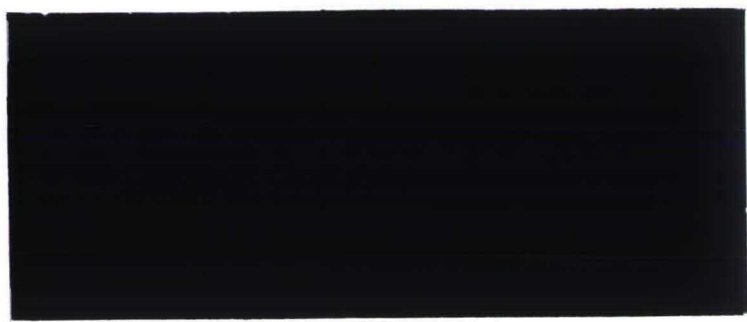


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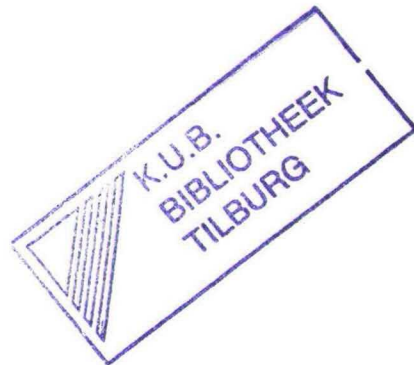
DEPARTMENT OF ECONOMICS
RESEARCH MEMORANDUM

**AN ALGORITHM ON ADDITION CHAINS WITH
RESTRICTED MEMORY**

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An Algorithm on Addition Chains with Restricted Memory

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Abstract

This paper considers addition chains, addition sequences and vector addition chains, introducing a new constraint — namely restricted memory — which is important in all of the applications on computers. We consider an algorithm for calculating addition chains, addition sequences and vector addition chains — namely a Generalized Continued Fraction Algorithm — which uses just a restricted number of memory locations on the computer. The average length of addition chains/sequences constructed by this algorithm will be calculated using a number theoretical tools (from Ergodic Theory and Special Function Theory). Finally, this algorithm will be compared to some other known algorithms.

Keywords & Phrases: Addition Chain, Addition Sequence, Vector Addition Chain, Algorithm, Fast Exponentiation, RSA, Space- and Time- Complexity, Ergodic Theory.

1985 AMS Mathematics Subject Classification: 65V05, 68M20; Computing Reviews code: F21: Number theoretic computation; G4: Algorithm analysis and efficiency.

1 Introduction

Much research has been concerned with speeding up RSA calculations, with the aim of increasing the speed of multiplications. More recently, further improvements have been achieved by applying so-called addition chains. In RSA applications, an exponentiation is done by some modular multiplications using addition chains. For each element in the addition chain, a multiplication is done. Hence RSA becomes faster if the addition chain is shorter.

For instance, new RSA-applications (cf. [21] and [15]) can take advantage of a generalization called vector addition chains. Use of these shorter addition chains significantly speeds up the RSA application. Olivos gave in [27] a description of how such vector addition chains can be constructed. This construction was implemented by Bos in [8]. Addition chains also have applications in exponentiations of discrete log-based systems [19], exponentiations in $GF(2^n)$ (cf. [1]) and factoring algorithms (cf. [25, 39]). In fact, addition chains and addition sequences can be used for any abelian group with large sizes. This paper will often use X , X^n , $Y \cdot Z$, as if we were doing an RSA-calculation. The reader may substitute an addition or another group operation.

Many algorithms on addition chains and addition sequences are known: the Binary Algorithm, the Window Algorithm (cf. [23]), the Generalized Window Algorithm (cf. [40, 33]), the Continued Fraction Algorithm (cf. [4, 3]), the Generalized Continued Fraction Algorithm (cf. [8]) and the Batch-RSA Algorithm (cf. [21]). For a good overview, see [16]. But in applications on the computer, not all these algorithms are equal. It is clear that the length of the chains and sequences constructed by those algorithms is important (time complexity). But also the number of memory location used by the computer when the algorithms are applied is important (space complexity). For example, the Generalized Window Algorithm is rather fast, but it uses a large number of memory locations (cf. [16]). We are interested in algorithms which are both fast and use only a small number of memory locations. The Generalized Continued Fraction Algorithm is such an algorithm. It is based on the Multi-Continued Fraction Algorithm of Brun, (cf. [10, 12, 30]). Thus we will call it the Brun Algorithm. The two-dimensional case was described in [4]. This paper will show that the Brun Algorithm uses a small number of memory locations, and we will predict the time complexity, insofar as that is possible.

This paper consists of 5 sections. Section 2 defines the notation used in this paper and Section 3 gives a brief review of the literature, explains the space complexity, defines the average number of steps and explains the Brun Algorithm.

Section 4 provides a proof that the number of memory locations used by the Brun-algorithm is equal to the width of the sequence (or vector addition chain). From there the average number of steps can be calculated. This is far from trivial. We need deep Ergodic Theory, partly known theory, partly new theory. Comparable theory was used in order to calculate the number of steps in Euclid's Algorithm. We find an expression in terms of n -dimensional integrals, which can be solved for small dimensions. Unfortunately, since in this paper we were unable to calculate these integrals, we conjecture that the average lengths of chains and sequences, constructed by the Brun Algorithm, are of the order $O(n \log(\max(a_1, \dots, a_n)) / \log(n))$, where a_1, \dots, a_n are the numbers for which an addition sequence/vector addition chain has to be found.

The last section discusses the results, mentioning some open problems and suggesting topics for further research.

Results that are related to vector addition chains will be omitted. In fact, all results proved in this paper hold also for vector addition chains. For a good survey on vector addition chains [8, 16, 23, 27].

2 Definitions and notation.

The following notation will be used:

\mathbf{a}	a vector
$\lfloor x \rfloor$	largest integer which does not exceed x
$\nu(n)$	the number of ones that occur in the binary representation of n
$\log_2 n$	2-based logarithm
$\lambda(n)$	$\lfloor \log_2 n \rfloor$

$\ln n$	$\log_e n$
μ_n	root of the equation $x^n - x^{n-1} - 1 = 0$, with $\mu_n > 1$
E_n	Unit cube in n dimensions = $\{\mathbf{x} 0 \leq x_i \leq 1 \text{ for } 1 \leq i \leq n\}$
$E_{n,k}$	$= \{\mathbf{x} 0 \leq x_i \leq \frac{1}{k} \text{ for } 1 \leq i \leq n\}$
$\Delta_{n,k}$	$E_{n,k} \setminus E_{n,k+1}$
$M(L)$	Number of memory locations used by Algorithm L
$T(a_1, \dots, a_n)$	an integral map related to the Brun–algorithm, see Section 4.1
$t(x_1, \dots, x_n)$	a real map on E_n related to the Brun–algorithm, see Section 4.1
$\Psi_n(\mathbf{x})$	$\frac{1}{(1+x_1) \cdots (1+x_1 + \cdots + x_n)}$
X_n	$\int \int_{E_n} \int \Psi_n(\mathbf{x}) \, d\mathbf{x}$
Y_n	$-\int \int_{E_n} \int \ln(\max(x_1, \dots, x_n)) \cdot \Psi_n(\mathbf{x}) \, d\mathbf{x}$
$Z_{n,k}$	$\int \int_{E_{n,k}} \int \Psi_n(\mathbf{x}) \, d\mathbf{x}$

An *addition chain* for a positive integer a is the set of positive integers $\{b_0, \dots, b_l\}$ with the following properties:

- (i) $b_0 = 1$,
- (ii) for all $1 \leq k \leq l$ there exist i, j such that $b_k = b_i + b_j$, for $0 \leq i, j < k$,
- (iii) $b_l = a$.

We call the index l the length of the addition chain. We denote an addition chain by $L(a)$ and its length by $l(a)$.

An addition sequence for a set of positive integers $\{a_1, \dots, a_n\}$ is a set of positive integers $\{b_0, \dots, b_l\}$ with the following properties:

- (i) $b_0 = 1$,
- (ii) for all $1 \leq k \leq l$ there exist i, j such that $b_k = b_i + b_j$, for $0 \leq i, j < k$,
- (iii) for $1 \leq m \leq n$: $a_m \in \{b_0, \dots, b_l\}$.

We call n the *width* of the addition sequence and l the length. It will be assumed in the rest of the text that an addition sequence will be constructed for a_1, \dots, a_n . The set $\{b_0, \dots, b_l\}$ will be denoted by $L(a_1, \dots, a_n)$. An addition chain is an addition sequence of width 1.

We use also the following definitions and functions:

- $L^{(k)}(a_1, \dots, a_n)$ an addition sequence containing a_1, \dots, a_n using only k memory locations ($k \geq n$)
- $l(a_1, \dots, a_n)$ length of an addition sequence containing a_1, \dots, a_n

$\rho(a_1, \dots, a_n)$	$l(a_1, \dots, a_n) / \log_2 a_n$
$\bar{\rho}(\alpha, n)$	average value of $\rho(a_1, \dots, a_n)$ such that $\lambda(a_n) = a$. We abbreviate this notation to $\bar{\rho}$
$L_1(a)$	the addition chain for a constructed by the binary algorithm
$L_n(a_1, \dots, a_n)$	the addition sequence containing a_1, \dots, a_n constructed by the Brun-algorithm (cf. [16, 8])
$l_n(a_1, \dots, a_n)$	length of the addition sequence containing a_1, \dots, a_n , constructed by the Brun-algorithm
$\rho_n(a_1, \dots, a_n)$	$l_n(a_1, \dots, a_n) / \log_2 a_n$
$\bar{\rho}_n$	average value of $\rho_n(a_1, \dots, a_n)$

3 A brief review of the literature

Much is known about bounds for addition chains. For instance, it is known that

$$\log_2 a + \log_2 \nu(a) - 2.13 \leq l(a). \quad (1)$$

This bound is from [29]. In [9] Brauer gives an upper bound of

$$l(a) \leq \log_2 a + \log_2 a / \log_2 \log_2 a + o(\log a / \log \log a). \quad (2)$$

This bound is theoretical. In practise we can't get this bound for larger numbers. The k -window-method (k -ary-method) described in [23] gives a worse upper bound:

$$l(a) \leq \log_2 a + \frac{1}{k} \log_2 a + 2^{k-1} - k - 1, \quad (3)$$

which is optimal if $k^2 \cdot 2^k \approx 2 \cdot \log_2 a / \ln 2$. Less is known about addition sequences and vector addition chains. Straus gives in [33] an upper bound for vector addition chains:

$$l(a_1, \dots, a_n) \leq \log_2 a_n + \frac{1}{k} \log_2 a_n + 2^{n_k} - n - 1, \quad (4)$$

which is optimal if $k^2 \cdot 2^{n_k} \approx \log_2 a_n / (n \cdot \ln 2)$. In [40], Yao gives an upper bound for addition sequences:

$$l(a_1, \dots, a_n) \leq \log_2 a_n + \frac{n}{k} \log_2 a_n + n \cdot 2^k - k - 1, \quad (5)$$

which is optimal if $k^2 \cdot 2^k \approx \log_2 a_n / \ln 2$. Here a_n is the largest number in the sequence.

3.1 Space complexity

In the practice of RSA it is possible to calculate X^{23} by $X, X^2, X^4, X^5, X^{10}, X^{11}, X^{22}, X^{23}$ or by $X, X^2, X^4, X^8, X^{16}, X^{17}, X^{19}, X^{23}$; the length of the chains in both cases are equal (7). The difference is that in the second case, 3 memory locations are needed for storing X, X^2 , and X^4 , in order to calculate X^{17}, X^{19} , and X^{23} respectively, while in the first case only X has to be stored for later use. Therefore we introduce a new constraint,

namely addition chains and sequences with a restricted number of memory locations. The definition of the number of memory locations seems to be arbitrary, but it corresponds to the practical situation (see [16, 8]).

Definition. Let $L(a) = \{a_0, a_1, \dots, a_l\}$, where $a_0 = 1, a_l = a$ be an addition chain for a . We define by m_i the number of memory locations which are in use after the calculation of X^{a_i} . More precisely: $m_i = \#\{a_j, 0 \leq j \leq i \mid \exists a_k, i+1 \leq k \leq l, \text{ with } a_k = a_{k-1} + a_j \text{ and } k-j > 1\}$. (In this definition we assume star-step chains, but the definition can easily be generalized.) We define $M(L) = \max m_i$ the total number of memory locations used for constructing $L(a)$. The definitions for the memory restrictions on addition sequences and vector addition chains are comparable.

Example. $L(23) = 1, 2, 3, 5, 10, 20, 23$. Now $a_2 = 3$ and $m_2 = 2$, since X^2 is stored for calculating X^5 and X^3 is stored for calculating X^{23} .

We define by $L^{(n)}(a)$ an addition chain which uses at most n memory locations. The binary algorithm can be executed as an $L^{(1)}$ algorithm, (namely by storing X and multiplying by X for each bit "1" in the binary representation of a . Nevertheless there exists a faster $L^{(1)}$ algorithm than the binary algorithm (cf. [16]).

Less is known about $L^{(n)}$ algorithms for $n > 1$. The Generalized Window Algorithm of Yao is an $L^{(n(2^k-1))}$ algorithm, here is n the width and k the size of the windows. The algorithm of Straus is an $L^{(2^{kn}-1)}$ algorithm. Both algorithms are therefore of no use in the RSA practice for larger n .

3.2 Brun's algorithm

This algorithm is a generalization of the continued fraction algorithm described in [4]. In that paper only sequences of width 2 were obtained. The Brun Algorithm is its generalization. We distinguish two algorithms. The first algorithm is an addition sequence algorithm. The second algorithm is the vector addition chain algorithm, which was considered in [8]. The description of this algorithm will not be given in this paper. The basis for both algorithms is Brun's multi continued fraction algorithm. Suppose that $a_1 \leq \dots \leq a_n$. Let $r = \left\lfloor \frac{a_n}{a_{n-1}} \right\rfloor$. Let $T : \mathbb{Z}^n \rightarrow \mathbb{Z}^n$ be a map with $T(a_1, \dots, a_n) = (a_1, \dots, a_i, b, a_{i+1}, \dots, a_{n-1})$, where $b = a_n - ra_{n-1}$ and $a_i \leq b \leq a_{i+1}$. Suppose that the addition sequence for $T(a_1, \dots, a_n)$ is known. The addition sequence for a_1, \dots, a_n can then be constructed by adding to $L_n(T(a_1, \dots, a_n))$ the elements $r_i a_{n-1}$ for $1 \leq i \leq l$ and a_n , where $L_1(r) = \{r_0, r_1, \dots, r_l\}$ is the binary addition chain for r .

This algorithm is an $L^{(n)}$ algorithm. Hence, using the Brun Algorithm we need only n memory locations. This will be proved in the following theorem.

Theorem 3.1 *The Brun Algorithm for width n is an $L^{(n)}$ algorithm.*

Proof. This will be proved by induction to n and $a = \max\{a_1, \dots, a_n\}$. For $n = 1$ we consider the binary algorithm, which needs only 1 memory location. Suppose we proved the theorem up to $n - 1$ and for n -tuples with $a_n < a$. Now we consider $L_n(a_1, \dots, a_n)$, with $a_n = a$. Hence we proved that we can construct $L_n(T(a_1, \dots, a_n))$ with at most n

memory locations. We may assume that after constructing $L_n(T(a_1, \dots, a_n))$ the memory locations are filled by X^c , where c runs through the elements of $T(a_1, \dots, a_n)$. Since the binary algorithm is an $L(1)$ algorithm, we can construct $X^{a_{n-1}}, X^{2a_{n-1}}, \dots, X^{ra_{n-1}}$ without any extra memory location. Then we calculate $X^b \cdot X^{ra_{n-1}}$, where $b = a_n - ra_{n-1}$ and place the result in the memory location where X^b was stored. \square

In case of the Brun Algorithm for vector addition chains of width n , it can be proved that this is an $L^{(n)}$ algorithm too. For examination of the proof, see [16]. For a detailed description of the algorithm, see [8].

4 Average value of the Brun algorithm

Suppose that the computer needs t operations on average for a multiplication $Y \cdot Z$ or Y^2 . (This paper makes no distinction between multiplying different multiplicands and squaring; there are differences, however, if we consider, eg., $\text{GF}(2^n)$ (cf. [1]).) The number of operations in order to calculate $L(a_1, \dots, a_n)$ is $t \cdot l(a_1, \dots, a_n)$. We introduce the number $\rho(a_1, \dots, a_n) = l(a_1, \dots, a_n) / \log_2 a_n$. Now the number of operations can be expressed in terms of $\log_2 a_n$. If $\rho(a_1, \dots, a_n)$ were independent of the choice of a_1, \dots, a_n , then we could easily calculate the number of operations. Unfortunately this is not the case. However we can approximate $\rho(a_1, \dots, a_n)$ by $\bar{\rho}(\alpha, n)$. We define $\bar{\rho}(\alpha, n)$ by

$$\bar{\rho}(\alpha, n) = \frac{1}{\Sigma} \cdot \sum_{(a_1, \dots, a_n)} \frac{l_n(a_1, \dots, a_n)}{\log_2 a_n}, \quad (6)$$

where the sum is taken over all n -tuples (a_1, \dots, a_n) with $\lambda(a_n) = \alpha$ and Σ is the number of those n -tuples (a_1, \dots, a_n) . We call $\bar{\rho}(\alpha, n)$ the average value of sequences/chains of width n . We will abbreviate this notation to $\bar{\rho}$. Notice that for Algorithm L_1 we have $\bar{\rho}(\alpha, 1) = \frac{3}{2}$. We will now study approximations of the form

$$l(a_1, \dots, a_n) \approx \bar{\rho} \log_2 a_n$$

in the case of the Brun Algorithm. In the case of the Brun Algorithm, we will denote the average value of ρ by $\bar{\rho}_n$, where the index n indicates the width.

Theorem 4.1 *Let X_n, Y_n , and $Z_{n,k}$ be the integrals, which were defined in Section 2.*

Then $\bar{\rho}_n = \frac{\sigma_n}{\tau_n}$, where $\tau_n = \frac{Y_{n-1}}{\ln 2 \cdot X_{n-1}}$ and $\sigma_n = 1 + \sum_{k=1}^{\infty} \frac{Z_{n-1,k}}{X_{n-1}} \cdot (l_1(k) - l_1(k-1))$.

Without proof, the following corollary will be given in this paper. The proof of (i) can be found in [16], while the proof of (ii) is still unpublished. In fact, the proofs consist of a numerical evaluation of Theorem 4.1. It can be verified that these results correspond very well with the results in Table II of the Appendix.

Corollary 4.2 *We have*

(i) $\bar{\rho}_2 = 1,6080967\dots$,

(ii) $\bar{\rho}_3 = 1,7768807\dots$

The following conjecture indicates the behavior of $\bar{\rho}_n$.

Conjecture 4.3 $\bar{\rho}_n = O\left(\frac{1}{\log_2 \mu_n}\right)$, where μ_n is the root of the equation $x^n - x^{n-1} = 1$, with $\mu_n > 1$.

We were unable to find a proof for this conjecture. We used two approaches. One approach was trying to find an upperbound for $\frac{Y_{n-1}}{X_{n-1}}$, the other approach is sketched in the motivation of this conjecture. A consequence of this conjecture is

Conjecture 4.4 $\bar{\rho}_n = O\left(\frac{n}{\log_2 n}\right)$.

4.1 Ergodic theoretical background

Before proving Theorem 4.1 and sketching Conjecture 4.3, we will give a brief overview of results from Ergodic Theory which will be used. Let E_n be the n -dimensional unit-cube. We consider on E_n the map $t : E_n \rightarrow E_n$ defined by $t(x_1, \dots, x_n) = \left(\frac{1}{x_i} - \left\lfloor \frac{1}{x_i} \right\rfloor, \frac{x_1}{x_i}, \dots, \frac{x_n}{x_i}\right)$, if $\max(x_1, \dots, x_n) = x_i$. (All coordinates except of the largest one is divided by the largest coordinate, while the largest coordinate is replaced by a function of it.) Notice that x_1, \dots, x_n are not necessarily ordered. This map t is due to Brun. In fact we consider the so called *Transposed Brun Algorithm*, while Brun's map is slightly different. For a good survey, see [35].

Ergodic Theory is interested in the behavior of x_1, \dots, x_n after several steps. Questions like "how often is $\left\lfloor \frac{1}{x_i} \right\rfloor = 1$?" , "how large is $\max(x_1, \dots, x_n)$ in average?" and "how often is $\frac{1}{x_i} - \left\lfloor \frac{1}{x_i} \right\rfloor$ smaller than the other coordinates?" can be answered using this theory.

Let $f : E_n \rightarrow \mathbb{R}$ be an integrable function. Suppose we want to know the average value $\frac{1}{m} \sum_{k=0}^{m-1} f(t^k(x_1, \dots, x_n))$, if m tends to infinity. Then Ergodic Theory tells us that

$$\lim_{m \rightarrow \infty} \frac{1}{m} \sum_{k=0}^{m-1} f(t^k(\mathbf{x})) = \frac{1}{X_n} \int \int_{E_n} f(\mathbf{x}) \cdot \Psi_n(\mathbf{x}) \, d\mathbf{x}, \quad (7)$$

where $\mathbf{x} = (x_1, \dots, x_n)$ and $X_n = \int \int_{E_n} \Psi_n(\mathbf{x}) \, d\mathbf{x}$ as defined in Section 2. Here

$\Psi_n(\mathbf{x}) = \frac{1}{(1+x_1) \cdots (1+x_1 + \cdots + x_n)}$ is called the *invariant measure*. For the case $n = 1$, this can be found in [6]. The case in which $n > 1$ is rather new. Schweiger found in [30] another invariant measure. He uses another map t and instead of the unit cube E_n , he uses the area B_n , which is defined by $B_n = \{\mathbf{x} | 0 \leq x_1 \leq \cdots \leq x_n \leq 1\}$. (In fact he folded the unit cube E_n $n!$ times and got B_n). His invariant measure seems to be different, but the two invariant measures are in fact identical ([32]).

4.2 Proofs

Proof of Theorem 4.1. Our proof can be compared with the calculation of the average number of steps in Euclid's Algorithm (cf. [23]). In fact, using this proof one can generalize the result to an algorithm for calculating $\gcd(a_1, \dots, a_n)$ using Brun's Algorithm. Unfortunately this yields worse results than $\gcd(\gcd(a_1, a_2), a_3)$, etc.

Let (a_1, \dots, a_n) be an arbitrary n -tuple (hence not necessarily ordered). Let $u_k = \max(T^k(a_1, \dots, a_n))$. Then $\rho_n(a_1, \dots, a_n) = l_n(a_1, \dots, a_n) / \log_2 u_0$. First we consider the denominator. Notice that $u_0 = \frac{u_0}{u_1} \cdot \frac{u_1}{u_2} \cdots \frac{u_{m-1}}{u_m}$, (we assume that $u_m = 1$). And

therefore we have that $\log_2(u_0) = \frac{1}{\ln 2} \sum_{k=0}^{m-1} \ln \left(\frac{u_k}{u_{k+1}} \right)$. Now we consider the numerator.

$l_n(a_1, \dots, a_n) = l_n(T(a_1, \dots, a_n)) + l_1(r) + 1$, where $r = \left\lfloor \frac{u_0}{u_1} \right\rfloor$. Therefore $l_n(a_1, \dots, a_n) = \sum_{k=0}^{m-1} (l_1 \left(\left\lfloor \frac{u_k}{u_{k+1}} \right\rfloor \right) + 1)$. Instead of the map $T(a_1, \dots, a_n)$ we will consider $t \left(\frac{a_1}{a_i}, \dots, \frac{a_n}{a_i} \right)$, in which the i -th coordinate is removed (hence we consider a map on E_{n-1}). Let $v_k = \max(t^k \left(\frac{a_1}{a_i}, \dots, \frac{a_n}{a_i} \right))$. Then we have $v_k = \frac{u_{k+1}}{u_k}$. Now $\rho_n(a_1, \dots, a_n)$ can be expressed as

$$\rho_n(a_1, \dots, a_n) = \frac{\frac{1}{m} \sum_{k=0}^{m-1} (l_1 \left(\left\lfloor \frac{1}{v_k} \right\rfloor \right) + 1)}{\frac{-1}{m \cdot \ln 2} \sum_{k=0}^{m-1} \ln(v_k)}. \quad (8)$$

In order to consider $\overline{\rho_n}$ we may assume that m tends to infinity. Notice that both the numerator and denominator of Formula 8 are finite. A small step is made from rational numbers v_k to real numbers. This is allowed, (see [6]). (For a more precise approach, see [23]). We apply Ergodic Theory on the numerator and denominator as was described in the previous section. It will be shown that

$$\lim_{m \rightarrow \infty} \frac{1}{m} \sum_{k=0}^{m-1} (l_1 \left(\left\lfloor \frac{1}{v_k} \right\rfloor \right) + 1) = \sigma_n$$

and

$$\lim_{m \rightarrow \infty} \frac{-1}{m \cdot \ln 2} \sum_{k=0}^{m-1} \ln(v_k) = \tau_n.$$

The calculation for the denominator is easy. We have

$$\begin{aligned} \tau_n &= \lim_{m \rightarrow \infty} \frac{-1}{m \cdot \ln 2} \sum_{k=0}^{m-1} \ln(v_k) \\ &= \frac{-1}{\ln 2} \frac{1}{X_{n-1}} \int \int_{E_{n-1}} \int \ln(\max(x_1, \dots, x_n)) \cdot \Psi_{n-1}(\mathbf{x}) \, d\mathbf{x} \\ &= \frac{Y_{n-1}}{\ln 2 \cdot X_{n-1}}. \end{aligned}$$

For the numerator we have

$$\begin{aligned}
\sigma_n &= \lim_{n \rightarrow \infty} \frac{1}{m} \sum_{k=0}^{m-1} (l_1 \left(\left\lfloor \frac{1}{v_k} \right\rfloor \right) + 1) \\
&= \frac{1}{X_{n-1}} \int \int_{E_{n-1}} \int (l_1(\max(x_1, \dots, x_n)) + 1) \cdot \Psi_{n-1}(\mathbf{x}) \, d\mathbf{x} \\
&= 1 + \frac{1}{X_{n-1}} \sum_{k=1}^{\infty} \int \int_{\Delta_{n-1,k}} \int l_1(k) \cdot \Psi_{n-1}(\mathbf{x}) \, d\mathbf{x} \\
&= 1 + \frac{1}{X_{n-1}} \sum_{k=1}^{\infty} l_1(k) \cdot (Z_{n-1,k} - Z_{n-1,k+1}).
\end{aligned}$$

This proves Theorem 4.1. □

Motivation of Conjecture 4.3. Let $a_1 < a_2 < \dots < a_n$ and $T(a_1, \dots, a_n) = (a_1, \dots, a_i, b, a_{i+1}, \dots, a_n)$ where $b = a_n - r a_{n-1}$ and $r = \left\lfloor \frac{a_n}{a_{n-1}} \right\rfloor$. It is simple to prove that $\lim_{n \rightarrow \infty} \sigma_n = 1$. This can be verified in Table I of the Appendix. It corresponds to the fact that if n tends to infinity then r tends to 1.

In order to approximate the behavior of τ_n if n tends to infinity, we have to approximate $\frac{\max\{a_1, \dots, a_n\}}{\max\{T(a_1, \dots, a_n)\}}$. Suppose $b = x_n - x_{n-1} < a_1$ and

$$\frac{a_n}{a_{n-1}} = \frac{a_{n-1}}{a_{n-2}} = \dots = \frac{a_1}{b}. \quad (9)$$

Denote $\mu_n = \frac{a_i+1}{a_i}$. Then $a_k = \mu_n^k \cdot b$. Hence $b = a_n - a_{n-1} = (\mu_n^n - \mu_n^{n-1})b$. Under these conditions we have

$$\bar{\rho}_n \approx \frac{\max\{a_1, \dots, a_n\}}{\max\{T(a_1, \dots, a_n)\}} \approx \frac{\log_{\mu_n} a_n}{\log_2 a_n} = \frac{\ln 2}{\ln \mu_n}, \quad (10)$$

using Formula 6. The main open question is how much do a_1, \dots, a_n differ from the situation sketched in 9 and what are the consequences?

Motivation of Conjecture 4.4. An approximation of the largest root of $x^n - x^{n-1} = 1$ is $\mu \approx 1 + \frac{\ln n}{n}$, since $(1 + \frac{\ln n}{n})^n \approx e^{n \ln(1 + \frac{\ln n}{n})} \approx e^{\ln n} = n$ and $(1 + \frac{\ln n}{n})^{n-1} \approx n - 1$.

5 Remarks, conclusions and open problems

The tables. Appendix A presents two tables. Table I shows some numerical approximations of the integrals X_n , Y_n and $Z_{n,2}$. Notice that $\bar{\rho}_n \approx \frac{1}{\tau_n} \approx \frac{X_{n-1}}{\ln(2) \cdot Y_{n-1}}$. Table II contains the results of 100 experiments for each width. Each experiment started by choosing randomly n 512-bit numbers. First we applied $2n$ steps of the Brun Algorithm without paying attention to the results. Then we considered 100 steps of which the results have been tabulated.

There are many multi-continued fraction algorithms (cf. [10]). Another algorithm, which is related to the Jacobi-Perron Algorithm, can be defined on E_n by

$$t(x_1, \dots, x_n) = \left(\frac{y}{x_i}, \frac{x_1}{x_i}, \dots, \frac{x_n}{x_i} \right), \text{ where } y = \frac{1}{x_i} - \left\lfloor \frac{1}{x_i} \right\rfloor \text{ and } x_i = \max(x_1, \dots, x_n).$$

This algorithm was considered by Veugen in [37]. He found worse results compared to the results of the Brun Algorithm. Besides this experimental fact, there is another problem. Even though it has been proved that Ergodic Theory can be applied on this algorithm, the invariant measure is still unknown (cf. [30]).

Some open problems. Let $L_{\text{OPT}}(a)$ denote a smallest addition chain for a , and let $l_{\text{OPT}}(a)$ be its length. Let $m_{\text{OPT}}(a) = M(L_{\text{OPT}}(a))$. Let d_n be the smallest number such that $m_{\text{OPT}}(d_n) = n$. Which are the numbers d_n ? We found $d_1 = 1$ and $d_2 = 15$. A comparable problem can be posed for addition sequences and vector addition chains.

Let $L(a_1, \dots, a_n)$ be a minimal addition sequence which needs k memory locations. How many memory locations are needed for the corresponding minimal vector addition chain? (In [23, 27, 8] one can read how vector addition chains are related to addition sequences.)

We are interested in a precise evaluation of the integrals X_n , Y_n and $Z_{n,k}$ for $n > 2$. We were able to express X_2 , Y_2 and $Z_{2,k}$ in terms of the poly-logarithm by applying [26]. Especially interesting is a precise evaluation of $\frac{Y_{n-1}}{X_{n-1}}$, since this fraction approximates $\bar{\rho}_n$.

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A Some Tables.

n	X_{n-1}	Y_{n-1}	$\tau_n = X_{n-1}/\ln(2) \cdot Y_{n-1}$	$Z_{n-1,2}$	$Z_{n-1,2}/X_{n-1}$
2	0.693147	0.8225	0.5841	0.4055	0.5850
3	0.374053	0.2504	1.035	0.1394	0.3726
4	0.166879	0.082	1.41	0.0418	0.2505
5	0.063856	0.025	1.75	0.0112	0.1748
6	0.021484	0.007	2.1	0.0027	0.1254

n	$\sigma_n - 1$	$1/\tau_n$	$\bar{\rho}_n$	$\frac{1}{\tau_n}$	$\frac{1}{\log_2(\mu_n)}$	$\bar{\rho}_n \log_2(\mu_n)$
2	1.7977	1.7396	1.6083	0.5747	1.4404	1.1166
3	0.7247	0.9694	1.7791	1.0315	1.8134	0.9811
4	0.3913	0.7079	1.9654	1.4126	2.1507	0.9138
5	0.2470	0.5727	2.1775	1.7462	2.4650	0.8837
6	0.1596	0.4847	2.3923	2.0631	2.7625	0.8660
7	0.1124	0.4286	2.5954	2.3331	3.0472	0.8517
8	0.0730	0.3808	2.8175	2.6259	3.3215	0.8483
9	0.0555	0.3483	3.0302	2.8709	3.5873	0.8447
10	0.0462	0.3228	3.2414	3.0983	3.8459	0.8393
11	0.0332	0.3004	3.4395	3.3290	4.0983	0.8420
12	0.0257	0.2803	3.6586	3.5670	4.3451	0.8388
13	0.0206	0.2652	3.8477	3.7701	4.5872	0.8347
14	0.0161	0.2523	4.0271	3.9633	4.8249	0.8399
15	0.0124	0.2383	4.2488	4.1968	5.0586	0.8432
16	0.0097	0.2264	4.4594	4.4165	5.2889	0.8404
17	0.0075	0.2173	4.6356	4.6011	5.5158	0.8438
18	0.0044	0.2074	4.8433	4.8221	5.7398	0.8492
19	0.0059	0.1987	5.0618	5.0321	5.9610	0.8475
20	0.0037	0.1916	5.2374	5.2181	6.1796	0.8443
21	0.0031	0.1857	5.4003	5.3836	6.3959	0.8503
22	0.0022	0.1783	5.6206	5.6084	6.6098	0.8528
23	0.0017	0.1722	5.8179	5.8081	6.8217	0.8535
24	0.0016	0.1669	6.0015	5.9919	7.0316	0.8516
25	0.0008	0.1623	6.1650	6.1600	7.2397	0.8484
30	0.0005	0.1418	7.0543	7.0508	8.0550	0.8585
40	0.0002	0.1134	8.8177	8.8159	10.1877	0.8655
50	0.0000	0.0951	10.5200	10.5200	12.0248	0.8749

For the explanation of the experiments, see Section 5.

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