

Dynamical detailed balance and local KMS condition for non-equilibrium states

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The principle of detailed balance is at the basis of equilibrium physics and is equivalent to the Kubo-Martin-Schwinger (KMS) condition (under quite general assumptions). In the present paper we prove that a large class of open quantum systems satisfies a dynamical generalization of the detailed balance condition (*dynamical detailed balance*) expressing the fact that all the micro-currents, associated to the Bohr frequencies are constant. The usual (equilibrium) detailed balance condition is characterized by the property that this constant is identically zero. From this we deduce a simple and experimentally measurable relation expressing the microcurrent associated to a transition between two levels $\epsilon_m \rightarrow \epsilon_n$ as a linear combination of the occupation probabilities of the two levels, with coefficients given by the generalized susceptivities (transport coefficients). Finally, using a master equation characterization of the dynamical detailed balance condition, we show that this condition is equivalent to a "local" generalization of the usual KMS condition.

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I. INTRODUCTION

To understand non-equilibrium phenomena is one of the most important challenges of modern physics. The monographs [1–3] summarize the early developments in this direction and, after them, several endeavors were made by many authors to construct a satisfactory description of non-equilibrium phenomena from the stand point of microscopic physics (cf. e.g. [4–10]). As pointed out by many authors (see for example [10]), the most crucial difficulty of the problem is that we lack a good characterization of non-equilibrium states whereas we have criteria for the equilibrium case: detailed balance, the KMS condition, stability and so on. In the present paper, starting from some physically interesting situations we deduce a general characterization of a class of stationary states which satisfy a condition (dynamical detailed balance) generalizing the usual detailed balance and KMS conditions. For this purpose, we apply the stochastic limit technique [11–15] to some concrete and widely studied models and show that this leads to a natural generalization of both the detailed balance and the KMS conditions which characterizes a rather wide and interesting class of non-equilibrium stationary states.

The first basic idea of the present paper can be described as follows. The most commonly used states in quantum field theory are the Fock (vacuum) or Gibbs (equilibrium) states. When a field in such a state interacts with a discrete system (e.g. an atom) in the stochastic limit one obtains a master equation for the system whose stationary state is the ground state of the atom, if the field was originally in the Fock state; while it is the Gibbs state of the system at inverse temperature β , if the field was originally in its equilibrium state at inverse temperature β . The systematic development of the theory of stochastic limit (see below and [11, 12]), has revealed that the above described phenomenon is quite universal namely: for a large class of states (including many concrete examples which are neither Fock nor equilibrium) the stochastic limit procedure allows to deduce master equations whose associated Markov semigroups drive the system to a stationary state ρ_∞ in the sense that, independently of the initial state ρ_0 , one has

$$\lim_{t \rightarrow +\infty} P_*^t \rho_0 = \rho_\infty$$

(P_*^t is the Markov semigroup acting on density matrices). This fact suggests to give a dynamical characterization of ground (or equilibrium) states of the system (atom) in terms of their response to an interaction with the environment (field) in the stochastic limit regime. This extends to the non-equilibrium regime the approach of [16, 17]. In fact, from the above considerations it is natural to expect that the analysis of the stationary states of master equations associated via stochastic limit to non equilibrium states of the environment, will lead to a new class of states, of

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discrete quantum systems, which should play for non-equilibrium phenomena, a role analogue to that played by Gibbs states for equilibrium phenomena. In the present paper, we prove that this is indeed the case.

The second basic idea of the present paper is to exploit the main advantage of stochastic limit with respect to the old Markovian approximation namely: the field degrees of freedom are not traced away, but they survive in the limit as "quantum noise" (or master field). In particular, as shown in [14, 15], the slow degrees of freedom of the field (e.g. the functions of the free energy of the field) survive in the stochastic limit. This allows us to define the energy currents in a natural way and to study their dynamics, thus going far beyond the Markov approximation where one only obtains the master equation for system observables and loses any control on the limits of field observables.

We will illustrate our ideas with two models: one is very well studied in the literature and consists of a system interacting with two equilibrium thermal reservoirs at different temperatures. The master equation approach to this model was discussed in [4]. As already mentioned, this technique cannot be applied to the problem studied in the present paper, i.e. the dynamical study of the currents associated to the field because the field degrees of freedom are traced away from the beginning. The second class of models is more general (see Sec.VI), because the field, with which the system interacts is not in a usual equilibrium state, but in a new class of states in which, roughly speaking, *each frequency is at local equilibrium at its own (frequency dependent) temperature*. Although states of this type have been considered in studies of molecular kinetics, we do not know if these states have been experimentally realized. However their structure, characterized by local equilibrium at energy dependent temperatures, is a natural modification of the usual equilibrium states (see Sec. VII below) and we are confident that the inventiveness of experimentalists is rich enough to allow their realization.

We briefly describe the general scheme of the stochastic limit technique for Hamiltonians of the form

$$H^{(\lambda)} = H_0 + \lambda H_I \quad (1)$$

where λ is a real parameter, H_0 is the free Hamiltonian and H_I is the interaction Hamiltonian (see the concrete example in the next section). The general idea of the stochastic limit approach [11, 12] is to introduce the time rescaling

$$t \rightarrow t/\lambda^2 \quad (2)$$

in the solution

$$U_t^{(\lambda)} = e^{itH_0} e^{-itH^{(\lambda)}} \quad (3)$$

of the Schrödinger equation in interaction picture associated to the Hamiltonian $H^{(\lambda)}$, i.e.

$$\frac{d}{dt} U_t^{(\lambda)} = -i\lambda H_I(t) U_t^{(\lambda)}, \quad H_I(t) = e^{itH_0} H_I e^{-itH_0}. \quad (4)$$

The rescaling (2) gives the rescaled equation

$$\frac{d}{dt} U_{t/\lambda^2}^{(\lambda)} = -\frac{i}{\lambda} H_I(t/\lambda^2) U_{t/\lambda^2}^{(\lambda)} \quad (5)$$

and the limit $\lambda \rightarrow 0$ (which is equivalent to $\lambda \rightarrow 0$ and $t \rightarrow \infty$ under the condition that $\lambda^2 t$ tends to a constant) captures the dominating contributions to the dynamics, which, under appropriate assumptions on the model [12] is shown to converge to the solution of

$$\frac{d}{dt} U_t = -ih_t U_t, \quad h_t = \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} H_I(t/\lambda^2), \quad U(0) = 1 \quad (6)$$

Similarly one obtains the limit of the Heisenberg evolution

$$\lim_{\lambda \rightarrow 0} X_t^{(\lambda)} := \lim_{\lambda \rightarrow 0} U_{t/\lambda^2}^{(\lambda) \dagger} X U_{t/\lambda^2}^{(\lambda)} = U_t^\dagger X U_t \quad (7)$$

where U_t is the solution of (6) and X is an observable belonging to a certain class (slow observables, cf. Sec.III below and [12]).

The main result of this theory is that the time rescaling induces a rescaling

$$a_k \longrightarrow \frac{1}{\lambda} e^{-i\frac{t}{\lambda^2}(\omega(k)-\Omega)} a_k \quad (8)$$

of the quantum field, defining the Hamiltonian (1), which in the present paper will be assumed to be a scalar boson field: ($[a_k, a_{k'}] = \delta(k - k')$) (the meaning of $\omega(k)$ and Ω will be described in next chapter) and, in the limit $\lambda \rightarrow 0$, the rescaled field becomes a quantum white noise (or master field) $b_\Omega(t, k)$ satisfying the commutation relations

$$[b_\Omega(t, k), b_{\Omega'}^\dagger(t', k')] = \delta_{\Omega, \Omega'} 2\pi \delta(t - t') \delta(k - k') \delta(\omega(k) - \Omega). \quad (9)$$

Moreover, if the initial state of the field is a mean zero gauge invariant Gaussian state $\rho_f(0)$ with correlations:

$$\langle a_k^\dagger a_{k'} \rangle = N(k) \delta(k - k') \quad (10)$$

then the state of the limit white noise will be of the same type with correlations

$$\langle b_\Omega^\dagger(t, k) b_{\Omega'}(t', k') \rangle = \delta_{\Omega, \Omega'} 2\pi \delta(t - t') \delta(k - k') \delta(\omega(k) - \Omega) N(k) \quad (11a)$$

$$\langle b_\Omega(t, k) b_{\Omega'}^\dagger(t', k') \rangle = \delta_{\Omega, \Omega'} 2\pi \delta(t - t') \delta(k - k') \delta(\omega(k) - \Omega) (N(k) + 1). \quad (11b)$$

It is now well understood that this scheme plays an important role in the analysis of the limit (7) when X is a system operator. In Sec.III, we describe a new development of the stochastic limit which allows to extend this scheme to a class of observables describing the slow degrees of freedom of the field.

The remaining part of this paper is arranged as follows: In Sec. II we consider a model which drives the system to a non-equilibrium stationary state. It describes a quantum system put between two reservoirs at different temperatures. By analysis of the reduced density matrix with stochastic limit, we show that this system has non-equilibrium stationary state which doesn't satisfy the detailed balance condition. In Sec.III, we apply the stochastic limit to the slow degrees of freedom of the field. This allows to define the currents associated to these degrees of freedom and to discuss their properties. In terms of these currents, we define the dynamical detailed balance condition which is a generalization of the usual detailed balance condition. In addition, we show that in the linear approximation these currents satisfy the Onsager reciprocal relations [18]. In Sec.IV, we investigate a master equation characterization of this dynamical detailed balance condition, which corresponds to the well-known fact that the usual detailed balance condition is characterized by the master equation which drives the state to equilibrium [16, 17]. Then in the next section, we introduce the local KMS condition and prove that it is equivalent to the dynamical detailed balance condition for the state. In addition, we consider another model in which the system interacts with an environment whose state is non-equilibrium and satisfies the local KMS condition. We show that such states of the environment drive the system to a non-equilibrium state satisfying the local KMS condition with a non linear temperature function which is uniquely determined by the state of the field. Finally in Sec.VII, we summarize the contents of this paper and discuss related topics.

II. DEDUCTION OF THE STOCHASTIC SCHRÖDINGER, LANGEVIN AND MASTER EQUATION

In this section, we consider a model in which the system is driven to a non-equilibrium stationary state by its interaction with two non-equilibrium boson fields. This interaction is described by the Hamiltonian

$$H = H_0 + \lambda \sum_{j=1,2} H_{I_j}, \quad (\lambda \text{ is a coupling constant.}) \quad (12a)$$

$$H_0 = H_S + H_B, \quad H_S = \sum_l \epsilon_l |\epsilon_l\rangle \langle \epsilon_l|, \quad H_B = \sum_j \int \omega_j(k) a_{j,k}^\dagger a_{j,k} \quad [a_{j,k}, a_{j',k'}^\dagger] = \delta_{jj'} \delta(k - k'), \quad (12b)$$

$$H_{I_j} = \int dk \left(g_j(k) D_j a_{j,k}^\dagger + g_j^*(k) D_j^\dagger a_{j,k} \right) \quad (12c)$$

where D_j and D_j^\dagger are operators on the system space, $a_{j,k}$ and $a_{j,k}^\dagger$ are the annihilation and creation operators of the j -th field ($j=1,2$) and $g_j(k)$ is a form factor.

The initial state of each field is a Gibbs state at temperature β_j^{-1} and chemical potential μ_j with respect to the free Hamiltonian (throughout the present paper we assume $\omega_j(k) - \mu_j > 0$ for all k as usual), i.e. the mean zero gauge invariant Gaussian state with correlations:

$$\langle a_{j,k}^\dagger a_{j',k'} \rangle = \delta_{jj'} N(k; \beta_j, \mu_j) \delta(k - k'), \quad N(k; \beta_j, \mu_j) = \frac{1}{e^{\beta_j(\omega_j(k) - \mu_j)} - 1} \quad (13)$$

The Schrödinger equation in the interaction picture is

$$\frac{d}{dt}U_t^{(\lambda)} = -i\lambda H_I(t)U_t^{(\lambda)}, \quad U_t^{(\lambda)} = e^{itH_0}e^{-itH} \quad (14)$$

where

$$\begin{aligned} H_I(t) &= \sum_{j=1,2} e^{itH_0} H_{I_j} e^{-itH_0} \\ &= \sum_{j=1,2} \sum_{\omega \in F} \sum_{lm} \int dk \left(g_{j:lm}(k) E_\omega(lm) a_{j,k}^\dagger e^{+i(\omega_i(k)-\omega)t} + g_{j:lm}^*(k) E_\omega^\dagger(lm) a_{j,k} e^{-i(\omega_i(k)-\omega)t} \right) \end{aligned} \quad (15a)$$

$$g_{j:lm}(k) = g_j(k) \langle \epsilon_l | D | \epsilon_m \rangle, \quad E_\omega(lm) = \sum_{\epsilon_r \in F_\omega} \langle \epsilon_r - \omega | \epsilon_l \rangle \langle \epsilon_m | \epsilon_r \rangle | \epsilon_r - \omega \rangle \langle \epsilon_r |, \quad (15b)$$

$$F = \{\omega = \epsilon_r - \epsilon_{r'}; \epsilon_r, \epsilon_{r'} \in \text{Spec.}(H_S)\}, \quad F_\omega = \{\epsilon_{r'} \in \text{Spec.}(H_S); \epsilon_{r'} - \omega \in \text{Spec.}(H_S)\} \quad (15c)$$

In the following, for simplicity, we assume that H_S is generic, i.e.

- 1) the spectrum Space H_S is not degenerate
 - 2) For any ω $|F_\omega| = 1$, i.e. there exist a unique pair of energy levels $\epsilon_l, \epsilon_m \in \text{Spec.}(H_S)$ such that $\omega = \epsilon_m - \epsilon_l$
- In such case, (15a) becomes

$$H_I(t) = \sum_{j=1,2} \sum_{\omega \in F} \int dk \left(g_{j:\omega}(k) E_\omega a_{j,k}^\dagger e^{+i(\omega_i(k)-\omega)t} + g_{j:\omega}^*(k) E_\omega^\dagger a_{j,k} e^{-i(\omega_i(k)-\omega)t} \right) \quad (16a)$$

where

$$g_{j:\omega}(k) = g_j(k) \langle \epsilon_l | D_j | \epsilon_m \rangle, \quad E_\omega = |\epsilon_l\rangle \langle \epsilon_m|, \quad \text{for } \epsilon_l, \epsilon_m \text{ s.t. } \epsilon_m - \epsilon_l = \omega. \quad (16b)$$

Giving an Hamiltonian such as (12) the stochastic limit technique proceeds in four steps:

1. Write the associated white noise Hamiltonian (WNH) equation (17).
2. The causally normally ordered form of the WNH equation gives the Stochastic Schrödinger (SS) equation (19).
3. From the SS one deduces the Langevin equation (e.g. (21) and (31)).
4. Partial trace of the Langevin gives the master equation (e.g. (22)).

In the following, we shall describe the results of these steps for our models and we refer to [12] for a detailed description of the steps necessary to achieve these results.

Applying stochastic limit as explained in Sec. I, we obtain the white noise Hamiltonian equation

$$\frac{d}{dt}U_t = -i \sum_{j=1,2} \sum_{\omega \in F} \left(E_\omega b_{t;j,\omega}^\dagger + E_\omega^\dagger b_{t;j,\omega} \right) U_t \quad (17a)$$

where

$$b_{t;j,\omega} = \int dk g_{j:\omega}^*(k) b_{t;j,\omega}(k), \quad b_{t;j,\omega}(k) = \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} e^{-i(\omega_j(k)-\omega)t/\lambda^2} a_{j,k}. \quad (17b)$$

Notice that the state of the limit white noise will be of the same type as (13) but with correlations

$$\langle b_{t;j,\omega}^\dagger(k) b_{t';j',\omega'}(k') \rangle = \delta_{jj'} \delta_{\omega\omega'} 2\pi\delta(t-t') \delta(k-k') \delta(\omega_j(k)-\omega) N(k; \beta_j, \mu_j) \quad (18a)$$

$$\langle b_{t;j,\omega}(k) b_{t';j',\omega'}^\dagger(k') \rangle = \delta_{jj'} \delta_{\omega\omega'} 2\pi\delta(t-t') \delta(k-k') \delta(\omega_j(k)-\omega) (N(k; \beta_j, \mu_j) + 1). \quad (18b)$$

The SS equation associated to the WNH equation (17) is

$$dU_t = -i \sum_{j=1,2} \left(E_\omega dB_{t;j,\omega}^\dagger + E_\omega^\dagger dB_{t;j,\omega} - i(\gamma_{-,j,\omega} E_\omega E_\omega^\dagger + \gamma_{+,j,\omega}^* E_\omega^\dagger E_\omega) dt \right) U_t. \quad (19a)$$

where

$$dB_{t;j,\omega} = \int_t^{t+dt} b_{\tau;j,\omega} d\tau, \quad dB_{t;j,\omega}^\dagger = \int_t^{t+dt} b_{\tau;j,\omega}^\dagger d\tau \quad (19b)$$

are stochastic differentials and satisfy the Ito table

$$dB_{t;j,\omega} dB_{t;j',\omega'}^\dagger = 2\delta_{jj'} \delta_{\omega\omega'} \text{Re}\gamma_{-,j,\omega} dt, \quad dB_{t;j,\omega}^\dagger dB_{t;j',\omega'} = 2\delta_{jj'} \delta_{\omega\omega'} \text{Re}\gamma_{+,j,\omega} dt \quad (19c)$$

$$dtdB_{t;j,\omega} = dB_{t;j,\omega} dB_{t;j',\omega'} = dB_{t;j,\omega}^\dagger dB_{t;j',\omega'}^\dagger = dtdB_{t;j,\omega}^\dagger = 0. \quad (19d)$$

The main physical information is contained in the generalized susceptivities (or transport coefficients):

$$\begin{aligned} \gamma_{-,j,\omega} &= \int dk |g_{j,\omega}(k)|^2 \frac{-i(N(k; \beta_j, \mu_j) + 1)}{\omega - \omega_j(k) - i0} \\ &= \pi \int dk |g_{j,\omega}(k)|^2 \frac{e^{\beta_i(\omega_j(k) - \mu_j)}}{e^{\beta_j(\omega_j(k) - \mu_j)} - 1} \delta(\omega_j(k) - \omega) - i\text{P.P} \int dk \frac{|g_{j,\omega}(k)|^2}{\omega_j(k) - \omega} \frac{e^{\beta_i(\omega_j(k) - \mu_j)}}{e^{\beta_j(\omega_j(k) - \mu_j)} - 1} \end{aligned} \quad (20a)$$

$$\begin{aligned} \gamma_{+,j,\omega} &= \int dk |g_{j,\omega}(k)|^2 \frac{-iN(k; \beta_j, \mu_j)}{\omega - \omega_j(k) - i0} \\ &= \pi \int dk |g_{j,\omega}(k)|^2 \frac{1}{e^{\beta_j(\omega_j(k) - \mu_j)} - 1} \delta(\omega_j(k) - \omega) - i\text{P.P} \int dk \frac{|g_{j,\omega}(k)|^2}{\omega_j(k) - \omega} \frac{1}{e^{\beta_j(\omega_j(k) - \mu_j)} - 1}. \end{aligned} \quad (20b)$$

For an operator X of the system space \mathcal{H}_S , from the SS equation (19), one obtains the Langevin equation

$$\begin{aligned} d(U_t^\dagger X U_t) &= \sum_{j=1,2} \sum_{\omega \in F} \left[i \left(U_t^\dagger [E_\omega, X] U_t dB_{t;j,\omega}^\dagger + U_t^\dagger [E_\omega^\dagger, X] U_t dB_{t;j,\omega} \right) \right. \\ &\quad \left. - \text{Im}\gamma_{-,j,\omega} U_t^\dagger [E_\omega E_\omega^\dagger, X] U_t dt + \text{Im}\gamma_{+,j,\omega} U_t^\dagger [E_\omega^\dagger E_\omega, X] U_t dt \right] \\ &\quad \left. - U_t^\dagger \left(\text{Re}\gamma_{-,j,\omega} (\{E_\omega E_\omega^\dagger, X\} - 2E_\omega X E_\omega^\dagger) + \text{Re}\gamma_{+,j,\omega} (\{E_\omega^\dagger E_\omega, X\} - 2E_\omega^\dagger X E_\omega) \right) U_t dt \right]. \end{aligned} \quad (21)$$

The Langevin equation with the state for some operators of the field degrees of freedom will be discussed in the following section (see (31)). Taking the partial expectation value of both sides of this Langevin equation with the state (13), the master equation for the reduced density matrix is obtained:

$$\begin{aligned} \frac{d}{dt} \rho_S(t) &= -i[\Delta, \rho_S(t)] \\ &\quad - \sum_{\omega \in F} \Gamma_{-, \omega} \left(\frac{1}{2} \{E_\omega^\dagger E_\omega, \rho_S(t)\} - E_\omega \rho_S(t) E_\omega^\dagger \right) - \sum_{\omega \in F} \Gamma_{+, \omega} \left(\frac{1}{2} \{E_\omega E_\omega^\dagger, \rho_S(t)\} - E_\omega^\dagger \rho_S(t) E_\omega \right) \end{aligned} \quad (22a)$$

$$\Delta = i \sum_{\omega \in F} \sum_{j=1,2} (\text{Im}(\gamma_{-,j,\omega}) E_\omega^\dagger E_\omega - \text{Im}(\gamma_{+,j,\omega}) E_\omega E_\omega^\dagger) \quad (22b)$$

$$\Gamma_{\mp, \omega} = 2\text{Re} \sum_{j=1,2} \gamma_{\mp, j, \omega} \geq 0, \quad (\Gamma_{\mp, \omega} = 0 \quad \text{for} \quad \omega \leq 0). \quad (22c)$$

The generator of (22a) has the standard GKSL form [19]. For the off-diagonal matrix elements $\rho_{mn}(t) = \langle \epsilon_m | \rho_S(t) | \epsilon_n \rangle$ ($m \neq n$) we obtain

$$\frac{d}{dt} \rho_{mn}(t) = (i\Delta_{mn} - G_{mn}) \rho_{mn}(t) \quad (23a)$$

$$\Delta_{mn} = \sum_l (\theta_{-, \epsilon_m - \epsilon_l} - \theta_{-, \epsilon_n - \epsilon_l} - \theta_{+, \epsilon_l - \epsilon_m} + \theta_{+, \epsilon_l - \epsilon_n}), \quad \theta_{\mp, \omega} = \text{Im}\gamma_{\mp, j, \omega} \quad (23b)$$

$$G_{mn} = \sum_l (\Gamma_{ml} + \Gamma_{nl}) > 0, \quad \text{where} \quad \Gamma_{ml} = \begin{cases} \Gamma_{-, \epsilon_m - \epsilon_l} & \text{for } \epsilon_m > \epsilon_l \\ \Gamma_{+, \epsilon_l - \epsilon_m} & \text{for } \epsilon_m < \epsilon_l \end{cases} \quad (23c)$$

which shows that these elements vanish at $t \rightarrow \infty$ whenever $G_{mn} \neq 0$, ($\forall m, n$).

The diagonal matrix elements $\rho_{mm}(t)$ describe a classical birth and death process characterized by the equation

$$\begin{aligned} \frac{d}{dt}\rho_{mm}(t) &= -\sum_l ((\Gamma_{-, \epsilon_m - \epsilon_l} + \Gamma_{+, \epsilon_l - \epsilon_m})\rho_{mm}(t) - (\Gamma_{-, \epsilon_l - \epsilon_m} + \Gamma_{+, \epsilon_m - \epsilon_l})\rho_{ll}(t)) \\ &= -\sum_l (\Gamma_{ml} \rho_{mm}(t) - \Gamma_{lm} \rho_{ll}(t)) \end{aligned} \quad (24a)$$

$$= -\sum_l A_{ml} \rho_{ll}, \quad A_{ml} = \begin{cases} \sum_l \Gamma_{ml} & \text{for } l = m \\ -\Gamma_{lm} & \text{for } l \neq m \end{cases} \quad (24b)$$

$$\frac{\Gamma_{ml}}{\Gamma_{lm}} = \frac{\text{Re} \sum_{j=1,2} \gamma_{-,j, \epsilon_m - \epsilon_l}}{\text{Re} \sum_{j=1,2} \gamma_{+,j, \epsilon_m - \epsilon_l}} \quad (\text{for } \epsilon_m > \epsilon_l), \quad \text{or} \quad \frac{\Gamma_{ml}}{\Gamma_{lm}} = \frac{\text{Re} \sum_{j=1,2} \gamma_{+,j, \epsilon_l - \epsilon_m}}{\text{Re} \sum_{j=1,2} \gamma_{-,j, \epsilon_l - \epsilon_m}} \quad (\text{for } \epsilon_l > \epsilon_m). \quad (24c)$$

Notice that this quotient is universal in the sense that it does not depend on g_j whenever in the interaction (12) form factors g_i do not depend on j ($g_j = g$). When the matrix A has a non-trivial eigenvector associated to the 0 eigenvalue, a stationary state exists. In addition, the convergence to the stationary state from any initial state $\rho_S(0)$ is guaranteed under quite general conditions (cf. [13]). Notice, that the stationary solution of (22) satisfies the detailed balanced condition, i.e.

$$\frac{\rho_{mm}}{\rho_{ll}} = \frac{\Gamma_{lm}}{\Gamma_{ml}}, \quad (25)$$

if and only if the coefficients Γ_{ml} satisfy

$$\frac{\Gamma_{ml}}{\Gamma_{lm}} = \frac{\Gamma_{mk}}{\Gamma_{km}} \frac{\Gamma_{kl}}{\Gamma_{lk}}, \quad \forall m, l, k \quad (26)$$

In the non-equilibrium case (26) is not satisfied. With this model given by (12) and (13), (26) is satisfied only in some special cases (for example when both fields have the same temperature and chemical potential, or the system has only one Bohr frequency).

In general, the stationary state of the master equation (22) can be described by the nonlinear temperature function

$$\beta_S(\epsilon_m) = \frac{-1}{\epsilon_m} \log \rho_{mm} > 0 \quad (27)$$

as

$$\rho_S = \frac{e^{-\beta_S(H_S)H_S}}{Z}, \quad Z = \text{tr}_S \left(e^{-\beta_S(H_S)H_S} \right). \quad (28)$$

The state is Gibbs state the function $\beta_S(H_S)$ becomes constant. This fact actually leads to the idea that a rather wide class of non-equilibrium stationary states can be treated with such generalized temperature functions. This notion is valid not only for the system but also for the state of the field. Indeed, in the Sec.VI below, we will consider another model in which the system is driven to a non-equilibrium stationary state by an interaction with a non-equilibrium field described by a generalized temperature function.

III. MICROSCOPIC CURRENTS AND DYNAMICAL DETAILED BALANCE

In the previous section, we have investigated the dynamics of a system interacting with fields in a non-equilibrium situation and we have already remarked some important difference from the equilibrium case. However one can see a more direct and crucial difference through the study of the dynamics of the field degrees of freedom.

A. Slow degrees of freedom and micro-current

In order to investigate the dynamics of the field, it is important to notice that some operators of the field degrees of freedom, i.e. the slow degrees, survive even after stochastic limit. As we explained in the introduction, the rescaled

field operators a_k and a_k^\dagger become white noise operators denoted by $b_\omega(t, k)$ and $b_\omega^\dagger(t, k)$ whose commutation relation is given by (9). Due to this fact we can intuitively say that the fast degrees of the field become noise (singular) in the stochastic limit. However we can describe the time evolution of some of operators of the field in terms of the rescaled time even after stochastic limit, and this approach gives us meaningful information on the original dynamics as well as on the system operator. Since the stochastic limit is an asymptotic theory, mathematically we have to prove the convergence of the dynamics and this has been done elsewhere [12]. In the present paper, we apply the theory to the number operator in the model and discuss its physical meaning.

Let us sketch how to compute the time evolution of the number operator $n_k = a_k^\dagger a_k$ under the white noise equation

$$\frac{d}{dt}U_t = -i \sum_{\omega \in F} \left(E_\omega b_t^\dagger + E_\omega^\dagger b_t \right) U_t. \quad (29)$$

We will illustrate the calculation only in the simplest (Fock) case. The more general states (10) can be reduced to a linear combination of two independent Fock representations (cf. [12] section 2.18). The key formula to apply stochastic limit to the number operator of the field $n_k = a_k^\dagger a_k$ is

$$[b_\omega(t, k), n_{k'}] = b_\omega(t, k) \delta(k - k'). \quad (30)$$

The Heisenberg evolution of n_k , after the stochastic limit is described by the Langevin equation

$$\begin{aligned} \frac{d}{dt} \left(U_t^\dagger n_k U_t \right) &= i \sum_{\omega \in F} U_t^\dagger [E_\omega b_{t,\omega}^\dagger + E_\omega^\dagger b_{t,\omega}, n_k] U_t \\ &= -i \sum_{\omega \in F} \left(U_t^\dagger (E_\omega b_\omega^\dagger(t, k) - E_\omega^\dagger b_\omega(t, k)) U_t \right) \\ &= -i \sum_{\omega \in F} \left(b_\omega^\dagger(t, k) U_t^\dagger E_\omega U_t - U_t^\dagger E_\omega U_t b_\omega(t, k) + [U_t^\dagger, b_\omega^\dagger(t, k)] E_\omega U_t - U_t^\dagger E_\omega^\dagger [b_\omega(t, k), U_t] \right) \\ &= -i \sum_{\omega \in F} \left(b_\omega^\dagger(t, k) U_t^\dagger E_\omega U_t - U_t^\dagger E_\omega U_t b_\omega(t, k) \right. \\ &\quad \left. + i \left(\gamma_\omega(k) U_t^\dagger E_\omega^\dagger E_\omega U_t + \gamma_\omega(k) U_t^\dagger E_\omega^\dagger E_\omega U_t \right) \delta(\omega(k) - \omega) \right) \end{aligned} \quad (31)$$

where in the Fock case

$$\gamma_\omega(k) = \pi |g_\omega(k)|^2. \quad (32)$$

Taking partial trace $\langle \cdot \rangle$ over the initial state of the system and noise we obtain the evolution equation of the mean number of quanta

$$\frac{d}{dt} \langle U_t^\dagger n_k U_t \rangle = 2 \sum_{\omega \in F} \gamma_\omega(k) \langle U_t^\dagger E_\omega^\dagger E_\omega U_t \rangle \delta(\omega(k) - \omega). \quad (33)$$

This can be expressed in terms of the time evolution (under the master equation (22)) of the reduced density matrix $\rho_S(t)$, i.e.

$$\begin{aligned} \frac{d}{dt} \langle U_t^\dagger n_k U_t \rangle &= 2 \sum_{\omega \in F} \delta(\omega(k) - \omega) \gamma_\omega(k) \text{tr}_S \left(E_\omega^\dagger E_\omega \rho_S(t) \right) \\ &= 2 \sum_{\epsilon_m > \epsilon_n} \delta(\omega(k) - (\epsilon_m - \epsilon_n)) \text{tr}_S \left(\gamma_\omega(k) |\epsilon_m\rangle \langle \epsilon_m| \rho_S(t) \right) \end{aligned} \quad (34)$$

In the case of a general initial state described by (10), the computation is similar, and one get

$$\begin{aligned} \frac{d}{dt} \langle U_t^\dagger n_k U_t \rangle &= 2 \sum_{\omega \in F} \delta(\omega(k) - \omega) \text{tr}_S \left((\gamma_{-, \omega}(k) E_\omega^\dagger E_\omega - \gamma_{+, \omega}(k) E_\omega E_\omega^\dagger) \rho_S(t) \right) \\ &= 2 \sum_{\epsilon_m > \epsilon_n} \delta(\omega(k) - (\epsilon_m - \epsilon_n)) \text{tr}_S \left(\left(\gamma_{-, \epsilon_m - \epsilon_n}(k) |\epsilon_m\rangle \langle \epsilon_m| - \gamma_{+, \epsilon_m - \epsilon_n}(k) |\epsilon_n\rangle \langle \epsilon_n| \right) \rho_S(t) \right) \end{aligned} \quad (35a)$$

where now instead of $\gamma_\omega(k)$ given by (32) one has:

$$\gamma_{-, \omega}(k) = \gamma_\omega(k)(N(k) + 1), \quad \gamma_{+, \omega}(k) = \gamma_\omega(k)N(k). \quad (35b)$$

As the consequence of (34), once we obtain the time evolution of $\rho_S(t)$ by solving the master equation discussed in the previous section, we find the time evolution of the number operator of field degrees of freedom.

In order to apply (34) to the model discussed in the previous section, we can consider the number operator for each field. Defining $n_{j,k} = a_{j,k}^\dagger a_{j,k}$, we obtain

$$\begin{aligned} \frac{d}{dt} \langle U_t^\dagger n_{j,k} U_t \rangle &= 2 \sum_{\omega \in F} \delta(\omega_j(k) - \omega) \text{tr}_S \left((\gamma_{-, \omega, j}(k) E_\omega^\dagger E_\omega - \gamma_{+, \omega, j}(k) E_\omega E_\omega^\dagger) \rho_S(t) \right) \\ &= 2 \sum_{\epsilon_m > \epsilon_n} \delta(\omega_j(k) - (\epsilon_m - \epsilon_n)) \text{tr}_S \left((\gamma_{-, \epsilon_m - \epsilon_n, j}(k) |\epsilon_m\rangle \langle \epsilon_m| - \gamma_{+, \epsilon_m - \epsilon_n, j}(k) |\epsilon_n\rangle \langle \epsilon_n|) \rho_S(t) \right) \\ &= 2 \sum_{\epsilon_m > \epsilon_n} \delta(\omega_j(k) - (\epsilon_m - \epsilon_n)) (\gamma_{-, \epsilon_m - \epsilon_n, j}(k) \rho_{mm}(t) - \gamma_{+, \epsilon_m - \epsilon_n, j}(k) \rho_{nn}(t)) \end{aligned} \quad (36a)$$

where

$$\gamma_{-, \omega, j}(k) = \pi |g_{j, \omega}(k)|^2 (N(k; \beta_j, \mu_j) + 1), \quad \gamma_{+, \omega, j}(k) = \pi |g_{j, \omega}(k)|^2 N(k; \beta_j, \mu_j). \quad (36b)$$

This time dependence of the slow degrees of freedom of the field is due to the interaction with the system and is a direct evidence of the existence of a family of currents passing through the system: one for each proper frequency $\omega = \epsilon_m - \epsilon_n > 0$. To investigate these currents, let us define, for each $\epsilon_m > \epsilon_n$, the region Ω_{mn} in k -space, resonating with the frequency $\omega_{mn} := \epsilon_m - \epsilon_n$ which includes all k_{mn} such that

$$\omega(k_{mn}) - (\epsilon_m - \epsilon_n) = 0. \quad (37)$$

Then define the microscopic number current, associated to the frequency ω_{mn} by:

$$\begin{aligned} J_{j, mn}(t) &:= \frac{d}{dt} \left(\int_{\Omega_{mn}} dk \langle U_t^\dagger n_{j,k} U_t \rangle \right) \\ &= 2 (\text{Re} \gamma_{-, j, \epsilon_m - \epsilon_n} \rho_{mm}(t) - \text{Re} \gamma_{+, j, \epsilon_m - \epsilon_n} \rho_{nn}(t)), \\ J_{j, mn} &:= 2 (\text{Re} \gamma_{-, j, \epsilon_m - \epsilon_n} \rho_{mm} - \text{Re} \gamma_{+, j, \epsilon_m - \epsilon_n} \rho_{nn}), \quad (\text{in stationary state of the system}) \\ &= 2 \gamma_{j, mn} \rho_{mm} \frac{e^{(\epsilon_m - \epsilon_n - \mu_j) \beta_j}}{e^{(\epsilon_m - \epsilon_n - \mu_j) \beta_j} - 1} \left(1 - e^{-(\epsilon_m - \epsilon_n - \mu_j) \beta_j} \frac{\rho_{nn}}{\rho_{mm}} \right) \end{aligned} \quad (38a)$$

and similarly the microscopic energy current

$$\begin{aligned} J_{j, mn}^E(t) &:= \frac{d}{dt} \left(\int_{\Omega_{mn}} dk \omega_j(k) \langle U_t^\dagger n_{j,k} U_t \rangle \right) \\ &= 2 (\epsilon_m - \epsilon_n) (\text{Re} \gamma_{-, j, \epsilon_m - \epsilon_n} \rho_{mm}(t) - \text{Re} \gamma_{+, j, \epsilon_m - \epsilon_n} \rho_{nn}(t)) \\ J_{j, mn}^E &:= 2 (\epsilon_m - \epsilon_n) (\text{Re} \gamma_{-, j, \epsilon_m - \epsilon_n} \rho_{mm} - \text{Re} \gamma_{+, j, \epsilon_m - \epsilon_n} \rho_{nn}), \quad (\text{in stationary state of the system}) \\ &= 2 (\epsilon_m - \epsilon_n) \gamma_{j, mn} \rho_{mm} \frac{e^{(\epsilon_m - \epsilon_n - \mu_j) \beta_j}}{e^{(\epsilon_m - \epsilon_n - \mu_j) \beta_j} - 1} \left(1 - e^{-(\epsilon_m - \epsilon_n - \mu_j) \beta_j} \frac{\rho_{nn}}{\rho_{mm}} \right) \end{aligned} \quad (38b)$$

where

$$\gamma_{j, mn} = \pi \int_{k \in \Omega_{mn}} dk |g_{j, \epsilon_m - \epsilon_n}(k)| \delta(\omega_j(k) - (\epsilon_m - \epsilon_n)). \quad (38c)$$

The term *microscopic* here refers to the fact that we define one current for each atomic frequency. We see, from (38) that in the stationary state for the system

$$\rho_S(t) = \rho_S$$

we have a constant flow of quanta from the field to the system.

The sum, over all m and n , of our micro-currents gives two macro-currents which coincide with those defined by H. Spohn and J. L. Lebowitz in terms of the master equation [4]. In fact, as seen in (38), these currents can be

represented with the matrix elements of the reduced density matrix and the generators of master equation like they defined (cf. also the formulas (41) and (42) bellow). However the micro-currents are essential to define dynamical detailed balance and the fact that we started from the dynamics of the fields and deduced them gives a physical interpretation to these currents.

Moreover our approach shows that in fact a much stronger condition is satisfied namely: for each Bohr frequency $\omega \in F$ the mean micro-current relative to the frequency $\omega = \epsilon_m - \epsilon_n$ is constant. This means that, for each $\omega \in F$, the flow of quanta from the modes of the field resonating with the frequency ω (in the sense of condition (37)) is constant. Thus the current of quanta in the field is split into a family of independent *microscopic currents*, one for each Bohr frequency ω . In the stationary state each of these microscopic currents is constant: we shall call this fact *dynamical detailed balance*. This condition gives a simple and experimentally measurable relation expressing the microcurrent associated to a transition between two levels $\epsilon_m \rightarrow \epsilon_n$ as a linear combination of the occupation probabilities of the two levels, with coefficients given by the generalized susceptivities (transport coefficients).

The usual (equilibrium) detailed balance condition is the particular case of the dynamical one corresponding to the case in which all the microscopic currents are zero. In fact in this case equation (38) is reduced to

$$\frac{\rho_{nn}}{\rho_{mm}} = \frac{\text{tr}(|n\rangle\langle n|\rho_S)}{\text{tr}(|m\rangle\langle m|\rho_S)} = e^{\beta_j(\epsilon_m - \epsilon_n - \mu_j)}, \quad \forall j = 1, 2$$

for any k_{mn} satisfying condition (37). From this, by standard arguments, it follows that there exists a constant $\beta > 0$ such that

$$\beta_1 = \beta_2 = \beta, \quad \rho_{mm} = \frac{e^{-\beta\epsilon_m}}{Z_\beta}; \quad Z_\beta = \sum_m e^{-\beta\epsilon_m}$$

so that ρ_S is the Gibbs distribution.

In the general case the dynamical detailed balance condition is

$$2(\text{Re}\gamma_{-, \epsilon_m - \epsilon_n, j} \rho_{mm} - \text{Re}\gamma_{+, \epsilon_m - \epsilon_n, j} \rho_{nn}) = J_{j, mn} \quad (39)$$

This gives, for $m > 0$

$$2\text{Re}\gamma_{-, \epsilon_m - \epsilon_0, j} \rho_{mm} = 2\text{Re}\gamma_{+, \epsilon_m - \epsilon_0, j} \rho_{00} + J_{j, m0}$$

or

$$\rho_{mm} = \frac{\text{Re}\gamma_{+, \epsilon_m - \epsilon_0, j}}{\text{Re}\gamma_{-, \epsilon_m - \epsilon_0, j}} \rho_{00} + \frac{J_{j, m0}}{2\text{Re}\gamma_{-, \epsilon_m - \epsilon_0, j}}$$

Replacing this into (39) we find

$$\begin{aligned} 2\text{Re}\gamma_{-, \epsilon_m - \epsilon_n, j} \left[\frac{\text{Re}\gamma_{+, \epsilon_m - \epsilon_0, j}}{\text{Re}\gamma_{-, \epsilon_m - \epsilon_0, j}} \rho_{00} + \frac{J_{j, m0}}{2\text{Re}\gamma_{-, \epsilon_m - \epsilon_0, j}} \right] \\ = 2\text{Re}\gamma_{+, \epsilon_m - \epsilon_n, j} \left[\frac{\text{Re}\gamma_{+, \epsilon_n - \epsilon_0, j}}{\text{Re}\gamma_{-, \epsilon_n - \epsilon_0, j}} \rho_{00} + \frac{J_{j, n0}}{2\text{Re}\gamma_{-, \epsilon_n - \epsilon_0, j}} \right] + J_{j, mn} \end{aligned}$$

or equivalently

$$\begin{aligned} J_{j, mn} = 2 \left[\frac{\text{Re}\gamma_{-, \epsilon_m - \epsilon_n, j} \text{Re}\gamma_{+, \epsilon_m - \epsilon_0, j}}{\text{Re}\gamma_{-, \epsilon_m - \epsilon_0, j}} - \frac{\text{Re}\gamma_{+, \epsilon_m - \epsilon_n, j} \text{Re}\gamma_{+, \epsilon_n - \epsilon_0, j}}{\text{Re}\gamma_{-, \epsilon_n - \epsilon_0, j}} \right] \rho_{00} \\ + \frac{\text{Re}\gamma_{-, \epsilon_m - \epsilon_n, j}}{\text{Re}\gamma_{-, \epsilon_m - \epsilon_0, j}} J_{j, m0} - \frac{\text{Re}\gamma_{+, \epsilon_m - \epsilon_n, j}}{\text{Re}\gamma_{-, \epsilon_n - \epsilon_0, j}} J_{j, n0} \end{aligned} \quad (40)$$

which shows that, under the dynamical detailed balance condition, the intensities of the microscopic currents are uniquely determined by the single sequence $J_{j, m0}$.

The following identities make the physical meaning of the currents $J_{j, mn}(t)$ and $J_{j, mn}^E(t)$ clear:

$$\begin{aligned} J_m(t) &:= \sum_{j=1,2} \left(\sum_{n < m} J_{j, mn}(t) - \sum_{n > m} J_{j, nm}(t) \right) \\ &= -\frac{d}{dt} \text{tr}(|\epsilon_m\rangle\langle \epsilon_m | \rho_S(t)) \end{aligned} \quad (41)$$

is the difference between the quanta emitted from and absorbed by the level ϵ_m .

$$\begin{aligned} \sum_m J_m^E(t) &:= \sum_m \sum_{j=1,2} \left(\sum_{n<m} J_{j,mn}^E(t) - \sum_{n>m} J_{j,nm}^E(t) \right) \\ &= -\frac{d}{dt} \text{tr}(H_S \rho_S(t)) \end{aligned} \quad (42)$$

expresses the fact that the variation of energy of the system is exactly balanced.

On the other hand, the behavior of each microscopic current $J_{j,mn}$ doesn't always follow a naive intuition. For example, even in the symmetric configuration of interaction ($g_1(k) = g_2(k) = g(k)$ and $\mu_1 = \mu_2$), there are cases when some micro currents flow backward (i.e. from the low to the high temperature reservoir), however it is impossible that all micro currents flow backward. A sufficient condition that the total energy current

$$J_1^{(E)} = \sum_m \left(\sum_{n<m} J_{1,mn}^E - \sum_{n>m} J_{1,nm}^E \right) = -J_2^{(E)} \quad (43)$$

is positive when the reservoir 1 is at lower temperature than 2 is that

$$\frac{\rho_{mm}}{\rho_{nn}} < 1, \quad \forall m > n, \quad (44)$$

i.e. that there is no inversely populated state. In addition, if all $J_{1,mn}$ and $J_{2,mn}$ have opposite sign, the following strong relation (*Gibbs domination bound*) holds:

$$e^{-(\epsilon_m - \epsilon_n - \mu_1)\beta_1} \leq \frac{\rho_{mm}}{\rho_{nn}} \leq e^{-(\epsilon_m - \epsilon_n - \mu_2)\beta_2}, \quad \epsilon_m > \epsilon_n. \quad (45)$$

However

$$J_{1,mn}^{(E)} = -J_{2,mn}^{(E)} \quad (46)$$

is not true when the stationary state of the system does not satisfy the detailed balance condition (See (24), (25) and (26)). In fact

$$\begin{aligned} J_{1,mn} + J_{2,mn} &= \sum_{j=1,2} J_{j,mn} \\ &= 2 \sum_{j=1,2} (\text{Re}\gamma_{-,j,\epsilon_m-\epsilon_n} \rho_{mm} - \text{Re}\gamma_{+,j,\epsilon_m-\epsilon_n} \rho_{nn}) \\ &= \Gamma_{mn} \rho_{mm} - \Gamma_{nm} \rho_{nn} \neq 0, \end{aligned} \quad (47a)$$

$$J_{1,mn}^E + J_{2,mn}^E \neq 0. \quad (47b)$$

In other words, these stationary current can satisfy (46) if and only if the stationary state of the system satisfies the detailed balance condition. When the stationary state can be described with detailed balance condition, the generalized temperature defined by (28) becomes constant which can be interpreted as the local temperature of the system in between two fields. Thus this condition gives a characterization of those non-equilibrium stationary states which are local equilibrium stationary states with current. We show an important example of such state in the following, however apart from few trivial cases, to satisfy the detailed balance condition strictly is impossible in this model as explained in the previous section. We consider the case where the detailed balance condition is satisfied approximately, i.e. the linear transport regime.

B. Linear approximation, local equilibrium and Onsager relation

Here we show that the stationary current defined by (38) is consistent with well-known non-equilibrium physics in linear regime. First we assume that the form factors in the interactions are the same for the two fields ($g_1(k) = g_2(k) := g(k)$). This implies that the stationary solution is symmetric with respect to the indices 1 and 2. Now consider a small variation of these parameters

$$\beta_0 = \frac{\beta_1 + \beta_2}{2}, \quad \delta\beta = \beta_1 - \beta_2, \quad \text{and} \quad \mu_0 = \frac{\mu_1 + \mu_2}{2}, \quad \delta\mu = \mu_2 - \mu_1 \quad (48)$$

and the first order expansion of the stationary solution in $\delta\beta$ and $\delta\mu$. This gives

$$\rho_{mm} \Big|_{\substack{\beta_1 = \beta_0 + \frac{\delta\beta}{2}, \mu_1 = \mu_0 - \frac{\delta\mu}{2} \\ \beta_2 = \beta_0 - \frac{\delta\beta}{2}, \mu_2 = \mu_0 + \frac{\delta\mu}{2}}} = \left(1 + \frac{\delta\beta}{2} \frac{\partial}{\partial\beta_1} - \frac{\delta\beta}{2} \frac{\partial}{\partial\beta_2} - \frac{\delta\mu}{2} \frac{\partial}{\partial\mu_1} + \frac{\delta\mu}{2} \frac{\partial}{\partial\mu_2}\right) \rho_{mm} \Big|_{\substack{\beta_1 = \beta_0, \mu_1 = \mu_0 \\ \beta_2 = \beta_0, \mu_2 = \mu_0}} \quad (49)$$

+higher order corrections

Using the symmetry (in 1, 2) of ρ_{mm} at $\delta\beta = \delta\mu = 0$:

$$\frac{\partial\rho_{mm}}{\partial\beta_1} \Big|_{\substack{\beta_1 = \beta_0, \mu_1 = \mu_0 \\ \beta_2 = \beta_0, \mu_2 = \mu_0}} = \frac{\partial\rho_{mm}}{\partial\beta_2} \Big|_{\substack{\beta_1 = \beta_0, \mu_1 = \mu_0 \\ \beta_2 = \beta_0, \mu_2 = \mu_0}}, \quad \frac{\partial\rho_{mm}}{\partial\mu_1} \Big|_{\substack{\beta_1 = \beta_0, \mu_1 = \mu_0 \\ \beta_2 = \beta_0, \mu_2 = \mu_0}} = \frac{\partial\rho_{mm}}{\partial\mu_2} \Big|_{\substack{\beta_1 = \beta_0, \mu_1 = \mu_0 \\ \beta_2 = \beta_0, \mu_2 = \mu_0}} \quad (50)$$

all the cross terms in (49) cancel and we obtain

$$\rho_{mm} \Big|_{\substack{\beta_1 = \beta_0 + \frac{\delta\beta}{2}, \mu_1 = \mu_0 - \frac{\delta\mu}{2} \\ \beta_2 = \beta_0 - \frac{\delta\beta}{2}, \mu_2 = \mu_0 + \frac{\delta\mu}{2}}} = \rho_{mm} \Big|_{\substack{\beta_1 = \beta_0, \mu_1 = \mu_0 \\ \beta_2 = \beta_0, \mu_2 = \mu_0}} + (\text{corrections of order } \geq 2). \quad (51)$$

Therefore as far as we consider $J_{j,mn}^{(E)}$ up to the first order in $\delta\beta$ and $\delta\mu$ (linear transport regime) we can replace ρ_{mm} in the definition (38) into

$$\tilde{\rho}_{mm} = \rho_{mm} \Big|_{\substack{\beta_1 = \beta_0, \mu_1 = \mu_0 \\ \beta_2 = \beta_0, \mu_2 = \mu_0}} \quad (52)$$

Using

$$\text{Re}\gamma_{-,1,\epsilon_m-\epsilon_n} - \text{Re}\gamma_{-,2,\epsilon_m-\epsilon_n} = \gamma_{mn} \left(\delta\beta \frac{\partial}{\partial\beta_0} - \delta\mu \frac{\partial}{\partial\mu_0} \right) \frac{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0}}{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0} - 1} + \text{higher order correction} \quad (53a)$$

$$\text{Re}\gamma_{+,1,\epsilon_m-\epsilon_n} - \text{Re}\gamma_{+,2,\epsilon_m-\epsilon_n} = \gamma_{mn} \left(\delta\beta \frac{\partial}{\partial\beta_0} - \delta\mu \frac{\partial}{\partial\mu_0} \right) \frac{1}{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0} - 1} + \text{higher order correction} \quad (53b)$$

$$\gamma_{mn} = \pi \int_{k \in \Omega_{mn}} dk |g_{0,\epsilon_m-\epsilon_n}(k)|^2 \delta(\omega(k) - (\epsilon_m - \epsilon_n)) \quad (53c)$$

we get (we denote the approximate currents $\tilde{J}_{j,mn}^{(E)}$)

$$\begin{aligned} \tilde{J}_{2 \rightarrow 1, mn} &:= \frac{1}{2} (\tilde{J}_{1, mn} - \tilde{J}_{2, mn}) \\ &= \gamma_{mn} \left(\tilde{\rho}_{mm} \left(\delta\beta \frac{\partial}{\partial\beta_0} - \delta\mu \frac{\partial}{\partial\mu_0} \right) \frac{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0}}{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0} - 1} - \tilde{\rho}_{nn} \left(\delta\beta \frac{\partial}{\partial\beta_0} - \delta\mu \frac{\partial}{\partial\mu_0} \right) \frac{1}{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0} - 1} \right) \\ &= \frac{\gamma_{mn}}{\tilde{Z}} \left[\tilde{\rho}_{mm} \left(\frac{\delta\beta}{\beta_0} (\epsilon_m - \epsilon_n - \mu_0) - \delta\mu \right) \frac{\partial}{\partial(\epsilon_m - \epsilon_n)} \frac{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0}}{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0} - 1} \right. \\ &\quad \left. - \tilde{\rho}_{nn} \left(\frac{\delta\beta}{\beta_0} (\epsilon_m - \epsilon_n - \mu_0) - \delta\mu \right) \frac{\partial}{\partial(\epsilon_m - \epsilon_n)} \frac{1}{e^{(\epsilon_m-\epsilon_n-\mu_0)\beta_0} - 1} \right] \end{aligned} \quad (54)$$

$$J_{2 \rightarrow 1, mn}^E = (\epsilon_m - \epsilon_n) J_{2 \rightarrow 1, mn} \quad (55)$$

In addition, if $\epsilon_m \gg \mu_0 \gg \delta\mu$, by the equilibrium approximation

$$\tilde{\rho}_{mm} = \frac{1}{\tilde{Z}} e^{-\beta_0 \epsilon_m}, \quad \tilde{Z} = \sum_m e^{-\beta_0 \epsilon_m}, \quad (56a)$$

one can see

$$\tilde{J}_{2 \rightarrow 1, mn}^{(E)} = \tilde{J}_{1, mn}^{(E)} = -\tilde{J}_{2, mn}^{(E)} \neq 0, \quad (56b)$$

which hold the condition (46).

From this it is clear that, for the system S (say atom), the non-equilibrium effects appear as *first order* effects in the currents (56b), but only as *second order* terms in the state. This suggests a theoretical explanation of both the empirical success and the limitations of Kubo linear response theory.

Let us show a relation [18] between the two currents $\tilde{J}_{1 \rightarrow 2, mn}$ and $\tilde{J}_{1 \rightarrow 2, mn}^Q = \tilde{J}_{1 \rightarrow 2, mn}^E - \mu_0 \tilde{J}_{1 \rightarrow 2, mn}$, which is the analogue of the famous Onsager relation between the electric and heat currents in the conductivity problem. It is only an analogy because the carrier of our currents is a Boson particle and not Fermion (electron). From (54),

$$\begin{bmatrix} \tilde{J}_{1 \rightarrow 2, mn} \\ \tilde{J}_{1 \rightarrow 2, mn}^Q \end{bmatrix} = \begin{bmatrix} \Gamma_{mn} & L_{mn} \\ L_{mn} & M_{mn} \end{bmatrix} \begin{bmatrix} \delta\mu_0 \\ \frac{\delta\beta}{\beta_0} \end{bmatrix} \quad (57a)$$

where

$$\begin{aligned} \Gamma_{mn} &= -\gamma_{mn} \left(\tilde{\rho}_{mm} \frac{\partial}{\partial(\epsilon_m - \epsilon_n)} \frac{e^{(\epsilon_m - \epsilon_n - \mu_0)\beta_0}}{e^{(\epsilon_m - \epsilon_n - \mu_0)\beta_0} - 1} - \tilde{\rho}_{nn} \frac{\partial}{\partial(\epsilon_m - \epsilon_n)} \frac{1}{e^{(\epsilon_m - \epsilon_n - \mu_0)\beta_0} - 1} \right) \\ &= \frac{\gamma_{mn} \beta_0 e^{(\epsilon_m - \epsilon_n - \mu_0)\beta_0}}{(e^{(\epsilon_m - \epsilon_n - \mu_0)\beta_0} - 1)^2} (\tilde{\rho}_{mm} - \tilde{\rho}_{nn}) \quad (< 0 \text{ when (44) holds.}) \end{aligned} \quad (57b)$$

$$L_{mn} = -(\epsilon_m - \epsilon_n - \mu_0)\Gamma_{mn}, \quad M_{mn} = -(\epsilon_m - \epsilon_n + \mu_0)^2\Gamma_{mn} \quad (57c)$$

or we obtain explicitly

$$\frac{\partial \tilde{J}_{1 \rightarrow 2, mn}}{\partial \left(\frac{\delta\beta}{\beta_0} \right)} = \frac{\partial \tilde{J}_{1 \rightarrow 2, mn}^Q}{\partial \delta\mu} = L_{mn}, \quad (58)$$

which is the Onsager reciprocal relation.

One can easily see that these currents produce positive entropy. Following [1], the entropy production with these currents is given as

$$\begin{aligned} \sigma &: = \beta_0 \left(\tilde{J}_{1 \rightarrow 2, mn}(-\delta\mu) + \tilde{J}_{1 \rightarrow 2, mn}^Q \frac{\delta\beta}{\beta_0} \right) \\ &= \beta_0 \left(-\Gamma_{mn} \delta\mu^2 - 2L_{mn} \delta\mu \frac{\delta\beta}{\beta_0} + M_{mn} \left(\frac{\delta\beta}{\beta_0} \right)^2 \right), \end{aligned} \quad (59)$$

and as far as (44) holds, since $L_{mn}^2 + \Gamma_{mn} M_{mn} = 0$, δS is positive for any $(\delta\mu, \delta\beta)$ except for

$$\delta\mu = \delta\beta = 0, \quad \delta\mu = (\epsilon_m - \epsilon_n - \mu_0) \frac{\delta\beta}{\beta_0} \quad (60)$$

which imply $\tilde{J}_{1 \rightarrow 2, mn}^{(E)} = 0$.

As is well known, Onsager reciprocal relation is understood as a consequence of microscopic symmetry of the dynamics, based on the following two assumptions [18]: (i) There exists an intermediate time scale between macro and micro dynamics. (ii) Average of spontaneous thermal fluctuation of the microscopic observable decaying is described by macroscopic transport theory. Notice that both the above assumptions were deduced in our model from the stochastic limit. (i) corresponds to the fact that the convergence to the stationary state of the system is described in the rescaled time scale. This time scale is exactly the time scale used in assumption (i). Moreover what the stochastic limit tells us is that the dynamics of the currents (or the transport coefficients) are given in terms of the time correlations of the original field in the initial state. This is nothing but the situation described by assumption (ii). In the context of derivation of the Onsager relation between heat and electric currents by linear response theory, since there is no Hamiltonian which can describe the force generating a heat current whereas chemical potential can be treated always dynamically, (ii) has to be required as assumption [20]. In the present paper, both temperature and chemical potential are treated as parameters of the environment fields in the framework of the quantum mechanics for an open system. Moreover one should notice that the current is described directly in terms of the dynamics of the fields. It is also important to notice that the equilibrium state approximation (56) is not necessary to derive the Onsager relation (58). Usually, Onsager relation is derived assuming a symmetric property of the microscopic dynamics [18]. However as is discussed in the next section, this symmetric property is equivalent to the requirement that the state is equilibrium (see below (71)). Our results prove that the Onsager reciprocal relation (58) can be valid without any symmetry of the dynamics. Gabrielli, Jona-Lasinio and Landim illustrated such a possibility using a classical, solvable and phenomenological model [21].

IV. MASTER EQUATION CHARACTERIZATION OF DYNAMICAL DETAILED BALANCE

In the equilibrium case, it is well known that the detailed balance condition can be characterized by a generator of the master equation of the system interacting with the environment [16, 17]. Given the dynamical semigroup which drives the state to an equilibrium state

$$\frac{d}{dt}\rho_t = \mathcal{L}^* \rho_t, \quad \rho_t \rightarrow \rho_{eq}, \quad (61)$$

where

$$\text{tr}(X\mathcal{L}^*(\rho_t)) = \text{tr}(\rho_t\mathcal{L}(X)). \quad (62)$$

The detailed balance condition or KMS condition for ρ_{eq} is characterized by the following equations [17]:

$$\text{tr}(\rho_{eq}\mathcal{L}^+(A)B) := \text{tr}(\rho_{eq}A\mathcal{L}(B)) \quad \text{for all } A, B \quad (63a)$$

$$\mathcal{L}(X) - \mathcal{L}^+(X) = 2i[H, X] \quad (H = H^\dagger) \quad \text{for all } X \quad (63b)$$

In this section, we prove a generalization of the above characterization to non-equilibrium stationary states in terms of the dynamical detailed balance condition defined in the previous section.

We consider the forward and the backward Heisenberg evolution of a system operator X , i.e. (cf. [12] Chap I, section 1.1.29)

$$j_t^{(F)}(X) := U_t^\dagger X U_t \quad \text{for } t > 0, \quad j_t^{(B)}(X) := U_{-t} X U_{-t}^\dagger \quad \text{for } t < 0 \quad (64)$$

where U_t is the time evolution operator in interaction picture. After stochastic limit and in the notations (17), (23), these lead to the master equations for observables

$$\begin{aligned} \frac{d}{dt}\langle j_t^{(F)}(X) \rangle &= i[\Delta, \langle j_t^{(F)} \rangle] \\ &\quad - \sum_{\omega \in F} \left(\Gamma_{\omega-} \left(\frac{1}{2} \{ E_\omega^\dagger E_\omega, \langle j_t^{(F)}(X) \rangle \} - E_\omega^\dagger \langle j_t^{(F)}(X) \rangle E_\omega \right) \right. \\ &\quad \left. + \Gamma_{\omega+} \left(\frac{1}{2} \{ E_\omega E_\omega^\dagger, \langle j_t^{(F)}(X) \rangle \} - E_\omega \langle j_t^{(F)}(X) \rangle E_\omega^\dagger \right) \right) \\ &=: \mathcal{L}(\langle j_t^{(F)}(X) \rangle), \quad \text{for } t \geq 0 \end{aligned} \quad (65a)$$

$$\begin{aligned} \frac{d}{dt}\langle j_t^{(B)}(X) \rangle &= i[\Delta, \langle j_t^{(B)} \rangle] \\ &\quad + \sum_{\omega \in F} \left(\Gamma_{\omega-} \left(\frac{1}{2} \{ E_\omega^\dagger E_\omega, \langle j_t^{(B)}(X) \rangle \} - E_\omega^\dagger \langle j_t^{(B)}(X) \rangle E_\omega \right) \right. \\ &\quad \left. + \Gamma_{\omega+} \left(\frac{1}{2} \{ E_\omega E_\omega^\dagger, \langle j_t^{(B)}(X) \rangle \} - E_\omega \langle j_t^{(B)}(X) \rangle E_\omega^\dagger \right) \right) \\ &=: -\mathcal{L}_B(\langle j_t^{(B)}(X) \rangle), \quad \text{for } t \leq 0. \end{aligned} \quad (65b)$$

where $\langle \cdot \rangle$ denotes partial trace of the field degrees of freedom. Through (62), the dual master equation (22) (for density matrices) is written as

$$\frac{d}{dt}\rho_S(t) = \mathcal{L}^* \rho_S(t), \quad t \geq 0. \quad (66)$$

Similarly, we introduce a master equation associated to \mathcal{L}_B as

$$\frac{d}{dt}\rho_S^{(B)}(t) = -\mathcal{L}_B^* \rho_S^{(B)}(t), \quad t \leq 0. \quad (67)$$

Both master equations have the same stationary state ρ_S (see (23) and (24)).

As easily seen from (65), with $\Delta = \Delta^\dagger$ given by (23) one has

$$\mathcal{L}(X) - \mathcal{L}_B(X) = 2i[\Delta, X]. \quad (68a)$$

By direct computation we obtain the deviation from the symmetry condition $\text{tr}(\rho_S x \mathcal{L}(y)) = \text{tr}(\rho_S \mathcal{L}_B(x)y)$ which characterizes equilibrium:

$$\begin{aligned} \text{tr}(\rho_S X \mathcal{L}(Y)) - \text{tr}(\rho_S \mathcal{L}_B(X)Y) &= \sum_{lm} X_{ll} Y_{mm} (\rho_{ll}(\Gamma_{-, \epsilon_l - \epsilon_m} + \Gamma_{+, \epsilon_m - \epsilon_l}) - \rho_{mm}(\Gamma_{-, \epsilon_m - \epsilon_l} + \Gamma_{+, \epsilon_l - \epsilon_m})) \\ &= \sum_{lm} X_{ll} Y_{mm} \theta(\epsilon_l - \epsilon_m)(J_{1,lm} + J_{2,lm}) - \theta(\epsilon_m - \epsilon_l)(J_{1,ml} + J_{2,ml}) \end{aligned} \quad (68b)$$

where

$$X_{ll} = \langle \epsilon_l | X | \epsilon_l \rangle, \quad Y_{mm} = \langle \epsilon_m | Y | \epsilon_m \rangle, \quad \rho_{ll} = \langle \epsilon_l | \rho_S | \epsilon_l \rangle. \quad (68c)$$

Choosing

$$X = |\epsilon_a\rangle\langle\epsilon_a| =: P_a, \quad Y = |\epsilon_b\rangle\langle\epsilon_b| =: P_b, \quad (69)$$

(68b) becomes

$$\text{tr}(\rho_S P_a \mathcal{L}(P_b)) - \text{tr}(\rho_S \mathcal{L}_B(P_a)P_b) = \theta(\epsilon_a - \epsilon_b)(J_{1,ab} + J_{2,ab}) - \theta(\epsilon_b - \epsilon_a)(J_{1,ba} + J_{2,ba}). \quad (70)$$

The left hand side describes the balance between two processes: transition from $|\epsilon_a\rangle$ to $|\epsilon_b\rangle$ and its converse in stationary state ρ_S . Thus (68) (or (70)) is a characterization of the dynamical detailed balance condition discussed the previous section. Remember usual detailed balance condition is characterized by (63) which is the case when the right hand side of (68b) is identically zero.

Notice that ρ_S is an equilibrium state when $J_{1,mn} + J_{2,mn} = 0$. Let us remark again that as far as linear approximation is concerned, $\tilde{J}_{1,mn} = \tilde{J}_{2,mn} = 0$ is not necessary to realize an equilibrium state $\tilde{\rho}_{eq}$ (the equilibrium approximation (56)) which follows the condition (63) up to the first order (see Sec.III B). In this case,

$$\begin{aligned} \text{tr}(\tilde{\rho}_{eq} X \mathcal{L}(Y)) - \text{tr}(\tilde{\rho}_{eq} \mathcal{L}_B(X)Y) &= \text{tr}(\tilde{\rho}_{eq} X \mathcal{L}(Y)) - \text{tr}(\tilde{\rho}_{eq} \mathcal{L}(X)Y) \\ &= 0 \end{aligned} \quad (71)$$

and it is exactly the symmetry of microscopic dynamics assumed in the original derivation of Onsager law[18].

V. LOCAL KMS CONDITION

The KMS condition is known to be a characterization of equilibrium states equivalent to the detailed balance condition. In this section, we prove that a generalization of the KMS condition which characterizes the state described with the dynamical detailed balance condition.

First, we introduce a generalization of the KMS condition which distinguishes between those general density matrices which commutes with a given discrete Hamiltonian and those which are function of the given Hamiltonian. This condition, which we call *local KMS condition* in the sense of energy space, can describe states with mode-dependent temperatures

Given a discrete spectrum Hamiltonian H_S :

$$H_S = \sum_{\epsilon} \epsilon P_{\epsilon} \quad , \quad P_{\epsilon} = |\epsilon\rangle\langle\epsilon| \quad , \quad H_S |\epsilon\rangle = \epsilon |\epsilon\rangle \quad (72)$$

For any complex valued Borel function $f : \mathbb{R} \rightarrow \mathbb{C}$ the map $x \mapsto e^{itf(H_S)} x e^{-itf(H_S)}$ is defined by the spectral theorem and one has

$$x(t) := e^{itf(H_S)} x e^{-itf(H_S)} = \sum_{\epsilon, \epsilon'} e^{it(f(\epsilon) - f(\epsilon'))} P_{\epsilon} x P_{\epsilon'} = \sum_{\delta \in B_f} e^{it\delta} E_{\delta}^f(x) \quad (73a)$$

where

$$B_f := \{f(\epsilon) - f(\epsilon'); \forall \epsilon, \epsilon'\} \quad , \quad E_{\delta}^f(x) := \sum_{\epsilon, \epsilon' : f(\epsilon) - f(\epsilon') = \delta} P_{\epsilon} x P_{\epsilon'}. \quad (73b)$$

For such Hamiltonian H_S the following theorem holds:

Theorem 1. For a density matrix ρ and the corresponding state $\langle\langle \cdot \rangle\rangle$ the following are equivalent:

(i) There exists a real valued Borel function $\beta : \mathbb{R} \rightarrow \mathbb{R}$ such that $\exp -\beta(H_S)H_S$ is trace class and

$$\rho = \frac{1}{Z} e^{-\beta(H_S)H_S} \quad (74a)$$

(ii) There exists a real valued Borel function $\beta : \mathbb{R} \rightarrow \mathbb{R}$ such that $\exp -\beta(H_S)H_S$ is trace class and ρ satisfies the following local KMS condition with respect to the Heisenberg dynamics $x \mapsto e^{itH_S} x e^{-itH_S}$:

$$\forall x, y, t, \quad \langle\langle xy(t + i\beta(H_S)) \rangle\rangle = \langle\langle y(t)x \rangle\rangle \quad (74b)$$

where the meaning of $y(t + i\beta(H_S))$ is given by (73a).

Proof.

(74a) \Rightarrow (74b).

$$\langle\langle xy(t + i\beta(H_S)) \rangle\rangle = \text{tr} \left(\rho x e^{-\beta(H_S)H_S} y(t) e^{+\beta(H_S)H_S} \right) = \frac{1}{Z} \text{tr} \left(x e^{-\beta(H_S)H_S} y(t) \right) = \text{tr} (y(t)x\rho) = \langle\langle y(t)x \rangle\rangle \quad (75)$$

(74b) \Rightarrow (74a).

(74b) means that for all x, y and for all t

$$\text{tr} \left(e^{-\beta(H_S)H_S} y(t) e^{+\beta(H_S)H_S} \rho x \right) = \text{tr} (\rho y(t)x) \quad (76)$$

Therefore for all y and for all t

$$e^{-\beta(H_S)H_S} y(t) e^{+\beta(H_S)H_S} \rho = \rho y(t) \quad (77)$$

or equivalently, putting $t = 0$ and replacing y by $y e^{-\beta(H_S)H_S}$

$$e^{-\beta(H_S)H_S} y \rho = \rho e^{\beta(H_S)H_S} y \quad (78)$$

hence, putting $y = 1$

$$e^{\beta(H_S)H_S} \rho = \rho e^{\beta(H_S)H_S} \quad (79)$$

(78),(79) imply that, for all y

$$y e^{\beta(H_S)H_S} \rho = e^{\beta(H_S)H_S} \rho y \quad (80)$$

and this implies that, for some scalar λ

$$e^{\beta(H_S)H_S} \rho = \lambda 1 \quad (81)$$

Since $\text{tr}(\rho) = 1$, (81) implies that

$$\rho = \frac{1}{Z} e^{-\beta(H_S)H_S}. \quad (82)$$

(Q.E.D)

Notice that when $\beta(H_S) = \beta$ (constant), the state (74a) is the Gibbs state at temperature β^{-1} and (74b) becomes the KMS condition.

We shall prove that this local KMS condition (74) is equivalent to the dynamical detailed balance condition (68). To avoid infinite-valued functions, we assume that all the ρ_u are strictly positive and we represent the stationary solution ρ_S of (66) and (67) in the form

$$\rho_S = \frac{1}{Z} e^{-\beta_S(H_S)H_S}, \quad \beta_S(\epsilon_l) = -\frac{1}{\epsilon_l} \log \rho_u. \quad (83)$$

For such state the following theorem holds:

Theorem 2. The dynamical detailed balance condition (68) holds if and only if the local KMS condition (74) is satisfied.

Proof. (74) \Rightarrow (68).

Applying the local KMS-condition (74) to this state, we get

$$\langle\langle AB \rangle\rangle = \langle\langle B(-i\beta_S(H_S))A \rangle\rangle, \quad (84)$$

In addition in the notations (17), (23) and using relations

$$\Delta(-i\beta_S(H_S)) = \Delta \quad (85a)$$

$$E_{\epsilon_m - \epsilon_n}(-i\beta_S(H_S)) = e^{\beta_S(\epsilon_n)\epsilon_n - \beta_S(\epsilon_m)\epsilon_m} E_{\epsilon_m - \epsilon_n}, \quad E_{\epsilon_m - \epsilon_n}^\dagger(-i\beta_S(H_S)) = e^{\beta_S(\epsilon_m)\epsilon_m - \beta_S(\epsilon_n)\epsilon_n} E_{\epsilon_m - \epsilon_n}^\dagger, \quad (85b)$$

we obtain

$$\begin{aligned} \langle\langle X[\Delta, Y] \rangle\rangle &= \langle\langle X\Delta Y - \Delta(-i\beta_S(H_S))XY \rangle\rangle \\ &= \langle\langle X\Delta Y - \Delta XY \rangle\rangle \\ &= \langle\langle [X, \Delta]Y \rangle\rangle \end{aligned} \quad (86a)$$

$$\begin{aligned} \langle\langle X\{E_{\epsilon_m - \epsilon_n}^\dagger E_{\epsilon_m - \epsilon_n}, Y\} \rangle\rangle &= \langle\langle XE_{\epsilon_m - \epsilon_n}^\dagger E_{\epsilon_m - \epsilon_n} Y + XY E_{\epsilon_m - \epsilon_n}^\dagger E_{\epsilon_m - \epsilon_n} \rangle\rangle \\ &= \langle\langle XE_{\epsilon_m - \epsilon_n}^\dagger E_{\epsilon_m - \epsilon_n} Y + E_{\epsilon_m - \epsilon_n}^\dagger(-i\beta_S(H_S))E_{\epsilon_m - \epsilon_n}(-i\beta_S(H_S))XY \rangle\rangle \\ &= \langle\langle XE_{\epsilon_m - \epsilon_n}^\dagger E_{\epsilon_m - \epsilon_n} Y + E_{\epsilon_m - \epsilon_n}^\dagger E_{\epsilon_m - \epsilon_n} XY \rangle\rangle \\ &= \langle\langle \{X, E_{\epsilon_m - \epsilon_n}^\dagger E_{\epsilon_m - \epsilon_n}\}Y \rangle\rangle \end{aligned} \quad (86b)$$

$$\langle\langle XE_{\epsilon_m - \epsilon_n}^\dagger Y E_{\epsilon_m - \epsilon_n} \rangle\rangle = e^{\beta_S(\epsilon_n)\epsilon_n - \beta_S(\epsilon_m)\epsilon_m} \langle\langle E_{\epsilon_m - \epsilon_n} X E_{\epsilon_m - \epsilon_n}^\dagger Y \rangle\rangle \quad (86c)$$

$$\langle\langle XE_{\epsilon_m - \epsilon_n} Y E_{\epsilon_m - \epsilon_n}^\dagger \rangle\rangle = e^{\beta_S(\epsilon_m)\epsilon_m - \beta_S(\epsilon_n)\epsilon_n} \langle\langle E_{\epsilon_m - \epsilon_n}^\dagger X E_{\epsilon_m - \epsilon_n} Y \rangle\rangle. \quad (86d)$$

Now let us define \mathcal{L}_G^+ by the relation:

$$\langle\langle \mathcal{L}_G^+(X)Y \rangle\rangle := \langle\langle X\mathcal{L}(Y) \rangle\rangle \quad (87)$$

for \mathcal{L} given by (65a). Notice that we are defining \mathcal{L}_G^+ not only in equilibrium state but also in the non-equilibrium stationary state which is described with the local KMS condition (74), unlike (63a). Using relation (86), we find ($\omega = \epsilon_m - \epsilon_n$)

$$\begin{aligned} \mathcal{L}_G^+(X) &= -i[\Delta, X] - \sum_{\omega \in F} \left(\Gamma_{-, \omega} \left(\frac{1}{2} \{E_\omega^\dagger E_\omega, X\} - E_\omega^\dagger X E_\omega \right) + \Gamma_{+, \omega} \left(\frac{1}{2} \{E_\omega E_\omega^\dagger, X\} - E_\omega X E_\omega^\dagger \right) \right) \\ &\quad + \sum_{\omega \in F} \left((\Gamma_{+, \omega} e^{\beta_S(\epsilon_m)\epsilon_m - \beta_S(\epsilon_n)\epsilon_n} - \Gamma_{-, \omega}) E_\omega^\dagger X E_\omega + (\Gamma_{-, \omega} e^{\beta_S(\epsilon_n)\epsilon_n - \beta_S(\epsilon_m)\epsilon_m} - \Gamma_{+, \omega}) E_\omega X E_\omega^\dagger \right) \\ &= \mathcal{L}_B(X) + \sum_{\omega \in F} \hat{\Pi}_\omega(X) \end{aligned} \quad (88a)$$

$$\hat{\Pi}_\omega(X) = (\Gamma_{+, \omega} e^{\beta_S(\epsilon_m)\epsilon_m - \beta_S(\epsilon_n)\epsilon_n} - \Gamma_{-, \omega}) E_\omega^\dagger X E_\omega + (\Gamma_{-, \omega} e^{\beta_S(\epsilon_n)\epsilon_n - \beta_S(\epsilon_m)\epsilon_m} - \Gamma_{+, \omega}) E_\omega X E_\omega^\dagger \quad (88b)$$

(87) and (88) mean

$$\langle\langle X\mathcal{L}(Y) \rangle\rangle = \langle\langle \mathcal{L}_B(X)Y \rangle\rangle + \sum_{\omega \in F} \langle\langle \hat{\Pi}_\omega(X)Y \rangle\rangle \quad (89)$$

and

$$\begin{aligned} \sum_{\omega \in F} \langle\langle \hat{\Pi}_\omega(X)Y \rangle\rangle &= \sum_{\omega \in F} \text{tr} \left(\frac{e^{-\beta_S(H_S)H_S}}{Z} \left((\Gamma_{+, \omega} e^{\beta_S(\epsilon_m)\epsilon_m - \beta_S(\epsilon_n)\epsilon_n} - \Gamma_{-, \omega}) E_\omega^\dagger X E_\omega \right. \right. \\ &\quad \left. \left. + (\Gamma_{-, \omega} e^{\beta_S(\epsilon_n)\epsilon_n - \beta_S(\epsilon_m)\epsilon_m} - \Gamma_{+, \omega}) E_\omega X E_\omega^\dagger \right) Y \right) \\ &= \sum_{\epsilon_m, \epsilon_n} (X_{nn} Y_{mm} (\Gamma_{+, \epsilon_m - \epsilon_n} \rho_{nn} - \Gamma_{-, \epsilon_m - \epsilon_n} \rho_{mm}) \\ &\quad + X_{mm} Y_{nn} (\Gamma_{-, \epsilon_m - \epsilon_n} \rho_{mm} - \Gamma_{+, \epsilon_m - \epsilon_n} \rho_{nn})) \\ &= \sum_{\epsilon_m, \epsilon_n} X_{nn} Y_{mm} (\Gamma_{+, \epsilon_m - \epsilon_n} \rho_{nn} - \Gamma_{-, \epsilon_m - \epsilon_n} \rho_{mm} + \Gamma_{-, \epsilon_n - \epsilon_m} \rho_{nn} - \Gamma_{+, \epsilon_n - \epsilon_m} \rho_{mm}) \\ &= \sum_{\epsilon_m, \epsilon_n} X_{nn} Y_{mm} \theta(\epsilon_n - \epsilon_m) (J_{1, nm} + J_{2, nm}) - \theta(\epsilon_m - \epsilon_n) (J_{1, mn} + J_{2, mn}) \end{aligned} \quad (90)$$

(89) and (90) is exactly the dynamical detailed balance condition (68).

(68) \Rightarrow (74).

Following (84)~(90) conversely, we see that the dynamical detailed balance condition (68) implies

$$\text{tr}(\rho_S X \mathcal{L}(Y)) = \text{tr}\left(\rho_S e^{\beta_S(H_S)H_S} \mathcal{L}(Y) e^{-\beta_S(H_S)H_S} X\right), \quad \forall X, Y. \quad (91)$$

For off diagonal type operator

$$\tilde{y} = \sum_{m \neq n} C_{mn} |\epsilon_m\rangle \langle \epsilon_n|$$

there exists Y such that

$$\mathcal{L}(Y) = \tilde{y} \quad (92)$$

and putting $\tilde{y} = e^{itH_S} y e^{-itH_S}$ (y is also off diagonal type) we get

$$\text{tr}(\rho_S X e^{itH_S} y e^{-itH_S}) = \text{tr}\left(\rho_S e^{\beta_S(H_S)H_S} e^{itH_S} y e^{-itH_S} e^{-\beta_S(H_S)H_S} X\right), \quad \forall X.$$

or

$$\text{tr}(\rho_S X y(t)) = \text{tr}(\rho_S y(t + i\beta_S(H_S)) X), \quad \forall X. \quad (93)$$

In addition, since ρ_{st} is diagonal, (93) is always satisfied with any diagonal type operator $y = \sum_m C_{mm} |\epsilon_m\rangle \langle \epsilon_m|$ also. Therefore, (93) is always satisfied with any operator X and y .

(Q.E.D)

Notice that since

$$\mathcal{L}_G^+(1) = \sum_{\omega} \hat{\Pi}_{\omega}(1) \neq 0$$

in the non-equilibrium case, \mathcal{L}_G^+ cannot be a generator of any dynamical semigroup whereas \mathcal{L}_B always exists as generator of dynamical semigroup. This is also one of the particular properties of the non-equilibrium state. In an equilibrium case, as we have seen $\beta_S(x)$ become a constant β which is the same inverse temperature of the environment fields, and the equality $\Gamma_{+,\omega}/\Gamma_{-,\omega} = e^{-\beta \cdot (\epsilon_m - \epsilon_n)}$ holds, i.e. $\hat{\Pi}_{\omega}(X) = 0$ which implies $\mathcal{L}_B = \mathcal{L}_G^+$.

VI. INTERACTION WITH NON-EQUILIBRIUM FIELD

In the previous sections, we considered the non-equilibrium stationary states of a system driven by two environments at two different temperatures and we discussed several characterizations of such states. In this section, applying these characterizations to the state of the environment, we consider a system interacting with an environment in local equilibrium. (On the local KMS condition for the field degrees of freedom, see the next section.) One will see not only that the stationary state of the system driven by such non-equilibrium environment can be characterized as for the previous model, but also that interesting non-linear effects due to the interaction with non-equilibrium environment exist whose physical meaning is different from the previous model.

We consider a system interacting with a single boson field whose state is described by a generalized temperature function. Technically, the analysis of the model can be done in the same way as the previous one. Instead of (12) but similarly, the Hamiltonian

$$H = H_0 + \lambda H_I, \quad (\lambda \text{ is a coupling constant.}) \quad (94a)$$

$$H_0 = H_S + H_B, \quad H_S = \sum_l \epsilon_l |\epsilon_l\rangle \langle \epsilon_l|, \quad H_B = \int \omega(k) a_k^\dagger a_k \quad [a_k, a_{k'}^\dagger] = \delta(k - k'), \quad (94b)$$

$$H_I = \int dk \left(g(k) D a_k^\dagger + g^*(k) D^\dagger a_k \right). \quad (94c)$$

On the other hand, we assume that the initial state of the field is a mean zero gauge invariant Gaussian state with correlations:

$$\langle a_k^\dagger a_{k'} \rangle = N(k) \delta(k - k'), \quad N(k) = \frac{1}{e^{\beta(\omega(k))\omega(k)} - 1} \quad (95)$$

where $\beta(\omega(k))$ is some positive function. This is a natural generalization of the Gibbs factor to which it reduces when $\beta(\omega)$ is constant:

$$\beta(\omega) = \beta. \quad (96)$$

Exactly in the same way as in the previous argument, one can derive the white noise Hamiltonian equation

$$\frac{d}{dt} U_t = -i \sum_{\omega \in F} \left(E_\omega b_{t;\omega}^\dagger + E_\omega^\dagger b_{t;\omega} \right) U_t \quad (97)$$

where

$$b_{t;\omega} = \int dk g_\omega^*(k) b_{t;\omega}(k), \quad b_{t;\omega}(k) = \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} e^{-i(\omega_j(k) - \omega)t/\lambda^2} a_k. \quad (98)$$

The state of the limit white noise will be of the same type with correlations

$$\langle b_{t;\omega}^\dagger(k) b_{t';\omega'}(k') \rangle = \delta_{\omega\omega'} 2\pi \delta(t - t') \delta(k - k') \delta(\omega(k) - \omega) N(k) \quad (99a)$$

$$\langle b_{t;\omega}(k) b_{t';\omega'}^\dagger(k') \rangle = \delta_{\omega\omega'} 2\pi \delta(t - t') \delta(k - k') \delta(\omega(k) - \omega) (N(k) + 1). \quad (99b)$$

Finally we obtain the master equation (22) but with different parameters

$$\Delta = i \sum_{\omega \in F} \left(\text{Im}(\gamma_{-\omega}) E_\omega^\dagger E_\omega - \text{Im}(\gamma_{+\omega}) E_\omega E_\omega^\dagger \right) \quad (100a)$$

$$\Gamma_{\mp, \omega} = 2\text{Re} \gamma_{\mp, \omega} \geq 0, \quad (\Gamma_{\mp, \omega} = 0 \quad \text{for} \quad \omega \leq 0). \quad (100b)$$

where

$$\begin{aligned} \gamma_{-, \omega} &= \int dk |g_\omega(k)|^2 \frac{-i(N(k) + 1)}{\omega - \omega(k) - i0} \\ &= \pi \int dk |g_\omega(k)|^2 \frac{e^{\beta(\omega(k))\omega(k)}}{e^{\beta(\omega(k))\omega(k)} - 1} \delta(\omega(k) - \omega) - i\text{P.P} \int dk \frac{|g_\omega(k)|^2}{\omega(k) - \omega} \frac{e^{\beta(\omega(k))\omega(k)}}{e^{\beta(\omega(k))\omega(k)} - 1} \end{aligned} \quad (100c)$$

$$\begin{aligned} \gamma_{+, \omega} &= \int dk |g_\omega(k)|^2 \frac{-iN(k)}{\omega - \omega(k) - i0} \\ &= \pi \int dk |g_\omega(k)|^2 \frac{1}{e^{\beta(\omega(k))\omega(k)} - 1} \delta(\omega(k) - \omega) - i\text{P.P} \int dk \frac{|g_\omega(k)|^2}{\omega(k) - \omega} \frac{1}{e^{\beta(\omega(k))\omega(k)} - 1}. \end{aligned} \quad (100d)$$

As in the previous model, the off-diagonal elements vanish when $G_{mn} \neq 0$, ($\forall m, n$) which is defined in (23c). In order to see if the stationary state can violate the detailed balance condition or not, let us check condition (26). With direct computation we find

$$\frac{\Gamma_{ml}}{\Gamma_{lm}} = e^{+\beta(\epsilon_m - \epsilon_l)(\epsilon_m - \epsilon_l)} \quad \text{for} \quad \epsilon_m > \epsilon_l \quad (101a)$$

$$\frac{\Gamma_{ml}}{\Gamma_{lm}} = e^{-\beta(\epsilon_l - \epsilon_m)(\epsilon_l - \epsilon_m)} \quad \text{for} \quad \epsilon_m < \epsilon_l \quad (101b)$$

Let us remark this fraction does not depend on the structure function $g(k)$ unlike the previous model, however it can violate condition (26) due to the generalized temperature function $\beta(\omega)$, i.e.

$$\frac{\Gamma_{ml}}{\Gamma_{lm}} \neq \frac{\Gamma_{mk}}{\Gamma_{km}} \frac{\Gamma_{kl}}{\Gamma_{lk}} \quad (102)$$

except for the constant temperature case (96).

Let us show a typical example of non-equilibrium effects due to the generalized temperature function. To realize the stationary state with non-detailed balance condition at least, two Bohr frequencies (three level system) are necessary. With a generic 3-level system, whose energy levels are given by $\epsilon_1 < \epsilon_2 < \epsilon_3$ and $\epsilon_3 - \epsilon_2 \neq \epsilon_2 - \epsilon_1$: the concrete form of the matrix A in (24) is written as

$$A = \begin{pmatrix} \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} & -\Gamma_{-, \epsilon_2 - \epsilon_1} & -\Gamma_{-, \epsilon_3 - \epsilon_1} \\ -\Gamma_{+, \epsilon_2 - \epsilon_1} & \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} & -\Gamma_{-, \epsilon_3 - \epsilon_2} \\ -\Gamma_{+, \epsilon_3 - \epsilon_1} & -\Gamma_{+, \epsilon_3 - \epsilon_2} & \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_2} \end{pmatrix} \quad (103)$$

and one can directly see that its eigenvalues are

$$\lambda = 0, \frac{b \pm \sqrt{b^2 - 4c}}{2} > 0, \quad (104a)$$

$$b = \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_2} + \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_2} \quad (104b)$$

$$c = \Gamma_{+, \epsilon_2 - \epsilon_1} \Gamma_{+, \epsilon_3 - \epsilon_2} + \Gamma_{+, \epsilon_2 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_1} + \Gamma_{+, \epsilon_2 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_2} + \Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{+, \epsilon_3 - \epsilon_2} \\ + \Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_2} + \Gamma_{-, \epsilon_2 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_1} + \Gamma_{-, \epsilon_2 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_2} + \Gamma_{+, \epsilon_3 - \epsilon_2} \Gamma_{-, \epsilon_3 - \epsilon_1} \quad (104c)$$

and the stationary state

$$\rho_{11} = \frac{1}{1 + X + Y}; \quad \rho_{22} = \frac{X}{1 + X + Y}; \quad \rho_{33} = \frac{Y}{1 + X + Y} \quad (105a)$$

where

$$\frac{\rho_{22}}{\rho_{11}} = \frac{\Gamma_{-, \epsilon_3 - \epsilon_1} \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_2} \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_2}}{\Gamma_{-, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_1} \Gamma_{+, \epsilon_3 - \epsilon_2} + \Gamma_{-, \epsilon_3 - \epsilon_2} \Gamma_{-, \epsilon_2 - \epsilon_1}} =: X \quad (105b)$$

$$\frac{\rho_{33}}{\rho_{11}} = \frac{\Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_2} \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{+, \epsilon_3 - \epsilon_2}}{\Gamma_{-, \epsilon_3 - \epsilon_2} \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_1} \Gamma_{+, \epsilon_3 - \epsilon_2}} =: Y \quad (105c)$$

$$\frac{\rho_{33}}{\rho_{22}} = \frac{\Gamma_{+, \epsilon_3 - \epsilon_2} \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_2} \Gamma_{+, \epsilon_3 - \epsilon_1}}{\Gamma_{-, \epsilon_3 - \epsilon_1} \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{-, \epsilon_3 - \epsilon_2} \Gamma_{+, \epsilon_2 - \epsilon_1} + \Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_2}} =: Z. \quad (105d)$$

When (26) is not satisfied, the above solution does not satisfy the detailed balance condition. Notice that in this case the detailed balance condition is equivalent to

$$\delta := \beta(\epsilon_2 - \epsilon_1)(\epsilon_2 - \epsilon_1) - \beta(\epsilon_3 - \epsilon_1)(\epsilon_3 - \epsilon_1) + \beta(\epsilon_3 - \epsilon_2)(\epsilon_3 - \epsilon_2) = 0. \quad (106)$$

Let us remark that the physics of this model can be different from the previous model. For example, taking $\langle \epsilon_1 | D | \epsilon_2 \rangle = 0$ (so as $\Gamma_{\pm, \epsilon_2 - \epsilon_1} = 0$) for simplicity, the above quotients become

$$\frac{\rho_{22}}{\rho_{11}} = \frac{\Gamma_{+, \epsilon_3 - \epsilon_1} \Gamma_{-, \epsilon_3 - \epsilon_2}}{\Gamma_{-, \epsilon_3 - \epsilon_1} \Gamma_{+, \epsilon_3 - \epsilon_2}} = e^{\beta(\epsilon_3 - \epsilon_2)(\epsilon_3 - \epsilon_2)} e^{-\beta(\epsilon_3 - \epsilon_1)(\epsilon_3 - \epsilon_1)} := X \quad (107a)$$

$$\frac{\rho_{33}}{\rho_{11}} = \frac{\Gamma_{+, \epsilon_3 - \epsilon_1}}{\Gamma_{-, \epsilon_3 - \epsilon_1}} = e^{-\beta(\epsilon_3 - \epsilon_1)(\epsilon_3 - \epsilon_1)} < 1, \quad \frac{\rho_{33}}{\rho_{22}} = \frac{\Gamma_{+, \epsilon_3 - \epsilon_2}}{\Gamma_{-, \epsilon_3 - \epsilon_2}} = e^{-\beta(\epsilon_3 - \epsilon_2)(\epsilon_3 - \epsilon_2)} < 1 \quad (107b)$$

and X is larger than 1 when

$$\beta(\epsilon_3 - \epsilon_2) > \frac{\epsilon_2 - \epsilon_1}{\epsilon_3 - \epsilon_2} \beta(\epsilon_3 - \epsilon_1) \quad (108)$$

Thus, for such temperature function $\beta(x)$ the stationary state satisfies $\rho_{22} > \rho_{11}$ which means that 2 is a so-called inversely populated state.

Here, we focus on the current passing through the stationary state and discuss the non-linear effects. For simplicity, we discuss the case of a three level system. In this case ($\epsilon_1 < \epsilon_2 < \epsilon_3$), with direct computation we obtain

$$\begin{aligned} J_{mn} &:= \int_{\Omega_{mn}} dk \langle U_t^\dagger n_k U_t \rangle \\ &= (-1)^{m+n+1} \frac{e^{\beta(\epsilon_2 - \epsilon_1)(\epsilon_2 - \epsilon_1) - \beta(\epsilon_3 - \epsilon_1)(\epsilon_3 - \epsilon_1) + \beta(\epsilon_3 - \epsilon_2)(\epsilon_3 - \epsilon_2)} - 1}{(e^{\beta(\epsilon_2 - \epsilon_1)(\epsilon_2 - \epsilon_1)} - 1)(e^{\beta(\epsilon_3 - \epsilon_2)(\epsilon_3 - \epsilon_2)} - 1)(1 - e^{-\beta(\epsilon_3 - \epsilon_1)(\epsilon_3 - \epsilon_1)})} I \end{aligned} \quad (109a)$$

$$J_{mn}^E := \int_{\Omega_{mn}} dk \omega(k) \langle U_t^\dagger n_k U_t \rangle = (\epsilon_m - \epsilon_n) J_{mn} \quad (109b)$$

$$\begin{aligned} I &= |\langle \epsilon_1 | D | \epsilon_2 \rangle|^2 \int_{k \in \Omega_{21}} dk |g(k)|^2 \delta(\omega(k) - (\epsilon_2 - \epsilon_1)) \\ &\quad \times |\langle \epsilon_2 | D | \epsilon_3 \rangle|^2 \int_{k \in \Omega_{32}} dk |g(k)|^2 \delta(\omega(k) - (\epsilon_3 - \epsilon_2)) \\ &\quad \times |\langle \epsilon_3 | D | \epsilon_1 \rangle|^2 \int_{k \in \Omega_{31}} dk |g(k)|^2 \delta(\omega(k) - (\epsilon_3 - \epsilon_1)) \end{aligned} \quad (109c)$$

Notice $J_{21}^{(E)}$ and $J_{32}^{(E)}$ have same (and $J_{31}^{(E)}$ has opposite) sign. In addition

$$J_{31}^{(E)} = -(J_{21}^{(E)} + J_{32}^{(E)}) \quad (110)$$

and the sign of each currents depends on

$$\delta := \beta(\epsilon_2 - \epsilon_1)(\epsilon_2 - \epsilon_1) - \beta(\epsilon_3 - \epsilon_1)(\epsilon_3 - \epsilon_1) + \beta(\epsilon_3 - \epsilon_2)(\epsilon_3 - \epsilon_2). \quad (111)$$

In the case $\delta = 0$, all currents vanish. Especially, when the function is a constant β (i.e. the initial state of the field is an equilibrium state with temperature β^{-1}), this is easily understood with the fact that the state of the system converges to the equilibrium state at the same temperature without any stationary currents. Notice that even within the linear approximation up to order δ , there is no local stationary state (with currents) which satisfies the detailed balance condition, unlike the previous model. In this model, the existence of currents always implies the deviation from the equilibrium.

Now let us see some interesting properties of the currents (109). In the case $\delta > 0$, we obtain from (109)

$$J_{21}^{(E)}, J_{32}^{(E)} > 0, \quad \text{and} \quad J_{13}^{(E)} < 0. \quad (112)$$

As clearly understood from the definition of the currents, the relation (112) is describing the process that a field quantum with energy $\epsilon_3 - \epsilon_1$ is converted into two quanta with energy $\epsilon_2 - \epsilon_1$ and $\epsilon_3 - \epsilon_2$. On the contrary when $\delta < 0$,

$$J_{21}^{(E)}, J_{32}^{(E)} < 0, \quad \text{and} \quad J_{13}^{(E)} > 0 \quad (113)$$

and this can be interpreted as a process from two quanta to one quantum. There are interesting analogies of these processes with parametric downconversion and second harmonic generation in non-linear quantum optics[22]. They are considered as opposite process of another. In our model, the direction of the process depends on the generalized temperature function $\beta(\omega)$ which is a parameter of the initial state of the field. This phenomenon can be understood as the fact that through interaction with a non-equilibrium field the system can have such a function, which is an example of dissipative structure in the Prigogine sense [1].

VII. DISCUSSION

In conclusion, let us further comment on a few related topics.

1) On the irreversibility and unitarity of time evolution.

As we discussed in Sec.III B, we can see irreversibility in this model through the entropy production (59) due to the stationary currents, which should be considered as processes involving the total system including the environment. On the other hand, the time evolution operator of the total system U_t is unitary in the sense that

$$U_t^\dagger U_t = U_t U_t^\dagger = 1, \quad t > 0, \quad (114)$$

which is easily checked by putting $X = 1$ in (21). These statements might seem to be contradiction. However, one should notice that the appearance of irreversibility has nothing to do with the unitarity of U_t . When the temperatures of both environments are the same, it is known that the unitarity condition (114) is required to realize a physical fluctuation-dissipation relation or a correct equilibrium stationary state [12]. Moreover, when we speak of macroscopic phenomena like entropy production, we need a good procedure to extract the proper degrees of freedom to discuss them. Since there exist same macroscopic states which are distinguishable microscopically from each other, not all microscopic degrees can be employed to discuss macroscopic properties. Indeed, the entropy production (59) is discussed in terms of what we call slow degrees of freedom, and the stochastic limit can be considered as the procedure of extracting the proper degrees of freedom. In other words, we extract information from the total dynamics as slow degrees which can describe the macroscopic phenomena.

2.) Local KMS condition for field.

A possible formulation of the local KMS condition for the field is the following.

Definition 1. A state $\langle \cdot \rangle$ on the polynomial algebra a_k, a_k^\dagger , is said to satisfy the local KMS condition with temperature function $\beta : \mathbb{R}^d \rightarrow \mathbb{R}$ if, for every $m, n \in \mathbb{N}$, $\varepsilon_1, \dots, \varepsilon_n, \eta_1, \dots, \eta_m \in \{0, 1\}$, and with the convention $x^0 = x^\dagger, x^1 = x$ for any operator x , the following identities hold in the sense of distributions.

$$\begin{aligned} \langle a_{k_1}^{\eta_1}(0) \dots a_{k_m}^{\eta_m}(0) a_{h_n}^{\varepsilon_n}(t + i\beta_{h_n}) a_{h_{n-1}}^{\varepsilon_{n-1}}(t + i\beta_{h_{n-1}}) \dots a_{h_1}^{\varepsilon_1}(t + i\beta_{h_1}) \rangle \\ = \langle a_{h_n}^{\varepsilon_n}(t) \dots a_{h_1}^{\varepsilon_1}(t) a_{k_1}^{\eta_1}(0) \dots a_{k_m}^{\eta_m}(0) \rangle. \end{aligned} \quad (115)$$

Lemma 1. Define the local inverse temperature function by

$$-\beta(k) := \left(\log \frac{n(k)}{m(k)} \right) \frac{1}{\omega_k}, \quad (116)$$

where

$$\langle a_k a_{k'}^\dagger \rangle =: m(k) \delta(k - k') = \frac{e^{\beta \omega_k}}{e^{\beta \omega_k} - q} = (qn(k) + 1) \delta(k - k') \quad (117)$$

($q = -1$ for Bosons and $q = +1$ for Fermions). Then the local KMS condition is satisfied by the 2-point functions:

$$\langle a_k(0) a_{k'}^\dagger(t + i\beta(k')) \rangle = \langle a_{k'}^\dagger(t) a_k \rangle \quad (118)$$

$$\langle a_k^\dagger(0) a_{k'}(t + i\beta(k')) \rangle = \langle a_{k'}(t) a_k^\dagger(0) \rangle \quad (119)$$

Proof. In the above notations, one has

$$\begin{aligned} \langle a_k(0) a_{k'}^\dagger(t + i\beta(k')) \rangle &= e^{i(t+i\beta(k'))\omega_{k'}} \langle a_k a_{k'}^\dagger \rangle = e^{-\beta(k')\omega_{k'}} e^{it\omega_{k'}} \langle a_k a_{k'}^\dagger \rangle \\ &= e^{it\omega_k} \frac{m(k)}{n(k)} n(k) \delta(k - k') = e^{it\omega_{k'}} m(k') \delta(k' - k) = e^{it\omega_{k'}} \langle a_{k'}^\dagger a_k \rangle = \langle a_{k'}^\dagger(t) a_k \rangle \end{aligned}$$

and this proves (118). In a similar way one verifies that (119) holds.

Proposition 1. If the state $\langle \cdot \rangle$ is mean zero gauge invariant and Boson Gaussian then condition (115) is satisfied.

Proof. By Gaussianity both sides of (115) are reduced to weighted sums of pair correlation functions. Since in both sides of (115) we can distinguish the (h, ε) -terms from the (k, η) -terms and since the pair correlations preserve the order, there will be 3 types of pair correlations: (i) those of type (h, k) , (ii) those of type (h, h) , (iii) those of type (k, k) .

In case (i), due to gauge invariance, the only none zero combinations are of the form $\langle aa^\dagger \rangle$ or $\langle a^\dagger a \rangle$ so we can apply (118) and (119).

In case (ii) the terms are already in the correct order.

In case (iii), again by gauge invariance, the only possibilities are

$$\begin{aligned} \langle a_h(t + i\beta_h)a_{h'}^\dagger(t + i\beta_{h'}) \rangle &= e^{-(t+i\beta_h)\omega_h} e^{i(t+i\beta_{h'})\omega_{h'}} \langle a_h a_{h'}^\dagger \rangle \\ &= e^{it(\omega_{h'} - \omega_h) + (\beta_h \omega_h - \beta_{h'} \omega_{h'})} \delta(h - h') \\ &= \langle a_h^\dagger(t) a_{h'}(t) \rangle \end{aligned} \quad (120)$$

and similarly for the other term.

Since in the Boson case the weight of each pair partition is equal to 1, after the replacements (118), (119), (120) the pair-partition expansion of the left hand side of (115) becomes the pair-partition expansion of the right hand side.

The validity of the local KMS condition for more general Gaussian states as well as for quantum Markov states is now under investigation.

3.) The generalized temperature function and its thermodynamics.

On the description of the generalized temperature function $\beta(H)$, R. S. Ingarden, A. Kossakowski, M. Ohya, T. Nakagomi have discussed similar idea in the context of information theory [23]. They introduce a system described by the density operator

$$\rho = \frac{1}{Z(\beta_1, \dots, \beta_n)} \exp \left(- \sum_{j=1}^n \beta_j H^j \right), \quad \beta_j > 0 \quad (121)$$

and discussed possible generalization of thermodynamics for structured complex systems (e.g. biological system) including bifurcations, catastrophes and self organization. As mentioned in their book [23], their phenomenological idea is in the line of thought of synergetics by Haken [24]. In the present paper, we explained the microscopic origin of such states and their physical meaning through the dynamical detailed balance condition. Through the local KMS condition a general classification of such non-equilibrium states became possible. We believe that our approach gives a good insight to generalization of thermodynamics in this direction.

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