# A simple explanation for the non-invariance of a Wald statistic to a reformulation of a null hypothesis 

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#### Abstract

For a given null hypothesis and its reformulation, the associated Wald statistics are shown to be members of a wider family of statistics where all members are asymptotically equivalent under the null hypothesis. Therefore, the non-invariance of a Wald statistic (to a reformulation of a null hypothesis) is equivalent to using different members of the wider family and, in addition, this non-invariance implies that these members use different estimators of an appropriate variance-covariance matrix.


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## 1. INTRODUCTION

It is well known that, in general, a Wald statistic is not invariant to a reformulation of a null hypothesis where a vector of restrictions $r(\theta)=0$ is rewritten in an algebraically equivalent form $q(\theta)=0$ with $\theta$ being a vector of unknown parameters. Initially, Gregory and Veall (1985) provided Monte Carlo evidence of the effect of a reformulation and, subsequently, Lafontaine and White (1986) and Breusch and Schmidt (1988) showed how this non-invariance could be exploited to obtain a desired numerical value for a Wald statistic, Phillips and Park (1988) examined the effect of a reformulation on the small sample distribution of a Wald statistic, and Kemp (2001) provided a justification for ruling out certain reformulations. In contrast to the explanations provided by Davidson (1990) and Critchley, Marriott, and Salmon (1996), which apply the methods of differential geometry, this note provides a simple explanation for the non-invariance of a Wald statistic.

Using the terminology in Dastoor (2003), the original family of Wald statistics for testing $H_{0}: r(\theta)=0$ is a family where all members are asymptotically equivalent under $H_{0}$, and each member (called an original Wald statistic) is a quadratic form in $\sqrt{n} r\left(\hat{\theta}_{n}\right)$ with all components of its weighting matrix evaluated at $\hat{\theta}_{n}$, the (unrestricted) maximum likelihood estimator of $\theta$ based on $n$ observations. Then, the extended family of Wald statistics is a wider family where all members are asymptotically equivalent under $H_{0}$, and each member (called an extended Wald statistic) is a quadratic form in $\sqrt{n} r\left(\hat{\theta}_{n}\right)$ with all components of its weighting matrix not necessarily evaluated at $\hat{\theta}_{n}$. In both these families, the weighting matrix of any member is (under $H_{0}$ ) a consistent estimator of the inverse of the asymptotic variance-covariance matrix of $\sqrt{n} r\left(\hat{\theta}_{n}\right)$. Similarly, the original and extended families of Wald statistics for testing $H_{0}^{*}: q(\theta)=0$ are families whose members are appropriate quadratic forms in $\sqrt{n} q\left(\hat{\theta}_{n}\right)$ and asymptotically equivalent under $H_{0}^{*}$ or, equivalently, under $H_{0}$. In general, the two original families differ, but it can be shown that the two extended families are identical. Therefore, an original Wald statistic for testing $H_{0}$ and an original Wald statistic for testing $H_{0}^{*}$ are members of the extended family for testing $H_{0}$. This provides a
simple explanation for the non-invariance of a Wald statistic; i.e., when $H_{0}$ is replaced with $H_{0}^{*}$, the non-invariance of a Wald statistic is equivalent to replacing one extended statistic for testing $H_{0}$ with a different extended statistic for testing $H_{0}$, and it can be shown that this non-invariance implies that the two extended statistics use different estimators of the asymptotic variance-covariance matrix of $\sqrt{n} r\left(\hat{\theta}_{n}\right)$ under $H_{0}$.

The next section presents the original and extended families for testing each of $H_{0}$ and $H_{0}^{*}$. Section 3 derives the simple explanation, and some concluding remarks are stated in Section 4.

## 2. ORIGINAL AND EXTENDED FAMILIES

Let $\theta$ be a $p \times 1$ vector of unknown parameters, $\Omega \subseteq \mathbb{R}^{p}$ be the parameter space, $L_{n}(\theta)$ be a log-likelihood function for $n$ observations, and $r(\theta)=0$ be an $r \times 1$ vector of known restrictions with $r \leq p$. Then, $\hat{\theta}_{n}=\operatorname{argmax}_{\theta \in \Omega} L_{n}(\theta)$ is the (unrestricted) maximum likelihood estimator of $\theta$, and the null and alternative hypotheses are $H_{0}: \theta \in \Omega_{0}$ and $H_{1}: \theta \in \Omega_{1}$, respectively, where $\Omega_{0}=\{\theta \mid r(\theta)=0, \theta \in \Omega\}$ and $\Omega_{1}$ constitute a partition of $\Omega$. Also, let $R(\theta)=\partial r(\theta) / \partial \theta^{\top}$ be the $r \times p$ matrix of derivatives with rank $r$ for all $\theta \in \Omega$, $R_{0}=R\left(\theta_{0}\right), \hat{R}=R\left(\hat{\theta}_{n}\right)$, and $J_{n}(\theta)$ be a $p \times p$ symmetric nonsingular matrix such that $\hat{J}_{n}=$ $J_{n}\left(\hat{\theta}_{n}\right) \xrightarrow{p} J_{0}$ where $\theta_{0}$ is the true value of $\theta, J_{0}=-\operatorname{plim} n^{-1} \partial^{2} L_{n}\left(\theta_{0}\right) / \partial \theta \partial \theta^{\top}$ is the (positive definite) limiting information matrix under $H_{0}$, and $\xrightarrow{p}$ denotes convergence in probability under $H_{0}$. Throughout, $\theta_{0} \in \Omega_{0}$, all asymptotic results are obtained under $H_{0}$, the usual regularity conditions are assumed to hold, and standard results will be used. Rigorous statements of the appropriate conditions required and formal derivations of standard results can be found in, for example, Davidson and MacKinnon (1993) and Newey and McFadden (1994). Therefore, under $H_{0}$ and appropriate conditions, $\hat{\theta}_{n} \xrightarrow{p} \theta_{0}, \sqrt{n}\left(\hat{\theta}_{n}-\theta_{0}\right) \stackrel{a}{\sim} N\left(0, J_{0}^{-1}\right)$, and $\sqrt{n} r\left(\hat{\theta}_{n}\right) \stackrel{a}{\sim} N\left(0, R_{0} J_{0}^{-1} R_{0}^{\top}\right)$. Then, an original Wald statistic for testing $H_{0}$ is

$$
\begin{equation*}
W_{n}\left(\hat{J}_{n}\right)=n r\left(\hat{\theta}_{n}\right)^{\top}\left\{\hat{R} \hat{J}_{n}^{-1} \hat{R}^{\top}\right\}^{-1} r\left(\hat{\theta}_{n}\right), \tag{1}
\end{equation*}
$$

which is asymptotically distributed as a $\chi^{2}(r)$ variate under $H_{0}$.

Henceforth, as all asymptotic results are obtained under $H_{0}$, the terms 'consistent estimator' and 'family of asymptotically-equivalent Wald statistics' will mean 'consistent estimator under $H_{0}$ ' and 'a family of Wald statistics where all members are asymptotically equivalent under $H_{0}$ ', respectively. Let $\hat{\mathscr{J}}=\left\{\hat{J}_{n} \mid \hat{J}_{n}=J_{n}\left(\hat{\theta}_{n}\right)=J_{n}\left(\hat{\theta}_{n}\right)^{\top} \xrightarrow{p} J_{0}, \hat{J}_{n}^{-1}\right.$ exists $\}$, a set of consistent estimators of $J_{0}$ that are evaluated at $\hat{\theta}_{n}$. Then,

$$
\mathscr{W}=\left\{W_{n}\left(\hat{J}_{n}\right) \mid W_{n}\left(\hat{J}_{n}\right) \text { is given by }(1), \quad \hat{J}_{n} \in \hat{\mathscr{J}}\right\}
$$

is the original family of asymptotically-equivalent Wald statistics for testing $H_{0}$. In this family, one member is distinguished from another only by the choice of $J_{n}(\theta)$ and all members evaluate their chosen $J_{n}(\theta)$ at $\hat{\theta}_{n}$. Therefore, an original Wald statistic is a quadratic form in $\sqrt{n} r\left(\hat{\theta}_{n}\right)$ where all components of its weighting matrix are evaluated at $\hat{\theta}_{n}$. Now, let $\mathscr{J}=\left\{J_{n} \mid J_{n}=J_{n}^{\top} \xrightarrow{p} J_{0}, J_{n}^{-1}\right.$ exists $\}$ and $\mathscr{R}=\left\{R_{n} \mid R_{n} \xrightarrow{p} R_{0}, R_{n}\right.$ has rank $\left.r\right\}$ be sets of consistent estimators of $J_{0}$ and $R_{0}$, respectively. Then, replacing $\hat{J}_{n}$ and $\hat{R}$ in $W_{n}\left(\hat{J}_{n}\right)$ with the more general estimators $J_{n}$ and $R_{n}$, respectively, gives a statistic that is asymptotically equivalent to $W_{n}\left(\hat{J}_{n}\right)$ under $H_{0}$. Therefore, an extended Wald statistic is

$$
\begin{equation*}
W_{n}\left(J_{n}, R_{n}\right)=n r\left(\hat{\theta}_{n}\right)^{\top}\left\{R_{n} J_{n}^{-1} R_{n}^{\top}\right\}^{-1} r\left(\hat{\theta}_{n}\right), \tag{2}
\end{equation*}
$$

which corresponds to $W_{1 n}$ in Newey and McFadden (1994, Table 2, p. 2222) and which is a special case of $\xi_{n}^{w}$ in Gourieroux and Monfort (1989, equation (37), p. 75) where the restrictions are written in a more general form than $r(\theta)=0$. Then,

$$
\mathscr{E} \mathscr{W}=\left\{W_{n}\left(J_{n}, R_{n}\right) \mid W_{n}\left(J_{n}, R_{n}\right) \text { is given by }(2), J_{n} \in \mathscr{J}, \quad R_{n} \in \mathscr{R}\right\}
$$

is the extended family of asymptotically-equivalent Wald statistics for testing $H_{0}$; the sets $\hat{\mathcal{J}}, \mathscr{J}, \mathscr{R}, \mathscr{W}$, and $\mathscr{E} \mathscr{W}$ correspond to $\hat{\mathscr{A}}, \mathscr{A}, \mathscr{R}, \overline{\mathscr{W}}$, and $\overline{\mathscr{E}}_{1}$, respectively, in Dastoor (2003). In this extended family, one member is distinguished from another by the choice of $J_{n}$ and $R_{n}$ and, for each member, the chosen $J_{n}$ and $R_{n}$ need not necessarily be matrices evaluated at $\hat{\theta}_{n}$. Since $\hat{\mathscr{J}} \subset \mathscr{J}, \hat{R} \in \mathscr{R}$, and $W_{n}\left(\hat{J}_{n}\right)=W_{n}\left(\hat{J}_{n}, \hat{R}\right)$, any original Wald statistic is an extended Wald statistic so $\mathscr{W} \subset \mathscr{E} \mathscr{W}$.

Let $\Omega_{0}^{*}=\{\theta \mid q(\theta)=0, \theta \in \Omega\}, Q(\theta)=\partial q(\theta) / \partial \theta^{\top}$ be the $r \times p$ matrix of derivatives with rank $r$ for all $\theta \in \Omega, \hat{Q}=Q\left(\hat{\theta}_{n}\right)$, and $Q_{0}=Q\left(\theta_{0}\right)$ where $q(\theta)$ is such that $q(\theta)=0$ if and only if $r(\theta)=0$. Then, $\Omega_{0}^{*}=\Omega_{0}$ so $H_{0}^{*}: \theta \in \Omega_{0}^{*}$ is a reformulation of $H_{0}: \theta \in \Omega_{0}$; cf. Dagenais and Dufour (1991, p. 1605) where $\psi(\theta)$ and $\bar{\psi}(\theta)$ correspond to $r(\theta)$ and $q(\theta)$, respectively. For testing $H_{0}^{*}$, an original Wald statistic is

$$
\begin{equation*}
W_{n}^{*}\left(\hat{J}_{n}\right)=n q\left(\hat{\theta}_{n}\right)^{\top}\left\{\hat{Q} \hat{J}_{n}^{-1} \hat{Q}^{\top}\right\}^{-1} q\left(\hat{\theta}_{n}\right), \tag{3}
\end{equation*}
$$

which is asymptotically equivalent to $W_{n}\left(\hat{J}_{n}\right)$ under $H_{0}$,

$$
\mathscr{W}^{*}=\left\{W_{n}^{*}\left(\hat{J}_{n}\right) \mid W_{n}^{*}\left(\hat{J}_{n}\right) \text { is given by }(3), \hat{J}_{n} \in \hat{\mathscr{J}}\right\}
$$

is the original family of asymptotically-equivalent Wald statistics,

$$
\begin{equation*}
W_{n}^{*}\left(J_{n}, Q_{n}\right)=n q\left(\hat{\theta}_{n}\right)^{\top}\left\{Q_{n} J_{n}^{-1} Q_{n}^{\top}\right\}^{-1} q\left(\hat{\theta}_{n}\right) \tag{4}
\end{equation*}
$$

is an extended Wald statistic, and the extended family of asymptotically-equivalent Wald statistics is

$$
\mathscr{E} \mathscr{W}^{*}=\left\{W_{n}^{*}\left(J_{n}, Q_{n}\right) \mid W_{n}^{*}\left(J_{n}, Q_{n}\right) \text { is given by }(4), J_{n} \in \mathscr{J}, Q_{n} \in \mathscr{Q}\right\}
$$

where $\mathscr{Q}=\left\{Q_{n} \mid Q_{n} \xrightarrow{p} Q_{0}, Q_{n}\right.$ has rank $\left.r\right\}$ and $W_{n}^{*}\left(\hat{J}_{n}\right)=W_{n}^{*}\left(\hat{J}_{n}, \hat{Q}\right) \in \mathscr{W}^{*} \subset \mathscr{E} \mathscr{W}^{*}$.

For later reference, it is useful to note the following results, which are proved in the appendix. First, in general, there exist two $r \times r$ nonsingular matrices $P_{0}$ and $\bar{P}_{n}$ such that

$$
\begin{align*}
& Q_{0}=P_{0} R_{0},  \tag{5}\\
& q\left(\hat{\theta}_{n}\right)=\bar{P}_{n} r\left(\hat{\theta}_{n}\right), \tag{6}
\end{align*}
$$

and $\bar{P}_{n} \xrightarrow{p} P_{0}$. Second, consider the special case of $q(\theta)=\operatorname{Pr}(\theta)$ where $P$ is an $r \times r$ nonstochastic nonsingular matrix whose elements do not depend on $\theta$; i.e., $q(\theta)$ is a nonsingular linear transformation of $r(\theta)$. In this special case,

$$
\begin{equation*}
q\left(\hat{\theta}_{n}\right)=\operatorname{Pr}\left(\hat{\theta}_{n}\right), \quad \hat{Q}=P \hat{R}, \quad Q_{0}=P R_{0}, \quad \text { and } \quad \bar{P}_{n}=P_{0}=P . \tag{7}
\end{equation*}
$$

## 3. A SIMPLE EXPLANATION

The original families $\mathscr{W}$ and $\mathscr{W}^{*}$ differ, unless $q(\theta)=0$ is a particular type of reformulation of $r(\theta)=0$. For example, if $q(\theta)$ is a nonsingular linear transformation of $r(\theta)$, then $\mathscr{W}=\mathscr{W}^{*}$ as (1), (3), and (7) yield $W_{n}\left(\hat{J}_{n}\right)=W_{n}^{*}\left(\hat{J}_{n}\right)$; cf. Davidson and MacKinnon (1993, p. 469). Although $\mathscr{W} \neq \mathscr{W}^{*}$ in general, it can be shown that

$$
\begin{equation*}
\mathscr{E} \mathscr{W}=\mathscr{E} \mathscr{W}^{*} \tag{8}
\end{equation*}
$$

which is proved in the appendix. Basically, the extended Wald statistics use estimators of $J_{0}, R_{0}$, and $Q_{0}$ that have the flexibility to exploit the relationship between $r\left(\hat{\theta}_{n}\right)$ and $q\left(\hat{\theta}_{n}\right)$ in (6), which results in the equality of the extended families, whereas, the estimators used by the original Wald statistics are only those evaluated at $\hat{\theta}_{n}$, which cannot always exploit (6) so the original families differ in general. The equality of the extended families shows that, for a given sample, any extended Wald statistic for testing $H_{0}^{*}$ is identical to some extended Wald statistic for testing $H_{0}$ (and vice versa) so (8) implies (but is not implied by) the asymptotic equivalence of $W_{n}\left(J_{n}, R_{n}\right)$ and $W_{n}^{*}\left(J_{n}, Q_{n}\right)$ under $H_{0}$. Therefore, the original Wald statistics will now be viewed as members of $\mathscr{E} \mathscr{W}$; i.e., $W_{n}\left(\hat{J}_{n}\right)=W_{n}\left(\hat{J}_{n}, \hat{R}\right)$ and

$$
\begin{equation*}
W_{n}^{*}\left(\hat{J}_{n}\right)=W_{n}\left(\hat{J}_{n}, R^{*}\right)=W_{n}\left(J_{n}^{*}, \hat{R}\right) \tag{9}
\end{equation*}
$$

where $R^{*}=\bar{P}_{n}^{-1} \hat{Q} \in \mathscr{R}$ and $J_{n}^{*} \in \mathscr{J}$ is a particular matrix whose form is given in the proof of (9) in the appendix. Also, it can be shown that $R^{*} \hat{J}_{n}^{-1} R^{* \top}=\hat{R}\left(J_{n}^{*}\right)^{-1} \hat{R}^{\top}$.

Let $\hat{V}_{n}=\hat{R} \hat{J}_{n}^{-1} \hat{R}^{\top} \xrightarrow{p} V_{0}$ and $V_{n}^{*}=R^{*} \hat{J}_{n}^{-1} R^{* \top} \xrightarrow{p} V_{0}$ where $V_{0}=R_{0} J_{0}^{-1} R_{0}^{\top}$ is the asymptotic variance-covariance matrix of $\sqrt{n} r\left(\hat{\theta}_{n}\right)$ under $H_{0}$. Then, $W_{n}\left(\hat{J}_{n}\right)$ and $W_{n}^{*}\left(\hat{J}_{n}\right)$ are quadratic forms in $\sqrt{n} r\left(\hat{\theta}_{n}\right)$ with weighting matrices $\hat{V}_{n}^{-1}$ and $\left(V_{n}^{*}\right)^{-1}$, respectively. Here, the estimation of $V_{0}$ (instead of just $R_{0}$ or just $J_{0}$ ) is relevant since (9) shows that $W_{n}^{*}\left(\hat{J}_{n}\right)$ can be obtained from (2) by setting either $R_{n}=R^{*}$ with $J_{n}=\hat{J}_{n}$ or $J_{n}=J_{n}^{*}$ with $R_{n}=\hat{R}$. Since $W_{n}\left(\hat{J}_{n}\right)=W_{n}^{*}\left(\hat{J}_{n}\right)$ if $\hat{V}_{n}=V_{n}^{*}$, a Wald statistic is invariant if a reformulation of $H_{0}$ as $H_{0}^{*}$ does not result in $W_{n}\left(\hat{J}_{n}\right)$ and $W_{n}^{*}\left(\hat{J}_{n}\right)$ using different consistent estimators of $V_{0}$. For
example, if $q(\theta)$ is a nonsingular linear transformation of $r(\theta)$, then (7) holds and $R^{*}=\bar{P}_{n}^{-1} \hat{Q}$ reduces to $R^{*}=\hat{R}$ so $\hat{V}_{n}=V_{n}^{*}$. In this case, $W_{n}\left(\hat{J}_{n}\right)$ and $W_{n}^{*}\left(\hat{J}_{n}\right)$ use the same consistent estimator of $V_{0}$ so a Wald statistic is invariant or, equivalently, these two statistics are identical extended statistics for testing $H_{0}$. However, if $W_{n}\left(\hat{J}_{n}\right) \neq W_{n}^{*}\left(\hat{J}_{n}\right)$, then $\hat{V}_{n} \neq V_{n}^{*}$. This provides a simple explanation for the non-invariance of a Wald statistic; i.e., when $H_{0}$ is replaced with $H_{0}^{*}$, the non-invariance of a Wald statistic is equivalent to replacing one extended statistic for testing $H_{0}$ with a different extended statistic for testing $H_{0}$ and, in addition, this non-invariance implies that $W_{n}\left(\hat{J}_{n}\right)$ and $W_{n}^{*}\left(\hat{J}_{n}\right)$ use different estimators $\hat{V}_{n}$ and $V_{n}^{*}$, respectively, as consistent estimators of $V_{0}$. Also, in the case where $r=1$ with $r\left(\hat{\theta}_{n}\right) \neq 0$, it is easily seen that $W_{n}\left(\hat{J}_{n}\right)=W_{n}^{*}\left(\hat{J}_{n}\right)$ if and only if $\hat{V}_{n}=V_{n}^{*}$. Therefore, when testing a single restriction, the non-invariance of a Wald statistic is also equivalent to using different consistent estimators of $V_{0}$.

## 4. CONCLUDING REMARKS

Given the simple explanation, the results of Lafontaine and White (1986) and Breusch and Schmidt (1988) can be interpreted as showing how an estimator of $V_{0}$ can be easily chosen such that $W_{n}^{*}\left(\hat{J}_{n}\right)$ has a desired numerical value. In principle, some criterion could be used either to choose among estimators or to rule out certain estimators of $V_{0}$; indirectly, this would either provide an optimal formulation of the restrictions or rule out certain formulations, respectively. For example, the results of Phillips and Park (1988) and Kemp (2001) could be interpreted as providing some guidance on choosing an estimator and on ruling out certain estimators of $V_{0}$, respectively. Now, if two extended Wald statistics for testing $H_{0}$ use different consistent estimators of $V_{0}$, then it is reasonable to expect (if not require) the statistics to be different for a given sample. Therefore, since the non-invariance of a Wald statistic implies the use of different consistent estimators of $V_{0}$, this non-invariance should (contrary to econometrics folklore) not be viewed as an undesirable property of a Wald statistic, and especially in the case of testing a single restriction where the non-invariance is equivalent to using different consistent estimators of $V_{0}$.

## APPENDIX

Proof of Equation (5). Let $R(\theta)=\left[R_{1}(\theta), R_{2}(\theta)\right]$ and $Q(\theta)=\left[Q_{1}(\theta), Q_{2}(\theta)\right]$ be comformably partitioned with $\theta=\left(\theta_{1}^{\top}, \theta_{2}^{\top}\right)^{\top}$ where $\theta_{1}$ is an $r \times 1$ vector, and $R_{1}(\theta)$ and $Q_{1}(\theta)$ are $r \times r$ nonsingular matrices for $\theta \in \Omega_{0}$. Then, as shown by Dagenais and Dufour (1991, p. 1606), the implicit function theorem ensures that (for $\theta \in \Omega_{0}$ ) there exists a differentiable function $h$ such that $\theta_{1}=h\left(\theta_{2}\right)$ so

$$
\frac{\partial \theta_{1}}{\partial \theta_{2}^{\top}}=\frac{\partial h}{\partial \theta_{2}^{\top}}=-R_{1}(\theta)^{-1} R_{2}(\theta)=-Q_{1}(\theta)^{-1} Q_{2}(\theta)
$$

where the last equality follows as $q(\theta)=0$ if and only if $r(\theta)=0$. This last equality provides $Q_{2}\left(\theta_{0}\right)=Q_{1}\left(\theta_{0}\right) R_{1}\left(\theta_{0}\right)^{-1} R_{2}\left(\theta_{0}\right)$, which can be substituted into $Q_{0}=\left[Q_{1}\left(\theta_{0}\right), Q_{2}\left(\theta_{0}\right)\right]$ to yield (5) where

$$
\begin{equation*}
P_{0}=Q_{1}\left(\theta_{0}\right) R_{1}\left(\theta_{0}\right)^{-1} \tag{A.1}
\end{equation*}
$$

is an $r \times r$ nonsingular matrix.

Proof of Equation (6). Let $s_{n}(\theta)=\partial L_{n}(\theta) / \partial \theta, \lambda$ be an $r \times 1$ vector of Lagrange multipliers, and $\tilde{R}=R\left(\tilde{\theta}_{n}\right)$ where $\tilde{\theta}_{n}$ is the restricted estimator of $\theta$ under $H_{0}$. Then, from the Lagrangean $\mathfrak{L}(\theta, \lambda)=L_{n}(\theta)-\lambda^{\top} r(\theta)$, the first-order condition $\partial \mathfrak{L}\left(\tilde{\theta}_{n}, \tilde{\lambda}_{n}\right) / \partial \theta=0$ gives $s_{n}\left(\tilde{\theta}_{n}\right)=\tilde{R}^{\top} \tilde{\lambda}_{n}$. Another equation for $s_{n}\left(\tilde{\theta}_{n}\right)$ can be obtained from a mean-value expansion of $s_{n}\left(\tilde{\theta}_{n}\right)$ at $\hat{\theta}_{n}$ so, as $s_{n}\left(\hat{\theta}_{n}\right)=0, s_{n}\left(\tilde{\theta}_{n}\right)=n \bar{J}_{n}\left(\hat{\theta}_{n}-\tilde{\theta}_{n}\right)$ where $\bar{J}_{n}$ is the matrix $-n^{-1} \partial^{2} L_{n}(\theta) / \partial \theta \partial \theta^{\top}$ with each of its rows evaluated at a (possibly different) mean value given by a convex combination of $\hat{\theta}_{n}$ and $\tilde{\theta}_{n}$. Assuming that $\bar{J}_{n}$ is nonsingular, the two equations for $s_{n}\left(\tilde{\theta}_{n}\right)$ provide

$$
\begin{equation*}
\hat{\theta}_{n}-\tilde{\theta}_{n}=n^{-1} \bar{J}_{n}^{-1} \tilde{R}^{\top} \tilde{\lambda}_{n} \tag{A.2}
\end{equation*}
$$

Since $r\left(\tilde{\theta}_{n}\right)=0$, a mean value expansion of $r\left(\hat{\theta}_{n}\right)$ at $\tilde{\theta}_{n}$ gives $r\left(\hat{\theta}_{n}\right)=\bar{R}\left(\hat{\theta}_{n}-\tilde{\theta}_{n}\right)$ where $\bar{R}$ is the matrix $R(\theta)$ with each of its rows evaluated at a (possibly different) mean value given by a convex combination of $\hat{\theta}_{n}$ and $\tilde{\theta}_{n}$. Then, assuming that $\bar{R} \bar{J}_{n}^{-1} \tilde{R}^{\top}$ is nonsingular,
substituting (A.2) into $r\left(\hat{\theta}_{n}\right)=\bar{R}\left(\hat{\theta}_{n}-\tilde{\theta}_{n}\right)$ gives $\tilde{\lambda}_{n}=n\left\{\bar{R} \bar{J}_{n}^{-1} \tilde{R}^{\top}\right\}^{-1} r\left(\hat{\theta}_{n}\right)$ so (A.2) can be written as

$$
\begin{equation*}
\hat{\theta}_{n}-\tilde{\theta}_{n}=\bar{J}_{n}^{-1} \tilde{R}^{\top}\left\{\bar{R} \bar{J}_{n}^{-1} \tilde{R}^{\top}\right\}^{-1} r\left(\hat{\theta}_{n}\right) \tag{A.3}
\end{equation*}
$$

Since $q\left(\tilde{\theta}_{n}\right)=0$, a mean value expansion of $q\left(\hat{\theta}_{n}\right)$ at $\tilde{\theta}_{n}$ gives $q\left(\hat{\theta}_{n}\right)=\bar{Q}\left(\hat{\theta}_{n}-\tilde{\theta}_{n}\right)$ where $\bar{Q}$ is the matrix $Q(\theta)$ with each of its rows evaluated at a (possibly different) mean value given by a convex combination of $\hat{\theta}_{n}$ and $\tilde{\theta}_{n}$. Finally, substituting (A.3) into $q\left(\hat{\theta}_{n}\right)=\bar{Q}\left(\hat{\theta}_{n}-\tilde{\theta}_{n}\right)$ gives (6) where

$$
\begin{equation*}
\bar{P}_{n}=\bar{Q} \bar{J}_{n}^{-1} \tilde{R}^{\top}\left\{\bar{R} \bar{J}_{n}^{-1} \tilde{R}^{\top}\right\}^{-1} \tag{A.4}
\end{equation*}
$$

is an $r \times r$ nonsingular matrix (assuming that $\bar{Q} \bar{J}_{n}^{-1} \tilde{R}^{\top}$ is nonsingular) and $\bar{P}_{n} \xrightarrow{p} P_{0}$ as $\bar{Q} \xrightarrow{p} Q_{0}=P_{0} R_{0}, \bar{J}_{n} \xrightarrow{p} J_{0}, \tilde{R} \xrightarrow{p} R_{0}$, and $\bar{R} \xrightarrow{p} R_{0}$.

Proof of the equations in (7). Since $q(\theta)=\operatorname{Pr}(\theta)$ and $Q(\theta)=P R(\theta)$, the first three equations in (7) are obvious, and the last two equalities are easily seen as, in this special case, $Q_{1}\left(\theta_{0}\right)=P R_{1}\left(\theta_{0}\right)$ and $\bar{Q}=P \bar{R}$ so (A.1) and (A.4) reduce to $P_{0}=P$ and $\bar{P}_{n}=P$, respectively.

Proof of Equation (8). It will be shown that $\mathscr{E} \mathscr{W}^{*} \subseteq \mathscr{E} \mathscr{W}$ and $\mathscr{E} \mathscr{W} \subseteq \mathscr{E} \mathscr{W}^{*}$, which imply (8); throughout this proof, $R_{n} \in \mathscr{R}, Q_{n} \in \mathscr{Q}$, and $J_{n} \in \mathscr{J}$. Let $R_{Q n}=\bar{P}_{n}^{-1} Q_{n}$ where $\bar{P}_{n}$ is as in (6). Then, $R_{Q n}$ has rank $r$ with $R_{Q n} \xrightarrow{p} P_{0}^{-1} Q_{0}=R_{0}$ as $Q_{0}=P_{0} R_{0}$. Therefore, $R_{Q n} \in \mathscr{R}$ so $W_{n}\left(J_{n}, R_{Q n}\right) \in \mathscr{E} \mathscr{W}$. Now, (2), (4), and (6) show that

$$
\begin{equation*}
W_{n}\left(J_{n}, R_{Q n}\right)=W_{n}^{*}\left(J_{n}, Q_{n}\right), \tag{A.5}
\end{equation*}
$$

which provides $\mathscr{E} \mathscr{W}^{*} \subseteq \mathscr{E} \mathscr{W}$ as $W_{n}^{*}\left(J_{n}, Q_{n}\right)$ is an arbitrary member of $\mathscr{E} \mathscr{W}^{*}$. Similarly, let $Q_{R n}=\bar{P}_{n} R_{n}$. Then, $Q_{R n} \in \mathscr{Q}$ so $W_{n}^{*}\left(J_{n}, Q_{R n}\right) \in \mathscr{E} \mathscr{W}^{*}$. Here, (2), (4), and (6) show that $W_{n}^{*}\left(J_{n}, Q_{R n}\right)=W_{n}\left(J_{n}, R_{n}\right)$ so $\mathscr{E} \mathscr{W} \subseteq \mathscr{E} \mathscr{W}^{*}$ as $W_{n}\left(J_{n}, R_{n}\right)$ is an arbitrary member of $\mathscr{E} \mathscr{W}$. Hence, $\mathscr{E} \mathscr{W}=\mathscr{E} \mathscr{W}^{*}$.

The equality in (8) can also be obtained by showing that there exist two matrices $J_{Q n} \in$ $\mathscr{J}$ and $J_{R n} \in \mathscr{J}$ such that $W_{n}\left(J_{Q n}, R_{n}\right)=W_{n}^{*}\left(J_{n}, Q_{n}\right)$ and $W_{n}^{*}\left(J_{R n}, Q_{n}\right)=W_{n}\left(J_{n}, R_{n}\right)$. To see this, let $R_{Q n}$ be as above and $M_{R n}=I_{p}-R_{n}^{\top}\left\{R_{n} J_{n}^{-1} R_{n}^{\top}\right\}^{-1} R_{n} J_{n}^{-1}$. Then,

$$
\begin{equation*}
D_{n}=J_{n}^{-1} R_{n}^{\top}\left\{R_{n} J_{n}^{-1} R_{n}^{\top}\right\}^{-1} R_{Q n} J_{n}^{-1} R_{Q n}^{\top}\left\{R_{n} J_{n}^{-1} R_{n}^{\top}\right\}^{-1} R_{n} J_{n}^{-1}+J_{n}^{-1} M_{R n} \tag{A.6}
\end{equation*}
$$

is a symmetric matrix such that $D_{n} \xrightarrow{p} J_{0}^{-1}$. A proof by contradiction shows that $D_{n}^{-1}$ exists. Therefore, suppose that $D_{n}$ is singular. Then, there exists a $p \times 1$ vector $\xi \neq 0$ such that $D_{n} \xi=0$, which (using (A.6)) can be written as

$$
\begin{equation*}
J_{n}^{-1} R_{n}^{\top}\left\{R_{n} J_{n}^{-1} R_{n}^{\top}\right\}^{-1} R_{Q n} J_{n}^{-1} R_{Q n}^{\top}\left\{R_{n} J_{n}^{-1} R_{n}^{\top}\right\}^{-1} R_{n} J_{n}^{-1} \xi+J_{n}^{-1} M_{R n} \xi=0 \tag{A.7}
\end{equation*}
$$

Since $\left\{R_{Q n} J_{n}^{-1} R_{Q n}^{\top}\right\}^{-1}$ exists, premultiplying (A.7) by $R_{n} J_{n}^{-1} R_{n}^{\top}\left\{R_{Q n} J_{n}^{-1} R_{Q n}^{\top}\right\}^{-1} R_{n}$ gives $R_{n} J_{n}^{-1} \xi=0$ (which implies $M_{R n} \xi=\xi$ ) so (A.7) reduces to $J_{n}^{-1} \xi=0$, which provides the contradiction that $\xi=0$. Hence, $D_{n}$ is a symmetric nonsingular matrix. Now, let $J_{Q n}=D_{n}^{-1}$ and note that (A.6) gives $R_{n} J_{Q n}^{-1} R_{n}^{\top}=R_{Q n} J_{n}^{-1} R_{Q n}^{\top}$. Then, $J_{Q n} \in \mathscr{J}$ and, using (2), it is easily seen that $W_{n}\left(J_{Q n}, R_{n}\right)=W_{n}\left(J_{n}, R_{Q n}\right)$ so, given (A.5),

$$
\begin{equation*}
W_{n}^{*}\left(J_{n}, Q_{n}\right)=W_{n}\left(J_{n}, R_{Q n}\right)=W_{n}\left(J_{Q n}, R_{n}\right) \tag{A.8}
\end{equation*}
$$

Similarly, it can be shown that $W_{n}\left(J_{n}, R_{n}\right)=W_{n}^{*}\left(J_{n}, Q_{R n}\right)=W_{n}^{*}\left(J_{R n}, Q_{n}\right)$ where $Q_{R n}$ is as above and

$$
J_{R n}=\left[J_{n}^{-1} Q_{n}^{\top}\left\{Q_{n} J_{n}^{-1} Q_{n}^{\top}\right\}^{-1} Q_{R n} J_{n}^{-1} Q_{R n}^{\top}\left\{Q_{n} J_{n}^{-1} Q_{n}^{\top}\right\}^{-1} Q_{n} J_{n}^{-1}+J_{n}^{-1} M_{Q n}\right]^{-1} \in \mathscr{J}
$$

with $M_{Q n}=I_{p}-Q_{n}^{\top}\left\{Q_{n} J_{n}^{-1} Q_{n}^{\top}\right\}^{-1} Q_{n} J_{n}^{-1}$.

Proof of Equation (9). Let $R^{*}=\bar{P}_{n}^{-1} \hat{Q} \in \mathscr{R}$ and

$$
J_{n}^{*}=\left[\hat{J}_{n}^{-1} \hat{R}^{\top}\left\{\hat{R} \hat{J}_{n}^{-1} \hat{R}^{\top}\right\}^{-1} R^{*} \hat{J}_{n}^{-1} R^{* \top}\left\{\hat{R} \hat{J}_{n}^{-1} \hat{R}^{\top}\right\}^{-1} \hat{R} \hat{J}_{n}^{-1}+\hat{J}_{n}^{-1} \hat{M}_{R n}\right]^{-1} \in \mathscr{J}
$$

where $\hat{M}_{R n}=I_{p}-\hat{R}^{\top}\left\{\hat{R} \hat{J}_{n}^{-1} \hat{R}^{\top}\right\}^{-1} \hat{R} \hat{J}_{n}^{-1}$; i.e., $R^{*}, J_{n}^{*}$, and $\hat{M}_{R n}$ are special cases of $R_{Q n}$, $J_{Q n}$, and $M_{R n}$, respectively, obtained by setting $J_{n}=\hat{J}_{n}, R_{n}=\hat{R}$, and $Q_{n}=\hat{Q}$. Then, (9) is obtained from (A.8) by noting that $W_{n}^{*}\left(\hat{J}_{n}, \hat{Q}\right)=W_{n}^{*}\left(\hat{J}_{n}\right)$.

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