

Using STATA's - ml method d2 - to estimate a multistate Markov transition model with unobserved heterogeneity

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May 22, 2003

1 CAVEAT....

Inference on the basis of ONE observation...

2 STATA's - ml methods -

If "linear form restrictions" are met, i.e. $\ln L = \sum_i \ln L_i$;

- - lf - supply likelihood function only

If "linear form restrictions" are violated;

- - d0 - code likelihood function only
- - d1 - code analytical gradient
- - d2 - code analytical Hessian

3 The main message

When - ml method d0 -

- has trouble converging (“numerical derivatives cannot be computed”)
- or is just too slow,

STATA’s - ml method d2 - can offer HUGE improvements

- convergence and
- speed of convergence

Coding a - ml method d2 - estimator

- is in principle straightforward,
- **BUT** can be complicated by STATA’s limited matrix capabilities.
[NOTE: Bobby Gutierrez pointed out during the meeting that there is an undocumented routine - mlmatbysum - that solves my problem]

4 The state transition model

- time is discrete t
- there are S discrete states
- in each period t , we observe each individual i , its
 - state s_{it}
 - individual specific characteristics x_{it} (potentially time varying)

| | | | | | | | |
|------------------|-------------|-------------|-------------|-------------|-------------|-------|-----|
| t | 0 | 1 | 2 | 3 | 4 | 5 | ... |
| s_t | 2 | 2 | 1 | 2 | 3 | 2 | ... |
| x_t | x_0 | x_1 | x_2 | x_3 | x_4 | x_5 | ... |
| <i>Transprob</i> | $P(22 x_0)$ | $P(21 x_1)$ | $P(12 x_2)$ | $P(23 x_3)$ | $P(32 x_4)$ | ... | ... |

- without unobserved heterogeneity: MNL (- mlogit -) for each state separately;
- consider unobserved heterogeneity in the form of discrete types a la Heckman-Singer (1984)
location and mass of types to be estimated jointly with other parameters

So, conditional on x_{it} , we get transition matrices:

| Type 1 (mass q_1) | | Type 2 (mass q_2) | | |
|----------------------|---|----------------------|---|---|
| State in $t + 1$ | | State in $t + 1$ | | |
| | 1 | 2 | 3 | |
| State in t | 1 | · | · | 1 |
| | 2 | · | · | · |
| | 3 | · | · | · |
| | | | | 3 |

5 The likelihood function

Conditional on individual i being of type j , the likelihood of observing the sequence of states $\{s_{it}\}_{t=t_0}^{t_1}$ is

$$L_{ij} = \prod_{t=t_0}^{t_1-1} P(s_{it} \rightarrow s_{it+1} | x_{it}, \gamma = j, \beta_{s_{it}, s_{it+1}})$$

The unconditional likelihood for the individual becomes:

$$L_i = \sum_{j \in \Gamma} q_j L_{ij}$$

And the sample log likelihood takes the form:

$$\ln L = \sum_{i=1}^N \ln L_i = \sum_{i=1}^N \ln \left(\sum_{j \in \Gamma} q_j L_{ij} \right)$$

Note: "Linear form restrictions" are not met. The total coefficient vector to be estimated is:

$$(\beta_{1,1}, \beta_{1,2}, \dots, \beta_{n,n-1}, \beta_{n,n}, q_1, \dots, q_m)$$

5.1 The gradient:

”Typical element”:

$$\frac{\partial \ln L}{\partial \beta_{kl}} = \sum_{i=1}^N \sum_{j=1}^M \sum_{t=t_0}^{t_1} q_j \frac{L_{ij}}{L_i} \frac{1}{P_{ijt}} \frac{\partial P_{ijt}}{\partial \beta_{kl}}$$

5.2 The Hessian:

”Typical element”:

$$\frac{\partial \ln L}{\partial \beta_{kl} \partial \beta_{mn}} = \sum_{i=1}^N \sum_{j=1}^M \sum_{t=t_0}^{t_1} q_j \frac{L_{ij}}{L_i} \frac{1}{P_{ijt}} \left\{ \frac{1}{L_{ij}} \frac{\partial L_{ij}}{\partial \beta_{kl}} \frac{\partial P_{ijt}}{\partial \beta_{mn}} - \frac{1}{L_i} \frac{\partial L_i}{\partial \beta_{kl}} \frac{\partial P_{ijt}}{\partial \beta_{mn}} - \frac{1}{P_{ijt}} \frac{\partial P_{ijt}}{\partial \beta_{kl}} \frac{\partial P_{ijt}}{\partial \beta_{mn}} + \frac{\partial P_{ijt}}{\partial \beta_{kl} \partial \beta_{mn}} \right\}$$

6 Computational issues

6.1 Constraints:

- System memory
- Computing time

→ want to generate as few temporary variables as possible

6.2 Issues:

- Expand data (which has $N * T$ obs. to start with) by a factor M to facilitate computation
- Log likelihood and gradient straightforward to compute

6.3 Problem:

- Hessian involves computation of terms of the form:

$$A'WB$$

where $A = (a * [1, 1, \dots, 1]) * X$ (element by element)

$B = (b * [1, 1, \dots, 1]) * X$ (element by element)

W - block diagonal with blocks of ones

- STATA cannot do this!! Or at least I couldn't...
[NOTE: As Bobby Gutierrez pointed out during the meeting, STATA CAN DO THIS with the, so far, undocumented -ML MATBYSUM- so the problem is solved] .
- W is square with dimensions $N * T * M$ (i.e. potentially very big (> max matsize SE: 11000))

6.4 ”Solution”

Circumvent problem by manually multiplying in weights:

- create A : each variable in X multiplied by a .
- create B : each variable in X multiplied by a .
- use - matrix glsaccum - to get $(A, B)'W(A, B) = \begin{bmatrix} A'WA & A'WB \\ B'WA & B'WB \end{bmatrix}$
and only use the $A'WB$ part.

- This involves generating LOADS of temporary variables

... takes a long time to compute

... and a lot of memory – I once ran out of memory on a 256M machine

(recall that data is already expanded)

...BUT: IT WORKS !!!