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## "A generalization of Hukuhara difference for interval and fuzzy arithmetic"

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# A generalization of Hukuhara difference for interval and fuzzy arithmetic 

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#### Abstract

We propose a generalization of the Hukuhara difference. First, the case of compact convex sets is examined; then, the results are applied to generalize the Hukuhara difference of fuzzy numbers, using their compact and convex level-cuts. Finally, a similar approach is suggested to attempt a generalization of division for real intervals.


## 1 General setting

We consider a metric vector space $\mathbb{X}$ with the induced topology and in particular the space $\mathbb{X}=\mathbb{R}^{n}$, $n \geq 1$, of real vectors equipped with standard addition and scalar multiplication operations. Following Diamond and Kloeden (see [3]), denote by $\mathcal{K}(\mathbb{X})$ and $\mathcal{K}_{C}(\mathbb{X})$ the spaces of nonempty compact and compact convex sets of $\mathbb{X}$. Given two subsets $A, B \subseteq \mathbb{X}$ and $k \in \mathbb{R}$, Minkowski addition and scalar multiplication are defined by $A+B=\{a+b \mid a \in A, b \in B\}$ and $k A=\{k a \mid a \in A\}$ and it is well known that addition is associative and commutative and with neutral element $\{0\}$. If $k=-1$, scalar multiplication gives the opposite $-A=$ $(-1) A=\{-a \mid a \in A\}$ but, in general, $A+(-A) \neq\{0\}$, i.e. the opposite of $A$ is not the inverse of $A$ in Minkowski addition (unless $A=\{a\}$ is a singleton). Minkowski difference is $A-B=A+(-1) B=\{a-b \mid a \in A, b \in B\}$. A first implication of this fact is that, in general, even if it true that $(A+C=B+C) \Longleftrightarrow A=B$, addition/subtraction simplification is not valid, i.e. $(A+B)-B \neq A$.

To partially overcome this situation, Hukuhara [4] introduced the following H-difference:

$$
\begin{equation*}
A \oplus B=C \Longleftrightarrow A=B+C \tag{1}
\end{equation*}
$$

and an important property of $\Theta$ is that $A \ominus A=\{0\}, \forall A \in \mathbb{R}^{n}$ and $(A+B) \ominus B=$ $A, \forall A, B \in \mathbb{R}^{n} ;$ H-difference is unique, but a necessary condition for $A \ominus B$ to exist is that $A$ contains a translate $\{c\}+B$ of $B$. In general, $A-B \neq A \oplus B$.

From an algebraic point of view, the difference of two sets $A$ and $B$ may be interpreted both in terms of addition as in (1) or in terms of negative addition, i.e.

$$
\begin{equation*}
A \boxminus B=C \Longleftrightarrow B=A+(-1) C \tag{2}
\end{equation*}
$$

where $(-1) C$ is the opposite set of $C$. Conditions (1) and (2) are compatible each other and this suggests a generalization of Hukuhara difference:

Definition 1. Let $A, B \in \mathcal{K}(\mathbb{X})$; we define the generalized difference of $A$ and $B$ as the set $C \in \mathcal{K}(\mathbb{X})$ such that

$$
A \Theta_{g} B=C \Longleftrightarrow\left\{\begin{array}{c}
(i) \quad A=B+C  \tag{3}\\
\text { or }(i i) B=A+(-1) C
\end{array}\right.
$$

Proposition 1. (Unicity of $A \Theta_{g} B$ )
If $C=A \Theta_{g} B$ exists, it is unique and if also $A \Theta B$ exists then $A \Theta_{g} B=A \Theta B$.

Proof. If $C=A \Theta_{g} B$ exists in case ( $i$ ), we obtain $C=A \ominus B$ which is unique. Suppose that case (ii) is satisfied for $C$ and $D$, i.e. $B=A+(-1) C$ and $B=$ $A+(-1) D$; then $A+(-1) C=A+(-1) D \Longrightarrow(-1) C=(-1) D \Longrightarrow C=D$. If case ( $i$ ) is satisfied for $C$ and case (ii) is satisfied for $D$, i.e. $A=B+C$ and $B=A+(-1) D$, then $B=B+C+(-1) D \Longrightarrow\{0\}=C-D$ and this is possible only if $C=D=\{c\}$ is a singleton.

The generalized Hukuhara difference $A \Theta_{g} B$ will be called the gH-difference of $A$ and $B$.

Remark 1. A necessary condition for $A \Theta_{g} B$ to exist is that either $A$ contains a translate of $B$ (as for $A \ominus B$ ) or $B$ contains a translate of $A$. In fact, for any given $c \in C$, we get $B+\{c\} \subseteq A$ from (i) or $A+\{-c\} \subseteq B$ from (ii).

Remark 2. It is possible that $A=B+C$ and $B=A+(-1) C$ hold simultaneously; in this case, $A$ and $B$ translate into each other and $C$ is a singleton. In fact, $A=B+C$ implies $B+\{c\} \subseteq A \forall c \in C$ and $B=A+(-1) C$ implies $A-\{c\} \subseteq B$ $\forall c \in C$ i.e. $A \subseteq B+\{c\}$; it follows that $A=B+\{c\}$ and $B=A+\{-c\}$. On the other hand, if $c^{\prime}, c^{\prime \prime} \in C$ then $A=B+\left\{c^{\prime}\right\}=B+\left\{c^{\prime \prime}\right\}$ and this requires $c^{\prime}=c^{\prime \prime}$.

Remark 3. If $A \Theta_{g} B$ exists, then $B \Theta_{g} A$ exists and $B \Theta_{g} A=-\left(A \Theta_{g} B\right)$.
Proposition 2. If $A \Theta_{g} B$ exists, it has the following properties:

1) $A \Theta_{g} A=\{0\}$;
2) $(A+B) \Theta_{g} B=A$;
3) If $A \Theta_{g} B$ exists then also $(-B) \Theta_{g}(-A)$ does and $-\left(A \Theta_{g} B\right)=(-B) \Theta_{g}(-A)$; 4) $(A-B)+B=C \Longleftrightarrow A-B=C \Theta_{g} B$;
4) In general, $B-A=A-B$ does not imply $A=B$; but $\left(A \Theta_{g} B\right)=\left(B \Theta_{g} A\right)=C$ if and only if $C=\{0\}$ and $A=B$;
5) If $B \Theta_{g} A$ exists then either $A+\left(B \Theta_{g} A\right)=B$ or $B-\left(B \Theta_{g} A\right)=A$ and both equalities hold if and only if $B \Theta_{g} A$ is a singleton set.

Proof. Properties 1 and 5 are immediate. To prove 2) if $C=(A+B) \Theta_{g} B$ then either $A+B=C+B$ or $B=(A+B)+(-1) C=B+(A+(-1) C)$; in the first case it follows that $C=A$, in the second case $A+(-1) C=\{0\}$ and $A$ and $C$ are singleton sets so $A=C$. To prove the firat part of 3) let $C=A \Theta_{g} B$ i.e.
$A=B+C$ or $B=A+(-1) C$, then $-A=-B+(-C)$ or $-B=-A-(-C)$ and this means $(-B) \Theta_{g}(-A)=-C$; the second part is immediate. To see the first part of 5) consider for example the unidimensional case $A=\left[a^{-}, a^{+}\right]$, $B=\left[b^{-}, b^{+}\right]$; equality $A-B=B-A$ is valid if $a^{-}+a^{+}=b^{-}+b^{+}$and this does not require $A=B$ (unless $A$ and $B$ are singletons). For the second part of 5), from $\left(A \Theta_{g} B\right)=\left(B \Theta_{g} A\right)=C$, considering the four combinations derived from (3), one of the following four case is valid: $(A=B+C$ and $B=A+C)$ or $(A=B+C$ and $A=B-C)$ or $(B=A+(-1) C$ and $B=A+C)$ or $(B=A+(-1) C$ and $A=B+(-1) C)$; in all of them we deduce $C=\{0\}$. To see 6), consider that if $\left(B \Theta_{g} A\right)$ exists in the sense of $(i)$ the first equality is valid and if it exists in the sense of (ii) the second one is valid.

If $\mathbb{X}=\mathbb{R}^{n}, n \geq 1$ is the real $n$-dimensional vector space with internal product $\langle x, y\rangle$ and corresponding norm $\|x\|=\sqrt{\langle x, x\rangle}$, we denote by $\mathcal{K}^{n}$ and $\mathcal{K}_{C}^{n}$ the spaces of (nonempty) compact and compact convex sets of $\mathbb{R}^{n}$, respectively. If $A \subseteq \mathbb{R}^{n}$ and $\mathcal{S}^{n-1}=\left\{u \mid u \in \mathbb{R}^{n},\|u\|=1\right\}$ is the unit sphere, the support function associated to $A$ is

$$
\begin{aligned}
s_{A} & : \mathbb{R}^{n} \longrightarrow \mathbb{R} \text { defined by } \\
s_{A}(u) & =\sup \{\langle u, a\rangle \mid a \in A\}, u \in \mathbb{R}^{n} .
\end{aligned}
$$

If $A \neq \emptyset$ is compact, then $s_{A}(u) \in \mathbb{R}, \forall u \in \mathcal{S}^{n-1}$. The following properties are well known (see e.g. [3] or [5]):

- Any function $s: \mathbb{R}^{n} \longrightarrow \mathbb{R}$ which is continuous, positively homogeneous $s(t u)=t s(u),), \forall t \geq 0, \forall u \in \mathbb{R}^{n}$ and subadditive $s\left(u^{\prime}+u^{\prime \prime}\right) \leq s\left(u^{\prime}\right)+s\left(u^{\prime \prime}\right)$, $\forall u^{\prime}, u^{\prime \prime} \in \mathbb{R}^{n}$ is a support function of a compact convex set; the restriction $\widehat{s}$ of $s$ to $\mathcal{S}^{n-1}$ is such that $\widehat{s}\left(\frac{u}{\|u\|}\right)=\frac{1}{\|u\|} s(u), \forall u \in \mathbb{R}^{n}, u \neq 0$ and we can consider $s$ restricted to $\mathcal{S}^{n-1}$. It also follows that $s: \mathcal{S}^{n-1} \longrightarrow \mathbb{R}$ is a convex function.
- If $A \in \mathcal{K}_{C}^{n}$ is a compact convex set, then it is characterized by its support function and

$$
A=\left\{x \in \mathbb{R}^{n} \mid\langle u, x\rangle \leq s_{A}(u), \forall u \in \mathbb{R}^{n}\right\}=\left\{x \in \mathbb{R}^{n} \mid\langle u, x\rangle \leq s_{A}(u), \forall u \in \mathcal{S}^{n-1}\right\}
$$

- For $A, B \in \mathcal{K}_{C}^{n}$ and $\forall u \in \mathcal{S}^{n-1}$ we have $s_{\{0\}}(u)=0$ and

$$
\begin{aligned}
A & \subseteq B \Longrightarrow s_{A}(u) \leq s_{B}(u) ; A=B \Longleftrightarrow s_{A}=s_{B} \\
s_{k A}(u) & =k s_{A}(u), \forall k \geq 0 ; s_{k A+h B}(u)=s_{k A}(u)+s_{h B}(u), \forall k, h \geq 0
\end{aligned}
$$

and in particular

$$
s_{A+B}(u)=s_{A}(u)+s_{B}(u)
$$

- If $s_{A}$ is the support function of $A \in \mathcal{K}_{C}^{n}$ and $s_{-A}$ is the support function of $-A \in \mathcal{K}_{C}^{n}$, then $\forall u \in \mathcal{S}^{n-1}, s_{-A}(u)=s_{A}(-u)$;
- If $v$ is a measure on $\mathbb{R}^{n}$ such that $v\left(\mathcal{S}^{n-1}\right)=\int_{\mathcal{S}^{n-1}} v(d u)=1$, a distance is defined by

$$
\rho_{2}(A, B)=\left\|s_{A}-s_{B}\right\|=\left(n \int_{\mathcal{S}^{n-1}}\left[s_{A}(u)-s_{B}(u)\right]^{2} v(d u)\right)^{\frac{1}{2}}
$$

- The Steiner point of $A \in \mathcal{K}_{C}^{n}$ is defined by $\sigma_{A}=n \int_{\mathcal{S}^{n-1}} u s_{A}(u) v(d u)$ and $\sigma_{A} \in A$.

We can express the generalized Hukuhara difference (gH-difference) of compact convex sets $A, B \in \mathcal{K}_{C}^{n}$ by the use of the support functions. Consider $A, B, C \in \mathcal{K}_{C}^{n}$ with $C=A \Theta_{g} B$ as defined in (3); let $s_{A}, s_{B}, s_{C}$ and $s_{(-1) C}$ be the support functions of $A, B, C$, and $(-1) C$ respectively. In case ( $i$ ) we have $s_{A}=s_{B}+s_{C}$ and in case ( $i i$ ) we have $s_{B}=s_{A}+s_{(-1) C}$. So, $\forall u \in \mathcal{S}^{n-1}$

$$
s_{C}(u)=\left\langle\begin{array}{ll}
s_{A}(u)-s_{B}(u) & \text { in case }(i) \\
s_{B}(-u)-s_{A}(-u) \text { in case }(i i)
\end{array}\right.
$$

i.e.

$$
s_{C}(u)=\left\langle\begin{array}{ll}
s_{A}(u)-s_{B}(u) & \text { in case }(i)  \tag{4}\\
s_{(-1) B}(u)-s_{(-1) A}(u) & \text { in case }(i i)
\end{array} .\right.
$$

Now, $s_{C}$ in (4) is a correct support function if it is continuous, positively homogeneous and subadditive and this requires that, in the corresponding cases (i) and (ii), $s_{A}-s_{B}$ and/or $s_{-B}-s_{-A}$ be support functions, assuming that $s_{A}$ and $s_{B}$ are.

Consider $s_{1}=s_{A}-s_{B}$ and $s_{2}=s_{B}-s_{A}$. Continuity of $s_{1}$ and $s_{2}$ is obvious. To see their positive homogeneity let $t \geq 0$; we have $s_{1}(t u)=s_{A}(t u)-s_{B}(t u)$ $=t s_{A}(u)-t s_{B}(u)=t s_{1}(u)$ and similarly for $s_{2}$. But $s_{1}$ and/or $s_{2}$ may fail to be subadditive and the following four cases, related to the definition of gH difference, are possible.

Proposition 3. Let $s_{A}$ and $s_{B}$ be the support functions of $A, B \in \mathcal{K}_{C}^{n}$ and consider $s_{1}=s_{A}-s_{B}, s_{2}=s_{B}-s_{A}$; the following four cases apply:

1. If $s_{1}$ and $s_{2}$ are both subadditive, then $A \Theta_{g} B$ exists; (i) and (ii) are satisfied simultaneously and $A \Theta_{g} B=\{c\}$;
2. If $s_{1}$ is subadditive and $s_{2}$ is not, then $C=A \Theta_{g} B$ exists, (i) is satisfied and $s_{C}=s_{A}-s_{B}$;
3. If $s_{1}$ is not subadditive and $s_{2}$ is, then $C=A \Theta_{g} B$ exists, (ii) is satisfied and $s_{C}=s_{-B}-s_{-A}$;
4. If $s_{1}$ and $s_{2}$ are both not subadditive, then $A \Theta_{g} B$ does not exist.

Proof. In case 1. subadditivity of $s_{1}$ and $s_{2}$ means that, $\forall u^{\prime}, u^{\prime \prime} \in \mathcal{S}^{n-1}$

$$
\begin{aligned}
& s_{1}: s_{A}\left(u^{\prime}+u^{\prime \prime}\right)-s_{B}\left(u^{\prime}+u^{\prime \prime}\right) \leq s_{A}\left(u^{\prime}\right)+s_{A}\left(u^{\prime \prime}\right)-s_{B}\left(u^{\prime}\right)-s_{B}\left(u^{\prime \prime}\right) \text { and } \\
& s_{2}: s_{B}\left(u^{\prime}+u^{\prime \prime}\right)-s_{A}\left(u^{\prime}+u^{\prime \prime}\right) \leq s_{B}\left(u^{\prime}\right)+s_{B}\left(u^{\prime \prime}\right)-s_{A}\left(u^{\prime}\right)-s_{A}\left(u^{\prime \prime}\right) ;
\end{aligned}
$$

it follows that

$$
\begin{aligned}
& s_{A}\left(u^{\prime}+u^{\prime \prime}\right)-s_{A}\left(u^{\prime}\right)-s_{A}\left(u^{\prime \prime}\right) \leq s_{B}\left(u^{\prime}+u^{\prime \prime}\right)-s_{B}\left(u^{\prime}\right)-s_{B}\left(u^{\prime \prime}\right) \text { and } \\
& s_{B}\left(u^{\prime}+u^{\prime \prime}\right)-s_{B}\left(u^{\prime}\right)-s_{B}\left(u^{\prime \prime}\right) \leq s_{A}\left(u^{\prime}+u^{\prime \prime}\right)-s_{A}\left(u^{\prime}\right)-s_{A}\left(u^{\prime \prime}\right)
\end{aligned}
$$

so that equality holds

$$
s_{B}\left(u^{\prime}+u^{\prime \prime}\right)-s_{A}\left(u^{\prime}+u^{\prime \prime}\right)=s_{B}\left(u^{\prime}\right)+s_{B}\left(u^{\prime \prime}\right)-s_{A}\left(u^{\prime}\right)-s_{A}\left(u^{\prime \prime}\right)
$$

Taking $u^{\prime}=-u^{\prime \prime}=u$ produces, $\forall u \in \mathcal{S}^{n-1}, s_{B}(u)+s_{B}(-u)=s_{A}(u)+s_{A}(-u)$ i.e. $s_{B}(u)+s_{-B}(u)=s_{A}(u)+s_{-A}(u)$ i.e. $s_{B-B}(u)=s_{A-A}(u)$ and $B-B=A-A$ ( $A$ and $B$ translate into each other); it follows that $\exists c \in \mathbb{R}^{n}$ such that $A=B+\{c\}$ and $B=A+\{-c\}$ so that $A \Theta_{g} B=\{c\}$.
In case 2. we have that, being $s_{1}$ a support function it characterizes a nonempty set $C \in \mathcal{K}_{C}^{n}$ and $s_{C}(u)=s_{1}(u)=s_{A}(u)-s_{B}(u), \forall u \in \mathcal{S}^{n-1}$; then $s_{A}=s_{B}+s_{C}=$ $s_{B+C}$ and $A=B+C$ from which ( $i$ ) is satisfied.
In case 3. we have that $s_{2}$ the support function of a nonempty set $D \in \mathcal{K}_{C}^{n}$ and $s_{D}(u)=s_{B}(u)-s_{A}(u), \forall u \in \mathcal{S}^{n-1}$ so that $s_{B}=s_{A}+s_{D}=s_{A-D}$ and $B=A+D$. Defining $C=(-1) D$ (or $D=(-1) C$ ) we obtain $C \in \mathcal{K}_{C}^{n}$ with $s_{C}(u)=s_{-D}(u)=s_{D}(-u)=s_{B}(-u)-s_{A}(-u)=s_{-B}(u)-s_{-A}(u)$ and (ii) is satisfied.
In case 4. there is no $C \in \mathcal{K}_{C}^{n}$ such that $A=B+C$ (otherwise $s_{1}=s_{A}-s_{B}$ is a support function) and there is no $D \in \mathcal{K}_{C}^{n}$ such that $B=A+D$ (otherwise $s_{2}=s_{B}-s_{A}$ is a support function); it follows that (i) and (ii) cannot be satisfied and $A \Theta_{g} B$ does not exist.

Proposition 4. If $C=A \Theta_{g} B$ exists, then $\|C\|=\rho_{2}(A, B)$ and the Steiner points satisfy $\sigma_{C}=\sigma_{A}-\sigma_{B}$.

Proof. In fact $\rho_{2}(A, B)=\left\|s_{A}-s_{B}\right\|$ and, if $A \Theta_{g} B$ exists, then either $s_{C}=$ $s_{A}-s_{B}$ or $s_{C}=s_{-B}-s_{-A}$; but $\left\|s_{A}-s_{B}\right\|=\left\|s_{-A}-s_{-B}\right\|$ as, changing variable $u$ into $-v$ and recalling that $s_{-A}(u)=s_{A}(-u)$, we have

$$
\begin{align*}
\left\|s_{-A}-s_{-B}\right\| & =\int_{\mathcal{S}^{n-1}}\left[s_{-A}(u)-s_{-B}(u)\right]^{2} v(d u)  \tag{5}\\
& =\int_{\mathcal{S}^{n-1}}\left[s_{A}(-u)-s_{B}(-u)\right]^{2} v(d u) \\
& =\int_{\mathcal{S}^{n-1}}\left[s_{A}(v)-s_{B}(v)\right]^{2} v(-d v)=\left\|s_{A}-s_{B}\right\|
\end{align*}
$$

For the Steiner points, we proceed in a similar manner:

$$
\sigma_{C}=\left\{\begin{array}{l}
n \int_{\mathcal{S}^{n-1}} u\left[s_{A}(u)-s_{B}(u)\right] v(d u), \text { or }  \tag{6}\\
n \int_{\mathcal{S}^{n-1}} u\left[s_{-B}(u)-s_{-A}(u)\right] v(d u)=n \int_{\mathcal{S}^{n-1}} v\left[s_{A}(v)-s_{B}(v)\right] v(-d v)
\end{array}\right.
$$

and the result follows from the additivity of the integral.

## 2 The case of compact intervals in $\mathbb{R}^{n}$

In this section we consider the gH -difference of compact intervals in $\mathbb{R}^{n}$. If $n=1$, i.e. for unidimensional compact intervals, the gH-difference always exists. In fact, let $A=\left[a^{-}, a^{+}\right]$and $B=\left[b^{-}, b^{+}\right]$be two intervals; the gH -difference is

$$
\left[a^{-}, a^{+}\right] \Theta_{g}\left[b^{-}, b^{+}\right]=\left[c^{-}, c^{+}\right] \Longleftrightarrow\left\{\begin{array}{r}
\text { (i) }\left\{\begin{array}{l}
a^{-}=b^{-}+c^{-} \\
a^{+}=b^{+}+c^{+} \\
b^{-}=a^{-}-c^{+} \\
b^{+}=a^{+}-c^{-}
\end{array}\right. \text {or (ii)}
\end{array}\right.
$$

so that $\left[a^{-}, a^{+}\right] \Theta_{g}\left[b^{-}, b^{+}\right]=\left[c^{-}, c^{+}\right]$is always defined by

$$
c^{-}=\min \left\{a^{-}-b^{-}, a^{+}-b^{+}\right\}, c^{+}=\max \left\{a^{-}-b^{-}, a^{+}-b^{+}\right\}
$$

i.e.

$$
[a, b] \Theta_{g}[c, d]=[\min \{a-c, b-d\}, \max \{a-c, b-d\}]
$$

Conditions (i) and (ii) are satisfied simultaneously if and only if the two intervals have the same length and $c^{-}=c^{+}$. Also, the result is $\{0\}$ if and only if $a^{-}=b^{-}$ and $a^{+}=b^{+}$.

Two simple examples on real compact intervals illustrate the generalization (from $[3]$, p. 8$) ;[-1,1] \Theta[-1,0]=[0,1]$ as in fact (i) is $[-1,0]+[0,1]=[-1,1]$ but $[0,0] \Theta_{g}[0,1]=[-1,0]$ and $[0,1] \Theta_{g}\left[-\frac{1}{2}, 1\right]=\left[0, \frac{1}{2}\right]$ satisfy (ii).

Of interest are the symmetric intervals $A=[-a, a]$ and $B=[-b, b]$ with $a, b \geq 0$; it is well known that Minkowski operations with symmetric intervals are such that $A-B=B-A=A+B$ and, in particular, $A-A=A+A=2 A$. We have $[-a, a] \Theta_{g}[-b, b]=[-|a-b|,|a-b|]$.

As $\mathcal{S}^{0}=\{-1,1\}$ and the support functions satisfy $s_{A}(-1)=-a^{-}, s_{A}(1)=$ $a^{+}, s_{B}(-1)=-b^{-}, s_{B}(1)=b^{+}$, the same results as before can be deduced by definition (4).

Remark 4. An alternative representation of an interval $A=\left[a^{-}, a^{+}\right]$is by the use of the midpoint $\widehat{a}=\frac{a^{-}+a^{+}}{2}$ and the (semi)width $\bar{a}=\frac{a^{+}-a^{-}}{2}$ and we can write $A=(\widehat{a}, \bar{a}), \bar{a} \geq 0$, so that $a^{-}=\widehat{a}-\bar{a}$ and $a^{+}=\widehat{a}+\bar{a}$. If $B=(\widehat{b}, \bar{b})$, $\bar{b} \geq 0$ is a second interval, the Minkowski addition is $A+B=(\widehat{a}+\widehat{b}, \bar{a}+\bar{b})$ and the gH-difference is obtained by $A \Theta_{g} B=(\widehat{a}-\widehat{b},|\bar{a}-\bar{b}|)$. We see immediately that $A \Theta_{g} A=\{0\}, A=B \Longleftrightarrow A \Theta_{g} B=\{0\},(A+B) \Theta_{g} B=A$, but $A+\left(B \Theta_{g} A\right)=B$ only if $\bar{a} \leq \bar{b}$.

Let now $A=\times{ }_{i=1}^{n} A_{i}$ and $B=\times{ }_{i=1}^{n} B_{i}$ where $A_{i}=\left[a_{i}^{-}, a_{i}^{+}\right], B_{i}=\left[b_{i}^{-}, b_{i}^{+}\right]$ are real compact intervals ( $\times_{i=1}^{n}$ denotes the cartesian product).

In general, considering $D=\times_{i=1}^{n}\left(A_{i} \Theta_{g} B_{i}\right)$, we may have $A \Theta_{g} B \neq D$ e.g. $A \Theta_{g} B$ may not exist as for the example $A_{1}=[3,6], A_{2}=[2,6], B_{1}=[5,10]$, $B_{2}=[7,9]$ for which $\left(A_{1} \Theta_{g} B_{1}\right)=[-4,-2],\left(A_{2} \Theta_{g} B_{2}\right)=[-5,-3], D=$ $[-4,-2] \times[-5,-3]$ and $B+D=[1,8] \times[2,6] \neq A, A+(-1) D=[5,10] \times[5,11] \neq$ B.

But if $A \Theta_{g} B$ exists, then equality will hold. In fact, consider the support function of $A$ (and similarly for $B$ ), defined by

$$
\begin{equation*}
s_{A}(u)=\max _{x}\left\{\langle u, x\rangle \mid a_{i}^{-} \leq x_{i} \leq a_{i}^{+}\right\}, u \in \mathcal{S}^{n-1} \tag{7}
\end{equation*}
$$

it can be obtained simply by $s_{A}(u)=\sum_{u_{i}>0} u_{i} a_{i}^{+}+\sum_{u_{i}<0} u_{i} a_{i}^{-}$as the box-constrained maxima of the linear objective functions $\langle u, x\rangle$ above are attained at vertices $\widehat{x}(u)=\left(\widehat{x}_{1}(u), \ldots, \widehat{x}_{i}(u), \ldots, \widehat{x}_{n}(u)\right)$ of $A$, i.e. $\widehat{x}_{i}(u) \in\left\{a_{i}^{-}, a_{i}^{+}\right\}, i=1,2, \ldots, n$. Then

$$
\begin{equation*}
s_{A}(u)-s_{B}(u)=\sum_{u_{i}>0} u_{i}\left(a_{i}^{+}-b_{i}^{+}\right)+\sum_{u_{i}<0} u_{i}\left(a_{i}^{-}-b_{i}^{-}\right) \tag{8}
\end{equation*}
$$

and, being $s_{-A}(u)=s_{A}(-u)=-\sum_{u_{i}<0} u_{i} a_{i}^{+}-\sum_{u_{i}>0} u_{i} a_{i}^{-}$,

$$
\begin{equation*}
s_{-B}(u)-s_{-A}(u)=\sum_{u_{i}>0} u_{i}\left(a_{i}^{-}-b_{i}^{-}\right)+\sum_{u_{i}<0} u_{i}\left(a_{i}^{+}-b_{i}^{+}\right) . \tag{9}
\end{equation*}
$$

From the relations above, we deduce that

$$
A \Theta_{g} B=C \Longleftrightarrow\left\{\begin{array}{c}
\text { (i) }\left\{\begin{array}{l}
C=\times_{i=1}^{n}\left[a_{i}^{-}-b_{i}^{-}, a_{i}^{+}-b_{i}^{+}\right] \\
\text {provided that } a_{i}^{-}-b_{i}^{-} \leq a_{i}^{+}-b_{i}^{+}, \forall i
\end{array}\right. \\
\text { or }(i i)\left\{\begin{array}{l}
C=\times_{i=1}^{n}\left[a_{i}^{+}-b_{i}^{+}, a_{i}^{-}-b_{i}^{-}\right] \\
\text {provided that } a_{i}^{-}-b_{i}^{-} \geq a_{i}^{+}-b_{i}^{+}, \forall i
\end{array}\right.
\end{array}\right.
$$

and the gH-difference $A \Theta_{g} B$ exists if and only if one of the two conditions are satisfied:
case (i) $a_{i}^{-}-b_{i}^{-} \leq a_{i}^{+}-b_{i}^{+}, i=1,2, \ldots, n$
case (ii) $a_{i}^{-}-b_{i}^{-} \geq a_{i}^{+}-b_{i}^{+}, i=1,2, \ldots, n$

## Examples:

1. case $(i): A_{1}=[5,10], A_{2}=[1,3], B_{1}=[3,6], B_{2}=[2,3]$ for which $\left(A_{1} \Theta_{g} B_{1}\right)=[2,4],\left(A_{2} \Theta_{g} B_{2}\right)=[-1,0]$ and $A \Theta_{g} B=C=[2,4] \times[-1,0]$ exists with $B+C=A, A+(-1) C \neq B$.
2. case $(i i): A_{1}=[3,6], A_{2}=[2,3], B_{1}=[5,10], B_{2}=[1,3]$ for which
 exists with $B+C \neq A, A+(-1) C=B$.
3. case $(i)+(i i): A_{1}=[3,6], A_{2}=[2,3], B_{1}=[5,8], B_{2}=[3,4]$ for which $\left(A_{1} \frac{\left.\Theta_{g} B_{1}\right)=[-2,-2]=\{-2\},\left(A_{2} \Theta_{g} B_{2}\right)=[-1,-1]=\{-1\} \text { and } A \Theta_{g} B=}{n}\right.$ $C=\{(-2,-1)\}$ exists with $B+C=A$ and $A+(-1) C=B$.

We end this section with a comment on the simple interval equation

$$
\begin{equation*}
A+X=B \tag{10}
\end{equation*}
$$

where $A=\left[a^{-}, a^{+}\right], B=\left[b^{-}, b^{+}\right]$are given intervals and $X=\left[x^{-}, x^{+}\right]$is an interval to be determined satisfying (10). We have seen that, for unidimensional intervals, the gH-difference always exists. Denote by $l(A)=a^{+}-a^{-}$the length of interval $A$. It is well known from classical interval arithmetic that an interval
$X$ satisfying (10) exists only if $l(B) \geq l(A)$ (in Minkowski arithmetic we have $l(A+X) \geq \max \{l(A), l(X)\})$; in fact, no $X$ exists with $x^{-} \leq x^{+}$if $l(B)<l(A)$ and we cannot solve (10) unless we interpret it as $B-X=A$. If we do so, we get

$$
\begin{aligned}
& \text { case } l(B) \leq l(A):\left\{\begin{array}{l}
a^{-}+x^{-}=b^{-} \\
a^{+}+x^{+}=b^{+}
\end{array} \text {i.e. } \begin{array}{l}
x^{-}=b^{-}-a^{-} \\
x^{-}=b^{-}-a^{-}
\end{array}\right. \\
& \text {case } l(B) \geq l(A):\left\{\begin{array}{l}
b^{-}-x^{+}=a^{-} \\
b^{+}-x^{-}=a^{+}
\end{array} \text {i.e. } \begin{array}{l}
x^{-}=b^{+}-a^{+} \\
x^{+}=b^{-}-a^{-}
\end{array}\right.
\end{aligned}
$$

We then obtain that $X=B \Theta_{g} A$ is the unique solution to (10) and it always exists, i.e.

Proposition 5. Let $A, B \in \mathcal{K}_{C}(\mathbb{R})$; the $g H$-difference $X=B \Theta_{g} A$ always exists and either $A+\left(B \Theta_{g} A\right)=B$ or $B-\left(B \Theta_{g} A\right)=A$.

From property 6) of Proposition 7, a similar result is true for equation $A+$ $X=B$ with $A, B \in \mathcal{K}_{C}\left(\mathbb{R}^{n}\right)$ but for $n>1$ the gH -difference may non exist.

## 3 gH-difference of fuzzy numbers

A general fuzzy set over a given set (or space) $\mathbb{X}$ of elements (the universe) is usually defined by its membership function $\mu: \mathbb{X} \longrightarrow \mathbb{T} \subseteq[0,1]$ and a fuzzy (sub)set $u$ of $\mathbb{X}$ is uniquely characterized by the pairs $\left(x, \mu_{u}(x)\right)$ for each $x \in \mathbb{X}$; the value $\mu_{u}(x) \in[0,1]$ is the membership grade of $x$ to the fuzzy set $u$. We will consider particular fuzzy sets, called fuzzy numbers, defined over $\mathbb{X}=\mathbb{R}$ having a particular form of the membership function. Let $\mu_{u}$ be the membership function of a fuzzy set $u$ over $\mathbb{X}$. The support of $u$ is the (crisp) subset of points of $\mathbb{X}$ at which the membership grade $\mu_{u}(x)$ is positive: $\operatorname{supp}(u)=\{x \mid x \in \mathbb{X}$, $\left.\mu_{u}(x)>0\right\}$. For $\left.\left.\alpha \in\right] 0,1\right]$, the $\alpha$-level cut of $u$ (or simply the $\alpha-c u t$ ) is defined by $[u]_{\alpha}=\left\{x \mid x \in \mathbb{X}, \mu_{u}(x) \geq \alpha\right\}$ and for $\alpha=0$ (or $\alpha \rightarrow+0$ ) by the closure of the support $[u]_{0}=\operatorname{cl}\left\{x \mid x \in \mathbb{X}, \mu_{u}(x)>0\right\}$.

A well-known property of the level - cuts is $[u]_{\alpha} \subseteq[u]_{\beta}$ for $\alpha>\beta$ (i.e. they are nested).

A particular class of fuzzy sets $u$ is when the support is a convex set and the membership function is quasi-concave i.e. $\mu_{u}\left((1-t) x^{\prime}+t x^{\prime \prime}\right) \geq \min \left\{\mu_{u}\left(x^{\prime}\right), \mu_{u}\left(x^{\prime \prime}\right)\right\}$ for every $x^{\prime}, x^{\prime \prime} \in \operatorname{supp}(u)$ and $t \in[0,1]$. Equivalently, $\mu_{u}$ is quasi-concave if the level sets $[u]_{\alpha}$ are convex sets for all $\alpha \in[0,1]$. A third property of the fuzzy numbers is that the level-cuts $[u]_{\alpha}$ are closed sets for all $\alpha \in[0,1]$.

By using these properties, the space $\mathcal{F}$ of (real unidimensional) fuzzy numbers is structured by an addition and a scalar multiplication, defined either by the level sets or, equivalently, by the Zadeh extension principle. Let $u, v \in \mathcal{F}$ have membership functions $\mu_{u}, \mu_{v}$ and $\alpha$-cuts $[u]_{\alpha},[v]_{\alpha}, \alpha \in[0,1]$ respectively. The addition $u+v \in \mathcal{F}$ and the scalar multiplication $k u \in \mathcal{F}$ have level cuts

$$
\begin{align*}
{[u+v]_{\alpha} } & =[u]_{\alpha}+[v]_{\alpha}=\left\{x+y \mid x \in[u]_{\alpha}, y \in[v]_{\alpha}\right\}  \tag{11}\\
{[k u]_{\alpha} } & =k[u]_{\alpha}=\left\{k x \mid x \in[u]_{\alpha}\right\} \tag{12}
\end{align*}
$$

In the fuzzy or in the interval arithmetic contexts, equation $u=v+w$ is not equivalent to $w=u-v=u+(-1) v$ or to $v=u-w=u+(-1) w$ and this has motivated the introduction of the following Hukuhara difference ([3], [5]). The generalized Hukuhara difference is (implicitly) used by Bede and Gal (see [1]) in their definition of generalized differentiability of a fuzzy-valued function.

Definition 2. Given $u, v \in \mathcal{F}$, the H-difference is defined by $u \ominus v=w \Longleftrightarrow u=$ $v+w$; if $u \Theta v$ exists, it is unique and its $\alpha-$ cuts are $[u \Theta v]_{\alpha}=\left[u_{\alpha}^{-}-v_{\alpha}^{-}, u_{\alpha}^{+}-v_{\alpha}^{+}\right]$. Clearly, $u \ominus u=\{0\}$.

The Hukuhara difference is also motivated by the problem of inverting the addition: if $x, y$ are crisp numbers then $(x+y)-y=x$ but this is not true if $x, y$ are fuzzy. It is possible to see that (see [2]), if $u$ and $v$ are fuzzy numbers (and not in general fuzzy sets), then $(u+v) \Theta v=u$ i.e. the H-difference inverts the addition of fuzzy numbers.

The gH-difference for fuzzy numbers can be defined as follows:
Definition 3. Given $u, v \in \mathcal{F}$, the $g H$-difference is the fuzzy number $w$, if it exists, such that

$$
u \Theta_{g} v=w \Longleftrightarrow\left\{\begin{align*}
(i) \quad u & =v+w  \tag{13}\\
\text { or (ii) } v & =u+(-1) w
\end{align*}\right.
$$

If $u \Theta_{g} v$ exists, its $\alpha-$ cuts are given by $\left[u \Theta_{g} v\right]_{\alpha}=\left[\min \left\{u_{\alpha}^{-}-v_{\alpha}^{-}, u_{\alpha}^{+}-\right.\right.$ $\left.\left.v_{\alpha}^{+}\right\}, \max \left\{u_{\alpha}^{-}-v_{\alpha}^{-}, u_{\alpha}^{+}-v_{\alpha}^{+}\right\}\right]$and $u \Theta v=u \Theta_{g} v$ if $u \Theta v$ exists. If (i) and (ii) are satisfied simultaneously, then $w$ is a crisp number. Also, $u \Theta_{g} u=u \Theta u=\{0\}$.

A definition of $w=u \Theta_{g} v$ for multidimensional fuzzy numbers can be obtained in terms of support functions in a way similar to (4)

$$
s_{w}(p ; \alpha)=\left\langle\begin{array}{ll}
s_{u}(p ; \alpha)-s_{v}(p ; \alpha) & \text { in case }(i)  \tag{14}\\
s_{(-1) v}(p ; \alpha)-s_{(-1) u}(p ; \alpha) \text { in case }(i i)
\end{array}, \alpha \in[0,1]\right.
$$

where, for a fuzzy number $u$, the support functions are considered for each $\alpha-$ cut and defined to characterize the (compact) $\alpha-$ cuts $[u]_{\alpha}$ :

$$
\begin{aligned}
s_{u} & : \mathbb{R}^{n} \times[0,1] \longrightarrow \mathbb{R} \text { defined by } \\
s_{u}(p ; \alpha) & =\sup \left\{\langle p, x\rangle \mid x \in[u]_{\alpha}\right\} \text { for each } p \in \mathbb{R}^{n}, \alpha \in[0,1]
\end{aligned}
$$

In the unidimensional fuzzy numbers, the conditions for the definition of $w=u \Theta_{g} v$ are

$$
[w]_{\alpha}=\left[w_{\alpha}^{-}, w_{\alpha}^{+}\right]=[u]_{\alpha} \Theta_{g}[v]_{\alpha}:\left\{\begin{array}{l}
w_{\alpha}^{-}=\min \left\{u_{\alpha}^{-}-v_{\alpha}^{-}, u_{\alpha}^{+}-v_{\alpha}^{+}\right\}  \tag{15}\\
w_{\alpha}^{+}=\max \left\{u_{\alpha}^{-}-v_{\alpha}^{-}, u_{\alpha}^{+}-v_{\alpha}^{+}\right\}
\end{array} .\right.
$$

provided that $w_{\alpha}^{-}$is nondecreasing, $w_{\alpha}^{+}$is nonincreasing and $w_{\alpha}^{-} \leq w_{\alpha}^{+}$.
If $u \Theta_{g} v$ is a proper fuzzy number, it has the same properties illustrated in section 1. for intervals.

Proposition 6. If $u \Theta_{g} v$ exists, it is unique and has the following properties:

1) $u \Theta_{g} u=0$;
2) $(u+v) \Theta_{g} v=u$;
3) If $u \Theta_{g} v$ exists then also $(-v) \Theta_{g}(-u)$ does and $\{0\} \Theta_{g}\left(u \Theta_{g} v\right)=(-v) \Theta_{g}(-u)$;
4) $(u-v)+v=w \Longleftrightarrow u-v=w \Theta_{g} v$;
5) $\left(u \Theta_{g} v\right)=\left(v \Theta_{g} u\right)=w$ if and only if $(w=\{0\}$ and $u=v)$;
6) If $v \Theta_{g} u$ exists then either $u+\left(v \Theta_{g} u\right)=u$ or $v-\left(v \Theta_{g} u\right)=u$ and if both equalities hold then $v \Theta_{g} u$ is a crisp set.

If the gH -differences $[u]_{\alpha} \Theta_{g}[v]_{\alpha}$ do not define a proper fuzzy number, we can use the nested property and obtain a proper fuzzy number by

$$
\begin{equation*}
\left[u \widetilde{\Theta}_{g} v\right]_{\alpha}:=\bigcup_{\beta \geq \alpha}\left([u]_{\beta} \Theta_{g}[v]_{\beta}\right) \tag{16}
\end{equation*}
$$

As each gH-difference $[u]_{\beta} \Theta_{g}[v]_{\beta}$ exists for $\beta \in[0,1]$ and (16) defines a proper fuzzy number, it follows that $u \widetilde{\Theta}_{g} v$ can be considered as a generalization of Hukuhara difference for fuzzy numbers, existing for any $u, v$. A second possibility for a gH-difference of fuzzy numbers may be obtained following a suggestion by Kloeden and Diamond ([3]) and defining $z=u \widetilde{\Theta}_{g} v$ to be the fuzzy number whose $\alpha$-cuts are as near as possible to the gH -differences $[u]_{\alpha} \Theta_{g}[v]_{\alpha}$, for example by minimizing the functional ( $\omega_{\alpha} \geq 0$ and $\gamma_{\alpha} \geq 0$ are weighting functions)

$$
G(z \mid u, v)=\int_{0}^{1}\left(\omega_{\alpha}\left[z_{\alpha}^{-}-\left(u \Theta_{g} v\right)_{\alpha}^{-}\right]^{2}+\gamma_{\alpha}\left[z_{\alpha}^{+}-\left(u \Theta_{g} v\right)_{\alpha}^{+}\right]^{2}\right) d \alpha
$$

such that $z_{\alpha}^{-} \uparrow, z_{\alpha}^{+} \downarrow, z_{\alpha}^{-} \leq z_{\alpha}^{+} \forall \alpha \in[0,1]$.
A discretized version of $G(z \mid u, v)$ can be obtained by choosing a partition $0=\alpha_{0}<\alpha_{1}<\ldots<\alpha_{N}=1$ of $[0,1]$ and defining the discretized $G(z \mid u, v)$ as

$$
G_{N}(z \mid u, v)=\sum_{i=0}^{N} \omega_{i}\left[z_{i}^{-}-\left(u \Theta_{g} v\right)_{i}^{-}\right]^{2}+\gamma_{i}\left[z_{i}^{+}-\left(u \Theta_{g} v\right)_{i}^{+}\right]^{2}
$$

we minimize $G_{N}(z \mid u, v)$ with the given data $\left(u \Theta_{g} v\right)_{i}^{-}=\min \left\{u_{\alpha_{i}}^{-}-v_{\alpha_{i}}^{-}, u_{\alpha_{i}}^{+}-v_{\alpha_{i}}^{+}\right\}$ and $\left(u \Theta_{g} v\right)_{i}^{+}=\max \left\{u_{\alpha_{i}}^{-}-v_{\alpha_{i}}^{-}, u_{\alpha_{i}}^{+}-v_{\alpha_{i}}^{+}\right\}$, subject to the constraints $z_{0}^{-} \leq z_{1}^{-} \leq$ $\ldots \leq z_{N}^{-} \leq z_{N}^{+} \leq z_{N-1}^{+} \leq \ldots \leq z_{0}^{+}$. We obtain a linearly constrained least squares minimization of the form

$$
\min _{z \in \mathbb{R}^{2 N+2}}(z-w)^{T} D^{2}(z-w) \text { s.t. } E z \geq 0
$$

where $z=\left(z_{0}^{-}, z_{1}^{-}, \ldots, z_{N}^{-}, z_{N}^{+}, z_{N-1}^{+}, \ldots, z_{0}^{+}\right), w_{i}^{-}=\left(u \Theta_{g} v\right)_{i}^{-}, w_{i}^{+}=\left(u \Theta_{g} v\right)_{i}^{+}$, $w=\left(w_{0}^{-}, w_{1}^{-}, \ldots, w_{N}^{-}, w_{N}^{+}, w_{N-1}^{+}, \ldots, w_{0}^{+}\right), D=\operatorname{diag}\left\{\sqrt{\omega_{0}}, \ldots, \sqrt{\omega_{N}}, \sqrt{\gamma_{N}}, \ldots, \sqrt{\gamma_{0}}\right\}$ and $E$ is the $(N, N+1)$ matrix

$$
E=\left[\begin{array}{llllll}
-1 & 1 & 0 & \ldots & \ldots & 0 \\
0 & -1 & 1 & 0 & \ldots & 0 \\
\ldots & \ldots & \ldots & \ldots & \ldots & \ldots \\
0 & 0 & \ldots & \ldots & -1 & 1
\end{array}\right]
$$

which can be solved by standard efficient procedures (see the classical book [6], ch. 23). If, at solution $z^{*}$, we have $z^{*}=w$, then we obtain the gH -difference as defined in (13).

## 4 Generalized division

An idea silmilar to the gH -difference can be used to introduce a division of real intervals and fuzzy numbers. We consider here only the case of real compact intervals $A=\left[a^{-}, a^{+}\right]$and $B=\left[b^{-}, b^{+}\right]$with $b^{-}>0$ or $b^{+}<0$ (i.e. $0 \notin B$ ).

The interval $C=\left[c^{-}, c^{+}\right]$defining the multiplication $C=A B$ is given by

$$
c^{-}=\min \left\{a^{-} b^{-}, a^{-} b^{+}, a^{+} b^{-}, a^{+} b^{+}\right\}, c^{+}=\max \left\{a^{-} b^{-}, a^{-} b^{+}, a^{+} b^{-}, a^{+} b^{+}\right\}
$$

and the multiplicative "inverse" (it is not the inverse in the algebraic sense) of an interval $B$ is defined by $B^{-1}=\left[\frac{1}{b^{+}}, \frac{1}{b^{-}}\right]$; we define the generalized division (g-division) $\div g$ as follows:

$$
A \div{ }_{g} B=C \Longleftrightarrow\left\{\begin{array}{c}
(i) A=B C \\
\text { or }(i i) B=A C^{-1} .
\end{array}\right.
$$

If both cases (i) and (ii) are valid, we have $C C^{-1}=C^{-1} C=\{1\}$, i.e. $C=\{\widehat{c}\}$, $C^{-1}=\left\{\frac{1}{\hat{c}}\right\}$ with $\widehat{c} \neq 0$. It is easy to see that $A \div{ }_{g} B$ always exists and is unique for given $A=\left[a^{-}, a^{+}\right]$and $B=\left[b^{-}, b^{+}\right]$with $0 \notin B$. It is easy to see that it can be obtained by the following rules:

Case 1. If $\left(a^{-} \leq a^{+}<0\right.$ and $\left.b^{-} \leq b^{+}<0\right)$ or $\left(0<a^{-} \leq a^{+}\right.$and $\left.0<b^{-} \leq b^{+}\right)$then

$$
c^{-}=\min \left\{\frac{a^{-}}{b^{-}}, \frac{a^{+}}{b^{+}}\right\} \geq 0, c^{+}=\max \left\{\frac{a^{-}}{b^{-}}, \frac{a^{+}}{b^{+}}\right\} \geq 0
$$

Case 2. If $\left(a^{-} \leq a^{+}<0\right.$ and $\left.0<b^{-} \leq b^{+}\right)$or $\left(0<a^{-} \leq a^{+}\right.$and $b^{-} \leq b^{+}<0$ ) then

$$
c^{-}=\min \left\{\frac{a^{-}}{b^{+}}, \frac{a^{+}}{b^{-}}\right\} \leq 0, c^{+}=\max \left\{\frac{a^{-}}{b^{+}}, \frac{a^{+}}{b^{-}}\right\} \leq 0
$$

Case 3. If $\left(a^{-} \leq 0, a^{+} \geq 0\right.$ and $\left.b^{-} \leq b^{+}<0\right)$ then

$$
c^{-}=\frac{a^{-}}{b^{-}} \leq 0, \quad c^{+}=\frac{a^{+}}{b^{-}} \geq 0
$$

Case 4. If $\left(a^{-} \leq 0, a^{+} \geq 0\right.$ and $\left.0<b^{-} \leq b^{+}\right)$then

$$
c^{-}=\frac{a^{-}}{b^{+}} \leq 0, \quad c^{+}=\frac{a^{+}}{b^{+}} \geq 0
$$

Remark 5. If $0 \in] b^{-}, b^{+}$[ the g-division is undefined; for intervals $B=\left[0, b^{+}\right]$or $B=\left[b^{-}, 0\right]$ the division is possible but obtaining unbounded results $C$ of the form $\left.C=]-\infty, c^{+}\right]$or $C=\left[c^{-},+\infty\left[\right.\right.$ : we work with $B=\left[\varepsilon, b^{+}\right]$or $B=\left[b^{-}, \varepsilon\right]$ and we obtain the result by the limit for $\varepsilon \longrightarrow 0^{+}$. Example: for $[-2,-1] \div g[0,3]$ we consider $[-2,-1] \div{ }_{g}[\varepsilon, 3]=\left[c_{\varepsilon}^{-}, c_{\varepsilon}^{+}\right]$with (case 2.) $c_{\varepsilon}^{-}=\min \left\{\frac{-2}{3}, \frac{-1}{\varepsilon}\right\}$ and $c_{\varepsilon}^{+}=\max \left\{\frac{-2}{\varepsilon}, \frac{-1}{3}\right\}$ and obtain the result $C=\left[-\infty,-\frac{1}{3}\right]$ at the limit $\varepsilon \xrightarrow{\varepsilon} 0^{+}$.

The following properties are immediate.
Proposition 7. For any $A=\left[a^{-}, a^{+}\right]$and $B=\left[b^{-}, b^{+}\right]$with $0 \notin B$, we have (here 1 is the same as $\{1\}$ ):

1. $B \div{ }_{g} B=1, B \div{ }_{g} B^{-1}=\left\{b^{-} b^{+}\right\}\left(=\left\{\widehat{b}^{2}\right\}\right.$ if $\left.b^{-}=b^{+}=\widehat{b}\right)$;
2. $(A B) \div{ }_{g} B=A$;
3. $1 \div{ }_{g} B=B^{-1}$ and $1 \div{ }_{g} B^{-1}=B$.

In the case of fuzzy numbers $u, v \in \mathcal{F}$ having membership functions $\mu_{u}, \mu_{v}$ and $\alpha$-cuts $[u]_{\alpha}=\left[u_{\alpha}^{-}, u_{\alpha}^{+}\right],[v]_{\alpha}=\left[v_{\alpha}^{-}, v_{\alpha}^{+}\right], 0 \notin[v]_{\alpha} \forall \alpha \in[0,1]$, the $g$-division $\div{ }_{g}$ can be defined as the operation that calculates the fuzzy number $w=u \div{ }_{g} v \in$ $\dot{\mathcal{F}}$ having level cuts $[w]_{\alpha}=\left[w_{\alpha}^{-}, w_{\alpha}^{+}\right]\left(\right.$here $\left.[w]_{\alpha}^{-1}=\left[\frac{1}{w_{\alpha}^{+}}, \frac{1}{w_{\alpha}^{-}}\right]\right)$:

$$
[u]_{\alpha} \div{ }_{g}[v]_{\alpha}=[w]_{\alpha} \Longleftrightarrow\left\{\begin{array}{c}
\text { (i) }[u]_{\alpha}=[v]_{\alpha}[w]_{\alpha} \\
\text { or (ii) }[v]_{\alpha}=[u]_{\alpha}[w]_{\alpha}^{-1}
\end{array}\right.
$$

provided that $w$ is a proper fuzzy number.

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