# Density of the quotient of non-negative quadratic forms in normal variables with application to the F-statistic 

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#### Abstract

The density of the quotient of two non-negative quadratic forms in normal variables is considered. The covariance matrix of these variables is arbitrary. The result is useful in the study of the robustness of the $F$-test with respect to errors of the first and second kind. An explicit expression for this density is given in the form of a proper Riemann-integral on a finite interval, suitable for numerical calculation.


Keywords: Ratio of quotient of quadratic forms in normal variables, $F$-test, $F$-statistic, numerical evaluation of probability densities

## 1. Introduction

Let $Y \sim N_{n}(\mu, \boldsymbol{\Omega})$ be the $n$-variate normal distribution with expectation $\mu$ and covariance matrix $\boldsymbol{\Omega}$. Let $\boldsymbol{A}$ and $\boldsymbol{B}$ be two non-negative definite $n \times n$-matrices. Set

$$
\begin{align*}
X & =\left(Y^{\prime} \boldsymbol{B} Y\right) /\left(Y^{\prime} \boldsymbol{A} Y\right)  \tag{1}\\
F & =(\operatorname{tr}(\boldsymbol{A}) / \operatorname{tr}(\boldsymbol{B})) X
\end{align*}
$$

A relatively simple expression is given for the density $g$ of $X$ (or equivalently for the density of $F$ ). For numerical calculation, some eigenvalues and eigenvectors must be computed once and then a one-dimensional proper Riemann-integral on a finite interval must be evaluated for each point $x \in \mathbb{R}$ to get the value $g(x)$.

A special case with singular $\boldsymbol{A}$ and $\boldsymbol{B}$ arises with quotients of orthogonal projections. Let $L$ and $R$ be two orthogonal linear subspaces of $\mathbb{R}^{n}$ of dimensions $l$ and $r$, respectively, $(l \geq 1, r \geq 1, l+r \leq n)$. Set

$$
\begin{align*}
X & =\left|Y_{L}\right|^{2} /\left|Y_{R}\right|^{2} \\
F & =(r / l) X \tag{2}
\end{align*}
$$

with $Y_{L}=\boldsymbol{P}_{L} Y$ and $\boldsymbol{P}_{L}$ the orthogonal projection matrix belonging to $L ; Y_{R}$ and $R$ are similarly defined. Then Equation 1 leads to Equation 2 for $\boldsymbol{A}=\boldsymbol{P}_{R}, \boldsymbol{B}=\boldsymbol{P}_{L}$.

This result is useful in studying the robustness of the $F$-test in linear models. Let $\boldsymbol{Y}=\boldsymbol{Z} \beta+\varepsilon$ with $\boldsymbol{Z} \in \mathbb{R}^{n \times k}$ the (non-stochastic) matrix of explanatory variables and
$\varepsilon \sim N_{n}(0, \boldsymbol{\Omega})$. Then $Y \sim N_{n}(\mu, \boldsymbol{\Omega})$ with $\mu=Z \beta \in \mathbb{R}^{n}$. An (identifiable) hypothesis $\mathrm{H}_{0}$ in terms of restrictions on $\beta$ is equivalent to $\mathrm{H}_{0}: \mu \in L_{0}$ with $L_{0}$ some linear subspace of $\mathscr{R}(\boldsymbol{Z})$. The usual $F$-statistic $F$ for testing $\mathrm{H}_{0}: \mu \in L_{0}$ against $\mathrm{H}_{1}: \mu \in \mathscr{R}(\boldsymbol{Z})-L_{0}$ is given by $F$ in Equation 2, where $L$ and $R$ are determined by $L \perp L_{0}, L+L_{0}=\mathscr{R}(\boldsymbol{Z})$ and $R \perp \mathscr{R}(\boldsymbol{Z}), R+\mathscr{R}(\boldsymbol{Z})=\mathbb{R}^{n}$.

The usual assumption, $\boldsymbol{\Omega}=\sigma^{2} I_{n}$, gives $F \sim F_{r}^{l}(\delta)$, the non-central $F$-distribution with degrees of freedom $l$ and $r$ and non-centrality parameter $\delta=\left|\mu_{L}\right|^{2} / \sigma^{2}$. Equivalently, $X$ follows the distribution with density

$$
\begin{equation*}
\exp \left(-\frac{1}{2} \delta\right) \sum_{k=0}^{\infty} \frac{(\delta / 2)^{k}}{k!} p(x ; l / 2+k, r / 2) \quad x>0 \tag{3}
\end{equation*}
$$

where $p\left(x ; \rho_{1}, \rho_{2}\right)$ stands for the density of the beta-distribution of the second kind given by

$$
\begin{equation*}
p\left(x ; \rho_{1}, \rho_{2}\right)=x^{\rho_{1}-1}(1+x)^{-\rho_{1}-\rho_{2}} / B\left(\rho_{1}, \rho_{2}\right) \quad x>0 \tag{4}
\end{equation*}
$$

So with an expression for the density $g$ of $X$ for general $\mu$ and $\Omega$ it is possible to study the robustness of the $F$-test for specified probabilities for errors of the first and second kind.

The question of robustness of the $F$-test is a very old problem. A detailed study for heteroskedasticity and autocorrelation in some special ANOVA-designs can be found in Scheffe (1959). Readers are referred to this book for an overview.

The best references within the context of the general problem are Lugannani and Rice (1984) and Magnus (1986).

## 2. Statement of results

Let $\left(\lambda_{j}, \boldsymbol{h}_{j}\right), j=1, \ldots, n$, be the eigenvalues and orthogonal eigenvectors of $\boldsymbol{\Omega}$. Set $\alpha_{j}=\boldsymbol{h}_{j}^{\prime} \boldsymbol{A} \boldsymbol{h}_{j}, \quad \beta_{j}=\boldsymbol{h}_{j}^{\prime} \boldsymbol{B} \boldsymbol{h}_{j}$. Throughout this section it is assumed that $\alpha_{j} \lambda_{j}>0$ for some $j, \beta_{j} \lambda_{j}>0$ for some $j$ and that $\beta_{j} / \alpha_{j}$ is not constant in $j$. Let $I=\left(\min \beta_{j} / \alpha_{j}, \max \beta_{j} / \alpha_{j}\right)$, where min and max extend over $j=1, \ldots, n$ with $\lambda_{j}>0$ and $\left(\alpha_{j}, \beta_{j}\right) \neq(0,0)$. The following theorem 1 precedes the main theorem 2 and is interesting in its own right.

Theorem 1. The density $g$ of $X$ defined by Equation 1 is restricted to the interval $I$ and its value at $x \in I$ is given by

$$
\begin{align*}
g(x)= & \frac{\mathrm{e}^{-\frac{1}{2} \Sigma \delta_{k}}}{4 \pi \mathrm{i}} \sum_{j=1}^{n} \alpha_{j} \lambda_{j} \int_{-\mathrm{i} \infty}^{\mathrm{i} \infty}\left\{1-\delta_{j} /\left(1-c_{j} z\right)\right\} \mathrm{e}^{\frac{1}{2} \Sigma \delta_{k} /\left(1-c_{k} z\right)} \\
& \times \prod\left(1-c_{k} z\right)^{-\frac{1}{2}-\delta_{k j}} \mathrm{~d} z \tag{5}
\end{align*}
$$

where the $\Sigma$ and $\Pi$ operators extend over $k=1, \ldots, n$ with $\lambda_{k}>0$ and with

$$
\begin{align*}
\delta_{j} & =\left(\boldsymbol{h}_{j}^{\prime} \mu\right)^{2} / \lambda_{j}  \tag{6}\\
c_{j} & =\lambda_{j}\left(\beta_{j}-\alpha_{j} x\right)
\end{align*}
$$

Example 1. $\left(\boldsymbol{\Omega}=\sigma^{2} \boldsymbol{I}_{n}\right.$, Equation 2, $\left.\mu \in L\right)$ : If $\boldsymbol{\Omega}=\sigma^{2} \boldsymbol{I}_{n}$ then $\lambda_{j}=\sigma^{2}$ for all $j$. Hence, without loss of generality, it is possible to take $\boldsymbol{h}_{j}$ such that $L=\mathscr{R}\left(\boldsymbol{h}_{1}, \ldots, \boldsymbol{h}_{l}\right)$, $R=\mathscr{R}\left(\boldsymbol{h}_{l+1}, \ldots, \boldsymbol{h}_{l+r}\right)$. Then $\quad \delta_{j}=\left(\boldsymbol{h}_{j}^{\prime} \mu\right)^{2} / \sigma^{2} \quad$ for $j=1, \ldots, l$ and $\delta_{j}=0$ elsewhere. This implies $\delta=\Sigma \delta_{k}=\left|\mu_{L}\right|^{2} / \sigma^{2}$. Furthermore, $\alpha_{j}=1 \quad$ for $j=l+1, \ldots, l+r, \beta_{j}=1$ for $j=1, \ldots, l$; other $\alpha$ - and $\beta$-values are equal to 0 . This gives $I=(0, \infty), c_{j}=\sigma^{2}$ for $j=1, \ldots, l, c_{j}=-\sigma^{2} x$ for $j=l+1, \ldots, l+r$ and $c_{j}=0$ for $j=l+r+1, \ldots, n$. Substitution into Equation 5 leads, for any $x>0$, to

$$
\begin{align*}
g(x)= & \frac{\mathrm{e}^{-\delta / 2}}{4 \pi \mathrm{i}} r \sigma^{2} \int_{-\mathrm{i} \infty}^{\mathrm{i} \infty} \mathrm{e}^{\frac{1}{2} \delta /\left(1-\sigma^{2} z\right)}\left(1-\sigma^{2} z\right)^{-l / 2} \\
& \times\left(1+\sigma^{2} x z\right)^{-r / 2-1} \mathrm{~d} z \\
= & \mathrm{e}^{-\delta / 2} \sum_{k=0}^{\infty} \frac{(\delta / 2)^{k}}{k!} \frac{r}{4 \pi \mathrm{i}} \int_{-\mathrm{i} \infty}^{\mathrm{i} \infty}(1-z)^{-(l / 2+k)} \\
& \times(1+x z)^{-(r / 2+1)} \mathrm{d} z \tag{7}
\end{align*}
$$

The integral in the sum is a variation of Pochhammer's contour integral for the beta-function (see also Lugannani and Rice (1984) p. 487).

$$
\begin{equation*}
\frac{1}{2 \pi \mathrm{i}} \int_{-\mathrm{i} \infty}^{+\infty} \frac{\mathrm{d} z}{(z-a)^{\alpha}(b-z)^{\beta}}=\frac{\Gamma(\alpha+\beta-1)}{(b-a)^{\alpha+\beta-1} \Gamma(\alpha) \Gamma(\beta)} \tag{8}
\end{equation*}
$$

where $\operatorname{Re}(\alpha+\beta)>1$ and $a<0<b$. This leads to

$$
\begin{align*}
& \frac{r}{4 \pi \mathrm{i}} \int_{-\mathrm{i} \infty}^{\mathrm{i} \infty}(1-z)^{-(l / 2+k)}(1+x z)^{-(r / 2+1)} \mathrm{d} z \\
& \quad=p(x ; l / 2+k, r / 2) \tag{9}
\end{align*}
$$

where $p$ is defined by Equation 4. Hence

$$
\begin{equation*}
g(x)=\mathrm{e}^{-\delta / 2} \sum_{k=0}^{\infty} \frac{(\delta / 2)^{2}}{k!} p(x ; l / 2+k, r / 2) \quad x>0 \tag{10}
\end{equation*}
$$

in agreement with Equation 3.
The following theorem shows that Equation 6 can be written as a proper Riemann-integral on a finite interval.

Theorem 2. (Conditions of theorem 1):

$$
\begin{align*}
g(x)= & \frac{1}{4 \pi}\left(a^{-1}+b^{-1}\right) \exp \left(-\frac{1}{2} \sum \delta_{k}\right) \\
& \times \sum_{j=1}^{n} \alpha_{j} \lambda_{j} I_{j} \Pi\left(f_{k}\right)^{-\frac{1}{2}-\delta_{k j}} \tag{11}
\end{align*}
$$

with

$$
\begin{align*}
& I_{j}=\int_{0}^{\pi / 2} B_{j}(t) \prod\left(A_{k}(t)\right)^{-\frac{1}{4}-\frac{3}{2} \delta_{k j}} \exp \left\{\frac{1}{2} \sum \delta_{k} f_{k} \cos ^{2} t / A_{k}(t)\right\} \\
& \times \cos ^{\frac{1}{2} n-1} t \cos \left[\sum\left\{\left(\frac{1}{2}+\delta_{k j}\right) \arcsin \left(\gamma_{k} \sin t / A_{k}(t)\right)-S_{k}(t)\right\}\right. \\
& \left.+\arcsin \left(S_{j}(t) / C_{j}(t)\right)\right] \mathrm{d} t \tag{12}
\end{align*}
$$

where

$$
\begin{align*}
a & =\max \left(\lambda_{j} \beta_{j}\right) \\
b & =x \max \left(\lambda_{j} \alpha_{j}\right) \\
f_{j} & =1-\frac{1}{2} c_{j}\left(a^{-1}-b^{-1}\right)  \tag{13}\\
\gamma_{j} & =\frac{1}{2} c_{j}\left(a^{-1}+b^{-1}\right) / f_{j} \\
A_{j}(t) & =\cos ^{2} t+\gamma_{j}^{2} \sin ^{2} t \\
C_{j}(t) & =\left(1-\delta_{j} f_{j}\right) \cos ^{2} t+\gamma_{j}^{2} \sin ^{2} t \\
S_{j}(t) & =\delta_{j} f_{j} \gamma_{j} \sin t \cos t  \tag{14}\\
B_{j}(t) & =\left\{C_{j}^{2}(t)+S_{j}^{2}(t)\right\}^{\frac{1}{2}}
\end{align*}
$$

Remark. Since $a \geq \max c_{j}, b \geq-\min c_{j}$ it follows that $f_{j}>0$ and $\left|\gamma_{j}\right| \leq 1$.

Corollary. If $\mu=0$ then $\delta_{j}=0$ for all $j$. Then $C_{j}(t)=A_{j}(t)=B_{j}(t)$ and $S_{j}(t)=0$ and so Equation 12 reduces to

$$
\begin{align*}
I_{j}= & \int_{0}^{\pi / 2} \Pi\left(A_{k}(t)\right)^{-\frac{1}{4}-\frac{1}{2} \delta_{k j}} \cos ^{\frac{1}{2} n-1} t \\
& \times \cos \left[\sum\left(\frac{1}{2}+\delta_{k j}\right) \arcsin \left(\gamma_{k} \sin t / A_{k}(t)\right)\right] \mathrm{d} t \tag{15}
\end{align*}
$$

Example $2\left(\boldsymbol{\Omega}=\sigma^{2} I_{n}\right.$, Equation 2, $\left.\mu=0\right)$ : Using the results in example 1 it is seen that $\delta_{j}=0$ for all $j$ and $a=\sigma^{2}, b=\sigma^{2} x$. This leads to $f_{j}=\frac{1}{2}(1+1 / x), \gamma_{j}=1$ for $j=1, \ldots, l ; f_{j}=\frac{1}{2}(1+x), \gamma_{j}=-1$ for $j=l+1, \ldots, l+r$ and $f_{j}=1, \gamma_{j}=0$ for $j=l+r+1, \ldots, n$. Substitution into Equations 13-15 leads for any $x \in I=(0, \infty)$ to

$$
\begin{align*}
g(x)= & x^{l / 2-1}(1+x)^{-(l+r) / 2} 2^{(l+r) / 2} \frac{r}{2 \pi} \int_{0}^{\pi / 2} \cos ^{(l+r) / 2-1} t \\
& \times \cos \{(l-r) / 2-1\} \mathrm{d} t \tag{16}
\end{align*}
$$

The integral is a variant for the integral expression for the beta-function (see Gradshteyn and Ryzhik (1965) p. 375)

$$
\begin{align*}
& \int_{0}^{\pi / 2} \cos ^{\alpha+\beta-1} t \cos (\alpha-\beta-1) \mathrm{d} t \\
& \quad=\pi /\left\{2^{\alpha+\beta}(\alpha+\beta) B(\alpha, \beta+1)\right\} \tag{17}
\end{align*}
$$

where $\operatorname{Re} \alpha>0$ and $\operatorname{Re} \beta>-1$. This leads to $g(x)=$ $p(x ; l / 2, r / 2)$, where $p$ is defined by Equation 4.

## 3. Proof of theorems

Lemma 1. Let ( $X_{1}, X_{2}$ ) have an absolutely continuous distribution with joint characteristic function $\varphi$. If $X_{2} \geq 0$ a.s. and $E\left\{X_{2}\right\}<\infty$ then $Y=X_{1} / X_{2}$ has a density $g$ given by

$$
\begin{equation*}
g(y)=\left.\frac{1}{2 \pi \mathrm{i}} \int_{-\infty}^{\infty}\left(\frac{\partial \varphi\left(u_{1}, u_{2}\right)}{\partial u_{2}}\right)\right|_{u_{2}=-y u_{1}} \mathrm{~d} u_{1} \tag{18}
\end{equation*}
$$

Proof. See Cramer (1946), exercise 6, p. 317 or Geary (1944) and for the multivariate generalization Phillips (1985).

Lemma 2. Let $X \sim N_{n}(\mu, \boldsymbol{\Omega}), \boldsymbol{\Omega}=\boldsymbol{T} \boldsymbol{T}^{\prime}>\mathbf{0}$ with $\boldsymbol{T} \in \mathbb{R}^{n \times n}$. Let $\quad X_{1}=X^{\prime} \boldsymbol{A}_{1} X, \quad \boldsymbol{X}_{2}=X^{\prime} \boldsymbol{A}_{2} X \quad$ with symmetric $A_{1}, A_{2} \in \mathbb{R}^{n \times n}$. Then the joint characteristic function $\varphi$ of $X_{1}$ and $X_{2}$ is given by
$\varphi\left(u_{1}, u_{2}\right)=\left|\boldsymbol{I}_{n}-2 \mathrm{i} \boldsymbol{C}\right|^{-\frac{1}{2}} \exp \left\{-\frac{1}{2} \eta^{\prime} \eta\right\} \exp \left\{\frac{1}{2} \eta^{\prime}\left(\boldsymbol{I}_{n}-2 \mathrm{i} \boldsymbol{C}\right)^{-1} \eta\right\}$
where

$$
\begin{align*}
\eta & =T^{-1} \mu  \tag{19}\\
C & =u_{1} T^{\prime} A_{1} T+u_{2} T^{\prime} A_{2} T \tag{20}
\end{align*}
$$

Proof. See Magnus (1986), lemma 5, p. 102.
Lemma 3. (Conditions of lemma 2 with $\boldsymbol{A}_{2} \geq \mathbf{0}$ ): If vec $\left(\boldsymbol{A}_{1}\right)$ and $\operatorname{vec}\left(\boldsymbol{A}_{2}\right)$ are linearly independent, then the density $g$ of $\boldsymbol{Y}=X_{1} / \boldsymbol{X}_{2}$ is given by

$$
\begin{align*}
g(y)= & \frac{\mathrm{e}^{-\frac{1}{2} \eta^{\prime} \eta}}{4 \pi \mathrm{i}} \int_{-\mathrm{i} \infty}^{\mathrm{i} \infty} \mathrm{e}^{\frac{1}{2} \eta^{\prime} S^{-1}(y, z) \eta}|S(y, z)|^{-\frac{1}{2}} \\
& \times\left[\operatorname{tr}\left(S^{-1}(y, z) \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T}\right)\right. \\
& \left.+\eta^{\prime} S^{-1}(y, z) \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T} \boldsymbol{S}^{-1}(y, z) \eta\right] \mathrm{d} z \tag{21}
\end{align*}
$$

where

$$
\begin{equation*}
S(y, z):=\boldsymbol{I}_{n}-z\left(\boldsymbol{T}^{\prime} \boldsymbol{A}_{1} \boldsymbol{T}-y \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T}\right) \tag{22}
\end{equation*}
$$

Proof. Note that $\left(\boldsymbol{X}_{1}, \boldsymbol{X}_{2}\right)$ has an absolutely continuous distribution iff $\operatorname{vec}\left(\boldsymbol{A}_{1}\right)$ and $\operatorname{vec}\left(\boldsymbol{A}_{2}\right)$ are linearly independent. Lemmas 1 and 2 and the following formula are used:

$$
\begin{align*}
\frac{\mathrm{d} \boldsymbol{A}^{-1}}{\mathrm{~d} x} & =-\boldsymbol{A}^{-1} \frac{\mathrm{~d} \boldsymbol{A}}{\mathrm{~d} x} \boldsymbol{A}^{-1}  \tag{23}\\
\frac{\mathrm{~d}|\boldsymbol{A}|}{\mathrm{d} x} & =|\boldsymbol{A}| \mathrm{tr}\left(\boldsymbol{A}^{-1} \frac{\mathrm{~d} \boldsymbol{A}}{\mathrm{~d} x}\right) \quad|\boldsymbol{A}| \neq 0
\end{align*}
$$

Differentiation of Equation 19 leads with Equation 20 and

$$
\begin{align*}
& \frac{\partial}{\partial u_{2}}\left|I_{n}-2 \mathrm{i} C\right|^{-\frac{1}{2}}=\mathrm{i}\left|I_{n}-2 \mathrm{i} C\right|^{-\frac{1}{2}} \operatorname{tr}\left\{\left(\boldsymbol{I}_{n}-2 \mathrm{i} C\right)^{-1} \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T}\right\} \\
& \frac{\partial}{\partial u_{2}}\left(\boldsymbol{I}_{n}-2 \mathrm{i} C\right)^{-1}=2 \mathrm{i}\left(I_{n}-2 \mathrm{i} C\right)^{-1} \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T}\left(I_{n}-2 \mathrm{i} C\right)^{-1} \tag{24}
\end{align*}
$$

to

$$
\begin{align*}
\frac{\partial \varphi\left(u_{1}, u_{2}\right)}{\partial u_{2}}= & \mathrm{i} \varphi\left(u_{1}, u_{2}\right)\left[\operatorname{tr}\left\{\left(I_{n}-2 \mathrm{i} \boldsymbol{C}\right)^{-1} \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T}\right\}\right. \\
& \left.+\eta^{\prime}\left(\boldsymbol{I}_{n}-2 \mathrm{i} \boldsymbol{C}\right)^{-1} \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T}\left(\boldsymbol{I}_{n}-2 \mathrm{i} \boldsymbol{C}\right)^{-1} \eta\right] \tag{25}
\end{align*}
$$

So with Equation 22

$$
\begin{align*}
\varphi\left(u_{1},-y u_{1}\right)= & \left.S\left(y, 2 \mathrm{i} u_{1}\right)\right|^{-\frac{1}{2}} \exp \left\{-\frac{1}{2} \eta^{\prime} \eta\right\} \\
& \times \exp \left\{\frac{1}{2} \eta^{\prime} S^{-1}\left(y, 2 \mathrm{i} u_{1}\right) \eta\right\}  \tag{26}\\
\left.\frac{\partial \varphi\left(u_{1}, u_{2}\right)}{\partial u_{2}}\right|_{u_{2}=-y u_{1}}= & \mathrm{i} \varphi\left(u_{1},-y u_{1}\right)\left[\operatorname{tr}\left\{S^{-1}\left(y, 2 \mathrm{i} u_{1}\right) \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T}\right\}\right. \\
& \left.+\eta^{\prime} S^{-1}\left(y, 2 \mathrm{i} u_{1}\right) \boldsymbol{T}^{\prime} \boldsymbol{A}_{2} \boldsymbol{T} S^{-1}\left(y, 2 \mathrm{i} u_{1}\right) \eta\right] \tag{27}
\end{align*}
$$

Substitution of these expressions into Equation 18 together with $z=2 \mathrm{i} u_{1}$ leads to Equation 21.

Proof of theorem 1. Suppose $\Omega>0$ or, equivalently, $\lambda_{j}>0$ for all $j$. Use Equations 21 and 22 with $\boldsymbol{A}_{1}=\boldsymbol{B}$ and $\boldsymbol{A}_{2}=\boldsymbol{A}$. Since $\boldsymbol{\Omega}=\boldsymbol{\Sigma} \lambda_{j} h_{j} h_{j}^{\prime}$ it is possible to take $\boldsymbol{T}=\Sigma \lambda_{j}^{\frac{1}{2}} h_{j} h_{j}^{\prime}$. This gives

$$
\begin{align*}
& \boldsymbol{T}^{\prime} \boldsymbol{B} \boldsymbol{T}=\sum \beta_{j} \lambda_{j} \boldsymbol{h}_{j} \boldsymbol{h}_{j}^{\prime} \\
& \boldsymbol{T}^{\prime} \boldsymbol{A} \boldsymbol{T}=\sum \alpha_{j} \lambda_{j} h_{j} h_{j}^{\prime} \\
& S=S(y, z)=\sum\left(1-c_{j} z\right) \boldsymbol{h}_{j} \boldsymbol{h}_{j}^{\prime} \\
& S^{-1}=\sum\left(1-c_{j} z\right)^{-1} \boldsymbol{h}_{j} \boldsymbol{h}_{j}^{\prime} \\
&|\boldsymbol{S}|^{-\frac{1}{2}}=\prod\left(1-c_{j} z\right)^{-\frac{1}{2}}  \tag{28}\\
& \operatorname{tr}\left(S^{-1} \boldsymbol{T}^{\prime} \boldsymbol{A} \boldsymbol{T}\right)=\sum\left(1-c_{j} z\right)^{-1} \alpha_{j} \lambda_{j} \\
& \eta=\sum \delta_{j}^{\frac{1}{3}} \boldsymbol{h}_{j} \\
& \eta^{\prime} \eta=\sum \delta_{j} \\
& \eta^{\prime} S^{-1} \eta=\sum \delta_{j}\left(1-c_{j} z\right)^{-1} \\
& \eta^{\prime} \boldsymbol{S}^{-1} \boldsymbol{T}^{\prime} \boldsymbol{A} \boldsymbol{T} S^{-1} \eta=\sum \alpha_{j} \lambda_{j} \delta_{j}\left(1-c_{j} z\right)^{-2}
\end{align*}
$$

Substitution into Equation 21 with the Kronecker symbol $\delta_{k j}=1$ if $k=j, \delta_{k j}=0$ if $k \neq j$ leads to Equation 5.

For fixed $j$ with $\alpha_{j} \lambda_{j}>0$ the integrand in Equation 5 is $O\left(|z|^{-\frac{3}{2}}\right)$ for $|z| \rightarrow \infty$; furthermore it has singular points in the half plane $\operatorname{Re} z>0$ iff $x<\beta_{j} / \alpha_{j}$ for some $j$ and singular points in $\operatorname{Re} z<0$ iff $x>\beta_{j} / \alpha_{j}$ for some $j$. So $g(x)=0$ if $x>\max \left(\beta_{j} / \alpha_{j}\right)$ or $x<\min \left(\beta_{j} / \alpha_{j}\right)$. This concludes the proof of the theorem for $\boldsymbol{\Omega}>\boldsymbol{0}$. The general case follows by continuity arguments with respect to the eigenvalues $\lambda_{j}$ of $\boldsymbol{\Omega}$.

Proof of theorem 2. The substitution $s=(b-a-2 a b z) /$ $(b+a)$ and $c=(b-a)(b+a)$ can be made into Equation 5. Then $1-c_{k} z=\left(1+\gamma_{k} s\right) / f_{k}$ and so

$$
\begin{equation*}
g(x)=\frac{\mathrm{e}^{-\frac{1}{2} \Sigma \delta_{k}}}{8 \pi \mathrm{i}}\left(a^{-1}+b^{-1}\right) \sum_{j=1}^{n} \alpha_{j} \lambda_{j} \prod\left(f_{k}\right)^{\frac{1}{2}+\delta_{k j}} I_{j}(c) \tag{29}
\end{equation*}
$$

with

$$
\begin{align*}
I_{j}(c)= & \int_{-\mathrm{i} \infty+c}^{i \infty+c}\left\{\Pi\left(1+\gamma_{k} s\right)^{-\frac{1}{2}-\delta_{k j}}\right\} \\
& \times\left\{1-\delta_{j} f_{j} /\left(1+\gamma_{j} s\right)\right\} \mathrm{e}^{\frac{1}{2} \delta_{k} f_{k} /\left(1+\gamma_{k} s\right)} \mathrm{d} s \tag{30}
\end{align*}
$$

The integrand has singular points at $s=-1 / \gamma_{k}$. Since $a \geq \max c_{k}$ and $b \geq-\min c_{k}$ then $\left|\gamma_{k}\right| \leq 1$ and so all singular points are outside $\{s:|\operatorname{Re} s|<1\}$. Therefore $I_{j}(c)$ does not depend on $c$ provided that $|c|<1$. Since $|b-a| \mid$ $(b+a)<1$ it is possible to replace the particular value $c=(b-a) /(b+a)$ by $c=0$. This gives the intermediate result

$$
\begin{equation*}
g(x)=\frac{\mathrm{e}^{-\frac{1}{2} \Sigma \delta_{k}}}{8 \pi}\left(a^{-1}+b^{-1}\right) \sum_{j=1}^{n} \alpha_{j} \lambda_{j} \prod\left(f_{k}\right)^{\frac{1}{2}+\delta_{k_{j}}} I_{j} \tag{31}
\end{equation*}
$$

with

$$
\begin{align*}
I_{j}=I_{j}(0)= & \int_{-\infty}^{\infty}\left\{\prod\left(1+\mathrm{i} \gamma_{k} u\right)^{-\frac{1}{2}-\delta_{k_{j}}}\right\} \\
& \times\left\{1-\delta_{j} f_{j} /\left(1+\mathrm{i} \gamma_{j} u\right)\right\} \mathrm{e}^{\frac{1}{2} \Sigma \delta_{k} f_{k} /\left(1+\mathrm{i} \gamma_{k} u\right)} \mathrm{d} u \tag{32}
\end{align*}
$$

This expression can be rewritten in the form of a Riemann integral on a finite interval. Substitution of $u=\operatorname{tg} t$ and $\mathrm{d} u=\cos ^{2} t \mathrm{~d} t$ together with

$$
\begin{align*}
1+\mathrm{i} \gamma_{k} u=A_{k}(t) \cos t & \exp \left\{\mathrm{i} \arcsin \left(\gamma_{k} \sin t / A_{k}(t)\right)\right\} \\
1-\delta_{j} f_{j} /\left(1+\mathrm{i} \gamma_{j} u\right)= & A_{j}^{-1}(t) B_{j}(t) \\
& \times \exp \left\{\mathrm{i} \arcsin \left(S_{j}(t) / A_{j}(t)\right)\right\}  \tag{33}\\
\exp \left\{\frac{1}{2} \delta_{k} f_{k} /\left(1+\mathrm{i} \gamma_{k} u\right)\right\}= & \exp \left\{\frac{1}{2} \delta_{k} f_{k} \cos ^{2} t / A_{k}(t)\right\} \\
& \times \exp \left\{-\mathrm{i} S_{k}(t)\right\}
\end{align*}
$$

leads to Equations 11 and 12.

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