Instability in U.S. Inflation: 1967–2005

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Concerns about price stability and high, persistent, and volatile inflation are universal among central bankers. These concerns are institutionalized in the United States by the Federal Reserve Act in its statement of monetary policy objectives:

The Board of Governors of the Federal Reserve System and the Federal Open Market Committee shall maintain long run growth of the monetary and credit aggregates commensurate with the economy's long run potential to increase production, so as to promote effectively the goals of maximum employment, stable prices, and moderate long-term interest rates. (Federal Reserve Act, sec. 2A)

Although the price stability goal is wedged between mandates to promote employment and restrain long-term interest rates, maintaining a stable price level has come to dominate discussions among academic economists and many central bankers. Statements by Federal Reserve policymakers have been remarkably consistent about what constitutes the price stability objective over the past twenty years. For example, in 1994 Alan Greenspan told a congressional subcommittee, "We will be at price stability when households and businesses need not factor expectations of changes in the average level of prices into their decisions" (1994). This statement suggests that price stability occurs when the only source of inflation dynamics is unpredictable shocks whose size does not vary "too much" over time.

This article studies U.S. inflation, inflation growth, and price level dynamics. The analysis is disciplined with autoregressive (AR), moving average (MA), and unobserved components (UC) models. The models produce mean inflation; inflation and inflation growth persistence; and inflation, inflation growth, and price level volatility estimates for a sample that begins in January 1967 (1967M01) and ends with September 2005 (2005M09). Although this article is silent on the success of policies aimed at price stability, these estimates reveal whether the persistence

and volatility of inflation, inflation growth, and the price level have changed during the past forty years.

The disinflation of the 1980s suggests that inflation became less persistent and volatile in the 1990s and early 2000s compared to the inflation of the 1970s. For example, Stock and Watson (2005) report that quarterly U.S. inflation became less persistent and volatile after 1984. This finding suggests that it is possible to better forecast inflation. However, lower inflation volatility also makes it more difficult to

The estimates in this article reveal whether the persistence and volatility of inflation, inflation growth, and the price level have changed during the past forty years. choose the best inflation forecast from among a set of competing models. Stock and Watson (1999, 2005) verify the impact of lower persistence and volatility on post-1984 inflation forecasts.¹

Compared to the aims of Stock and Watson (2005), the goal of this article is modest. The article presents evidence about

inflation, inflation growth, and price level dynamics that complements Stock and Watson's evidence. Estimates of AR, MA, and UC models are reported in this article on the 1967M01–2005M09 sample and on two samples that roll through the 1970s, 1980s, and 1990s. The two rolling samples, described in a later section, produce AR, MA, and UC model estimates that provide information about instability in mean inflation and the persistence and volatility of inflation and inflation growth.

Four price level measures—different versions of the monthly consumer price index (CPI) and monthly personal consumption expenditure deflator (PCED)—are studied in this article. The CPI and PCED deflators are defined as CPI-CORE and PCED-CORE, which exclude food and energy items, and CPI-ALL and PCED-ALL, which include the relevant universe of consumer goods. These four series provide information on price level, inflation, and inflation growth.

This article reports AR persistence and volatility estimates that are sensitive to the choice of sample. For example, the first rolling sample yields AR persistent estimates that exhibit little change after the 1973–75 recession for the four inflation rates. When the second rolling sample drops observations from the 1970s for CPI inflation and from the 1970s and 1980s for PCED inflation, drift in the AR coefficients suggests instabilities in inflation persistence.

The MA and UC model estimates appear consistent with instabilities in the persistence and volatility of CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE inflation growth and levels. Especially striking are MA and UC model estimates on the second rolling sample that suggest PCED-CORE inflation is serially uncorrelated subsequent to the early 1990s recession, a result that is affirmed by the AR persistence estimates. Thus, a reasonable current forecast of PCED-CORE inflation might be its average of the past fifteen years. Whether such a forecast is consistent with the Greenspan (1994) notion of price stability is outside the scope of this article.

The Models

This section reviews the empirical models: a *p*th-order autoregression, AR(*p*); a firstorder moving average, MA(1); and an unobserved components-local level (UC-LL) model. These models are employed to study inflation, inflation growth, and price level dynamics; the choice of these models is guided by the literature on inflation dynamics. For example, Stock and Watson (2005) report estimates of AR(*p*), MA(1), and UC models on quarterly inflation and inflation growth. This article employs similar models but engages monthly samples of CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE. The AR(p) model yields estimates of average or mean inflation, inflation persistence, and inflation volatility. These estimates are generated by AR(p) models written in deviations from mean inflation,

$$\boldsymbol{\pi}_{l} - \boldsymbol{\pi}_{0} = \sum_{j=1}^{p} \boldsymbol{\gamma}_{j} (\boldsymbol{\pi}_{l-j} - \boldsymbol{\pi}_{0}) + \boldsymbol{\varepsilon}_{l},$$

where inflation, π_t , is defined as the difference between the (natural) log of the month *t* price level, P_t , and month t - 1 price level, $\pi_t = 1200 \times (\ln P_t - \ln P_{t-1})$, π_0 is mean inflation, and ε_t is the inflation forecast innovation or shock. Maximum likelihood estimates (MLEs) of the AR(*p*) are generated from Kalman filter iterations. (See the appendix for details.)

Information about inflation persistence is contained in the γ_j s. One measure of inflation persistence is the sum of the γ s, defined by $\gamma(\mathbf{1}) = \sum_{j=1}^{p} \gamma_j$. This sum represents the cumulative response of inflation to its own shock, ε_t . Another metric of inflation persistence is the largest AR root of the γ s, Λ .² The largest eigenvalue Λ of the γ s captures the speed at which inflation returns to its long-run average in response to ε_t .³ Since $\gamma(\mathbf{1})$ and Λ are functions of the AR coefficients, $\gamma_1 \dots \gamma_p$, these statistics reveal different aspects of inflation persistence. The length of time inflation takes to return halfway to its long-run mean is a function of the largest eigenvalue Λ , ln0.5/ln Λ . Inflation persistence rises as $\gamma(\mathbf{1})$ and Λ approach 1 (from below).

As inflation persistence rises, it takes on a unit root and becomes nonstationary. This condition arises when, for example, $\gamma(1) \ge 1$. Stock and Watson (2005) report estimates of $\gamma(1)$ larger than 1 that point to a unit root in quarterly U.S. inflation since 1970. A lesson they draw is that it is better to study models of inflation growth, $\Delta \pi_t = \pi_t - \pi_{t-1}$, rather than the level of inflation. One such model is the MA(1) process,

$$\Delta \pi_t = \eta_t - \theta \eta_{t-1},$$

where θ is the MA1 coefficient of inflation growth and η_t is the MA(1) mean zero forecast innovation or shock, with homoskedastic standard deviation σ_{s} .⁴

Estimates of the MA(1) coefficient θ contain information about inflation growth persistence. The MA(1) yields the AR(∞), $\Delta \pi_i = \sum_{j=1}^{\infty} \vartheta_j \Delta \pi_{i,j} + \eta_i$, where $\vartheta_j = \theta^j$, given $|\theta| \in (-1, 1)$. The sum $\vartheta(\mathbf{1})$ equals $-\theta/1 - \theta$. Therefore, the long-run response of inflation growth to its shock η_i increases as $\theta \rightarrow 1$. At $\theta = 1$, the speed of adjustment of inflation to an own shock is instantaneous.

It is interesting to explore the impact of $\theta = 1$ on the MA(1) of inflation growth. In this case, $\Delta \pi_t = \Delta \eta_t$. Since the difference operator Δ appears on either side of the equality, the Δ operators cancel. The result is that inflation collapses to the white noise process, $\pi_t = \eta_t$.⁵ When $\theta = 1$, inflation is unforecastable because it is driven only by the unpredictable shock η_t .

^{1.} Hansen, Lunde, and Nason (2005) provide similar evidence. They apply their metric for choosing the best forecasting models on pre- and post-1984 samples. The Hansen, Lunde, and Nason metric finds it more difficult to distinguish between competing inflation forecasting models in the post-1984 sample. Nonetheless, that study is able to identify several Phillips curve models that outperform a random walk model in out-of-sample inflation forecasting exercises across the two samples. This result stands in contrast to results in Atkeson and Ohanian (2001) and Fisher, Liu, and Zhou (2002).

^{2.} Computation of Λ is described in the appendix.

^{3.} Another way to describe Λ is that it is the speed of adjustment of inflation along its transition path.

^{4.} Nelson and Schwert (1977) and Pearce (1979) also find that an integrated MA(1) best fits U.S. inflation.

^{5.} This white noise process for inflation ignores $\pi_{\scriptscriptstyle 0}$.

Another implication of $\theta = 1$ is that the price level is a random walk, $\ln P_t = \ln P_{t-1} + \eta_t$. A random walk forces persistence onto the price level because an increase in η_t never decays regardless of the length of the forecast horizon.⁶ For example, the forecast of $\ln P_{t+j}$, j > 1, is $\ln P_{t-1} + \eta_t$, according to the random walk. A random walk in the price level also sets its trend to the sum of the shocks, $\ln P_t = \sum_{i=0}^{\infty} \eta_{t-i}$.

The UC-LL model imposes random walks on $\ln P_t$ and π_t . Besides placing a random walk trend in the price level, the UC-LL model endows inflation with a random walk that measures deviations from the price level trend. A convenient way to write the UC-LL model is

$$\begin{split} & \ln P_{t} = \mu_{1,t}, \\ & \mu_{1,t+1} = \mu_{1,t} + \mu_{2,t} + \delta_{t+1}, \, \delta_{t+1} \sim \mathbf{N}(0, \, \sigma_{\delta}^{2}), \\ & \mu_{2,t+1} = \mu_{2,t} + \psi_{t+1}, \, \psi_{t+1} \sim \mathbf{N}(0, \, \sigma_{\psi}^{2}), \end{split}$$

where $\mu_{1,t}$ denotes the price level trend, δ_t is its forecast innovation, $\mu_{2,t}$ represents trend deviations from the price level, and ψ_t is its forecast innovation.⁷ When δ_{t+1} rises, the impact on $\mu_{1,t+j}$ ($j \ge 1$) and $\ln P_{t+j}$ is permanent because it never decays. The same response is generated by the shock to trend deviations from the price level, ψ_{t+1} .

The UC-LL model provides estimates of expected inflation, $\mathbf{E}_{i}\pi_{t+1}$.⁸ Recognize that $\Delta \ln P_{t} = \mu_{1, t} - \mu_{1, t-1} = \mu_{2, t} + \delta_{t+1}$. Next, use the expectations operator, \mathbf{E}_{t} {·}, to find $\mathbf{E}_{t} \Delta \ln P_{t+1} = \mathbf{E}_{t}\pi_{t+1} = \mu_{2, t}$. Thus, deviations from the price level trend provide estimates of expected inflation. These deviations are persistent—a random walk, in fact—and have innovations, ψ_{t+1} , whose impact on $\mathbf{E}_{t}\pi_{t+1}$ is permanent. Given MLEs of the UC-LL model, $\mathbf{E}_{t}\pi_{t+1}$ can be computed using the Kalman filter or smoother.⁹

Data and Sample Construction

The four series studied are CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE. ¹⁰The sample begins with 1967M01 and runs to 2005M09, providing 465 observations.

Evidence of instability in inflation, inflation growth, and price level dynamics on the MLEs of AR(p), MA(1), and UC-LL models is explored with two samples that move or roll through the entire sample. The process involves the following steps:

- 1. The first rolling sample always starts with 1967M01, and its initial pass through the data sets its last observation to J = 1972M08, which covers 15 percent of the entire sample.
- 2. The second rolling sample starts where the first rolling ends—at the next observation J + 1 = 1972M09—and ends with 2005M09, which is the remaining 85 percent of the sample.
- 3. Next, the first rolling sample is extended one observation to J = 1972M09, which forces the second rolling sample to commence with J + 1 = 1972M10, but the second sample retains 2005M09 as its final observation.
- 4. The procedure is complete when the last observation of the first rolling sample reaches J = 1999M09, which is 85 percent of the entire sample, and J + 1 = 1999M10 is the initial observation of the second rolling sample that ends with 2005M09, which represents the other 15 percent of the sample.

Steps 1–4 create two rolling samples on the four price indexes from which 326 sets of MLEs of the AR(p), MA(1), and UC model parameters are taken.

Table 1 Summary of Empirical Results

	CPI-ALL	CPI-CORE	PCED-ALL	PCED-CORE
Mean π First rolling sample	Falls at end of second oil price shock	Same	Same	Same
Second rolling sample	Falls at end of first oil price shock	Same	Same	Same
Persistence First rolling sample	Near 1 after 1973–75 recession	Same	Same	Same
Second rolling sample	Falls during 1980 recession	Falls at 1990–91 recession	Same as CPI-ALL	Same as CPI-CORE
Volatility First rolling sample	Rises at first oil price shock	Same	Same	Same
Second rolling sample	Rises at 1990–91 recession	Falls at 1980 recession	Same as CPI-ALL	Falls at 1981–82 recession

Results

This section reports MLEs of AR(p), MA(1), and UC-LL models on the CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE indexes. The entire 1967M01–2005M09 sample and the two rolling samples are used to produce estimates. Table 1 summarizes the results.

AR(*p***) model estimates.** Table 2 presents MLEs of AR(*p*)s. Lag lengths of the AR(*p*)s are set by the Schwarz information criterion (SIC), where p = 1, ..., 18.¹¹ Compared to CPI-ALL and PCED-ALL inflation, CPI-CORE and PCED-CORE inflation have smaller estimated means, $\hat{\pi}_0$, and are less volatile as measured by estimates of the standard deviation of regression residuals, $\hat{\sigma}_{\epsilon}$. Also, CPI inflation is higher on average and more volatile than PCED inflation given the MLEs of $\hat{\pi}_0$ and $\hat{\sigma}_{\epsilon}$.

The estimates of the AR(p)s yield evidence that CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE inflation are persistent on the 1967M01–2005M09 sample. Sums of the estimated $\gamma_i s$, $\hat{\gamma}(\mathbf{1})s$, are all greater than 0.8. The estimates of the largest eigenvalue,

^{6.} The price level random walk ignores drift produced by π_0 .

^{7.} Harvey (1990) and Gourieroux and Monfort (1997) sketch the UC-LL model. The appendix outlines methods to estimate it and the MA(1) model.

^{8.} $\mathbf{E}_{\{\cdot\}}$ is the mathematical expectations operator conditional on date t information.

^{9.} Hamilton (1994) presents methods to compute the Kalman filter and smoother; also see the appendix.

^{10.} The CPI equals the ratio of the date t value of a fixed market basket of goods to the same fixed market basket valued at the base year, which is 1982–84 at the moment. The PCED weights are chained to the 2000 base year. This article uses data available on December 1, 2005.

^{11.} Besides the SIC, the Akaike information criterion (AIC) and likelihood ratio (LR) tests are computed. It is no surprise that the AIC picks a longer lag length than the SIC for CPI-ALL (p = 13), CPI-CORE (p = 9), and PCED-ALL (p = 13) but p = 6 for PCED-CORE inflation. LR tests select ps that fall between SIC and AIC choices except for PCED-CORE inflation (p = 13).

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	CPI-ALL	CPI-CORE	PCED-ALL	PCED-CORE
$\hat{\pi}_{_0}$	4.64	4.36	4.10	3.97
	(0.71)	(0.73)	(0.87)	(0.92)
Ŷı	0.40	0.31	0.41	0.29
	(0.07)	(0.05)	(0.06)	(0.08)
$\hat{\gamma}_2$	0.14	0.31	0.04	0.07
	(0.06)	(0.07)	(0.06)	(0.05)
γ̂₃	0.06	0.05	0.09	0.18
	(0.05)	(0.06)	(0.05)	(0.05)
Υ̂4	0.08	-0.06	0.06	0.10
	(0.05)	(0.06)	(0.05)	(0.05)
$\hat{\gamma}_5$	0.15	0.10	0.15	0.07
	(0.06)	(0.05)	(0.06)	(0.05)
$\hat{\gamma}_6$	_	0.17 (0.06)	0.16 (0.05)	0.22 (0.05)
$\hat{\gamma}(\textbf{1})$	0.83	0.89	0.90	0.92
	(0.05)	(0.06)	(0.04)	(0.04)
Â	0.94	0.96	0.97	0.98
	[11.7]	[16.3]	[20.5]	[29.4]
$\hat{\sigma}_{\epsilon}$	2.65	2.03	1.89	1.50
	(0.15)	(0.13)	(0.07)	(0.09)

Table 2
Estimates of AR(p)s of Inflation: Sample, 1967M01–2005M09

Notes: Heteroskedastic-consistent asymptotic standard errors appear in parentheses. The persistence measures are $\hat{\gamma}(\mathbf{1}) = \sum_{i=1}^{p} \hat{\gamma}_{i}$ and $\hat{\Lambda}$, which is the largest eigenvalue of the estimated AR coefficients $\hat{\gamma}_{i}$ j = 1, ..., p. Numbers in brackets are estimates of the half-life (in years) of the response of inflation to an own shock, according to the persistence measure In0.5/In $\hat{\Lambda}$.

 $\hat{\Lambda}$, of the $\hat{\gamma}_j$ s are no smaller than 0.94. The $\hat{\Lambda}$ s translate into measures of the half-life of the response to an own shock of about twelve and sixteen years for CPI-ALL and CPI-CORE inflation, respectively. The PCEDs are more persistent than the CPIs because the former's $\hat{\Lambda}$ s predict between twenty and twenty-nine years for the half-life of the response to an own shock. Also, note that CORE inflation is more persistent than ALL inflation.

Table 2 presents MLEs that suggest monthly CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE inflation are persistent. However, this is not evidence that U.S. inflation has a unit root. Rather than report unit root tests, estimates of the largest AR root of these inflation measures, along with 95 percent confidence intervals, are reported next.

Andrews and Chen (1993) develop an (approximate) median-unbiased estimator of the largest AR root of a time series.¹² The largest monthly median-unbiased AR root of CPI-ALL inflation is close to but less than 1 at 0.9965, which fails to support the unit root hypothesis on the 1967M01–2005M09 sample. However, this estimate predicts a half-life of an own shock to CPI-ALL inflation of 16.5 years, which is long-lived relative to a sample of nearly thirty-nine years.¹³ The evidence supports a unit root in the three other inflation rates because the Andrews-Chen median-unbiased estimator yields 95 percent confidence intervals of the largest AR root of CPI-CORE, PCED-ALL, and PCED-CORE inflation equal to [0.9863 1.0004], [0.9868 1.0007], and [0.9900 1.0017], respectively.

Part of the puzzle of U.S. inflation dynamics is whether it suffers from instability. For example, Cogley and Sargent (2001) argue that shifts in the structure of monetary policy alter the process generating inflation. Since such changes can force inflation to appear nonstationary, which can be confused for a unit root, they raise questions about the stability of persistence estimates and unit root tests of inflation.

Figure 1 plots mean inflation estimates, $\hat{\pi}_{0,t}$, constructed on the two rolling samples and four inflation measures.¹⁴ The first rolling sample produces $\hat{\pi}_{0,t}$ on observations that always begin with 1967M01 and end with J = 1972M08, ... 1999M09. For example, the first element of the line plotting the first rolling sample is estimated on a 1967M01–1972M08 sample, the second element on a 1967M01–1972M09 sample, and so on. The figure also includes plots of $\hat{\pi}_{0,t}$ estimated on the second rolling sample, which runs from J + 1 = 1972M09, ..., 1999M10 to 2005M09. Thus, plots of $\hat{\pi}_{0,t}$ are obtained from the first rolling sample by adding an observation to its end at each date J, while the second rolling sample sequentially eliminates the initial observation as J + 1 advances from 1972M09 to 1999M10.

The four windows of Figure 1 show that $\hat{\pi}_{0,t}$ fell during several of the recessions of the last forty years. The largest drop in $\hat{\pi}_{0,t}$ for the four inflation measures occurs in the 1973–75 recession. However, $\hat{\pi}_{0,t}$ rises for CPI inflation in the 1980 recession in the first rolling sample, while $\hat{\pi}_{0,t}$ shows little change for PCED inflation in the same period for this sample. The recessions of 1980 and 1981–82 see lower $\hat{\pi}_{0,t}$ for the four inflation measures on the second rolling sample. The first rolling sample also finds $\hat{\pi}_{0,t}$ drops in the recession of 1981–82. Subsequent to this recession, $\hat{\pi}_{0,t}$ falls, continuing for the four inflation rates on the rest of the two rolling samples. By the end of the first (second) rolling sample, CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE $\hat{\pi}_{0,t}$ equal 4.8 (2.8), 4.8 (2.1), 4.1 (2.3), and 4.0 (1.7 percent), respectively.

Figure 1 also shows that prior to mid-1974 the second rolling sample yields larger $\hat{\pi}_{0,t}$ than the first rolling sample across all inflation measures. This pattern is reversed subsequent to the end of the 1973–75 recession. The first rolling sample also reveals that $\hat{\pi}_{0,t}$ begins to drift higher after 1975 and peaks prior to the 1980 recession at about 7 percent for CPI inflation, 6 percent for PCED-ALL inflation, and 5.5 percent for PCED-CORE inflation. Since the second rolling sample produces a fall in mean inflation prior to (or around) the 1980 recession, it points to possible instability in $\hat{\pi}_{0,t}$ for the four inflation rates toward the end of the 1970s.

- 13. Stock (1991) and Andrews and Chen (1993) discuss that a least squares estimate of the largest AR root of a unit root process is biased downward. This result explains the smaller root of CPI-ALL inflation to an own shock reported in Table 2 compared to the estimate of 0.9965 of the medianunbiased estimator.
- 14. The two rolling samples yield MLEs that suggest using tests, say, by Andrews (1993), of parameter instability given an unknown break date. The problem is that the Hansen (1997) and Andrews (2003) critical values cannot always be used because the two rolling samples produce MLEs of the AR(p)s, MA(1), and UC-LL models that are often on the boundary of the permissible parameter space, which implies that critical values would have to be constructed on a case-by-case basis.

^{12.} Estimates of the largest AR root rely on AR(6)s that contain an intercept but not a time trend.



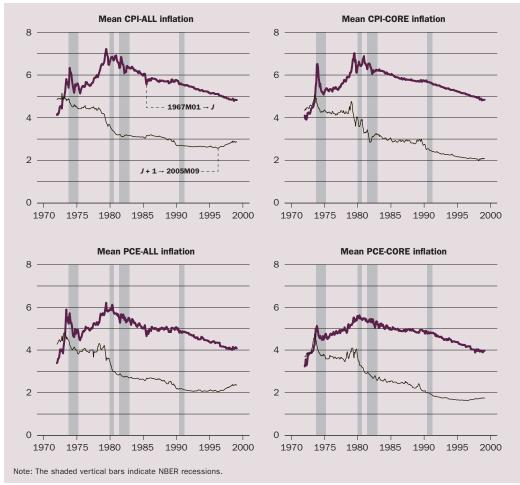
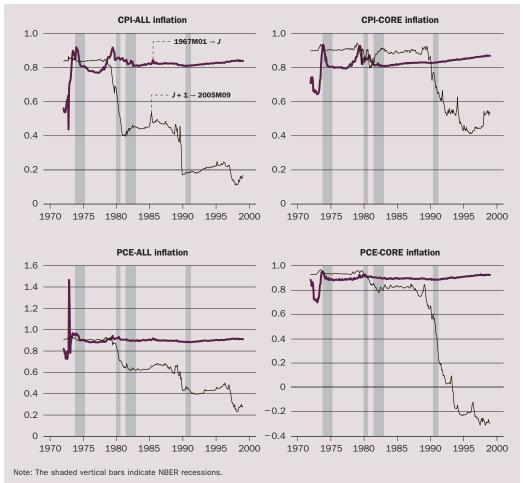


Figure 2 presents estimates of time variation in inflation persistence, $\hat{\gamma}(\mathbf{1})_{t}^{15}$ The first rolling sample yields plots of $\hat{\gamma}(\mathbf{1})_{t}$ that remain close to but below 1 from just before the 1973–75 recession to 1999M09. The second rolling sample generates $\hat{\gamma}(\mathbf{1})_{t}$ that are close to 1 until the 1980 recession for the ALL inflation rates and until the 1990–91 recession for the CORE inflation series. Prior to the latter recession, the second rolling sample generates $\hat{\gamma}(\mathbf{1})_{t}$ that drop from 0.9 to nearly 0.4 in 1996 for CPI-CORE inflation before rising to about 0.55 in 1999. PCED-CORE inflation persistence exhibits the same behavior except that its $\hat{\gamma}(\mathbf{1})_{t}$ turns negative in the mid-1990s and remains negative for the remainder of the second rolling sample; this downturn suggests either a negatively serially correlated or a serially uncorrelated process once observations from the 1970s and 1980s leads to smaller persistence estimates for the four inflation series.

Sargent (1999) provides an interpretation of the first and second rolling sample $\hat{\gamma}(\mathbf{1})_{i}$ s found in Figure 2. In his analysis, a key element is the interaction of beliefs about monetary policy and the discount applied to past observations, say, on inflation. For example, discounting past observations can lead to less inflation persistence





because, according to Sargent, discounting is a reasonable response by monetary policy if inflation dynamics are suspected of being unstable. Whether this explanation accounts for the past forty years of U.S. inflation and monetary policy is not addressed by this article, but Cogley and Sargent (2005) and Sargent, Williams, and Zha (forthcoming) provide useful analyses.

Figure 3 presents plots of the volatility of the four inflation series measured by $\hat{\sigma}_{\epsilon}$. Given the first rolling sample, plots of $\hat{\sigma}_{\epsilon,t}$ support the view that CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE inflation volatility began to increase around the first oil price shock of the mid-1970s, continuing until the end of the 1981–82 recession before leveling off or declining in the early to mid-1980s.

The second rolling sample generates $\hat{\sigma}_{\epsilon,t}$ plots that give a different view of inflation volatility. Figure 3 shows that volatility in the four inflation measures began to drop off subsequent either to the second oil price shock or to the 1981–82 recession based

^{15.} Plots of Λ_t yield the same qualitative evidence about persistence for CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE inflation using the two rolling samples. These plots are available on request.

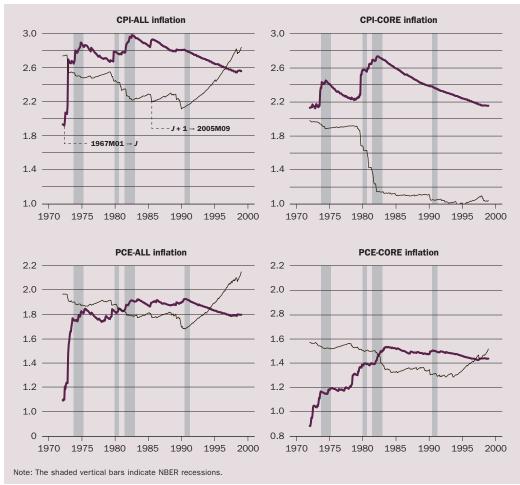


Figure 3 Time Variation in Standard Deviation of Inflation AR Residuals

on the second rolling sample. CPI-CORE inflation has the largest fall in $\hat{\sigma}_{\epsilon,t}$, while the other three inflation measures decline less.

There is no consistent pattern to inflation volatility instability according to the AR(p) model estimates. For CPI-ALL inflation, instability in $\hat{\sigma}_{\epsilon, i}$ possibly exists between the 1980 recession and the late 1990s. The 1980 recession begins a period of instability in $\hat{\sigma}_{\epsilon, i}$ for CPI-CORE inflation. The beginning and end of the two rolling samples most likely suggest when instability in $\hat{\sigma}_{\epsilon, i}$ of PCED-ALL inflation can be found. For PCED-CORE inflation, instability in $\hat{\sigma}_{\epsilon, i}$ appears to occur from 1972M08 to the 1980 recession. Thus, there seems to be no consistent pattern of instability in $\hat{\sigma}_{\epsilon, i}$ for the four inflation rates.

MA(1) model estimates. Table 3 reports estimates of the MA(1) coefficient, $\hat{\theta}$, and the standard deviation of the MA(1) residual, $\hat{\sigma}_{\eta}$, on the 1967M01–2005M09 sample. Estimates of $\hat{\theta}$ are similar across the four inflation growth measures. The point estimates range from 0.72 to 0.78, which predict that within one month inflation growth loses about three-fourths of the increase caused by an own-unit shock. However, inflation growth is lower by about 2.5 to 3.5 percent in the long run given such a shock,

	CPI-ALL	CPI-CORE	PCED-ALL	PCED-CORE
ô	0.75	0.72	0.75	0.78
	(0.05)	(0.06)	(0.05)	(0.05)
$\hat{\sigma}_{\eta}$	2.67	2.07	1.94	1.53
	(0.15)	(0.15)	(0.08)	(0.09)
$\hat{\vartheta}(1)$	-2.97	-2.56	-2.93	-3.45
	(0.39)	(0.34)	(0.37)	(0.49)

Table 3	
Estimates of Inflation Growth MA(1): Sample, 1967M01–2005M0)9

Note: Heteroskedastic-consistent asymptotic standard errors appear in parentheses.

as measured by $\vartheta(1)$. This result indicates inflation growth is subject to large lowfrequency fluctuations. Not unexpectedly, $\hat{\sigma}_{\eta}$ shows that CPI-ALL (PCED-ALL) inflation growth is more volatile than CPI-CORE (PCED-CORE) inflation growth. PCED-ALL and PCED-CORE inflation growth are also less volatile than their CPI counterparts.

Figure 4 suggests instability in $\hat{\theta}_i$ across the four inflation growth measures and the two rolling samples. Instability in $\hat{\theta}_i$ appears to arise between the recessions of 1980 and 1981–82 for CPI-ALL inflation growth and the first oil price shock for CPI-CORE, PCED-ALL, and PCED-CORE inflation growth. Also, the first rolling sample generates $\hat{\theta}_i$ that are close to 0.70 and stable subsequent to the 1981–82 recession. The plots of $\hat{\theta}_i$ drift toward 1 for the four inflation growth measures on the second rolling sample around the 1980 recession for the CPI inflation growth rates and the 1973–75 recession for the PCED inflation growth rates.

A prominent feature of the bottom right window of Figure 4 is that $\hat{\theta}_t = 1$ for PCED-CORE inflation growth on the second rolling sample from 1992M04 to 1999M10. The impact on inflation dynamics is that the MA(1) collapses to $\pi_t = \eta_t$ (ignoring mean inflation) when $\theta = 1$. Thus, the second rolling sample yields $\hat{\theta}_t$ that predict PCED-CORE inflation is driven only by white noise shocks from the recovery of the early 1990s to 1999M10. This result matches the small AR persistence estimates reported in this article for PCED-CORE inflation and evidence reported by Stock and Watson (2005).

Figure 5 contains plots of $\hat{\sigma}_{\eta,t}$ for the four inflation growth series. CPI-ALL inflation growth and the first rolling sample yield $\hat{\sigma}_{\eta,t}$ that are below those of the second rolling sample except around the first oil price shock. CPI-CORE inflation growth and the first rolling sample produce $\hat{\sigma}_{\eta,t}$ that are always above those of the second rolling samples. The second oil price shock matters for CPI-CORE inflation growth volatility because around this time $\hat{\sigma}_{\eta,t}$ falls by 45 and 70 percent on its first and second rolling samples.

The bottom row of graphs in Figure 5 includes plots of $\hat{\sigma}_{\eta,t}$ that qualitatively resemble plots of $\hat{\sigma}_{\varepsilon,t}$ for PCED-ALL and PCED-CORE inflation in Figure 3. Thus, the MA(1) and AR(*p*) models produce PCED inflation growth and inflation volatility estimates that are similar.

UC-LL model estimates. Table 4 provides estimates of the standard deviations of innovations to the price level trend, $\hat{\sigma}_{\delta}$, and to price level trend deviations, $\hat{\sigma}_{\psi}$. The largest estimates of $\hat{\sigma}_{\delta}$ and $\hat{\sigma}_{\psi}$ are obtained from the CPI indexes. The last row of the table shows that shocks to the price level trend dominate fluctuations in the four

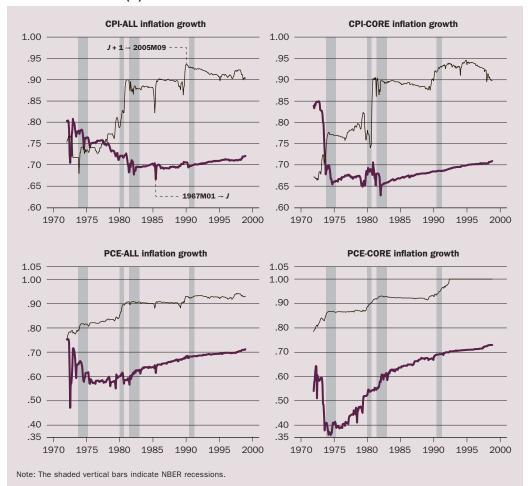


Figure 4 Time Variation in MA(1) Coefficient of Inflation Growth

price indexes because $\hat{\sigma}_{\delta}$ is always larger than $\hat{\sigma}_{\psi}$ by a factor of almost three to four. Also, note that the largest estimated ratio of $\hat{\sigma}_{\delta}$ to $\hat{\sigma}_{\psi}$ is for PCED-CORE.

The UC-LL model predicts that inflationary expectations equal trend price level deviations, $\mathbf{E}_{t}\pi_{t+1} = \mu_{2,t}$. Figure 6 contains smoothed and filtered estimates of $\hat{\mu}_{2,t}$ computed from MLEs of the UC-LL model for the four price indexes on the 1967M01–2005M09 sample. Although the filtered $\hat{\mu}_{2,t}$ are more volatile and "choppier" than smoothed $\hat{\mu}_{2,t}$, the latter have earlier turning points because smoothing employs information in the entire 1967M01–2005M09 sample. Only observations from 1967M01 to date *t* are available to compute filtered $\hat{\mu}_{2,t}$.

Estimates of $\mathbf{E}_{t}\pi_{t+1}$ reveal that the relatively small $\hat{\sigma}_{\varphi}$ of Table 3 generates economically important fluctuations in inflationary expectations. For example, CPI estimates of $\mathbf{E}_{t}\pi_{t+1}$ peak during every recession during the 1967M01–2005M09 sample except the 2001 recession, as found in the top row of graphs in Figure 6. These plots show peaks in CPI-ALL and CPI-CORE filtered (smoothed) expected annual inflation rates of 12.4 and 12.7 (10.9 and 11.6) percent at 1974M08 and 1974M07 (1974M06 and 1974M06) and 14.8 and 14.2 (13.4 and 12.8) percent at 1980M03 (1979M12).

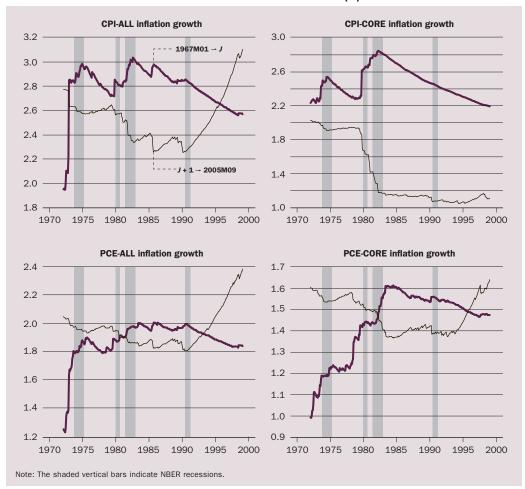


Figure 5 Time Variation in Standard Deviation of Inflation Growth MA(1) Residuals

Subsequently, filtered (smoothed) $\mathbf{E}_{t}\pi_{t+1}$ falls to -0.9 (0.7) percent by 1986M04 (1986M02) for CPI-ALL and to 3.4 (3.6) percent by 1986M05 (1986M04) for CPI-CORE. At 1990M09 and 1990M07 (1990M06 and 1990M05), filtered (smoothed) CPI-ALL and CPI-CORE $\mathbf{E}_{t}\pi_{t+1}$ peak at about 7 and 6 (6 and 5) percent. From 1992 to 2004, filtered (smoothed) CPI-ALL and CPI-CORE $\mathbf{E}_{t}\pi_{t+1}$ are no higher than 3.5 and 3.7 percent and no smaller than -0.02 and 0.08 percent before reaching 6.7 and 1.5 percent by 2005M09.

PCED-ALL and PCED-CORE $\mathbf{E}_{t}\pi_{t+1}$ appear in the bottom two rows of Figure 6. These measures of inflation are qualitatively similar to those for the CPI indexes in the top row of graphs, but estimates of $\mathbf{E}_{t}\pi_{t+1}$ peak only during the 1973–75, 1980, and 1990–91 recessions. Peaks in PCED-ALL and PCED-CORE $\mathbf{E}_{t}\pi_{t+1}$ are successively lower at each recession irrespective of the filtered or smoothed estimates. These estimates

^{16.} Filtered and smoothed $\hat{\mu}_{2,t}$ are generated with the Kalman filter, as discussed by Hamilton (1994). Smoothed $\hat{\mu}_{2,t}$ involves a two-sided (in-sample) forecast (using the full data set), while filtered $\hat{\mu}_{2,t}$ is a one-sided forecast given observations 1, ..., t. Filtered $\hat{\mu}_{2,t}$ is initialized with $\mathbf{E}_{0}\pi_{1907M01} = 0$.

	CPI-ALL	CPI-CORE	PCED-ALL	PCED-CORE
$\hat{\sigma}_{\delta}$	2.31	1.74	1.67	1.34
	(0.16)	(0.15)	(0.08)	(0.05)
$\hat{\sigma}_{\!\psi}$	0.68	0.61	0.51	0.36
	(0.14)	(0.14)	(0.10)	(0.07)
$\hat{\sigma}_{\!\delta}/\hat{\sigma}_{\!\psi}$	3.38	2.85	3.29	3.77
	(0.76)	(0.73)	(0.74)	(0.86)
Note: Heteroske	. ,	c standard errors appear in pare	· · /	(0.00)

Table 4		
Estimates of the UC-LL	Model: Sample,	1967M01-2005M09

are between 9 and 10.5 percent during the 1973–75 recession and 1974M06, 9.5 and 12 percent at the 1980 recession, and 4.5 to 5 percent for the 1990–91 recession. From 1992 through 2004, PCED-ALL and PCED-CORE $\mathbf{E}_{t}\pi_{t+1}$ range from 0.5 to 3 percent. By 2005M09, PCED-ALL and PCED-CORE $\mathbf{E}_{t}\pi_{t+1}$ equal 5.2 and 1.8 percent, respectively.

Information about parameter instability in the MLEs of σ_{δ} and σ_{ψ} appears in Figures 7 and 8. Parameter instability in the UC-LL model garners information about changing CPI-ALL, CPI-CORE, PCED-ALL, and PCI-CORE price dynamics. This information is useful to understanding whether the declines in $\mathbf{E}_{t}\pi_{t+1}$ subsequent to the recession of the early 1980s that appear in Figure 6 are related to small shock realizations to trend deviations from the price level, ψ_{t} , or to instability in the volatility of this shock, σ_{w} .

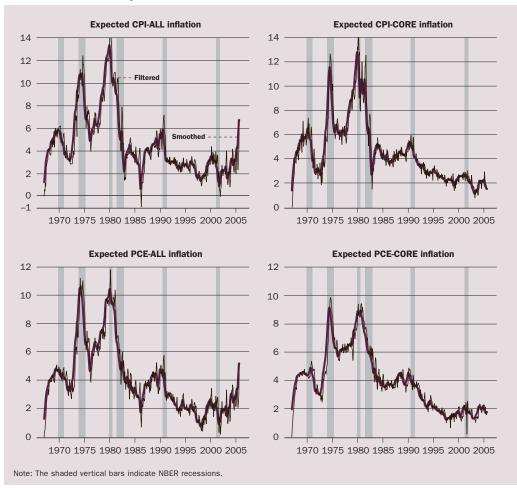
Figure 7 contains four graphs that plot the first and second rolling sample estimates of the standard deviation of the price level trend shock innovation, $\hat{\sigma}_{\delta,t}$. These estimates suggest instability in $\hat{\sigma}_{\delta,t}$. The instability in $\hat{\sigma}_{\delta,t}$ appears to arise in the late 1990s for the ALL price indexes. Evidence of a break in $\hat{\sigma}_{\delta,t}$ for CPI-CORE is suggested by its drop in the second rolling sample at the end of the 1980 recession. For PCED-CORE, the instability in $\hat{\sigma}_{\delta,t}$ possibly occurs during the first oil price shock.

Another feature of Figure 7 is that the second rolling sample generates $\hat{\sigma}_{\delta,t}$ with little movement until the early 1990s, when it begins to rise steadily for CPI-ALL, PCED-ALL, and PCED-CORE. CPI-CORE is the exception because for the second rolling sample $\hat{\sigma}_{\delta,t}$ falls from around 1.75 in mid-1979 to slightly greater than 1 from late 1983 to late 1999. Also note that $\hat{\sigma}_{\delta,t}$ rises, for the most part, from 1972M07 to 1999M10 for PCED-ALL and PCED-CORE for the two rolling samples.

Figure 8 replicates Figure 7 except that $\hat{\sigma}_{\psi,t}$ replaces $\hat{\sigma}_{\delta,t}$.¹⁷ Instability in $\hat{\sigma}_{\psi,t}$ is possible for CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE according to Figure 8. The CPIs and the two rolling samples suggest that instability begins at the 1980 recession. For PCED-ALL and PCED-CORE, instability seems to start with the 1973–75 recession.

The two rolling samples have different implications for the paths of $\hat{\sigma}_{\psi,t}$. The first rolling sample yields $\hat{\sigma}_{\delta,t}$ that range from about 0.4 to 0.8 for CPI-ALL, PCED-ALL, and PCED-CORE and between 0.5 and 0.9 for CPI-CORE. Thus, adding observations to the first rolling sample produces $\hat{\sigma}_{\psi,t}$ that do not fall by much. The second rolling sample shows that $\hat{\sigma}_{\psi,t}$ falls to around 0.2 for CPI-ALL, CPI-CORE, and PCED-ALL

Figure 6 UC-LL Estimates of Expected Inflation



subsequent to the 1980 recession. For PCED-CORE, the drop in $\hat{\sigma}_{\psi, t}$ to 0.2 occurs around the 1973–75 recession. These estimates suggest that smaller realizations of $\hat{\psi}_t$ (that imply smaller $\hat{\sigma}_{\psi}$) are responsible for the fall in $\mathbf{E}_t \pi_{t+1}$ subsequent to the 1980 recession, as plotted in Figure 6.

The lower right graph of Figure 8 reveals that PCED-CORE and the second rolling sample drive $\hat{\sigma}_{\psi,t}$ to 0 by 1992M08, where it remains through 1999M10. If $\sigma_{\psi} = 0$, the UC-LL model predicts that the price level is a random walk driven by δ_t . An implication is that PCED-CORE inflation resembles a white noise process when observations from the 1970s, 1980s, and early 1990s are eliminated from the second rolling sample. A similar result is reported in this study for the AR(p) and MA(1) models and by Stock and Watson (2005).

^{17.} Figures 7 and 8 contain plots of $\hat{\sigma}_{\psi,\iota}$ and $\hat{\sigma}_{\delta,\iota}$ that appear to be step functions on the first rolling sample. The mapping from the MA(1) coefficients θ and σ_{η} to σ_{ψ} and σ_{δ} is one explanation for this observation. The recursive mapping is $(1 + \theta^2) \sigma_{\eta}^2 = 2\sigma_{\delta}^2 + \sigma_{\psi}^2$ and $-\theta\sigma_{\eta}^2 = -\sigma_{\delta}^2$. Watson (1986) and Morley, Nelson, and Zivot (2003) review the link between UC and ARMA models.

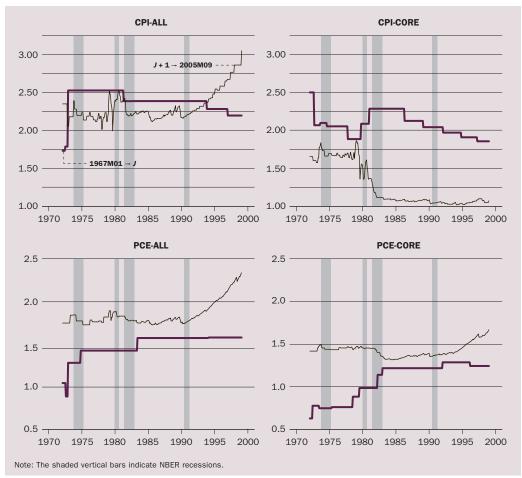


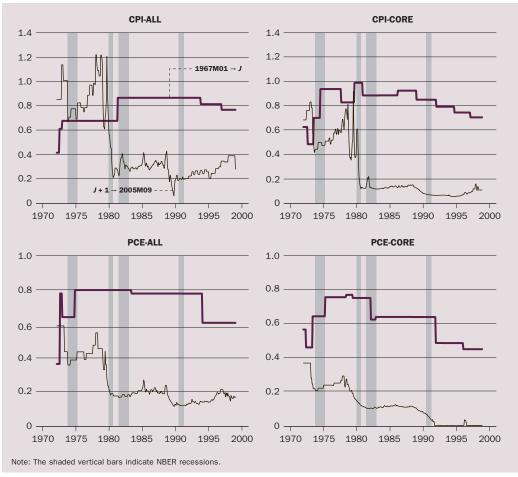
Figure 7 Time Variation in Standard Deviation of Price Level Trend

Conclusions

This article studies U.S. inflation, inflation growth, and price level dynamics with the CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE on a sample that runs from 1967M01 to 2005M09. Two rolling samples are constructed to uncover evidence about instability in inflation, inflation growth, and price level dynamics.

Autoregressive models produce persistence and volatility estimates that vary with different combinations of the two rolling samples and four price indexes. For example, inflation and inflation growth persistence estimates differ across CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE and are sensitive to observations from the 1970s, 1980s, and early 1990s. For example, inflation persistence appears to be large and stable if these observations are included in the sample. However, instabilities appear to arise when the observations are discounted. Equally striking is that PCED-CORE inflation approximates serially uncorrelated white noise when observations up to and including the recession of 1990–91 are eliminated.

Inflation, inflation growth, and price level volatility estimates behave similarly across CPI-ALL, CPI-CORE, PCED-ALL, PCED-CORE, and the two rolling samples. An impor-



 $\label{eq:Figure 8} \ensuremath{\mbox{Figure 8}} \ensuremath{\mbox{Figure 8}} \ensuremath{\mbox{Time Variation in Standard Deviation of Price Level Trend Deviations} \ensuremath{\mbox{Figure 8}} \ensuremath{\mbox{Figu$

tant example is that the volatility of shocks to expected inflation has fallen substantially for the four price indexes either prior to or during the 1980 recession. Especially striking is the lack of volatility in these shocks for PCED-CORE subsequent to the 1990–91 recession. Along with the AR persistence estimates, it suggests that at the moment a sensible forecast for PCED-CORE inflation is its mean on the 1992–2005 sample.

Another way to summarize the empirical results of this article is that instability in the persistence and volatility of CPI-ALL, CPI-CORE, PCED-ALL, and PCED-CORE inflation, inflation growth, and levels coincides with different economic events. An unresolved question is whether such changes are one-time events or can be expected to be repeated systematically in the future. For example, was the decline in PCED-CORE inflation persistence around the end of the 1990–91 recession caused by changes in beliefs about the systematic engineering of monetary policy, or did it reflect technology innovations, changes in market structure, or changes in the composition of the economy (that is, away from manufacturing to the service sector)? Such questions pose a challenge to economic research, forecasting, and monetary policy. Any response should find useful the tools developed by Sargent (1999), Cogley and Sargent (2005), Sims and Zha (2006), Sargent, Williams, and Zha (forthcoming), and Brock, Durlauf, and West (forthcoming).

Appendix The Models

The models studied in this article are a *p*thorder autoregression, AR(p); a first-order moving average, MA(1); and an unobserved components (UC) structure. The choice of these models to study inflation, inflation growth, and price level dynamics is guided by the literature on inflation dynamics. For example, Stock and Watson (2005) report estimates of AR(p), MA(1), and UC models on quarterly gross domestic product (GDP) deflator inflation, PCED-ALL, and PCED-CORE inflation and inflation growth. This article employs similar models but includes estimates on monthly samples of PCED-ALL and PCED-CORE as well as the CPI-ALL and CPI-CORE.

The univariate AR(p) yields estimates of mean inflation, inflation persistence, and inflation volatility. In deviations from mean inflation, π_0 , the AR(p) model is

(A.1)
$$\pi_t - \pi_0 = \sum_{j=1}^p \gamma_j (\pi_{t-j} - \pi_0) + \varepsilon_t,$$

where inflation, π_i , is defined as the difference between the (natural) log of the month *t* price level, P_i , and month t - 1 price level, $\pi_t = 1200 \times (1 - \mathbf{L}) \ln P_i$; the lag operator \mathbf{L} produces $\mathbf{L} \ln P_i = \ln P_{t-1}$; and ε_t is the Gaussian inflation forecast innovation with standard deviation σ_{ϵ} . The article reports MLEs of $\pi_0, \gamma_1, \ldots, \gamma_p$, and σ_{ϵ} from Kalman filter iterations of the state space model

(A.2)
$$\begin{aligned} \pi_t &= \pi_0 + \mathbf{e}_1 \Xi_t, \\ \Xi_{t+1} &= \Gamma \Xi_t + \boldsymbol{\mathcal{E}}_{t+1} \end{aligned}$$

where the first equation is the observer equation, the second equation is the state equation, $\Xi_t = [\xi_{1,t} \dots \xi_{p,t}]'$ is the $p \times 1$ state vector, the row vector $\mathbf{e}_1 = [\mathbf{1} \ \mathbf{0}_p], \mathbf{0}_p$ is a $1 \times (p-1)$ vector of zeros, $\mathcal{E}_t = [\varepsilon_t \mathbf{0}_p]'$, and Γ is the companion matrix of the $\gamma_t s$:

	γ_1	$\gamma_{\rm 2}$		γ_{p-1}	γ_p	
	1	0		0	0	
Γ =	0	1		0	0	
	÷	÷	·	÷	÷	
	0	0		1	0	

The state vector Ξ_t is initialized with a vector of zeros because under the null of the AR(p) the eigenvalues of Γ are inside the unit circle. At date t = 0, the mean square error of Ξ_t is set to $[\mathbf{I}_{p^2} - \Gamma \otimes \Gamma]^{-1} \operatorname{vec}(\mathbf{E}\{E_t E_t'\})$ where $\operatorname{vec}(\cdot)$ denotes placing the second column below the first, the third column below the previous two, and so on. Hamilton (1994) discusses in detail the Kalman filter approach to MLE of ARMA models.

Information about inflation persistence is contained in the γ_s . One measure of inflation persistence is denoted with the sum $\gamma(1) = \sum_{i=1}^{p} \gamma_i$. Another is the largest AR root of inflation, which can be found by computing the largest eigenvalue of Γ , $\Lambda(\Gamma)$. Since $\gamma(1)$ and $\Lambda(\Gamma)$ are functions of the AR coefficients, $\gamma_1 \dots \gamma_p$, these statistics reveal different aspects of inflation persistence. A metric of the cumulative response of inflation to an own shock is $\gamma(1)$. The largest eigenvalue of the companion matrix Γ measures the speed of adjustment of inflation to an own shock along the transition path. The speed of adjustment is translated into the length of time inflation takes to return halfway to its (long-run) mean with $\ln 0.5 / \ln \Lambda(\Gamma)$. Inflation persistence rises as $\gamma(\mathbf{1})$ and $\Lambda(\Gamma)$ approach 1 (from below).¹

As $\gamma(1) \rightarrow 1$, inflation persistence increases. In the limit, inflation takes on a unit root and becomes nonstationary. Stock and Watson (2005) report estimates of $\gamma(1) \ge 1$ that point to a unit root in quarterly inflation since 1970. A lesson they draw is that it is better to work with inflation growth instead of the level of inflation. This conclusion leads them to advocate a model in which inflation growth is decomposed into unobserved permanent (that is, a unit root or random walk) and transitory components

$$\begin{aligned} \boldsymbol{\pi}_{t} &= \boldsymbol{\mu}_{\pi, t} + \boldsymbol{\upsilon}_{t}, \boldsymbol{\upsilon}_{t} \sim \mathbf{N}(0, \sigma_{\upsilon}^{2}), \\ \boldsymbol{\mu}_{\pi, t+1} &= \boldsymbol{\mu}_{\pi, t} + \boldsymbol{\tau}_{t+1}, \boldsymbol{\tau}_{t+1} \sim \mathbf{N}(0, \sigma_{\upsilon}^{2}), \end{aligned}$$

where $\mu_{\pi,i}$ is the permanent component of inflation, its forecast innovation is τ_i , and υ_i denotes the transitory shock innovation.² Also assume $\mathbf{E}\{\upsilon_{i,i}, \tau_{i,i}\} = 0, \forall_{q,j}$.

The reduced form of the Stock and Watson (SW-)UC model is a first-order MA. The reduced-form MA(1) is constructed by passing the first difference operator, $1 - \mathbf{L}$, through $\pi_t = \mu_{\pi,t} + \upsilon_t$ and substituting for $(1 - \mathbf{L})\mu_{\pi,t} = \tau_t$ to find $(1 - \mathbf{L})\pi_t = \tau_t + \upsilon_t - \upsilon_{t-1}$, with the one-stepahead forecast error $\eta_t \equiv \tau_t + \upsilon_t + \mu_{\pi,t} - \mu_{\pi,t-1|t-1}$, where $\mu_{\pi,t-1|t-1}$ is conditional on observations through date t - 1. The first-order moving average dynamics of inflation growth motivates studying it with the fixed-coefficient MA(1),

(A.3)
$$(1-\mathbf{L})\pi_t = (1-\theta\mathbf{L})\eta_t$$

to obtain evidence of changes in inflation growth persistence, as measured by θ . In this case, time variation in σ_v and σ_τ drives changes in inflation growth persistence and volatility. The map between the SW-UC model and the MA(1) of equation (A.3) consists of $(1 + \theta^2)\sigma_{\eta}^2 = 2\sigma_v^2 + \sigma_{\tau}^2$ and $-\theta\sigma_{\eta}^2 = -\sigma_v^2$.

MLEs of θ and σ_{η} are obtained from iterating the Kalman filter. The filter is initialized following the procedure outlined for the AR(*p*) of equation (A.1). The article reports estimates of θ and σ_{η} on the two rolling samples corrected for Blaschke factors when necessary. Hansen and Sargent (1980) and Hamilton (1994) show how to extract Blaschke factors of noninvertible MA processes to adjust MLEs of θ and σ_{η} to obtain an invertible MA.

Estimates of the MA(1) coefficient θ of equation (A.3) contain information about inflation growth persistence. The MA(1) of equation (A.3) yields the AR(∞), $(1-\mathbf{L}) \pi_t = \sum_{j=1}^{\infty} \vartheta_j (1-\mathbf{L}) \pi_{t,j} + \eta_t$, where $\vartheta_j = \theta^j$, given $|\theta| \in (-1, 1)$. The sum $\vartheta(\mathbf{1})$ equals $-\theta/1 - \theta$. Therefore, the long-run response of inflation growth to an own shock increases as $\theta \rightarrow 1$. At $\theta = 1$, the speed of adjustment of inflation to an own shock is instantaneous.

Price level dynamics are not directly studied by the SW-UC model. Rather than define the observer equation with inflation, expressing it in (the log of) the price level, $\ln P_i$, gives the UC-LL model,

A.4)
$$\begin{aligned} \ln P_t &= \mu_{1,t}, \\ \mu_{1,t+1} &= \mu_{1,t} + \mu_{2,t} + \delta_{t+1, -} \delta_{t+1} \sim \mathbf{N}(0, \sigma_{\delta}^2), \\ \mu_{2,t+1} &= \mu_{2,t} + \psi_{t+1, -} \psi_{t+1} \sim \mathbf{N}(0, \sigma_{\psi}^2), \end{aligned}$$

where $\mu_{1,t}$ denotes the price level trend, δ_t is its forecast innovation, $\mu_{2,t}$ represents price level trend deviations, and ψ_t is its forecast innovation. When δ_{t+1} rises, the impact on $\mu_{1,t+j}$ ($j \ge 1$) and $\ln P_{t+j}$ is permanent because it never decays. The same response is generated by the shock to price level trend deviations, ψ_{t+1} . Details about UC models are found in Harvey (1990) and Gourieroux and Monfort (1997). Harvey suggests that mean square error estimates of the state vector distinguish the SW-UC and UC-LL models.

The reduced-form MA(1) of the UC-LL model is $(1 - \mathbf{L})\pi_i = (1 - \mathbf{L})\delta_i + \psi_i$. Since the reduced form of the UC-LL model is a first-order moving average, the results discussed above about the connection between the SW-UC model and the MA(1) of equation (A.3) are applicable. For the UC-LL model, the mapping is $(1 + \theta^2)\sigma_{\eta}^2 = 2\sigma_{\delta}^2 + \sigma_{\psi}^2$ and $-\theta\sigma_{\eta}^2 = -\sigma_{\delta}^2$. The UC-LL also draws out implications for inflation of price level trend shocks, δ_i . This aspect of the UC-LL model ties inflation persistence and volatility, in part, to price level shocks as predicted by the monetary growth model Brock (1974) analyzes.

Harvey (1990) and Gourieroux and Monfort (1997) show how to obtain MLEs of the UC-LL model from the Kalman filter. An issue is that the Kalman filter cannot be initialized using standard approaches because the state space includes unit root processes. Instead, an algorithm Koopman (1997) develops is employed to initialize the nonstationary components of the state vector. These procedures impose a diffuse prior on the initial state vector to compute an exact initialization of the Kalman filter.

The UC-LL model (A.4) and Kalman filter yield estimates of expected inflation. Let $\mathbf{E}_{t}\pi_{t+1}$ denote expected inflation, where \mathbf{E}_{t} is the mathematical expectations operator conditional on

^{1.} A priori, there is no restriction that $\gamma(1) \leq 1$ or $0 \leq \gamma(1)$, but (in modulus) $\Lambda(\Gamma) \in [0, 1]$.

^{2.} The SW-UC model implies that the mean of inflation growth is zero.

Appendix (continued)

date *t* information. Pass the first difference operator $1 - \mathbf{L}$ through the first line of equation (A.4) followed by the expectations operator, $\mathbf{E}_{t}\{\cdot\}$, to obtain $\mathbf{E}_{t}(1 - \mathbf{L}) \ln P_{t+1} \equiv \mathbf{E}_{t}\pi_{t+1} = \mu_{2, t}$. Thus, expected inflation equals deviations from the price level trend. These deviations are persistent—a random walk, in fact—and have innovations, ψ_{t+1} , whose impact on $\mathbf{E}_{t}\pi_{t+1+j}$ is permanent. Given MLEs of the UC-LL model, $\mathbf{E}_{t}\pi_{t+1}$ is computed using the Kalman filter or smoother. Hamilton (1994) describes these procedures. The initialization of the filtered estimates of $\mathbf{E}_{t}\pi_{t+1}$ follows Koopman (1997).

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