

# **In-process Strain Measurement in Roll Forming**

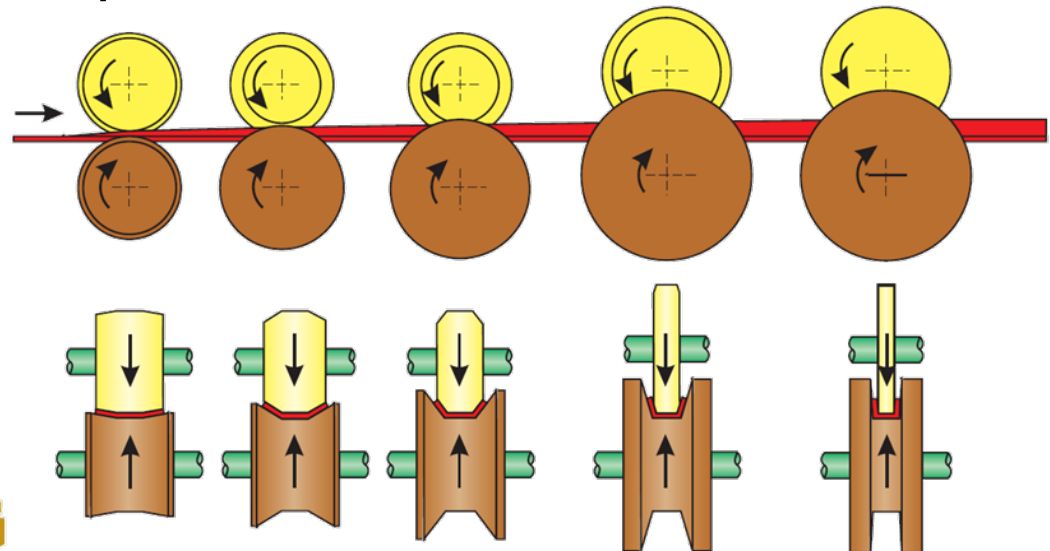
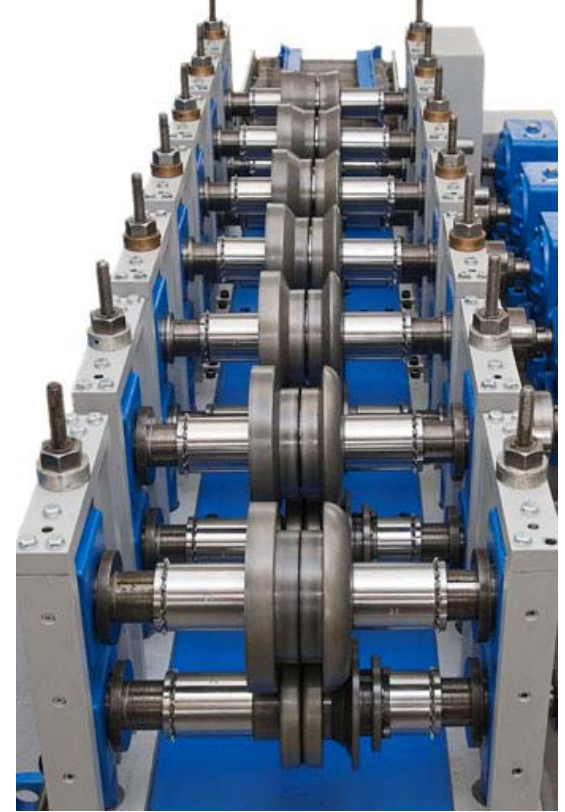
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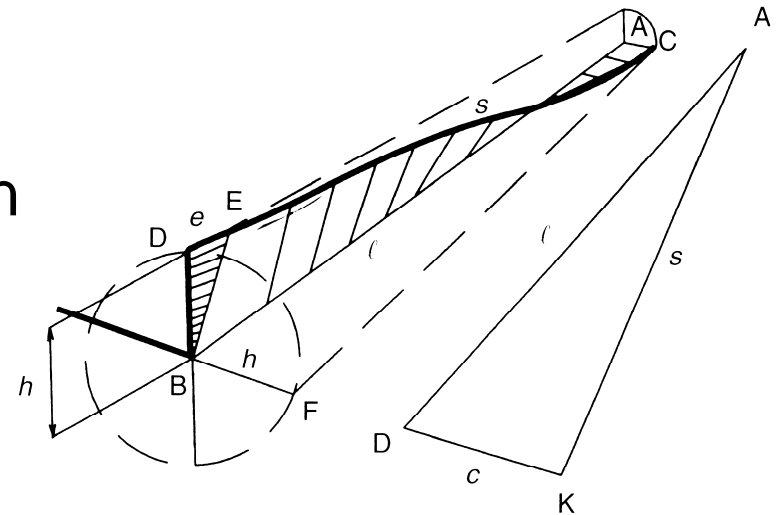
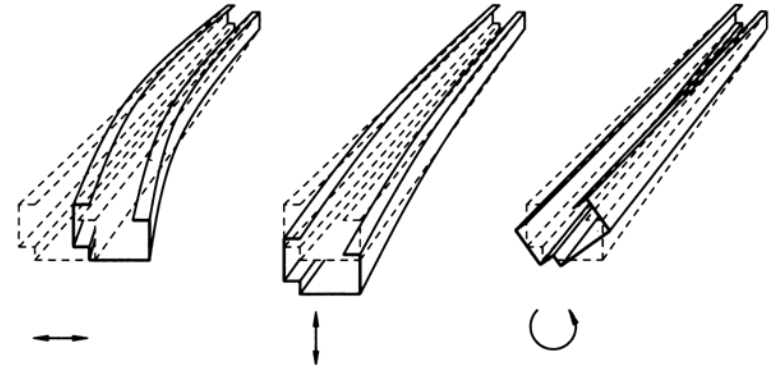
# Roll Forming

- Bending process
- Angle introduced continuously along straight line
- Set of contoured rolls
- Strip motion applied by rotation of rolls (friction)
- Alternatively, pulling of strip
- Unlimited length



# Motivation

- Geometric defects a frequent occurrence in roll forming
  - Largely caused by plastic deformation outside the intended forming zone
  - Verification of FEA-simulation of the process
- ➔ Continuous, non-contact strain measurement in flange area

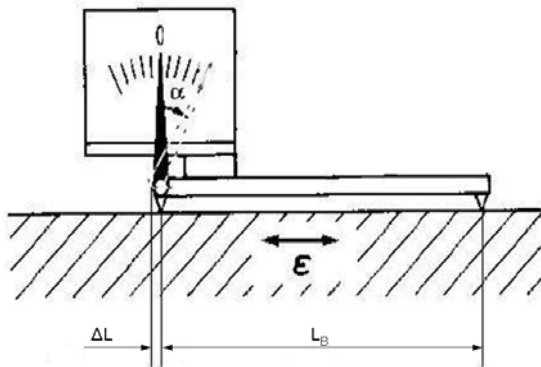


Source: Halmos

# Strain Measurement Methods I

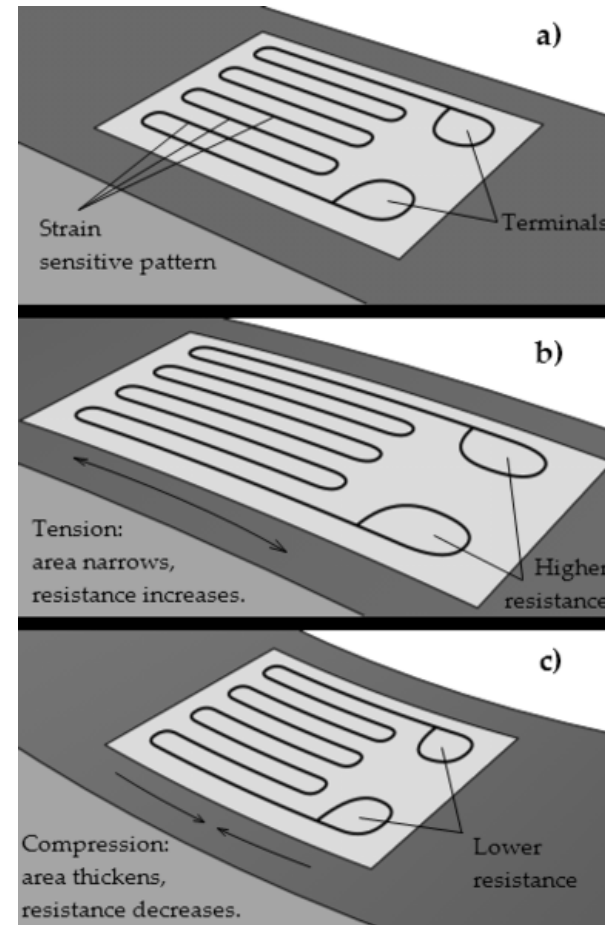
Mechanical

Strain Gauge



Source: Ferber

Mechanic longitudinal strain device

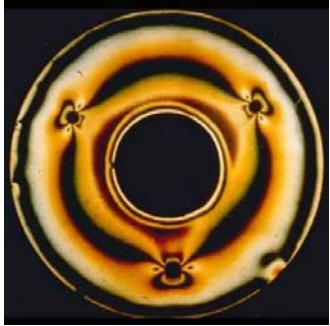


Source: Wikipedia

Electric conductor changes resistance when being compressed or elongated

# Strain Measurement Methods II

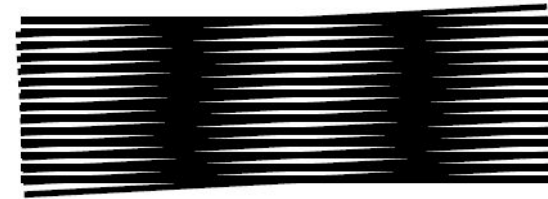
## Photoelasticity



Source: Onera

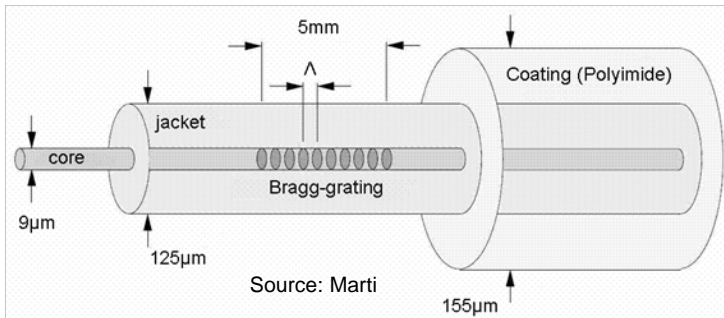
iso-chromatic and isoclinic lines in a specimen under load

## Moiré Pattern



Moiré effect of two rotated superimposed line pattern

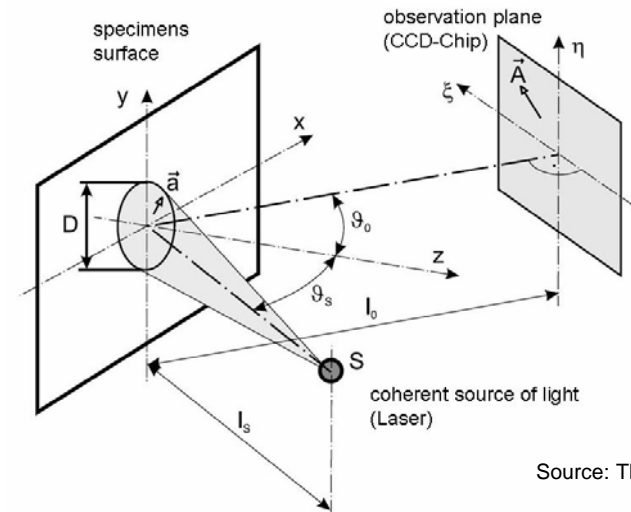
## Fibre Bragg Grating



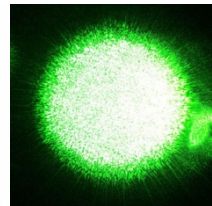
Source: Marti

$$\Delta\varepsilon = \frac{1}{1 - p_e} \cdot \left( \frac{\Delta\lambda_B}{\lambda_B} - (\alpha - \zeta) \cdot \Delta T \right)$$

## Laser Speckle



Source: Thurner



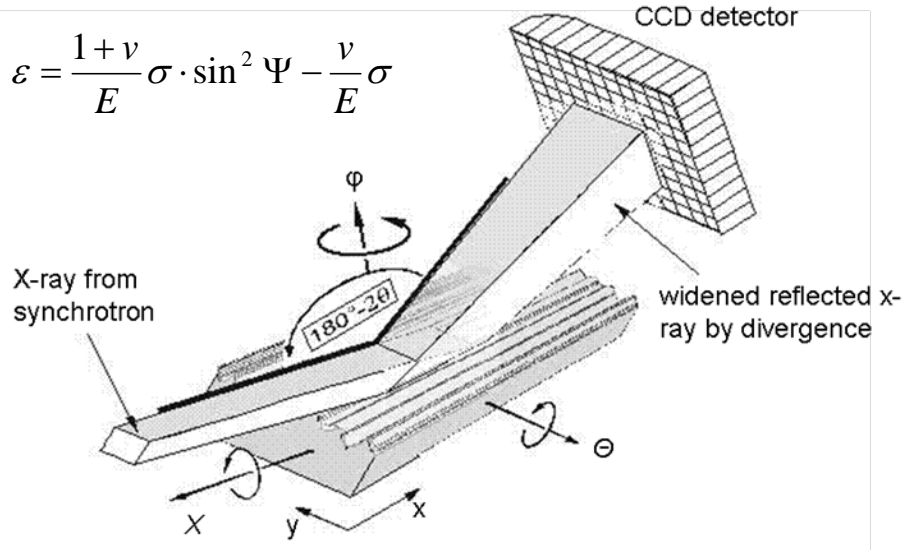
Source: Wikipedia

Principle geometry for strain measurement with objective Speckles

# Strain Measurement Methods IV

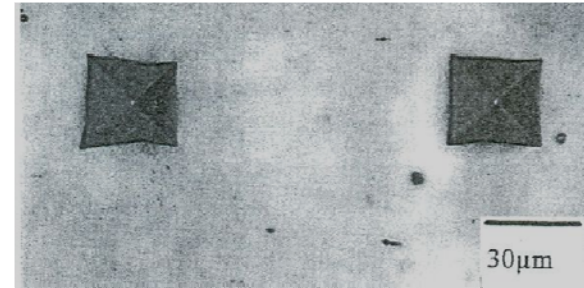
X-ray Diffraction

Optical



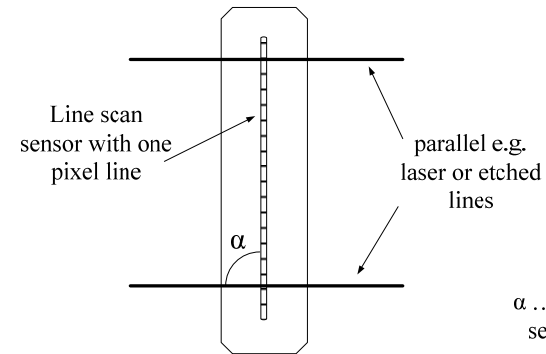
Source: Tönshoff

Set-up to measure strain in the surface zone of a specimen



Source: Ziebs

Vickers micro hardness indentations



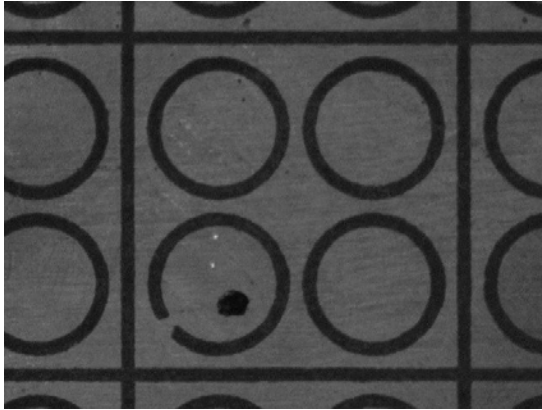
$\alpha$  ... angle between sensor and mark

Line camera

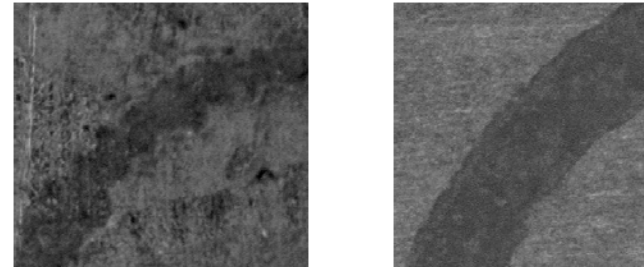


# Strain Measurement Methods IV

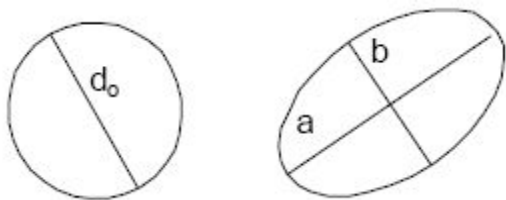
## Grid Analysis



Undeformed  $\varnothing$  2.5mm laser grids with straight laser lines



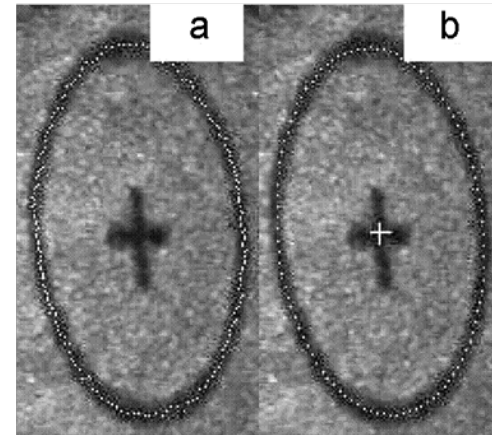
Etched (left) and laser (right) grids shown at 50x magnification, circle radius of 2.5mm



Deformation of a circle grid

$$e_{major} (\%) = \frac{a - d_0}{d_0} \times 100$$

$$e_{minor} (\%) = \frac{b - d_0}{d_0} \times 100$$



Source: Hsu

Fitted ellipses

- a: automatic grid acquisition
- b: elliptic grid for a MRA

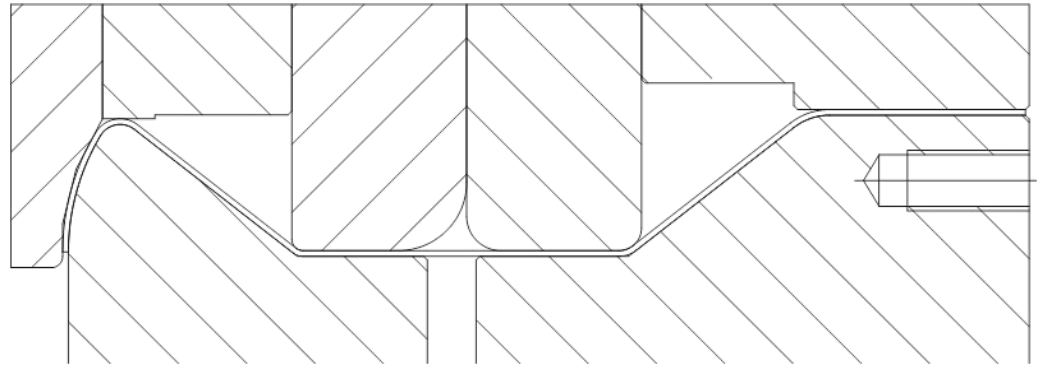
# Strain Measurement - Conclusions

Balance between accuracy and cost

Compromise: Strain gauge

laborious preparation, but:

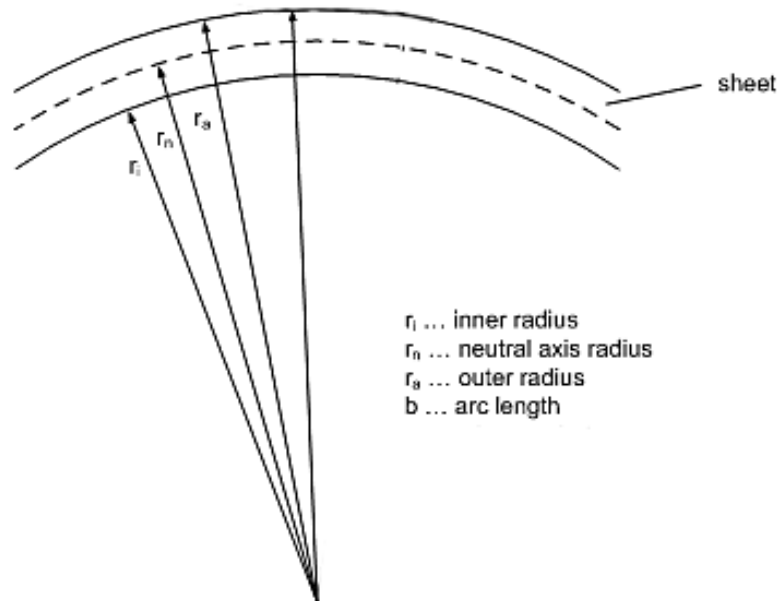
- continuous data
- inexpensive (in comparison)
- well established
- accurate (compared to other inexpensive solutions)
- delivers full set of data (3 directions)



Problem: How to acquire bending strain with one side of the strip inaccessible?

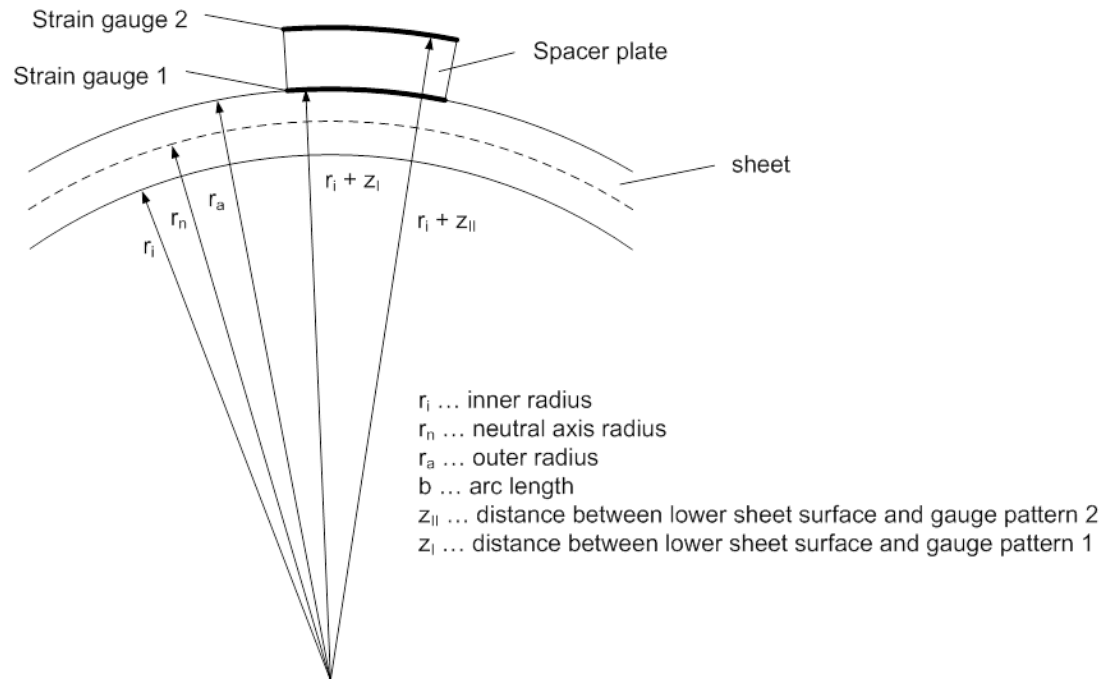


# Spacer Plate – Principle I



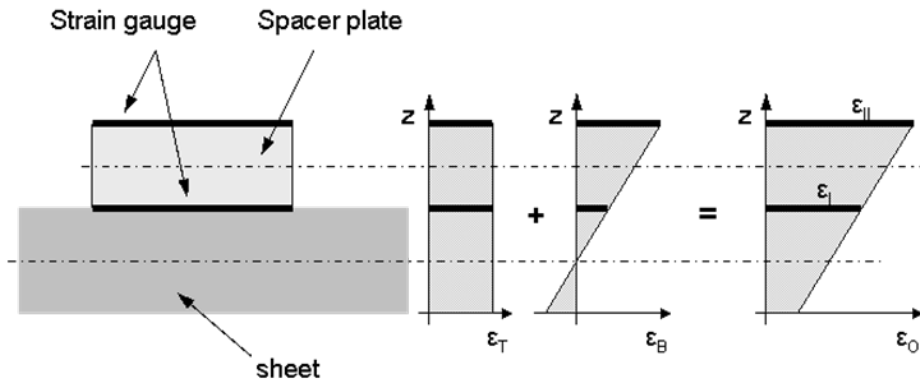
$$\varepsilon_O(z) = z \left( \frac{\varepsilon_{II} - \varepsilon_I}{z_{II} - z_I} \right) + \left( \varepsilon_I - z_I \frac{\varepsilon_{II} - \varepsilon_I}{z_{II} - z_I} \right)$$

# Spacer Plate – Principle I



$$\varepsilon_O(z) = z \left( \frac{\varepsilon_{II} - \varepsilon_I}{z_{II} - z_I} \right) + \left( \varepsilon_I - z_I \frac{\varepsilon_{II} - \varepsilon_I}{z_{II} - z_I} \right)$$

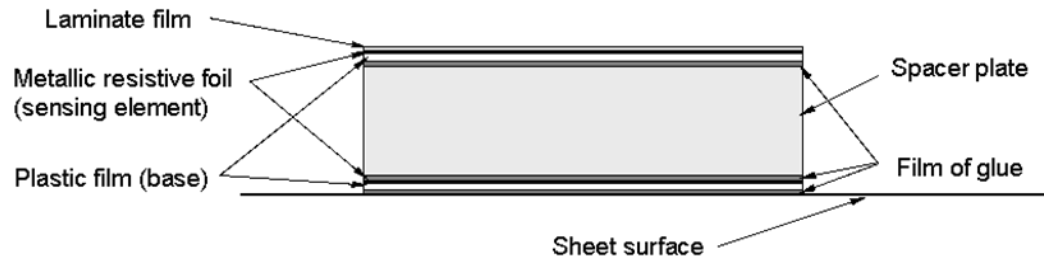
# Spacer Plate – Principle II



$\epsilon_{II}$  ... strain of the gauge on the top of the spacer plate  
 $\epsilon_I$  ... strain of the gauge between sheet and spacer plate

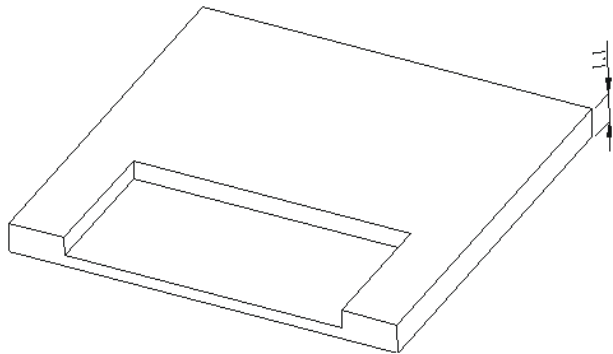
$\epsilon_T$  ... tensile strain  
 $\epsilon_B$  ... bending strain  
 $\epsilon_0$  ... tensile + bending strain

Trend of the strain in a cross-section of sheet and spacer plate

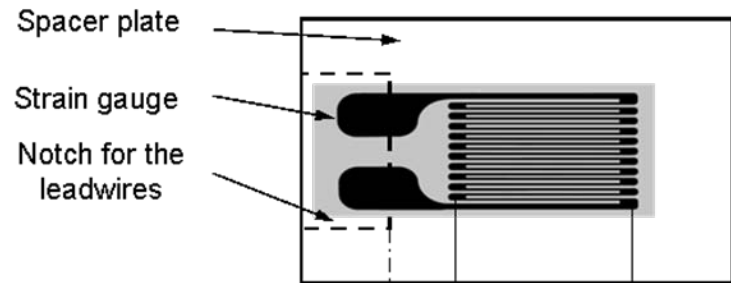
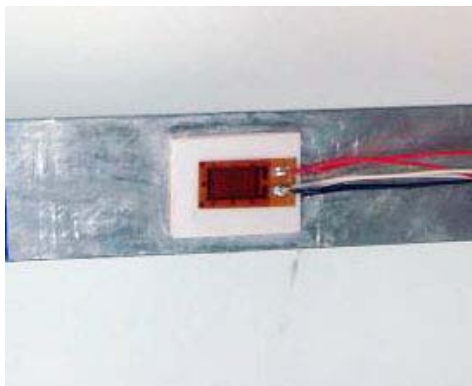


Strain measurement from one side of the sheet

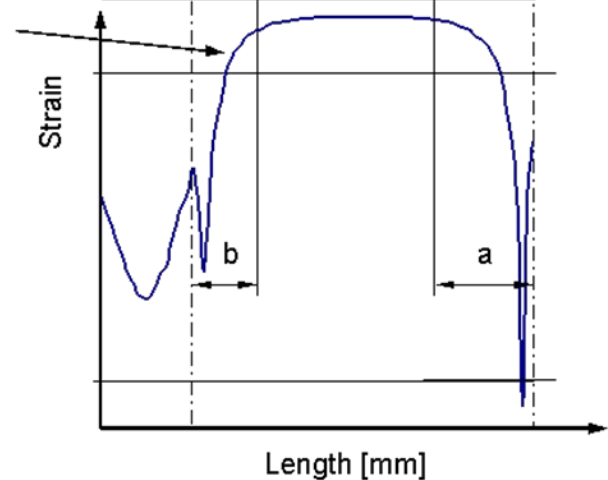
# Design of Spacer Plate



ABS spacer plate



Strain curve over the length, on topside of the spacer plate

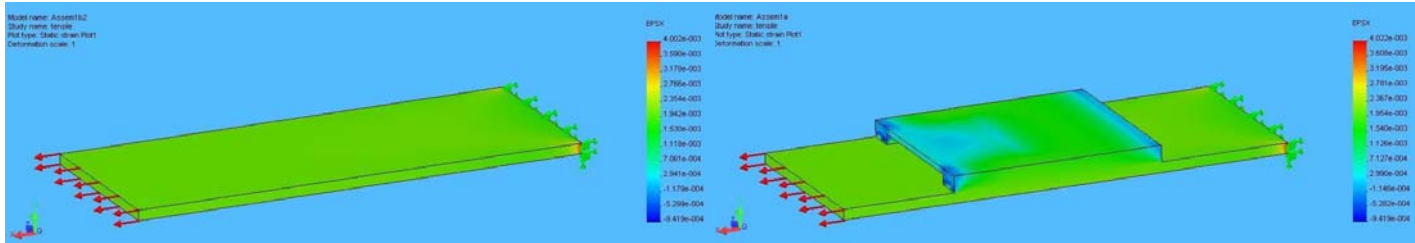


a... distance between gauge pattern and edge of spacer plate

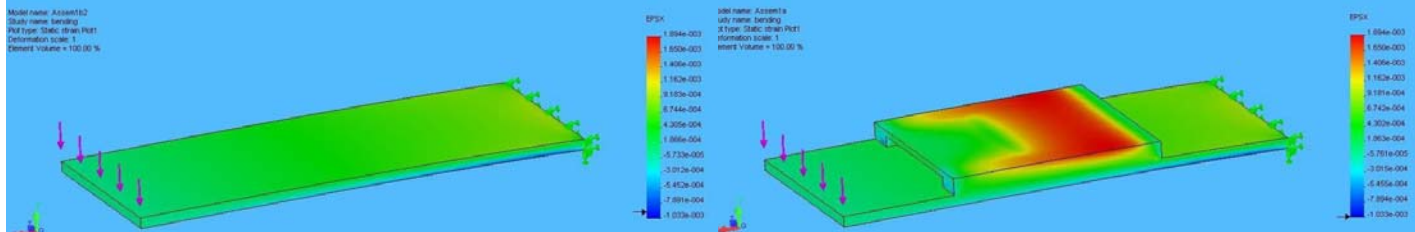
b... distance between gauge pattern and notch edge of spacer plate

# Simulation of Spacer Plate I

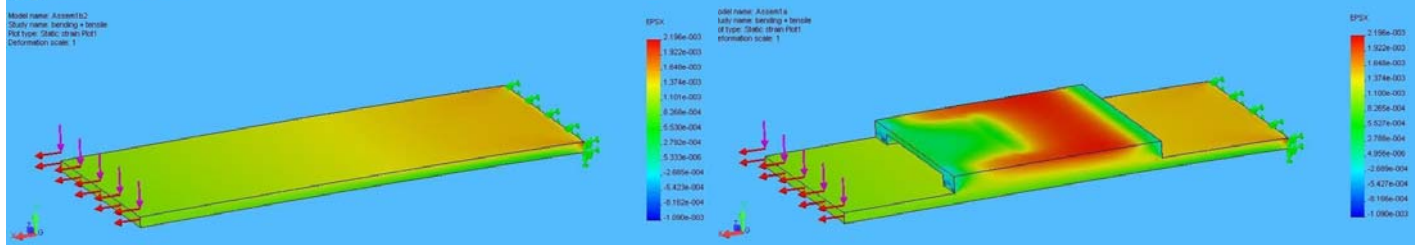
tensile



bending

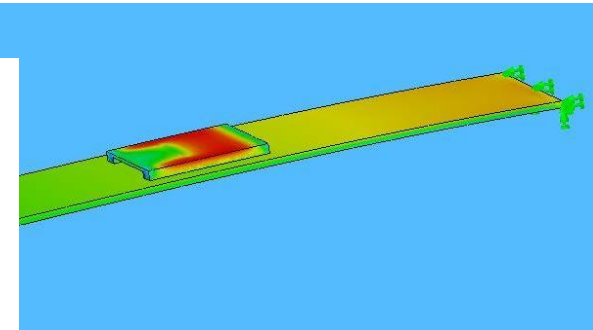
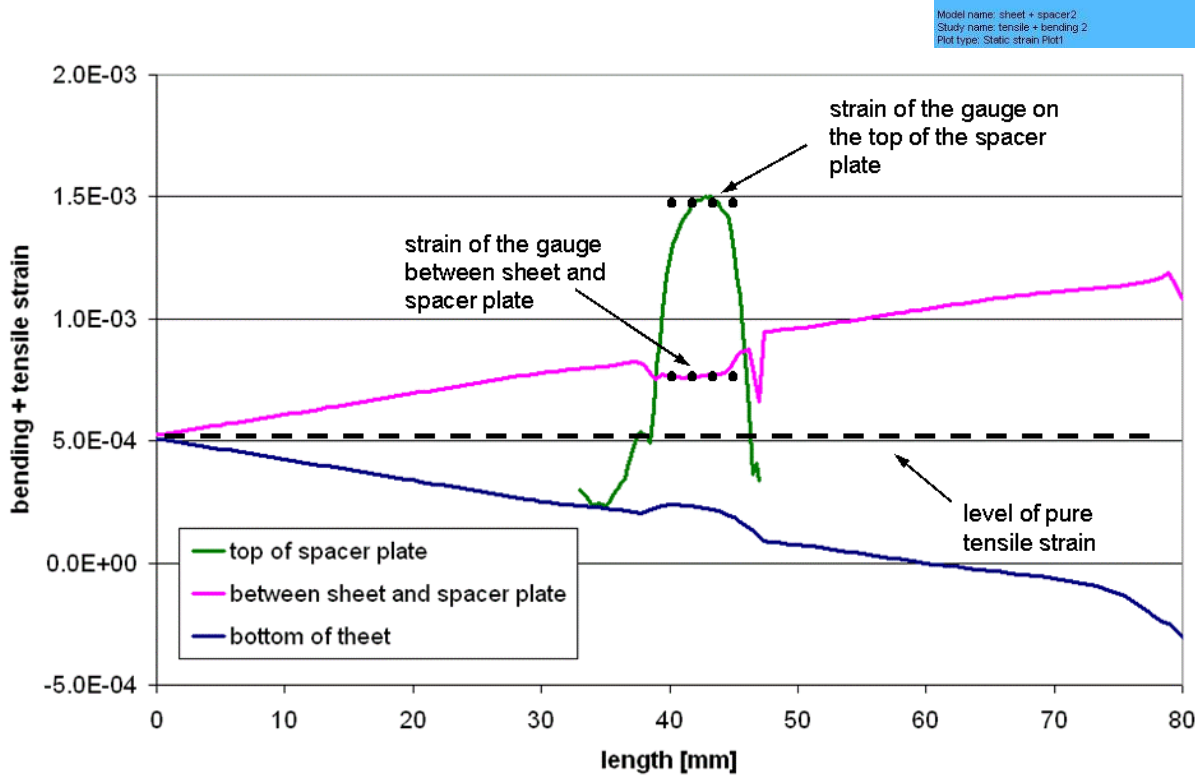


tensile +  
bending



Simulation of the strain layout during deformation with and without applied spacer plate on the sheet

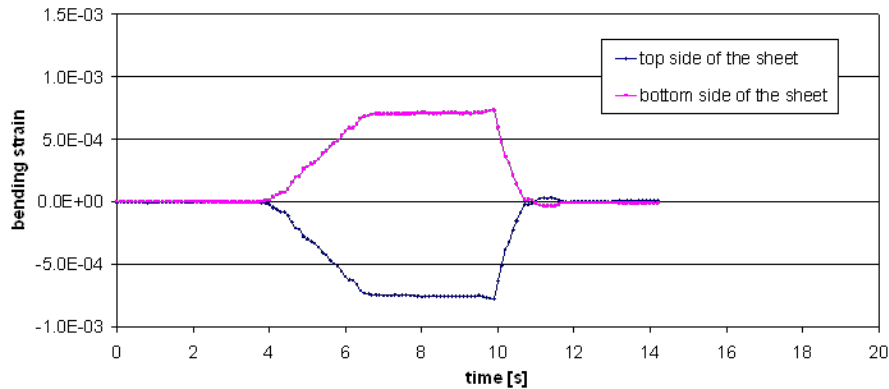
# Simulation of Spacer Plate II



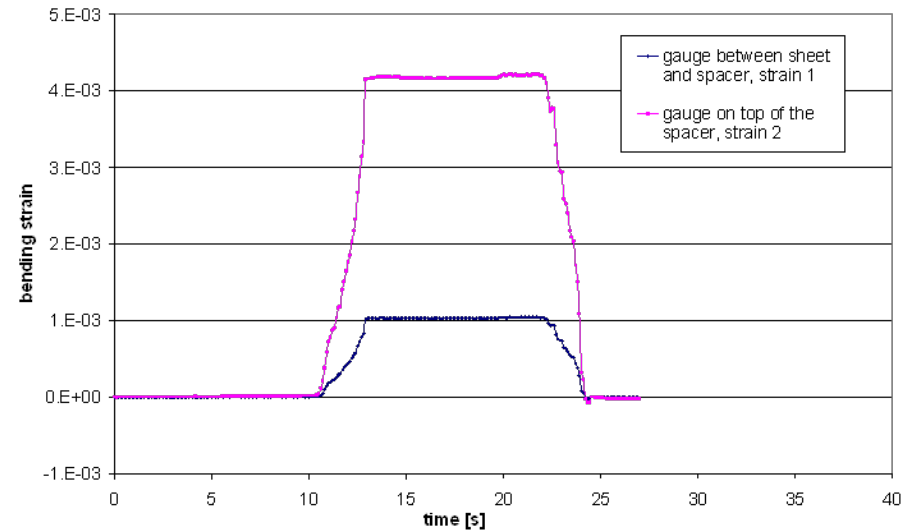
Strain in x direction (xy-plane, centre)  
3.5N shear force, 1625N tensile force,  
14mm long spacer plate



# Accuracy of Measurement



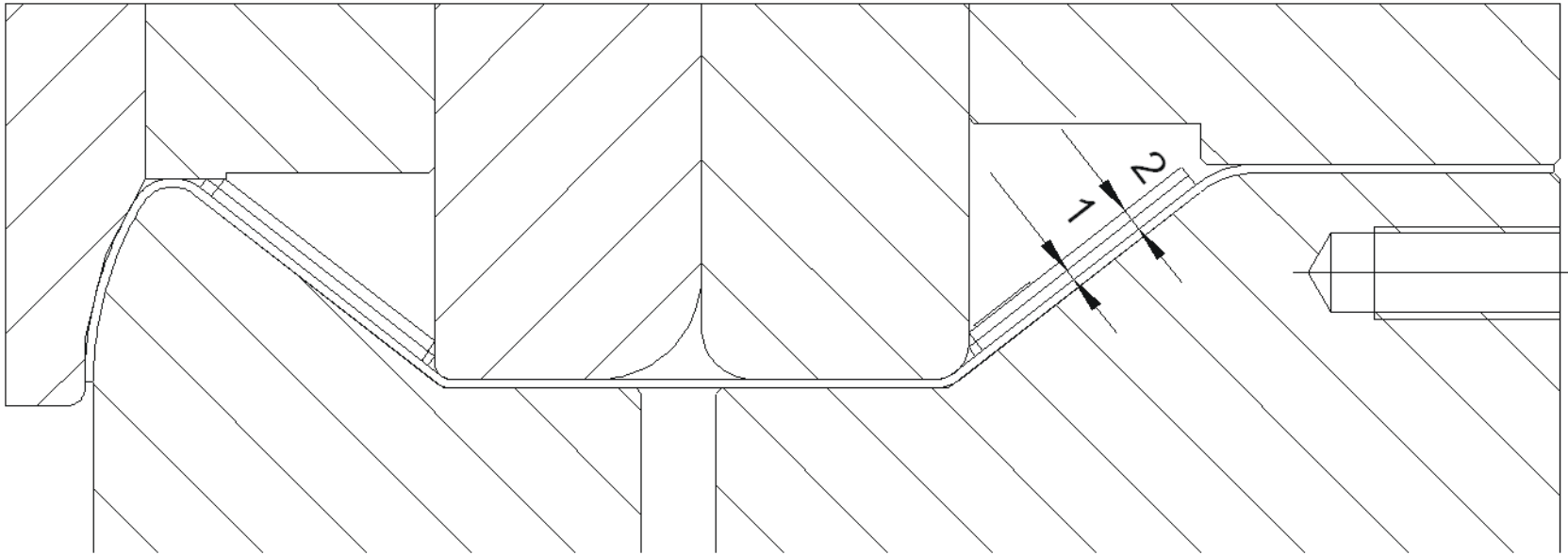
Bending, one strain gauge on each side



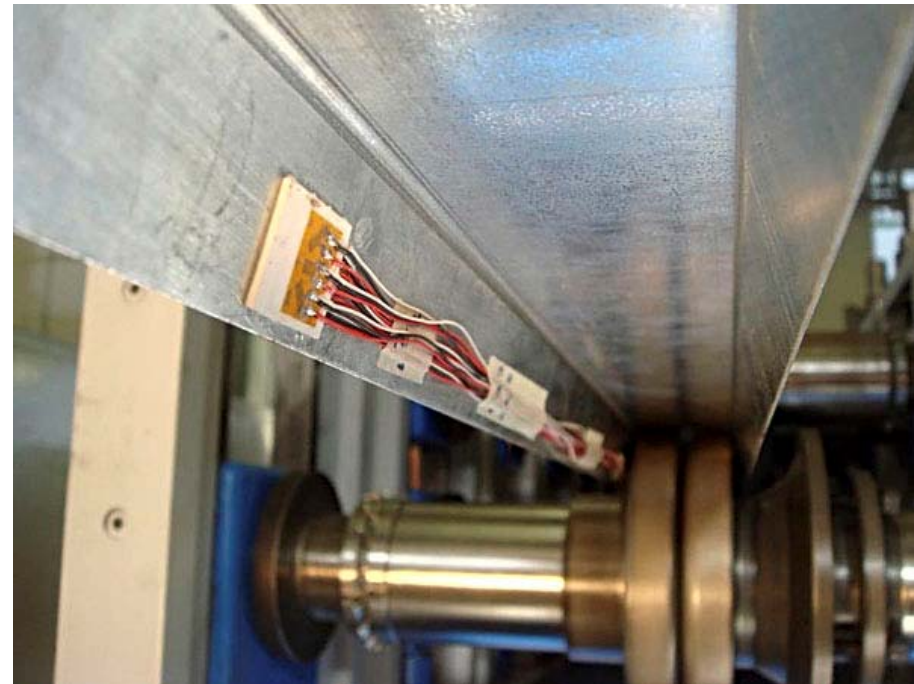
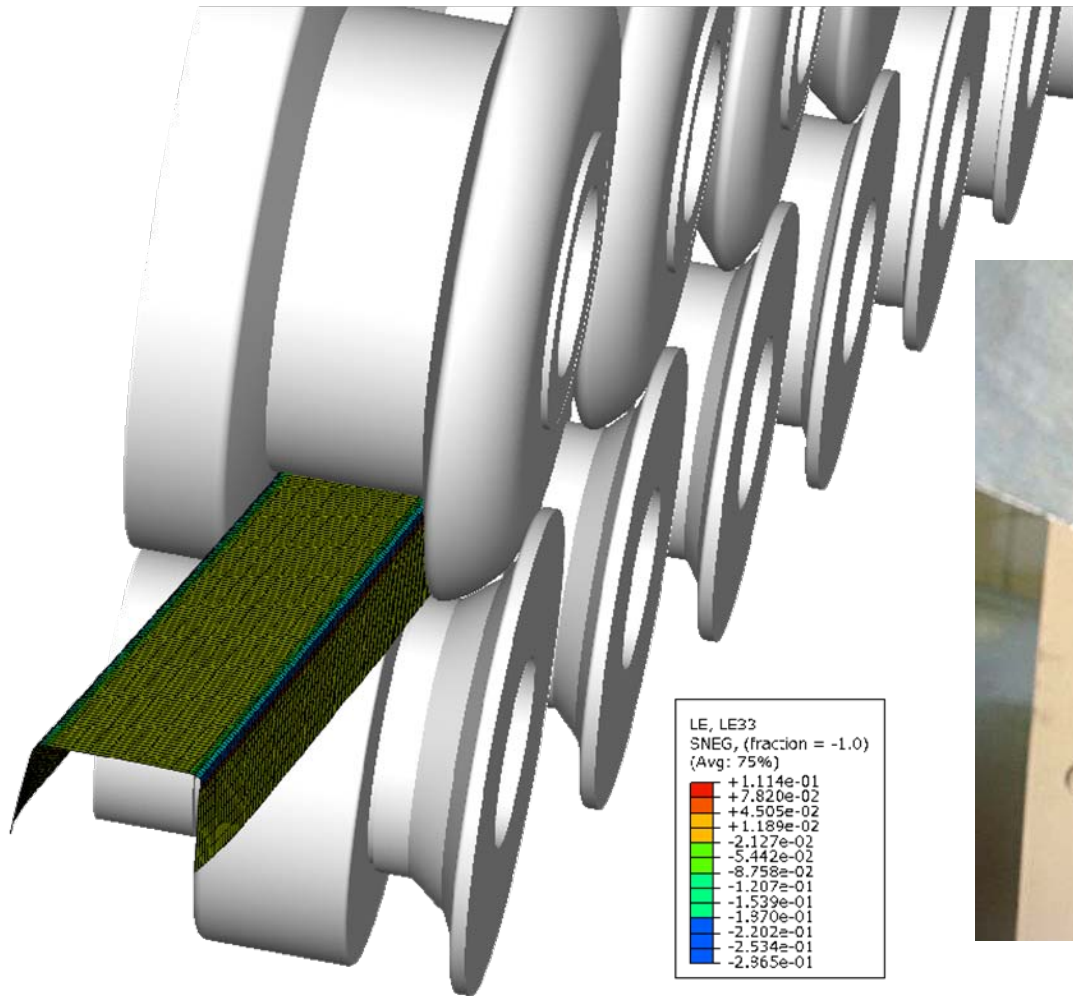
Bending, two strain gauges and spacer plate on one side of the specimen

Bending strain can be measured with accuracy of  $\pm 3\%$

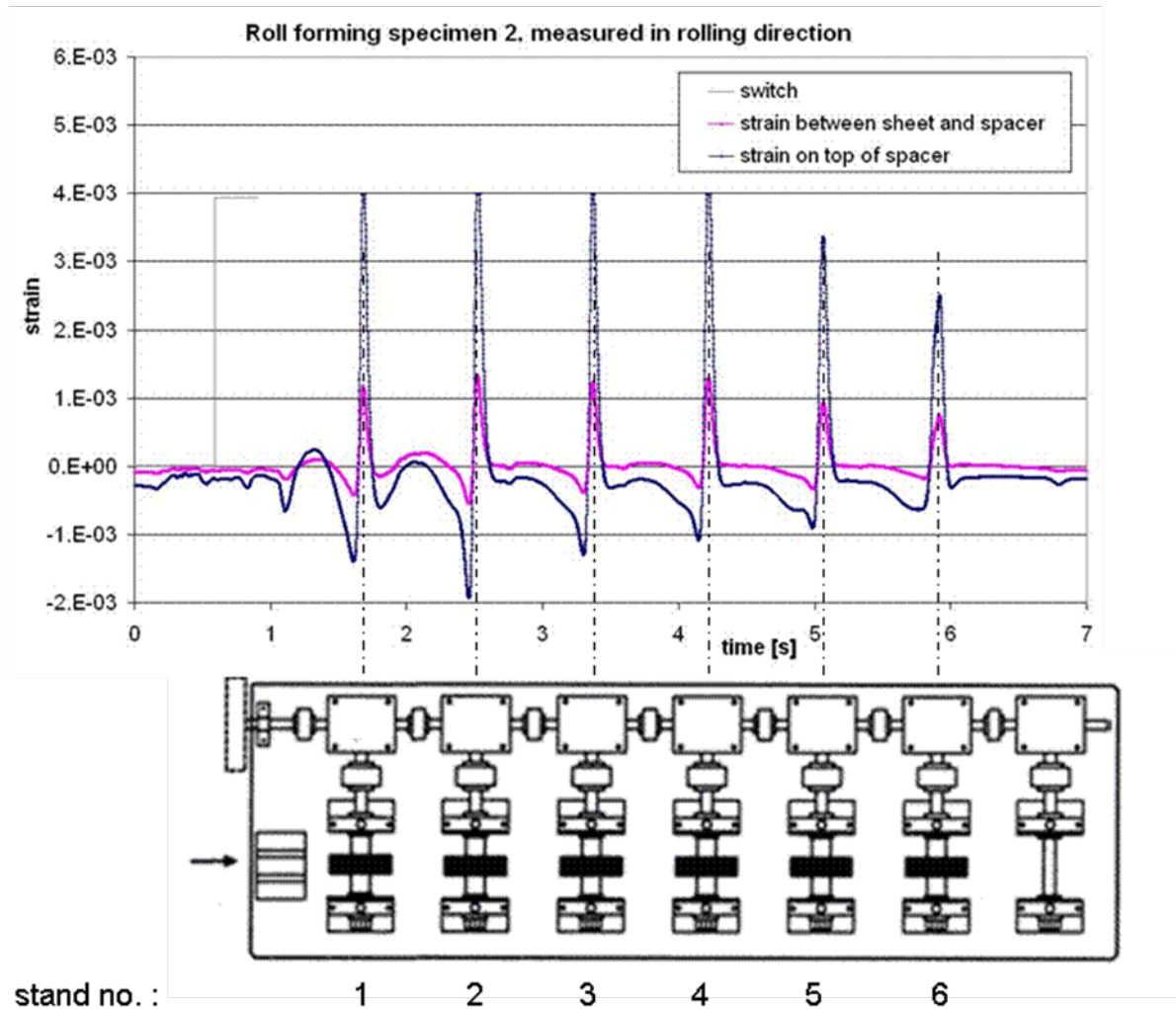
# Spatial Constraints in Roll Former



# Application of strain gauge device

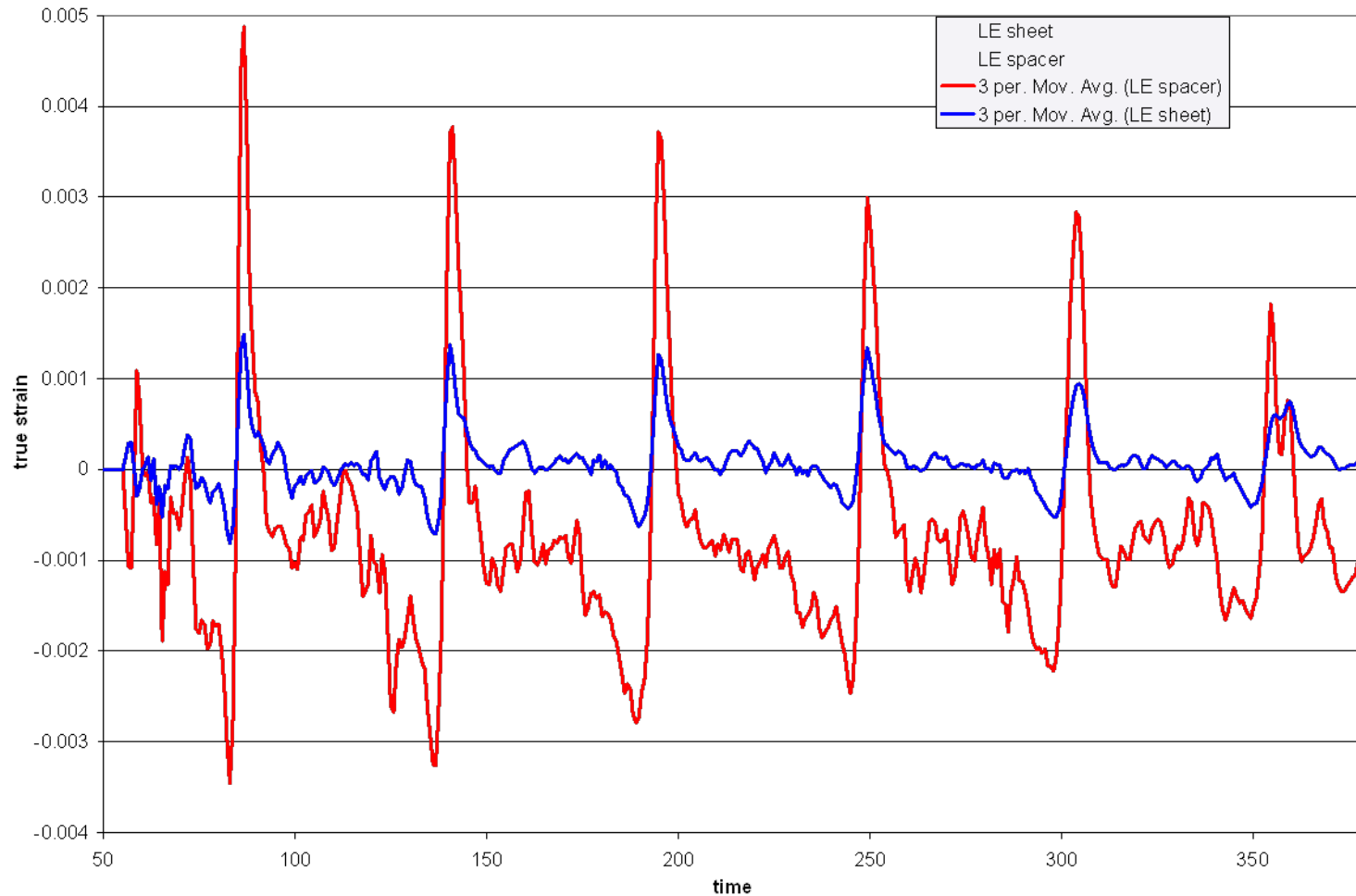


# Measured Longitudinal Strain



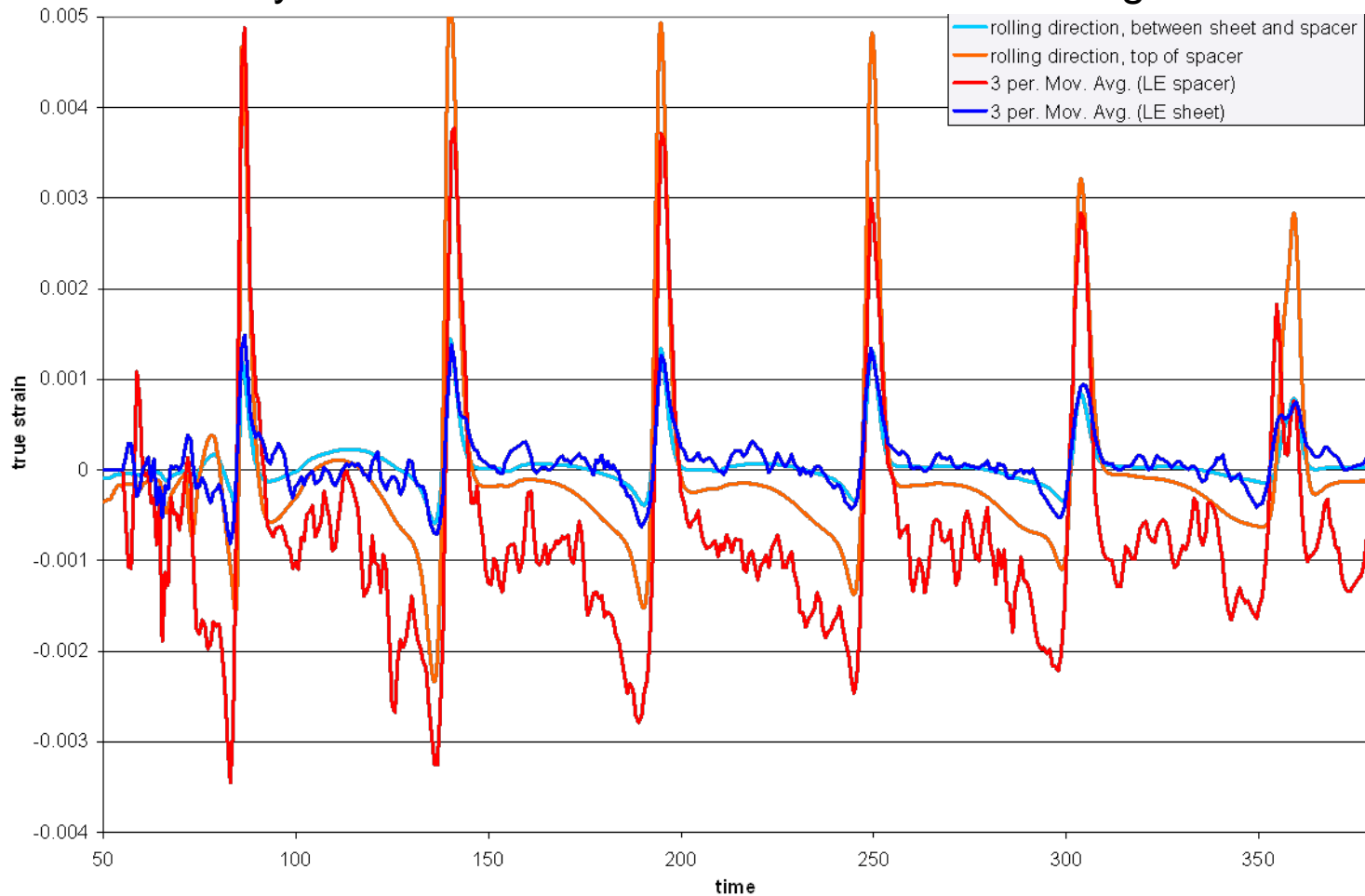
# Simulated Longitudinal Strain

Simulated flange strain in rolling direction



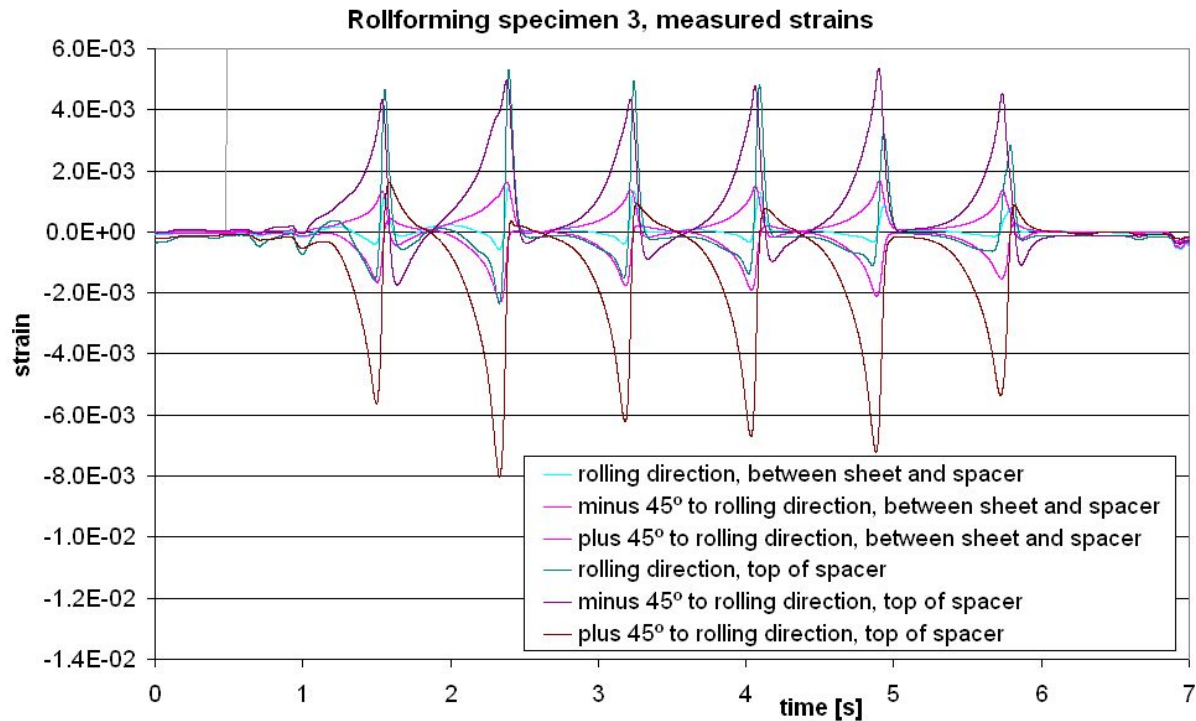
# Longitudinal Strain

Overlay of simulated and measured strain in rolling direction





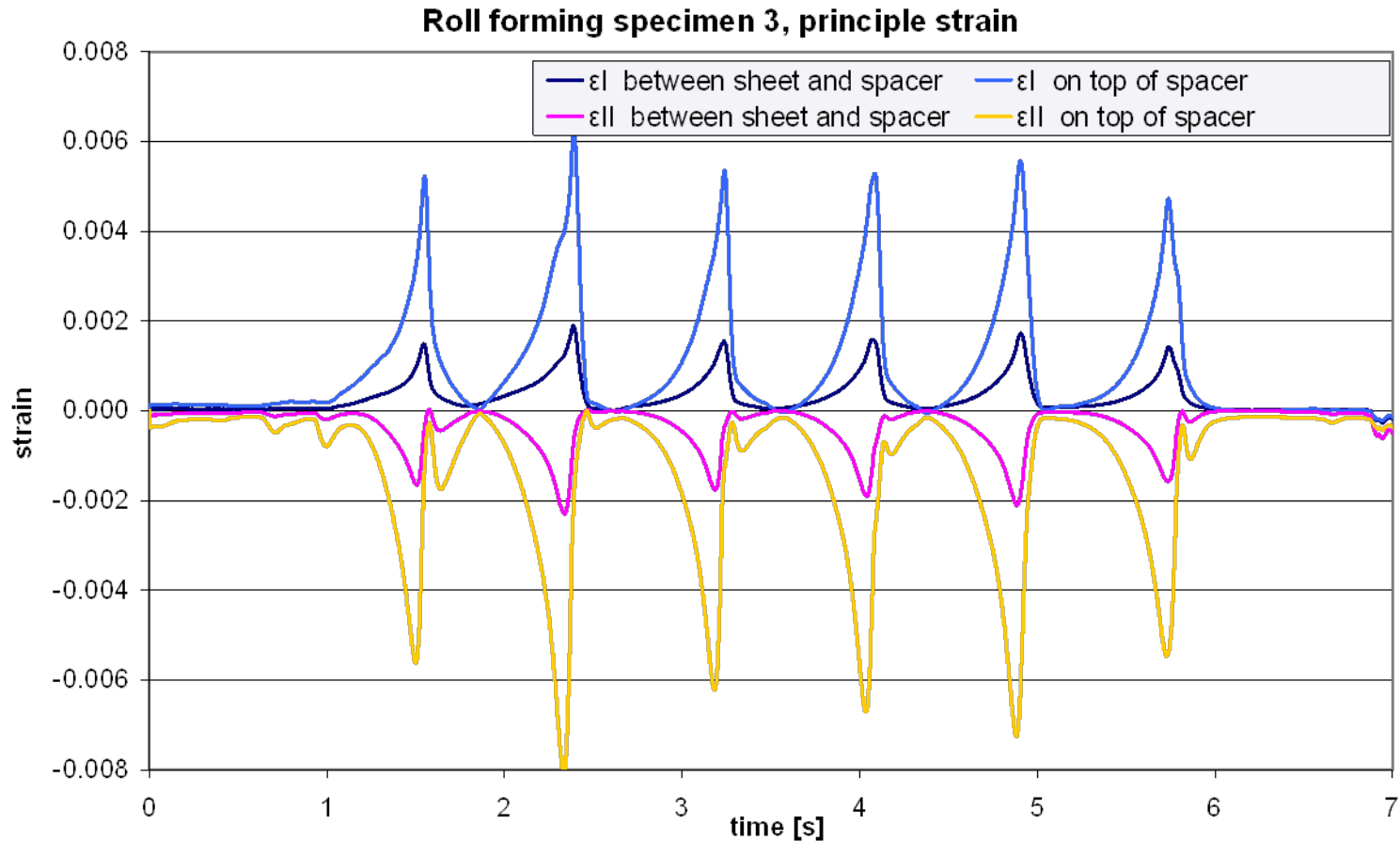
# Principal Strain



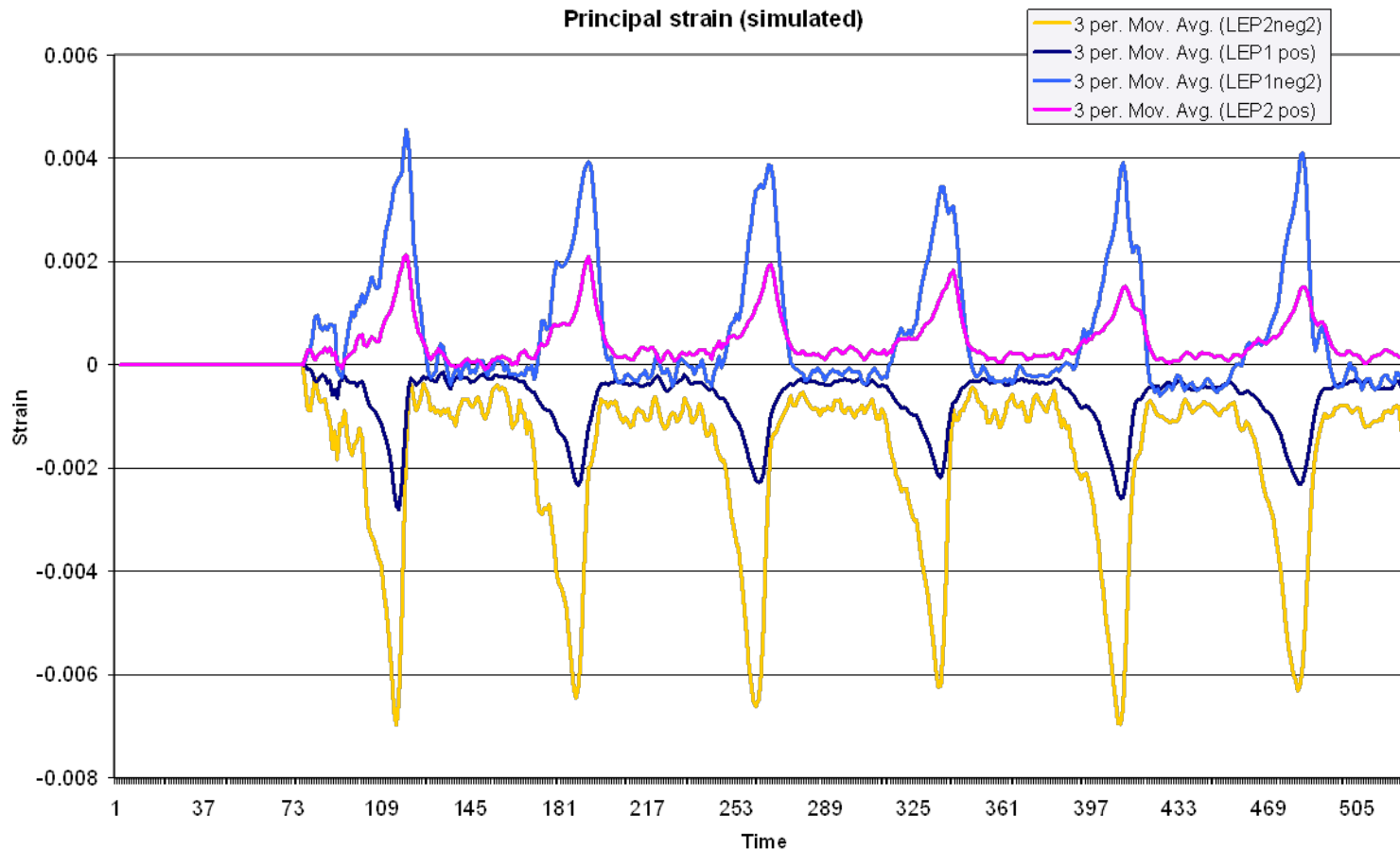
$$\varepsilon_{I,II} = \frac{\varepsilon_A + \varepsilon_C}{2} \pm \frac{1}{2} \sqrt{2} \sqrt{(\varepsilon_A - \varepsilon_B)^2 + (\varepsilon_B - \varepsilon_C)^2}$$

$$\tan 2\phi = \frac{\varepsilon_A - 2\varepsilon_B + \varepsilon_C}{\varepsilon_A - \varepsilon_C}$$

# Principal Strain - Measured



# Principal Strain - Simulated



# Summary and future work

- Review of strain measurement methods
- Design of strain gauge device that acquires all desired data from one side of the strip
- Agreement between measurements and simulation
- Gather data under conditions that generate geometric deviations
- Develop rules for corrective intervention

