m_i \ 1)^2}$; $\frac{1}{8} \frac{1}{m^2}$, m⁻rms enter in equilibrium, and entry times become earlier and closer together as F decreases within this range. The incentive for early entry stems from the higher gross pro⁻t through greater probability of being protected on both sides.

If rms di[®]er in ⁻xed costs, all ⁻rms with costs above some (endogenous) threshold level stay out. Those with lower costs enter earlier, and earn rents to the extent that their costs are below those of the most competitive ⁻rm kept out. Thus temporal competition leads to an order of entry that is e±cient in the sense that only the lowest cost ⁻rms will produce. Lower cost ⁻rms enter earlier than higher-cost ones so that the extent of rent dissipation is lessened.

We show in the next section that the atemporal sequential entry model of Section 3 leads to too few rms in the market. Competition for rents leads to wasteful early commitment of capital to the market to stake claims on prortable slots. An entry subsidy would alleviate the rst distortion, but aggravate the second. The trade-o[®] is analyzed in Section 6.

5. Welfare Properties.

One of the problems with static location models is that they do not make tight predictions: there are multiple equilibria. The received theory is also mute on the issue of rent dissipation (it is ignored because there is no channel for competition for rents). Nevertheless, it is still instructive to compare the equilibria in a purely atemporal sense, by which we mean we can compare the welfare

properties of the timeless sequential-entry game with those of the timeless simultaneous-entry one. In other words, we contrast a situation in which ⁻rms move in a given order at the date the market opens, with one in which they all move simultaneously at that date. Another way to interpret the timeless sequential-entry model is to suppose that the government auctions o[®] slots in the order of moves, so the rents are not dissipated, but simply transferred to the government. This experiment allows us to separate out the sources of ine±ciency in the dynamic model. In this section, we argue that the timeless sequential-entry location equilibrium yields lower total surplus than nearly all the simultaneous-entry equilibrium outcomes. We address the role for tax policy in reducing ine±ciency in Section 6.

Recall that m_U denotes the (integer) number of \neg rms at the simultaneous-entry equilibrium with the highest (uppermost) number of \neg rms, and m_L is the number of \neg rms at the simultaneous-entry equilibrium with the lowest number of \neg rms. As we have shown, m_L is also the equilibrium number of \neg rms in the sequential-entry equilibrium. Clearly welfare is lower with m_L \neg rms entering sequentially than simultaneously, by P3, because symmetric locations yield higher surplus than asymmetric ones. Since the total surplus is a strictly concave function of the number of \neg rms than at the sequential-entry one with m_L \neg rms for the sequential-entry equilibrium to be worse than all the simultaneous-entry ones. As we show, this is true if m_U is even, but may not necessarily be so if m_U is odd, although in the latter case it remains true that the sequential-entry equilibrium is worse than all the other simultaneous-entry equilibria. Thus the sequential-entry equilibrium is worse than nearly all the simultaneous-entry ones.

PROPOSITION 2. Social surplus is strictly lower at the atemporal sequential-entry equilibrium than at:

a) almost any simultaneous-entry equilibrium if m_U is even;

b) any simultaneous-entry equilibrium with fewer than m_U ⁻rms if m_U is odd.

The proof is in the Appendix. The Proposition implies that the allocation attained when allowance is made for rent-seeking behavior is more ine±cient than would be thought from considering the usual static (simultaneous-entry) models. Once we couple the lost rents with the pure locational ine±ciency, we see that di®erentiated product markets may be a source of signi⁻cant cause for concern regarding market performance. In the next section, we look at the case for corrective subsidies or taxes. Doing so gives further insight into the nature of the market failure.

6. Entry Tax or Subsidy?

Various governments pursue policies aimed at encouraging the start-up of new businesses. In this section we examine whether taxes or subsidies can improve the allocation of resources. We rst argue that the static model is not useful for answering these questions for two reasons. First, the multiple equilibria inherent to the static model include both those equilibria that would be improved by subsidies and those that would be improved by taxes. Second, by ignoring competition for rents the static model systematically overlooks a key source of deadweight loss.

The indeterminacy due to multiplicity of equilibria is illustrated by considering the two extreme cases. These are the minimum pro⁻t equilibrium (with m_U ⁻rms), and the maximum pro⁻t equilibrium (with m_L ⁻rms). An entry tax e[®]ectively raises the ⁻xed cost an entrant incurs and so decreases both the minimum and the maximum number of ⁻rms. From P8 through P10 (and Figure 2), welfare falls with a tax if the equilibrium with the minimum number of ⁻rms is the

relevant one, and rises if the maximum number of <code>-rms</code> is the relevant one. Hence a subsidy is optimal if one believes that the market equilibrium involves the minimum number of <code>-rms</code>. A subsidy works in this case by rendering entry more pro<code>-table</code> and so requiring tighter spacing between <code>-rms</code> and hence a greater variety of products. In either case, social welfare is a step function of the tax/subsidy because welfare only changes at critical values that alter the number of <code>-rms</code>.

Now consider the timeless version of the sequential-entry model (with m_L rms). Here the social welfare still has discontinuities where the number of rms changes, but is no longer constant between these discontinuities. This is because rms early in the sequence of moves locate so as just to deter entry on their inside; the critical distance depends on the size of the tax/subsidy. By P6, symmetric locations are preferred to asymmetric ones, so the optimal tax/subsidy will always involve symmetric locations. Second, the optimal policy will be a subsidy rather than a tax, in order to increase the number of rms to the optimal level (the rst-best optimum is attainable).

The conclusion of the previous paragraph is drastically altered once proper account is taken of the competition for the rents from moving early.²⁷ To analyze the optimal policy, we assume for simplicity that transport costs are linear, and equal to distance. The complication that "rms' successors' locations are unknown causes no di±culty because total expected gross pro⁻ts equal total actual gross pro⁻ts. Thus total resource costs are the same as when all but the last three "rms know that they will earn $\frac{1}{2}(z;z)$, the next two know they will be adjacent to the niche "rm, and the last is the niche "rm. With linear transport costs, the shielded "rms all enter at $\frac{1}{2} = 4$ (since gross pro⁻ts of a "rm that just deters are four times those of a potential entrant). The two neighbors to the niche "rm enter at $\frac{1}{2} = \frac{1}{2}n_{i-1}$ as given in Section 4, and the niche "rm enters at $\frac{1}{2} = \frac{1}{2}n$ (again as given in Section 4, since both the niche "rm and its neighbors earn the same in this deterministic version as in the earlier one).

Total social cost C, is the sum of transport costs and capital costs. With n ⁻rms,

$$C = TTC + (n_{i} 3)4F + 2F_{i_{1}} + F_{i_{2}};$$

where TTC represents total transport costs. From Section 3 the equilibrium number of \neg rms will be d1=ze, and in the sequel, the reader should interpret n as being equal to d1=ze. For notational clarity, we do not make the substitution.

There are (n_i 2) gaps of length z, and two of length [1_i (n_i 2)z]=2; since a gap of length x entails a transport cost of x²=4, we have TTC = (n_i 2)z²=4 + $\frac{1}{2}$ [(1_i (n_i 2)z)=2]². Recall that the gross pro⁻t of a ⁻rm that is [`] from its left neighbor and r from its right neighbor is [`]r=2. Hence in and in_i 1 are determined by the zero pro⁻t conditions (F + T)in = $\frac{1}{2}$ [(1_i (n_i 2)z)=2]², and (F + T)in = $\frac{1}{2}$ [(1_i (n_i 2)z)=2]², where T is the tax on each entrant. Total cost is thus

$$C = (n_{i} 2)z^{2} + \frac{1}{2}[(1_{i} (n_{i} 2)z) + (n_{i} 3)4F + \frac{1}{8}[1_{i} (n_{i} 2)z]^{2} + \frac{z}{2}[(1_{i} (n_{i} 2)z] F + (F + T):$$

²⁷The ⁻rst-best optimum can be achieved if the tax/subsidy policy is allowed to be time dependent. In this case, high entry taxes can be set before the market opens, to deter completely the loss from early entry. These would be followed by the optimal subsidy (at the opening date) as in the previous paragraph. In practice, however, policies rarely vary ⁻nely with time. Instead, there are blanket policies, like the small business start-up subsidy. At this level, we ask whether such a subsidy is a move in the right direction. We shall answer no, that the optimal policy is rather a tax.

We now de ne z(T) to be the maximal distance between neighbors that does not allow pro table P_{R} try, if tax T is imposed. Under our linear transport cost assumption, F + T = z²=8, or z(T) = 8(F + T). Substituting this in the cost expression, and then di[®]erentiating with respect to z yields

$$\frac{dC}{dz} = \frac{\frac{1}{2}}{4}(n_{i} 2)(nz_{i} 1)_{i} \frac{2F[1_{i} (n_{i} 4)z]}{z^{3}}$$

where the \bar{r} st term is positive (transport costs rise because \bar{r} ms are less symmetrically placed), and the second term is negative (less rents are dissipated). The derivative expression holds for all z such that 1=z is not an integer, i.e. for all values of z such that n does not jump to the next integer down. The following result will be used in the proof that a subsidy is never optimal: dC=dz < 0 for all T < 0 wherever the derivative is de ned. That is, the cost function is decreasing in T, (i:e. increasing in the subsidy), except where the number of \bar{r} ms changes.²⁸

We next consider the values of C as 1=z approaches an integer. For z # 1=n, the spatial pattern approaches n equispaced -rms, and C approaches

$$C^+ = 4nF + \frac{1}{4n} = \frac{4F}{z} + \frac{z}{4};$$

where z = 1=n (since the average distance travelled by consumers is $\frac{1}{4n}$ and each of n ⁻rms enters at z = 4, so incurring cost 4F each). Similarly, for $z = \frac{1}{n}$, the spatial arrangement allows n + 1 ⁻rms, with n of them almost symmetrically placed around the circle, and the last ⁻rm in the niche midway between the pair that is slightly further apart than the other adjacent pairs.

Let Cⁱ denote $\lim_{z''=n} C(z) = 4nF_i$ 4F i T + $\frac{1}{4n}$:²⁹ Since F + T = z^2 =8 = 1=8n², we can write

$$C^{\dagger} = 4nF_{\dagger} 3F + \frac{1}{4n}_{\dagger} \frac{1}{8n^{2}} = \frac{4F}{z}_{\dagger} 3F + \frac{z}{4}_{\dagger} \frac{z^{2}}{8}$$

Clearly $C^i < C^+$, C^+ is strictly convex, and C^i is minimized at a higher value of z than C^+ . The relation between C^i , C^+ , and C is illustrated in Figure 4.

INSERT FIGURE 4

The proof of the following Proposition (which is in the Appendix) con⁻rms the pattern suggested by Figure 4.

PROPOSITION 3. At the equilibrium to the timing game for the spatial price discrimination model of product di[®]erentiation with linear transport costs, an entry subsidy is never optimal.

The last part of the proof (for monopoly) also indicates that one ⁻rm serves the market absent intervention if and only if one ⁻rm serves the market under the optimal tax. Moreover, if two

 n^{28} To show this, note rst that dz = dT > 0, and that, for a subsidy (T < 0), F > z²=8 and dC=dz is less than $\frac{1}{4}$ i $\frac{[1_i (n_i 4)z]}{z} + (n_i 2)(nz_i 1)$, which can be written as $= \frac{1}{4z} f(nz + 1)[(n_i 2)z_i 1]g$; and is negative as required since $(n_i 2)z < 1$:

²⁹To understand the relation between Cⁱ and C⁺, suppose we start at a symmetric position and then the tax, T, were decreased slightly, so another \neg rm would enter. This \neg rm would earn zero pro \neg t, so its social cost is F, but the bene \neg ts in terms of transport costs saved would be F + T. In addition, its entry will halve the gross pro \neg ts of its two neighbors. They used to enter at $i_{c} = 4$, they now do so at $i_{c} = 2$, so resource costs fall by 4F. Hence Cⁱ = C⁺ i 4F i T:

⁻rms serve the market under laisser-faire, then two ⁻rms will serve the market under the optimal tax (which takes away all their rents and so eliminates temporal dissipation). More generally, if m ⁻rms serve the market under laisser-faire, then the number that serve under the optimal tax is m or fewer. One characteristic of the model is that (unless the optimum entails one or two ⁻rms) a symmetric con⁻guration of ⁻rms is never optimal. This is because a slight decrease in the tax would induce an extra entrant, reducing social cost from C⁺(z) to Cⁱ(z) (see also Figure 4).

To understand this result better, suppose that F is small, so that the number of entrants is large and we can e[®]ectively ignore the integer problem. In the static (simultaneous-entry) model, the equilibrium with the largest number of ⁻rms entails zero pro⁻t and hence there are $\frac{1}{2F}$ entrants (since gross pro⁻t is $\frac{1}{2n^2}$), while the equilibrium with the smallest number of ⁻rms has half this number, or $\frac{1}{8F}$ ⁻rms. The latter is also the number of ⁻rms at the sequential-entry equilibrium. In an atemporal setting, the optimum number minimizes $\frac{1}{4n}$ + nF, where $\frac{1}{4n}$ is the average (and aggregate) transport cost and nF is the total entry cost. The socially optimal number is then $\frac{1}{4F}$, which lies between the two extremes of the static equilibria. Hence, under the atemporal sequential-entry equilibrium, a subsidy would be prescribed because a subsidy raises the number of ⁻rms towards the optimum as incumbents close ranks to deter entrants. However, once we introduce entry-time competition, the social entry cost per ⁻rm is 4F rather than F because of entry competition: the entrant who is just deterred would earn a gross pro⁻t of one fourth of that earned by equilibrium entrants. The social cost is then $\frac{1}{4n}$ + 4nF, with a minimum at $\frac{1}{16F}$ ⁻rms. Since this is fewer ⁻rms than the equilibrium number, a tax is desirable.³⁰ For larger F, the result still holds since the Cⁱ locus is minimized at a lower number of ⁻rms than the C⁺ locus (see Figure 4: note too that these loci are virtually coincident for F small).

7. Conclusions.

In spatial models there are typically multiple equilibria, ranging from a zero-pro⁻t equilibrium to one at which a potential entrant would just fail to cover its costs and active ⁻rms earn substantial pure pro⁻ts. These pro⁻ts persist because a potential entrant must enter a niche in the market between existing ⁻rms - even if post-entry price competition were no more intense, the entrant would serve half the market that an incumbent does before entry. Allowing for ⁻ercer price competition renders entry even less attractive, and consequently raises the threshold pro⁻t that is immune to entry. The potential for pure pro⁻t in equilibrium in spatial (or characteristics) models was a key insight of Vickrey (1964) and Eaton and Lipsey (1978). Subsequently, faced with this multiplicity of equilibria, many authors have chosen to concentrate on the zero-pro⁻t equilibrium, and typically ⁻nd that there are too many ⁻rms in equilibrium. At the other extreme, there can be too few ⁻rms at the equilibrium at which active ⁻rms' pro⁻ts are maximal (see Capozza and van Order, 1980, and Eaton and Wooders, 1985). Given the multiplicity of equilibria, an obvious question is whether there is a reasonable mechanism to select one of them.

We introduce a dimension (time) that allows ⁻rms to compete for possible pro⁻ts. The process of competition resolves the multiplicity problem: it determines a unique number of ⁻rms and pattern of ⁻rm locations. The equilibrium obtained is similar to the static equilibrium with maximal pro⁻ts

³⁰When F is small, the preceding analysis also applies when transport costs are non-linear, since the derivative of the transport cost function at zero provides a local approximation to the function over the relevant range.

rather than the zero-pro⁻t static equilibrium favored by many authors. But there is an important di[®]erence between the equilibrium in the model with timing and any of the static equilibria - the possibility that rents may be dissipated can radically change the policy implications of the analysis. As we showed, the atemporal sequential-entry model suggests that a subsidy is an optimal corrective policy: however, if timing is considered, a subsidy is never desired, at least under linear transport costs or su±ciently many ⁻rms. What is surprising in this result is that the ine±ciencies due to suboptimal locations and insu±cient entry are always outweighed by the wasteful rent dissipation. This no-subsidy result emphasizes the point that the properties of the equilibrium with endogenous entry times can be very di[®]erent from those in the atemporal sequential-entry model.

Because our setting is quite speci⁻c it is worth putting our results in a broader perspective, to see how the insights generalize and point out some limitations. First, the rents in the model stem from the spatial environment and there are many ways in which the details of the spatial model can be varied. As discussed above, the assumption of a circular market does not really matter in that a linear market would give similar results, and we believe that the same is true in a market with more dimensions. It would be worthwhile to consider the spatial model with mill-pricing instead of spatial price discrimination: this is intractable since an entrant a[®]ects the equilibrium prices of all ⁻rms through the chain-linking of competition that is absent in the \extreme localization" that characterizes the discriminatory model.³¹ Despite the added complications, there is no reason to expect the results to be fundamentally altered. Indeed, the mill-pricing model is tractable when F is small so that the integer problem can be ignored. Deneckere and Rothschild (1992) argue that the atemporal sequential-entry model under mill-pricing entails more ⁻rms than is socially optimal. Although this result di[®]ers from the spatial price discrimination result, it reinforces the case for an entry tax since such a tax both alleviates overentry of ⁻rms and rent dissipation.

Non-spatial models of product di[®]erentiation may give very di[®]erent results. In standard symmetric models (such as the logit and CES³²), there are virtually no rents at the free-entry equilibrium (only those minor rents arising from the integer constraint on the number of ⁻rms). Hence there is no multiplicity of equilibrium problem, and, with negligible rents, the standard analysis applies. It is quite easy to introduce asymmetries in non-spatial models by allowing di[®]erent products to be associated with di[®]erent production costs, or else assigning them di[®]erent \quality'' variables (which essentially shift demand). This leads to di[®]erential rents across products and hence to rent dissipation in our framework, but does not typically lead to fundamental multiplicity of equilibria, and hence, without multiplicity, the issue is more straightforward. Insofar as the market solution tends to err on the side of producing too many products (see Anderson and de Palma, 1999), an entry tax both deters marginal goods and alleviates rent dissipation.

We have focussed on rent dissipation via early entry, in a simple framework in which all rent dissipation is socially wasteful. Other channels of competition for rents (such as lobbying for building permits by promising infrastructure improvements) might have bene⁻cial side e[®]ects, thereby reducing the damage from dissipation and weakening the case for an entry tax. In our model, if the market were to grow continuously (rather than discretely) over time, then early commitment has some social value because some consumers are served. However, in such situations, early ⁻rms face a trade-o[®] between pre-emption for the later market, and optimally serving the current market. The spatial entry pattern is then rather intricate - a ⁻rm may anticipate entrants on both sides

³¹See Anderson, de Palma, and Thisse (1992) for further discussion of these issues, and Neven (1987) for some preliminary results on sequential entry under mill-pricing.

³²See Spence (1976), Dixit and Stiglitz (1977), and Anderson, de Palma, and Thisse (1992).

but still enter. This is a topic for future research.

Finally, the model of this paper has $\$ rms already fully informed about future demand, and so they have only to sink the entry cost to lay claim to a product. This assumption may well characterize the location of retail stores in a growing town, but the creation of new products is a more uncertain prospect. In the latter situation, a $\$ rst entrant must typically engage in product development, market research, and marketing to develop a new market. Other $\$ rms can then enter at a much lower cost once they learn that there is a potential market in the o \pm ng. The signi cant free-rider problem associated with the initial market development is a force that may counteract the ine \pm ciency of rent dissipation. This is another topic that should be investigated in more detail.

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Appendix.

Proof of Proposition 1.

The proof proceeds in ve steps. Let $e(s) = ds=ze_i$ 1, where die denotes the ceiling function. In (i) we consider e(s) = 1, i.e., a gap of size s 2 (z; 2z]. Thenceforth we have s > 2z. For the induction step, given any integer n 2 we suppose that the result holds true for all intervals of length s, with $e(s) = n_i$ 1, and show that this implies it is true for any interval such that e(s) = n (recall that e(s) will be the equilibrium number of \neg rms that will enter a gap of length s). For the remainder of the proof, we consider four kinds of subintervals; in each we show that locating at z is better than locating at any point in the subinterval. In (ii), we consider x such that $e(s_i = x) = n_i$ that is, locating so close to the left end that n further \neg rms still enter on the right (and none on the left). In (iii), we consider e(x) = 0 and $e(s_i = x) = n_i$ 1, and show that pro \neg t rises with x in this interval, as x approaches its maximum value, z. In (iv) we have e(x) = k > 0 and $e(s_i = x) = n_i k_i = 1$:

(i) Let e(s) = 1, so that s 2 (z;2z]. Clearly an entrant in this gap will locate at the midpoint (by P6) and no further pro⁻table entry is then possible.

(ii) We show that any $\bar{r}m$ entering a gap of size s > 2z will never enter at $x \ge [0, s_i nz]$, where $n = e(s) = ds = ze_i$ 1, because locating at x in this interval is less protable than locating at z. The former strategy would yield the $\bar{r}m$ a left neighbor at distance $s_i nz$, and a right neighbor at most z away. Locating at z gives = z and at worst (when neighboring the niche $\bar{r}m$) $r = [s_i (n_i 1)z]=2$. It therefore $su\pm ces$ that $[s_i (n_i 1)z]=2$, $(s_i nz)$, or s (n + 1)z, which is true since n = e(s):

(iii) We next show that locating at x 2 [s_i nz; z) is less pro⁻table than locating at z. By the induction hypothesis, a ⁻rm entering at x 2 [s_i nz; z) knows it will be followed by (n_i 1) entrants on its right and none on its left. With probability 1_i $2^{2_i n}$ it will have a right neighbor at distance r = z; with probability $2^{2_i n}$ it will be adjacent to the niche ⁻rm and its right neighbor is at a distance: r(x) = [s_i (n_i 2)z_i x]=2: Its expected pro⁻t is then [1_i $2^{2_i n}$]; (x; z) + $2^{2_i n}$; (x; r(x)). Now, locating at z gives an expected pro⁻t of (1_i $2^{2_i n}$); (z; z) + $2^{2_i n}$; (z; r(z)). Clearly ; (z; z) > ; (x; z), so it su±ces to show that $\frac{1}{2^{2_i n}} + \frac{1}{2^{2_i n}} + \frac{1}{2^{$

$$\frac{d_1}{dx} = \frac{@_1}{@_1} ; \frac{1}{2} \frac{@_1}{@_r} = \frac{1}{2} \frac{\frac{y_2}{r}}{c(\frac{x+r(x)}{2}) + c(\frac{r(x)}{2}) ; 2c(\frac{x}{2})}$$

To show this is positive, \neg rst note that r(x) > x=2 (since s > nz) s_i (n_i 2) z_i $x > 2z_i$ x > x, i:e:, 2r(x) > x). Because c is increasing, it then su±ces that $d_i^{+} = dx_j^{-}$ 0 when r(x) = x=2, i.e.

$$c(\frac{3x}{4}) + c(\frac{x}{4}) = 2c(\frac{x}{2}) = 0;$$

which is true by convexity of c.

It remains to consider x 2 (z; s=2] (where s > 2z; s 2z has already been treated). There are two cases, depending on the number of subsequent entrants that the <code>-rst</code> entrant's location choice induces. Recall that n denotes e(s), the total number of <code>-rms</code> that, in equilibrium, will enter an interval of length s. If the <code>-rst</code> entrant locates at x in [0; s], then there will be e(x) entrants on the left, and e(s <code>i</code> x) entrants on the right. Hence the total number of subsequent entrants is $e(x) + e(s_i x)$. This total is periodic, with period z, since increasing x a distance z increases the <code>-rst</code> term by one, and decreases the second by one. Note that $e(x) + e(s_i x)$ is either equal to n (case

(iv)) or equal to $n_i = 1$ (case (v)) depending on whether x mod z < s mod z or not, respectively. [To see this, it su±ces to consider the subinterval [0; z), by periodicity: clearly e(x) = 0, and $e(s_i = x)$ is n if x < s_i nz(i:e:, x = x mod z < s mod z = s_i nz) and $e(s_i = x)$ is n_i 1 if x s_i nz:]

Suppose the "rst entrant comes in at x = kz +[®] where k is a positive integer and [®] 2 [0; z), so [®] = x mod z. Hence k further entrants locate to its left, i.e., e(x) = k. Of these entrants, all but the last will locate z from an end of the remaining subinterval, leaving the last "rm to locate in the middle of the remaining gap. Since the k_i 1 "rms are equally likely to locate z from either end of their subinterval, the "rst entrant will end up adjacent to the niche "rm (i.e., \holding the baby") with probability $2^{1_i k}$. In this case it is $[z + ^e]=2$ from its left neighbor. It is protected with probability 1 is $2^{1_i k}$, and in this case it is the maximal distance z from its left neighbor.

If the entrant locates at z, it precludes further entry on its left and is z from its left neighbor with probability one. With probability $2^{2_i n}$ its right neighbor is at distance [s i (n i 1)z]=2, otherwise that neighbor is at distance z:

The di[®]erence between cases (iv) and (v) is the number of -rms on the right.

(iv) Here $e(s_i x) = n_i k$. With probability $2^{1_i n+k}$ the rst entrant is not shielded on its right and is then $[s_i (n_i 1)z_i @]=2 = [s \mod z + z_i x \mod z]=2$ from its right neighbor; with probability $1_i 2^{1_i n+k}$ it is z from its right neighbor. We wish to compare the corresponding expected prort with that obtained by entering at z. From the expressions in the preceding paragraph, expected prorts are higher at z if:

 $\begin{array}{l} [1_{i} \ 2^{2_{i}} \ n]_{i} \ (z; z) \ + \ 2^{2_{i}} \ n}_{i} \ (z; [s_{i} \ (n_{i} \ 1)z]=2) \ > \ [1_{i} \ 2^{1_{i}} \ k] [1_{i} \ 2^{1_{i}} \ n+k}]_{i} \ (z; z) \\ + [1_{i} \ 2^{1_{i}} \ k] 2^{1_{i}} \ n+k}_{i} \ (z; [s_{i} \ (n_{i} \ 1)z_{i} \ \ensuremath{\$}]=2) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{1_{i}} \ n+k}] \\ + \ ([z \ + \ensuremath{\$}]=2; z) \ + \ 2^{1_{i}} \ k2^{1_{i}} \ n+k}_{i} \ ([z \ + \ensuremath{\$}]=2; [s_{i} \ (n_{i} \ 1)z_{i} \ \ensuremath{\$}]=2): \end{array}$

First note that $[1_i 2^{2i} n] \ [1_i 2^{1i} k] [1_i 2^{1i} n+k]$, so that the [(z; z) terms (which are the highest ones) on the right of the inequality are more heavily weighted than those on the left: the probability of being shielded on both °anks is greater when the $\$ rm shields one °ank with certainty. To prove the inequality, it now su±ces to show that the term $[(z, [s_i (n_i 1)z]=2)]$ from the left left hand side is greater than each of the other pro $\$ t terms (that is, excepting the [(z; z)] term) on the right-hand side. This follows by symmetry of the pro $\$ t functions in their arguments, and that the smaller length is always less than $[s_i (n_i 1)z]=2$: the only case that is not trivial is that $[s_i (n_i 1)z]=2 > [z + @]=2$, which follows since s mod z > @ in Case (iv).

(v) Here $e(s_i x) = n_i k_i 1$, and $@2[s \mod z, z)$. With probability $2^{2_i n+k}$ the -rst entrant is not shielded on its right and is then $[s_i (n_i 2)z_i @]=2 = [s \mod z + 2z_i x \mod z]=2$ from its right-hand neighbor; with probability $1_i 2^{2_i n+k}$ it is z from its right-hand neighbor. Expected pro-ts are no lower at z if and only if:

$$\begin{array}{l} [1_{i} \ 2^{2_{i}} \ n]_{i} \ (z; z) \ + \ 2^{2_{i}} \ n|_{i} \ (z; [s_{i} \ (n_{i} \ 1)z]=2) \ [1_{i} \ 2^{1_{i}} \ k][1_{i} \ 2^{2_{i}} \ n+k]_{i} \ (z; z) \ + \ [1_{i} \ 2^{1_{i}} \ k]2^{2_{i}} \ n+k|_{i} \ (z; [s_{i} \ (n_{i} \ 2)z_{i} \ ^{\otimes}]=2) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ [(z; z) \ + \ [1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ [1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ + \ 2^{1_{i}} \ k[1_{i} \ 2^{2_{i}} \ n+k] \ (z; z) \ ($$

Consolidating the terms in |(z;z) and using symmetry:

 $\begin{bmatrix} i & 2^{3_{i}} & n \\ i & 2^{2_{i}} & n + 2^{1_{i}} & k + 2^{2_{i}} & n+k \end{bmatrix} | (z;z) + 2^{2_{i}} & n \\ [1 & i & 2^{1_{i}} & k \end{bmatrix} 2^{2_{i}} & n+k \\ [2 & (z;[s_{i} & (n_{i} & 2)z_{i} & ^{\mathbb{B}}]=2) + 2^{1_{i}} & [1_{i} & 2^{2_{i}} & n+k] \\ + 2^{1_{i}} & k & 2^{2_{i}} & n+k \\ [2 & (z;[z_{i} + \mathbb{B}]=2;[s_{i} & (n_{i} & 2)z_{i} & ^{\mathbb{B}}]=2) \\ \end{bmatrix} = 2;$

To show this inequality holds, we rewrite it in the form:

$$W_0 |_0 + W_1 |_1 , W_2 |_2 + W_3 |_3 + W_4 |_4$$

where $w_0 = [i \ 2^{3_i} n_i \ 2^{2_i} n + 2^{1_i} k + 2^{2_i} n + k]$, $|_0 = |(z; z)$, etc., and we reverse the order of the rst two terms on the RHS if necessary so that $|_2 = |_3$. Since $|_4 = |_3$, it su±ces to show that

$$W_0 \mid_0 + W_1 \mid_1 , W_2 \mid_2 + W_5 \mid_3;$$
 (A.1)

where we have de ned $w_5 = w_3 + w_4$.

We now show that $w_0 \ w_1$ and $w_0 \ w_2$. The <code>rst</code> amounts to showing (a) $\begin{bmatrix} 2^{3i} n \\ 2^{2i} n \end{bmatrix} 2^{2i} n + 2^{1i} k + 2^{2i} n + k \end{bmatrix} 2^{2i} n$; while the second is established by showing both (b) $\begin{bmatrix} 2^{3i} n \\ 2^{2i} n \end{bmatrix} 2^{2i} n + 2^{1i} k + 2^{2i} n + k \end{bmatrix} [1 \\ \begin{bmatrix} 2^{1i} k \\ 2^{2i} n \end{bmatrix} 2^{2i} n + 2^{1i} k + 2^{2i} n + k \end{bmatrix} 2^{1i} k \begin{bmatrix} 1 \\ 2^{2i} n + k \end{bmatrix}$; (c) $\begin{bmatrix} 2^{3i} n \\ 2^{2i} n \end{bmatrix} 2^{2i} n + 2^{1i} k + 2^{2i} n + k \end{bmatrix} 2^{1i} k \begin{bmatrix} 1 \\ 2^{2i} n + k \end{bmatrix}$; To see (a), rewrite it as $\begin{bmatrix} 2^{2i} k + 2^{3i} n + k \end{bmatrix} = 2 \\ 2^{2i} 2^{4i} n$, and the note that the LHS is at least $2^{(5i} n) = 2$, by the inequality between the arithmetic mean and the geometric mean. Since n 3 for the case

by the inequality between the arithmetic mean and the geometric mean. Since n_j 3 for the case at hand, the RHS is no greater than this bound. Condition (b) reduces to n_j k + 1, which is true since k n_j 1. Finally, (c) reduces to the trivial k $_{\rm s}$ 0:

We can now show that (A1) holds. Note that $|_i$ can be written as $|_(z; r_i)$, with $r_1 < r_3 < r_2 < r_0$ and $r_3 \downarrow r_1 = r_0 \downarrow r_2$. Since $|_(\mathfrak{k})$ is convex in its second argument (P4b), $(|_{3} \downarrow |_1) = (r_3 \downarrow r_1) = (r_3 \downarrow r_1) = (|_{0} \downarrow |_2) = (r_0 \downarrow r_2)$, and hence $(|_{3} \downarrow |_1) = (|_{0} \downarrow |_2)$ $(r_3 \downarrow r_1) = (r_0 \downarrow r_2) = 1$ $w_0 = w_1$. Thus $w_0 \mid_0 + w_1 \mid_1$, $w_0 \mid_2 + w_1 \mid_3$, $w_2 \mid_2 + w_5 \mid_3$, since w_0 , w_2 , $|_2$, $|_3$, and $w_0 + w_1 = w_2 + w_5$:2 Proof of Proposition 2.

From P10, there are three cases to consider. The <code>-rst</code> (razor's edge case) has $n_U = m_U$ an even integer, in which case 1 mod z = 0, and the sequential-entry equilibrium has the same outcome as the simultaneous-entry one with the fewest <code>-rms</code>. Welfare under sequential entry is the same as at the two extreme cases of simultaneous-entry (see P9), and lower than at any other simultaneous-entry equilibrium.

Suppose next that m_U is even but n_U is not an even integer, so $m_L = m_U = 2 + 1$. Since all pairs of adjacent ⁻rms except two are z apart at the sequential-entry equilibrium, adding a ⁻rm at the midpoint of each gap of size z (and there are $m_U = 2_i$ 1 such gaps) will leave welfare unchanged (by P7) and bring the number of ⁻rms to m_U . Hence there are now m_U ⁻rms in both cases, and the simultaneous-entry case has them symmetrically placed and so is preferred to the other one, which does not.

Now suppose that m_U is odd, in which case $m_L = (m_U + 1)=2$. The argument of the previous paragraph can be adapted to show that the sequential-entry equilibrium is worse than any simultaneous-entry one with fewer than m_U rms. There are $m_{L\,i}$ 2 gaps of size z, so when these are "Iled, there are $2m_{L\,i}$ 2 = $m_{U\,i}$ 1 rms in the market. The sequential-entry equilibrium is therefore worse than the simultaneous-entry one with $m_{U\,i}$ 1 rms, and is worse than the one with m_L rms (P6). By P9, it is therefore worse than all of the simultaneous-entry ones, expect possibly that with m_U rms.

To show that the comparison of an odd number m_U and the sequential-entry equilibrium with m_L rms is ambiguous in terms of welfare, consider two special cases. In the rst, take the limit with the m_U rms just making zero pro ts, so $1 = m_U z = 2$. By P7, taking out a rm (and not rearranging) leaves social surplus unchanged. We now have $m_U i = 2$ gaps of size z = 2, and one of size

z. We can also bring the sequential-entry equilibrium to the same number of \neg rms without changing its welfare level by adding \neg rms in each of the m_{L i} 2 gaps of size z, to yield 2(m_{L i} 2) = m_{U i} 3 gaps of size z=2, and two of size 3z=4. The latter scenario dominates the former since two gaps of size 3z=4 are preferable to one of size z=2 plus one of size z (by P3 applied to the subinterval of size 3z=2):

To establish that the comparison can go the other way, take the other extreme case in which $m_U + 1$ rms are just unpro table. Then the simultaneous-entry equilibrium has a higher welfare level than when $m_U + 1$ rms are in the market, and the sequential-entry equilibrium has the same welfare level as when there are $m_U + 1$ rms: just add a rm in the middle of each of the gaps of size z, and note that all gaps are this size.2

Proof of Proposition 3.

We show here that a subsidy (T < 0) is never optimal. We <code>-rst</code> consider the case z(0) < 1=2, i.e., F < 1=32, so at least three <code>-rms</code> enter if T = 0. To show a subsidy is never optimal, suppose one were, then $C(z(0)) \ C(z(T^{\pi}))$ for some $T^{\pi} < 0$. Since we have already shown that C(z(T)) is decreasing in T for all T < 0 except where C jumps (i.e., where z(T) = 1=m with m an integer), it su±ces to consider the function C i at integer values of 1=z and to show that $C^{i}(\frac{1}{m})$ is increasing in m for all m $_{\circ}$ n $_{i}$ 1, where n = $\frac{1}{z(0)} = \frac{p_{1}}{p_{1}}$ is the number of <code>-rms</code> if taxes are zero. That is, we show that Cⁱ($\frac{1}{n_{i}-1}$) < C($z(T^{\pi})$), hence lower costs than at $z(T^{\pi})$ can be achieved. To show that Cⁱ($\frac{1}{m}$) is increasing as required, it su±ces that Cⁱ($\frac{1}{m}$) > Cⁱ($\frac{1}{m_{i}-1}$) for all m $_{\circ}$ n, or equivalently

$$4mF + \frac{1}{4m}i \frac{1}{8m^2} > 4(m_i 1)F + \frac{1}{4(m_i 1)}i \frac{1}{8(m_i 1)^2}$$
$$2m^2 : 4m + 1$$

or

$$32F > \frac{2m^2 i 4m + 1}{m^2(m i 1)^2}$$
 (A.2)

Since $m_n = \frac{1}{m^2}$, then $\frac{4}{m^2} = 32F$, and it su±ces that $\frac{4}{m^2} > \frac{2m^2i}{m^2(m_i-1)^2}$, or, equivalently, that $2(m_i-1)^2 + 1 > 0$, which is clearly true.

It remains to be shown that the no-subsidy result also holds for F $_{-}$ 1=32 (which corresponds to z(0) $_{-}$ 1=2, i.e. duopoly, monopoly, or no $^{-}$ rm at all). First consider duopoly, or z(0) 2 [1=2; 1), that is, F 2 [1=32; 1=8). The cost C(z) is decreasing on [1=2; 1) since locations are diametrically opposite regardless of z in this range, so the only e[®]ect of increasing T (or equivalently, increasing z) is to reduce wasteful dissipation. This means that Cⁱ (1) < C(z) for all z 2 [1=2; 1). Furthermore, by (A.2) for m $_{-}$ 3, since F $_{-}$ 1=32, Cⁱ (z) is decreasing on (0; 1=2], so Cⁱ (1=2) < C(z) for all z < 1=2. Thus, it su±ces to show that Cⁱ (1) < Cⁱ (1=2), or 2F + 1=8 < 5F + 3=32, which is implied by F $_{-}$ 1=32. Hence we have shown that if there would be a duopoly in the absence of any tax or subsidy, then subsidizing to increase the number of products is not worthwhile.

The case of monopoly arises for F $_{\rm 1}$ 1=8. Clearly costs fall with the tax, up to the tax at which F + T equals the monopolist's gross pro⁻t. At this tax, the social cost of serving the market is F + 1=4. Hence, by the argument of the previous paragraph, to show that a subsidy is never optimal, we need only show that this number does not exceed Cⁱ (1), i:e. F + 1=4 2F + 1=8, which is true exactly when F $_{\rm 1}$ 1=8. In other words, if there is just one producer in the market in the absence of government intervention, then optimal policy proscribes altering the number of ⁻rms, and prescribes taxing (almost) all the monopolist's net pro⁻t.³³2

³³Because of our choice of tie-breaking rule (namely, that a ⁻rm stays out if it would earn zero pro⁻t entering at

time zero), there may be no minimum total cost, although the in⁻mum will always exist. This problem arises at the points where C (z) jumps. The planner can get arbitrarily close to the in⁻mum by appropriate choice of T. Even though an optimum may not exist in a strict sense, this poses no real economic problem, and we shall continue to refer to the **\optimal tax**" in the text.