



# Explaining Gabriel-Zisman localization to the computer

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# EXPLAINING GABRIEL-ZISMAN LOCALIZATION TO THE COMPUTER

CARLOS SIMPSON

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## 1. INTRODUCTION

We formalize the localization of categories, as in the book of Gabriel and Zisman [9], with the Coq computer proof assistant. The purpose of this preprint is to provide some discussion of this work. On the other hand, the computer files themselves are attached to the companion preprint “Files for Gabriel-Zisman localization”. The text of that preprint consists mainly of the definitions and statements of results from the computer files (in other words it is equal to the files with the proofs removed), plus some instructions for compiling the files.

There are several reasons for choosing this project. A certain amount of basic category theory was done in the files attached to my previous paper on this subject [30]. Thus it is natural to look for some further topics to do in category theory. A long-range goal is to be able to do the theory and practice of closed model categories. A glance at Quillen [23] suggests that the notion of localization of categories *à la* Gabriel-Zisman is an important component of the statements of some of Quillen’s main results. Also in philosophical terms it is clear that Quillen was influenced by Gabriel and Zisman, so it is reasonable to think that doing a computer formalization of their construction of localization would be a good warm-up exercise.

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*Key words and phrases.* Category, Functor, Localization, Calculus of fractions, Proof assistant, Computer proof verification.

A little bit of investigation into the bibliographical references for this construction has also turned up another interesting reason to formalize it on the computer. It turns out that the full details of the construction (and specially of the calculus of fractions construction) have never really appeared in print. Or at least, a search for these details has not turned up any reference. Of course it wouldn't be surprising to find a complete reference somewhere—you might say that this would be the expected normalcy. Nonetheless it seems pretty clear that the vast majority of the very numerous mathematicians who use this theory every day haven't in fact read a text with the full details written down.

The notion of localization of a category is foundational for some of the most popular tools used by mathematicians today: the homotopy category (of spaces, simplicial sets, or other things), and the derived category (of an abelian category, coming in various flavors). It is surprising that the theory is so hard to find written down in its integrality. This might contribute as part of an explanation for why the theories of homotopy categories and derived categories are so much used and considered as “black boxes”.

One possible point of view would be to say that few have bothered to try to publish the full details of the construction, because in a certain sense that just wouldn't be worth it: writing something down presupposes that there would be somebody interested in reading it; and writing down the full details of an argument which is in essence straightforward, presupposes that a human reader would desire to, and be capable of, verifying in a meaningful way that the written text really did contain all of the details. Factors such as the total cost of publication also push towards leaving out much of this type of argument.

In trying to write up the present note explaining the computer proof, it became evident that one had to agree with the other published texts on this: the full details of the argument just aren't sufficiently interesting to justify the rather extensive linguistic effort which would be required to accurately convey them to a human reader, nor interesting enough for the reader to bother reading such an explanation. And this is with a fundamental piece of category theory more than 40 years old. The arrival of the possibility that the “reader” might be a computer changes this calculation. The computer is a perfect listener for an explanation that can be given as a sort of flow of little arguments, sometimes with a necessary global strategy behind them, but always with lots of things to remember, lots of referential notations to refer to various objects, and so forth.

The purpose of the present preprint is to discuss our computer formulation, both of the general localization construction and the special construction when there is a calculus of fractions. We don't pretend to give all the details in the text—indeed we stop at about the same place as previous authors have. However, the details are necessarily all there in the computer files [31].

Historically, the notion of localization appeared informally in a somewhat different form in the Tôhoku paper of Grothendieck [11] where he formalizes (to some extent) language which he attributes to Serre [27] of working in a category “modulo” a subcategory.

After Gabriel-Zisman, the question of localization of categories has been treated in a number of references. Several people were helpful in pointing out some of these in response to requests posted to the topology and category-theory mailing lists. The references include books by L. and N. Popescu [19] [20], H. Schubert [25], and F. Borceux [3]. Curiously enough

the localization construction doesn't seem to appear in [14], although the underlying free and quotient category techniques are there. A classical reference which chronologically goes alongside Gabriel and Zisman is Verdier's thesis but which was only recently published [32]. Verdier considers the case of localization of an additive category, inverting a multiplicative system which satisfies a two-sided calculus of fractions. The construction is similar to the left-fraction construction.

The above list of references is undoubtedly partial. It doesn't include very many of what are certainly numerous research papers since the time of [9] which may treat aspects of these issues in some detail ([1] is an example).

Nonetheless, it is interesting to note the prevalence of formulations leaving "to the reader" parts of the proofs of details of the localization constructions. For example (the following all refer to the left or right fractions construction):

[32], p. 117: "La preuve est facile et laissée au lecteur qui pourra démontrer de même la proposition ci-après ...".

[25], p. 260: "Using (i), (ii), (iii) and (v), there is no difficulty in verifying that the composite ... is well defined, ...".

[20], p. 155: "It is not difficult to see that with the equivalence relation (2) introduced above one also has a well-defined composition law ...".

Another interesting reference is Pronk's paper on localization of 2-categories [21], pointed out to me by I. Moerdijk. This paper constructs the localization of a 2-category by a subset of 1-morphisms satisfying a generalization of the right fraction condition. In this case, there is no need to divide by an equivalence relation on the set of 1-arrows, because the appropriate arrows (i.e. pairs or what we call "fraction symbols") are identified by the presence of 2-cells making them equivalent. On the other hand, knowing which 2-cells are there would tell us which fraction-symbols need to be identified in the 1-localization. Thus it seems likely that from the high level of detail present in [21], one could extract the complete set of necessary arguments for the localization of a 1-category. Nonetheless, the full set of details for the coherence relations on the level of 2-cells is still too much, so the paper ends with:

[21], p. 302: "It is left to the reader to verify that the above defined isomorphisms  $a$ ,  $l$  and  $r$  are natural in their arguments and satisfy the identity coherence axioms."

We take the opportunity at this point in the introduction to mention the colimit point of view about localization, even though it isn't treated in our proof verification files. The contents of this discussion are touched upon by Gabriel-Zisman in 1.5.4 of Chapter I, see also 6.2 of Chapter II, and since then has become even more well-known.

The localization  $\mathcal{C}[\Sigma^{-1}]$  can be viewed as a pushout or colimit in the category of categories (one has to fix a universe  $\mathcal{U}$  and consider colimits in the category of  $\mathcal{U}$ -categories). To be precise, it is a pushout fitting into a cocartesian diagram

$$\begin{array}{ccc} \Sigma \times I & \rightarrow & \mathcal{C} \\ \downarrow & & \downarrow \\ \Sigma \times \bar{I} & \rightarrow & \mathcal{C}[\Sigma^{-1}] \end{array}$$

where here  $\Sigma$  denotes the discrete set of maps to be inverted (considered as a discrete category),  $I$  denotes the category with objects 0 and 1 and one non-identity arrow  $0 \rightarrow 1$ , and  $I \subset \bar{I}$  denotes the completion to a category with two objects 0 and 1 joined by a single

isomorphism. In a certain sense the fact that this diagram is cocartesian just restates the universal property of the localization.

Ross Street in [24] mentioned the above pushout point of view as well as another closely related terminology, saying that the localization is the “coinverter” of the 2-cell  $\sigma$  which is the natural transformation from

$$\text{dom} : \Sigma \rightarrow C \text{ to } \text{cod} : \Sigma \rightarrow C.$$

The fact that the localization is a pushout implies that this operation is compatible with colimits of categories. For example suppose

$$\begin{array}{ccc} A & \rightarrow & B \\ \downarrow & & \downarrow \\ C & \rightarrow & P \end{array}$$

is a cocartesian diagram of categories, and  $\Sigma_A$ ,  $\Sigma_B$ , and  $\Sigma_C$  are subsets of morphisms in  $A$ ,  $B$  and  $C$  respectively such that  $\Sigma_A$  maps into  $\Sigma_B$  and  $\Sigma_C$ . Let  $\Sigma_P$  be the union of the images of  $\Sigma_B$  and  $\Sigma_C$ . Then the diagram

$$\begin{array}{ccc} A[\Sigma_A^{-1}] & \rightarrow & B[\Sigma_B^{-1}] \\ \downarrow & & \downarrow \\ C[\Sigma_C^{-1}] & \rightarrow & P[\Sigma_P^{-1}] \end{array}$$

is cocartesian. Let’s stress that none of this is proven in the proof files.

An interesting case is when we take  $\Sigma = \text{Mor}(C)$  to be the full set of morphisms of a category. In this case the localization is the *groupoid-completion*, the universal groupoid with a functor from  $C$ , denoted

$$C^{\text{gr}} := C[\text{Mor}(C)^{-1}].$$

The compatibility with colimits stated above gives the following statement for groupoid completions: if

$$\begin{array}{ccc} A & \rightarrow & B \\ \downarrow & & \downarrow \\ C & \rightarrow & P \end{array}$$

is a cocartesian diagram of categories then the diagram of groupoids

$$\begin{array}{ccc} A^{\text{gr}} & \rightarrow & B^{\text{gr}} \\ \downarrow & & \downarrow \\ C^{\text{gr}} & \rightarrow & P^{\text{gr}} \end{array}$$

is cocartesian (either in the category of  $\mathcal{U}$ -categories, or in the category of  $\mathcal{U}$ -groupoids). The groupoid completion  $C^{\text{gr}}$  is equivalent to the Poincaré fundamental groupoid of the realization of the nerve of  $C$  (denoted by  $|C|$  for short). In view of which, the above statement can be viewed as a sort of Van Kampen theorem for fundamental groupoids in the style of R. Brown [4]. To make this view totally precise we would have to look at when the corresponding diagram of spaces  $|A|$ ,  $|B|$ ,  $|C|$ ,  $|P|$  is a pushout of spaces, which is sometimes but not always the case.

Ross Street also pointed out to me in [24], that the problem of localizing a noncommutative ring is closely related (and somewhat similar to the Verdier case in that it brings in additive structure). He sent me some notes treating in great detail the ring localization; it should

be relatively easy to transform those into a computer proof for this case. On the subject of notes, Clark Barwick mentions that he had written up some notes about Lemma 1.2 of Gabriel-Zisman; there are probably (one would hope) a number of mathematicians who have done so.

Here is the plan of the paper. We will discuss first the general construction of the localization in a mathematical fashion; this is followed by a section discussing the issues which arise in the computer formulation. Then we come back to a mathematical discussion of the calculus-of-fractions construction, including discussion of the subtleties which arise when we go towards the full details of the argument. The section after that discusses the new issues which arise in the computer formulation, notably how we deal with the commutative diagrams which one is tempted to use for the proof. In the last section, we mention very briefly the contents of the remaining files in the present development.

## 2. THE GENERAL LOCALIZATION CONSTRUCTION

We recall in usual mathematical terms how the general construction of the localization of a category works, taken directly from the first two pages after the introduction in Gabriel-Zisman [9]. Fix a category  $\mathcal{C}$  and a subset  $\Sigma \subset \text{Mor}(\mathcal{C})$  of morphisms. We make no assumption about  $\Sigma$ . We construct the localization, denoted  $\mathcal{C}[\Sigma^{-1}]$ , as follows. Start by taking the disjoint union  $\text{Mor}(\mathcal{C}) \sqcup \Sigma$ . The arrows in the first factor are thought of as going in the forward direction, and the arrows in the second factor as going in the backward direction. This allows us to create a directed graph whose vertices are the objects of  $\mathcal{C}$  and whose set of edges is  $\text{Mor}(\mathcal{C}) \sqcup \Sigma$ . Let  $\mathcal{F}$  denote the free category over this graph. Recall that this means that the objects of  $\mathcal{F}$  are the vertices of the graph (thus, the same as the objects of  $\mathcal{C}$ ), and the morphisms of  $\mathcal{F}$  are directed paths in the graph.

Next introduce some relations on  $\mathcal{F}$ , and let  $\mathcal{C}[\Sigma^{-1}]$ , which we denote as  $\mathcal{L}$  for short, be the quotient of  $\mathcal{F}$  by these relations. The relations are trivial on the set of objects, that is to say no different objects are put in relation and related morphisms share the same source and target. The relations are introduced with the purpose of insuring the following properties for the quotient  $\mathcal{L}$ :

- (1) the natural map on arrows  $\text{Mor}(\mathcal{C}) \rightarrow \text{Mor}(\mathcal{F})$  (which is not itself a functor) projects to a functor  $\mathcal{C} \rightarrow \mathcal{L}$ ; and
- (2) if  $u \in \Sigma$  then the image in  $\mathcal{C}$  of the backward edge corresponding to  $u$  (that is, the element of the second factor of the disjoint union) is inverse in  $\mathcal{L}$  to the image of  $u$  by the functor in (1).

The relations are chosen heuristically in a minimal way to accomplish this. In Gabriel-Zisman this process is written in a compact way: the very process of taking the quotient category implies that we want the set-theoretical quotient of  $\text{Mor}(\mathcal{F})$  by the full set of relations, to be the set of morphisms of a category. This in itself contains some properties of compatibility between the relations and the composition and identity operations. Call a relation which satisfies these properties, a *categorical relation*. We can start by specifying an arbitrary list of relations and then take the closure under this condition, that is the smallest categorical relation containing our list of relations. Once we have decided to do this, we can list the germinal relations as follows: condition (1) requires that we specify two

types of relations, one for compatibility of the functor with the composition, and one for the compatibility of the functor with the identity; and condition (2) requires again two types of relations, one each for the left and right inverse properties. Thus we need to impose 4 families of relations to start with. These are listed on page 6 of Gabriel-Zisman (as well as in our proof file, see below). Given this list of relations, the quotient  $\mathcal{L}$  is constructed by first completing to the smallest categorical relation  $\sim$  containing the list, then taking  $Mor(\mathcal{L}) := Mor(\mathcal{F})/\sim$ . It is straightforward to show that this defines a category  $\mathcal{L}$ , with a functor  $\mathcal{F} \rightarrow \mathcal{L}$  satisfying properties (1) and (2) above, since we constructed the relation that way on purpose. We obtain a functor  $P_\Sigma : \mathcal{C} \rightarrow \mathcal{L}$  sending elements of  $\Sigma$  to invertible morphisms in  $\mathcal{L}$ .

So much for the construction. The next step is to state and prove an appropriate universal property. On the first page of the construction they give the main properties which are (I am quoting):

- “(i)  $P_\Sigma$  makes the morphisms of  $\Sigma$  invertible,
- (ii) If a functor  $F : \mathcal{C} \rightarrow \mathcal{X}$  makes the morphisms of  $\Sigma$  invertible, there exists one and only one functor  $G : \mathcal{C}[\Sigma^{-1}] \rightarrow \mathcal{X}$  such that  $F = G \cdot P_\Sigma$ .”

After explaining the construction in 14 lines at the bottom of page 6 and the top of page 7 (which I have paraphrased above), Gabriel-Zisman jumped right up to a highly abstract formulation of the universal property which we recopy here together with a few subsequent phrases:

“1.2. Lemma: For each category  $X$ , the functor  $\underline{Hom}(P_\Sigma, X) : \underline{Hom}(\mathcal{C}[\Sigma^{-1}], \mathcal{X}) \rightarrow \underline{Hom}(\mathcal{C}, \mathcal{X})$  is an isomorphism from  $\underline{Hom}(\mathcal{C}[\Sigma^{-1}], \mathcal{X})$  onto the full subcategory of  $\underline{Hom}(\mathcal{C}, \mathcal{X})$  whose objects are the functors  $F : \mathcal{C} \rightarrow \mathcal{X}$  which make all the morphisms of  $\Sigma$  invertible.

“The proof is left to the reader. This lemma states more precisely conditions (i) and (ii). From now on ...”

Afterwards they pass immediately to the discussion of motivating examples like when the multiplicative system comes from a pair of adjoint functors.

This text (which totals less than a full page) is quite interesting from the point of view of the problem of formalizing mathematics on the computer. In a very short space the authors have indicated, without error and indeed giving all of the necessary information, a relatively complex mathematical construction, together with a very abstract statement of the universal property satisfied by this construction. Starting with the information given here, it is a straightforward (and mathematically uninteresting) exercise to fill in all of the required details.

Creating a proof document to be read by a computer proof assistant raises a certain number of mild difficulties. As a test, I have tried to attain the exact statement of Lemma 1.2 given above. Before getting to a discussion of some details of this process in the next section, it is interesting to note here that the time it took to do this was about a month, and the resulting total size of the 3 proof files involved (`freecat.v`, `qcat.v` and `gzdef.v`) is about 10,000 lines.

### 3. THE COMPUTER FORMULATION

In order to formalize the general localization construction, we use the Coq proof assistant [6]. We place ourselves in an axiomatic environment which implements classical Zermelo-Fraenkel set theory, and also relates it to the type theory of Coq. Concretely, the proof files attached to [31] include identical copies of the proof files of my earlier set theory and category theory developments [30]. The set-theoretical part of this starts with a file `axioms.v` containing all of the axioms we assume (that is, no subsequent files use the `Axiom` or `Parameter` commands). These axioms are intended to implement ZFC within Coq. However, we furnish no formal proof of the fact that they do indeed do that, in other words that together with the Coq “calculus of inductive constructions” type system, they furnish a mathematical system which is consistent within the context of the usual ZFC axioms. It would be good to have such a proof, but that seems to be complicated (due to the complicated structure of Coq) and possibly nontrivial due to certain aspects of Coq’s type system such as cumulativity between sorts `Prop` and `Type`. One would have to prove Conjecture 2 of Miquel and Werner [18]. This is left to the reader!

The next question which is left open is to convince oneself that the definitions and statements of lemmas contained both in the present files as well as in the category theory files, accurately represent what the mathematician means when he speaks of categories, functors and so forth. This again may contain some nontrivial aspects and is left to the reader. The accompanying preprint “Files for Gabriel-Zisman Localization” [31] is intended to help with this task: the textual part of this preprint consists of the Coq files, with all proofs taken out. There one can look directly at the definitions and statements of lemmas, which are the only parts which need to be understood in order to verify the meaning of what is being said. (However, this is done only for the files concerning localization; in principle it might be a good idea to have the same thing for the set-theory and category-theory developments but that would be lengthy.)

While speaking about these foundational questions for the computer formulation, it is important to note that one could undoubtedly use any of a number of other environments for treating this question. For example, it should be possible to proceed based on Saibi’s category theory contribution [26] where sets are replaced by “setoids” (types plus equivalence relations). This is particularly so in that one major element of the localization construction is the notion of quotient category. It is likely that a setoid approach would simplify certain aspects, at the price of introducing other complications elsewhere. We don’t venture to predict how economical that would be on the whole. One should of course also envision doing this type of formalization within other proof assistants (the list of which is getting very long and we don’t attempt to reproduce it here, see [28] [16] [15]).

For the reader who, at this point, still feels that a computer formalization can add something to the question of verifying the mathematics underlying the localization construction, we now consider some details.

**3.1. Category theory.** We only treat small categories, i.e. ones whose objects and morphisms form sets. In this context any distinction between small and big categories would be made by referring to a Grothendieck universe (which would itself be a set). However, in the current development we don’t treat the question of when the localization of a category



which is big but has small *hom* sets with respect to a given universe, is again big but with small *hom* sets with respect to that universe. Thus, we are always working with sets and no foundational acrobatics come into play.

Most major notational questions about categories have already been dealt with in the category theory files. A category is a 5-uple consisting of the set of objects, the set of morphisms, the graph of the partially defined composition operation, the graph of the identity operation, and a fifth set which is destined to contain any eventual extra structure one might want to include. The positions in the 5-uple are indicated by character strings (i.e. the 5-uple is a function whose domain is a set of 5 specific character strings corresponding to the 5 places). This schema isn't the most economical: the necessary data (excepting the last structure variable) is contained in the graph of the composition morphism. The goal is rather to achieve some rudimentary standardization of the procedure for considering mathematical objects.

One feature of the category-theory encoding which is worthwhile to recall here is that the set of morphisms is supposed to contain only objects *u* which themselves are triples containing a source, a target, and a third indicative element. This property is written `Arrow.like u`. Here as before, these triples are realized as functions whose domain is a set of 3 character strings. This allows us to consider `source u` and `target u` for an arrow *u*, independantly of the category for which *u* is a morphism. Here we have an economy of notation which has been extremely useful throughout the category theory development. In our discussion below we will encounter several places where a certain modification of the “obvious” approach is made necessary by the `Arrow.like` hypothesis. These modifications are easy to do once we are aware of the phenomenon—which is why I am devoting some space below to these explanations.

Similar notational considerations hold for functors and natural transformations. We refer to [30] for further discussion of these issues.

**3.2. The free category.** The first step in our current files is `freecat.v` where we construct the free category on a graph. Since a morphism in the free category is a path in the graph, we need to implement the notion of path. This touches on what G. Gonthier explained was an important piece of their work formalizing the 4-color theorem [10]. However, the approaches are not the same since we are much less concerned with efficient computation on these objects and more concerned with their theoretical manipulation. The notion of path also appears in T. Hales' recent formalization of the Jordan curve theorem [12].

To implement a notion of “path”, we obviously need a theory of “uples”, which are implemented as functions whose domain is an interval of natural numbers of the form  $[0, \dots, n-1]$  where *n* is the length of the uple. We define the function `Uple.create` to create an uple of length *l* from a function `f:nat -> E`, and a function `component` to get back the *i*th element of an uple. We need the `length` function as well as `concatenate`.

An important lemma is `uple_extensionality` which says that two uples of the same length with the same elements are the same; this allows us to prove associativity of concatenation. J.S. Moore said for his ACL2 system that the first thing you would want to prove was associativity of concatenation. In that type of system, uples or lists are inductive objects and associativity is a statement proved by recurrence on the length. In Gonthier's

paper [10], the notion of path is defined structurally so that associativity is automatic by term reduction and need not be mentioned as a lemma. In our case, the technical tool used to simplify the proof of associativity, and most other manipulations of our uples which are functions of natural numbers, is the **omega** tactic. The usefulness of this tactic, developed by Crégut [7] based on an algorithm of Pugh [22], was pointed out to me by Marco Maggesi. It dispatches easily any arithmetic statement involving the standard operations and inequalities on natural numbers. In our proof files this powerful tactic is abbreviated as **om** which could be interpreted alternatively as a reference to Buddhism or the Marseille soccer team. Finishing the **Uple** module is the operation **utack** which corresponds to concatenation with an uple of length one. This specific case enters often later so we treat it specifically.

The notion of graph is relatively easy to encode. A graph is a pair consisting of a set of vertices, and a set of edges. The edges of a graph are also supposed to be arrows. This situation is simple enough to provide a good example of our general notational procedure which we can recopy here:

```

Definition Vertices := R (v_(r_(t_ DOT ))).
Definition Edges := R (e_(d_(g_ DOT))).
Definition vertices a := V Vertices a.
Definition edges a := V Edges a.
Definition create v e :=
denote Vertices v
(denote Edges e stop).
Definition Graph.like a := a = create (vertices a) (edges a).

Definition Graph.axioms a := Graph.like a &
(forall u, inc u (edges a) -> Arrow.like u) &
(forall u, inc u (edges a) -> inc (source u) (vertices a)) &
(forall u, inc u (edges a) -> inc (target u) (vertices a)).

```

We don't do any theory of graphs beyond just the definition.

Next we look at the paths which will make up the morphisms of the free category on a graph. These are arrows whose third term are uples; and furthermore the uples will eventually (in the definitions **arrow\_chain** and **mor\_freecat**) be supposed to be sequences of composable arrows in the graph, starting from the source of the arrow and ending at the target. This situation requires a certain amount of specific treatment, for example we define a version **segment** of the previous **component** function (and **seg\_length** instead of **length**). In general terms, this type of definition contracting two or some other small number of functions which often occur together, necessitating the transposition of all of the lemmas concerning the pieces, occurs all over the place and seems to be a general phenomenon. The composition operation for the free category is defined by using concatenation of the underlying uples. We also define the identity (whose uple has length 0) and prove all the various things needed to obtain the category axioms. We then would like to consider functors from the free category into another category. For this, we need to define the operation of composing together a composable sequence of arrows in a category (the definition **mor\_chain** is very much like **arrow\_chain**). In this way we can state a universal property of the free category on a graph (see the results concerning the construction **free\_functor**). To close out this discussion we also consider (in the results concerning **free\_nt**) natural transformations

between functors whose sources are the free category. This is significantly easier because a natural transformation is a function on objects, and the objects of the free category are just the vertices of the graph.

**3.3. Quotient categories.** After the free category, the other main element of the construction is the notion of quotient category (`qcat.v`). We are in a situation which is significantly easier than the general case: our relation has no effect on the objects. In other words, we have a relation on the set of morphisms of a category, such that two morphisms which are related already have the same source and target. It is convenient to distinguish two separate notions, denoted (`cat_rel a r`) and (`cat_equiv_rel a r`). The first means that `r` is an arbitrary relation on the morphisms of a category `a`, respecting source and target. The second means that `r` is an equivalence relation and compatible with the composition of `a`. One important example of a `cat_equiv_rel` is (`coarse a`) which puts in relation any two morphisms with the same source and target. The existence of this maximal relation allows us by intersection to define the smallest `cat_equiv_rel` containing a given `cat_rel r`. We call this construction (`cer a r`) (here `cer` stands for the “categorical equivalence relation” on the category `a` generated by `r`).

In order to construct the quotient category of `a` by `r`, we need a manipulation called `arrow_class`. The reason for this is that in our notion of category, the morphisms are supposed to be `Arrow.like`, i.e. triples having a source, a target and an arrow. Thus we can’t just say that the set of morphisms of the quotient category is the usual quotient (i.e. set of equivalence classes) of the set of morphisms by the relation. Thus we define (`arrow_class r u`) to be the arrow with the same source and target as `u`, but whose third element is the equivalence class of `u` for the relation `r`. Now the set of morphisms of the quotient category will be the image of this construction as `u` runs through the morphisms of `a`. The definition (`is_quotient_arrow a r u`) formalizes the statement that `u` is in the image. We also need a construction (`arrow_rep v`) going in the other direction (see Lemmas `related_arrow_rep_arrow_class` and `arrow_class_arrow_rep` saying that the two constructions are inverse in the appropriate sense). We then define `quot_id` and `quot_comp`, the operations which will become the identity and composition for the quotient category. As usual, before trying to construct the category it is a good idea to prove all of the necessary properties for these constructions. Then when we construct (`quotient_cat a r`) we prove destruct-create lemmas `comp_quotient_cat` and `id_quotient_cat` saying that the identity and composition are `quot_id` and `quot_comp`. The destruct-create lemmas `ob_quotient_cat` and `mor_quotient_cat` are proven after `quotient_cat_axioms` because the properties `ob` and `mor` include the category axioms for their first variables.

The module `Quotient_Functor` does similar things for defining a functor `qfunctor` to the quotient category, and a functor `qdotted` from the quotient category. The latter terminology is intended to suggest that `qdotted` is the dotted arrow which is filled in in the universal property of the quotient category. Thus if `f` is a functor and `r` a categorical equivalence relation on the category `source f` we get a functor `qdotted r f` such that

```
source (qdotted r f) = quotient_cat (source f) r
target (qdotted r f) = target f
fcompose (qdotted r f) (qprojection (source f) r) = f.
```

The unicity statement for the universal property says that if  $f$  is a functor with  
`source f = quotient_cat a r`

then

`f = qdotted r (fcompose f (qprojection a r)).`

There are no particular difficulties encountered in these arguments beyond the kind we have already discussed above.

Also contained in the file `qcat.v` is a module `Ob_Iso_Functor` dedicated to studying the following situation. We have a functor  $f$  and a category  $a$ . We study the pullback morphism induced by  $f$ , denoted `(pull_morphism a f)`, from `(functor_cat (target f) a)` to `(functor_cat (source f) a)`. Recall that these constructions come from the file on functor categories `functor_cat.v` in the category-theory development. The purpose of this module is to contribute to the proof of Gabriel-Zisman's Lemma 1.2. In particular, we will want to apply this to the case where  $f$  is the functor from a category to its localization. Thus we assume that  $f$  is an isomorphism on objects. We develop a criterion for when `(pull_morphism a f)` is fully faithful and injective on objects (see the definition `iso_to_full_subcategory`), or equivalently that it induces an isomorphism from `(functor_cat (target f) a)` to a full subcategory of `(functor_cat (source f) a)`. The equivalence between these notions is shown in Lemma `iso_to_full_subcategory_interp`.

Intervening in the statement of the criterion is the construction `add_inverses a s`. This is the subset of morphisms of  $a$  which are either already in  $s$ , or else are inverses in  $a$  to morphisms in  $s$ . Our criterion, stated at the end of this module in Lemma `iso_to_full_subcategory_pull_morphism_criterion`, says that if a functor  $f$  is an isomorphism on objects, and if `(add_inverses (target f) (mor_image f))` generates the category `(target f)`, then for any category  $a$  the pullback functor `pull_morphism a f` is an isomorphism onto a full subcategory. We will use this criterion, applied to the functor from a category to its localization, to obtain half of the statement of Lemma 1.2.

Finishing out the file `qcat.v` is a module `Associating_Quotient` which substantially recopies much of the definition of quotient category. The only difference is that we don't start with a category but only with a structure like a category but which doesn't necessarily satisfy the associativity or left and right identity axioms. The idea is that the equivalence relation will enforce these axioms. This construction is not needed for the general construction of localization, but it will be needed later for the construction of the category of fractions. It didn't seem necessary to go back and redo the whole quotient construction with this generality in mind: it is easier to recopy the relevant parts and change them. This might result in a file which is longer than necessary, but one should keep in mind that the variable we are trying to economize is the energy necessary to produce (or understand) the collection of files, not their total length.

**3.4. Construction of the localization.** Recall that the construction of the localization starts by looking at the graph whose edge set is the disjoint union of the morphisms of  $a$  with the elements of  $s$ . Since these two sets are anything but disjoint, we need some additional notation to implement the disjoint union. To this end, the first thing one notices at the start of the file `gzdef.v` is the introduction of two sets `Forward` and `Backward`. These are

character strings (which are elements of  $\mathbf{E}$  hence sets, see `notation.v` [29]). An edge of the graph is either a “forward edge” corresponding to a morphism in  $\mathbf{a}$ , or else a “backward edge” corresponding to an element of the localizing system  $\mathbf{s}$ . The obvious thing is to try putting

```
forward_arrow u := pair Forward u
backward_arrow u := pair Backward u.
```

However, *this doesn't work*. The reason is that the elements of the set of edges of the graph are supposed to be `Arrow.like`. To remedy this problem, we set

```
forward_arrow u := Arrow.create (source u) (target u) (pair Forward u)
backward_arrow u := Arrow.create (target u) (source u) (pair Backward u).
```

Notice that the source and target are interchanged in the function `backward_arrow`. The function `original_arrow` yields back the arrow we started with. Now `loc_edges a s` is the set of such edges, i.e. the union of the images of `forward_arrow` and `backward_arrow` respectively on the morphisms of  $\mathbf{a}$  and on  $\mathbf{s}$ . The union is disjoint because `Forward` and `Backward` are distinct. Define the graph `gz_graph a s` whose vertices are the objects of  $\mathbf{a}$  and whose edges are `loc_edges a s`.

From here, the construction basically follows the ordinary one, and doesn't really take up too much space. The free category on `gz_graph a s` is called `gz_freecat a s`. The definition `gz_rel a s` is where the defining relations for the construction of the localization are listed. We recopy here a lemma which rewrites that definition in a slightly more readable fashion.

```
Lemma related_gz_rel : forall a s e f, localizing_system a s ->
related (gz_rel a s) e f =
((exists x, (ob a x &
e = (forward_edge (id a x)) &
f = (freecat_id x))) \ /
(exists q, (inc q s &
e = (freecat_comp (forward_edge q) (backward_edge q)) &
f = (freecat_id (target q)))) \ /
(exists q, (inc q s &
e = (freecat_comp (backward_edge q) (forward_edge q)) &
f = (freecat_id (source q)))) \ /
(exists u, exists v, (mor a u & mor a v & source u = target v &
e = (freecat_comp (forward_edge u) (forward_edge v)) &
f = (forward_edge (comp a u v))))).
```

The size of this text is comparable to the size of the paragraph of [9] where the relations are listed. Then `gz_cer a s` is the associated categorical equivalence relation, and `gz_loc a s` is the quotient category. The functor from  $\mathbf{a}$  to `gz_loc a s` is called `gz_proj a s`.

The module `GZ_Thm` is where we prove Gabriel-Zisman's Lemma 1.2. From the file `qcat.v`, the module `Ob_Iso_Functor` furnishes the results necessary to prove the part of Lemma 1.2 which says that pullback is an isomorphism onto a full subcategory. As pointed out above, one of the delicate points is that the statement of Lemma 1.2 involves the pullback morphism `pull_morphism` between functor categories. Functor categories were treated in the category theory development [30], and the place where we made use of that theory was in the module

`Ob_Iso_Functor` so we don't actually encounter it too much anymore here. This conclusion is stated in the present file as `iso_to_subcategory_pull_gz_proj`, a corollary of the fact that `gz_loc` is generated by adding available inverses to the morphism image of the functor `gz_proj`.

The main part of the work done in the present module is to prove the versal part of the universal property. Furthermore, rather than just giving a proof we would like to have some useful notation. We start by introducing this notation for the free category: the operation `fr_dotted` corresponds to filling in the dotted line in a diagram expressing the versality of the universal property. Similarly `qdotted` did the same thing in the file `qcat.v`, and putting them together we get a construction called `gz_dotted` which expresses versality in the following way. Given `a`, `s` and a functor `f` with `source f = a`, we say `loc_compatible a s f` if `f` sends elements of `s` to invertible morphisms in `target f`. Then `gz_dotted a s f` is a functor with

```
source (gz_dotted a s f) = gz_loc a s
target (gz_dotted a s f) = target f
fcompose (gz_dotted a s f) (gz_proj a s) = f
```

The last property here, which is Lemma `fcompose_gz_dotted_gz_proj`, corresponds to the versality property (ii) of [9], page 6. The uniqueness property (i) on page [9] was our Lemma `gz_proj_epimorphic`. These are actually the properties which are the most useful in practice.

Our version of Lemma 1.2 is given by two statements, `iso_to_subcategory_pull_gz_proj` as noted above, and for identification of the full subcategory image of `pull_gz_proj`, the lemma `ob_image_pull_gz_proj`.

It might eventually be useful to have a more concrete description of natural transformations between functors starting from the localization, but apart from the fact that it is implicitly contained in the statement of Lemma 1.2, we don't treat this further here.

#### 4. CALCULUS OF LEFT (OR RIGHT) FRACTIONS

When I gave a talk in Nice about the computer formulation of the general localization construction, Charles Walter suggested that it would be interesting to compare the formalization of the general construction of localization, with what would have to be done to construct the localization in the presence of the habitual calculus of fractions conditions. With this motivation I set out a while later to formalize the fractions construction from Chapter 2 of Gabriel-Zisman.

Contrarily to the general construction, it turned out (in my own opinion at least) that filling in the details of the left-fractions construction involved some nontrivial (if easy) mathematical thought, and drawing lots of diagrams. We don't draw diagrams in the computer formulation (that might someday be possible but it is beyond the reach of most computer proof assistants for the moment). As a replacement, we set up definitions of situations involving several arrows of a category, which correspond to the diagrams we would want to draw. This will be discussed in the next section.

In the present section we go into some detail about the mathematics of the problem, which stems from the fact that Gabriel-Zisman state their fraction construction under a somewhat weak collection of hypotheses about the localizing system.

The dual notions of left and right calculus of fractions are intended to be analogues of the notion of multiplicative system for a commutative ring, which as was well-known leads to a description of the localization as a set of “fractions”. In the case of categories, one would like to represent elements of the localizations as “fractions” or diagrams

$$x \xrightarrow{v} y \xleftarrow{t} z,$$

where by convention the arrows going backward are supposed to be in  $\Sigma$ . This diagram is viewed as representing the morphism  $t^{-1}v$  of  $\mathcal{C}[\Sigma^{-1}]$  so it is called a *left fraction symbol*. We would like to have a nice set of conditions guaranteeing first of all that every morphism of the localization can be written as a fraction; and second guaranteeing that the equivalence relation on formal symbols  $(t, v)$  whose quotient the set of morphisms  $t^{-1}v$  is easy to understand. This collection of conditions is the *calculus of left fractions*. There will be a dual notion of *calculus of right fractions* obtained by conjugating everything with the ‘opposite’ construction. Aside from the problem of implementing this conjugation in the computer formulation, we will focus on the left-fraction case.

The conditions for a calculus of left fractions are given on [9] page 12, (2.2 a,b,c,d). For convenience we reproduce them here:

- (a)  $\Sigma$  contains the identity morphisms of all objects of  $\mathcal{C}$ ;
- (b)  $\Sigma$  is closed under composition;
- (c) If

$$X' \xleftarrow{s} X \xrightarrow{u} Y$$

is a diagram with  $s \in \Sigma$  then there exists a commutative square

$$\begin{array}{ccc} X & \rightarrow & Y \\ \downarrow & & \downarrow \\ X' & \rightarrow & Y' \end{array}$$

such that the right downward map in the square is in  $\Sigma$ ; and

- (d) If  $f$  and  $g$  are two maps from  $X$  to  $Y$  such that there exists  $s \in \Sigma$  with  $fs = gs$ , then there is a morphism  $t : Y \rightarrow Y'$  in  $\Sigma$  such that  $tf = tg$ .

Condition (c) says that every right fraction symbol can be completed to a left fraction symbol (in the commutative square,  $X' \rightarrow Y' \leftarrow Y$  is a left fraction), that is dividing by an element of  $\Sigma$  on the right can be changed to division on the left. Condition (d) says that equalization on the right can be changed to equalization on the left.

Most notable about this definition, specially in light of common practice in more recent times, is what is left out. It is natural to require the following condition, which we call *three for two*:

- (e) if  $X \xrightarrow{g} Y \xrightarrow{f} Z$  is a composable pair of morphisms, then if any two of  $f$ ,  $g$  and  $fg$  are in  $\Sigma$ , the third one is too.

In general we can define the *saturation* of a set of morphisms to be the set  $\Sigma^{\text{sat}}$  of all morphisms in  $\mathcal{C}$  which become invertible in  $\mathcal{C}[\Sigma^{-1}]$ . It is clear from the universal property

that the functor

$$\mathcal{C}[\Sigma^{-1}] \rightarrow \mathcal{C}[(\Sigma^{\text{sat}})^{-1}]$$

is an isomorphism, that is a set  $\Sigma$  and its saturation share the same localization. It is also clear that for any set of morphisms, the saturation satisfies conditions (a), (b) and (e). Thus from a certain perspective there would be no loss of generality in requiring that our set of morphisms satisfy condition (e). For example, Quillen will later incorporate this condition as an important part of his notion of “closed model category”.

Nonetheless, Gabriel-Zisman don’t make this requirement (and indeed they don’t even speak of the three-for-two condition (e) near here in the text). When you start to look closely at the details it becomes clear that stating and proving the construction of the left-fraction localization in the absence of the three-for-two condition is a bit of a challenge, one which they happily ask the reader to meet almost without saying anything about it, just subtly giving the correct definition of the equivalence relation so as to make it work.

Throughout the discussion of the left-fraction condition—as was the case for the general construction too—Gabriel-Zisman make reference to the construction of the sets of morphisms as being a direct limit construction. We ignore this aspect here: it isn’t treated in the formal proof development and we don’t discuss it in the informal presentation either. In fact it goes beyond the concrete character of the construction and it isn’t clear whether it represents a useable piece of information (although that doesn’t mean that it isn’t conceptually important).

We now get to the description of the equivalence relations. We define a preliminary set of formal symbols  $(t, f)$  consisting of two arrows having the same target, the first of which is in  $\Sigma$ . A left fraction symbol  $(t, f)$  is drawn as a diagram

$$x \xrightarrow{f} y \xleftarrow{t} z.$$

We would like to define the set of morphisms of the left-fraction category to be the quotient of this preliminary set by an equivalence relation ([9], the top of page 13). Before stating the relation, notice that the “source” of the formal symbol  $(t, f)$  is the source of  $f$ , whereas the “target” of  $(t, f)$  is defined to be the source of  $t$ . We call the common target of  $t$  and  $f$  the *vertex* of the symbol. The equivalence relation will preserve source and target. Two symbols  $(s, f)$  and  $(t, g)$  are said to be *equivalent* if there are maps  $a$  and  $b$  such that the source of  $a$  is the vertex of  $(s, f)$  and the source of  $b$  is the vertex of  $(t, g)$ , and  $af = bg$ ,  $as = bt$ , and furthermore  $as = bt$  is in  $\Sigma$ . Note that these conditions automatically say that the targets of  $a$  and  $b$  are the same. See the second diagram on page 13 of Gabriel-Zisman.

We can think of these conditions as giving a symbol  $(as, af) = (bt, bg)$  which is “beyond” both  $(s, f)$  and  $(t, g)$ , and indeed this notion is what we use in the proof development. We say that a symbol  $(r, u)$  is *beyond*  $(s, f)$  if there exists a morphism  $a$  whose source is the vertex of  $(s, f)$  and target the vertex of  $(r, u)$ , such that  $r = as$  and  $u = af$ . In this case we say that the morphism  $a$  is an *intermediary* from  $(s, f)$  to  $(r, u)$ .

A natural impulse would be to ask that the morphism  $a$  (or the morphisms  $a$  and  $b$  in the definition of the equivalence relation) be in  $\Sigma$ . This would be automatic from the conditions that  $s$  and  $as$  are in  $\Sigma$ , if we had the three-for-two condition (e). However, if we try to do the construction in the absence of (e), we shouldn’t ask that the intermediary morphism  $a$



be in  $\Sigma$  because then the construction wouldn't work. A counterexample is discussed in the file `lfcx.v`.

If we have condition (e), then the proof that this defines an equivalence relation is relatively straightforward. Without it, things are somewhat more tricky. The details necessary to overcome this problem must be considered as subsumed in the phrase “It follows from (a), (b), (c), (d) that this defines an equivalence relation ...” in the middle of page 13 [9]. We will now explain how to see that.

The main difficulty lies in proving that the equivalence relation is transitive. This may be rewritten in terms of the notion of “beyond” as trying to show\* that if two different symbols  $(r, u)$  and  $(r', u')$  are both beyond  $(s, f)$ , then there is a symbol  $(q, v)$  which is beyond both  $(r, u)$  and  $(r', u')$ . In this case we have morphisms  $a$  and  $a'$  serving as intermediaries between  $(s, f)$  and  $(r, u)$  or  $(r', u')$  respectively. We would like to complete  $a$  and  $a'$  to a commutative square. For this we would hope to use condition (c), which requires one of the morphisms to be in  $\Sigma$ . If we had condition (e) then this would be OK; in general an additional step is necessary.

Say that  $(r, u)$  is *under*  $(s, f)$  if there is a morphism  $a$  intermediary from  $(s, f)$  to  $(r, u)$  such that  $a \in \Sigma$ . Note that “under” implies “beyond” but not necessarily vice-versa. The main observation is the following lemma, which gives a sort of weak replacement for the 3 for 2 property, and its corollaries.

**Lemma 4.1.** *Suppose  $s \in \Sigma$  and  $a$  is a morphism composable with  $s$ , such that  $r := as$  is in  $\Sigma$ . Then there exists a morphism  $b$  such that  $ba \in \Sigma$ .*

*Proof:* Consider the diagram

$$\cdot \xleftarrow{r} \cdot \xrightarrow{s} \cdot$$

It is a right-fraction symbol because  $r \in \Sigma$ . By condition (c) it can be transformed into a left-fraction symbol: there exist morphisms  $x$  and  $t$  with  $t \in \Sigma$  and  $xr = ts$ . We would like to factorize  $t$  into a product  $ba$ , however we may need to go farther yet using condition (d). Our morphism  $a$  goes from the target of  $s$  to the target of  $r$ , and we have

$$xas = xr = ts.$$

In particular, we have two morphisms  $xa$  and  $t$  with the same source and target, equalized on the right by  $s \in \Sigma$ . By condition (d) there is a morphism  $c \in \Sigma$  such that  $cxa = ct$ . Recall that  $t \in \Sigma$  so  $ct \in \Sigma$ , and we can set  $b = cx$  to obtain the lemma.  $\square$

In the proof files, the argument of Lemma 4.1 is integrated into the proof of Lemma `exists_lf_under` as in the following corollary.

**Corollary 4.2.** *Suppose  $(r, u)$  is beyond  $(s, f)$ . Then there is another left fraction symbol  $(t, v)$  such that  $(t, v)$  is beyond  $(r, u)$  and under  $(s, f)$ .*

*Proof:* (see `exists_lf_under` in the proof files). Let  $a$  be the intermediary morphism going from  $(s, f)$  to  $(r, u)$ . Recall that  $r$  and  $s$  are in  $\Sigma$ , and  $r = as$ . The lemma says there is another morphism  $b$  such that  $ba \in \Sigma$ . Let  $t = br = (ba)s$  and  $v = bu = (ba)f$ .  $\square$

---

\*Curiously enough, this type of reasoning closely resembles the notions of reduction and normalization for  $\lambda$ -calculus; it might be interesting to explore the analogy.

**Corollary 4.3.** *If  $(r, u)$  and  $(t, v)$  are both beyond  $(s, f)$  then there is a symbol  $(q, w)$  which is beyond  $(r, u)$  and  $(t, v)$ .*

*Proof:* By the previous corollary (and transitivity of “beyond” which is easy) we may assume that  $(r, u)$  is under  $(s, f)$ . Then (and this part is Lemma `exists_lf_further` in the proof files) applying condition (c) to the intermediate morphisms we obtain intermediate morphisms going from  $(r, u)$  and  $(t, v)$  to a single  $(q, w)$ .  $\square$

Transitivity of the relation follows easily from Corollary 4.3. See `lf_equiv_trans` in the proof files.

A well-thought out direct argument for transitivity (which doesn’t occupy too much space) is given in Borceux [3] Proposition 5.2.4. The essential information is reduced to a single diagram (Diagram 5.4, page 185) containing 9 objects and 13 arrows.

For the definition of the composition, Borceux writes (p. 185):

“... Moreover this definition is independent of the choices of  $f, s, g, t, h, r$ . This is lengthy but straightforward: the arguments are analogous to those for proving the transitivity of the equivalence relation defined on the arrows. We leave those details to the reader as well as the checking of the category axioms ...”

This analysis is basically sound: once one has gotten over the hurdle discussed above, which first shows up at the proof of transitivity, the remainder of the argument necessary for checking well-definedness of the composition, associativity and identity axioms and so forth, presents no further difficulties. Nonetheless, it might be the case that the simplified presentation of the proof of the transitivity of the equivalence relation, could have as a consequence that checking the facts about the composition law becomes more involved (we needed to use techniques similar to those for transitivity, in the proof of well-definedness of the composition for example). Similarly in [25] and [20], the composition representative is constructed but well-definedness and associativity of the composition are not verified in detail.

For completeness, we describe here some of the main points. Suppose we are given two left-fraction symbols which are composable:

$$x \xrightarrow{f} y \xleftarrow{t} z \xrightarrow{g} u \xleftarrow{r} v.$$

Then the middle arrows give a right-fraction symbol which we can fill in to a square with a left-fraction symbol going in the other direction:

$$(4.1) \quad \begin{array}{ccc} & z & \\ \swarrow & & \searrow \\ y & & u \\ \searrow & & \swarrow \\ & z' & \end{array}$$

which in turn fits into the previous collection to yield a composite left-fraction symbol  $(g' \circ f, t' \circ r)$ :

$$x \xrightarrow{f} y \xrightarrow{g'} z' \xleftarrow{t'} u \xleftarrow{r} v.$$

In order to define the composition, we make a choice of fill-in square and set the composition equal to the composite symbol  $(g' \circ f, t' \circ r)$ . This composition rule is not associative, nor does

it satisfy the left and right identity relations. On the other hand, modulo the equivalence relation established above, the composition will become associative and unitary.

The first and main step is to show that the composition is well-defined modulo the equivalence relation. This has two parts: first that if we make two different choices of fill-in square then the resulting composite symbols are equivalent; and secondly if we choose different representatives for the symbols which are being composed, then the composites are equivalent. These proofs make use of the same kind of arguments as we have described above, invoking things like Corollary 4.2 when necessary. The reader can by now imagine why no authors have attempted to write down the full text of these proofs in a forum destined for human readers. Those who are interested may refer directly to the proof files.

Once the well-definedness is established, the associativity is significantly easier at least on a conceptual level. It suffices to look at the following diagram:

$$(4.2) \quad \begin{array}{ccccccc} & & \cdot & & \cdot & & \cdot & & \cdot & & \cdot \\ & & \searrow & \nearrow & \searrow & \nearrow & \searrow & \nearrow & \searrow & \nearrow & \\ & & \cdot & & 1 & & \cdot & & 2 & & \cdot \\ & & \searrow & \nearrow & \searrow & \nearrow & \searrow & \nearrow & \searrow & \nearrow & \\ & & \cdot & & & & 3 & & \cdot & & \cdot \\ & & & & \searrow & \nearrow & & & \searrow & \nearrow & \\ & & & & & & \cdot & & & & \cdot \end{array}$$

where, along the top, are the three left-fraction symbols we want to compose. Choose the top two fill-in squares denoted 1 and 2 first, which gives the middle row of arrows; then choose the bottom fill-in square 3. Now the two different associated products may be obtained as follows (here we use the invariance under choice of fill-in square):

—one is obtained by using square 1 to compose the first two symbols; then the composite rectangle  $2 + 3$  is a fill-in square for multiplying this first composite with the rightmost symbol;

—the other is obtained by using square 2 to compose the second two symbols; and the composite rectangle  $1 + 3$  is a fill-in square for multiplying the leftmost symbol with this first composite.

Both methods give as result the left-fraction symbol obtained using the composites along the bottom edges of the big diagram. Thus, with the choices made as described above, the composition becomes associative “on the nose”; and because of the invariance of choices up to equivalence, we get that composition is associative up to equivalence when we make arbitrary choices for the fill-in squares.

The left and right unit conditions are proved similarly.

We obtain a category of “left fractions”. Defining the functor from our original category into the left fraction category, and proving that the images of elements of the localizing system are invertible, involve again some lemmas of a similar nature, whose proofs basically consist of setting up the appropriate diagrams and using good choices for the fill-in squares to define the compositions in question. For all of these things, we are in agreement with all of the authors found so far, that it isn’t worthwhile to write a mathematical text for these proofs. The proofs may be found directly in the proof files attached to [31].

The construction of the localization by left fractions can be considered as the statement of a nontrivial theorem about any localization (for example, about the general localization constructed previously).

**Theorem 4.4.** *Suppose  $\mathcal{C}$  is a category and  $\Sigma$  is a multiplicative system satisfying the left-fraction conditions (a)–(d) above. Let  $\mathcal{C}[\Sigma^{-1}]$  be a localization. Then the morphisms of  $\mathcal{C}[\Sigma^{-1}]$  have the following description. Every morphism can be written as a composition  $t^{-1} \circ u$  where  $u$  comes from  $\mathcal{C}$  and  $t$  comes from  $\Sigma$  (and their targets coincide). If, for two such pairs  $t^{-1} \circ u = r^{-1} \circ v$ , then there exist morphisms  $a$  and  $b$  in  $\mathcal{C}$  such that:  $a$  is composable with  $u$  and  $t$ ;  $b$  is composable with  $v$  and  $r$ ;  $au = bv$ ; and  $at = br$  and this is in  $\Sigma$ .*

The proof is that this description holds by definition for the left-fraction localization we are discussing in the present section. Then the universal properties show that any two localizations are isomorphic, so the same description holds in any other localization. This theorem is treated in the file `gzloc.v` (it is only there that we treat the fact that different localizations are isomorphic). It might be interesting to try to prove this description directly for the general construction of the localization. The left-fractions conditions imply fairly directly that morphisms in the localization can be written as simple products. However, to verify the statement about the equivalence relation seems difficult.

As a conclusion to this section, it is interesting to note that the mathematics behind the fraction construction is not one hundred percent straightforward, as was the case for the mathematics behind the general construction. On the other hand, it is commonly believed that the “calculus of fractions” construction is much more concrete and easy to understand. A possible reason for this is that mathematicians are very attached to considering the “size” of the mathematical objects which they manipulate, rather than the size of the associated mathematical theories. Since the arrows in the fraction construction are paths of length two whereas the arrows of the general construction are paths of arbitrary length, people prefer to think about the fraction construction (for example D. Pronk generalized the fraction construction to the case of 2-categories [21] but didn’t mention generalizing the general construction). This tendency is similar to the constructionist or intuitionist philosophy: even while admitting reasoning based on less constructive arguments, mathematicians of all philosophies gravitate towards smaller and more constructive objects when they are available.

## 5. FORMALIZING THE LEFT-FRACTION CONSTRUCTION

The formalization is contained in the file `left_fractions.v`, where `Left_Fractions` is the first module treating all of the essential constructions and properties. It starts with what is by now a fairly standard kind of definition, `lf_symbol f t` is an object (`Arrow.like`, in fact) containing the pair  $(f, t)$  and corresponding to the left-fraction symbols used in the informal discussion above. The construction `lf_choice a s r g` represents a choice of fill-in left-fraction symbol creating a commutative square whose upper sides are the right-fraction symbol  $(r, g)$ .

A left-fraction symbol has an additional object besides its `source` and `target`, which we call `lf_vertex u`. This is the common target of the two morphisms involved. The operation `lf_extend a s p u` corresponds to composing both arrows of the left-fraction symbol  $u$ , with a morphism  $p$  whose source is `source p = lf_vertex u`.

The `lf_extend` enters into the definitions of the notions `lf_beyond` and `lf_under` as defined in the previous section. In turn we define `lf_equiv` as existence of a common symbol which is `lf_beyond` the two in question. Then comes the main part of the proof which is Lemma `lf_equiv_trans`. This proof is done as described in the previous section (the division into sublemmas is slightly different from what is done informally above; we have referred above to the corresponding places in the proof files).

The main thing I would like to talk about in this section is the method we use for representing situations which, in informal argument, would be represented by a commutative diagram drawn in the text. Consider for example the definition

```

Definition fills_in a s u v w :=
has_left_fractions a s &
is_lf_symbol a s u & is_lf_symbol a s v & is_lf_symbol a s w
& source u = target v & source w = lf_vertex v &
target w = lf_vertex u &
comp a (lf_forward w) (lf_backward v) =
comp a (lf_backward w) (lf_forward u).

```

This represents the diagram 4.1 we have drawn in the previous section for defining composition. The variables `u`, `v` and `w` are the three left-fraction symbols occurring in the diagram (the first two on the upper row and the last one completing the bottom).

In a similar way, the definition `assoc_board a s u v w x y z` represents the diagram 4.2 we have drawn above for the associativity of composition. Another important pair of diagrams are `lf_lean_to a s e f g h i j` and `closes_lf_lean_to a s e f g h i j k l`. These correspond to diagrams, vaguely shaped like “lean-to’s”, which we haven’t drawn above (due mostly to my lack of  $\text{\TeX}$ -nique), and which enter into the proof that the composition is well-defined up to equivalence.

The idea in all of these cases is to make a definition involving all of the objects occurring in the diagram, which corresponds to commutativity of the diagram plus all of the other basic information it is supposed to satisfy (for example saying what the elements are, and that the sources and targets match up). In the cases `fills_in` and `assoc_board` we have chosen to represent the elements as being the left-fraction symbols (i.e. they are pairs of arrows) whereas in the diagrams `lf_lean_to` and `closes_lf_lean_to` the elements are morphisms of `a`. In both cases the first variable `a` is the category and the second variable `s` is the multiplicative system we are considering.

Given this way of manipulating diagrams, we can then state the main steps in the proof. For example, the main step of the well-definedness of composition is

```

Lemma lf_lean_to_closure : forall a s e f g h i j,
lf_lean_to a s e f g h i j ->
(exists k, exists l, (closes_lf_lean_to a s e f g h i j k l)).

```

This lemma is then used in Lemma `weak_rep_lf_equiv` (this fact doesn’t show up in the text as recopied in the preprint [31] because it is inside the proof—which shows a limitation to the idea of just copying definitions and lemma statements as a simplified presentation).

Often the diagram definition will occur as a hypothesis of a lemma. This is particularly true of the hypothesis `assoc_board a s u v w x y z` which occurs as a hypothesis in a few different intermediate lemmas before the main statement of Lemma `make_comp_assoc_board`.

The definitions `ffb_symbol` and `fb_symbol` correspond to the two operations of juxtaposing two fill-in squares to get a rectangle which composes to a new fill-in square giving the outer compositions in the associativity statement (in the previous section this was where we looked at rectangles denoted  $1 + 3$  or  $2 + 3$ ).

As a general matter, writing mathematics for the computer requires that we go to a notation which is completely precise. Different strategies might be used for trying to keep a lid on the length of such notation. It is interesting to note that in situations such as the present one, precise definitions such as `ffb_symbol a s y z` replace vague statements such as “juxtapose the squares denoted 1 and 3 in the above diagram”. One major problem in both cases is the problem of referring to pieces of the diagram in question. The fact that we have included the various pieces as variables in our diagram definition `assoc_board a s u v w x y z` means that we can give small variable letters to each piece. Thus the `y` and `z` in `ffb_symbol a s y z` refer to places in `assoc_board`. In a mathematical text this referentiation operation becomes cumbersome when we start to manipulate large numbers of objects: we are led to circumlocutions like “the arrow on the upper left” and generally get lost in the meanders of referencing conventions of natural language (which are not totally precise nor sufficiently powerful). Another tempting solution would be to create a distinct mathematical object for the whole diagram. This is pretty much what we have done with the notion of `lf_symbol` for example. The drawback is that we then need long names for the component pieces of the diagrams. In the case of `lf_symbol` these were the functions `lf_forward` and `lf_backward`. This approach was called for in the case of `lf_symbol` because of the frequency and diversity of manipulations we have to do with these objects. On the other hand, with big diagrams which occur basically only once or a few times, it seems better to avoid allocating specific long names to their component pieces, and let the components be variables in a propositional representation of the diagram as a functional property. The observations in this paragraph are not intended as strict edicts but rather as ideas for one possible way to approach the language problems which are posed by computer formulation.

Rather than going on in detail about the remainder of the construction (the module `Left_Fraction_Category` is where we use the `Associating_Quotient` module to actually construct the category of left fractions; then we need to establish its universal properties and so forth), we close this section with an observation about proof technique. The proofs of the main lemmas referred to above are often rather long, because they involve manipulations of large amounts of information. Since steps such as rewriting tend to produce residual goals, one arrives at a situation where there is an impossibly large number of residual goals to treat at the end of a proof. Furthermore the treatment of these goals tends to be highly repetitive. In this situation it is essential to maintain a certain level of discipline in the following sense: when one comes upon a rewriting situation which generates an additional goal, one must go back to the start of the proof and add in that goal as an `Assert` statement. This can be done without changing the numbering of hypotheses (which would be painful to correct at each occurrence of this phenomenon) by considering the `Assert` statements as “sublemmas” in the proof and naming them as such. Thus, rather than writing

```
Assert (...)
```

it is better to write

```
Assert (lemA : ...).
```

The proof itself becomes a location where there are many sublemmas. One can even recopy the sublemma texts with their proofs, from one proof to another (when the proof contexts are going to be similar in both cases). Once the required sublemmas are there, a combined rewriting tactic (such as our abbreviations `rw` or `wr`) which does a rewrite and then tries `assumption` and `trivial` on the subgoals, gives a proof where the number of auxiliary subgoals is reduced significantly enough to be only “very annoying” rather than “impossibly painful”.

## 6. FURTHER FORMALIZATIONS

After the file on the left fraction construction, we include a few more files in the present development. In `gzloc.v`, we start by going back to some general considerations about localization. Lemmas whose names finish with `_recall` are statements meant to recall definitions from earlier files, so as to make reading of this part a little bit more self-contained. The first main corollary of the section is that two different localizations are isomorphic. Recall that `are_finverse a b` means that two functors are inverse (which is to say that their compositions are *equal* to the identity—hence they establish an isomorphism between their sources and targets). Thus the lemma `are_finverse_dotted_choice` says that any two localization functors are isomorphic (refer to `source_dotted_choice` and `target_dotted_choice` as well as `fcompose_dotted_choice` to complete this statement).

The next step is to investigate the relationship between all of our various definitions, and the opposite category and opposite functor structures. The main point here is to define the calculus of right fractions, by conjugating left fractions with “opposite”. This is of course completely straightforward, but many statements require lengthy proofs, which is certainly evidence that our overall setup is not really optimal.

In the part of the `gzloc.v` file starting with the definitions `lf_vee`, `lf_vee_image` and `lf_vee_equivalent`, we treat Theorem 4.4. As pointed out above, the proof is based on the fact that our left-fraction construction of a localization is isomorphic to any other localization due to the universal property. The statement of Theorem 4.4 is contained in Lemmas `left_fraction_description_for_loc` (for the case of an arbitrary localization) and `left_fraction_description_gz_proj` (for the case of the original general construction). Dualizing (by applying the opposite construction discussed in the previous paragraph) we obtain the corresponding results for right fractions.

The last file of the localization discussion is `lfcx.v`. Here we construct a little counterexample to one of the technical points encountered in the left-fractions construction. This part of the formalisation takes us back to one of the basic points of our approach to types and set-theory, namely that we integrate the inductive creation of types in COQ into our axiomatization of set theory. This allows us to manipulate small finite sets by creating them as inductive objects. In this way we can do a relatively large amount of case analysis by defining recursive tactics using the `Ltac` tactic language. In this way many of the proofs of properties of our constructed objects are very short lists of tactics (which take some time

for the computer to digest). This could perhaps be thought of as a very very baby version of Gonthier-Werner’s techniques which they have applied to the 4-color theorem. The conclusion of the file is existence of a category  $\mathbf{a}$  and localizing system  $\mathbf{s}$ , satisfying left fractions, but with two left-fraction symbols  $\mathbf{u}$  and  $\mathbf{v}$  with `lf_beyond a s u v` (thus  $\mathbf{u}$  and  $\mathbf{v}$  project to equivalent arrows in the localization), however there is no symbol  $\mathbf{w}$  such that `lf_under a s u w` and `lf_under a s v w`. This shows that we need to use the condition `lf_beyond` rather than `lf_under` (see the discussion of this point above).

The last file of the development is `infinite.v`. This is a complete digression from the subject: here we prove the fundamental properties of cardinal arithmetic for infinite cardinals, namely that the union or product of two infinite cardinals has the maximum of the two cardinalities. By Russell’s paradox on the other hand, the powerset of an infinite cardinal is strictly bigger. Along the way we do a certain number of basic properties of finite and infinite sets, cardinals, and ordinals. It is beyond the scope of the present preprint to go into further detail about the strategy of proof; and (contrarily to the case of localization of categories as we have seen) this is a subject in which there is no lack of different treatments in the literature—which we have not tried at all to index in the references.

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