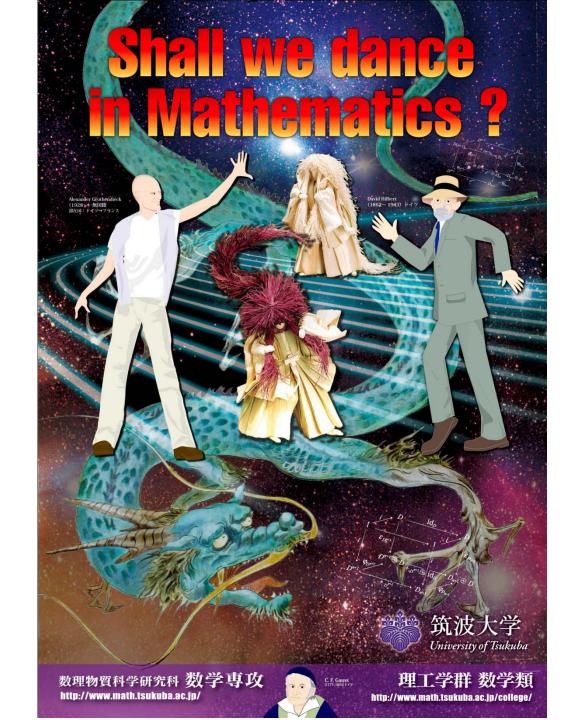


Differential Geometry of Microlinear Frolicher Spaces

著者	Nishimura Hirokazu			
内容記述	Algebra Geometry Mathematical Physics			
	(AGMP-7).University of Haute Alsace, Mulhouse,			
	France.24-26 October 2011			
year	2011-10			
URL	http://hdl.handle.net/2241/114523			



Differential Geometry of Microlinear Frölicher Spaces

Hirokazu Nishimura logic@math.tsukuba.ac.jp

Abstract:

Three distinct approaches to jet bundles are presented

1 Nilpotent Infinitesimals and Weil Algebras

$$D = D_1 = \{ d \in \mathbb{R} \mid d^2 = 0 \} \approx \mathbb{R}[X]/(X^2)$$
$$D_n = \{ d \in \mathbb{R} \mid d^{n+1} = 0 \} \approx \mathbb{R}[X]/(X^{n+1})$$

 $D(m)_n = \{ (d_1, ..., d_m) \in \mathbb{R}^m | d_{i_1} ... d_{i_{n+1}} = 0 \} \approx \mathbb{R}[X_1, ..., X_m] / (X_{i_1} ... X_{i_{n+1}})$

 $(i_1,...,i_{n+1} \mbox{ shall range over natural numbers between 1 and <math display="inline">m$ including both ends)

The category $\xrightarrow{\mathcal{D}}$ The category of Weil algebras $\xrightarrow{\mathcal{W}}$ of infinitesimal objects

$$\mathcal{D}_{\mathbb{R}[X]/(X^{n+1})} = D_n$$
$$\mathcal{W}_{D_n} = \mathbb{R}[X]/(X^{n+1})$$

Weil, André : Théorie des points proches sur les variétés différentiables,

Colloques Internationaux du Centre National de la Reserche Scientifique, Strassbourg, pp.111-117, 1953.

2 Synthetic Differential Geometry

 $\begin{array}{ccc} \text{Our Real World} & \xrightarrow{} & \text{V} \\ \text{of Mathematics} & \stackrel{}{\leftarrow} & \text{o} \end{array}$

 $\begin{array}{ll} \rightleftarrows & \text{Virtual World} \\ \overrightarrow{} & \text{of Mathematics} \end{array}$

the construction of Grothendieck topos

MacLane and Moerdijk : Sheaves in Geometry and Logic Universitext, Springer-Verlag, 1992

Real WorldVirtual Worldclassical logicintuitionistic logic $D = \{0\}$ $D \neq \{0\}$ manifoldsmicrolinear spacesMany non-smooth entities !Everything is smooth !::

Anders Kock : Synthetic Differential Geometry 2nd ed. London Mathematical Society Lecture Note Series **333** Cambridge University Press 2006

2.1 Differential Calculus

The Kock-Lawvere Axiom

$$(\forall f: D \to \mathbb{R}) \ (\exists ! a \in \mathbb{R}) \ (\forall d \in D) \ (f(d) = f(0) + ad)$$

More abstractly,

The canonical homomorphism $\mathbb{R}[X]/(X^2) \to \mathbb{R}^D$ of \mathbb{R} -algebras is an isomorphism.

Generally, The Generalized Kock-Lawvere Axiom

The canonical homomorphism $W \to \mathbb{R}^{\mathcal{D}_W}$ of \mathbb{R} -algebras is an isomorphism for any Weil algebra W.

2.2 Microlinear Spaces

Definition 1 A space M is microlinear iff $M^{\mathcal{D}_{\mathbb{L}}}$ is a limit diagram for any finite limit diagram \mathbb{L} in the category of Weil algebras.

Proposition 2 The space \mathbb{R} is microlinear.

Proof. By the generalized Kock-Lawvere axiom.

Proposition 3 Given a microlinear space M and $x \in M$, the space

$$\mathbf{T}_{x}M = \left(M^{D}\right)_{x} = \left\{t: D \to M \mid t(0) = x\right\}$$

is naturally an \mathbb{R} -module.

2.3 Vector Fields

Exponential Laws

$$\left(M^{\mathcal{D}}\right)^{M} = M^{\mathcal{D} \times M} = \left(M^{M}\right)^{\mathcal{D}}$$

1. The first viewpoint as a section of the tangent bundle:

 $X: M \to M^D$ with $X_x(0) = x$ for any $x \in M$.

2. The second viewpoint as an infinitesimal flow:

 $X: D \times M \to M$ with X(0, x) = x for any $x \in M$.

3. The third viewpoint as an infinitesimal transformation:

$$X: D \to M^M$$
 with $X_0 = \mathrm{id}_M$.

Theorem 4 The totality of vector fields on M forms a Lie algebra.

Addition

$$(X+Y)_d = X_d \circ Y_d = Y_d \circ X_d$$

for any $d \in D$. Scalar Multiplication

 $(\alpha X)_d = X_{\alpha d}$

for any $d \in D$ and any $\alpha \in \mathbb{R}$. <u>Lie Bracket</u> $[X, Y]_{d_1d_2} = Y_{-d_2} \circ X_{-d_1} \circ Y_{d_2} \circ X_{d_1}$

for any $d_1, d_2 \in D$.

3 Our Framework

Our General Framework

 $\pi: E \to M$

with microlinear spaces E, M.

4 The First Approach to Jet Bundles

- $\widetilde{\mathbf{J}}^n(\pi)$ non-holonomic jet bundle
- $\hat{\mathbf{J}}^{n}(\pi)$...semi-holonomic jet bundle
- $\mathbf{J}^{n}(\pi)$...holonomic jet bundle

Definition 5 We let

$$\begin{split} \mathbf{\bar{J}}^{0}(\pi) &= \mathbf{\hat{J}}^{0}(\pi) = \mathbf{J}^{0}(\pi) = E \\ \bar{\pi}_{0,0} &= \hat{\pi}_{0,0} = \pi_{0,0} = \mathrm{id}_{E} \\ \bar{\pi}_{0} &= \hat{\pi}_{0} = \pi_{0} = \pi \end{split}$$

 $\mathbf{\overline{J}}^1(\pi) = \mathbf{\overline{J}}^1(\pi) = \mathbf{J}^1(\pi)$ consists of $\nabla_x : (M^D)_{\pi(x)} \to (E^D)_x$ ($x \in E$) abiding by the following two conditions:

1.

$$\pi \circ \left(\nabla_{x} \left(t \right) \right) = t$$

for any $t \in (M^D)_{\pi(x)}$.

$$\nabla_{x}\left(\alpha t\right) = \alpha\left(\nabla_{x}\left(t\right)\right)$$

for any $t \in (M^D)_{\pi(x)}$ and any $\alpha \in \mathbb{R}$.

We define $\bar{\pi}_{1,0} = \hat{\pi}_{1,0} = \pi_{1,0}$: $\mathbf{J}^1(\pi) = \mathbf{J}^1(\pi) = \mathbf{J}^1(\pi) \to E$ to be the assignment of x to each $\nabla_x \in \mathbf{J}^1(\pi) = \mathbf{J}^1(\pi) = \mathbf{J}^1(\pi)$. We define $\bar{\pi}_1 = \hat{\pi}_1 = \pi_1 : \mathbf{J}^1(\pi) = \mathbf{J}^1(\pi) = \mathbf{J}^1(\pi) \to M$ to be $\pi \circ \pi_{1,0}$.

We proceed by induction on *n*. We are going to define $\bar{\mathbf{J}}^{n+1}(\pi)$, $\hat{\mathbf{J}}^{n+1}(\pi)$ and $\mathbf{J}^{n+1}(\pi)$ together with mappings $\bar{\pi}_{n+1,n} : \bar{\mathbf{J}}^{n+1}(\pi) \to \bar{\mathbf{J}}^n(\pi)$, $\hat{\pi}_{n+1,n} : \hat{\mathbf{J}}^{n+1}(\pi) \to \hat{\mathbf{J}}^n(\pi)$ and $\pi_{n+1,n} : \mathbf{J}^{n+1}(\pi) \to \mathbf{J}^n(\pi)$ by induction on $n \ge 1$. We let $\bar{\pi}_{k+1} = \bar{\pi}_k \circ \bar{\pi}_{k+1,k}$, $\hat{\pi}_{k+1} = \hat{\pi}_k \circ \pi_{k+1,k}$ and $\pi_{k+1} = \pi_k \circ \pi_{k+1,k}$.

Definition 6 We define $\overline{\mathbf{J}}^{n+1}(\pi)$ to be $\mathbf{J}^1(\overline{\pi}_k)$ with $\overline{\pi}_{k+1,k} = (\overline{\pi}_k)_{1,0}$.

Definition 7 We define $\hat{\mathbf{J}}^{n+1}(\pi)$ to be the subspace of $\mathbf{J}^1(\hat{\pi}_n)$ consisting of ∇_x 's with $x = \nabla_y \in \hat{\mathbf{J}}^n(\pi)$ subject to the following condition: The diagram

$$\begin{array}{ccc} & D \\ \nabla_x \left(t \right) \swarrow & & \searrow \nabla_y \left(t \right) \\ \hat{\mathbf{J}}^n (\pi) & \stackrel{\rightarrow}{\pi_{n,n-1}} & \hat{\mathbf{J}}^{n-1} (\pi) \end{array}$$

commutes for any $t \in (M^D)_{\hat{\pi}_n(x)}$.

Definition 8 We define $\mathbf{J}^{n+1}(\pi)$ to be the subspace of $\mathbf{J}^1(\pi_n)$ consisting of ∇_x 's with $x = \nabla_y \in \mathbf{J}^n(\pi)$ subject to the following two conditions:

1. The diagram

$$\begin{array}{ccc} & D \\ \nabla_x \left(t \right) \swarrow & & \searrow \nabla_y \left(t \right) \\ \mathbf{J}^n (\pi) & \stackrel{\rightarrow}{\pi_{n,n-1}} & \mathbf{J}^{n-1} (\pi) \end{array}$$

commutes for any $t \in (M^D)_{\pi_n(x)}$.

2. Given
$$\gamma \in (M^{D^2})_{\pi_n(x)}$$
 with $d_1, d_2 \in D$, we have
 $\nabla_z(\gamma(d_1, \cdot))(d_2) = \nabla_w(\gamma(\cdot, d_2))(d_1)$

with

$$z = \nabla_{y}(\gamma(\cdot, \mathbf{0}))(d_{1})$$
$$w = \nabla_{y}(\gamma(\mathbf{0}, \cdot))(d_{2})$$

Nishimura, Hirokazu : Holonomicity in sythetic differential geometry of jet bundles, Beiträge zur Algebra und Geometrie, 44 (2003), 471-481.

5 The Second Approach to Jet Bundles

We proceed by induction on n.

Definition 9 Let $\mathbb{J}^{D}(\pi) = \mathbf{J}^{1}(\pi)$

Definition 10 $\mathbb{J}^{D^{n+1}}$ consists of mappings $\nabla_x : (M^{D^{n+1}})_{\pi(x)} \to (E^{D^{n+1}})_x$ $(x \in E)$ subject to the following conditions:

1. Given
$$\gamma \in \left(M^{D^{n+1}}\right)_{\pi(x)}$$
, we have

$$\pi \circ (\nabla_x(\gamma)) = \gamma$$

2.

$$\nabla_x(\alpha \underset{i}{\cdot} \gamma) = \alpha \underset{i}{\cdot} \nabla_x(\gamma) \qquad (1 \le i \le n+1)$$

with

$$(\alpha_{i}, \gamma)(d_{1}, ..., d_{n+1}) = \gamma(d_{1}, ..., \alpha d_{i}, ..., d_{n+1})$$

8.

$$\nabla_{x} \left(\gamma^{\sigma} \right) = \left(\nabla_{x} \left(\gamma \right) \right)^{\sigma} \ \left(\sigma \in \mathbf{S}_{n+1} \right)$$

with

$$\gamma^{\sigma}\left(d_{1},...,d_{n+1}\right) = \gamma\left(d_{\sigma\left(1\right)},...,d_{\sigma\left(n+1\right)}\right)$$

4. We have $\pi_{n+1,n}(\nabla_x) \in \mathbb{J}^{D^n}$ with

$$\nabla_{x} \left((d_{1}, ..., d_{n+1}) \in D^{n+1} \longmapsto \gamma(d_{1}, ..., d_{n}) \right) \\= (d_{1}, ..., d_{n+1}) \in D^{n+1} \longmapsto \left((\pi_{n+1,n} \left(\nabla_{x} \right) \right) (\gamma)) (d_{1}, ..., d_{n})$$

for any $\gamma \in (M^{D^n})_{\pi(x)}$.

5. Given $\gamma \in (M^{D^n})_{\pi(x)}$, we have

$$\nabla_x((d_1, ..., d_{n+1}) \in D^{n+1} \longmapsto \gamma(d_1, ..., d_{n-1}, d_n d_{n+1})) = (d_1, ..., d_{n+1}) \in D^{n+1} \longmapsto ((\pi_{n+1, n}(\nabla_x))(\gamma))(d_1, ..., d_{n-1}, d_n d_{n+1})$$

Nishimura, Hirokazu : Higher-order preconnections in synthetic differential geometry of jet bundles, Beiträge zur Algebra und Geometrie, 45 (2004), 677-696.

6 The Third Approach to Jet Bundles

We proceed by induction on n.

Definition 11 $\mathbb{J}^{D_{n+1}}$ consists of mappings $\nabla_x : (M^{D_{n+1}})_{\pi(x)} \to (E^{D_{n+1}})_x$ $(x \in E)$ subject to the following conditions:

$$\pi \circ (\nabla_x(\gamma)) = \gamma$$

2.

1.

 $\nabla_x(\alpha\gamma) = \alpha\nabla_x(\gamma)$

with

$$(\alpha\gamma)(d) = \gamma(\alpha d)$$

3. We have $\pi_{n+1,n}(\nabla_x) \in \mathbb{J}^{D_n}$ with

$$\nabla_{x} \left(d \in D_{n+1} \longmapsto \gamma(dd') \right)$$

= $d \in D_{n+1} \longmapsto \left(\left(\pi_{n+1,n} \left(\nabla_{x} \right) \right) (\gamma) \right) (dd')$

for any
$$\gamma \in \left(M^{D^n}\right)_{\pi(x)}$$
 and any $d' \in D_n$

4. The other technical condition

Nishimura, Hirokazu : Synthetic differential geometry of higher-order total differentials, Cahiers de Topologie et Géométrie Différentielle Catégoriques, 47 (2006), 129-154 and 207-232.

7 From the First Approach to the Second Approach

Definition 12 Mappings $\varphi_0 : \mathbf{J}^0(\pi) \to \mathbb{J}^1(\pi)$ and $\mathbf{J}^1(\pi) \to \mathbb{J}^D(\pi)$ shall be the identity mappings. We are going to define $\varphi_n : \mathbf{J}^n(\pi) \to \mathbb{J}^{D^n}(\pi)$ for any natural number n by induction on n. Given $\nabla_x \in \mathbf{J}^{n+1}(\pi)$, we define $\varphi_{n+1}(\nabla_x) \in \mathbb{J}^{D^{n+1}}(\pi)$ to be

$$\begin{split} \varphi_{n+1}(\nabla_x)(\gamma)(d_1,...,d_{n+1}) \\ &= \varphi_n(\nabla_x(\gamma(0,...,0,\cdot))(d_{n+1}))(\gamma(\cdot,...,\cdot,d_{n+1}))(d_1,...,d_n) \end{split}$$

8 From the Second Approach to the Third Approach

Definition 13 Mappings $\varphi_0 : \mathbf{J}^0(\pi) \to \mathbb{J}^1(\pi)$ and $\mathbf{J}^1(\pi) \to \mathbb{J}^D(\pi)$ shall be the identity mappings. We are going to define $\psi_n : \mathbb{J}^{D^n}(\pi) \to \mathbb{J}^{D_n}(\pi)$ for any natural number n by induction on n. Given $\nabla_x \in \mathbb{J}^{D^{n+1}}(\pi)$, we have

$$\begin{aligned} \nabla_x((d_1,...,d_{n+1}) \in D^{n+1} \longmapsto \gamma(d_1+...+d_{n+1})) \\ &= (d_1,...,d_{n+1}) \in D^{n+1} \longmapsto \varphi_{n+1}(\nabla_x)(d_1+...+d_{n+1}) \end{aligned}$$

9 The Equivalence of the Three Approaches with Coordinates

9.1 <u>The Conventional Framework</u>

$$E = \mathbb{R}^{p+q}$$

 $M = \mathbb{R}^{p}$

with π being the canonical projection.

9.2 The Conventional Description

Definition 14 We denote by $\mathcal{J}^n(\pi)$ the totality of

 $\gamma \in E^{D(p)_n}$

such that $\pi \circ \gamma$ is constant.

Proposition 15 Each $\nabla \in \mathcal{J}^n(\pi)$ can be identified uniquely with a sequence

$$\left(x^{1},...,x^{p},u^{1},...,u^{q},u^{j}_{i_{1}},u^{j}_{i_{1},i_{2}},...,u^{j}_{i_{1},i_{2},...,i_{n}}\right)_{1\leq i_{1}\leq i_{2}\leq ...\leq i_{n}\leq p}$$

of real numbers at length

$$p+q+qp+\ldots+q_{p+n-1}C_n$$

in the sense that

$$\begin{split} (d_1, ..., d_p) &\in D(p)_n \mapsto \left(x^1, ..., x^p, u^1, ..., u^q\right) + \sum_{1 \leq i_1 \leq p} \left(0, ...0, u^1_{i_1}, ..., u^q_{i_1}\right) d_{i_1} \\ &+ \sum_{1 \leq i_1 \leq i_2 \leq p} \left(0, ...0, u^1_{i_1, i_2}, ..., u^q_{i_1, i_2}\right) d_{i_1} d_{i_2} + ... \\ &+ \sum_{1 \leq i_1 \leq i_2 \leq ... \leq i_n \leq p} \left(0, ...0, u^1_{i_1, i_2, ..., i_n}, ..., u^q_{i_1, i_2, ..., i_n}\right) d_{i_1} d_{i_2} ... d_{i_n} \\ &\in \mathbb{R}^{p+q} \end{split}$$

9.3 The First Approach with Coordinates

 $\text{Definition 16} \qquad 1. \ \text{We define } \theta_{\mathbf{J}^1(\pi)}^{\mathcal{J}^1(\pi)}: \mathcal{J}^1(\pi) \to \mathbf{J}^1(\pi) \text{ to be}$

$$\begin{split} \theta_{\mathbf{J}^{1}(\pi)}^{\mathcal{J}^{1}(\pi)} \left(x^{1}, ..., x^{p}, u^{1}, ..., u^{q}, u^{j}_{i}\right) \\ &= \left[d \in D \mapsto \left(x^{1}, ..., x^{p}\right) + \left(y^{1}, ..., y^{p}\right) d \in \mathbb{R}^{p}\right] \in \left(M^{D}\right)_{(x^{1}, ..., x^{p})} \mapsto \\ &\left[d \in D \mapsto \left(x^{1}, ..., x^{p}, u^{1}, ..., u^{q}\right) + \left(y^{1}, ..., y^{p}, \sum_{i=1}^{p} u^{j}_{i} y^{i}\right) d \in \mathbb{R}^{p+q}\right] \\ &\in \left(E^{D}\right)_{(x^{1}, ..., x^{p}, u^{1}, ..., u^{q})} \end{split}$$

2. Taking a step forward, we define $\theta_{\mathbf{J}^2(\pi)}^{\mathcal{J}^2(\pi)} : \mathcal{J}^2(\pi) \to \mathbf{J}^2(\pi)$ to be

$$\begin{split} \theta_{\mathbf{J}^{2}(\pi)}^{\mathcal{J}^{2}(\pi)} \left(x^{i}, u^{j}, u^{j}_{i_{1}}, u^{j}_{i_{1}, i_{2}} \right) \\ &= \left[d \in D \mapsto \left(x^{i} \right) + \left(y^{i} \right) d \in \mathbb{R}^{p} \right] \in \left(M^{D} \right)_{(x^{i})} \mapsto \\ \left[d \in D \mapsto \theta_{\mathbf{J}^{1}(\pi)}^{\mathcal{J}^{1}(\pi)} \left(\left(x^{i}, u^{j}, u^{j}_{i_{1}} \right) + \left(y^{i}, \sum_{i_{1}=1}^{p} u^{j}_{i_{1}} y^{i_{1}}, \sum_{i_{2}=1}^{p} u^{j}_{i_{1}, i_{2}} y^{i_{2}} \right) d \right) \in \mathbf{J}^{1}(\pi) \right] \\ &\in \left(\mathbf{J}^{1}(\pi)^{D} \right)_{\boldsymbol{\theta}_{\mathbf{J}^{1}(\pi)}^{\mathcal{J}^{1}(\pi)} \left(x^{i}, u^{j}, u^{j}_{i_{1}} \right)} \end{split}$$

3. Generally, proceeding by induction on n, we define $\theta_{\mathbf{J}^{n+1}(\pi)}^{\mathcal{J}^{n+1}(\pi)} : \mathcal{J}^{n+1}(\pi) \to \mathbf{J}^{n+1}(\pi)$ to be

$$\begin{split} \theta^{\mathcal{J}^{n+1}(\pi)}_{\mathbf{J}^{n+1}(\pi)} \begin{pmatrix} x^{i}, u^{j}, u^{j}_{i_{1}}, u^{j}_{i_{1}, i_{2}}, \dots, u^{j}_{i_{1}, i_{2}, \dots, i_{n+1}} \end{pmatrix} \\ &= \begin{bmatrix} d \in D \mapsto (x^{i}) + (y^{i}) d \in \mathbb{R}^{p} \end{bmatrix} \in (M^{D})_{(x^{i})} \mapsto \\ \begin{bmatrix} d \in D \mapsto \\ \theta^{\mathcal{J}^{n}(\pi)}_{\mathbf{J}^{n}(\pi)} \begin{pmatrix} (x^{i}, u^{j}, u^{j}_{i_{1}}, \dots, u^{j}_{i_{1}, i_{2}, \dots, i_{n}}) + \\ (y^{i}, \sum_{i_{1}=1}^{p} u^{j}_{i_{1}} y^{i_{1}}, \dots, \sum_{i_{n+1}=1}^{p} u^{j}_{i_{1}, i_{2}, \dots, i_{n+1}} y^{i_{n+1}}) d \end{bmatrix} \in \mathbf{J}^{n}(\pi) \end{bmatrix} \\ &\in (\mathbf{J}^{n}(\pi)^{D})_{\theta^{\mathcal{J}^{n}(\pi)}_{\mathbf{J}^{n}(\pi)}(x^{i}, u^{j}, u^{j}_{i_{1}}, \dots, u^{j}_{i_{1}, i_{2}, \dots, i_{n}})} \end{split}$$

Theorem 17 The mapping $\theta_{\mathbf{J}^n(\pi)}^{\mathcal{J}^n(\pi)} : \mathcal{J}^n(\pi) \to \mathbf{J}^n(\pi)$ is bijective.

9.4 The Second Approach with Coordinates

Definition 18 We define mappings $\theta_{\mathbb{J}^{D^n}(\pi)}^{\mathcal{J}^n(\pi)} : \mathcal{J}^n(\pi) \to \mathbb{J}^{D^n}(\pi)$ as $\varphi_n \circ \theta_{\mathbb{J}^n(\pi)}^{\mathcal{J}^n(\pi)}$.

Theorem 19 The mapping $\theta_{\mathbb{J}^{D^n}(\pi)}^{\mathcal{J}^n(\pi)}$ is bijective and is of the following description:

$$\begin{aligned} & \theta_{\mathbf{J}^{\mathcal{D}^{n}}(\pi)}^{\mathcal{T}^{n}(\pi)}(x^{i}, u^{j}, u^{j}_{i_{1}}, u^{j}_{i_{1}, i_{2}}, \dots, u^{j}_{i_{1}, i_{2}, \dots, i_{n}}) \\ & = \left[(\delta_{1}, \dots, \delta_{n}) \in \mathbb{R}^{n} \longmapsto (x^{i}) + \sum_{r=1}^{n} \sum_{1 \leq k_{1} < \dots < k_{r} \leq n} \delta_{k_{1}} \dots \delta_{k_{r}}(y^{i}_{k_{1}, \dots, k_{r}}) \in \mathbb{R}^{p} \right] \\ & \in (M \otimes \mathcal{W}_{D^{n}})_{(x^{i})} \mapsto \\ & \left[\begin{array}{c} (\delta_{1}, \dots, \delta_{n}) \in \mathbb{R}^{n} \longmapsto (x^{i}, u^{j}) + \\ \sum_{r=1}^{n} \sum_{1 \leq k_{1} < \dots < k_{r} \leq n} \delta_{k_{1}} \dots \delta_{k_{r}}(y^{i}_{k_{1}, \dots, k_{r}}, \sum \sum_{i_{1}=1}^{p} \dots \sum_{i_{s}=1}^{p} y^{i_{1}}_{\mathbf{J}_{1}} \dots y^{i_{s}}_{\mathbf{J}_{s}} u^{j}_{i_{1}, \dots, i_{s}}) \in \mathbb{R}^{p+q} \\ & \in (E \otimes \mathcal{W}_{D^{n}})_{(x^{i}, u^{j})} \end{aligned} \end{aligned}$$

where the completely undecorated \sum is taken over all partitions of the set $\{k_1, ..., k_r\}$ into nonempty subsets $\{J_1, ..., J_s\}$, and if $J = \{k_1, ..., k_t\}$ is a set of natural numbers with $k_1 < ... < k_t$, then y_J^i denotes $y_{k_1, ..., k_t}^i$.

9.5 The Third Approach with Coordinates

Definition 20 We define mappings $\theta_{\mathbb{J}^{D_n}(\pi)}^{\mathcal{J}^n(\pi)} : \mathcal{J}^n(\pi) \to \mathbb{J}_{D_n}(\pi)$ as $\psi_n \circ \theta_{\mathbb{J}^{D^n}(\pi)}^{\mathcal{J}^n(\pi)}$.

Theorem 21 The mapping $\theta_{\mathbb{J}^{D_n}(\pi)}^{\mathcal{J}^n(\pi)} : \mathcal{J}^n(\pi) \to \mathbb{J}_{D_n}(\pi)$ is bijective and is of the

following description:

$$\begin{split} \theta_{\mathbf{J}^{\mathcal{D}_{n}}(\pi)}^{\mathcal{D}^{n}(\pi)}(x^{i}, u^{j}, u^{j}_{i_{1}}, u^{j}_{i_{1}, i_{2}}, \dots, u^{j}_{i_{1}, i_{2}, \dots, i_{n}}) \\ &= \left[\delta \in \mathbb{R} \longmapsto (x^{i}) + \sum_{k=1}^{n} \frac{\delta^{k}}{k!}(y^{i}_{k}) \in \mathbb{R}^{p} \right] \in (M \otimes \mathcal{W}_{D_{n}})_{(x^{i})} \mapsto \\ &\left[\delta \in \mathbb{R} \longmapsto (x^{i}, u^{j}) + \sum_{k=1}^{n} \frac{\delta^{k}}{k!} \sum_{i_{1}=1}^{p} \dots \sum_{i_{r}=1}^{p} \left(y^{i}_{k}, u^{j}_{i_{1}, \dots, i_{r}} y^{i_{1}}_{k_{1}} \dots y^{i_{r}}_{k_{r}} \right) \in \mathbb{R}^{p+q} \right] \\ &\in (E \otimes \mathcal{W}_{D_{n}})_{(x^{i}, u^{j})} \end{split}$$

where the undecorated \sum is taken over all partitions of the positive integer k into positive integers $k_1, ..., k_r$ (so that $k = k_1 + ... + k_r$) with $1 \le k_1 \le ... \le k_r \le n$.

10 Frölicher Spaces

Theorem 22 The category of Frölicher spaces and smooth mappings is cartesian closed.

Theorem 23 The category of convenient vector spaces and smooth linear mappings is cartesian closed.

However

Remark 24 The category of smooth manifolds modelled after convenient vector spaces as local models and smooth mappings is by no means cartesian closed !!!

Alfred Frölicher and Anreas Kriegl : Linear Spaces and Differentiation Theory John Wiley and Sons 1988

11 Externalized Microlinearity

Weil prolongation

 $X \otimes W$ (X:Frölicher space, W:Weil algebra)

standing intuitively for

 $X^{\mathcal{D}_W}$

Weil exponentiability

Definition 25 A Frölicher space X is called Weil exponentiable if

$$(X \otimes (W_1 \otimes_{\infty} W_2))^Y = (X \otimes W_1)^Y \otimes W_2$$

holds naturally for any Frölicher space Y and any Weil algebras W1 and W2.

If Y = 1, $X \otimes (W_1 \otimes_{\infty} W_2) = (X \otimes W_1) \otimes W_2$

If $W_1 = \mathbb{R}$,

 $(X \otimes W_2)^Y = X^Y \otimes W_2$

Nishimura, Hirokazu : A muchlarger class of Frölicher spaces than that of convenient vector spaces may embed into the Cahiers topos, Far East Journal of Mathematical Sciences, **35**(2009), 211-223.

Microlinearity

Definition 26 A Frölicher space X is called <u>microlinear</u> providing that any finite limit diagram \mathbb{L} in the category of Weil algebras yields a limit diagram $X \otimes \mathbb{L}$ in the category of Frölicher spaces.

Theorem 27 Weil exponentiable and microlinear Frölicher spaces, together with smooth mappings among them, form a cartesian closed category

Nishimura, Hirokazu : Microlinearity in Frölicher spaces -beyond the regnant philosophy of manifolds-, International Journal of Pure and Applied Mathematics, 60 (2010), 15-24.

Thank you for your attention!