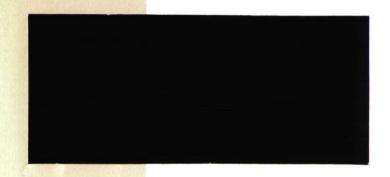


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Discussion paper







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THE D*-TRIANGULATION FOR CONTINUOUS DEFORMATION ALGORITHMS TO COMPUTE SOLUTIONS OF $\ensuremath{\mathcal{R}}\xspace$ NONLINEAR EQUATIONS

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The D_2^* -Triangulation for Continuous Deformation Algorithms to Compute Solutions of Nonlinear Equations

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Abstract

We propose a new triangulation of $(0,1] \times R^n$, called the D_2^* -triangulation, with continuous refinement of grid sizes for use in continuous deformation algorithms to compute solutions of nonlinear equations. Any positive even integer can be chosen as one of its factors of refinement of grid sizes. We prove that the D_2^* -triangulation is superior to the well-known K_2^* -triangulation and J_2^* -triangulation when we compare the number of simplices. Numerical tests show that the continuous deformation algorithm based on the D_2^* -triangulation indeed is more efficient.

Keywords: Triangulations, Measures of Efficiency of Triangulations, Continuous Deformation Algorithms

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1 Introduction

Simplicial methods were originated by Scarf in his seminar paper [18] to compute fixed points of a continuous mapping from the unit simplex to itself. They are also called the fixed point methods in literature. By now, simplicial methods have been developed for over twenty years. As a tool to solve highly nonlinear problems, which are derived from decision-making, economic modelling, and engineering, simplicial methods are very powerful. The so-called continuous deformation algorithm is one of the most successful simplicial methods. It was initiated by Eaves in [9] to compute fixed points on the unit simplex, and generalized to R^n by Eaves and Saigal in [10] to find solutions of nonlinear equations. This method is also named the simplicial homotopy algorithm. The principles of the continuous deformation algorithm are as follows. Let $f: \mathbb{R}^n \to \mathbb{R}^n$ be a nonlinear mapping, $f = (f_1, f_2, \dots, f_n)^{\mathsf{T}}$. We want to compute a zero point of f. Let $g: \mathbb{R}^n \to \mathbb{R}^n$ be an affinely linear mapping with a zero point x^0 , i.e., $g(x) = A(x - x^{0})$, where A is a $n \times n$ nonsingular matrix. Then the homotopy function h is given by h(t,x) = (1-t)f(x) + tg(x), for $(t,x) \in [0,1] \times \mathbb{R}^n$. The underlying space $(0,1] \times \mathbb{R}^n$ is subdivided into simplices by a triangulation, denoted by T, with continuous refinement of grid sizes. The piecewise linear approximation H of h with respect to T is given by, for $(t,x)=\sum_{i=-1}^n\lambda_iy^i\in\sigma,$ a simplex in T, with $\lambda_i\geq0,$ for $i=-1,0,\ldots,n,$ and $\sum_{i=-1}^0\lambda_i=1,$

$$H(t,x) = \sum_{i=-1}^{n} \lambda_i h(y^i),$$

where y^i is a vertex of σ for $i=-1,0,\ldots,n$. Then there exist some piecewise linear paths defined by the set of zero points of H. In particular, one of the paths starts at x^0 and goes to either infinity or converges to a zero point of f. One can trace this path with the standard lexicographical pivoting rule. Numerical tests have shown that simplicial algorithms heavily depend on the underlying triangulation. In order to improve the efficiency of the continuous deformation algorithm, a number of triangulations with continuous refinement of grid sizes has been proposed, for example, the K_3 -triangulation and the J_3 -triangulation of Todd in [20], the D_3 -triangulation and the D_2 -triangulation of Dang in [5] and [6], the arbitrary grid size

refinement triangulation of van der Laan and Talman in [15] and of Shamir in [19], the K2triangulation, the J_2 -triangulation, the K_2^* -triangulation, and the J_2^* -triangulation of Kojima and Yamamoto in [14], the triangulation of Broadie and Eaves in [2], and the triangulation of Doup and Talman in [7]. All these triangulations were derived from the well-known K₁triangulation or J₁-triangulation, except the D₃-triangulation and the D₂-triangulation, which were obtained from the D_1 -triangulation. The latter triangulation of \mathbb{R}^n was proposed in [4] and is superior to the K_1 -triangulation and the J_1 -triangulation according to all measures of efficiency of triangulations. Theoretical results and numerical tests have proved that the D₃triangulation is superior to both the K3-triangulation and the J3-triangulation, and that the D2triangulation is superior to both the K_2 -triangulation and the J_2 -triangulation. As mentioned by Kojima and Yamamoto in [14], the K_3 -triangulation is a special case of the K_2^* -triangulation for the factor of refinement equal to two, and the J_3 -triangulation is a special case of the J_2^* triangulation for the factor of refinement equal to two. Numerical tests have shown in [5] that the continuous deformation algorithm based on the D_3 -triangulation is very efficient. However, its factors of refinement are also equal to two. Motivated by the results in [14], we construct a new triangulation of $(0,1] \times \mathbb{R}^n$, called the D_2^* -triangulation, with continuous refinement of grid sizes for the continuous deformation algorithm, using the D_1 -triangulation. Any positive even integer can be chosen as one of its factors of refinement. This feature is the same as that of the K_2^* -triangulation and of the J_2^* -triangulation. Similarly to the K_3 -triangulation and the J_3 -triangulation, the D_3 -triangulation now becomes a special case of the D_2^* -triangulation for the factor of refinement equal to two. To compare with the D_2^* -triangulation, we also present the K_2^* -triangulation and the J_2^* -triangulation, which were given by Kojima and Yamamoto in [14] without their algebraic definitions. We prove that the D_2^* -triangulation is superior to the K_2^* -triangulation and the J_2^* -triangulation when we count the number of simplices. Since it is rather complicated to calculate the surface density of these triangulations, we refer for it to [4] and [12]. Numerical tests show that the continuous deformation algorithm based on the D_2^* -triangulation indeed is more efficient. We remark that the structure of the D_2^* -

triangulation is quite different from that of the D_2 -triangulation. Numerical tests show that the D_2^* -triangulation is in general faster than the D_2 -triangulation. Note that there exists a number of other interesting triangulations of R^n , see [17], [16], [22], and [13]. However, it is not known how these triangulations of R^n can be used to obtain triangulations of $(0,1] \times R^n$ with continuous refinement of grid sizes.

In Section 2, an algebraic definition of the D_2^* -triangulation is presented. In Section 3, we prove that the definition given in Section 2 yields a triangulation. The pivot rules of the D_2^* -triangulation for moving from one simplex to an adjacent simplex are described in Section 4. Comparison with other triangulations is presented in Section 5.

2 Algebraic Definition of the D₂*-Triangulation

Let N_0 denote the index set $\{0,1,\ldots,n\}$ and let u^i be the ith unit vector in \mathbb{R}^{n+1} for $i=0,1,\ldots,n$. Take $\alpha_0\in(0,1]$ and $\beta_i\in\{1/j\mid j=1,2,\ldots\}$ for $i=0,1,\ldots$, and choose α_j such that $\alpha_{j+1}=\alpha_j\beta_j/2$ for $j=0,1,\ldots$. Let us set $\beta_{-1}=1$.

Let $\pi = (\pi(0), \pi(1), \dots, \pi(n))$ be a permutation of the elements of N_0 . Let q denote the integer with $\pi(q) = 0$. Take a vector $y \in (0, 1] \times R^n$ such that for an integer $k \geq 0$, $y_0 = 2^{-(k+1)}$, $y_{\pi(i)}/2\alpha_{k+1}$ is an integer for $i = 0, \dots, q-1$, and $y_{\pi(i)}/\alpha_k$ is odd for $i = q+1, \dots, n$. Then we define

$$w_{\pi(i)} = \left\{ \begin{array}{ll} \lfloor y_{\pi(i)}/\alpha_k \rfloor + 1 & \text{if } \lfloor y_{\pi(i)}/\alpha_k \rfloor \text{ is odd,} \\ \\ \lfloor y_{\pi(i)}/\alpha_k \rfloor & \text{otherwise,} \end{array} \right.$$

for $i = 0, 1, \dots, q - 1$.

Definition 2.1. Let y and π be as above. Then the vectors y^{-1}, y^0, \ldots, y^n are given as follows.

$$y^{-1} = y,$$

$$y^{i} = y^{i-1} + 2\alpha_{k+1}u^{\pi(i)}, i = 0, 1, \dots, q - 1,$$

$$y^{q} = \alpha_{k} \sum_{j=0}^{q-1} w_{\pi(j)}u^{\pi(j)} + \sum_{j=q+1}^{n} (y_{\pi(j)} - \alpha_{k})u^{\pi(j)} + 2y_{0}u^{0},$$

$$y^{i} = y^{i-1} + 2\alpha_{k}u^{\pi(i)}, i = q + 1, \dots, n.$$

Let y^{-1}, y^0, \ldots, y^n be obtained in the above manner. Then it is obvious that they are affinely independent. Thus their convex hull is a simplex. Let us denote this simplex by $K_2^*(y,\pi)$. Let K_2^* denote the collection of all such simplices $K_2^*(y,\pi)$. It will be shown in the next section that K_2^* is a triangulation of $(0,1] \times \mathbb{R}^n$ such that any positive even integer can be chosen as one of its factors of refinement, and when its factor of refinement is always equal to two, the K_3 -triangulation is induced as one of its special cases. We call it the K_2^* -triangulation.

Let $\pi = (\pi(0), \pi(1), \dots, \pi(n))$ be a permutation of the elements of N_0 . Let q denote the integer with $\pi(q) = 0$. Take a vector $y \in (0,1] \times \mathbb{R}^n$ such that for an integer $k \geq 0$, $y_0 = 2^{-(k+1)}$, if $1/\beta_k$ is even, $y_{\pi(i)}/2\alpha_{k+1}$ is even for $i=0,\ldots,q-1$, if $1/\beta_k$ is odd, $y_{\pi(i)}/2\alpha_{k+1}$ is odd for $i=0,\ldots,q-1$, and $y_{\pi(i)}/\alpha_k$ is odd for $i=q+1,\ldots,n$. Then we define

$$w_{\pi(i)} = \begin{cases} [y_{\pi(i)}/\alpha_k \text{ is odd for } i = q+1, \dots, n. \text{ Then we define} \\ [y_{\pi(i)}/\alpha_k] + 1 & \text{if } [y_{\pi(i)}/\alpha_k] \text{ is odd and either } y_{\pi(i)}/\alpha_k \neq [y_{\pi(i)}/\alpha_k] \\ & \text{or both } [y_{\pi(i)}/\alpha_k] = y_{\pi(i)}/\alpha_k \text{ and } s_{\pi(i)} = 1, \\ [y_{\pi(i)}/\alpha_k] & \text{if } [y_{\pi(i)}/\alpha_k] \text{ is even,} \\ [y_{\pi(i)}/\alpha_k] - 1 & \text{otherwise,} \end{cases}$$

for $i = 0, 1, \ldots, q - 1$. If $1/\beta_{k-1}$ is odd, let us define

$$t_{\pi(i)} = \begin{cases} -1 & \text{if } y_{\pi(i)}/\alpha_k = 1 \pmod{4}, \\ \\ 1 & \text{if } y_{\pi(i)}/\alpha_k = 3 \pmod{4}, \end{cases}$$

for i = q + 1, ..., n, and if $1/\beta_{k-1}$ is even, let us define

$$t_{\pi(i)} = \begin{cases} 1 & \text{if } y_{\pi(i)}/\alpha_k = 1 \pmod{4}, \\ -1 & \text{if } y_{\pi(i)}/\alpha_k = 3 \pmod{4}, \end{cases}$$

for $i=q+1,\ldots,n$. Take a sign vector $s=(s_1,s_2,\ldots,s_n)^{\mathsf{T}}$ such that $s_i\in\{-1,+1\}$ for i = 1, 2, ..., n, and $s_{\pi(i)} = t_{\pi(i)}$ for i = q + 1, ..., n.

Definition 2.2. Let y, π and s be as above. Then the vectors y^{-1} , y^0 , ..., y^n are given as

follows.

$$y^{-1} = y,$$

$$y^{i} = y^{i-1} + 2\alpha_{k+1}s_{\pi(i)}u^{\pi(i)}, i = 0, 1, \dots, q-1,$$

$$y^{q} = \alpha_{k} \sum_{j=0}^{q-1} w_{\pi(j)}u^{\pi(j)} + \sum_{j=q+1}^{n} (y_{\pi(j)} - \alpha_{k}s_{\pi(j)})u^{\pi(j)} + 2y_{0}u^{0},$$

$$y^{i} = y^{i-1} + 2\alpha_{k}s_{\pi(i)}u^{\pi(i)}, i = q+1, \dots, n.$$

Let y^{-1} , y^0 , ..., y^n be obtained in the above manner. Then it is obvious that they are affinely independent. Thus their convex hull is a simplex. Let us denote this simplex by $J_2^*(y,\pi,s)$. Let J_2^* denote the set of all such simplices $J_2^*(y,\pi,s)$. It will be shown in the next section that J_2^* is a triangulation of $(0,1] \times R^n$ such that any positive even integer can be chosen as one of its factors of refinement, and when its factor of refinement is always equal to two, the J_3 -triangulation is induced as one of its special cases. We call it the J_2^* -triangulation.

Let $\pi = (\pi(0), \pi(1), \ldots, \pi(n))$ be a permutation of the elements of N_0 . Let q denote the integer with $\pi(q) = 0$. Take a vector $y \in (0,1] \times R^n$ such that for an integer $k \geq 0$, $y_0 = 2^{-(k+1)}$, if $1/\beta_k$ is even, $y_{\pi(i)}/2\alpha_{k+1}$ is even for $i = 0, \ldots, q-1$, if $1/\beta_k$ is odd, $y_{\pi(i)}/2\alpha_{k+1}$ is odd for $i = 0, \ldots, q-1$, and $y_{\pi(i)}/\alpha_k$ is odd for $i = q+1, \ldots, n$. Then we define

$$w_{\pi(i)} = \begin{cases} \lfloor y_{\pi(i)}/\alpha_k \rfloor + 1 & \text{if } \lfloor y_{\pi(i)}/\alpha_k \rfloor \text{ is odd and either } y_{\pi(i)}/\alpha_k \neq \lfloor y_{\pi(i)}/\alpha_k \rfloor \\ & \text{or both } \lfloor y_{\pi(i)}/\alpha_k \rfloor = y_{\pi(i)}/\alpha_k \text{ and } s_{\pi(i)} = 1, \\ \\ \lfloor y_{\pi(i)}/\alpha_k \rfloor & \text{if } \lfloor y_{\pi(i)}/\alpha_k \rfloor \text{ is even,} \\ \\ \lfloor y_{\pi(i)}/\alpha_k \rfloor - 1 & \text{otherwise,} \end{cases}$$

for $i = 0, 1, \dots, q - 1$. If $1/\beta_{k-1}$ is odd, let us define

$$t_{\pi(i)} = \begin{cases} -1 & \text{if } y_{\pi(i)}/\alpha_k = 1 \pmod{4}, \\ \\ 1 & \text{if } y_{\pi(i)}/\alpha_k = 3 \pmod{4}, \end{cases}$$

for i = q + 1, ..., n, and if $1/\beta_{k-1}$ is even, let us define

$$t_{\pi(i)} = \begin{cases} 1 & \text{if } y_{\pi(i)}/\alpha_k = 1 \pmod{4}, \\ \\ -1 & \text{if } y_{\pi(i)}/\alpha_k = 3 \pmod{4}, \end{cases}$$

for $i=q+1,\ldots,n$. Take a sign vector $s=(s_1,s_2,\ldots,s_n)^{\mathsf{T}}$ such that $s_i\in\{-1,+1\}$ for $i=1,2,\ldots,n$, and $s_{\pi(i)}=t_{\pi(i)}$ for $i=q+1,\ldots,n$. Then we define

$$I = \left\{ \begin{array}{l} \left\{\pi(i) \mid w_{\pi(i)}/2 \text{ is even and } 0 \leq i \leq q-1\right\} & \text{if } 1/\beta_{k-1} \text{ is odd,} \\ \\ \left\{\pi(i) \mid w_{\pi(i)}/2 \text{ is odd and } 0 \leq i \leq q-1\right\} & \text{if } 1/\beta_{k-1} \text{ is even.} \end{array} \right.$$

Let h denote the number of elements in I. Take two integers p_1 and p_2 such that $-1 \le p_1 \le q-2$ if $q \ge 1$; $p_1 = -1$ if q = 0; when h = 0, $0 \le p_2 \le n - q - 1$ if q < n, and $p_2 = 0$ if q = n; when h > 0, $p_2 = n - q$.

Definition 2.3. Let y, π, s, p_1 and p_2 be as above. Then the vectors y^{-1}, y^0, \ldots, y^n are given as follows.

When $p_1 = -1$,

$$y^{-1} = y,$$

$$y^{i} = y + 2\alpha_{k+1}s_{\pi(i)}u^{\pi(i)}, i = 0, 1, \dots, q-1,$$

and when $p_1 \geq 0$,

$$y^{-1} = y + 2\alpha_{k+1} \sum_{j=0}^{q-1} s_{\pi(j)} u^{\pi(j)},$$

$$y^i = y^{i-1} - 2\alpha_{k+1} s_{\pi(i)} u^{\pi(i)}, \ i = 0, 1, \dots, p_1 - 1,$$

$$y^i = y + 2\alpha_{k+1}s_{\pi(i)}u^{\pi(i)}, i = p_1, \dots, q-1.$$

When h > 0,

$$y^{q} = \alpha_{k} \sum_{j=0}^{q-1} w_{\pi(j)} u^{\pi(j)} + \sum_{j=q+1}^{n} (y_{\pi(j)} + \alpha_{k} s_{\pi(j)}) u^{\pi(j)} + 2y_{0} u^{0},$$

$$y^{i} = y^{i-1} - 2\alpha_{k} s_{\pi(i)} u^{\pi(i)}, i = q+1, \dots, n,$$

and when h = 0, if $p_2 = 0$, then

$$y^{q} = \alpha_{k} \sum_{j=0}^{q-1} w_{\pi(j)} u^{\pi(j)} + \sum_{j=q+1}^{n} (y_{\pi(j)} - \alpha_{k} s_{\pi(j)}) u^{\pi(j)} + 2y_{0} u^{0},$$

$$y^{i} = y^{q} + 2\alpha_{k} s_{\pi(i)} u^{\pi(i)}, i = q+1, \dots, n,$$

and if $p_2 \geq 1$, then

$$y^{q} = \alpha_{k} \sum_{j=0}^{q-1} w_{\pi(j)} u^{\pi(j)} + \sum_{j=q+1}^{n} (y_{\pi(j)} + \alpha_{k} s_{\pi(j)}) u^{\pi(j)} + 2y_{0} u^{0},$$

$$y^{i} = y^{i-1} - 2\alpha_{k} s_{\pi(i)} u^{\pi(i)}, i = q+1, \dots, q+p_{2}-1,$$

$$y^{i} = y^{*} + 2\alpha_{k} s_{\pi(i)} u^{\pi(i)}, i = q+p_{2}, \dots, n,$$

where

$$y^* = \alpha_k \sum_{j=0}^{q-1} w_{\pi(j)} u^{\pi(j)} + \sum_{j=q+1}^{n} (y_{\pi(j)} - \alpha_k s_{\pi(j)}) u^{\pi(j)} + 2y_0 u^0.$$

Let y^{-1} , y^0 , ..., y^n be obtained in the above manner. Then it is obvious that they are affinely independent. Thus their convex hull is a simplex. Let us denote this simplex by $D_2^*(y,\pi,s,p_1,p_2)$. Let D_2^* denote the set of all such simplices $D_2^*(y,\pi,s,p_1,p_2)$. It will be shown in the next section that D_2^* is a triangulation of $(0,1] \times R^n$ such that any positive even integer can be chosen as one of its factors of refinement, and when its factor of refinement is always equal to two, the D_3 -triangulation is induced as one of its special cases. We call it the D_2^* -triangulation.

3 Construction of the D_2^* -Triangulation

Let N denote the index set $\{1, 2, ..., n\}$ and let Q denote the set

 $\{w \mid \text{all components of } w \text{ are integers} \}$.

We take an arbitrary element $w \in Q$. Then we define

$$I_o(w) = \{i \in N \mid w_i \text{ is odd}\} \text{ and } I_e(w) = \{j \in N \mid w_j \text{ is even}\}.$$

Furthermore, let A(w) denote the set

$$\{x \in \mathbb{R}^n \mid w_i - 1 \le x_i \le w_i + 1 \text{ for } i \in I_o(w), \text{ and } x_i = w_i \text{ for } i \in I_e(w)\}$$

and let B(w) denote the set

$$\{x \in \mathbb{R}^n \mid x_i = w_i \text{ for } i \in I_o(w), \text{ and } w_i - 1 \le x_i \le w_i + 1 \text{ for } i \in I_e(w)\}.$$

Let k be a nonnegative integer. Then let $D^k(w)$ denote the convex hull of the set

$$(\{2^{-k}\} \times A(w)) \cup (\{2^{-(k+1)}\} \times B(w)).$$

The following lemmas can be found in [5] and [14].

Lemma 3.1.

$$D^{k}(w) = \left\{ d \in [2^{-(k+1)}, 2^{-k}] \times R^{n} \middle| \begin{array}{l} |d_{i} - w_{i}| \leq 2^{k+1}d_{0} - 1 \text{ for } i \in I_{o}(w) \\ |d_{i} - w_{i}| \leq 2 - 2^{k+1}d_{0} \text{ for } i \in I_{e}(w) \end{array} \right\}.$$

Lemma 3.2. $\bigcup_{w \in Q} D^k(w) = [2^{-(k+1)}, 2^{-k}] \times R^n$.

Lemma 3.3. For w^1 , $w^2 \in Q$, $D^k(w^1) \cap D^k(w^2)$ is either empty or a common face of both $D^k(w^1)$ and $D^k(w^2)$, and when $D^k(w^1) \cap D^k(w^2)$ is not empty, it is equal to the convex hull of the set

$$(\left\{2^{-k}\right\} \times (A(w^1) \cap A(w^2))) \cup (\left\{2^{-(k+1)}\right\} \times (B(w^1) \cap B(w^2))).$$

For convenience of the following discussion, we give the definitions of the D_1 -triangulation, the K_1 -triangulation, and the J_1 -triangulation. For more details, see [4] and [20]. Let e^i be the *i*th unit vector in \mathbb{R}^n for $i = 1, 2, \ldots, n$.

Let D denote either the set

$$\{x \in \mathbb{R}^n \mid \text{all components of } x \text{ are odd}\}$$

or the set

$$\{x \in \mathbb{R}^n \mid \text{all components of } x \text{ are even}\}.$$

Let $\pi = (\pi(1), \pi(2), \dots, \pi(n))$ be a permutation of the elements of N. Take a sign vector $s = (s_1, s_2, \dots, s_n)^{\top}$ with $s_i \in \{-1, 1\}$ for $i = 1, 2, \dots, n$. Let p be an integer with $0 \le p \le n-1$. Take a vector p from the set p.

Definition 3.1. Let y, π, s , and p be as above. Then the vectors y^0, y^1, \ldots, y^n are as follows. If p = 0, then $y^0 = y$, and $y^j = y + s_{\pi(j)}e^{\pi(j)}, j = 1, 2, \ldots, n$.

If
$$p \ge 1$$
, then

$$y^{0} = y + s,$$

 $y^{j} = y^{j-1} - s_{\pi(j)}e^{\pi(j)}, \ j = 1, 2, \dots, p - 1,$
 $y^{j} = y + s_{\pi(j)}e^{\pi(j)}, \ j = p, p + 1, \dots, n.$

Let D_1 denote the collection of all simplices $D_1(y, \pi, s, p)$ that are the convex hull of y^0, y^1, \ldots, y^n , as obtained from the above definition. Then D_1 is a triangulation of R^n , called the D_1 -triangulation.

Let K denote the set

$$\{x \in \mathbb{R}^n \mid \text{all components of } x \text{ are integers}\}.$$

Let $\pi = (\pi(1), \pi(2), \dots, \pi(n))$ be a permutation of the elements of N. Take a vector y from the set K.

Definition 3.2. Let y and π be as above. Then the vectors y^0, y^1, \ldots, y^n are given as follows

$$y^0 = y$$
, and $y^j = y^{j-1} + e^{\pi(j)}$, $j = 1, 2, ..., n$.

Let K_1 denote the collection of all simplices $K_1(y, \pi)$ that are the convex hull of y^0 , y^1 , ..., y^n , as obtained from the above definition. Then K_1 is a triangulation of R^n , called the K_1 -triangulation.

Let J denote either the set

$$\{x \in \mathbb{R}^n \mid \text{all components of } x \text{ are odd}\}$$

or the set

$$\{x \in \mathbb{R}^n \mid \text{all components of } x \text{ are even}\}.$$

Let $\pi = (\pi(1), \pi(2), \dots, \pi(n))$ be a permutation of the elements of N. Take a vector y from the set J, and a sign vector $s = (s_1, s_2, \dots, s_n)^{\mathsf{T}}$ with $s_i \in \{-1, 1\}$ for $i = 1, 2, \dots, n$.

Definition 3.3. Let y, π , and s be as above. Then the vectors y^0, y^1, \ldots, y^n are given as follows.

$$y^0 = y$$
, and $y^j = y^{j-1} + s_{\pi(j)}e^{\pi(j)}$, $j = 1, 2, ..., n$.

Let J_1 denote the collection of all simplices $J_1(y, \pi, s)$ that are the convex hull of y^0, y^1, \ldots, y^n , as obtained from the above definition. Then J_1 is a triangulation of R^n , called the J_1 -triangulation.

We take G to be one of these triangulations of R^n . Let \bar{G} denote the set of faces of all simplices in G. Then, as before in the second section, we take $\alpha_0 \in (0,1]$ and $\beta_i \in \{1/j \mid j=1,2,\ldots\}$ for $i=0,1,\ldots$, and choose α_j such that $\alpha_{j+1}=\alpha_j\beta_j/2$ for $j=0,1,\ldots$ We set $\beta_{-1}=1$.

Let $2\alpha_k \bar{G} \mid \alpha_k A(w)$ be the set given by

$$\left\{\sigma \subseteq \alpha_k A(w) \mid \sigma \in 2\alpha_k \bar{G} \text{ and } \dim(\sigma) = \dim(A(w))\right\}$$

and let $2\alpha_{k+1}\bar{G} \mid \alpha_k B(w)$ be the set given by

$$\left\{\sigma\subseteq\alpha_kB(w)\mid\sigma\in2\alpha_{k+1}\bar{G}\text{ and }\dim(\sigma)=\dim(B(w))\right\}.$$

For the D_1 -triangulation, the K_1 -triangulation, and the J_1 -triangulation, it is obvious that $2\alpha_k \bar{G} \mid \alpha_k A(w)$ is a triangulation of $\alpha_k A(w)$ and $2\alpha_{k+1} \bar{G} \mid \alpha_k B(w)$ is a triangulation of $\alpha_k B(w)$.

Let a denote the number of elements in the set $I_o(w)$, and b the number of elements in the set $I_e(w)$. Let $\sigma_A \in 2\alpha_k \bar{G} \mid \alpha_k A(w)$ be equal to the convex hull of y_A^0 , y_A^1 , ..., y_A^a , and let $\sigma_B \in 2\alpha_{k+1} \bar{G} \mid \alpha_k B(w)$ be equal to the convex hull of y_B^0 , y_B^1 , ..., y_B^b . Furthermore, let σ denote the convex hull of the set $(\{2^{-k}\} \times \sigma_A) \cup (\{2^{-(k+1)}\} \times \sigma_B)$. It can easily be proved that σ is a simplex in $[2^{-(k+1)}, 2^{-k}] \times R^n$ and is equal to the convex hull of $(2^{-k}, y_A^0)^{\top}$, $(2^{-k}, y_A^1)^{\top}$, ..., $(2^{-k}, y_A^a)^{\top}$, $(2^{-(k+1)}, y_B^0)^{\top}$, $(2^{-(k+1)}, y_B^1)^{\top}$, ..., $(2^{-(k+1)}, y_B^0)^{\top}$.

Let T(k, k+1) denote the collection of all such simplices σ . Then, following the conclusions mentioned above, we have that, for σ^1 and σ^2 in T(k, k+1), the intersection $\sigma^1 \cap \sigma^2$ is either empty or a common face of both σ^1 and σ^2 , and that the union of all $\sigma \in T(k, k+1)$ is equal to $[2^{-(k+1)}, 2^{-k}] \times \mathbb{R}^n$. Hence, T(k, k+1) is a triangulation of $[2^{-(k+1)}, 2^{-k}] \times \mathbb{R}^n$.

Theorem 3.4. The union of T(k, k+1) over all nonnegative integers k is a triangulation of $(0,1] \times \mathbb{R}^n$.

Proof. From the choice of α_j and β_j for j = 0, 1, ..., the theorem follows immediately.

We call the triangulation obtained in the above manner the G_2^* -triangulation. In this way, we obtain the K_2^* -triangulation, the J_2^* -triangulation, and the D_2^* -triangulation, as described in Section 2. Considering consistency, one can easily prove these results.

4 Pivot Rules of the D_2^* -Triangulation

As described in the first section, when a piecewise linear path of zero points is traced, the problem one faces is how to move from a simplex crossed by the path to an adjacent simplex crossed by the path with the standard lexicographic pivoting rule. As follows, the pivot rules of the K_2^* -triangulation, the J_2^* -triangulation, and the D_2^* -triangulation are described. The continuous deformation algorithm based on one of these triangulations can be implemented according to these pivot rules. In these following pivot rules, $y_0 = 2^{-(k+1)}$, $y = (y_1, \ldots, y_n)^{\mathsf{T}}$, $\bar{y}_0 = 2^{-(\bar{k}+1)}$, $\bar{y} = (\bar{y}_1, \ldots, \bar{y}_n)^{\mathsf{T}}$, and $u = (1, 1, \ldots, 1)^{\mathsf{T}}$.

Let a simplex of the K_2^* -triangulation, $\sigma = K_2^*(y, \pi)$, be given with vertices y^{-1}, y^0, \ldots, y^n . We want to obtain the simplex of the K_2^* -triangulation, $\bar{\sigma} = K_2^*(\bar{y}, \bar{\pi})$, such that all vertices of σ are also vertices of $\bar{\sigma}$ except the vertex y^i . As follows, we show how \bar{y} and $\bar{\pi}$ depend on y, π , and i.

$$\underline{0 \le i < q-1}$$
: $\bar{y} = y$, $\bar{\pi} = (\pi(0), \dots, \pi(i+1), \pi(i), \dots, \pi(n))$, $\bar{q} = q$, and $\bar{k} = k$.

$$\underline{0 \leq i = q-1} \text{: If } y_{\pi(q-1)} = \alpha_k(w_{\pi(q-1)}-1), \text{ then } \bar{y} = y, \ \bar{\pi} = (\pi(0), \dots, \pi(q), \pi(q-1), \dots, \pi(n)),$$

$$\bar{q} = q-1, \text{ and } \bar{k} = k. \text{ If } y_{\pi(q-1)} \neq \alpha_k(w_{\pi(q-1)}-1), \text{ then } \bar{y} = y-2\alpha_{k+1}u^{\pi(q-1)}, \ \bar{\pi} = (\pi(q-1), \pi(0), \dots, \pi(q-2), \pi(q), \dots, \pi(n)), \ \bar{q} = q, \text{ and } \bar{k} = k.$$

$$q = i < n$$
: $\bar{y} = y$, $\bar{\pi} = (\pi(0), \dots, \pi(q+1), \pi(q), \dots, \pi(n))$, $\bar{q} = q+1$, and $\bar{k} = k$.

$$q < i < n$$
: $\bar{y} = y$, $\bar{\pi} = (\pi(0), \dots, \pi(i+1), \pi(i), \dots, \pi(n))$, $\bar{q} = q$, and $\bar{k} = k$.

$$\underline{i} = \underline{n}$$
: In case $q < n, \ \bar{y} = y - 2\alpha_{k+1}u^{\pi(n)}, \ \bar{\pi} = (\pi(n), \pi(0), \dots, \pi(n-1)), \ \bar{q} = q+1, \ \text{and} \ \bar{k} = k.$
In case $q = n, \ \bar{y} = y + \alpha_{k+1}u, \ \bar{\pi} = (\pi(n), \pi(0), \dots, \pi(n-1)), \ \bar{q} = 0, \ \text{and} \ \bar{k} = k+1.$

Next, let a simplex of the J_2^* -triangulation, $\sigma = J_2^*(y, \pi, s)$, be given with vertices y^{-1} , y^0 , ..., y^n . We want to obtain the simplex of the J_2^* -triangulation, $\bar{\sigma} = J_2^*(\bar{y}, \bar{\pi}, \bar{s})$, such that all vertices of σ are also vertices of $\bar{\sigma}$ except the vertex y^i . As follows, we show how \bar{y} , $\bar{\pi}$, and \bar{s} depend on y, π , s, and i.

$$\underline{i=-1}$$
: In case $q=0, \ \bar{y}=y-\alpha_k s, \ \bar{s}=s, \ \bar{\pi}=(\pi(1),\pi(2),\dots,\pi(n),\pi(0)), \ \bar{q}=n, \ \text{and}$ $\bar{k}=k-1$. In case $q>0, \ \bar{y}=y+4\alpha_{k+1}s_{\pi(0)}u^{\pi(0)}, \ \bar{s}=s-2s_{\pi(0)}u^{\pi(0)}, \ \bar{\pi}=\pi, \ \bar{q}=q, \ \text{and}$ $\bar{k}=k$.

$$0 \le i < q-1$$
: $\bar{y} = y$, $\bar{s} = s$, $\bar{\pi} = (\pi(0), \dots, \pi(i+1), \pi(i), \dots, \pi(n))$, $\bar{q} = q$, and $\bar{k} = k$.

$$\underline{0 \leq i = q-1} \text{: In case } y_{\pi(q-1)} = \alpha_k(w_{\pi(q-1)} - s_{\pi(q-1)}), \text{ if } s_{\pi(q-1)} = t_{\pi(q-1)}, \text{ then } \bar{y} = y, \ \bar{s} = s, \\ \bar{\pi} = (\pi(0), \dots, \pi(q), \pi(q-1), \dots, \pi(n)), \ \bar{q} = q-1, \text{ and } \bar{k} = k; \text{ if } s_{\pi(q-1)} \neq t_{\pi(q-1)}, \text{ then } \\ \bar{y} = y, \ \bar{s} = s - 2s_{\pi(q-1)}u^{\pi(q-1)}, \ \bar{\pi} = (\pi(0), \dots, \pi(q-2), \pi(q), \dots, \pi(n), \pi(q-1)), \ \bar{q} = q-1, \\ \text{and } \bar{k} = k. \text{ In case } y_{\pi(q-1)} \neq \alpha_k(w_{\pi(q-1)} - s_{\pi(q-1)}), \ \bar{y} = y, \ \bar{s} = s - 2s_{\pi(q-1)}u^{\pi(q-1)}, \ \bar{\pi} = \pi, \\ \bar{q} = q, \text{ and } \bar{k} = k.$$

$$q = i < n$$
: $\bar{y} = y$, $\bar{s} = s$, $\bar{\pi} = (\pi(0), \dots, \pi(q+1), \pi(q), \dots, \pi(n))$, $\bar{q} = q+1$, and $\bar{k} = k$.

$$q < i < n$$
: $\bar{y} = y$, $\bar{s} = s$, $\bar{\pi} = (\pi(0), \dots, \pi(i+1), \pi(i), \dots, \pi(n))$, $\bar{q} = q$, and $\bar{k} = k$.

$$\underline{i} = \underline{n}$$
: In case $q < n$, $\bar{y} = y$, $\bar{s} = s - 2s_{\pi(n)}u^{\pi(n)}$, $\bar{\pi} = (\pi(0), \dots, \pi(q-1), \pi(n), \pi(q), \dots, \pi(n-1))$, $\bar{q} = q+1$, and $\bar{k} = k$. In case $q = n$, $\bar{y} = y + \alpha_{k+1}s$, $\bar{s} = s$, $\bar{\pi} = (\pi(n), \pi(0), \dots, \pi(n-1))$, $q = 0$, and $\bar{k} = k+1$.

Finally, let a simplex of the D_2^* -triangulation, $\sigma = D_2^*(y, \pi, s, p_1, p_2)$, be given with vertices y^{-1}, y^0, \ldots, y^n . We want to obtain the simplex of the D_2^* -triangulation, $\bar{\sigma} = D_2^*(\bar{y}, \bar{\pi}, \bar{s}, \bar{p}_1, \bar{p}_2)$, such that all vertices of σ are also vertices of $\bar{\sigma}$ except the vertex y^i . As follows, we show how $\bar{y}, \bar{\pi}, \bar{s}, \bar{p}_1$, and \bar{p}_2 depend on y, π, s, p_1, p_2 , and i.

$$\underline{i=-1}: \text{ In case } q=0, \ \bar{y}=y-\alpha_k s, \ \bar{s}=s, \ \bar{\pi}=(\pi(1),\ldots,\pi(n),\pi(0)), \ \bar{p}_1=p_2-1, \ \bar{p}_2=0,$$

$$\bar{q}=n, \text{and } \bar{k}=k-1. \ \text{ In case } q=1, \ \bar{y}=y+4\alpha_{k+1}s_{\pi(0)}u^{\pi(0)}, \ \bar{s}=s-2s_{\pi(0)}u^{\pi(0)}, \ \bar{\pi}=\pi,$$

$$\begin{split} &\bar{p}_1 = p_1, \; \bar{p}_2 = p_2, \; \bar{q} = q, \; \text{and} \; \bar{k} = k. \; \text{In case } q > 1, \; \text{when } p_1 = -1, \; \bar{y} = y, \; \bar{s} = s, \\ &\bar{\pi} = \pi, \; \bar{p}_1 = p_1 + 1, \; \bar{p}_2 = p_2, \; \bar{q} = q, \; \text{and} \; \bar{k} = k; \; \text{when } p_1 = 0, \; \bar{y} = y, \; \bar{s} = s, \; \bar{\pi} = \pi, \\ &\bar{p}_1 = p_1 - 1, \; \bar{p}_2 = p_2, \; \bar{q} = q, \; \text{and} \; \bar{k} = k; \; \text{when } p_1 \geq 1 \; \text{and} \; y_{\pi(0)} = \alpha_k(w_{\pi(0)} - s_{\pi(0)}), \; \text{if} \\ &h = 0 \; \text{and} \; p_2 = 0, \; \text{then} \; \bar{y} = y, \; \bar{s} = s - 2s_{\pi(0)}u^{\pi(0)}, \; \bar{\pi} = (\pi(1), \ldots, \pi(n), \pi(0)), \; \bar{p}_1 = p_1 - 1, \\ &\bar{p}_2 = p_2, \; \bar{q} = q - 1, \; \text{and} \; \bar{k} = k, \; \text{if} \; h = 0 \; \text{and} \; p_2 \geq 1, \; \text{then} \; \bar{y} = y, \; \bar{s} = s - 2s_{\pi(0)}u^{\pi(0)}, \\ &\bar{\pi} = (\pi(1), \ldots, \pi(q), \pi(0), \pi(q+1), \ldots, \pi(n)), \; \bar{p}_1 = p_1 - 1, \; \bar{p}_2 = p_2 + 1, \; \bar{q} = q - 1, \\ &\text{and} \; \bar{k} = k, \; \text{if} \; s_{\pi(0)} = t_{\pi(0)} \; \text{and} \; h = 1, \; \text{then} \; \bar{y} = y, \; \bar{s} = s, \; \bar{\pi} = (\pi(1), \ldots, \pi(n), \pi(0)), \\ &\bar{p}_1 = p_1 - 1, \; \bar{p}_2 = p_2, \; \bar{q} = q - 1, \; \text{and} \; \bar{k} = k, \; \text{if} \; s_{\pi(0)} = t_{\pi(0)} \; \text{and} \; h > 1, \; \text{then} \; \bar{y} = y, \; \bar{s} = s, \\ &\bar{\pi} = (\pi(1), \ldots, \pi(n), \pi(0)), \; \bar{p}_1 = p_1 - 1, \; \bar{p}_2 = p_2 + 1, \; \bar{q} = q - 1, \; \text{and} \; \bar{k} = k, \; \text{and if} \; s_{\pi(0)} \neq t_{\pi(0)} \\ &\text{and} \; h > 0, \; \text{then} \; \bar{y} = y, \; \bar{s} = s - 2s_{\pi(0)}u^{\pi(0)}, \; \bar{\pi} = (\pi(1), \ldots, \pi(q), \pi(0), \pi(q+1), \ldots, \pi(n)), \\ &\bar{p}_1 = p_1 - 1, \; \bar{p}_2 = p_2 + 1, \; \bar{q} = q - 1, \; \text{and} \; \bar{k} = k; \; \text{when} \; p_1 \geq 1 \; \text{and} \; y_{\pi(0)} \neq \alpha_k(w_{\pi(0)} - s_{\pi(0)}), \\ &\bar{y} = y, \; \bar{s} = s - 2s_{\pi(0)}u^{\pi(0)}, \; \bar{\pi} = \pi, \; \bar{p}_1 = p_1, \; \bar{p}_2 = p_2, \; \bar{q} = q, \; \text{and} \; \bar{k} = k. \end{split}$$

 $\bar{s} = s - 2s_{\pi(i^*)}u^{\pi(i^*)}, \ \bar{\pi} = \pi, \ \bar{p}_1 = p_1, \ \bar{p}_2 = p_2, \ \bar{q} = q, \ \text{and} \ \bar{k} = k, \ \text{where}$

$$i^* = \left\{ egin{array}{l} q-1 & \mbox{if } i=q-2, \\ q-2 & \mbox{if } i=q-1. \end{array} \right.$$

 $\frac{q < i \leq n:}{(\pi(0), \dots, \pi(q-1), \pi(i), \pi(q), \dots, \pi(i-1), \pi(i+1), \dots, \pi(n))}, \ \bar{p}_1 = p_1, \ \bar{p}_2 = p_2, \ \bar{q} = q+1,$ $\text{and } \bar{k} = k, \text{ and if } p_1 \geq 0, \text{ then } \bar{y} = y, \ \bar{s} = s-2s_{\pi(i)}u^{\pi(i)}, \ \bar{\pi} = (\pi(i), \pi(0), \dots, \pi(i-1), \pi(i+1), \dots, \pi(n)), \ \bar{p}_1 = p_1, \ \bar{p}_2 = p_2, \ \bar{q} = q+1,$ $\text{and } \bar{k} = k, \text{ and if } p_1 \geq 0, \text{ then } \bar{y} = y, \ \bar{s} = s-2s_{\pi(i)}u^{\pi(i)}, \ \bar{\pi} = (\pi(i), \pi(0), \dots, \pi(i-1), \pi(i+1), \dots, \pi(n)), \ \bar{p}_1 = p_1 + 1, \ \bar{p}_2 = p_2, \ \bar{q} = q+1, \ \text{and } \bar{k} = k; \text{ when } i < q+p_2-1, \ \bar{y} = y,$ $\bar{s} = s, \ \bar{\pi} = (\pi(0), \dots, \pi(i+1), \pi(i), \dots, \pi(n)), \ \bar{p}_1 = p_1, \ \bar{p}_2 = p_2, \ \bar{q} = q, \ \text{and } \bar{k} = k; \text{ when } i = q+p_2-1, \ \bar{y} = y, \ \bar{s} = s, \ \bar{\pi} = \pi, \ \bar{p}_1 = p_1, \ \bar{p}_2 = p_2-1, \ \bar{q} = q, \ \text{and } \bar{k} = k; \text{ when } i \geq q+p_2 \ \text{and } 1 \leq p_2 < n-q-1, \ \bar{y} = y, \ \bar{s} = s, \ \bar{\pi} = (\pi(0), \dots, \pi(q+p_2-1), \pi(i), \pi(q+p_2), \dots, \pi(i-1), \pi(i+1), \dots, \pi(n)), \ \bar{p}_1 = p_1, \ \bar{p}_2 = p_2+1, \ \bar{q} = q, \ \text{and } \bar{k} = k; \text{ when } i \geq n-1 \ \text{and } 1 \leq p_2 = n-q-1, \ \text{if } p_1 = -1, \ \text{then } \bar{y} = y, \ \bar{s} = s, \ \bar{\pi} = (\pi(0), \dots, \pi(q-p-1), \pi(q-p-$

1), $\pi(i^{**})$, $\pi(q)$, ..., $\pi(i^{**}-1)$, $\pi(i^{**}+1)$, ..., $\pi(n)$), $\bar{p}_1=p_1$, $\bar{p}_2=p_2$, $\bar{q}=q+1$, and $\bar{k}=k$, and if $p_1\geq 0$, then $\bar{y}=y$, $\bar{s}=s$, $\bar{\pi}=(\pi(i^{**}),\pi(0),\ldots,\pi(i^{**}-1),\pi(i^{**}+1),\ldots,\pi(n))$, $\bar{p}_1=p_1+1$, $\bar{p}_2=p_2$, $\bar{q}=q+1$, and $\bar{k}=k$, where

$$i^{**} = \begin{cases} n & \text{if } i = n - 1, \\ n - 1 & i = n. \end{cases}$$

In case h > 0, when i < n, $\bar{y} = y$, $\bar{s} = s$, $\bar{\pi} = (\pi(0), \dots, \pi(i+1), \pi(i), \dots, \pi(n))$, $\bar{p}_1 = p_1$, $\bar{p}_2 = p_2$, $\bar{q} = q$, and $\bar{k} = k$; when i = n, if $p_1 = -1$, then $\bar{y} = y$, $\bar{s} = s$, $\bar{\pi} = (\pi(0), \dots, \pi(q-1), \pi(n), \pi(q), \dots, \pi(n-1))$, $\bar{p}_1 = p_1$, $\bar{p}_2 = p_2 - 1$, $\bar{q} = q + 1$, and $\bar{k} = k$, and if $p_1 \ge 0$, then $\bar{y} = y$, $\bar{s} = s$, $\bar{\pi} = (\pi(n), \pi(0), \dots, \pi(n-1))$, $\bar{p}_1 = p_1 + 1$, $\bar{p}_2 = p_2 - 1$, $\bar{q} = q + 1$, and $\bar{k} = k$.

5 Comparison of Triangulations

Since it is very complicated to calculate the surface density of the K_2^* -triangulation, of the J_2^* -triangulation, and of the D_2^* -triangulation, we only compare the number of simplices of these triangulations. For details about the surface density, we refer to [4] and [12]. Let H^n denote the unit cube $\{x \in R^n \mid 0 \le x_i \le 1 \text{ for } i = 1, 2, ..., n\}$. We set $\alpha = 1/\beta_k$.

Theorem 5.1. The number of simplices of the K_2^* -triangulation and of the J_2^* -triangulation in the set $[2^{-(k+1)}, 2^{-k}] \times 2\alpha_k H^n$ is equal to $p_n(\alpha)$ given by

$$p_n(\alpha) = ((2\alpha)^{n+1} - 1)n!/(2\alpha - 1).$$

The number of simplices of the D_2^* -triangulation in the same set is equal to $q_n(\alpha)$ given by

$$q_n(\alpha) = \sum_{m=0}^{n} ((2^m - 1)C_n^m \alpha^m d_m (n - m)! + C_n^m \alpha^m d_m d_{n-m}),$$

where

$$d_j = j + j(j-1) + \cdots + j(j-1) \cdots 4 \cdot 3 + 2$$

for $j \ge 2$, $d_0 = d_1 = 1$, and $C_n^m = n!/m!(n-m)!$.

Proof. Let \bar{Q} denote the set $\{w \in \mathbb{R}^n \mid w_i \in \{0,1,2\} \text{ for } i=1,2,\ldots,n\}$. We take an arbitrary

vector $w \in \bar{Q}$. Let $\bar{A}(w)$ denote the set

$$\{x \in \mathbb{R}^n \mid w_i - 1 \le x_i \le w_i + 1 \text{ for } i \in I_o(w), \text{ and } x_i = w_i \text{ for } i \in I_e(w)\}$$

and let $\bar{B}(w)$ denote the set

$$\left\{x \in R^n \middle| \begin{array}{l} x_i = w_i \text{ for } i \in I_o(w), \\ \\ w_i \le x_i \le w_i + 1 \text{ for } i \in I_e(w) \text{ and } w_i = 0, \\ \\ w_i - 1 \le x_i \le w_i \text{ for } i \in I_e(w) \text{ and } w_i = 2 \end{array}\right\}.$$

Furthermore, let $\alpha_k \bar{D}(w)$ denote the convex hull of the set

$$(\left\{2^{-k}\right\} \times \alpha_k \bar{A}(w)) \cup (\left\{2^{-(k+1)}\right\} \times \alpha_k \bar{B}(w)).$$

Then it is obvious that

$$[2^{-(k+1)}, 2^{-k}] \times 2\alpha_k H^n = \bigcup_{w \in \bar{\mathcal{Q}}} \alpha_k \bar{D}(w).$$

Let m denote the number of elements in $I_e(w)$. Then there are $2^m C_n^m$ elements in \bar{Q} such that m components of each of them are even. Thus the numbers of simplices of the K_2^* -triangulation and of the J_2^* -triangulation in the set

$$\cup_{w\in\bar{Q},|I_{\mathsf{c}}(w)|=m}\alpha_k\bar{D}(w)$$

is equal to

$$2^m \alpha^m C_n^m (n-m)! m! (= (2\alpha)^m n!).$$

The number of simplices of the D_2^* -triangulation in the same set is equal to

$$(2^m-1)C_n^m\alpha^md_m(n-m)!+C_n^m\alpha^md_md_{n-m}.$$

Since

$$\bigcup_{m=0}^{n} (\bigcup_{w \in \bar{\mathcal{Q}}, |I_{\epsilon}(w)| = m} \alpha_{k} \bar{\mathcal{D}}(w)) = [2^{-(k+1)}, 2^{-k}] \times 2\alpha_{k} H^{n},$$

the theorem follows immediately.

Theorem 5.2. When $n \geq 3$, $q_n(\alpha) < p_n(\alpha)$. As n goes to infinity, $q_n(\alpha)/p_n(\alpha)$ converges to

e-2.

Proof. The conclusion is obvious, the proof is omitted.

From Theorem 5.2, we have that the number of simplices of the D_2^* -triangulation is smallest for these three triangulations.

Let us denote the continuous deformation algorithms based on the K_2^* -triangulation, the J_2^* -triangulation, and the D_2^* -triangulation by CDAK₂*, CDAJ₂*, and CDAD₂*, respectively. We have made computer codes of these algorithms in PASCAL. As introduced about the principles of the continuous deformation algorithm in the first section, letting A be the identity matrix and starting at $x^0 = (0.5, 0.5, \dots, 0.5)^{\mathsf{T}}$, we have run these computer codes on a few functions for finding a zero point. Numerical tests are given as follows. Let NFE denote the number of function evaluations. The algorithm terminates when the accuracy for $\max_{1 \le i \le n} |f_i(x^*)|$ of less than 10^{-5} has been reached. In the following tables, if the accuracy has not been satisfied when the number of function evaluations is equal to 40000, a symbol * is marked.

Problem A: The function $f: \mathbb{R}^n \to \mathbb{R}^n$ is given by

$$f_i(x) = x_i - \cos(i\sum_{j=1}^n x_j), i = 1, 2, \dots, n.$$

When $\alpha_0 = 0.25$ and $\beta_j = 1$ for j = 0, 1, ..., numerical results are given in the following table.

n	NFE(CDAK2)	NFE(CDAJ ₂)	NFE(CDAD*)
5	376	327	311
6	867	1007	787
7	2732	1794	1671
8	7843	5371	618
9	14505	12573	8663
10	35797	26006	23735

When $\alpha_0 = 0.25$ and $\beta_{2j} = 1$ and $\beta_{2j+1} = 0.5$ for j = 0, 1, ..., numerical results are given in the following table.

NFE(CDAK2)	NFE(CDAJ*)	NFE(CDAD*)
377	336	313
941	1029	818
2873	1817	1691
8390	5392	705
15209	13342	8060
*	27453	26418
	377 941 2873 8390	377 336 941 1029 2873 1817 8390 5392 15209 13342

Problem B: The function $f: \mathbb{R}^n \to \mathbb{R}^n$ is given by

$$f_i(x) = x_i - e^{\cos(i\sum_{j=1}^n x_j)}, i = 1, 2, \dots, n.$$

When $\alpha_0 = 0.25$ and $\beta_j = 1$ for j = 0, 1, ..., numerical results are given in the following table.

n	NFE(CDAK2)	NFE(CDAJ ₂)	NFE(CDAD*2)
5	771	254	199
6	826	543	278
7	6575	1937	1465
8	12781	4152	3476
9	*	12821	4706
10	*	30102	23365

When $\alpha_0 = 0.25$ and $\beta_{2j} = 1$ and $\beta_{2j+1} = 0.5$ for j = 0, 1, ..., numerical results are given in the following table.

n	NFE(CDAK2)	NFE(CDAJ2)	NFE(CDAD*2)
5	781	214	189
6	851	577	300
7	6535	2027	1631
8	11576	4326	3418
9	*	13585	5357
10	*	33443	23098

Problem C: The function $f: \mathbb{R}^n \to \mathbb{R}^n$ is given by

$$f_i(x) = x_i - e^{\sin(i\sum_{j=1}^n x_j)}, i = 1, 2, \dots, n.$$

When $\alpha_0 = 0.25$ and $\beta_j = 1$ for j = 0, 1, ..., numerical results are given in the following table.

n	NFE(CDAK*)	NFE(CDAJ ₂)	NFE(CDAD*)
5	553	298	294
6	1032	286	323
7	7993	454	417
8	22559	463	2077
9	*	21398	10284
10	*	36616	15170

When $\alpha_0 = 0.25$ and $\beta_{2j} = 1$ and $\beta_{2j+1} = 0.5$ for j = 0, 1, ..., numerical results are given in the following table.

n	NFE(CDAK ₂)	NFE(CDAJ ₂)	NFE(CDAD*)
5	634	307	349
6	1162	335	367
7	7374	588	486
8	1805	651	1999
9	36390	18954	10705
10	*	*	16392

Problem D: The function $f: \mathbb{R}^n \to \mathbb{R}^n$ is given by

$$f_i(x) = x_i - \sin(i\sum_{j=1}^n x_j), i = 1, 2, \dots, n.$$

When $\alpha_0 = 0.25$ and $\beta_j = 1$ for j = 0, 1, ..., numerical results are given in the following table.

n	NFE(CDAK2)	NFE(CDAJ*)	NFE(CDAD*)
5	452	405	364
6	1123	978	874
7	3499	2279	1726
8	6863	3461	4939
9	17264	16970	7734
10	*	*	25711

When $\alpha_0 = 0.25$ and $\beta_{2j} = 1$ and $\beta_{2j+1} = 0.5$ for j = 0, 1, ..., numerical results are given in the following table.

n	NFE(CDAK*)	NFE(CDAJ*)	NFE(CDAD*)
5	444	406	370
6	1131	1088	908
7	3829	2364	1897
8	7358	3726	5107
9	15259	17891	8173
10	*	*	32636

From these numerical examples, it appears that the continuous deformation algorithm based on the D_2^* -triangulation indeed is more efficient.

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