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A Mechanism of Inflation Differentials and Current Account Imbalances in the Euro Area

Taiji Harashima*

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Abstract

This paper examines the mechanism of persistent inflation differentials, current account imbalances, and fiscal deficits in the euro area by constructing a multi-country model in which the optimization behaviors of governments as well as those of households, firms, and the European Central Bank are explicitly incorporated. The model indicates that governments can temporarily adhere to their own intrinsic preferences because fiscal policies are not unified in the euro area. This behavior generates problems, such as inflation differentials, and the stability and growth pact does not appear to be sufficiently effective in preventing such deviations. The results in this paper imply that the balance between national sovereignty and economic stability should be shifted more to the side of stability and that the euro area has to become more politically unified. In addition, the inflation differentials provide clear evidence that inflation acceleration is not caused by monetary policies but by government behavior because monetary policies are unified in the euro area whereas fiscal policies are not.

JEL Classification code: E58, E63, F33, N14, O52

Keywords: The euro; Monetary union; Inflation; Inflation differential; Current account imbalance; Fiscal deficit; Time preference; The European Central Bank; The stability and growth pact

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1. INTRODUCTION

The Greek financial crisis in 2010 intensified concerns that the euro is seriously flawed and reignited the dispute about the feasibility of a euro-type monetary union. Often mentioned problems, such as persistent inflation differentials, current account imbalances, and the violation of fiscal rules, portended the crisis. National inflation rates of the member states have diverged over the last decade and non-negligible inflation differentials have continued (ECB, 2003; Angeloni and Ehrmann, 2007; Gregoriou et al., 2011). The inflation differentials in the euro area have been far more substantial and persistent than those among the states of the U.S. (Angeloni and Ehrmann, 2007; Fendel and Frenkel, 2009). In addition, asymmetry in current account balances between northern members (e.g., Austria, Finland, Germany, and the Netherlands) and southern members (e.g., Greece, Ireland, Portugal, and Spain) have persisted (Gros et al., 2005; de Grauwe, 2009; Decressin and Stavrev, 2009; EC, 2009; Holinskia et al., 2010; Jaumotte and Sodsriwiboon, 2010). The northern members' current accounts have shown surpluses, whereas those of the southern members have shown deficits. The current account imbalances have been substantial, and they persisted and deteriorated until the wake of the financial crisis, after which there were signs of a temporary reversal of the trend (Gros et al., 2005; Decressin and Stavrev, 2009; de Grauwe, 2009). In addition, the 3% fiscal deficit cap has been violated by many member governments (ECB, 2007, 2008b), particularly Greece, France, Italy, and Portugal (ECB, 2008b).

Inflation differentials in the euro area basically originate in the prices of non-tradable goods and services (ECB, 2005; Žďárek and Aldasoro, 2009; Zemanek et al., 2010), and the non-tradable sector contributes to substantial unit-labor-cost differentials between the member countries (Zemanek et al., 2010). These observations indicate that competitiveness differentials within the euro area exist, and those differentials will lead to intra-euro area current account imbalances (Blanchard, 2007; Arghyrou and Chortareas, 2008; EC, 2009). Without full labor market flexibility, heterogeneous competitiveness results in large-scale and persistent current account deficits in relatively less competitive member states and surpluses in more competitive ones (Blanchard and Giavazzi, 2002; Blanchard, 2007; EC, 2009). Diversified prices of non-tradable goods and services makes the Balassa–Samuelson effect a compelling explanation for the observed inflation differentials (Samuelson, 1994), but most empirical studies estimate that the Balassa–Samuelson effect is small (Coudert, 2004; Égert et al, 2006; Mihaljek and Klau, 2008; Égert, 2010). Hence, many other potential mechanisms have been examined as the explanation for inflation differentials. For example, demand or potential output shocks as well as cost-push and exchange rate shocks (Angeloni and Ehrmann, 2007), fluctuations in the effective exchange rate (Hofmann and Remsperger, 2005), and asymmetric productivity shocks (Altissimo et al., 2005) have been proposed as the main source of inflation differentials (see also Honohan and Lane, 2003; Altissimo et al., 2005; Hofmann and Remsperger, 2005; Fendel and Frenkel, 2009; Žďárek and Aldasoro, 2009). However, at present there is no consensus on the mechanism of inflation differentials.

Since its creation, the euro has been criticized for lacking a unified fiscal authority (e.g., ECB, 2008a). Intuitively, the lack of a unified fiscal authority (i.e., the lack of a federal government) is a serious problem that could generate substantial negative effects, most likely including problems such as inflation differentials. However, these problems as well as the mechanisms by which they are generated have not been sufficiently explored theoretically, in part because most models used to analyze the euro area economy do not explicitly deal with the optimization behavior of government. If the behavior of government is not explicitly modeled, it will be impossible to show why and how the lack of a federal government causes problems. The financial crisis suggests that some member governments took profligate actions that appear to be irrational, but without a model that describes the behavior of government, it is difficult to determine why such actions were taken.

To unravel the mechanism of problems such as inflation differentials, therefore, a model that explicitly describes the behavior of government as well as those of households, firms, and the central bank is needed. In this paper, such a model is constructed. In particular, the government and the central bank are treated as different entities, and their behaviors are clearly separated in the model. The model shows that inflation accelerates if the time preference rate of government is higher than that of the representative household. To stabilize inflation, therefore, the government's time preference rate needs to be controlled by delegating monetary policies to an independent central bank. The model in this paper indicates that if there is more than one government but only one central bank (as is the case with the euro area), the central bank cannot sufficiently control the time preference rate of each member government. Thus, inflation differentials can be generated, and accordingly, current account imbalances are widened and fiscal balances are governed by complex non-linear processes. All of the model's predictions are basically consistent with the abovementioned facts about the euro area economy.

An important result obtained is that the euro area needs to become more politically unified. The model indicates that the problems are generated not because the member governments are stupid, foolish, or irrational; rather they act quite rationally. The governments follow their own preferences, and the temptation to do so is so strong that the governments seek to exploit weaknesses in the structure of the euro. One such weakness is that the European Central Bank (ECB) cannot implement monetary policies aimed separately and specifically at each member state. By exploiting this weakness, governments can behave based on their own intrinsic time preferences. The stability and growth pact (SGP) was enacted to fix this flaw but it does not appear to have been sufficiently effective, and an alternative mechanism that controls each government's preference is required.

In addition, the examination using the model presented in this paper makes an important contribution to the theory of inflation. The observed inflation differentials in the euro area provide clear evidence that inflation acceleration is not caused by monetary policies but by government behavior because inflation rates in the member states have diverged even though the monetary policies are unified.

The paper is organized as follows. In Section 2, a single-country model is constructed in which the optimization behaviors of government as well as those of households, firms, and the central bank are explicitly incorporated. This model is extended to a multi-country model in Section 3. With the extended multi-country model, the euro's flaw is examined in Section 4. Concluding remarks are offered in Section 5.

2 THE SINGLE-COUNTRY MODEL

The single-country model is based on the model of inflation by Harashima (2008). The single-country model will be extended to a multi-country model in Section 3.

2.1 *The optimal trend inflation*

2.1.1 The government

2.1.1.1 The government budget constraint

The government budget constraint is

$$\dot{B}_t = B_t i_t + G_t - X_t - \mathcal{Q}_t ,$$

where B_t is the nominal obligation of the government to pay for its accumulated bonds, i_t is the nominal interest rate for government bonds, G_t is the nominal government expenditure, X_t is the nominal tax revenue, and \mathcal{Q}_t is the nominal amount of seigniorage at time t . The tax is assumed

to be lump sum, the government bonds are long term, and the returns on the bonds are realized only after the bonds are held during a unit period (e.g., a year). The government bonds are redeemed in a unit period, and the government successively refines the bonds by issuing new ones at each time t . Let $b_t = \frac{B_t}{P_t}$, $g_t = \frac{G_t}{P_t}$, $x_t = \frac{X_t}{P_t}$, and $\varphi_t = \frac{\varrho_t}{P_t}$, where P_t is the price level at time t . Let also $\pi_t = \frac{\dot{P}_t}{P_t}$ be the inflation rate at time t . By dividing by P_t , the budget constraint is transformed to $\frac{\dot{B}_t}{P_t} = b_t i_t + g_t - x_t - \varphi_t$, which is equivalent to

$$\dot{b}_t = b_t i_t + g_t - x_t - \varphi_t - b_t \pi_t = b_t (i_t - \pi_t) + g_t - x_t - \varphi_t . \quad (1)$$

Because the returns on government bonds are realized only after holding the bonds during a unit period, investors buy the bonds if $\bar{i}_t \geq E_t \int_t^{t+1} (\pi_s + r_t) ds$ at time t , where \bar{i}_t is the nominal interest rate for bonds bought at t and r_t is the real interest rate in markets at t . Hence, by arbitrage, $\bar{i}_t = E_t \int_t^{t+1} (\pi_s + r_t) ds$ and if r_t is constant such that $r_t = r$ (i.e., if it is at steady state), then

$$\bar{i}_t = E_t \int_t^{t+1} \pi_s ds + r .$$

The nominal interest rate $\bar{i}_t = E_t \int_t^{t+1} \pi_s ds + r$ means that, during a sufficiently small period between t and $t + dt$, the government's obligation to pay for the bonds' return in the future increases not by $dt(\pi_t + r)$ but by $dt \left(E_t \int_t^{t+1} \pi_s ds + r \right)$. If π_t is constant, then $E_t \int_t^{t+1} \pi_s ds = \pi_t$ and $\bar{i}_t = \pi_t + r$, but if π_t is not constant, these equations do not necessarily hold.

Since bonds are redeemed in a unit period and successively refinanced, the bonds the government is holding at t have been issued between $t - 1$ and t . Hence, under perfect foresight, the average nominal interest rate for all government bonds at time t is the weighted sum of \bar{i}_t such that

$$i_t = \int_{t-1}^t \bar{i}_s \left(\frac{\overline{B}_{s,t}}{\int_{t-1}^t \overline{B}_{v,t} dv} \right) ds = \int_{t-1}^t \int_s^{s+1} \pi_v dv \left(\frac{\overline{B}_{s,t}}{\int_{t-1}^t \overline{B}_{v,t} dv} \right) ds + r ,$$

where $\overline{B}_{s,t}$ is the nominal value of bonds at time t that were issued at time s . If the weights $\frac{\overline{B}_{s,t}}{\int_{t-1}^t \overline{B}_{v,t} dv}$ between $t - 1$ and t are not so different from each other, then approximately $i_t = \int_{t-1}^t \int_s^{s+1} \pi_v dv ds + r$. To be precise, if the absolute values of π_s for $t-1 < s \leq t+1$ are sufficiently smaller than unity, the differences among the weights are negligible and then approximately

$$i_t = \int_{t-1}^t \int_s^{s+1} \pi_v dv ds + r \quad (2)$$

(see Harashima, 2008). The average nominal interest rate for the total government bonds, therefore, develops by $i_t = \int_{t-1}^t \int_s^{s+1} \pi_v dv ds + r$. If π_t is constant, then $\int_{t-1}^t \int_s^{s+1} \pi_v dv ds = \pi_t$; thus, $i_t = \pi_t + r$. If π_t is not constant, however, the equations $\int_{t-1}^t \int_s^{s+1} \pi_v dv ds = \pi_t$ and $i_t = \pi_t + r$ do not necessarily hold.

2.1.1.2 An economically Leviathan government

Under a proportional representation system, the government represents the median household whereas the representative household from an economic perspective represents the mean household.¹ Because of this difference, they usually have different preferences. To account for this essential difference, a Leviathan government is assumed in the model.² There are two extremely different views regarding government's behavior in the literature on political economy: the Leviathan view and the benevolent view (e.g., Downs 1957; Brennan and Buchanan 1980; Alesina and Cukierman 1990). From an economic point of view, a benevolent government maximizes the expected economic utility of the representative household, but a Leviathan government does not. Whereas the expenditure of a benevolent government is a tool used to maximize the economic utility of the representative household, the expenditure of a Leviathan government is a tool used to achieve the government's own policy objectives.³ For example, if a Leviathan government considers national security to be the most important political issue, defense spending will increase greatly, but if improving social welfare is the top political priority, spending on social welfare will increase dramatically, even though the increased expenditures may not necessarily increase the economic utility of the representative household.

Is it possible, however, for such a Leviathan government to hold office for a long period? Yes, because a government is generally chosen by the median of households under a proportional representation system (e.g., Downs 1957), whereas the representative household usually presumed in the economics literature is the mean household. The economically representative household is not usually identical to the politically representative household, and a majority of people could support a Leviathan government even if they know that the government does not necessarily pursue only the economic objectives of the economically representative household. In other words, the Leviathan government argued here is an economically Leviathan government that maximizes the political utility of people, whereas the conventional economically benevolent government maximizes the economic utility of people. In addition, because the politically and economically representative households are different (the median and mean households, respectively), the preferences of future governments will also be similarly different from those of the mean representative household. In this sense, the current and future governments presented in the model can be seen as a combined government that goes on indefinitely; that is, the economically Leviathan government always represents the median representative household.

The Leviathan view generally requires the explicit inclusion of government

¹ See the literature on the median voter theorem (e.g., Downs 1957). Also see the literature on the delay in reforms (e.g., Alesina and Drazen 1991; Cukierman et al. 1992).

² The most prominent reference to Leviathan governments is Brennan and Buchanan (1980).

³ The government behavior assumed in the fiscal theory of the price level reflects an aspect of a Leviathan government. Christiano and Fitzgerald (2000) argue that non-Ricardian policies correspond to the type of policies in which governments are viewed as selecting policies and committing themselves to those policies in advance of prices being determined in markets.

expenditure, tax revenue, or related activities in the government's political utility function (e.g., Edwards and Keen 1996). Because an economically Leviathan government derives political utility from expenditure for its political purposes, the larger the expenditure is, the happier the Leviathan government will be. But raising tax rates will provoke people's antipathy, which increases the probability of being replaced by the opposing party that also nearly represents the median household. Thus, the economically Leviathan government regards taxes as necessary costs to obtain freedom of expenditure for its own purposes. The government therefore will derive utility from expenditure and disutility from taxes. Expenditure and taxes in the political utility function of the government are analogous to consumption and labor hours in the economic utility function of the representative household. Consumption and labor hours are both control variables, and as such, the government's expenditure and tax revenue are also control variables. As a whole, the political utility function of economically Leviathan government can be expressed as $u_G(g_t, x_t)$.⁴ In addition, it can be assumed on the basis of previously mentioned arguments that $\frac{\partial u_G}{\partial g_t} > 0$ and $\frac{\partial^2 u_G}{\partial g_t^2} < 0$, and therefore that $\frac{\partial u_G}{\partial x_t} < 0$

and $\frac{\partial^2 u_G}{\partial x_t^2} > 0$.⁵ An economically Leviathan government therefore maximizes the expected sum of these utilities discounted by its time preference rate under the constraint of deficit financing.

2.1.1.3 The optimization problem

The optimization problem of an economically Leviathan government is

$$\text{Max } E \int_0^{\infty} u_G(g_t, x_t) \exp(-\theta_G t) dt$$

subject to the budget constraint

$$\dot{b}_t = b_t(i_t - \pi_t) + g_t - x_t - \varphi_t, \quad (3)$$

where u_G is the constant relative risk aversion utility function of the government, θ_G is the government's rate of time preference, and E is the expectation operator. All variables are expressed in per capita terms, and population is assumed to be constant. The government maximizes its expected political utility considering the behavior of the economically representative household that is reflected in i_t in its budget constraint.

2.1.2 Households

The economically representative household maximizes its expected economic utility. Sidrauski (1967)'s well-known money in the utility function model is used for the optimization problem.

⁴ It is possible to assume that governments are partially benevolent. In this case, the utility function of a government can be assumed to be $u_G(g_t, x_t, c_t, l_t)$, where c_t is real consumption and l_t is the leisure hours of the representative household. However, if a lump-sum tax is imposed, the government's policies do not affect steady-state consumption and leisure hours. In this case, the utility function can be assumed to be $u_G(g_t, x_t)$.

⁵ Some may argue that it is more likely that $\frac{\partial u_G}{\partial x_t} > 0$ and $\frac{\partial^2 u_G}{\partial x_t^2} < 0$. However, the assumption used is not an

important issue here because $-x_t \left[\frac{\partial u_G(g_t, x_t)}{\partial x_t} \right]^{-1} \frac{\partial^2 u_G(g_t, x_t)}{\partial x_t^2} \dot{x}_t = 0$ at steady state, as will be shown in the solution to the optimization problem later in the paper. Thus, the results are not affected by which assumption is used.

The representative household maximizes its expected utility

$$E \int_0^{\infty} u_p(c_t, m_t) \exp(-\theta_p t) dt$$

subject to the budget constraint

$$\dot{a}_t = (r_t a_t + w_t + \sigma_t) - [c_t + (\pi_t + r_t)m_t] - g_t ,$$

where u_p and θ_p are the utility function and the time preference rate of the representative household, c_t is real consumption, w_t is real wage, σ_t is lump-sum real government transfers, m_t is real money, $a_t = k_t + m_t$, and k_t is real capital. It is assumed that $r_t = f'(k_t)$, $w_t = f(k_t) - k_t f'(k_t)$, $u_p' > 0$, $u_p'' < 0$, $\frac{\partial u_p(c_t, m_t)}{\partial m_t} > 0$, and $\frac{\partial^2 u_p(c_t, m_t)}{\partial m_t^2} < 0$, where $f(\cdot)$ is the

production function. Government expenditure (g_t) is an exogenous variable for the representative household because it is an economically Leviathan government. It is also assumed that, although all households receive transfers from a government in equilibrium, when making decisions, each household takes the amount it receives as given, independent of its money holdings. Thus, the budget constraint means that the real output $f(k_t)$ at any time is demanded for the real consumption c_t , the real investment \dot{k}_t , and the real government expenditure g_t such that $f(k_t) = c_t + \dot{k}_t + g_t$. The representative household maximizes its expected economic utility considering the behavior of government reflected in g_t in the budget constraint. In this discussion, a central bank is not assumed to be independent of the government; thus, the functions of the government and the central bank are not separated. This assumption can be relaxed, and the roles of the government and the central bank are explicitly separated in Section 2.2.

Note that the time preference rate of government (θ_G) is not necessarily identical to that of the representative household (θ_p) because the government and the representative household represent different households (i.e., the median and mean households, respectively). In addition, the preferences will differ because (1) even though people want to choose a government that has the same time preference rate as the representative household, the rates may differ owing to errors in expectations (e.g., Alesina and Cukierman 1990); and (2) current voters cannot bind the choices of future voters and, if current voters are aware of this possibility, they may vote more myopically as compared with their own rates of impatience in private economic activities (e.g., Tabellini and Alesina 1990). Hence, it is highly likely that the time preference rates of a government and the representative household are heterogeneous. It should be also noted, however, that even though the rates of time preference are heterogeneous, an economically Leviathan government behaves based only on its own time preference rate, without hesitation.

2.1.3 The simultaneous optimization

First, I examine the optimization problem of the representative household. Let Hamiltonian H_p be $H_p = u_p(c_t, m_t) \exp(-\theta_p t) + \lambda_{p,t} [r_t a_t + w_t + \sigma_t - c_t - (\pi_t + r_t)m_t - g_t]$, where $\lambda_{p,t}$ is a costate variable, c_t and m_t are control variables, and a_t is a state variable. The optimality conditions for the representative household are;

$$\frac{\partial u_p(c_t, m_t)}{\partial c_t} \exp(-\theta_p t) = \lambda_{p,t} , \quad (4)$$

$$\frac{\partial u_p(c_t, m_t)}{\partial m_t} \exp(-\theta_p t) = \lambda_{p,t} (\pi_t + r_t) , \quad (5)$$

$$\dot{\lambda}_{p,t} = -\lambda_{p,t} r_t , \quad (6)$$

$$\dot{a}_t = (ra_t + w_t + \sigma_t) - [c_t + (\pi_t + r_t)m_t - g_t] , \quad (7)$$

$$\lim_{t \rightarrow \infty} \lambda_{p,t} a_t = 0 . \quad (8)$$

By conditions (4) and (5), $\left[\frac{\partial u_p(c_t, m_t)}{\partial c_t} \right]^{-1} \frac{\partial u_p(c_t, m_t)}{\partial m_t} = \pi_t + r_t$, and by conditions (4) and (6),

$$-c_t \left[\frac{\partial u_p(c_t, m_t)}{\partial c_t} \right]^{-1} \frac{\partial^2 u_p(c_t, m_t)}{\partial c_t^2} \frac{\dot{c}_t}{c_t} + \theta_p = r_t . \quad (9)$$

Hence,

$$\theta_p = r_t = r \quad (10)$$

at steady state such that $\dot{c}_t = 0$ and $\dot{k}_t = 0$.

Next, I examine the optimization problem of the economically Leviathan government. Let Hamiltonian H_G be $H_G = u_G(g_t, x_t) \exp(-\theta_G t) + \lambda_{G,t} [b_t(i_t - \pi_t) + g_t - x_t - \varphi_t]$, where $\lambda_{G,t}$ is a costate variable. The optimality conditions for the government are;

$$\frac{\partial u_G(g_t, x_t)}{\partial g_t} \exp(-\theta_G t) = -\lambda_{G,t} , \quad (11)$$

$$\frac{\partial u_G(g_t, x_t)}{\partial x_t} \exp(-\theta_G t) = \lambda_{G,t} , \quad (12)$$

$$\dot{\lambda}_{G,t} = -\lambda_{G,t} (i_t - \pi_t) , \quad (13)$$

$$\dot{b}_t = b_t(i_t - \pi_t) + g_t - x_t - \varphi_t , \quad (14)$$

$$\lim_{t \rightarrow \infty} \lambda_{G,t} b_t = 0 . \quad (15)$$

Combining conditions (11), (12), and (13) and equation (2) yields the following equations:

$$-g_t \left[\frac{\partial u_G(g_t, x_t)}{\partial g_t} \right]^{-1} \frac{\partial^2 u_G(g_t, x_t)}{\partial g_t^2} \frac{\dot{g}_t}{g_t} + \theta_G = i_t - \pi_t = r_t + \int_{t-1}^t \int_s^{s+1} \pi_v dv ds - \pi_t \quad (16)$$

and

$$-x_t \left[\frac{\partial u_G(g_t, x_t)}{\partial x_t} \right]^{-1} \frac{\partial^2 u_G(g_t, x_t)}{\partial x_t^2} \frac{\dot{x}_t}{x_t} + \theta_G = i_t - \pi_t = r_t + \int_{t-1}^t \int_s^{s+1} \pi_v dv ds - \pi_t . \quad (17)$$

Here, $g_t \left[\frac{\partial u_G(g_t, x_t)}{\partial g_t} \right]^{-1} \frac{\partial^2 u_G(g_t, x_t)}{\partial g_t^2} \frac{\dot{g}_t}{g_t} = 0$ and $x_t \left[\frac{\partial u_G(g_t, x_t)}{\partial x_t} \right]^{-1} \frac{\partial^2 u_G(g_t, x_t)}{\partial x_t^2} \frac{\dot{x}_t}{x_t} = 0$ at steady state such that $\dot{g}_t = 0$ and $\dot{x}_t = 0$; thus,

$$\theta_G = r_t + \int_{t-1}^t \int_s^{s+1} \pi_v dv ds - \pi_t . \quad (18)$$

Hence, by equation (10),

$$\int_{t-1}^t \int_s^{s+1} \pi_v dv ds = \pi_t + \theta_G - \theta_P \quad (19)$$

at steady state such that $\dot{g}_t = 0$, $\dot{x}_t = 0$, $\dot{c}_t = 0$, and $\dot{k}_t = 0$.⁶

Equation (19) is a natural consequence of simultaneous optimization by the economically Leviathan government and the representative household. If the rates of time preference are heterogeneous between them, then

$$i_t - r = \int_{t-1}^t \int_s^{s+1} \pi_v dv ds \neq \pi_t .$$

This result might seem surprising because it has been naturally conjectured that $i_t = \pi_t + r$. However, this is a simple misunderstanding because π_t indicates the instantaneous rate of inflation at a point such that $\pi_t = \frac{\dot{P}_t}{P_t}$, whereas $\int_{t-1}^t \int_s^{s+1} \pi_v dv ds$ roughly indicates the average inflation rate in a period. Equation (19) indicates that π_t develops according to the integral equation $\pi_t = \int_{t-1}^t \int_s^{s+1} \pi_v dv ds - \theta_G + \theta_P$. If π_t is constant, the equations $i_t = \pi_t + r$ and $\int_{t-1}^t \int_s^{s+1} \pi_v dv ds = \pi_t$ are true. However, if π_t is not constant, the equations do not necessarily hold. Equation (19) indicates that the equations $i_t = \pi_t + r$ and $\int_{t-1}^t \int_s^{s+1} \pi_v dv ds = \pi_t$ hold only in the case where $\theta_G = \theta_P$ (i.e., a homogeneous rate of time preference). It has been previously thought that a homogeneous rate of time preference naturally prevails; thus, the equation $i_t = \pi_t + r$ has not been questioned. As argued previously, however, a homogeneous rate of time preference is not usually guaranteed.

2.1.4 The law of motion for trend inflation

Equation (19) indicates that inflation accelerates or decelerates as a result of the government and the representative household reconciling the contradiction in heterogeneous rates of time

⁶ If and only if $\theta_G = -\frac{g_t - x_t - \phi_t}{b_t}$ at steady state, then the transversality condition (15) $\lim_{t \rightarrow \infty} \lambda_{G,t} b_t = 0$ holds.

The proof is shown in Harashima (2008).

preference. If π_t is constant, the equation $\pi_t = \int_{t-1}^t \int_s^{s+1} \pi_v dv ds$ holds; conversely, if $\pi_t \neq \int_{t-1}^t \int_s^{s+1} \pi_v dv ds$, then π_t is not constant. Without the acceleration or deceleration of inflation, therefore, equation (19) cannot hold in an economy in which $\theta_G \neq \theta_P$. In other words, it is not until $\theta_G \neq \theta_P$ that inflation can accelerate or decelerate. Heterogeneous time preferences ($\theta_G \neq \theta_P$) bend the path of inflation and enables inflation to accelerate or decelerate. The difference of time preference rates ($\theta_G - \theta_P$) at each time needs to be transformed to the accelerated or decelerated inflation rate π_t at each time.

Equation (19) implies that inflation accelerates or decelerates nonlinearly in the case in which $\theta_G \neq \theta_P$. For a sufficiently small period dt , π_{t+dt} is determined with π_s ($t-1 < s \leq t+1$) that satisfies $\int_{t-1}^t \int_s^{s+1} \pi_v dv ds - \pi_t = \theta_G - \theta_P$, so as to hold the equation $\int_t^{t+dt} \int_s^{s+1} \pi_v dv ds = \int_{t-1}^{t-1+dt} \int_s^{s+1} \pi_v dv ds + \pi_{t+dt} - \pi_t$. A solution of the integral equation (19) for given θ_G and θ_P is

$$\pi_t = \pi_0 + 6(\theta_G - \theta_P)t^2 . \quad (20)$$

Generally, the path of inflation that satisfies equation (19) for $0 \leq t$ is expressed as

$$\pi_t = \pi_0 + 6(\theta_G - \theta_P)\exp[z_t \ln(t)] ,$$

where z_t is a time dependent variable. The stream of z_t is various depending on the boundary condition, i.e., the past and present inflation during $-1 < t \leq 0$ and the path of inflation during $0 < t \leq 1$ that is set to make π_0 satisfy equation (19). However, z_t has the following important property. If π_t satisfies equation (19) for $0 \leq t$, and $-\infty < \pi_t < \infty$ for $-1 < t \leq 1$, then

$$\lim_{t \rightarrow \infty} z_t = 2 .$$

Proof is shown in Harashima (2008). Any inflation path that satisfies equation (19) for $0 \leq t$ therefore asymptotically approaches the path of equation (20). The mechanism behind the law of motion for inflation (equation [20]) is examined more in detail in Harashima (2008).

2.2 The central bank

A central bank manipulates the nominal interest rate according to the following Taylor-type instrument rule in the model;

$$i_t = \bar{y} + \gamma_\pi (\pi_t - \pi^*) + \gamma_x x_t , \quad (21)$$

where π^* is the target rate of inflation and \bar{y} , γ_π , and γ_x are constant coefficients. $\bar{y} = \pi^* + r$ as is usually assumed.

In Section 2.1, central banks are not explicitly considered because they are not assumed to be independent of governments. However, in actuality, central banks are independent organizations in most countries even though some of them are not sufficiently independent. Furthermore, in the conventional inflation model, it is the central banks that control inflation and governments have no role in controlling inflation. Conventional inflation

models show that the rate of inflation basically converges at the target rate of inflation set by a central bank. The target rate of inflation therefore is the key exogenous variable that determines the path of inflation in these models.

Both the government and the central bank can probably affect the development of inflation, but they would do so in different manners, as equation (20) and conventional inflation models indicate. However, the objectives of the government and the central bank may not be the same. For example, if trend inflation is added to conventional models by replacing their aggregate supply equations with equation (20), inflation cannot necessarily converge at the target rate of inflation because another key exogenous variable (θ_G) is included in the models. A government makes inflation develop consistently with the equation (20), which implies that inflation will not necessarily converge at the target rate of inflation. Conversely, a central bank makes inflation converge at the target rate of inflation, which implies that inflation will not necessarily develop consistently with equation (20). That is, unless either θ_G is adjusted to be consistent with the target rate of inflation or the target rate of inflation is adjusted to be consistent with θ_G , the path of inflation cannot necessarily be determined. Either θ_G or the target rate of inflation need be an endogenous variable. If a central bank dominates, the target rate of inflation remains as the key exogenous variable and θ_G should then be an endogenous variable. The reverse is also true.

A central bank will be regarded as truly independent if θ_G is forced to be adjusted to the one that is consistent with the target rate of inflation set by the central bank. For example, suppose that $\theta_G > \theta_p$ and a truly independent central bank manipulates the nominal interest rate according to the Taylor-type instrument rule (equation [21]). Here,

$$i_t = \int_{t-1}^t \int_s^{s+1} \pi_v dv ds + r = \theta_G + \pi_t \quad (22)$$

at steady state such that $\dot{g}_t = 0$, $\dot{x}_t = 0$, $\dot{c}_t = 0$, and $\dot{k}_t = 0$ by equations (2), (10), and (19). If the accelerating inflation rate is higher than the target rate of inflation, the central bank can raise the nominal interest rate from $i_t = \theta_G + \pi_t$ (equation [22]) to

$$i_t = \theta_G + \pi_t + \psi$$

by positive ψ by intervening in financial markets to lower the accelerating rate of inflation. In this case, the central bank keeps the initial target rate of inflation because it is truly independent. The government thus faces a rate of increase of real obligation that is higher than θ_G by the extra rate ψ .⁷ If the government lowers θ_G so that $\theta_G < \theta_p$ and inflation stops accelerating, the central bank will accordingly reduce the extra rate ψ . If, however, the government does not accommodate θ_G to the target rate of inflation, the extra rate ψ will increase as time passes because of the gap between the accelerating inflation rate and the target rate of inflation widens by equation (20) and γ_x in Taylor-type instrument rules is usually larger than unity, say 1.5. Because of the extra rate ψ , the government has no other way to achieve optimization unless it lowers θ_G to one that is consistent with the target rate of inflation. Once the government recognizes that the central bank is firmly determined to be independent and it is in vain to try to intervene in the central bank's decision makings, the government would not dare to attempt to raise θ_G again anymore.

Equation (20) implies that a government allows inflation to accelerate because it acts

⁷ The extra rate ψ affects not only the behavior of government but also that of the representative household, in which the conventional inflation theory is particularly interested. In this sense, the central bank's instrument rule that concerns and simultaneously affects both behaviors of the government and the representative household is particularly important for price stability.

to maximize its expected utility based only on its own preferences. A government is hardly the only entity that cannot easily control its own preferences even when these preferences may result in unfavorable consequences. It may not even be possible to manipulate one's own preferences at will. Thus, even though a government is fully rational and is not weak, foolish, or untruthful, it is difficult for it to self-regulate its preferences. Hence, an independent neutral organization is needed to help control θ_G . Delegating the authority to set and keep the target rate of inflation to an independent central bank is a way to control θ_G . The delegated independent central bank will control θ_G because it is not the central bank's preference to stabilize the price level—it is simply a duty delegated to it. An independent central bank is not the only possible choice. For example, pegging the local currency with a foreign currency can be seen as a kind of delegation to an independent neutral organization. In addition, the gold standard that prevailed before World War II can be also seen as a type of such delegation.

Note also that the delegation may not be viewed as bad from the Leviathan government's point of view because only its rate of time preference is changed, and the government can still pursue its political objectives. One criticism of the argument that central banks should be independent (e.g., Blinder 1998) is that, since the time-inconsistency problem argued in Kydland and Prescott (1977) or Barro and Gordon (1983) is more acute with fiscal policy, why is it not also necessary to delegate fiscal policies? An economically Leviathan government, however, will never allow fiscal policies to be delegated to an independent neutral organization because the Leviathan government would then not be able to pursue its political objectives, which in a sense would mean the death of the Leviathan government. The median household that backs the Leviathan government, but at the same time dislikes high inflation, will therefore support the delegation of authority but only if it concerns monetary policy. The independent central bank will then be given the authority to control θ_G and oblige the government to change θ_G in order to meet the target rate of inflation.

Without such a delegation of authority, it is likely that generally $\theta_G > \theta_P$ because θ_G represents the median household whereas θ_P represents the mean household. Empirical studies indicate that the rate of time preference negatively correlates with permanent income (e.g., Lawrance 1991), and the permanent income of the median household is usually lower than that of the mean household. If generally $\theta_G > \theta_P$, that suggests that inflation will tend to accelerate unless a central bank is independent. The independence of the central bank is therefore very important in keeping the path of inflation stable.

Note also that the forced adjustments of θ_G by an independent central bank are exogenous shocks to both the government and the representative household because they are planned solely by the central bank. When a shock on θ_G is given, the government and the representative household must recalculate their optimal paths including the path of inflation by resetting θ_G , π_t , and φ .

3 THE MULTI-COUNTRY MODEL

In this section, the single-country model shown in Section 2 is extended to a multi-country model in the framework of endogenous growth, in which there is more than one government but only one central bank. More concretely, the single-country model is extended by combining it with the multi-country endogenous growth model by Harashima (2010). In addition, some technical modifications are made to the extended model so that the economics of monetary union can be analyzed.

3.1 *The optimization of households*

3.1.1 The base model

The production function is $Y_t = F(A_t, K_t, L_t)$, and the accumulation of capital is

$$\dot{K}_t = Y_t - C_t - v\dot{A}_t ,$$

where Y_t is outputs, A_t is technology, K_t is capital inputs, L_t is labor inputs, C_t is consumption, $v(> 0)$ is a constant, and a unit of K_t and v^{-1} of a unit of A_t are equivalent: that is, they are produced using the same quantities of inputs. All firms are identical and have the same size, and for any period,

$$\mu = \frac{M_t}{L_t} , \quad (23)$$

where M_t is the number of firms, and $\mu(> 0)$ is a constant. In addition,

$$\frac{\partial Y_t}{\partial K_t} = \frac{\varpi}{M_t} \frac{\partial Y_t}{\partial (vA_t)} ; \quad (24)$$

thus,

$$\frac{\partial y_t}{\partial k_t} = \frac{\varpi}{\mu v} \frac{\partial y_t}{\partial A_t} \quad (25)$$

is always kept, where y_t is output per capita, k_t is capital per capita, and $\varpi(> 1)$ is a constant. For simplicity, the period of patent is assumed to be indefinite, and no capital depreciation is assumed. ϖ indicates the effect of patent protection. With patents, the income is distributed to not only capitals and labors but technologies. Equation (23) indicates that population and number of firms are positively correlated. Equations (24) and (25) indicate that returns on investing in K_t and in A_t are kept equal and that a firm that produces a new technology cannot obtain all the returns on an investment in A_t . This means that investing in A_t increases Y_t , but the investing firm's return on the investment in A_t is only a fraction of the increase of Y_t , such that $\frac{\varpi}{M_t} \frac{\partial Y_t}{\partial (vA_t)} = \frac{\varpi}{\mu L_t} \frac{\partial Y_t}{\partial (vA_t)}$ because of uncompensated knowledge spillovers to other firms

and complementarity of technologies.

A part of the knowledge generated as a result of an investment made by a firm spills over to other firms. Researchers in firms as well as universities and research institutions could not effectively generate innovations if they were isolated from other researchers. They contact and stimulate each other. Probably, mutual partial knowledge spillovers among researchers and firms give each other reciprocal benefits. Researchers take hints on their researches in exchange for spilled knowledge. Therefore, even though the investing firm wishes to keep its knowledge secret, some parts of it will spill over. In addition, many uncompensated knowledge spillovers occur because many technologies are regarded as so minor that they are not applied for patents and left unprotected by patents. Nevertheless, even if a technology that was generated as a byproduct is completely useless for the investing firm, it may be a treasure for firms in a different industry. A_t includes all these technologies, and an investment in technology generates many technologies that the investing firm cannot protect by patents.

Broadly speaking, there are two types of uncompensated knowledge spillovers: intra-sectoral knowledge spillovers (i.e., Marshall-Arrow-Romer [MAR] externalities; Marshall, 1890; Arrow, 1962; Romer, 1986) and inter-sectoral knowledge spillovers (i.e., Jacobs externalities; Jacobs, 1969). MAR theory assumes that knowledge spillovers between

homogenous firms work out most effectively and that spillovers will therefore primarily emerge within one sector. As a result, uncompensated knowledge spillovers will be more active if the number of firms within a sector is larger. On the other hand, Jacobs (1969) argues that knowledge spillovers are most effective among firms that practice different activities and that diversification (i.e., a variety of sectors) is important for spillovers. As a result, uncompensated knowledge spillovers will be more active if the number of sectors in the economy is larger. Nevertheless, if all sectors have the same number of firms, an increase in the number of firms in the economy results in more active knowledge spillovers in any case, owing to either MAR externalities or Jacobs externalities.

Furthermore, as the volume of uncompensated knowledge spillovers increases, the investing firm's returns on the investment in A_t decrease. $\frac{\partial Y_t}{\partial A_t}$ indicates the total increase in Y_t

in the economy by an increase in A_t , which consists of increases in both outputs in the firm that invested in the new technologies and outputs in other firms that utilize the newly invented technologies, whether the firms obtained the technologies by compensating the originating firm or by using uncompensated knowledge spillovers. If the number of firms becomes larger and uncompensated knowledge spillovers occur more actively, the compensated fraction in $\frac{\partial Y_t}{\partial A_t}$

that the investing firm can obtain becomes smaller, and the investing firm's returns on the investment in A_t also become smaller.

Complementarity of technologies also reduces the fraction of $\frac{\partial Y_t}{\partial A_t}$ that the investing

firm can obtain. If a new technology is effective only if it is combined with some particular technologies, the return on the investment in technology will belong not only to the investing firm but to the firms that hold these particular technologies. For example, an innovation in software technology generated by a software company increases the sales and profits of computer hardware companies. The economy's productivity increases because of the innovation but the increased incomes are attributed not only to the firm that generated the innovation but also to the firms that hold complementary technologies. A part of $\frac{\partial Y_t}{\partial A_t}$ leaks to these firms. For

them, the leaked income is a kind of rent revenue unexpectedly become obtainable thanks to the innovation. Most new technologies will have complementary technologies. In addition, as the number of firms increases, the number of firms that holds complementary technologies will also increase, and thereby these leaks will also increase.

Because of the uncompensated knowledge spillovers and the complementarity of technologies, therefore, the fraction of $\frac{\partial Y_t}{\partial A_t}$ that an investing firm can obtain on average will

be comparatively small, i.e., ϖ will be far smaller than M_t except that M_t is very small,⁸ and the fraction will decrease as M_t increases.

The production function is specified as $Y_t = A_t^\alpha f(K_t, L_t)$ where α ($0 < \alpha < 1$) is a

⁸ If M_t is very small, the value of ϖ will be far smaller than that for sufficiently large M_t , because the number of firms that can benefit from an innovation is constrained owing to very small M_t . The very small number of firms indicates that the economy is not sufficiently sophisticated, and thereby the benefit of an innovation can not be fully realized in the economy. This constraint can be modeled as $\varpi = \bar{\varpi} \left[1 - (1 - \bar{\varpi}^{-1})^{M_t} \right]$ where $\bar{\varpi} (\geq 1)$ is a constant. Nevertheless, for sufficiently large M_t (i.e., in sufficiently sophisticated economies), the constraint is removed such that $\lim_{M_t \rightarrow \infty} \bar{\varpi} \left[1 - (1 - \bar{\varpi}^{-1})^{M_t} \right] = \bar{\varpi} = \varpi$.

constant. Let $y_t = \frac{Y_t}{L_t}$, $k_t = \frac{K_t}{L_t}$, $c_t = \frac{C_t}{L_t}$, and $n_t = \frac{\dot{L}_t}{L_t}$, and assume that $f(K_t, L_t)$ is homogenous of degree one. Thus $y_t = A_t^\alpha f(k_t)$ and $\dot{k}_t = y_t - c_t - \frac{v\dot{A}_t}{L_t} - n_t k_t$. By equation (25), $A_t = \frac{\varpi \alpha f(k_t)}{\mu \nu f'(k_t)}$ because $\frac{\varpi \partial y_t}{\mu \nu \partial A_t} = \frac{\partial y_t}{\partial k_t} \Leftrightarrow \frac{\varpi \alpha}{\mu \nu} A_t^{\alpha-1} f(k_t) = A_t^\alpha f'(k_t)$.

3.1.2 Models with heterogeneous households

Three heterogeneities—heterogeneous time preference, risk aversion, and productivity—are examined in endogenous growth models, which are modified versions of the model shown in Section 3.1.1. First, suppose that there are two economies—economy 1 and economy 2—that are identical except for time preference, risk aversion, or productivity. The population growth rate is zero (i.e., $n_t = 0$). The economies are fully open to each other, and goods, services, and capital are freely transacted between them, but labor is immobilized in each economy. Note that the two-country models shown in this section can be extended to include numerous economies that have differing degrees of heterogeneity, which will be constructed in Section 3.2.

3.1.2.1 Heterogeneous time preference model

First, a model in which the two economies are identical except for time preference is constructed. The rate of time preference of the representative household in economy 1 is $\theta_{p,1}$ and that in economy 2 is $\theta_{p,2}$, and $\theta_{p,1} < \theta_{p,2}$. The production function in economy 1 is $y_{1,t} = A_t^\alpha f(k_{1,t})$ and that in economy 2 is $y_{2,t} = A_t^\alpha f(k_{2,t})$, where $y_{\rho,t}$ and $k_{\rho,t}$ are, respectively, output and capital per capita in economy ρ in period t for $\rho = 1, 2$. The population of each economy is $\frac{L_t}{2}$; thus, the total for both is L_t , which is sufficiently large. Firms operate in both economies, and the number of firms is M_t . The current account balance in economy 1 is τ_t and that in economy 2 is $-\tau_t$. Because a balanced growth path requires Harrod neutral technological progress, the production functions are further specified as

$$y_{\rho,t} = A_t^\alpha k_{\rho,t}^{1-\alpha} \quad ;$$

thus, $Y_{\rho,t} = K_{\rho,t}^{1-\alpha} (A_t L_t)^\alpha$ ($\rho = 1, 2$).

Because both economies are fully open, returns on investments in each economy are kept equal through arbitrage such that

$$\frac{\partial y_{1,t}}{\partial k_{1,t}} = \frac{\varpi}{2\mu\nu} \frac{\partial (y_{1,t} + y_{2,t})}{\partial A_t} = \frac{\partial y_{2,t}}{\partial k_{2,t}} \quad . \quad (26)$$

Equation (26) indicates that an increase in A_t enhances outputs in both economies such that $\frac{\partial Y_{i,t}}{\partial K_{i,t}} = \frac{\varpi}{M_t} \frac{\partial (Y_{1,t} + Y_{2,t})}{\partial (vA_t)}$, and because the population is equal ($\frac{L_t}{2}$), $\frac{\partial Y_{i,t}}{\partial K_{i,t}} = \frac{\partial y_{i,t}}{\partial k_{i,t}} = \frac{\varpi}{M_t} \frac{\partial (Y_{1,t} + Y_{2,t})}{\partial (vA_t)} = \frac{\varpi}{\mu L_t} \frac{\partial (y_{1,t} + y_{2,t})}{\partial (vA_t)} \frac{L_t}{2} = \frac{\varpi}{2\mu\nu} \frac{\partial (y_{1,t} + y_{2,t})}{\partial A_t}$. Therefore,

$$A_t = \frac{\varpi \alpha [f(k_{1,t}) + f(k_{2,t})]}{2 \mu \nu f'(k_{1,t})} = \frac{\varpi \alpha [f(k_{1,t}) + f(k_{2,t})]}{2 \mu \nu f'(k_{2,t})} .$$

Because equation (26) is always held through arbitrage, equations $k_{1,t} = k_{2,t}$, $\dot{k}_{1,t} = \dot{k}_{2,t}$, $y_{1,t} = y_{2,t}$ and $\dot{y}_{1,t} = \dot{y}_{2,t}$ are also held. Hence,

$$A_t = \frac{\varpi \alpha f(k_{1,t})}{\mu \nu f'(k_{1,t})} = \frac{\varpi \alpha f(k_{2,t})}{\mu \nu f'(k_{2,t})} .$$

In addition, because $\frac{\partial(y_{1,t} + y_{2,t})}{\partial A_{1,t}} = \frac{\partial(y_{1,t} + y_{2,t})}{\partial A_{2,t}}$ through arbitrage, then $\dot{A}_{1,t} = \dot{A}_{2,t}$ is held.

The accumulated current account balance $\int_0^t \tau_s ds$ mirrors capital flows between the two economies. The economy with current account surpluses invests them in the other economy. Since $\frac{\partial y_{1,t}}{\partial k_{1,t}} (= \frac{\partial y_{2,t}}{\partial k_{2,t}})$ are returns on investments, $\frac{\partial y_{1,t}}{\partial k_{1,t}} \int_0^t \tau_s ds$ and $\frac{\partial y_{2,t}}{\partial k_{2,t}} \int_0^t \tau_s ds$ represent income receipts or payments on the assets that an economy owns in the other economy. Hence,

$$\tau_t - \frac{\partial y_{2,t}}{\partial k_{2,t}} \int_0^t \tau_s ds$$

is the balance on goods and services of economy 1, and

$$\frac{\partial y_{1,t}}{\partial k_{1,t}} \int_0^t \tau_s ds - \tau_t$$

is that of economy 2. Because the current account balance mirrors capital flows between the economies, the balance is a function of capital in both economies such that

$$\tau_t = g(k_{1,t}, k_{2,t}) .$$

The representative household in economy 1 maximizes its expected utility

$$E \int_0^\infty u_1(c_{1,t}) \exp(-\theta_{p,1} t) dt ,$$

subject to

$$\dot{k}_{1,t} = y_{1,t} + \frac{\partial y_{2,t}}{\partial k_{2,t}} \int_0^t \tau_s ds - \tau_t - c_{1,t} - \nu \dot{A}_{1,t} \left(\frac{L_t}{2} \right)^{-1} , \quad (27)$$

and the representative household in economy 2 maximizes its expected utility

$$E \int_0^{\infty} u_2(c_{2,t}) \exp(-\theta_{\rho,2}t) dt \quad ,$$

subject to

$$\dot{k}_{2,t} = y_{2,t} - \frac{\partial y_{1,t}}{\partial k_{1,t}} \int_0^t \tau_s ds + \tau_t - c_{2,t} - v \dot{A}_{2,t} \left(\frac{L_t}{2} \right)^{-1} \quad , \quad (28)$$

where $u_{\rho,t}$, $c_{\rho,t}$, and $\dot{A}_{\rho,t}$, respectively, are the utility function, per capita consumption, and the increase in A_t by R&D activities in economy ρ in period t for $\rho = 1, 2$; E is the expectation operator; and $\dot{A}_t = \dot{A}_{1,t} + \dot{A}_{2,t}$. Equations (27) and (28) implicitly assume that each economy does not have foreign assets or debt in period $t = 0$.

Because the production function is Harrod neutral and because $A_t = \frac{\varpi \alpha f(k_{1,t})}{\mu \nu f'(k_{1,t})}$
 $= \frac{\varpi \alpha f(k_{2,t})}{\mu \nu f'(k_{2,t})}$ and $f = k_{\rho,t}^{1-\alpha}$, then

$$A_t = \frac{\varpi \alpha}{\mu \nu (1-\alpha)} k_{\rho,t}$$

and

$$\frac{\partial y_{\rho,t}}{\partial k_{\rho,t}} = \left(\frac{\varpi \alpha}{\mu \nu} \right)^\alpha (1-\alpha)^{1-\alpha} \quad .$$

Since $\dot{A}_{1,t} = \dot{A}_{2,t}$ and $\frac{\partial y_{1,t}}{\partial k_{1,t}} = \frac{\partial y_{2,t}}{\partial k_{2,t}}$, then

$$\begin{aligned} \dot{k}_{1,t} &= y_{1,t} + \frac{\partial y_{1,t}}{\partial k_{1,t}} \int_0^t \tau_s ds - \tau_t - c_{1,t} - \frac{v \dot{A}_t}{2} \left(\frac{L_t}{2} \right)^{-1} \\ &= \left(\frac{\varpi \alpha}{\mu \nu} \right)^\alpha (1-\alpha)^{-\alpha} k_{1,t} + \left(\frac{\varpi \alpha}{\mu \nu} \right)^\alpha (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds - \tau_t - c_{1,t} - \frac{\varpi \alpha}{\mu L_t (1-\alpha)} \dot{k}_{1,t} \end{aligned}$$

and

$$\dot{k}_{1,t} = \frac{\mu L_t (1-\alpha)}{\mu L_t (1-\alpha) + \varpi \alpha} \left[\left(\frac{\varpi \alpha}{\mu \nu} \right)^\alpha (1-\alpha)^{-\alpha} k_{1,t} + \left(\frac{\varpi \alpha}{\mu \nu} \right)^\alpha (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds - \tau_t - c_{1,t} \right] \quad .$$

Because L_t is sufficiently large and ϖ is far smaller than M_t , the problem of scale effects vanishes and thereby $\frac{\mu L_t (1-\alpha)}{\mu L_t (1-\alpha) + \varpi \alpha} = 1$.

Putting the above elements together, the optimization problem of economy 1 can be rewritten as

$$\text{Max } E \int_0^{\infty} u_1(c_{1,t}) \exp(-\theta_{p,1}t) dt \quad ,$$

subject to

$$\dot{k}_{1,t} = \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{-\alpha} k_{1,t} + \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds - \tau_t - c_{1,t} \quad .$$

Similarly, that of economy 2 can be rewritten as

$$\text{Max } E \int_0^{\infty} u_2(c_{2,t}) \exp(-\theta_{p,2}t) dt \quad ,$$

subject to

$$\dot{k}_{2,t} = \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{-\alpha} k_{2,t} - \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds + \tau_t - c_{2,t} \quad .$$

3.1.2.2 Heterogeneous risk aversion model

The basic structure of the model with heterogeneous risk aversion is the same as that of heterogeneous time preference. The two economies are identical except in regard to risk aversion. The degree of relative risk aversion of economy 1 is $\varepsilon_1 = -\frac{c_{1,t} u_1''}{u_1'}$ and that of economy 2 is $\varepsilon_2 = -\frac{c_{2,t} u_2''}{u_2'}$, which are constant, and $\varepsilon_1 < \varepsilon_2$. The optimization problem of economy 1 is

$$\text{Max } E \int_0^{\infty} u_1(c_{1,t}) \exp(-\theta_p t) dt \quad ,$$

subject to

$$\dot{k}_{1,t} = \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{-\alpha} k_{1,t} + \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds - \tau_t - c_{1,t} \quad ,$$

and that of economy 2 is

$$\text{Max } E \int_0^{\infty} u_2(c_{2,t}) \exp(-\theta_p t) dt \quad ,$$

subject to

$$\dot{k}_{2,t} = \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{-\alpha} k_{2,t} - \left(\frac{\varpi \alpha}{\mu \nu} \right)^{\alpha} (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds + \tau_t - c_{2,t} \quad .$$

3.1.2.3 Heterogeneous productivity model

With heterogeneous productivity, the production function is heterogeneous, not the utility function. Because technology A_t is common to both economies, a heterogeneous production function requires heterogeneity in elements other than technology. Prescott (1998) argues that unknown factors other than technology have made total factor productivity (TFP) heterogeneous across countries. Harashima (2009) argues that average workers' innovative activities are an essential element of productivity and make TFP heterogeneous across workers, firms, and economies. Since average workers are human and capable of creative intellectual activities, they can create innovations even if their innovations are minor. It is rational for firms to exploit all the opportunities that these ordinary workers' innovative activities offer. Furthermore, innovations created by ordinary workers are indispensable for efficient production. A production function incorporating average workers' innovations has been shown to have a Cobb-Douglas functional form with a labor share of about 70% (Harashima 2009), such that

$$Y_t = \bar{\sigma} \omega_A \omega_L A_t^\alpha K_t^{1-\alpha} L_t^\alpha, \quad (29)$$

where ω_A and ω_L are positive constant parameters with regard to average workers' creative activities, and $\bar{\sigma}$ is a parameter that represents a worker's accessibility limit to capital with regard to location. The parameters ω_A and ω_L are independent of A_t but are dependent on the creative activities of average workers. Thereby, unlike with technology A_t , these parameters can be heterogeneous across workers, firms, and economies.

In this model of heterogeneous productivity, it is assumed that workers whose households belong to different economies have different values of ω_A and ω_L . In addition, only productivity that is represented by $\bar{\sigma} \omega_A \omega_L A_t^\alpha$ in equation (29) is heterogeneous between the two economies. The production function of economy 1 is $y_{1,t} = \omega_1^\alpha A_t^\alpha f(k_{1,t})$ and that of economy 2 is $y_{2,t} = \omega_2^\alpha A_t^\alpha f(k_{2,t})$, where $\omega_1 (0 < \omega_1 \leq 1)$ and $\omega_2 (0 < \omega_2 \leq 1)$ are constants and $\omega_2 < \omega_1$. Since $\frac{\partial Y_{\rho,t}}{\partial K_{\rho,t}} = \frac{\partial y_{\rho,t}}{\partial k_{\rho,t}} = M_t^{-1} \frac{\partial (Y_{1,t} + Y_{2,t})}{\partial (vA_t)} = \frac{\bar{\sigma}}{\mu L_t} \frac{\partial (y_{1,t} + y_{2,t}) L_t}{\partial (vA_t)} = \frac{\bar{\sigma}}{2\mu L_t} \frac{\partial (y_{1,t} + y_{2,t})}{\partial A_t}$ by equation (26), then

$$A_t = \frac{\bar{\sigma} \alpha [\omega_1^\alpha f(k_{1,t}) + \omega_2^\alpha f(k_{2,t})]}{2\mu\nu \omega_1^\alpha f'(k_{1,t})} = \frac{\bar{\sigma} \alpha [\omega_1^\alpha f(k_{1,t}) + \omega_2^\alpha f(k_{2,t})]}{2\mu\nu \omega_2^\alpha f'(k_{2,t})}. \quad (30)$$

Because equation (26) is always held through arbitration, equations $k_{1,t} = \frac{\omega_1}{\omega_2} k_{2,t}$, $\dot{k}_{1,t} = \frac{\omega_1}{\omega_2} \dot{k}_{2,t}$,

$y_{1,t} = \frac{\omega_1}{\omega_2} y_{2,t}$, and $\dot{y}_{1,t} = \frac{\omega_1}{\omega_2} \dot{y}_{2,t}$ are also held. In addition, since $\frac{\partial (y_{1,t} + y_{2,t})}{\partial A_{1,t}} = \frac{\partial (y_{1,t} + y_{2,t})}{\partial A_{2,t}}$

by arbitration, $\dot{A}_{1,t} = \frac{\omega_1}{\omega_2} \dot{A}_{2,t}$ is held. Because of equation (30) and $f = \omega_\rho^\alpha k_{\rho,t}^{1-\alpha}$, then $A_t =$

$$\frac{\bar{\sigma} \alpha}{2\mu\nu(1-\alpha)\omega_1^\alpha} (\omega_1^\alpha k_1 + \omega_2^\alpha k_1^\alpha k_2^{1-\alpha}) = \frac{\bar{\sigma} \alpha}{2\mu\nu(1-\alpha)\omega_2^\alpha} (\omega_1^\alpha k_1^{1-\alpha} k_2^\alpha + \omega_2^\alpha k_2), \quad \frac{\omega_1^\alpha k_1 + \omega_2^\alpha k_1^\alpha k_2^{1-\alpha}}{\omega_1^\alpha} = \frac{\omega_1^\alpha k_1^{1-\alpha} k_2^\alpha + \omega_2^\alpha k_2}{\omega_2^\alpha},$$

and $\frac{\partial y_{\rho,t}}{\partial k_{\rho,t}} = \left(\frac{\bar{\sigma} \alpha}{2\mu\nu} \right)^\alpha (1-\alpha)^{1-\alpha} (\omega_1^\alpha k_1 + \omega_2^\alpha k_1^\alpha k_2^{1-\alpha})^\alpha k_1^{-\alpha} = \left(\frac{\bar{\sigma} \alpha}{2\mu\nu} \right)^\alpha (1-\alpha)^{1-\alpha} (\omega_1^\alpha k_1^{1-\alpha} k_2^\alpha + \omega_2^\alpha k_2)^\alpha k_2^{-\alpha}$. Since

$$\frac{\omega_2}{\omega_1} k_{1,t} = k_{2,t}, \text{ then } \frac{\omega_1^\alpha k_1 + \omega_2^\alpha k_1^\alpha k_2^{1-\alpha}}{\omega_1^\alpha} = \frac{\omega_1^\alpha k_1 + \omega_2^\alpha k_1^\alpha \left(\frac{\omega_2}{\omega_1}\right)^{1-\alpha} k_1^{1-\alpha}}{\omega_1^\alpha} = k_1 (1 + \omega_1^{-1} \omega_2) \text{ and}$$

$$\frac{\omega_1^\alpha k_1^{1-\alpha} k_2^\alpha + \omega_2^\alpha k_2}{\omega_2^\alpha} = \frac{\omega_1^\alpha k_1^{1-\alpha} \left(\frac{\omega_2}{\omega_1}\right)^\alpha k_1^\alpha + \omega_2^\alpha \frac{\omega_2}{\omega_1} k_1}{\omega_2^\alpha} = k_1 + \frac{\omega_2}{\omega_1} k_1 = k_1 (1 + \omega_1^{-1} \omega_2) = k_2 (1 + \omega_1 \omega_2^{-1}). \text{ Hence,}$$

$$A_t = k_1 \frac{\varpi \alpha (1 + \omega_1^{-1} \omega_2)}{2 \mu \nu (1 - \alpha)} = k_2 \frac{\varpi \alpha (1 + \omega_1 \omega_2^{-1})}{2 \mu \nu (1 - \alpha)},$$

and

$$\frac{\partial y_{\rho,t}}{\partial k_{\rho,t}} = \left(\frac{\omega_1 + \omega_2}{2}\right)^\alpha \left(\frac{\varpi \alpha}{\mu \nu}\right)^\alpha (1 - \alpha)^{1-\alpha}$$

for $\rho = 1, 2$. Because $\dot{A}_{1,t} = \left(\frac{\omega_2}{\omega_1}\right)^{\frac{1}{\alpha}} \dot{A}_{2,t}$ (i.e., $\dot{A}_t = \dot{A}_{1,t} + \dot{A}_{2,t} = (1 + \omega_1^{-1} \omega_2) \dot{A}_{1,t}$) and

$$\frac{\partial y_{1,t}}{\partial k_{1,t}} = \frac{\partial y_{2,t}}{\partial k_{2,t}}, \text{ then}$$

$$\begin{aligned} \dot{k}_{1,t} &= y_{1,t} + \frac{\partial y_{1,t}}{\partial k_{1,t}} \int_0^t \tau_s ds - \tau_t - c_{1,t} - \nu \dot{A}_{1,t} \left(\frac{L_t}{2}\right)^{-1} \\ &= y_{1,t} + \frac{\partial y_{1,t}}{\partial k_{1,t}} \int_0^t \tau_s ds - \tau_t - c_{1,t} - \nu \dot{A}_t (1 + \omega_1^{-1} \omega_2)^{-1} \left(\frac{L_t}{2}\right)^{-1} \\ &= \omega_1^\alpha \left[\frac{(1 + \omega_1^{-1} \omega_2) \varpi \alpha}{2 \mu \nu (1 - \alpha)} \right]^\alpha k_{1,t} + \left[\frac{(\omega_1 + \omega_2) \varpi \alpha}{2 \mu \nu} \right]^\alpha (1 - \alpha)^{1-\alpha} \int_0^t \tau_s ds - \tau_t - c_{1,t} - \frac{\varpi \alpha}{\mu L_t (1 - \alpha)} \dot{k}_{1,t}, \end{aligned}$$

and

$$\dot{k}_{1,t} = \frac{\mu L_t (1 - \alpha)}{\mu L_t (1 - \alpha) + \varpi \alpha} \left\{ \left[\frac{(\omega_1 + \omega_2) \varpi \alpha}{2 \mu \nu (1 - \alpha)} \right]^\alpha k_{1,t} + \left[\frac{(\omega_1 + \omega_2) \varpi \alpha}{2 \mu \nu} \right]^\alpha (1 - \alpha)^{1-\alpha} \int_0^t \tau_s ds - \tau_t - c_{1,t} \right\}.$$

Because L_t is sufficiently large and ϖ is far smaller than M_t and thus $\frac{\mu L_t (1 - \alpha)}{\mu L_t (1 - \alpha) + \varpi \alpha} = 1$, the optimization problem of economy 1 is

$$\text{Max } E \int_0^\infty u_1(c_{1,t}) \exp(-\theta_p t) dt,$$

subject to

$$\dot{k}_{1,t} = \left[\frac{(\omega_1 + \omega_2)\varpi\alpha}{2\mu\nu(1-\alpha)} \right]^\alpha k_{1,t} + \left[\frac{(\omega_1 + \omega_2)\varpi\alpha}{2\mu\nu} \right]^\alpha (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds - \tau_t - c_{1,t} ,$$

and similarly, that of economy 2 is

$$\text{Max } E \int_0^\infty u_2(c_{2,t}) \exp(-\theta_\rho t) dt ,$$

subject to

$$\dot{k}_{2,t} = \left[\frac{(\omega_1 + \omega_2)\varpi\alpha}{2\mu\nu(1-\alpha)} \right]^\alpha k_{2,t} - \left[\frac{(\omega_1 + \omega_2)\varpi\alpha}{2\mu\nu} \right]^\alpha (1-\alpha)^{1-\alpha} \int_0^t \tau_s ds + \tau_t - c_{2,t} .$$

3.1.3 Sustainable heterogeneity

Heterogeneity is defined as being sustainable if all the optimality conditions of all heterogeneous households are satisfied indefinitely. The nature of sustainable heterogeneity is examined in a multi-country model of heterogeneous time preference, risk aversion and productivity, which is constructed by combining the three models in the previous section (see Harashima, 2010).

Suppose that there are N economies with identical population, and let $\tau_{\rho,\varsigma,t}$ be the current account balance of economy ρ with economy ς , where $\rho = 1, 2, \dots, N$, $\varsigma = 1, 2, \dots, N$, and $\rho \neq \varsigma$.

Proposition: If and only if

$$\lim_{t \rightarrow \infty} \frac{\dot{c}_{\rho,t}}{c_{\rho,t}} = \left(\frac{\sum_{q=1}^N \varepsilon_q \omega_q}{\sum_{q=1}^N \omega_q} \right)^{-1} \left\{ \left[\frac{\varpi\alpha \sum_{q=1}^N \omega_q}{N\mu\nu(1-\alpha)} \right]^\alpha - \frac{\sum_{q=1}^N \theta_{\rho,q} \omega_q}{\sum_{q=1}^N \omega_q} \right\} \quad (31)$$

for any ρ ($= 1, 2, \dots, N$), all the optimality conditions of all heterogeneous economies are satisfied at steady state such that $\lim_{t \rightarrow \infty} \frac{\dot{c}_{\rho,t}}{c_{\rho,t}}$, $\lim_{t \rightarrow \infty} \frac{\dot{k}_{\rho,t}}{k_{\rho,t}}$, and $\lim_{t \rightarrow \infty} \frac{\dot{\tau}_{\rho,\varsigma,t}}{\tau_{\rho,\varsigma,t}}$ are constants, and

$$\lim_{t \rightarrow \infty} \frac{\dot{c}_{\rho,t}}{c_{\rho,t}} = \lim_{t \rightarrow \infty} \frac{\dot{k}_{\rho,t}}{k_{\rho,t}} = \lim_{t \rightarrow \infty} \frac{\dot{y}_{\rho,t}}{y_{\rho,t}} = \lim_{t \rightarrow \infty} \frac{\dot{A}_t}{A_t} = \lim_{t \rightarrow \infty} \frac{\dot{\tau}_{\rho,\varsigma,t}}{\tau_{\rho,\varsigma,t}} = \lim_{t \rightarrow \infty} \frac{d \int_0^t \tau_{\rho,\varsigma,s} ds}{\int_0^t \tau_{\rho,\varsigma,s} ds}$$

for any ρ and ς ($\rho \neq \varsigma$).

Proof: See Harashima (2010).

On the balanced growth path satisfying the condition shown in Proposition, heterogeneities in time preference, risk aversion and productivity are sustainable by definition because all the optimality conditions of the two economies are indefinitely satisfied. Economies that keep

sustainable heterogeneity constitute a combined economy with productivity $\left[N^{-1} \sum_{q=1}^N \omega_q \right]^\alpha A_t^\alpha$ and the time preference rate $\left(\sum_{q=1}^N \omega_q \right)^{-1} \sum_{q=1}^N \theta_{P,q} \omega_q$ and degree of risk aversion $\left(\sum_{q=1}^N \omega_q \right)^{-1} \sum_{q=1}^N \varepsilon_q \omega_q$ of the representative household. The nature of sustainable heterogeneity is examined more in detail in Harashima (2010).

3.2 The law of motion for inflation in the multi-country endogenous growth model

3.2.1 The monetary union

Suppose that there is a monetary union that consists of N member states and one currency. There is no federal government in the monetary union, and fiscal policies are therefore implemented separately by each member. Monetary policies are unified and implemented only by the central bank of the monetary union, which is sufficiently independent of the member states. For simplicity, population in each member state is assumed to be identical and constant, and the total population in the monetary union is sufficiently large. Sustainable heterogeneity, as shown in Section 3.1.3, is kept. The time preference rate of the representative household in member state ρ is $\theta_{P,\rho}$ for $\rho = 1, 2, \dots, N$. The time preference rate of the government of member state ρ is $\theta_{G,\rho}$ and $\theta_{G,\rho} > \theta_{P,\rho}$. Suppose for simplicity that $-\mathbf{g}_{\rho,t} \left[\frac{\partial u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t})}{\partial \mathbf{g}_{\rho,t}} \right]^{-1} \frac{\partial^2 u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t})}{\partial \mathbf{g}_{\rho,t}^2} = \varepsilon_{g,\rho}$ and $-x_{\rho,t} \left[\frac{\partial u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t})}{\partial x_{\rho,t}} \right]^{-1} \frac{\partial^2 u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t})}{\partial x_{\rho,t}^2} = \varepsilon_{x,\rho}$ are positive and constant, similar to the degree of relative risk aversion of households. ε_g and ε_x are, respectively, identical across member governments, such that $\varepsilon_{g,\rho} = \varepsilon_g$ and $\varepsilon_{x,\rho} = \varepsilon_x$ for any ρ .

As shown in Section 3.1.3, economies that keep sustainable heterogeneity constitute a combined economy with productivity $\left[N^{-1} \sum_{q=1}^N \omega_q \right]^\alpha A_t^\alpha$ and the time preference rate $\left(\sum_{q=1}^N \omega_q \right)^{-1} \sum_{q=1}^N \theta_{P,q} \omega_q$ and degree of risk aversion $\left(\sum_{q=1}^N \omega_q \right)^{-1} \sum_{q=1}^N \varepsilon_q \omega_q$ of the representative household. The combined economy grows at the constant rate

$$\lim_{t \rightarrow \infty} \frac{\dot{c}_t}{c_t} = \left(\frac{\sum_{q=1}^N \varepsilon_q \omega_q}{\sum_{q=1}^N \omega_q} \right)^{-1} \left\{ \left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N \mu \nu (1 - \alpha)} \right]^\alpha - \frac{\sum_{q=1}^N \theta_{P,q} \omega_q}{\sum_{q=1}^N \omega_q} \right\}$$

(equation [31]) where c_t is the consumption of the representative household of the monetary union. Because sustainable heterogeneity is kept in the monetary union, the time preference rate

of the representative household of the monetary union is $\left(\sum_{q=1}^N \omega_q\right)^{-1} \sum_{q=1}^N \theta_{p,q} \omega_q = \theta_p$. Because

the size of an economy in the monetary union is measured by the productivity differential parameter ω_p , the integrated time preference rate of government in the monetary union is $\left(\sum_{q=1}^N \omega_q\right)^{-1} \sum_{q=1}^N \theta_{G,p} \omega_q = \theta_G$. The overall rate of inflation in the monetary union is π_t . The central bank of the monetary union sets θ_G equal to θ_p so that π_t will not accelerate.

Because

$$\frac{\partial y_t}{\partial k_t} = \left(N^{-1} \sum_{q=1}^N \omega_q\right)^\alpha \left(\frac{\varpi \alpha}{\mu \nu}\right)^\alpha (1-\alpha)^{1-\alpha} = \text{constant},$$

then

$$r_t = \left(N^{-1} \sum_{q=1}^N \omega_q\right)^\alpha \left(\frac{\varpi \alpha}{\mu \nu}\right)^\alpha (1-\alpha)^{1-\alpha} = \bar{r} \quad (32)$$

across the monetary union, where y_t , k_t , and r_t are the per capita outputs, per capita capital inputs, and the real interest rate in the monetary union, respectively, and \bar{r} is a constant. By equation (9),

$$\left(\sum_{q=1}^N \omega_q\right)^{-1} \sum_{q=1}^N \varepsilon_q \omega_q \frac{\dot{c}_t}{c_t} + \theta_p = \bar{r} \quad (33)$$

in the monetary union. By equations (31), (32), and (33),

$$\theta_p = \bar{r} - \left(\sum_{q=1}^N \omega_q\right)^{-1} \sum_{q=1}^N \varepsilon_q \omega_q \frac{\dot{c}_t}{c_t} = \bar{r} - \left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N \mu \nu (1-\alpha)}\right]^\alpha + \theta_p = \text{constant} \quad (34)$$

if sustainable heterogeneity is kept.

3.2.2 The law of motion for inflation

Each member government maximizes its expected utility subject to constraints. However, unlike the single-country model, the constraint is not limited to equation (3). The real current account balance ($\eta_{p,t}$) within the monetary union in each member state must be stable at steady state; thus,

$$\lim_{t \rightarrow \infty} \frac{\dot{\eta}_{p,t}}{\eta_{p,t}} = \lim_{t \rightarrow \infty} \frac{\dot{c}_{p,t}}{c_{p,t}} \quad (35)$$

because the economy of the monetary union otherwise eventually collapses. As will be discussed in Section 4.2.4, current account balances depend on inflation differentials; thereby,

$\eta_{\rho,t}$ is a function of $\pi_{1,t}, \pi_{2,t}, \dots, \pi_{N,t}$ and thus a function of $\theta_{G,1,t}, \theta_{G,2,t}, \dots, \theta_{G,N,t}$ and θ_P , such that

$$\eta_{i,t} = h(\theta_{G,1,t}, \theta_{G,2,t}, \dots, \theta_{G,N,t}, \theta_P),$$

where $\pi_{\rho,t}$ is the rate of inflation in member state ρ . Each member government therefore maximizes its expected utility subject to not only equation (3) but also equation (35).

By equations (18), (32) and (34), the law of motion for inflation is

$$\theta_{G,\rho} = \left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N\mu\nu(1-\alpha)} \right]^\alpha + \int_{t-1}^t \int_s^{s+1} \pi_{\rho,v} dv ds - \pi_{\rho,t}.$$

Therefore, if

$$\theta_{G,\rho} = \theta_G = \left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N\mu\nu(1-\alpha)} \right]^\alpha \quad (36)$$

for any ρ , inflation does not accelerate in the monetary union (i.e., $\dot{\pi}_i = 0$). Because

$$\left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N\mu\nu(1-\alpha)} \right]^\alpha - \theta_P > 0, \text{ equation (36) indicates that, unlike the exogenous growth model}$$

shown in Section 2 in which inflation does not accelerate if $\theta_G = \theta_P$, inflation does not accelerate in the framework of endogenous growth if $\theta_G > \theta_P$.

However, an additional element in the behavior of government should also be considered in the framework of endogenous growth. Unlike the exogenous growth model, the economy grows at a constant rate in the endogenous growth model. As y_t increases, x_t and g_t will not remain at the same level as before because, as the economy grows, the capability of the government to collect and spend money also increases. Conversely, as the economy grows, the utility obtained by spending a unit of g_t and disutility generated by imposing a unit of x_t decrease. Considering this scale effect, the utility function of government is replaced with

$$u_{G,\rho}(g_{\rho,t}, x_{\rho,t}, y_{\rho,t}).$$

Notice that $y_{\rho,t}$ is exogenous for the government, although it is endogenous for households. The constant endogenous growth of $y_{\rho,t}$ is perceived by the government as successive exogenous shocks on $y_{\rho,t}$ in $u_{G,\rho}(g_{\rho,t}, x_{\rho,t}, y_{\rho,t})$. When an exogenous upward shock of $y_{\rho,t}$ occurs, larger $g_{\rho,t}$ and $x_{\rho,t}$ are optimal for the government because of the scale effect; thus, $g_{\rho,t}$ and $x_{\rho,t}$ begin to increase on the transition path to the new steady state. The government perceives that exogenous shocks on $y_{\rho,t}$ continuously occur because of the constant endogenous growth of $y_{\rho,t}$.

thereby, $g_{\rho,t}$ and $x_{\rho,t}$ continuously move to new transition paths. Because $\varepsilon_{g,\rho} \frac{\dot{g}_{\rho,t}}{g_{\rho,t}} + \theta_{G,\rho} = r_t + \int_{t-1}^t \int_s^{s+1} \pi_{\rho,v} dv ds - \pi_{\rho,t}$, $\varepsilon_{x,\rho} \frac{\dot{x}_{\rho,t}}{x_{\rho,t}} + \theta_{G,\rho} = r_t + \int_{t-1}^t \int_s^{s+1} \pi_{\rho,v} dv ds - \pi_{\rho,t}$, $\frac{\dot{g}_{\rho,t}}{g_{\rho,t}} > 0$, and $\frac{\dot{x}_{\rho,t}}{x_{\rho,t}} > 0$ on transition paths, and because $\varepsilon_{g,\rho} > 0$ and $\varepsilon_{x,\rho} > 0$, then by equations (32) and (34), if

$$\theta_{G,\rho} + \Omega = \theta_G + \Omega = \left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N\mu\nu(1-\alpha)} \right]^\alpha \quad (37)$$

is always satisfied for any ρ , inflation does not accelerate where Ω is a positive variable. Hence,

if $\Omega = \left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N\mu\nu(1-\alpha)} \right]^\alpha - \theta_p$, then when the central bank of the monetary union keeps

$\theta_G = \theta_p$, inflation does not accelerate even in the framework of endogenous growth.

4 THE EURO'S FLAW

4.1 The basic structure

The euro is examined in this section using the model of monetary union constructed in Section 3. For simplicity, the degree of relative risk aversion of the representative household is assumed to be identical in all euro member states. Productivity and the time preference rate of the representative household, however, are assumed to be heterogeneous across member states. The productivity differential parameter in member state ρ (ω_ρ) is given exogenously and is constant for any ρ . The time preference rate of the representative household in member state ρ is $\theta_{p,\rho}$ and is inversely correlated to the productivity differential parameter ω_ρ (see, e.g., Lawrance, 1991; Samwick, 1998; Ventura, 2003). The integrated time preference rate of the representative

household of all member states is $\left(\sum_{q=1}^N \omega_q \right)^{-1} \sum_{q=1}^N \theta_{p,q} \omega_q = \theta_p$. The intrinsic time preference

rate of the government of member state ρ is $\bar{\theta}_{G,\rho}$ and $\bar{\theta}_{G,\rho} > \theta_{p,\rho}$. The actual time preference rate of the government of member state ρ in period t is $\theta_{G,\rho,t}$ and it is time variable because of control by the ECB. The integrated actual time preference rate of all member governments in

period t is $\left(\sum_{q=1}^N \omega_q \right)^{-1} \sum_{q=1}^N \theta_{G,\rho,t} \omega_q = \theta_{G,t}$. For simplicity, suppose that, because of the scale

effect shown in Section 3.2.2, $\Omega = \left[\frac{\varpi \alpha \sum_{q=1}^N \omega_q}{N\mu\nu(1-\alpha)} \right]^\alpha - \theta_p$ is always satisfied. Hence, the ECB

needs to set $\theta_{G,t}$ equal to θ_p not to accelerate the overall rate of inflation in the euro area.

Because $\theta_{G,t} = \theta_P$ is kept by the ECB, each government is expected to adjust its time preference rate $\theta_{G,\rho,t}$ equal to θ_P . If a government does not sufficiently adjust its $\theta_{G,\rho,t}$ and sets $\theta_{G,\rho,t} > \theta_P$, it deviates from the expected behavior; such behavior is called a “deviation” hereafter.

4.2 Factors that generate the flaw

4.2.1 Adhering to own preferences

The law of motion for inflation shown in equation (20) indicates that inflation does not accelerate because a government acts in a stupid, foolish, or irrational manner, but rather because it behaves quite normally—it adheres to its intrinsic time preference unless an independent neutral institution (i.e., a central bank) forces it to stop doing so. However, a fundamental question arises. Even if the government is acting quite normally, is this behavior rational? In economics, rationality usually means that, given the available information, optimal decisions to achieve an objective are taken and rational behavior is generally assumed. However, can rational behavior still prevail when a government cannot optimize its behavior to achieve its objective? This special situation emerges if the central bank is perfectly independent and is firmly determined to stabilize inflation and if, at the same time, the intrinsic time preference rate of government is unchangeable. In this situation, the economy will destabilize and eventually collapse as shown in Section 2. Therefore, the government cannot achieve its objective (i.e., cannot maximize its expected utility) and can only behave irrationally in this case. Conversely, if the government wants to optimize its objective and behave rationally, it must change its time preference. Clearly, trade-offs between rationality and time preference exist in some situations, and either rationality or time preference must be endogenized.

Nevertheless, it is highly unlikely that people will not optimize their behavior to meet their objectives (i.e., maximize utility) if they have complete knowledge of the optimal path. Hence, rationality should prevail over preferences, and time preference will be endogenized when a clash between rationality and time preference occurs. If time preference is endogenized, rational decisions become possible.

Even though rationality should eventually prevail over preferences, governments will not easily change their own preferences. They will resist endogenizing them and search for options to escape from doing so—it is this stubborn nature that drives governments to deviate from the path specified by the ECB. Section 2 indicated that the inflation problem is equivalent to the deviation problem. The mechanism of inflation differentials in the euro area, therefore, must be fully examined considering this driving force of deviation.

Even though unfavorable consequences are expected if no change is made, it can be very difficult to change one’s own preferences alone. Controlling preferences therefore usually requires the help of other people or institutions, which is one of the reasons why independent central banks were established to stabilize inflation. Nevertheless, as will be examined in the following sections, the question arises whether the ECB can fully control each member government’s desire to adhere to its own time preference rate.

4.2.2 The limited capability of the ECB

The ECB faces a problem that most other central banks do not face. There are an infinite number of combinations of $\theta_{G,\rho,t}$ that satisfy $\theta_{G,t} = \left(\sum_{q=1}^N \omega_q \right)^{-1} \sum_{q=1}^N \theta_{G,\rho,t} \omega_q = \theta_P$, but the ECB cannot force its member governments to select the combination that it wants them to select. That is, the ECB cannot separately control $\theta_{G,\rho,t}$, only $\theta_{G,t}$ collectively.

As shown in Section 2.2, the central bank in the single-country model punishes the government’s deviation by raising the nominal interest rate such that $i_t = \theta_{G,t} + \pi_t + \psi$. Equation $\theta_{G,t} = i_t - \pi_t$ (equation [22]) is not satisfied until the government obeys the central bank and

lowers $\theta_{G,t}$. However, the ECB cannot effectively impose ψ separately on each member state; thereby, equation $\theta_{G,\rho,t} = i_{\rho,t} - \pi_{\rho,t}$ can be satisfied in a member state even though $\theta_{G,\rho,t} > \theta_{G,t} = \theta_P$. Even if a government behaves based on its own $\bar{\theta}_{G,\rho}$ that is different from θ_P , the ECB can neither punish nor force the government to transition to $\theta_{G,\rho,t} = \theta_{G,t} = \theta_P$. As a result, the combination of $\theta_{G,\rho,t}$ is not selected only by the ECB but rather through conflict, negotiation, and cooperation among the member governments. Thereby, the possibility exists that, at the same time, $\theta_{G,\rho,t} > \theta_P$ for some member states and $\theta_{G,\rho,t} < \theta_P$ for others and $\theta_{G,t} = \theta_P$ is kept. Unlike most other central banks, independence is not sufficient for the ECB to fully stabilize inflation.

4.2.3 Diverse inflation rates owing to non-tradability

Because all member states use the same currency, the price level would be identical across the euro area by arbitrage if all goods and services were traded freely inside the euro area. However, not all goods and services are tradable. If anything, the share of non-tradable goods and services in the euro area is large (e.g., Altissimo et al., 2005). Unlike tradable goods and services, the prices of non-tradable goods and services are not equalized by arbitrage. This price heterogeneity indicates that the rate of inflation in each member state can also be heterogeneous, and heterogeneous inflation indicates that governments may deviate from the path the ECB sets, at least temporarily. Member governments may enjoy periods when they behave based on their own intrinsic $\bar{\theta}_{G,\rho}$ that is higher than $\theta_{G,t} = \theta_P$.

Note that even though inflation is heterogeneous, the marginal product of capital in every industry in every member state is kept identical by arbitrage; that is, $\frac{\partial y_{\rho,t}}{\partial k_{\rho,t}} = \theta_P$, because capital flows freely within the euro area.

4.2.4 Current account imbalances owing to inflation differentials

Inflation differentials will lead to current account imbalances (e.g., Blanchard, 2007; Arghyrou and Chortareas, 2008; EC, 2009). Although inflation rates diverge among the member states, the prices of tradable goods and services are still generally equalized across the euro area by arbitrage. The equalization is realized by outflows of cheaper tradable goods and services from member states with lower inflation member states to the states with higher inflation. The inflowing goods and services eventually will need to be purchased with money from the exporting member states (lower inflation states) because the importing states (higher inflation states) are not obtaining money by exporting either their higher priced tradable goods or their non-tradable goods and services. A large part of borrowed money, therefore, is used not for investment but for consumption in the higher inflation member states. As a result, the trade and current account balances in member states with higher inflation will show continuous deficits.

4.3 The mechanism of the flaw

4.3.1 The utility functional

Considering the conflict between rationality and preference, the government's utility function $u_{G,\rho}(g_{\rho,t}, x_{\rho,t})$ is extended to the functional consisting of the utility function $u_{G,\rho}(g_{\rho,t}, x_{\rho,t})$ and a variable $\tilde{\theta}_{G,\rho,t}$ such that

$$\tilde{u}_{G,\rho} [u_{G,\rho}(g_{\rho,t}, x_{\rho,t}), \tilde{\theta}_{G,\rho,t}] ,$$

where $\tilde{\theta}_{G,\rho,t} = \bar{\theta}_{G,\rho} - \theta_{G,\rho,t}$.⁹ The government has a strong desire to behave based on its intrinsic time preference rate but it has to change its rate for it to behave rationally under the control of the ECB. $\tilde{\theta}_{G,\rho,t}$ represents the gap between the reality ($\theta_{G,\rho,t}$) and the desire ($\bar{\theta}_{G,\rho}$). For simplicity, only the case $\tilde{\theta}_{G,\rho,t} \geq 0$ is examined. The functional has the following properties:

$$\frac{\partial \tilde{u}_{G,\rho} [u_{G,\rho}(g_{\rho,t}, x_{\rho,t}), \tilde{\theta}_{G,\rho,t}]}{\partial \tilde{\theta}_{G,\rho,t}} < 0 \quad \text{and} \quad \frac{\partial^2 \tilde{u}_{G,\rho} [u_{G,\rho}(g_{\rho,t}, x_{\rho,t}), \tilde{\theta}_{G,\rho,t}]}{\partial \tilde{\theta}_{G,\rho,t}^2} > 0 .$$

The more $\theta_{G,\rho,t}$ is forced to decrease, the more utility decreases, but the magnitude of the decrease diminishes as the scale of the forced decrease increases. As a whole, each member government maximizes its expected utility

$$E \int_0^{\infty} \tilde{u}_{G,\rho} [u_{G,\rho}(g_{\rho,t}, x_{\rho,t}), \tilde{\theta}_{G,\rho,t}] \int_0^t \exp(-\theta_{G,\rho,s}) ds dt$$

subject to equations (3) and (35). In addition, the ECB always keeps $\theta_{G,t} = \theta_p$ for any t , by which $\theta_{G,\rho,t}$ is endogenized.

If there is an inflation differential, equation (35) cannot be satisfied. Hence, a necessary condition for satisfying equation (35) is $\theta_{G,\rho,t} = \theta_{G,t} = \theta_p$ for any ρ , and an indefinite deviation is therefore impossible. Although an indefinite deviation is impossible, temporary and intermittent deviations may be possible. However, because of equation (35) and $\theta_{G,t} = \theta_p$, deviations necessitate future corrections. Because deviations increase current account deficits and, consequently, external debt burdens (see Section 4.2.4), $\theta_{G,\rho,t}$ must be made temporarily lower than θ_p in some future periods to decrease $\pi_{\rho,t}$ and external debt burdens before current account imbalances can stabilize (i.e., before $\theta_{G,\rho,\rho} = \theta_{G,t} = \theta_p$ for any ρ is achieved). If the utility gains resulting from a temporary deviation exceed the discounted sum of disutility caused by the future correction of the deviation, the deviation will be selected as a rational choice.

Note that if a member government temporarily behaves based on a $\theta_{G,\rho,t}$ that is higher than $\theta_{G,t} = \theta_p$, then at least one of the other member states has to set its $\theta_{G,\rho}$ below $\theta_{G,t}$ during the deviating period because the ECB keeps $\theta_{G,t} = \theta_p$.

4.3.2 Rational deviations

Suppose that a member government deviates by discontinuously increasing (hereafter “jumping”) its $\theta_{G,\rho,t}$ from the ECB’s target rate ($\theta_{G,t} = \theta_p$) to $\bar{\theta}_{G,\rho}$ ($> \theta_p$) and keeping it until $t = t_1$. The government corrects the deviation after t_1 by jumping $\theta_{G,\rho,t}$ downwards to $\hat{\theta}_{G,\rho}$ ($< \theta_p$) and keeping it there during $t_1 \leq t < t_2$. After t_2 , the government keeps $\theta_{G,\rho,t} = \theta_{G,t} = \theta_p$. Hence, the government’s expected utility when it deviates and later corrects the deviation is

$$A_D = E \int_0^{t_1} \tilde{u}_{G,\rho} [u_{G,\rho}(g_{\rho,t}, x_{\rho,t}), 0] \exp(-\bar{\theta}_{G,\rho} t) dt \\ + E \int_0^{t_1} \exp(-\bar{\theta}_{G,\rho} t) dt \int_{t_1}^{t_2} \tilde{u}_{G,\rho} [u_{G,\rho}(g_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \hat{\theta}_{G,\rho})] \exp(-\hat{\theta}_{G,\rho} t) dt$$

⁹ The utility function of government is $u_{G,\rho}(g_{\rho,t}, x_{\rho,t}, y_{\rho,t})$ if the scale effect shown in Section 3.2.2 is explicitly considered. However, for simplicity, the scale effect is made implicit and $u_{G,\rho}(g_{\rho,t}, x_{\rho,t})$ is used.

$$+ E \int_0^{t_1} \exp(-\bar{\theta}_{G,\rho} t) dt \int_{t_1}^{t_2} \exp(-\hat{\theta}_{G,\rho} t) dt \int_{t_2}^{\infty} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \theta_{G,t})] \exp(-\theta_{G,t} t) dt .$$

Here, if the government does not deviate, its expected utility is

$$A_N = E \int_0^{\infty} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \theta_{G,t})] \exp(-\theta_{G,t} t) dt .$$

Hence,

$$\begin{aligned} A_D - A_N &= E \int_0^{t_1} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), 0] \exp(-\bar{\theta}_{G,\rho} t) dt \\ &\quad - E \int_0^{t_1} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \theta_{G,t})] \exp(-\theta_{G,t} t) dt \\ &\quad + E \int_0^{t_1} \exp(-\bar{\theta}_{G,\rho} t) dt \int_{t_1}^{t_2} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \hat{\theta}_{G,\rho})] \exp(-\hat{\theta}_{G,\rho} t) dt \\ &\quad - E \int_0^{t_1} \exp(-\theta_{G,t} t) dt \int_{t_1}^{t_2} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \theta_{G,t})] \exp(-\theta_{G,t} t) dt \\ &\quad + E \int_0^{t_1} \exp(-\bar{\theta}_{G,\rho} t) dt \int_{t_1}^{t_2} \exp(-\hat{\theta}_{G,\rho} t) dt \int_{t_2}^{\infty} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \theta_{G,t})] \exp(-\theta_{G,t} t) dt \\ &\quad - E \int_0^{t_2} \exp(-\theta_{G,t} t) dt \int_{t_2}^{\infty} \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), (\bar{\theta}_{G,\rho} - \theta_{G,t})] \exp(-\theta_{G,t} t) dt . \end{aligned} \quad (38)$$

Let A_1, A_2, \dots, A_6 be the first, second, ..., sixth terms of the right side of equation (38), respectively. $A_1 + A_2$ indicates the utility gain owing to the deviation, and $A_3 + A_4$ indicates the utility loss owing to the future correction. $A_5 + A_6 \approx 0$ and $A_D - A_N \approx A_1 + A_2 + A_3 + A_4$ because $\int_0^{t_1} \exp(-\bar{\theta}_{G,\rho} t) dt \int_{t_1}^{t_2} \exp(-\hat{\theta}_{G,\rho} t) dt - \int_0^{t_2} \exp(-\theta_{G,t} t) dt \approx 0$.

If the correction is implemented in a far shorter period than the deviating period and thus the scale of correction in each period is far larger than the scale of deviation in each period, then $A_1 + A_2 > -(A_3 + A_4)$ because $\frac{\partial^2 \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), \tilde{\theta}_{G,\rho,t}]}{\partial \tilde{\theta}_{G,\rho,t}^2} < 0$ and of the effect of the

discount factor. Hence, if $\frac{\partial^2 \tilde{u}_{G,\rho} [u_{G,\rho}(\mathbf{g}_{\rho,t}, x_{\rho,t}), \tilde{\theta}_{G,\rho,t}]}{\partial \tilde{\theta}_{G,\rho,t}^2}$ is sufficiently large, $A_D - A_N > 0$; that is,

the expected utility gains owing to the early deviation will exceed the discounted sum of the expected utility losses resulting from the future correction. This means that a government will rationally choose to deviate. Therefore, in a euro-type monetary union in which the central bank has only limited enforcement power, substantial deviations of member governments will happen and be left unchecked for a relatively long period.

Notice that deviation paths are not limited to the type shown above. It was assumed in the above examination that the correction is taken just after the deviation ends. However, it is possible to postpone the correction to the far future. During the period between the deviation and the postponed corrections, $\theta_{G,\rho,t} = \theta_{G,t} = \theta_p$ is kept.

4.3.3 Inflation differentials

By the law of motion for inflation, inflation will temporarily accelerate in the deviating member state even though overall inflation in the euro area does not accelerate because of ECB control.

Because the deviations should be temporary, inflation acceleration will be small scale, but non-negligible inflation differentials will be observed. If the correction is postponed to far future periods after the deviation ends, $\theta_{G,\rho,t} = \theta_{G,t} = \theta_\rho$ is kept and inflation does not accelerate during the interim period. However, because the deviation is left uncorrected, the relatively high rate of inflation continues in the deviating member state by the law of motion for inflation, and the inflation differentials thereby continue during this period. In addition, because the scale of deviation increases as the government's intrinsic time preference rate ($\bar{\theta}_{G,\rho}$) increases and the rate of time preference is empirically inversely correlated to productivity (see, e.g., Lawrance, 1991; Samwick, 1998; Ventura, 2003), relatively less productive member states (that have a relatively higher intrinsic time preference rate) will experience larger scale deviations and consequently higher inflation than relatively more productive member states. These features of inflation differentials predicted by the model are basically consistent with the observed persistent inflation differentials in the euro area.

4.3.4 Fiscal deficits

When $\theta_{G,\rho,t}$ jumps upwards, the government's fiscal balance and debts are governed by non-linear complex processes. For simplicity, these processes are examined here based on the exogenous growth model used in Section 2. The thick solid line in Figure 1 indicates the steady state values of $\frac{x_{\rho,t} - g_{\rho,t} + \varphi_{\rho,t}}{b_{\rho,t}}$ corresponding to those of $i_{\rho,t} - \pi_{\rho,t}$. Suppose that the economy is first at

steady state (point E in Figure 1). Then, by the upwards jump of $\theta_{G,\rho,t}$, the steady state moves from E to \tilde{E} . Because of the steady state shift, $\frac{x_{\rho,t} - g_{\rho,t} + \varphi_{\rho,t}}{b_{\rho,t}}$ jumps downwards from E to

J and then moves upwards on the transition path to \tilde{E} (along the thick dotted line in Figure 1). Accordingly, $g_{\rho,t}$ and $x_{\rho,t}$ jump to their transition paths and proceed on them to the new steady state. Note that, because seigniorage ($\varphi_{\rho,t}$) plays a limited role in modern economies, it is assumed here for simplicity that $\frac{\dot{\varphi}_{\rho,t}}{\varphi_{\rho,t}} = 0$ even after the jump.

By equations (14), (16) and (17),

$$\theta_{G,\rho,t} = \frac{x_{\rho,t} - g_{\rho,t} + \varphi_{\rho,t}}{b_{\rho,t}} \quad (39)$$

at any steady state (see Harashima, 2006, 2008). Hence, the upwards jump of $\theta_{G,\rho,t}$ requires a decrease of steady state $b_{\rho,t}$ and/or an increase of steady state $x_{\rho,t} - g_{\rho,t}$ to satisfy equation (39). Because both an increase of steady state $x_{\rho,t}$ and a decrease of steady state $g_{\rho,t}$ reduce the utility at steady state, the steady state $b_{\rho,t}$ is expected to decrease to satisfy equation (39). Hence, the government's real debts $b_{\rho,t}$ are smaller at the new steady state \tilde{E} than at the previous steady state E . Note that the level of $b_{\rho,t}$ is not determined only by equation (39) but also by the initial level of $b_{\rho,t}$ and exogenous shocks on $b_{\rho,t}$ (e.g., discretionary fiscal policies in case of a recession).

Because $b_{\rho,t}$ is a stock variable and cannot move drastically and discontinuously, $x_{\rho,t} - g_{\rho,t}$ (not $b_{\rho,t}$) jumps downward substantially as $\frac{x_{\rho,t} - g_{\rho,t} + \varphi_{\rho,t}}{b_{\rho,t}}$ jumps downward to J .

Here, $\frac{\dot{b}_{\rho,t}}{b_{\rho,t}} = i_{\rho,t} - \pi_{\rho,t} - \frac{x_{\rho,t} - g_{\rho,t} + \varphi_{\rho,t}}{b_{\rho,t}}$ by equation (1). In addition, $\pi_{\rho,t}$ and $i_{\rho,t}$ cannot jump and

remain at almost the same values just after the jump by the law of motion for inflation. Therefore, if the downward jump of $x_{\rho,t} - g_{\rho,t}$ is sufficiently large, $\frac{\dot{b}_{\rho,t}}{b_{\rho,t}} > 0$ and the fiscal balance ($\dot{b}_{\rho,t}$) shows deficits initially after the jump. However, as $b_{\rho,t}$ gradually increases because of the fiscal deficits, $x_{\rho,t} - g_{\rho,t}$ also gradually increases but more rapidly than $b_{\rho,t}$ to satisfy equation (39) (i.e., $\frac{x_{\rho,t} - g_{\rho,t} + \varphi_{\rho,t}}{b_{\rho,t}}$ gradually increases on the transition path from J to

\tilde{E} in Figure 1), and after a certain period, fiscal deficits turn to surpluses. The government's real debts $b_{\rho,t}$ that initially increased after the jump eventually then start to decrease and move to a lower level than the previous steady state $b_{\rho,t}$ at E (Figure 2). The fiscal balance and government debt after the jump therefore are governed by non-linear complex processes. If the deviation is not a single jump but intermittently repeated, the process of fiscal balance will become substantially more complex.

The amount by which fiscal deficits initially increase depends on the values of $\varepsilon_{g,\rho}$ and $\varepsilon_{x,\rho}$ and other conditions, including the scale of deviation. The values of $\varepsilon_{g,\rho}$ and $\varepsilon_{x,\rho}$ will be heterogeneous among the member states, similar to $\theta_{G,\rho,t}$, and the scale of deviation will be also heterogeneous. Therefore, fiscal balances after deviations will be governed by different processes across the member states. The features of non-linearity, complexity, and heterogeneity indicate that the SGP requirement that budget deficits of less than 3% of GDP are allowable whereas those over 3% must be punished in any period for any member state may not be reasonable. These features suggest that focusing only on fiscal deficits and setting an inflexible and non-country-specific ceiling on fiscal deficits and debts are not necessarily an appropriate way to prevent deviations.

4.3.5 Current account deficits

As discussed in Section 4.2.3, although inflation diverges among the member states owing to deviations, the prices of tradable goods and services are still equalized generally across the euro area by arbitrage. As a result, the trade and current account balances in the deviating member state will show continuous deficits. Accordingly, relatively less competitive firms producing tradable goods or services in deviating member states will disappear more rapidly because of the price differentials and the inflows of foreign goods and services. Industries of tradable goods and services will decline and the share of non-tradable goods and services industries will increase in deviating member states. The features of current account imbalances predicted by the model are basically consistent with the observed current account imbalances in the euro area.

If floating exchange rates were working, current account imbalances would be adjusted substantially through currency depreciation in deviating member states, but there is no such mechanism within the euro area. As a result, external debts of the deviating member states will accumulate continuously until the distortion caused by the deviation is corrected. The accumulation of external debts may not immediately threaten the euro. However, as more external debts accumulate, the economies of the deviating member states will become more vulnerable to various shocks, and because the member states' economies are closely linked, the entire economy of the euro area also becomes more vulnerable to various shocks.

4.4 Comparison with a currency peg

A foreign currency peg is similar to the situation with the euro because, in essence, more than one state uses the same currency. However, there is a fundamental difference between these situations. In the case of a currency peg, there are not only multiple governments but also

multiple central banks. Hence, the central bank can directly control its government's behavior in each country. Nevertheless, the fixed exchange ratio can only be maintained if inflation is stabilized in the pegging and pegged countries. The fixed exchange rate is not automatically kept—it is the result of work to stabilize inflation in both countries. The exchange rate will soon destabilize if the efforts to stabilize inflation are relaxed. Central banks in countries adopting a currency peg need to be sufficiently independent or the peg cannot be maintained. This is one reason why a currency peg is usually introduced as a tool to stabilize ongoing high inflation in pegging countries.

On the other hand, the euro unconditionally guarantees the same value across member states regardless of efforts to stabilize inflation in each state. Combining central banks deprives the incentive to and removes the tool to locally stabilize inflation. It may have been presumed that, if the overall inflation in the euro area is stabilized, local inflation will also naturally stabilize even though member governments are heterogeneous and independent. However, as shown in the previous sections, local inflation can be differentiated if governments are heterogeneous and independent.

4.5 *Solution?*

4.5.1 **The ECB and the SGP**

Because the ECB cannot control $\theta_{G,p,t}$ separately but only $\theta_{G,t}$ collectively, the only way for the ECB to punish deviating governments is to raise the interest rate with the hope of targeting the deviating governments. However, the higher interest rate will hurt not only the deviating member states but also non-deviating member states. Hence, this method is not practical. Alternatively, therefore, the SGP was created to control the behavior of each member government. The SGP was regarded as a substitute for the functions of a federal government. If the SGP functioned well, each $\theta_{G,p,t}$ could be controlled separately and sufficiently. However, the current financial crisis indicates that the rules stipulated in the SGP are ineffective and insufficient as a substitute. Moreover, even before the financial crisis, the SGP was criticized for not functioning well.

Two deficiencies of the SGP have often been mentioned. First, the SGP has been accused of lacking flexibility (e.g., de Grauwe, 2005). Namely, even in a severe recession, large discretionary fiscal policies are not allowed because fiscal deficits of more than 3% of GDP are prohibited. This prohibition is not necessarily groundless because it is difficult to distinguish discretionary fiscal policies from deviations, and if this restriction were relaxed, deviations would no doubt prevail. However, fiscal deficits of more than 3% of GDP have not been historically rare. In fact, actual violations of the rule have been relatively common on the pretext of discretionary fiscal policies. The SGP reform in 2005 added some flexibility to this rule, but its fundamental property was not changed.

The SGP has also been criticized for possessing weak enforcement powers (e.g., Eichengreen and Wyplosz, 1998; Buti et al., 2003). Even if a government violates a rule, the other governments cannot immediately and sufficiently punish the violating government. Furthermore, the weak enforcement power generates an unfavorable byproduct, that is, a high probability of cheating by member governments. A cheating government may expect support from other governments because the non-cheating governments want to prevent the euro area from breaking up. A government may also expect, perhaps wishfully, that relatively stronger economies in the euro area have a responsibility to stabilize the euro in any case, thereby generating moral hazard.

In addition to the abovementioned deficiencies, Section 4.3.4 shows another problem of the SGP—fiscal deficits are not necessarily an appropriate indicator of government's deviating behavior. It is well known that the relationship between fiscal deficits and inflation is empirically ambiguous (Karras, 1994; Darrat, 2000; Fischer et al., 2002). Section 4.3.4 shows that this ambiguity is attributed to the non-linear complex relationship between fiscal deficits

and $\theta_{G,\rho,t}$ (Figures 1 and 2). The movement of fiscal deficits caused by a shift of $\theta_{G,\rho,t}$ is determined by the functional form of $u_{G,\rho}(g_{\rho,t}, x_{\rho,t}, y_{\rho,t})$ and the values of $\varepsilon_{g,\rho}$, $\varepsilon_{x,\rho}$, and other parameters. The magnitude of allowable fiscal deficits will vary according to complex interactions among all of these variables. Therefore, controlling fiscal deficits is not necessarily equivalent to controlling $\theta_{G,\rho,t}$. The 3% ceiling may restrain deviations to some extent, but a significant deviation may not generate a fiscal deficit of more than 3% of GDP. As a whole, relying only on a rule that sets an inflexible ceiling on fiscal deficits and debts to prevent deviations in the behavior of governments does not appear to address real-world needs.

4.5.2 Greater political unification

Although the euro may be regarded by and large as a success because it can prevent indefinite deviations of government, this paper has pointed out an important flaw that exacerbates imbalances and instability. To fix the flaw, innovative tools must be used that separately control $\theta_{G,\rho,t}$. However, doing so is an extremely difficult task, and an alternative approach may be necessary. Consideration should be given to unifying $\theta_{G,\rho,t}$ so it would no longer have to be controlled in each country separately. A unified $\theta_{G,\rho,t}$ would mean that a federal euro area government is created, but that will be politically very difficult and unrealistic under current political conditions. A more realistic alternative is to create an institution that is not as rigid as a federal government but that can more effectively monitor and supervise member governments and more forcibly bind their activities. This supranational institution should possess similar enforcement power of a federal government in some policy fields, particularly in allocating budgets.

The creation of such a supranational institution poses fundamental problems, however. Governments decide the amount and the allocation of expenditures on defense, social welfare, education, and other areas as well as the amount and allocation of taxes imposed to cover these expenditures. These decisions are an indispensable source of the power and sovereign authority of a government. The people in a member state give the power to allocate budgets to a government, but they do not give it unconditionally. People give such power through a political process because determinations of government expenditures and taxes are fundamentally political issues. Hence, the power of allocating budgets will never be delegated to a politically neutral institution. In contrast, monetary policies are usually delegated to politically neutral central banks because the central bank is only given the power to control the time preference of government, and the power to allocate budgets still remains in the hands of the government (i.e., the people). People do not therefore regard the delegation of some authority to a central bank a renunciation of their essential sovereignty. It may represent a renunciation of a very small part of their sovereignty, but the benefits of the delegation far exceed the costs. On the other hand, people will regard that the delegation of the power to allocate budgets to a politically neutral institution as a significant renunciation of sovereignty because a politically neutral institution is not required to follow people's political demands. Therefore, the supranational institution required to fix the euro's flaw must be a fundamentally political institution similar to a federal government. This nature is important because, for the supranational institution to be sufficiently political, the national sovereignty of each member state needs to be substantially renounced and transferred to the supranational institution.

The flaw in the euro highlights the tension between national sovereignty and stability in the euro area economy. The more the member states renounce their national sovereignty, the more the euro area economy will stabilize. The current financial crisis indicates that the problem caused by this tension is economically important and implies that the balance between national sovereignty and economic stability should shift more towards economic stability. The magnitude and persistence of inflation differentials in the euro area are much more substantial than those among the states in the U.S. (Angeloni and Ehrmann, 2007; Fendel and Frenkel, 2009). The model in this paper implies that this difference emerges because of the different

degrees of political unification between the states in the U.S. and the member states of the euro area. A political mechanism that unifies political positions of the member governments on fiscal policies in a flexible manner and enforces the unified political decisions is needed to increase stability in the euro area. Any such mechanism or organization should not be governed by inflexible rules or bureaucrats but by representatives democratically elected from across the euro area who would determine overall fiscal policies at any given time.

5 CONCLUDING REMARKS

Since its creation, the euro has been criticized for lacking a unified fiscal authority, and the recent financial crisis has intensified the anxiety that the euro is seriously flawed. In this paper, a model is constructed in which the optimization behaviors of government as well as those of households, firms, and the ECB are explicitly and separately incorporated. The model indicates that inflation accelerates if the rate of time preference of the government is higher than that of the representative household; thus, the government must change its time preference for inflation not to accelerate. However, the desire to adhere to own preferences is so strong that governments seek to maintain their own time preference rates. Euro area governments can temporarily maintain their own intrinsic time preference rates because the ECB cannot implement monetary policies aimed separately and specifically at each of the member states. The model indicates that deviations in an individual government's behavior generate inflation differentials, current account imbalances, and fiscal deficits. In addition, the examination of the inflation differentials in the euro area provides important and clear evidence that inflation acceleration is not caused by monetary policies but by government behavior because inflation in the member states has diverged even though monetary policies are unified.

The SGP does not appear to have been sufficiently effective in preventing government deviations. An alternative mechanism that controls each government's time preference is required. Establishing a federal government or some other supranational institution in the euro area may help solve the problem, but it will be very difficult and perhaps even unrealistic under current political conditions. In any case, any supranational or federal institution created must be a political institution that represents the political will of the people.

The current financial crisis implies that the flaw of the euro shown in this paper is economically important. Furthermore, other types of deviations may be induced because of the lack of a federal government. The flaw has made the euro substantially vulnerable to various shocks, and therefore the balance between national sovereignty and economic stability should be shifted more towards stability through a higher degree of political unification or the probability of breakup of the euro area remains relatively high.

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Figure 1 *The transition path after the jump of $\theta_{G,\rho}$*

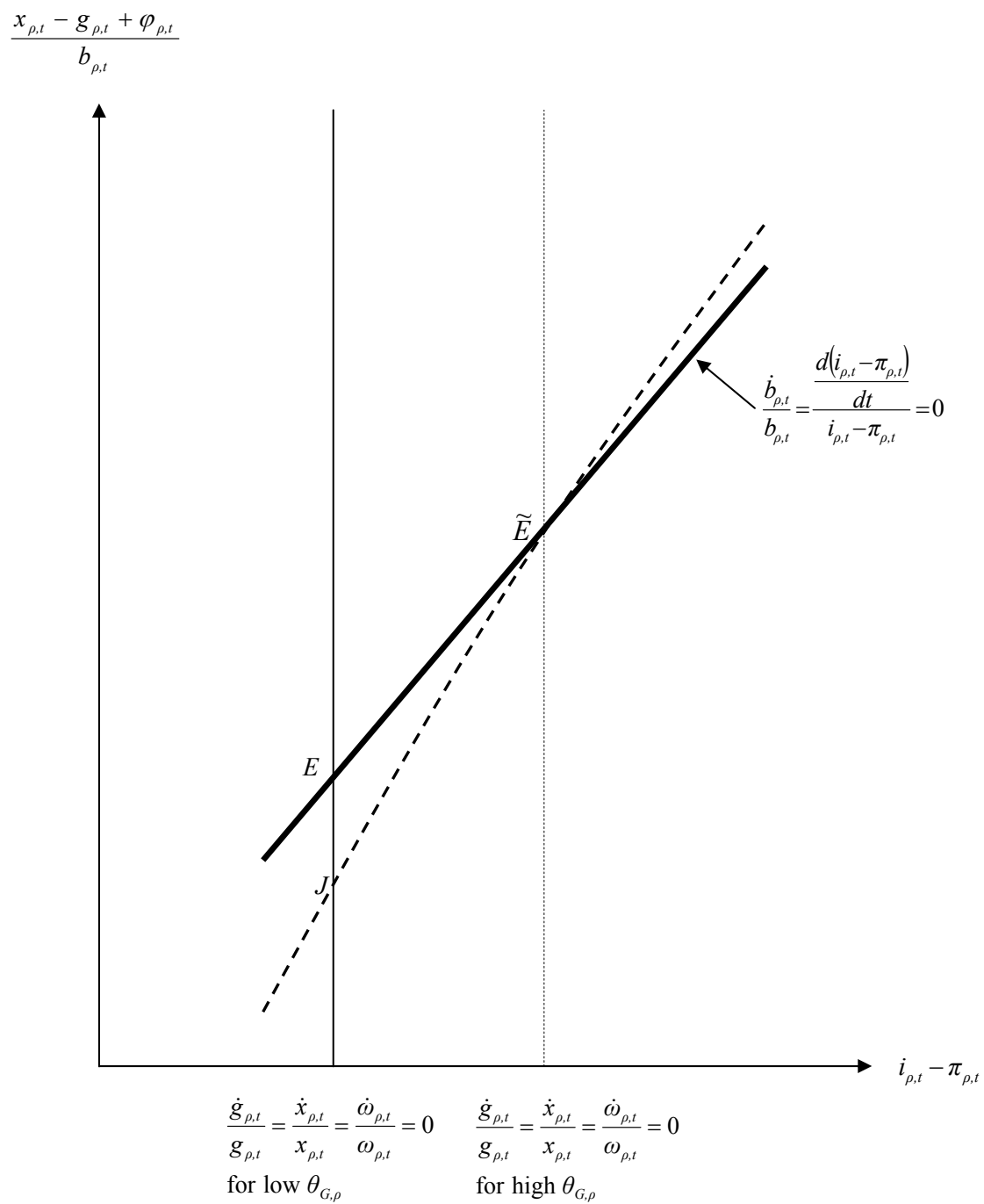


Figure 2 *The government's real debts after the jump of $\theta_{G,\rho}$*

