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Research Article

Bayesian spatial analysis of demographic survey data: An application to contraceptive use at first sexual intercourse

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Riccardo Borgoni¹

Francesco C. Billari²

Abstract

In this paper we analyze the spatial patterns of the risk of unprotected sexual intercourse for Italian women during their initial experience with sexual intercourse. We rely on geo-referenced survey data from the Italian Fertility and Family Survey, and we use a Bayesian approach relying on weakly informative prior distributions. Our analyses are based on a logistic regression model with a multilevel structure. The spatial pattern uses an intrinsic Gaussian conditional autoregressive (CAR) error component. The complexity of such a model is best handled within a Bayesian framework, and statistical inference is carried out using Markov Chain Monte Carlo simulation.

In contrast with previous analyses based on multilevel model, our approach avoids the restrictive assumption of independence between area effects. This model allows us to borrow strength from neighbors in order to obtain estimates for areas that may, on their own, have inadequate sample sizes. We show that substantial geographical variation exists within Italy (Southern Italy has higher risks of unprotected first-time sexual intercourse). The findings are robust with respect to the specification of the prior distribution. We argue that spatial analysis can give useful insights on unmet reproductive health needs.

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1. Introduction

In the literature on potential health risks caused by sexual behavior, a particular emphasis is placed on the behavior of adolescents. Adolescents are more likely to contract sexually transmitted diseases (STDs), including HIV/AIDS. Adolescents also have a higher risk of unplanned pregnancies (Kotckick et al., 2001). Consequently, adolescent sexual behavior has been considered one of the fundamental factors for the study of health risks among young people. This is mainly due to the fact that half of all new cases of HIV infections involve young people between 15 and 24 years of age (UNFPA, 2000). Also, the definition of risk behavior is often linked with sexual activity at a particularly early age (Duberstein Lindberg et al., 2000), but attention is also being placed on the use of contraceptive methods at first-time sexual intercourse (Hogan et al., 2000). Ku and collaborators (Ku et al., 1994) have also shown that the use of contraceptive decisions.

In this paper we analyze data from Italy. In this country, young adults tend to wait to have sexual intercourse considerably longer than their counterparts in other Western countries do (Bozon and Kontula 1997; Cazzola 1999; Ongaro 2001). Our attention is directed towards the reproductive health risks of young people who do not use contraceptive methods at first sexual intercourse. Obviously, this indicator needs to be studied in a multi-dimensional context and may be insufficient when considered on its own. More precisely, the study of risk connected with behavior is flawed when the contraceptive method is not known, as the method may not be suitable for the prevention of STDs and/or pregnancy. This is a concern particularly in Italy where traditional contraceptive methods are still used, even by adults (Note 1) (Bonarini 1999; Spinelli et al., 2000). Because of the limits of available data, this study concentrates on the non-use of contraception at first-time sexual intercourse as a risk indicator, not on different types of birth control methods. This indicator will provide an underestimated risk measure of being exposed to pregnancy (because even when birth control is used, the method involved may not be fully effective), and an even more underestimated risk measure for the exposure to STDs (even effective contraceptive methods such as oral contraceptives do not provide protection against STDs) (Note 2). The indicator may however overestimate risks because especially when first sexual intercourse takes place after first marriage, non-contraception may be a choice, although first sexual intercourse in Italy for recent cohorts is almost completely detached from marriage (Ongaro, 2001).

A fundamental factor in the study of contraceptive decision-making is the environment in which young people operate. The information that flows through social networks, public services, local media, and schools, and the availability of contraceptives are important contextual characteristics in this regard (Brewster et al. 1993; Billy et al. 1994; Teitler and Weiss 2000). This speaks to the importance of georeferencing individual-level data. Italy is a particularly interesting case for scholars interested in studying geographical differentials, as social and historical heterogeneity within the country corresponds, to a wide extent, to geographical heterogeneity. Throughout Italy, for example, the age at which people have sexual intercourse for the first time varies widely, especially for women (Billari and Borgoni 2002; Ongaro 2001). Mapping territorial influence is also important because any potential policy intervention for risk reduction is more effective when planned at a local level, as in any Western country. With reference to the United States, Teitler and Weiss (2000) found educational context to be of great importance. Furthermore, Mauldon and Luker (1996) showed that contraceptive education makes it one-third more likely that contraception will be used at first-time intercourse, and that condoms will be the method used. The absence of official statistics on the subject creates problems both in terms of measurement and statistical appraisal of reproductive health risks (with the exception of voluntary abortions). In these cases, survey data becomes extremely useful. Furthermore, if one wants to take into account the importance of spatial distribution, one should apply adequate mapping techniques. Such techniques have to be suitable in terms of controlling for sample variability, possibly by exploiting the data's geographical distribution and the differential spatial incidence of the phenomenon of interest.

This paper proposes methods for the study of spatial distribution in Italy pertaining to the non-use of contraceptives at first-time sexual intercourse by studying the data provided by the Fertility and Family Survey. More precisely, with a spatial statistical model featuring a Bayesian approach, we produce maps at the provincial level. The paper is structured as follows: Section 2 provides an introduction of the data studied. The methodological approach and estimate methods are given in Section 3. The application and results are given in Section 4, and Section 5 contains some concluding remarks. The appendix provides further diagnostics and sensitivity analysis of the MCMC inference.

2. Data: Geo-referenced FFS

The data analyzed for this research are from the Fertility and Family Survey (FFS), a sample survey conducted by means of an interviewer-administered questionnaire (De Sandre et al. 1997) which contains questions about the respondent's present situation and biography. The study was part of a program implemented by the Population

Activities Unit (PAU) of the United Nations Economic Commission (UN/ECE) with the intent of collecting comparative information on an international scale.

The sampling strategy, which was created by the National Statistical Institute (ISTAT), is described in detail by Zannella et al. (1997). The survey has a three-stage design, (municipality, electoral section, and individual) and the sample comprises 6,030 individuals, with two independent samples for men and women. More precisely, 4,824 women and 1,206 men born between 1946 and 1975 were interviewed. The interviews were carried out between November 1995 and January 1996 and contained questions pertaining to a series of bio-demographic events. The age of the respondents when these events were experienced was also registered (Note 3).

For the following analysis, we select the subset of individuals who had experienced sexual intercourse. The vast majority of the sample, 5,279 individuals, is included in this subset. Furthermore, all of the respondents whose answer on whether they had experienced sexual intercourse was missing are excluded from the data set (95 cases). The data is considered to be reliable and of good quality by cross-validation with other surveys (Cazzola 1999). In general, data on retrospectively-reported contraceptive use at first intercourse are of sufficiently high reliability in a wide variety of contexts (Wilder 2000). In what follows, we only differentiate between respondents who had used contraceptive method. We include cases in which respondents answered "don't know" on the use of contraception (24 cases) as part of the set of those who had not used any contraception. We thus assume that in absence of explicit reporting of contraceptive use, contraception was not used.

In order to study where respondents lived when they had their first sexual intercourse, we use the place of main residence during the first fifteen years of his/her life (Note 4). This may not have been the respondent's actual hometown, but we assume that it is a fair reflection of the environment in which the first sexual intercourse was experienced. Individuals living abroad at age fifteen and individuals who did not indicate any residence location are excluded. The municipal data are then aggregated at the provincial level. Given the methodological focus of the present work, we limit our attention exclusively to the sub-sample of women. Finally, cases in which age at first sexual intercourse was not given are excluded from the analysis (32). The final data set includes 4,006 female cases. Among them, 47.6% used some contraceptive methods during their first sexual experience. The sample distribution across age and cohorts is reported in table 1.

Figure 1 (a) shows the sample size by province while Figure 1 (b) shows the number of women who used contraception during their first sexual intercourse. As there are 103 provinces in Italy, the sample size is quite small for many provinces (40% of the provinces have fewer than 18 observations, and the same share has fewer than 8

cases). This results in a wide variability of the summary statistics, like relative frequencies, in those provinces with few observations.

	intercou	rse una c	onori						
Number of women				Percentage of contraceptive use					
Cohort			Cohort						
Age at first intercourse	1946-55	1956-65	1966-76	total	1946-55	1956-65	1966-76	total	
under 18	193	388	341	922	35.8	51.8	63.9	52.9	
18-20	549	643	577	1769	35.9	44.2	72.1	50.7	
21-24	416	289	234	939	28.4	38.4	65.4	40.7	
over 25	193	139	44	376	32.1	40.3	52.3	37.5	
total	1351	1459	1196	4006	33.0	44.7	67.7	47.6	

 Table 1:
 Sample size and percentage of contraceptive use by age at first intercourse and cohort

a)

b)

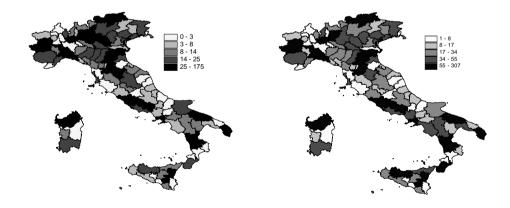
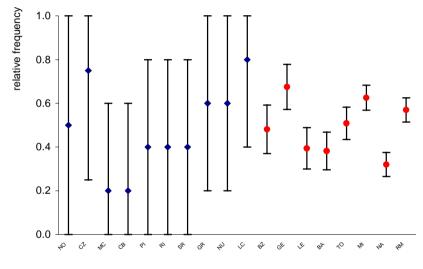


Figure 1: Sample size (a) and contraceptive use counts (b)

In Figure 2, we show the empirical probabilities for the 8 provinces with the largest sample size (more than 78 units, which is approximately the upper decile of the distribution of the number of observations across provinces) and for the 10 provinces with the smallest sample size (Note 5) (less or equal to 5, approximately the first decile of the distribution of the sample size across provinces) along with their 95% confidence interval (Note 6).



- Smaller sample size
- Bigger sample size

Figure 2: Frequency of contraceptive use for the provinces with more than 78 observations and less than 5

The map in Figure 3, where observed percentages of contraceptive use are depicted across provinces, already shows a spatial pattern. The following analysis thus aims at using a model that borrows strength from neighbors in order to obtain estimates for areas that may, on their own, have inadequate sample sizes.

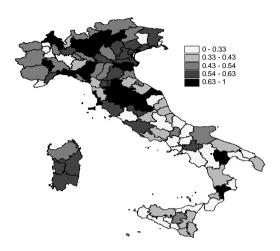


Figure 3: Relative Frequency of contraceptive use by provinces

3. Methods: Why Bayesian inference?

This section describes the statistical techniques employed; the results are analyzed in detail in Section 4. We use a Bayesian computational approach to statistical inference. This approach makes use of simulation to estimate the posterior distribution of parameters, that otherwise cannot be estimated using standard techniques.

Let *O* denote the observed data, β the parameter of a model for the data, $L(O|\beta)$ the likelihood function of the model, and $\pi(\beta)$ the *prior distribution* which conveys past knowledge of the parameter β , or the absence of such past knowledge in case of prior distributions with high variability. In Bayesian inference, the *posterior distribution*, $\pi(\beta|O) \propto L(O|\beta) \times \pi(\beta)$, links the assumptions made (the prior distribution) with the empirical evidence (the likelihood). The goal is to use the characteristics of this distribution (say the mean or the quantiles) to make inferences about β . This approach can be extended to multivariate contexts where β becomes a vector of parameters. Because the parameters are themselves random variables, it is natural to deal with them in a hierarchical way. This means that we are assuming that their distribution may

depend on other parameters, called *hyperparameters*. These hyperparameters are also random variables with their own prior distributions, called *hyperpriors*. Such hierarchical thinking helps to understand multiple parameter problems to develop computational strategies and, in practice, to provide enough parameters to deal with complex, hierarchical, data structures (Gelman et al. 1995).

The derivation of any posterior quantity requires evaluation of integrals of the form $\int \xi(\beta) \pi(\beta/O) d\beta$, for some function $\xi(\beta)$. Direct integration of this expression is usually problematic both in analytic and numerical terms. In order to overcome this problem we use the approach known as Markov Chain Monte Carlo (MCMC). MCMC is used to indirectly obtain the posterior distribution: given a sample generated from the posterior distribution, the characteristics of the probability density function are approximated using the sample counterparts. The key of MCMC is to simulate a Markov process whose stationary distribution (the distribution which the transition distributions converge to) is the posterior we are interested in. The simulation has to iterate long enough so that the distribution of the last generated draws is sufficiently close to the posterior distribution.

A full discussion of the advantages and the features of Bayesian modeling and MCMC is, however, far beyond the scope of this paper. The reader may refer, for instance, to Congdon (2001) for an applied perspective, and to Gelman et al. (1995) and Gilks et al. (1996) for a more formal presentation.

We now give a description of the statistical model we used, and we describe the estimation algorithms used in the inferential procedures based on the MCMC approach.

3.1 A Bayesian spatial model

Epidemiologists often study disease risk clustered within geographical areas (see, for instance, Elliot and Wakefield 2001, Lawson 2001). The clustering of risks has been defined in different ways (Wakefield et al. 2000). Knox (1989) defines a cluster in a qualitative and general manner as a group of occurrences that are geographically and/or temporally bounded, that are related to each other through some social or biological mechanism or that have a common relationship with some other event or circumstance. One may for instance hypothesize that contraceptive use varies geographically without an underlying spatial trend, but only due to various local effects. Testing this hypothesis requires the introduction of a variance component into the model. The assumption of independence and equal distribution of variance components is generally inconsistent. Clusters, in fact, often depend on cultural and economic factors which we can reasonably assume to be more similar in adjacent areas than in distant ones. In other

words, we can expect the effects within adjacent areas to be correlated. In section 4.3, we return to the problems arising when one does not consider this type of correlation.

The dependent variable, Y, is dichotomous, where the value 1 represents the respondent's use of a contraceptive method at first intercourse (0 otherwise). The probability assumption we make is that Y follows a p-mean Bernoulli distribution, and that p is linked to a linear predictor through a logit link function. To model spatial patterns, we add two random variables to the linear predictor. The first random variable, U, is assumed to be independently and identically distributed for all areas (the *unstructured component*). The second random variable, S, represents a spatial process (the *structured component*). The model is formally specified as follows:

$$logit(p_{gi}) = X_{gi}'\beta + U_g + S_g \qquad g = 1, \dots, G$$
(1)

where *G* stands for the number of areas taken into consideration (in our case the number of Italian provinces totaling 103) and the subscript g_i refers to the generic *i*-th sample unit in the province *g*.

Hereafter, the β 's are referred to as *fixed* effects and the spatial components as *random* effects. We should keep in mind that in a Bayesian framework all the parameters of the model are random variables. Unlike in the frequentist tradition, the term 'fixed' means that no higher hierarchical level is present beyond the assumed prior, while the term 'random' means that a further prior (called hyperprior) is elicited for the parameters (the so called hyperparameters) of such distributions (Gelman et al. 1995).

Regarding the unstructured component, we assume that the vector $U'=\{U_1, ..., U_G\}$ follows a normal prior distribution with a vector of 0 mean, and a variance and covariance matrix $\sigma^2 \mathbf{I}$ (with \mathbf{I} being identity matrix and $\sigma^2 > 0$ unknown). For the structured component $S'=\{S_1, ..., S_G\}$, we assume that the prior is represented by a Markov Gaussian field or conditional Gaussian autoregressive model (Besag et al. 1991).

In this case, therefore, with S_{-g} indicating the vector of the effects excluding that of the *g*-th location, we assume that:

$$S_g \mid S_{-g} \sim N(\sum_r w_{gr} S_r, \tau_g^2)$$

where w_{gr} and τ_g are defined in terms of the precision matrix. More specifically, we use a limit model in the form of intrinsic Gaussian autoregression (Besag and Kooperberg 1995). In this model, the only single relevant weights for the determination of the conditional law are the adjacent areas. By indicating the set of the provincial g adjacent areas with ∂g and its cardinality with m_g , a weight equal to $1/m_g$ is assigned to

each adjacent area and a 0 weight otherwise. The mean and the variance are given respectively by:

$$E(S_{g} | S_{-g}) = \sum_{r \in \partial g} S_{r} / m_{g}, \text{ and } Var(S_{g} | S_{-g}) = \tau^{2} / m_{g}$$
(2)

which are expressions that make the model's Markov structure clear.

The rationale behind this hypothesis is that a spatial effect is usually a surrogate of many unobserved influential factors. Some such factors may obey a strong spatial structure, while others may act only locally. The two different random processes are supposed to grasp such a double source of randomness.

The structured part of the prior allows us to borrow strength from neighbors in order to make the estimates based on inadequate sample sizes more robust. Accordingly, equation (2) states that the conditional mean of S_g is the average of the neighboring effects and the variance of the distribution is expected to be smaller the higher the number of the neighbors (Note 7).

Finally, in the model's third stage, we select prior distributions for the fixed effects and for the hyperparameters. We assume a highly dispersed but proper inverse gamma distribution both for the σ^2 and for the τ^2 parameter (specifically we used a scale parameter b=1 and form parameter a=0.005 inverse gamma law). As we do not have any specific information about the fixed parameters β , neither concerning their range nor their sign, we have assumed a "diffuse" prior distribution for them that is $\pi(\beta_j)$ is proportional to a constant for each regression parameter β_j . Our assumptions on prior distributions give almost all the weight to the likelihood function in the construction of posterior distributions (Note 8). For models such as the one we illustrated identification is a potential problem, and an assessment of a possible under-identification of the problem requires the calculation of model diagnostics. We discuss such problems in a detailed way in Appendix 1.

3.2 Monte Carlo Markov Chain inference

For complex models such as the one introduced in Section 3.2, the posterior distribution is both analytically and numerically intractable. Monte Carlo simulation methods are based on the principle of posterior distribution sampling and subsequent use of these simulated samples for estimating the characteristics (moments) of the posterior distribution. In particular, Markov Chain Monte Carlo methods (Gilks et al. 1996) are based on the simulation of observations of a Markov Chain where the transition probabilities converge to the selected posterior distribution. The obtained sample is adopted for inference, after the exclusion of an initial number of observations used to let the chain converge (*burn-in*). For the model adopted in this study, we make the following assumptions:

- conditional on explanatory variables and on the entire set of parameters, observations are independent;
- prior distributions for fixed and random effects and hyperpriors are mutually independent.

Given these assumptions, we denote the number of explanatory variables in the model by K, the conditional distributions generically by $\pi(z/y)$, and the contribution to likelihood of the *i*-th unit in the *g* area by $L_{gi}(y_{gi}), i = 1, ..., n_g$ (where n_g represents the number of observations in the *g*-th area). The posterior distribution is then factorized as follows:

$$\pi(\mathbf{s}, \mathbf{u}, \tau^2, \sigma^2, \beta \mid \mathbf{y}_1, \cdots, \mathbf{y}_n) \propto \left[\prod_{g=1}^G \prod_{i=1}^{n_g} L(\mathbf{y}_{gi} \mid \mathbf{s}, \mathbf{u}, \beta) \right] \left[\prod_{g=1}^G \pi(\mathbf{u}_g \mid \sigma^2) \pi(\sigma^2) \right] \\ \left[\prod_{g=1}^G \pi(\mathbf{s}_g \mid \mathbf{s}_{-g}, \tau^2) \pi(\tau^2) \right] \left[\prod_{j=1}^K \pi(\beta_j) \right]$$

MCMC inference is based, therefore, on sample simulation from each full conditional distribution.

The algorithms used for the MCMC simulations in this paper are described in detail in Fahrmeir and Lang (2001-A), so we provide only a brief description here. We adopt the algorithm proposed by Gamerman (1997) to update the model's fixed parameter values and those of the random unstructured intercepts. The essential idea behind Gamerman's algorithm is to generate an observation by means of a Metropolis-Hastings algorithm step inside the iterative weighted least squared (IWLS) procedure (Note 9). The algorithm we use for the updating of the structured component (CAR) was originally proposed by Knorr-Held (1999) within the framework of dynamic linear generalized models. This algorithm aims at improving the mixing and convergence of simulated chains by updating, at each iteration, a block of values. (Note 10).

The full conditional distributions for the variance parameters of spatial effects still match an inverse gamma distribution. Therefore, we can update the values of the chain using a Gibbs Sampler (Fahrmeir and Lang 2001-A).

4. Application to contraceptive use: methodological aspects and results

After giving a brief description of the application's technical aspects, this section contains a discussion of our results (Note 11). We then compare our results to those that would likely have been obtained by adopting an approach that is common in multilevel statistical models, where the usual assumption is the mutual independence between areas.

4.1 Monte Carlo Markov Chain setup

As indicated in the previous section, the basic idea of MCMC methods is to give an approximation of posterior distribution by means of a sample simulated through a Markov chain. The observations of the Markov chain are thus correlated. In principle, as many authors have observed (e.g. Gelman 1996), no substantial problems arise when considering correlated observations in MCMC inference. Nevertheless, correlation may imply the need for simulating very long chains. In this case, computing the results can become burdensome in terms of calculation. One solution is to use only one observation for each k simulated for inference (this is known as *thinning*). At the same time, the choice of the k-interval according to the auto-correlation in the chain allows for reduction in the correlation to be found in the sample actually used for inference (Note 12).

4.2 Results

We include as explanatory variables, in addition to the province the respondents lived in up until age 15, the respondent's age at first sexual intercourse (divided into four categories: 14-17 years old as the reference group, 18-20 years old, 21-24 and over 25 years old), and birth-cohort (divided into three categories: 1946-55 as the reference group, 1956-65 and 1966-75).

The results of the analyses regarding fixed effects are given in Table 2. Age at first sexual intercourse does not have a significant effect, meaning that the credibility interval, given by the 10th and 90th percentile of the posterior distribution, contains 0 for all categories examined. In contrast, birth cohort significantly influences the probability of using contraception. In other words, on the basis of this analysis, the propensity of Italian women to use contraception at first intercourse does not depend on age (even though respondents aged 21-24 appeared to be less inclined to use

contraception, as their odds were 7.8% lower than the 14-17 year old reference group). Regarding cohorts, the relative odds for the 1956-65 cohort is 69.5% higher than the oldest cohort, and the increase in odds for the youngest on the date of the interview (those born 1966-75) increased to 345% compared to the reference cohort. These values confirm the strong differentials in frequency of use of contraception mentioned in the introduction.

Variable	Mean	S.D.	1st decile	Median	9 th decile
Intercept	-0.716	0.096	-0.838	-0.715	-0.593
Age 18-20	0.066	0.088	-0.049	0.065	0.181
Age 21-24	-0.081	0.105	-0.210	-0.081	0.052
Age 25 and over	0.003	0.141	-0.177	0.002	0.183
1956-65 cohort	0.528	0.087	0.417	0.528	0.638
1966-75 cohort	1.493	0.093	1.377	1.491	1.615

Table 2:Fixed effects estimates.

Note: reference groups: age 14-17 and 1946-55 cohort.

Turning to spatial-related aspects, studied controlling for age and cohort effects, we observe immediately from Figure 4 (a) that there is an increasingly marked effect of the area on the odds of moving from the south to the north of the peninsula. Figure 4 (b) shows in which provinces the effect is either positively or negatively significant, or not significant, meaning that the credibility interval given by the 10th and 90th posterior percentile is above 0, below 0 or it contains 0 respectively.

The maps in Figure 4 show a significant level of heterogeneity at the spatial level between the various Italian provinces which, among other issues, reflects the southnorth differentials given by age at initial sexual intercourse found in the same data (Billari and Borgoni 2002; Ongaro 2001).

Considering only the structural variance and not the spatially unstructured component may sometimes be misleading, and may not provide complete information. Only by comparing the two can we understand which areas deviate from the latent structure (in our case, the south-north gradient).

Figure 5 (a) represents unstructured spatial effects (posterior means). The values used for the map are determined according to the distance in unit terms of standard deviation from the average province values. White provinces constitute the middle group, as they include the overall mean (0) of estimated effects. The upper and lower

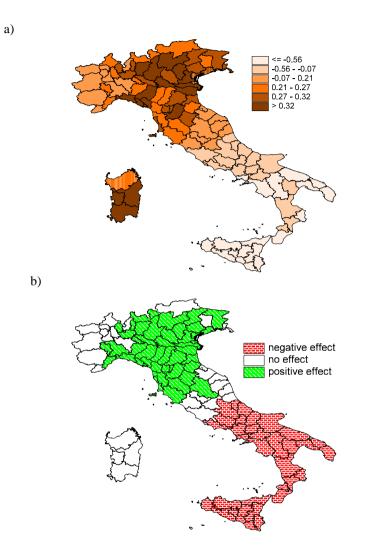


Figure 4: Structured spatial effects (posterior mean) (a) and their credibility intervals (b)

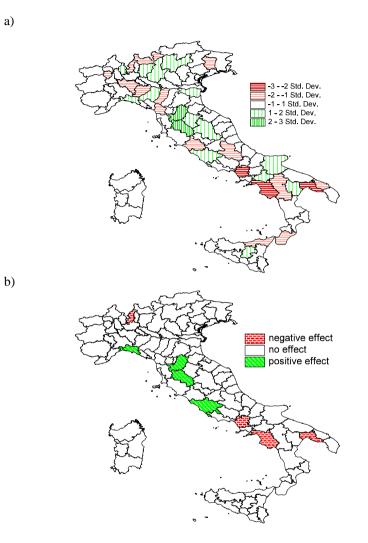


Figure 5. Unstructured spatial effects (posterior mean) (a) and their credibility intervals (b)

values used to delimit this middle group are obtained by adding and subtracting one standard deviation from the overall mean (Note 13). In the unstructured component, no particular trends are evident. In any case, the effects are less relevant in statistical terms than in the structured component. Only eight provinces show significant effects (in terms of an 80% credibility interval). These provinces are highlighted in color in Figure 5 (b), whereas the provinces with non-significant effects are left in white. The provinces of Genoa, Florence, Rome and Sienna stand out as having a positively significant unstructured effect. The provinces with a negatively significant unstructured effect are Caserta, Como, Salerno and Taranto.

Finally, by comparing the distribution of structured and non-structured provincial effects across Italy, we observe that the probability interval given by the 5^{th} and 95^{th} percentiles is equal to (-0.274, 0.329) for unstructured effects and (-0.693, 0.362) for structured effects. To sum up, we conclude that the structured component has more relevance compared to the unstructured component (Note 14).

4.3 Is there a problem with standard multilevel modeling approaches?

In social-demographic research, multilevel statistical models are often used to study spatial clustering problems (Goldstein 1999). With such models, it is usually assumed that the random components at the contextual level are mutually independent. Even though quite common, this assumption is not actually implied by the multilevel approach, so correlated random residuals can also be specified (e.g. Langford et al. 1999). The independence assumption has an inherent problem of inconsistency: if the spatial context matters, it makes sense to assume that areas close to each other are more similar than areas that are far apart. That is, the spatial correlation (i.e. structured component) that we used in the model presented in Section 3.1 applies here as well. In order to emphasize the differences that can be found by adopting this approach in a spatial context and the possible risks involved with the violation of the assumption of independence between aggregated spatial units, we used Model (1) with the non-structured variance component only.

The results regarding the fixed parts of the model are very similar to the results obtained by including both spatial components, and are therefore not reported here. Instead, the model's posterior effects are presented in Figure 6. The map is composed in the same way as in Figure 4 (a), using quintiles of the territorial distribution of the effects. Even though the center-northern area may appear, on average, to be darker compared to the center-south, detecting a clear spatial trend is now much harder than before: local and trend effects appear to be mixed. Thus, neglecting the correlation between areas significant information would have been lost.

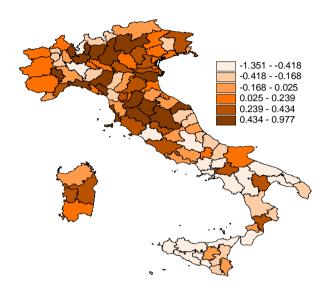


Figure 6: Unstructured spatial effects (posterior mean) for a multilevel model without the structured spatial component

5. Conclusion and future developments

In this paper, we show how it is possible to map a social-demographic risk indicator with the use of data taken from a sample survey that is not directly designed to ensure a coverage of geographical units such as those of interest. The Bayesian computational approach we adopted enables us to provide estimates of parameters in an otherwise too complex model. It also allows us to refrain from the assumption of mutual independence between areas usually imposed in multilevel statistical models.

The absence of information from the survey regarding the type of method used limits the potential of the data studied. Thus, for future reference, it is necessary for this information to be collected on a geo-referenced basis. One could gain a considerable advantage for spatial analysis with a time-varying geo-referencing of life-course events. In this way, it would also be possible to refer an event to the individual's context at the time it was experienced.

When considering the structured component, our results reveal how the southern areas have a higher risk at initial sexual intercourse, while the unstructured component indicates that the southern provinces of Caserta, Salerno and Taranto have higher risk factors. We can speculate that less available information and more pressure by the partner against using contraception lie at the root of the territorial differences we find, even though further research is definitely necessary to verify this assumption. As a final caveat, however, we must add that the data provided do not allow the study of the reasons why contraception is not used: therefore, we cannot exclude the fact that there are cases where conception is actually desired in first-time intercourse. More generally, maps enable us to produce "narratives" which are valuable for theory formation (Lesthaeghe and Neels 2002): the mere mapping of a phenomenon does not explain the phenomenon, although it constitutes a strong foundation.

6. Acknowledgements

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Notes

- 1. In the sample we worked with, which is described in detail in section 2, only 47.6% of the female respondents declared that they had used contraception during first-time intercourse. However, this percentage varies considerably across the various cohorts and goes to 33% for the 1946-55 decade birth cohort and to 44.7% for the 1956-65 birth cohort and reaches 64.7% in the 1966-75 birth cohort.
- 2. On the other hand, in some cases there may also have been a desire for pregnancy at first intercourse, which makes underestimating less serious.
- 3. The questions relevant to this analysis are given in the 'Fertility Regulation' section. The respondents were asked: 'In order to avoid further questions that may not be relevant, can I ask whether you have ever experienced complete intercourse?' (possible answers: 'yes', 'no', and 'no answer'). In case of an affirmative reply, the person was asked 'At what age did you have complete intercourse for the first time?' (with the possibility of stating 'no answer') and 'On that occasion, was any contraceptive method used?' (possible answers: 'yes', 'no', 'don't know', and 'no answer'). Unfortunately, the respondents were not asked what type of contraceptive method they had used, if any; this was investigated and limited to the last 4 weeks before the interview (Bonarini 1999).
- 4. The following question was asked 'Where did you live for most of the time until you were fifteen years old?'
- 5. From the set of those Italian provinces eligible to appear in the picture we exclude three provinces with 0 cases of contraceptive use and one province with one observation only.
- 6. Given the small sample size, we use Bca bootstrap intervals (Davison and Hinkley 1997).
- 7. We can suggest a demographic meaning for the formulation of the variance in equation (2). If we assume that behavior is influenced in an important way by the context (in our case by geography), and that spatial autocorrelation helps in capturing such influence, the mere fact of having more neighbors allows one to draw more precise conclusions about the average behavior in a given province.
- 8. An alternative to the Bayesian approach could be a "mixed effects" model where only the spatial variation is regarded as random. Examples of this approach are given by Pinheiro and Bates (2000), where both random effects and errors follow a Gaussian distribution, and by Langford et al. (1999) and Leyland (2001) for a Poisson model. Langford and his colleagues estimate the model via iterative

generalized least-squares (IGLS). The main advantage of the Bayesian approach consists in providing the full posterior distribution, while IGLS produces estimates of spatial residuals and their standard errors, the latter using sample estimates only (Leyland, 2001). On the other hand, the Bayesian approach is much more computationally intensive than the latter.

- 9. This procedure is usually chosen for the maximum likelihood estimations within the framework of generalised linear models (McCullagh and Nelder 1989).
- 10. These types of algorithms make considerable computational advantages from the sparse structure of the correlation matrix, and also reflect the adjacent relations between areas For further developments and details on highly efficient calculation methods for the generation of Gaussian Markov fields, see Rue (2001).
- 11. We conducted the analyses presented in this study using BayesX (Lang and Brezger 2000). BayesX is package for Bayesian data analysis, freely available through the Internet at www.stat.unimuenchen.de. They could alternatively have been conducted with the use of other software products for Bayesian analyses, particularly WinBug (Spiegelhalter et al. 2000). S-Plus functions (Venables and Ripley 2000) were used for the final preparation of the results and for the graphics, whereas the various maps were generated with Arc/View GIS (ESRI 1996).
- 12. For this reason, we simulated preliminarily a chain of 22,000 iterations (of which 2,000 were used for burn-in), from which we analysed the auto-correlation function. The correlation turned out to be negligible (< 0.15) for lags larger than 25-30 for all the parameters studied in the model, so that in the final simulation a thinning pass of one observation every 30 was used. This final simulation consisted in 95,000 iterations (5,000 for the chain burn-in) of which 3,000 (one out of every 30) were used for final estimations. A diagnostic on the results obtained by the MCMC inference is given in Appendix 2.
- 13. The middle group thus covers a two-standard-deviation interval, while other groups cover one-standard-deviation intervals.
- 14. In our analyses, we evaluated the trade-off between S and U in a graphical way, looking at maps and at some summary statistics of the distribution of effects (as in Fahrmeir and Lang, 2001-B). Other more formal approaches are also possible and have been suggested in the literature. For instance, Best et al. (1999) define the quantity

 $\psi = \mathrm{SD}(S) / \{ \mathrm{SD}(S) + \mathrm{SD}(U) \},\$

where SD(·) is the empirical marginal standard deviation of the considered random effect. ψ summarizes the posterior proportion of variation due to an excess of variation of the structured effect. A posterior of the index concentrated near 1 suggests that most of the excess variation is due to the structured part, while a posterior close to 0 suggests that the unstructured component is the most relevant. Eberly and Carlin (2000) discuss whether ψ can be fruitfully used to summarize the level of Bayesian learning about structured and unstructured components.

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Appendix 1. Identification issues

Identification is an issue in models like the one illustrated in Section 3.1, mostly because of two problems. The first problem concerns the CAR prior: as this prior is defined conditionally, the parameter is uniquely specified only up to an additive constant. This problem is well-known in spatial statistics, and several solutions have been proposed in the literature (i.e. imposing a 0-sum constraint to structured effects as in Besag and Kooperberg, 1995). A second problem concerns the identifiability of the two sources of randomness included in the model, namely the unstructured and structured spatial components. This problem is well described by Eberly and Carlin (2000) in the case of a Poisson spatial regression for aggregate area-level data. In that context, letting N_g be the number of events in the area g, it is usually assumed that N_g is Poisson-distributed, with expected value $E_g \exp(\mu_g)$, E_g being a known expected number of event for the area g and μ_{g} the log-rate of the event of interest. The model is specified as $\mu_g = Z'_g \beta + S_g + U_g$ where Z is a set of area-level covariates, and S and U are random effects allowing for overdispersion due to clustering and area-level heterogeneity respectively. Given the system of priors described in section 3.1, an identification problem arises because the number of events N_g cannot possibly provide information about both S_g and U_g , but only about their sum $W_g = S_g + U_g$ This basically means that once one reparameterizes the model in terms of (U, W), the conditional distribution $\pi(u_{e}/u_{r\neq 0}, w, y)$, does not depend on the data y. This is known as *Bayesian* unidentifiability (Gelfand and Sahu, 1999). Even if the model is affected by Bayesian unidentifiability, this does not preclude *Bayesian learning* about the parameter that would require $\pi(u_e/y) = \pi(u_e)$ instead, a stronger condition implying that the marginal (instead of the conditional) distribution is independent from the data (for a more detailed discussion of these issues see Poirier, 1998). From a Bayesian perspective, formal identifiability is not an issue. When proper priors are assigned to the parameters, also the posterior distribution is proper, and hence all the parameters of the model are well-estimable. Nevertheless, for some unknown parameters, the posterior distribution may differ only slightly from the prior distribution, which leads to a poor Bayesian learning. Implementing iterative simulation-based model estimation may bring to poor results, as in the case of the Gibbs algorithm. In addition, when rather vague priors are specified (as spatial statisticians usually do) Markov chain trajectories for weakly identified parameters tend to show drift to extreme values, the assessment of convergence tends to be difficult, and computation tends to become unstable (Gelfand et al., 2001). Gelfand and colleagues also observe that such problems can rise even in a multilevel model of individual binary data, where more than one observation is available for each area.

Taking all the above issues into account, the identification problem in such models (Fahrmeir and Lang , 2001-B) is more a data-related problem – how many isolated areas are there, how many observations are there in each area – than a problem connected to the estimation algorithm – which sampler, which starting values, the precise prior values chosen (Eberly and Carlin, 2000). A full analysis of identifiability in models such as the one discussed in Section 3.1 is beyond the scope of the present paper, and this Appendix is only provided to make the reader aware of the problem. Moreover as Eberly and Carlin (2000) and Gelfand et al. (2001) observed, even though the assessment of the effect of over-specification is still somehow possible when fixed values are assumed for the variance parameters (that is the model consists of two levels of hierarchy only) assessing clearly the effect of over-specification becomes much more difficult when hyperpriors on the variance parameters (as we do in the present paper) are used instead.

The fact that the analyses reported in this paper do not suffer from particular identification problems is assured by the model diagnostics presented in Appendix 2. Such diagnostics show a very stable behavior of the estimates, and the absence of anomalous drifts. Moreover a way to prevent unidentifiability is to put informative priors on the parameters one suspects to be weekly identified. Informative prior can be seen as the Bayesian equivalent of the frequentist approach to indentifiability namely, imposing constraints on the parameter space. Appendix 2 reports the results concerning the model estimated via informative priors for the variance parameters. Even though, as previously mentioned, interpretation is somewhat more difficult when hyperpriors are involved, what can be clearly observed is that the spatial patterns is basically not affected by this choice assuring us of the proper identification of the model.

Appendix 2. Diagnostics of MCMC inference

In this appendix, we report diagnostics on the analysis of section 4.2. Although no diagnostic analysis whatsoever can be considered conclusive proof of the validity of inference conducted with the use of MCMC methods, there is no doubt that a study based on this approach cannot avoid considering that inference. Figures A.1 and A.2 report the ergodic averages (first row), the simulated values (second row) and the auto-correlation functions for the 3,000 values used for the inference of the model's fixed effects. The chain presents a good mixing and a sufficiently quick convergence (even though it has to be considered that the graphs refer to the sampled chain with a 1-out-of-30 thinning). The same type of diagnosis was implemented for the structured and unstructured spatial effects as well. Showing all the pertinent graphs would have taken up too much space (there are 103 effects, one for each province, to be considered in both cases). However, this diagnostic was estimated and showed a very satisfactory convergence and mixing.

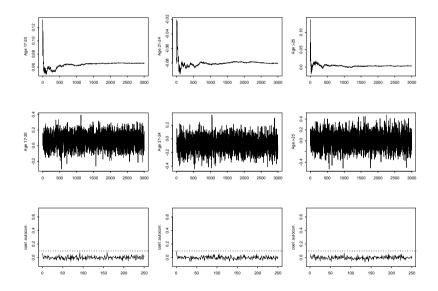


Figure A.1: Ergodic means, simulated values and autocorrelation functions of each parameter of variable "age"

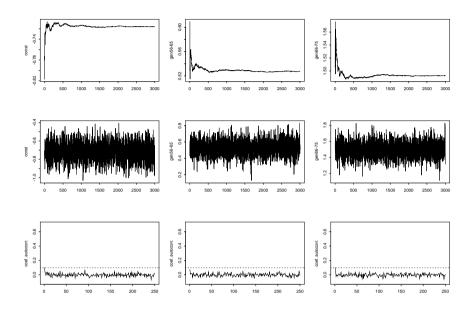


Figure A.2: Ergodic means, simulated values and autocorrelation functions of the intercept (first column) and of the 1956-65 and 1966-75 cohort parameters (second and third columns respectively)

Concerning spatial effects, here we provide a brief sensitivity analysis on the prior distributions. Particular attention is placed on the prior distribution of the CAR model variance parameter, and more informative and proper prior distributions are imposed on the same. In particular, we take distributions of inverse gamma (IG) type into consideration, having a b = 1 scale parameter and form parameter *a* respectively equal to 0.001, 0.01, 0.05, and 0.5. We can note that the probability mass assigned by each of these distributions to the interval, for example, [0,100] passes from 0.004 for an inverse parameter gamma equal to 1 and 0.001 to 0.89 in case of parameters equal to 1 and 0.5. For each prior distribution, the model is evaluated by implementing a Markov Chain consisting of 95,000 iterations with a 5,000 sample burn-in and a 1-out-of-30 thinning.

The results obtained are given in Figure A.3 for estimated spatial effects, and in Figure A.4 for credibility intervals. In Figure A.3 the mapping composition is obtained by establishing colors according to quintiles. A substantial stability concerning the

phenomenon's spatial trend and concerning the provinces that either do or do not present significant effects (positive or negative) stands out clearly. The prior differences appear to mainly influence the estimates on the tails of the province effect distribution whereas the percentiles appear to be very steady.

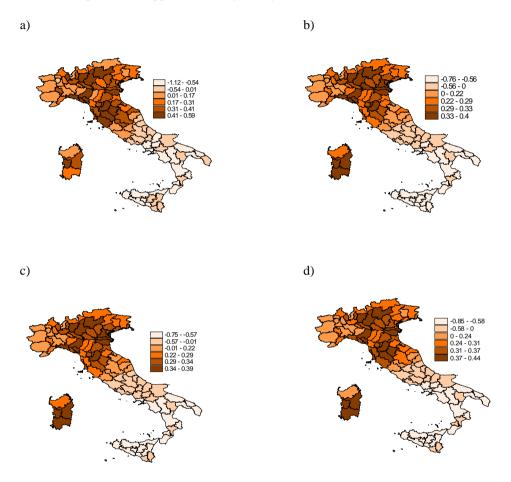


Figure A.3: Structured spatial effects (posterior mean) relative to different priors (a) IG(1,0.001), (b) IG(1,0.05), (c) IG(1,0.01), (d) IG(1,0.5)

90

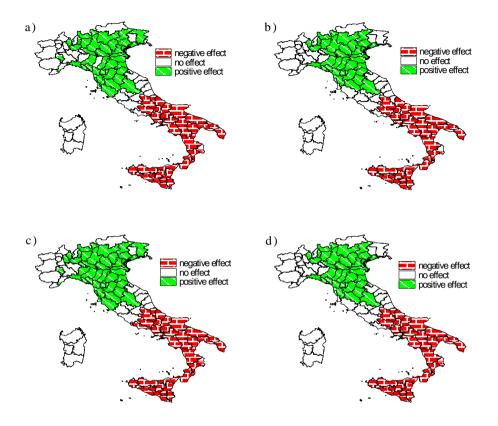


Figure A.4: Credibility intervals of structured spatial effects relative to different priors: (a) IG(1,0.001), (b) IG(1,0.05), (c) IG(1,0.01), (d) IG(1,0.5)

Finally, Figure A.5 portrays the posterior distributions of some of the 103 random structured spatial effects, in correspondence with the different priors, including those used in Section 4 for the estimate of the model. It appears once again to be evident that they differ very little, even though the informative prior distribution tends to yield a more symmetric and mesocurtic curve. We carried out an analogous analysis with similar results for unstructured effects, which, however, cannot be reported herein.

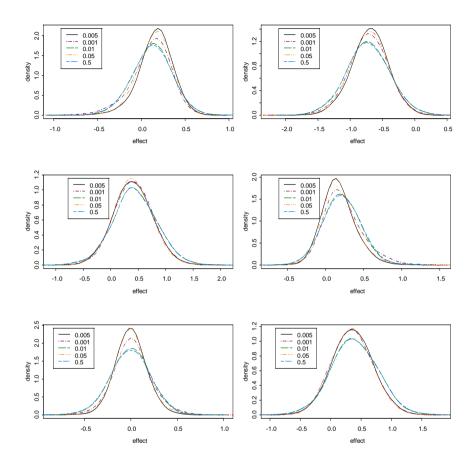


Figure A.5: Structured spatial effect distributions of six provinces for different inverse gamma priors (scale parameter equal to 1 and several shape parameter values)

Finally, although no indicator-based diagnostic was implemented for the model parameters (e.g. Gelman and Rubin 1992 and Brooks and Gelman 1998) other than the graphs presented at the beginning of this appendix, the large number of chains analyzed showed a substantial convergence to the values discussed in section 4. This assures us of the robustness of the estimates obtained.