# A Note on Spectral Decomposition and Maximum Likelihood Estimation in ANOVA Models with Balanced Data 

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Received July 1982


#### Abstract

A simple derivation of the spectral decomposition of the covariance matrix for a general multi-way variance components model is presented. So-called balanced data are assumed to be available. Spectral decomposition is exploited to derive the information matrix and the first-order conditions for the maximum likelihood estimation of the variance components parameters.


Keywords. ANOVA, spectral decomposition.

## 1. Introduction

In this note we present a simple derivation of the spectral decomposition of the covariance matrix for a general multi-way variance components model. Balanced data (to be defined below) are assumed to be available. This problem has been discussed before by Searle and Henderson (1979), who present a longer derivation. To illustrate the importance of the spectral decomposition, we exploit it to derive the information matrix and the first-order conditions for the maximum likelihood estimation of the variance components parameters.

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## 2. The model

Let there be a random vector $u$ which is normally distributed with zero expectation and covariance matrix $V$ of the following structure

$$
\begin{equation*}
V=\sum_{d} \lambda_{d} N_{d} \tag{2.1}
\end{equation*}
$$

where $d$ is a $k$-vector of zeros and ones. The summation runs over all such vectors (i.e. over $2^{k}$ elements). The $\lambda_{d}$ are nonnegative parameters and $N_{d}$ is a matrix consisting of a Kronecker product of $k$ separate matrices of order $n_{i}(i=1, \ldots, k)$, each of which is either a unit matrix ( $I_{n_{i}}$ ) or a square matrix of ones ( $J_{n_{i}}$ ). Furthermore, let $d_{i}$ be the $i$ th element of $d$. A unit matrix occurs in the $i$ th position when $d_{i}=1$ and a matrix of ones when $d_{i}=0$. For example, if $k=3, d=(0,1,1)$,
then
$N_{011}=J_{n_{1}} \otimes I_{n_{2}} \otimes I_{n_{3}}$,
with matrices of order $n_{1}, n_{2}$ and $n_{3}$, respectively. Whenever a covariance matrix has format (2.1), we have balanced data.

## 3. The spectral decomposition

Assume it is possible to rewrite the covariance matrix $V$ in the format
$V=\sum_{d} \phi_{d} M_{d}$,
with the $\phi_{d}$ scalar parameters, and $M_{d}$ a Kronecker product of $k$ separate matrices; but here the $i$ th matrix in $M_{d}$ equals $E_{n_{i}} \equiv I_{n_{i}}-J_{n_{i}} / n_{i}$ if $d_{i}=1$ and it equals $\bar{J}_{n_{i}}=\mathrm{J}_{\mathrm{n}_{i}} / n_{i}$ if $\mathrm{d}_{\mathrm{i}}=0$. For example
$M_{011}=\bar{J}_{n_{1}} \otimes E_{n_{2}} \otimes E_{n_{3}}$.
Whenever $V$ can be written as in (2.1), it can also be writen as in (3.1) (and vice versa). An example may suffice to show why
$N_{011}=n_{1}\left(M_{000}+M_{010}+M_{001}+M_{011}\right)$,
as is easily verified. In general, the relation between $N_{d}$ and $M_{d}$ can be written as
$N_{d}=n^{\bar{d}} \sum_{e \leqslant d} M_{e}$,
where the following shorthand notation is used: $\bar{d}=\iota-d$ ( $\iota \mathrm{a} k$-vector of ones) and
$n^{\bar{d}}=n^{i-d} \equiv \sum_{i=1}^{k} n_{i}^{1-d_{i}} ;$
the notation $e \leqslant d$ means that the elements of $e$ are not greater than the corresponding elements of $d$. So,

$$
\begin{align*}
V & =\sum_{d} \lambda_{d} N_{d}=\sum_{d} \lambda_{d} n^{\bar{d}} \sum_{e \leqslant d} M_{e} \\
& =\sum_{d}\left(\sum_{e \geqslant d} \lambda_{e} n^{\bar{e}}\right) M_{d} \equiv \sum_{d} \phi_{d} M_{d}, \tag{3.6}
\end{align*}
$$

where the third equality sign can be checked by writing out the third member. Now the $M_{d}$ can be verified to have the following properties:

- they add up (over all $d$ ) to the unit matrix;
- they are idempotent;
- $M_{d} M_{e}=0$ for $d \neq e$.

Thus (3.6) is exactly the spectral decomposition of $V$. There are at most $2^{k}$ different eigenvalues $\phi_{d}$ ( $\phi_{d}=\sum_{e \geqslant d} \lambda_{e} n^{\bar{c}}$ ), with multiplicity equal to the rank of the corresponding matrix $M_{d}$, which equals $n^{d}$.

The spectral decomposition of $V$ greatly facilitates the computation of its powers since
$V^{\alpha}=\sum_{d} \phi_{d}^{\alpha} M_{d}$ for any scalar $\alpha$.

## 4. Maximum likelihood estimation

Let $V_{f}=\partial v / \partial \lambda_{f}$, then the first-order condition for maximum likelihood estimation of $\lambda_{f}$ is
$\operatorname{tr}\left(V_{f} V^{-1}\right)=u^{\prime}\left(V^{-1} V_{f} V^{-1}\right) u$,
where $u$ was introduced at the beginning of Section 2.

A typical element of the information matrix (apart from a factor $-\frac{1}{2}$ ) is (e.g. Searle (1970))
$\operatorname{tr}\left(V_{f} V^{-1} V_{g} V^{-1}\right)$.
Given the spectral decomposition it is easy to calculate these quantities:
$v_{f}=\sum_{d} \frac{\partial \lambda_{d}}{\partial \lambda_{f}} N_{d} \equiv N_{f}=n^{\bar{f}} \sum_{e \leqslant f} M_{e} ;$
so,

$$
\begin{align*}
& \operatorname{tr}\left(V_{f} V^{-1}\right)=n^{\bar{f}} \operatorname{tr}\left(\sum_{d} \frac{1}{\phi_{d}} M_{d}\right)\left(\sum_{e \leqslant f} M_{e}\right) \\
&=n^{\bar{f}} \operatorname{tr}\left(\sum_{e \leqslant f} \frac{1}{\phi_{e}} M_{e}\right) \\
&=n^{j} \sum_{e \leqslant f} \frac{n^{e}}{\phi_{e}}=n^{\bar{f}} \sum_{e \leqslant f} \frac{n^{e}}{\sum_{d \geqslant e} \lambda_{d} n^{\bar{d}}} \\
&=\sum_{e \leqslant f} \frac{1}{\sum_{d \geqslant e} \lambda_{d} n^{\bar{d}-\overline{f-e}}} ;  \tag{4.4}\\
& u^{\prime}\left(V^{-1} V_{f} V^{-1}\right) u=n^{\bar{j}} \sum_{e \leqslant f} \frac{1}{\phi_{e}^{2}} u^{\prime} M_{e} u ; \tag{4.5}
\end{align*}
$$

$$
\begin{align*}
\operatorname{tr}\left(V_{f} V^{-1} V_{g} V^{-1}\right) & =n^{\bar{f}+\bar{g}} \sum_{e \leqslant f} \frac{1}{\phi_{e}^{2}} \operatorname{tr}\left(M_{e}\right) \\
& =n^{\bar{f}+\bar{g}} \sum_{e \leqslant f} \frac{n^{e}}{\phi_{e}^{2}} \quad(f \leqslant g) . \tag{4.6}
\end{align*}
$$

The last two expressions can be worked out further by substituting for $\phi_{e}$, just as in (4.4).

## 5. Conclusion

The spectral decomposition of the covariance matrix of balanced designs can be obtained in a
simple way. The spectral decomposition, in turn, greatly facilitates the derivation of the information matrix and first-order conditions for maximum likelihood estimation of the variance components parameters.

## References

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[^0]:    * The views expressed in this paper are those of the authors and do not necessarily reflect the policies of the Netherlands Central Bureau of Statistics.

