

# Which null hypothesis do overidentification restrictions actually test? 

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#### Abstract

In this note I investigate which alternatives are detected by over-identifying restrictions tests, when we test the null hypothesis that all excluded instruments are exogenous. A reformulated null hypothesis will result in a consistent test.


[^0]
## 1. Introduction

It is well-known that over-identifying restrictions tests are not consistent against all alternatives when they are used to test the null hypothesis, say $H_{0}$, that all excluded instruments are exogenous (see, for instance, Newey, 1985). Here we use the standard notion of test consistency whereby a test is consistent (of significance level $\alpha$ ) against some alternative if it is asymptotically of level $\alpha$ and the power of the test at this (fixed) alternative goes to one with increasing sample size, say $N$. This test is said to be consistent if it is consistent against all fixed alternatives. See for example van der Vaart (2000, p.193).

An inconsistent test, thus, has alternatives which it does not detect with power going to one for $N \rightarrow \infty$. We will show that, in the case of over-identifying restrictions tests, this inconsistency could be termed a blind spot, in the sense that certain alternatives, no matter how far from $H_{0}$, will not increase the power of the test statistic. This is unfortunate, since a "failure to reject" results are inherently ambiguous. In addition, results of the "failure to reject" kind can be considered stronger, the broader the class of alternatives is with respect to which one fails to reject. As a consequence, consistent tests are to be preferred over inconsistent ones.
One way to deal with an inconsistent test, is to add extra, a priori, assumptions which make the test consistent. In the instrumental variable context it is common to assume the presence of as much exogenous instruments as there are endogenous variables in the outcome equation. Instead of the latter strategy, one could try to identify the set of parameter combinations, say $S_{0}$, for which the considered test statistic has the same asymptotic distribution. It is possible that the null hypothesis of an inconsistent test does not coincide with $S_{0}$. In such a case, a reformulation of the null hypothesis (as $G_{0}$, say) is in order. If we subsequently show that the power of the test goes to one for $N \rightarrow \infty$ at every fixed element of $G_{A}$ (the reformulated alternative hypothesis), this simple reformulation of the null hypothesis is enough to result in a consistent test. This course of action has the added advantage (over adding extra assumptions) that fundamentally untestable alternatives (with respect to the initial null $H_{0}$ ) are are made explicit.
In the context of the over-identifying restrictions tests considered here, the new null $G_{0}$ will be expressed in terms of those parameters which seem most natural: those of the structural outcome equation and those of the reduced form for the treatment variables. In this context, a test of $G_{0}$ versus $G_{A}$ still can be interpreted in terms of over-identification (exclusion of the instruments from the structural outcome equation).

## 2. Framework

Consider the $N \times 1$ stacked observations of the outcome $y_{i}$ to be given by

$$
\begin{equation*}
Y=X \alpha_{x}+Z \alpha_{z}+E \tag{1}
\end{equation*}
$$

where the $N \times K_{1}$ matrix $X$ contains exogenous variables $x_{i}$, possibly including a constant term, and $E$ stacks the $N$ error terms $\varepsilon_{i}$. The $N \times L$ matrix $Z$ contains the treatment, choice or otherwise endogenous variables, which can be represented by the reduced form

$$
\begin{equation*}
Z=X B_{x}+W B_{w}+V \tag{2}
\end{equation*}
$$

where the $N \times K_{2}$ matrix $W$ fulfills $K_{2} \geq L$ and $\operatorname{rank}\left(\mathbf{E}\left[W^{\prime} Z\right]\right)=L$. These familiar identification restrictions allow the use of $W$ as a set of instruments for $Z$.

Remark. The first-stage parameters of the excluded instruments, i.e. $B_{w}$, will play a crucial role in the reformulation of the null hypothesis.

In the remainder of the text, the more compact notation $R=(X, Z)$ is used to denote the explanatory variables in the outcome equation (1) and $S=(X, W)$ for the exogenous variables in (2). Furthermore, following assumptions ${ }^{1}$ are maintained.

Assumption 1. The observations (rows) of ( $S, E, V$ ) are IID.
Assumption 2. The outcome disturbances $E$ are mean-independent of $S$, i.e.

$$
\mathbf{E}[E \mid S]=0
$$

Assumption 2 is crucial for consistency of the $I V$ estimator

$$
\hat{\alpha}_{I V}=\left(R^{\prime} S\left(S^{\prime} S\right)^{-1} S^{\prime} R\right)^{-1}\left(R^{\prime} S\left(S^{\prime} S\right)^{-1} S^{\prime} Y\right)
$$

While $\mathbf{E}[E \mid X]=0$ is untestable within this framework due to the imposed orthogonality between regressors and residuals by all $L S$ estimators, the assumption $\mathbf{E}[E \mid W]=0$ is (partly) testable. The latter tests are commonly called over-identifying restrictions tests or instrument validity tests and will be treated in the following section.

## 3. Some over-identifying restrictions tests

Two well-known such tests are the Sargan (1958)-Hansen (1982) $J$-test and the $L M$ or score test as described by Magdalinos (1988). The $J$-test uses the minimized optimal $G M M$ criterion as test statistic, which is, under homoskedasticity, given by

$$
\begin{equation*}
J=\left(\hat{E}^{\prime} S\right) \cdot\left(S^{\prime} S\right)^{-1} \cdot\left(S^{\prime} \hat{E}\right) / \widehat{\sigma_{\varepsilon}^{2}} \tag{3}
\end{equation*}
$$

with $\sigma_{\varepsilon}^{2}=\operatorname{Var}[\varepsilon]$, the error variance of the outcome equation (1). Under the null that all $K_{2}$ instruments are valid, the minimized optimal $G M M$ criterion is asymptotically distributed as a central chi-square distribution with $K_{2}-L$ degrees of freedom. The $L M$-statistic to test the null hypothesis that all instruments are exogenous is an omitted variable test for the variables $W$ in the outcome equation (1) ${ }^{2}$. It is given by

$$
\begin{equation*}
L M=N^{-1}\left(\hat{E}^{\prime} W\right) \hat{\Omega}^{-1}\left(W^{\prime} \hat{E}\right) \tag{4}
\end{equation*}
$$

where $\Omega$ is the covariance matrix of $N^{-1} E^{\prime} \hat{W}$. Under the hypothesis that the instruments $W$ are validly restricted from the outcome equation (1), it holds that $L M \xrightarrow{d} \chi_{K_{2}-L}^{2}(0)$, as well.

[^1]All such validity tests have one weakness in common: they are inconsistent when used for testing the null hypothesis $H_{0}: \mathbf{E}[E \mid W]=0$. This means that, even for growing sample size $N$, not all departures from $H_{0}$ are detected ${ }^{3}$. In other words, these tests have a blind spot. Some alternatives, no matter how far from $H_{0}$, will leave the test statistics unaffected. Sometimes correct application of over-identifying restrictions tests is stated as follows:

If at least $L$ instruments are exogenous, then it is possible to test the null hypothesis that all instruments are exogenous against the alternative that at least one (but no more than $K_{2}-L$ ) is endogenous (Stock 2001).

Such statements, by adding the extra assumptions that "at least $L$ instruments are exogenous", produce a consistent test in the sense that now all alternatives (falling within the added assumptions) are detected with power going to one for growing sample size. However, they incorrectly characterize the class of alternatives for which over-identifying restrictions tests are inconsistent if we do not wish to make the assumption that "at least $L$ instruments are exogenous". Furthermore, they discourage the use of $I V$ estimators, since they suggest that their use is somehow founded on the untestable belief in the presence of at least $L$ exogenous instruments. In the next section, I will characterize the set of alternatives to $H_{0}$, for which over-identifying restrictions tests, as currently formulated, are inconsistent. This will then lead to a reformulated null hypothesis, $G_{0}$, which, in combination with either of the test statistics (3) or (4) above, will constitute a consistent test.

## 4. Inconsistency

Consider again the outcome equation (1). Under the alternative hypothesis that not all instruments are exogenous, we can write the error term as

$$
\begin{align*}
E & =W \kappa+U  \tag{5}\\
\mathbf{E}[U \mid W] & =\mathbf{0}_{N \times 1} . \tag{6}
\end{align*}
$$

The $L \times 1$ vector $\kappa$ the indicates which linear combination of the instruments the error term $E$ is maximally correlated with, i.e. $\kappa=\mathbf{E}\left[W^{\prime} W\right]^{-1} \mathbf{E}\left[W^{\prime} E\right]$. The null hypothesis $H_{0}: \mathbf{E}[E \mid W]=\mathbf{0}_{N \times 1}$ can be reformulated as $H_{0}: \kappa=\mathbf{0}_{K_{2} \times 1}$. The following theorem characterizes the set of alternatives to $H_{0}$, for which over-identifying restrictions tests have power equal to size and the set of alternatives for which said test is consistent.

Theorem. Over-identifying restrictions tests, consisting of test statistics (3) or (4) and null hypothesis $H_{0}: \kappa=\mathbf{0}_{K_{2} \times 1}$, have asymptotic power equal to size against alternatives of the form $E=\left(W B_{w}\right) \gamma+U$, with $\gamma \in \mathbb{R}^{L}$. They are consistent against alternatives of the form $W \delta$, for which $B_{w}^{\prime} \Sigma_{w} \delta=\mathbf{0}_{L \times 1}$, where $\Sigma_{w}=\operatorname{Var}[w]$.

Proof. Consider model (1)-(2) where the covariates $X$ are partialed out for ease of exposition (and without loss of generality)

$$
\begin{align*}
\tilde{Y} & =\tilde{Z} \alpha_{z}+\tilde{E}  \tag{7}\\
\tilde{Z} & =\tilde{W} B_{w}+\tilde{V}, \tag{8}
\end{align*}
$$

[^2]i.e. where $\tilde{Y}$ denotes ${ }^{4} \mathcal{Q}_{X} Y$. Under $H_{A}: \mathbf{E}[\tilde{E} \mid \tilde{W}] \neq 0$, we can write (7) as
\[

$$
\begin{equation*}
\tilde{Y}=\tilde{Z} \alpha_{z}+\tilde{W} \kappa+\tilde{U}, \tag{9}
\end{equation*}
$$

\]

with $\mathbf{E}[\tilde{U} \mid \tilde{W}]=0$ by (6). Now, $I V$ of $\tilde{Y}$ on $\tilde{Z}$ using $\tilde{W}$ as instruments is identical to OLS of $\mathcal{P}_{\tilde{W}} \tilde{Y}$ on $\mathcal{P}_{\tilde{W}} \tilde{Z}$. To investigate its properties rewrite (9) as

$$
\mathcal{P}_{\tilde{W}} \tilde{Y}=\mathcal{P}_{\tilde{W}} \tilde{Z} \alpha_{z}+\mathcal{P}_{\tilde{W}} \tilde{W} \kappa+\mathcal{P}_{\tilde{W}} \tilde{U}
$$

Defining

$$
\begin{align*}
\hat{Z} & =\mathcal{P}_{\tilde{W}} \tilde{Z} \\
& =\tilde{W} \hat{B}_{w}, \tag{10}
\end{align*}
$$

where $\hat{B}_{w}=\left(\tilde{W}^{\prime} \tilde{W}\right)^{-1} \tilde{W}^{\prime} \tilde{Z}$ is the $O L S$ estimator of $B_{w}$, we have that

$$
\begin{aligned}
\mathcal{P}_{\tilde{W}} \tilde{Y} & =\mathcal{P}_{\tilde{W}} \tilde{Z} \alpha_{z}+\mathcal{P}_{\tilde{W}} \tilde{W} \kappa+\mathcal{P}_{\tilde{W}} \tilde{U} \\
& =\hat{\tilde{Z}} \alpha_{z}+\tilde{W} \kappa+\mathcal{P}_{\tilde{W}} \tilde{U} \\
& =\hat{\tilde{Z}} \alpha_{z}+\mathcal{P}_{\hat{\tilde{Z}}} \tilde{W} \kappa+\mathcal{Q}_{\hat{Z}} \tilde{W} \kappa+\mathcal{P}_{\tilde{W}} \tilde{U},
\end{aligned}
$$

where the first equality follows from (10) and the identity $\tilde{W}=\mathcal{P}_{\tilde{W}} \tilde{W}$ and the last equality follows from the identity $A=\mathcal{P}_{B} A+\mathcal{Q}_{B} A$, which holds for all conformable matrices $A$ and $B$. We have in general that $\mathcal{P}_{\hat{\tilde{Z}}} \tilde{W}=\hat{\tilde{Z}} \Lambda$ for some matrix $\Lambda \in \mathbb{R}^{L \times K_{2}}$ and, thus,

$$
\begin{equation*}
\mathcal{P}_{\tilde{W}} \tilde{Y}=\hat{\tilde{Z}}\left(\alpha_{z}+\Lambda \kappa\right)+\mathcal{Q}_{\hat{Z}} \tilde{W} \kappa+\mathcal{P}_{\tilde{W}} \tilde{U} . \tag{11}
\end{equation*}
$$

Now, $I V$ of $\tilde{Y}$ on $\tilde{Z}$ using $\tilde{W}$ as instruments, results in $\hat{\alpha}_{z ; I V}=\left(\hat{\tilde{Z}}^{\prime} \hat{\tilde{Z}}\right)^{-1}\left(\hat{\tilde{Z}}^{\prime} \mathcal{P}_{\tilde{W}} \tilde{Y}\right)$. Expression (11) informs us that

1. $\alpha_{z}$ is not identified unless $\Lambda=\mathbf{0}_{L \times K_{2}}$ or $\kappa=\mathbf{0}_{K_{2} \times 1}$.
2. $\mathcal{Q}_{\hat{Z}} \tilde{W} \kappa$ will be part of the residual, since $\hat{\tilde{Z}}^{\prime} \mathcal{Q}_{\hat{Z}} \tilde{W}=\mathbf{0}_{L \times K_{2}}$. Thus, unless $\mathcal{Q}_{\hat{Z}} \tilde{W} \kappa=$ $\mathbf{0}_{N \times 1}$, tests based on $\tilde{W}^{\prime} \hat{\tilde{E}}$, with $\hat{\tilde{E}}=\tilde{Y}-\tilde{Z} \hat{\alpha}_{z ; I V}$ the stacked $I V$ residuals, will pick up departures from $H_{0}$.

We will now determine under which conditions it holds that $\mathcal{Q}_{\hat{Z}} \tilde{W} \kappa=\mathbf{0}_{N \times 1}$, i.e. for which alternatives to $H_{0}$ the power of the over-identifying restrictions statistics (3) and (4) remains equal to their size.

- Given the definition (10), we have that $\mathcal{P}_{\hat{\tilde{Z}}} \tilde{W} \hat{B}_{w}=\mathcal{P}_{\hat{\tilde{Z}}} \hat{\tilde{Z}}=\hat{\tilde{Z}}=\tilde{W} \hat{B}_{w}$, which shows that the row space of $\mathcal{P}_{\hat{\tilde{Z}}}$ is given by $\tilde{W} \hat{B}_{w} \gamma$, with $\gamma \in \mathbb{R}^{L}$. Since the row space of $\mathcal{P}_{\hat{Z}}$ is identical to the null space of $\mathcal{Q}_{\hat{\tilde{Z}}}$, we have that

$$
\mathcal{Q}_{\hat{Z}} \tilde{W} \hat{B}_{w} \gamma=\mathbf{0}_{N \times 1} .
$$

[^3]- Conversely, the null space of $\mathcal{P}_{\hat{\tilde{Z}}}$ and, thus, the row space of $\mathcal{Q}_{\hat{Z}}$ consists of all $N \times 1$-vectors $D$ for which $\hat{\tilde{Z}}^{\prime} D=\hat{B}_{w}^{\prime} \tilde{W}^{\prime} D=\mathbf{0}_{L \times 1}$. Within this row space we are looking for linear combinations $\tilde{W} \kappa$ of the instruments $\tilde{W}$. Consequently, $K_{2} \times 1$ parameter vectors $\kappa$ satisfying $\hat{B}_{w}^{\prime} \tilde{W}^{\prime} \tilde{W} \kappa=\mathbf{0}_{L \times 1}$ generate linear combinations $\tilde{W} \kappa$ lying within the row space of $\mathcal{Q}_{\hat{Z}}$.

We now turn to the asymptotic distribution of the considered test statistics.

- In case $\kappa=\hat{B}_{w} \gamma$, equation (11) simplifies to

$$
\mathcal{P}_{\tilde{W}} \tilde{Y}=\hat{\tilde{Z}}\left(\alpha_{z}+\gamma\right)+\mathcal{P}_{\tilde{W}} \tilde{U}
$$

and the $I V$ residuals $\hat{\tilde{E}}=\tilde{Y}-\tilde{Z} \hat{\alpha}_{z ; I V}$ are asymptotically given by

$$
\begin{aligned}
\hat{\tilde{E}} & =\tilde{Z} \alpha_{z}+\hat{\tilde{Z}} \gamma+\tilde{U}-\tilde{Z} \hat{\alpha}_{z ; I V} \\
& \xrightarrow{p} \tilde{Z} \alpha_{z}+(\tilde{Z}-\tilde{V}) \gamma+\tilde{U}-\tilde{Z}\left(\alpha_{z}+\gamma\right) \\
& =\tilde{U}-\tilde{V} \gamma
\end{aligned}
$$

since $\hat{B}_{w} \xrightarrow{p} B_{w}$ and $\hat{\alpha}_{z ; I V} \xrightarrow{p} \alpha_{z}+\gamma$. As a consequence $N^{-\frac{1}{2}} \tilde{W}^{\prime} \hat{\tilde{E}} \xrightarrow{d} \mathcal{N}\left(\mathbf{0}_{K_{2} \times 1}, \Sigma_{I}\right)$, where $\Sigma_{I}=\operatorname{Var}\left[\tilde{w}\left(\tilde{u}-\tilde{v}^{\prime} \gamma\right)\right]$. Any test based on $\tilde{W}^{\prime} \hat{\tilde{E}}$, such as the Sargan-Hansen $J$-test (3) and the $L M$-test (4), will asymptotically have power equal to size against alternatives of the form $\tilde{E}=\left(\tilde{W} B_{w}\right) \gamma+\tilde{U}$. For the $L M$-test (4) the formal proof is given by Rao and Mitra (1971, Theorem 9.2.3, p.173), for the $J$-test the proof is given by Newey (1985, Theorem 1) ${ }^{5}$.

- Alternatively, if $B_{w}^{\prime} \tilde{W}^{\prime} \tilde{W} \kappa=\mathbf{0}_{L \times 1}{ }^{6}$, the $I V$ residuals $\hat{\tilde{E}}=\tilde{Y}-\tilde{Z} \hat{\alpha}_{z ; I V}$ are asymptotically given by $\hat{\tilde{E}}=\tilde{W} \kappa+\tilde{U}-\tilde{V} \Lambda \kappa$. Consequently, $N^{-\frac{1}{2}} \tilde{W}^{\prime} \hat{\tilde{E}} \xrightarrow{d} \mathcal{N}\left(\delta, \Sigma_{I I}\right)$, where $\Sigma_{\tilde{w}}=\operatorname{Var}[\tilde{w}], \delta=\sqrt{N} \Sigma_{\tilde{w}} \kappa$ and $\Sigma_{I I}=\operatorname{Var}\left[\tilde{w}\left(\tilde{w}^{\prime} \kappa+\tilde{u}-\tilde{v}^{\prime} \Lambda \kappa\right)\right]$. Following Rao and Mitra (1971, Theorem 9.2.3, p.173), we have that $L M \xrightarrow{d} \chi_{K_{2}-L}^{2}\left(\delta^{\prime} \Sigma_{I I}^{-1} \delta\right)$, which is in accordance with Newey (1985). This shows that alternatives $\tilde{W} \kappa$ for which $B_{w}^{\prime} \tilde{W}^{\prime} \tilde{W} \kappa=\mathbf{0}_{L \times 1}$, are detected by both tests with probability one, for $N \rightarrow \infty$, since non-centrality parameter $\delta^{\prime} \Sigma_{I I}^{-1} \delta \sim N$ (in Bachmann-Landau notation ${ }^{7}$ ).

The consequences of above Theorem are clear. For a model (1)-(2) with (5), the parameter subspace consisting of $\kappa=\hat{B}_{w} \gamma, \gamma \in \mathbb{R}^{L}$ has identical asymptotic distribution for each of the test statistics considered. In addition, in the complement of this subspace the $J$ and $L M$ test statistics have power going to one for $N \rightarrow \infty$. Reformulation of the null hypothesis as $G_{0}: \kappa=\hat{B}_{w} \gamma, \gamma \in \mathbb{R}^{L}$ thus results in a consistent test.

## 5. Discussion

[^4]Contrary to common formulations of over-identification tests, in the presence of $K_{2}>L$ instruments, it is possible to test against alternatives where all instruments are endogenous. However these tests are inconsistent when used for testing $H_{0}: \mathbf{E}[E \mid W]=\mathbf{0}_{N \times 1}$, in that they have no power against alternatives whereby the conditional mean of the disturbance $E$, given the instruments $W$ is identical to a linear combination of the conditional mean(s) of the endogenous regressor(s) $Z$, given the instruments.
To illustrate, consider a model with one single variable of interest $Z$. Alternatives of the form $\tilde{E}=\left(\tilde{W} B_{w}\right) c+\tilde{U}=\tilde{Z} c+\tilde{U}$, with $c$ any scalar, go undetected. When the (incorrectly) excluded instruments appear in the (structural) outcome equation in the same proportion as they appear in the reduced form for $Z$, this violation of $H_{0}$ goes undetected. In other words, we can not distinguish the effect of $\tilde{Z}$ on $\tilde{Y}$ from the effect of $\hat{\tilde{Z}}$ on $\tilde{Y}$. This is an example of the equivalence between (non-)testability and (non)identification (Dufour, 2003). All other departures from $H_{0}$, however, are testable. Consider some $K_{2} \times 1$ vector $\lambda$ for which $B_{w}^{\prime} \lambda=0$. It clearly holds that $\mathcal{P}_{\hat{Z}} \tilde{W} \lambda=0$ and thus $\mathcal{Q}_{\hat{\tilde{Z}}} \tilde{W} \lambda \neq 0$, since the null-space of $\mathcal{P}_{A}$ is equal to the row space of $\mathcal{Q}_{A}$, for any matrix $A$. This type of alternative is thus clearly testable, although all instruments are endogenous. The requirement that at least $L$ exogenous instruments are needed, for an over-identifying restriction test to work, thus seems to restrictive.
On the other hand, a priori assuming that $L$ instruments are valid, is one way to ensure that $\kappa$, having $L$ elements equal to zero, will never be equal to $B_{w} \gamma$. Interpreted this way, the inconsistency of the test is assumed away.

In contrast, I propose to formulate the different null $G_{0}: B_{w} \gamma=\mathbf{0}_{L \times 1}$. Remark that $H_{0} \subset G_{0}$. This extended null, in combination with the test statistics (3) and (4) results in a consistent test, as guaranteed by the above theorem.

The difference between both approaches can also be evaluated in terms of the dimensionality of the space over which is tested. The space spanned by the $K_{2}$ instruments can be represented by $\mathbb{R}^{K_{2}}$. Making over-identifying restrictions tests consistent by extra assumptions, reduces the space over which is tested to $\mathbb{R}^{K_{2}-L}$. However, changing the null from $H_{0}$ to $G_{0}$ leaves $\mathbb{R}^{K_{2}} \backslash \mathbb{R}^{L}$ alternatives testable, a clearly larger set. The validity of our claims will be checked empirically in the next section.

## 6. Monte Carlo

In this section the results of a small Monte Carlo study nicely illustrate the findings from previous sessions. The DGP consists of model (1)-(2)

$$
\begin{aligned}
Y & =X \alpha_{x}+Z \alpha_{z}+W \alpha_{w}+U \\
Z & =X \beta_{x}+W \beta_{w}+V
\end{aligned}
$$

with $\left(K_{1}, K_{2}, L\right)=(2,2,1)$. The variables $(x, w, u, v)^{\prime} \sim N I D\left(0 ; I_{6}\right) \beta_{x}=(1,1), \beta_{w}=$ $(1,1), \alpha_{x}=(1,1), \alpha_{z}=1, \alpha_{w}=\theta\left\{\phi \gamma_{w}+(1-\phi) \beta_{w}\right\}$, where $\gamma_{w}=(1,-1), \theta=0.1,0.2$ and $\phi=0,0.25,0.5,0.75,1$. The data were generated for the sample sizes $N=$ 100, 200, 500, 1000 and the number of Monte Carlo replications was 5000.

It is easy to verify that $\theta=0$ corresponds to $H_{0}$, the null that all instruments are exogenous. The null $G_{0}$ is given by $(\phi=0) \cup(\theta=0)$. The parameter $\theta$ can be interpreted

| $N$ | $\theta$ | 0 | 0.1 |  |  |  |  | 0.2 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\phi$ | / | 0 | 0.25 | 0.5 | 0.75 | 1 | 0 | 0.25 | 0.5 | 0.75 | 1 |
| $J$-statistic (3) |  |  |  |  |  |  |  |  |  |  |  |  |
| 100 |  | 0.0656 | 0.0660 | 0.0698 | 0.0992 | 0.1398 | 0.1936 | 0.0628 | 0.1044 | 0.2074 | 0.3494 | 0.5204 |
| 200 |  | 0.0574 | 0.0592 | 0.0734 | 0.1208 | 0.1966 | 0.2920 | 0.0586 | 0.1236 | 0.3168 | 0.5722 | 0.7978 |
| 500 |  | 0.0530 | 0.0508 | 0.0864 | 0.2096 | 0.3982 | 0.6024 | 0.0552 | 0.2236 | 0.6544 | 0.9302 | 0.9920 |
| 1000 |  | 0.0518 | 0.0532 | 0.1418 | 0.3658 | 0.6630 | 0.8896 | 0.0532 | 0.4050 | 0.9110 | 0.9986 | 1.0000 |
| $L M$-statistic (4) |  |  |  |  |  |  |  |  |  |  |  |  |
| 100 |  | 0.0562 | 0.0578 | 0.0622 | 0.0870 | 0.1270 | 0.1760 | 0.0554 | 0.0926 | 0.1890 | 0.3246 | 0.4956 |
| 200 |  | 0.0530 | 0.0544 | 0.0692 | 0.1138 | 0.1880 | 0.2794 | 0.0548 | 0.1168 | 0.3060 | 0.5624 | 0.7866 |
| 500 |  | 0.0514 | 0.0500 | 0.0844 | 0.2074 | 0.3938 | 0.5966 | 0.0542 | 0.2188 | 0.6494 | 0.9276 | 0.9918 |
| 1000 |  | 0.0512 | 0.0530 | 0.1406 | 0.3634 | 0.6608 | 0.8882 | 0.0522 | 0.4016 | 0.9104 | 0.9986 | 1.0000 |

Table 1: Rejection percentages of $H_{0}: \kappa=0$ for the different test statistics
as the degree to which $H_{0}$ is violated. Similarly, $\theta \phi$ constitutes a measure of the distance between the $D G P$ and $G_{0}$. According to the theorem above $D G P$ s for which $\theta=0$ will have power equal to size. $D G P \mathrm{~s}$ for which $\theta=1$, have $B_{w}^{\prime} \Sigma_{w} \kappa=\beta_{w}^{\prime} \kappa=0$, and have thus power going to one for $N \rightarrow \infty$. Intermediate values can be decomposed into an undetectable component and a detectable component, the latter having power going to one for $N \rightarrow \infty$.

In Table 1 the rejection percentages are given for both the $J$-statistic (3) and the $L M$ statistic (4). The table clearly shows that rejection percentages are very close to their nominal values for all parameter combinations that fall under $G_{0}$, with the $L M$-test staying slightly closer to its nominal size. In addition, for every column that falls under $G_{A}$, the power increases to one for increasing $N$. The difference between $J$ and $L M$ tests is again negligible.

## 7. Conclusion

In a way, above result is comforting. When the inconsistency of validity tests is interpreted as an a priori requirement of $L$ valid instruments (Stock, 2001), the seemingly insurmountable burden of proof rests on the scientist applying $I V$, who has to argue why these $L$ instruments are exogenous. However, the assumption that the excluded instruments $W$ do not appear in the outcome equation (1) in some linear combination of $B_{w}$ seems much easier to defend and the burden of proof seems to rest on the critic, who has to make the case why the instruments would appear in the outcome equation in exactly this linear combination.

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[^1]:    ${ }^{1}$ Throughout this note it is implicitly assumed that the instruments are not weak. See, for instance, Shea (1997) for a way to detect weak instruments.
    ${ }^{2}$ Under homoskedasticity, above $L M$ test is identical to Wooldridge's (1990) procedure to test for omitted variables in the outcome equation, where the variables under test here as being omitted are the excluded instruments.

[^2]:    ${ }^{3}$ This observation is well-known, see Newey (1985), for instance.

[^3]:    ${ }^{4}$ The projection operator $\mathcal{P}_{D}$ on any $N \times M$ matrix $D$ of rank $M$ is defined as $\mathcal{P}_{D}=D\left(D^{\prime} D\right)^{-1} D^{\prime}$. Its complement $\mathcal{Q}_{D}$ is given by $I_{N}-\mathcal{P}_{D}$. See Seber (2008) for the definition and properties of projection matrices.

[^4]:    ${ }^{5}$ This proof is valid for any $J$-test, not only for (3), which is only applicable under homoskedasticity of the errors.
    ${ }^{6}$ It holds that $\hat{B}_{w}^{\prime} \tilde{W}^{\prime} \tilde{W} \kappa \xrightarrow{p} B_{w}^{\prime} \Sigma_{\tilde{w}} \kappa$, where $\Sigma_{\tilde{w}}=\operatorname{Var}[\tilde{w}]$.
    ${ }^{7} x \sim y$ denotes that $\exists C \in \mathbb{R}: \lim _{N \rightarrow \infty} \frac{x}{y}=C$ (Knuth, 1976).

